

# Deep Generative Models

## Lecture 5

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AI Masters

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# Recap of previous lecture

## Bayes theorem

$$p(\mathbf{t}|\mathbf{x}) = \frac{p(\mathbf{x}|\mathbf{t})p(\mathbf{t})}{p(\mathbf{x})} = \frac{p(\mathbf{x}|\mathbf{t})p(\mathbf{t})}{\int p(\mathbf{x}|\mathbf{t})p(\mathbf{t})d\mathbf{t}}$$

- ▶  $\mathbf{x}$  – observed variables,  $\mathbf{t}$  – unobserved variables (latent variables/parameters);
- ▶  $p(\mathbf{x}|\mathbf{t})$  – likelihood;
- ▶  $p(\mathbf{x}) = \int p(\mathbf{x}|\mathbf{t})p(\mathbf{t})d\mathbf{t}$  – evidence;
- ▶  $p(\mathbf{t})$  – prior distribution,  $p(\mathbf{t}|\mathbf{x})$  – posterior distribution.

## Posterior distribution

$$p(\theta|\mathbf{X}) = \frac{p(\mathbf{X}|\theta)p(\theta)}{p(\mathbf{X})} = \frac{p(\mathbf{X}|\theta)p(\theta)}{\int p(\mathbf{X}|\theta)p(\theta)d\theta}$$

# Recap of previous lecture

## Latent variable models (LVM)

$$p(\mathbf{x}|\boldsymbol{\theta}) = \int p(\mathbf{x}, \mathbf{z}|\boldsymbol{\theta})d\mathbf{z} = \int p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta})p(\mathbf{z})d\mathbf{z}.$$

## MLE problem for LVM

$$\begin{aligned}\boldsymbol{\theta}^* &= \arg \max_{\boldsymbol{\theta}} \log p(\mathbf{X}|\boldsymbol{\theta}) = \arg \max_{\boldsymbol{\theta}} \sum_{i=1}^n \log p(\mathbf{x}_i|\boldsymbol{\theta}) = \\ &= \arg \max_{\boldsymbol{\theta}} \sum_{i=1}^n \log \int p(\mathbf{x}_i|\mathbf{z}_i, \boldsymbol{\theta})p(\mathbf{z}_i)d\mathbf{z}_i.\end{aligned}$$

## Naive Monte-Carlo estimation

$$p(\mathbf{x}|\boldsymbol{\theta}) = \int p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta})p(\mathbf{z})d\mathbf{z} = \mathbb{E}_{p(\mathbf{z})}p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta}) \approx \frac{1}{K} \sum_{k=1}^K p(\mathbf{x}|\mathbf{z}_k, \boldsymbol{\theta}),$$

where  $\mathbf{z}_k \sim p(\mathbf{z})$ .

# Recap of previous lecture

## ELBO derivation 1 (inequality)

$$\log p(\mathbf{x}|\boldsymbol{\theta}) = \log \int p(\mathbf{x}, \mathbf{z}|\boldsymbol{\theta}) d\mathbf{z} \geq \mathbb{E}_q \log \frac{p(\mathbf{x}, \mathbf{z}|\boldsymbol{\theta})}{q(\mathbf{z})} = \mathcal{L}(q, \boldsymbol{\theta})$$

## ELBO derivation 2 (equality)

$$\begin{aligned} \mathcal{L}(q, \boldsymbol{\theta}) &= \int q(\mathbf{z}) \log \frac{p(\mathbf{x}, \mathbf{z}|\boldsymbol{\theta})}{q(\mathbf{z})} d\mathbf{z} = \int q(\mathbf{z}) \log \frac{p(\mathbf{z}|\mathbf{x}, \boldsymbol{\theta}) p(\mathbf{x}|\boldsymbol{\theta})}{q(\mathbf{z})} d\mathbf{z} = \\ &= \log p(\mathbf{x}|\boldsymbol{\theta}) - KL(q(\mathbf{z})||p(\mathbf{z}|\mathbf{x}, \boldsymbol{\theta})) \end{aligned}$$

## Variational decomposition

$$\log p(\mathbf{x}|\boldsymbol{\theta}) = \mathcal{L}(q, \boldsymbol{\theta}) + KL(q(\mathbf{z})||p(\mathbf{z}|\mathbf{x}, \boldsymbol{\theta})) \geq \mathcal{L}(q, \boldsymbol{\theta}).$$

# Recap of previous lecture

## Variational lower Bound (ELBO)

$$\log p(\mathbf{x}|\boldsymbol{\theta}) = \mathcal{L}(q, \boldsymbol{\theta}) + KL(q(\mathbf{z})||p(\mathbf{z}|\mathbf{x}, \boldsymbol{\theta})) \geq \mathcal{L}(q, \boldsymbol{\theta}).$$

$$\mathcal{L}(q, \boldsymbol{\theta}) = \int q(\mathbf{z}) \log \frac{p(\mathbf{x}, \mathbf{z}|\boldsymbol{\theta})}{q(\mathbf{z})} d\mathbf{z} = \mathbb{E}_q \log p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta}) - KL(q(\mathbf{z})||p(\mathbf{z}))$$

## Log-likelihood decomposition

$$\log p(\mathbf{x}|\boldsymbol{\theta}) = \mathbb{E}_q \log p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta}) - KL(q(\mathbf{z})||p(\mathbf{z})) + KL(q(\mathbf{z})||p(\mathbf{z}|\mathbf{x}, \boldsymbol{\theta})).$$

- Instead of maximizing incomplete likelihood, maximize ELBO

$$\max_{\boldsymbol{\theta}} p(\mathbf{x}|\boldsymbol{\theta}) \rightarrow \max_{q, \boldsymbol{\theta}} \mathcal{L}(q, \boldsymbol{\theta})$$

- Maximization of ELBO by variational distribution  $q$  is equivalent to minimization of KL

$$\arg \max_q \mathcal{L}(q, \boldsymbol{\theta}) \equiv \arg \min_q KL(q(\mathbf{z})||p(\mathbf{z}|\mathbf{x}, \boldsymbol{\theta})).$$

# Recap of previous lecture

## EM-algorithm

- ▶ E-step

$$q^*(\mathbf{z}) = \arg \max_q \mathcal{L}(q, \boldsymbol{\theta}^*) = \arg \min_q KL(q(\mathbf{z}) || p(\mathbf{z} | \mathbf{x}, \boldsymbol{\theta}^*));$$

- ▶ M-step

$$\boldsymbol{\theta}^* = \arg \max_{\boldsymbol{\theta}} \mathcal{L}(q^*, \boldsymbol{\theta});$$

## Amortized variational inference

Restrict a family of all possible distributions  $q(\mathbf{z})$  to a parametric class  $q(\mathbf{z} | \mathbf{x}, \phi)$  conditioned on samples  $\mathbf{x}$  with parameters  $\phi$ .

## Variational Bayes

- ▶ E-step

$$\phi_k = \phi_{k-1} + \eta \nabla_{\phi} \mathcal{L}(\phi, \boldsymbol{\theta}_{k-1})|_{\phi=\phi_{k-1}}$$

- ▶ M-step

$$\boldsymbol{\theta}_k = \boldsymbol{\theta}_{k-1} + \eta \nabla_{\boldsymbol{\theta}} \mathcal{L}(\phi_k, \boldsymbol{\theta})|_{\boldsymbol{\theta}=\boldsymbol{\theta}_{k-1}}$$

# Outline

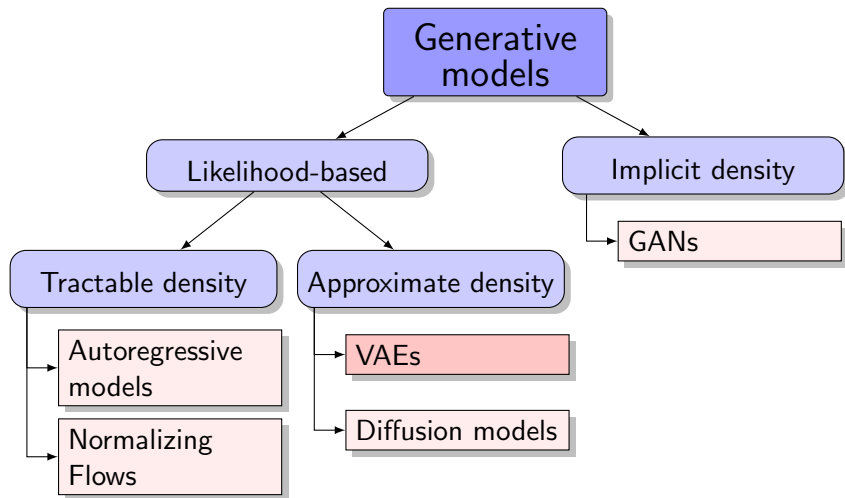
1. Variational autoencoder (VAE)
2. Data dequantization
3. Normalizing flows as VAE model
4. ELBO surgery

# Outline

1. Variational autoencoder (VAE)
2. Data dequantization
3. Normalizing flows as VAE model
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# Generative models zoo



# Variational autoencoder (VAE)

## Final EM-algorithm

- ▶ pick random sample  $\mathbf{x}_i, i \sim U[1, n]$ .
- ▶ compute the objective:

$$\epsilon^* \sim r(\epsilon); \quad \mathbf{z}^* = g(\mathbf{x}, \epsilon^*, \phi);$$

$$\mathcal{L}(\phi, \theta) \approx \log p(\mathbf{x}|\mathbf{z}^*, \theta) - KL(q(\mathbf{z}^*|\mathbf{x}, \phi)||p(\mathbf{z}^*)).$$

- ▶ compute a stochastic gradients w.r.t.  $\phi$  and  $\theta$

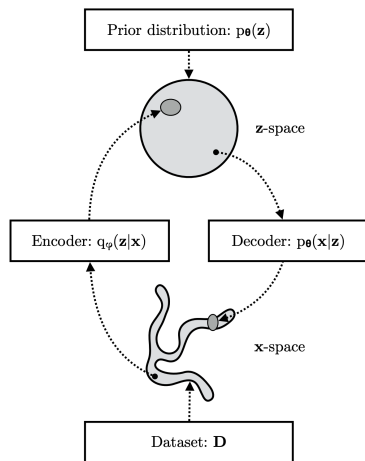
$$\begin{aligned}\nabla_{\phi}\mathcal{L}(\phi, \theta) &\approx \nabla_{\phi} \log p(\mathbf{x}|g_{\phi}(\mathbf{x}, \epsilon^*), \theta) - \nabla_{\phi} KL(q(\mathbf{z}|\mathbf{x}, \phi)||p(\mathbf{z})); \\ \nabla_{\theta}\mathcal{L}(\phi, \theta) &\approx \nabla_{\theta} \log p(\mathbf{x}|\mathbf{z}^*, \theta).\end{aligned}$$

- ▶ update  $\theta, \phi$  according to the selected optimization method (SGD, Adam, RMSProp):

$$\begin{aligned}\phi &:= \phi + \eta \nabla_{\phi} \mathcal{L}(\phi, \theta), \\ \theta &:= \theta + \eta \nabla_{\theta} \mathcal{L}(\phi, \theta).\end{aligned}$$

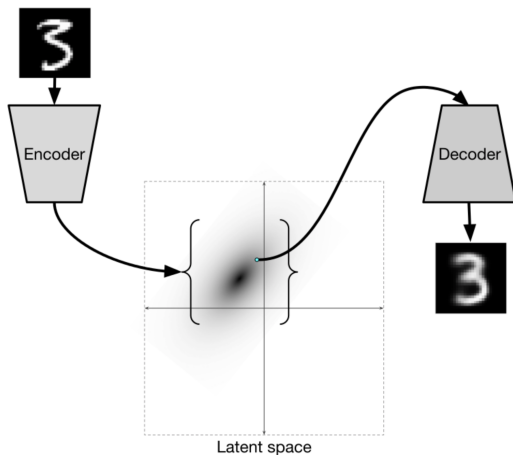
# Variational autoencoder (VAE)

- ▶ VAE learns stochastic mapping between  $\mathbf{x}$ -space, from complicated distribution  $\pi(\mathbf{x})$ , and a latent  $\mathbf{z}$ -space, with simple distribution.
- ▶ The generative model learns a joint distribution  $p(\mathbf{x}, \mathbf{z}|\theta) = p(\mathbf{z})p(\mathbf{x}|\mathbf{z}, \theta)$ , with a prior distribution  $p(\mathbf{z})$ , and a stochastic decoder  $p(\mathbf{x}|\mathbf{z}, \theta)$ .
- ▶ The stochastic encoder  $q(\mathbf{z}|\mathbf{x}, \phi)$  (inference model), approximates the true but intractable posterior  $p(\mathbf{z}|\mathbf{x}, \theta)$  of the generative model.



# Variational Autoencoder

$$\mathcal{L}(\phi, \theta) = \mathbb{E}_{q(\mathbf{z}|\mathbf{x}, \phi)} \left[ \log p(\mathbf{x}|\mathbf{z}, \theta) - \log \frac{q(\mathbf{z}|\mathbf{x}, \phi)}{p(\mathbf{z})} \right] \rightarrow \max_{\phi, \theta}.$$



# Variational autoencoder (VAE)

- ▶ Encoder  $q(\mathbf{z}|\mathbf{x}, \phi) = \text{NN}_e(\mathbf{x}, \phi)$  outputs  $\mu_\phi(\mathbf{x})$  and  $\sigma_\phi(\mathbf{x})$ .
- ▶ Decoder  $p(\mathbf{x}|\mathbf{z}, \theta) = \text{NN}_d(\mathbf{z}, \theta)$  outputs parameters of the sample distribution.

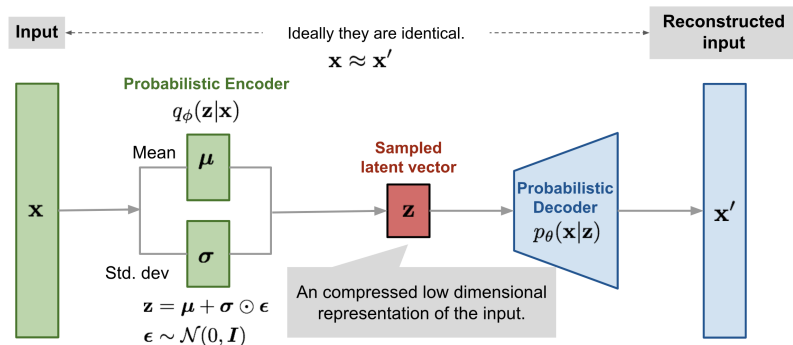


image credit:

<https://lilianweng.github.io/lil-log/2018/08/12/from-autoencoder-to-beta-vae.html>

# Outline

1. Variational autoencoder (VAE)
2. Data dequantization
3. Normalizing flows as VAE model
4. ELBO surgery

## Discrete data vs continuous model

Let our data  $\mathbf{y}$  comes from discrete distribution  $\Pi(\mathbf{y})$  and we have continuous model  $p(\mathbf{x}|\theta) = \text{NN}(\mathbf{x}, \theta)$ .

- ▶ Images (and not only images) are discrete data, pixels lie in the integer domain  $\{0, 255\}$ .
- ▶ By fitting a continuous density model  $p(\mathbf{x}|\theta)$  to discrete data  $\Pi(\mathbf{y})$ , one can produce a degenerate solution with all probability mass on discrete values.

## Discrete model

- ▶ Use **discrete** model (e.x.  $P(\mathbf{y}|\theta) = \text{Cat}(\pi(\theta))$ ).
- ▶ Minimize any suitable divergence measure  $D(\Pi, P)$ .
- ▶ NF works only with continuous data  $\mathbf{x}$  (there are discrete NF, see papers below).
- ▶ If pixel value is not presented in the train data, it won't be predicted.

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*Hoogeboom E. et al. Integer discrete flows and lossless compression, 2019*

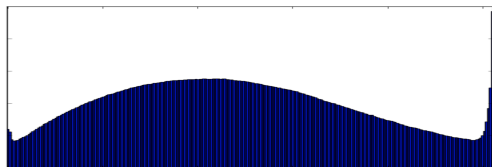
*Tran D. et al. Discrete flows: Invertible generative models of discrete data, 2019*

# Discrete data vs continuous model

## Continuous model

- ▶ Use **continuous** model (e.x.  $p(\mathbf{x}|\theta) = \mathcal{N}(\mu_{\theta}(\mathbf{x}), \sigma_{\theta}^2(\mathbf{x}))$ ), but
  - ▶ **discretize** model (make the model outputs discrete): transform  $p(\mathbf{x}|\theta)$  to  $P(\mathbf{y}|\theta)$ ;
  - ▶ **dequantize** data (make the data continuous): transform  $\Pi(\mathbf{y})$  to  $\pi(\mathbf{x})$ .
- ▶ Continuous distribution knows numerical relationships.

## CIFAR-10 pixel values distribution





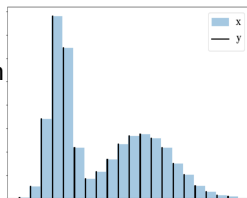
# Uniform dequantization

Let dequantize discrete distribution  $\Pi(\mathbf{y})$  to continuous distribution  $\pi(\mathbf{x})$  in the following way:  $\mathbf{x} = \mathbf{y} + \mathbf{u}$ , where  $\mathbf{u} \sim U[0, 1]$ .

## Theorem

Fitting continuous model  $p(\mathbf{x}|\theta)$  on uniformly dequantized data is equivalent to maximization of a lower bound on log-likelihood for a discrete model:

$$P(\mathbf{y}|\theta) = \int_{U[0,1]} p(\mathbf{y} + \mathbf{u}|\theta) d\mathbf{u}$$



## Proof

$$\begin{aligned}\mathbb{E}_{\pi} \log p(\mathbf{x}|\theta) &= \int \pi(\mathbf{x}) \log p(\mathbf{x}|\theta) d\mathbf{x} = \sum \Pi(\mathbf{y}) \int_{U[0,1]} \log p(\mathbf{y} + \mathbf{u}|\theta) d\mathbf{u} \leq \\ &\leq \sum \Pi(\mathbf{y}) \log \int_{U[0,1]} p(\mathbf{y} + \mathbf{u}|\theta) d\mathbf{u} = \\ &= \sum \Pi(\mathbf{y}) \log P(\mathbf{y}|\theta) = \mathbb{E}_{\Pi} \log P(\mathbf{y}|\theta).\end{aligned}$$

# Outline

1. Variational autoencoder (VAE)
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# VAE vs Normalizing flows

	VAE	NF
Objective	ELBO $\mathcal{L}$	Forward KL/MLE
Encoder	stochastic $\mathbf{z} \sim q(\mathbf{z} \mathbf{x}, \phi)$	deterministic $\mathbf{z} = f_{\theta}(\mathbf{x})$ $q(\mathbf{z} \mathbf{x}, \theta) = \delta(\mathbf{z} - f_{\theta}(\mathbf{x}))$
Decoder	stochastic $\mathbf{x} \sim p(\mathbf{x} \mathbf{z}, \theta)$	deterministic $\mathbf{x} = g_{\theta}(\mathbf{z})$ $p(\mathbf{x} \mathbf{z}, \theta) = \delta(\mathbf{x} - g_{\theta}(\mathbf{z}))$
Parameters	$\phi, \theta$	$\theta \equiv \phi$

## Theorem

MLE for normalizing flow is equivalent to maximization of ELBO for VAE model with deterministic encoder and decoder:

$$p(\mathbf{x}|\mathbf{z}, \theta) = \delta(\mathbf{x} - f^{-1}(\mathbf{z}, \theta)) = \delta(\mathbf{x} - g_{\theta}(\mathbf{z}));$$

$$q(\mathbf{z}|\mathbf{x}, \theta) = p(\mathbf{z}|\mathbf{x}, \theta) = \delta(\mathbf{z} - f_{\theta}(\mathbf{x})).$$

# Normalizing flow as VAE

## Proof

1. Dirac delta function property

$$\mathbb{E}_{\delta(\mathbf{x}-\mathbf{y})} f(\mathbf{x}) = \int \delta(\mathbf{x}-\mathbf{y}) f(\mathbf{x}) d\mathbf{x} = f(\mathbf{y}).$$

2. CoV theorem and Bayes theorem:

$$p(\mathbf{x}|\boldsymbol{\theta}) = p(\mathbf{z}) |\det(\mathbf{J}_f)|;$$

$$p(\mathbf{z}|\mathbf{x}, \boldsymbol{\theta}) = \frac{p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta}) p(\mathbf{z})}{p(\mathbf{x}|\boldsymbol{\theta})}; \quad \Rightarrow \quad p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta}) = p(\mathbf{z}|\mathbf{x}, \boldsymbol{\theta}) |\det(\mathbf{J}_f)|.$$

3. Log-likelihood decomposition

$$\log p(\mathbf{x}|\boldsymbol{\theta}) = \mathcal{L}(\boldsymbol{\theta}) + KL(q(\mathbf{z}|\mathbf{x}, \boldsymbol{\theta}) || p(\mathbf{z}|\mathbf{x}, \boldsymbol{\theta})) = \mathcal{L}(\boldsymbol{\theta}).$$

# Normalizing flow as VAE

## Proof

ELBO objective:

$$\begin{aligned}\mathcal{L} &= \mathbb{E}_{q(\mathbf{z}|\mathbf{x},\theta)} \left[ \log p(\mathbf{x}|\mathbf{z},\theta) - \log \frac{q(\mathbf{z}|\mathbf{x},\theta)}{p(\mathbf{z})} \right] \\ &= \mathbb{E}_{q(\mathbf{z}|\mathbf{x},\theta)} \left[ \log \frac{p(\mathbf{x}|\mathbf{z},\theta)}{q(\mathbf{z}|\mathbf{x},\theta)} + \log p(\mathbf{z}) \right].\end{aligned}$$

1. Dirac delta function property:

$$\mathbb{E}_{q(\mathbf{z}|\mathbf{x},\theta)} \log p(\mathbf{z}) = \int \delta(\mathbf{z} - f_\theta(\mathbf{x})) \log p(\mathbf{z}) d\mathbf{z} = \log p(f_\theta(\mathbf{x})).$$

2. CoV theorem and Bayes theorem:

$$\mathbb{E}_{q(\mathbf{z}|\mathbf{x},\theta)} \log \frac{p(\mathbf{x}|\mathbf{z},\theta)}{q(\mathbf{z}|\mathbf{x},\theta)} = \mathbb{E}_{q(\mathbf{z}|\mathbf{x},\theta)} \log \frac{p(\mathbf{z}|\mathbf{x},\theta) |\det(\mathbf{J}_f)|}{q(\mathbf{z}|\mathbf{x},\theta)} = \log |\det \mathbf{J}_f|.$$

3. Log-likelihood decomposition

$$\log p(\mathbf{x}|\theta) = \mathcal{L}(\theta) = \log p(f_\theta(\mathbf{x})) + \log |\det \mathbf{J}_f|.$$

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# ELBO surgery

$$\frac{1}{n} \sum_{i=1}^n \mathcal{L}_i(q, \theta) = \frac{1}{n} \sum_{i=1}^n \left[ \mathbb{E}_{q(\mathbf{z}|\mathbf{x}_i)} \log p(\mathbf{x}_i|\mathbf{z}, \theta) - KL(q(\mathbf{z}|\mathbf{x}_i)||p(\mathbf{z})) \right].$$

## Theorem

$$\frac{1}{n} \sum_{i=1}^n KL(q(\mathbf{z}|\mathbf{x}_i)||p(\mathbf{z})) = KL(q_{\text{agg}}(\mathbf{z})||p(\mathbf{z})) + \mathbb{I}_q[\mathbf{x}, \mathbf{z}];$$

- ▶  $q_{\text{agg}}(\mathbf{z}) = \frac{1}{n} \sum_{i=1}^n q(\mathbf{z}|\mathbf{x}_i)$  – **aggregated** posterior distribution.
- ▶  $\mathbb{I}_q[\mathbf{x}, \mathbf{z}]$  – mutual information between  $\mathbf{x}$  and  $\mathbf{z}$  under empirical data distribution and distribution  $q(\mathbf{z}|\mathbf{x})$ .
- ▶ **First term** pushes  $q_{\text{agg}}(\mathbf{z})$  towards the prior  $p(\mathbf{z})$ .
- ▶ **Second term** reduces the amount of information about  $\mathbf{x}$  stored in  $\mathbf{z}$ .

# ELBO surgery

## Theorem

$$\frac{1}{n} \sum_{i=1}^n KL(q(\mathbf{z}|\mathbf{x}_i)||p(\mathbf{z})) = KL(q_{\text{agg}}(\mathbf{z})||p(\mathbf{z})) + \mathbb{I}_q[\mathbf{x}, \mathbf{z}].$$

## Proof

$$\begin{aligned} \frac{1}{n} \sum_{i=1}^n KL(q(\mathbf{z}|\mathbf{x}_i)||p(\mathbf{z})) &= \frac{1}{n} \sum_{i=1}^n \int q(\mathbf{z}|\mathbf{x}_i) \log \frac{q(\mathbf{z}|\mathbf{x}_i)}{p(\mathbf{z})} d\mathbf{z} = \\ &= \frac{1}{n} \sum_{i=1}^n \int q(\mathbf{z}|\mathbf{x}_i) \log \frac{q_{\text{agg}}(\mathbf{z})q(\mathbf{z}|\mathbf{x}_i)}{p(\mathbf{z})q_{\text{agg}}(\mathbf{z})} d\mathbf{z} = \int \frac{1}{n} \sum_{i=1}^n q(\mathbf{z}|\mathbf{x}_i) \log \frac{q_{\text{agg}}(\mathbf{z})}{p(\mathbf{z})} d\mathbf{z} + \\ &+ \frac{1}{n} \sum_{i=1}^n \int q(\mathbf{z}|\mathbf{x}_i) \log \frac{q(\mathbf{z}|\mathbf{x}_i)}{q_{\text{agg}}(\mathbf{z})} d\mathbf{z} = KL(q_{\text{agg}}(\mathbf{z})||p(\mathbf{z})) + \frac{1}{n} \sum_{i=1}^n KL(q(\mathbf{z}|\mathbf{x}_i)||q_{\text{agg}}(\mathbf{z})) \end{aligned}$$

Without proof:

$$\mathbb{I}_q[\mathbf{x}, \mathbf{z}] = \frac{1}{n} \sum_{i=1}^n KL(q(\mathbf{z}|\mathbf{x}_i)||q_{\text{agg}}(\mathbf{z})) \in [0, \log n].$$



# ELBO surgery

## ELBO revisiting

$$\begin{aligned}\frac{1}{n} \sum_{i=1}^n \mathcal{L}_i(q, \theta) &= \frac{1}{n} \sum_{i=1}^n [\mathbb{E}_{q(\mathbf{z}|\mathbf{x}_i)} \log p(\mathbf{x}_i|\mathbf{z}, \theta) - KL(q(\mathbf{z}|\mathbf{x}_i)||p(\mathbf{z}))] = \\ &= \underbrace{\frac{1}{n} \sum_{i=1}^n \mathbb{E}_{q(\mathbf{z}|\mathbf{x}_i)} \log p(\mathbf{x}_i|\mathbf{z}, \theta)}_{\text{Reconstruction loss}} - \underbrace{\mathbb{I}_q[\mathbf{x}, \mathbf{z}]}_{\text{MI}} - \underbrace{KL(q_{\text{agg}}(\mathbf{z})||p(\mathbf{z}))}_{\text{Marginal KL}}\end{aligned}$$

Prior distribution  $p(\mathbf{z})$  is only in the last term.

## Optimal VAE prior

$$KL(q_{\text{agg}}(\mathbf{z})||p(\mathbf{z})) = 0 \quad \Leftrightarrow \quad p(\mathbf{z}) = q_{\text{agg}}(\mathbf{z}) = \frac{1}{n} \sum_{i=1}^n q(\mathbf{z}|\mathbf{x}_i).$$

The optimal prior  $p(\mathbf{z})$  is the aggregated posterior  $q_{\text{agg}}(\mathbf{z})$ !

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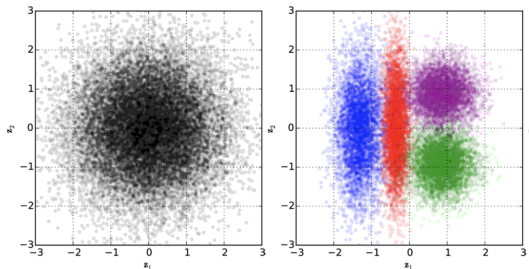
Hoffman M. D., Johnson M. J. *ELBO surgery: yet another way to carve up the variational evidence lower bound*, 2016

# Variational posterior

## ELBO decomposition

$$\log p(\mathbf{x}|\boldsymbol{\theta}) = \mathcal{L}(q, \boldsymbol{\theta}) + KL(q(\mathbf{z}|\mathbf{x}, \phi) || p(\mathbf{z}|\mathbf{x}, \boldsymbol{\theta})).$$

- ▶  $q(\mathbf{z}|\mathbf{x}, \phi) = \mathcal{N}(\mathbf{z}|\boldsymbol{\mu}_\phi(\mathbf{x}), \boldsymbol{\sigma}_\phi^2(\mathbf{x}))$  is a unimodal distribution.
- ▶ The optimal prior  $p(\mathbf{z})$  is the aggregated posterior  $q_{\text{agg}}(\mathbf{z})$ .



(a) Prior distribution

(b) Posteriors in standard VAE

It is widely believed that **mismatch between  $p(\mathbf{z})$  and  $q_{\text{agg}}(\mathbf{z})$  is the main reason of blurry images of VAE.**

# Summary

- ▶ The VAE model is an LVM with two neural network: stochastic encoder  $q(\mathbf{z}|\mathbf{x}, \phi)$  and stochastic decoder  $p(\mathbf{x}|\mathbf{z}, \theta)$ .
- ▶ Lots of data are discrete. We able to discretize the model or to dequantize our data to use continuous model.
- ▶ Uniform dequantization helps to make discrete data continuous. It gives us lower bound on the log-likelihood.
- ▶ NF models could be treated as VAE model with deterministic encoder and decoder.
- ▶ The ELBO surgery reveals insights about a prior distribution in VAE. The optimal prior is the aggregated posterior. It is widely believed that mismatch between  $p(\mathbf{z})$  and  $q_{\text{agg}}(\mathbf{z})$  is the main reason of blurry images of VAE.