Mengkun She

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EDUCATION

Christian-Albrechts-Universität zu Kiel, Kiel, Germany

Nov 2020- Present

- Ph.D. in Computer Science
- Topic: Underwater Refractive Camera Calibration and 3D Scene Reconstruction
- Adviser: Prof. Dr. -Ing. Kevin Köser

Chongqing University, Chongqing, China

Sep 2017- Jun 2020

• M.S. in Geoinformatics

Chongqing University, Chongqing, China

Sep 2013- Jun 2017

■ B.S. in Surveying and Mapping Engineering (Geoinformatics)

RESEARCH EXPERIENCE

Helmholtz Centre for Ocean Research, Kiel, GEOMAR,

Nov 2020- Jun 2024

- Research Assistant
 - Project: Deep Quanticam visual mapping and quantitative machine vision in the deep sea
 - Focus: Refractive geometry; Navigation-aided SfM; Refractive SfM; Underwater NeRF.

Helmholtz Centre for Ocean Research, Kiel, GEOMAR,

Jan 2019- Jan 2020

- Research Intern
 - Project: BubbleBox High-speed stereo camera system for seafloor bubble flow estimation
 - Focus: Refractive underwater camera calibration; Stereo; Object detection and tracking in video.

INDUSTIRAL EXPERIENCE

Computer Vision Freelancer on Fiverr

Mar 2021- Sep 2024

- Freelancer offering various small-to-medium computer vision services and solutions.
 - Delivered more than 30 orders with a customer rating of 4.8.

Wuhan Planning and Design Institute,

Mar 2017- Sep 2017

- Internship for WebOS Software Development
 - Project: Web-based office management system for Geo-information purpose.
 - Focus: HTML, CSS, Javascript.

SELECTED PUBLICATIONS

- 18 publications listed on Google Scholar, with a total of 192 citations and an H-index of 8. Below are selected publications:
 - **M. She**, F. Seegräber, D. Nakath, P. Schöntag, K. Köser. Relative Illumination Fields: Learning Medium and Light Independent Underwater Scenes. (Submitted to *CVPR*, *2025*)
 - **M. She**, F. Seegräber, D. Nakath, K. Köser. Refractive COLMAP: Refractive Structure-from-Motion Revisited. In *IROS*, *2024* (**Oral**)
 - **M. She**, Y. Song, D. Nakath, K. Köser. Semihierarchical Reconstruction and Weak-area Revisiting for Robotic Visual Seafloor Mapping. In *Journal of Field Robotics*
 - **M. She**, T. Weiß, Y. Song, P. Urban, J. Greinert, K. Köser. Marine Bubble Flow Quantification Using Wide-baseline Stereo Photogrammetry. In *ISPRS Photogrammetry and Remote Sensing*
- **M. She**, D. Nakath, Y.Song, K. Köser. Refractive Geometry on Underwater Domes. In *ISPRS Photogrammetry and Remote Sensing*
- X. Weng*, **M. She***, D. Nakath, K. Köser (**Equal Contribution*). Macal Macro Lens Calibration and the Focus Stack Camera Model. In *3DV*, *2021* (**Oral**)
- **M. She**, Y. Song, J Mohrmann, K. Köser. Adjustment and Calibration of Dome Port Camera Systems for Underwater Vision. In *GCPR*, *2019* (**Oral**)

AWARDS & SCHOLARSHIPS

Doctoral scholarship granted by China Scholarship Council (CSC)

2020 - 2024

Travel grant for young researchers by Deutsche Arbeitsgemeinschaft für Mustererkennung, DAGM 2019

SKILLS

 Computer Vision, Machine Learning, Imaging, Optimization, C++, Python, PyTorch, Ceres-Solver, Linux

REFERENCES

■ Prof. Dr. -Ing. Kevin Köser

Professor of Computer Science Marine Data Science Group

Christian-Albrechts-Universität zu Kiel

Alexander-Behm-Haus - EG.011, Neufeldtstraße 6, Kiel, Germany

Email: kk@informatik.uni-kiel.de

■ Dr. David Nakath

Postdoc at the Marine Data Science Group Christian-Albrechts-Universität zu Kiel Alexander-Behm-Haus, Neufeldtstraße 6, Kiel, Germany

Email: dna@informatik.uni-kiel.de