

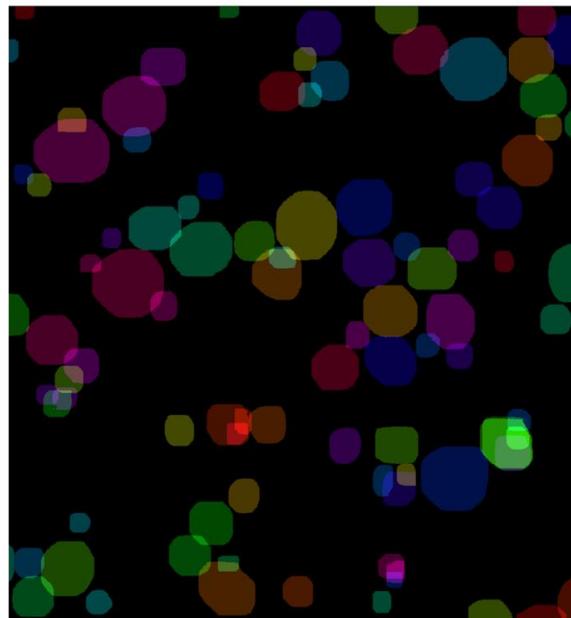
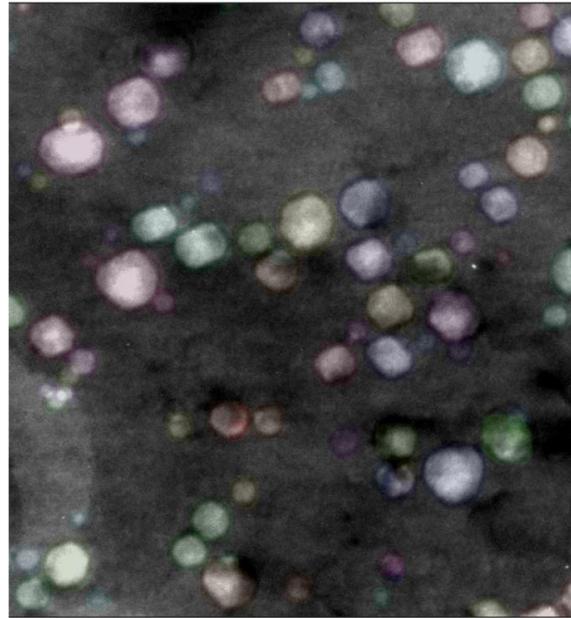
MSE 494/576

# Lecture 30: Labeling for CNN Image Segmentation

Given by Tommy Wong

Instructor: Sergei V. Kalinin

Labeling this image took ~ 1 hr, DL  
prediction took < 1 min.

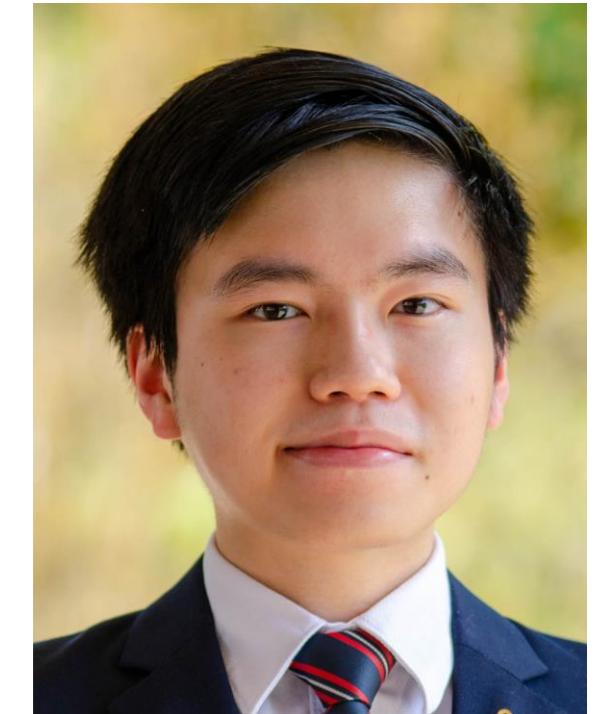


# About me

Tommy (Chun Yin) Wong

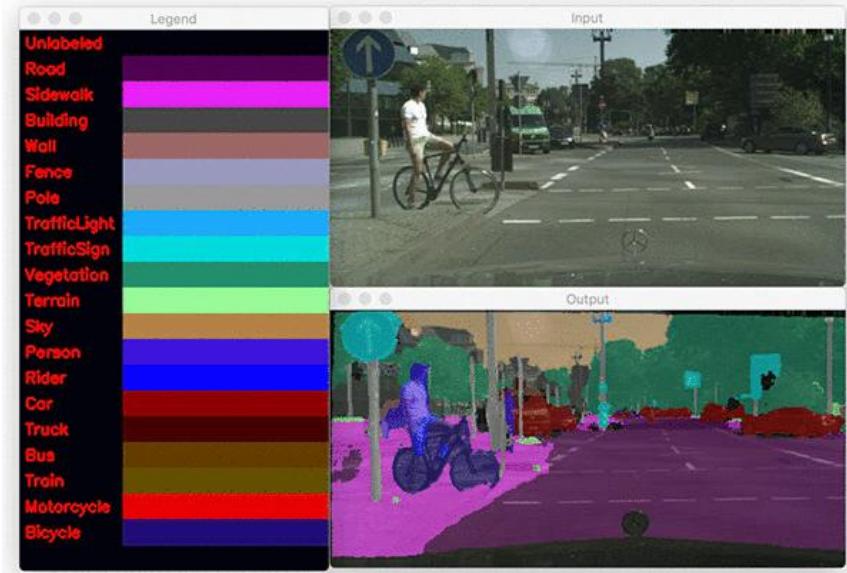
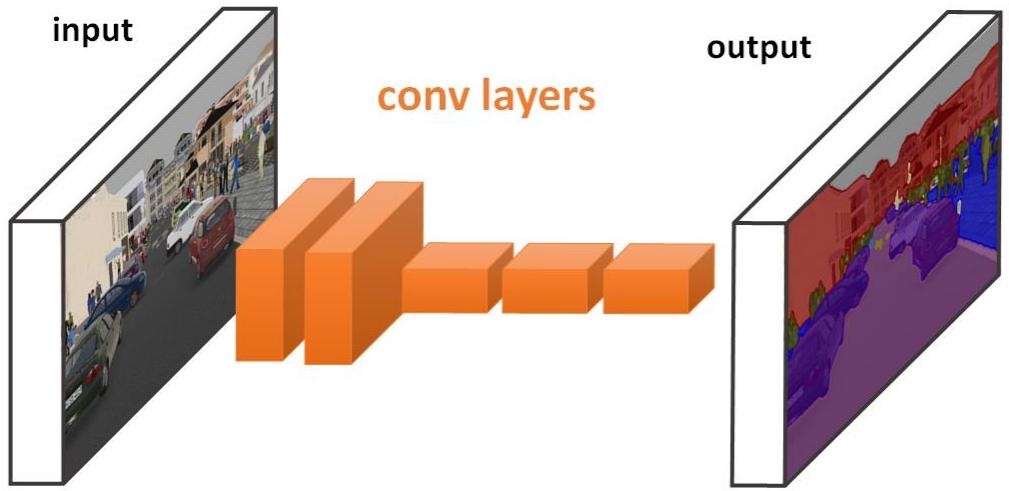
Advisors: Dr. Sergei Kalinin, Dr. Maxim Ziatdinov

- Research interests: deep learning & computer vision, electron microscopy, radiation damage
- 4th year Ph.D. student in Energy Science & Engineering, Bredesen Center
- M.S. in Materials Science & Engineering '22, University of Tennessee
- B.S.E. in Nuclear Engineering & Radiological Sciences '20, University of Michigan
- [cwong13@vols.utk.edu](mailto:cwong13@vols.utk.edu)
- My Github:  
[github.com/tommycwong](https://github.com/tommycwong)

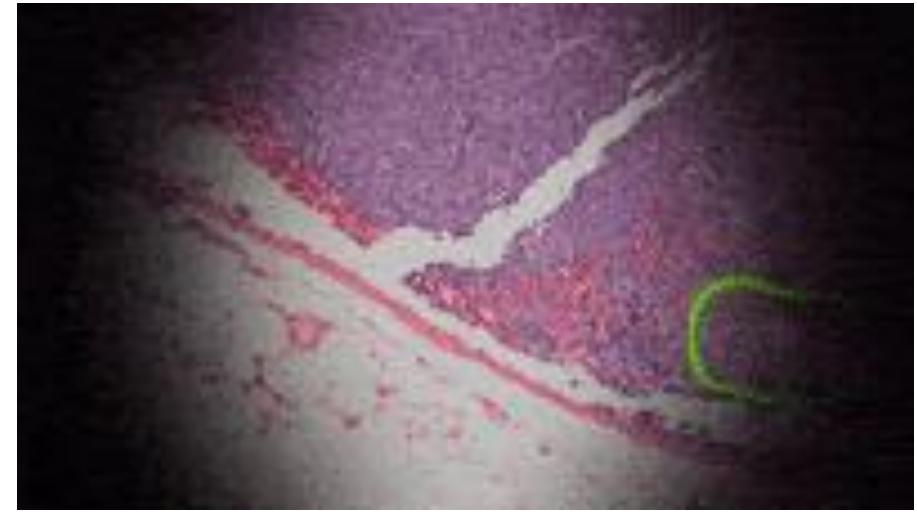


**Segmentation is the process of separating objects or regions of interest from the background and identifying the boundaries between them** -*ChatGPT*

- Associating each pixel in an image with a class
- Traditional ML methods: thresholding, edge detection, decision trees, etc.
- DL methods using CNN:
  - Semantic segmentation
  - Instance segmentation



# Semantic segmentation assigns class labels to each pixel



## Augmented reality microscope [3]

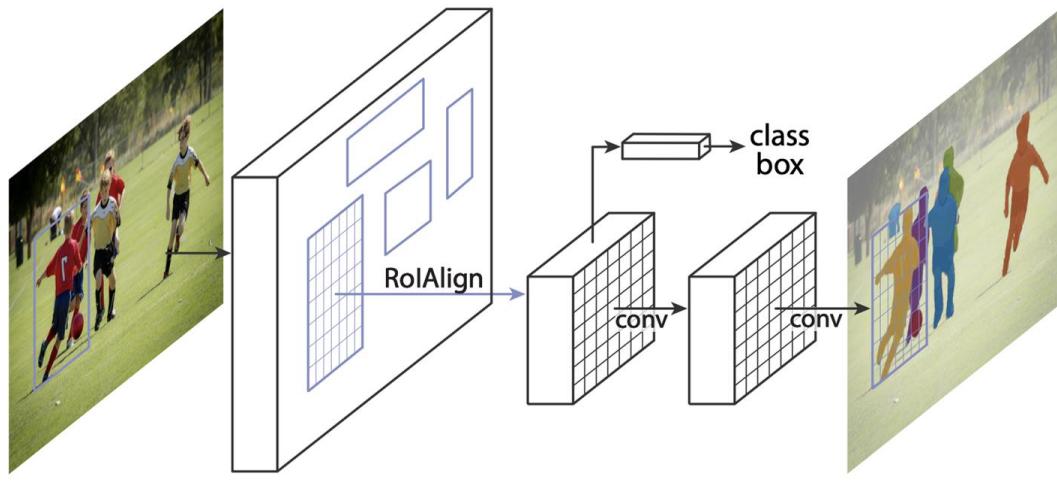
### Semantic segmentation of street views [1], [2]

[1] G. Heinrich, "Image Segmentation Using DIGITS 5," NVIDIA Developer Blog, Nov. 10, 2016. <https://developer.nvidia.com/blog/image-segmentation-using-digits-5/> (accessed Feb. 25, 2021).

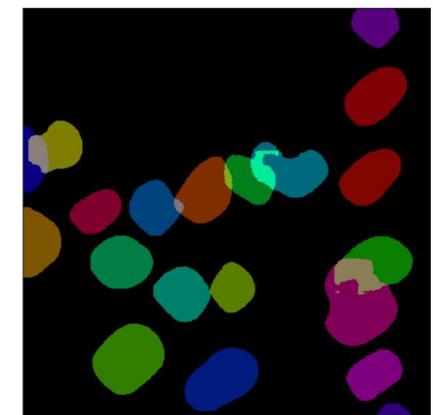
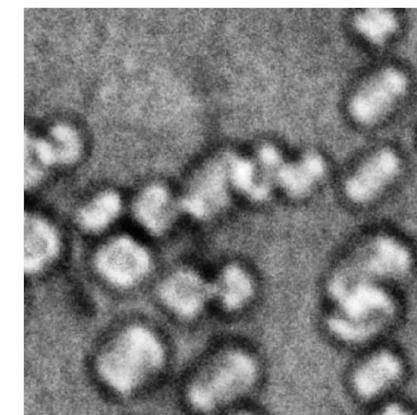
[2] M. Cordts et al., "The Cityscapes Dataset for Semantic Urban Scene Understanding," in 2016 IEEE Conference on Computer Vision and Pattern Recognition (CVPR), Las Vegas, NV, USA, Jun. 2016, pp. 3213–3223, doi: 10.1109/CVPR.2016.350.

[3] P.-H. C. Chen et al., "Microscope 2.0: An Augmented Reality Microscope with Real-time Artificial Intelligence Integration," arXiv:1812.00825 [cs], Dec. 2018, doi: 10.1038/s41591-019-0539-7.

# Instance segmentation w/ Mask R-CNN



Mask R-CNN

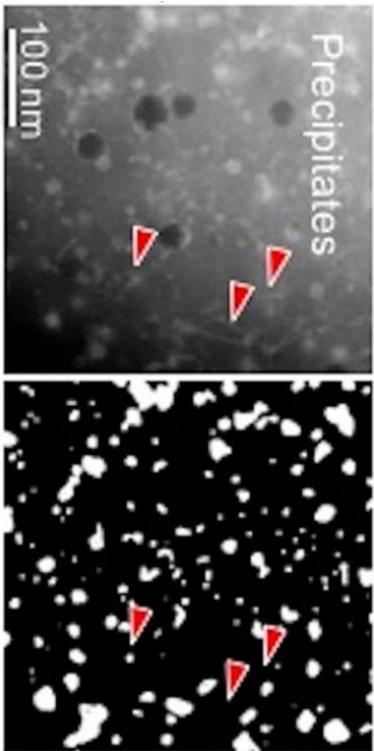


$$Loss = L_{class} + L_{box} + L_{mask}$$

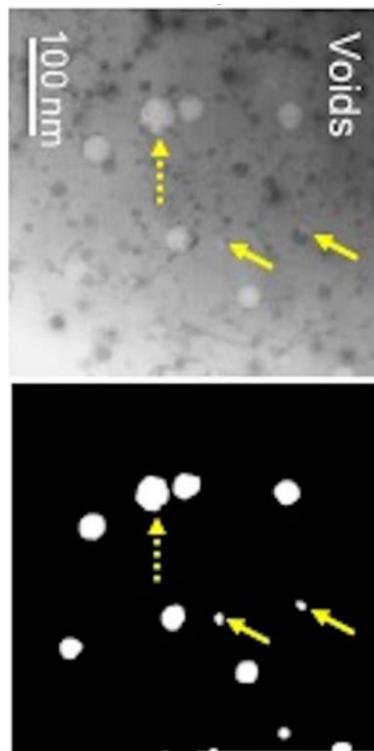
Adapted from Girschick (2015) <https://arxiv.org/abs/1504.08083>, He et al. (2018) <https://arxiv.org/abs/1703.06870v3>

# Microstructural defects can be labeled for pixel-wise segmentation

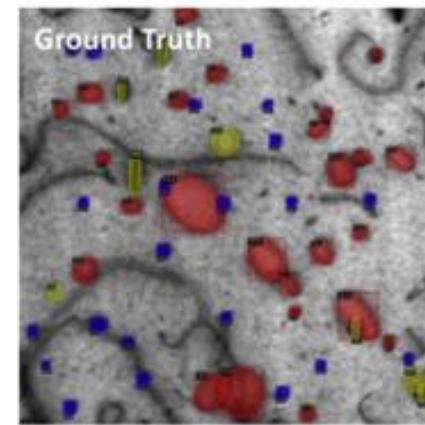
- Segmentation: associating each pixel in an image with a class



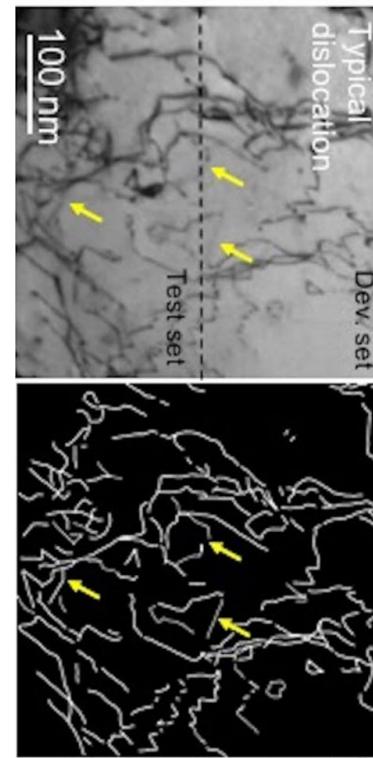
Cavities (bubbles & voids)



Precipitates



Dislocation loops

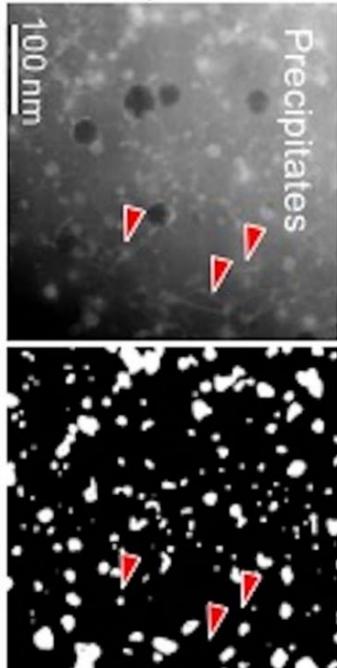


Dislocation lines

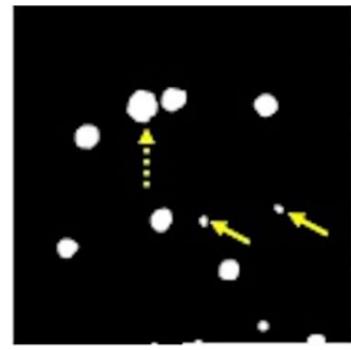
Adapted from Roberts et al. 2019 10.1038/s41598-019-49105-0, Jacobs et al. 2022 10.1016/j.xcrp.2022.100876

# Different labeling systems are required for different segmentation algorithms

- Important: labels are usually either 0 or 1



Precipitates

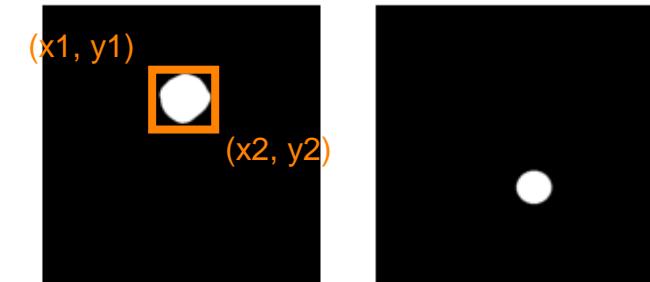
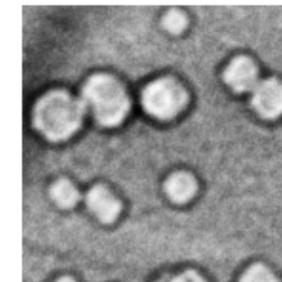
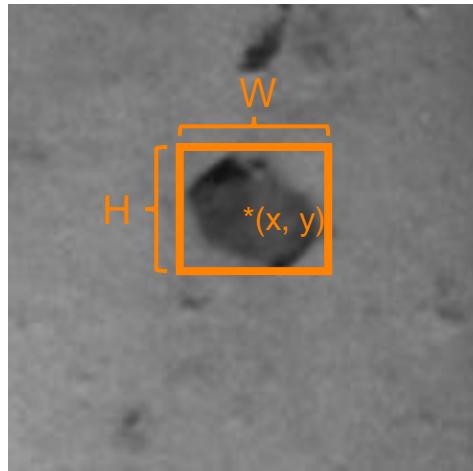


Voids

Semantic segmentation: one-hot encoding (U-Net)

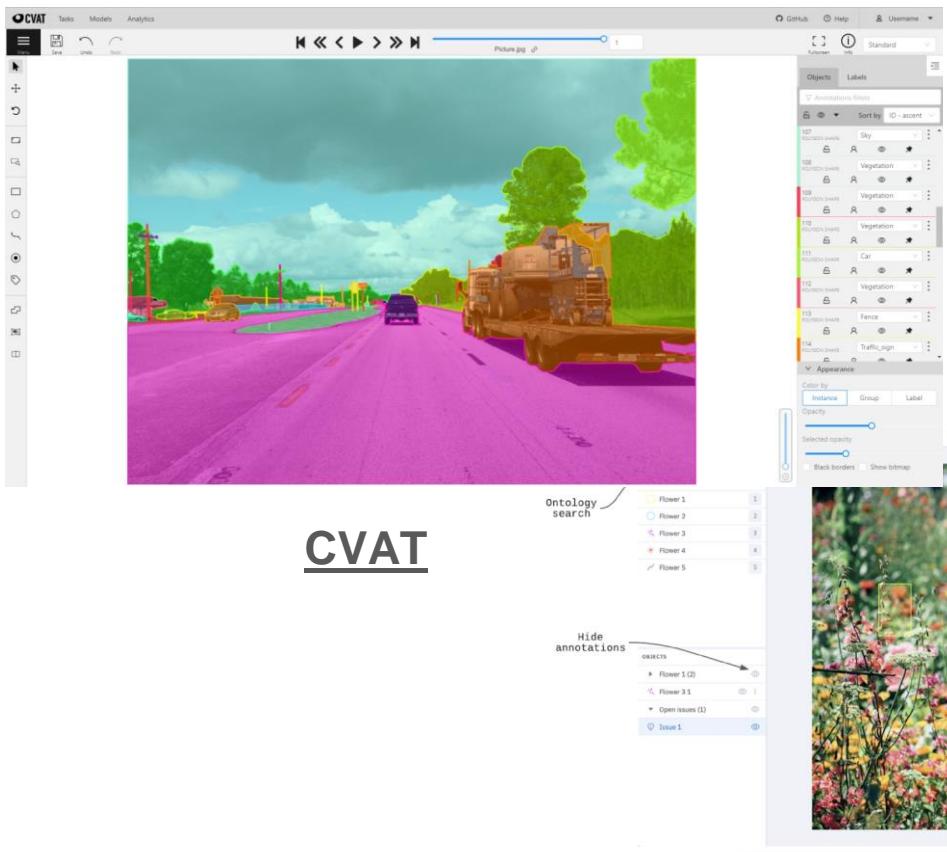
Object identification: bounding box (YOLO)

Instance segmentation: label encoding (Mask R-CNN)

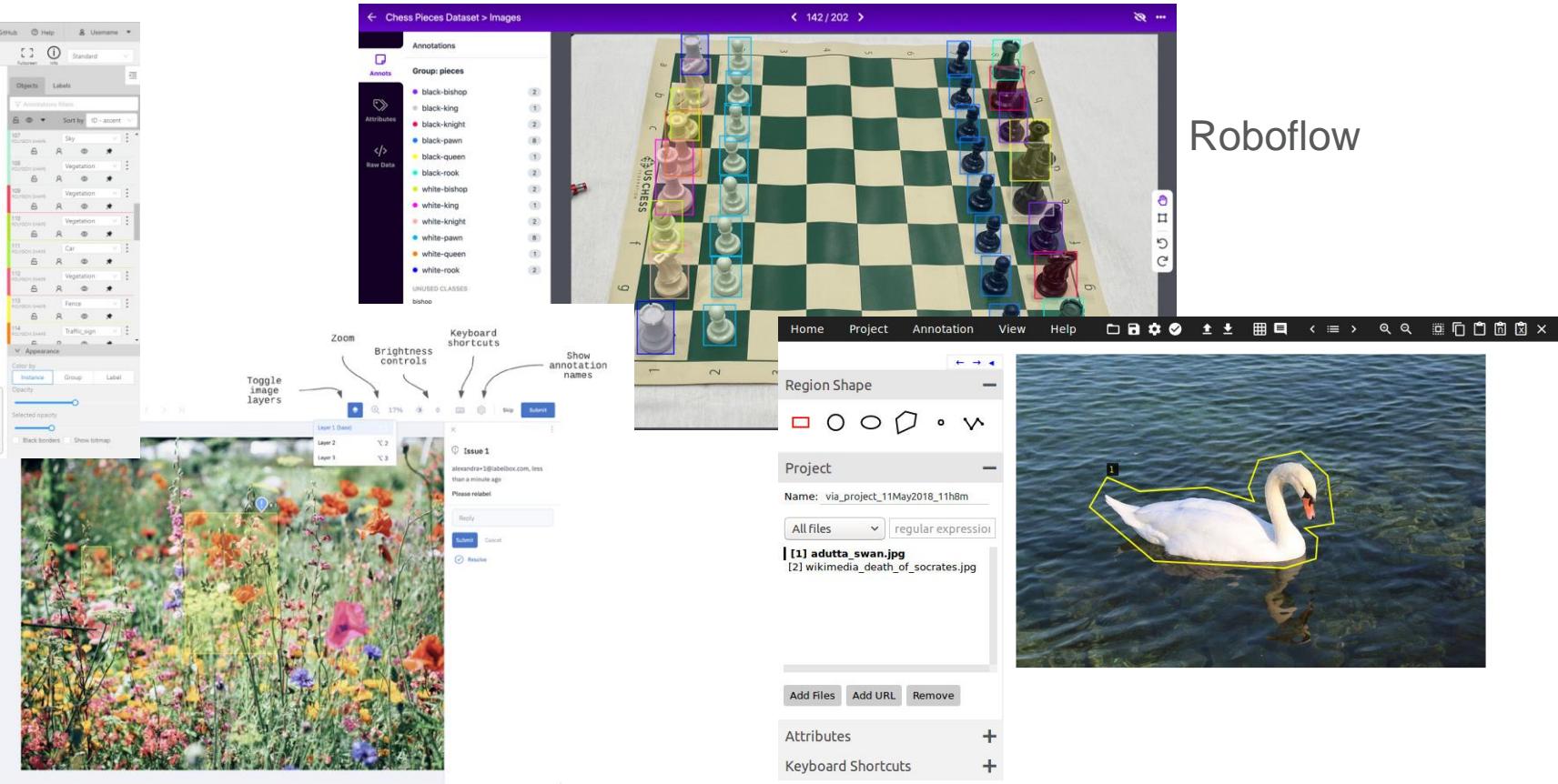


```
Dictionary{  
    'boxes': [x1 y1 x2 y2]  
    'labels': class  
    'masks': feature mask  
}
```

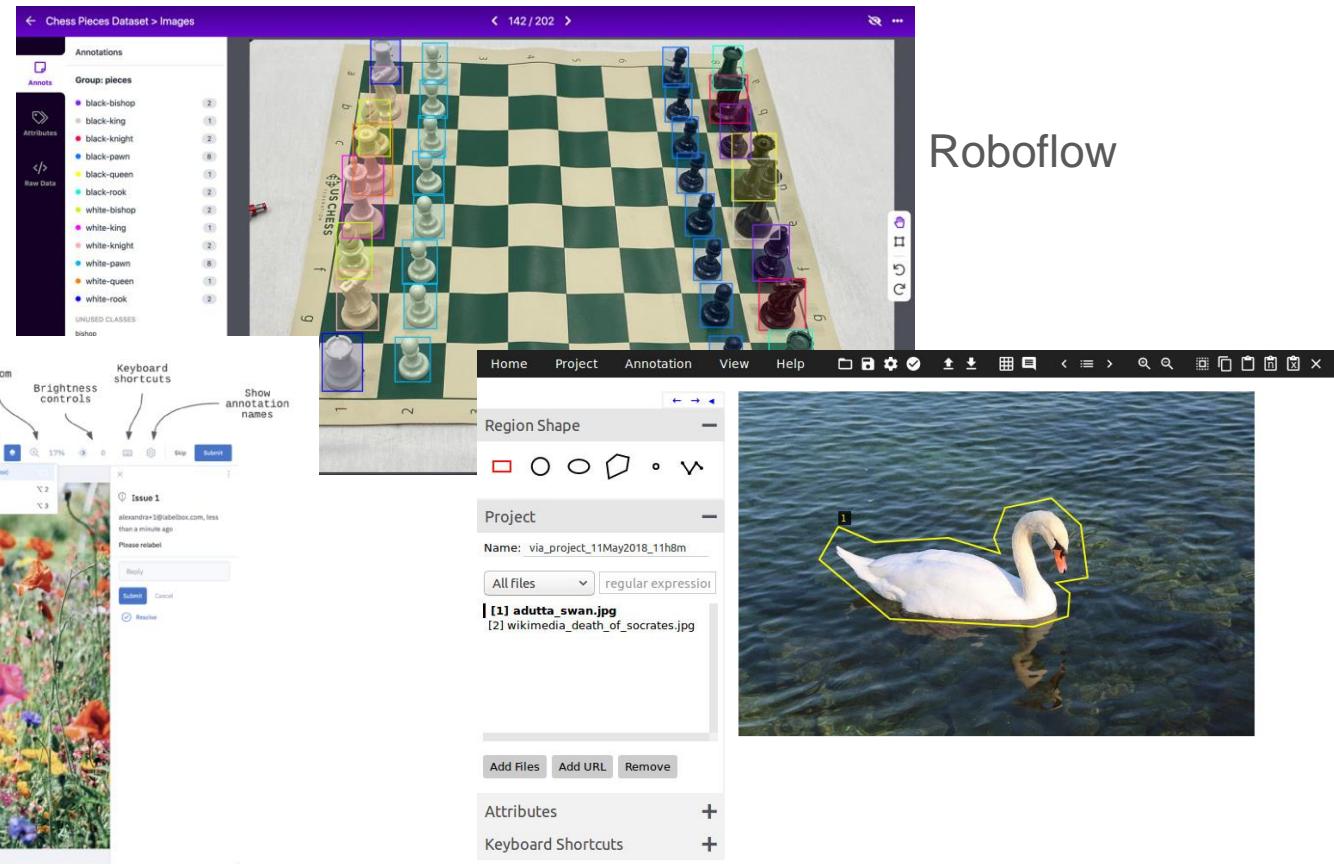
# Web-based GUI tools are used for labeling



**CVAT**



**Labelbox**



**Roboflow**

**VIA**

# Labeling using Computer Vision Annotation Tool (CVAT)

[cvat.ai](http://cvat.ai)

Documentation:

[github.com/TaSeeMba/cvat/blob/master/cvat/apps/documentation/user\\_guide.md](https://github.com/TaSeeMba/cvat/blob/master/cvat/apps/documentation/user_guide.md)

# CVAT labeling workflow

**Important:** before labeling, ensure all image data have the same dimensions e.g. 1024x1024



# Creating a project and labeling tasks

The image shows a three-step process for creating a project and labeling tasks in the CVAT interface:

- Step 1: Create a new project**

The first step shows the "Create a new project" dialog. The user has entered the project name "DL\_for\_Microscopy". Below the name input, there is a "Labels" section with two options: "Raw" and "Constructor". Under "Raw", "Bubble" is selected. There are also buttons for "Any", "Add an attribute", "Continue", and "Cancel". An orange arrow points from the "Submit & Open" button at the bottom right of this dialog to the "Submit & Open" button at the bottom right of the "Basic configuration" dialog in Step 2.
- Step 2: Create a new task**

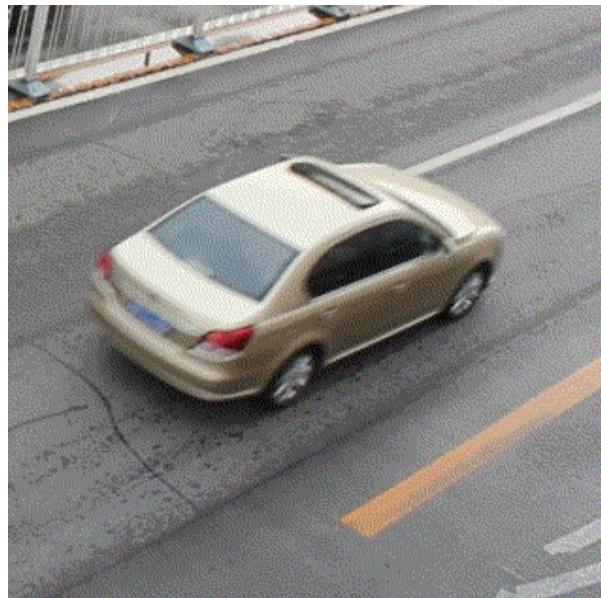
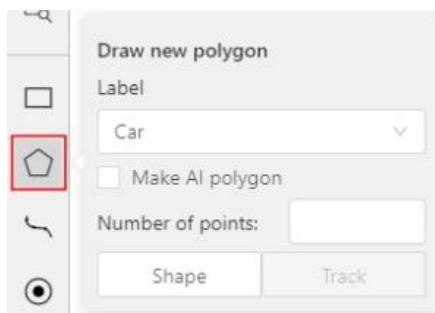
The second step shows the "Create a new task" dialog under "Basic configuration". The task name is "DL\_for\_Microscopy\_eg\_img". It includes fields for "Project" (set to "DL\_for\_Microscopy") and "Subset" (set to "Input subset"). The "Labels" section indicates that project labels will be used. A file upload area is shown with a message: "Click or drag files to this area. You can upload an archive with images, a video, or multiple images." A file named "DL\_for\_Microscopy\_Train\_eg\_img.png" is listed. An orange arrow points from the "Submit & Open" button at the bottom right of this dialog to the "Submit & Open" button at the bottom right of the project details page in Step 3.
- Step 3: Project Details**

The third step shows the project details page for "DL\_for\_Microscopy\_eg\_img". The page includes a thumbnail image of a microscopy image showing several cells. It displays information such as "Task #190008 Created by tommyc Wong on June 5th 2023", "Issue Tracker Not specified", and "Subset Input subset". Below this, a "Jobs" table is shown with one job entry: "Job #180806 0-0 annotation new June 5th 2023 02:06 a few seconds". An orange arrow points from the "Submit & Open" button at the bottom right of the "Basic configuration" dialog in Step 2 to the "Submit & Open" button at the bottom right of this project details page.

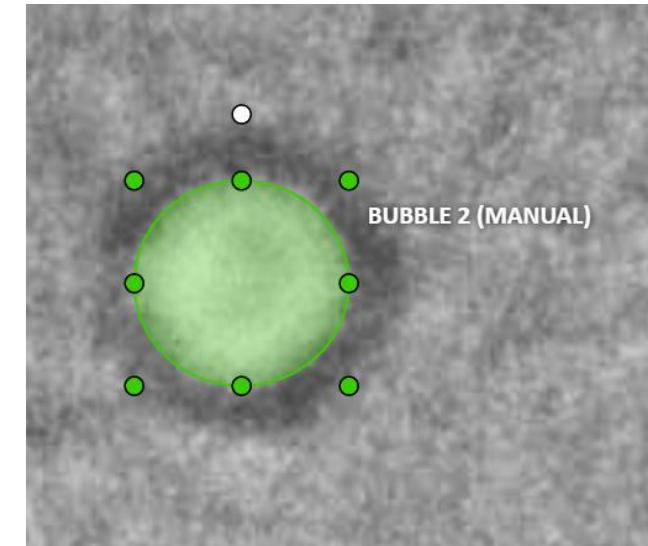
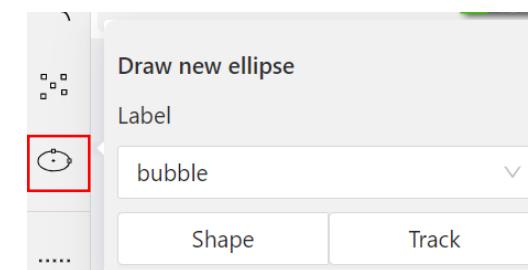
# Labeling using polygon and ellipse tools

Remember to click **Save**  
Polygon tool (preferred)

- Hold **Shift** to draw

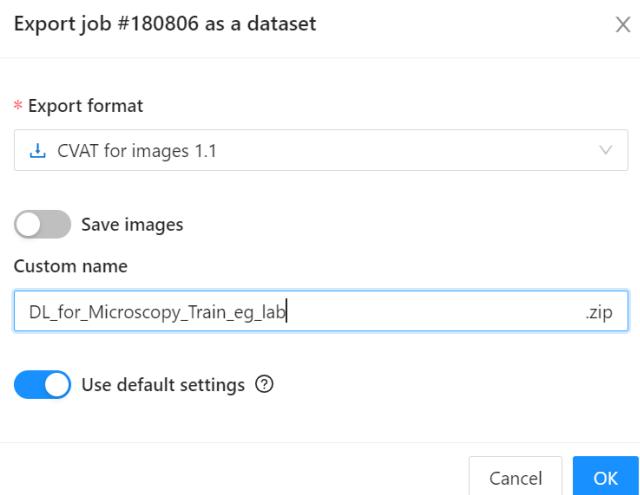


Ellipse tool



# Exporting and parsing labels

## Export as .xml



## Parsing labels using Python

```
get_imgs(train_img_names)
parse_anno_file(xml, train_img_filename)
get_unet_mask(annos)
get_maskrcnn_mask(annos)
get_maskrcnn_dataset(images=train_imgs,
labels=maskRcnn_masks)
```

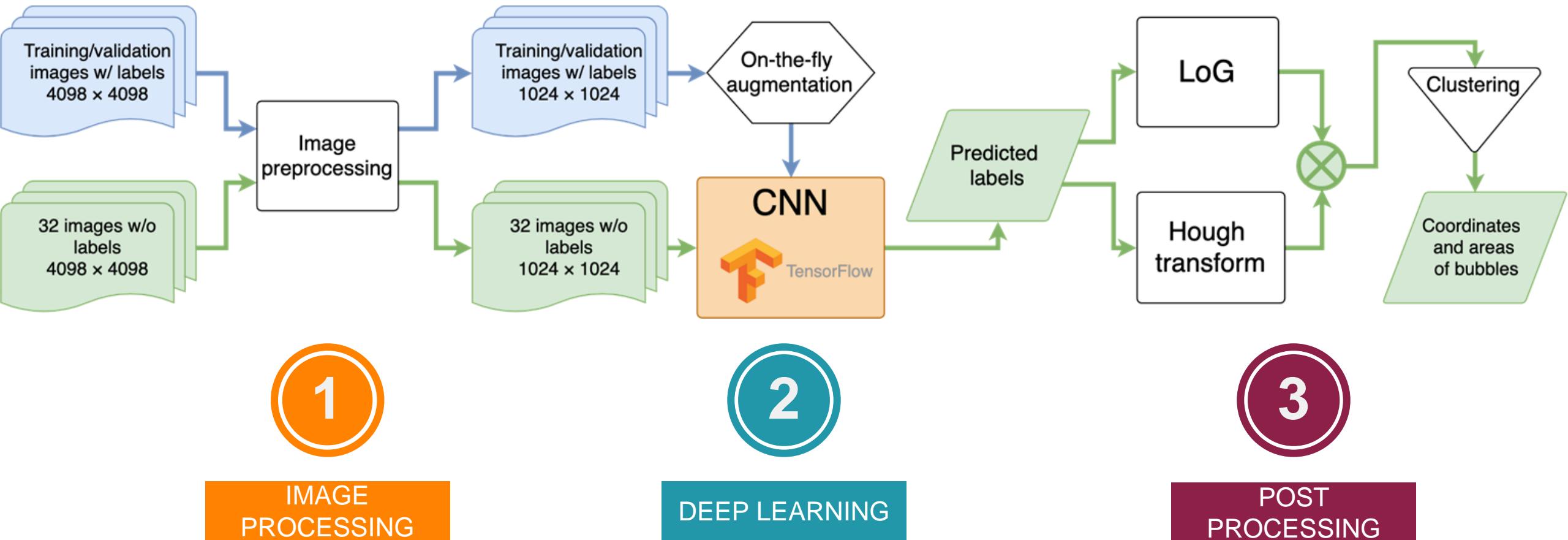
```
<image id="0" name="DL_for_Microscopy_Train_eg_img.png" width="512" height="512">
<ellipse label="Bubble" source="manual" occluded="0" cx="291.95" cy="334.99" rx="32.35" ry="30.94" z_order="0">
</ellipse>
<polygon label="Bubble" source="manual" occluded="0" points="282.22,131.08;289.47,135.54;295.61,142.23;300.07,1
</polygon>
```

# Additional notes on labeling

- Features typically should have a convex mask
  - Concave masks are likely occluded convex masks
- Don't leave holes between multiple overlapping masks
- Keep in mind output files: different parsing scripts needed for .xml, .json, etc.

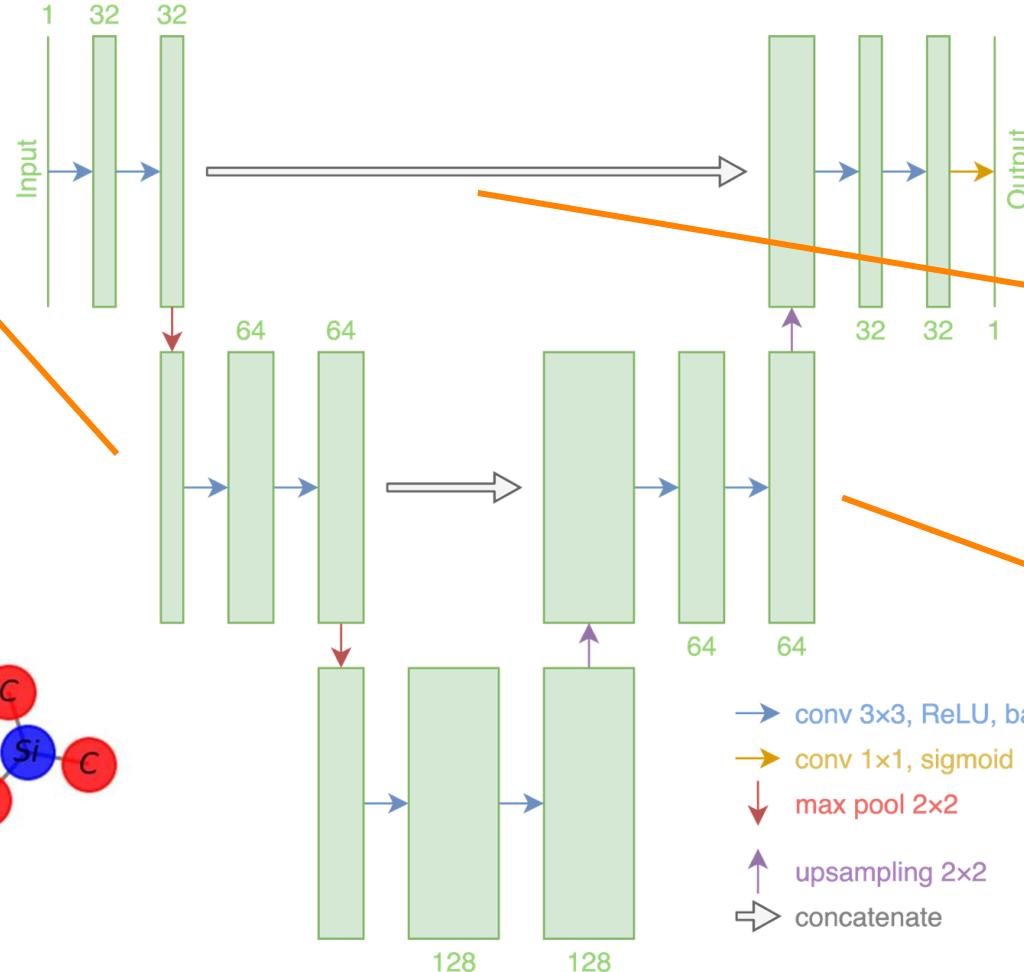
**Example of CNN image segmentation:  
Detecting He bubbles w/ U-net**

# Training & Classification Workflows



# Semantic segmentation w/ U-Net

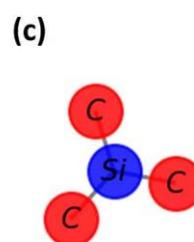
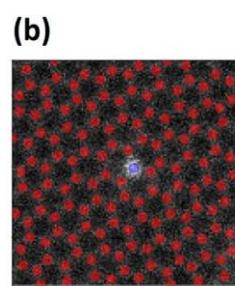
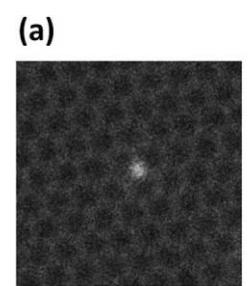
Look for salient features



Developed by Ronneberger et al. (2015) [11]

Preserve “big picture”

Expand back to original size

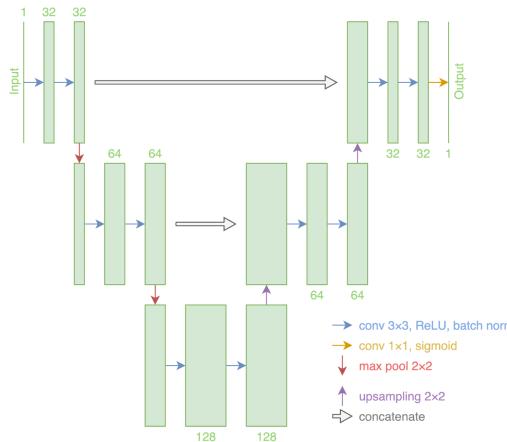
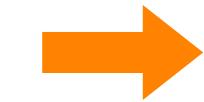


Ziatdinov et al. (2017) [12]

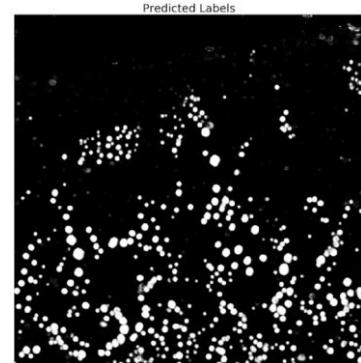
[12] M. Ziatdinov et al., “Deep Learning of Atomically Resolved Scanning Transmission Electron Microscopy Images: Chemical Identification and Tracking Local Transformations,” *ACS Nano*, vol. 11, no. 12, pp. 12742–12752, Dec. 2017, doi: 10.1021/acsnano.7b07504.

# Ensemble learning improves accuracy

random(weights)  $\times 12$



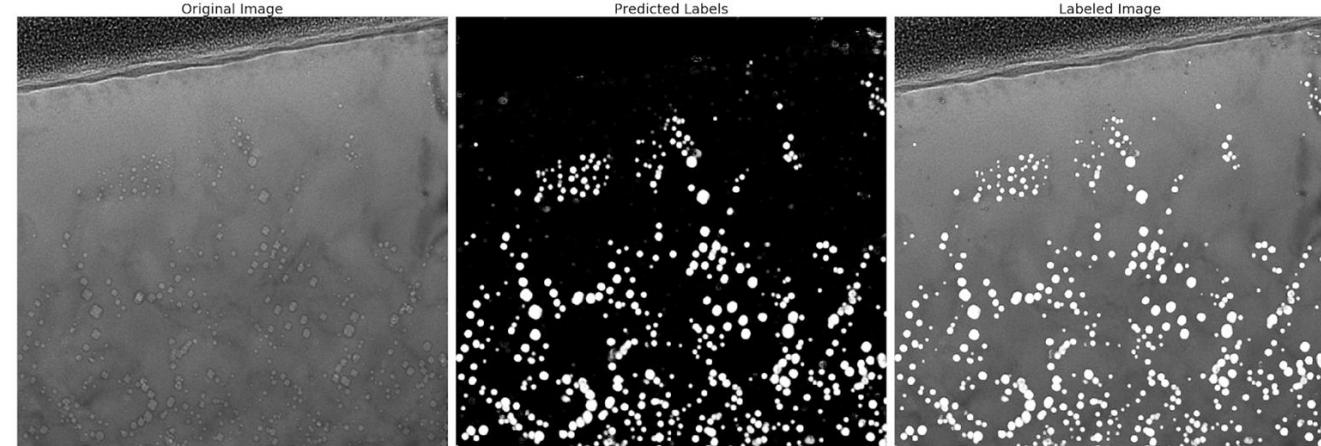
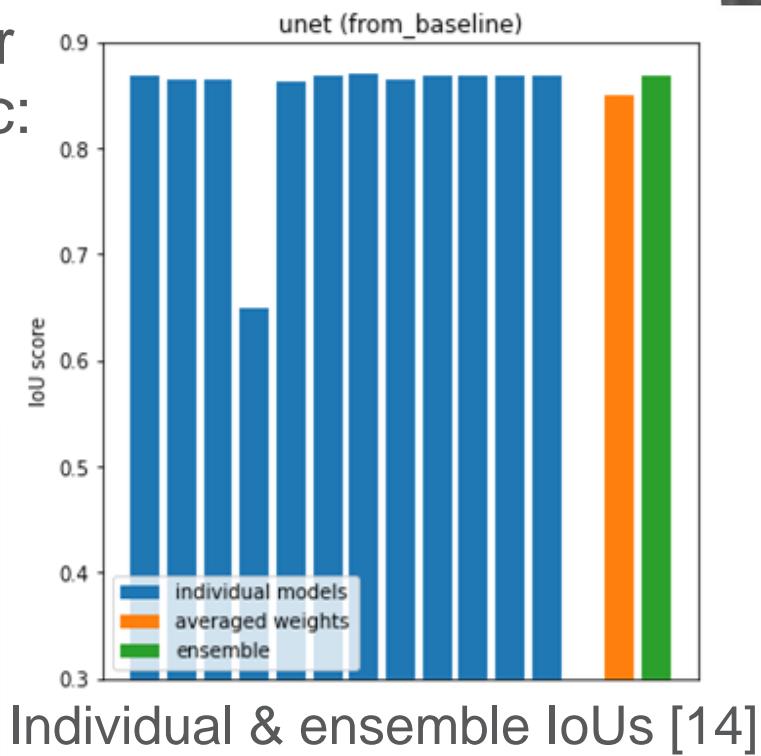
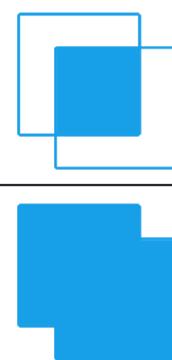
$\times 12$



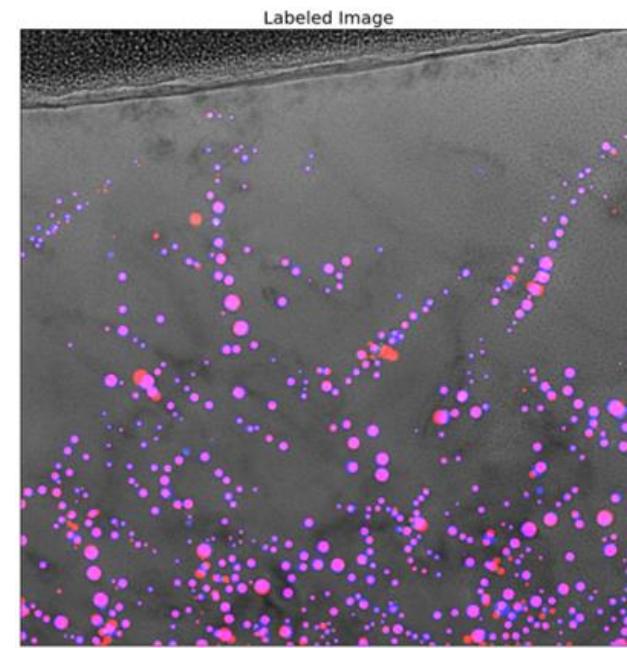
- Aim: to identify He bubbles in TEM images
- Based on **Pycroscopy AtomAI** ([github.com/pycroscopy/atomai](https://github.com/pycroscopy/atomai)) [13]
- Trained using open-source package via Google Colab 

# Results from CNN

- Overall px acc: 0.98
- Average per class px acc: 0.95
- IoU: 0.85
- F1: 0.91



Sample CNN labels [15]



CNN  
Both  
Manual

Comparing CNN to manual labels

# Workflow Can Be Generalized to Other Material Systems

- The algorithm was not altered at all— new training images
- Only resized images  $\Rightarrow$  bubbles are similar in size to those in training images

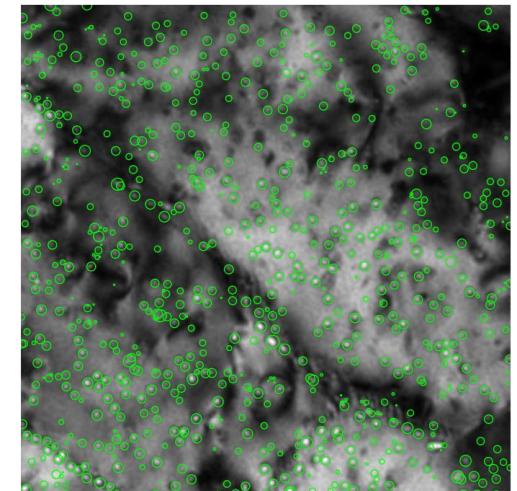
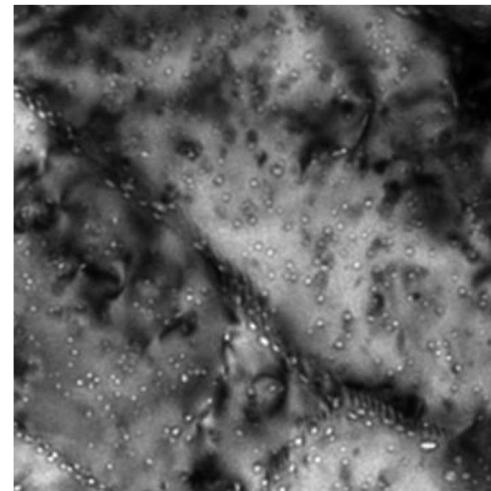
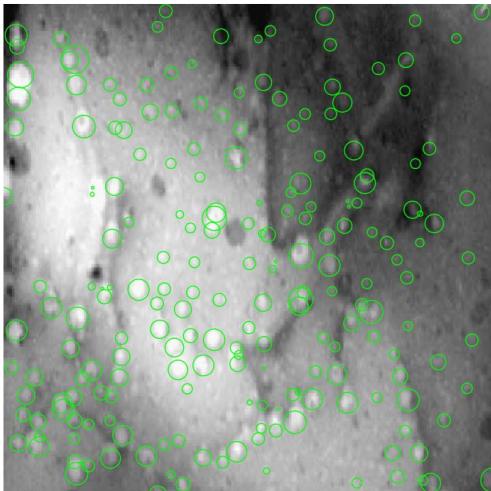
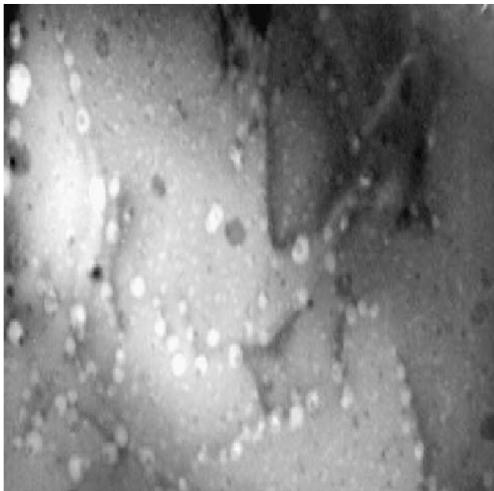


Fig. 19. Fission gas bubbles in UO<sub>2</sub> nuclear fuel  
*adapted from [10]*

Fig. 20. He bubbles in W plasma-facing material  
*adapted from [11]*

[10] C. Ronchi, "Thermophysical properties affecting safety and performance of nuclear fuel," *High Temp*, vol. 45, no. 4, pp. 552–571, Aug. 2007, doi: 10.1134/S0018151X07040177.

[11] F. Luo et al., "TEM observation of bubbles induced by single and sequential He/H irradiation in tungsten," *Fusion Engineering and Design*, vol. 125, pp. 463–467, Dec. 2017, doi: 10.1016/j.fusengdes.2017.04.014.

**Example of CNN image segmentation:  
Tracking He bubbles w/ Mask R-CNN**

# He bubbles in PdNi sample are tracked individually

