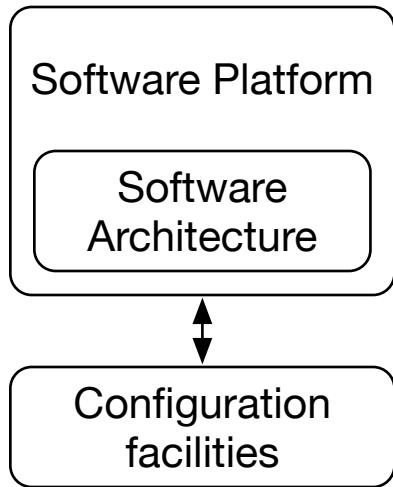


Single robot



Multi robot

