

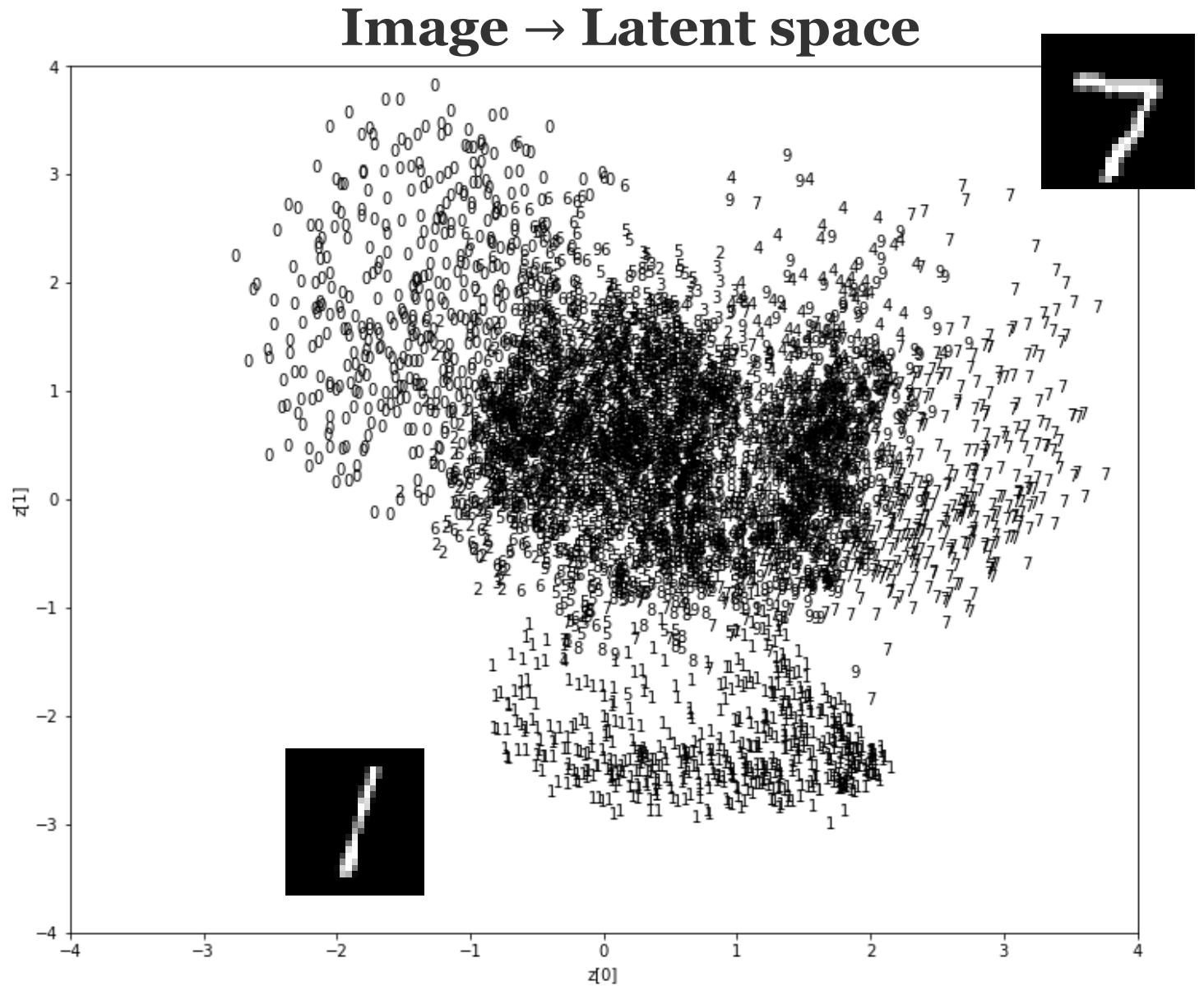
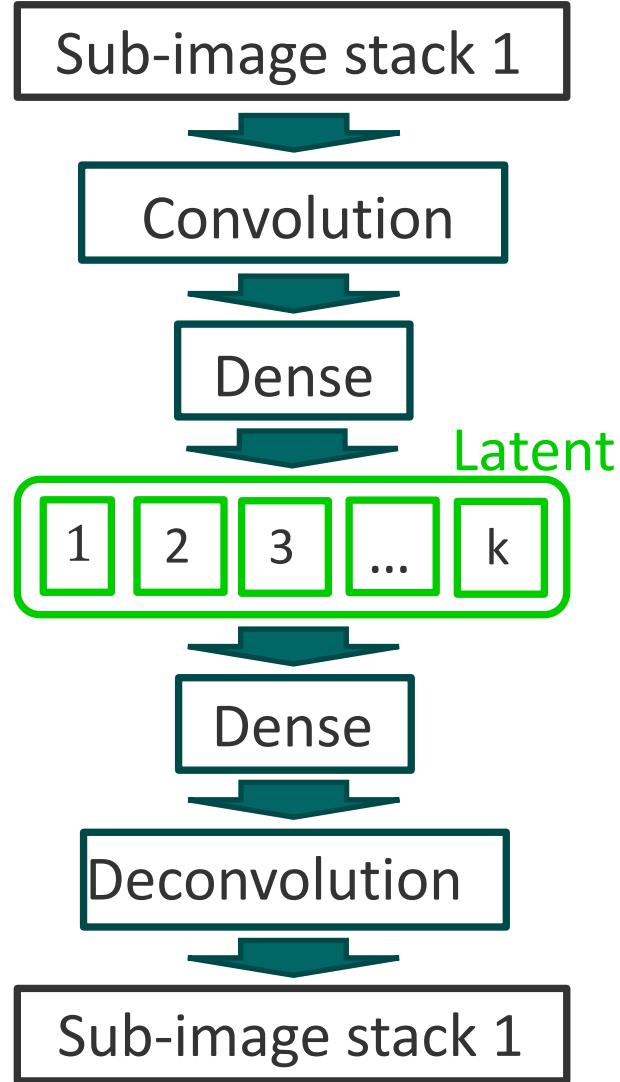
# Variational Autoencoders

Sergei V. Kalinin

# The VAE Story

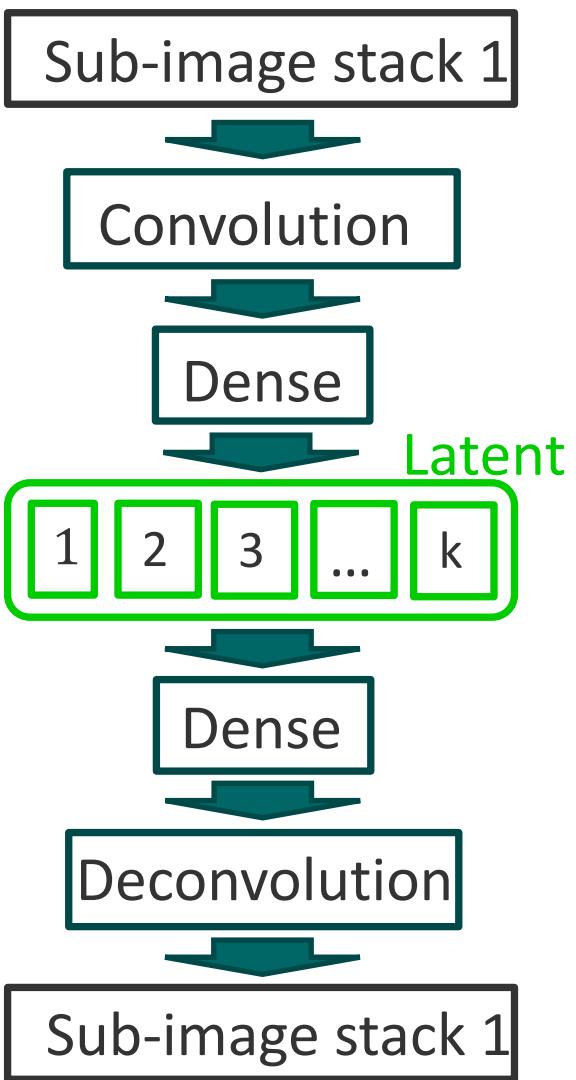
- What are (Variational) autoencoders?
  - Encoding and decoding
  - Latent distribution
  - Latent representations
  - Disentanglement of the representations
- Why invariances: rotational, translational, and shear
- Other colors of VAEs:
  - Semi-supervised
  - Conditional
  - Joint
- VAEs for real-world examples
- From VAEs to encoder-decoders (VED)
- BO in the latent space
- Active learning: DKL

# Autoencoders: Encoding

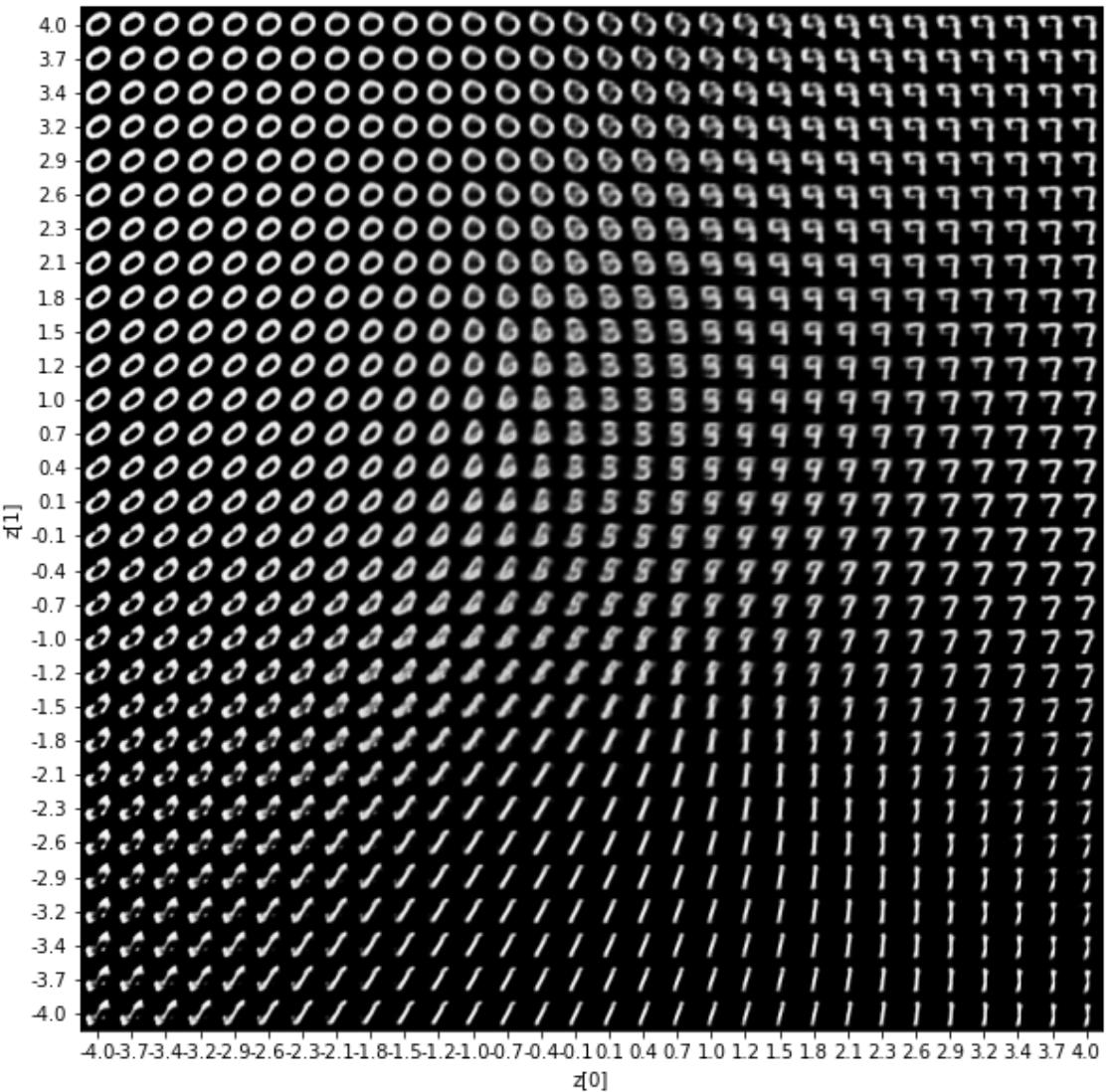


**Latent distribution:** Encoding the data via low dimensional vector

# Autoencoders: Decoding



**Latent space → Image**



**Latent representation:** Decoding images from uniform grid in latent space

# AE and Variational AE (VAE)



Geoffrey Hinton

FOLLOW

Emeritus Prof. Comp Sci, U.Toronto & Engineering Fellow, Google

Verified email at cs.toronto.edu - [Homepage](#)

machine learning psychology artificial intelligence cognitive science computer science

TITLE	CITED BY	YEAR
<a href="#">Imagenet classification with deep convolutional neural networks</a> A Krizhevsky, I Sutskever, GE Hinton Communications of the ACM 60 (6), 84-90	130318	2017
<a href="#">Deep learning</a> Y LeCun, Y Bengio, G Hinton Nature 521 (7553), 436-44	62790	2015
<a href="#">Dropout: a simple way to prevent neural networks from overfitting</a> N Srivastava, G Hinton, A Krizhevsky, I Sutskever, R Salakhutdinov The journal of machine learning research 15 (1), 1929-1958	42078	2014
<a href="#">Visualizing data using t-SNE</a> L van der Maaten, G Hinton Journal of Machine Learning Research 9 (Nov), 2579-2605	35035	2008
<a href="#">Learning representations by back-propagating errors</a> DE Rumelhart, GE Hinton, RJ Williams Nature 323 (6088), 533-536	32239	1986
<a href="#">Learning internal representations by error-propagation</a> DE Rumelhart, GE Hinton, RJ Williams Parallel Distributed Processing: Explorations in the Microstructure of ...	30711	1986
<a href="#">Schemata and sequential thought processes in PDP models.</a> D Rumelhart, P Smolenksy, J McClelland, G Hinton Parallel distributed processing: Explorations in the microstructure of ...	28073 *	1986
<a href="#">Learning multiple layers of features from tiny images</a> A Krizhevsky, G Hinton	21876	2009
<a href="#">Rectified linear units improve restricted boltzmann machines</a> V Nair, GE Hinton Proceedings of the 27th international conference on machine learning (ICML ...	21050	2010
<a href="#">Reducing the dimensionality of data with neural networks</a> GE Hinton, RR Salakhutdinov Science 313 (5786), 504-507	19930	2006

## Reducing the dimensionality of data with neural networks

Authors Geoffrey E Hinton, Ruslan R Salakhutdinov

Publication date 2006/7/28

Journal Science

Volume 313

Issue 5786

Pages 504-507

Publisher American Association for the Advancement of Science

Description High-dimensional data can be converted to low-dimensional codes by training a multilayer neural network with a small central layer to reconstruct high-dimensional input vectors. Gradient descent can be used for fine-tuning the weights in such "autoencoder" networks, but this works well only if the initial weights are close to a good solution. We describe an effective way of initializing the weights that allows deep autoencoder networks to learn low-dimensional codes that work much better than principal components analysis as a tool to reduce the dimensionality of data.

Total citations Cited by 19930



# Denoising



- **Training:** pairs of the high-noise and low-noise images
- **Application:** new high noise images (from the same distribution)
- **Concern:** has to be from the same distribution

# Restoration

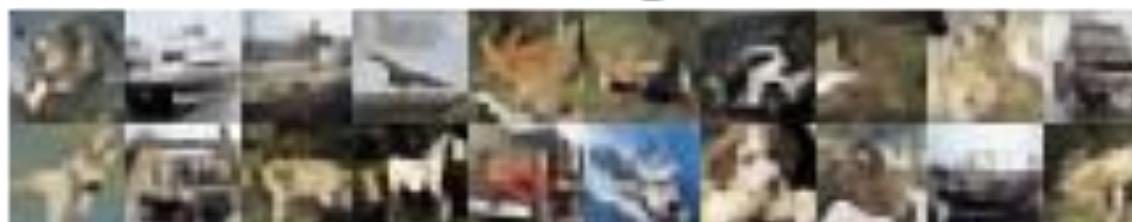
Test color images (Ground Truth)



Test gray images (Input)



Colorized test images (Predicted)



- **Training:** pairs of the grayscale and color images
- **Application:** new grayscale images (from the same distribution)
- **Concern:** has to be from the same distribution

# AE and Variational AE (VAE)



Diederik P. Kingma

Other names ▾

 FOLLOW

Research Scientist, [Google Brain](#)  
Verified email at google.com - [Homepage](#)

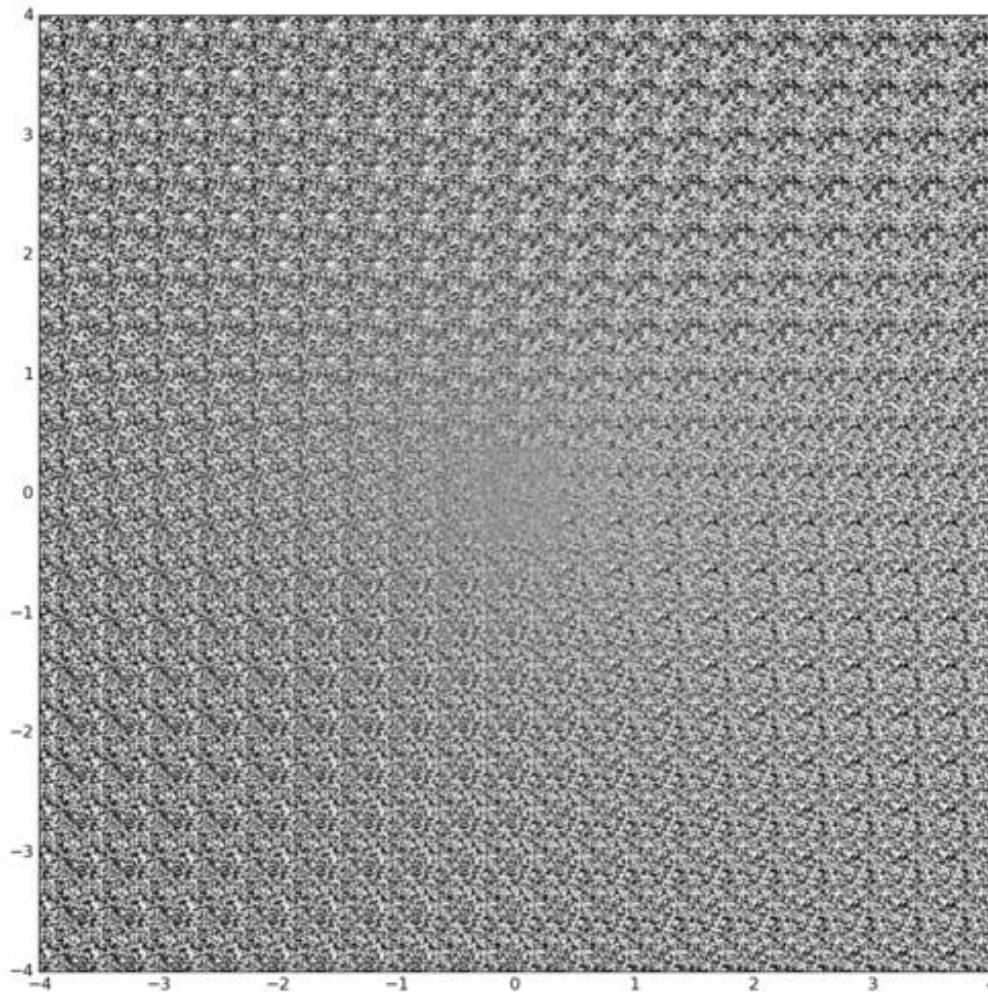
Machine Learning Deep Learning Neural Networks Generative Models Variational Inference

TITLE	CITED BY	YEAR
<a href="#">Adam: A Method for Stochastic Optimization</a> DP Kingma, J Ba Proceedings of the 3rd International Conference on Learning Representations ...	141306	2014
<a href="#">Auto-Encoding Variational Bayes</a> DP Kingma, M Welling arXiv preprint arXiv:1312.6114	26540	2013
<a href="#">Semi-Supervised Learning with Deep Generative Models</a> DP Kingma, S Mohamed, DJ Rezende, M Welling Advances in Neural Information Processing Systems, 3581-3589	2946	2014

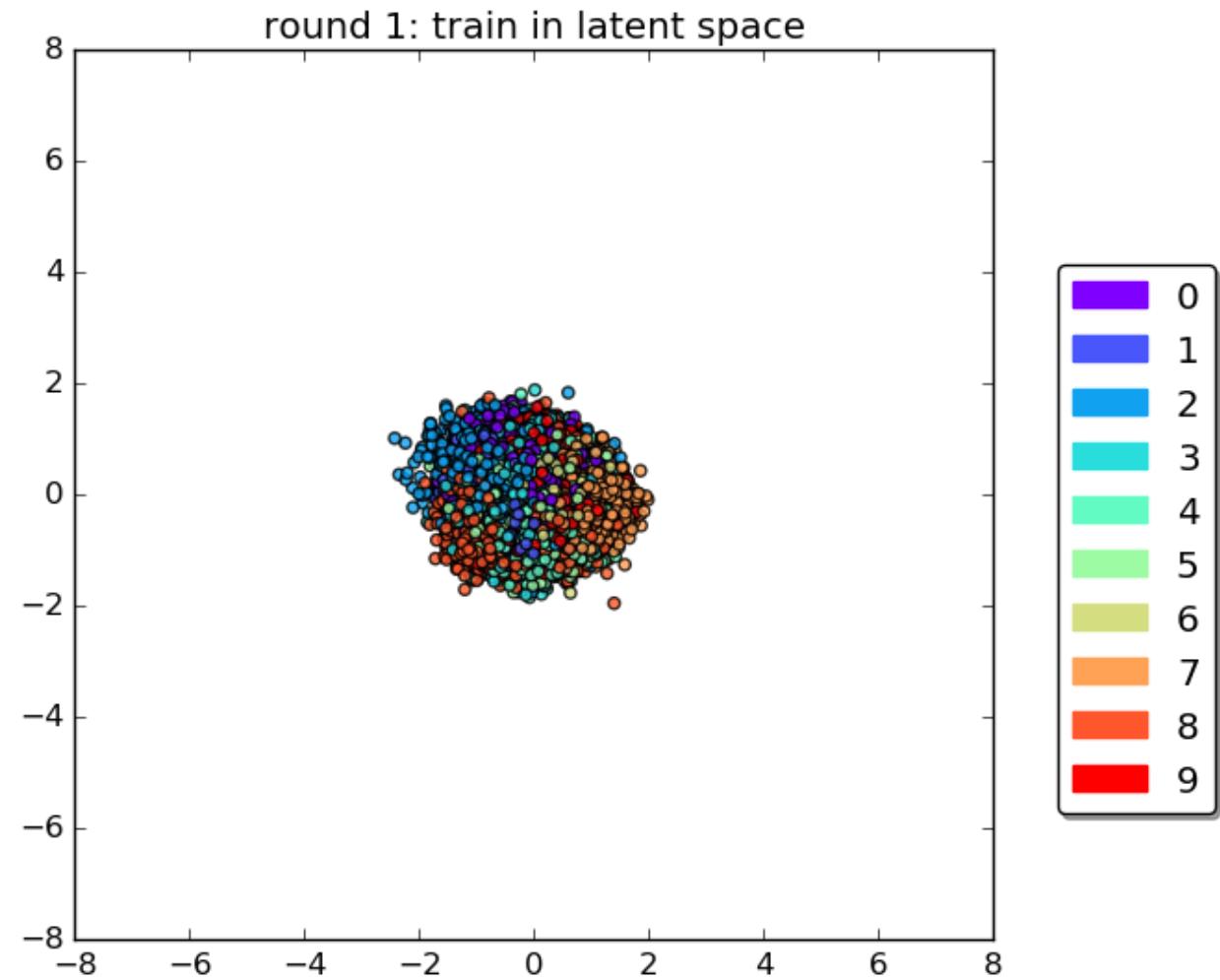
- Variational Autoencoder (VAE): uses “reparameterization trick” to sample from the latent space
- Can be used for same tasks as AE
- Have a much better-behaved latent space: **disentanglement of the representations**

# VAE Training

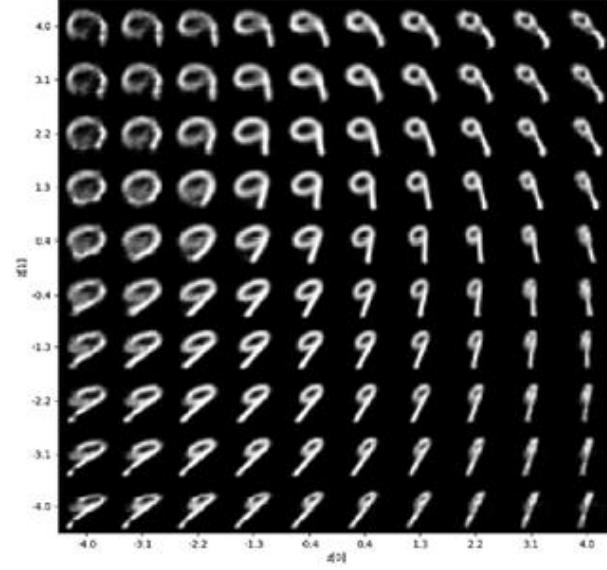
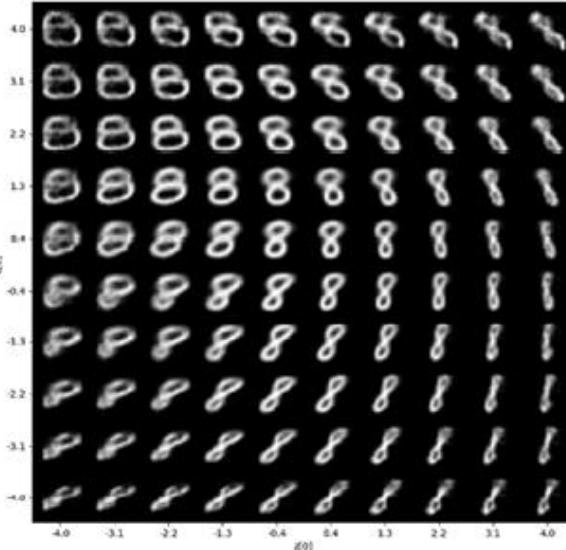
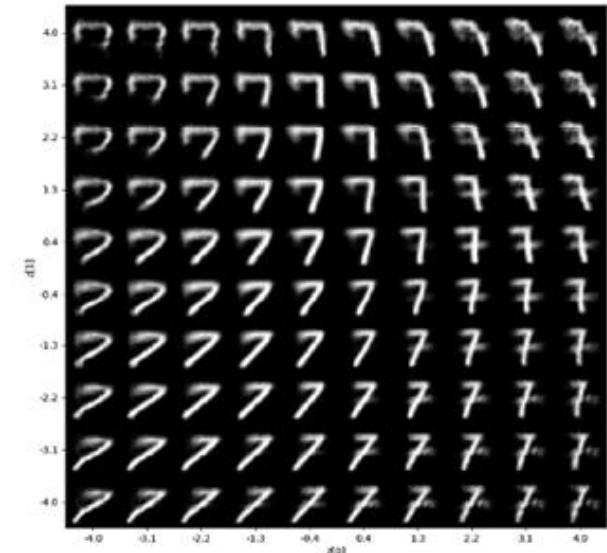
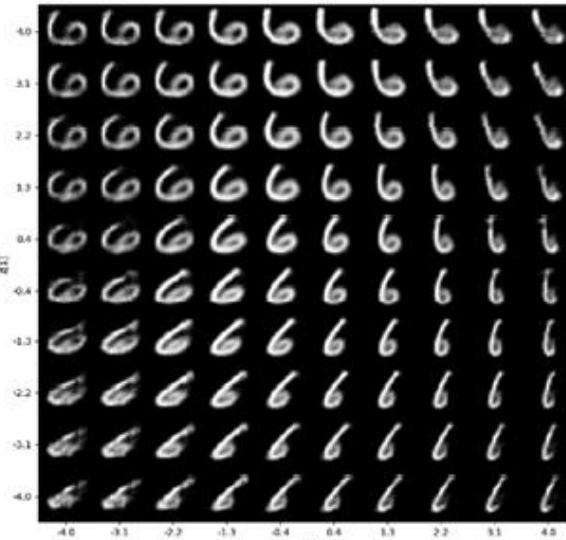
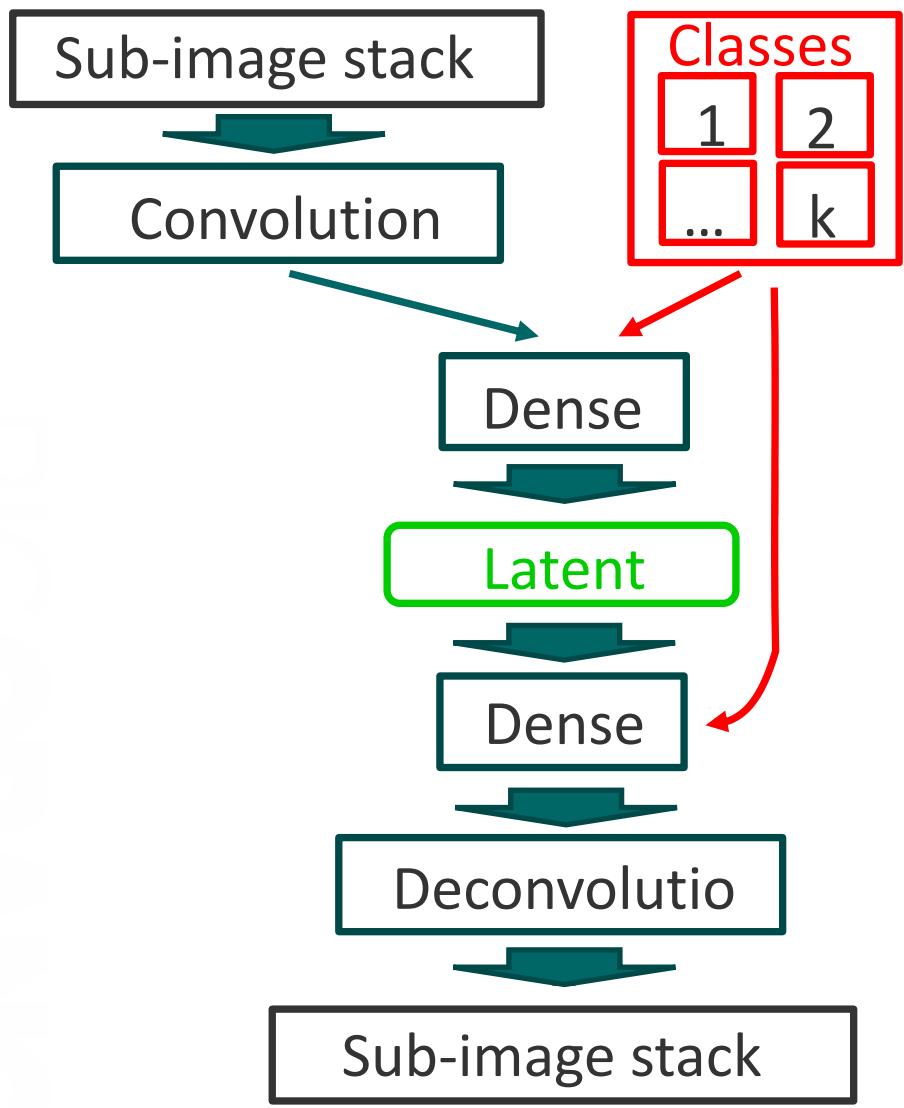
**Latent manifold -> Image space**



**Image space -> Latent space**



# Conditional VAE



Note the trends in the latent representation for each digit: **disentanglement of the representations**

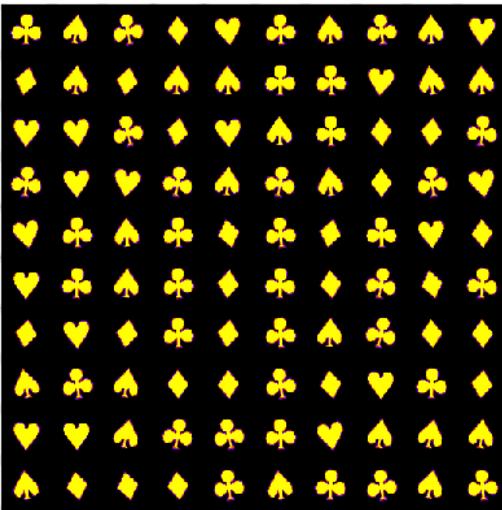
# (R)VAE on Cards

Introduce the **cards** data set:

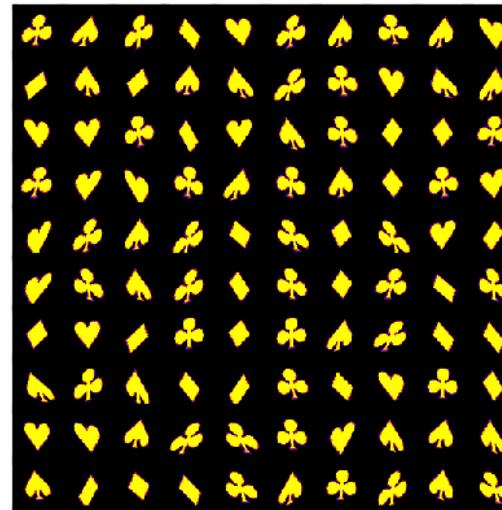
- Classical 4 hands (diamonds, clubs, pikes, hearts)
- Interesting similarities (pires and hearts)
- And invariances on affine transforms (e.g. diamonds)



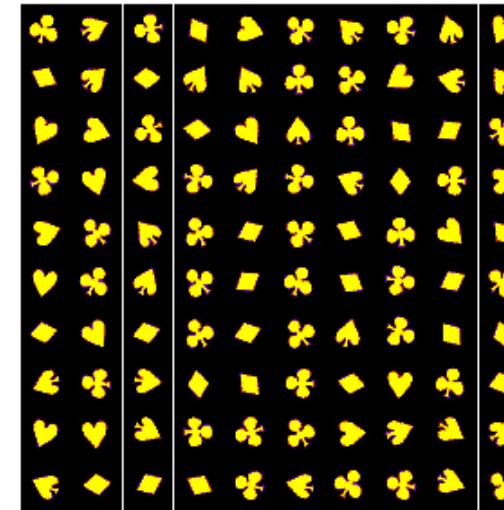
**Cards 1:** Low R (12 deg)  
and low S (1 deg)



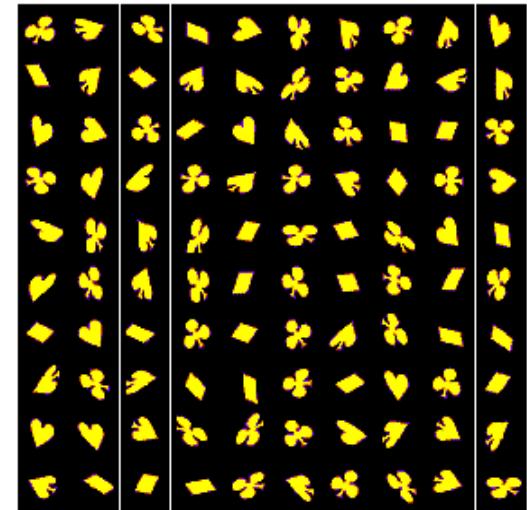
**Cards 2:** Low R (12 deg)  
and high S (20 deg)



**Cards 3:** High R (120  
deg) and Low S (1 deg)



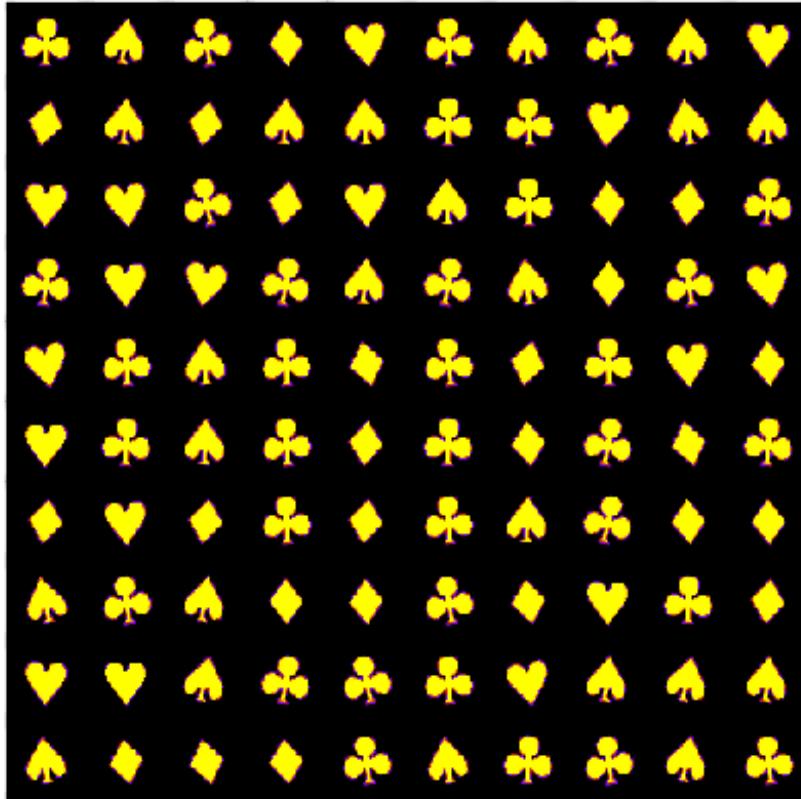
**Cards 4:** High R (120  
deg) and high S (20 deg)



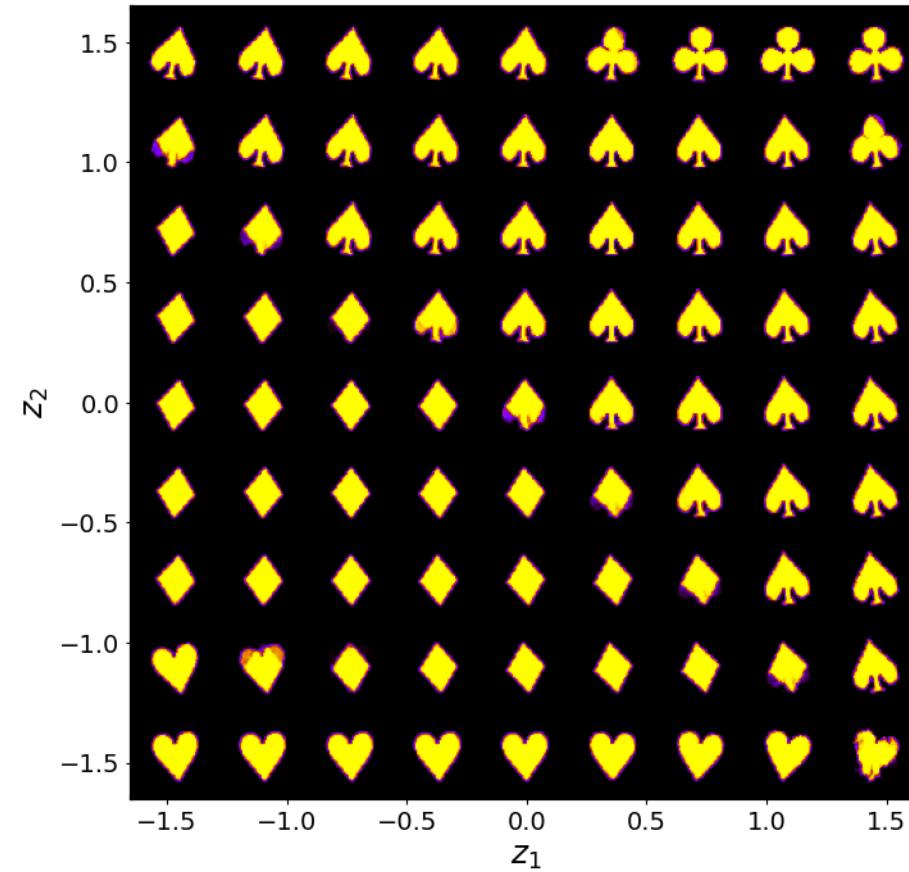
- Shear, rotations, and translations are **known** factors of variability (or traits) in data
- Can VAE disentangle representations and **discover** these factors of variability

# VAE on Cards

Example of data

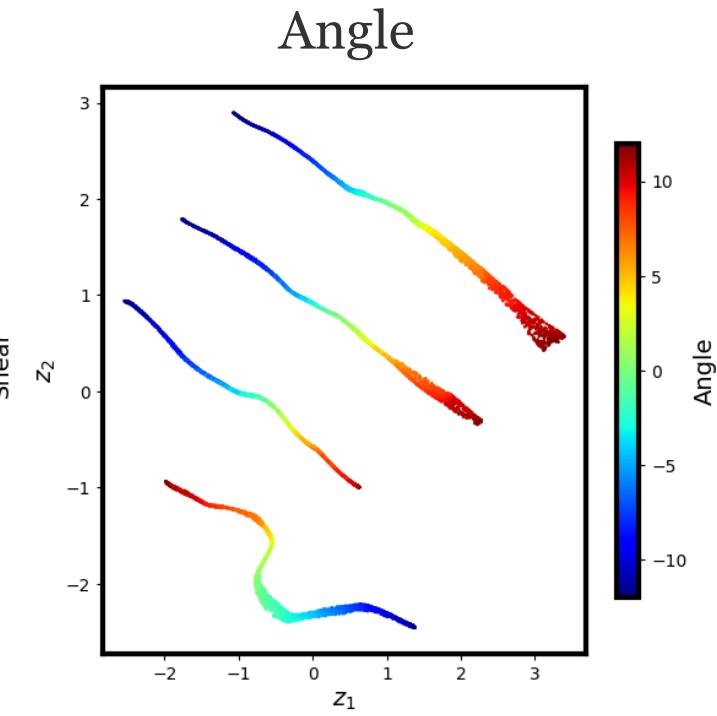
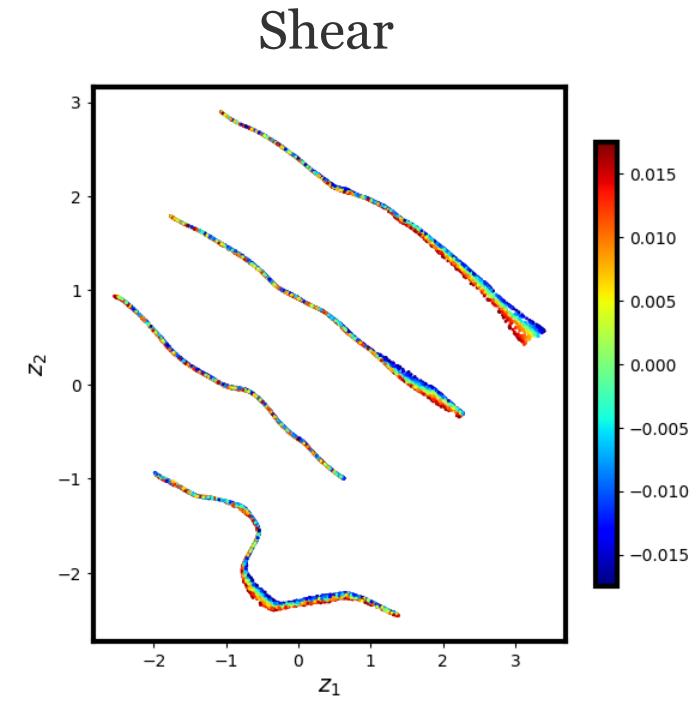
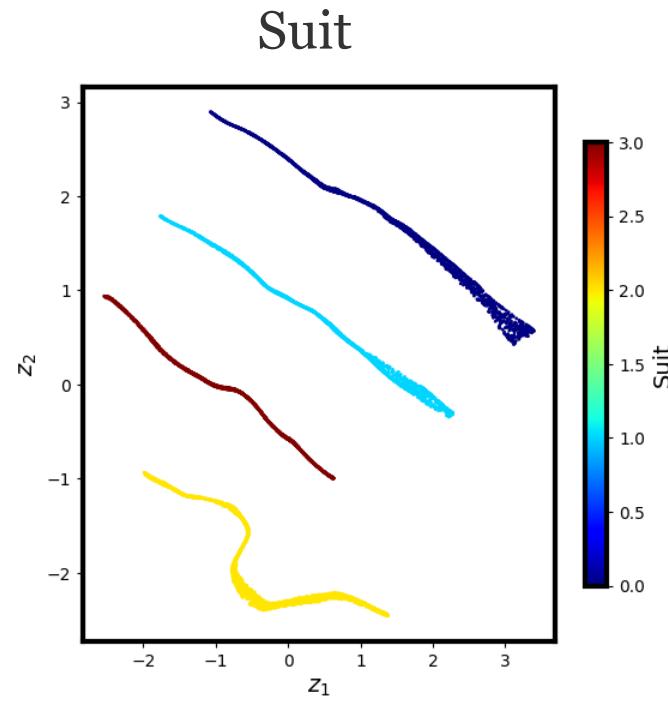


Latent representation



Cards 1: Low rotation (12 deg) and low shear (1 deg)

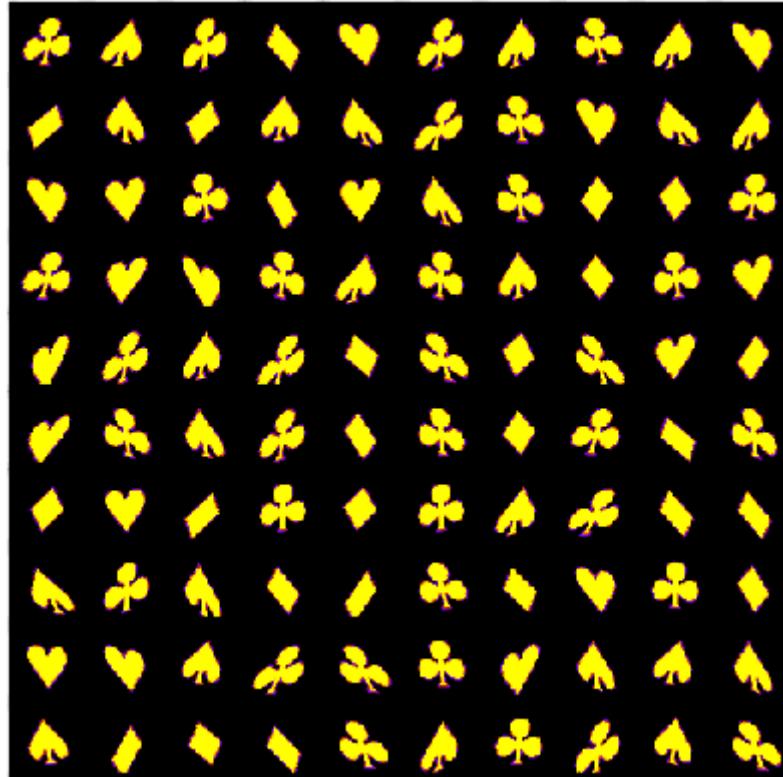
# VAE on Cards



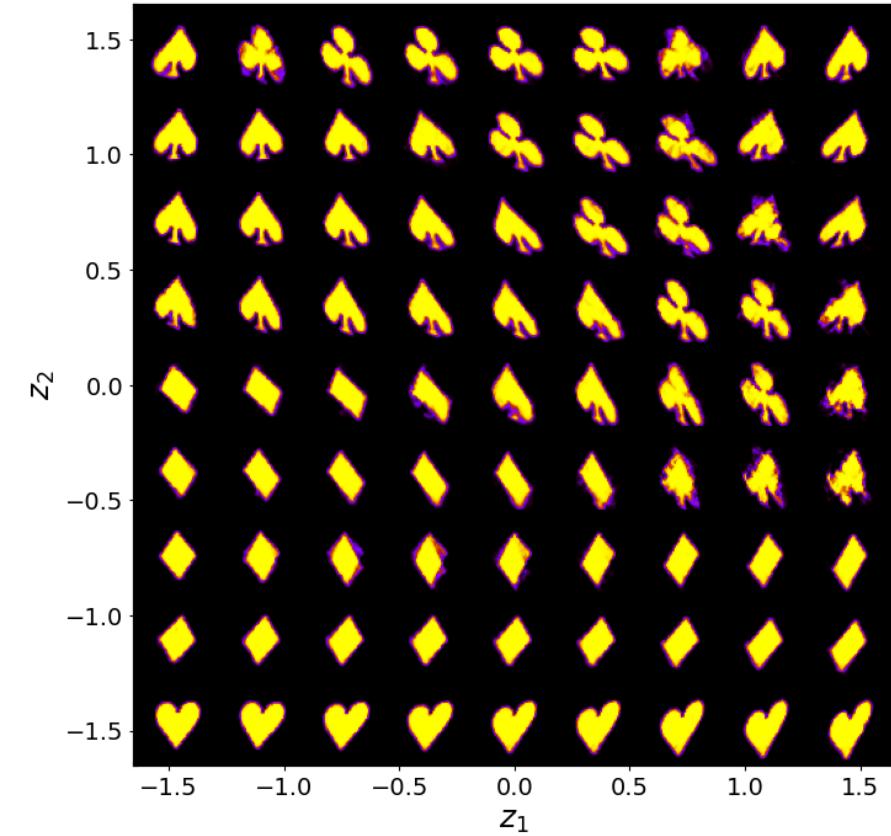
**Cards 1:** Low rotation (12 deg) and low shear (1 deg)

# VAE on Cards

Example of data

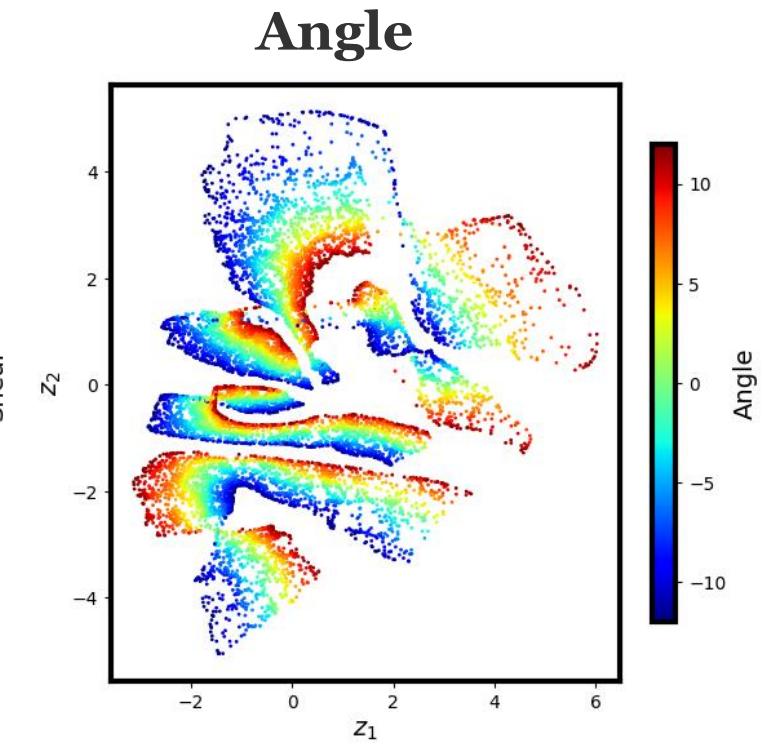
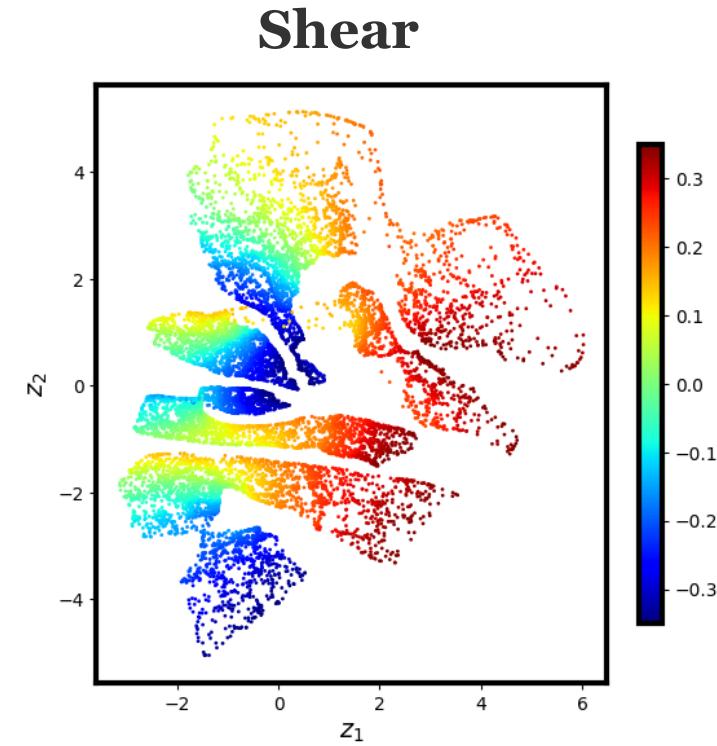
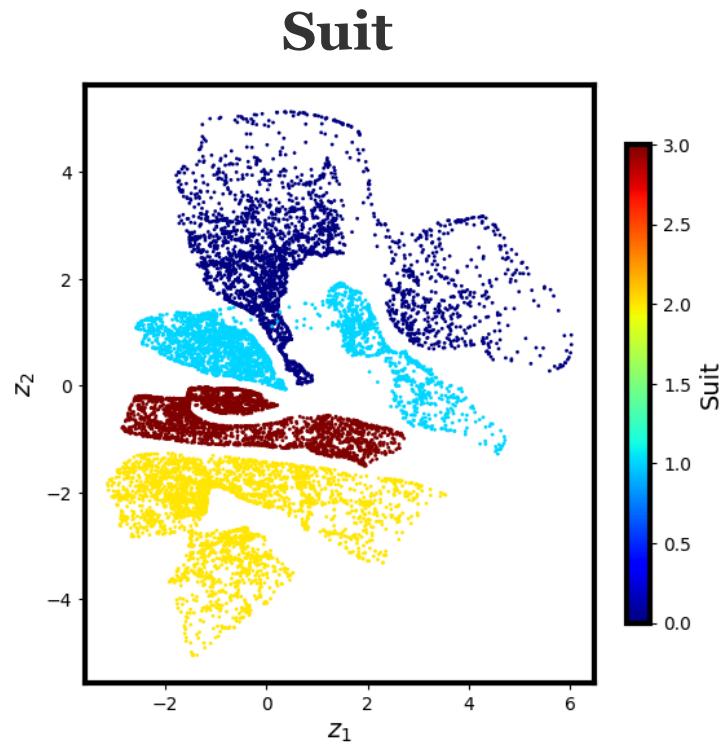


Latent representation



Cards 2: Low rotation (12 deg) and high shear (20 deg)

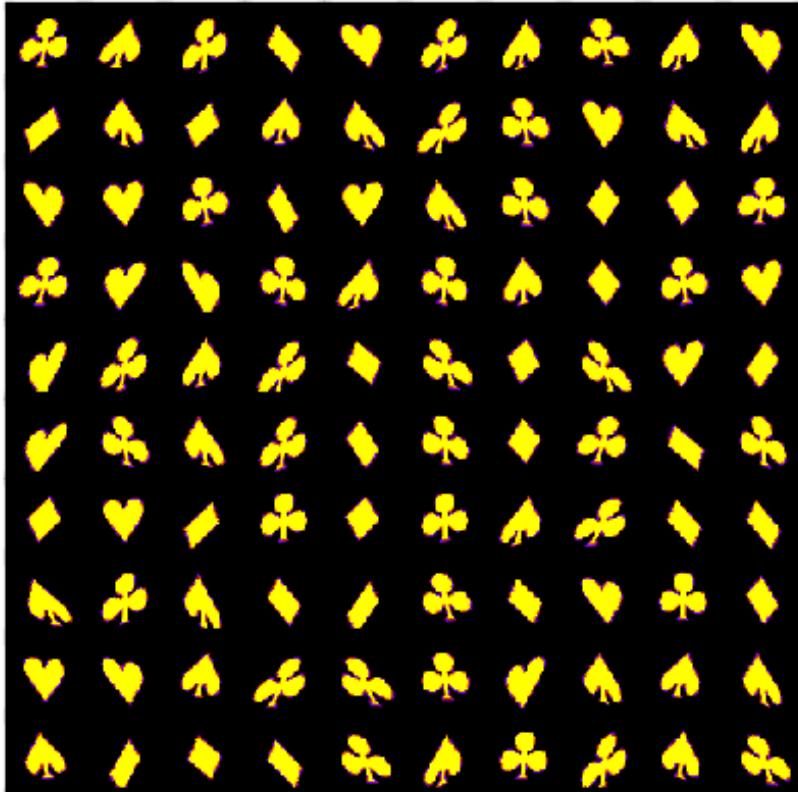
# VAE on Cards



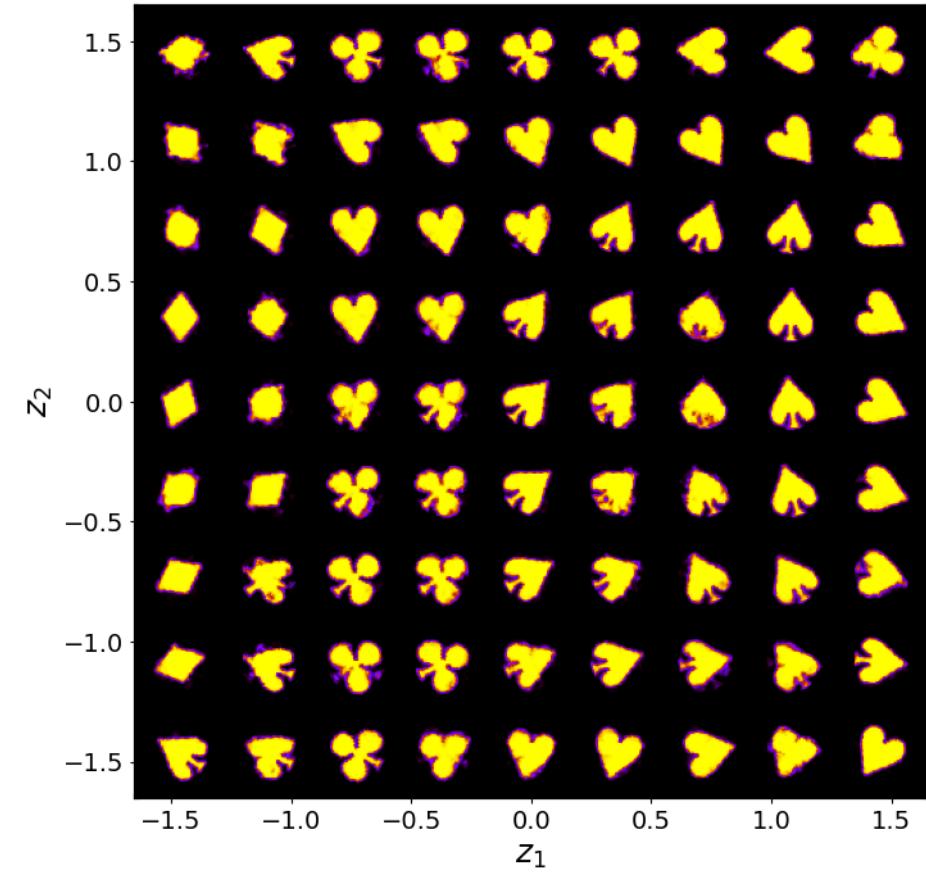
**Cards 2:** Low rotation (12 deg) and high shear (20 deg)

# VAE on Cards

Example of data

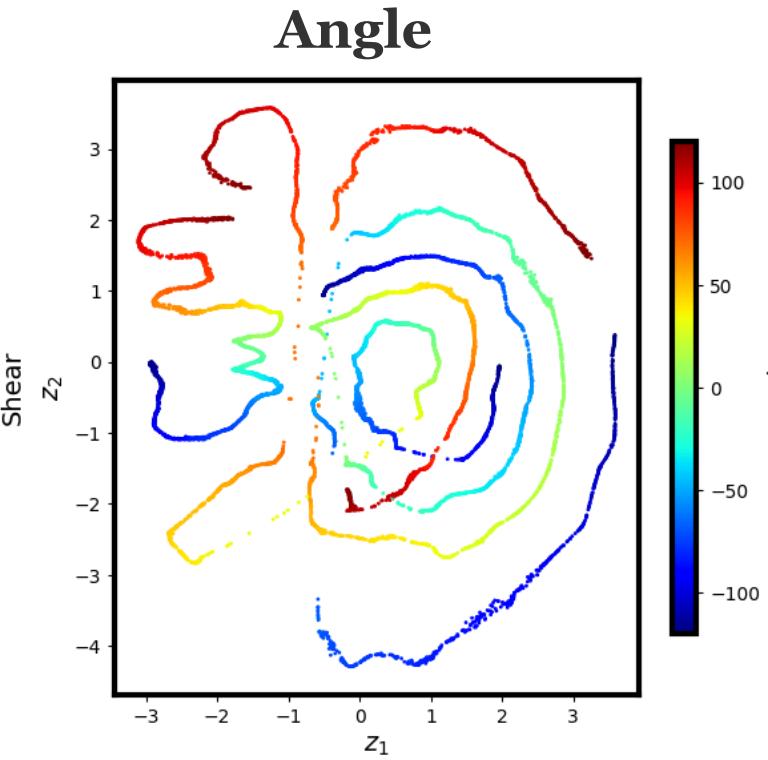
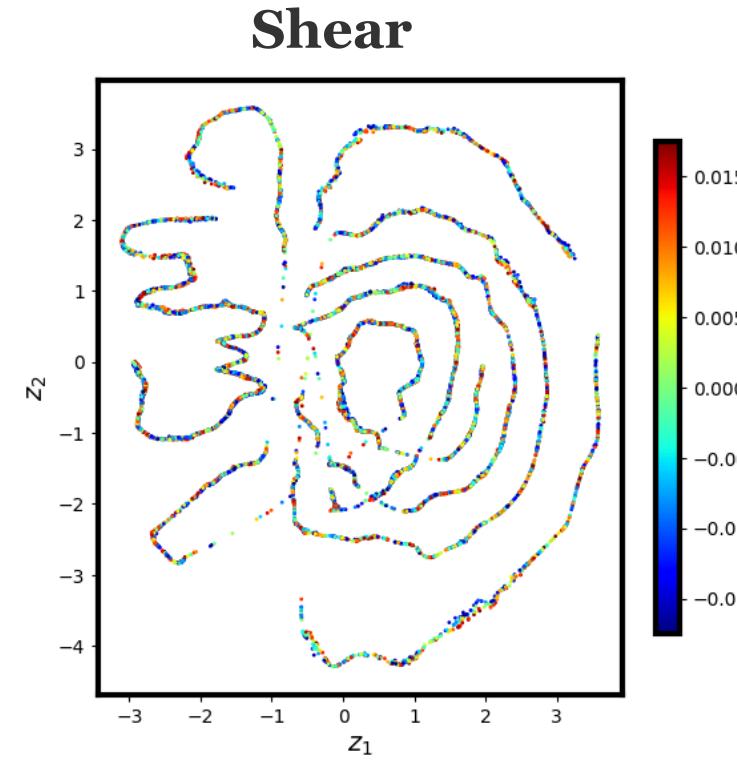
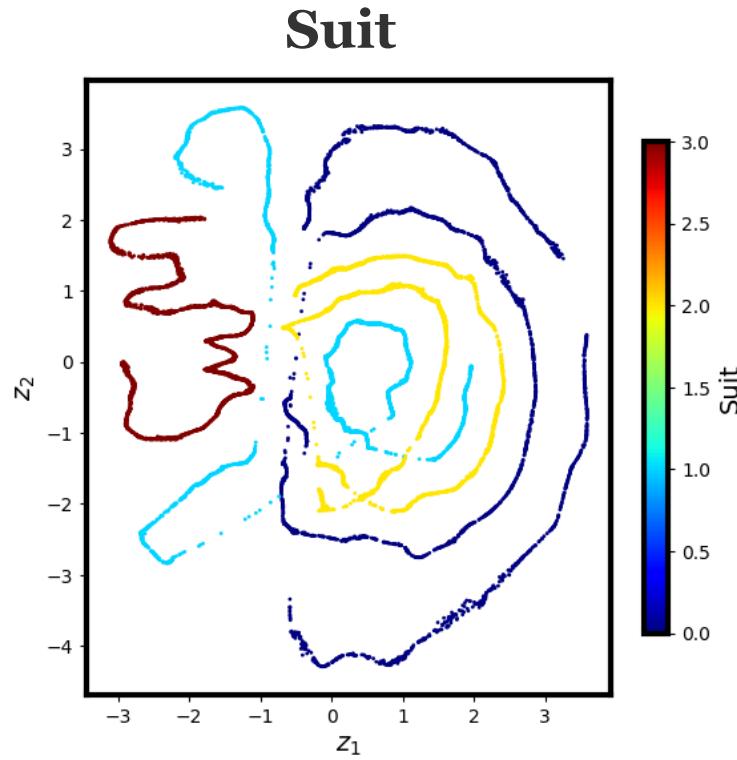


Latent representation



Cards 3: High rotation (120 deg) and low shear (1 deg)

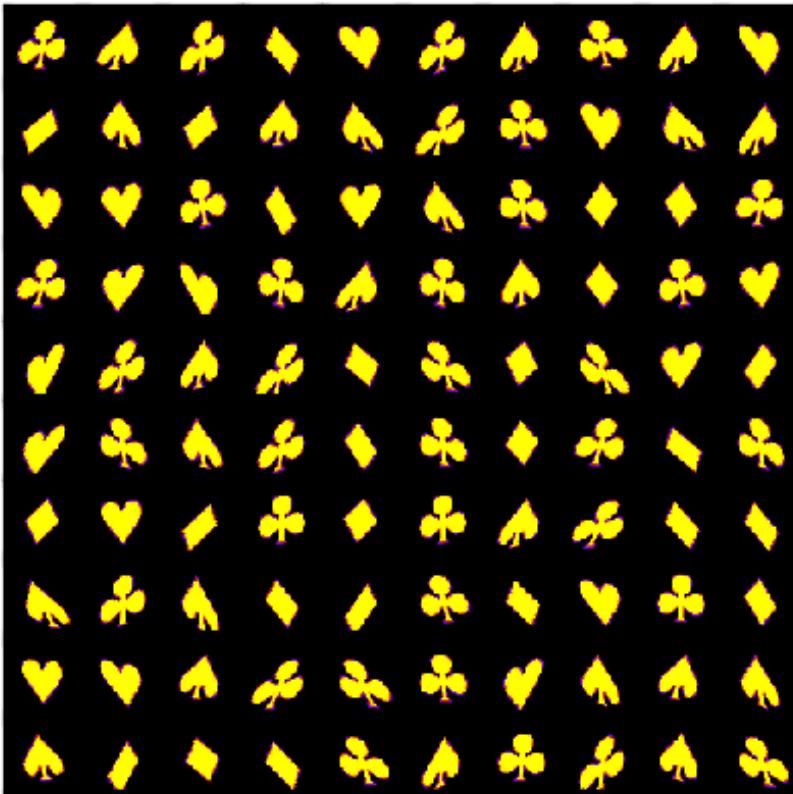
# VAE on Cards



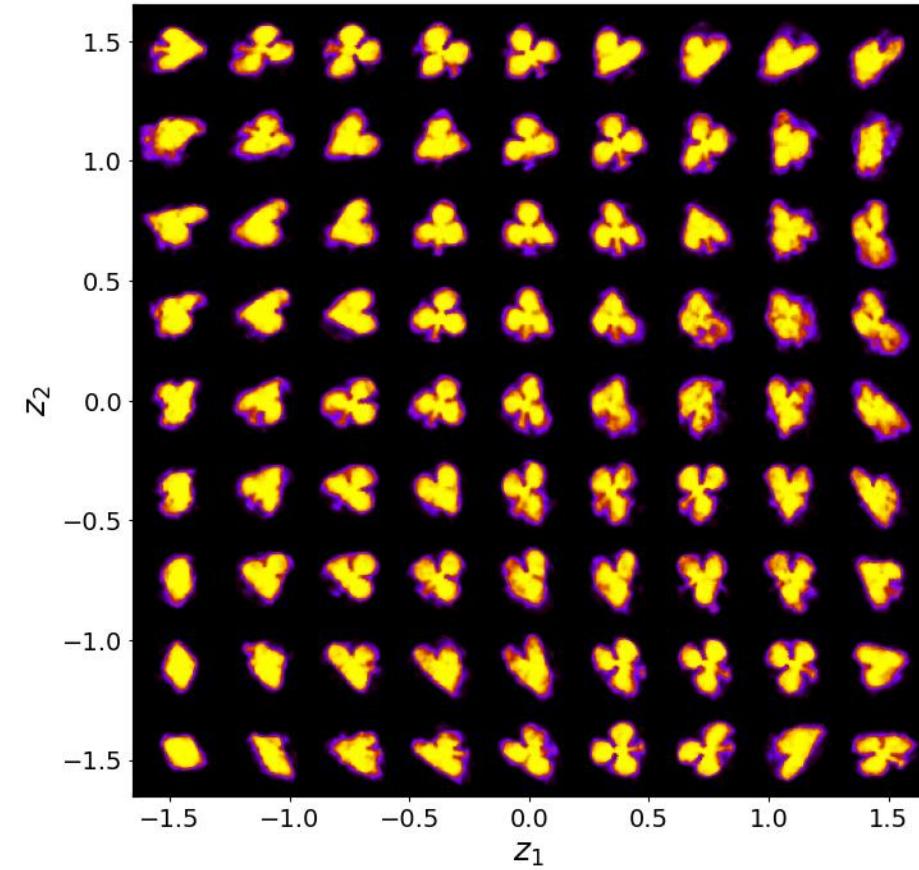
**Cards 3:** High rotation (120 deg) and low shear (1 deg)

# VAE on Cards

Example of data



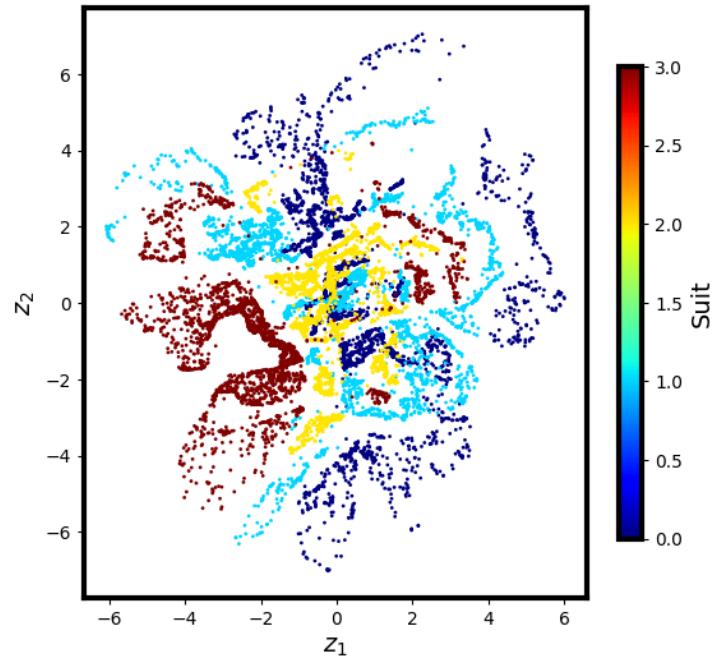
Latent representation



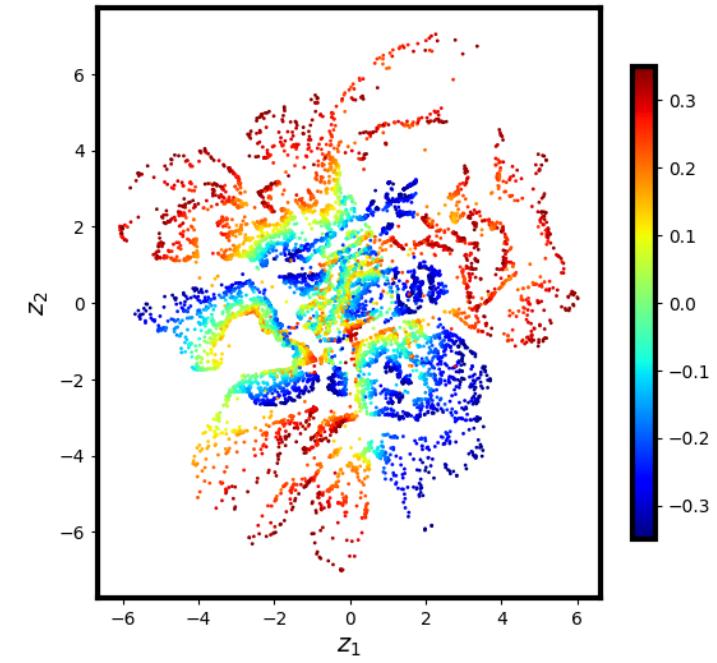
Cards 4: High rotation (120 deg) and high shear (20 deg)

# VAE on Cards

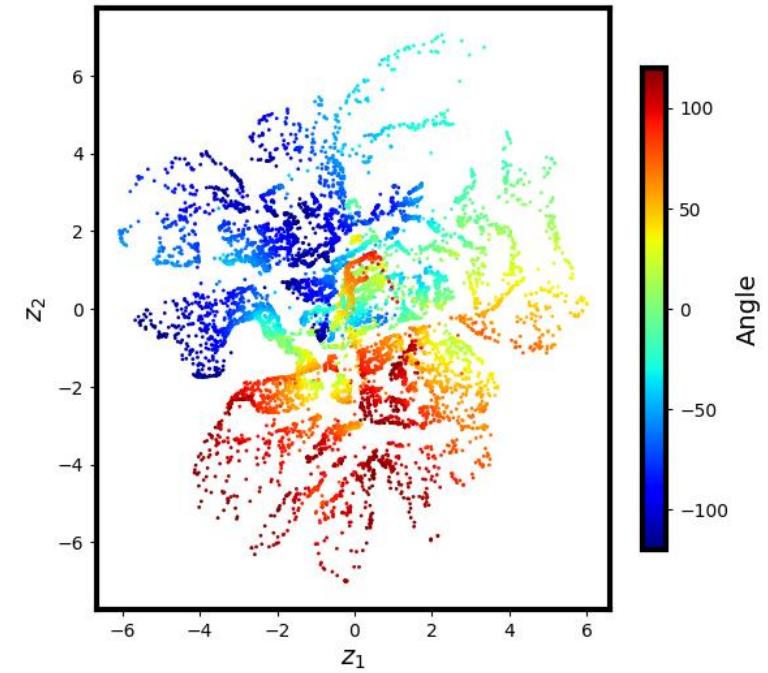
**Suit**



**Shear**



**Angle**



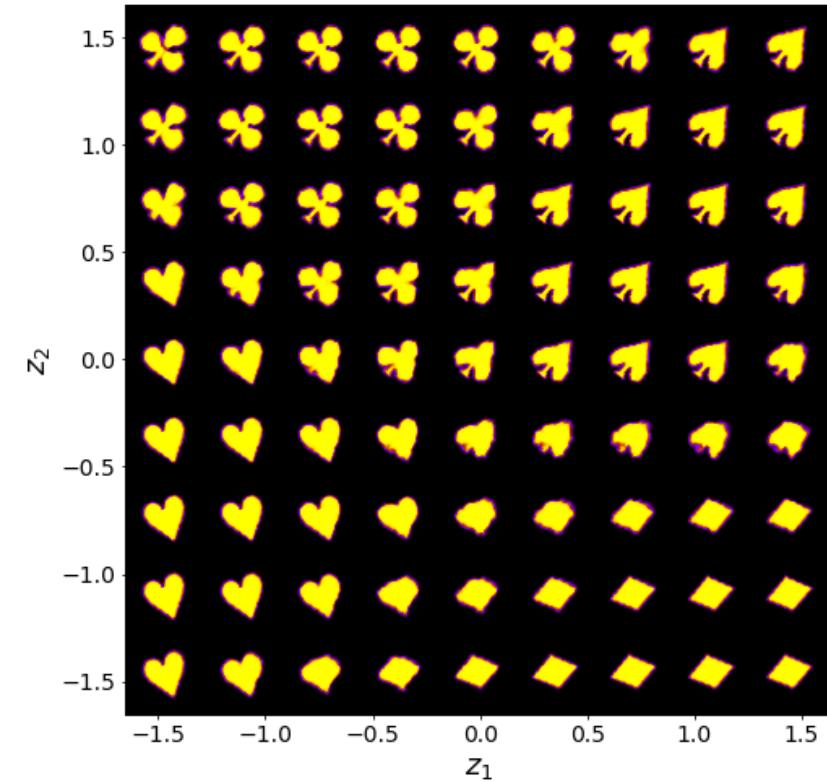
**Cards 4:** High rotation (120 deg) and high shear (20 deg)

# rVAE on Cards

Example of data

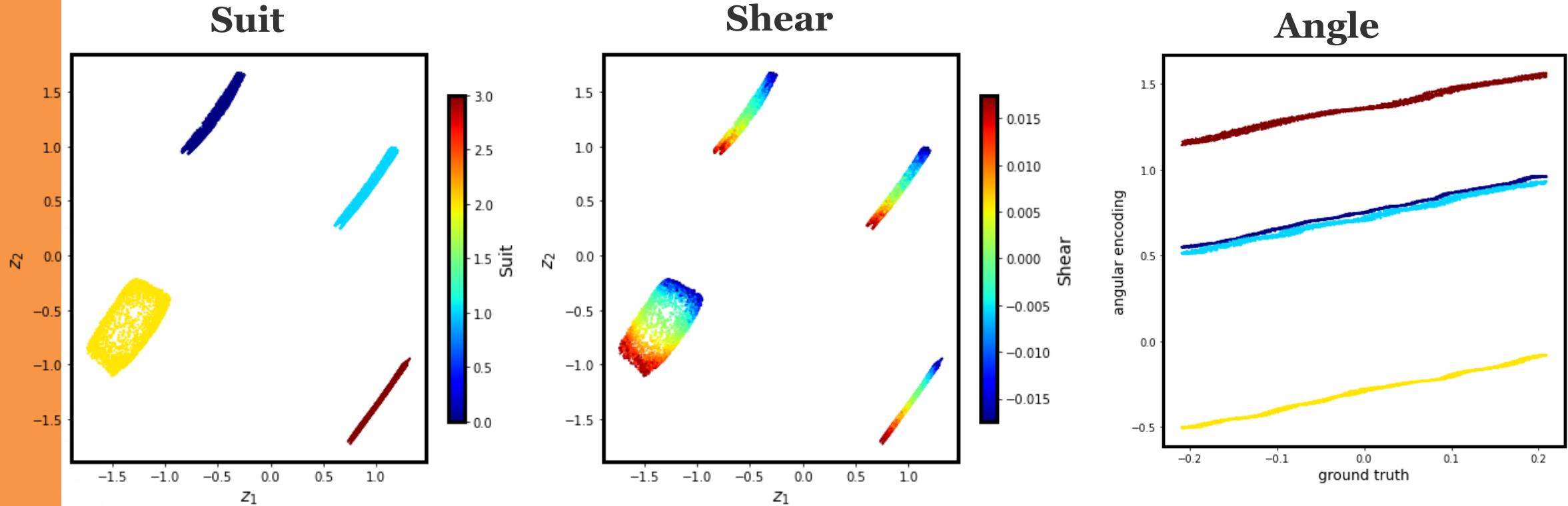


Latent representation



Cards 1: Low rotation (12 deg) and low shear (1 deg)

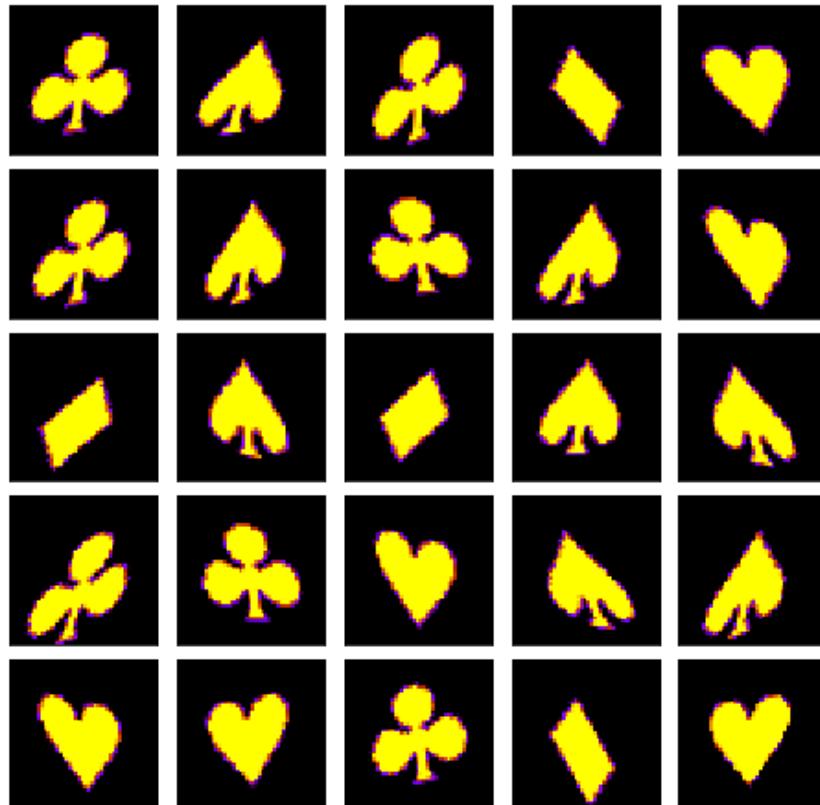
# rVAE on Cards



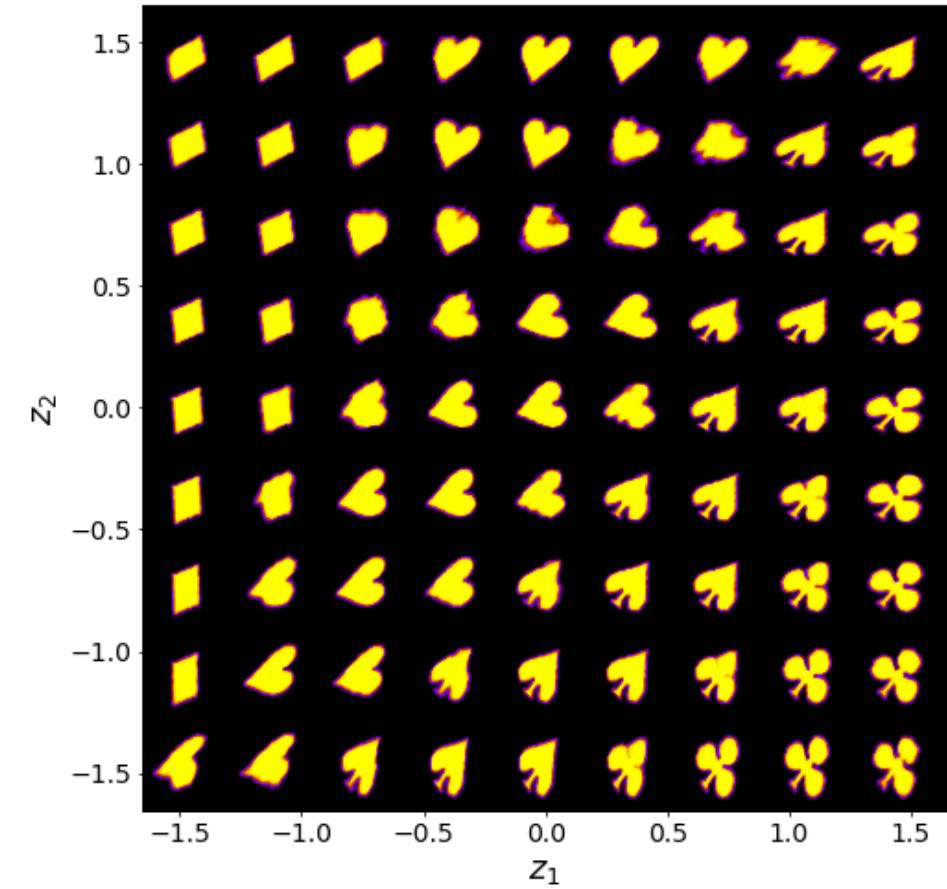
**Cards 1:** Low rotation (12 deg) and low shear (1 deg)

# rVAE on Cards

Example of data

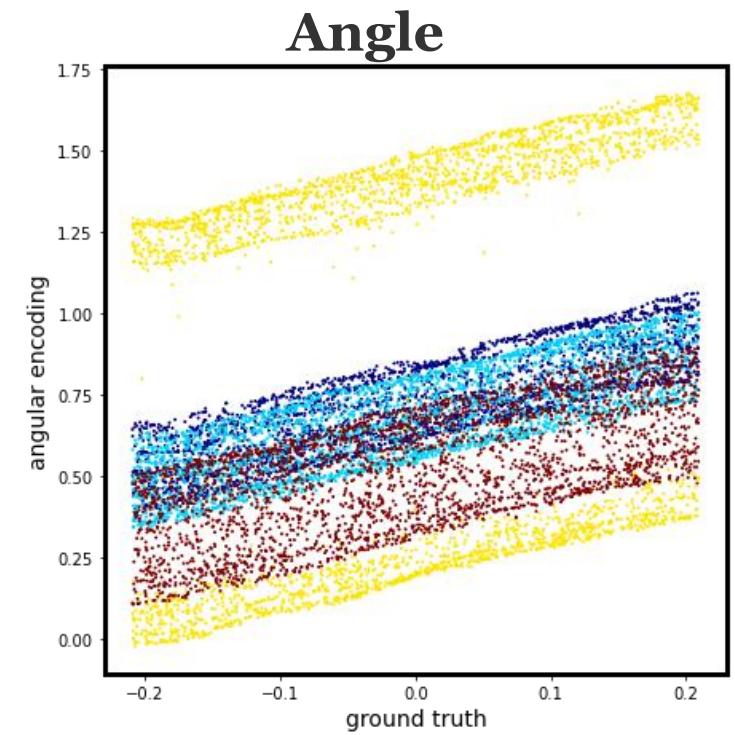
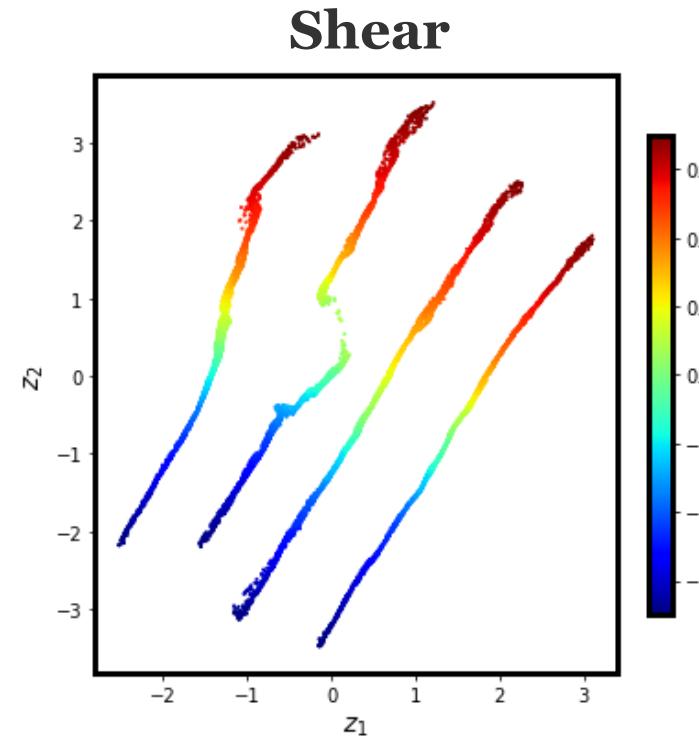
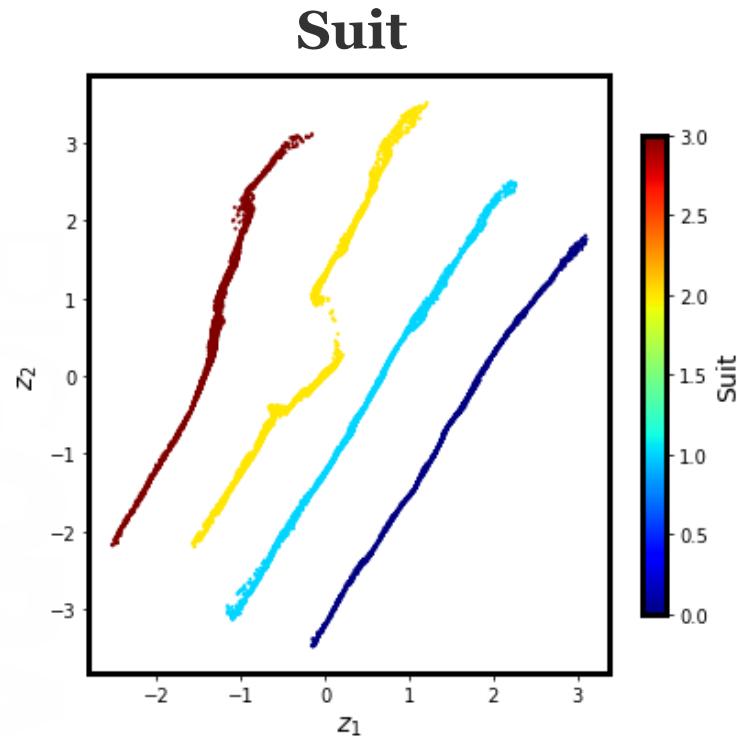


Latent representation



Cards 2: Low rotation (12 deg) and high shear (20 deg)

# rVAE on Cards



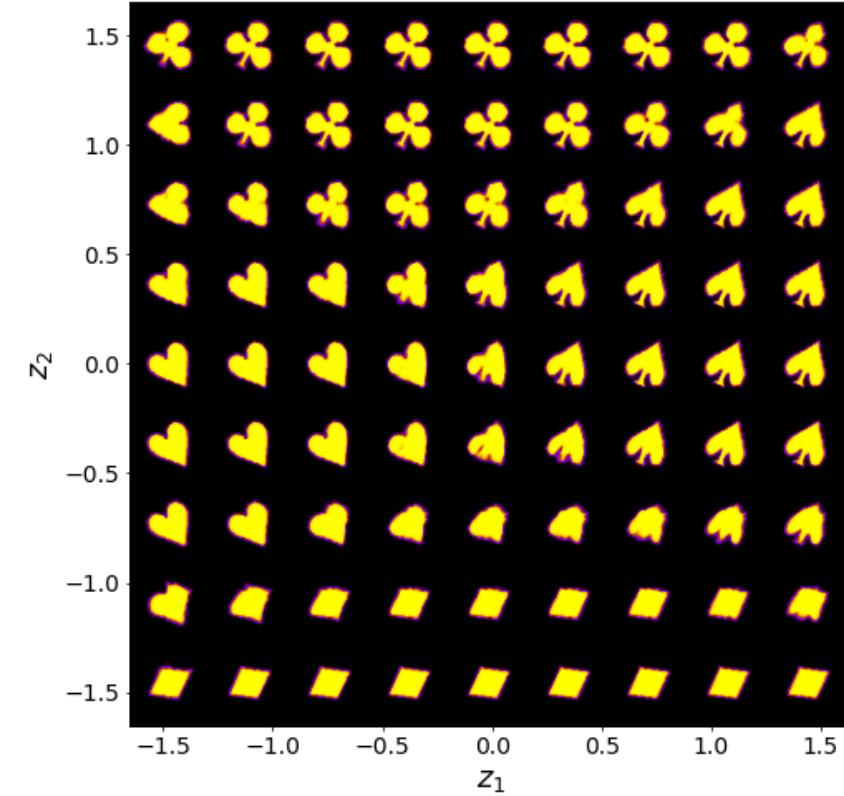
**Cards 2:** Low rotation (12 deg) and high shear (20 deg)

# rVAE on Cards

Example of data

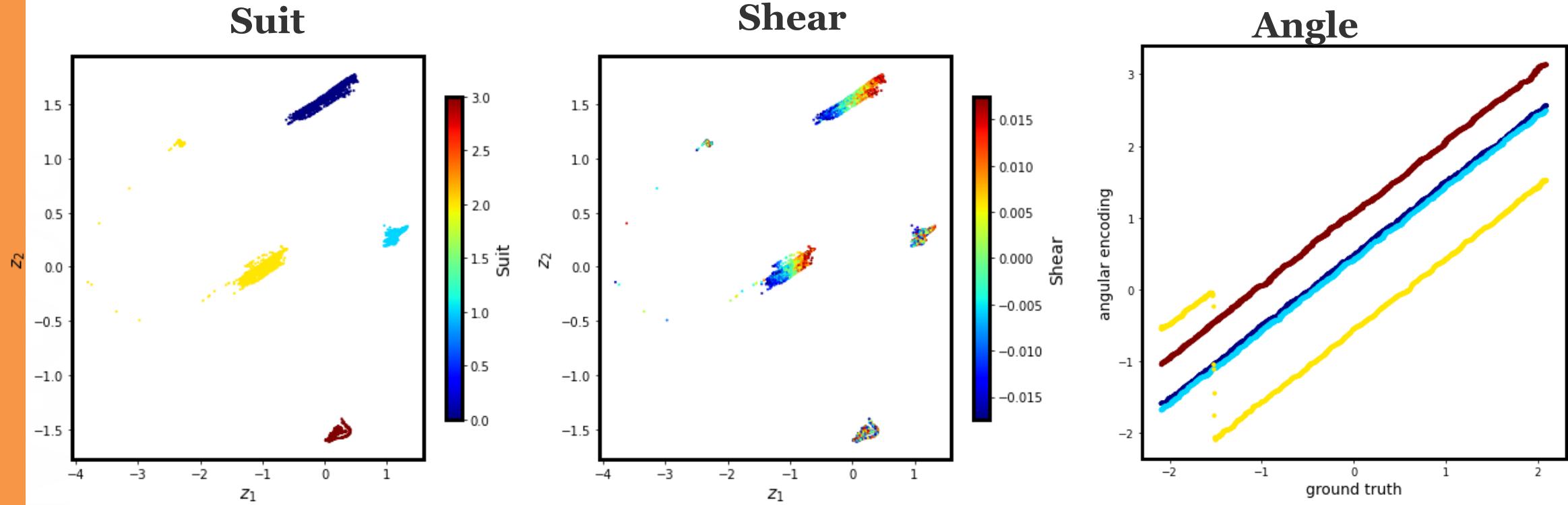


Latent representation



Cards 3: High rotation (120 deg) and low shear (1 deg)

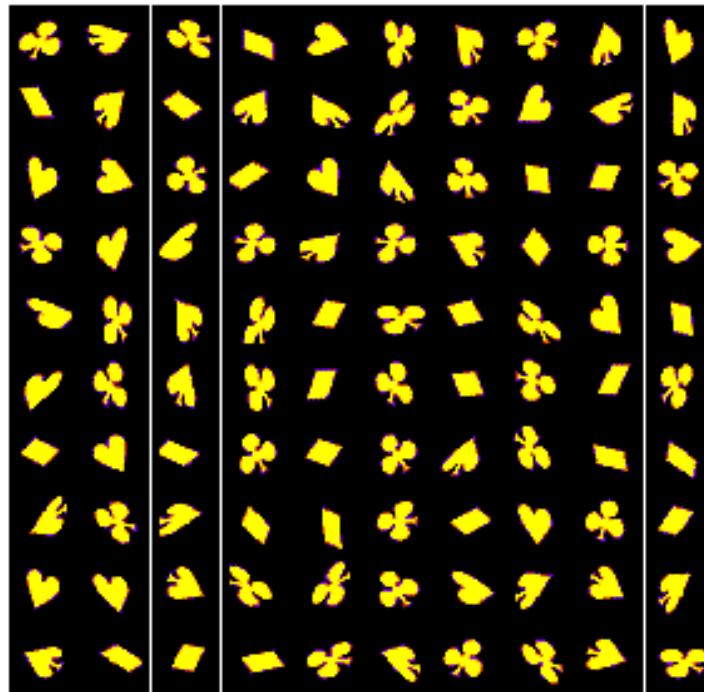
# rVAE on Cards



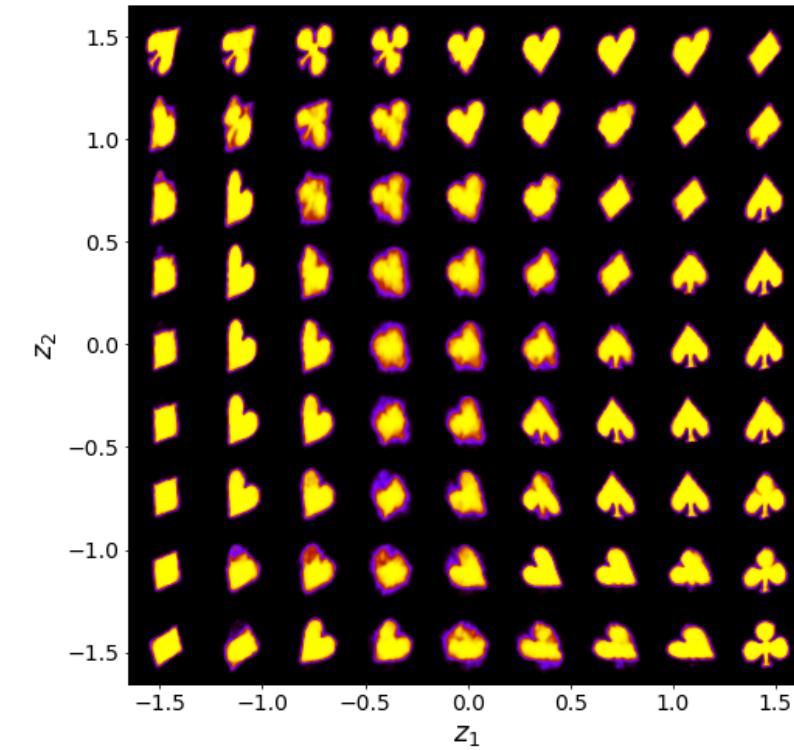
**Cards 3:** High rotation (120 deg) and low shear (1 deg)

# rVAE on Cards

Example of data



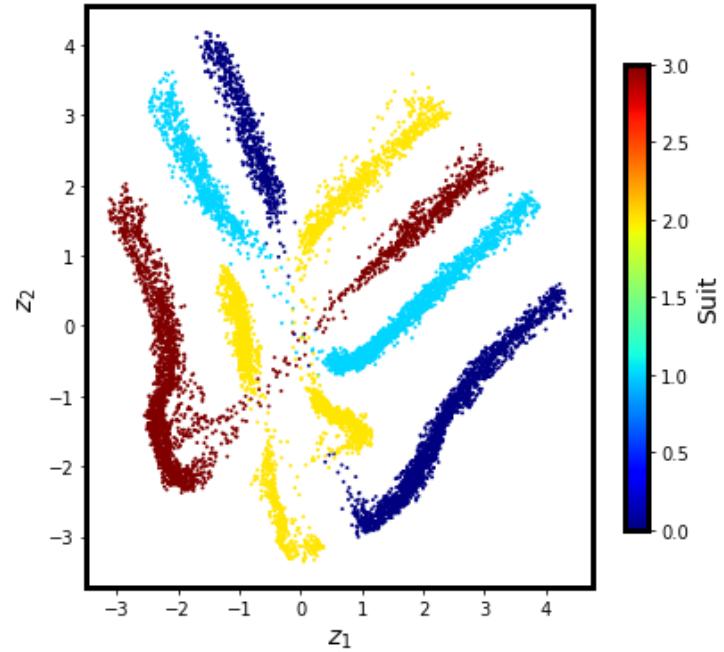
Latent representation



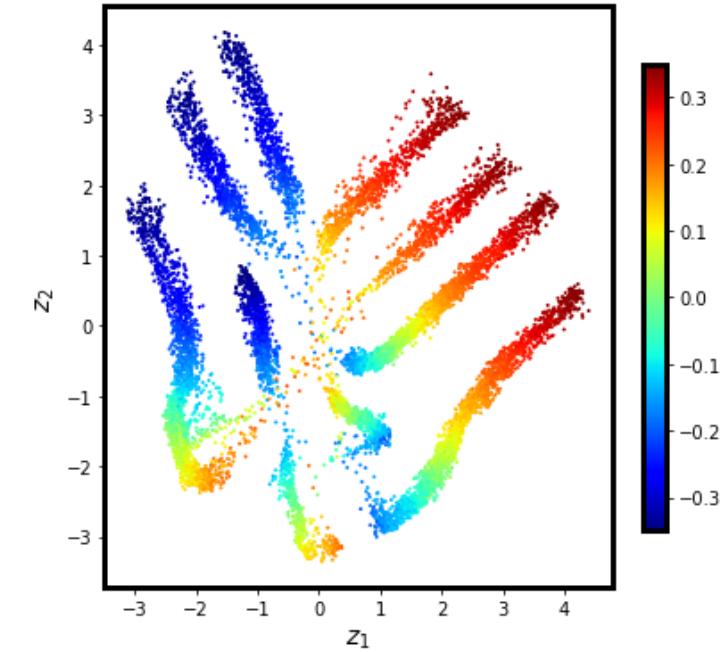
Cards 4: High rotation (120 deg) and high shear (20 deg)

# rVAE on Cards

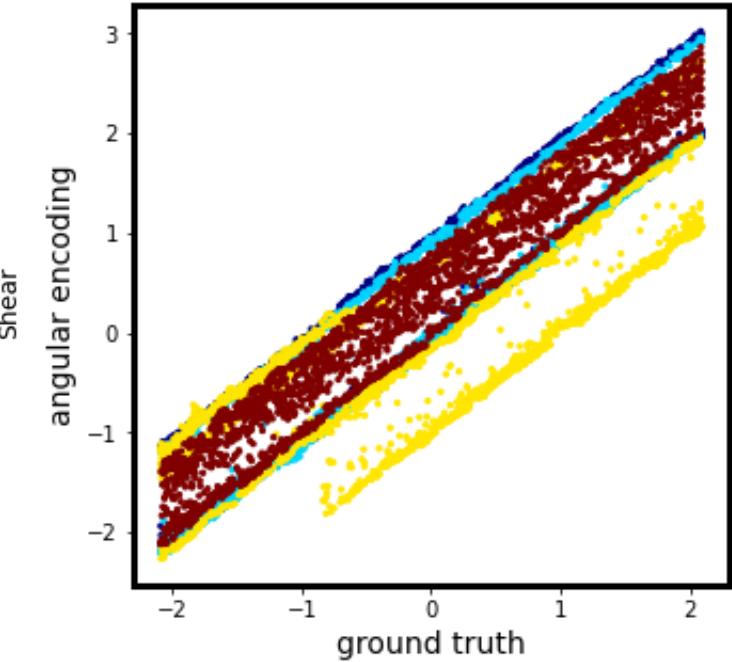
**Suit**



**Shear**



**Angle**



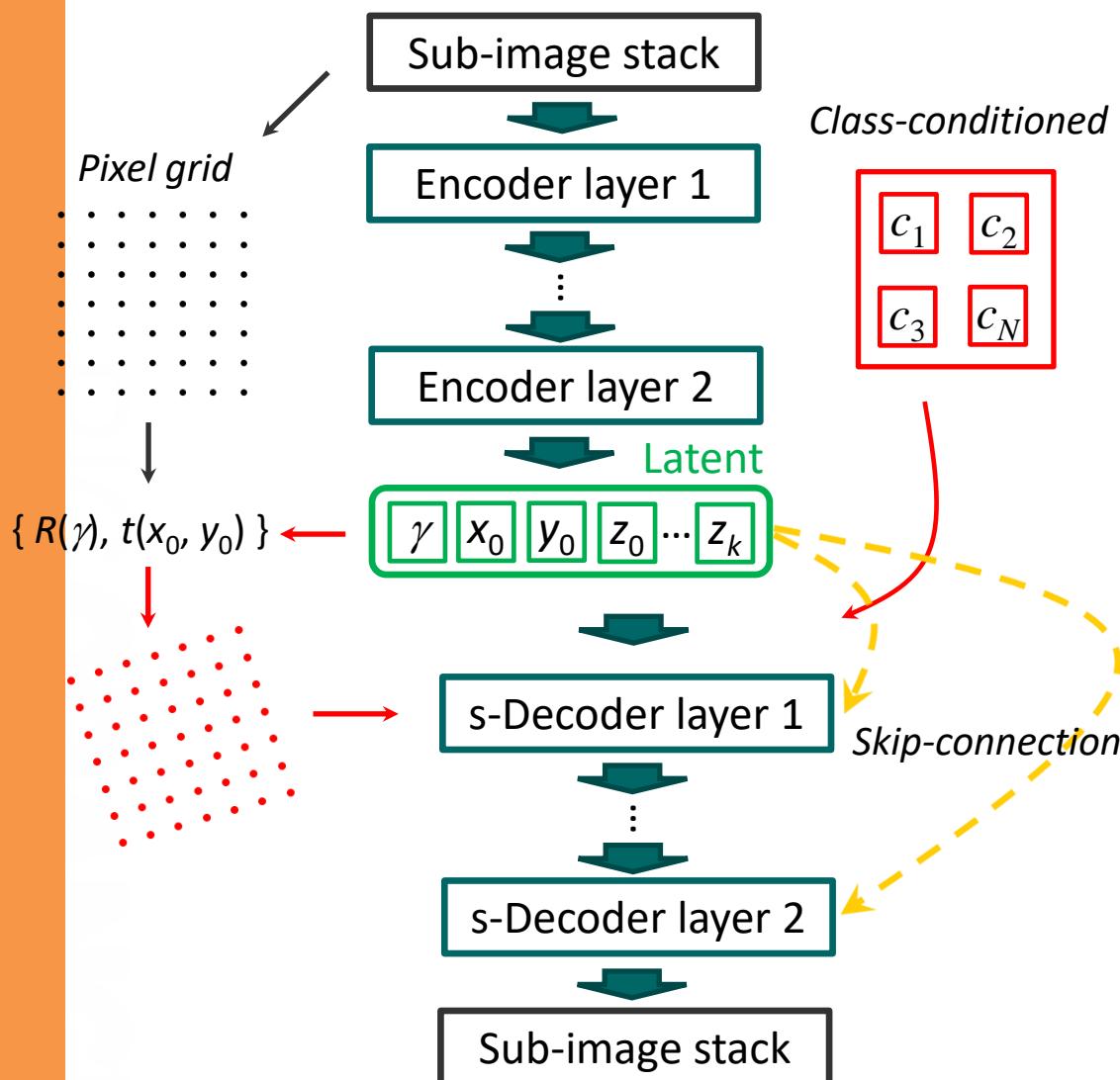
**Cards 4:** High rotation (120 deg) and high shear (20 deg)

- (Super-brief) introduction into Neural Networks
- What are (Variational) autoencoders?
- Key notions:
  - Encoding and decoding
  - Latent distribution
  - Latent representations
- Why invariances: rotational, translational, and scale
- Other colors of VAEs:
  - Semi-supervised
  - Conditional
  - Joint
- From VAEs to encoder-decoders (VED)
- Further opportunities:
  - Physics constraints
  - Representation learning
- Active learning: DKL

# What if we have multiple classes?

1. Classes are known: conditional (discrete) VAE
2. Factors of variability are known: conditional (continuous) VAE
3. Some classes are known: semi-supervised VAE
4. Number of classes are known: joint VAE

# Conditional VAE



- Generative model is a function of spatial coordinate
- 3 additional latent variables to absorb rotations and shifts
- Disentangles rotations and translations from image content
- Ideal for analyzing microscopy sub-images on atomic level

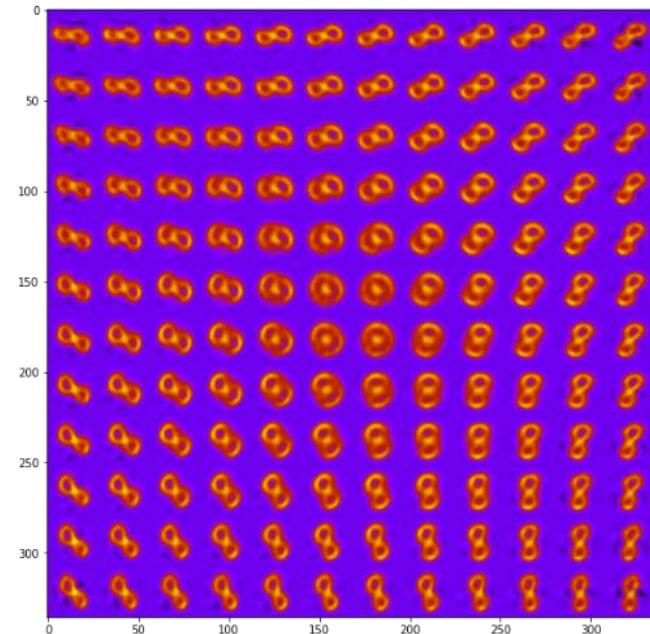
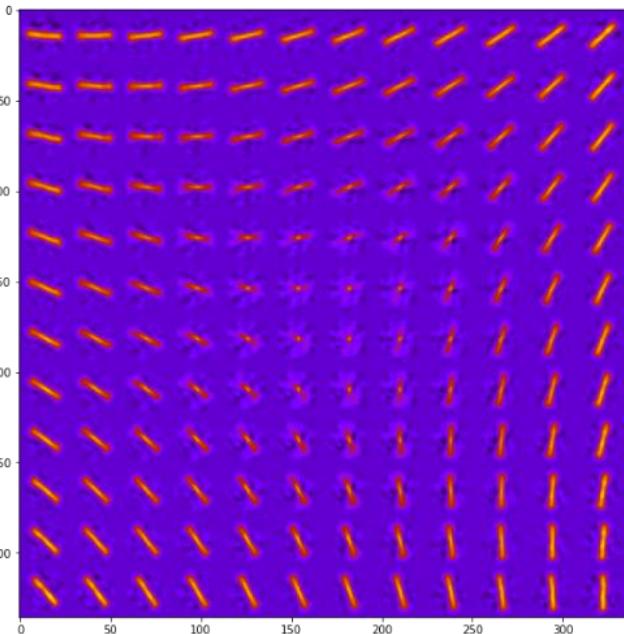
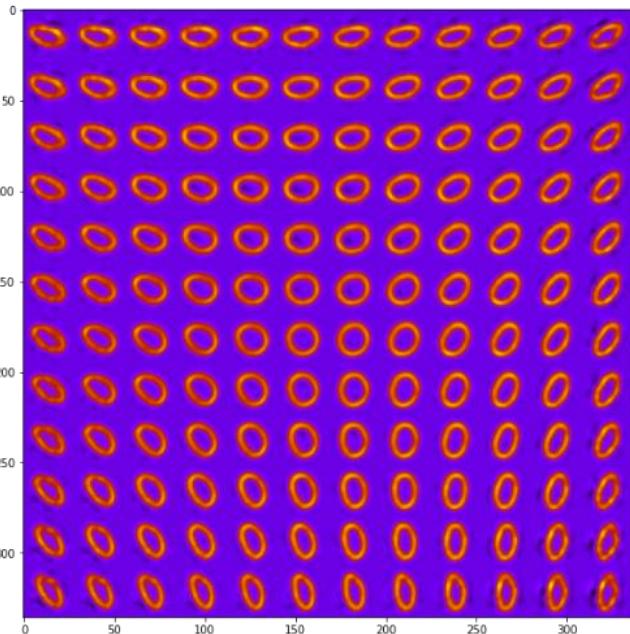
*ELBO*

$$\begin{aligned} &= \text{Reconstruction Loss} \\ &- D_{KL}(q(z|x)\|\mathcal{N}(0,I)) \\ &- D_{KL}(q(\gamma|x)\|\mathcal{N}(0,s_\gamma^2)) \\ &- D_{KL}(q(\Delta r|x)\|\mathcal{N}(0,s_{\Delta r}^2)) \quad \text{Regular VAE} \\ &+ D_{KL}(\text{physics-based "priors"}) ? \\ &+ D \quad (\text{physics}) ? \end{aligned}$$

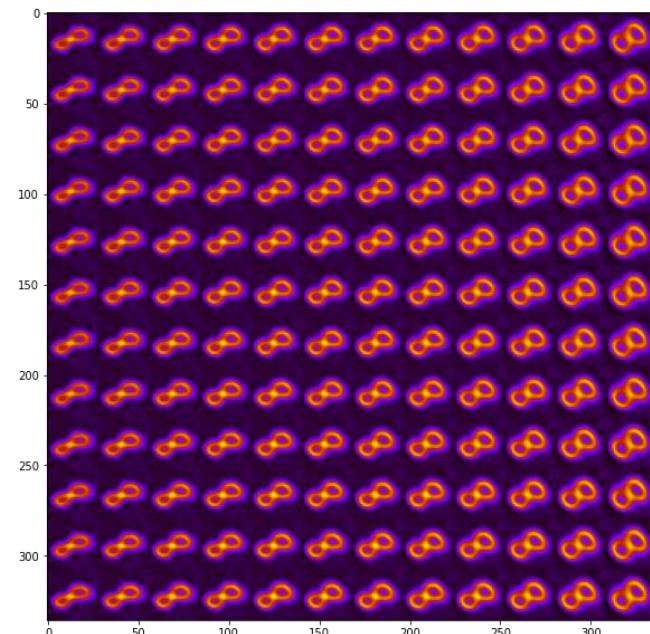
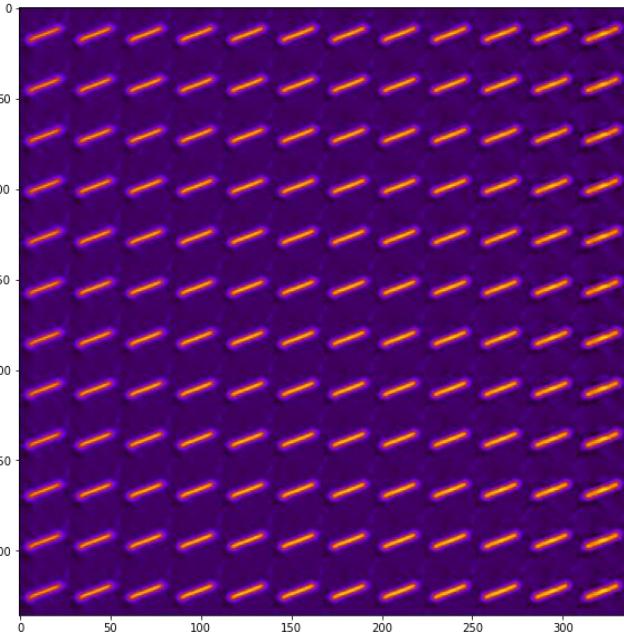
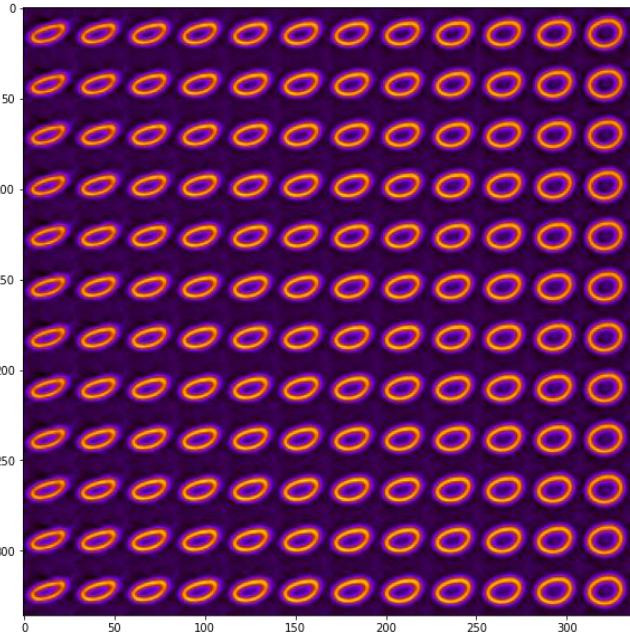
Rotation  
Translation

# MNIST: cVAE

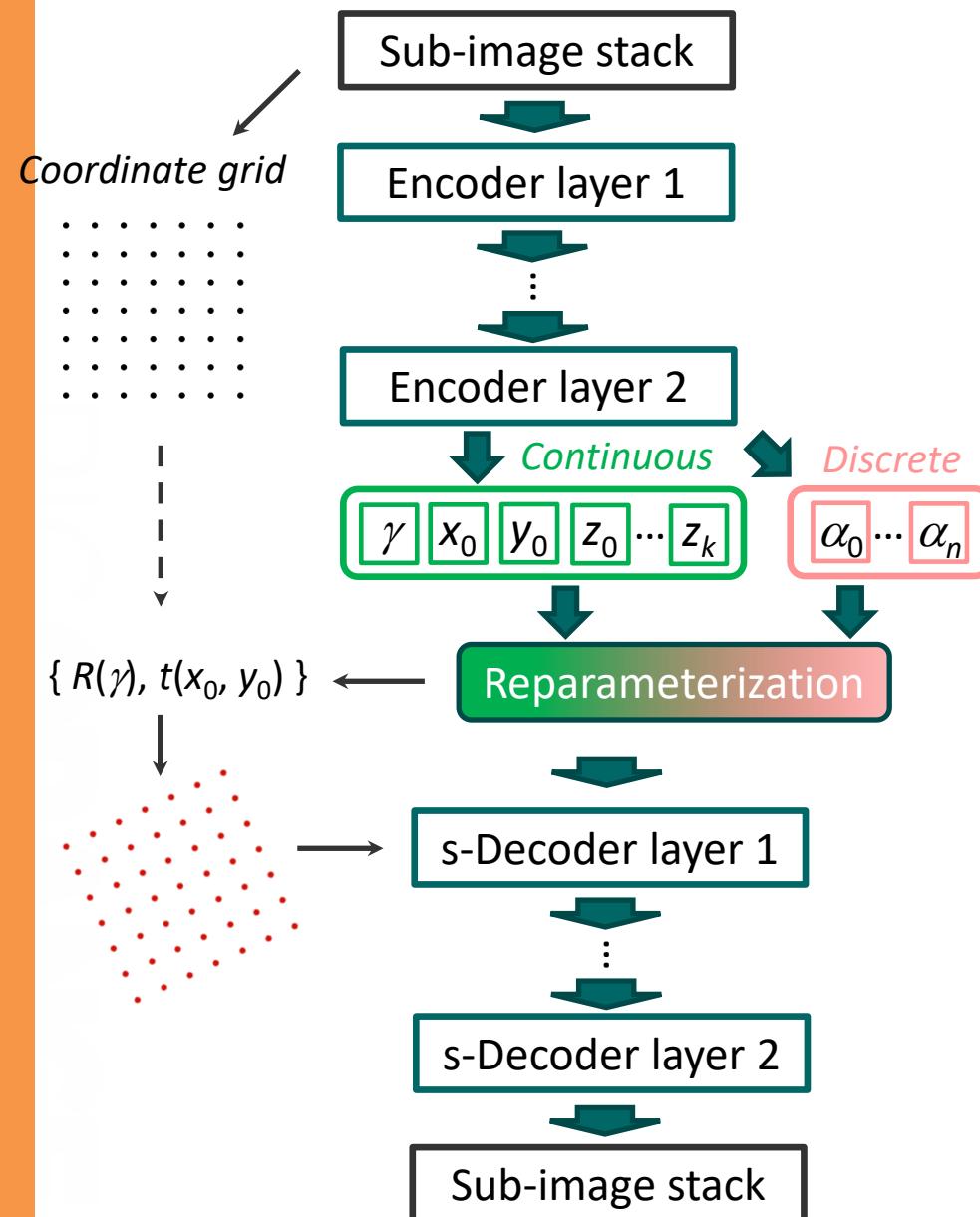
No rotations



With rotations



# Joint VAE

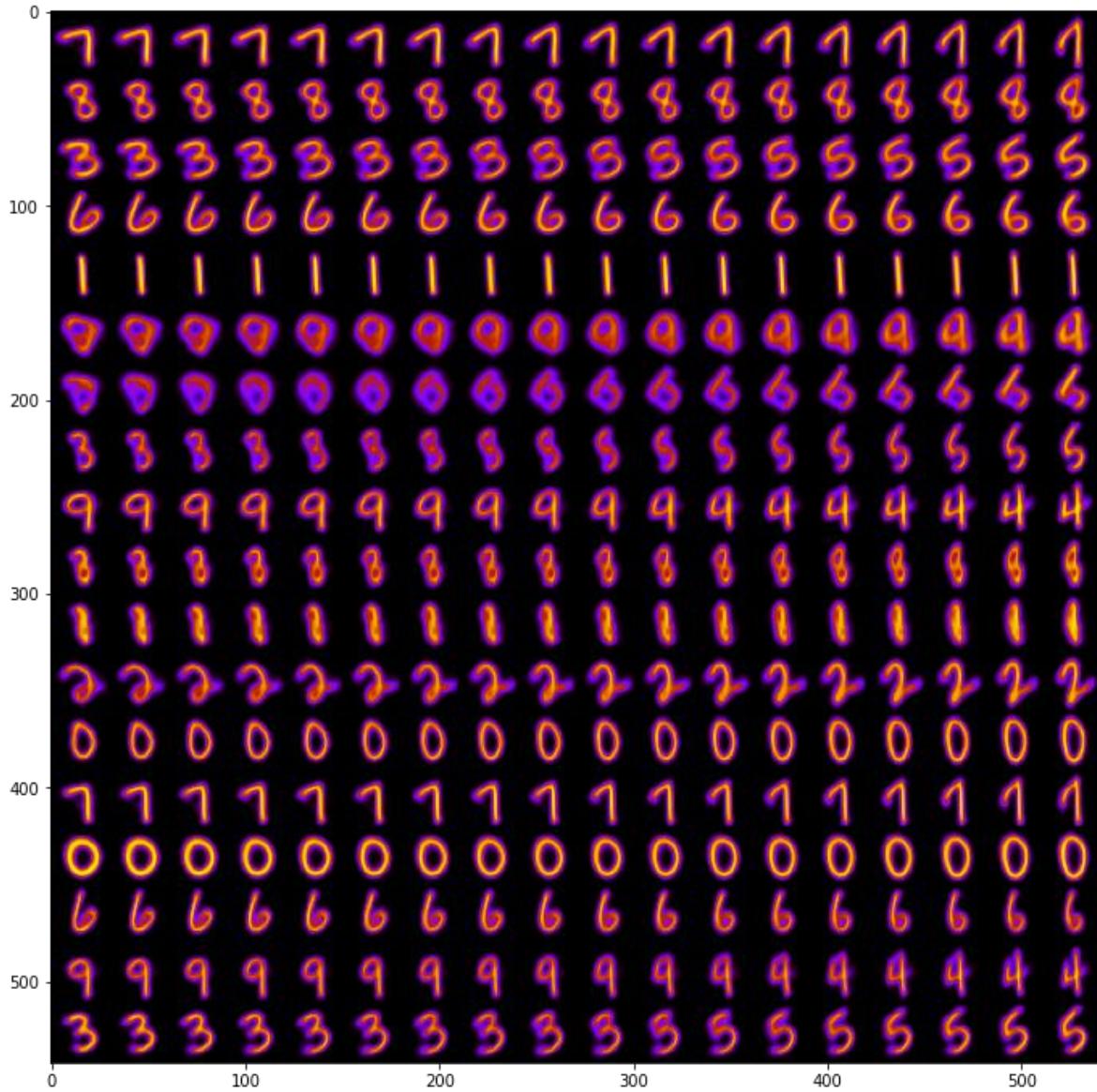
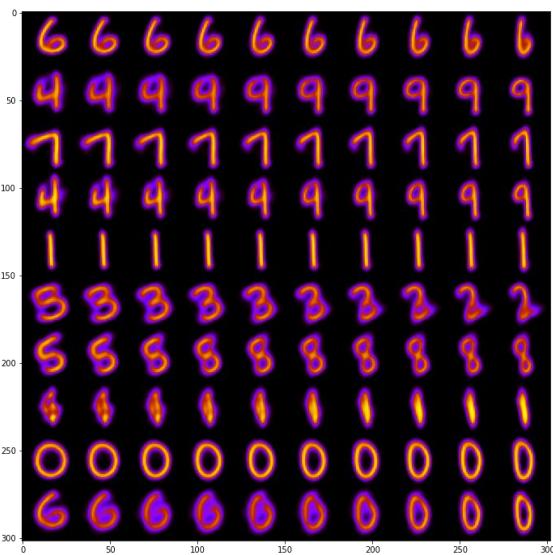
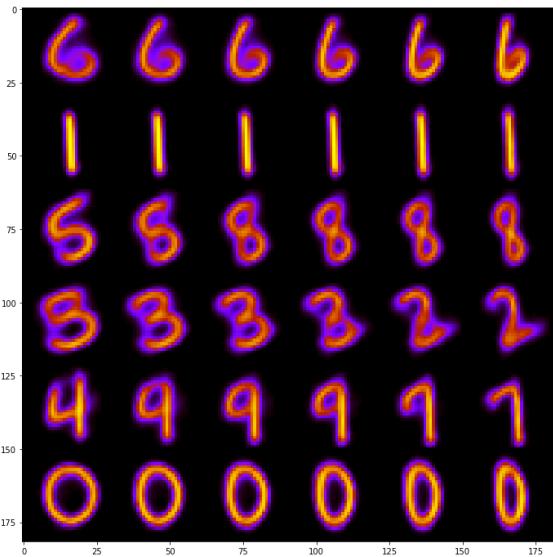


- Generative model is a function of spatial coordinate (e.g., via spatial broadcasting)
- 3 additional latent variables to absorb rotations and shifts
- Disentangles rotations and translations from image content
- Learns discrete classes in unsupervised fashion
- Well-suited for analyzing microscopy (sub-)images on atomic and molecular levels

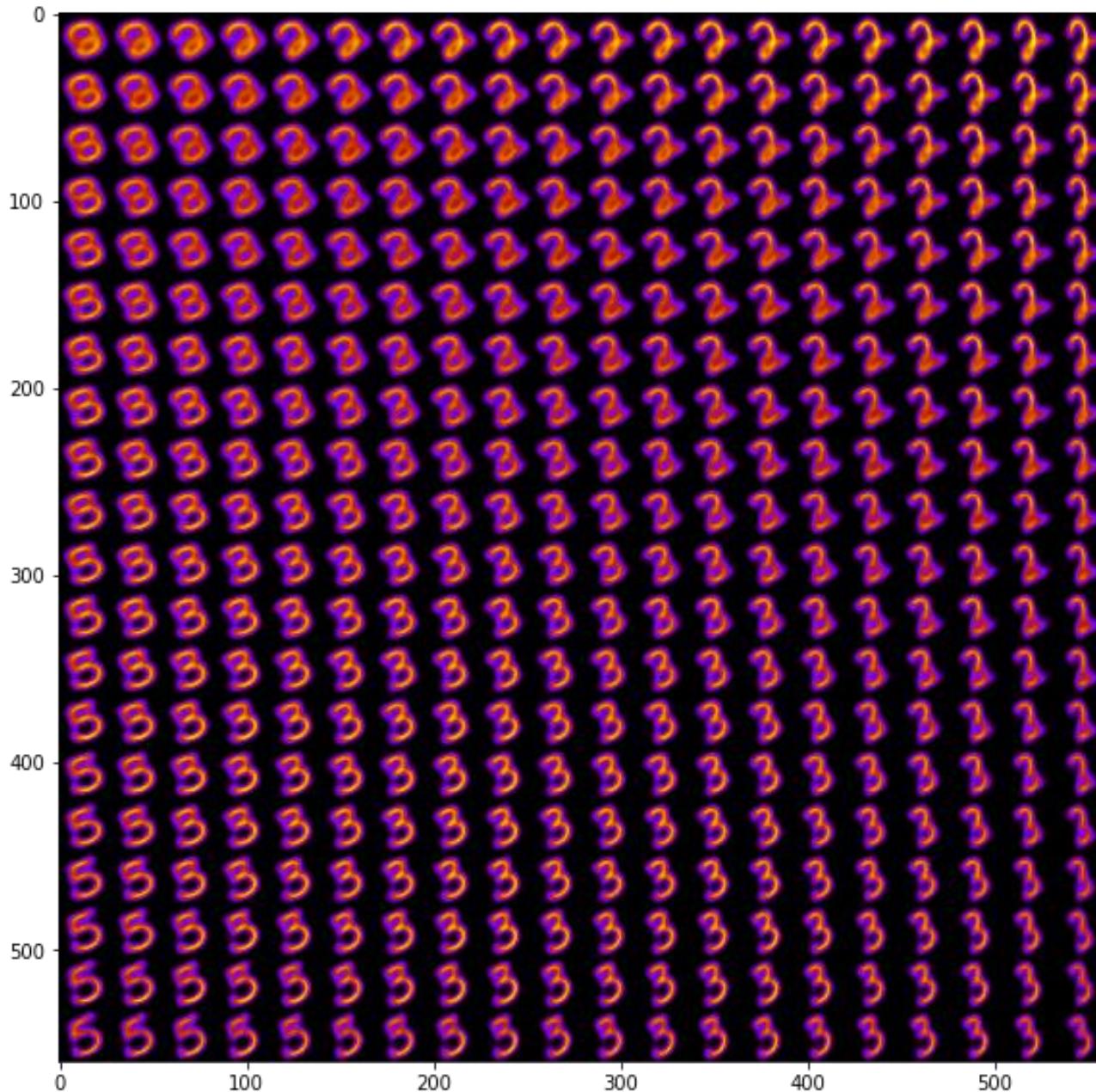
*ELBO =*

$$\begin{aligned} & - \text{Reconstruction Loss} \\ & - \beta_c(t) |(D_{KL}(q(z|x) \parallel p(z)) + D_{KL}(q(\gamma|x) \parallel p(\gamma)) - C_z| \quad \text{Continuous} \\ & - \beta_d(t) |D_{KL}(q(\alpha|x) \parallel p(\alpha)) - C_\alpha| \quad \text{Discrete} \\ & + \text{physics-based "loss" ?} \end{aligned}$$

# jVAE of MNIST

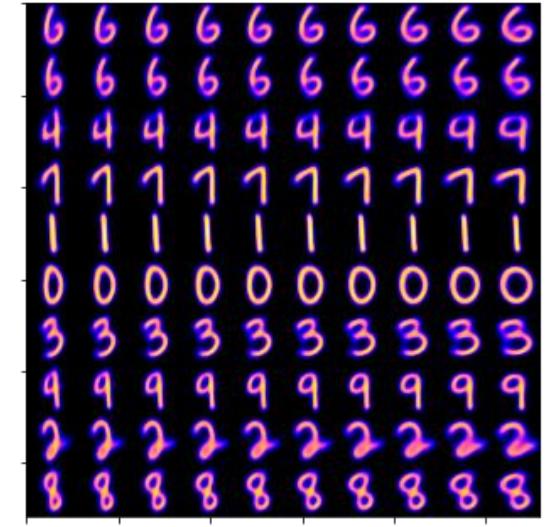


# Latent representation



# Ensemble jVAE

*Predictions from different ensemble models*

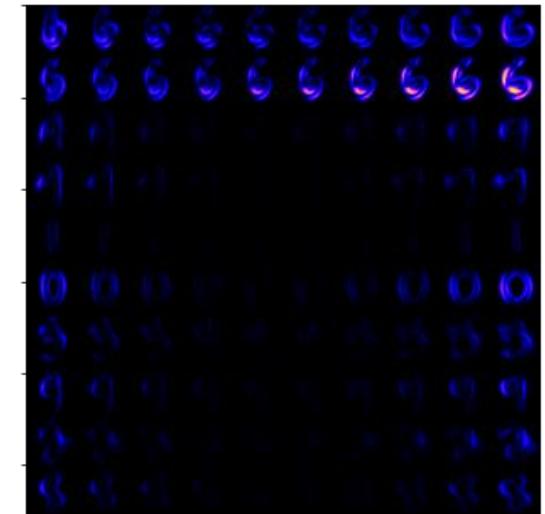
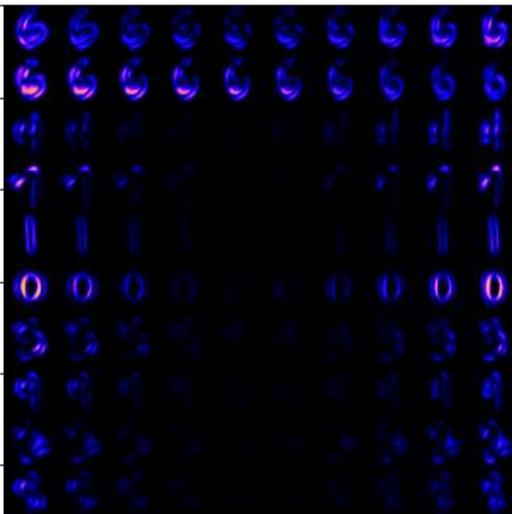


Baseline: 10 epochs  
Ensemble models: 8

- The unstable classes show the largest “uncertainty”
- Indication of the quality of separation and/or a guide for selection of the number of classes



*Dispersion in predictions ('uncertainty')*



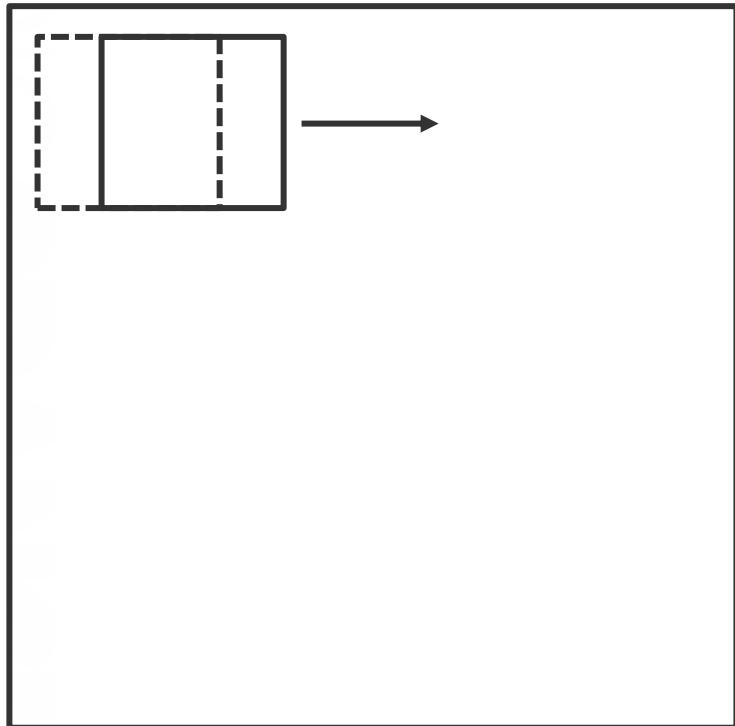
# What can (unsupervised) classification give us

- Our research deals with complex data sets containing information on physics of objects we seek to understand
  - This can be spectral data sets (EELS in STEM, CITS in STM, complex spectroscopies in PFM) or single, multimodal, or hyperspectral images
  - Often, we seek approaches to reduce dimensionality and explore similarities in these data sets.
- 
- When working with such data sets, two things matter: descriptors and ML method
  - In analysis of EELS or CITS data, very often our descriptor is just the spectrum at each pixel. Typical analysis will be either linear or non-linear dimensionality reduction or clustering:
    - Linear dimensionality reduction: PCA, NMF, BLU
    - Clustering: k-means, GMM
    - Manifold learning: ISO, UMAP, tSNE, DBSCAN
    - Neural nets: SOFM, AEs, VAEs
  - Typical result will be the components (representing behavior), and loading maps representing spatial variability of these behaviors. **By construct, components will not depend on the relative spatial positions of pixel.**
- 
- **What about images?**

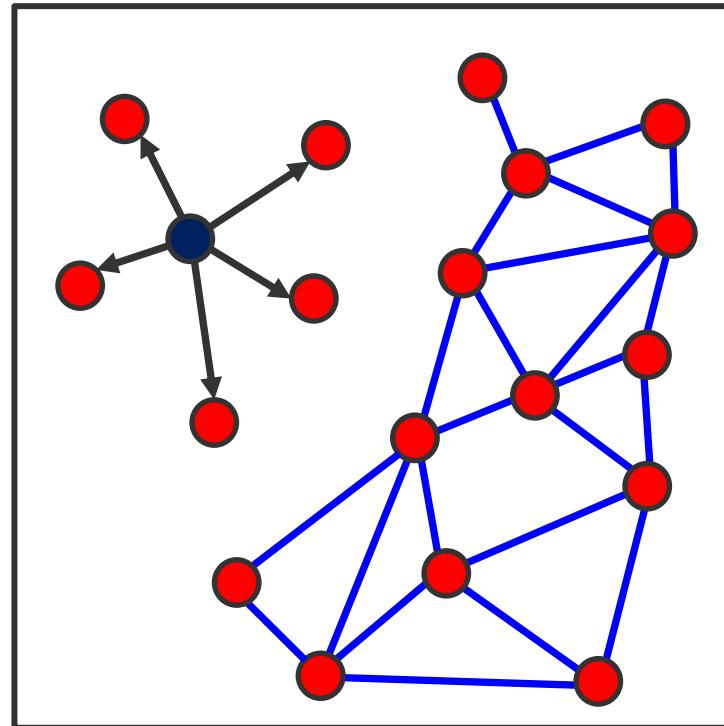
# Describing the building blocks

- The classical physical descriptions (symmetry, etc) can be defined locally only in Bayesian sense
- We can argue that local descriptors are simple, if not necessarily known
- And the rules that guide their emergence are also simple, if not known

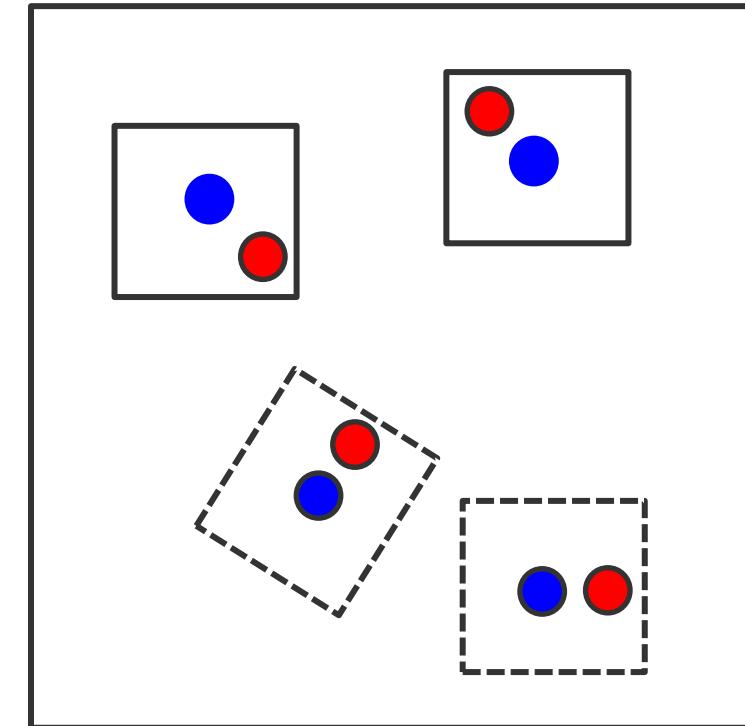
**Continuous translational symmetry**



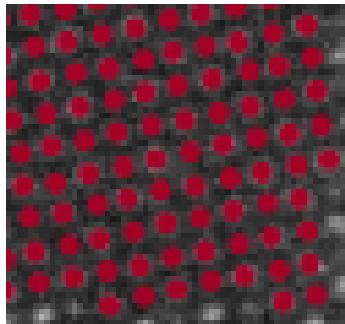
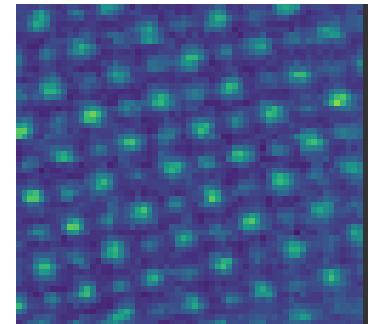
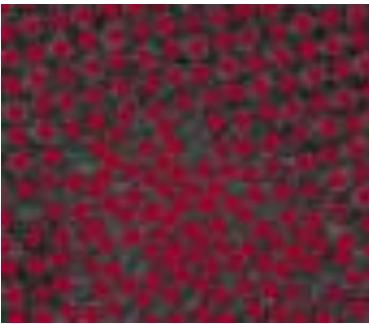
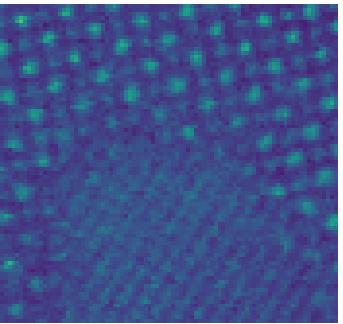
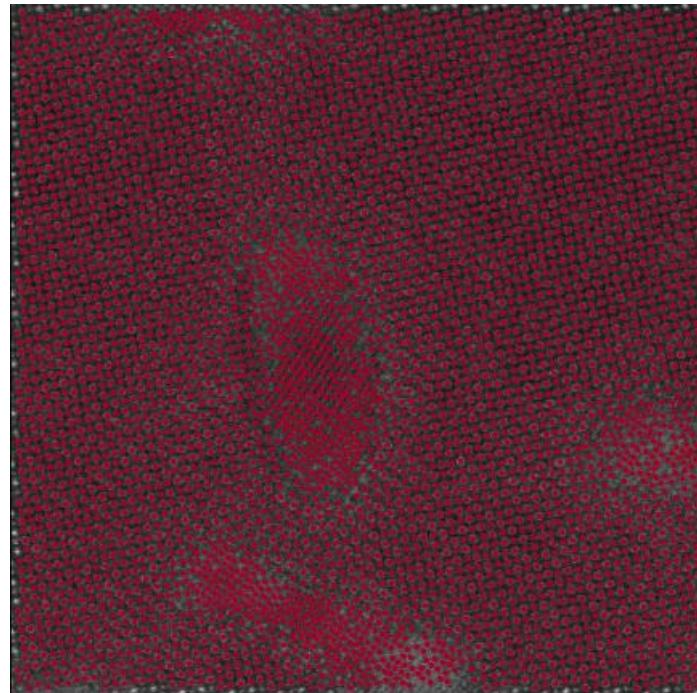
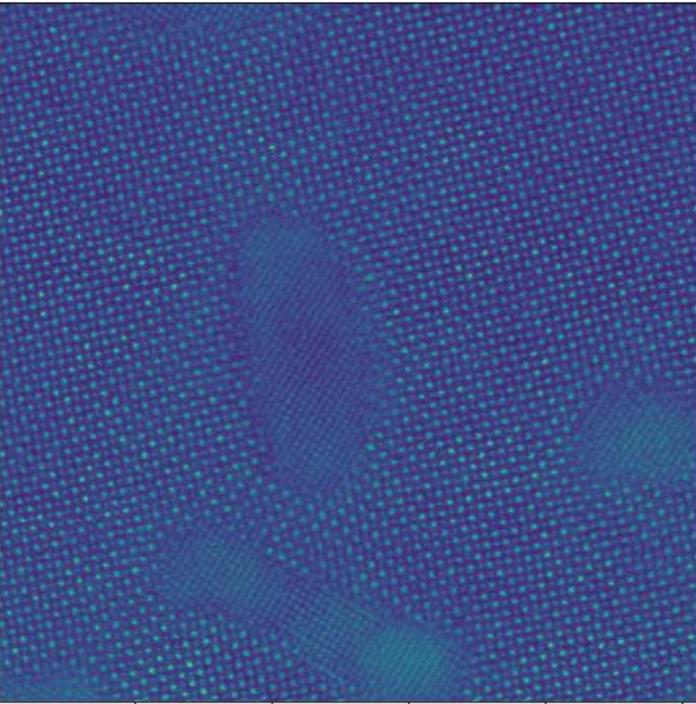
**Atom based descriptions**



**Localized sub-images**



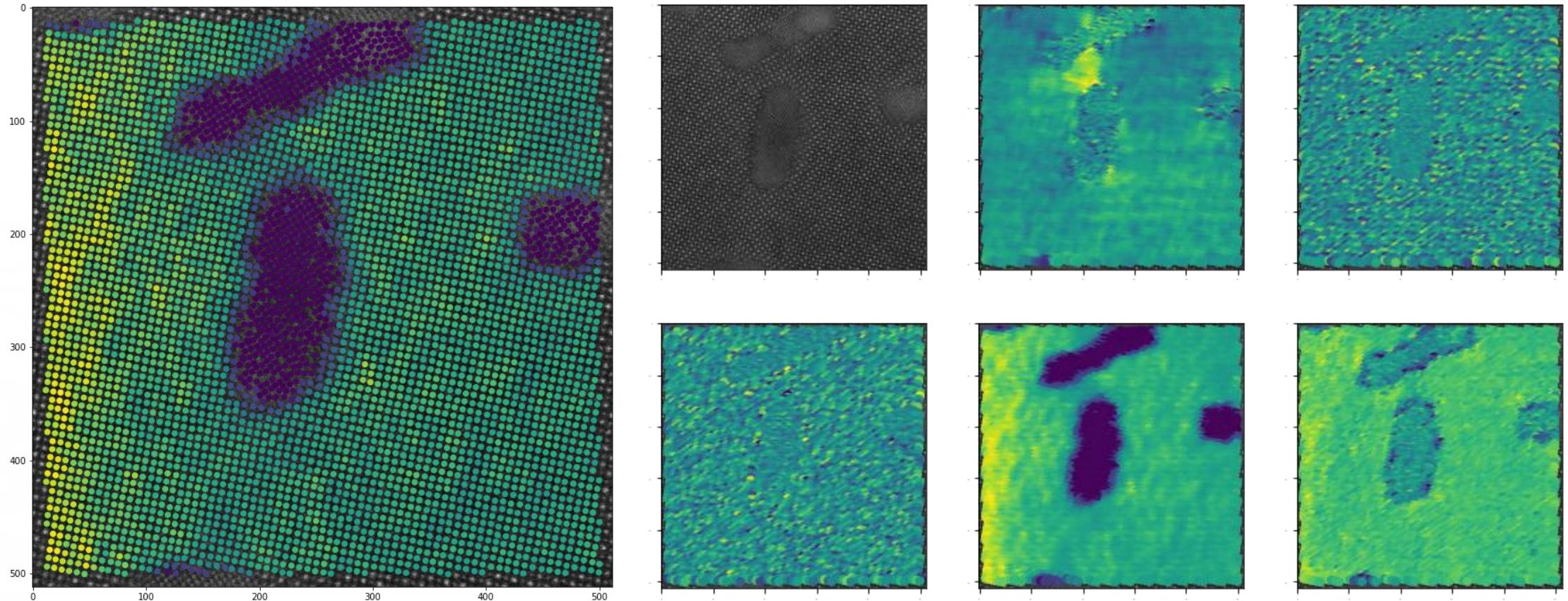
# Let's put it all together!



**Step 1:** Find all atoms (or all that you can) – use maximum finders, blob-log, or DCNNs

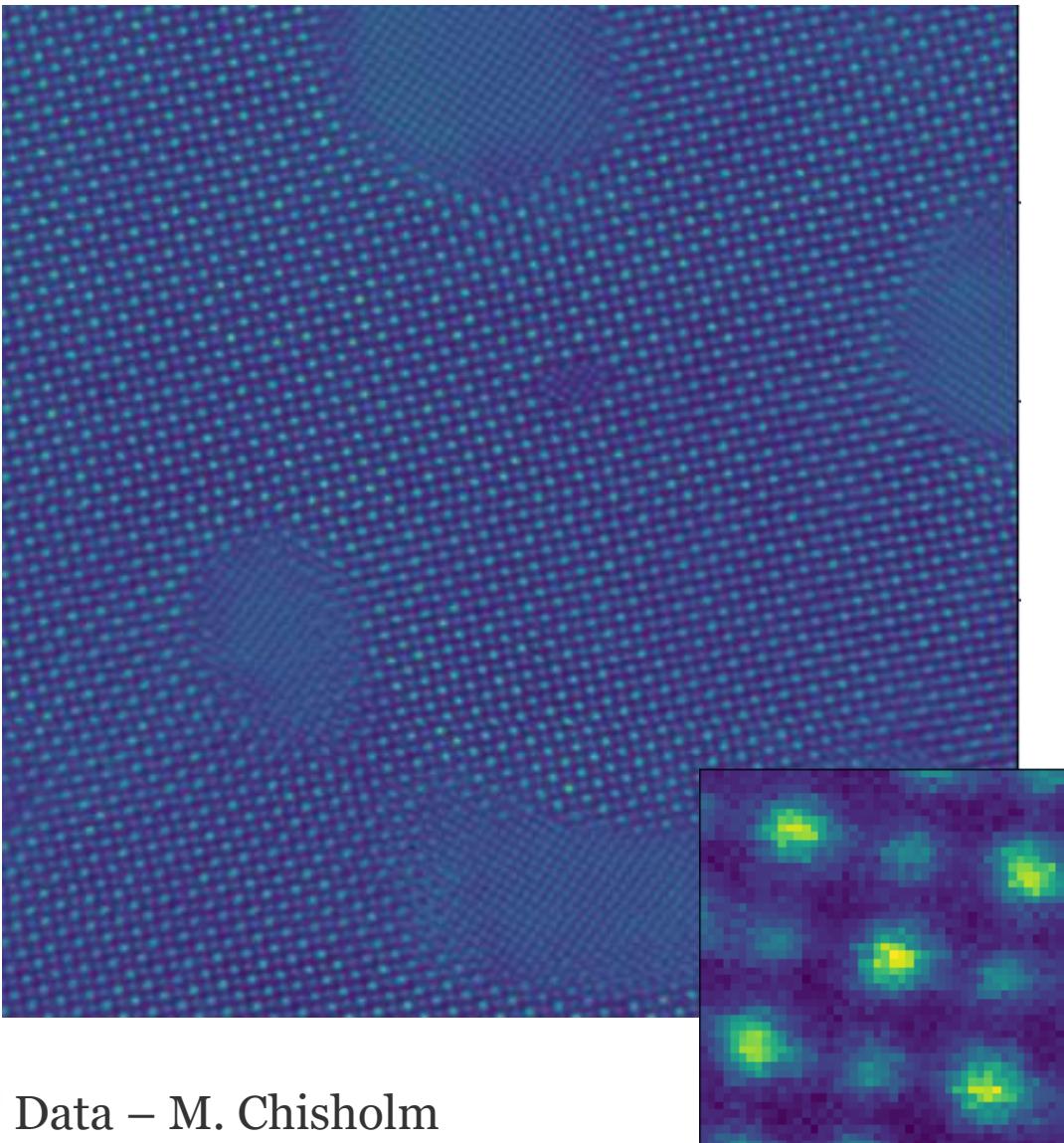
**Step 2:** Create descriptors – patches centered on atoms. Keep track on what part of image (or stack) it came from

# Step 3: rVAE

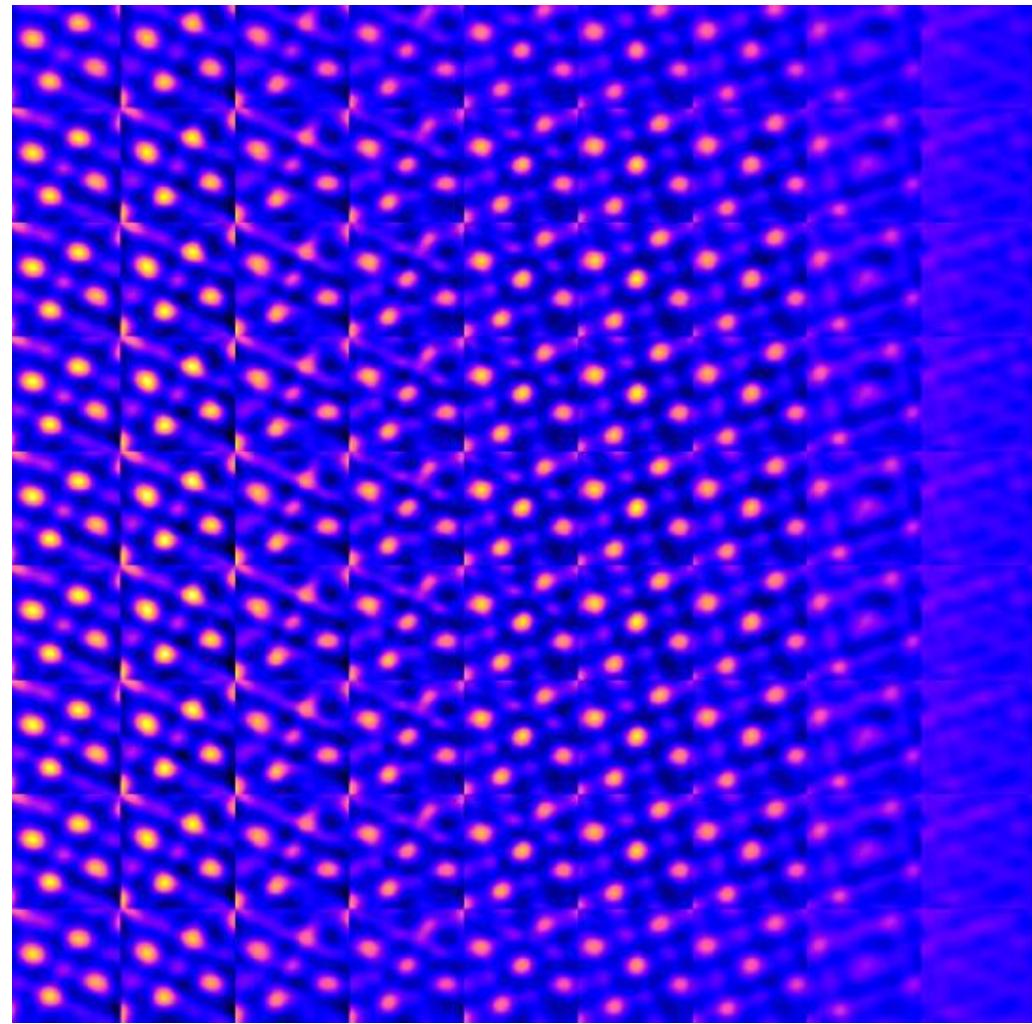


**Output:** Latent variable corresponding to local structure of each atomic site. Can be visualized on top of the original atomically resolved image, or as 2D maps (but – not rectangular array!)

# Analysis of the NiO-LSMO

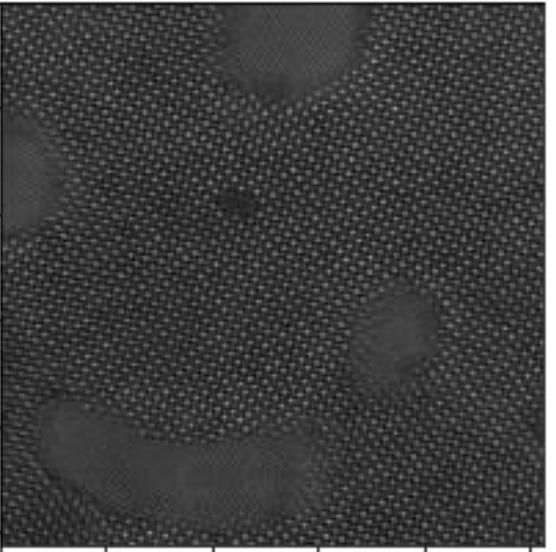


Data – M. Chisholm

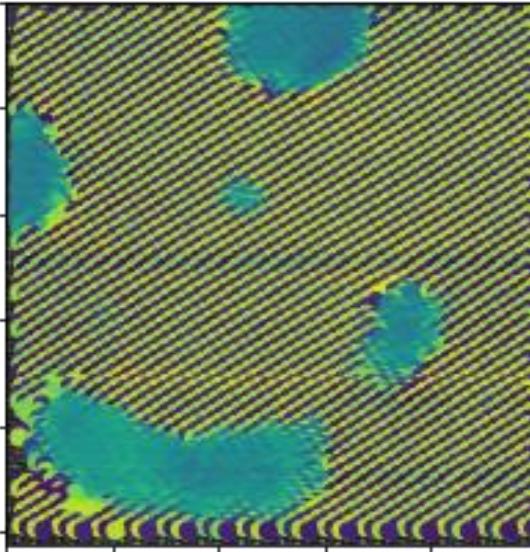


# Let's look at latent space

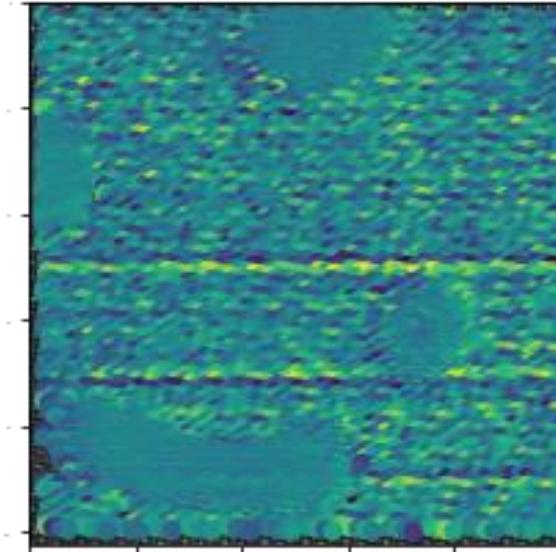
Image



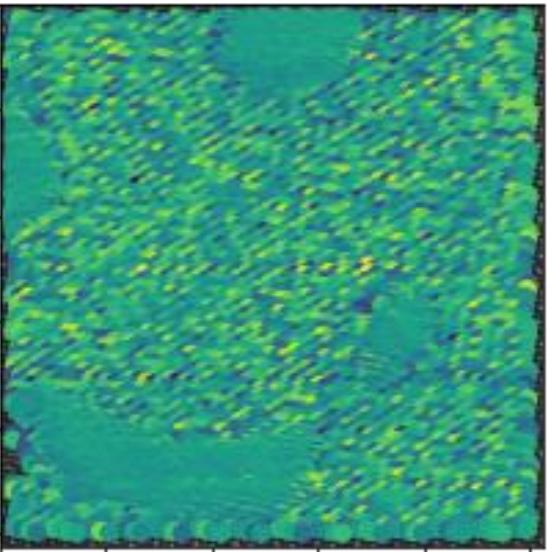
Angle



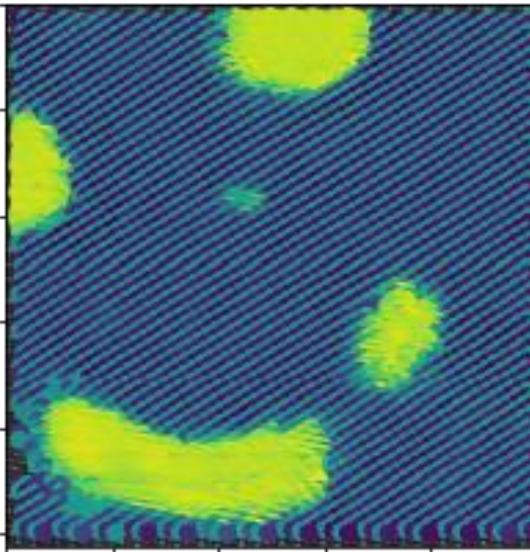
X Offset



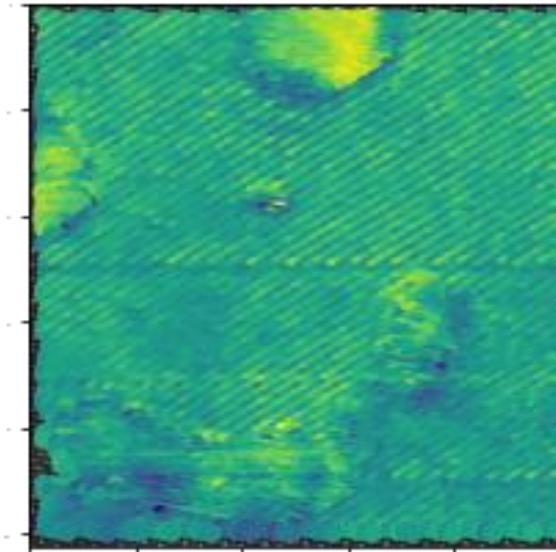
Y Offset



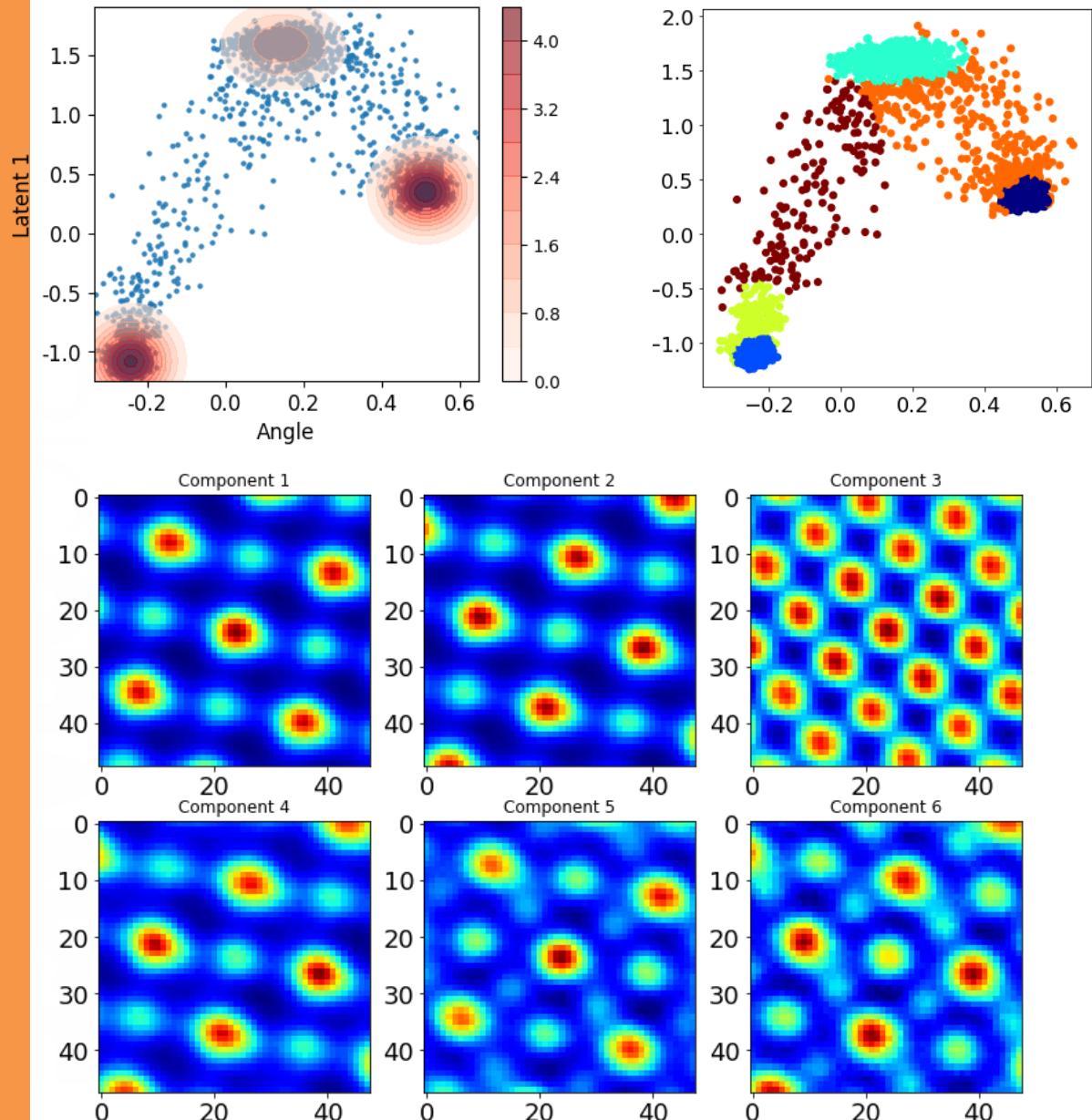
Latent 1



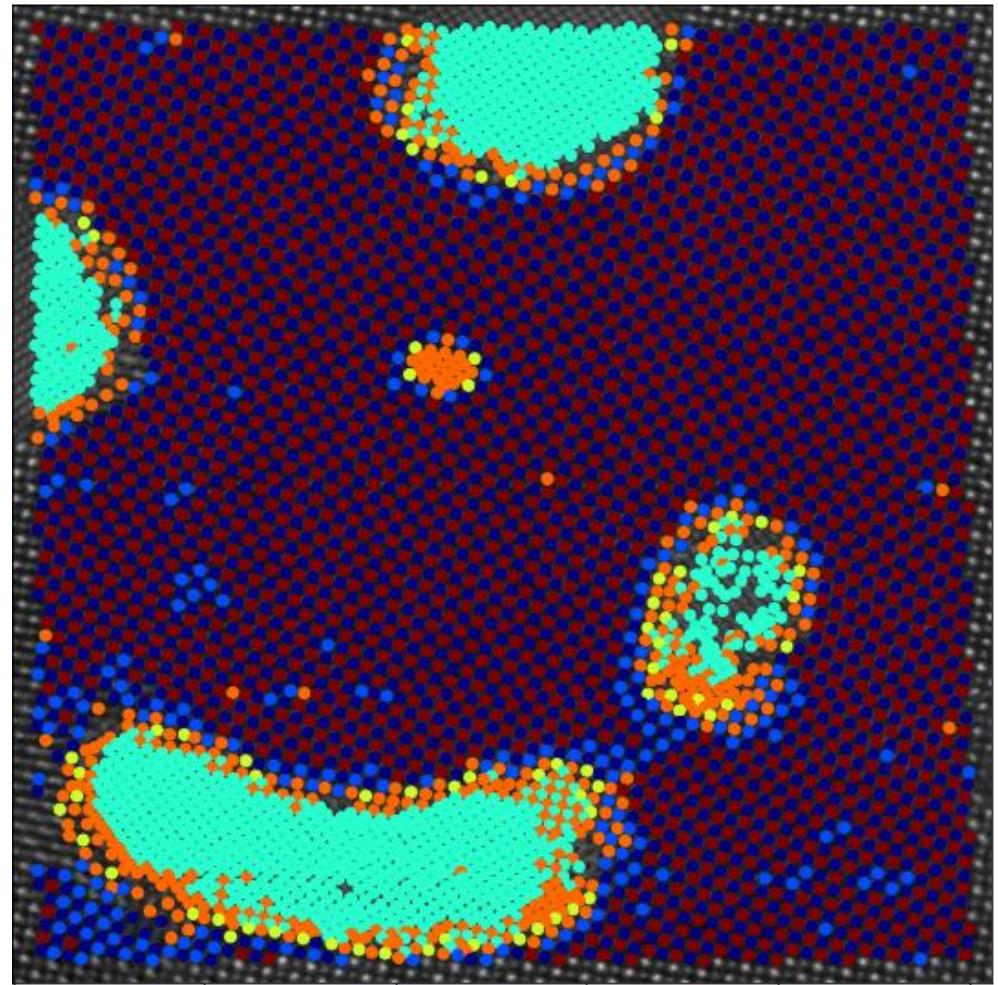
Latent 2



# Exploring latent distributions



Labeled image



- Classes and variability are mixed in a single latent space
- Disentangling of representation

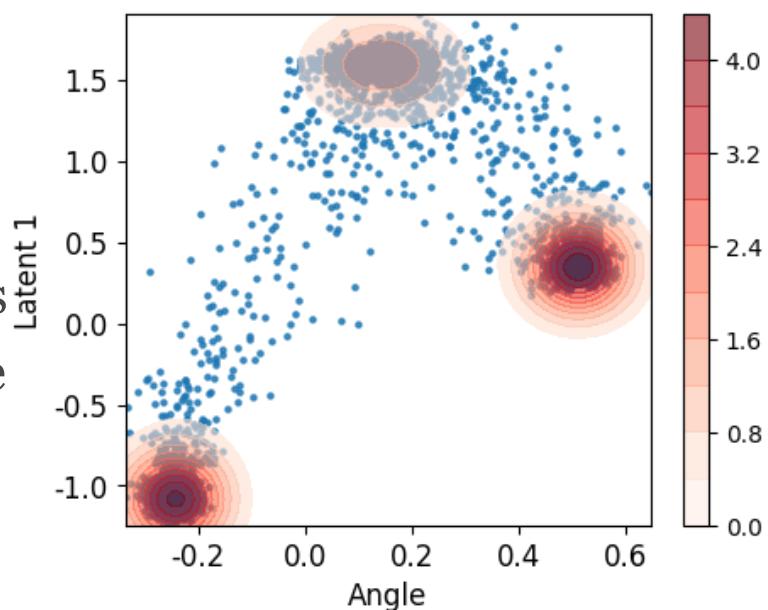
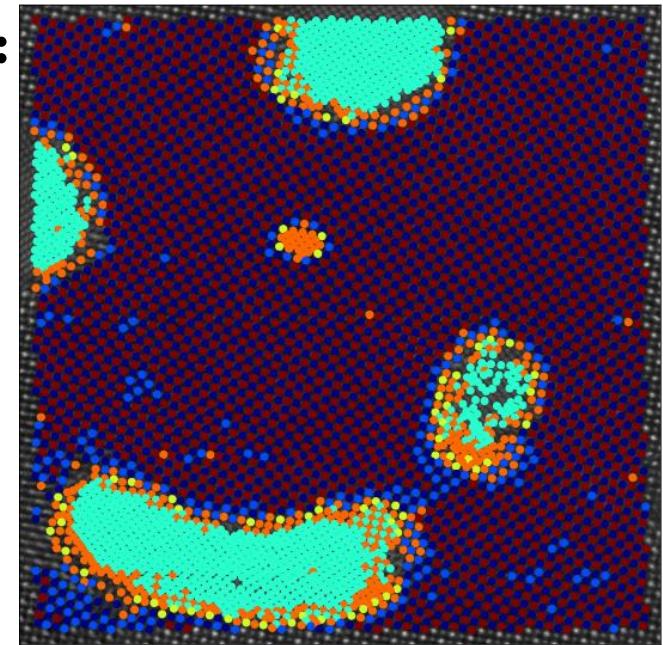
# That's where the jVAE has come from

**Currently, we have variants of invariant VAE that include:**

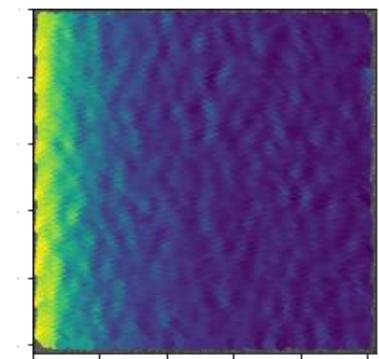
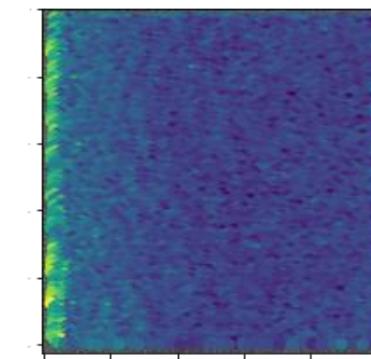
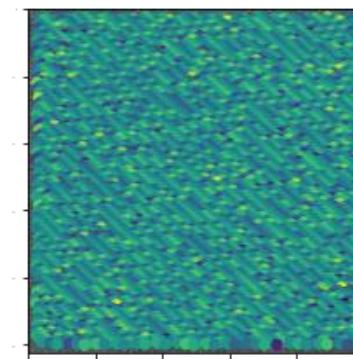
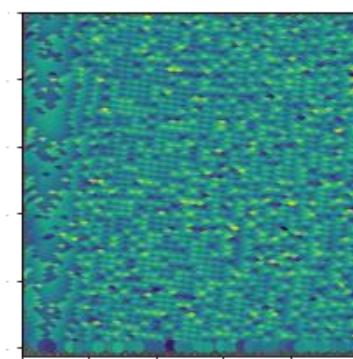
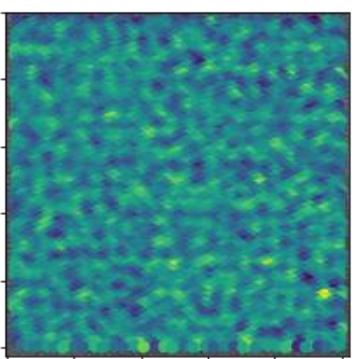
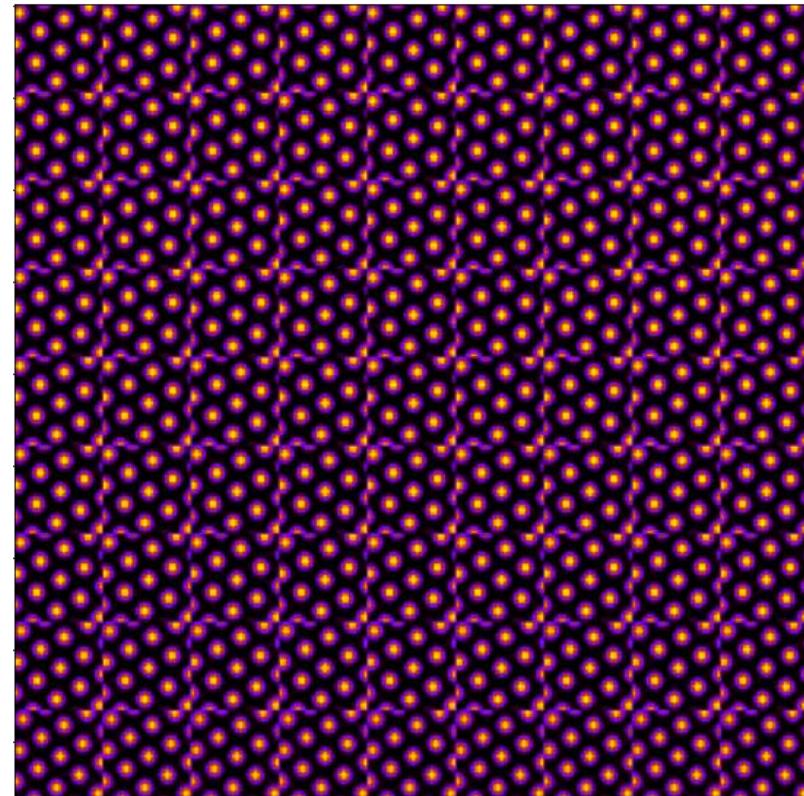
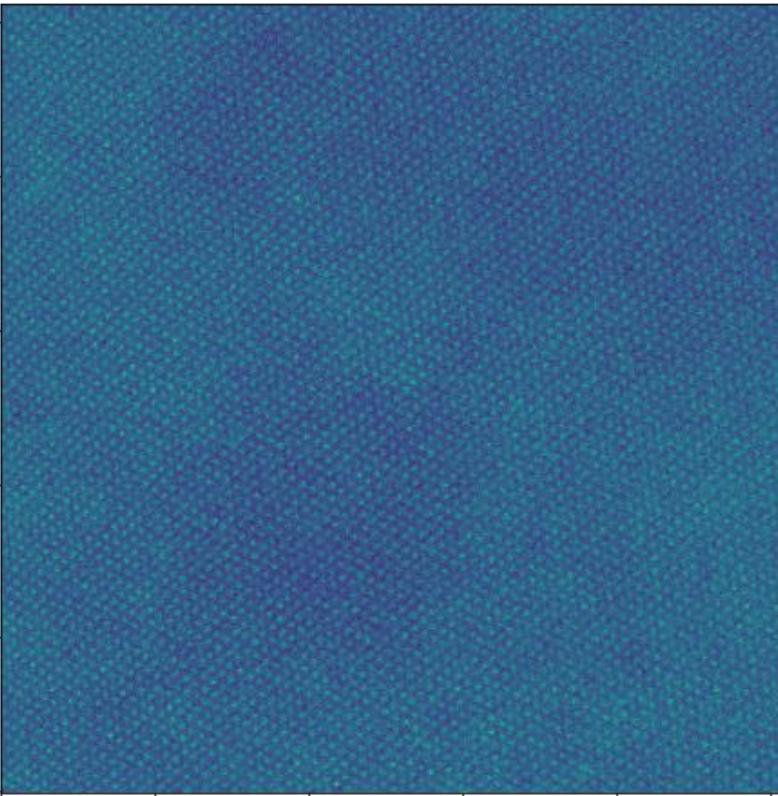
- Convolutional or dense layers (reconfigurable via `**kwargs`)
- Rotational invariance
- With and without offsets (as latent variables)
- Multilayer inputs

However, our rVAE collects everything in a single latent space. Realistically, very often we deal with system where we expect the presence of finite number of classes that may be known, partially known, or unknown, with certain continuous traits within classes.

- **Graphene and MX<sub>2</sub>:** structural units (discrete) and strain states
- **Crystalline solids:** phases and ferroic variants, strain states
- **Plasmonic EELS:** particle spectra, off-particle spectra, edge states
- **CITS:** lattice and defects, strain states

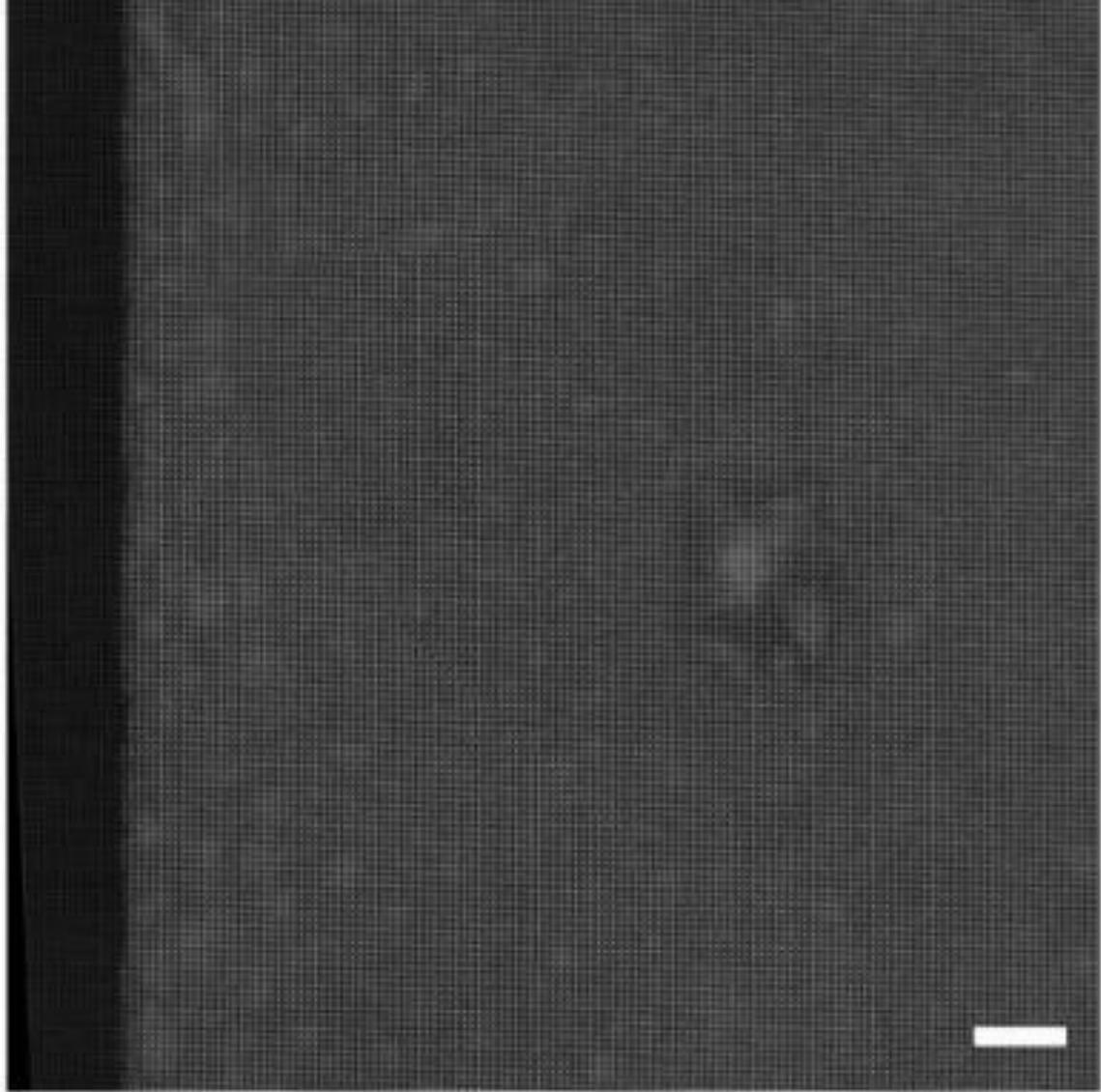


# Out of curiosity: single crystal?

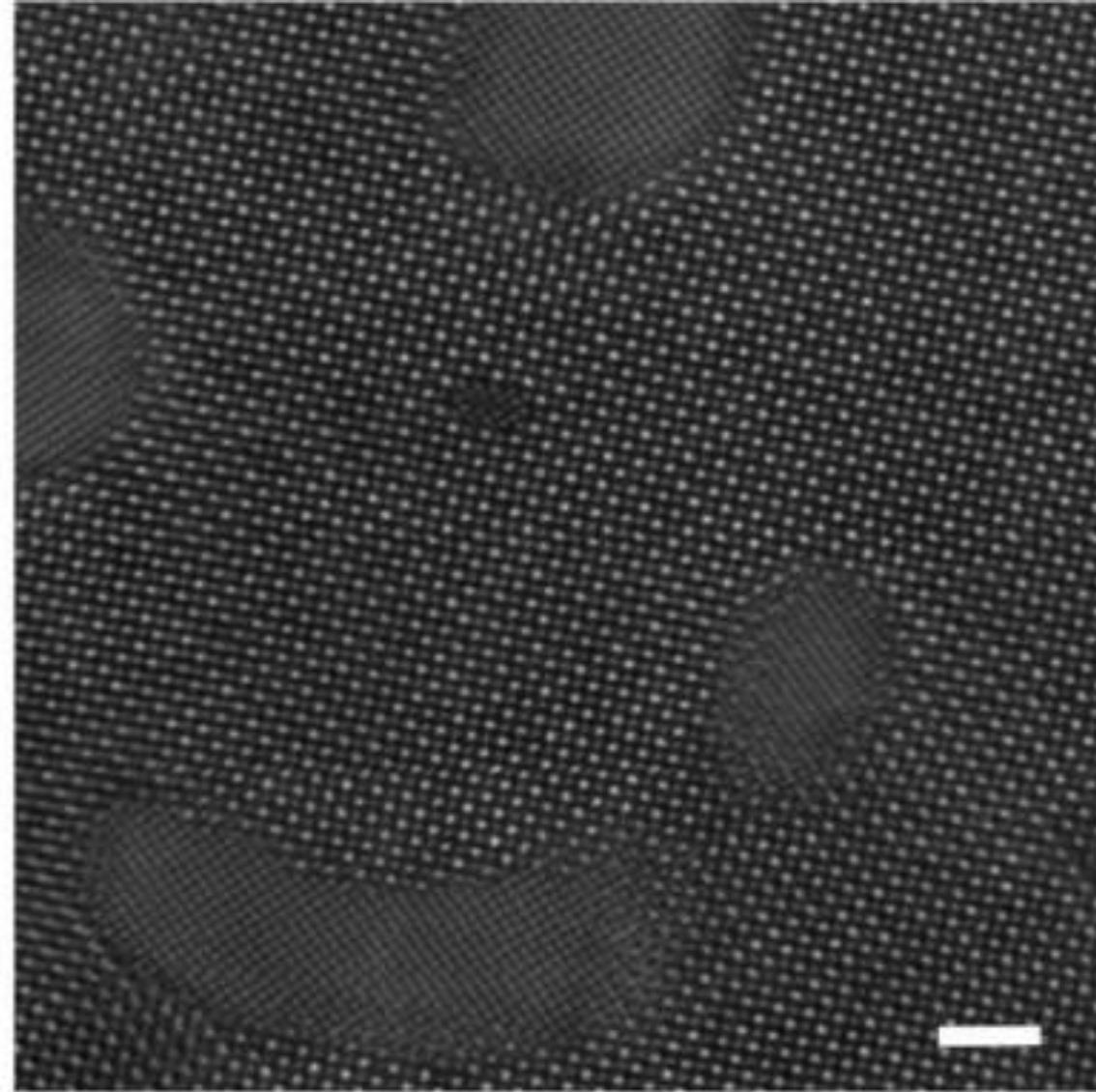


# VAE without Atom Finding

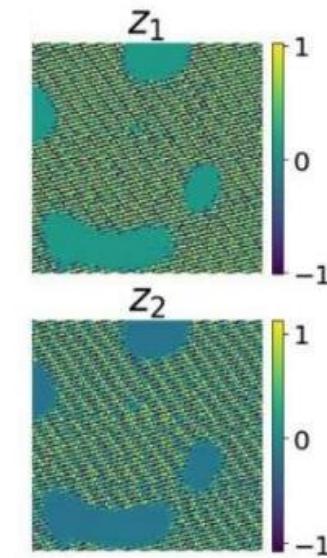
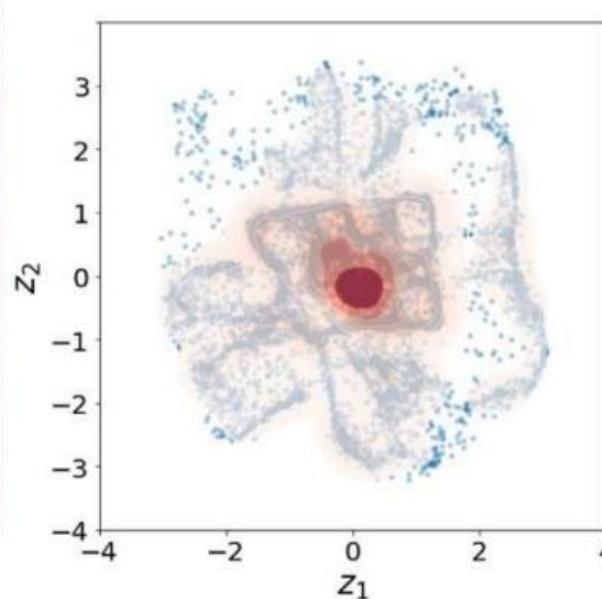
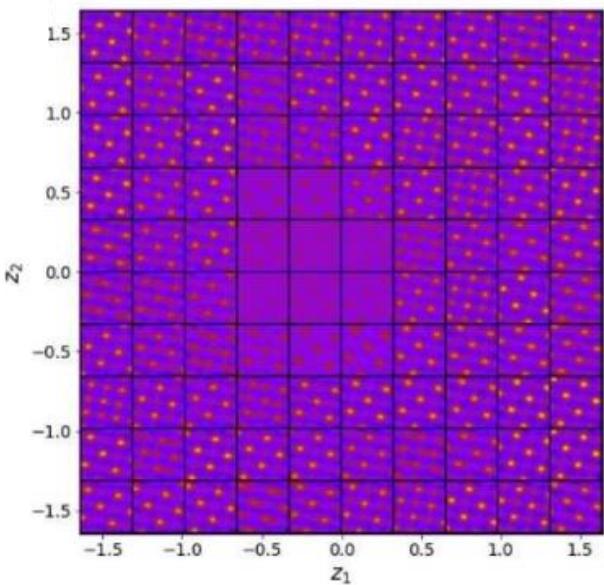
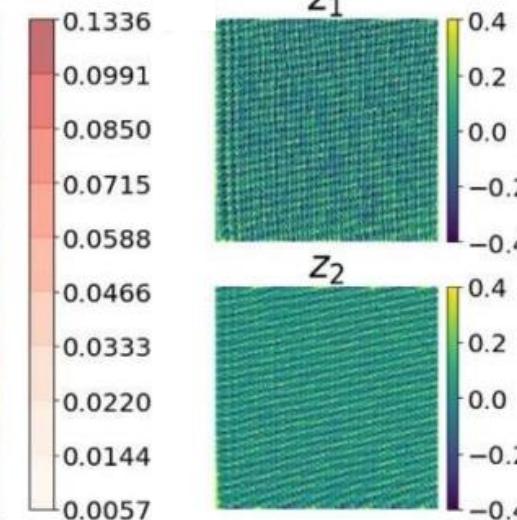
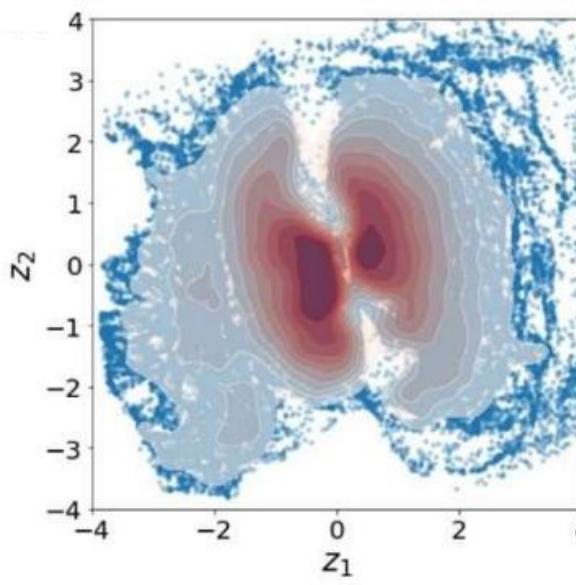
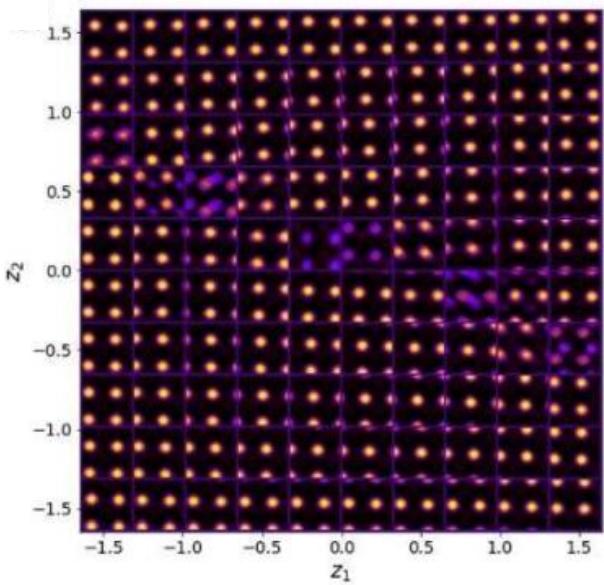
**Ferroelectric BiFeO<sub>3</sub>**



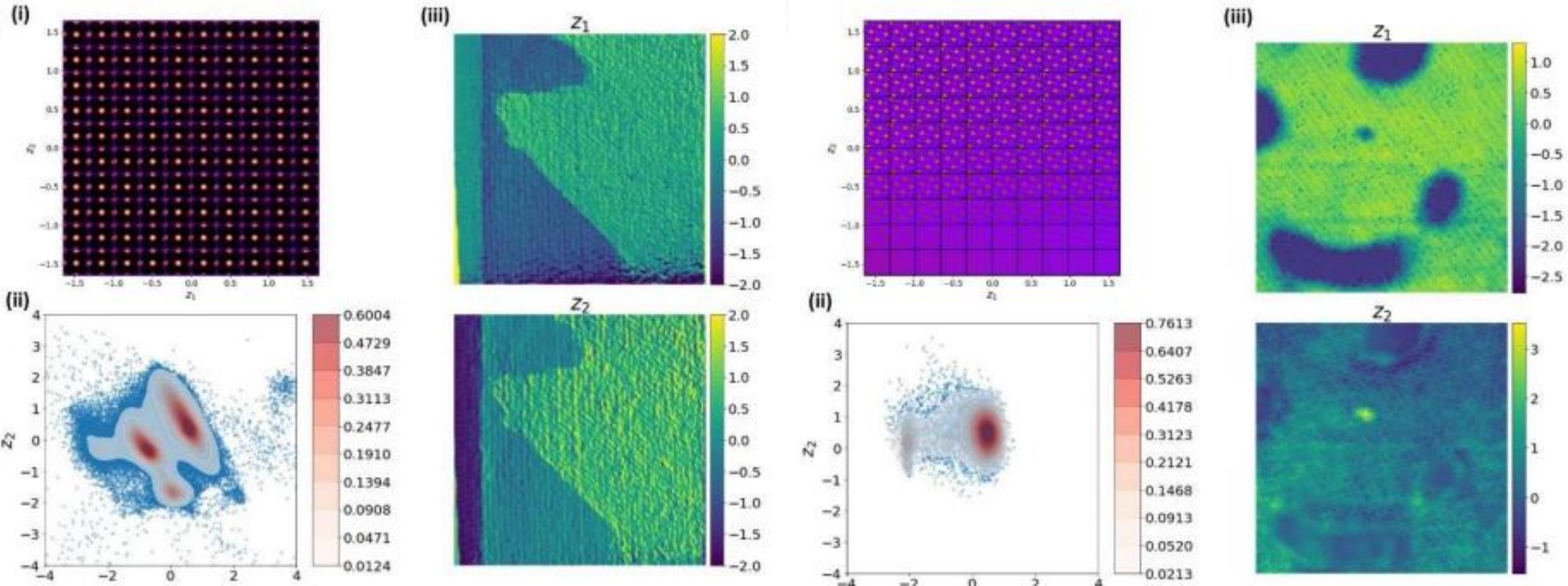
**NiO – La<sub>x</sub>Sr<sub>1-x</sub>MnO<sub>3</sub>**



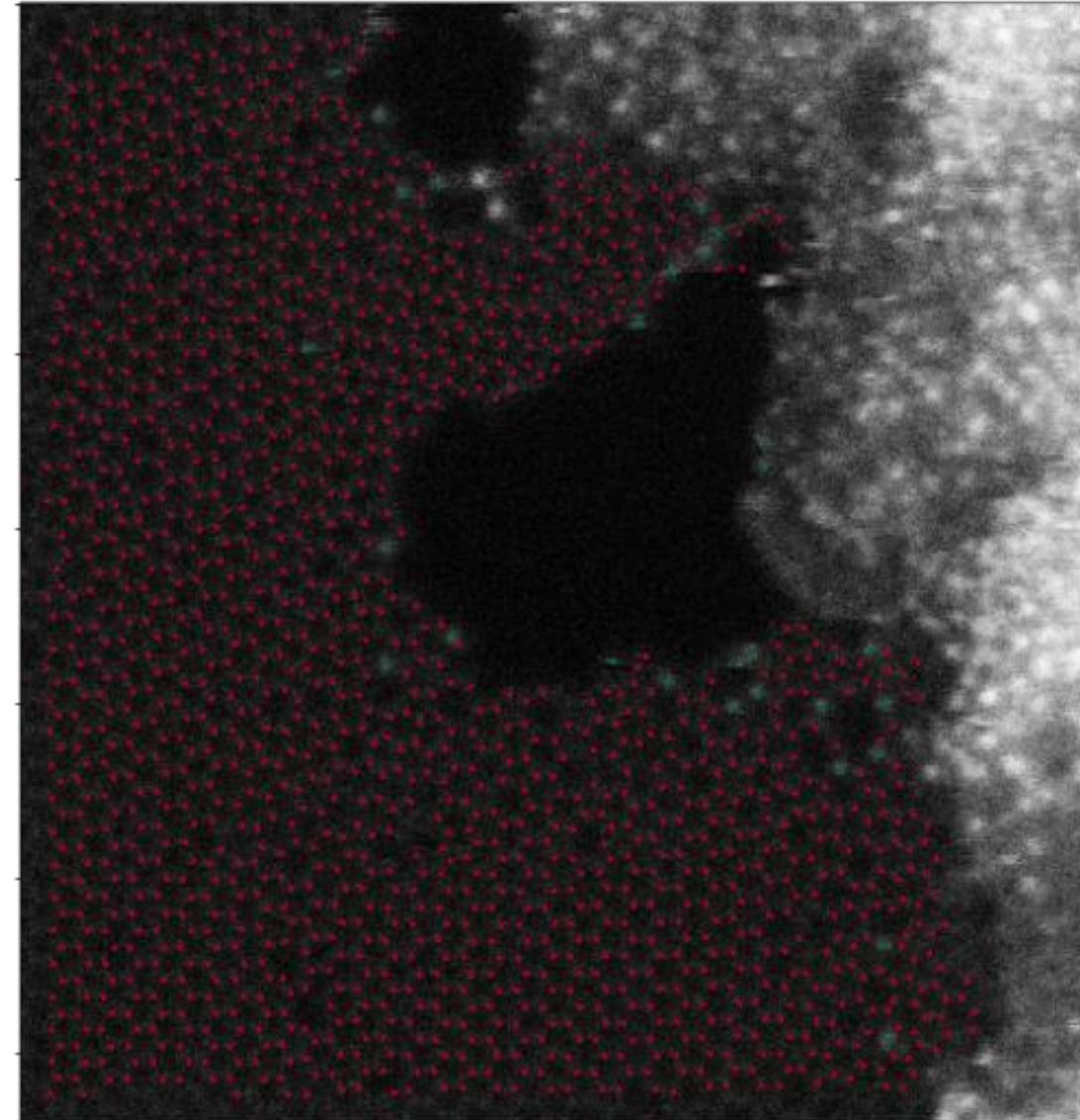
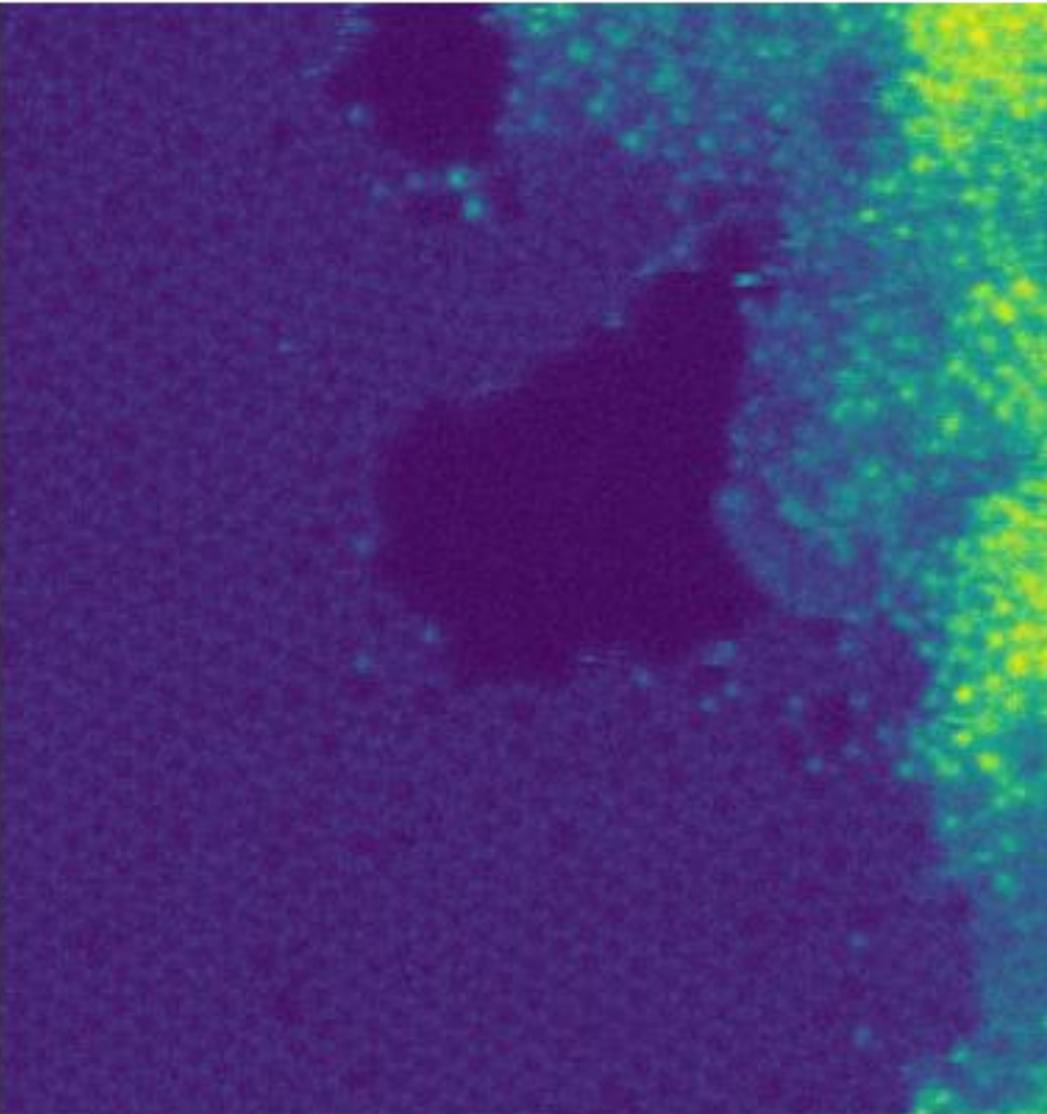
# Simple VAE



# Shift VAE: Translational Invariance

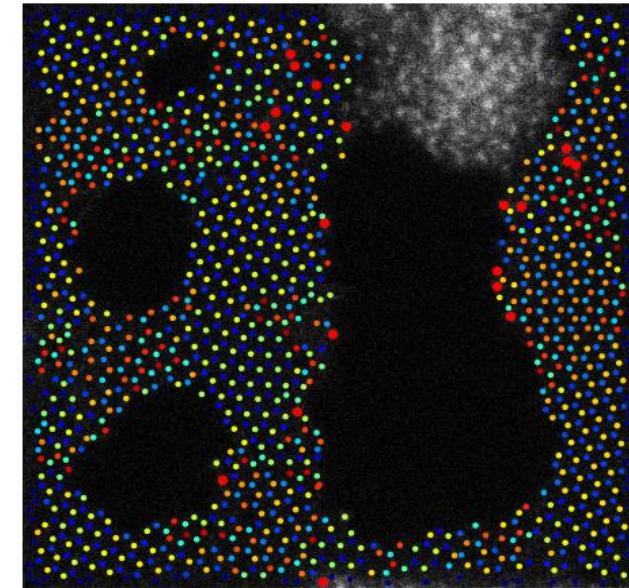
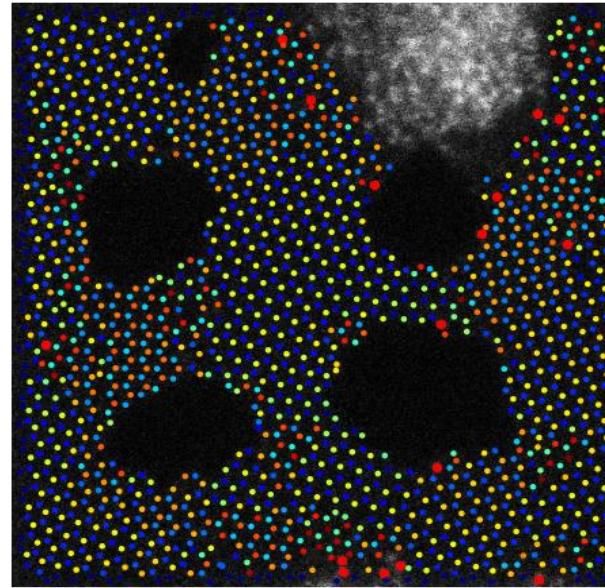
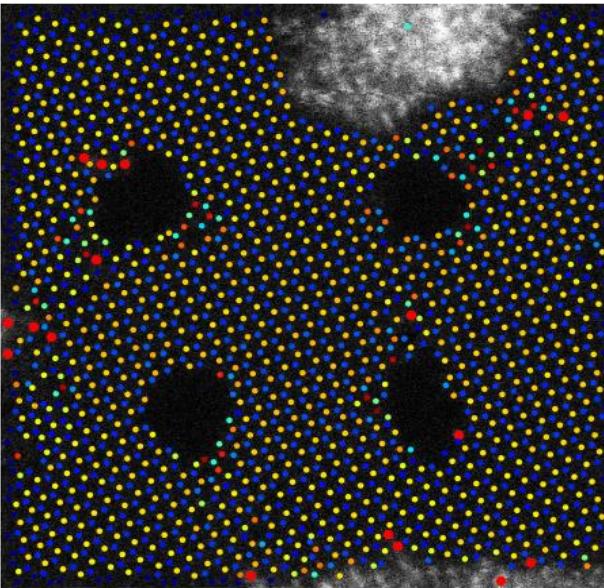


# Off to chemically-disordered systems

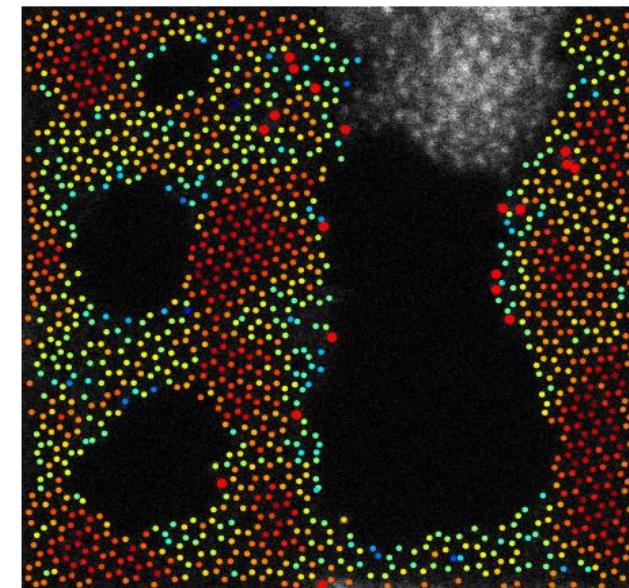
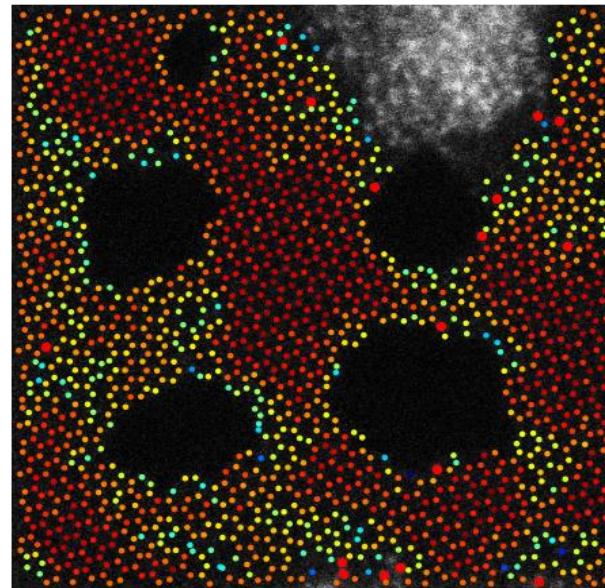
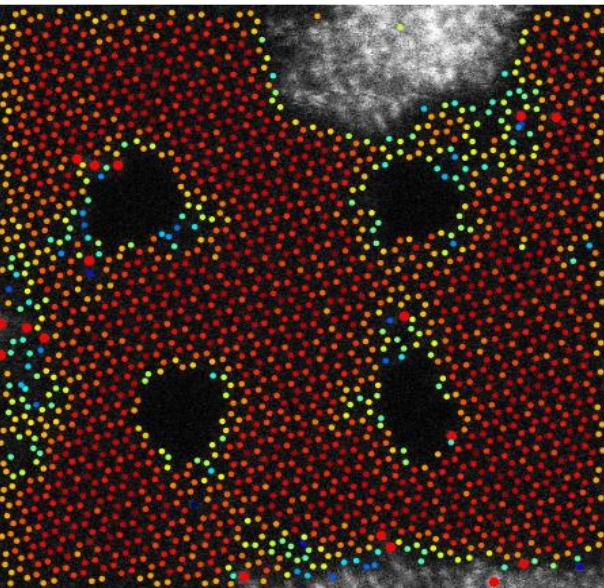


# rVAE analysis at different time steps

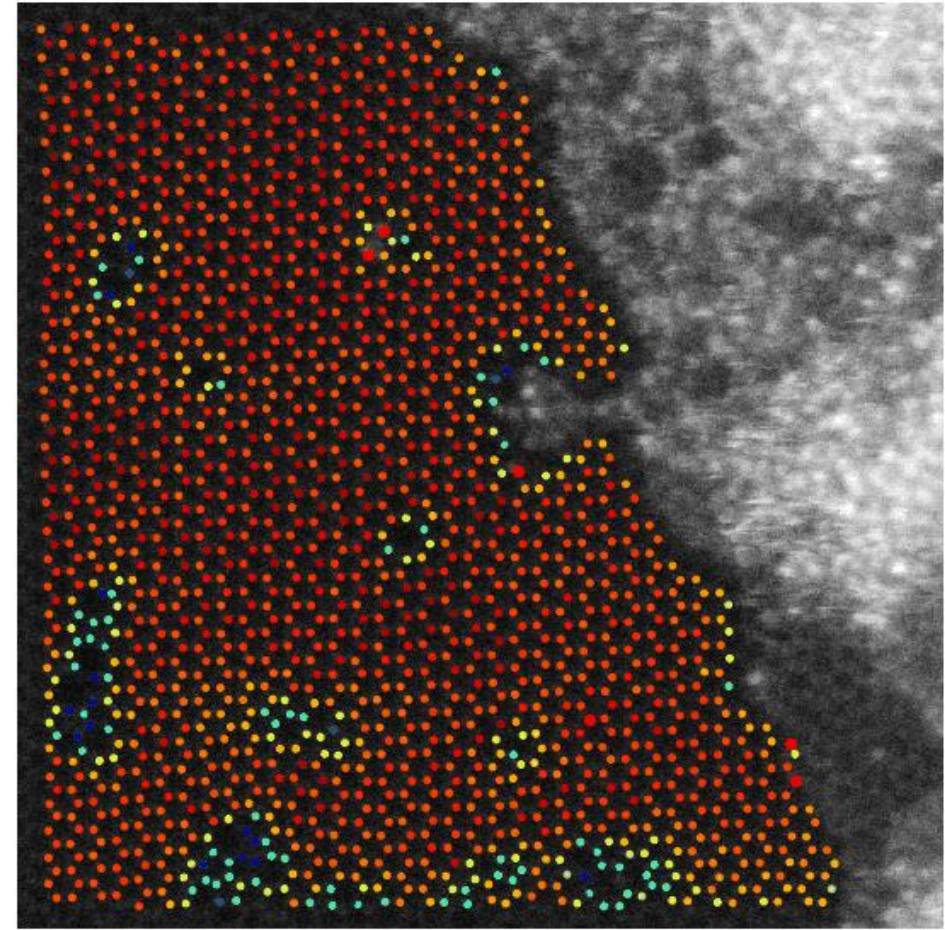
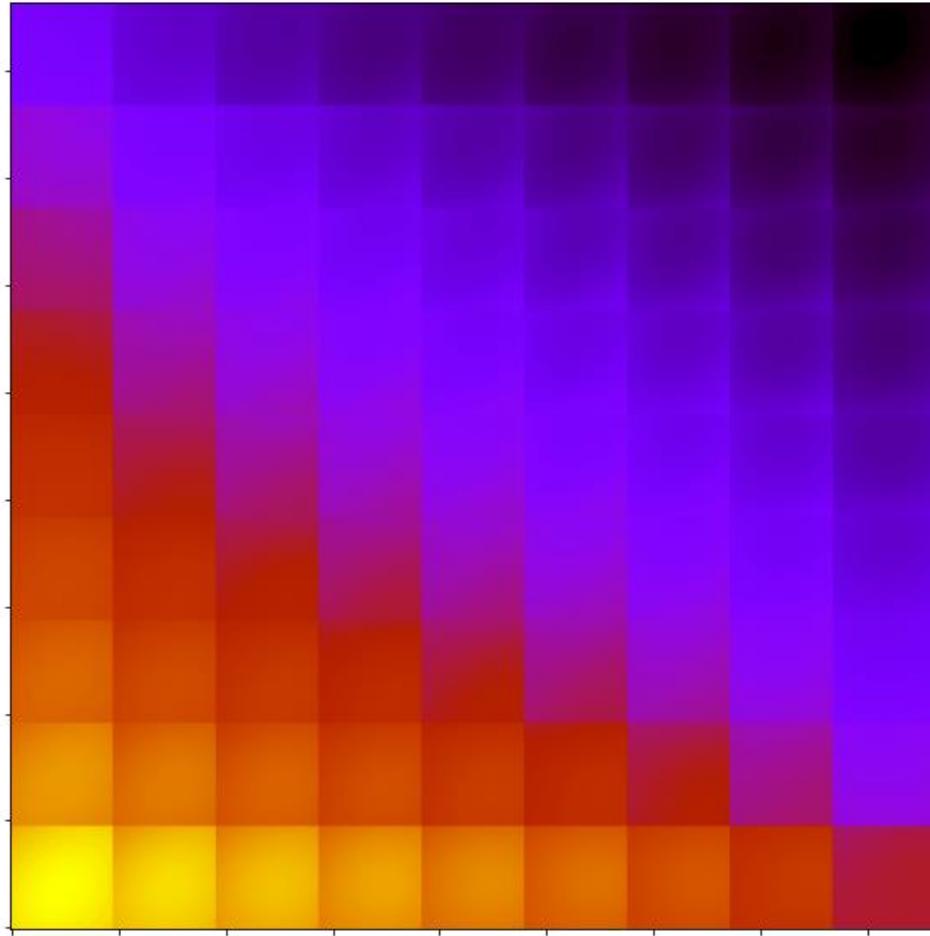
Angle



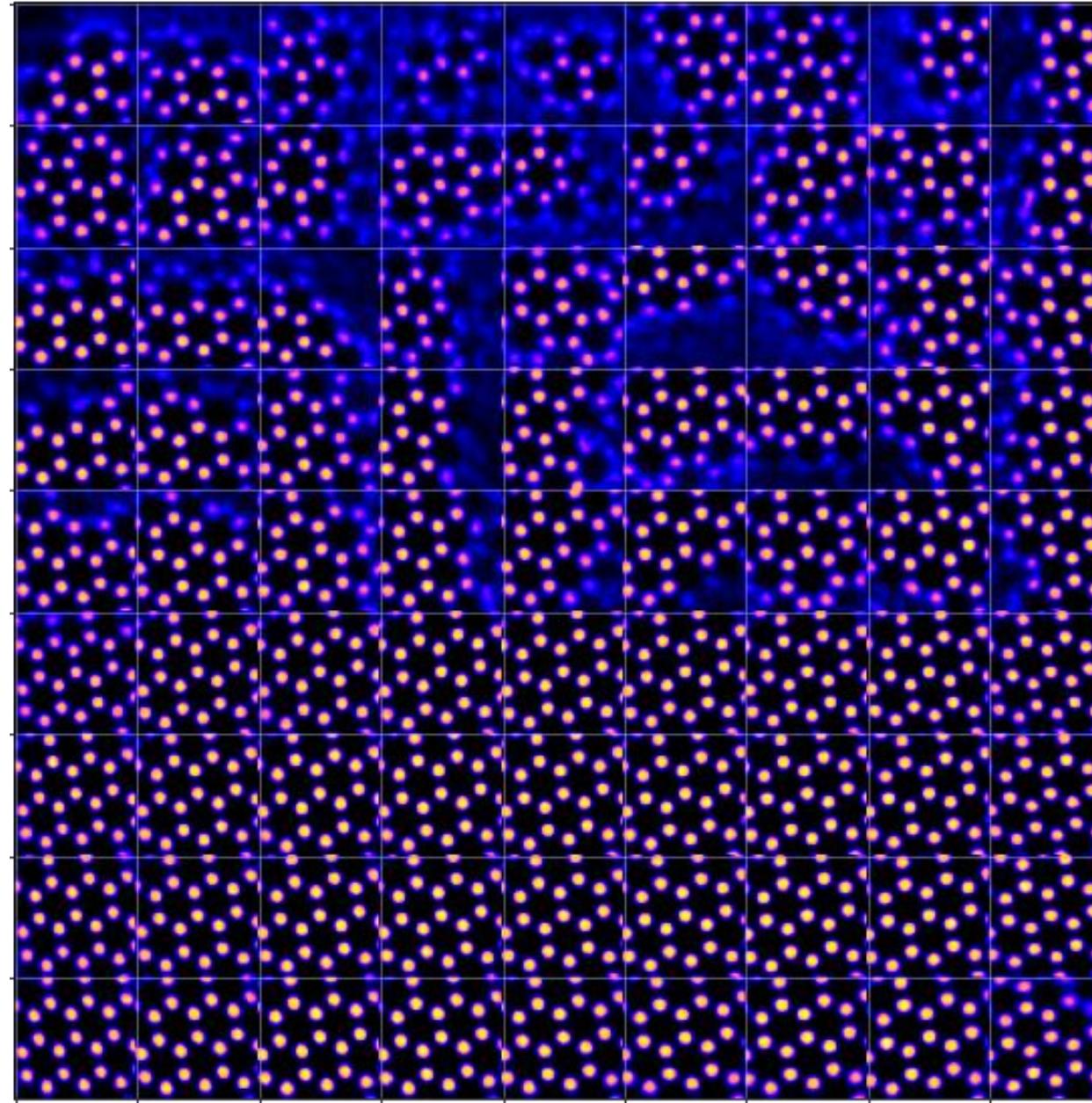
Latent variable



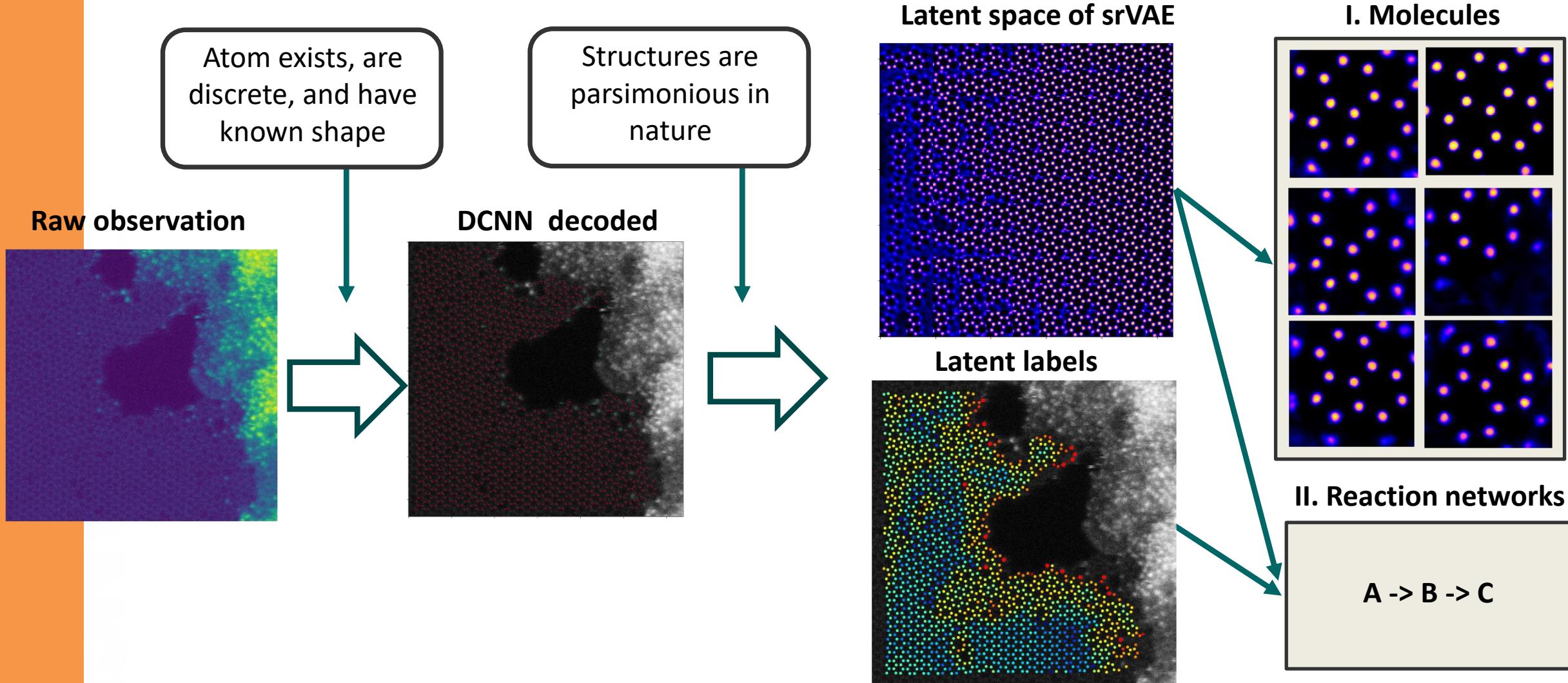
There is nothing as beautiful as training VAE



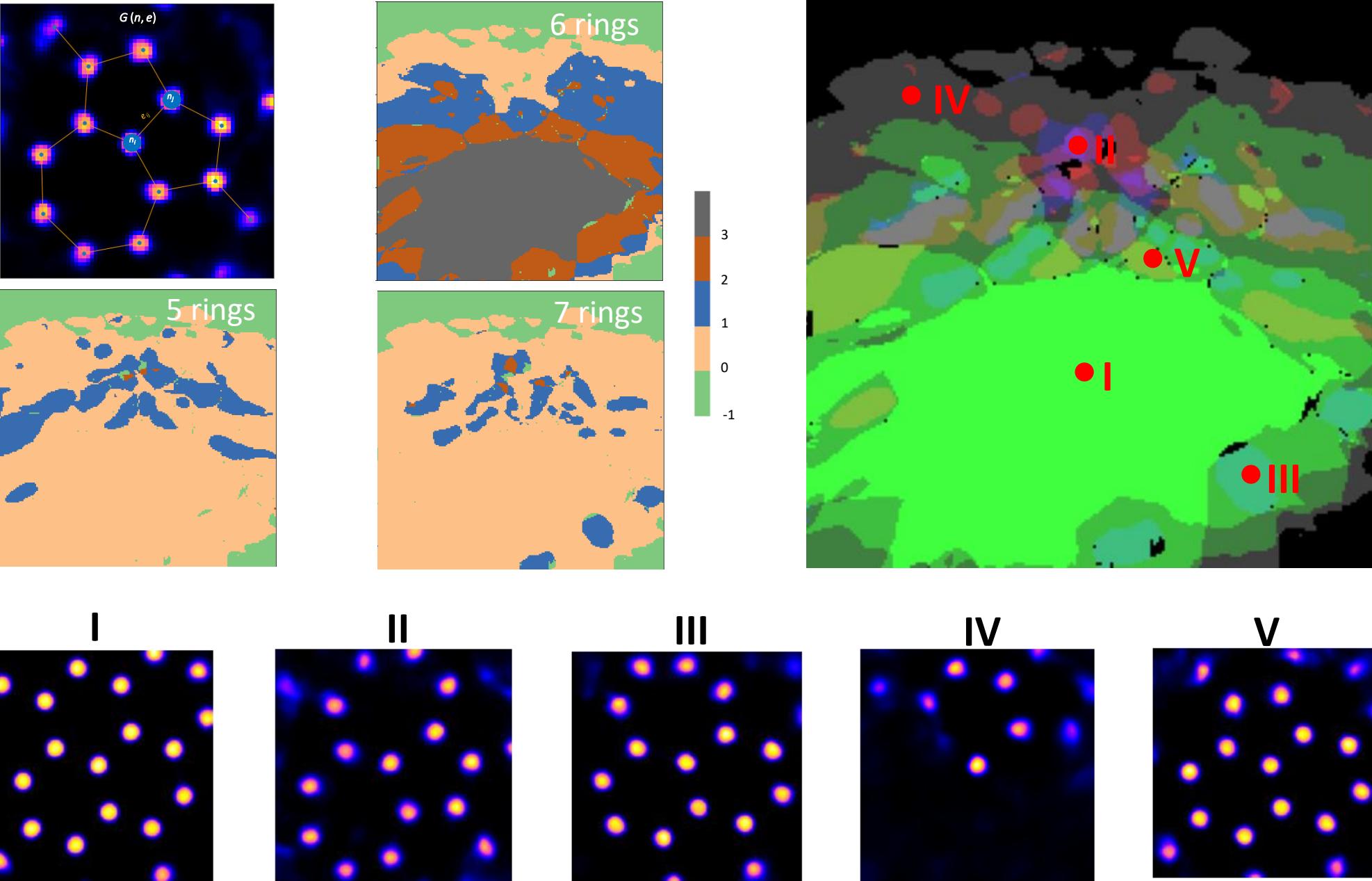
# Next step: skip-rVAE



# Unsupervised discovery of molecules

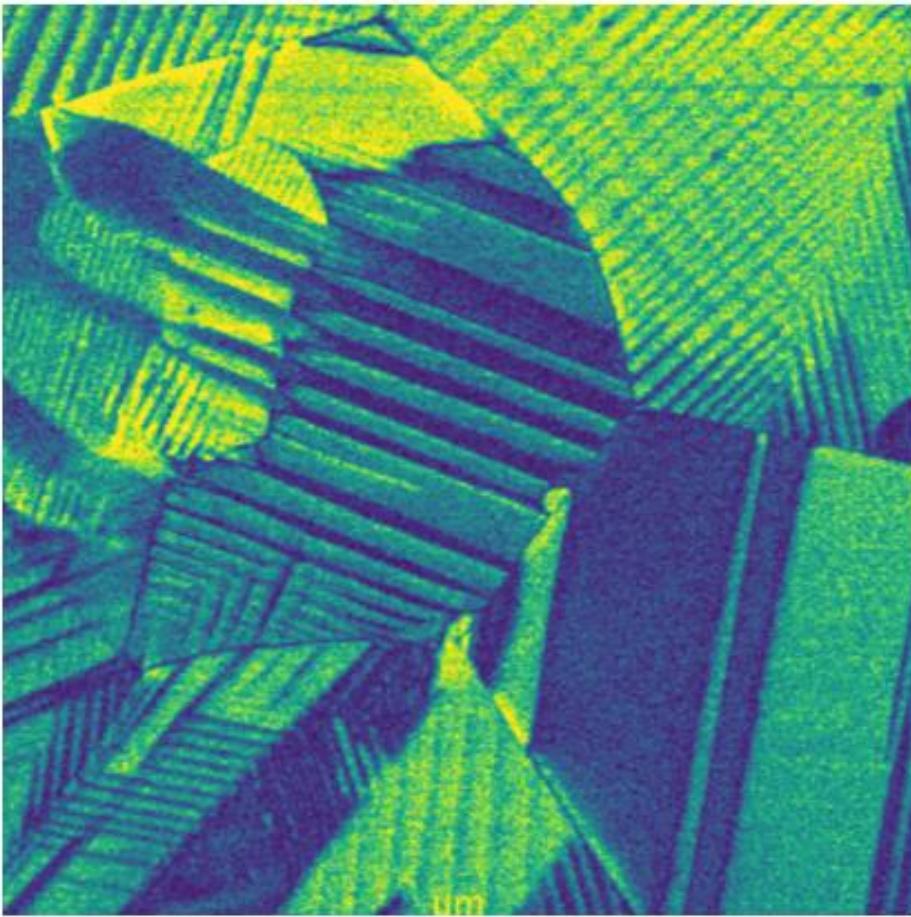


# Exploring the latent space structure

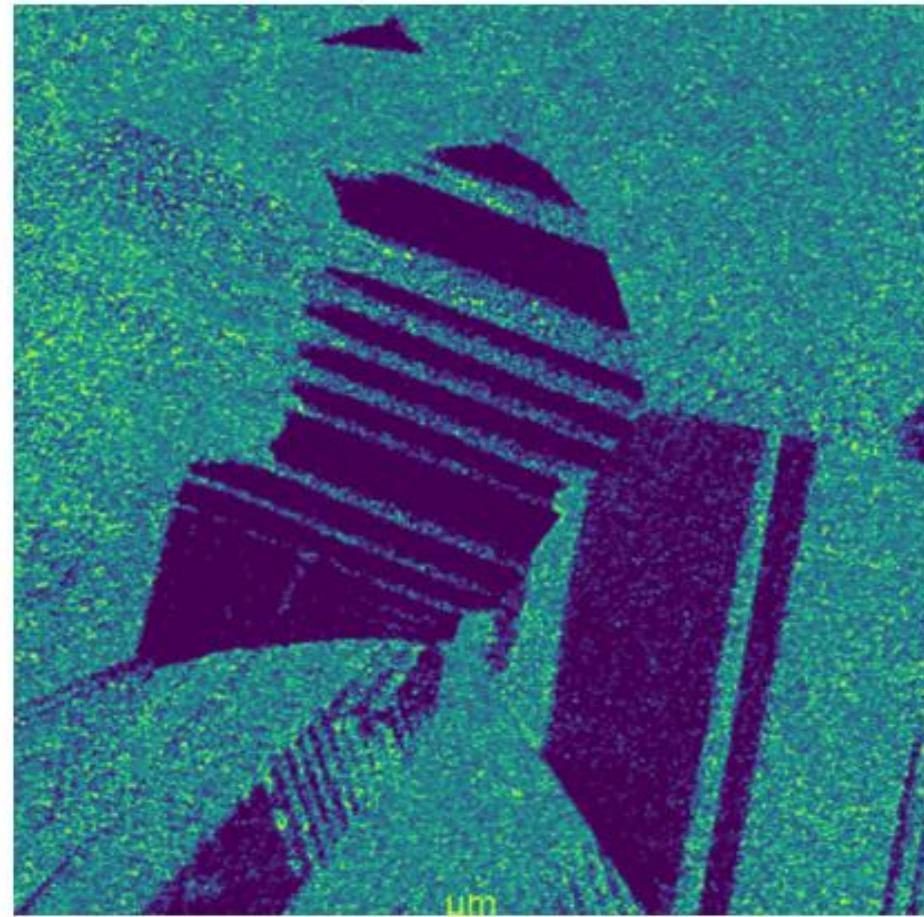


# Ferroelectric domain and domain walls

**Amplitude**



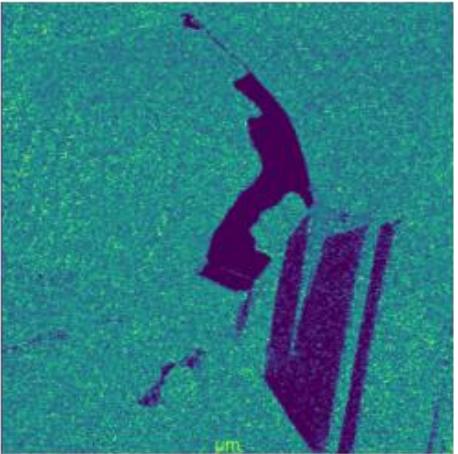
**Phase**



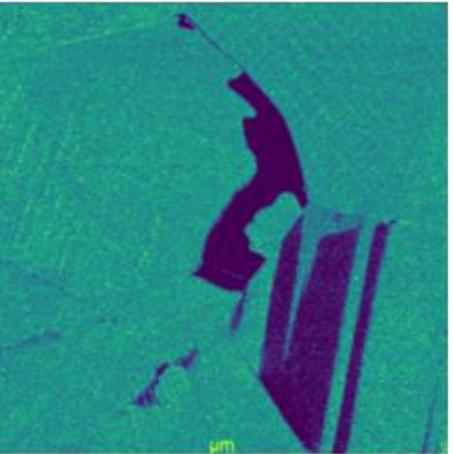
# Detecting domain walls

Canny filter

Phase Image



Gaussian Filter

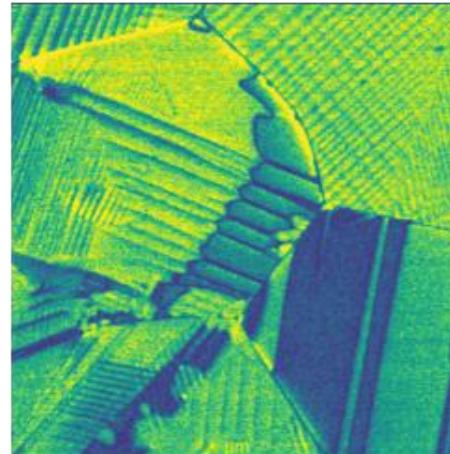


Wall by Canny Filter

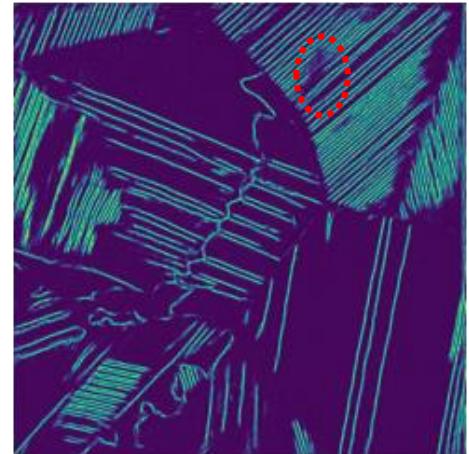


DCNN Prediction

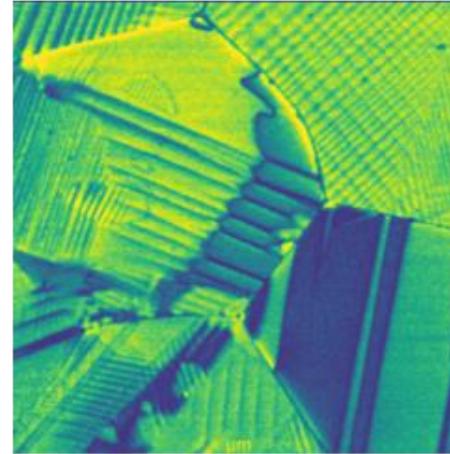
Image



Predicted



Gaussian Filter

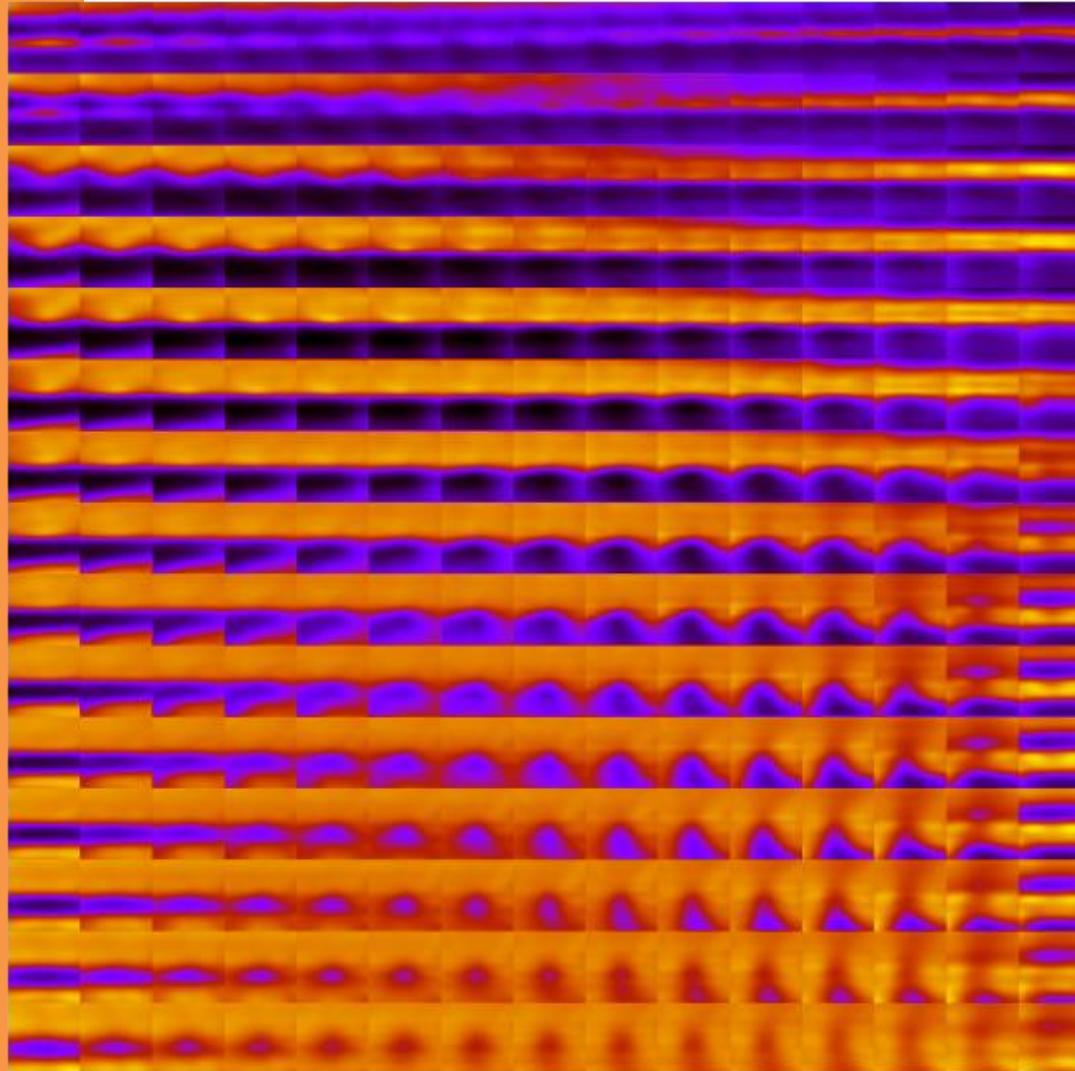


Gaussian Filter and Predicted

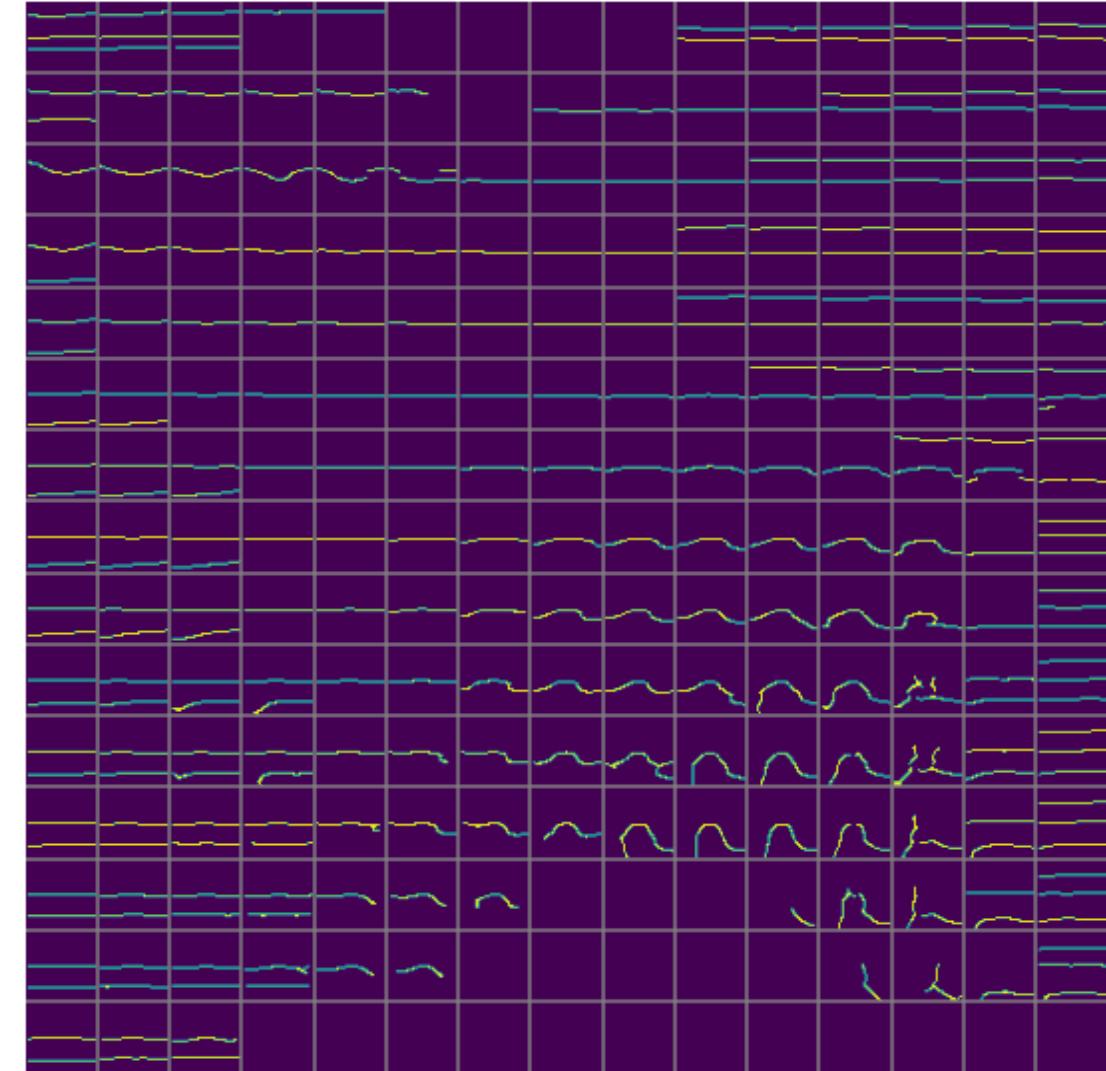


# rVAE analysis

**Latent Space**

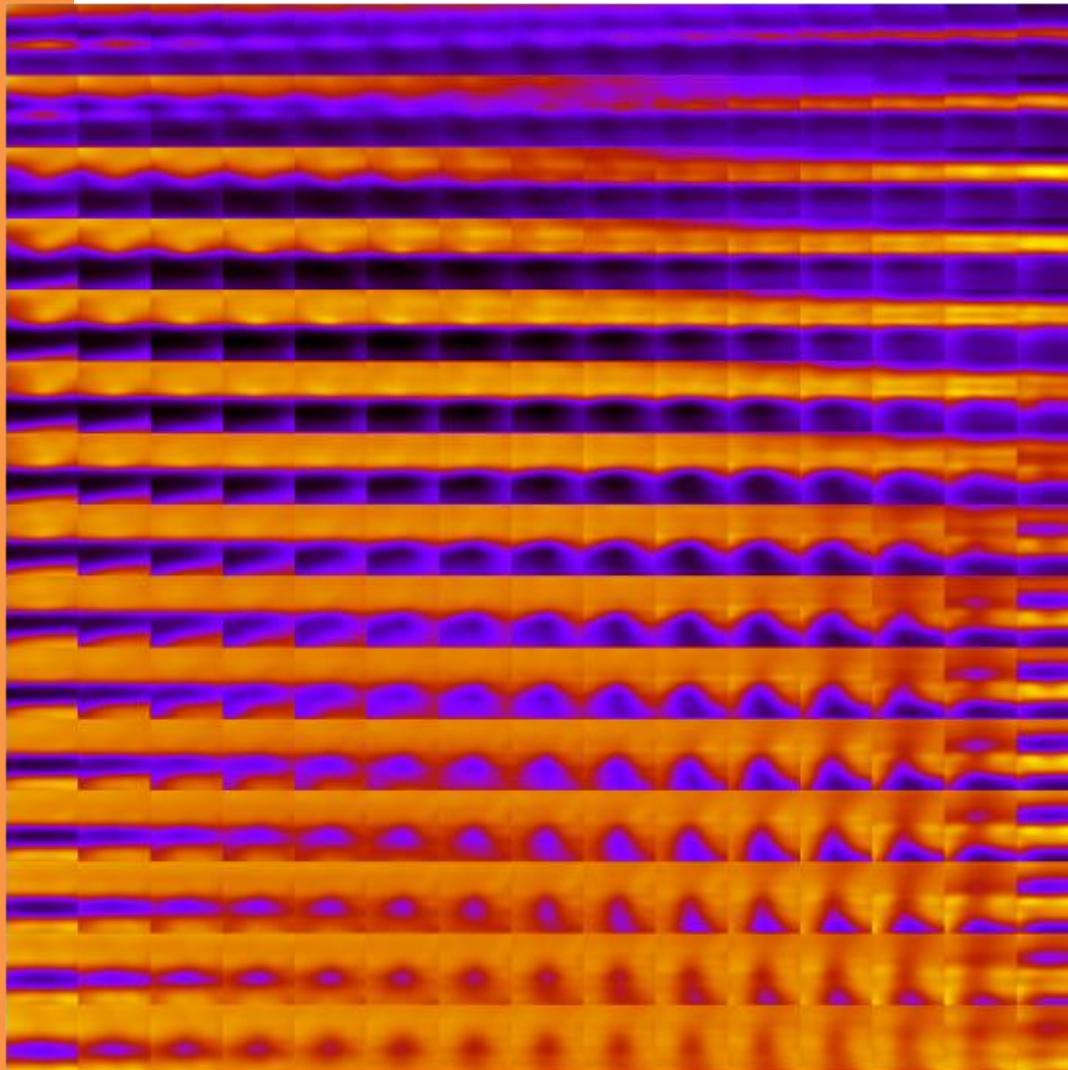


**Domain Walls**

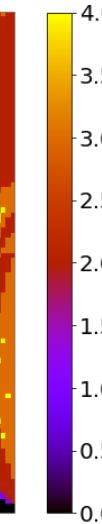
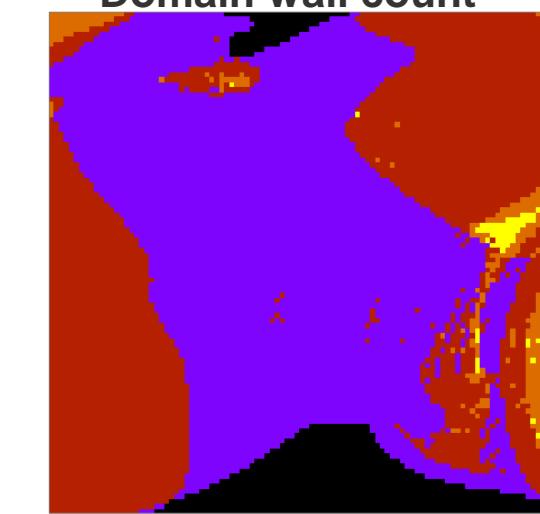


# rVAE latent space

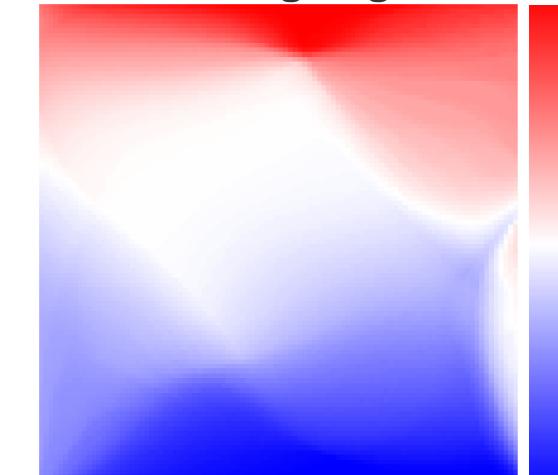
Latent Space



Domain wall count

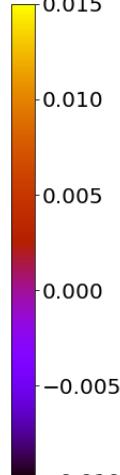
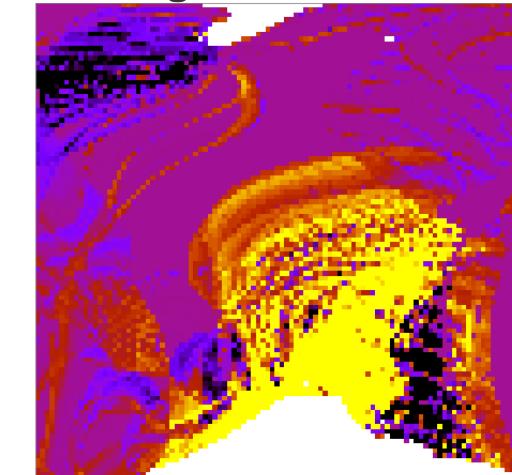


Switching degree



switched  
unswitched

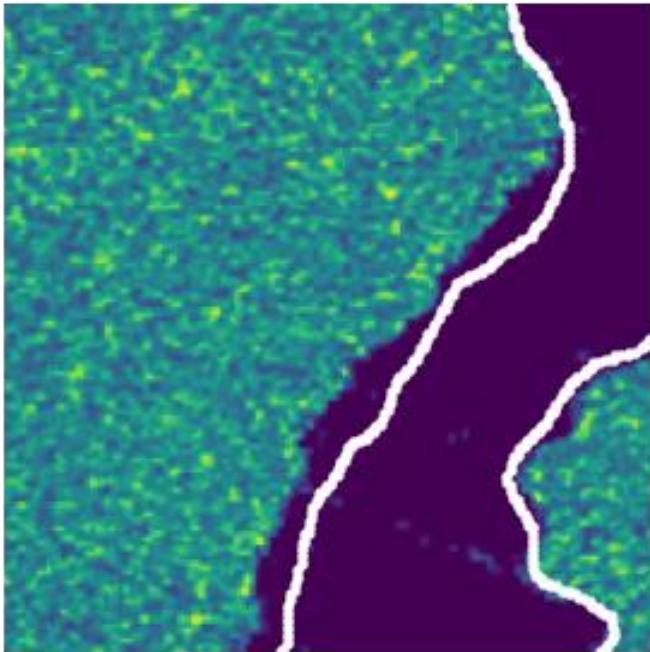
Average wall curvature



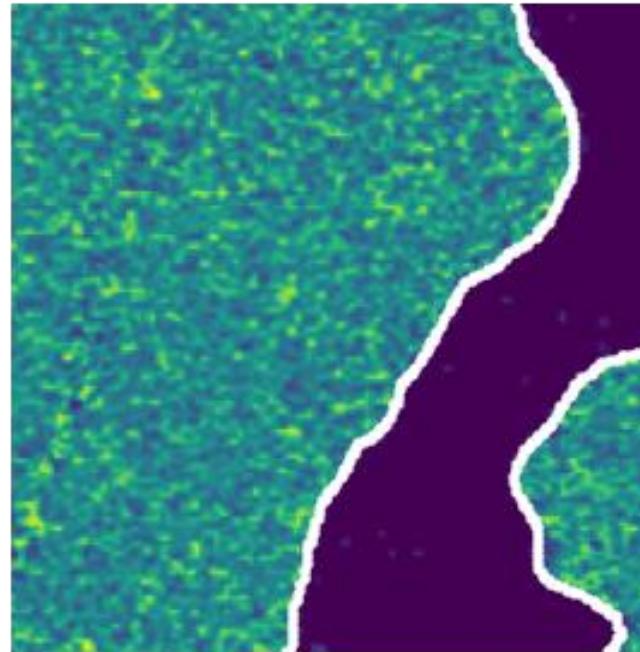
# rVAE with time delay

Training dataset

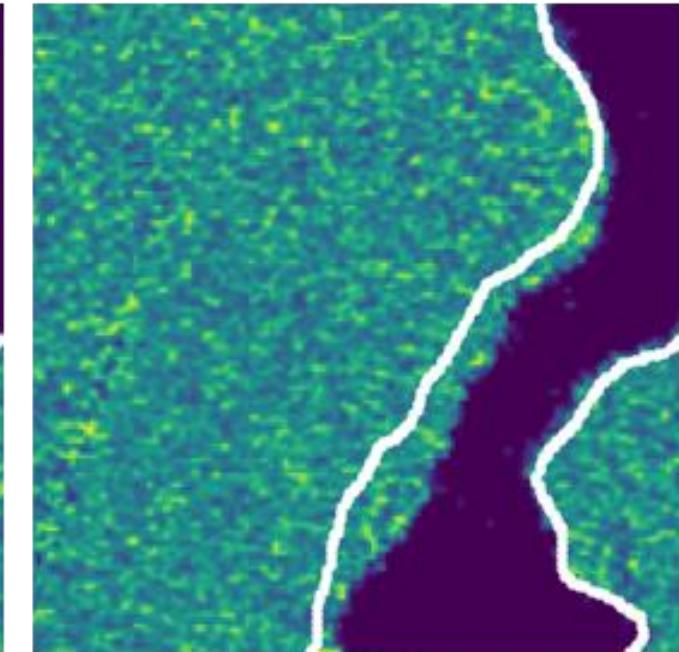
$t - dt$



$t$

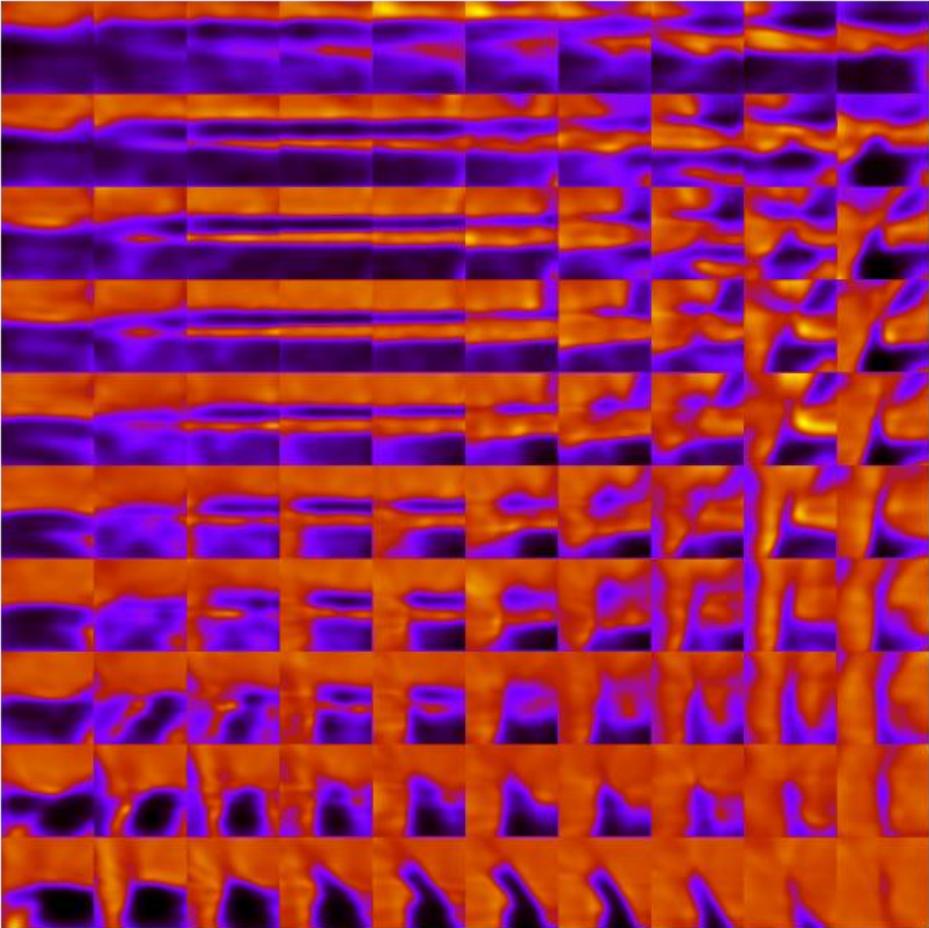


$t + dt$

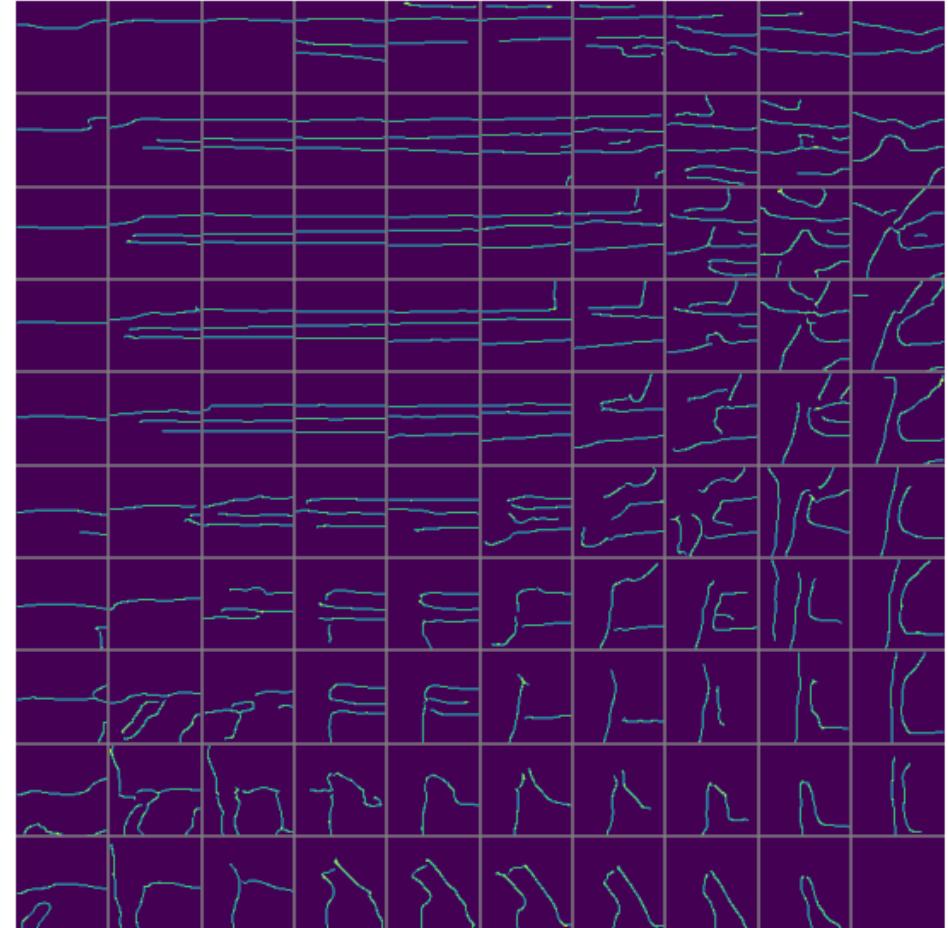


# rVAE with time delay

Latent space

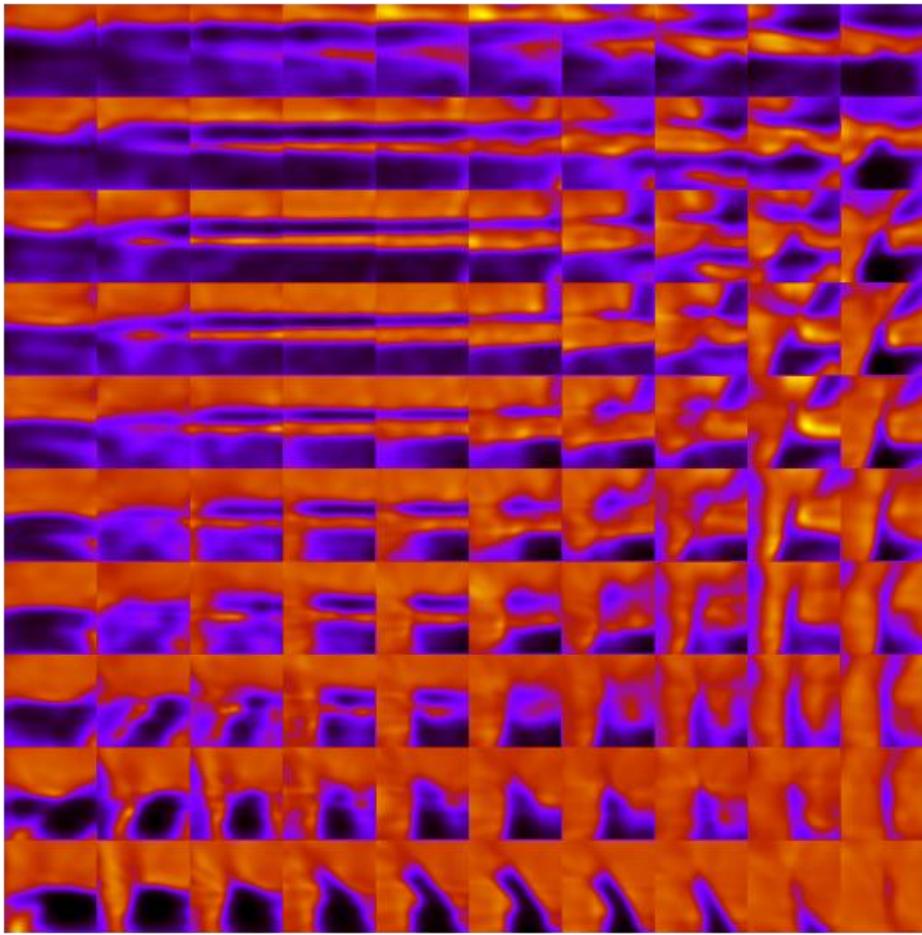


Domain wall

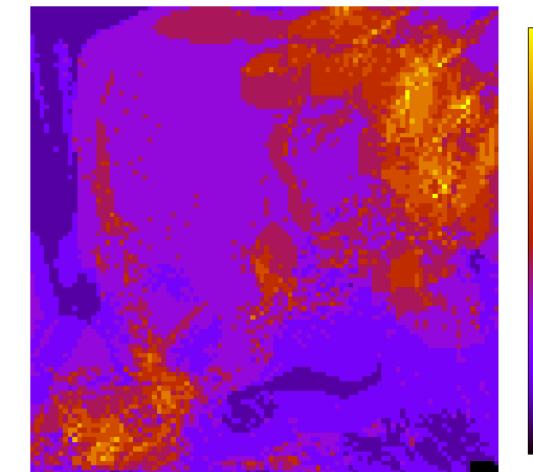


# rVAE with time delay

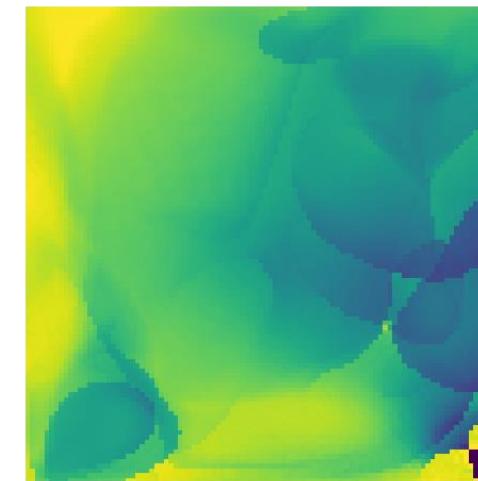
Latent space



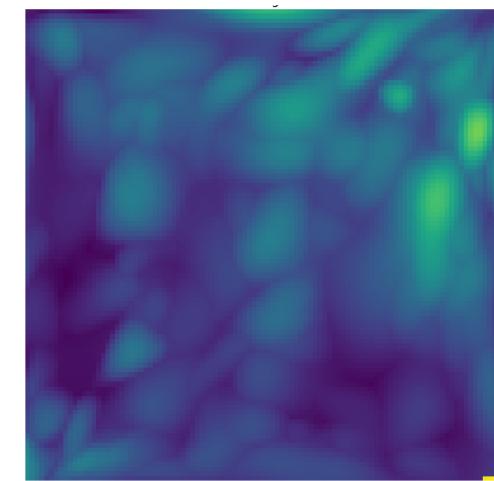
Wall count



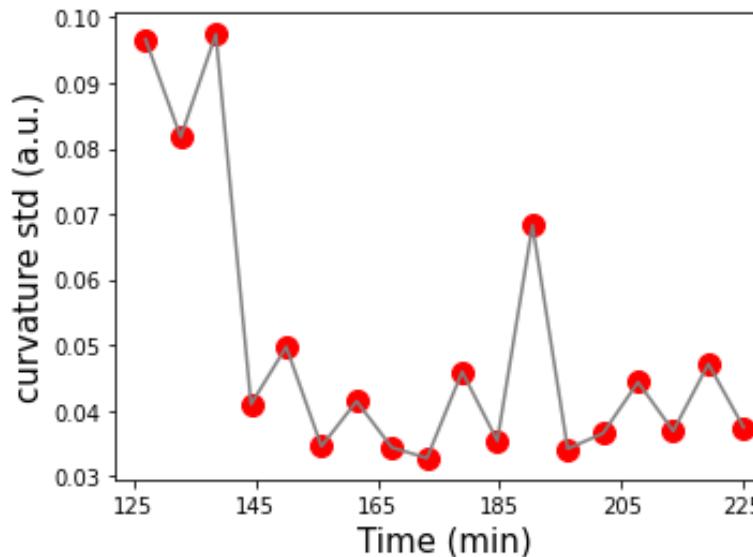
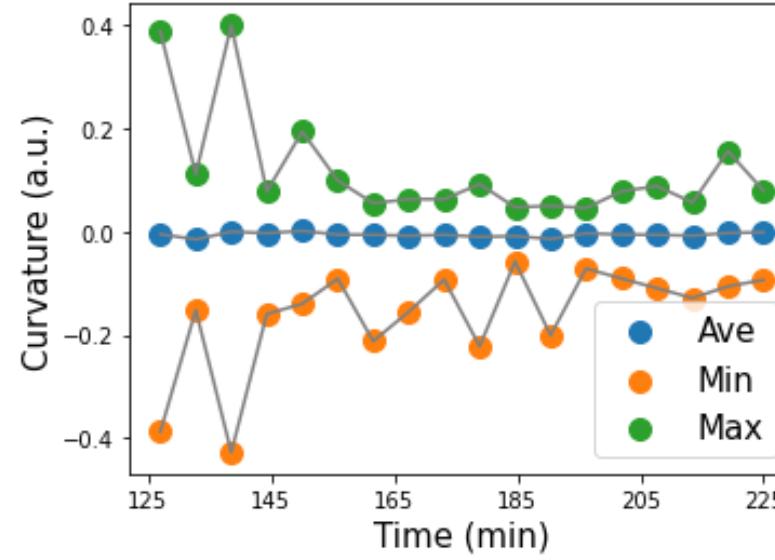
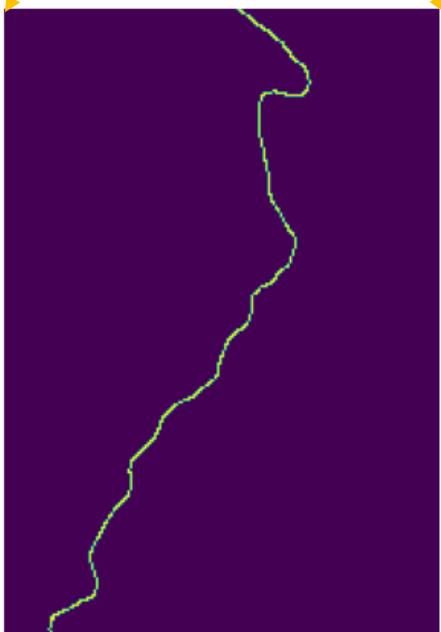
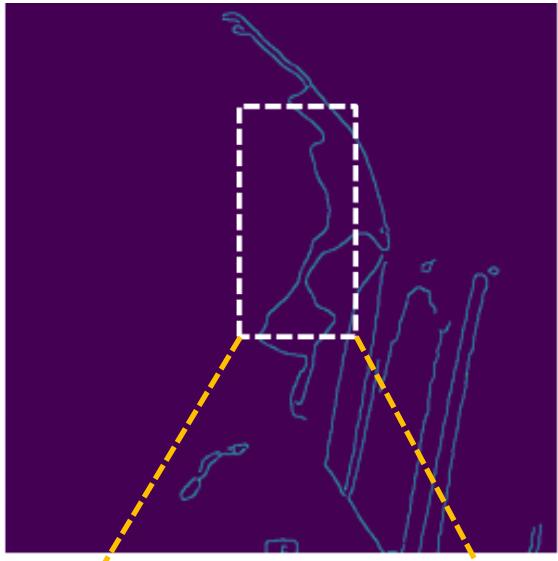
Domain convex



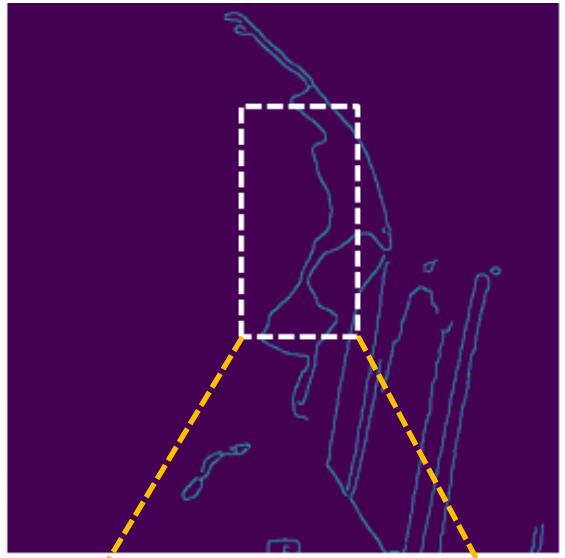
Switch significance



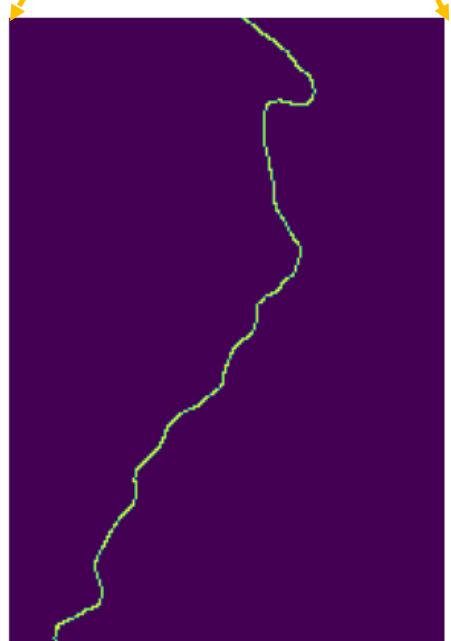
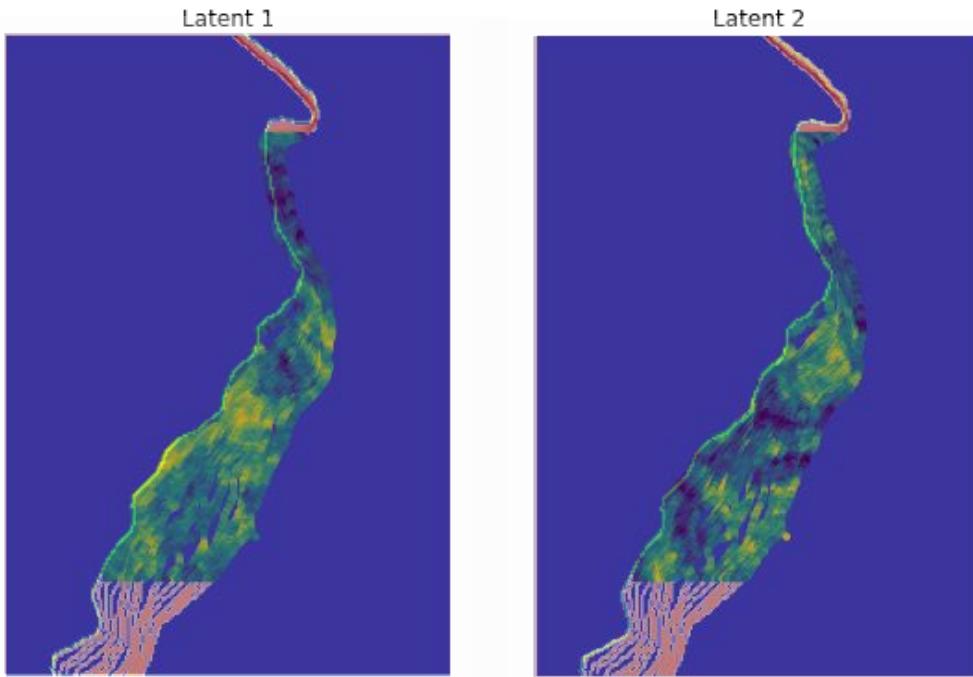
# Domain wall evolution



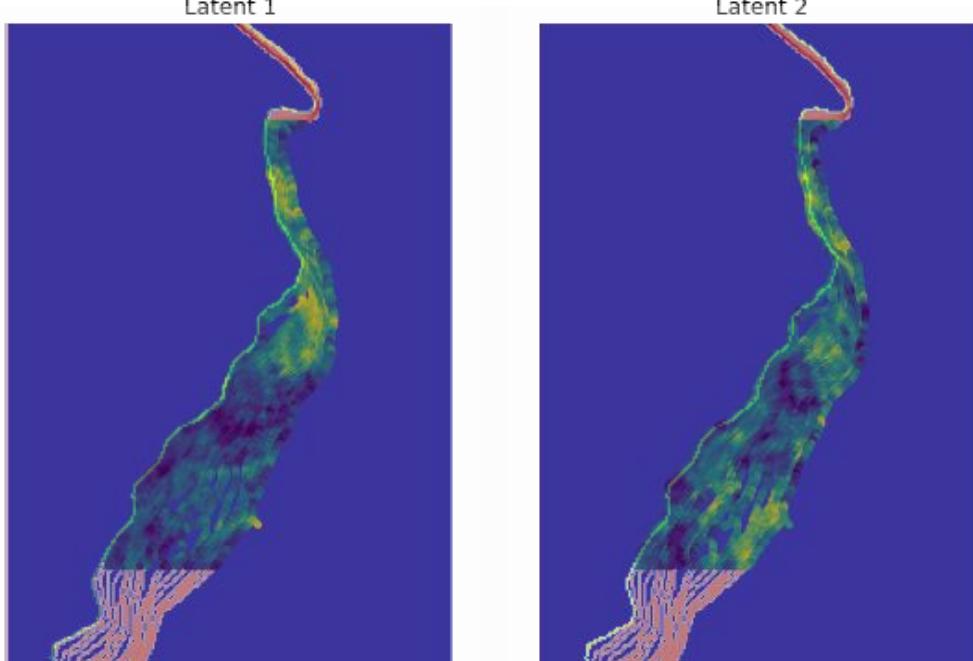
# Domain wall evolution



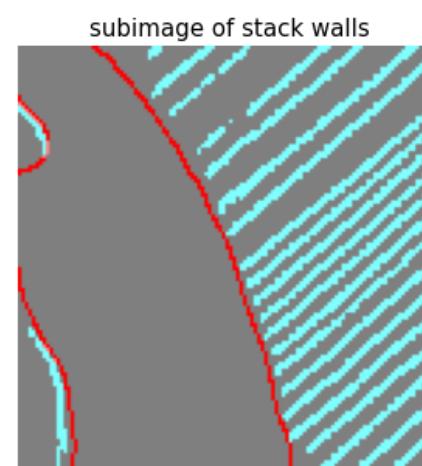
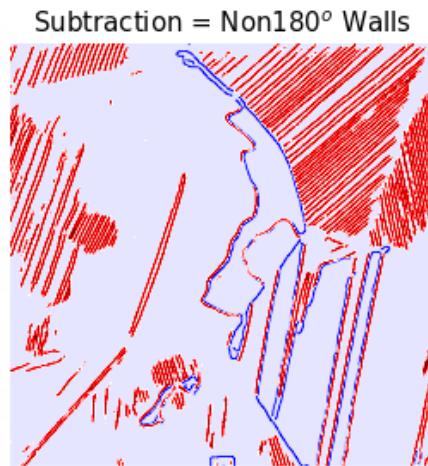
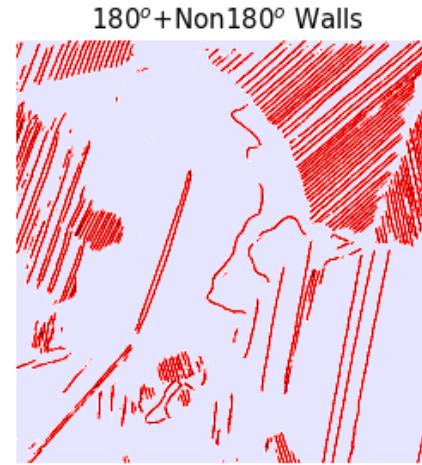
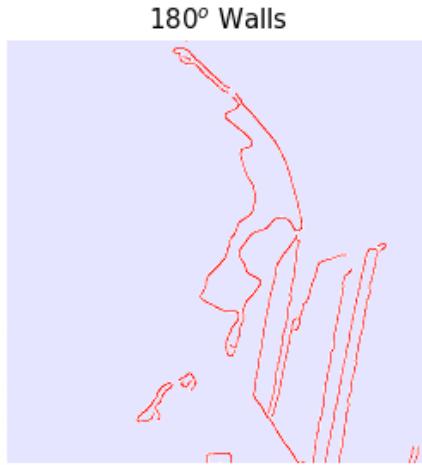
Forward:  
 $t$  vs  $t+1$



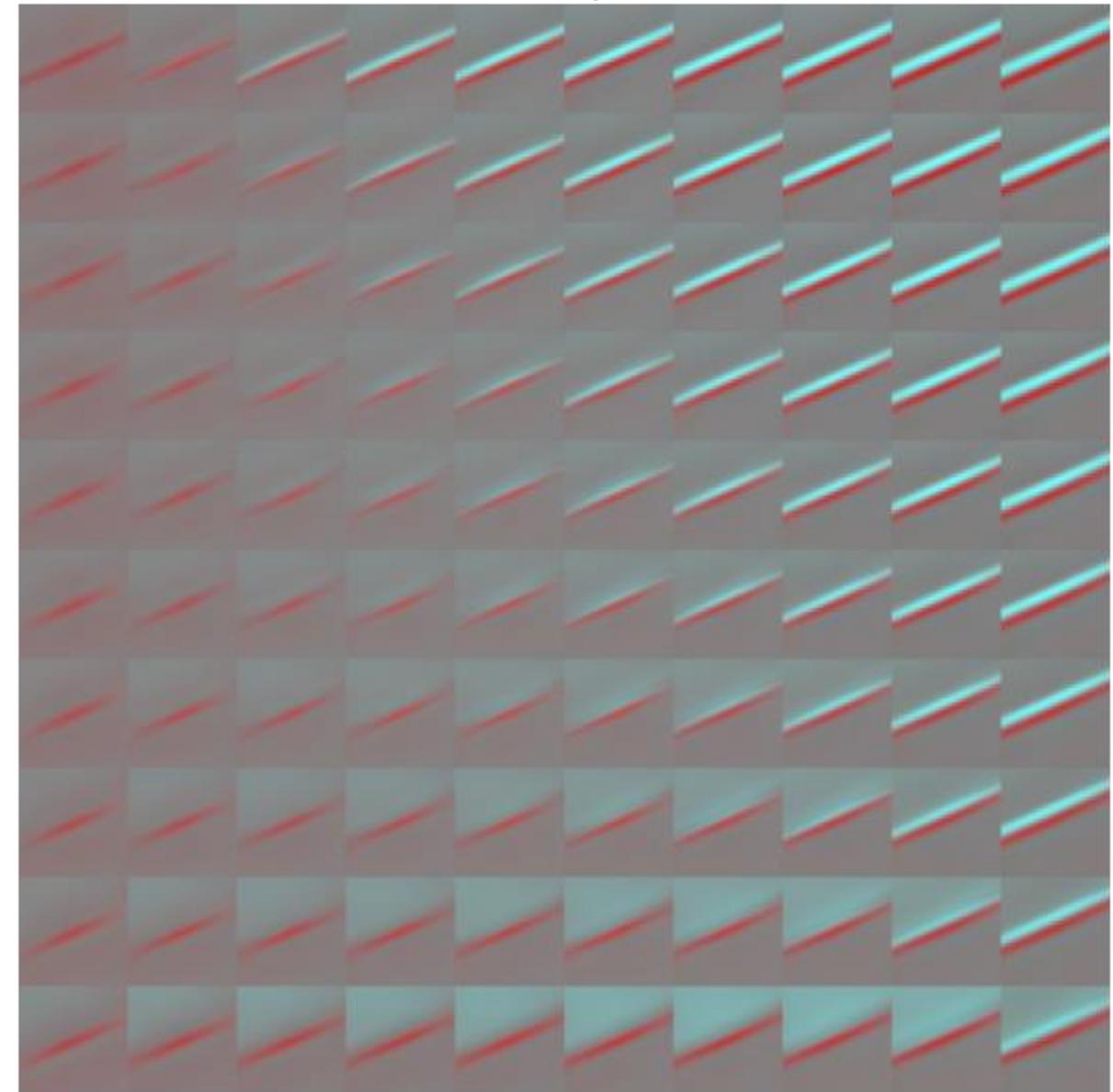
Reverse:  
 $t$  vs  $t+1$



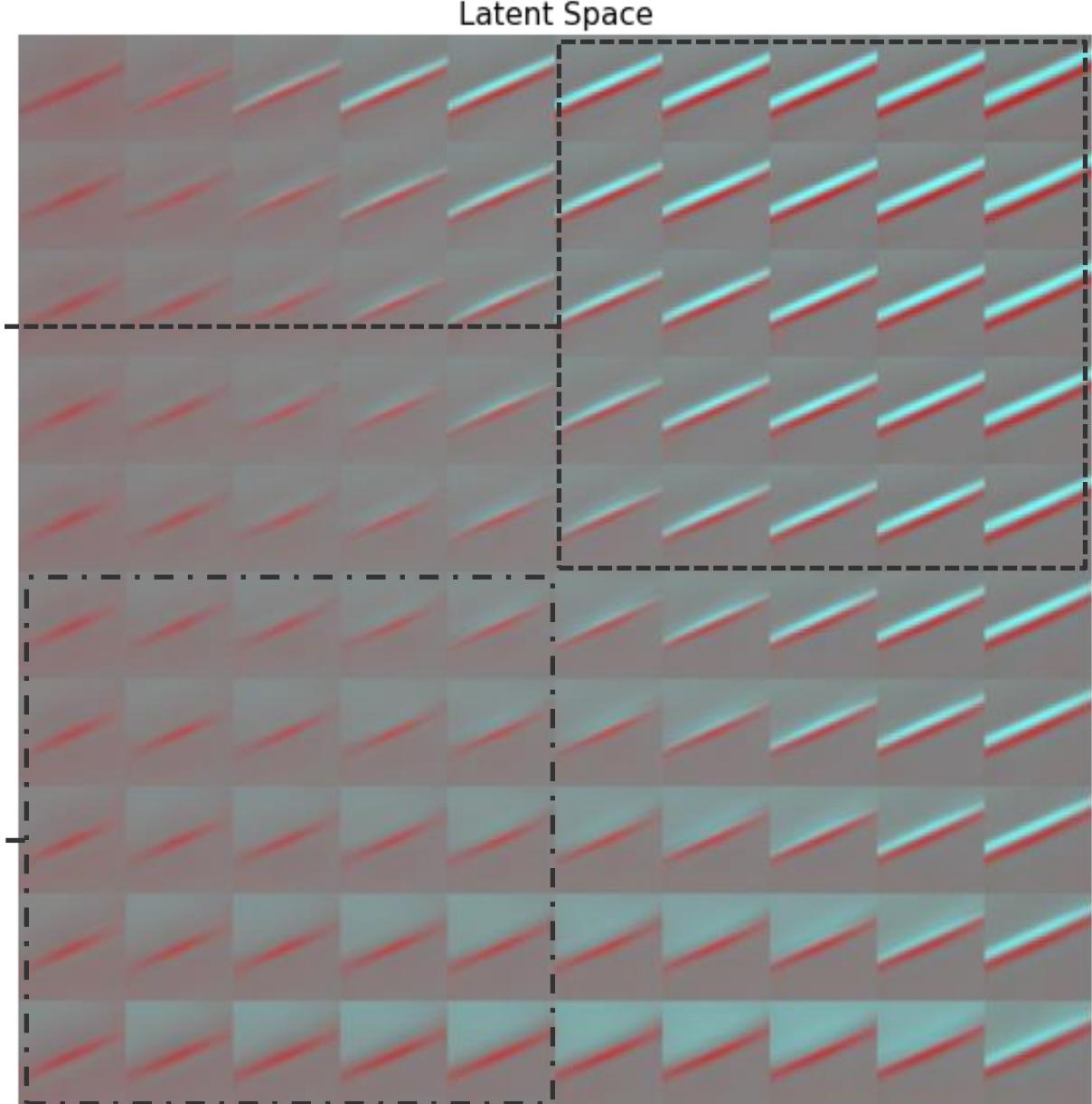
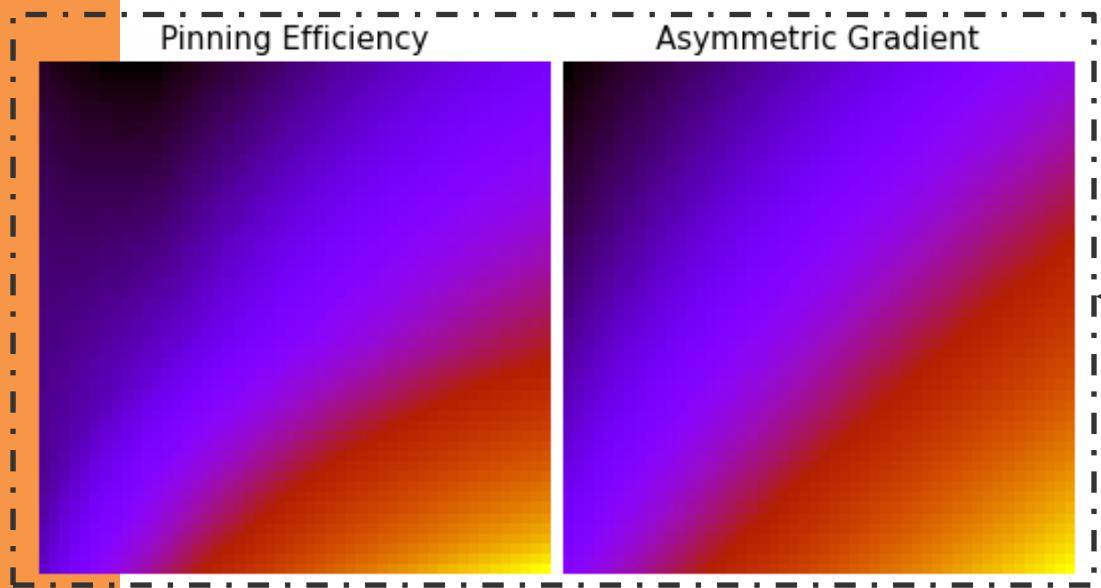
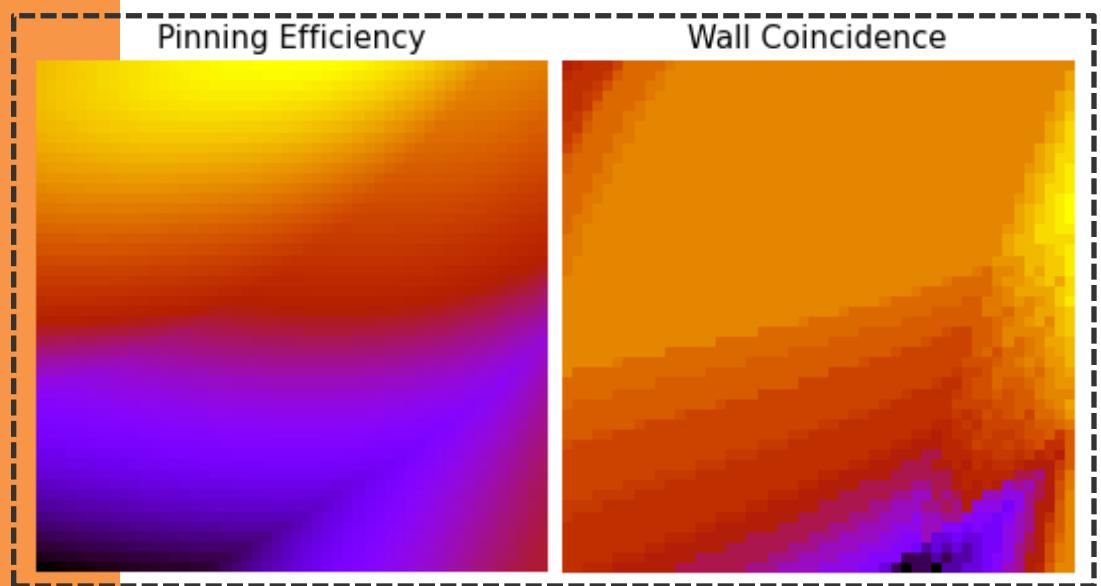
# Multilayer rVAE



Latent Space

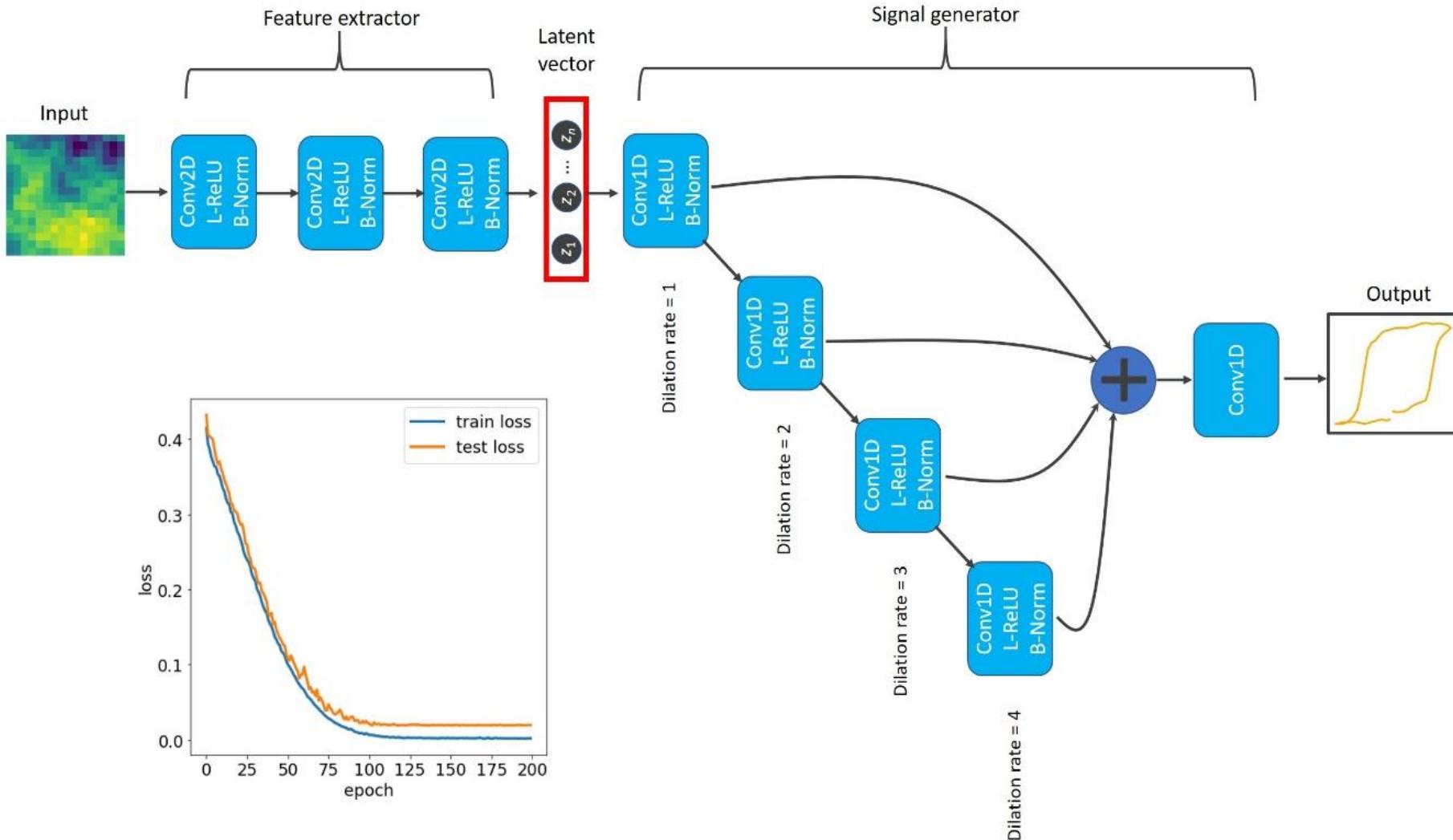


# Pinning mechanism



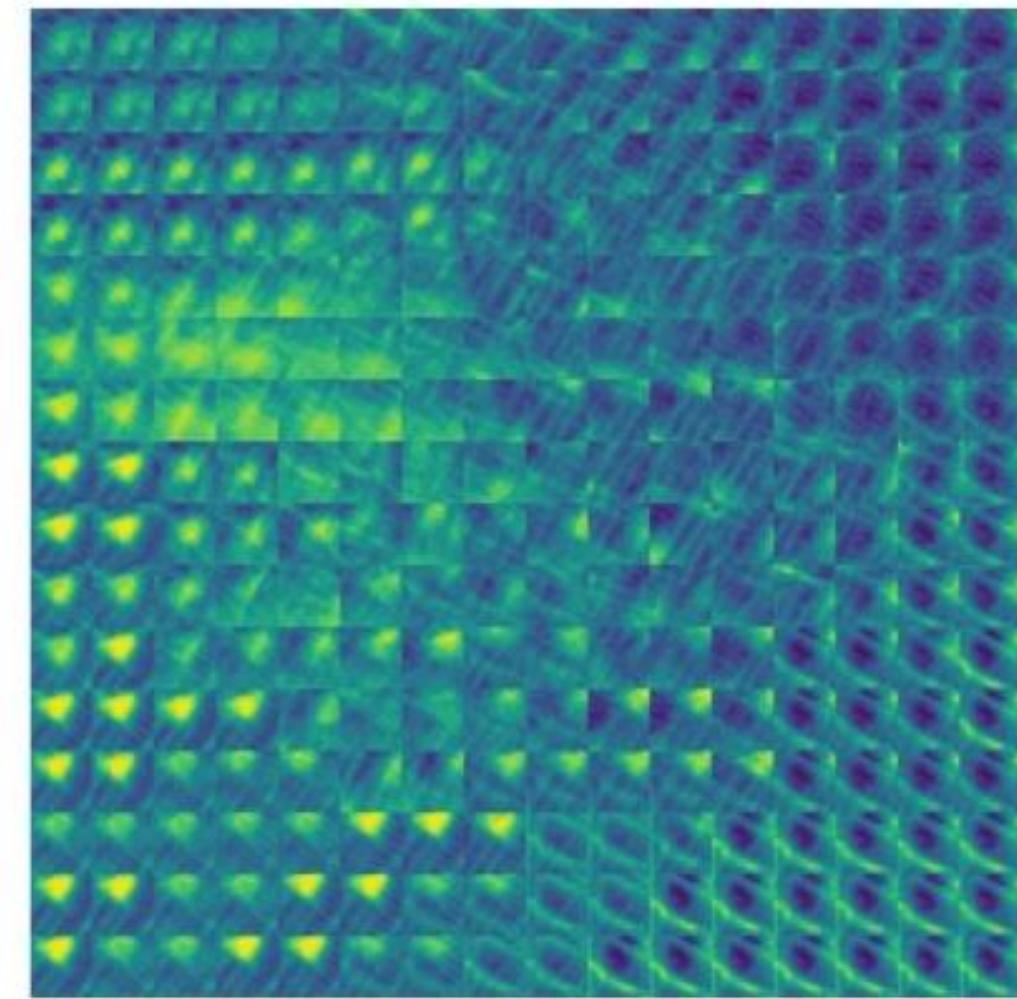
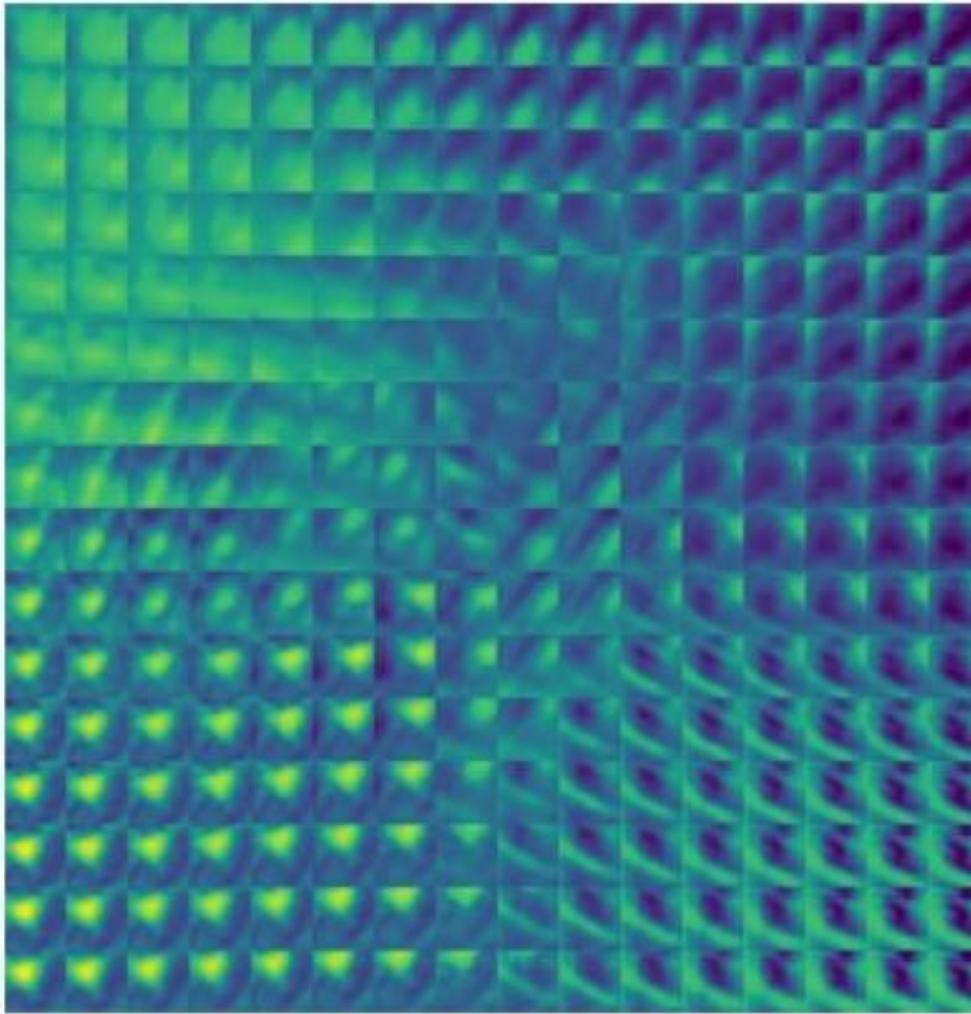
color scale

# Encoders-Decoders

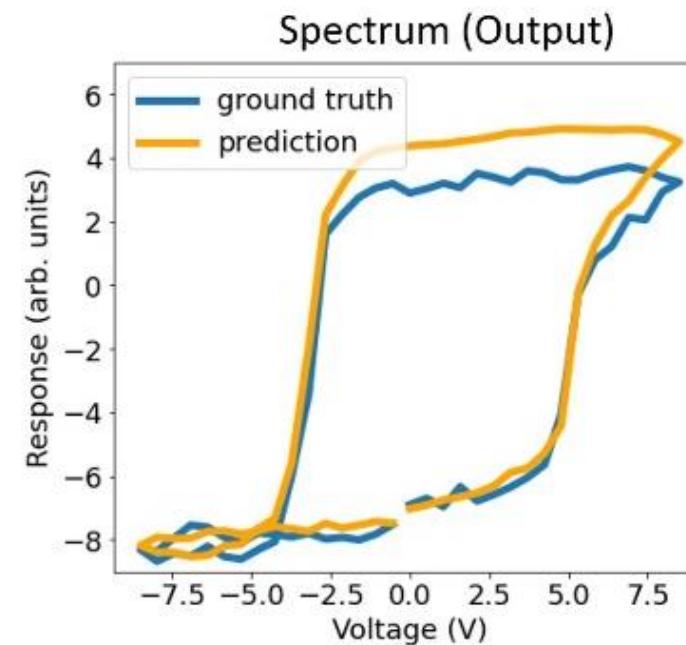
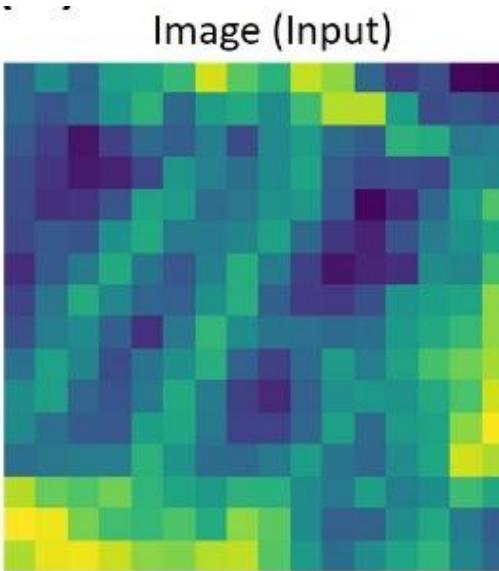
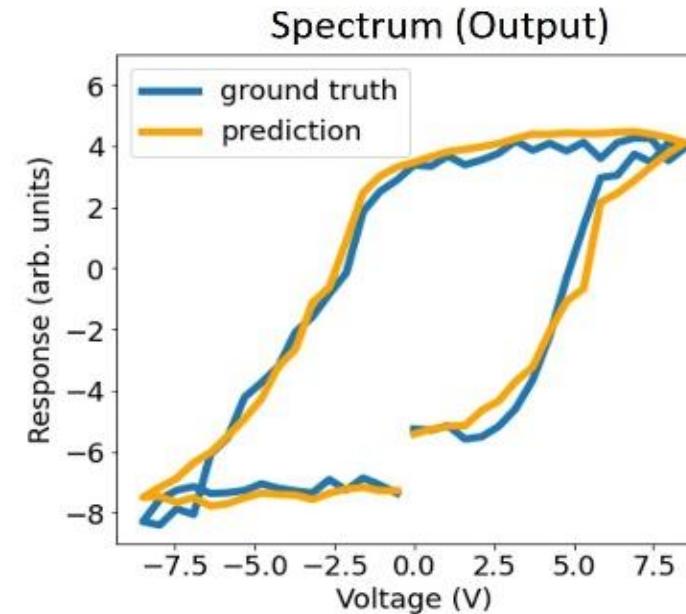
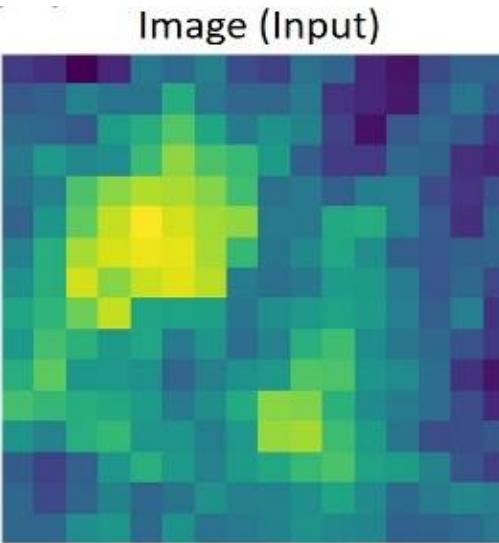


- Use encoder-decoder architecture to transform local structure to local spectra
- And spectra to images
- Predictive within the image

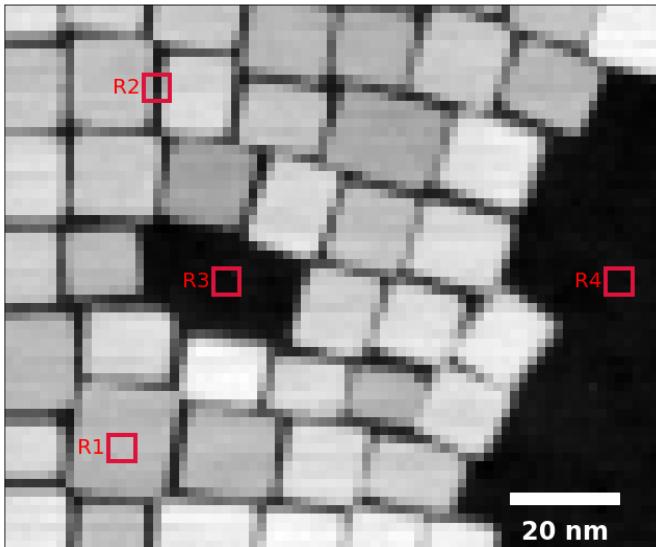
# Latent space



# Prediction

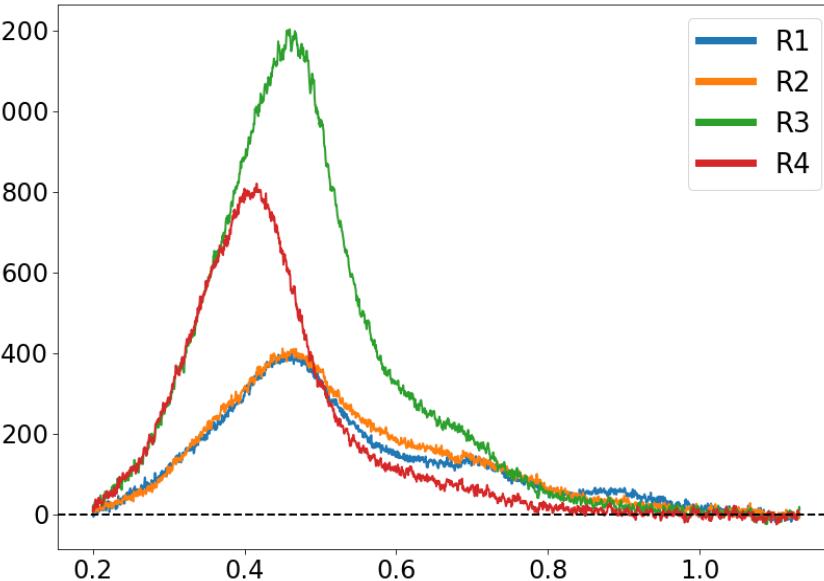


# Plasmonic nanoparticles



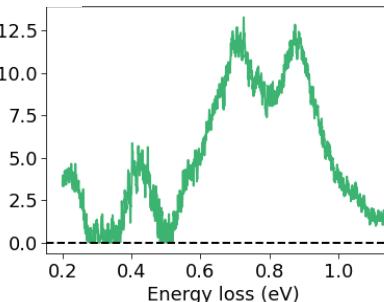
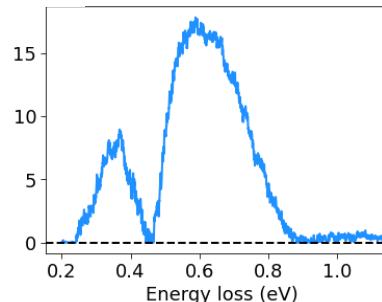
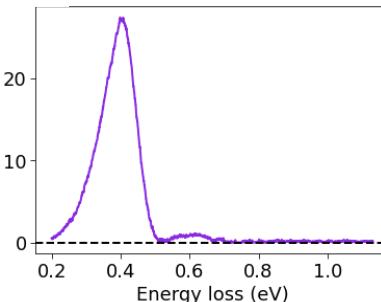
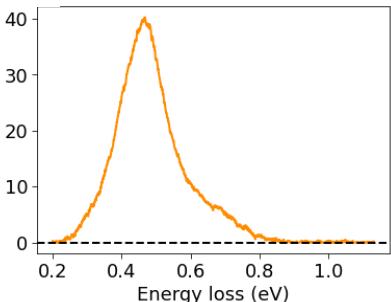
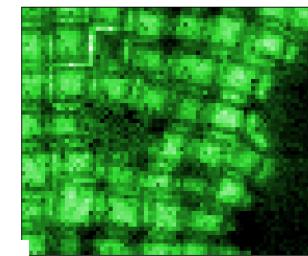
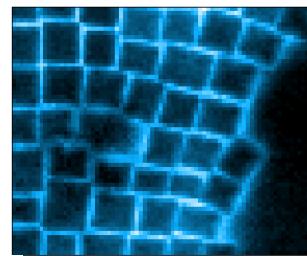
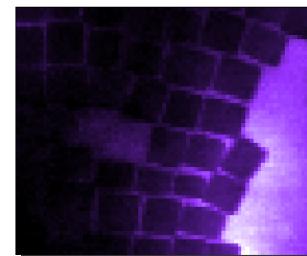
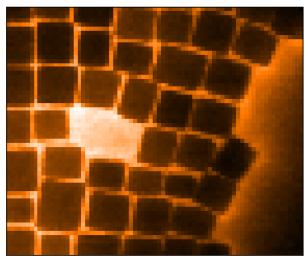
NMF 1

NMF 2

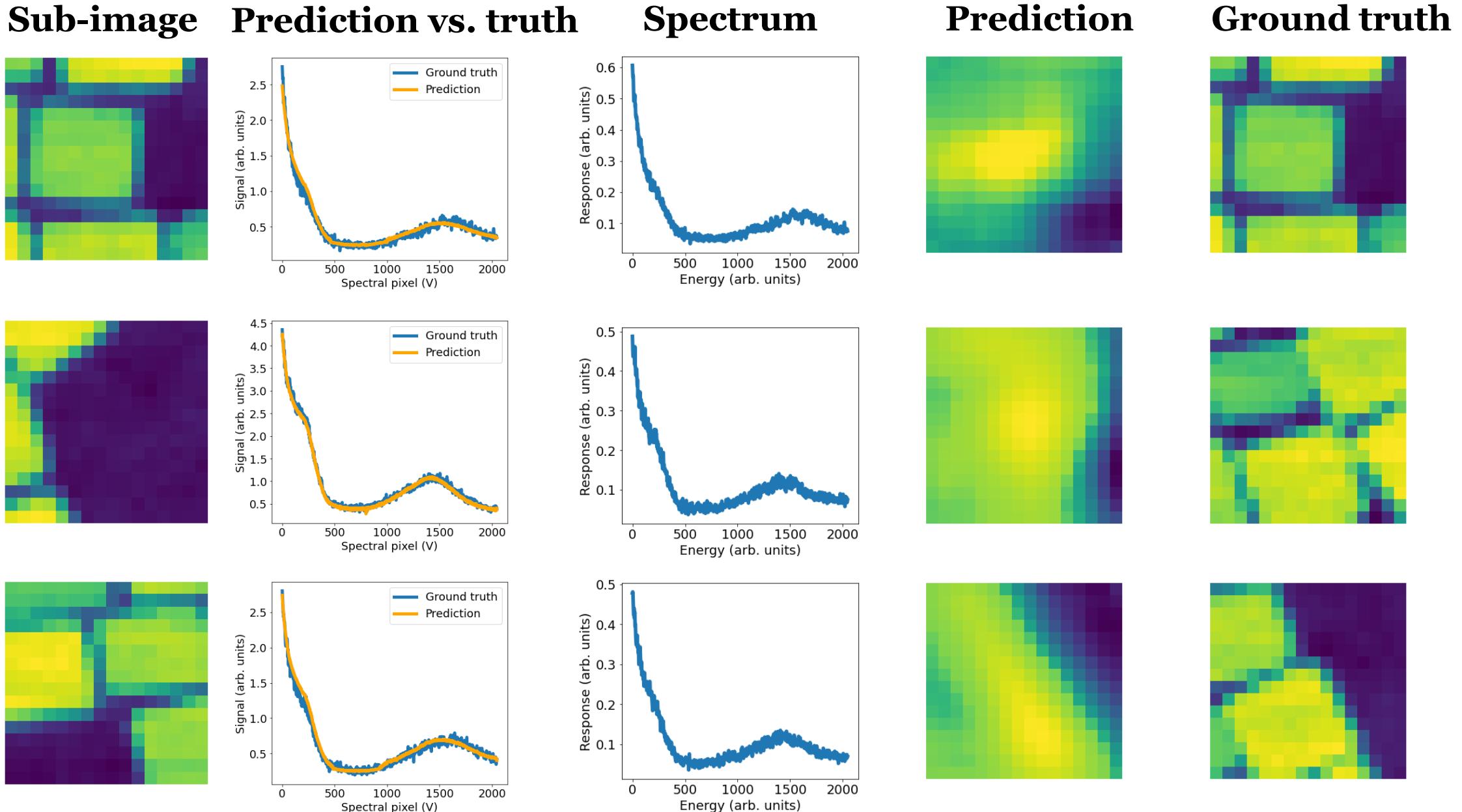


NMF 3

NMF 4

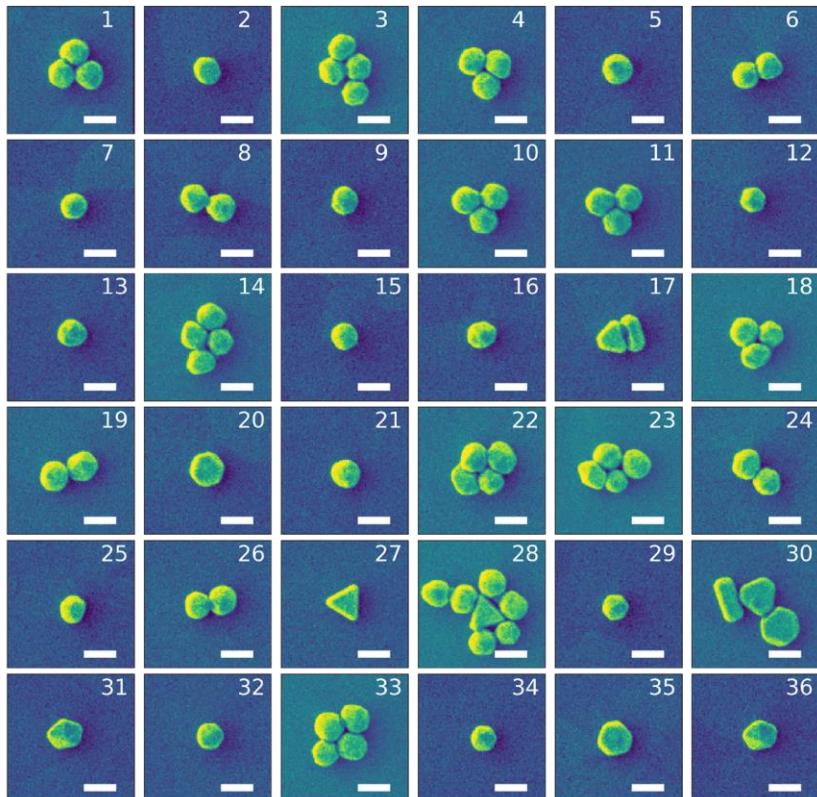


# Encoders-Decoders

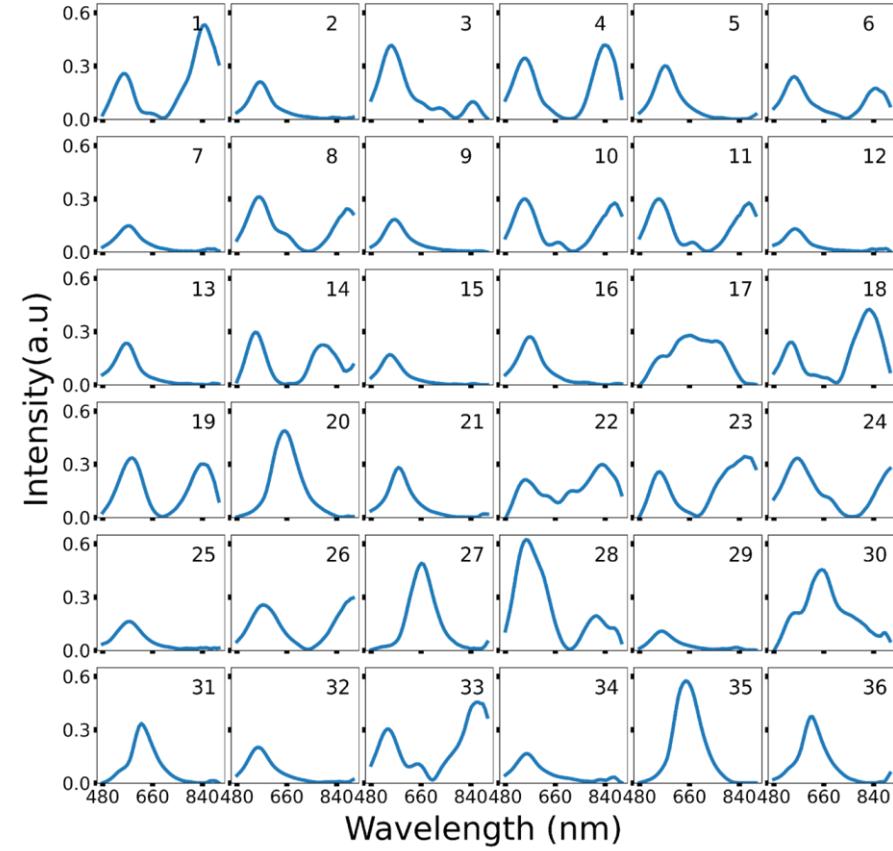


# Dual VAE: structure-property relationships

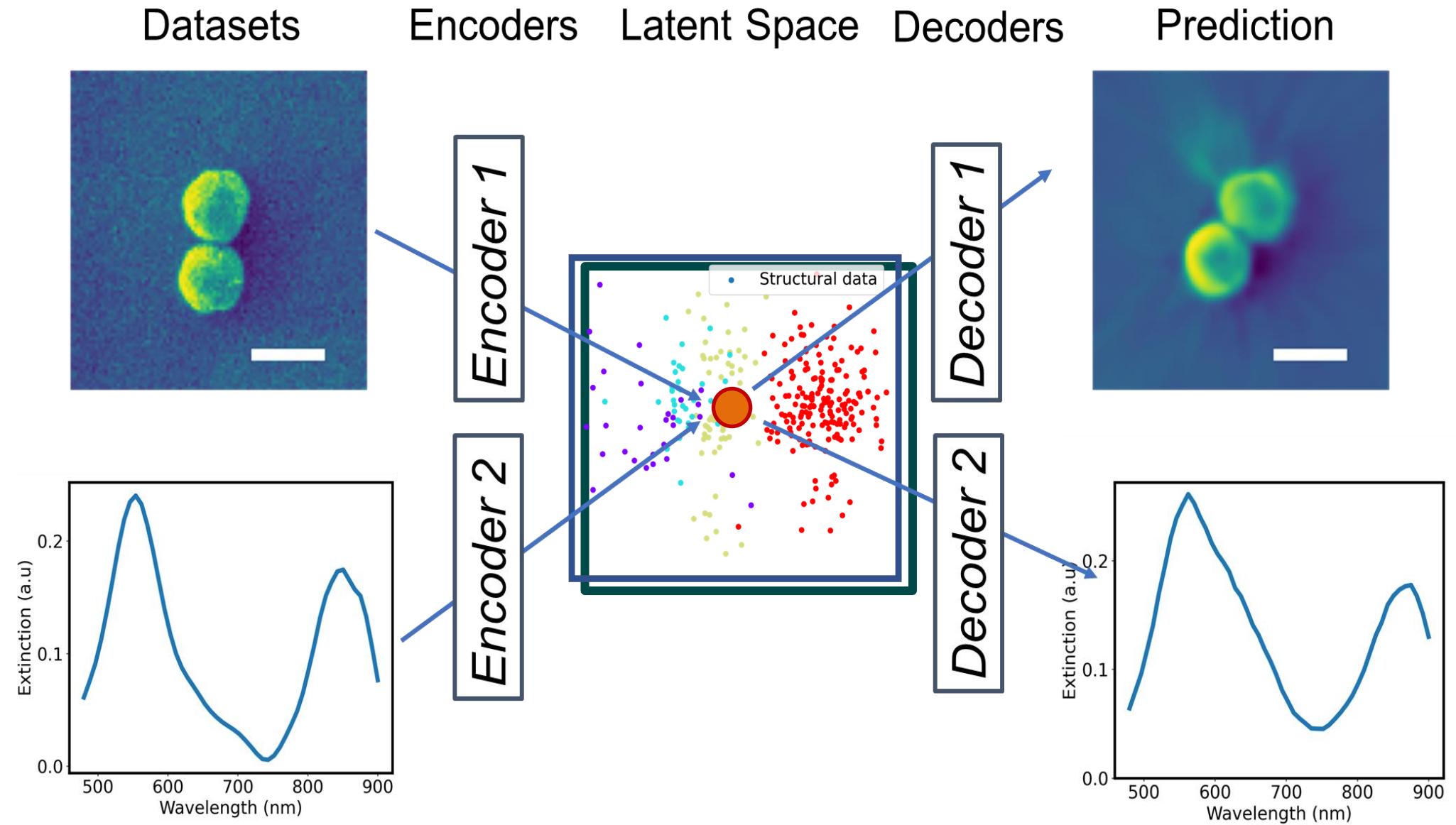
SEM images: "Structure Information"



Hyperspectral microscope: "Property Information"

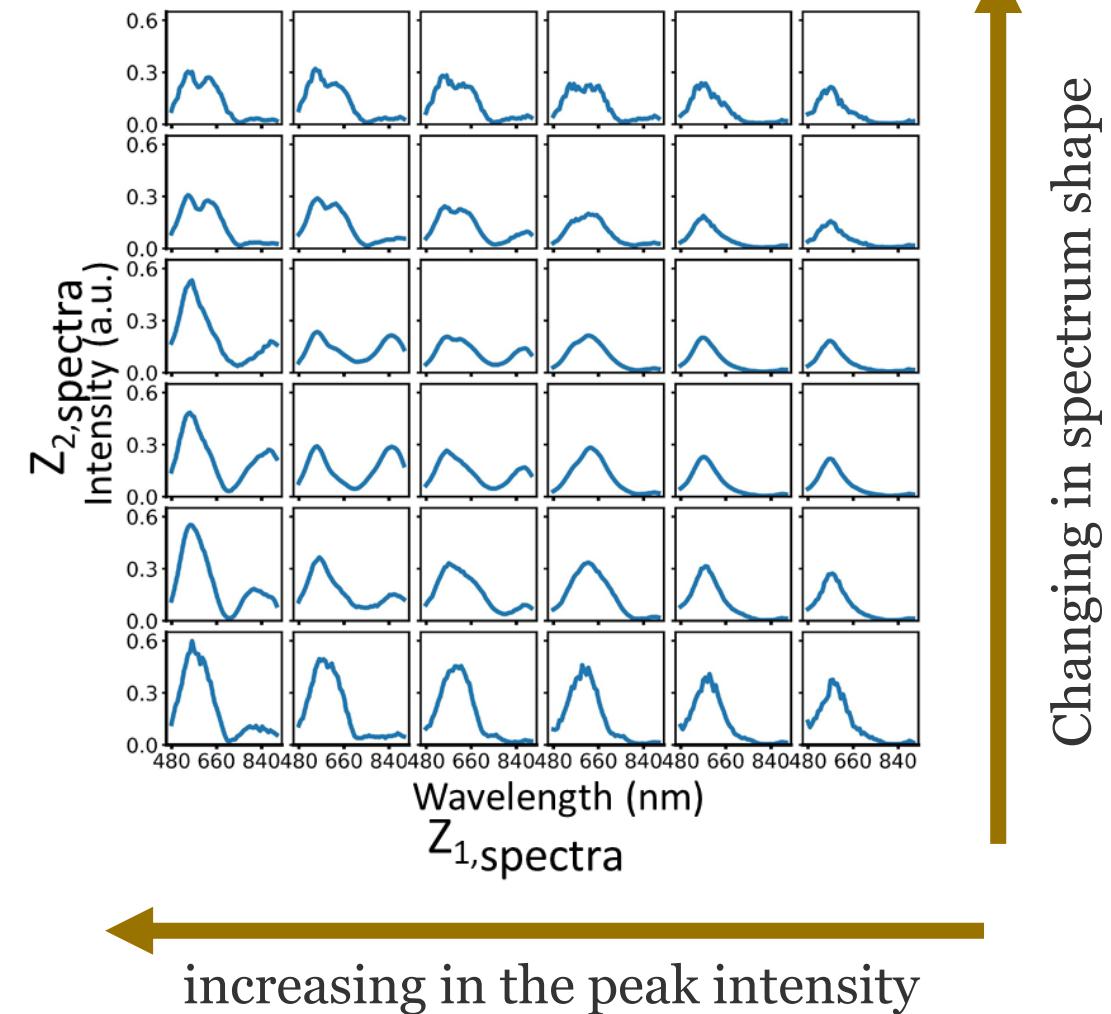
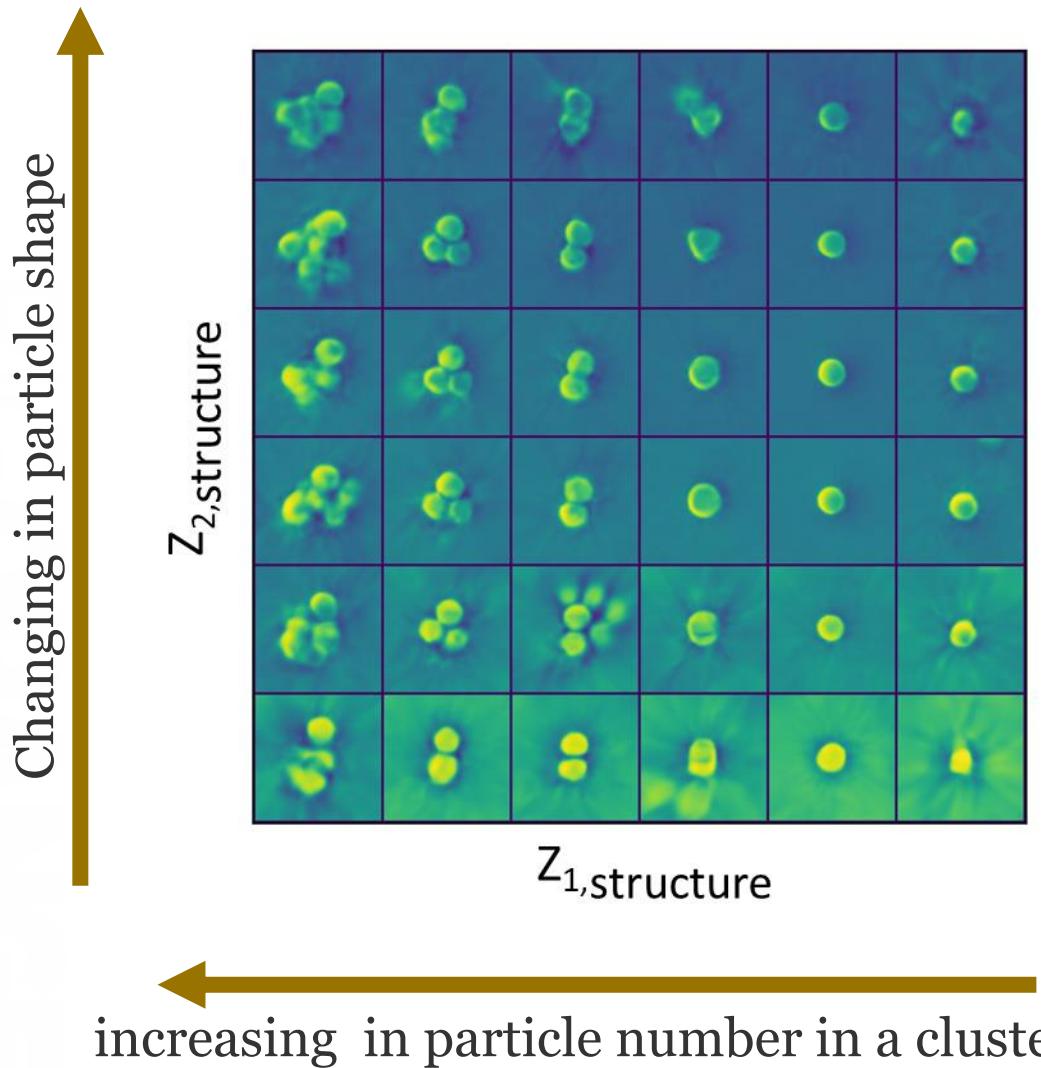


# Dual VAE



# Dual VAE: Latent Representations

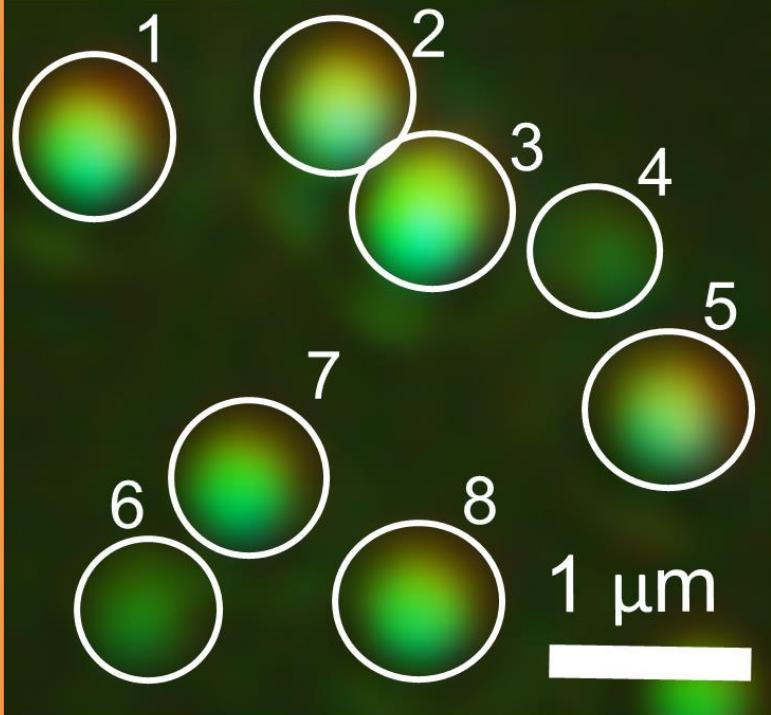
Manifold Representation



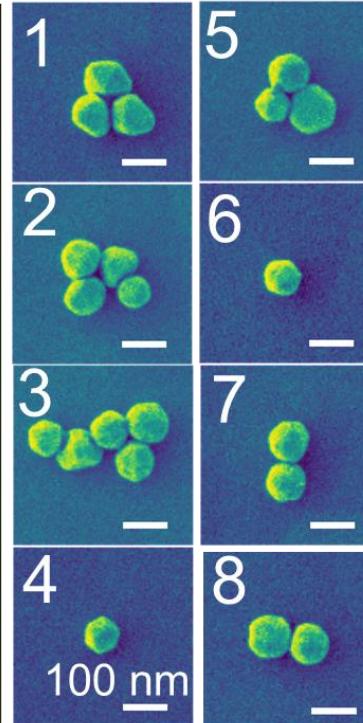
# Dual VAE: Predictions

## Example

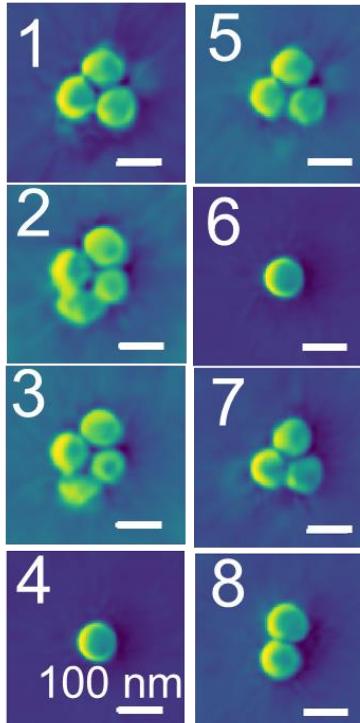
Darkfield Image



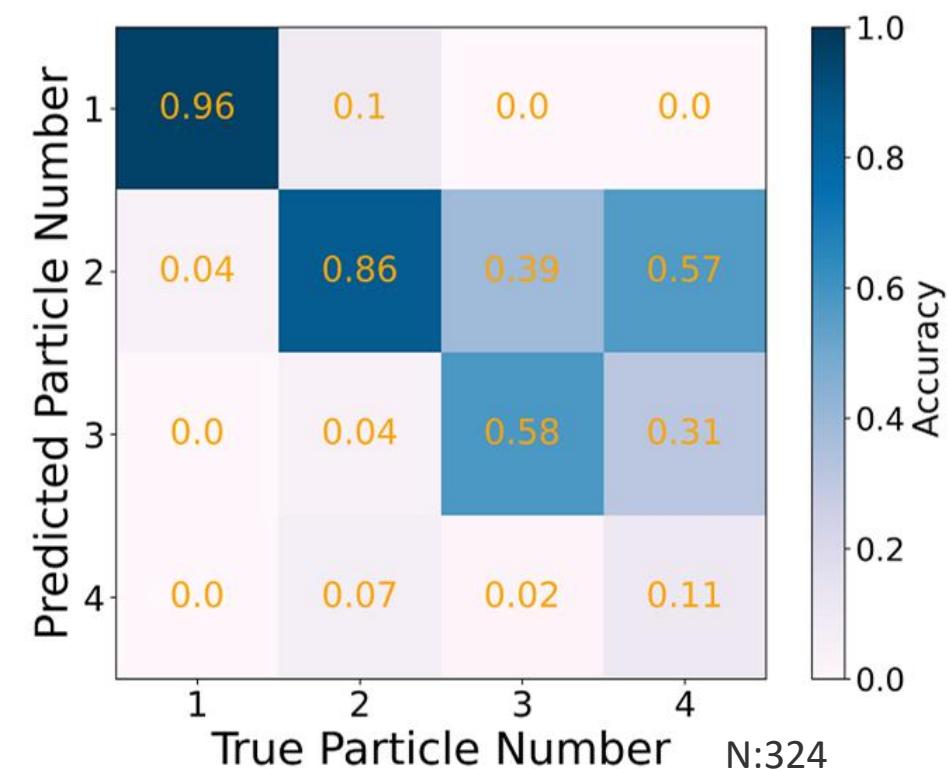
Ground Truth



Prediction



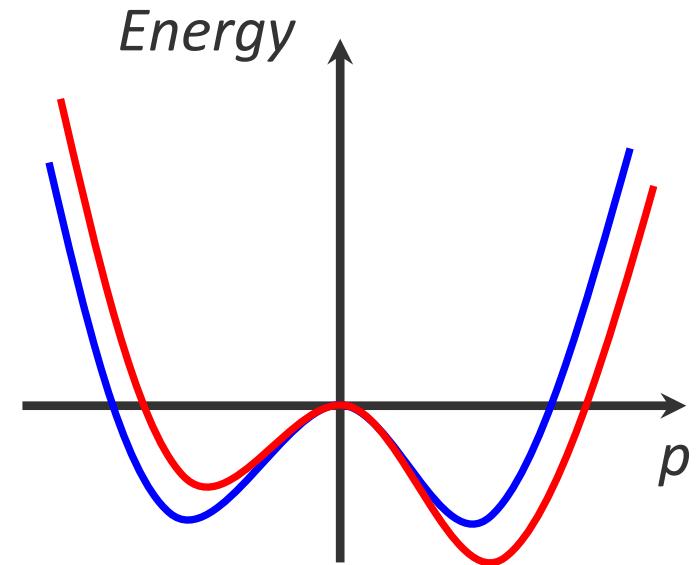
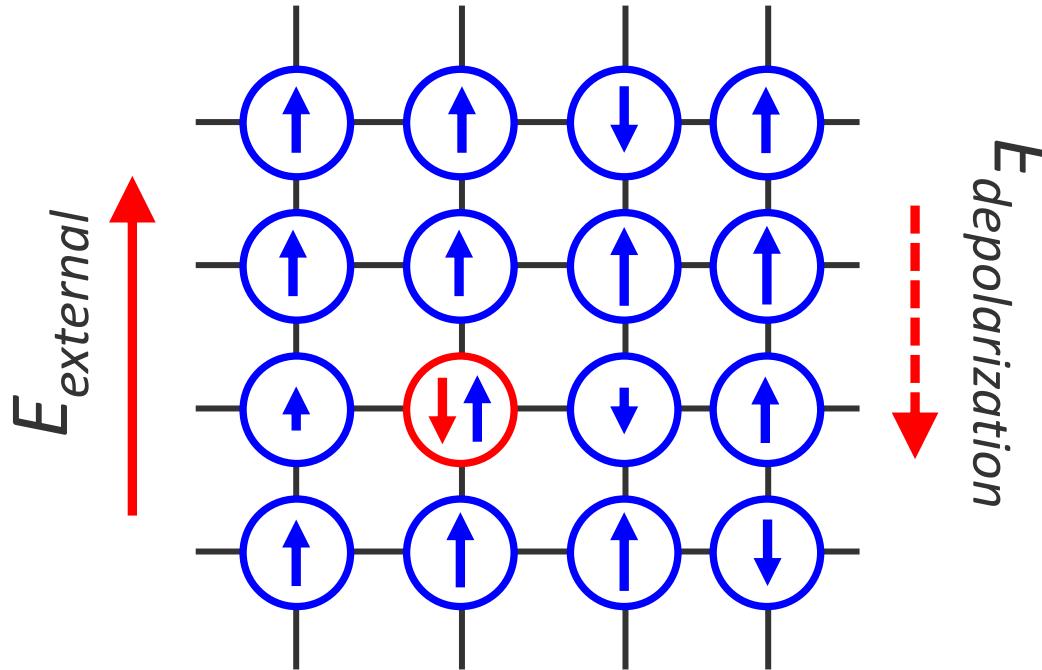
## Overall Particles



[2303.18236.pdf \(arxiv.org\)](https://arxiv.org/pdf/2303.18236.pdf)

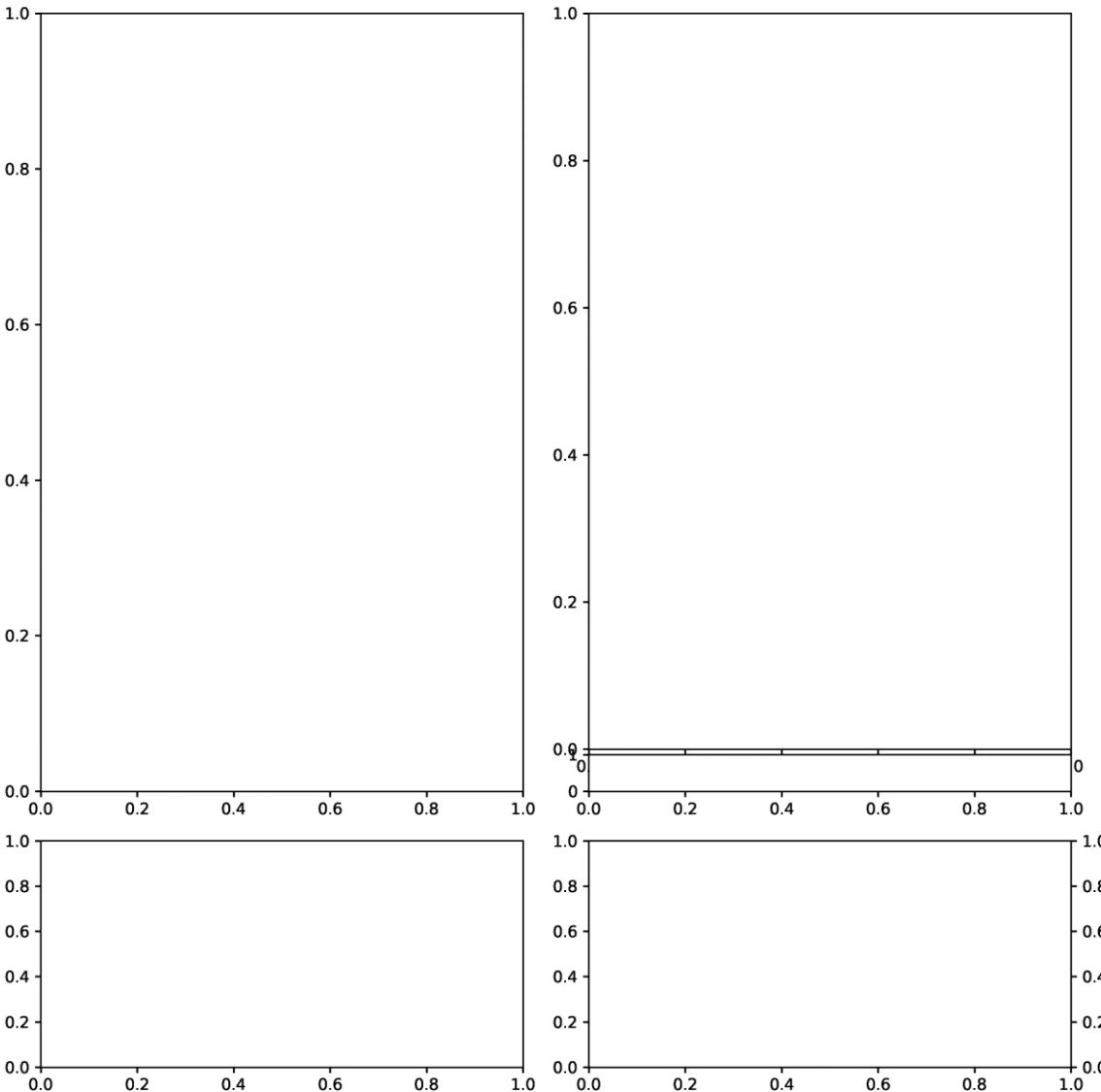
<https://github.com/saimani5/VAE-tutorials>

# FerroSIM: the simplest interesting ferroelectric



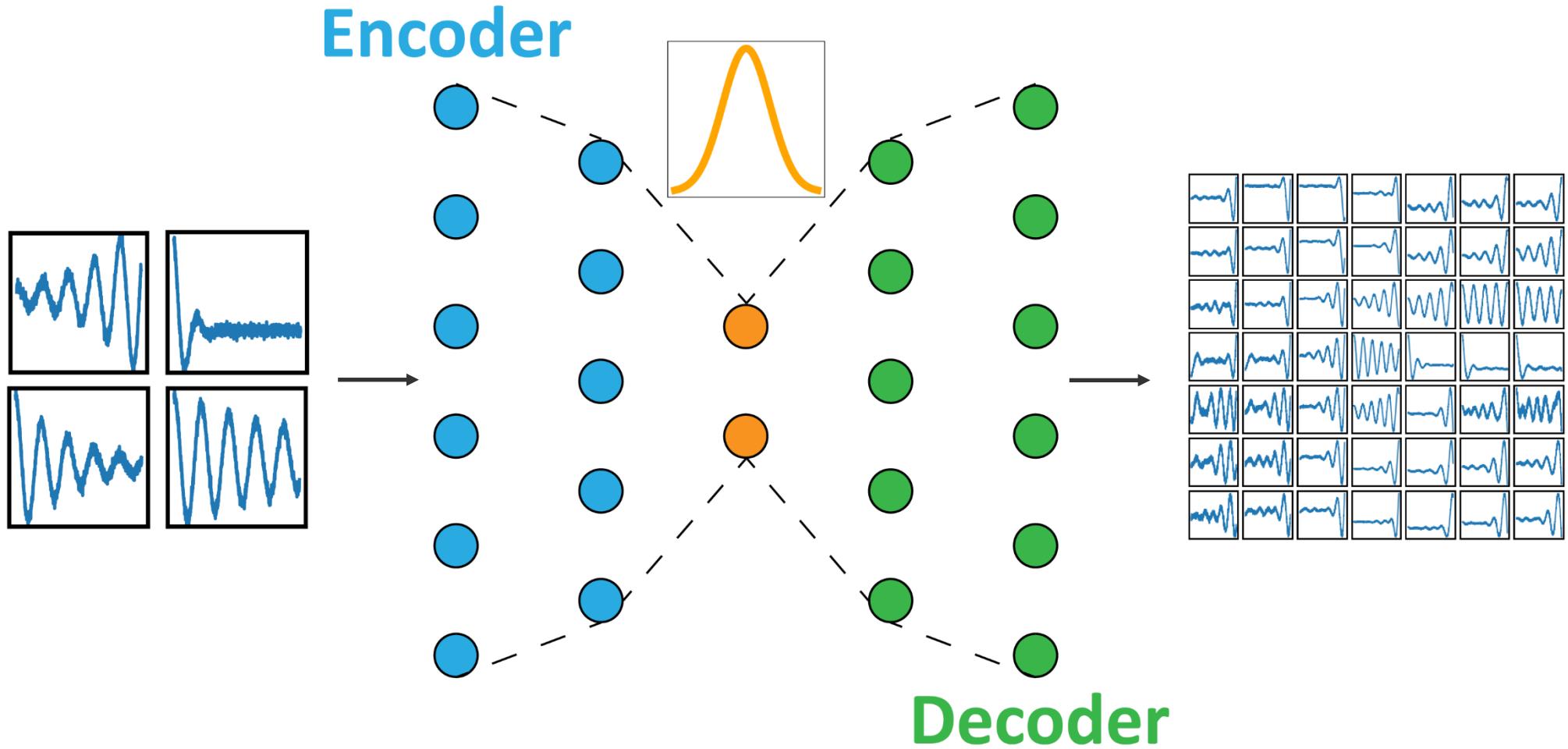
- A discrete square lattice where a continuous polarization vector resides at each lattice site
- The local free energy at each site takes the GLD form:
  - $F_{ij} = \alpha_1 (p_{x_{ij}}^2 + p_{y_{ij}}^2) + \alpha_2 (p_{x_{ij}}^4 + p_{y_{ij}}^4) + \alpha_3 p_{x_{ij}}^2 p_{y_{ij}}^2 - E_{loc_{x_{ij}}} p_{x_{ij}} - E_{loc_{y_{ij}}} p_{y_{ij}}$
  - Where,  $E_{loc} = E_{ext} + E_{dep} + E_d(i,j)$  and  $E_d = -\alpha_{dep} < p >$
- The total free energy is the sum of local free energies and coupling terms:
  - $F = \sum_{i,j}^N F_{ij} + K \sum_{k,l} (p_{x_{ij}} - p_{x_{i+k,j+l}})^2 + K \sum_{k,l} (p_{y_{ij}} - p_{y_{i+k,j+l}})^2$
- Polarization at each lattice site is updated to decrease the free energy using  $\frac{d p_{i,j}}{dt} = -\frac{\partial F}{\partial p_{i,j}}$

# But what about trajectories?



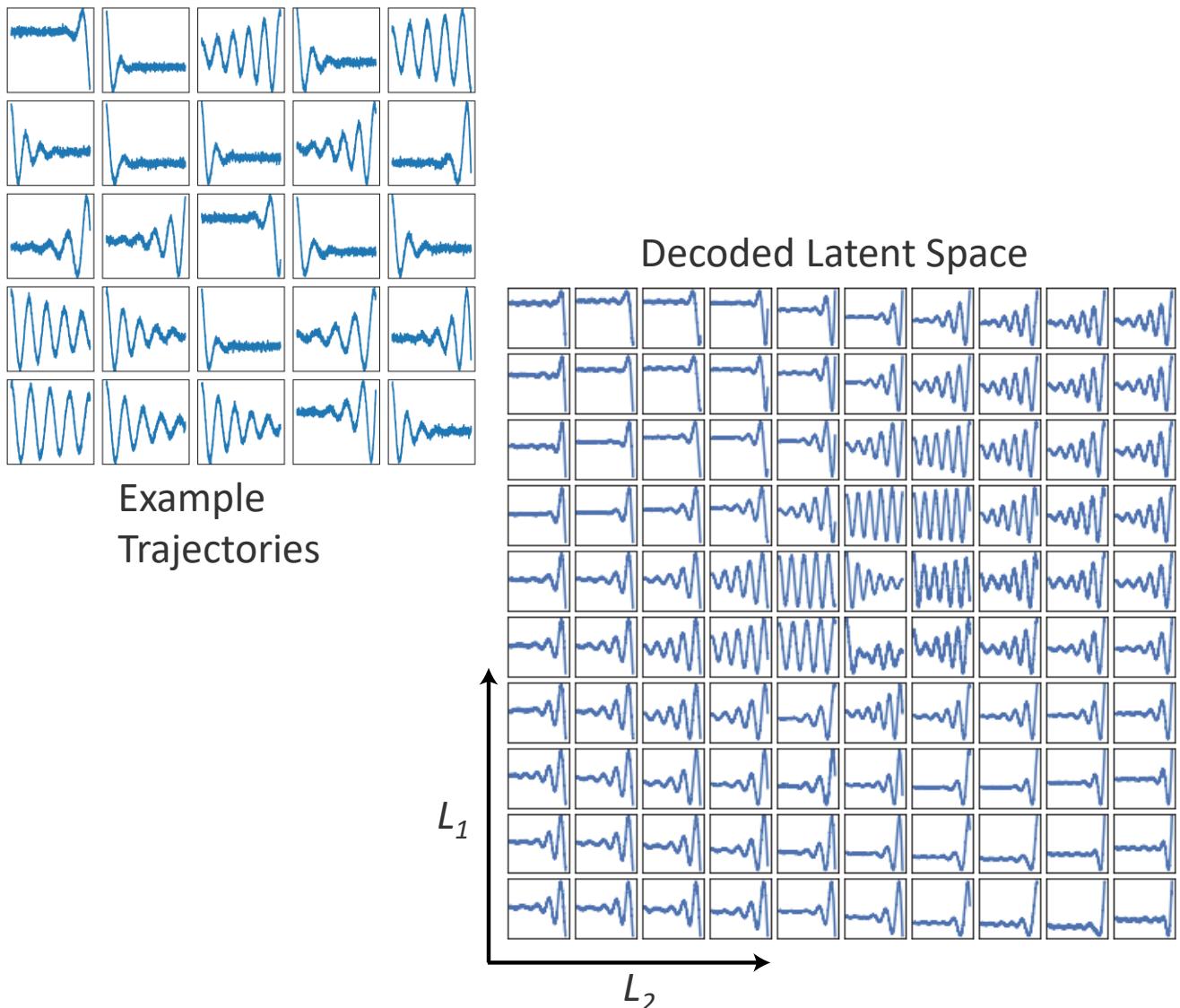
- The model has large number of microstates
- The global state depends on history, i.e. dependence of field vs. time
- Can we somehow optimize the chosen global state in the space of possible histories?
- This space is obviously intractable...
- ... however, we are not interested in ALL possible histories. We are interested in relatively simple histories
- **Thought:** what if we start with the histories that make sense from domain perspective, and look for way to simplify them?

# Can VAE help?

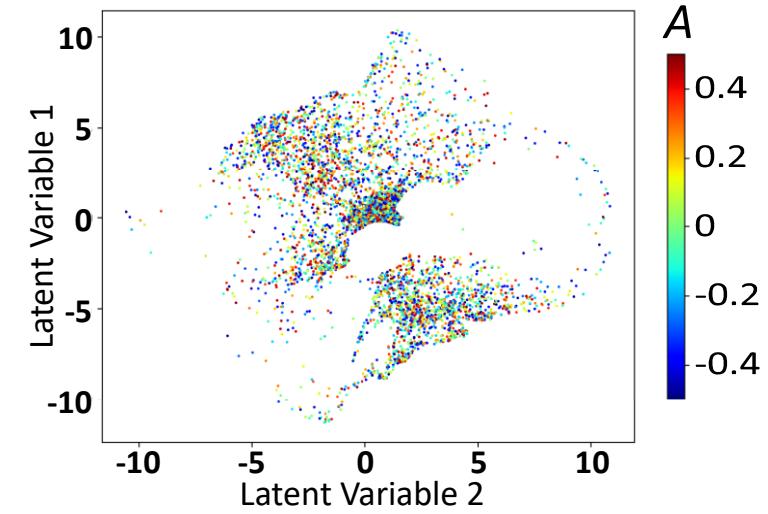
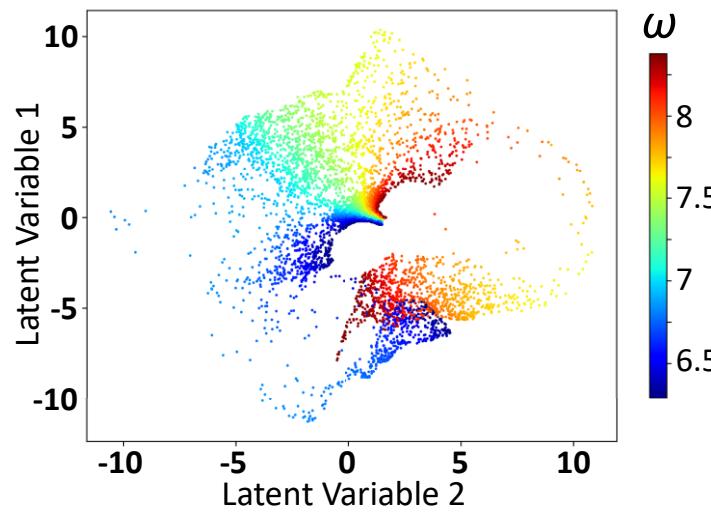
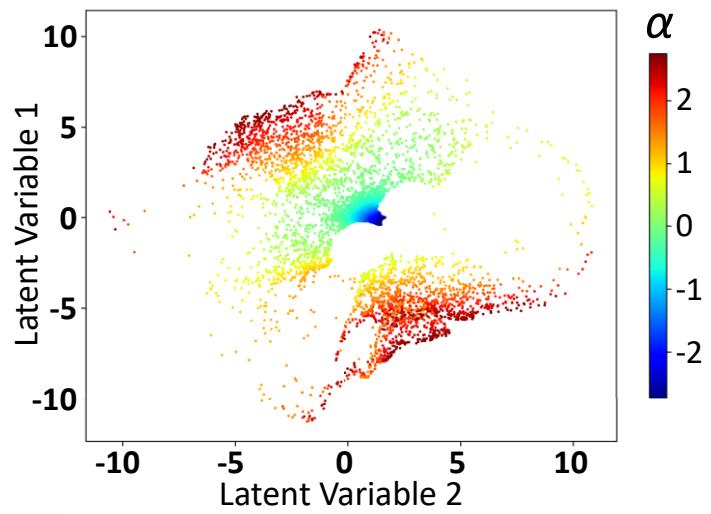


# VAE encoding of domain trajectories

- Sinusoidal trajectories with exponential functions as amplitude modulators
  - $A \exp(\alpha t) \sin(\omega t) + B$
- $A: [0, 0.75]$ ,
- $\alpha: [-2.75, 2.75]$ ,
- $\omega: [2\pi, \frac{8}{3}\pi]$ ,
- $B: [-0.5, 0.5]$
- These electric fields are divided into 900 discrete time steps.
- 7500 of these curves are then used to create a smooth latent space using a Variational Autoencoder (VAE)

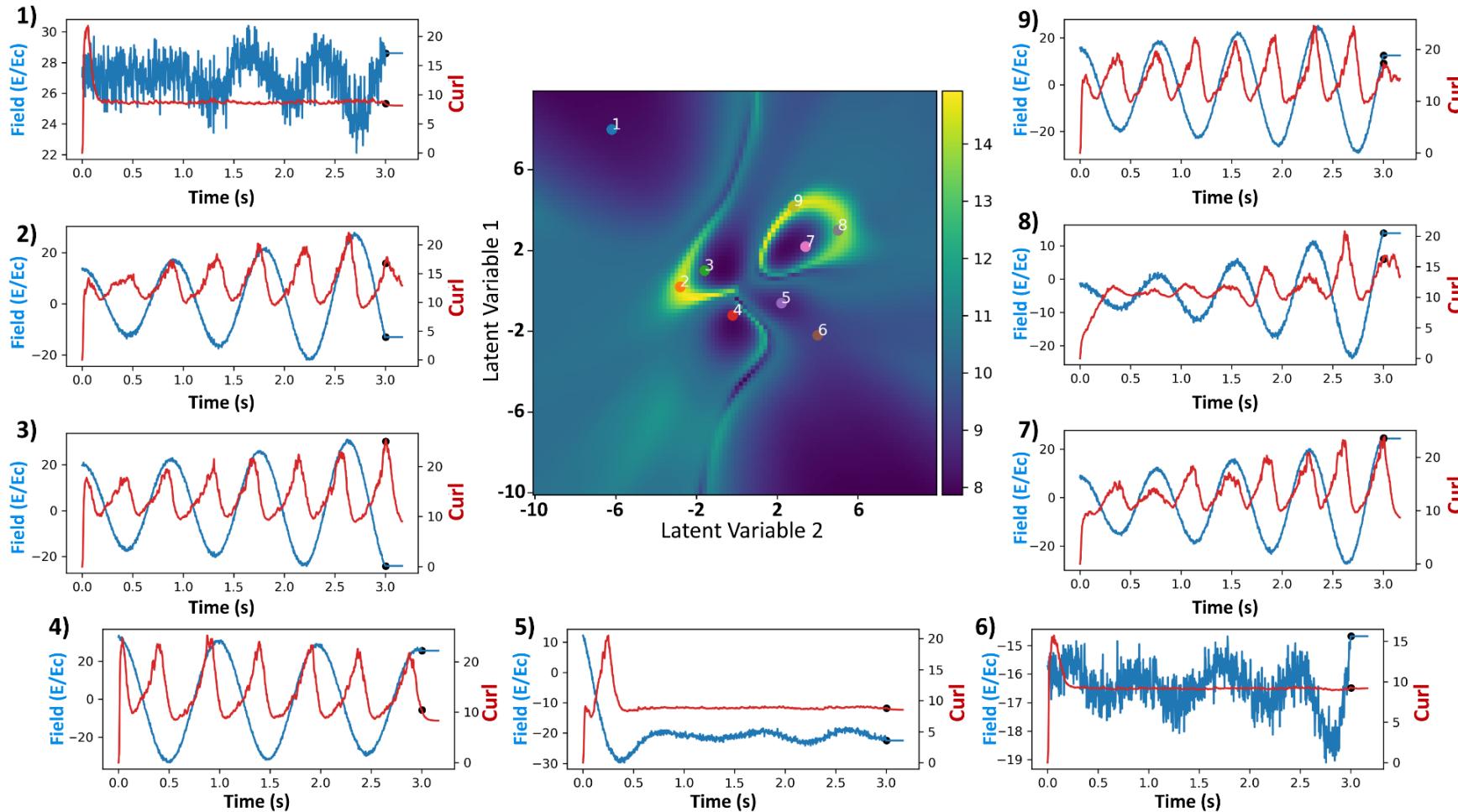


# Latent space distributions



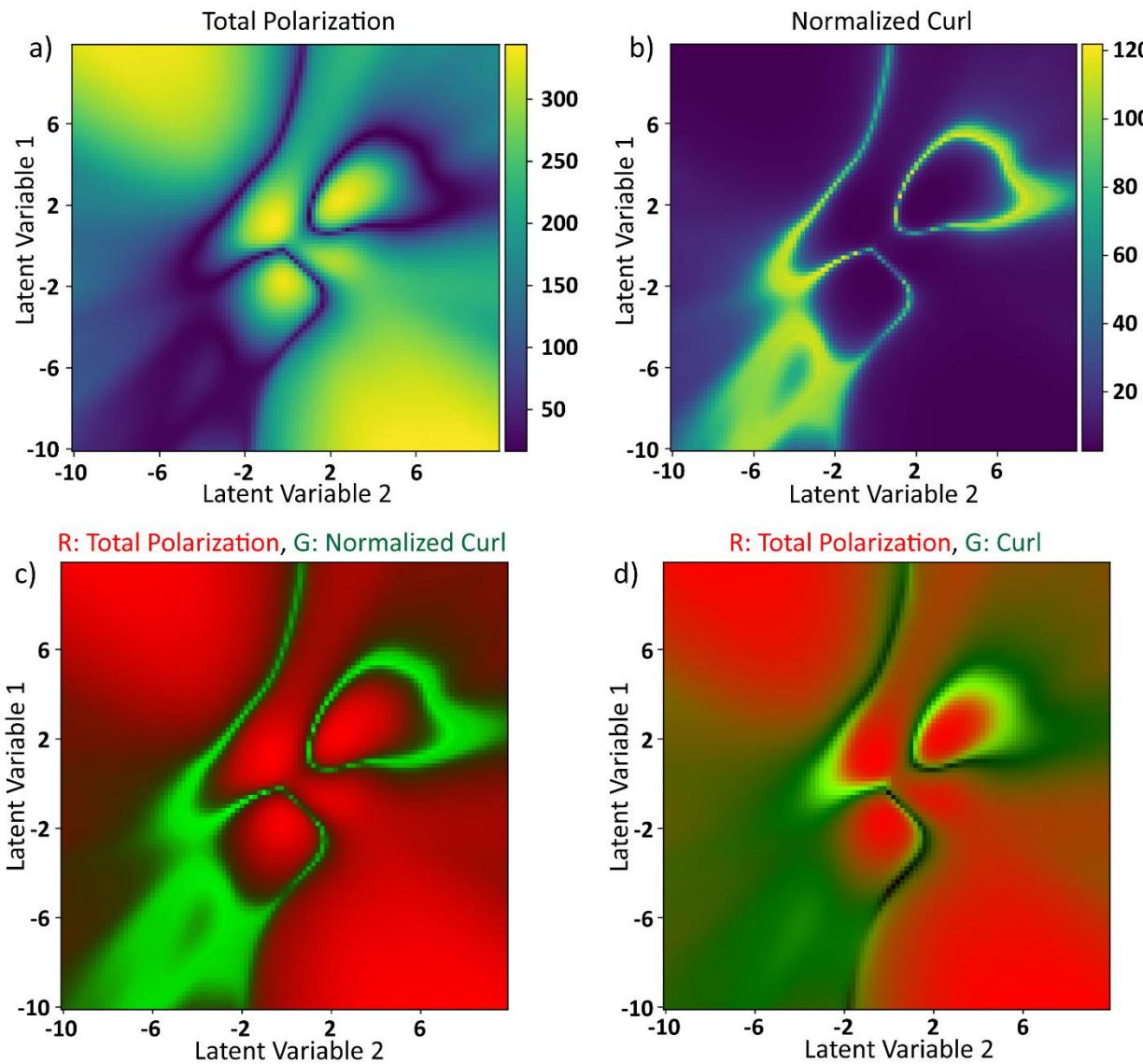
# Ground truth target function

- Latent space is sampled and then decoded back into the space of electric field of 900-dimensions
- An equilibration region of 50-time steps is then added where the electric field is held constant at the final value of the decoded electric field.
- The **sum of absolute value of curl** at each lattice site at the end of the simulation is the target value to be optimized



- Curl decays in the equilibration region
- The rate of decay of the curl is proportional to the curl at the onset of the equilibration region
- The local maxima of the curl seemingly coincides with the local optima of the electric field.

# Exploring the curl surface



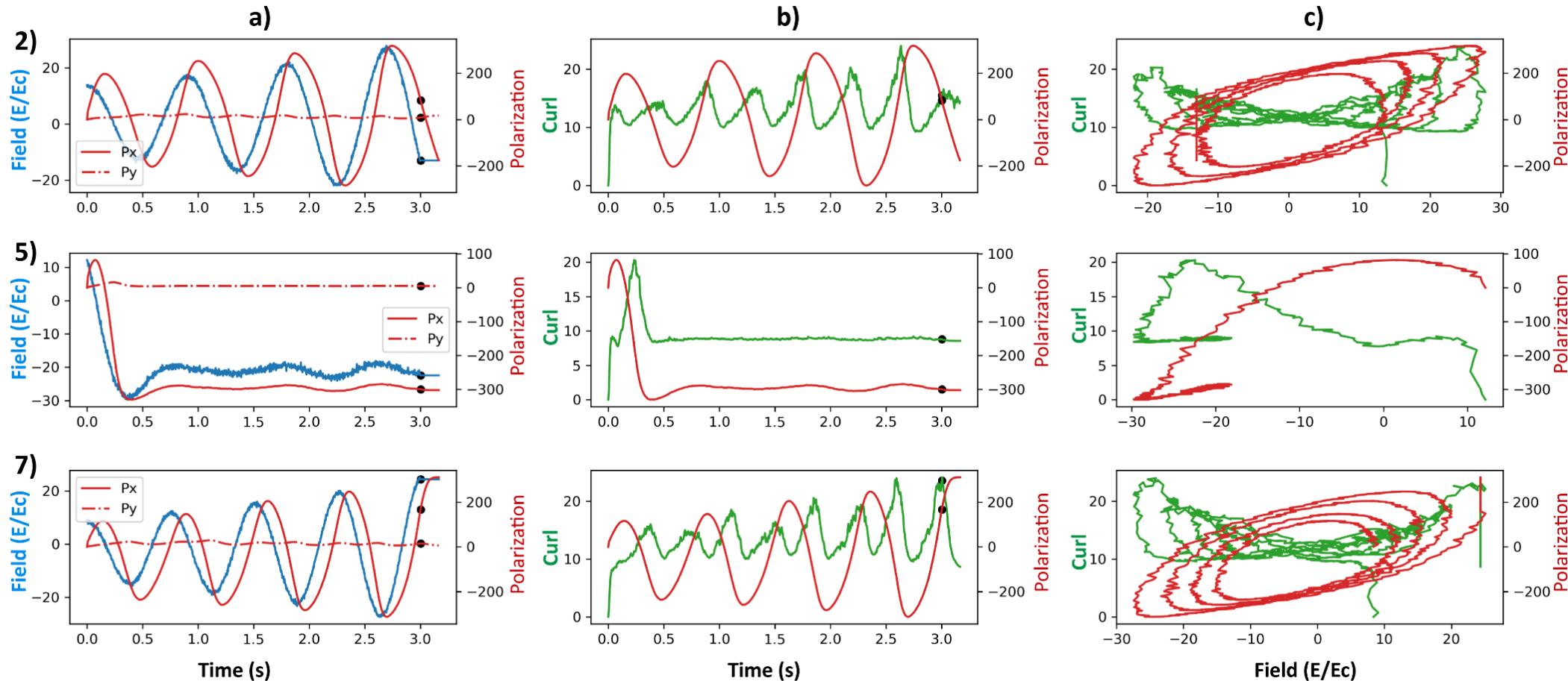
## Normalized Curl

- At the end of the simulations, the polarization vector at each lattice site is normalized
- These normalized polarization vectors are then used to recalculate curl
- We will refer to it as the normalized curl
- It is supposed to estimate how much the vector field rotates without considering the magnitude of the field

## Observations

- Normalized curl is inversely proportional to the magnitude of polarization
- The system is allowed to be in the most chaotic state when the polarization is the least as the effect of coupling terms is low
- The system's polarization is at the lowest the coercive field

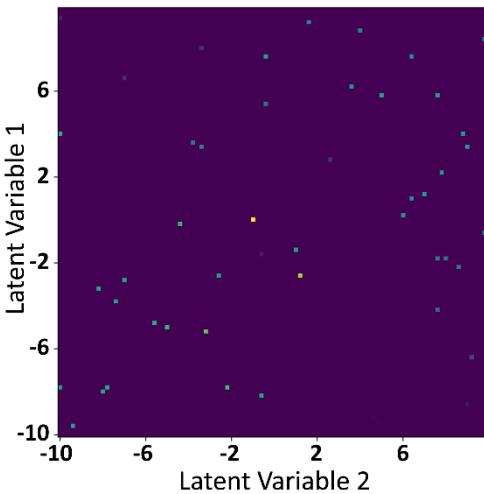
# Exploring the curl surface



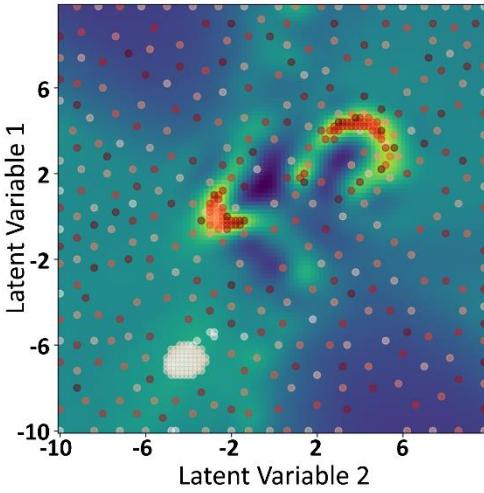
- The system's polarization is at the lowest the coercive field (A state of maximum normalized curl)
- But the curl is also a function of magnitude of the polarization
- Hence, the magnitude of the curl is maximum a few steps after the coercive field where the polarization grows in magnitude just enough that the coupling terms do not take over to kill the curl in the system
- This time coincides with the time it takes the electric field to reach the maximum from the coercive field, hence the overlap of the local maxima of curl and electric field

# Bayesian Optimization in the Latent Space

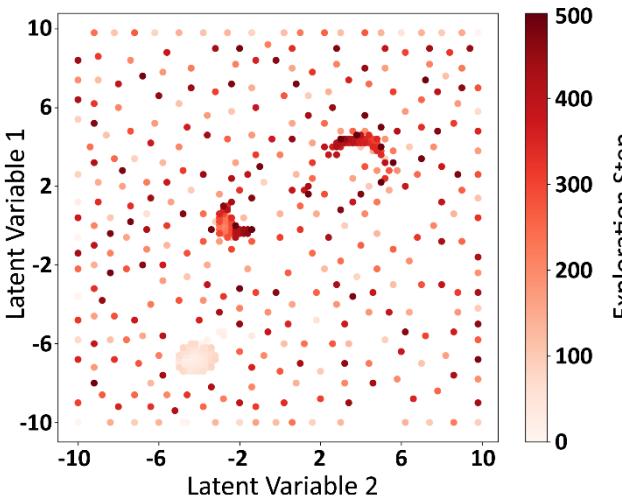
100 initial points



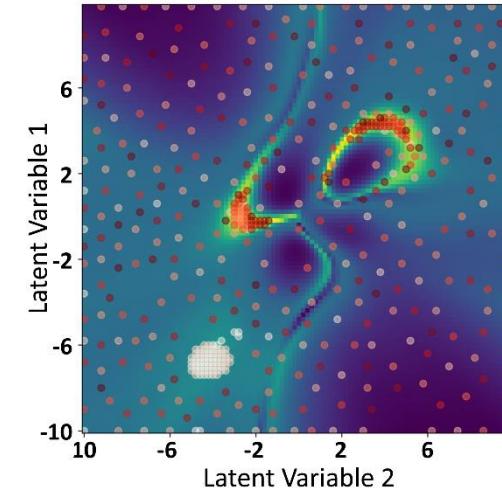
Reconstructed curl surface



Explored points

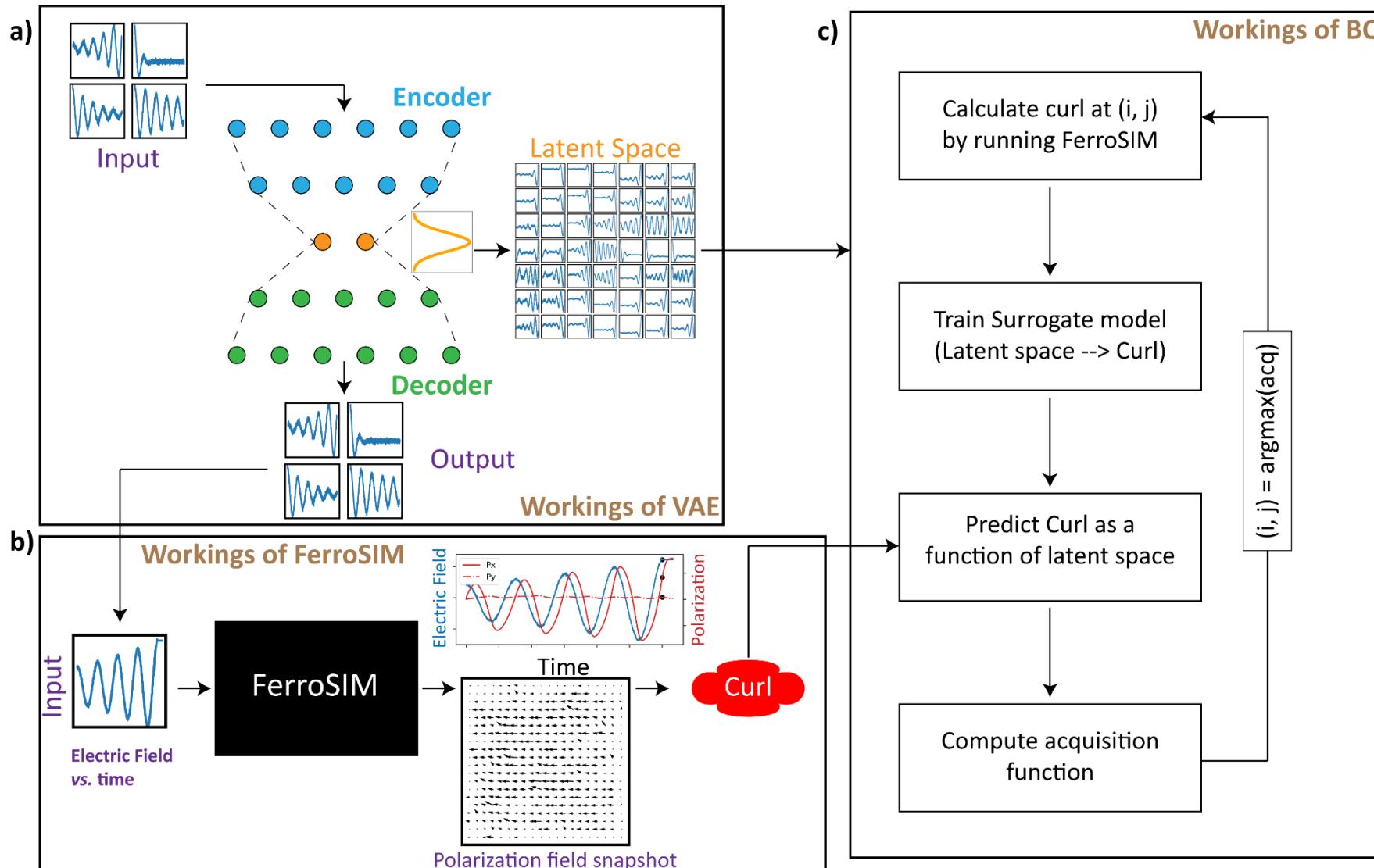


Original curl surface



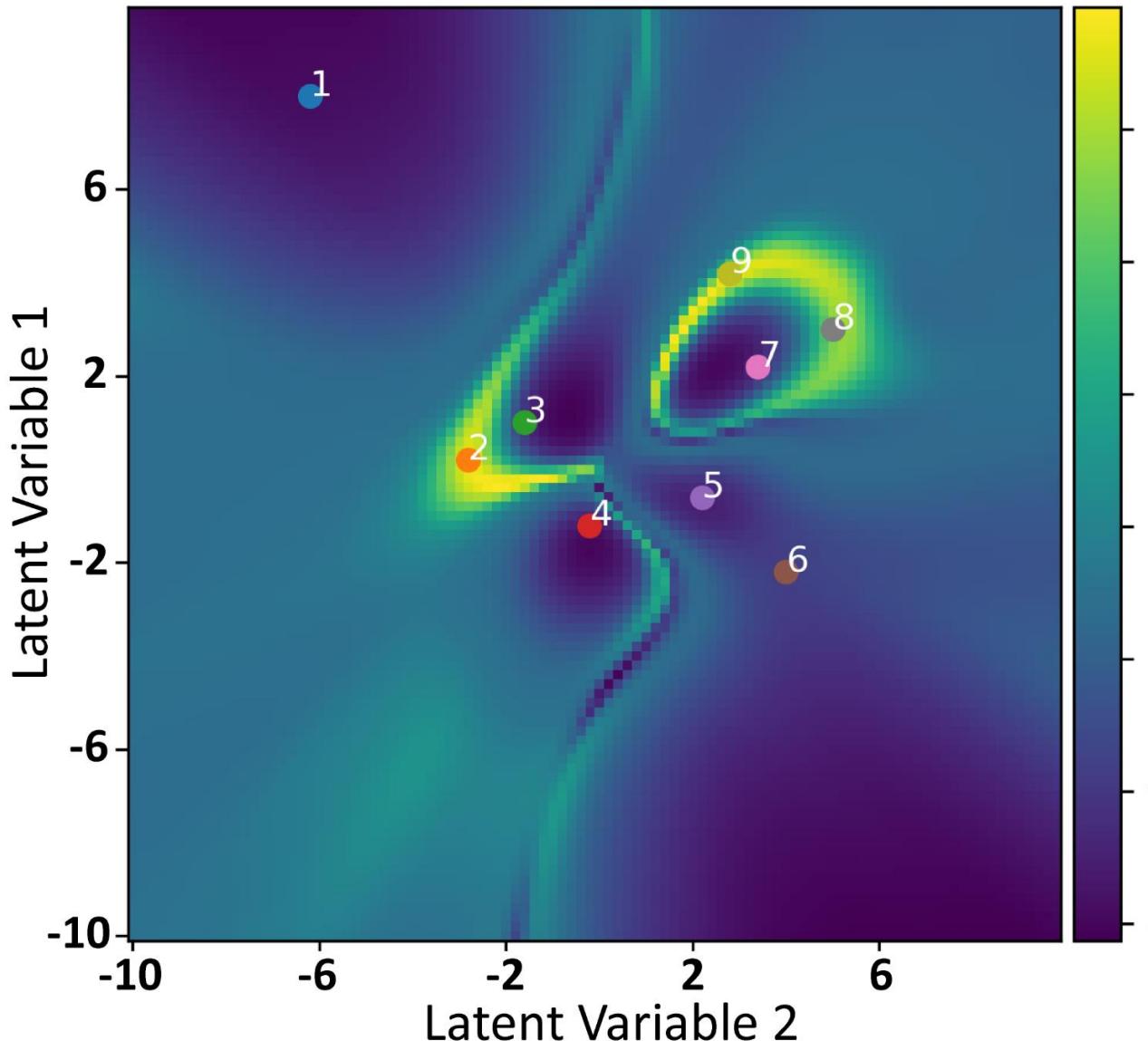
- 100 initialization points and the BO explored the latent space for the next 500 points
- Acq function:  $\mu + 10\sigma$
- So, at the end BO only explored a total of 600 points out of 10,000 points the latent space is divided into
- Caveat: we had to tune the Acq with the ground truth data known

# Putting everything together



Same approaches are used for molecular discovery, polymers, and biomolecules

# What determines success?



- The success of the BO in the latent space clearly depends on the shape on the manifold that points of interest form.
- For VAE, the shape of the manifold is determined by the properties of the data only, including
  - (a) how strong correlations in data reflect in correlation in properties and
  - (b) weight of the “good” trajectories