

# Mengkun She

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EDUCATION	<p><b>Christian-Albrechts-Universität zu Kiel</b>, Kiel, Germany Nov 2020- Present</p> <ul style="list-style-type: none"><li>▪ Ph.D. in Computer Science</li><li>▪ Topic: Underwater Refractive Camera Calibration and 3D Scene Reconstruction</li><li>▪ Adviser: Prof. Dr. -Ing. Kevin Köser</li></ul> <p><b>Chongqing University</b>, Chongqing, China Sep 2017- Jun 2020</p> <ul style="list-style-type: none"><li>▪ M.S. in Geoinformatics</li></ul> <p><b>Chongqing University</b>, Chongqing, China Sep 2013- Jun 2017</p> <ul style="list-style-type: none"><li>▪ B.S. in Surveying and Mapping Engineering (Geoinformatics)</li></ul>
RESEARCH EXPERIENCE	<p><b>Helmholtz Centre for Ocean Research, Kiel, GEOMAR</b>, Jan 2019- Jan 2020</p> <ul style="list-style-type: none"><li>▪ Research Intern<ul style="list-style-type: none"><li>• Project: BubbleBox - High-speed stereo camera system for seafloor bubble flow estimation</li><li>• Focus: Refractive underwater camera calibration; Stereo; Object detection and tracking in video.</li></ul></li></ul> <p><b>Helmholtz Centre for Ocean Research, Kiel, GEOMAR</b>, Nov 2020- Jun 2024</p> <ul style="list-style-type: none"><li>▪ Research Scientist<ul style="list-style-type: none"><li>• Project: Deep Quanticam - visual mapping and quantitative machine vision in the deep sea</li><li>• Focus: Refractive geometry; Navigation-aided SfM; Refractive SfM; Underwater NeRF.</li></ul></li></ul>
SELECTED PUBLICATIONS	<p><b>M. She</b>, F. Seegräber, D. Nakath, P. Schöntag, K. Köser. Relative Illumination Fields: Learning Medium and Light Independent Underwater Scenes. (Submitted to <i>CVPR</i>, 2025)</p> <p><b>M. She</b>, F. Seegräber, D. Nakath, K. Köser. Refractive COLMAP: Refractive Structure-from-Motion Revisited. In <i>IROS</i>, 2024 (<b>Oral</b>)</p> <p><b>M. She</b>, Y. Song, D. Nakath, K. Köser. Semihierarchical Reconstruction and Weak-area Revisiting for Robotic Visual Seafloor Mapping. In <i>Journal of Field Robotics</i></p> <p><b>M. She</b>, T. Weiß, Y. Song, P. Urban, J. Greinert, K. Köser. Marine Bubble Flow Quantification Using Wide-baseline Stereo Photogrammetry. In <i>ISPRS Photogrammetry and Remote Sensing</i></p> <p><b>M. She</b>, D. Nakath, K. Köser. Refractive Geometry on Underwater Domes. In <i>ISPRS Photogrammetry and Remote Sensing</i></p> <p>X. Weng*, <b>M. She*</b>, D. Nakath, K. Köser (*<i>Equal Contribution</i>). Macal - Macro Lens Calibration and the Focus Stack Camera Model. In <i>3DV</i>, 2021 (<b>Oral</b>)</p> <p><b>M. She</b>, Y. Song, J Mohrmann, K. Köser. Adjustment and Calibration of Dome Port Camera Systems for Underwater Vision. In <i>GCPR</i>, 2019 (<b>Oral</b>)</p>
AWARDS & SCHOLARSHIPS	<ul style="list-style-type: none"><li>▪ Doctoral scholarship granted by China Scholarship Council (CSC) 2020 – 2024</li><li>▪ Travel grant for young researchers by Deutsche Arbeitsgemeinschaft für Mustererkennung, DAGM 2019</li></ul>
SKILLS	C++, Python, PyTorch, Ceres-Solver, Linux
REFERENCES	<ul style="list-style-type: none"><li>▪ <b>Prof. Dr. -Ing. Kevin Köser</b> Professor of Computer Science Marine Data Science Group Christian-Albrechts-Universität zu Kiel Alexander-Behm-Haus - EG.011, Neufeldtstraße 6, Kiel, Germany Email: <a href="mailto:kk@informatik.uni-kiel.de">kk@informatik.uni-kiel.de</a></li></ul>

- **Dr. David Nakath**

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