

# Deep Generative Models

## Lecture 7

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# Recap of previous lecture

## Gaussian autoregressive flow (MAF)

$$\mathbf{x} = g(\mathbf{z}, \theta) \Rightarrow x_i = \sigma_i(\mathbf{x}_{1:i-1}) \cdot z_i + \mu_i(\mathbf{x}_{1:i-1}).$$

$$\mathbf{z} = f(\mathbf{x}, \theta) \Rightarrow z_i = (x_i - \mu_i(\mathbf{x}_{1:i-1})) \cdot \frac{1}{\sigma_i(\mathbf{x}_{1:i-1})}.$$

Generation function  $g(\mathbf{z}, \theta)$  is **sequential**. Inference function  $f(\mathbf{x}, \theta)$  is **not sequential**.

## Inverse autoregressive flow (IAF)

$$\mathbf{x} = g(\mathbf{z}, \theta) \Rightarrow x_i = \tilde{\sigma}_i(\mathbf{z}_{1:i-1}) \cdot z_i + \tilde{\mu}_i(\mathbf{z}_{1:i-1})$$

$$\mathbf{z} = f(\mathbf{x}, \theta) \Rightarrow z_i = (x_i - \tilde{\mu}_i(\mathbf{z}_{1:i-1})) \cdot \frac{1}{\tilde{\sigma}_i(\mathbf{z}_{1:i-1})}.$$

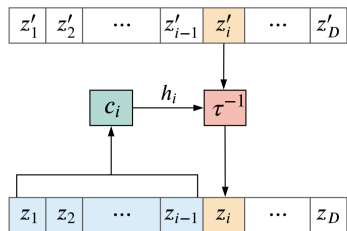
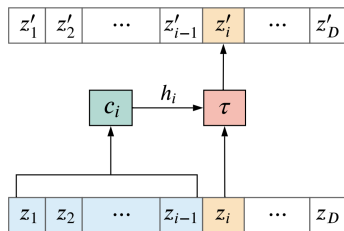
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Papamakarios G., Pavlakou T., Murray I. *Masked Autoregressive Flow for Density Estimation*, 2017

Kingma D. P. et al. *Improving Variational Inference with Inverse Autoregressive Flow*, 2016

# Recap of previous lecture

## Autoregressive flows



## RealNVP: Affine coupling law

$$\begin{cases} \mathbf{z}_{1:d} = \mathbf{x}_{1:d}; \\ \mathbf{z}_{d:m} = \tau(\mathbf{x}_{d:m}, c(\mathbf{x}_{1:d})); \end{cases} \quad \Leftrightarrow \quad \begin{cases} \mathbf{x}_{1:d} = \mathbf{z}_{1:d}; \\ \mathbf{x}_{d:m} = \tau^{-1}(\mathbf{z}_{d:m}, c(\mathbf{z}_{1:d})). \end{cases}$$

Dinh L., Krueger D., Bengio Y. *NICE: Non-linear Independent Components Estimation*, 2014

Dinh L., Sohl-Dickstein J., Bengio S. *Density estimation using Real NVP*, 2016

# Outline

# Likelihood-based models

## Exact likelihood evaluation

- ▶ Autoregressive models (PixelCNN, WaveNet);
- ▶ Flow models (NICE, RealNVP, Glow).

## Approximate likelihood evaluation

- ▶ Latent variable models (VAE).

What are the pros and cons of each of them?

# VAE limitations

- ▶ Poor generative distribution (decoder)

$$p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta}) = \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}_{\boldsymbol{\theta}}(\mathbf{z}), \boldsymbol{\sigma}_{\boldsymbol{\theta}}^2(\mathbf{z})).$$

- ▶ Loose lower bound

$$\log p(\mathbf{x}|\boldsymbol{\theta}) - \mathcal{L}(q, \boldsymbol{\theta}) = (?).$$

- ▶ **Poor prior distribution**

$$p(\mathbf{z}) = \mathcal{N}(0, \mathbf{I}).$$

- ▶ Poor variational posterior distribution (encoder)

$$q(\mathbf{z}|\mathbf{x}, \boldsymbol{\phi}) = \mathcal{N}(\mathbf{z}|\boldsymbol{\mu}_{\boldsymbol{\phi}}(\mathbf{x}), \boldsymbol{\sigma}_{\boldsymbol{\phi}}^2(\mathbf{x})).$$

# ELBO interpretations

$$\log p(\mathbf{x}|\boldsymbol{\theta}) = \mathcal{L}(\phi, \boldsymbol{\theta}) + KL(q(\mathbf{z}|\mathbf{x}, \phi)||p(\mathbf{z}|\mathbf{x}, \boldsymbol{\theta})) \geq \mathcal{L}(\phi, \boldsymbol{\theta}).$$

$$\mathcal{L}(\phi, \boldsymbol{\theta}) = \int q(\mathbf{z}|\mathbf{x}, \phi) \log \frac{p(\mathbf{x}, \mathbf{z}|\boldsymbol{\theta})}{q(\mathbf{z}|\mathbf{x}, \phi)} d\mathbf{z}.$$

- Evidence minus posterior KL

$$\mathcal{L}(\phi, \boldsymbol{\theta}) = \log p(\mathbf{x}|\boldsymbol{\theta}) - KL(q(\mathbf{z}|\mathbf{x}, \phi)||p(\mathbf{z}|\mathbf{x}, \boldsymbol{\theta})).$$

- Average reconstruction loss with regularizer (prior KL)

$$\begin{aligned}\mathcal{L}(\phi, \boldsymbol{\theta}) &= \mathbb{E}_{q(\mathbf{z}|\mathbf{x}, \phi)} [\log p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta}) + \log p(\mathbf{z}) - \log q(\mathbf{z}|\mathbf{x}, \phi)] \\ &= \mathbb{E}_{q(\mathbf{z}|\mathbf{x}, \phi)} \log p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta}) - KL(q(\mathbf{z}|\mathbf{x}, \phi)||p(\mathbf{z})).\end{aligned}$$

# ELBO surgery

$$\frac{1}{n} \sum_{i=1}^n \mathcal{L}_i(q, \theta) = \frac{1}{n} \sum_{i=1}^n [\mathbb{E}_{q(\mathbf{z}|\mathbf{x}_i)} \log p(\mathbf{x}_i|\mathbf{z}, \theta) - KL(q(\mathbf{z}|\mathbf{x}_i)||p(\mathbf{z}))].$$

## Theorem

$$\frac{1}{n} \sum_{i=1}^n KL(q(\mathbf{z}|\mathbf{x}_i)||p(\mathbf{z})) = KL(q(\mathbf{z})||p(\mathbf{z})) + \mathbb{I}_q[\mathbf{x}, \mathbf{z}],$$

- ▶  $q(\mathbf{z}) = \frac{1}{n} \sum_{i=1}^n q(\mathbf{z}|\mathbf{x}_i)$  – **aggregated** posterior distribution.
- ▶  $\mathbb{I}_q[\mathbf{x}, \mathbf{z}]$  – mutual information between  $\mathbf{x}$  and  $\mathbf{z}$  under empirical data distribution and distribution  $q(\mathbf{z}|\mathbf{x})$ .
- ▶ First term pushes  $q(\mathbf{z})$  towards the prior  $p(\mathbf{z})$ .
- ▶ Second term reduces the amount of information about  $\mathbf{x}$  stored in  $\mathbf{z}$ .



# ELBO surgery

## Theorem

$$\frac{1}{n} \sum_{i=1}^n KL(q(\mathbf{z}|\mathbf{x}_i)||p(\mathbf{z})) = KL(q(\mathbf{z})||p(\mathbf{z})) + \mathbb{I}_q[\mathbf{x}, \mathbf{z}].$$

## Proof

$$\begin{aligned} \frac{1}{n} \sum_{i=1}^n KL(q(\mathbf{z}|\mathbf{x}_i)||p(\mathbf{z})) &= \frac{1}{n} \sum_{i=1}^n \int q(\mathbf{z}|\mathbf{x}_i) \log \frac{q(\mathbf{z}|\mathbf{x}_i)}{p(\mathbf{z})} d\mathbf{z} = \\ &= \frac{1}{n} \sum_{i=1}^n \int q(\mathbf{z}|\mathbf{x}_i) \log \frac{q(\mathbf{z})q(\mathbf{z}|\mathbf{x}_i)}{p(\mathbf{z})q(\mathbf{z})} d\mathbf{z} = \int \frac{1}{n} \sum_{i=1}^n q(\mathbf{z}|\mathbf{x}_i) \log \frac{q(\mathbf{z})}{p(\mathbf{z})} d\mathbf{z} + \\ &+ \frac{1}{n} \sum_{i=1}^n \int q(\mathbf{z}|\mathbf{x}_i) \log \frac{q(\mathbf{z}|\mathbf{x}_i)}{q(\mathbf{z})} d\mathbf{z} = KL(q(\mathbf{z})||p(\mathbf{z})) + \frac{1}{n} \sum_{i=1}^n KL(q(\mathbf{z}|\mathbf{x}_i)||q(\mathbf{z})) \end{aligned}$$

Without proof:

$$\mathbb{I}_q[\mathbf{x}, \mathbf{z}] = \frac{1}{n} \sum_{i=1}^n KL(q(\mathbf{z}|\mathbf{x}_i)||q(\mathbf{z})) \in [0, \log n].$$

# ELBO surgery

## ELBO revisiting

$$\begin{aligned}\frac{1}{n} \sum_{i=1}^n \mathcal{L}_i(q, \theta) &= \frac{1}{n} \sum_{i=1}^n [\mathbb{E}_{q(\mathbf{z}|\mathbf{x}_i)} \log p(\mathbf{x}_i|\mathbf{z}, \theta) - KL(q(\mathbf{z}|\mathbf{x}_i)||p(\mathbf{z}))] = \\ &= \underbrace{\frac{1}{n} \sum_{i=1}^n \mathbb{E}_{q(\mathbf{z}|\mathbf{x}_i)} \log p(\mathbf{x}_i|\mathbf{z}, \theta)}_{\text{Reconstruction loss}} - \underbrace{\mathbb{I}_q[\mathbf{x}, \mathbf{z}]}_{\text{MI}} - \underbrace{KL(q(\mathbf{z})||p(\mathbf{z}))}_{\text{Marginal KL}}\end{aligned}$$

Prior distribution  $p(\mathbf{z})$  is only in the last term.

## Optimal VAE prior

$$KL(q(\mathbf{z})||p(\mathbf{z})) = 0 \quad \Leftrightarrow \quad p(\mathbf{z}) = q(\mathbf{z}) = \frac{1}{n} \sum_{i=1}^n q(\mathbf{z}|\mathbf{x}_i).$$

The optimal prior  $p(\mathbf{z})$  is the aggregated posterior  $q(\mathbf{z})$ .

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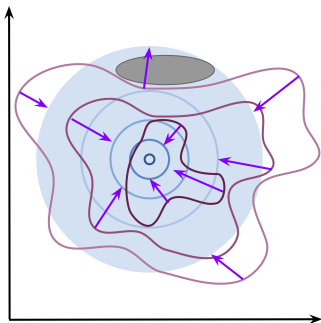
Hoffman M. D., Johnson M. J. *ELBO surgery: yet another way to carve up the variational evidence lower bound*, 2016

# Optimal VAE prior

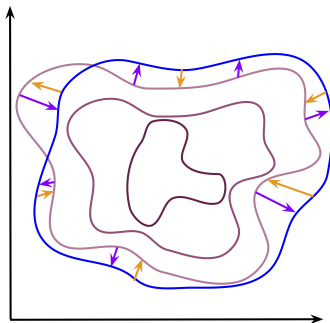
How to choose the optimal  $p(\mathbf{z})$ ?

- ▶ Standard Gaussian  $p(\mathbf{z}) = \mathcal{N}(0, I) \Rightarrow$  over-regularization;
- ▶  $p(\mathbf{z}) = q(\mathbf{z}) = \frac{1}{n} \sum_{i=1}^n q(\mathbf{z}|\mathbf{x}_i) \Rightarrow$  overfitting and highly expensive.

Non learnable prior  $p(\mathbf{z})$



Learnable prior  $p(\mathbf{z}|\lambda)$



# Learnable VAE prior

## Optimal prior

$$KL(q(\mathbf{z})||p(\mathbf{z})) = 0 \quad \Leftrightarrow \quad p(\mathbf{z}) = q(\mathbf{z}) = \frac{1}{n} \sum_{i=1}^n q(\mathbf{z}|\mathbf{x}_i).$$

## Mixture of Gaussians

$$p(\mathbf{z}|\boldsymbol{\lambda}) = \sum_{k=1}^K w_k \mathcal{N}(\mathbf{z}|\boldsymbol{\mu}_k, \boldsymbol{\sigma}_k^2), \quad \boldsymbol{\lambda} = \{w_k, \boldsymbol{\mu}_k, \boldsymbol{\sigma}_k\}_{k=1}^K.$$

## Variational Mixture of posteriors (VampPrior)

$$p(\mathbf{z}|\boldsymbol{\lambda}) = \frac{1}{K} \sum_{k=1}^K q(\mathbf{z}|\mathbf{u}_k),$$

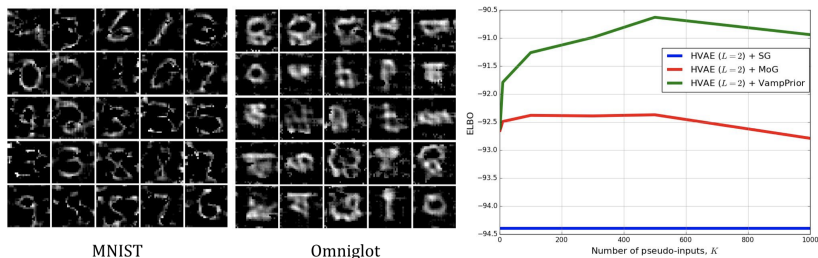
where  $\boldsymbol{\lambda} = \{\mathbf{u}_1, \dots, \mathbf{u}_K\}$  are trainable pseudo-inputs.

- ▶ Multimodal  $\Rightarrow$  prevents over-regularization;
- ▶  $K \ll n \Rightarrow$  prevents from potential overfitting + less expensive to train.

# VampPrior

- ▶ Do we really need the multimodal prior?
- ▶ Is it beneficial to couple the prior with the variational posterior or the MoG prior is enough?

## Results



**Top row:** generated images by PixelHVAE + VampPrior for chosen pseudo-input in the left top corner.

**Bottom row:** pseudo-inputs for different datasets.

# Flows-based VAE prior

## Flow model in latent space

$$\log p(\mathbf{z}|\boldsymbol{\lambda}) = \log p(\boldsymbol{\epsilon}) + \log \det \left| \frac{d\boldsymbol{\epsilon}}{d\mathbf{z}} \right| = \log p(\boldsymbol{\epsilon}) + \log \det \left| \frac{\partial f(\mathbf{z}, \boldsymbol{\lambda})}{\partial \mathbf{z}} \right|$$

$$\mathbf{z} = g(\boldsymbol{\epsilon}, \boldsymbol{\lambda}) = f^{-1}(\boldsymbol{\epsilon}, \boldsymbol{\lambda})$$

- ▶ RealNVP flow.
- ▶ Autoregressive flow (MAF).

Why it is not a good idea to use IAF for VAE prior?

## ELBO with flow-based VAE prior

$$\begin{aligned} \mathcal{L}(\phi, \theta) &= \mathbb{E}_{q(\mathbf{z}|\mathbf{x}, \phi)} [\log p(\mathbf{x}|\mathbf{z}, \theta) + \log p(\mathbf{z}|\boldsymbol{\lambda}) - \log q(\mathbf{z}|\mathbf{x}, \phi)] \\ &= \mathbb{E}_{q(\mathbf{z}|\mathbf{x}, \phi)} \left[ \log p(\mathbf{x}|\mathbf{z}, \theta) + \underbrace{\left( \log p(f(\mathbf{z}, \boldsymbol{\lambda})) + \log \left| \det \frac{\partial f(\mathbf{z}, \boldsymbol{\lambda})}{\partial \mathbf{z}} \right| \right)}_{\text{flow-based prior}} - \log q(\mathbf{z}|\mathbf{x}, \phi) \right] \end{aligned}$$

# VAE limitations

- ▶ Poor generative distribution (decoder)

$$p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta}) = \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}_{\boldsymbol{\theta}}(\mathbf{z}), \boldsymbol{\sigma}_{\boldsymbol{\theta}}^2(\mathbf{z})).$$

- ▶ Loose lower bound

$$\log p(\mathbf{x}|\boldsymbol{\theta}) - \mathcal{L}(q, \boldsymbol{\theta}) = (?).$$

- ▶ Poor prior distribution

$$p(\mathbf{z}) = \mathcal{N}(0, \mathbf{I}).$$

- ▶ **Poor variational posterior distribution (encoder)**

$$q(\mathbf{z}|\mathbf{x}, \boldsymbol{\phi}) = \mathcal{N}(\mathbf{z}|\boldsymbol{\mu}_{\boldsymbol{\phi}}(\mathbf{x}), \boldsymbol{\sigma}_{\boldsymbol{\phi}}^2(\mathbf{x})).$$

# Variational posterior

## ELBO

$$\log p(\mathbf{x}|\boldsymbol{\theta}) = \mathcal{L}(q, \boldsymbol{\theta}) + KL(q(\mathbf{z}|\mathbf{x}, \phi)||p(\mathbf{z}|\mathbf{x}, \boldsymbol{\theta})).$$

- ▶ In E-step of EM-algorithm we wish  $KL(q(\mathbf{z}|\mathbf{x}, \phi)||p(\mathbf{z}|\mathbf{x}, \boldsymbol{\theta})) = 0$ .  
(In this case the lower bound is tight  $\log p(\mathbf{x}|\boldsymbol{\theta}) = \mathcal{L}(q, \boldsymbol{\theta})$ ).
- ▶ Normal variational distribution  $q(\mathbf{z}|\mathbf{x}, \phi) = \mathcal{N}(\mathbf{z}|\boldsymbol{\mu}_\phi(\mathbf{x}), \boldsymbol{\sigma}_\phi^2(\mathbf{x}))$  is poor (e.g. has only one mode).
- ▶ Flows models convert a simple base distribution to a complex one using invertible transformation with simple Jacobian. How to use flows in VAE posterior?



# Summary

- ▶ The ELBO surgery reveals insights about a prior distribution in VAE. The optimal prior is the aggregated posterior.
- ▶ VampPrior proposes to use a variational mixture of posteriors as the prior to approximate the aggregated posterior.
- ▶ We could use flow-based prior in VAE (moreover, autoregressive) as well as flow-based posterior (next lecture).