Magnetized Polish doughnuts

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ABSTRACT

Aims. bla
Methods. bla
Results. bla

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1. Introduction

Qian et al. (2009) presented a method to build sequences of black hole accretion disks in dynamical equilibria based on assuming distributions of angular momentum in the disks. Building on this work, we present here the extension of those models to disks endowed with a purely toroidal magnetic field. For the particular case of constant angular momentum distributions our method shows good agreement with the results of Komissarov (2006).

In this paper, we consider that the space-time is described by the Kerr metric (test-fluid approximation). We use the geometrized units where $G = c = 1$ and the $(- + ++)$ signature for the metric.

2. Framework

2.1. Distribution of angular momentum

First, we introduce the specific angular momentum l and the angular velocity Ω by the standard definitions,

$$l = -\frac{u_\phi}{u_t}, \quad \Omega = \frac{u^\phi}{u^t}, \tag{1}$$

where u^μ is the fluid four-velocity and $g_{\mu\nu}$ is the metric tensor[1].

The relationship between l and Ω is given by the equations

$$l = -\frac{\Omega g_{\phi\phi} + g_{t\phi}}{\Omega g_{t\phi} + g_{tt}}, \quad \Omega = -\frac{l g_{tt} + g_{t\phi}}{l g_{t\phi} + g_{\phi\phi}}, \tag{2}$$

where we are assuming circular motion, i.e. the four-velocity can be written as

$$u^\mu = (u^t, 0, 0, u^\phi), \tag{3}$$

we also introduce the Keplerian angular momentum (for prograde motion) in the equatorial plane l_K.

$$l_K(r) = \frac{M^{1/2}(r^2 - 2aM^{1/2}r^{1/2} + a^2)}{r^{3/2} - 2Mr^{1/2} + aM^{1/2}}, \tag{4}$$

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[1] In Kerr-Schild coordinates. Although the use of the Boyer-Lindquist coordinates yields exactly the same mathematical derivation and results.

In Jaroszynski et al. (1980) is argued that the slope of the specific angular momentum should be between two cases: $l = $ const. and $\Omega = $ const..

We assume the angular momentum distribution proposed by Qian et al. (2009)

$$l(r,\theta) = \left\{ \begin{array}{ll} l_0 \left(\frac{l_K(r)}{l_0}\right)^\beta \sin^{2\gamma}\theta & \text{for } r \geq r_{ms} \\ l_{ms}(r) \sin^{2\gamma}\theta & \text{for } r < r_{ms} \end{array} \right\}. \tag{5}$$

where r_{ms} is the radius of the marginally stable circular orbit(INTRODUCIR RMS, RMB Y CUSP ANTES. Introduccion?), the constants l_0 and $l_{ms}(r)$ are defined by $l_0 \equiv \eta l_K(r_{ms})$ and $l_{ms}(r) \equiv l_0 [l_K(r_{ms})/l_0]^\beta$. It can be seen that the model for the distribution of angular momentum has three parameters (β, γ, η)

$$0 \leq \beta \leq 1, \quad -1 \leq \gamma \leq 1, \quad 1 \leq \eta \leq \eta_{max}, \tag{6}$$

with $\eta_{max} = l_K(r_{mb})/l_K(r_{ms})$. In this paper we chose $\eta = \eta_{max}$, then we can write l_0 as $l_0 = l_K(r_{mb})$. We take this choice because (l comprendido entre lms y lmb para los valores de beta. Discos que comienzan en el cusp no tienen borde exterior para l = lmb.)

2.2. Magnetized disks

The equations of ideal GRMHD are

$$\nabla_\mu T^{\mu\nu} = 0, \tag{7}$$

$$\nabla_\mu * F^{\mu\nu} = 0, \tag{8}$$

$$\nabla_\mu (\rho u^\mu) = 0, \tag{9}$$

where

$$T^{\mu\nu} = (w + b^2)u^\mu u^\nu + \left(p + \frac{1}{2}b^2\right)g^{\mu\nu} - b^\mu b^\nu, \tag{10}$$

is the energy-momentum tensor taking into account only the fluid and the Maxwell parts, w and p are the fluid enthalpy and pressure, respectively. And

$$*F^{\mu\nu} = b^\mu u^\nu - b^\nu u^\mu, \tag{11}$$

is the Faraday tensor relative to an observer with four-velocity u^μ and b^μ is the magnetic field in that frame. Assuming the magnetic field is purely azimuthal

$$b^r = b^\theta = 0, \tag{12}$$

and taking into account that the flow is stationary and axisymmetric, we can see that (9) is always satisfied. The same happens with (8). Contracting the equation (10) with the projection tensor $h^\alpha_\beta = \delta^\alpha_\beta + u^\alpha u_\beta$, we arrive at

$$(w + b^2)u_\nu\partial_i u^\nu + \partial_i\left(p + \frac{b^2}{2}\right) - b_\nu\partial_i b^\nu, \tag{13}$$

where the comma denotes partial derivatives and $i = r, \theta$. We can rewrite this equation in terms of the specific angular momentum l and the angular velocity Ω, to obtain

$$\partial_i(\ln u_t|) - \frac{\Omega\partial_i l}{1 - l\Omega} + \frac{\partial_i p}{w} + \frac{\partial_i(\mathcal{L}b^2)}{2\mathcal{L}w} = 0, \tag{14}$$

where

$$\mathcal{L} = g_{t\phi}^2 - g_{tt}g_{\phi\phi}. \tag{15}$$

To integrate the equation (14) first we assume a barotropic equation of state $w = w(p)$ of the form

$$p = Kw^\kappa, \tag{16}$$

with K and κ constants.

Then, we define the magnetic pressure as $p_m = b^2/2$. Also, we can define $\tilde{p}_m = \mathcal{L}p_m$ and $\tilde{w} = \mathcal{L}w$, so we can write an analogue of (16) for $\tilde{p}_m$

$$\tilde{p}_m = K_m\tilde{w}_m^\eta, \tag{17}$$

or, in terms of the magnetic pressure p_m

$$p_m = K_m\mathcal{L}^{\eta-1}w^\eta, \tag{18}$$

where K_m and η are constants.

This particular choice of relationships $w = w(p)$ and $\tilde{w} = \tilde{w}(\tilde{p}_m)$, fulfill the general relativistic version for a toroidal magnetic field of the von Zeipel theorem (von Zeipel 1924; **?**), that means the surfaces of Ω and l constant coincide.

We can rewrite equation (14) and integrate it to give

$$\ln|u_t| - \int_0^l \frac{\Omega dl}{1 - \Omega l} + \int_0^p \frac{dp}{w} + \int \frac{d\tilde{p}_m}{\tilde{w}} = \text{constant}. \tag{19}$$

On the surface of the disk, and particularly on its inner edge,

$$p = \tilde{p}_m = 0, \quad u_t = u_{t,in}, \quad l = l_{in} \tag{20}$$

then, the constant of integration is given by

$$\text{constant.} = \ln|u_t| - \int_{in}^l \frac{\Omega dl}{1 - \Omega l}. \tag{21}$$

Defining the total potential W Abramowicz et al. (1978), we can write

$$W - W_{in} = \ln|u_t| - \ln|u_{t,in}| - \int_{l_{in}}^l \frac{\Omega dl}{1 - \Omega l}, \tag{22}$$

where W_{in} is the potential on the inner edge of the disk. With this definition, we can write (19) as

$$W - W_{in} = \int_0^p \frac{dp}{w} + \int^{\tilde{p}_m} \frac{d\tilde{p}_m}{\tilde{w}}, \tag{23}$$

and

$$W - W_{in} + \frac{\kappa}{\kappa - 1}\frac{p}{w} + \frac{\eta}{\eta - 1}\frac{p_m}{w} = 0, \tag{24}$$

and then, replacing p and p_m by equations (16) and (18),

$$W - W_{in} + \frac{\kappa}{\kappa - 1}Kw^{\kappa-1} + \frac{\eta}{\eta - 1}K_m(\mathcal{L}w)^{\eta-1} = 0, \tag{25}$$

which relates the distribution of potential with the distribution of enthalpy.

3. Methodology

3.1. Building the disk

To construct the disks we follow the procedure described below:

First, we find the location of r_{cusp} and r_c as the solutions to the equation $l(r) - l_K = 0$. Next, we write the partial derivatives of the potential (22)

$$\partial_r W = \partial_r \ln|u_t| - \frac{\Omega\partial_r l}{1 - \Omega l}, \tag{26}$$

and

$$\partial_\theta W = \partial_\theta \ln|u_t| - \frac{\Omega\partial_\theta l}{1 - \Omega l}. \tag{27}$$

Then, we integrate the radial partial derivative of the potential along the segment $[r_{cusp}, r_c]$ at the equatorial plane, thus obtaining the equatorial distribution of potential between r_{cusp} and r_c

$$W_{eq}(r) = \int_{r_{cusp}}^r \left(\partial_r \ln|u_t| - \frac{\Omega\partial_r l}{1 - \Omega l}\right). \tag{28}$$

We can divide the equations (26) and (27) (Qian et al. 2009) to get

$$F(r, \theta) = -\frac{\partial_r W}{\partial_\theta W} = \frac{d\theta}{dr}. \tag{29}$$

which is an ordinary differential equation that can be integrated to obtain the location of the equipotential surfaces.

Next, we choose all the initial values for the integration of the equation (29) to be between r_{cusp} and r_c ($\theta = \pi/2$). Since we are only interested in the surfaces inside the Roche lobe, our choice of initial values provides us a mapping of the equipotential surfaces of the torus. Given that we have already obtained both the equipotential surfaces which cross the segment $[r_{cusp}, r_c]$ and the potential distribution there, we found the potential distribution for the torus. Once we have the potential distribution, we can find the gas pressure at the center, from equation (25)

$$p_c = w_c(W_{in} - W_c)\left(\frac{\kappa}{\kappa - 1} + \frac{\eta}{\eta - 1}\frac{1}{\beta_c}\right)^{-1}, \tag{30}$$

3.2. Numerical code

- Description of the numerical construction.

3.3. Parameter space

Parameters β, γ, η, β_{mag}, κ, η, r_{in} and a. We do not vary κ and η.
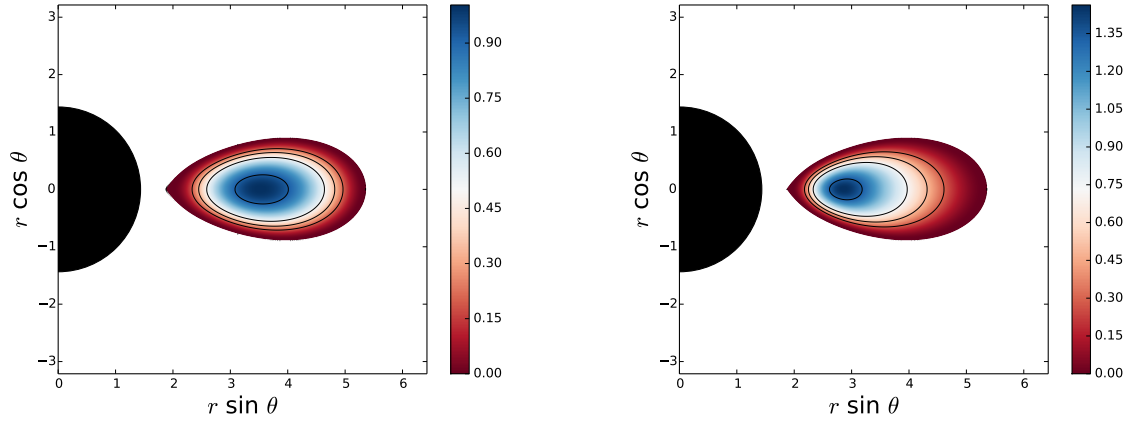And take $\eta = \eta_{max}$ for each value of a

4. Results

5. Conclusions

References

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Fig. 1. Adiabatic exponent Γ_1. Γ_1 is plotted as a function of lg internal energy [erg g^{-1}] and lg density [g cm^{-3}].