

Software Systems Verification and Validation

Vescan Andreea, PHD, Assoc. Prof.



Faculty of Mathematics and Computer Science
Babeș-Bolyai University



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Software Systems Verification and Validation

"Tell me and I forget, teach me and I may remember, involve me and I learn."

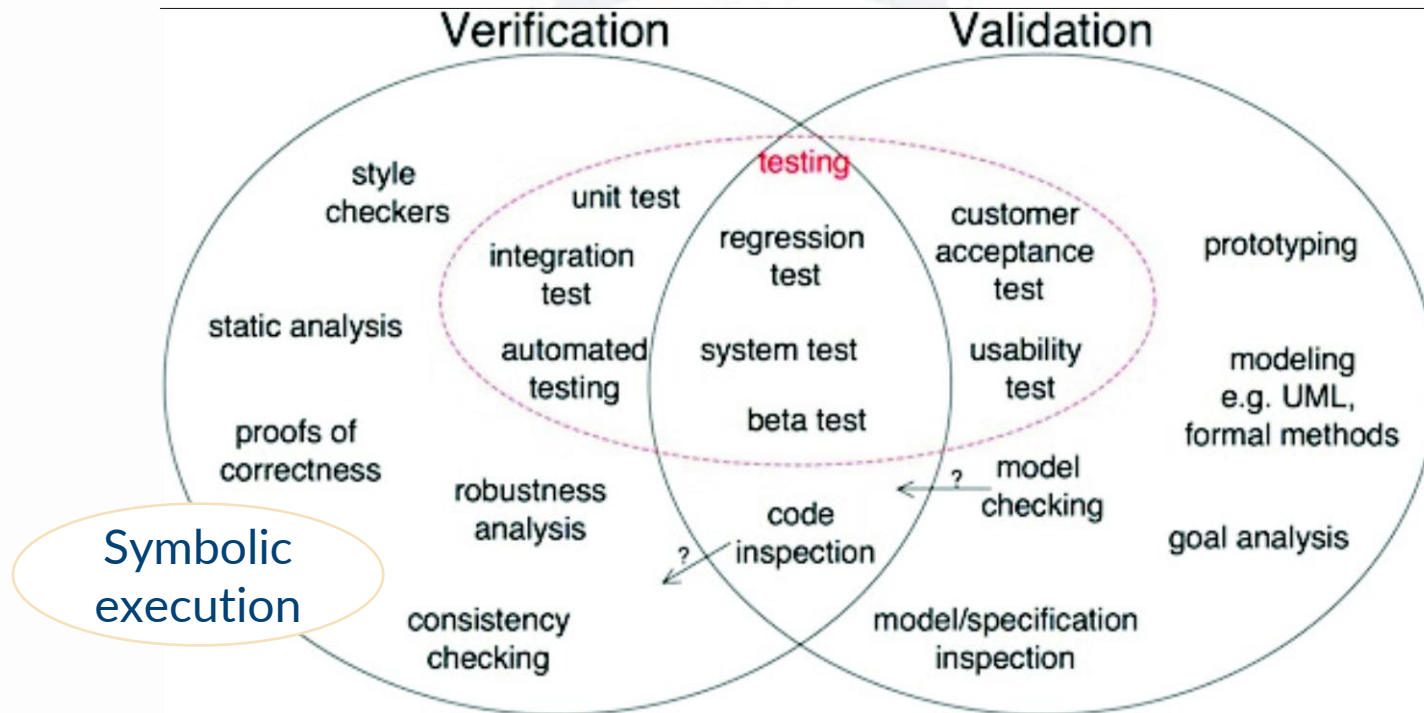
(Benjamin Franklin)

(Next)/Today Lecture

- Model checking



What we will learn!



- <http://www.easterbrook.ca/steve/2010/11/the-difference-between-verification-and-validation/>

Outline

Model checking

- System verification
- Model checking
- Transition system
- Linear-Time Properties
- Linear-Time Logic
- Computation Tree Logic

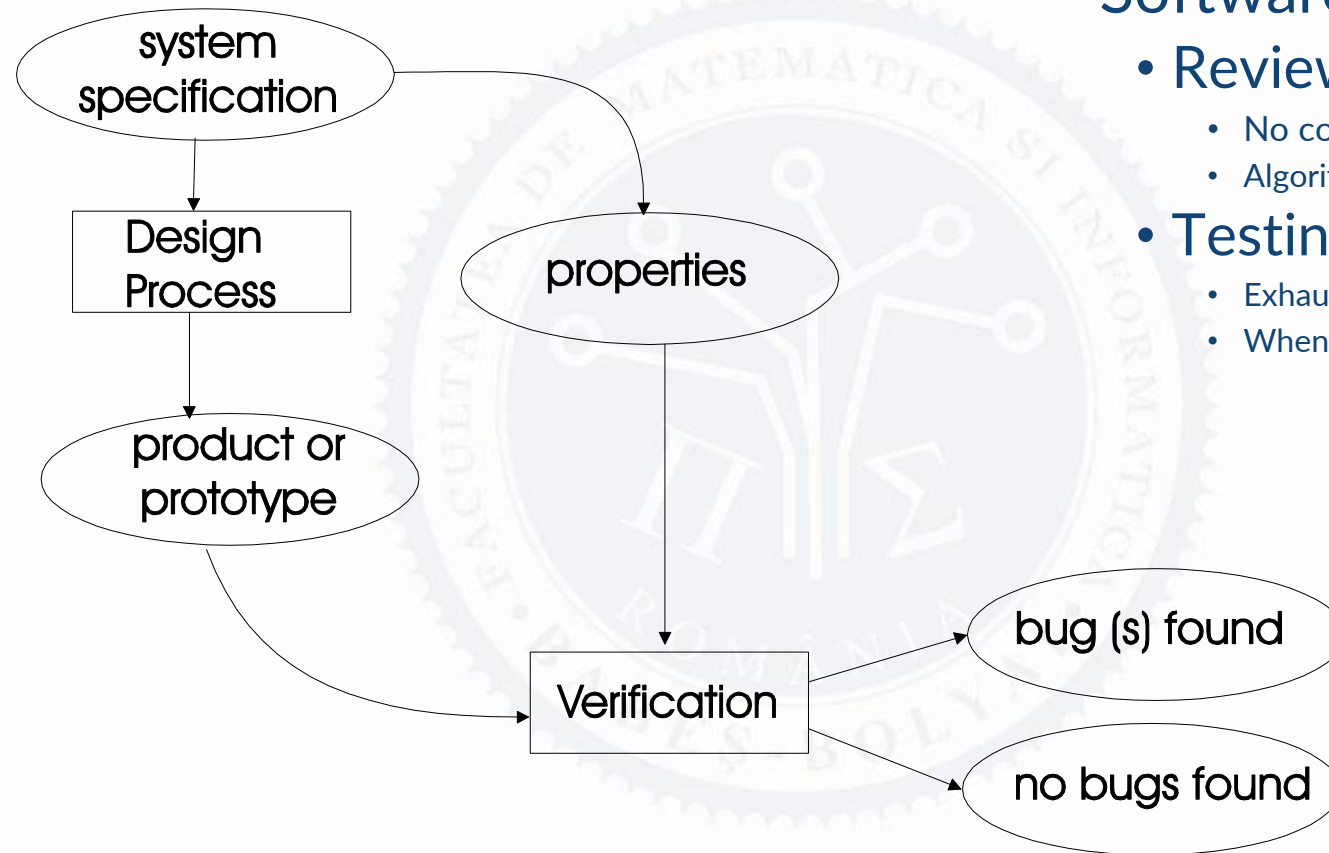
Spin Model Checker

- Spin
- Promela Model
 - Statements
 - Examples
- Concurrency and Interleaving Semantics
 - Examples
- Linear Temporal Logic
 - Examples
- JSpin
- Questions

System verification (1)

- Information and Communication Technology (ICT)
- Correct ICT systems
 - It is all about money.
 - It is all about safety.
- Reliability of the ICT systems
 - Interactive systems - concurrency & nondeterminism
 - Pressure - to reduce system development time
- System verification techniques

System verification (2)



- Software verification

- Review

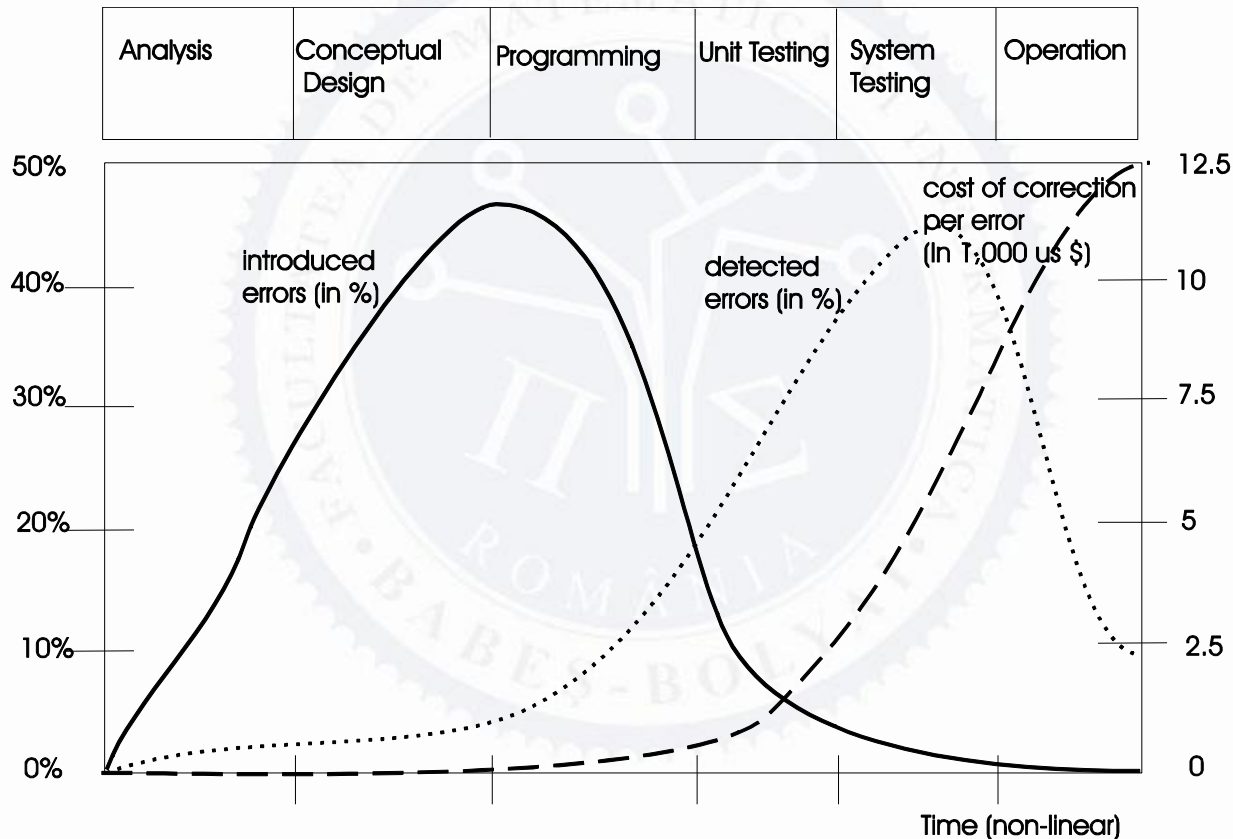
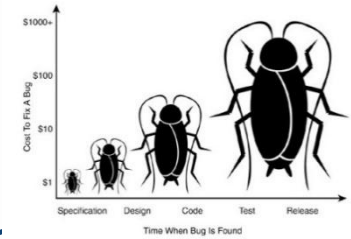
- No concurrency defects
 - Algorithm defects

- Testing

- Exhaustive testing?
 - When to stop?

System verification (2)

- Catching software errors: the sooner the better



Model checking (1)

Formal methods

- More time and effort spend on verification than on construction
 - in software/hardware design of complex systems.
- The role of formal methods:
 - To establish system correctness with mathematical rigor.
 - To facilitate the early detection of defects.
- Verification techniques
 - Testing – small subset of paths is treated
 - Simulation - restrictive set of scenarios in the model
 - Model checking - exhaustive exploration
- **Remark.** Any verification using **model-based techniques** is only as good as the model of the system.

Model checking (1)

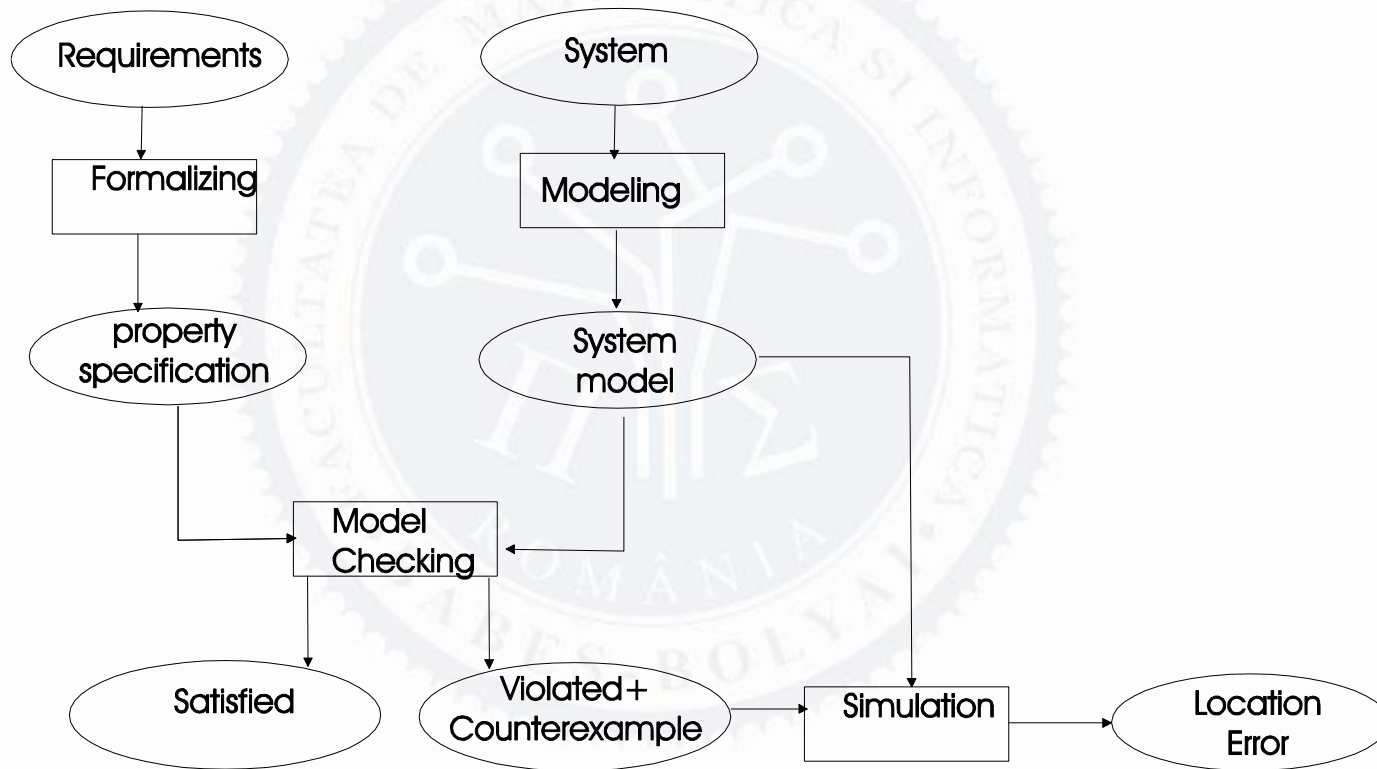
Formal methods



- Mechanical Engineering is like looking for a black cat in a lighted room.
- Chemical Engineering is like looking for a black cat in a dark room.
- Software Engineering is like looking for a black cat in a dark room in which there is no cat.
- Systems Engineering is like looking for a black cat in a dark room in which there is no cat and someone yells, "I got it!"

Model checking (2)

Approach



Model checking (3)

Characteristics

- Model checking is an automated technique that, given a finite-state model of a system and a formal property, systematically checks whether this property holds for (a given state in) that model.
- The model checking process
 - Modeling phase
 - model the system under consideration
 - formalize the property to be checked.
 - Running phase
 - Analysis phase
 - property satisfied?
 - property violated?

Model checking (4)

Strengths

- General verification approach
- Supports partial verification
- Provides diagnostic information
- Potential “push-button” technology
- Increasing interest by industry
- Easily integrated in existing development cycles

Weaknesses

- Appropriate to control-intensive applications
- Its applicability is subject to decidability issues
- It verifies a system model
- Checks only stated requirements
- Suffers from the state-space explosion problem
- Requires some expertise

Transition system (1)

Definition

- Transition systems - used in computer science as models to describe the behavior of the systems.
- Transition systems - directed graphs:
 - Nodes - represent states;
 - Edges - model transitions, i. e. state changes.
- A Transition System (TS) is tuple $(S, Act, \rightarrow, I, Ap, L)$, where
 - S is a set of states,
 - Act is a set of actions,
 - $\rightarrow \subseteq S \times Act \times S$ is a transition relation,
 - $I \subseteq S$ is a set of initial states,
 - AP is a set of atomic propositions, and
 - $L : S \rightarrow 2^{AP}$ is a labeling function.
- TS is called finite if S , Act and AP are finite.

Transition system (2)

Remark

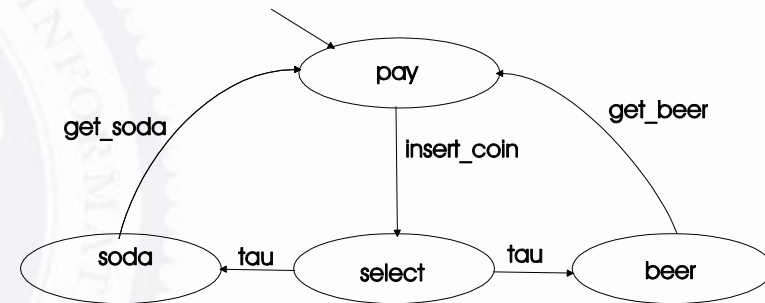
- Intuitive behavior of a transition system
 - Initial state $s_0 \in I$
 - Using the transition relation \rightarrow the system evolves
 - Current state s , a transition $s \xrightarrow{\alpha} s'$ is selected *nondeterministically*
 - The selection procedure is repeated and finishes once a state is encountered that has no outgoing transitions.
- The labeling function L relates a set $L(s) \in 2^{AP}$ at atomic propositions to any state s . $L(s)$ intuitively stands for exactly those atomic propositions $a \in AP$ which are satisfied by state s .
- Given that ϕ is a propositional logic formula, then s satisfies the formula ϕ if the evaluation induced by $L(s)$ makes the formula ϕ true,
 $s \models \phi$ iff $L(s) \models \phi$.

Transition system (3)

Example

Beverage Vending Machine

- $S = \{pay, select, soda, beer\}, I = \{pay\}$
- $Act = \{insert_coin, get_soda, get_beer, \tau\}$
- Example transitions: $pay \xrightarrow{insert_coin} select, beer \xrightarrow{get_beer} pay$
- Atomic propositions depends on the properties under consideration.
A simple choice - to let the state names act as atomic propositions, i. e. $L(s) = \{s\}$.
"The vending machine only delivers a drink after providing a coin,"
 $AP = \{paid, drink\}, L(pay) = \emptyset, L(soda) = L(beer) = \{paid, drink\}, L(select) = \{paid\}$.



Linear-Time Properties

- **Deadlock** – if the complete system is in a terminal state, although at least one component is in a (local) nonterminal state.
 - A typical deadlock scenarios occurs when components mutually wait for each other to progress.
- **Safety properties** = “nothing bad should happen”.
 - The number of inserted coins is always at least the number of dispensed drinks.
 - A typical safety property is deadlock freedom
 - Mutual exclusion problem – “bad” = more than one process is in the critical section
- **Liveness properties** = “something good will happen in the future”.
 - Mutual exclusion problem – typical liveness properties assert that:
 - (eventually) – each process will eventually enter its critical section
 - (repeated eventually) – each process will enter its critical section infinitely often
 - (starvation freedom) – each waiting process will eventually enter its critical section
- **Remark**
 - **Safety properties** - are violated in finite time (a finite system run)
 - **Liveness properties** – are violated in infinite time (by infinite system runs)

Temporal Logic

- **Propositional temporal logics** - extensions of propositional logic by temporal modalities.
- The elementary temporal modalities that are present in most temporal logics include the operators
 - “**eventually**” (eventually in the future) -
 - “**always**” (now and forever in the future) -
- The nature of time in temporal logics can be either **linear** or **branching**.
- The adjective “temporal”
 - specification of the relative order of events
 - does not support any means to refer to the precise timing of events

Linear-Time Logic (1)

Syntax of LTL

- Construction of LTL formulae in LTL - ingredients:
 - atomic propositions $a \in AP$, (stands for the state label a in a transition system)
 - boolean connectors like conjunction \wedge and negation \neg ,
 - basic temporal modalities "next" \bigcirc and "until" \bigcup .
- LTL formulae over the set AP of atomic proposition are formed according to the following grammar:
$$\varphi ::= true | a | \varphi_1 \wedge \varphi_2 | \neg \varphi | \bigcirc \varphi | \varphi_1 \bigcup \varphi_2, \text{ where } a \in AP.$$

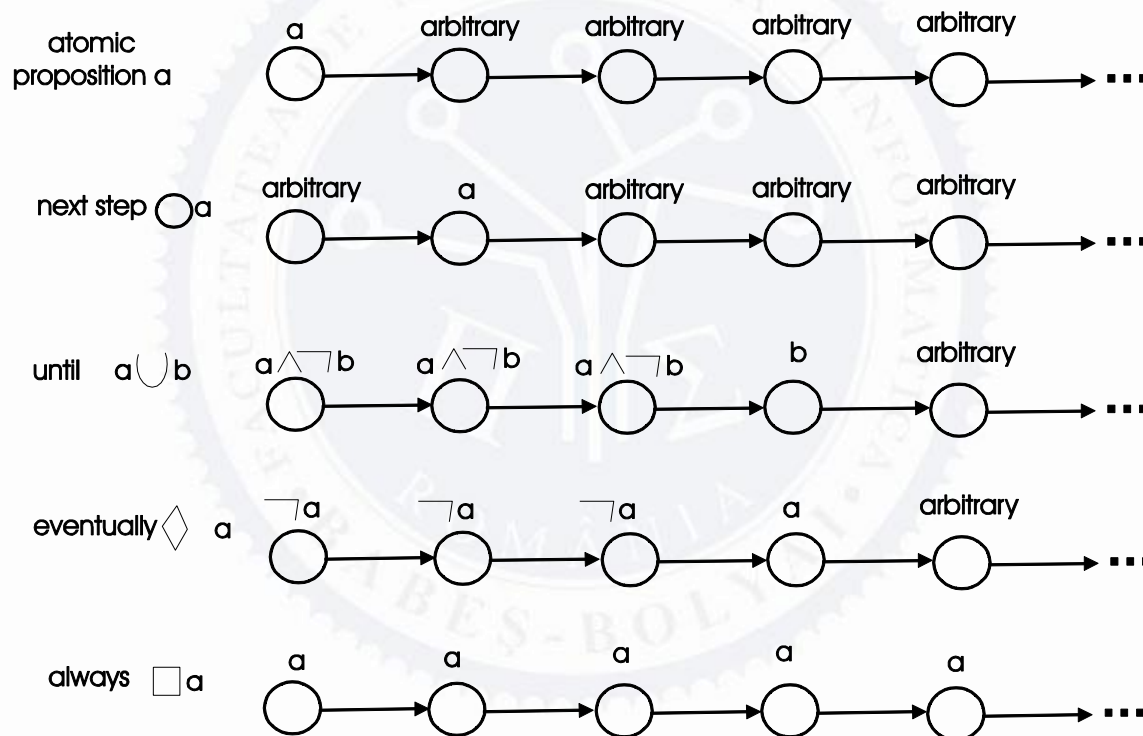
Linear-Time Logic (2)

LTL temporal modalities

- The until operator allows to derive the temporal modalities \Diamond ("eventually", sometimes in the future) and \Box ("always", from now on forever) as follows:
 - $\Diamond\varphi = \text{true} \cup \varphi$.
 - $\Box\varphi = \neg\Diamond\neg\varphi$.
- By combining the temporal modalities \Diamond and \Box , new temporal modalities are obtained:
 - $\Box\Diamond\varphi$ - "infinitely often φ ."
at any moment j there is a moment i $i \geq j$ at which an a state is visited
 - $\Diamond\Box\varphi$ - "eventually forever φ ."
from some moment j on, only a -states are visited.

Linear-Time Logic (3)

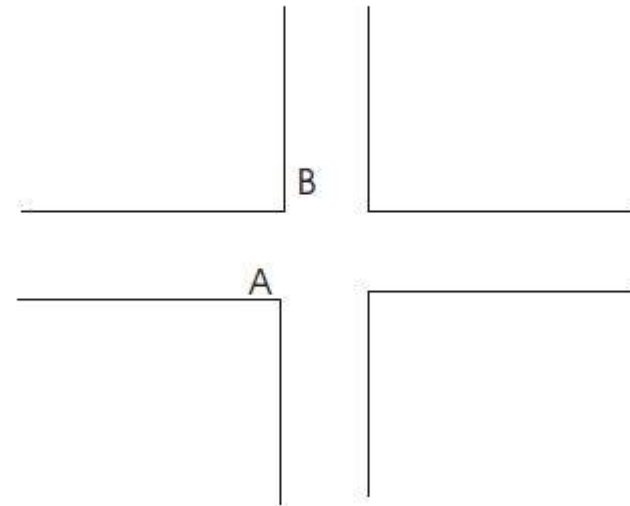
Intuitive meaning of temporal modalities



Linear-Time Logic (4)

LTL semaphore example

- $\Box(\neg(A = \text{green} \wedge B = \text{green}))$
 - A and B can not be simultaneously green.
- $\Box(A = \text{yellow} \rightarrow A = \text{red})$
 - If A is yellow eventually will become red.
- $\Box(A = \text{yellow} \rightarrow \bigcirc(A = \text{red}))$
 - If A is yellow then it will be red into the next state.
- $\Box(\neg(B = \text{green}) \cup (A = \text{red}))$
 - B will not be green until A changes in red.



Computation Tree Logic (1)

Syntax of CTL

- Construction of CTL formulae:
 - as in LTL by the next-step and until operators,
 - must be not combined with boolean connectives
 - no nesting of temporal modalities is allowed.
- CTL formulae over the set AP of atomic proposition are formed according to the following grammar:
$$\phi ::= \text{true} \mid a \mid \phi_1 \wedge \phi_2 \mid \neg\phi \mid \exists\phi \mid \forall\phi, \text{ where } a \in AP \text{ and } \phi \text{ is a path formula.}$$
- CTL path formulae are formed according to the following grammar:
$$\varphi ::= \bigcirc\phi \mid \phi_1 \bigcup \phi_2, \text{ where } \phi, \phi_1 \text{ and } \phi_2 \text{ are state formulae.}$$

Computation Tree Logic (2)

CTL - state and path formulae

- CTL distinguishes between state formulae and path formulae:
 - State formulae express a property of a state.
 - Path formulae express a property of a path, i.e. an infinite sequence of states.
- Temporal PATH operators \bigcirc and \bigcup
 - $\bigcirc\phi$ holds for a path if ϕ holds in the next state of the path;
 - $\phi \bigcup \psi$ holds for a path if there is some state along the path for which ψ holds, and ϕ holds in all states prior to that state.
- Path formulae \Rightarrow state formulae by prefixing them with
 - path quantifier \exists (pronounced "for some path");
 $\exists\phi$ - holds in a state if there exists some path satisfying ϕ that starts in that state.
 - path quantifier \forall (pronounced "for all paths".)
 $\forall\phi$ -holds in a state if all paths that start in that state satisfy ϕ .

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Model checking

Spin

- Developed at Bell Labs.
- In 2002, recognized by the ACM with Software System Award.
- SPIN (= Simple Promela Interpreter)
- is a tool for analyzing the logical consistency of concurrent systems
- Concurrent systems are described in the modelling language called Promela (= Protocol/Process Meta Language)

Promela

- Promela (= Protocol/Process Meta Language)
- allows for the dynamic creation of concurrent processes.
- communication via message channels can be defined to be
 - synchronous (i.e. rendezvous),
 - asynchronous (i.e. buffered).

Promela Model

- Promela model consist of:
 - type declarations
 - channel declarations
 - variable declarations
 - process declarations
 - **[init process]**
- A process type (**proctype**) consist of
 - a name
 - a list of formal parameters
 - local variable declarations
 - Body
- A process
 - is defined by a **proctype definition**
 - executes concurrently with all other processes, independent of speed of behaviour
 - communicate with other processes
 - using global (shared) variables
 - using channels
- There may be several processes of the same type.
- Each process has its own local state:
 - process counter (location within the **proctype**)
 - contents of the local variables

Promela Model - Statements

- The body of a process consists of a sequence of statements.
- A statement is either
 - executable: the statement can be executed immediately.
 - blocked: the statement cannot be executed.
- An assignment is always executable.
- An expression is also a statement; it is executable if it evaluates to non-zero
- The **skip statement is always executable**.
 - “does nothing”, only changes process’ process counter
- A **printf statement is always executable (but is not evaluated during verification, of course).**
- **assert(<expr>);**
 - The assert-statement is always executable.
 - If <expr> evaluates to zero, SPIN will exit with an error, as
- the <expr> “has been violated”.
 - The assert-statement is often used within Promela models,
- to check whether certain properties are valid in a state.

Examples (01 Simple Examples)

- ReversingDigits.pml
 - Check
 - Random
- DiscriminantOfQuadraticEquation.pml
 - Check
 - Random
- NumberDaysInMonth.pml
 - Check
 - Random
- MaximumNondeterminism.pml
 - Check
 - Random
 - “Branch 1” and “Branch 2”
- Maximum –second example-MaximumIfElse.pml
 - Check
 - Random
- GCD.pml
 - Check
 - Random
- IntegerDivison01.pml
 - Check
 - Random

Concurrency and Interleaving Semantics

02 Concurrency and interleaving semantics

- Promela processes execute concurrently.
 - Non-deterministic scheduling of the processes.
 - Processes are interleaved (statements of different processes do not occur at the same time).
 - exception: rendez-vous communication.
- All statements are atomic; each statement is executed without interleaving with other processes.
- Each process may have several different possible actions enabled at each point of execution - only one choice is made, non-deterministically.
- InterleavingStatements.pml
 - Check
 - Random
 - 6 possibilities of the execution
 - $n1, p, n2, q;$
 - $n1, n2, p, q;$
 - $n1, n2, q, p;$
 - $n2, q, n1, p;$
 - $n2, n1, q, p;$
 - $n2, n1, p, q.$
 - Interactive simulation – Interactive button
- InterferenceBetweenProcesses.pml
- InterferenceBetweenProcessesDeterministic.pml

Examples (03 Critical section)

- CriticalSection_Incorrect.pml
 - both processes – in the critical section
- CriticalSection_MutualExclusion.pml – not satisfied
 - Mutual exclusion – at most one process is executing its critical section at any time.
- CriticalSection_With_Deadlock.pml
 - Blocking on an expression – user Interactive simulation
 - Absence of deadlock – it is impossible to reach a state in which some processes are trying to enter their critical sections, but no process is successful.
- CriticalSection_SolutionAtomic.pml
 - The atomic sequence may be blocked from executing, but once it starts executing, both statements are executed without interference from the other process.

Linear Temporal Logic

- Temporal logic formulae can specify both safety and liveness properties.
- LTL \equiv propositional logic + temporal operators
 - $[]P$ always P
 - $\langle \rangle P$ eventually P
 - $P \text{ U } Q$ P is true until Q becomes true

Examples (04 LTL examples)

- CriticalSection_MutualExclusionLTL.pml
 - LTL formula:
 - $[]\text{mutex}$
 - Translate
 - Verify
- CriticalSection_MutualExclusionLTL02.pml
 - LTL formula:
 - $[]\text{mutex}$
 - Translate
 - Verify
- CriticalSection_With_Starvation.pml
 - LTL formula:
 - $\langle \rangle \text{csp}$
 - Translate
 - Acceptance
 - Verify

Channels in Promela 05

Channels

- A channel in Promela = a data type with two operations:
 - send
 - The send statement consists of a channel variable followed by **an exclamation point** and then a sequence of expressions whose number and types match the message type of the channel.
 - receive
 - The receive statement consists of a channel variable followed by **question mark** and a sequence of variables.
- Every channel has associated with it a message type.
- The message type that specifies the structure of each message that can be send on the channel as a sequence of fields).

Chan ch = [capacity] of {typename, ..., typename}

- There are two types of channels with different semantics:
 - Rendezvous channels of capacity 0
 - Buffered channels of capacity greater than 0
- Examples
 - **Client-server-channels.plm**

Rendezvous Channels in Promela

05 Channels (Book [2]: pages 107-109)

- Rendezvous channel – with capacity 0.
 - The transfer of the message from the sender (a process with a send statement) to the receiver (a process with the receive statement) is synchronous and is executed as a single atomic operation.
- Examples
- **Simple-Rendezvous.pml**
 - The rendezvous is one atomic operation; even if there were other processes, no interleaving could take place between the execution of the send statement and the receive statement.

Traffic-Pedestrian 06 Channels

- Examples
- **PromelaMarryMe_Simple.pml**
- **PromelaMarryMe.pml**
- **traffic_pedestrian.pml**

JSpin

- <http://spinroot.com/>
- Installation JSpin
<http://jspin.software.informer.com/5.0/>





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References

- [1] Baier Christel, Katoen Joost-Pieter, Principles of Model Checking , ISBN 9780262026499, The MIT Press, 2008
 - Chapter 1 - System verification, Chapter 2 – Modelling Concurrent systems (pag. 19-20), Chapter 3 (pag. 89, 107, 120-121), Chapter 5 – Linear Temporal Logic (pag. 229-233), Chapter 6 – Computation Tree Logic (pag. 313-323)
- [2] Ben-Ari, Mordechai, Principles of the Spin Model Checker, ISBN 978-1-84628-770-1, Springer-Verlag London, 2008

Next Lecture

- Correctness





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