

# Lecture 06

## Automated EELS and 4D STEM: Deep kernel learning

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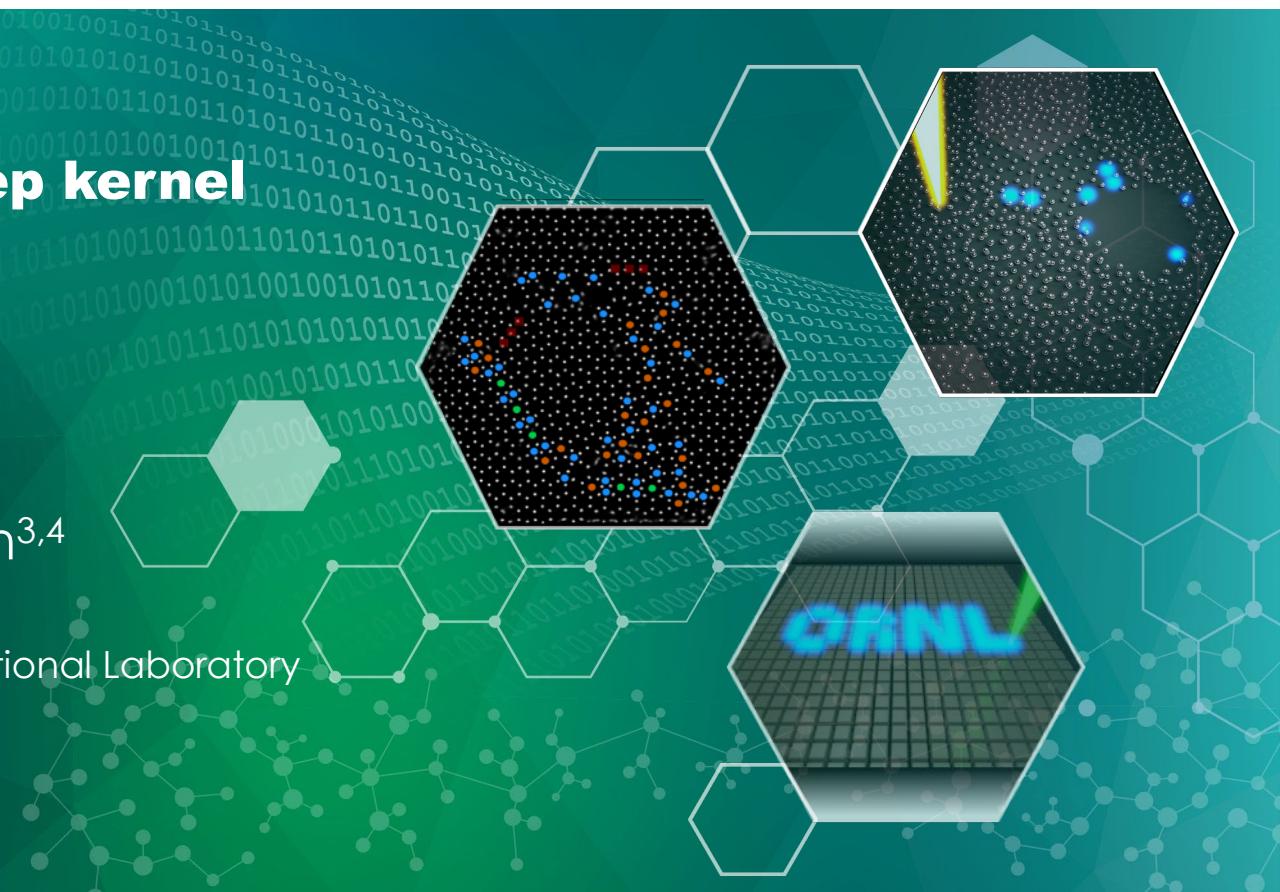
<sup>1</sup>Center for Nanophase Materials Sciences, Oak Ridge National Laboratory

<sup>2</sup>AtomQ

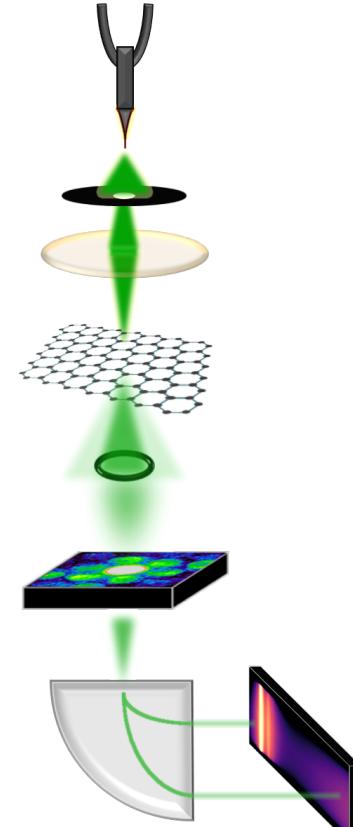
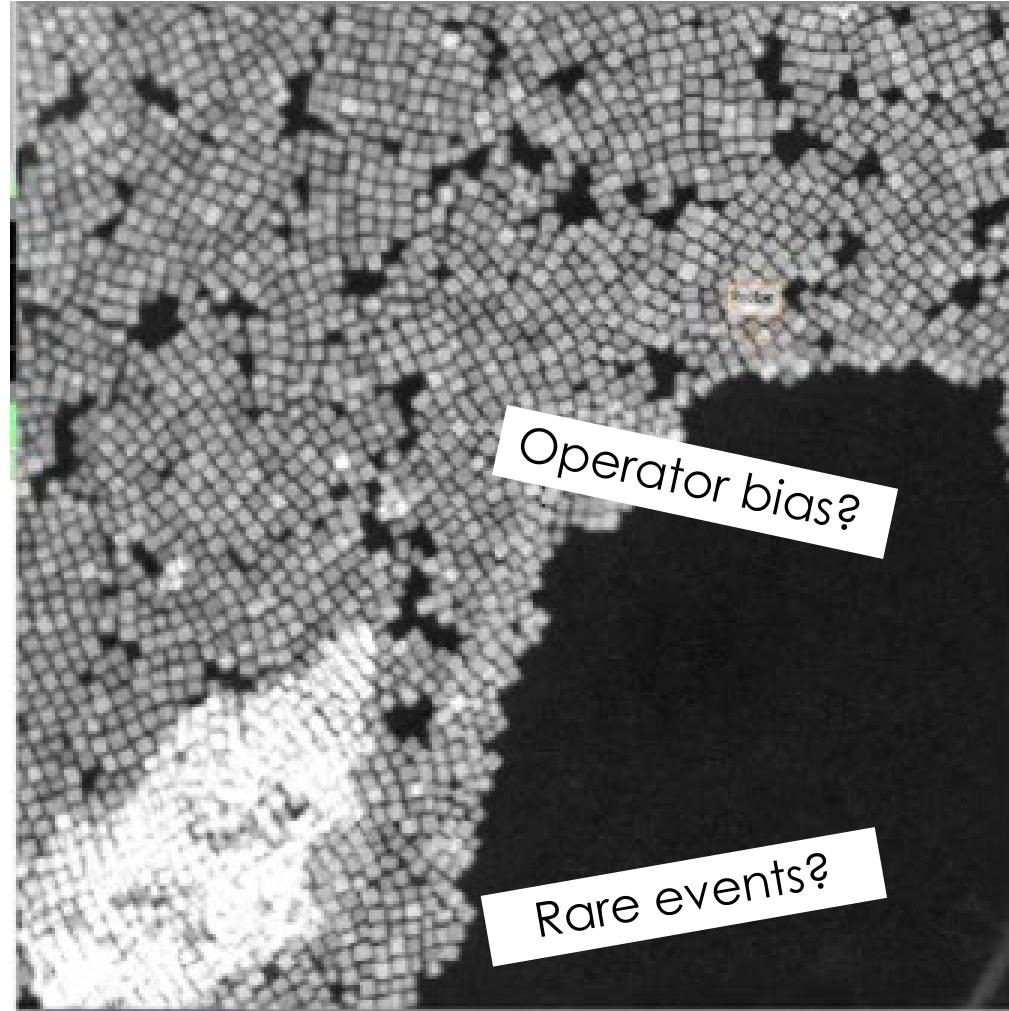
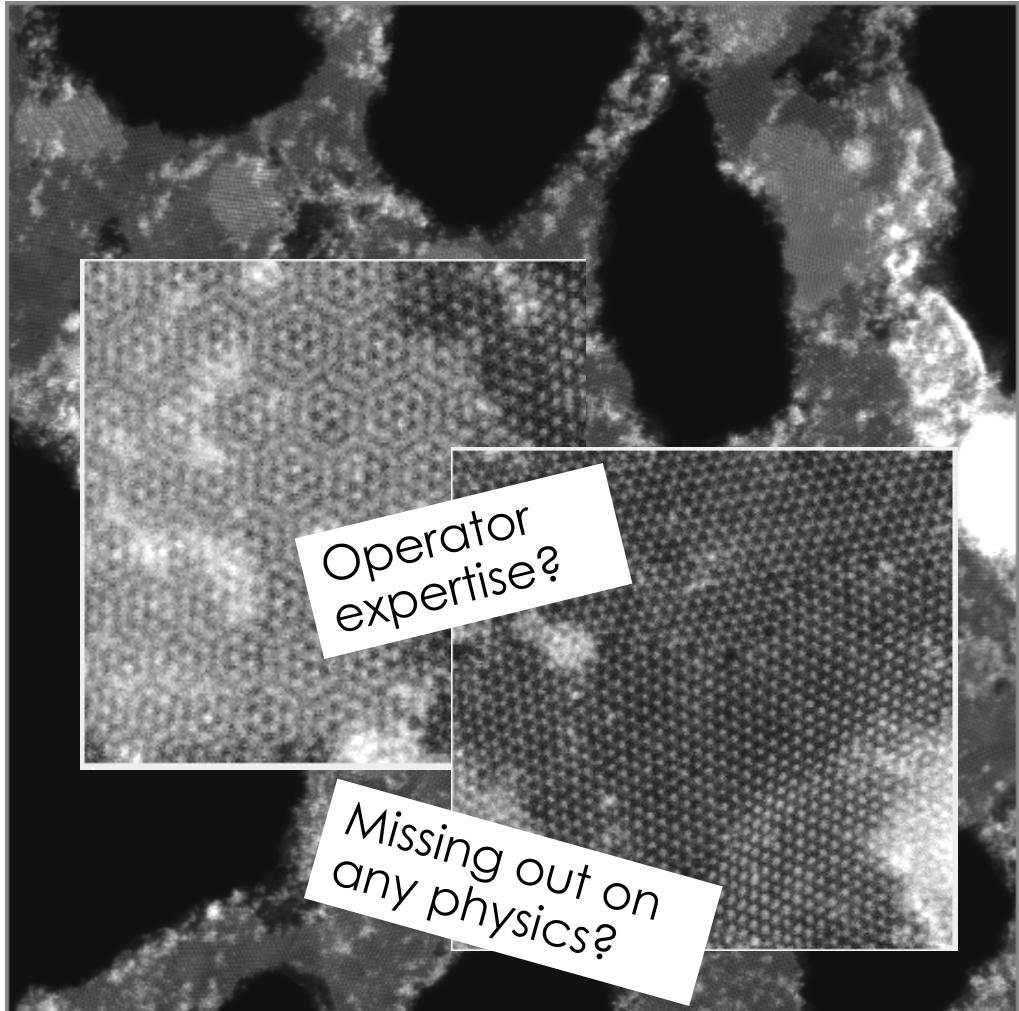
<sup>3</sup>University of Tennessee Knoxville

<sup>4</sup>Pacific Northwest National Laboratory

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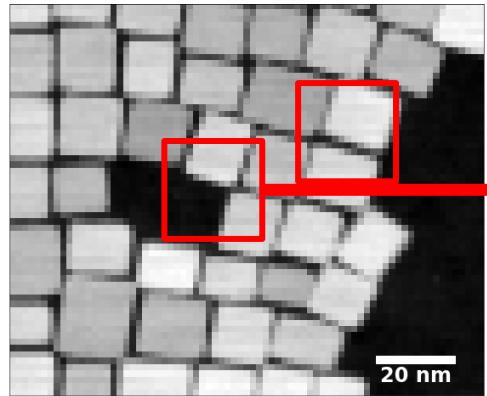


# How do we understand structure property relationships

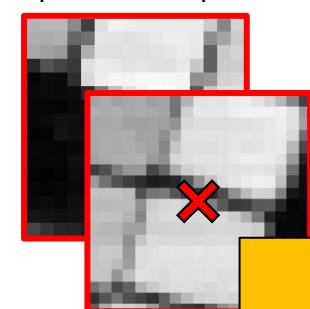


**Q:** Where should (would) you acquire analytical measurements? EELS spectrum image / 4D STEM, point spectra, where? **You can't say all points!**

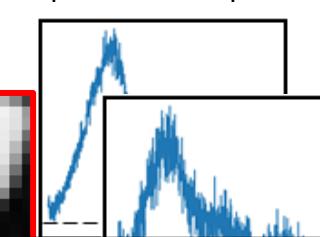
# Recall: Structure-property correlations: Autoencoder neural network



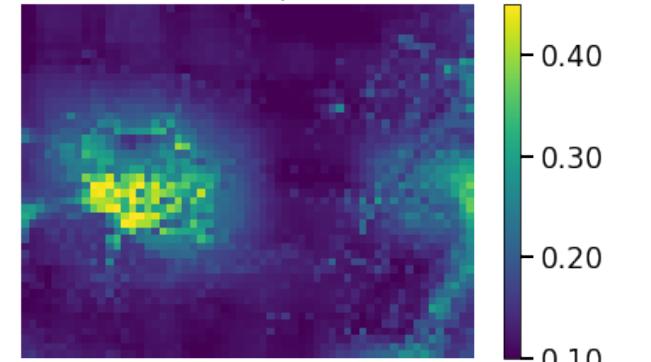
Spatial Descriptor



Spectral Descriptor

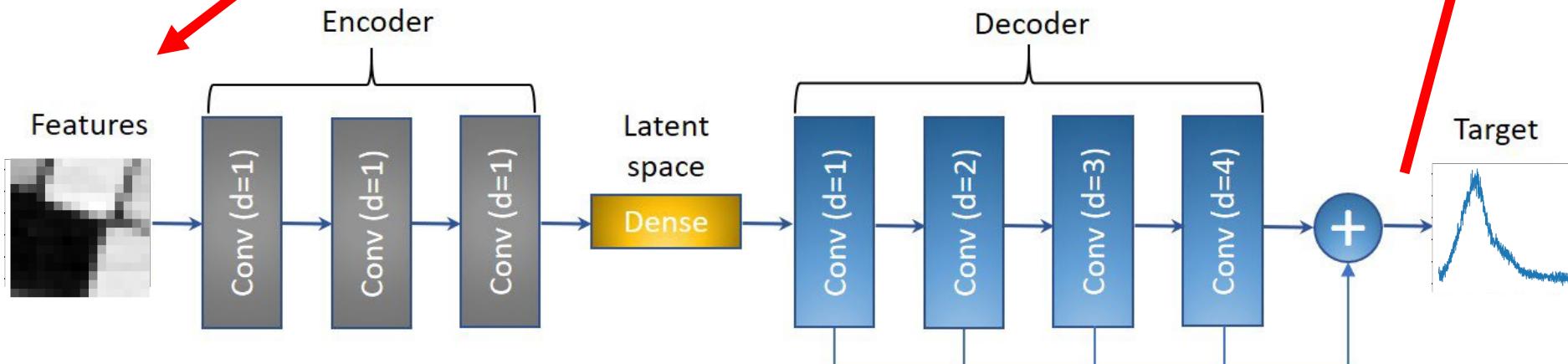


Uncertainty MSE



OFFLINE analysis!

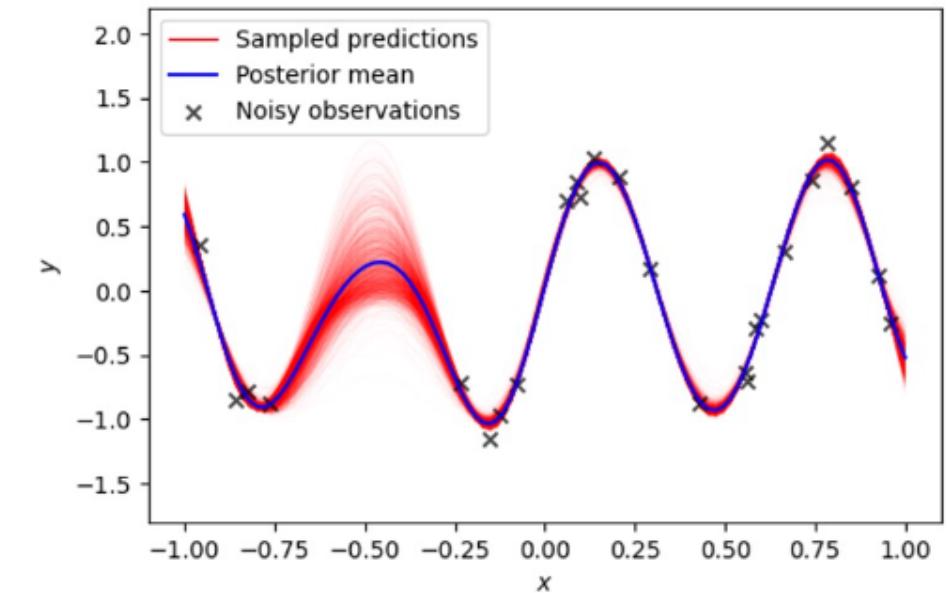
Training can take some time.



# Automated Experiment

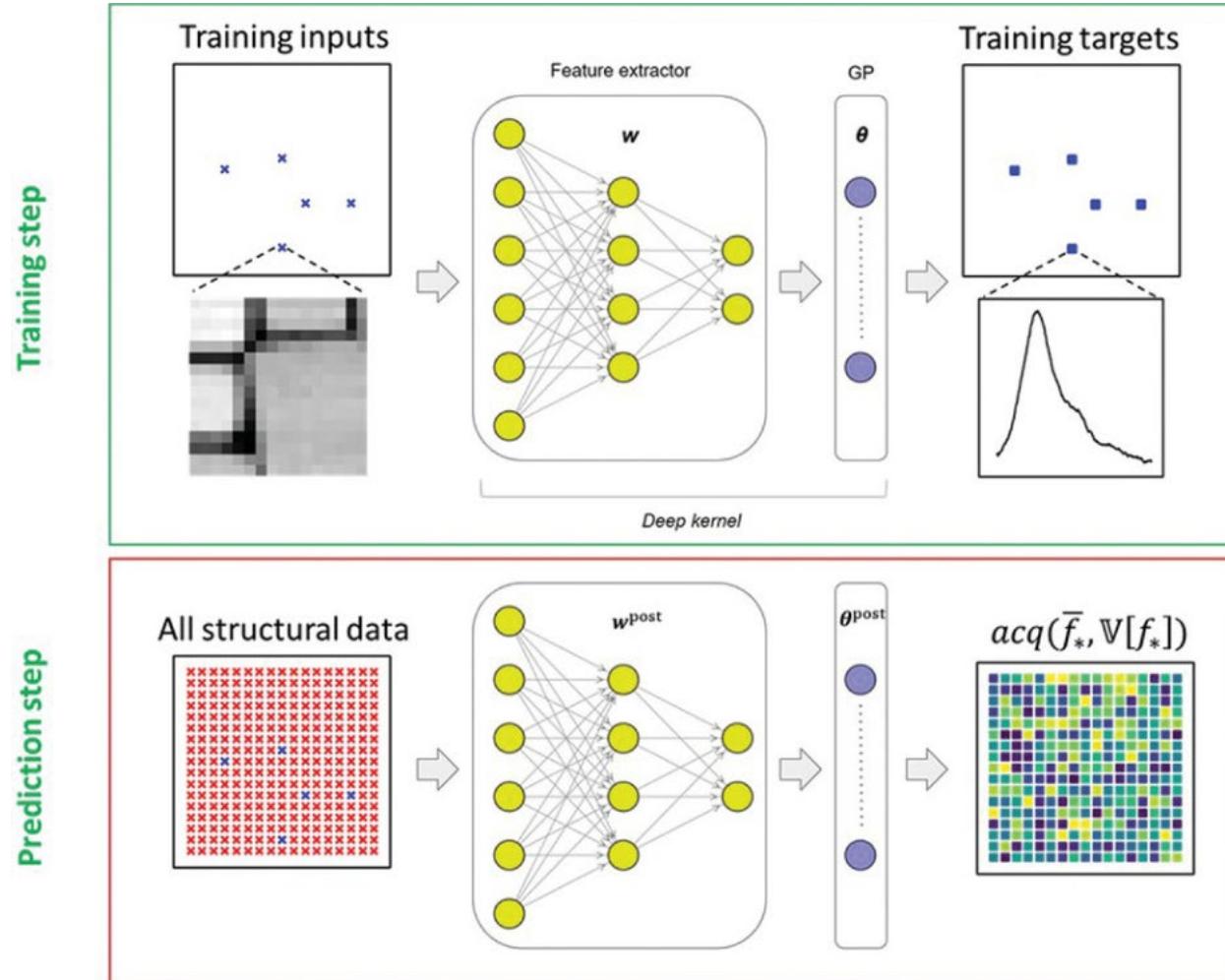
## How to perform sparse measurements (intelligently) in real time?

- Initial attempts →
  1. use gaussian process (**GP**) to “interpolate” the measurement space,
  2. then decide next measurements with Bayesian Optimization (**BO**)
- Gaussian Process → requires a kernel for reconstruction.
- - What kernel do we use?
  - Kernel length?
    - Periodic? Atoms... ok, lot of tuning... anything else?
    - Radial basis function (RBF) – maybe..
    - Custom kernel? But how to develop it?



If we could intelligently select a kernel... quickly!

# Deep kernel learning (DKL)



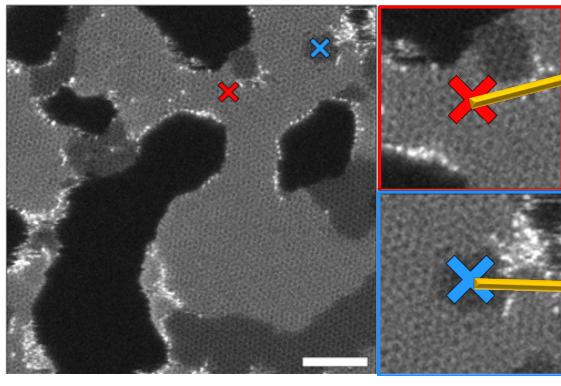
## Tuning knobs

- “Scalarizer”
  - Physics enters here
- Acquisition function
  - How to navigate given the predicted space
  - Expected improvement
  - Upper confidence bound
  - Uncertainty-based
  - Thompson sampling

# Actively learning structure-property relationships: Deep kernel learning (DKL)

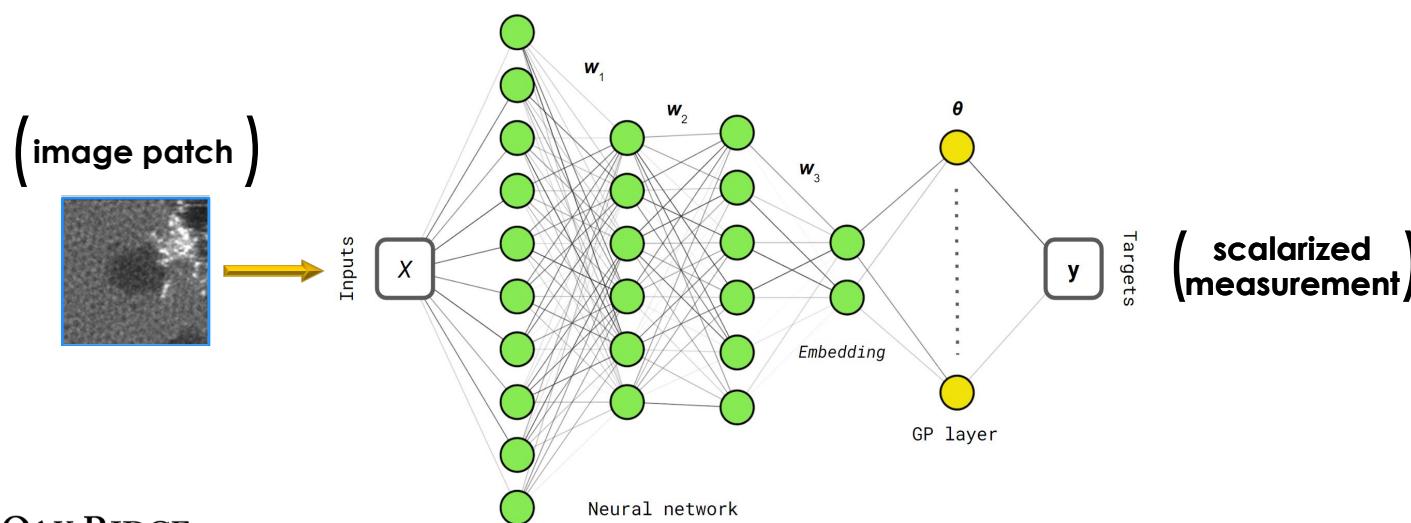
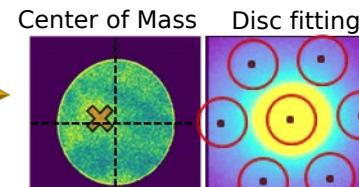
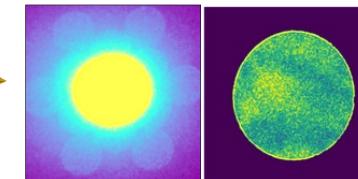
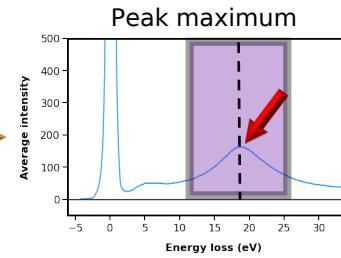
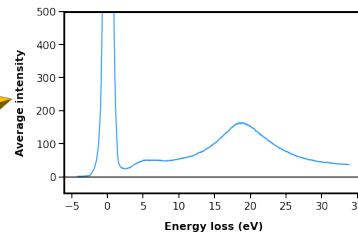
No pretraining!

This is all on-the-fly



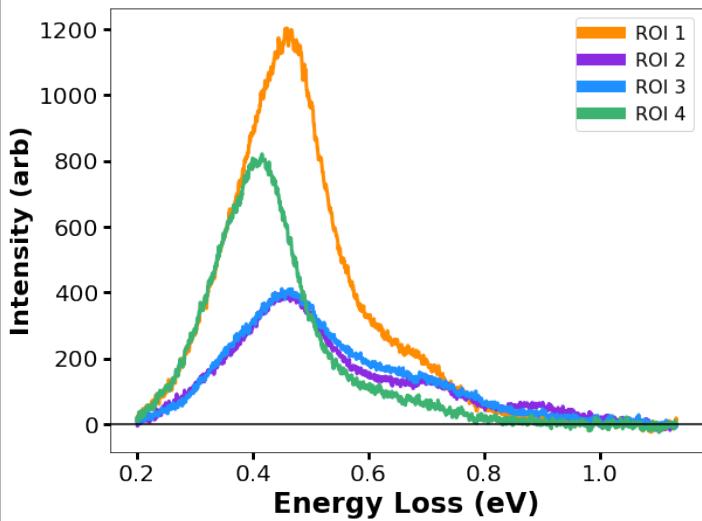
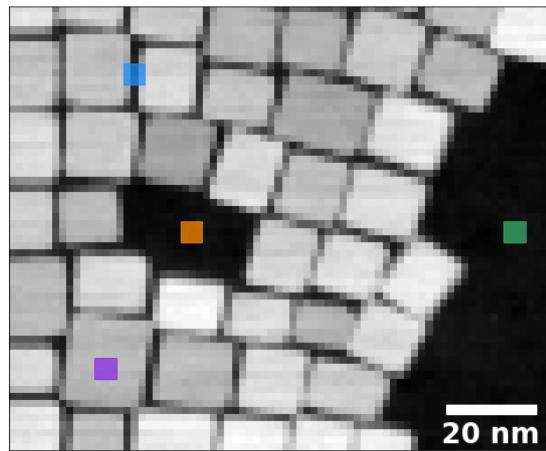
Complete  
**structural**  
image

Image  
patch

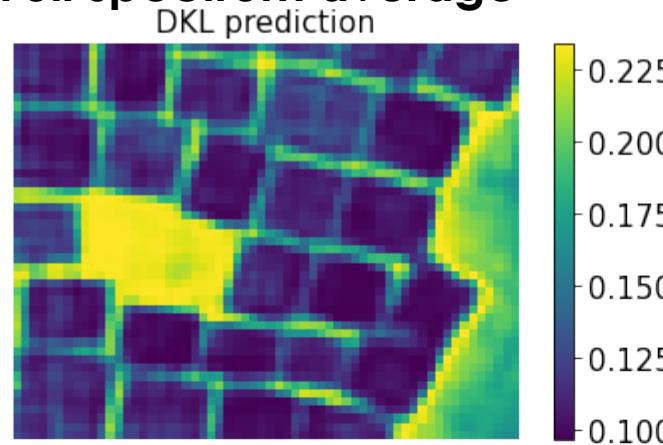


1. A complete **structural image**
2. Image **patches**
3. Perform a **measurement** @  $(x_1, y_1)$
4. “**Scalarize**” (**physics** incorporation)
5. Learn **correlation** between image signal and measurement signal (training step)
6. **Next measurement** @  $(x_2, y_2)$  based on learned correlation
7. Repeat

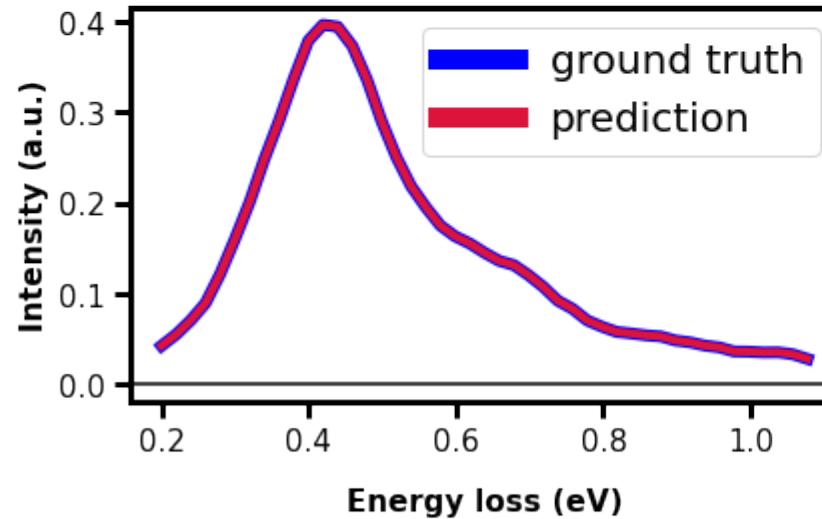
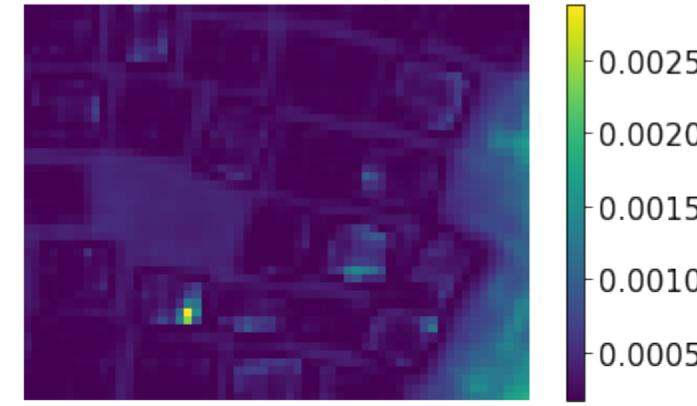
# DKL with **FULL** pre-acquired data (no active learning or BO)



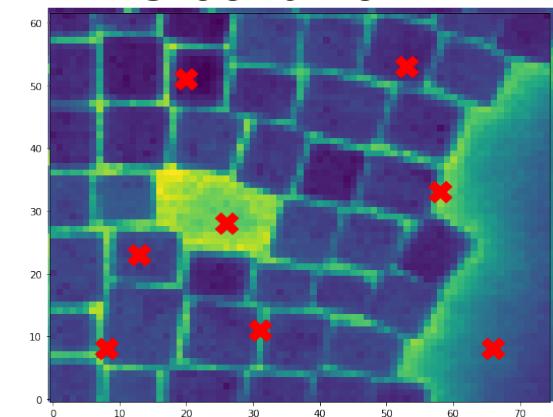
Full spectrum average



DKL uncertainty



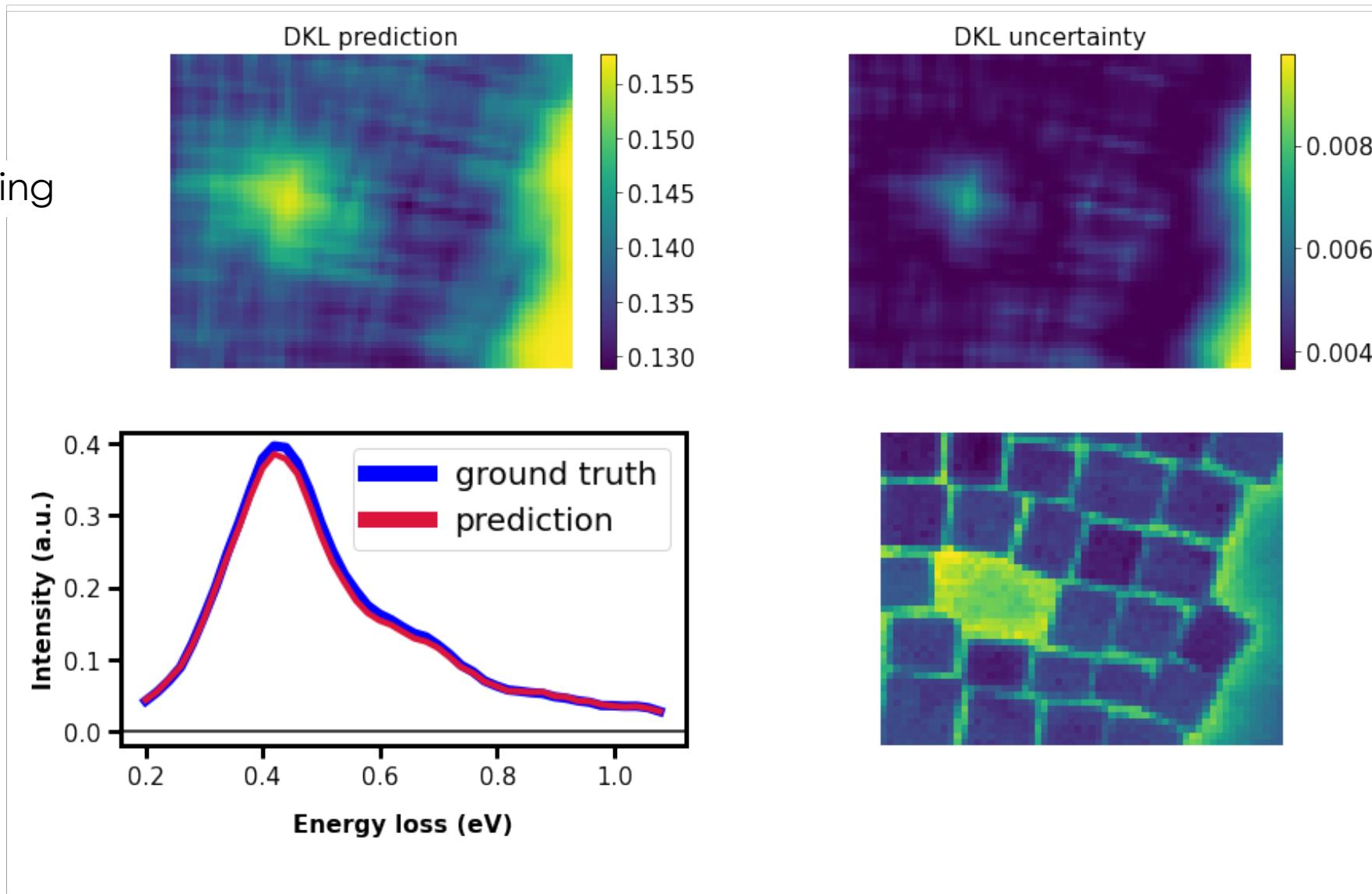
Ground truth



- This is actually “**vector**” DKL which **reconstructs entire 1D spectrum (or 2D image)**
- Is not so amenable for automated experiment, however

# DKL with partial pre-acquired data (no active learning or BO)

1% random sampling



# Active learning with DKL still on pre-acquired data using a scalarizer

## Scalarizers

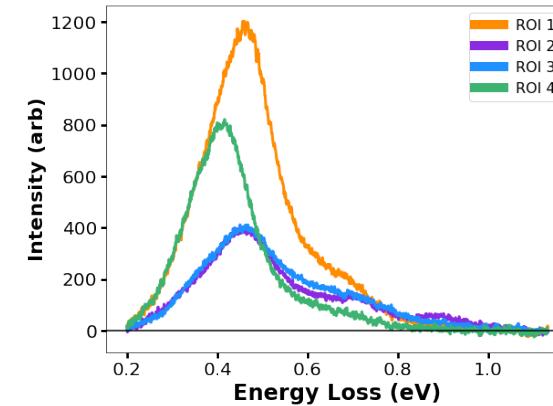
- Peak max in spectral range
- Ratio of peaks (e.g., L2,3 ratio, surface plasmon / bulk plasmon)
- Number of peaks
- Peak width
- .....
- Center of mass (magnitude, angle...)
- Charge density
- Strain (diffraction disc separation in fourier space)
- .....

## Acquisition functions

- Expected improvement
  - Upper confidence bound
  - Uncertainty-based
  - Thompson sampling
- **Handles the next measurement choice**, based on the currently learned structure-property relationship (i.e., prediction)
- “exploration” vs “exploitation”

# Active learning with DKL still on pre-acquired data using a scalarizer

```
1 def scalarize_acq(obj: np.ndarray) -> np.ndarray:  
2     """  
3         Scalarize acquisition function (n_samples x vector_size)  
4         by averaging over a selected energy band.  
5     """  
6     band = [0, -1]  
7     obj = obj[:, band[0]:band[1]].mean(-1)  
8     return obj
```



Measure & scalarize

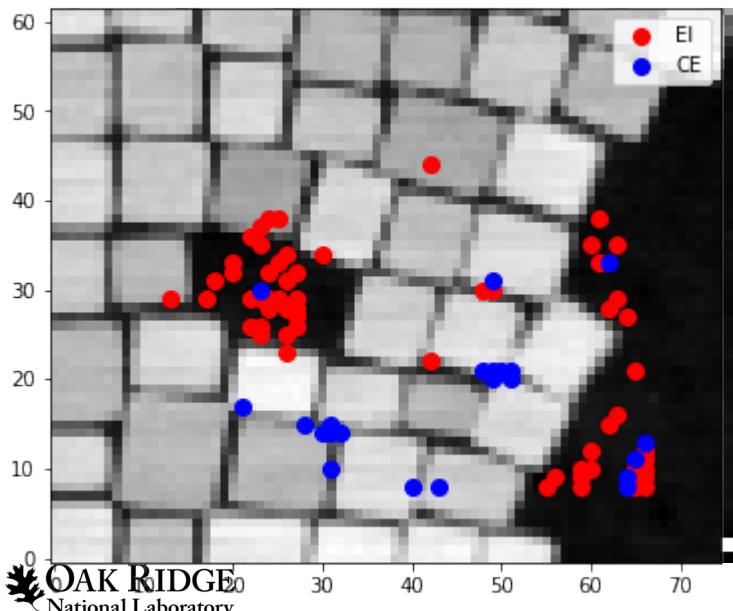


Train

New measurement  
**based on A.F.. Repeat**

Next measurement point: *argmax()*

- Averaging whole (background subtracted) spectrum → **favoring the strong dipole plasmon**



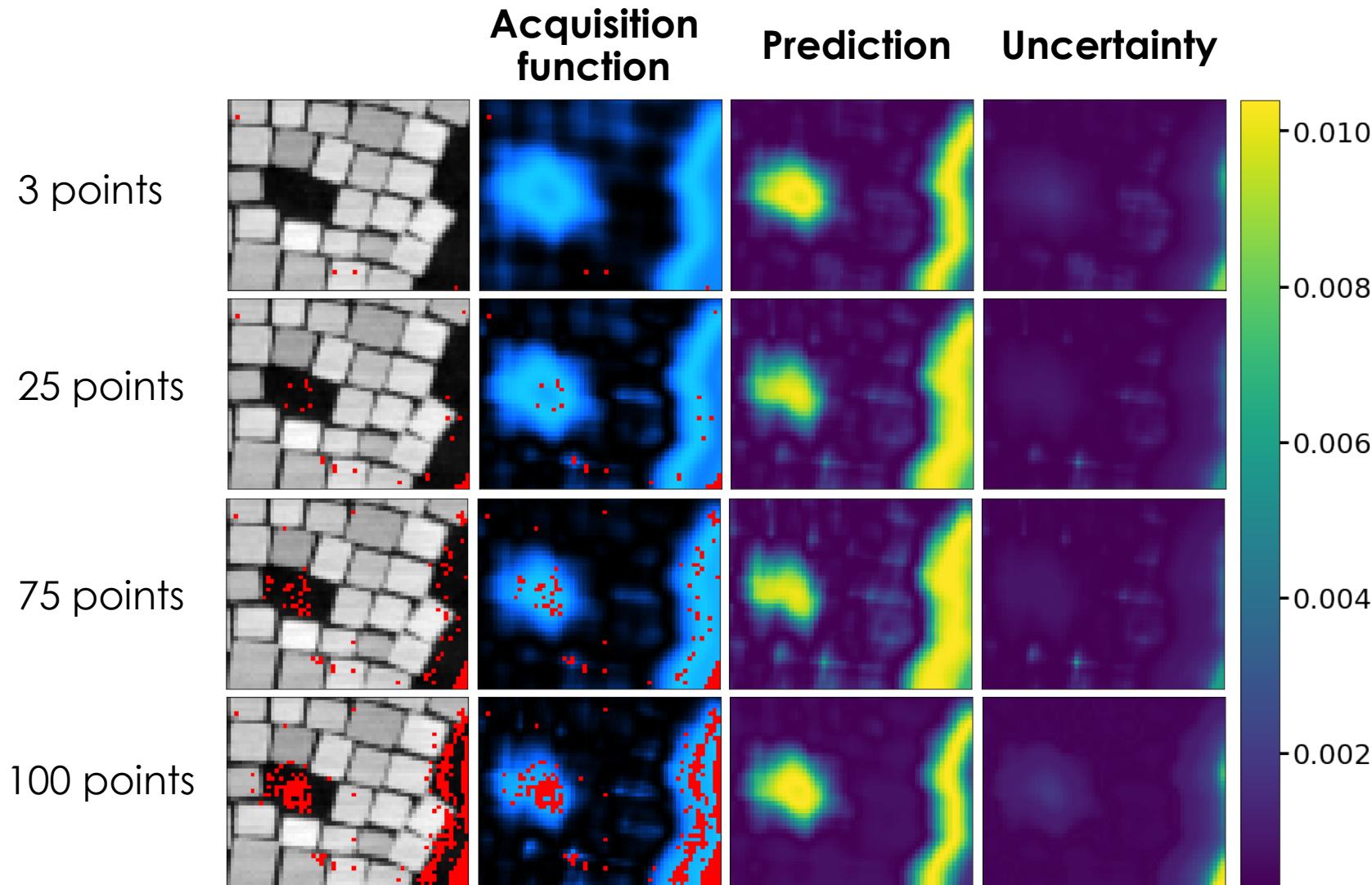
Choice of  
**acquisition  
function** affects  
pathway

Acquisition function (Video)



# Evolution and performance in time

## Have a look at predictions



- A good approximate structure-property relationship is **learned very quickly**
- In practice, we do not need to train at every new measurement
- Alternatively, can halt training after a few measurements (or some criterion met), then follow the acquisition function map
- Remember, **this is a prediction of the scalarized value** not the full spectrum

# **A real automated experiment**

# Can ML run experiment as a scientist?

(screen record video)

With **access to microscope controls** (Python API), this is deployed on an instrument

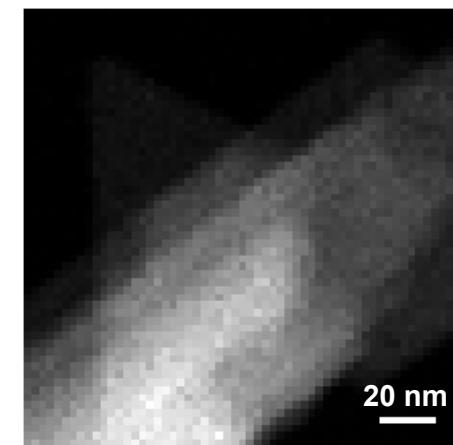
- **Continuously learning** structure-property relationships with each new measurement
- **Dose reduction!**
- In some sense, this is sparse sampling, but each subsequent point depends on the previous



Beam is blanked  
during training steps

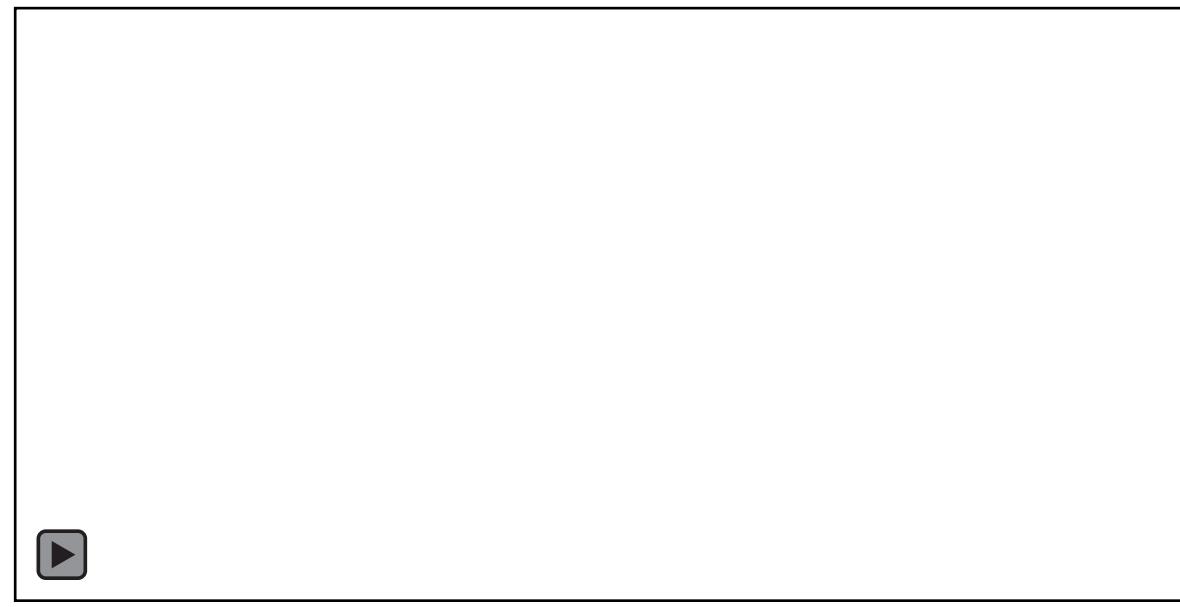
# Physics-based feature engineering: $\text{MnPS}_3$

- Discovering physics in a “new” material  $\text{MnPS}_3$



“Acquisition function”

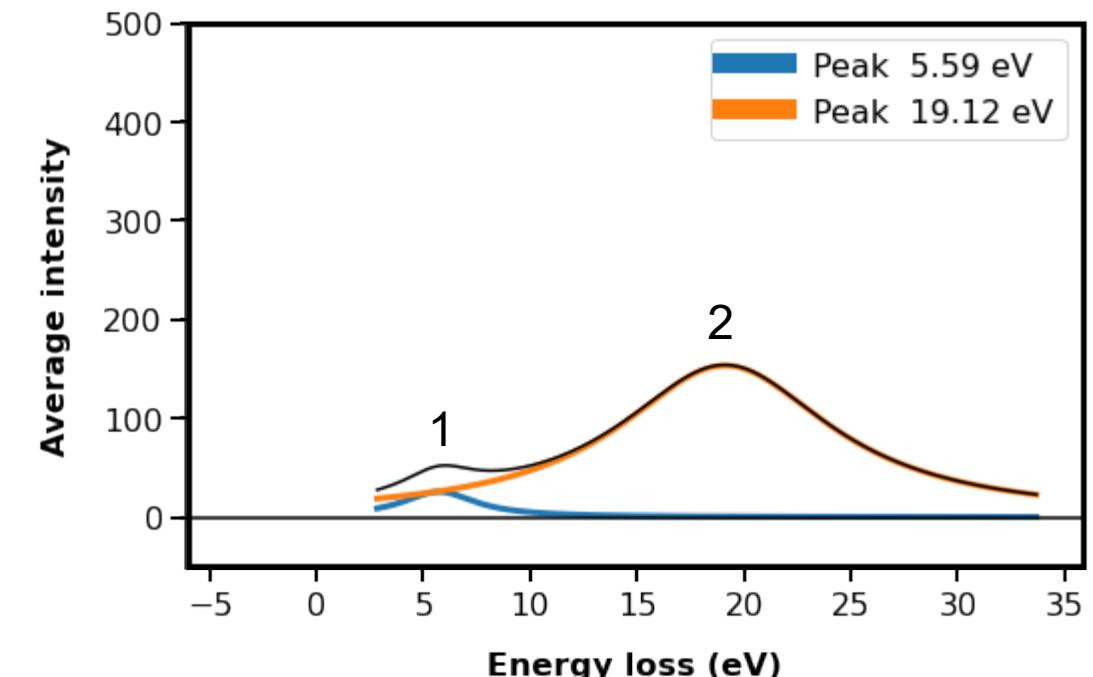
(Video)



HAADF-STEM  
+ points visited

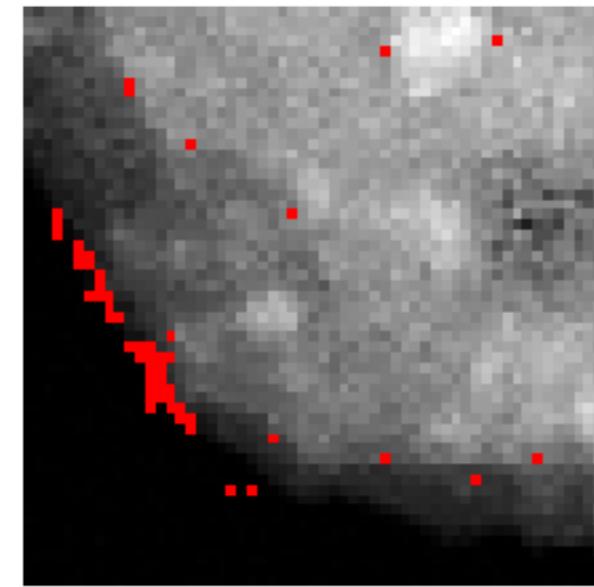
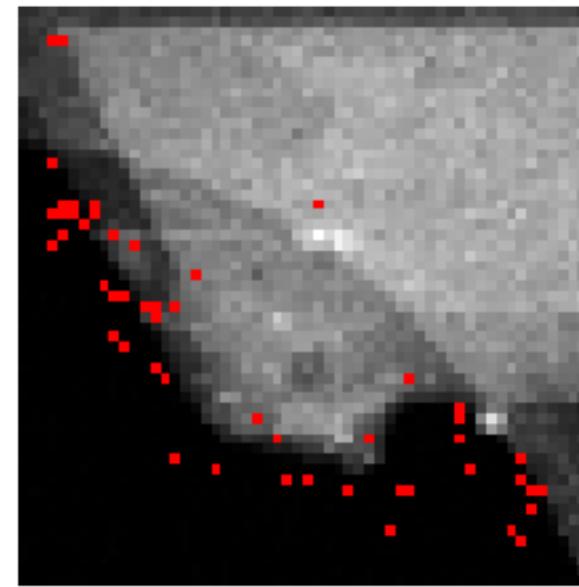
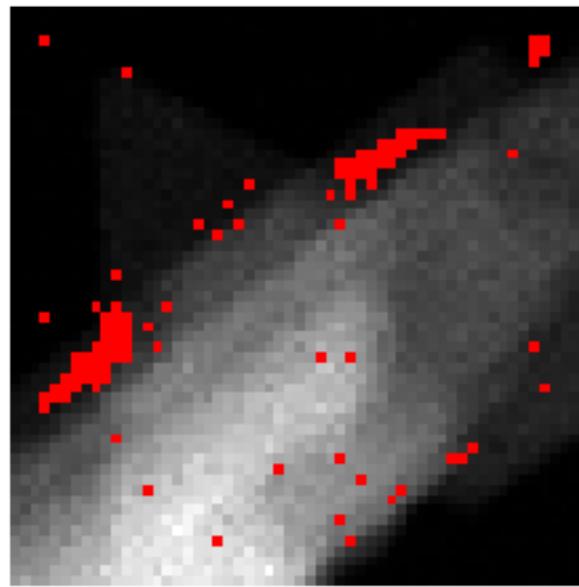
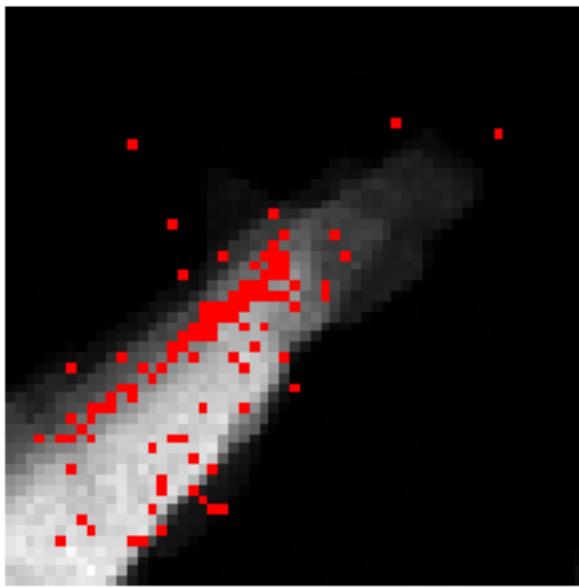
Physics search criteria:

$$\textit{Ratio} = \textit{Peak 1} / \textit{peak 2}$$



# Reproducible

- Very similar behavior when searching for the same criteria elsewhere!
- Success!



**Discovery pathway depends on the reward structure (scalarizer that defines signature of physics we want to discover)!**

# Change the scalarizer... change the physics

- (Same region) **Simple physics search:** peak max in selected region

Physics search criteria:

$$\text{Maximize}(f)$$

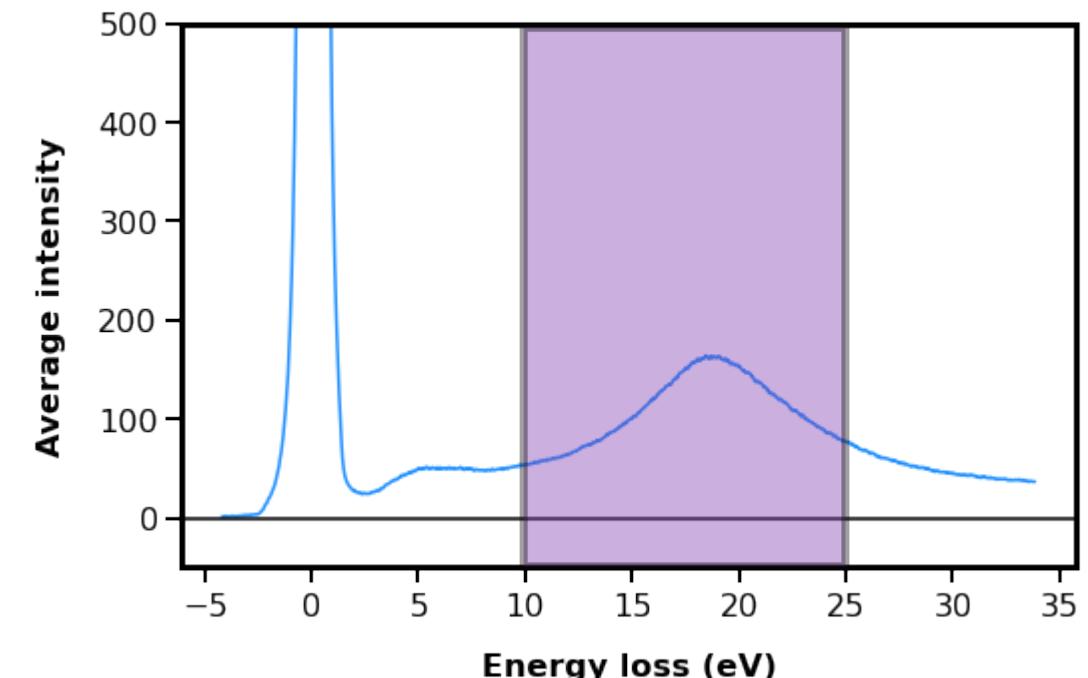
“Acquisition function”

(Video)

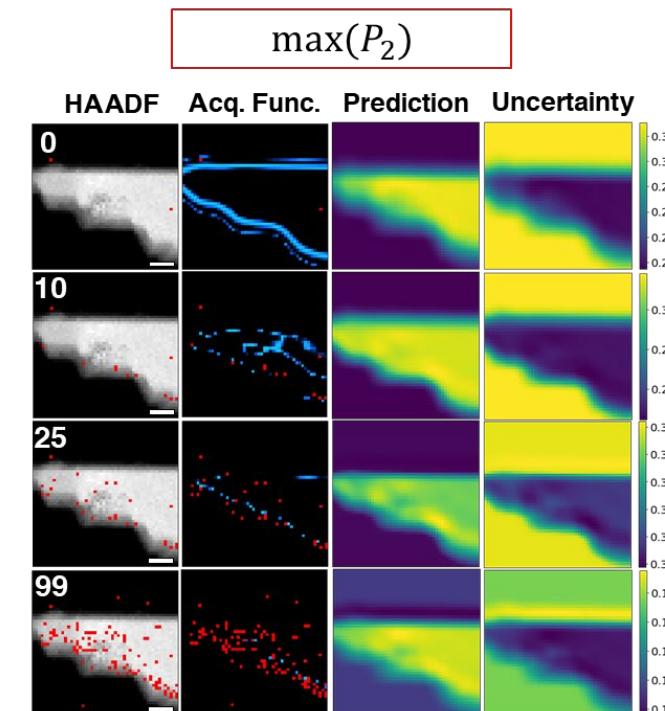
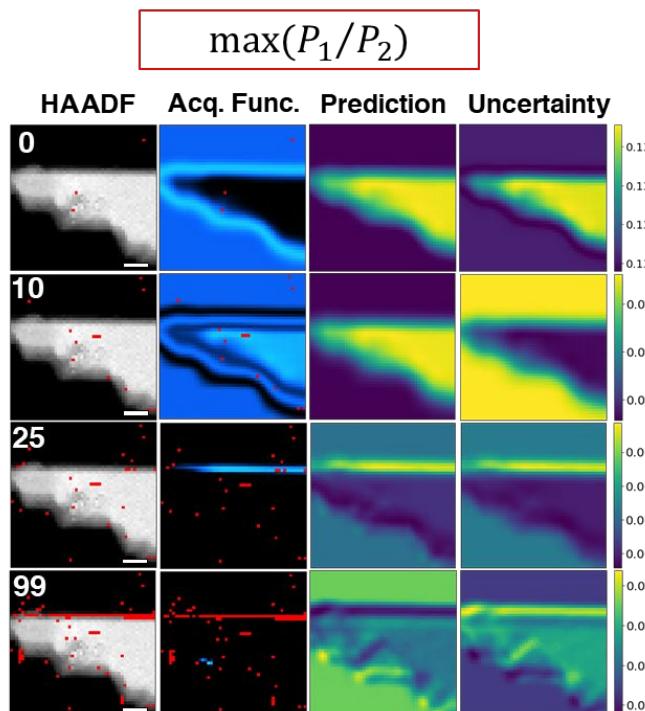
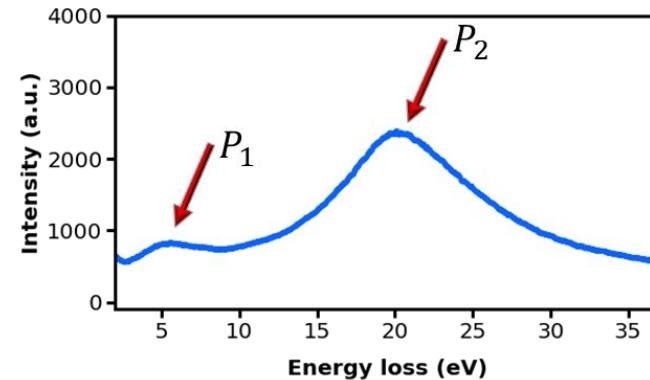
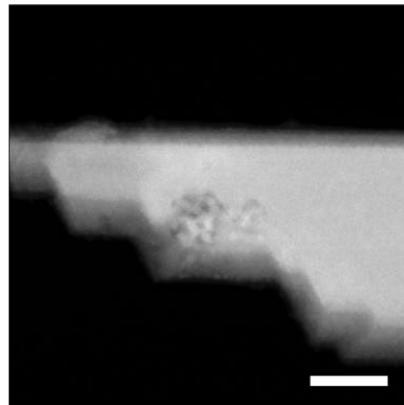


HAADF-STEM  
+ points visited

**(Specific peak intensity)**

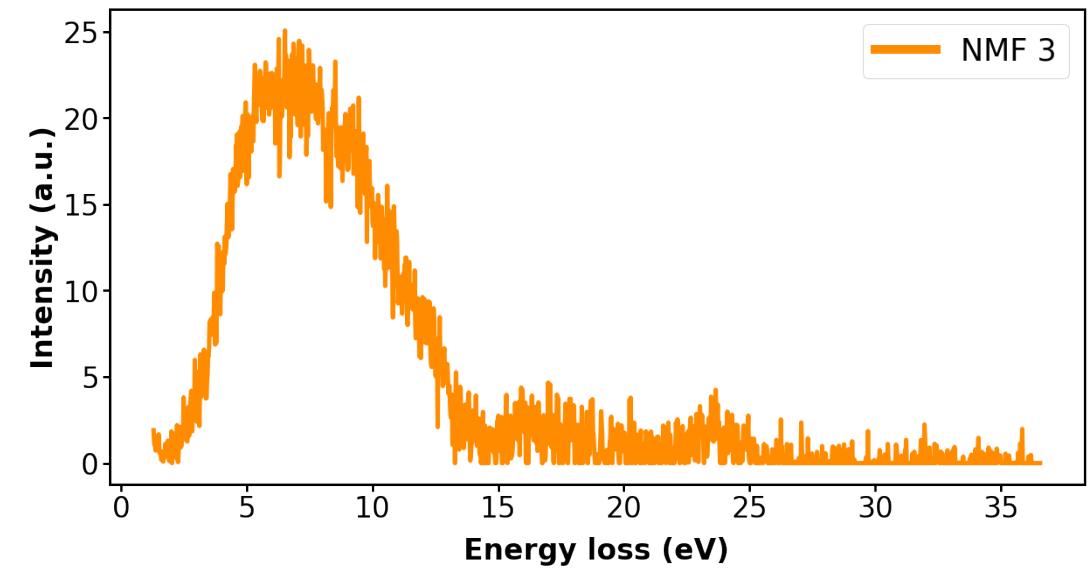
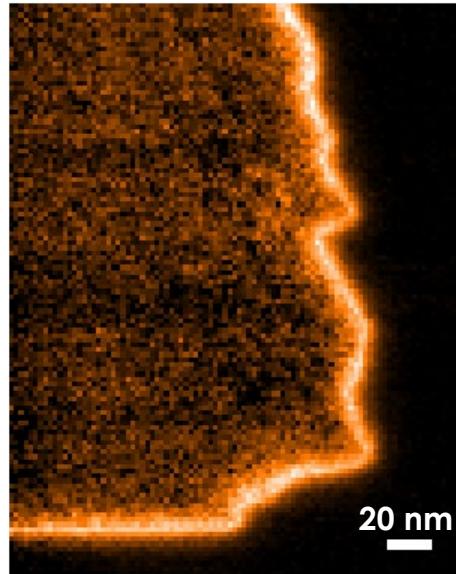


# Summarize these automated experiments..

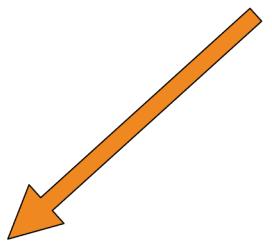


# Confirmation

- Full hyperspectral EELS set collected and decomposed into few number of components (NMF)
- Indeed, there is edge plasmon activity near the energies used in the DKL

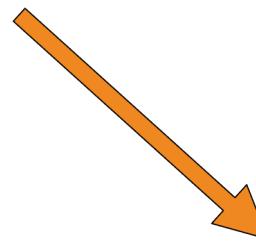


# 4D STEM



## Center of mass

- Electric field
- Potential
- charge density

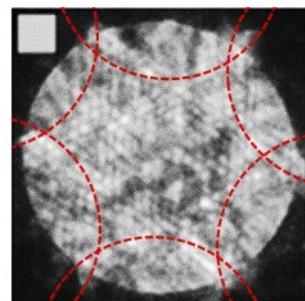
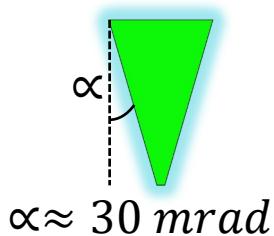


## NBED disc fitting

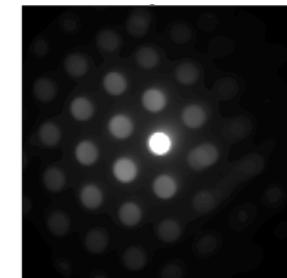
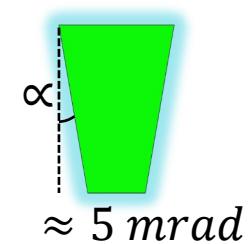
- Strain
- Grains

Require different probe conditions

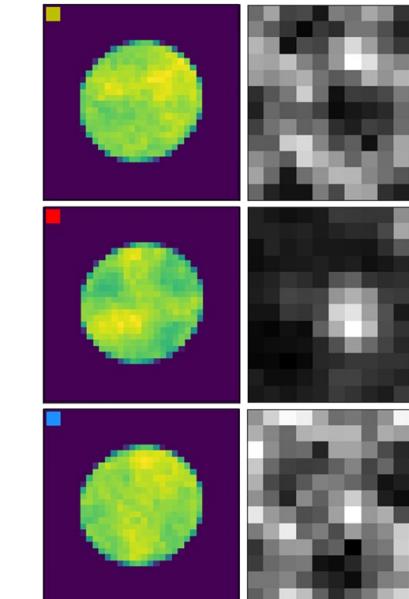
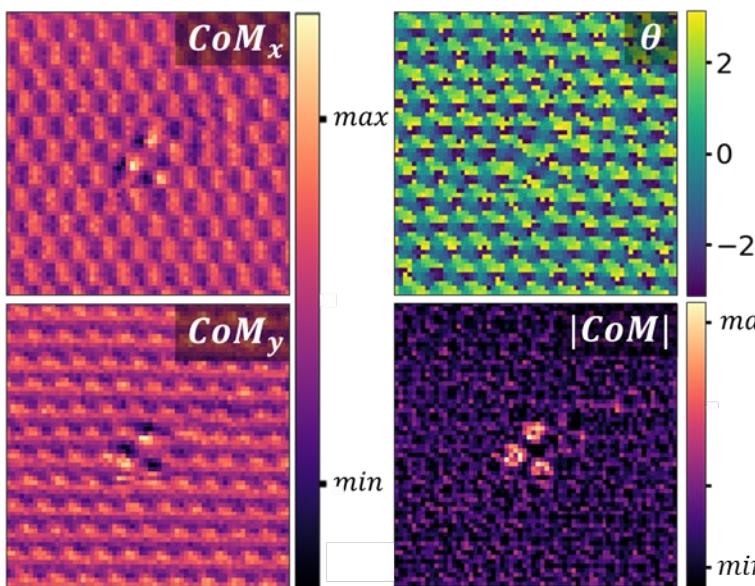
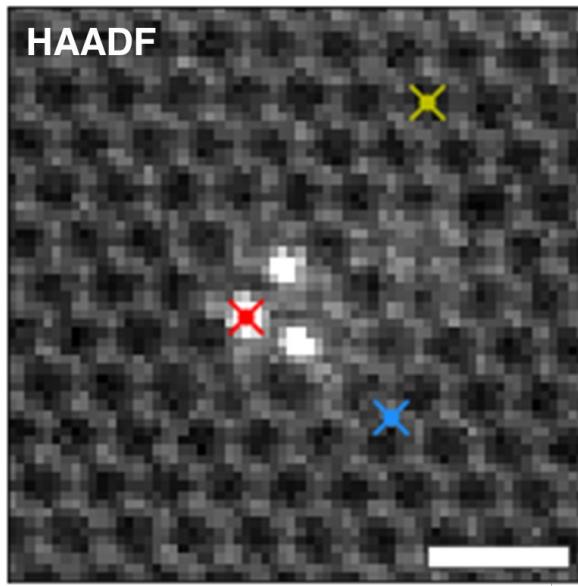
### Overlapping diffraction discs



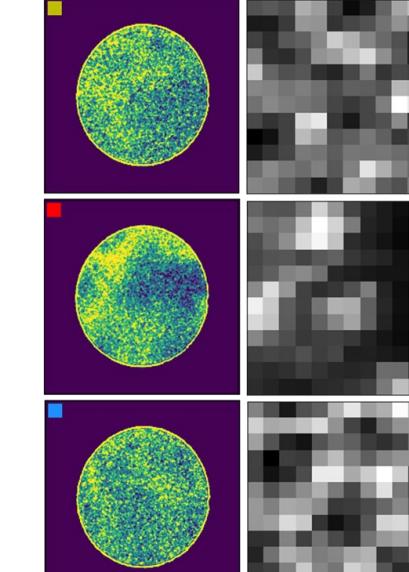
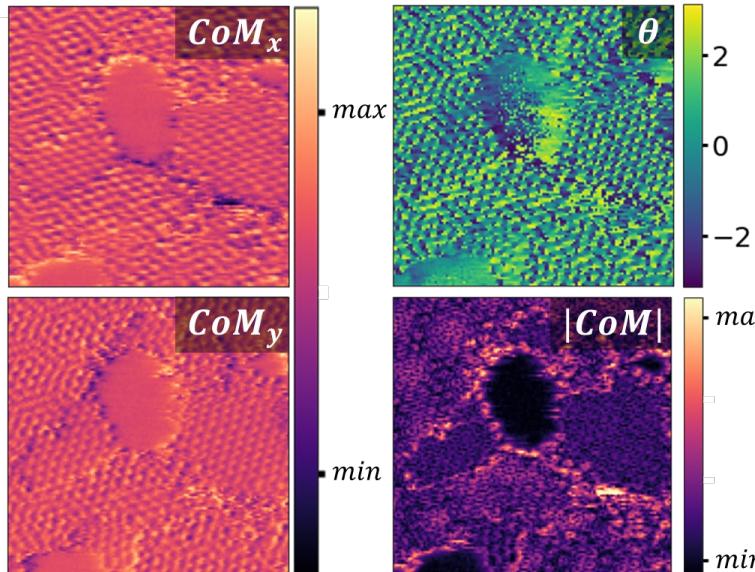
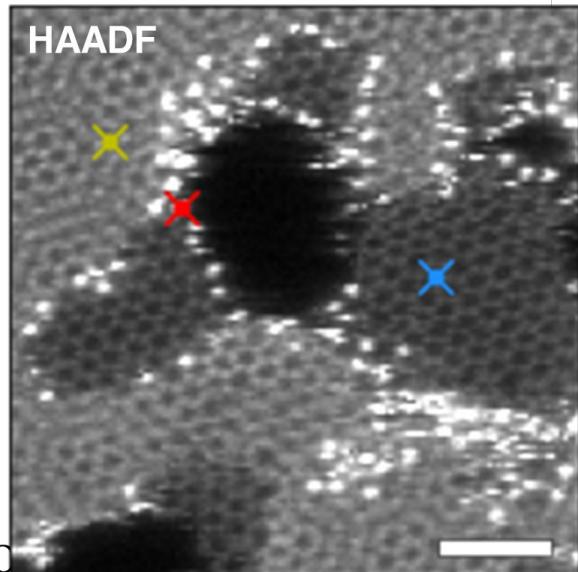
### Non-overlapping diffraction discs



# DKL: 4D STEM – center of mass (DPC)



Do not normally care about the local image information



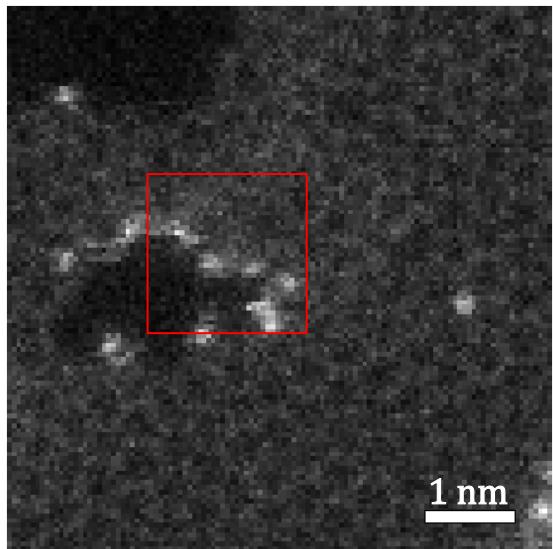
But again, let's make use of it!

# DKL: 4D STEM – center of mass

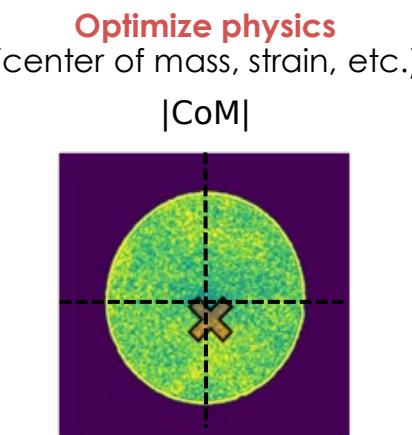
Example experiment:

- search for **maximum sample electric field**
- calculate  $|\text{center of mass}|$  of diffraction pattern

Full structural image



Measured quantity



Acquisition  
function



Prediction  
map



Uncertainty  
map

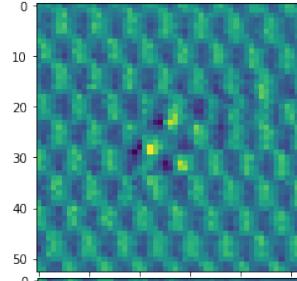


# DKL: 4D STEM (pre-acquired data)

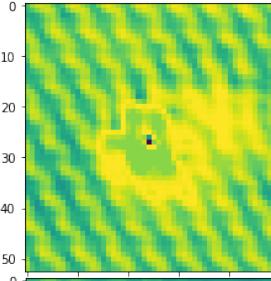
- Choosing **different scalarizers**, does one perform “better”?
- Some interesting (real) artifacts appear in some predictions

$\text{CoM}_x$

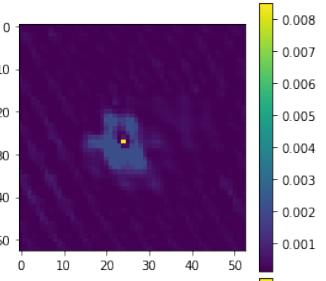
Ground truth



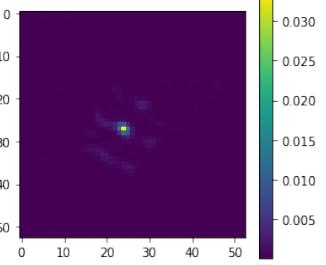
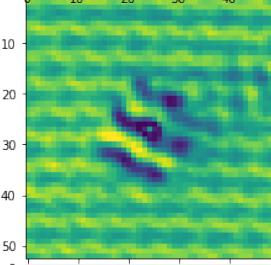
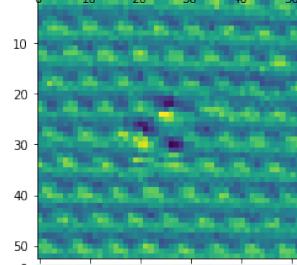
Prediction



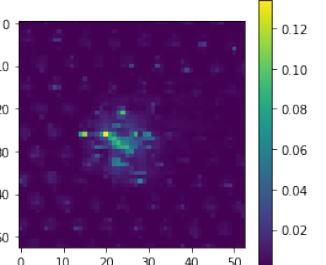
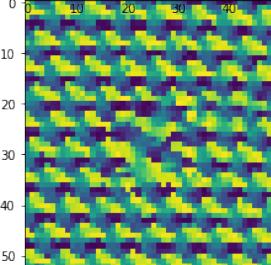
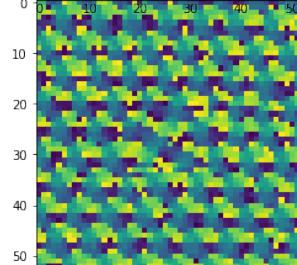
Uncertainty



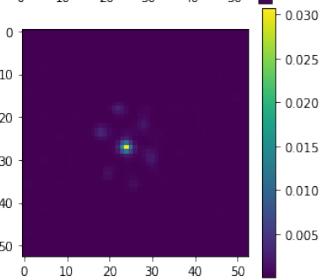
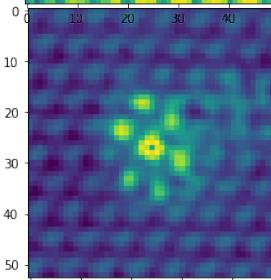
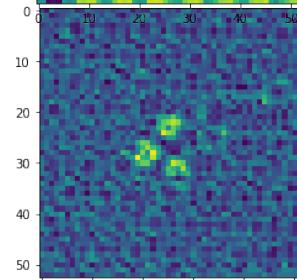
$\text{CoM}_y$



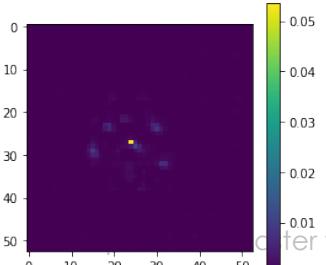
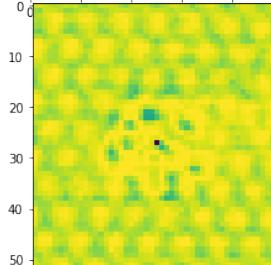
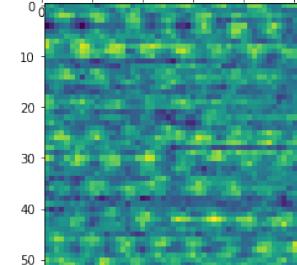
$\text{CoM}_\theta$



$|\text{CoM}|$



Virtual  
ABF



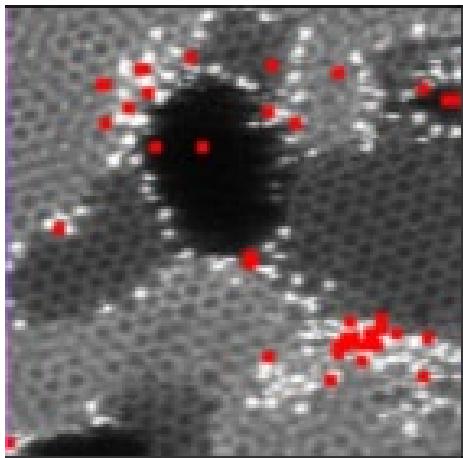
later to edit

# DKL: 4D STEM active learning (pre-acquired data)

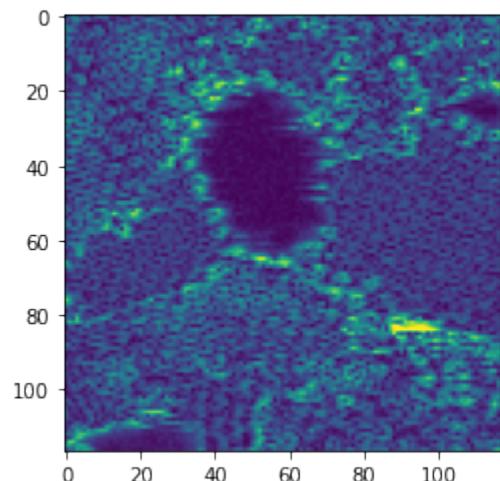
Scalarizer:  $|\text{CoM}|$

After 25 measurements

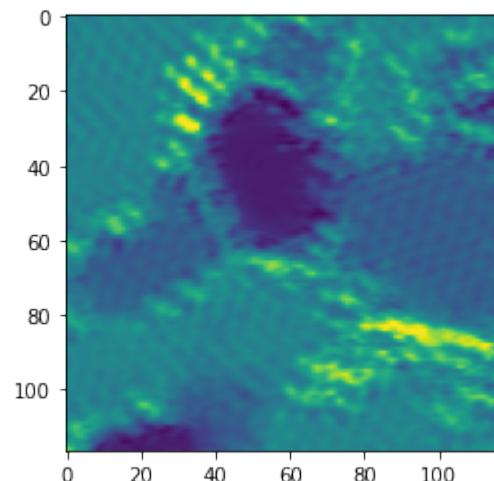
ADF with measurement points



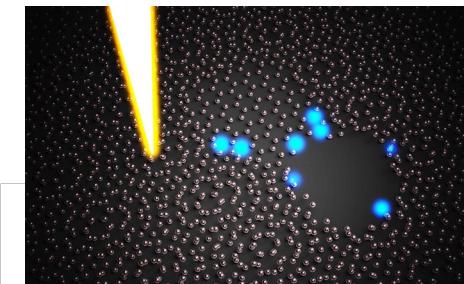
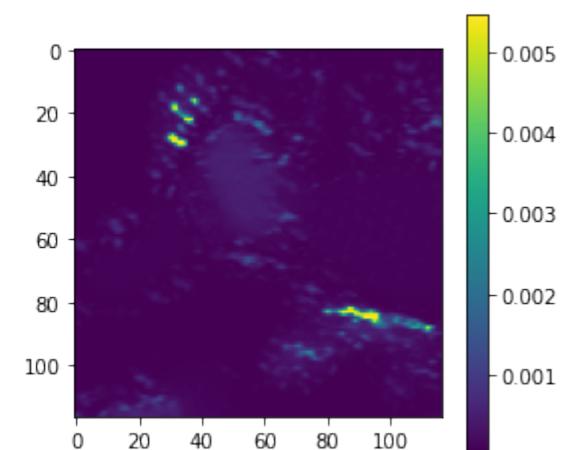
Ground truth



Prediction



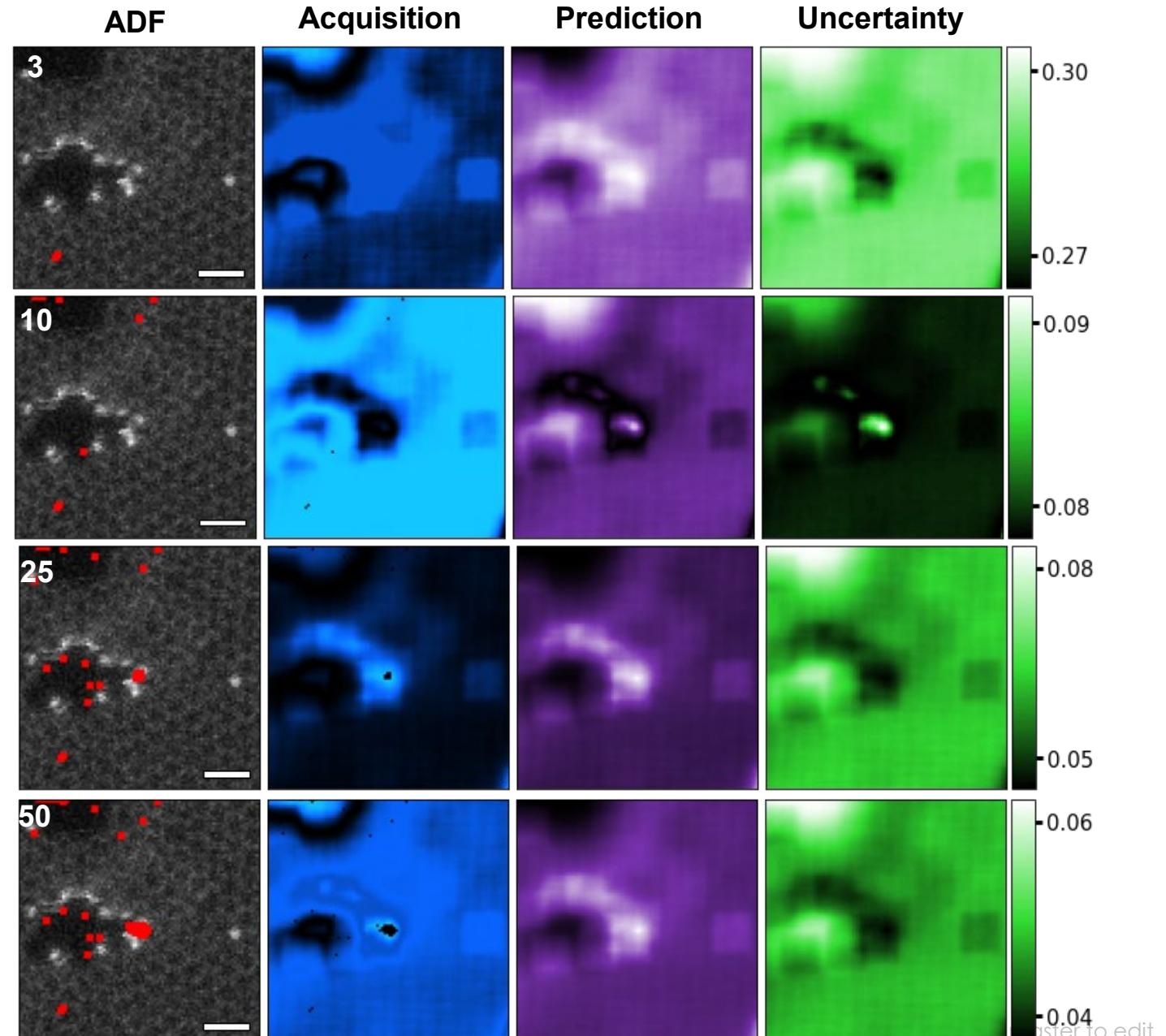
Uncertainty



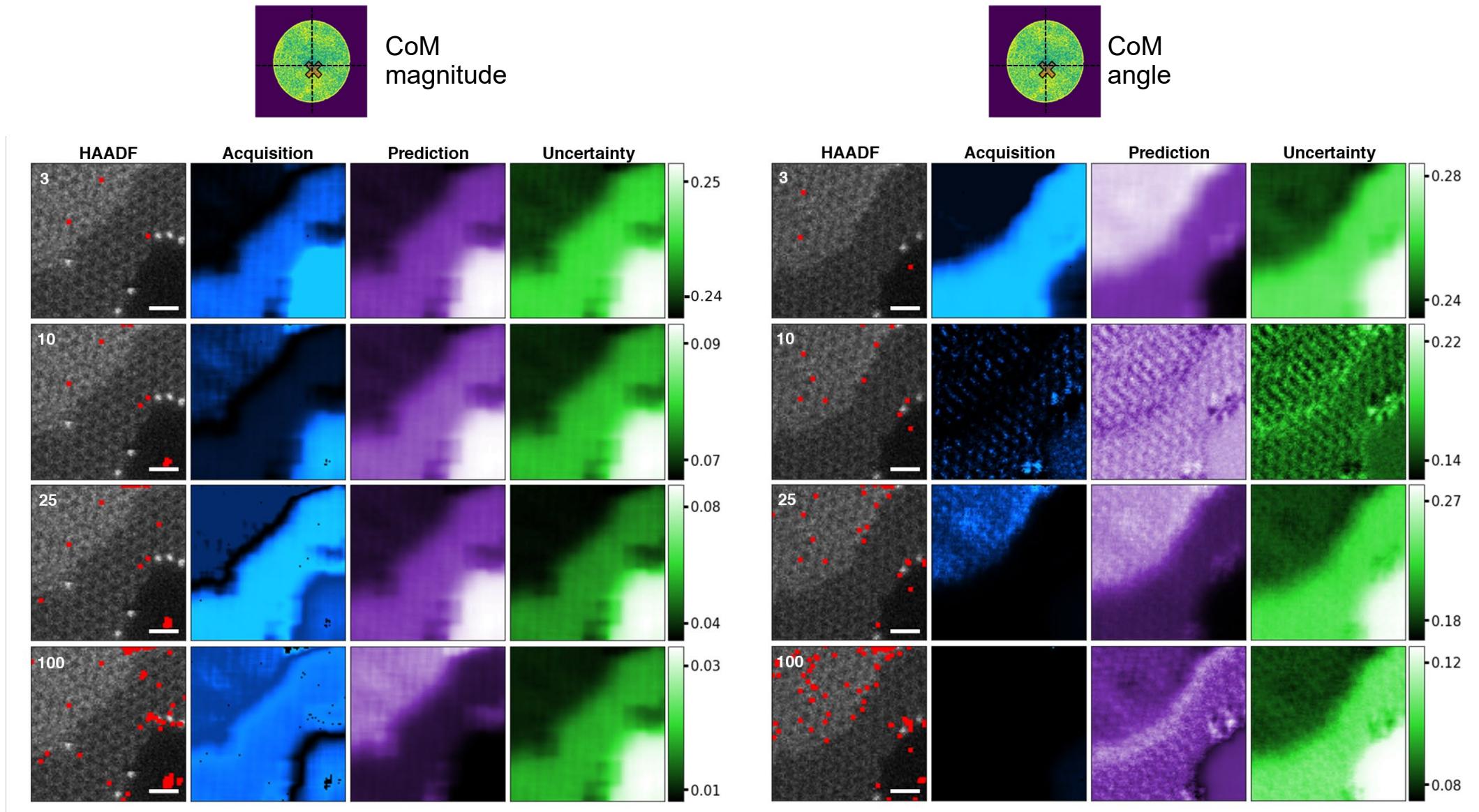
# Active learning: real automated experiment

## Scalarizer: *CoM* magnitude

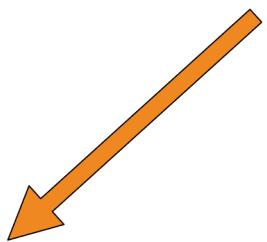
- High uncertainty @ start, but fairly quickly reduces
- Prediction actually doesn't drastically change throughout experiment
  - Structure-property relationship here is fairly rapidly learned
- Note the training can be halted after some criterion is met, making remainder of experiment go much quicker



# Effect of physics choice (scalarizer) on acquisition

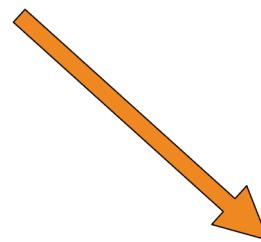


# 4D STEM



## Center of mass

- Electric field
- Potential
- charge density

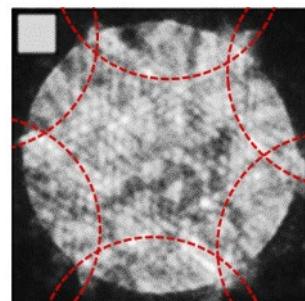
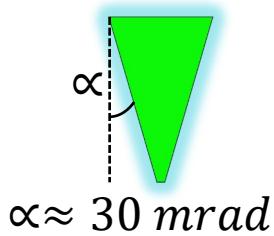


## NBED disc fitting

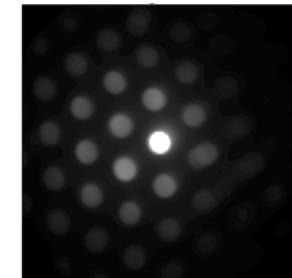
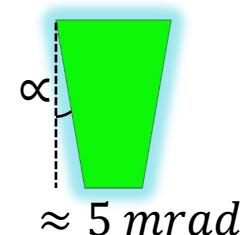
- Strain
- Grains

Require different probe conditions

### Overlapping diffraction discs

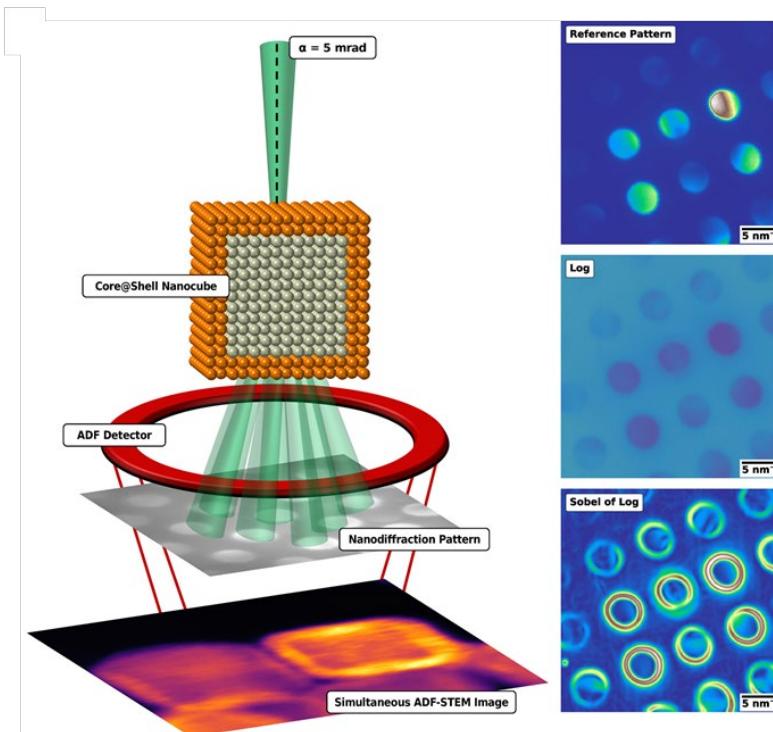


### Non-overlapping diffraction discs



# Measuring strain in the STEM

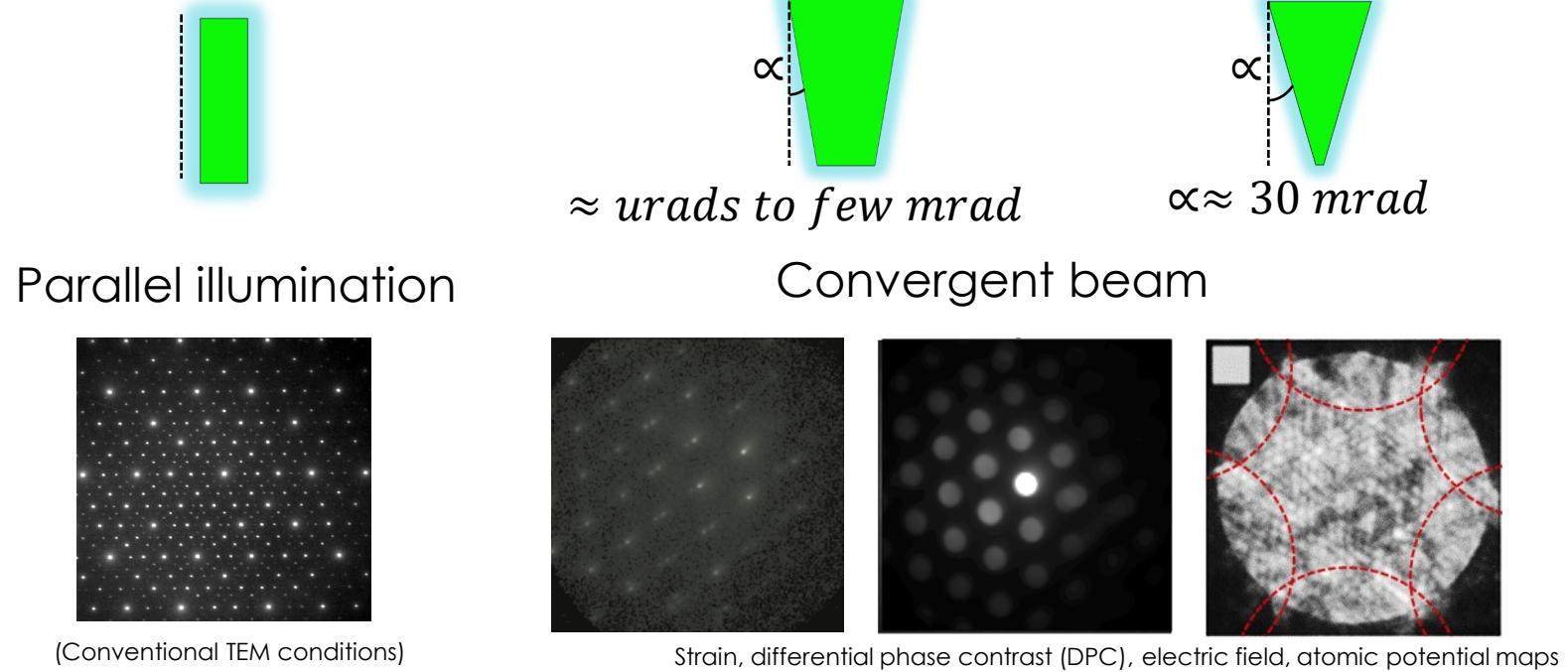
## Using local diffraction



Mukherjee D. et. al., ACS Catal. 2020, 10, 10, 5529–5541

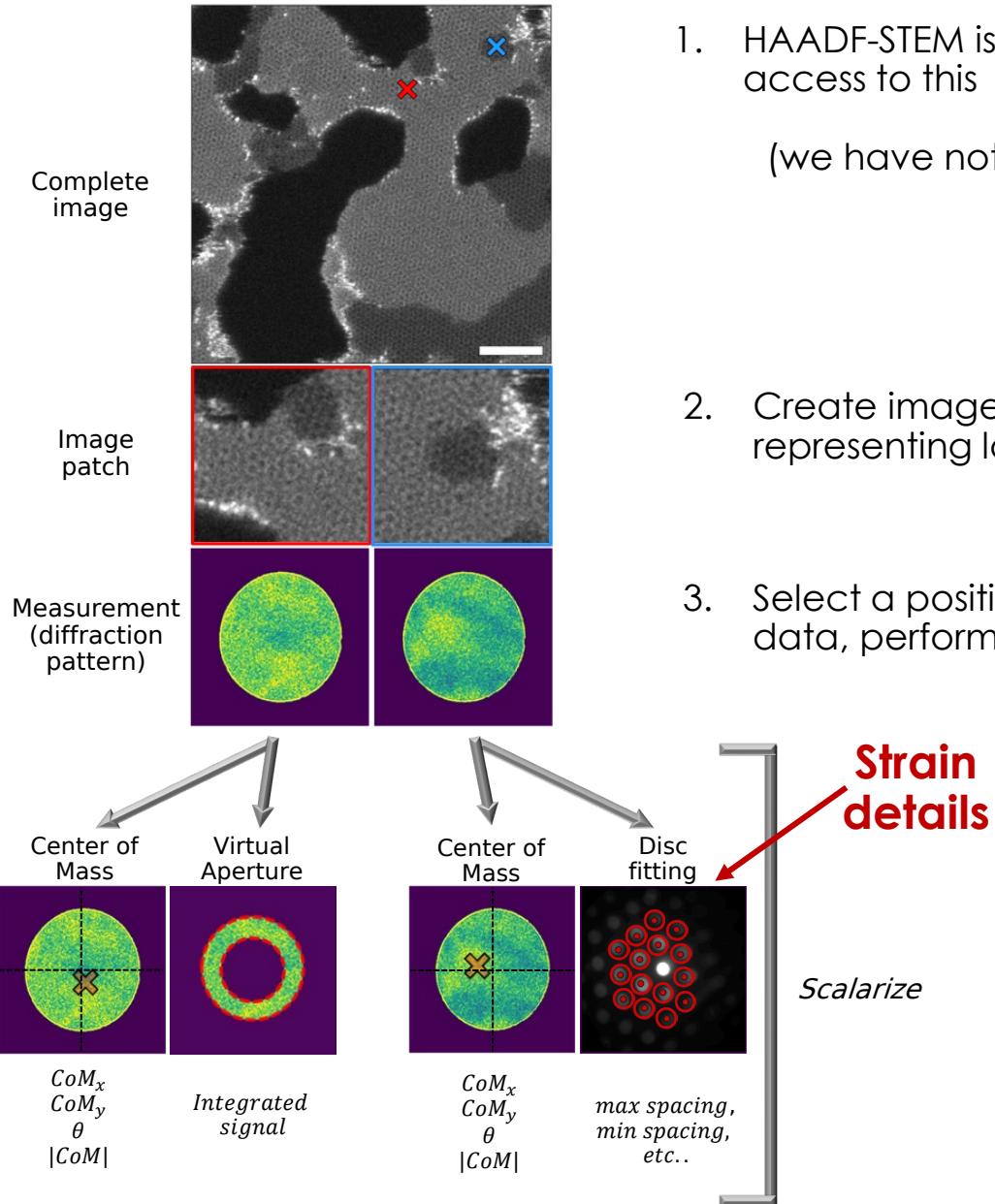
### Requirements:

- Pixelated detector
- Diffraction **disc** fitting



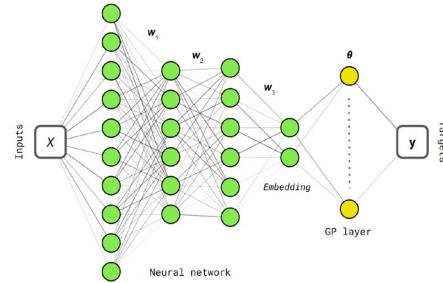
Strain is calculated **after** experiment (offline analysis)

# Neural Network Architecture

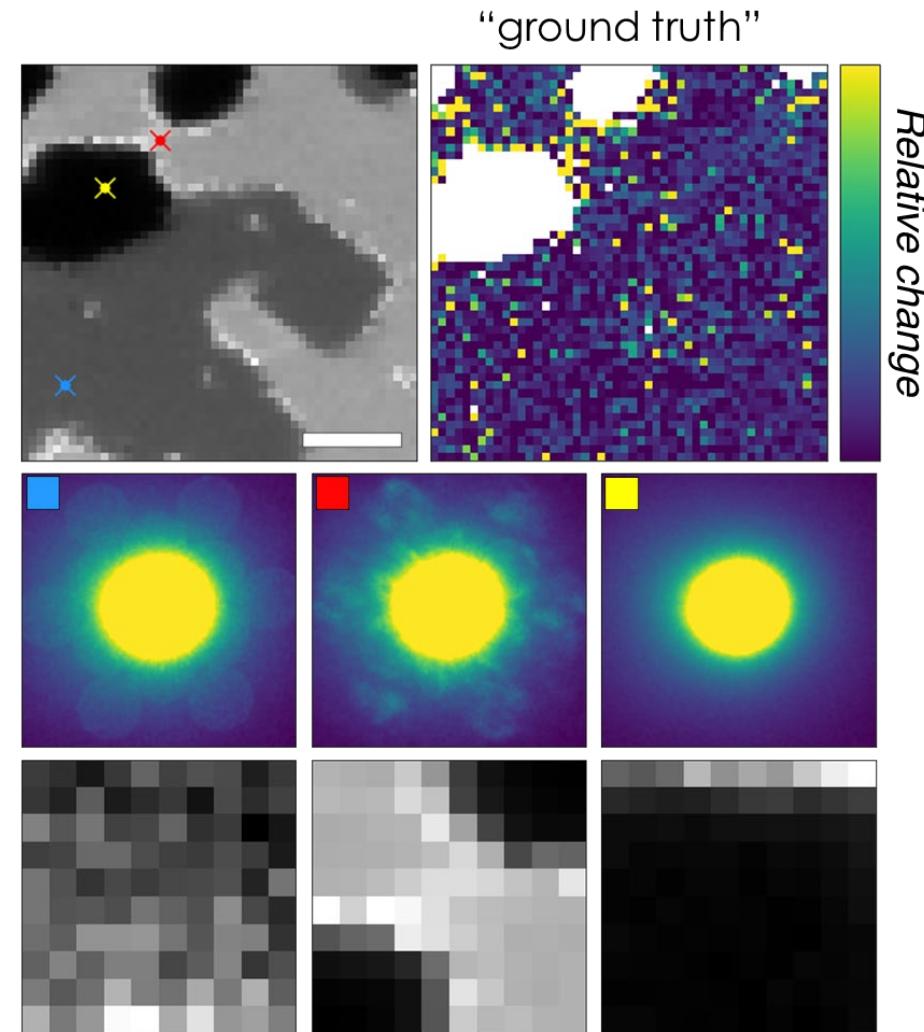
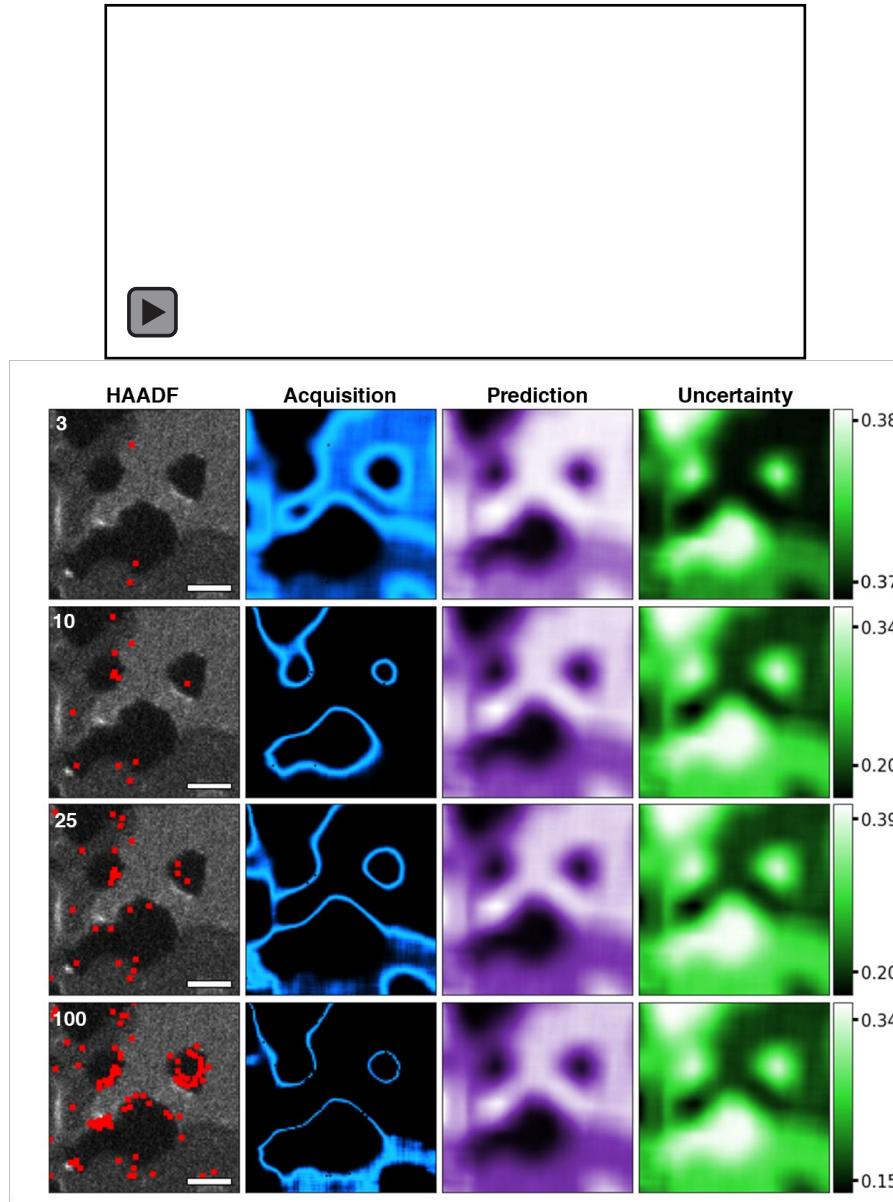


1. HAADF-STEM is acquired first, we have **complete** access to this  
(we have not yet collected diffraction data yet)
2. Create image patches at each pixel, representing local geometry/structure
3. Select a position in space to acquire diffraction data, perform computation (scalarize).
4. Train / update network with **image patch** and **scalarized quantity PAIR**. Repeat 3&4 (automated)

This is controlled by physics-based “acquisition function”



# Automated Experiments in 4D STEM: strain



# **Hands-on notebook!**

# Tips for speed / memory problems

- Change to **GPU runtime** if not already
- `spectralavg = 128`
- `dklgp = aoi.models.dklGPR(data_dim, embedim=2, precision="=single")`