

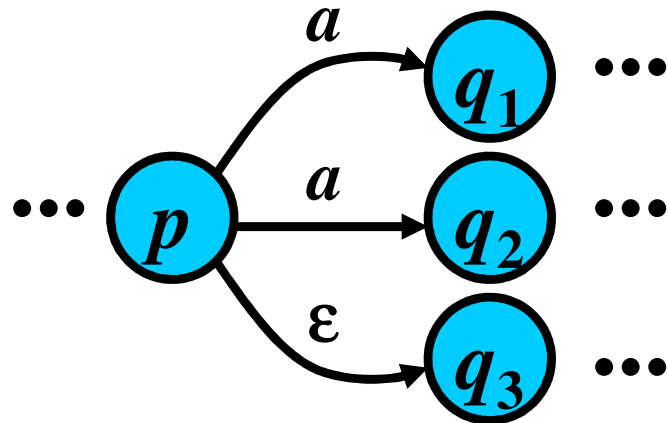
# **Part IV.**

# **Variants of Finite**

# **Automata**

# Theory vs. Practice

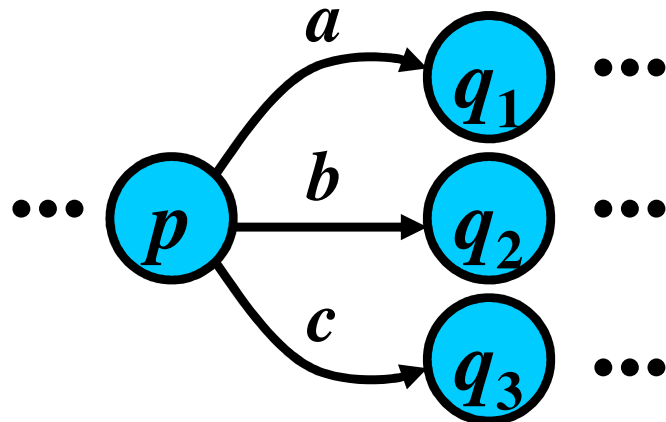
a) Configuration:  $pax$



Next Configuration:  
 $q_1x$  or  $q_2x$  or  $q_3ax$  ?

Theory: 😊 × Practice: ☹️

b) Configuration:  $pax$



Next Configuration:  
 only  $q_1x$

Theory: ☹️ × Practice: 😊

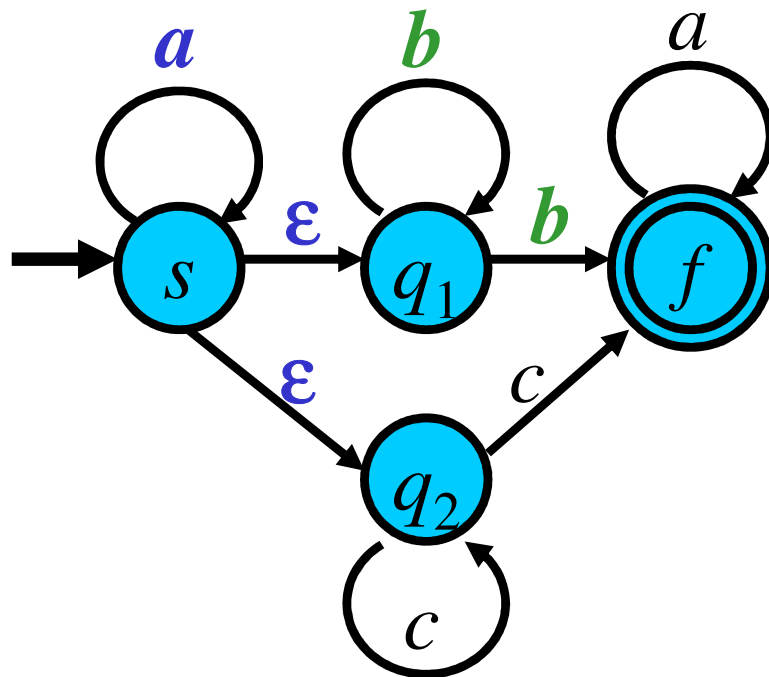
# Use of FA in General

Simulation of all possible moves from every configuration.

---

## Example:

FA  $M$  is defined as:



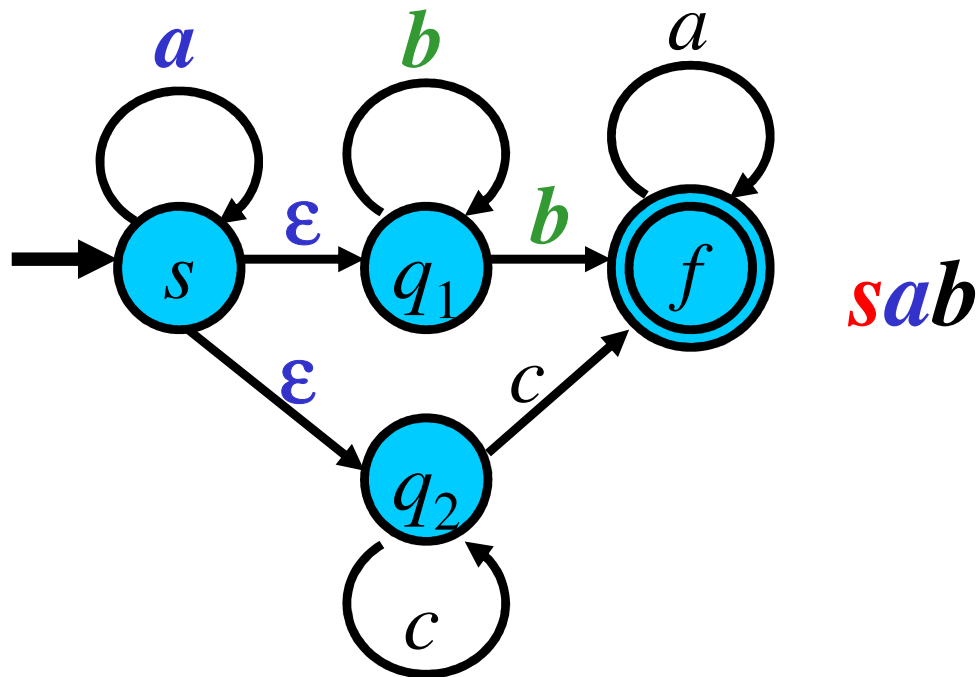
**Question:**  $ab \in L(M)$  ?

# Use of FA in General

Simulation of all possible moves from every configuration.

## Example:

FA  $M$  is defined as:



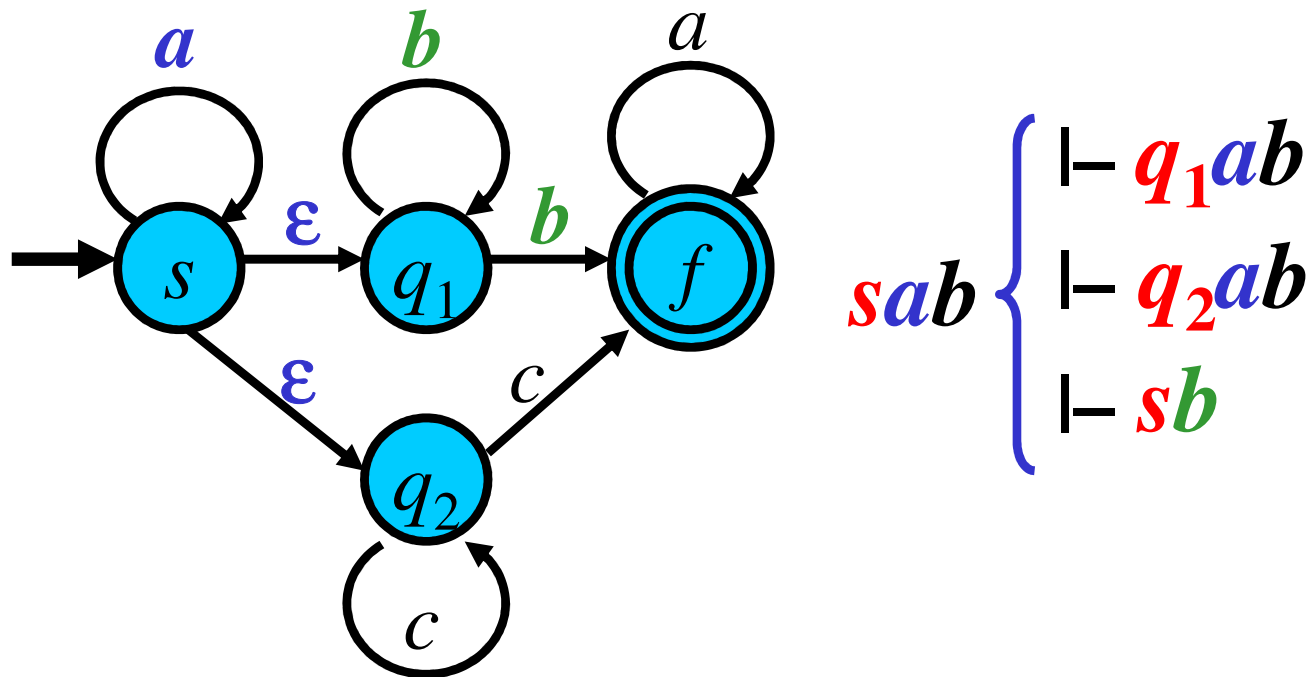
**Question:**  $ab \in L(M)$  ?

# Use of FA in General

Simulation of all possible moves from every configuration.

## Example:

FA  $M$  is defined as:



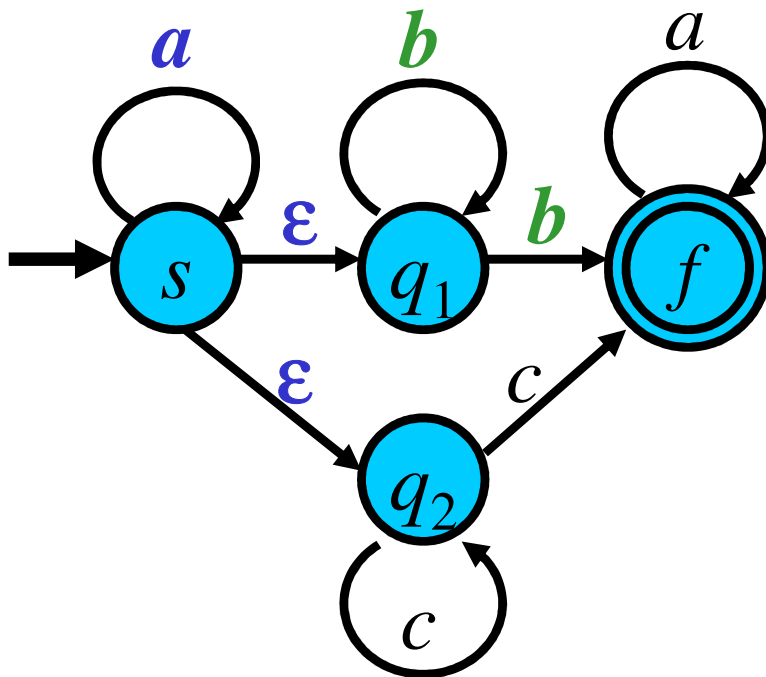
**Question:**  $ab \in L(M)$  ?

# Use of FA in General

Simulation of all possible moves from every configuration.

## Example:

FA  $M$  is defined as:



$sab$  {
 

- $\vdash q_1ab$
- $\vdash q_2ab$
- $\vdash sb$

No next configuration

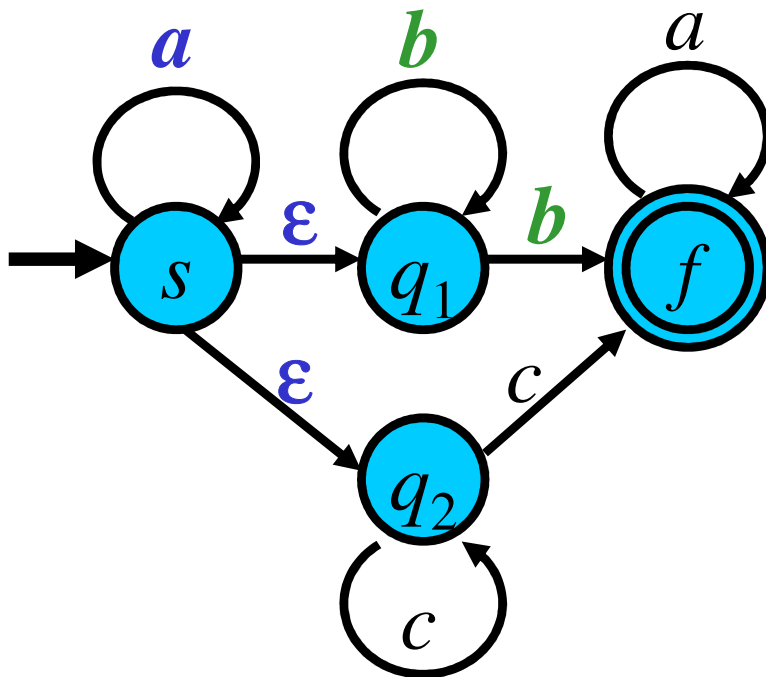
Question:  $ab \in L(M)$  ?

# Use of FA in General

Simulation of all possible moves from every configuration.

## Example:

FA  $M$  is defined as:



$sab$  {
 

- $\vdash q_1ab$
- $\vdash q_2ab$
- $\vdash sb$

No next configuration

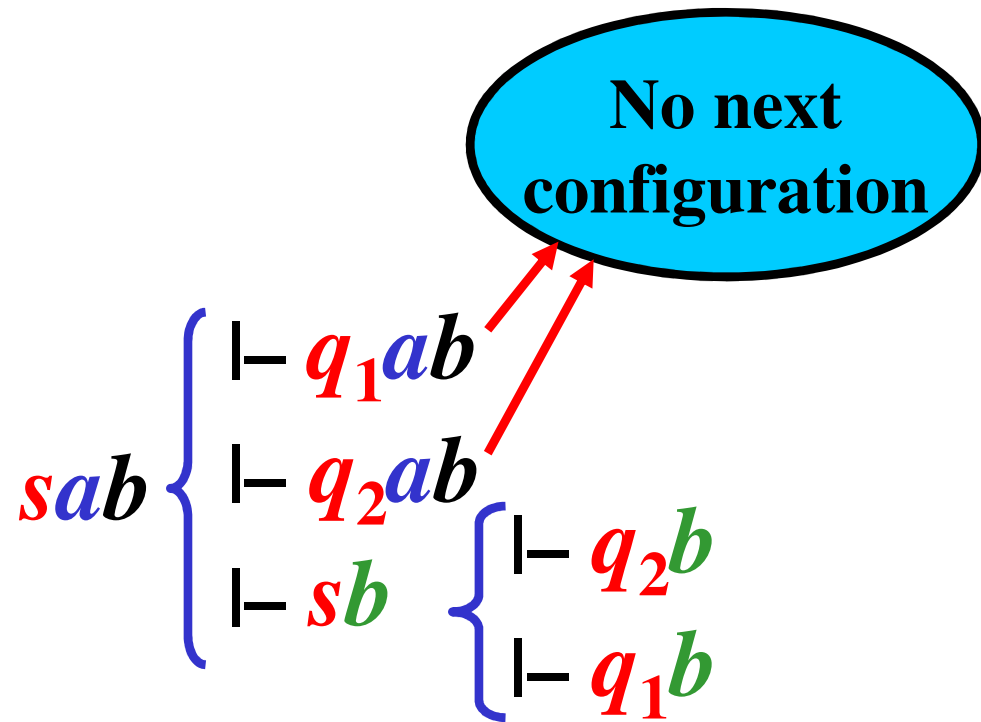
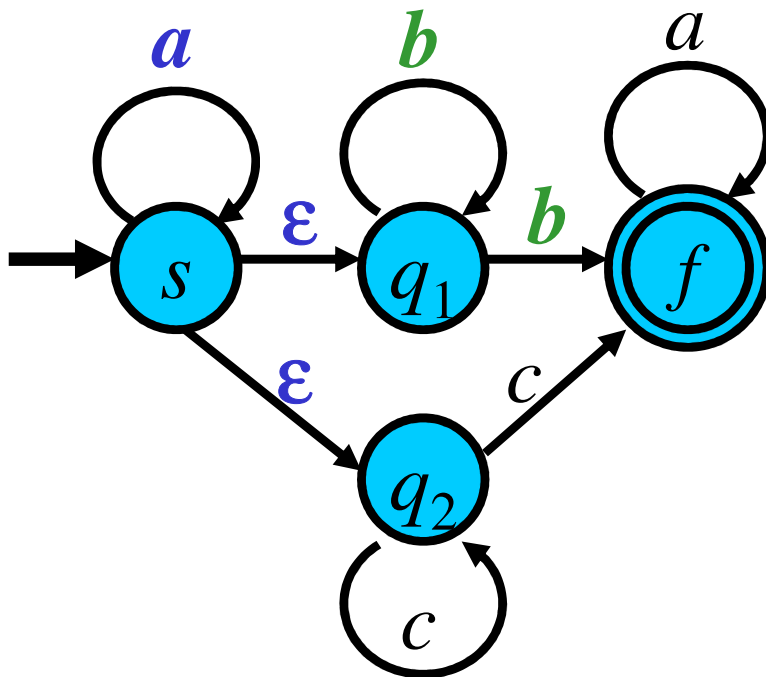
Question:  $ab \in L(M)$  ?

# Use of FA in General

Simulation of all possible moves from every configuration.

## Example:

FA  $M$  is defined as:



**Question:**  $ab \in L(M)$  ?

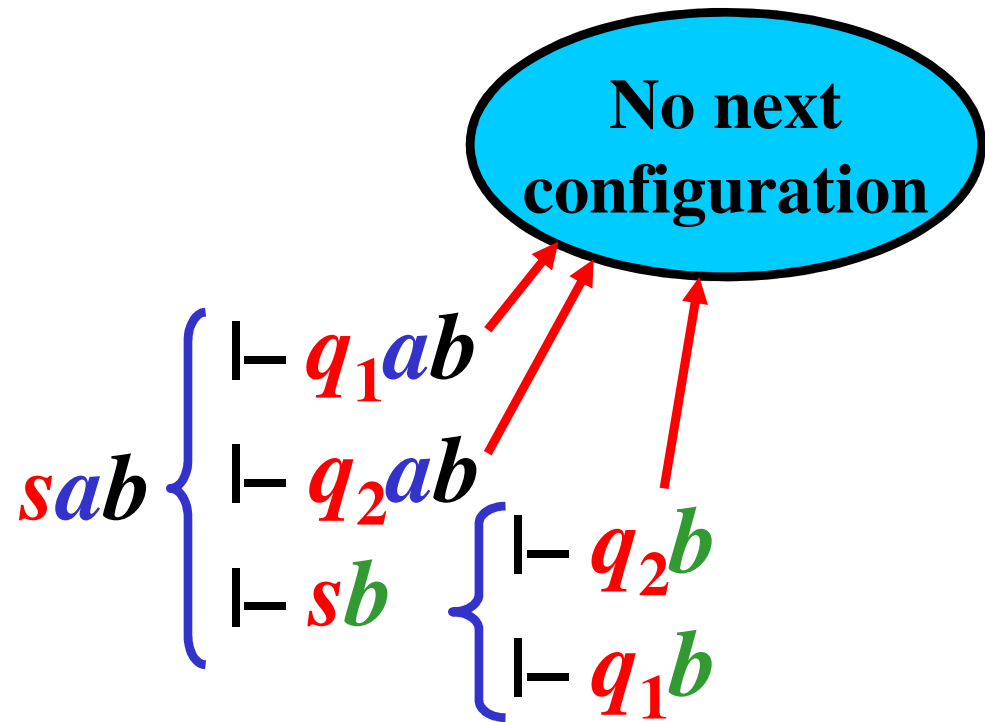
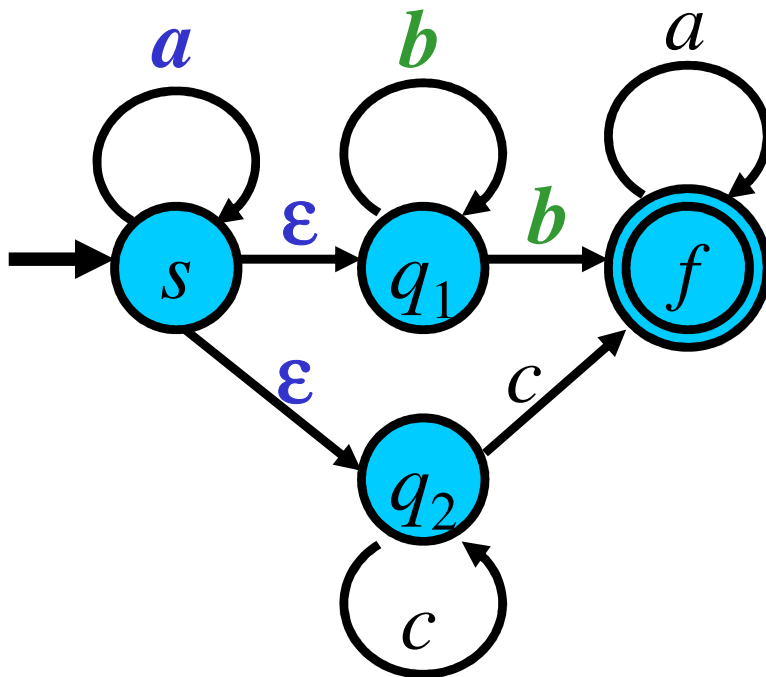


# Use of FA in General

Simulation of all possible moves from every configuration.

## Example:

FA  $M$  is defined as:



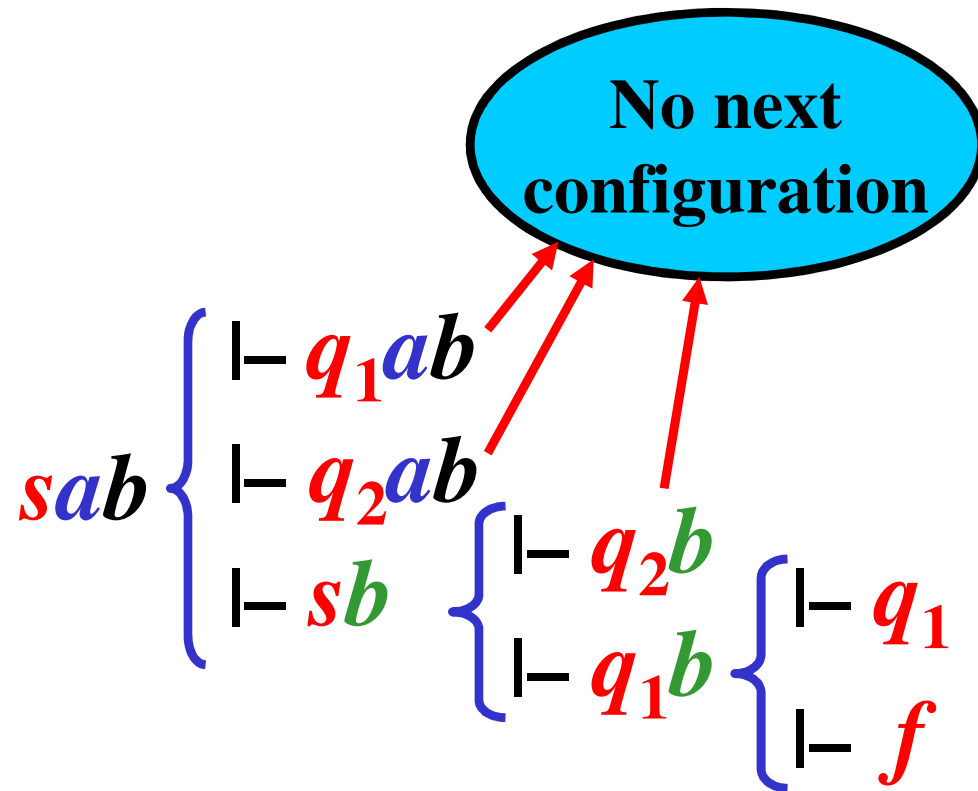
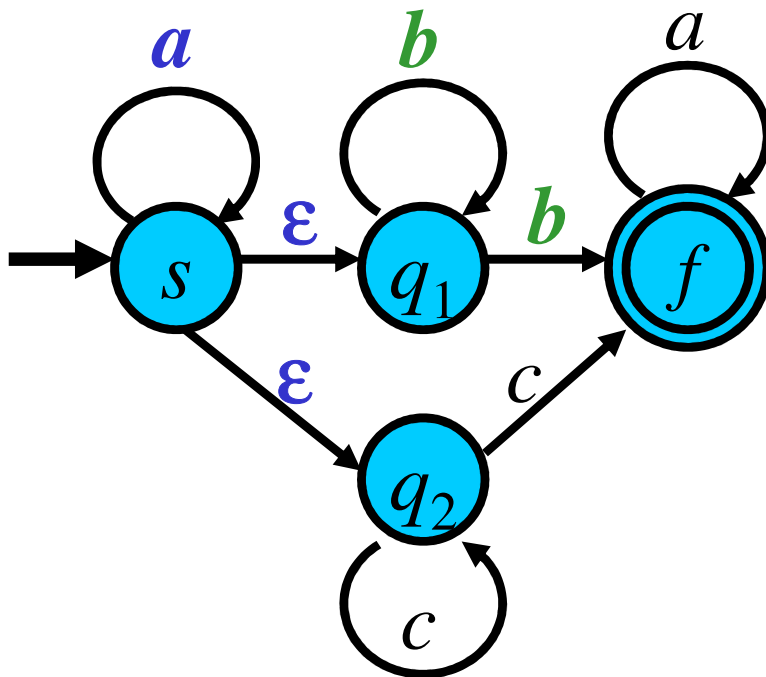
**Question:**  $ab \in L(M)$  ?

# Use of FA in General

Simulation of all possible moves from every configuration.

## Example:

FA  $M$  is defined as:



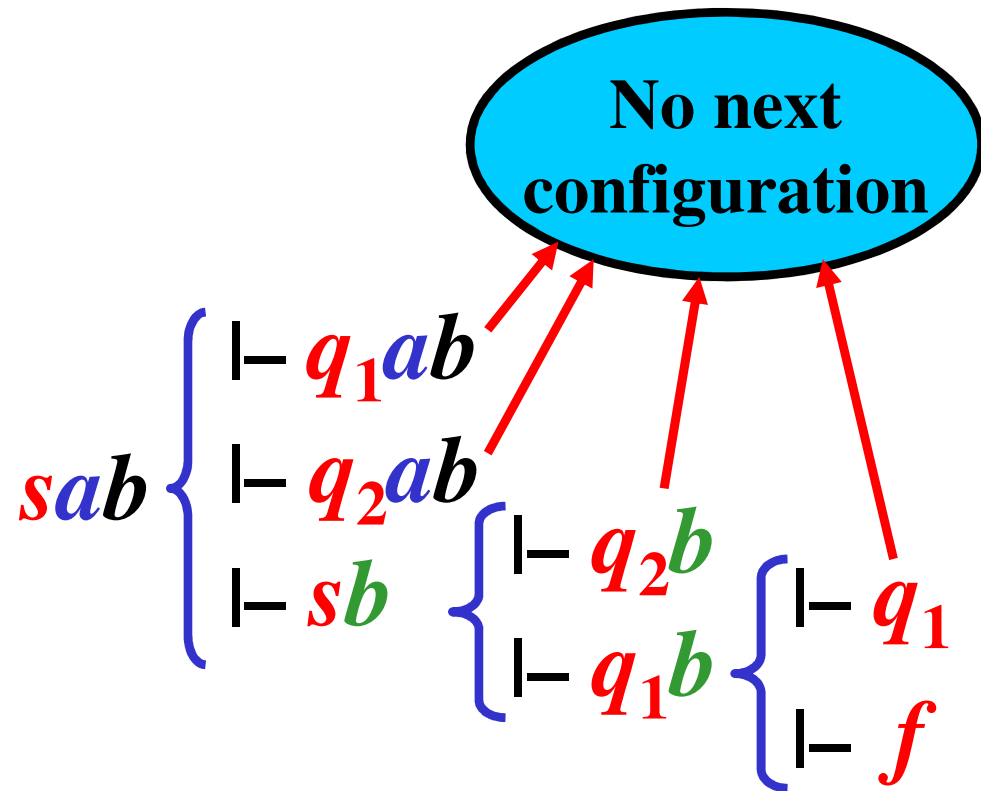
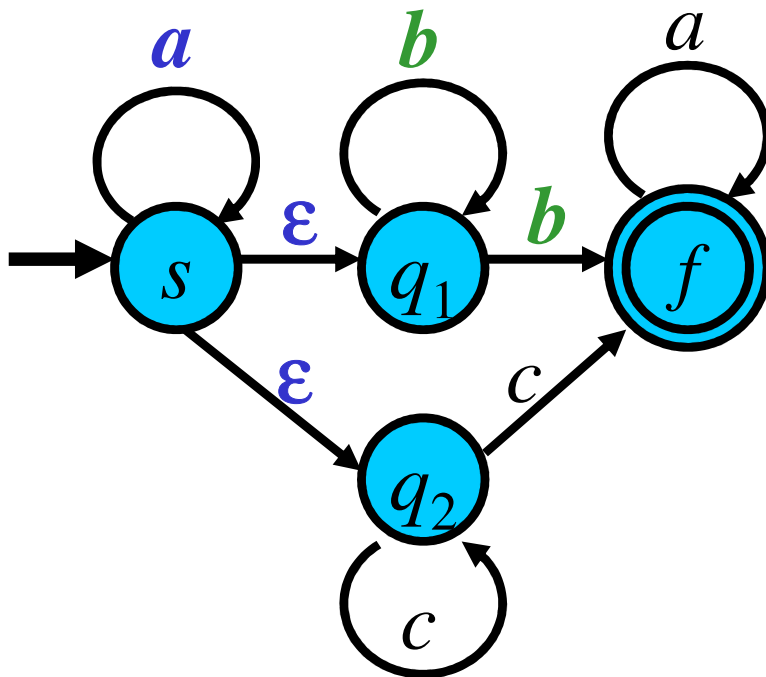
**Question:**  $ab \in L(M)$  ?

# Use of FA in General

Simulation of all possible moves from every configuration.

## Example:

FA  $M$  is defined as:



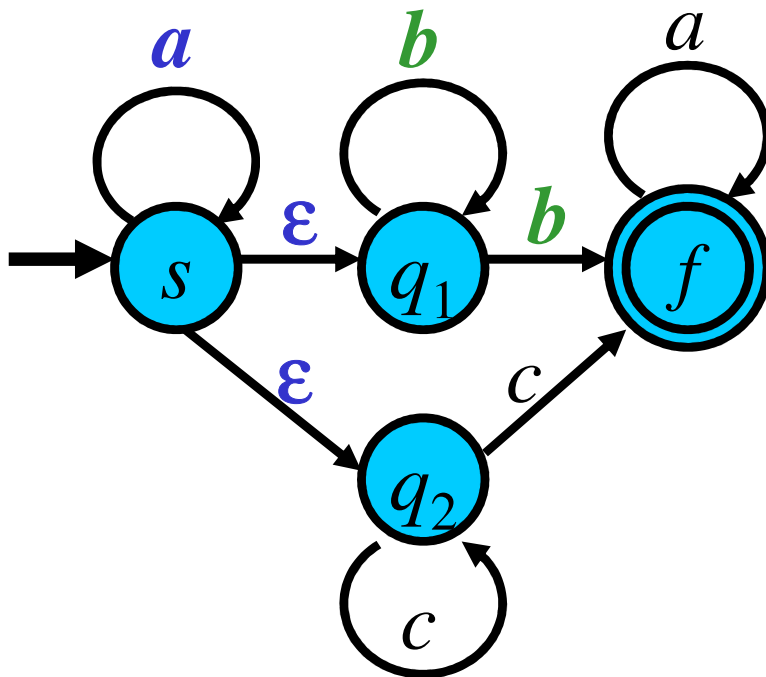
Question:  $ab \in L(M)$  ?

# Use of FA in General

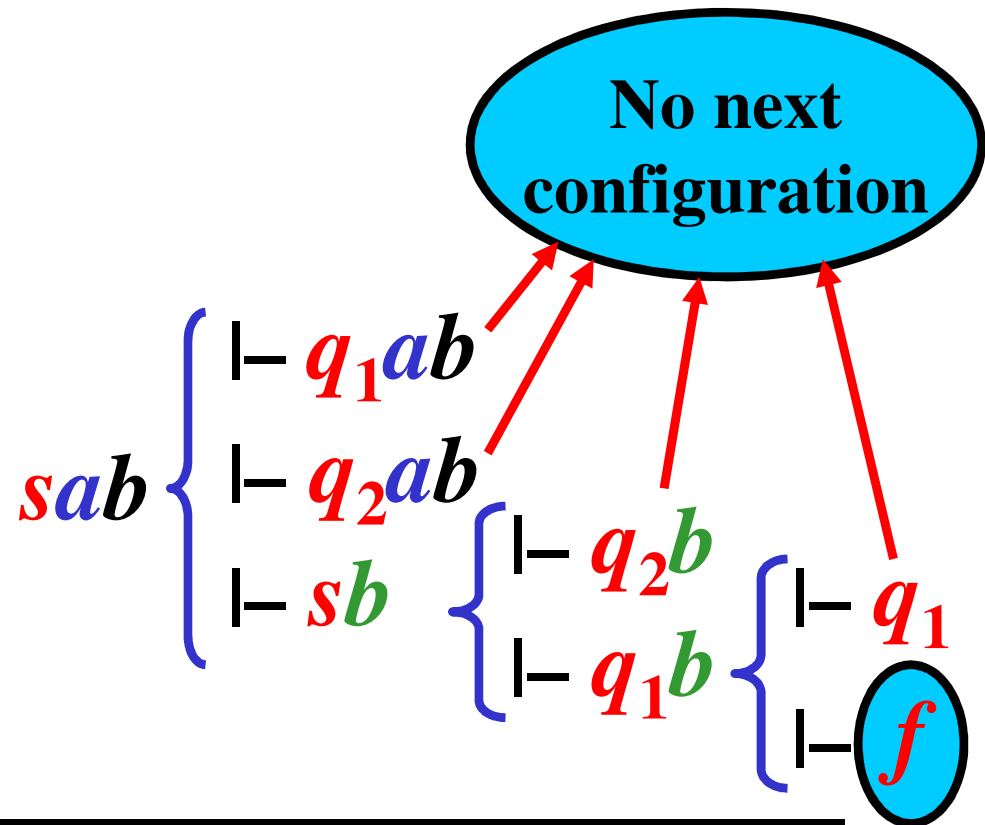
Simulation of all possible moves from every configuration.

## Example:

FA  $M$  is defined as:



**Question:**  $ab \in L(M)$  ?



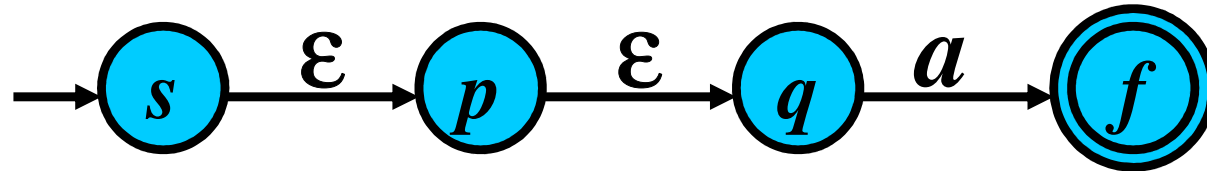
**Answer: YES**,  $ab \in L(M)$   
because  $f \in F$ .

# From FA to DFA in Essence 1/2

**Preference in practice:** *Deterministic FA* (DFA) that makes no more than one move from every configuration.

---

## 1) Gist: Removal of $\epsilon$ -moves

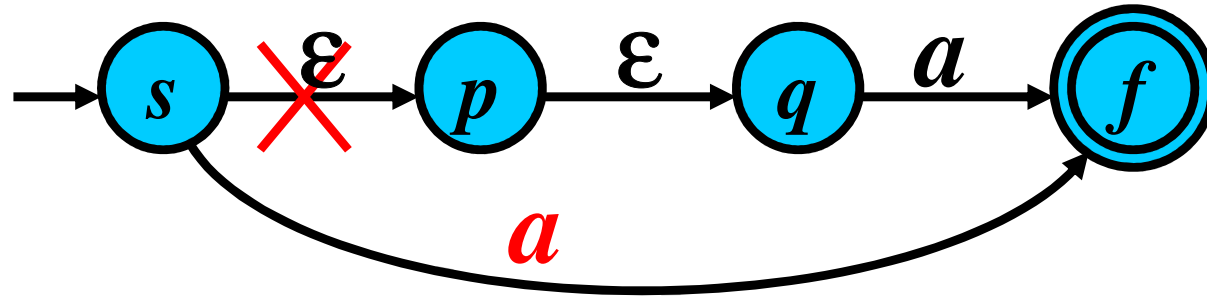


# From FA to DFA in Essence 1/2

**Preference in practice:** *Deterministic FA (DFA)* that makes no more than one move from every configuration.

---

## 1) Gist: Removal of $\epsilon$ -moves

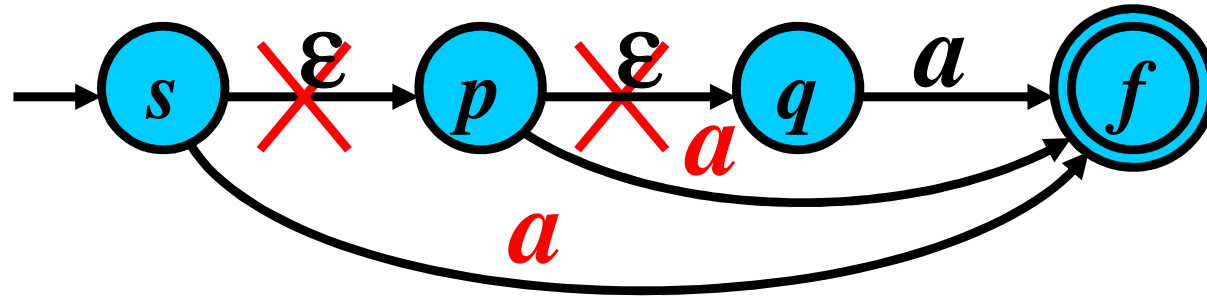


# From FA to DFA in Essence 1/2

**Preference in practice:** *Deterministic FA (DFA)* that makes no more than one move from every configuration.

---

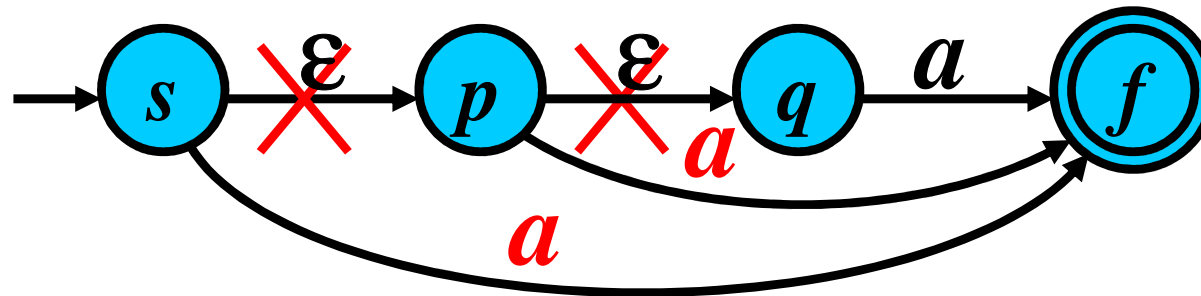
## 1) Gist: Removal of $\epsilon$ -moves



# From FA to DFA in Essence 1/2

**Preference in practice:** *Deterministic FA (DFA)* that makes no more than one move from every configuration.

## 1) Gist: Removal of $\varepsilon$ -moves



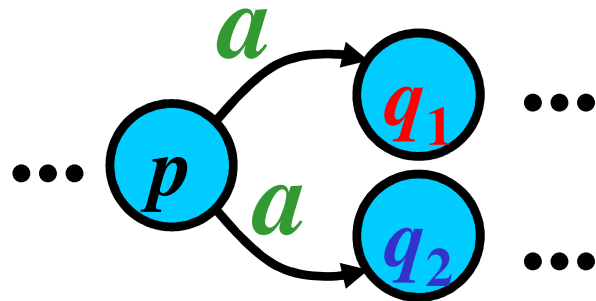
**Definition:** Let  $M = (Q, \Sigma, R, s, F)$  be a FA.  $M$  is an  *$\varepsilon$ -free finite automaton* if for all rules  $pa \rightarrow q \in R$ , where  $p, q \in Q$ , holds

$$a \in \Sigma \ (a \neq \varepsilon)$$



## From FA to DFA in Essence 2/2

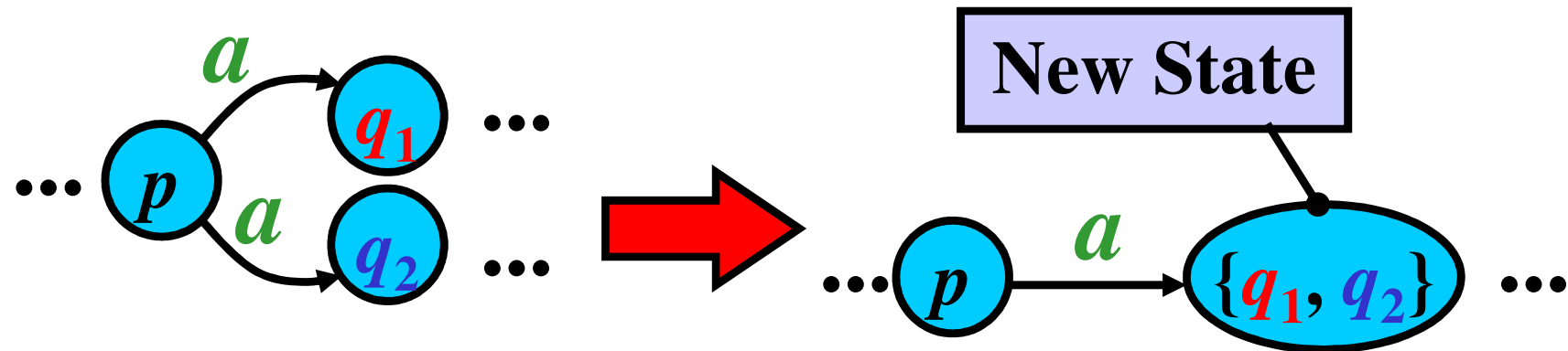
### 2) Gist: Removal of nondeterminism



**Definition:** Let  $M = (Q, \Sigma, R, s, F)$  be an  **$\epsilon$ -free FA**.  $M$  is a *deterministic finite automaton* (DFA) if for each rule  $pa \rightarrow q \in R$  it holds that  $R - \{pa \rightarrow q\}$  contains no rule with the left-hand side equal to  $pa$ .

# From FA to DFA in Essence 2/2

## 2) Gist: Removal of nondeterminism

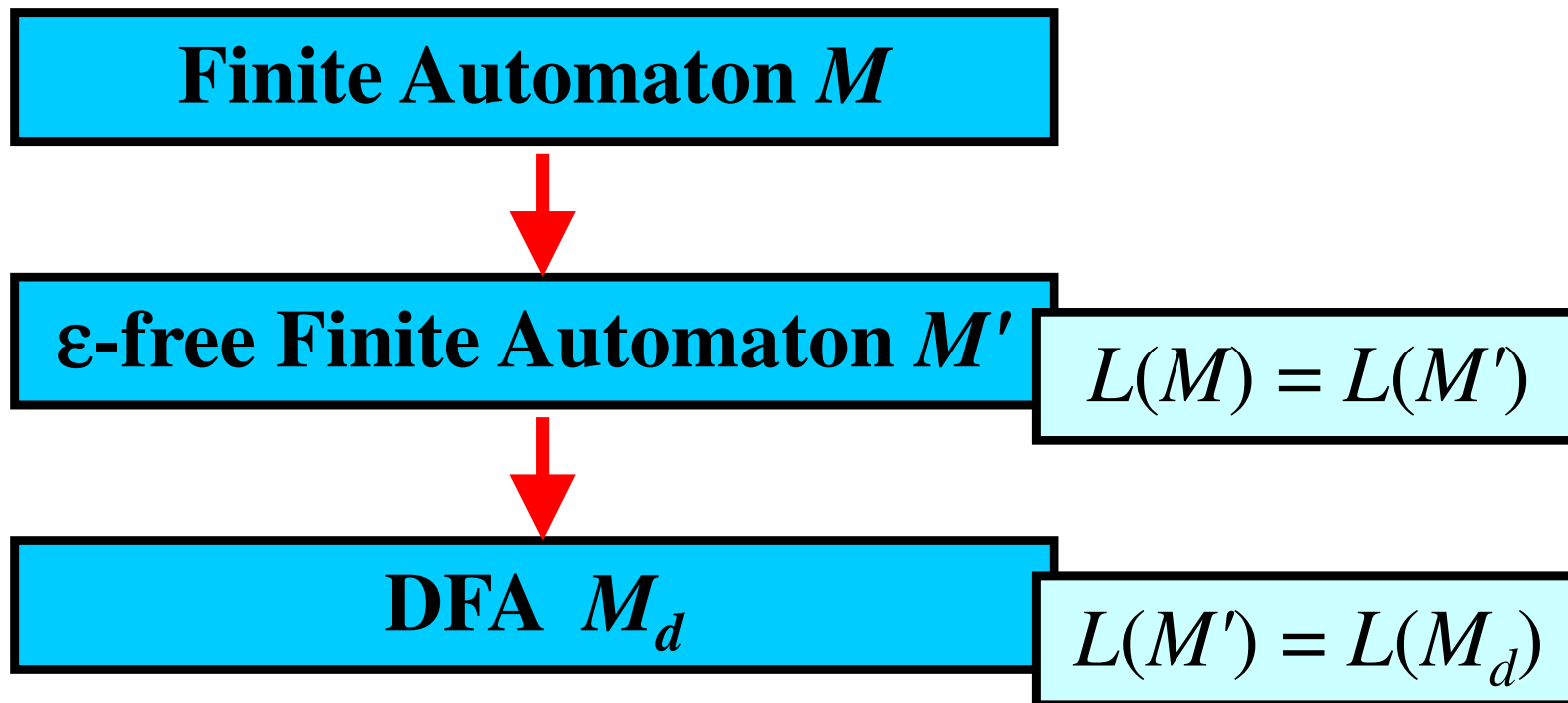


**Definition:** Let  $M = (Q, \Sigma, R, s, F)$  be an  **$\epsilon$ -free FA**.  $M$  is a *deterministic finite automaton* (DFA) if for each rule  $pa \rightarrow q \in R$  it holds that  $R - \{pa \rightarrow q\}$  contains no rule with the left-hand side equal to  $pa$ .

# Theorem

- For every FA  $M$ , there is an equivalent DFA  $M_d$ .

**Proof** is based on these conversions:

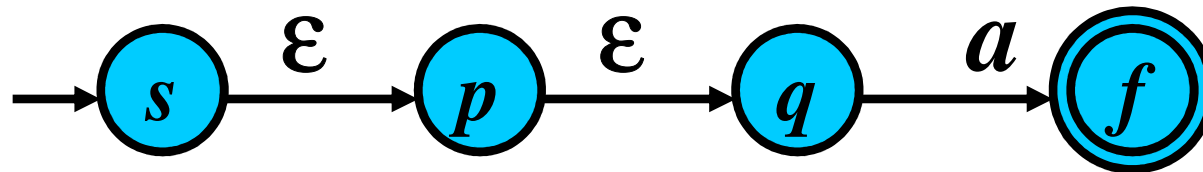


## $\epsilon$ -closure

**Gist:**  $q$  is in  $\epsilon$ -closure( $p$ ) if FA can reach  $q$  from  $p$  without reading.

**Definition:** For every states  $p \in Q$ , we define a set  $\epsilon$ -closure( $p$ ) as  $\epsilon$ -closure( $p$ ) =  $\{q: q \in Q, p \vdash^* q\}$

**Example:**

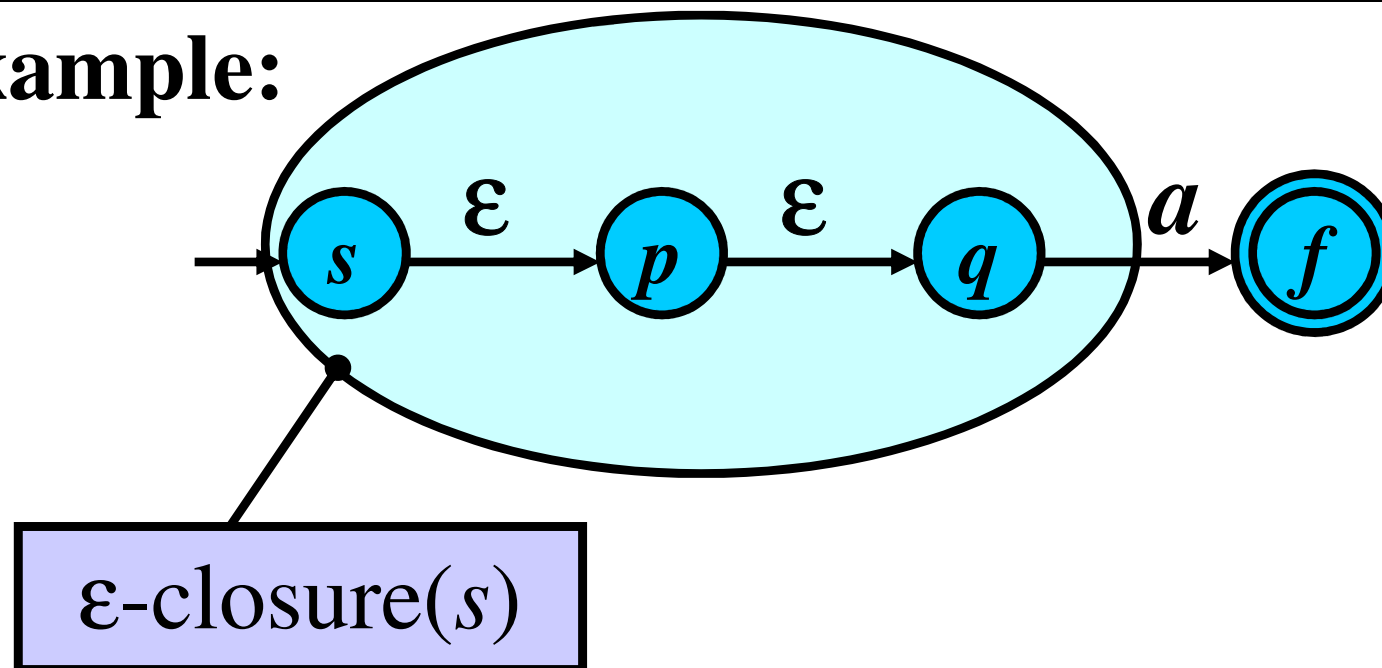


# $\epsilon$ -closure

**Gist:**  $q$  is in  $\epsilon$ -closure( $p$ ) if FA can reach  $q$  from  $p$  without reading.

**Definition:** For every states  $p \in Q$ , we define a set  $\epsilon$ -closure( $p$ ) as  $\epsilon$ -closure( $p$ ) =  $\{q: q \in Q, p \vdash^* q\}$

**Example:**

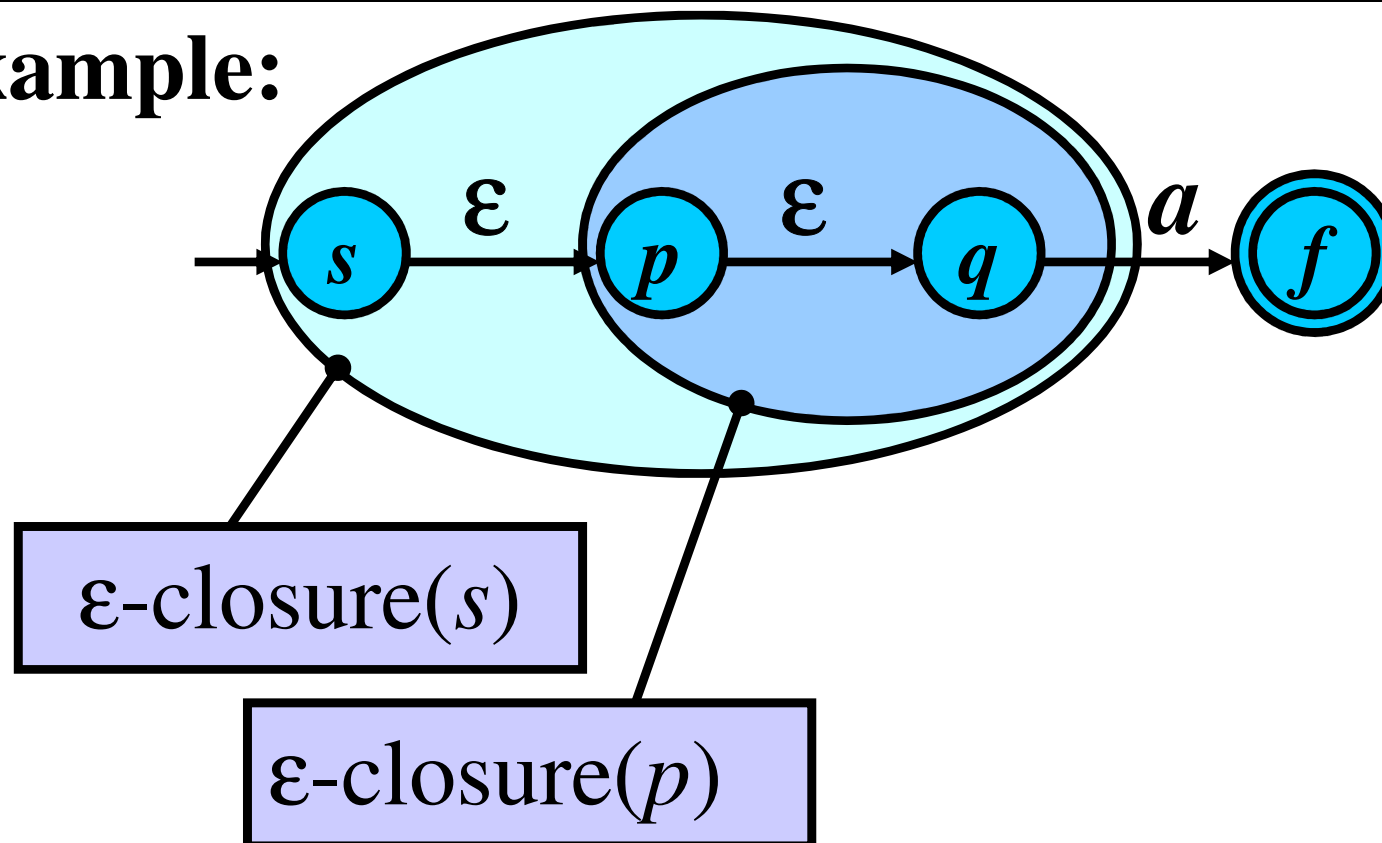


# $\epsilon$ -closure

**Gist:**  $q$  is in  $\epsilon$ -closure( $p$ ) if FA can reach  $q$  from  $p$  without reading.

**Definition:** For every states  $p \in Q$ , we define a set  $\epsilon$ -closure( $p$ ) as  $\epsilon$ -closure( $p$ ) =  $\{q: q \in Q, p \vdash^* q\}$

**Example:**

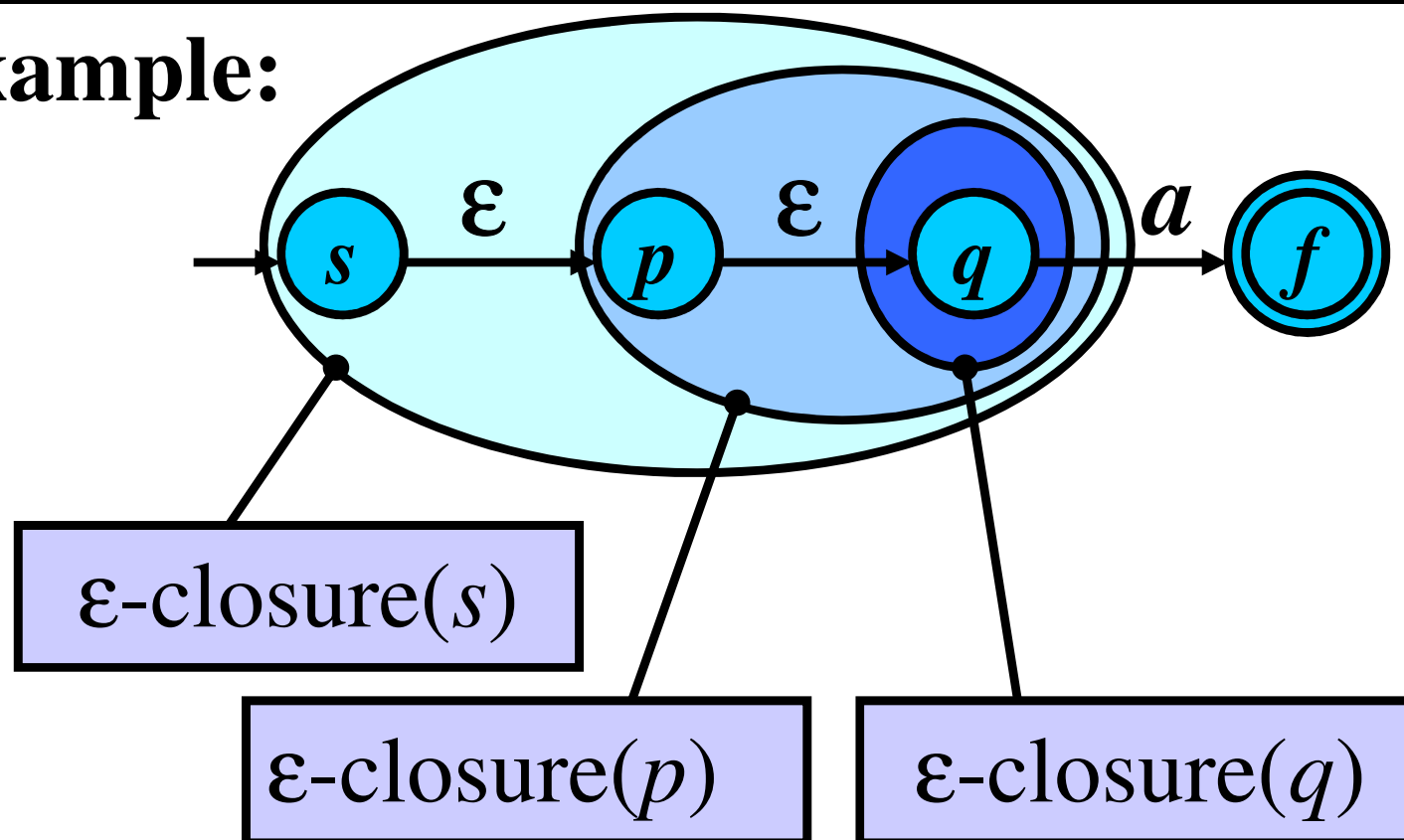


# $\epsilon$ -closure

**Gist:**  $q$  is in  $\epsilon$ -closure( $p$ ) if FA can reach  $q$  from  $p$  without reading.

**Definition:** For every states  $p \in Q$ , we define a set  $\epsilon$ -closure( $p$ ) as  $\epsilon$ -closure( $p$ ) =  $\{q: q \in Q, p \vdash^* q\}$

**Example:**

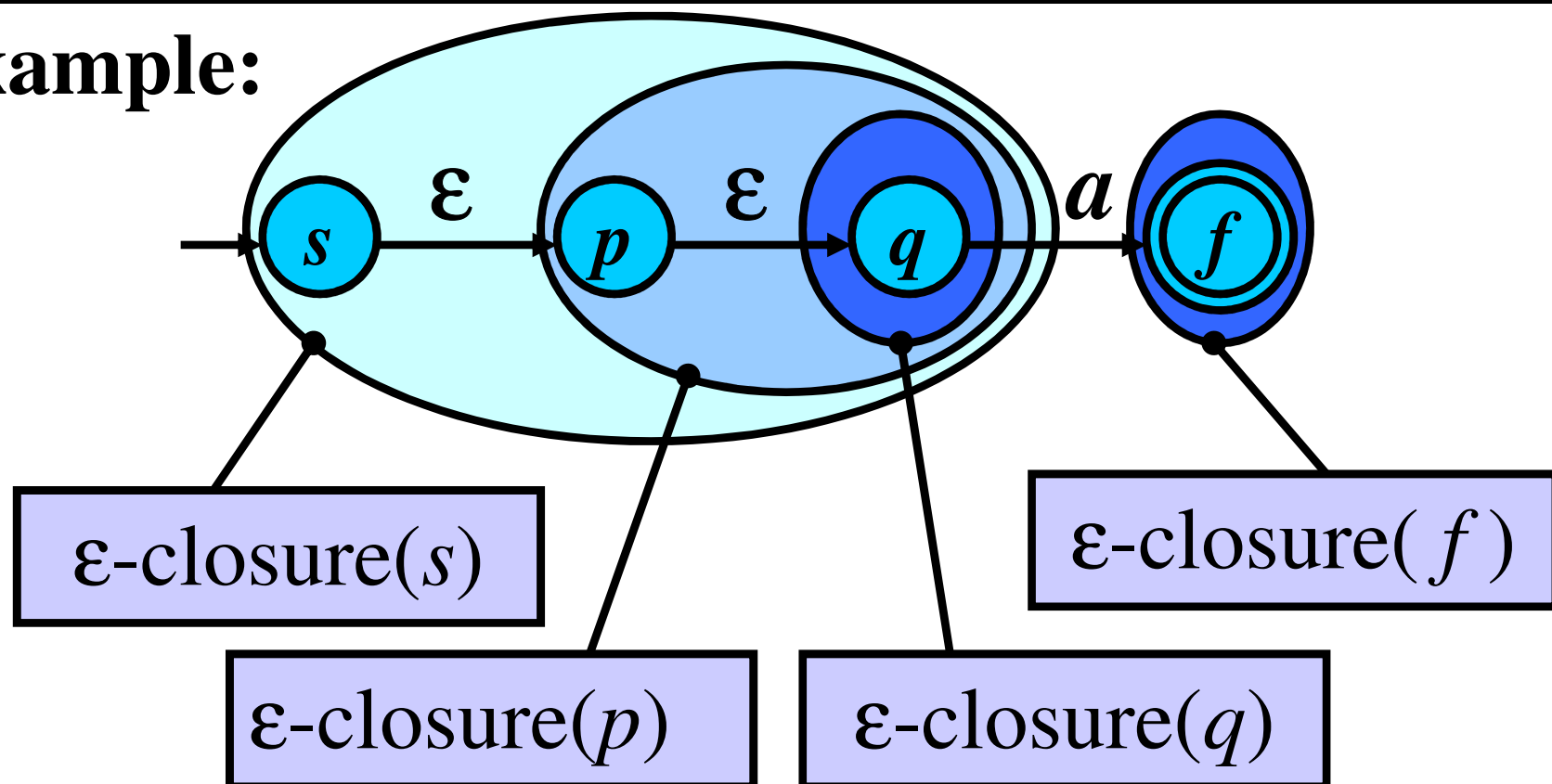


# $\epsilon$ -closure

**Gist:**  $q$  is in  $\epsilon$ -closure( $p$ ) if FA can reach  $q$  from  $p$  without reading.

**Definition:** For every states  $p \in Q$ , we define a set  $\epsilon$ -closure( $p$ ) as  $\epsilon$ -closure( $p$ ) =  $\{q: q \in Q, p \vdash^* q\}$

**Example:**





## Algorithm: $\varepsilon$ -closure

- **Input:**  $M = (Q, \Sigma, R, s, F)$ ;  $p \in Q$
  - **Output:**  $\varepsilon\text{-closure}(p)$
- 

- **Method:**

- $i := 0$ ;  $Q_0 := \{p\}$ ;

- **repeat**

$i := i + 1$ ;

$Q_i := Q_{i-1} \cup \{ p' : p' \in Q, q \rightarrow p' \in R, \\ q \in Q_{i-1} \}$ ;

**until**  $Q_i = Q_{i-1}$ ;

- $\varepsilon\text{-closure}(p) := Q_i$ .

## $\epsilon$ -closure: Example

$M = (Q, \Sigma, R, s, F)$ , where:  $Q = \{s, p, q, f\}$ ,  $\Sigma = \{a\}$ ,  
 $R = \{s \rightarrow p, p \rightarrow q, qa \rightarrow f\}$ ,  $F = \{f\}$

**Task:**  $\epsilon$ -closure( $s$ )

---

## $\epsilon$ -closure: Example

$M = (Q, \Sigma, R, s, F)$ , where:  $Q = \{s, p, q, f\}$ ,  $\Sigma = \{a\}$ ,  
 $R = \{s \rightarrow p, p \rightarrow q, qa \rightarrow f\}$ ,  $F = \{f\}$

**Task:**  $\epsilon$ -closure( $s$ )

---

$Q_0 = \{s\}$

---

## ε-closure: Example

$M = (Q, \Sigma, R, s, F)$ , where:  $Q = \{s, p, q, f\}$ ,  $\Sigma = \{a\}$ ,  
 $R = \{s \rightarrow p, p \rightarrow q, qa \rightarrow f\}$ ,  $F = \{f\}$

**Task:**  $\varepsilon\text{-closure}(s)$

---


$$Q_0 = \{\textcolor{red}{s}\}$$


---

$$1) \quad \textcolor{red}{s} \rightarrow p'; p' \in Q: \quad \textcolor{red}{s} \rightarrow \textcolor{blue}{p}$$

$$Q_1 = \{\textcolor{red}{s}\} \cup \{\textcolor{blue}{p}\} = \{\textcolor{red}{s}, \textcolor{red}{p}\}$$


---

# $\varepsilon$ -closure: Example

$M = (Q, \Sigma, R, s, F)$ , where:  $Q = \{s, p, q, f\}$ ,  $\Sigma = \{a\}$ ,  
 $R = \{s \rightarrow p, p \rightarrow q, qa \rightarrow f\}$ ,  $F = \{f\}$

**Task:**  $\varepsilon$ -closure( $s$ )

---


$$Q_0 = \{s\}$$


---

$$1) \quad s \rightarrow p'; p' \in Q: \quad s \rightarrow p$$

$$Q_1 = \{s\} \cup \{p\} = \{s, p\}$$


---

$$2) \quad \begin{array}{l} s \rightarrow p'; p' \in Q: \quad s \rightarrow p \\ p \rightarrow p'; p' \in Q: \quad p \rightarrow q \end{array}$$

$$Q_2 = \{s, p\} \cup \{p, q\} = \{s, p, q\}$$


---

# ε-closure: Example

$M = (Q, \Sigma, R, s, F)$ , where:  $Q = \{s, p, q, f\}$ ,  $\Sigma = \{a\}$ ,  
 $R = \{s \rightarrow p, p \rightarrow q, qa \rightarrow f\}$ ,  $F = \{f\}$

**Task:**  $\varepsilon$ -closure( $s$ )

---


$$Q_0 = \{s\}$$


---

$$1) \quad s \rightarrow p'; p' \in Q: \quad s \rightarrow p$$

$$Q_1 = \{s\} \cup \{p\} = \{s, p\}$$


---

$$2) \quad \begin{array}{ll} s \rightarrow p'; p' \in Q: & s \rightarrow p \\ p \rightarrow p'; p' \in Q: & p \rightarrow q \end{array}$$

$$Q_2 = \{s, p\} \cup \{p, q\} = \{s, p, q\}$$


---

$$3) \quad \begin{array}{ll} s \rightarrow p'; p' \in Q: & s \rightarrow p \\ p \rightarrow p'; p' \in Q: & p \rightarrow q \\ q \rightarrow p'; p' \in Q: & \text{none} \end{array}$$

$$Q_3 = \{s, p, q\} \cup \{p, q\} = \{s, p, q\} = Q_2 = \varepsilon\text{-closure}(s)$$


---

# Algorithm: FA to $\varepsilon$ -free FA

**Gist: Skip all  $\varepsilon$ -moves**

- 
- **Input:** FA  $M = (Q, \Sigma, R, s, F)$
  - **Output:**  $\varepsilon$ -free FA  $M' = (Q, \Sigma, R', s, F')$
- 

• **Method:**

- $R' := \emptyset$ ;
- **for all**  $p \in Q$  **do**  
$$R' := R' \cup \{ pa \rightarrow q : p'a \rightarrow q \in R, a \in \Sigma, \\ p' \in \varepsilon\text{-closure}(p), q \in Q \};$$
- $F' := \{ p : p \in Q, \varepsilon\text{-closure}(p) \cap F \neq \emptyset \}.$

# Algorithm: FA to $\epsilon$ -free FA

## Gist: Skip all $\epsilon$ -moves

- **Input:** FA  $M = (Q, \Sigma, R, s, F)$
- **Output:**  $\epsilon$ -free FA  $M' = (Q, \Sigma, R', s, F')$

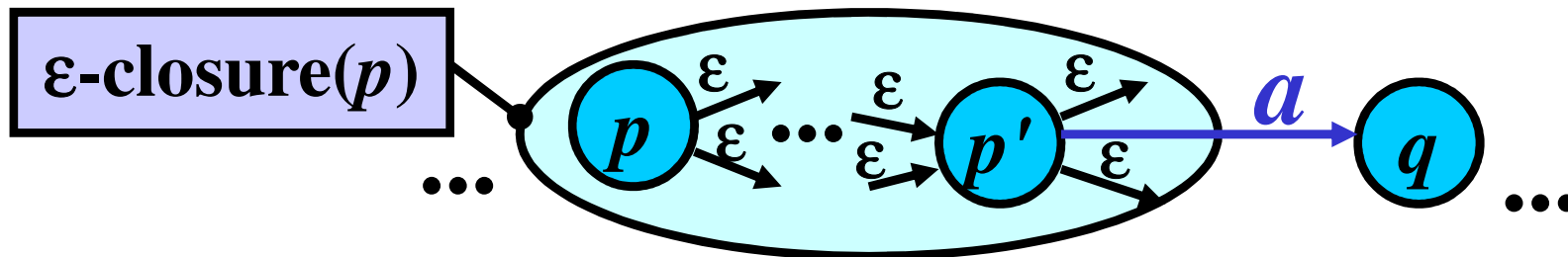
- **Method:**

- $R' := \emptyset;$

- **for all**  $p \in Q$  **do**

$$R' := R' \cup \{ pa \rightarrow q : p'a \rightarrow q \in R, a \in \Sigma, \\ p' \in \epsilon\text{-closure}(p), q \in Q \};$$

- $F' := \{ p : p \in Q, \epsilon\text{-closure}(p) \cap F \neq \emptyset \}.$





# Algorithm: FA to $\epsilon$ -free FA

## Gist: Skip all $\epsilon$ -moves

- **Input:** FA  $M = (Q, \Sigma, R, s, F)$
- **Output:**  $\epsilon$ -free FA  $M' = (Q, \Sigma, R', s, F')$

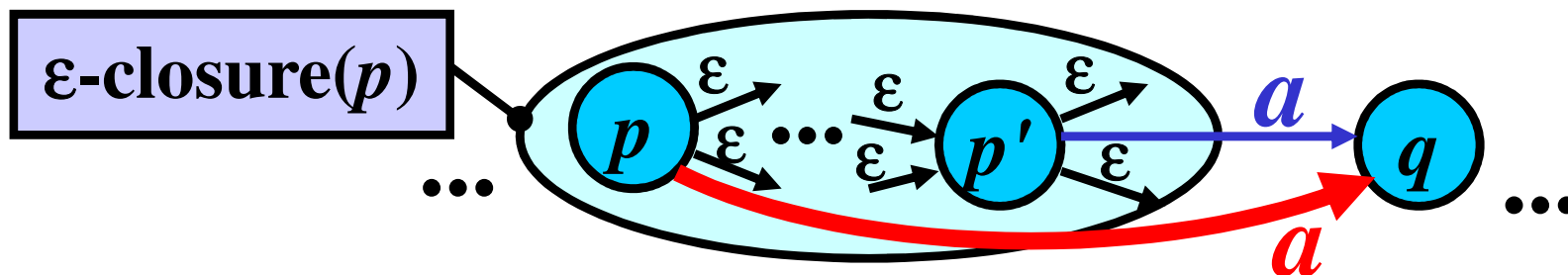
- **Method:**

- $R' := \emptyset$ ;

- **for all**  $p \in Q$  **do**

$$R' := R' \cup \{ pa \rightarrow q : p'a \rightarrow q \in R, a \in \Sigma, \\ p' \in \epsilon\text{-closure}(p), q \in Q \};$$

- $F' := \{ p : p \in Q, \epsilon\text{-closure}(p) \cap F \neq \emptyset \}.$



## FA to $\varepsilon$ -free FA: Example 1/3

$M = (Q, \Sigma, R, s, F)$ , where:

$Q = \{s, q_1, q_2, f\}; \Sigma = \{a, b, c\};$

$R = \{sa \rightarrow s, s \rightarrow q_1, q_1b \rightarrow q_1, q_1b \rightarrow f, s \rightarrow q_2,$   
 $q_2c \rightarrow q_2, q_2c \rightarrow f, fa \rightarrow f\}; F = \{f\}$

---

# FA to $\varepsilon$ -free FA: Example 1/3

$M = (Q, \Sigma, R, s, F)$ , where:

$Q = \{s, q_1, q_2, f\}; \Sigma = \{a, b, c\};$

$R = \{sa \rightarrow s, s \rightarrow q_1, q_1b \rightarrow q_1, q_1b \rightarrow f, s \rightarrow q_2,$   
 $q_2c \rightarrow q_2, q_2c \rightarrow f, fa \rightarrow f\}; F = \{f\}$

---

1) for  $p = s$ :  $\varepsilon\text{-closure}(s) = \{s, q_1, q_2\}$

A.  $sd \rightarrow q', d \in \Sigma, q' \in Q: sa \rightarrow s$

B.  $q_1d \rightarrow q', d \in \Sigma, q' \in Q: q_1b \rightarrow q_1, q_1b \rightarrow f$

C.  $q_2d \rightarrow q', d \in \Sigma, q' \in Q: q_2c \rightarrow q_2, q_2c \rightarrow f$

$R' = \emptyset \cup \{sa \rightarrow s, sb \rightarrow q_1, sb \rightarrow f, sc \rightarrow q_2, sc \rightarrow f\}$

# FA to $\varepsilon$ -free FA: Example 2/3

## FA to $\varepsilon$ -free FA: Example 2/3

2) for  $p = q_1$ :  $\varepsilon\text{-closure}(q_1) = \{q_1\}$

A.  $q_1 d \rightarrow q'$ ;  $d \in \Sigma$ ;  $q' \in Q$ :  $q_1 b \rightarrow q_1$ ,  $q_1 b \rightarrow f$

$R' = R' \cup \{q_1 b \rightarrow q_1, q_1 b \rightarrow f\}$

---

## FA to $\varepsilon$ -free FA: Example 2/3

2) for  $p = q_1$ :  $\varepsilon$ -closure( $q_1$ ) =  $\{q_1\}$

A.  $q_1 d \rightarrow q'$ ;  $d \in \Sigma$ ;  $q' \in Q$ :  $q_1 b \rightarrow q_1$ ,  $q_1 b \rightarrow f$

$R' = R' \cup \{q_1 b \rightarrow q_1, q_1 b \rightarrow f\}$

---

3) for  $p = q_2$ :  $\varepsilon$ -closure( $q_2$ ) =  $\{q_2\}$

A.  $q_2 d \rightarrow q'$ ;  $d \in \Sigma$ ;  $q' \in Q$ :  $q_2 c \rightarrow q_2$ ,  $q_2 c \rightarrow f$

$R' = R' \cup \{q_2 c \rightarrow q_2, q_2 c \rightarrow f\}$

---

## FA to $\varepsilon$ -free FA: Example 2/3

2) for  $p = q_1$ :  $\varepsilon\text{-closure}(q_1) = \{q_1\}$

A.  $q_1 d \rightarrow q'$ ;  $d \in \Sigma$ ;  $q' \in Q$ :  $q_1 b \rightarrow q_1$ ,  $q_1 b \rightarrow f$

$R' = R' \cup \{q_1 b \rightarrow q_1, q_1 b \rightarrow f\}$

---

3) for  $p = q_2$ :  $\varepsilon\text{-closure}(q_2) = \{q_2\}$

A.  $q_2 d \rightarrow q'$ ;  $d \in \Sigma$ ;  $q' \in Q$ :  $q_2 c \rightarrow q_2$ ,  $q_2 c \rightarrow f$

$R' = R' \cup \{q_2 c \rightarrow q_2, q_2 c \rightarrow f\}$

---

4) for  $p = f$ :  $\varepsilon\text{-closure}(f) = \{f\}$

A.  $f d \rightarrow q'$ ;  $d \in \Sigma$ ;  $q' \in Q$ :  $f a \rightarrow f$

$R' = R' \cup \{f a \rightarrow f\}$

---

## FA to $\varepsilon$ -free FA: Example 2/3

2) for  $p = q_1$ :  $\varepsilon\text{-closure}(q_1) = \{q_1\}$

A.  $q_1 d \rightarrow q'$ ;  $d \in \Sigma$ ;  $q' \in Q$ :  $q_1 b \rightarrow q_1$ ,  $q_1 b \rightarrow f$

$R' = R' \cup \{q_1 b \rightarrow q_1, q_1 b \rightarrow f\}$

---

3) for  $p = q_2$ :  $\varepsilon\text{-closure}(q_2) = \{q_2\}$

A.  $q_2 d \rightarrow q'$ ;  $d \in \Sigma$ ;  $q' \in Q$ :  $q_2 c \rightarrow q_2$ ,  $q_2 c \rightarrow f$

$R' = R' \cup \{q_2 c \rightarrow q_2, q_2 c \rightarrow f\}$

---

4) for  $p = f$ :  $\varepsilon\text{-closure}(f) = \{f\}$

A.  $f d \rightarrow q'$ ;  $d \in \Sigma$ ;  $q' \in Q$ :  $f a \rightarrow f$

$R' = R' \cup \{f a \rightarrow f\}$

---

$R' = \{s a \rightarrow s, s b \rightarrow q_1, s b \rightarrow f, s c \rightarrow q_2, s c \rightarrow f,$   
 $q_1 b \rightarrow q_1, q_1 b \rightarrow f, q_2 c \rightarrow q_2, q_2 c \rightarrow f, f a \rightarrow f\}$



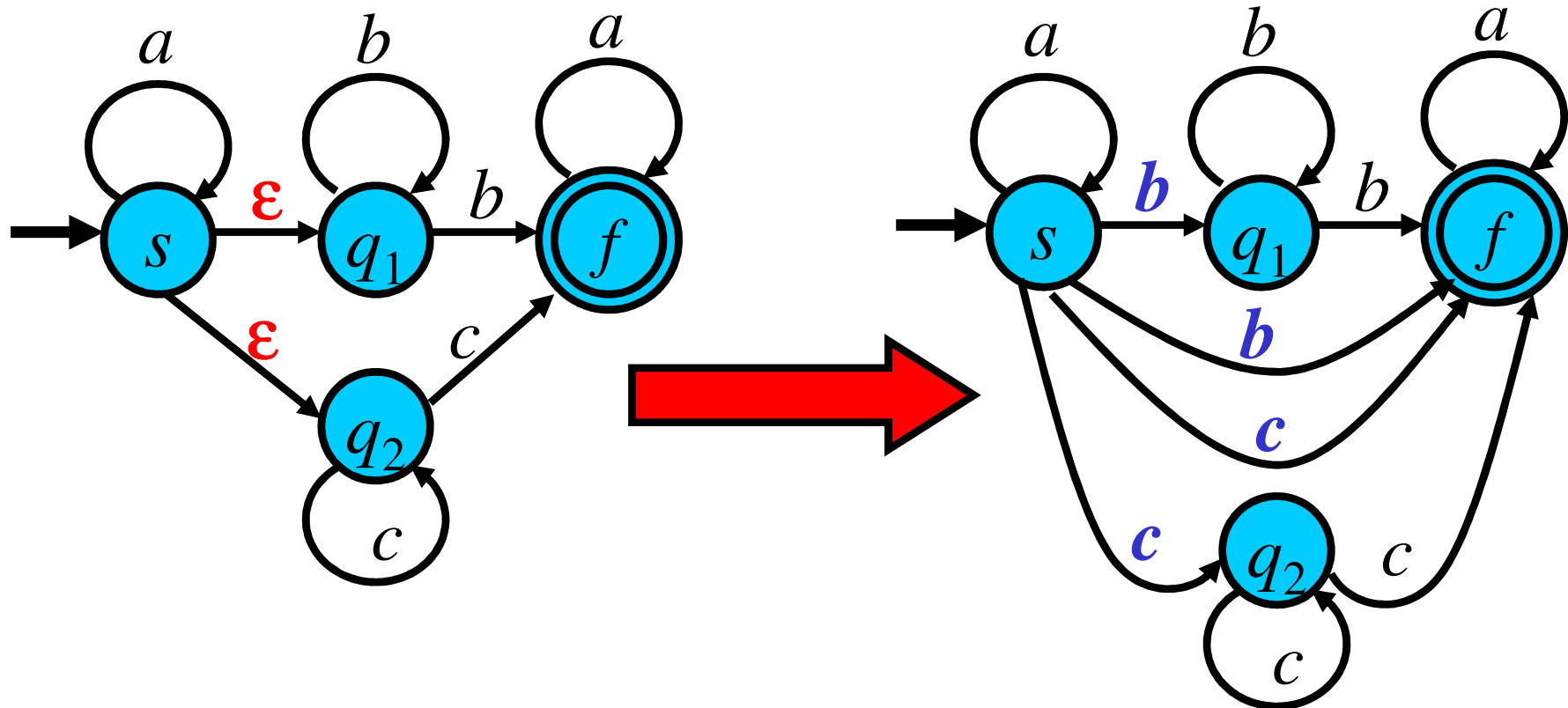
# FA to $\varepsilon$ -free FA: Example 3/3

$$\begin{array}{lcl}
 \varepsilon\text{-closure}(s) \cap F = \{s, q_1, q_2\} \cap \{f\} = \emptyset \\
 \varepsilon\text{-closure}(q_1) \cap F = \{q_1\} \cap \{f\} = \emptyset \\
 \varepsilon\text{-closure}(q_2) \cap F = \{q_2\} \cap \{f\} = \emptyset \\
 \varepsilon\text{-closure}(f) \cap F = \{f\} \cap \{f\} = \{f\} \neq \emptyset
 \end{array}
 \left. \vphantom{\begin{array}{l} \varepsilon\text{-closure}(s) \\ \varepsilon\text{-closure}(q_1) \\ \varepsilon\text{-closure}(q_2) \end{array}} \right\} F' = \{f\}$$


---

# FA to $\epsilon$ -free FA: Example 3/3

$$\begin{array}{lcl}
 \epsilon\text{-closure}(s) \cap F = \{s, q_1, q_2\} \cap \{f\} = \emptyset \\
 \epsilon\text{-closure}(q_1) \cap F = \{q_1\} \cap \{f\} = \emptyset \\
 \epsilon\text{-closure}(q_2) \cap F = \{q_2\} \cap \{f\} = \emptyset \\
 \epsilon\text{-closure}(f) \cap F = \{f\} \cap \{f\} = \{f\} \neq \emptyset
 \end{array}
 \left. \vphantom{\begin{array}{l} \epsilon\text{-closure}(s) \\ \epsilon\text{-closure}(q_1) \\ \epsilon\text{-closure}(q_2) \\ \epsilon\text{-closure}(f) \end{array}} \right\} F' = \{f\}$$



## Algorithm: $\epsilon$ -free FA to DFA 1/2

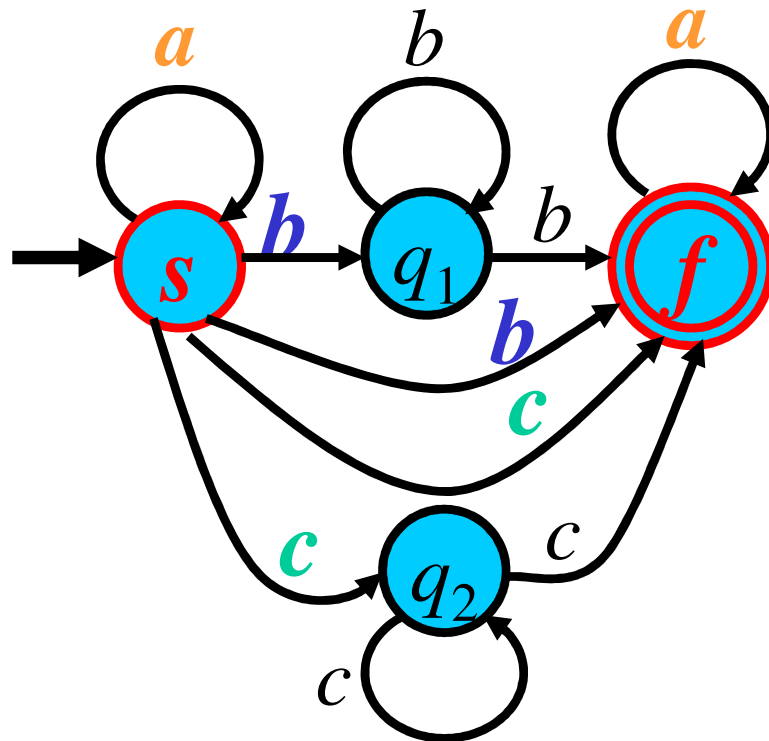
**Gist:** In DFA, make states from all subsets of states in  $\epsilon$ -free FA and move between them so that all possible states of  $\epsilon$ -free FA are simultaneously simulated.

---

# Algorithm: $\epsilon$ -free FA to DFA 1/2

**Gist:** In DFA, make states from all subsets of states in  $\epsilon$ -free FA and move between them so that all possible states of  $\epsilon$ -free FA are simultaneously simulated.

**Illustration:**

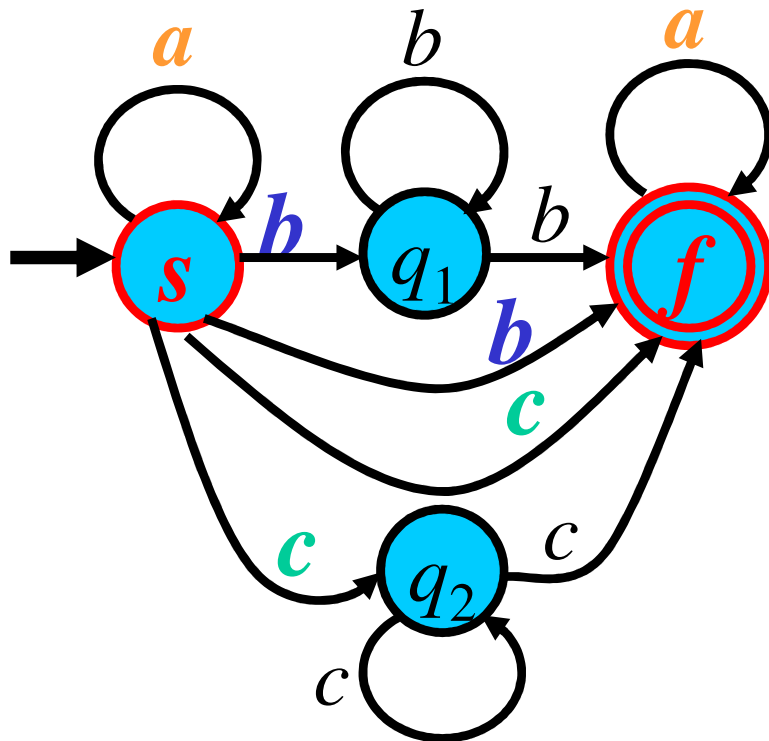


$$Q_{DFA} = \{\{s\}, \{q_1\}, \{q_2\}, \{f\}, \{s, q_1\}, \{s, q_2\}, \{s, f\}, \{q_1, q_2\}, \{q_1, f\}, \{q_2, f\}, \{s, q_1, q_2\}, \{s, q_1, f\}, \{s, q_2, f\}, \{q_1, q_2, f\}, \{s, q_1, q_2, f\}\}$$

# Algorithm: $\epsilon$ -free FA to DFA 1/2

**Gist:** In DFA, make states from all subsets of states in  $\epsilon$ -free FA and move between them so that all possible states of  $\epsilon$ -free FA are simultaneously simulated.

**Illustration:**



$$Q_{DFA} = \{\{s\}, \{q_1\}, \{q_2\}, \{f\}, \{s, q_1\}, \{s, q_2\}, \{s, f\}, \{q_1, q_2\}, \{q_1, f\}, \{q_2, f\}, \{s, q_1, q_2\}, \{s, q_1, f\}, \{s, q_2, f\}, \{q_1, q_2, f\}, \{s, q_1, q_2, f\}\}$$

For state  $\{s\}$ : ...

⋮

For state  $\{s, f\}$ :  $\{s, f\}$

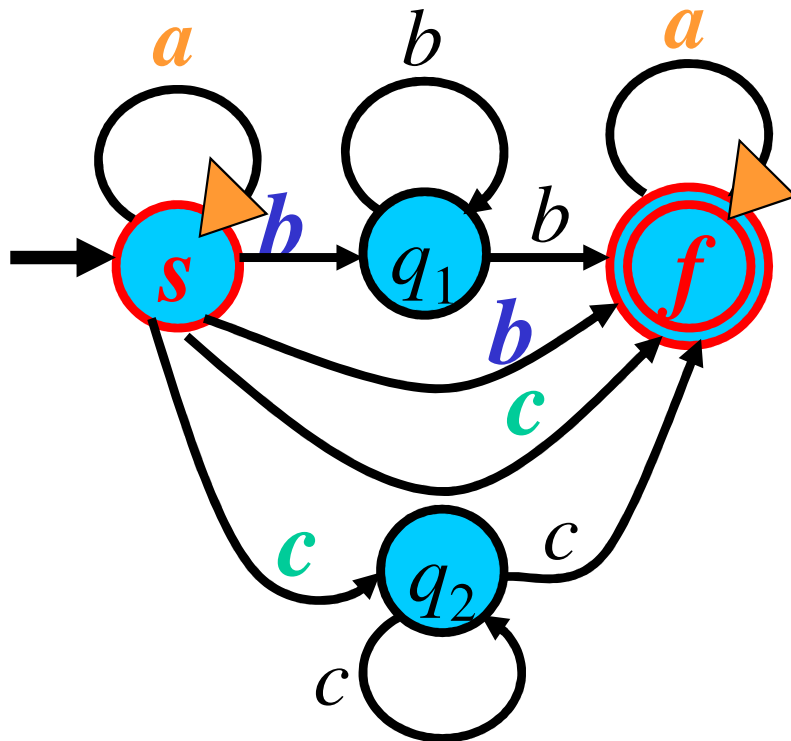
⋮

For state  $\{s, q_1, q_2, f\}$ : ...

# Algorithm: $\epsilon$ -free FA to DFA 1/2

**Gist:** In DFA, make states from all subsets of states in  $\epsilon$ -free FA and move between them so that all possible states of  $\epsilon$ -free FA are simultaneously simulated.

**Illustration:**



$Q_{DFA} = \{\{s\}, \{q_1\}, \{q_2\}, \{f\}, \{s, q_1\}, \{s, q_2\}, \{s, f\}, \{q_1, q_2\}, \{q_1, f\}, \{q_2, f\}, \{s, q_1, q_2\}, \{s, q_1, f\}, \{s, q_2, f\}, \{q_1, q_2, f\}, \{s, q_1, q_2, f\}\}$

For state  $\{s\}$ : ...

⋮

For state  $\{s, f\}$ :

⋮

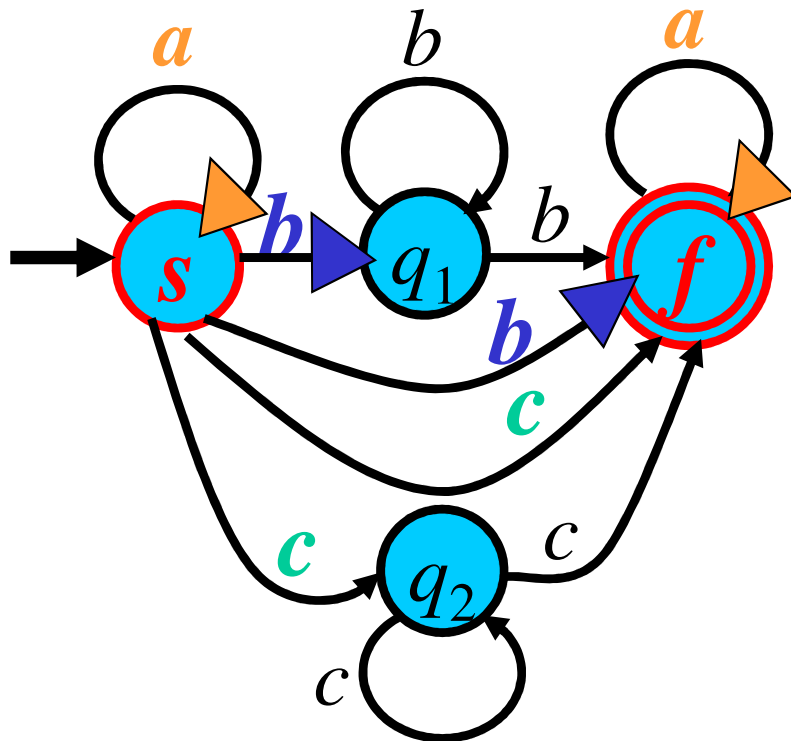
For state  $\{s, q_1, q_2, f\}$ : ...



# Algorithm: $\epsilon$ -free FA to DFA 1/2

**Gist:** In DFA, make states from all subsets of states in  $\epsilon$ -free FA and move between them so that all possible states of  $\epsilon$ -free FA are simultaneously simulated.

**Illustration:**



$Q_{DFA} = \{\{s\}, \{q_1\}, \{q_2\}, \{f\}, \{s, q_1\}, \{s, q_2\}, \{s, f\}, \{q_1, q_2\}, \{q_1, f\}, \{q_2, f\}, \{s, q_1, q_2\}, \{s, q_1, f\}, \{s, q_2, f\}, \{q_1, q_2, f\}, \{s, q_1, q_2, f\}\}$

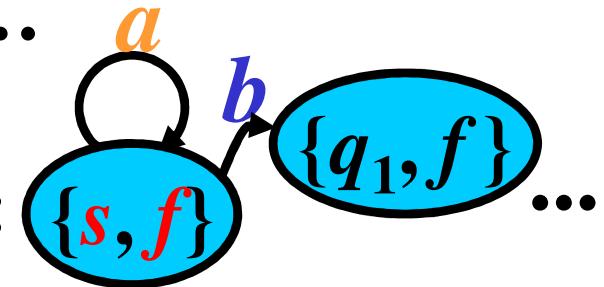
For state  $\{s\}$ : ...

⋮

For state  $\{s, f\}$ :

⋮

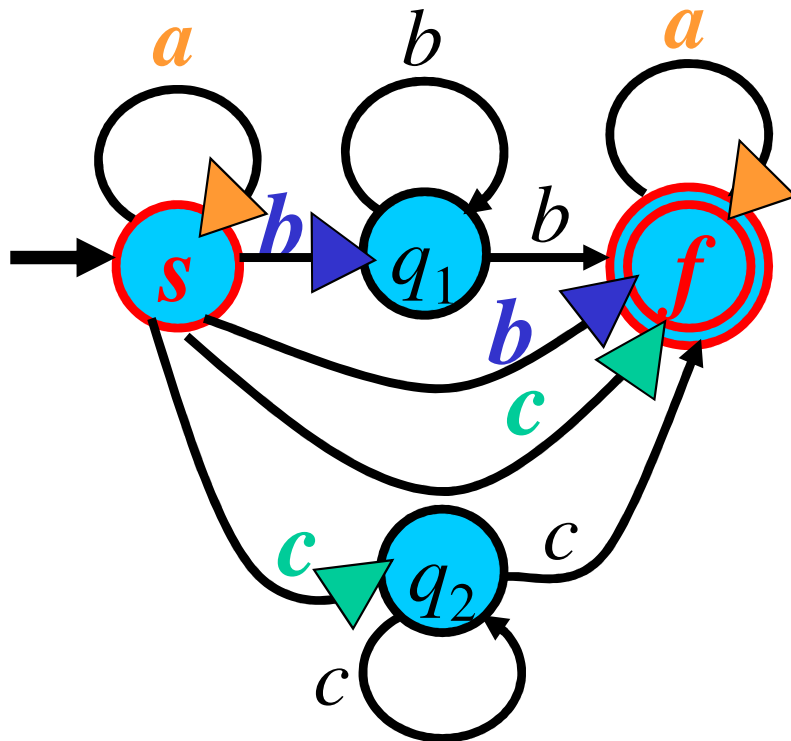
For state  $\{s, q_1, q_2, f\}$ : ...



# Algorithm: $\epsilon$ -free FA to DFA 1/2

**Gist:** In DFA, make states from all subsets of states in  $\epsilon$ -free FA and move between them so that all possible states of  $\epsilon$ -free FA are simultaneously simulated.

**Illustration:**



$$Q_{DFA} = \{\{s\}, \{q_1\}, \{q_2\}, \{f\}, \{s, q_1\}, \{s, q_2\}, \{s, f\}, \{q_1, q_2\}, \{q_1, f\}, \{q_2, f\}, \{s, q_1, q_2\}, \{s, q_1, f\}, \{s, q_2, f\}, \{q_1, q_2, f\}, \{s, q_1, q_2, f\}\}$$

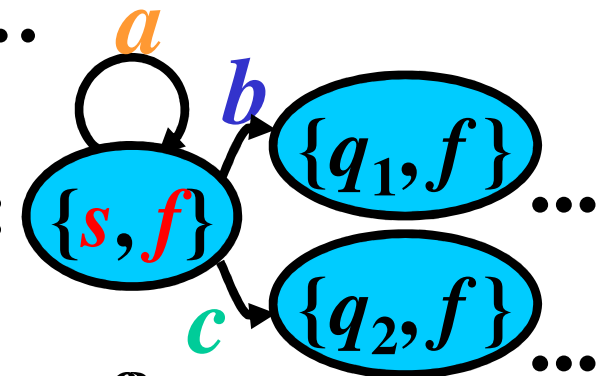
For state  $\{s\}$ : ...

⋮

For state  $\{s, f\}$ :

⋮

For state  $\{s, q_1, q_2, f\}$ : ...





# Algorithm: $\varepsilon$ -free FA to DFA 2/2

- **Input:**  $\varepsilon$ -free FA:  $M = (Q, \Sigma, R, s, F)$
  - **Output:** DFA:  $M_d = (Q_d, \Sigma, R_d, s_d, F_d)$
- 
- **Method:**
    - $Q_d := \{Q' : Q' \subseteq Q, Q' \neq \emptyset\}; R_d := \emptyset;$
    - **for each**  $Q' \in Q_d$ , **and**  $a \in \Sigma$  **do begin**
      - $Q'' := \{q : p \in Q', pa \rightarrow q \in R\};$
      - if**  $Q'' \neq \emptyset$  **then**  $R_d := R_d \cup \{Q'a \rightarrow Q''\};$
    - end**
    - $s_d := \{s\};$
    - $F_d := \{F' : F' \in Q_d, F' \cap F \neq \emptyset\}.$

# $\epsilon$ -free FA to DFA: Example 1/5

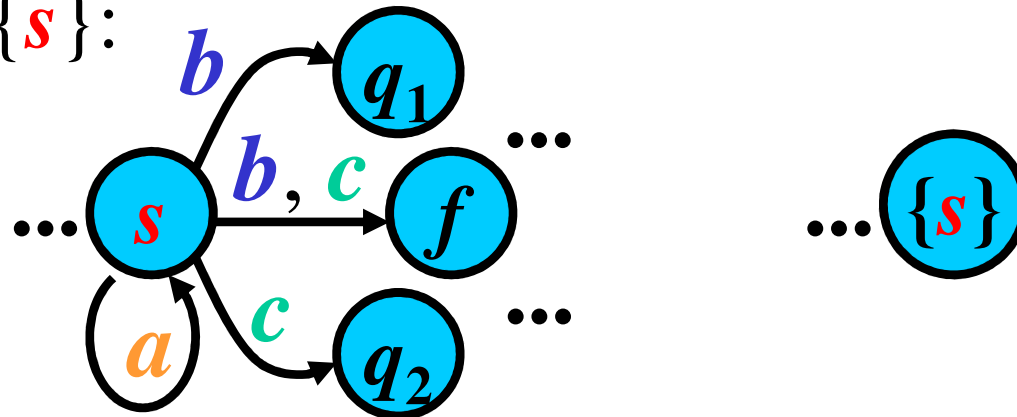
$M = (Q, \Sigma, R, s, F)$ , where:

$Q = \{s, q_1, q_2, f\}; \Sigma = \{a, b, c\}; F = \{f\}$

$R = \{sa \rightarrow s, sb \rightarrow q_1, sb \rightarrow f, sc \rightarrow q_2, sc \rightarrow f,$   
 $q_1b \rightarrow q_1, q_1b \rightarrow f, q_2c \rightarrow q_2, q_2c \rightarrow f, fa \rightarrow f\};$

$Q_d = \{\{s\}, \{s, q_1\}, \{s, q_1, q_2\}, \{s, q_1, f\}, \{s, q_1, q_2, f\}, \{s, q_2\}, \{s, q_2, f\},$   
 $\{s, f\}, \{q_1\}, \{q_1, q_2\}, \{q_1, f\}, \{q_1, q_2, f\}, \{q_2\}, \{q_2, f\}, \{f\}\}$

for  $Q' = \{s\}$ :



# $\epsilon$ -free FA to DFA: Example 1/5

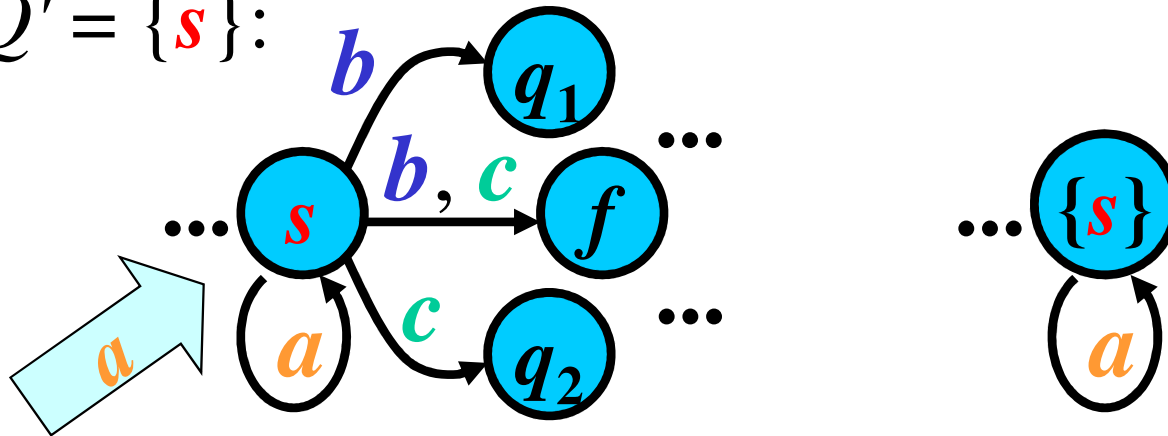
$M = (Q, \Sigma, R, s, F)$ , where:

$Q = \{s, q_1, q_2, f\}; \Sigma = \{a, b, c\}; F = \{f\}$

$R = \{sa \rightarrow s, sb \rightarrow q_1, sb \rightarrow f, sc \rightarrow q_2, sc \rightarrow f, \\ q_1b \rightarrow q_1, q_1b \rightarrow f, q_2c \rightarrow q_2, q_2c \rightarrow f, fa \rightarrow f\};$

$Q_d = \{\{s\}, \{s, q_1\}, \{s, q_1, q_2\}, \{s, q_1, f\}, \{s, q_1, q_2, f\}, \{s, q_2\}, \{s, q_2, f\}, \\ \{s, f\}, \{q_1\}, \{q_1, q_2\}, \{q_1, f\}, \{q_1, q_2, f\}, \{q_2\}, \{q_2, f\}, \{f\}\}$

for  $Q' = \{s\}$ :



# $\epsilon$ -free FA to DFA: Example 1/5

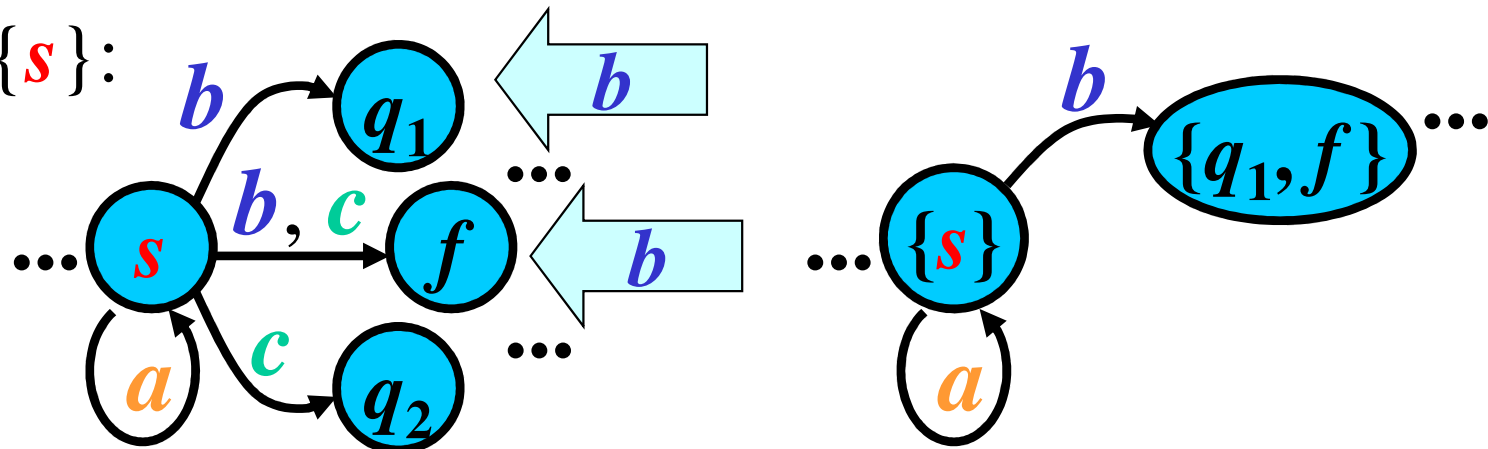
$M = (Q, \Sigma, R, s, F)$ , where:

$Q = \{s, q_1, q_2, f\}; \Sigma = \{a, b, c\}; F = \{f\}$

$R = \{sa \rightarrow s, sb \rightarrow q_1, sb \rightarrow f, sc \rightarrow q_2, sc \rightarrow f,$   
 $q_1b \rightarrow q_1, q_1b \rightarrow f, q_2c \rightarrow q_2, q_2c \rightarrow f, fa \rightarrow f\};$

$Q_d = \{\{s\}, \{s, q_1\}, \{s, q_1, q_2\}, \{s, q_1, f\}, \{s, q_1, q_2, f\}, \{s, q_2\}, \{s, q_2, f\},$   
 $\{s, f\}, \{q_1\}, \{q_1, q_2\}, \{q_1, f\}, \{q_1, q_2, f\}, \{q_2\}, \{q_2, f\}, \{f\}\}$

for  $Q' = \{s\}$ :



# $\varepsilon$ -free FA to DFA: Example 1/5

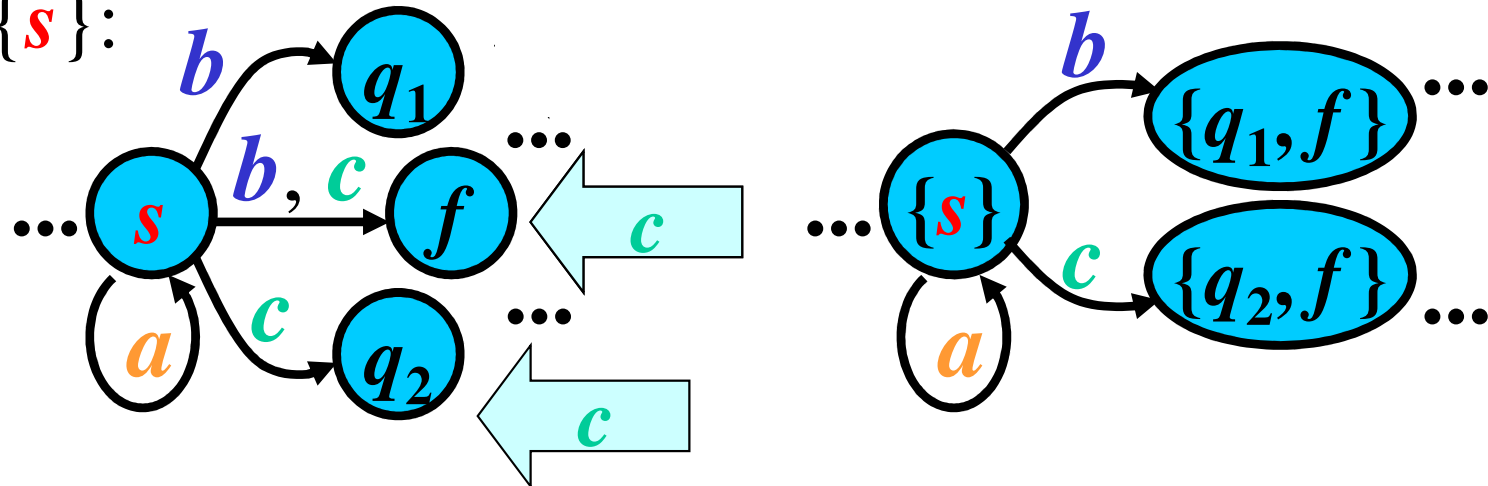
$M = (Q, \Sigma, R, s, F)$ , where:

$Q = \{s, q_1, q_2, f\}; \Sigma = \{a, b, c\}; F = \{f\}$

$R = \{sa \rightarrow s, sb \rightarrow q_1, sb \rightarrow f, sc \rightarrow q_2, sc \rightarrow f,$   
 $q_1b \rightarrow q_1, q_1b \rightarrow f, q_2c \rightarrow q_2, q_2c \rightarrow f, fa \rightarrow f\};$

$Q_d = \{\{s\}, \{s, q_1\}, \{s, q_1, q_2\}, \{s, q_1, f\}, \{s, q_1, q_2, f\}, \{s, q_2\}, \{s, q_2, f\},$   
 $\{s, f\}, \{q_1\}, \{q_1, q_2\}, \{q_1, f\}, \{q_1, q_2, f\}, \{q_2\}, \{q_2, f\}, \{f\}\}$

for  $Q' = \{s\}$ :



# $\epsilon$ -free FA to DFA: Example 1/5

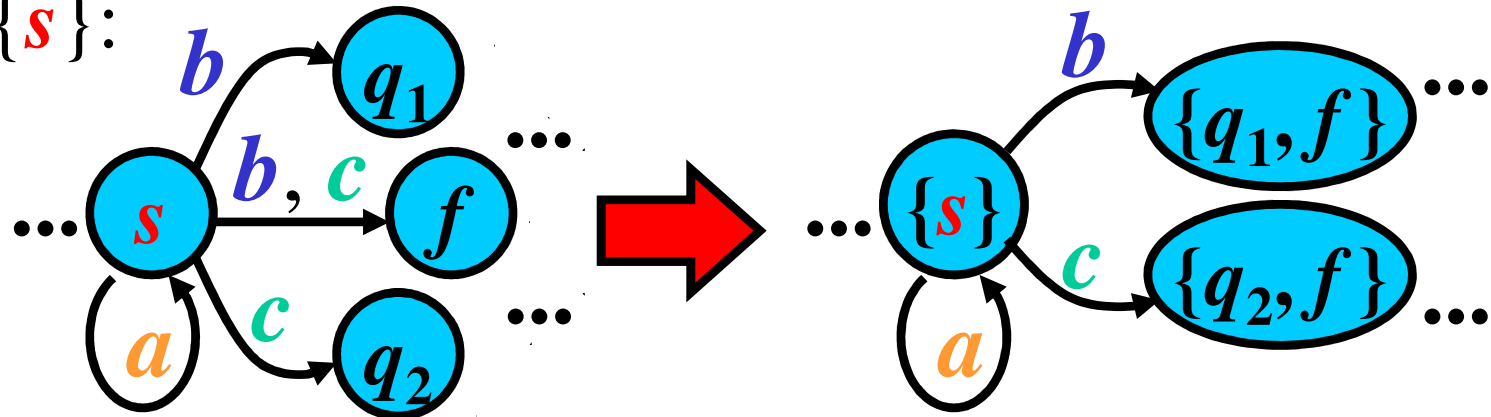
$M = (Q, \Sigma, R, s, F)$ , where:

$Q = \{s, q_1, q_2, f\}; \Sigma = \{a, b, c\}; F = \{f\}$

$R = \{sa \rightarrow s, sb \rightarrow q_1, sb \rightarrow f, sc \rightarrow q_2, sc \rightarrow f,$   
 $q_1b \rightarrow q_1, q_1b \rightarrow f, q_2c \rightarrow q_2, q_2c \rightarrow f, fa \rightarrow f\};$

$Q_d = \{\{s\}, \{s, q_1\}, \{s, q_1, q_2\}, \{s, q_1, f\}, \{s, q_1, q_2, f\}, \{s, q_2\}, \{s, q_2, f\},$   
 $\{s, f\}, \{q_1\}, \{q_1, q_2\}, \{q_1, f\}, \{q_1, q_2, f\}, \{q_2\}, \{q_2, f\}, \{f\}\}$

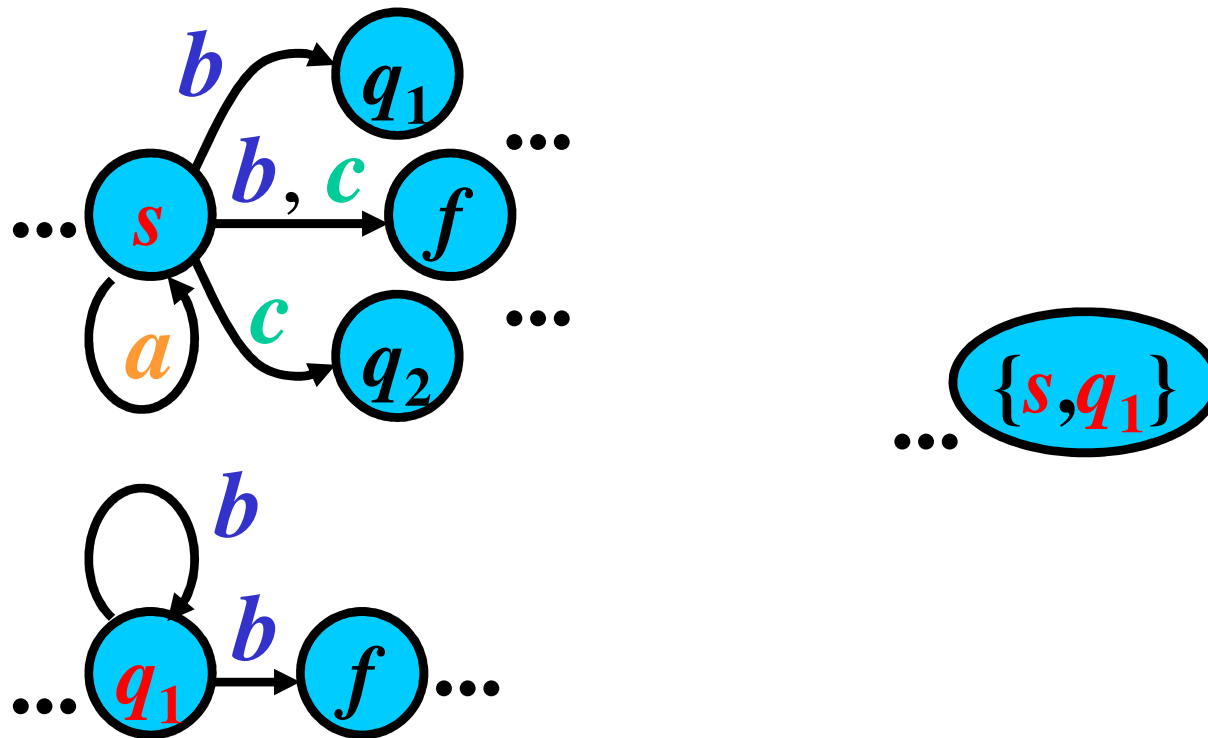
for  $Q' = \{s\}$ :



$R_d = \emptyset \cup \{\{s\}a \rightarrow \{s\}, \{s\}b \rightarrow \{q_1, f\}, \{s\}c \rightarrow \{q_2, f\}\}$

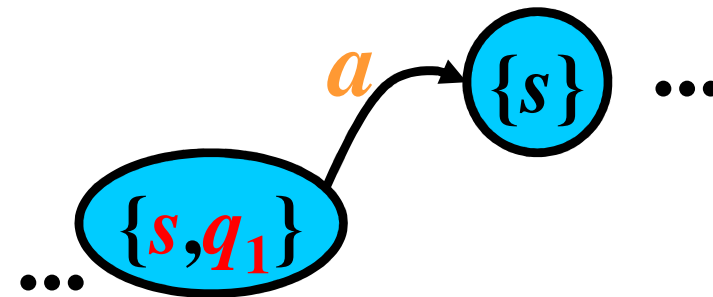
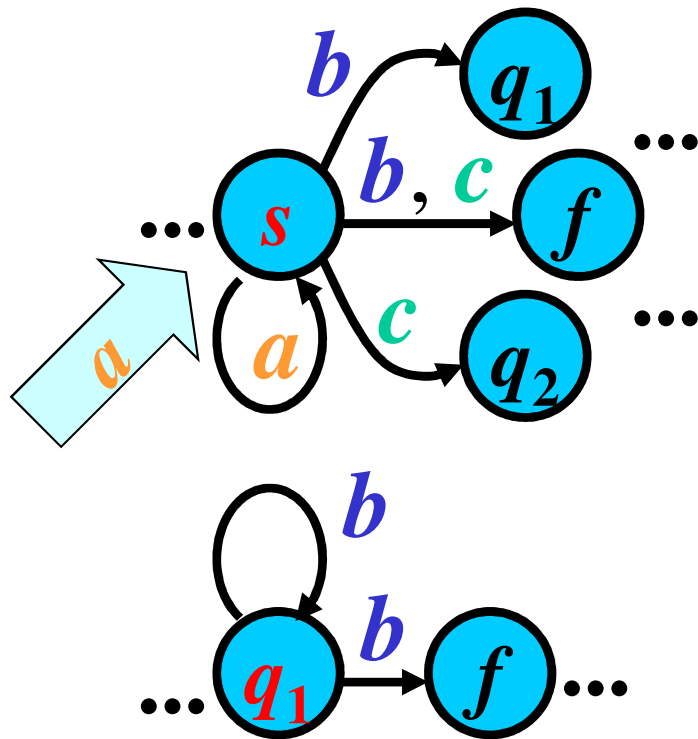
# $\epsilon$ -free FA to DFA: Example 2/5

for  $Q' = \{s, q_1\}$ :



# $\epsilon$ -free FA to DFA: Example 2/5

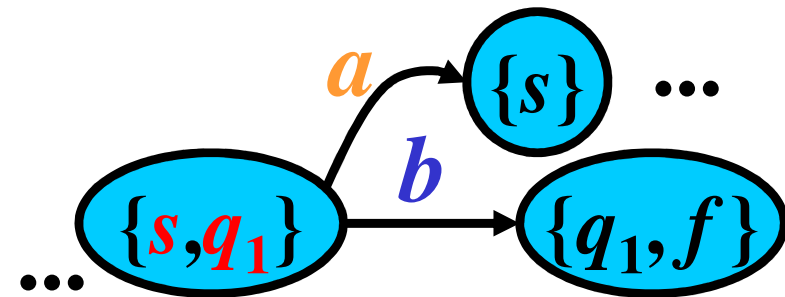
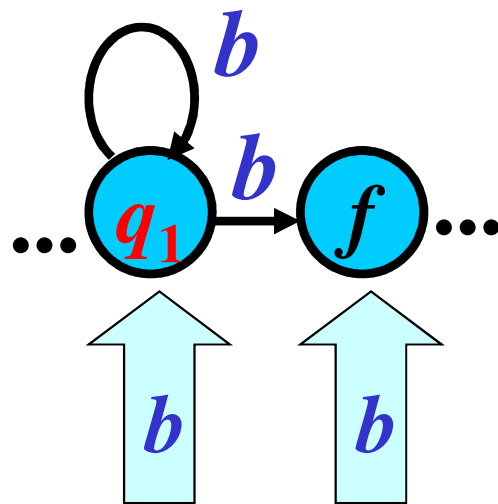
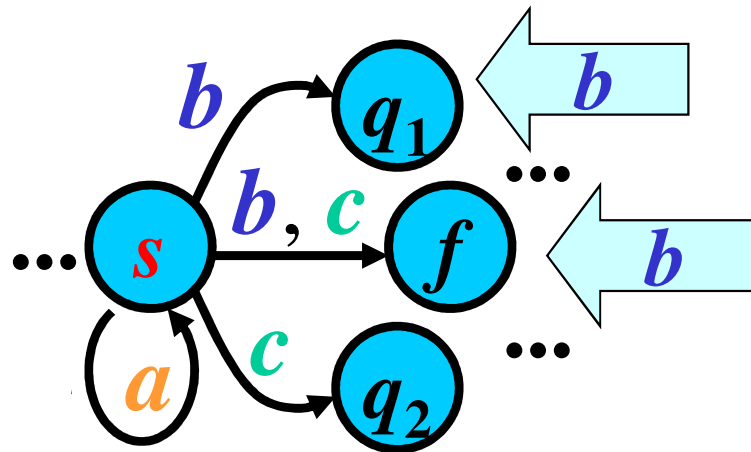
for  $Q' = \{s, q_1\}$ :





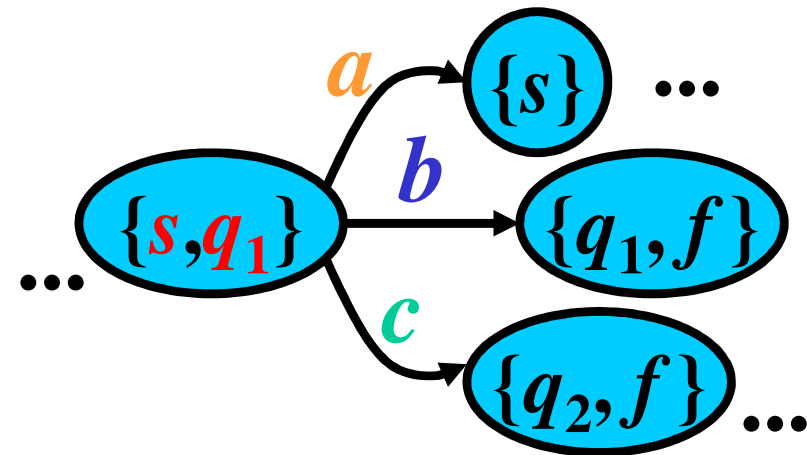
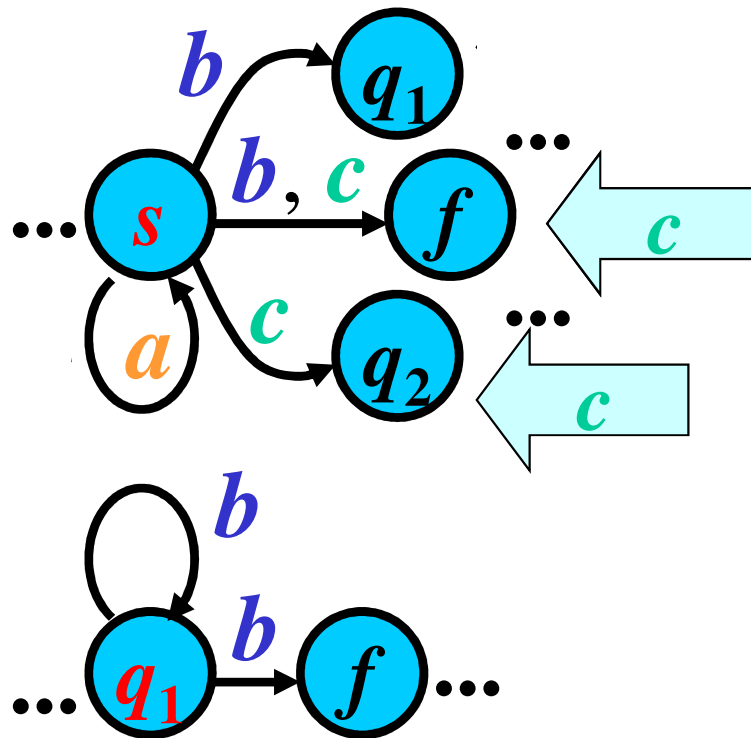
# $\epsilon$ -free FA to DFA: Example 2/5

for  $Q' = \{s, q_1\}$ :



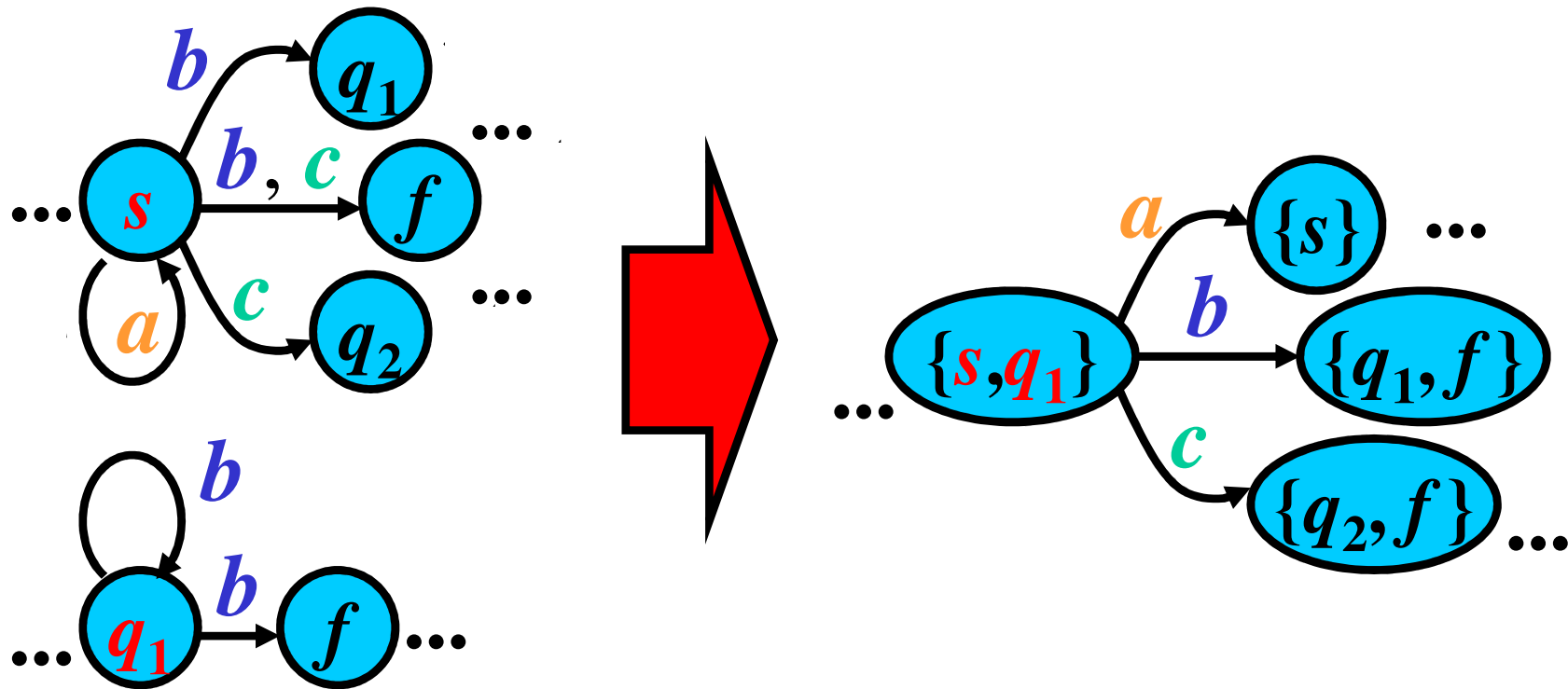
# $\epsilon$ -free FA to DFA: Example 2/5

for  $Q' = \{s, q_1\}$ :



# $\varepsilon$ -free FA to DFA: Example 2/5

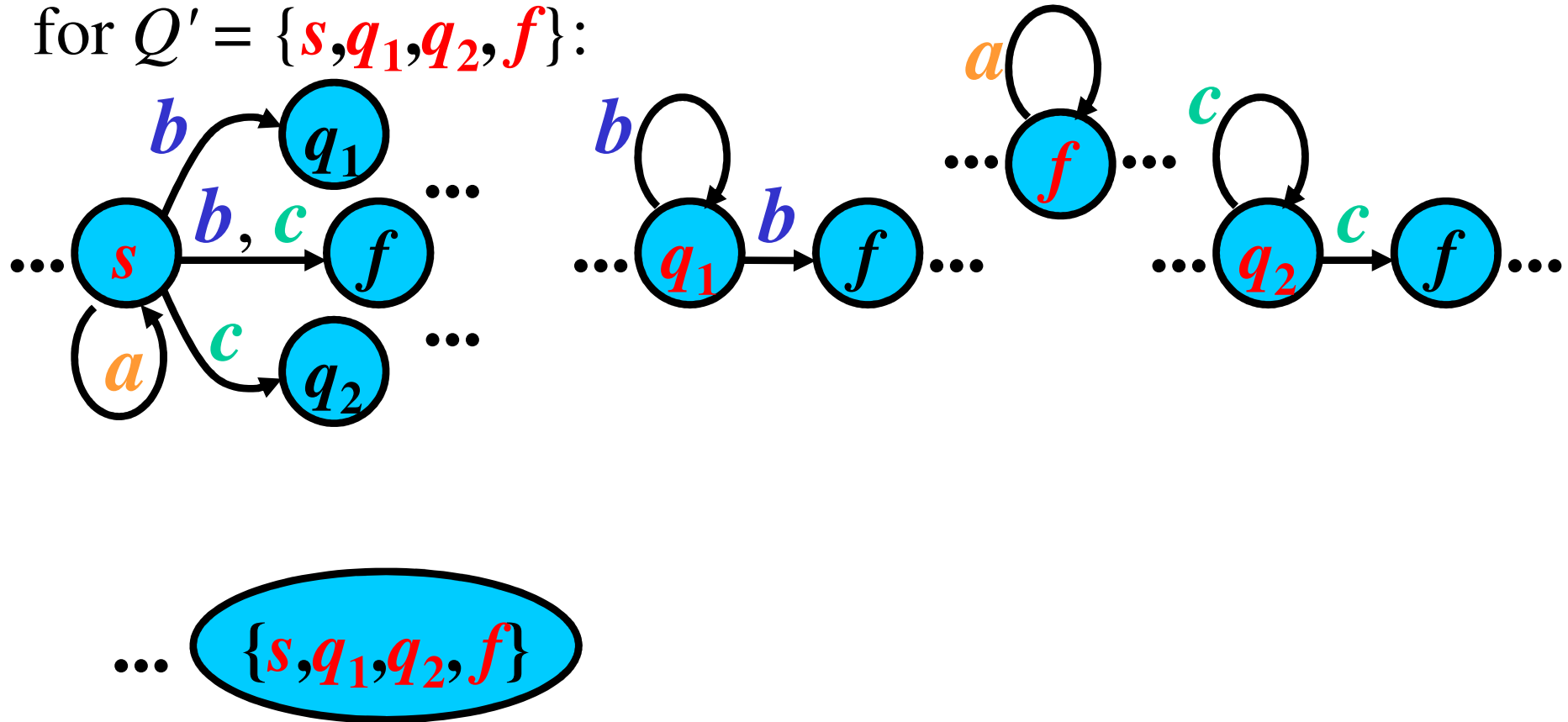
for  $Q' = \{s, q_1\}$ :



$$R_d = R_d \cup \{ \{s, q_1\} a \rightarrow \{s\}, \{s, q_1\} b \rightarrow \{q_1, f\}, \{s, q_1\} c \rightarrow \{q_2, f\} \}$$

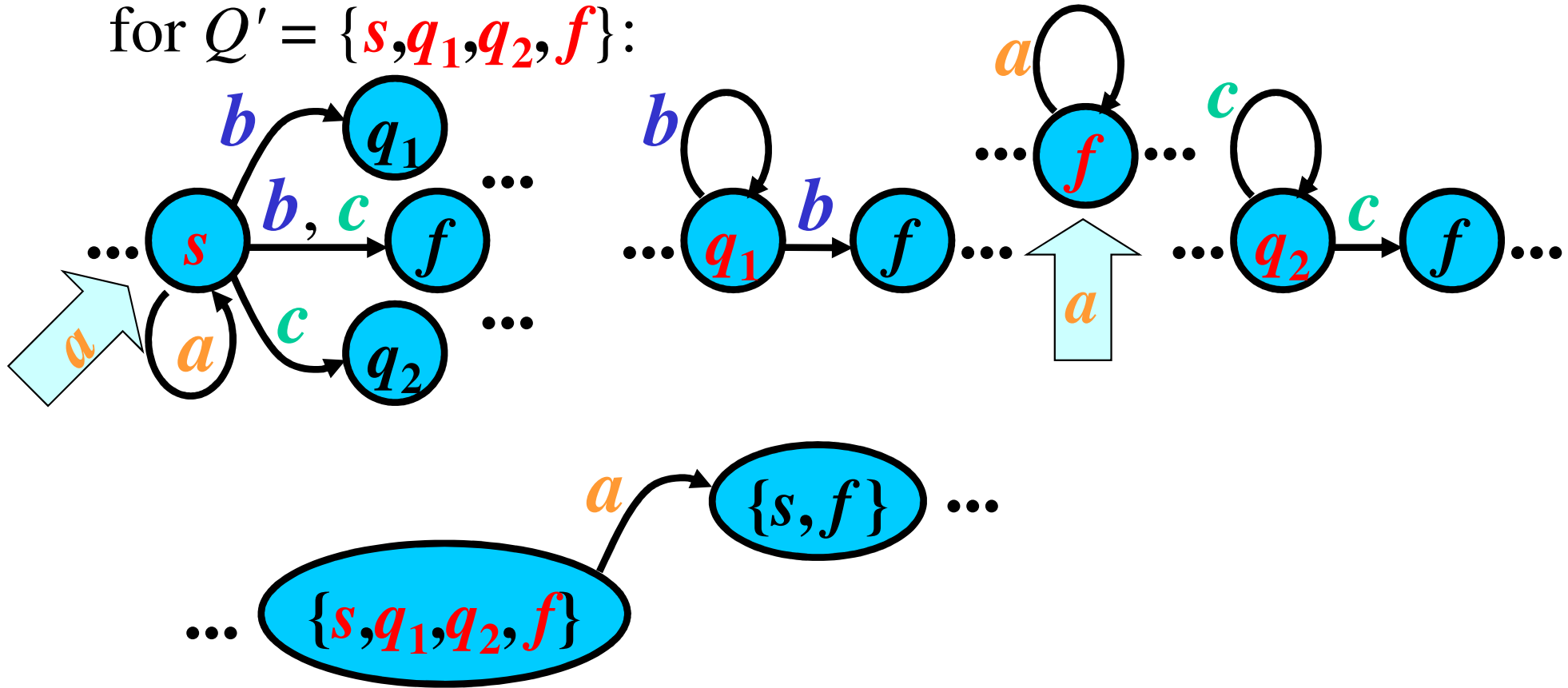
# $\epsilon$ -free FA to DFA: Example 3/5

for  $Q' = \{s, q_1, q_2, f\}$ :



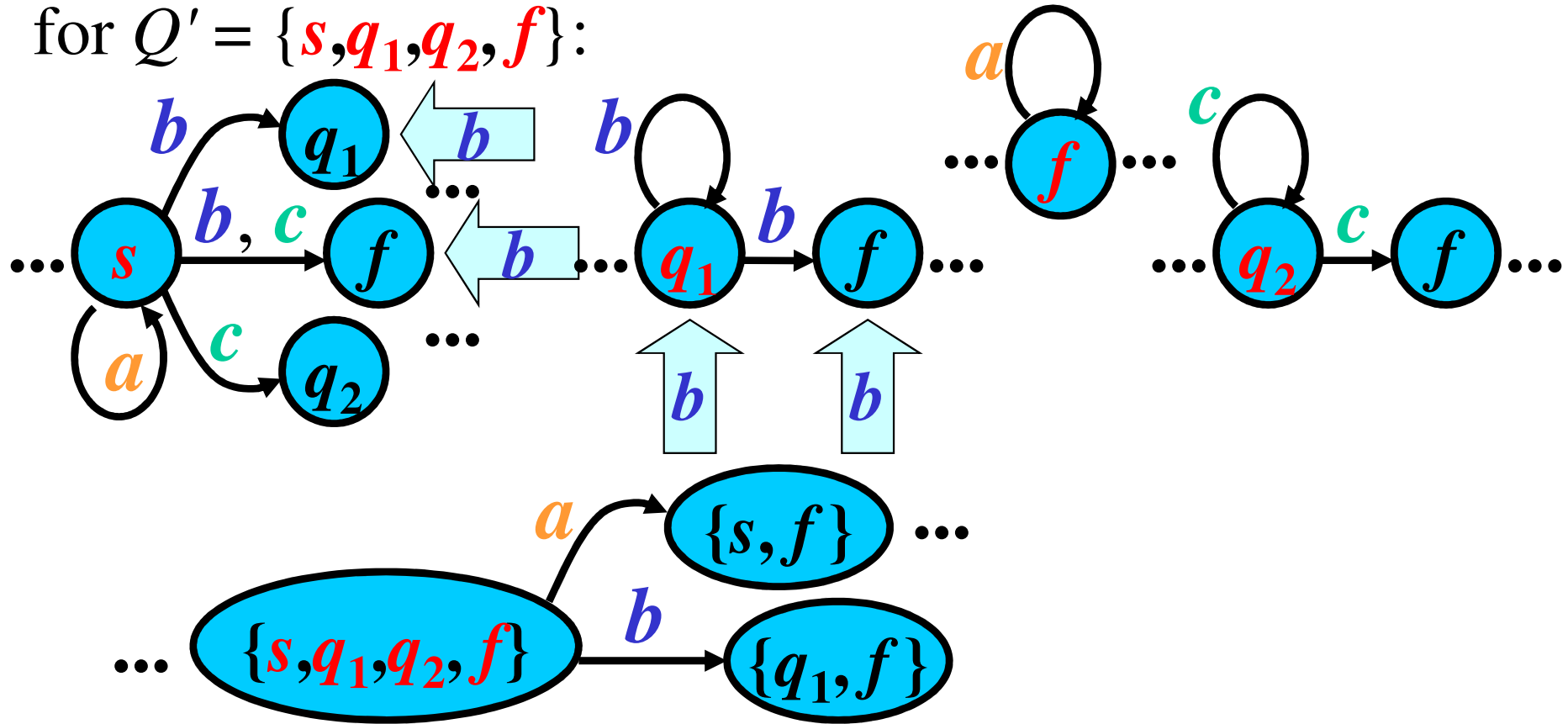
# $\epsilon$ -free FA to DFA: Example 3/5

for  $Q' = \{s, q_1, q_2, f\}$ :



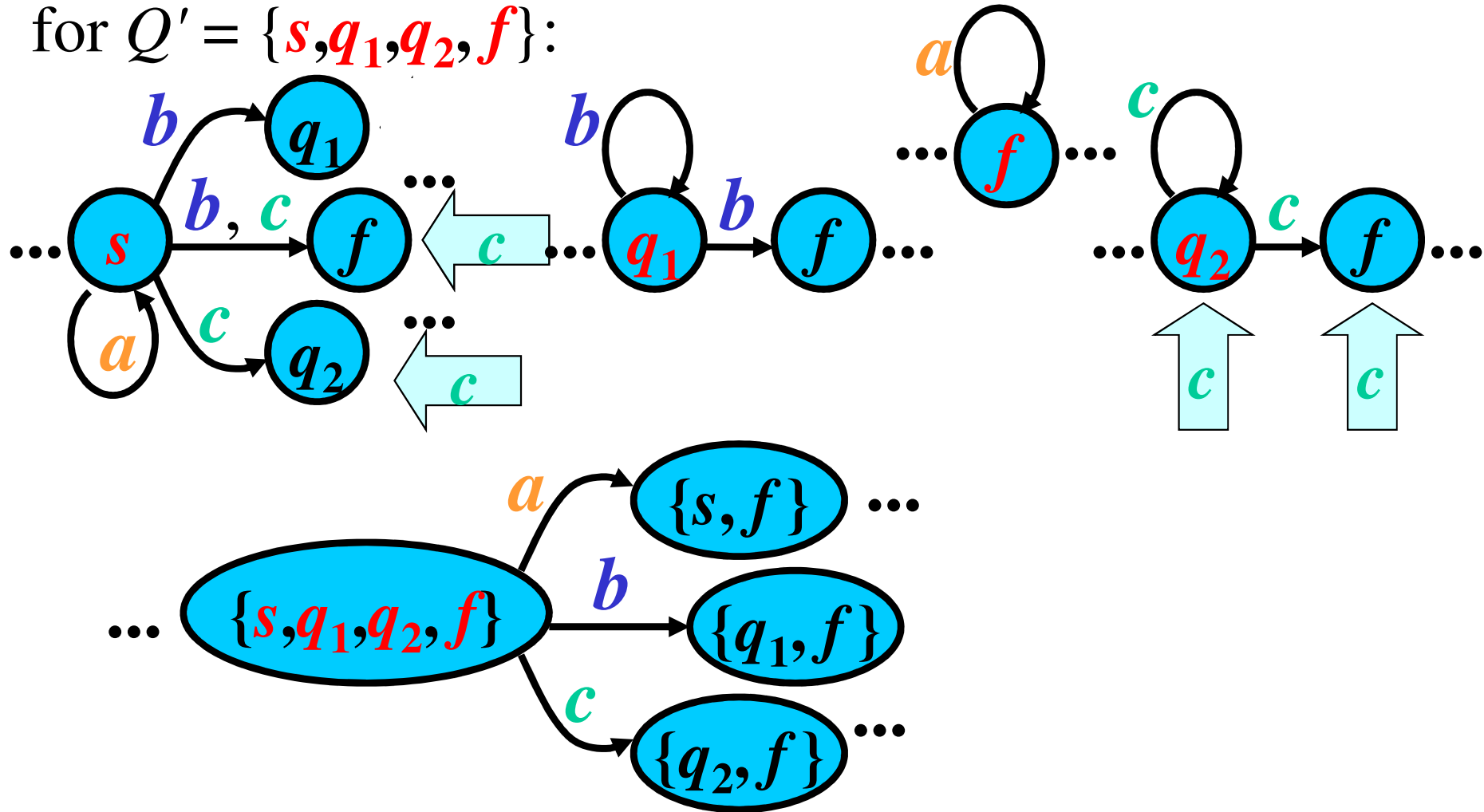
# $\epsilon$ -free FA to DFA: Example 3/5

for  $Q' = \{s, q_1, q_2, f\}$ :



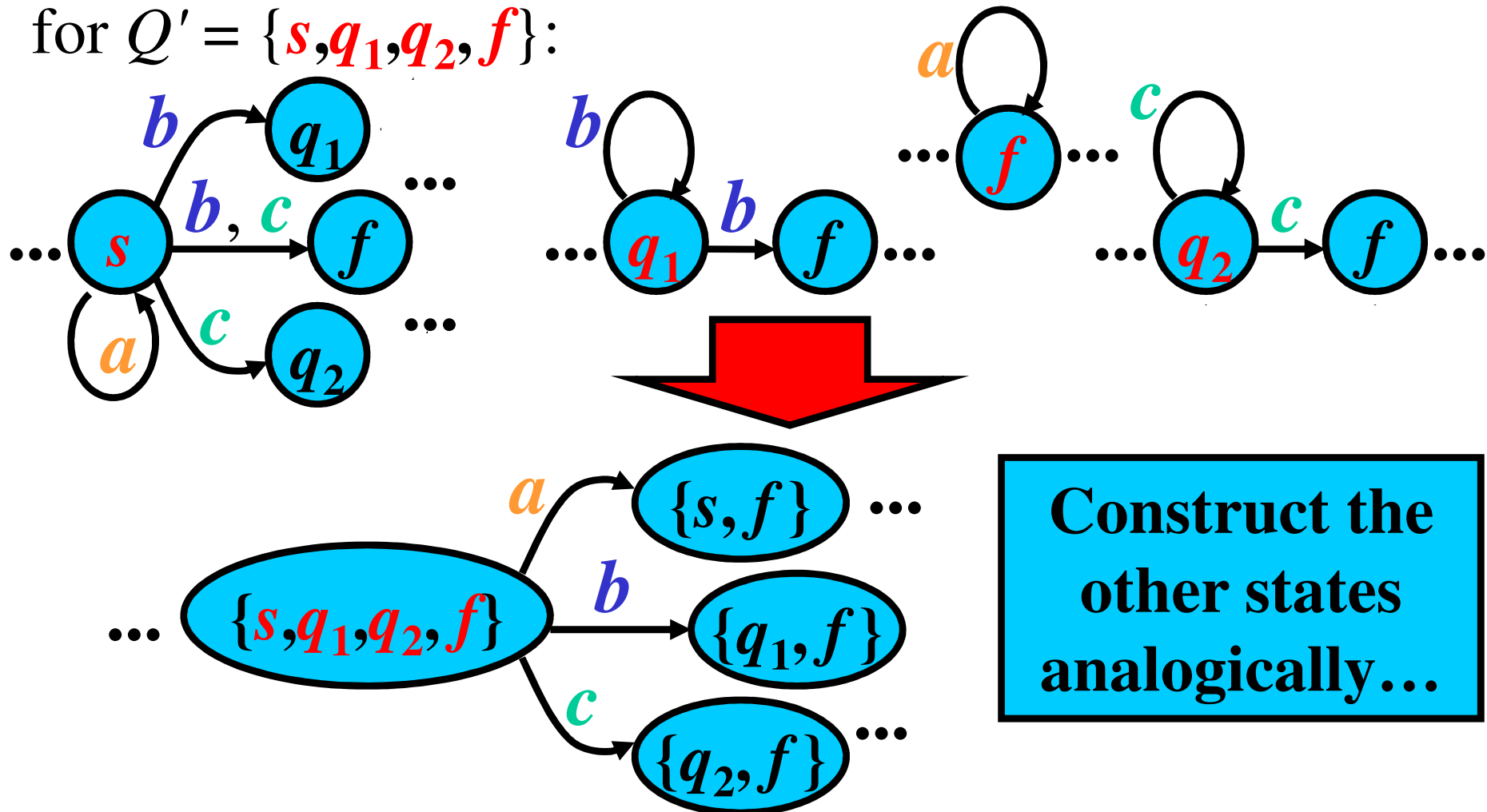
# $\epsilon$ -free FA to DFA: Example 3/5

for  $Q' = \{s, q_1, q_2, f\}$ :



# $\epsilon$ -free FA to DFA: Example 3/5

for  $Q' = \{s, q_1, q_2, f\}$ :



$$R_d = R_d \cup \{ \{s, q_1, q_2, f\} a \rightarrow \{s, f\}, \{s, q_1, q_2, f\} b \rightarrow \{q_1, f\}, \{s, q_1, q_2, f\} c \rightarrow \{q_2, f\} \}$$



# $\varepsilon$ -free FA to DFA: Example 4/5

**Final states:**  $F_d := \{F': F' \in Q_d, F' \cap F \neq \emptyset\}$   
 for  $F = \{f\}$ :

$$\{s\} \cap \{f\} = \emptyset \quad \Rightarrow \quad \{s\} \notin F_d$$

$$\{s, q_1\} \cap \{f\} = \emptyset \quad \Rightarrow \quad \{s, q_1\} \notin F_d$$

$$\{s, q_1, q_2\} \cap \{f\} = \emptyset \quad \Rightarrow \quad \{s, q_1, q_2\} \notin F_d$$

$$\{s, q_1, f\} \cap \{f\} = \{f\} \neq \emptyset \quad \Rightarrow \quad \{s, q_1, f\} \in F_d$$

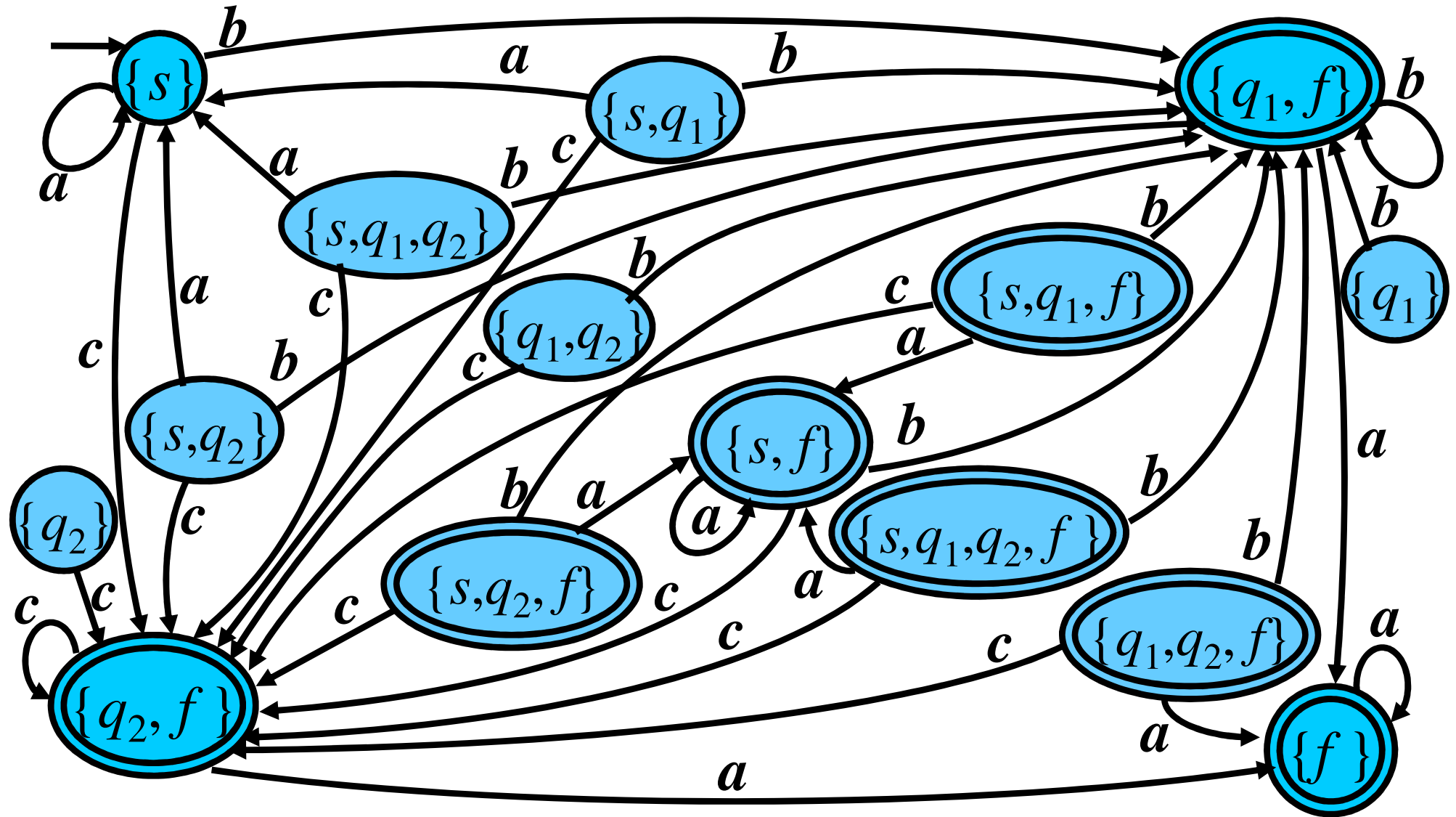
$$\{s, q_1, q_2, f\} \cap \{f\} = \{f\} \neq \emptyset \quad \Rightarrow \quad \{s, q_1, q_2, f\} \in F_d$$

⋮

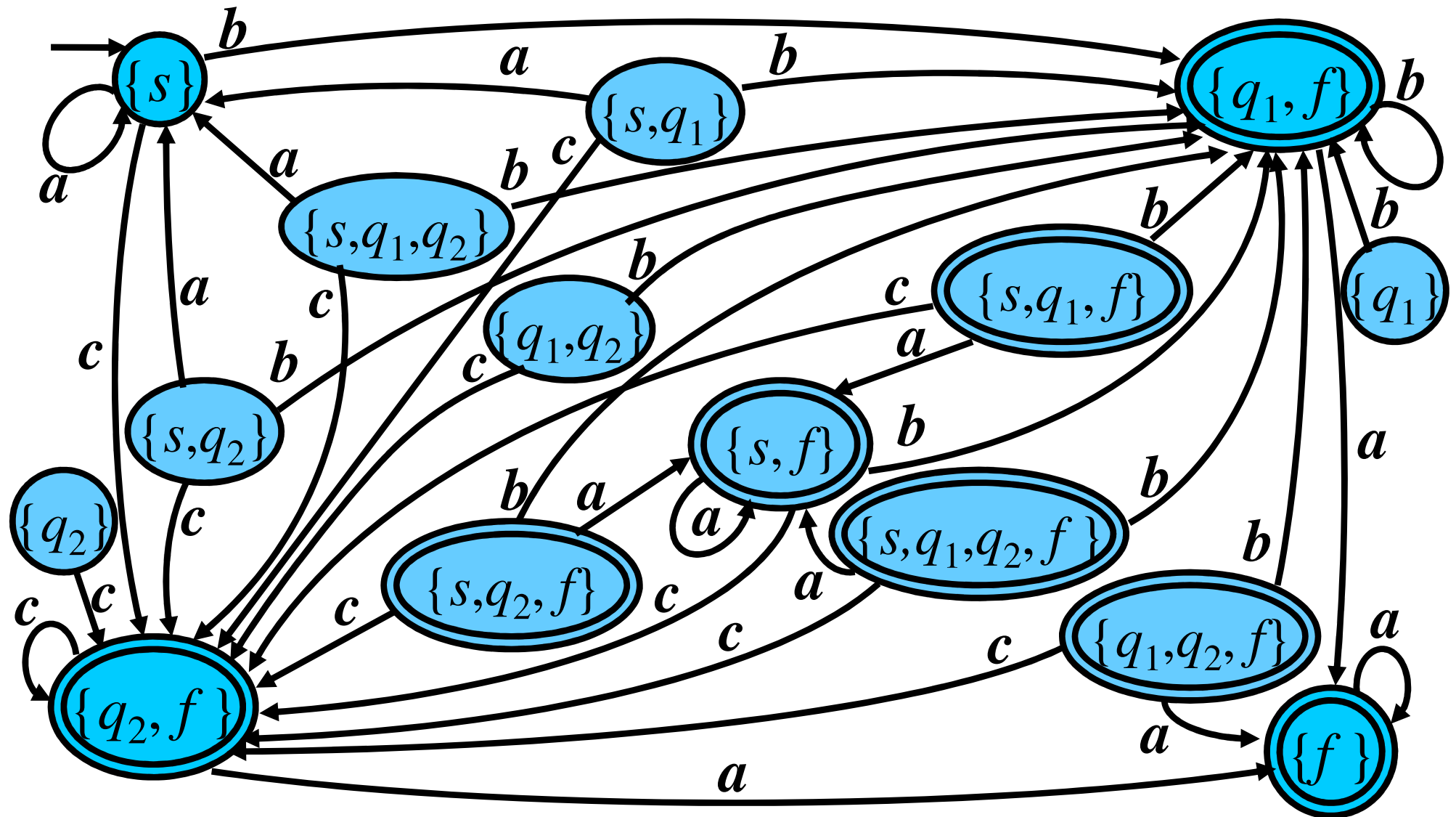
---


$$F_d = \{\{s, q_1, f\}, \{s, q_1, q_2, f\}, \{s, q_2, f\}, \{s, f\}, \\ \{q_1, f\}, \{q_1, q_2, f\}, \{q_2, f\}, \{f\}\}$$

# $\epsilon$ -free FA to DFA: Example 5/5

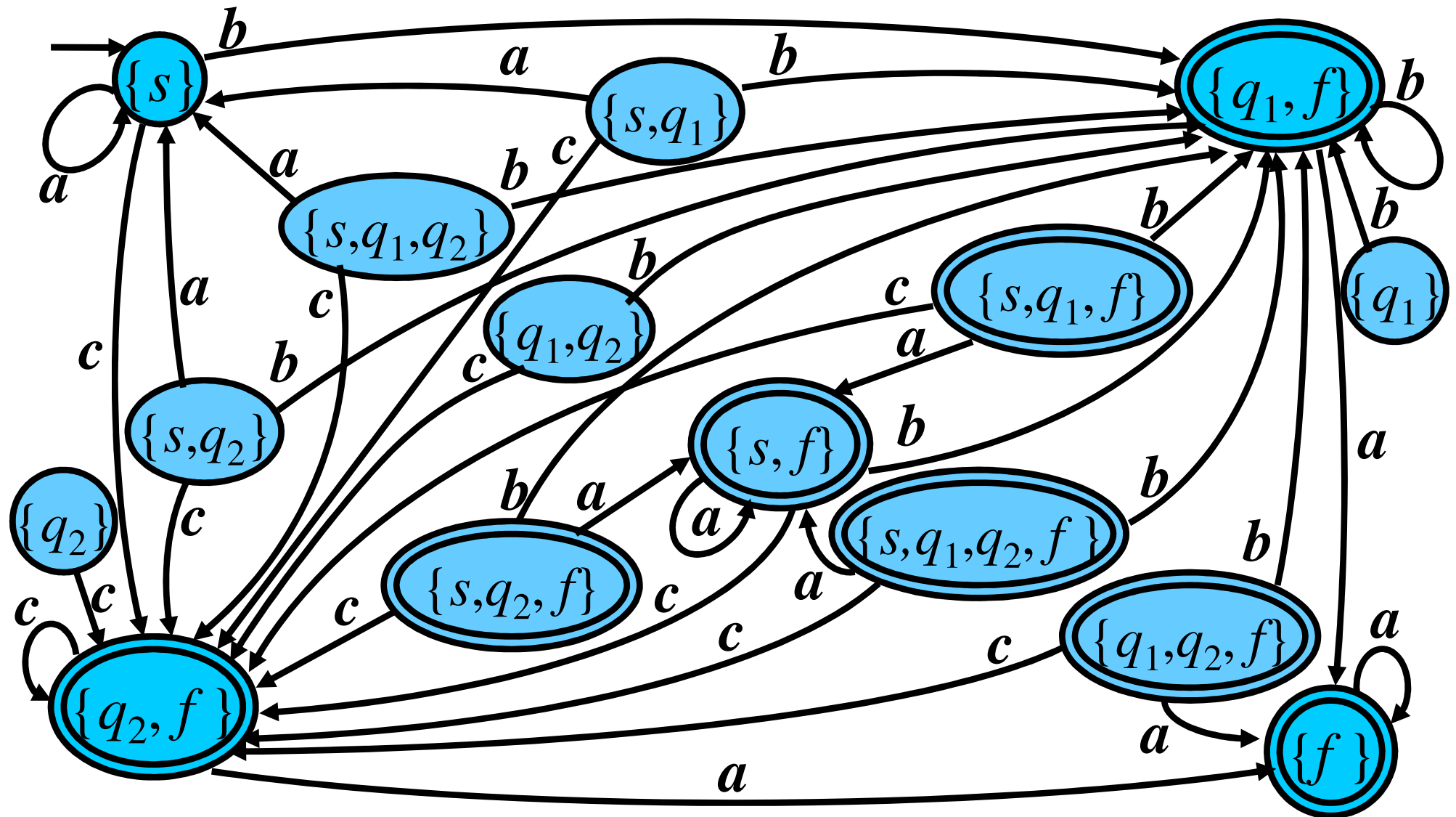


# $\epsilon$ -free FA to DFA: Example 5/5



**Question:** Can we make DFA smaller?

# $\epsilon$ -free FA to DFA: Example 5/5



**Question:** Can we make DFA smaller?

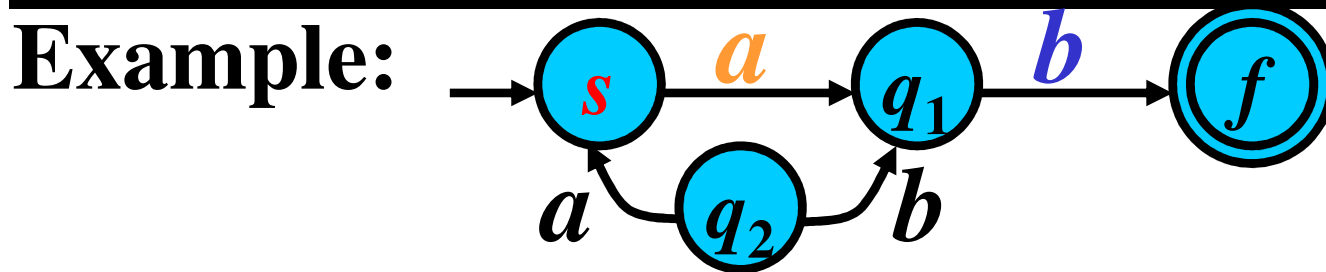
**Answer:** **YES**

# Accessible States

**Gist:** State  $q$  is *accessible* if a string takes DFA from  $s$  (the start state) to  $q$ .

**Definition:** Let  $M = (Q, \Sigma, R, s, F)$  be an FA. A state  $q \in Q$  is *accessible* if there exists  $w \in \Sigma^*$  such that  $sw \vdash^* q$ ; otherwise,  $q$  is *inaccessible*.

**Note:** Each inaccessible state can be removed from FA

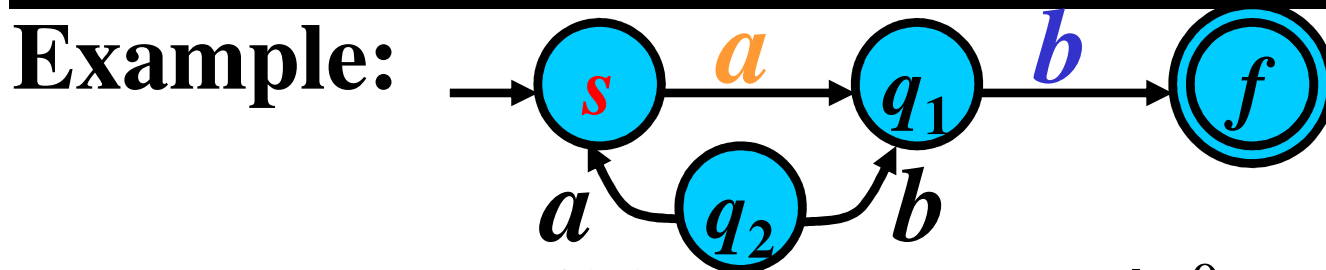


# Accessible States

**Gist:** State  $q$  is *accessible* if a string takes DFA from  $s$  (the start state) to  $q$ .

**Definition:** Let  $M = (Q, \Sigma, R, s, F)$  be an FA. A state  $q \in Q$  is *accessible* if there exists  $w \in \Sigma^*$  such that  $sw \vdash^* q$ ; otherwise,  $q$  is *inaccessible*.

**Note:** Each inaccessible state can be removed from FA



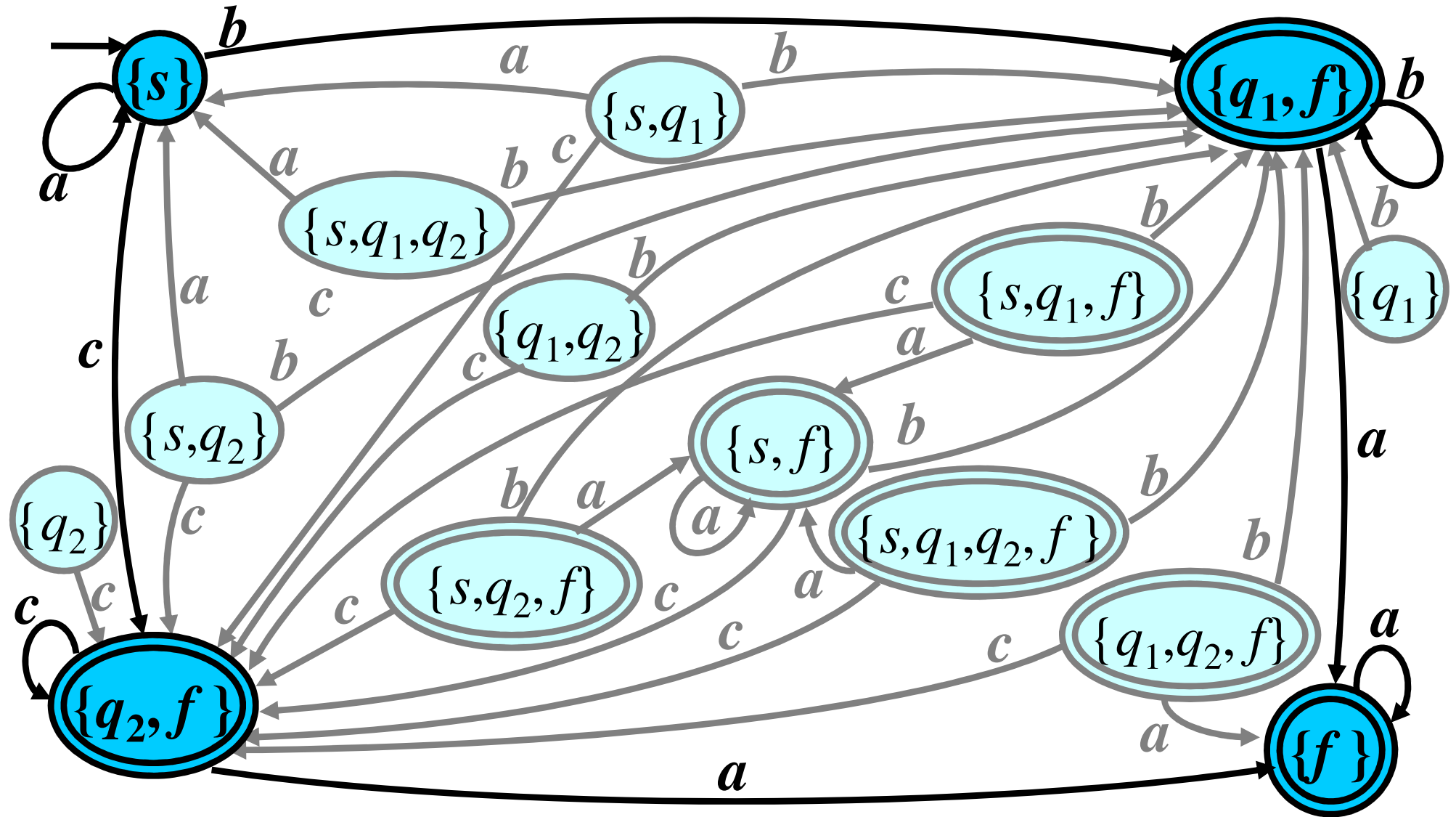
State  $s$  - accessible:  $w = \varepsilon$  :  $s \vdash^0 s$

State  $q_1$  - accessible:  $w = a$  :  $sa \vdash q_1$

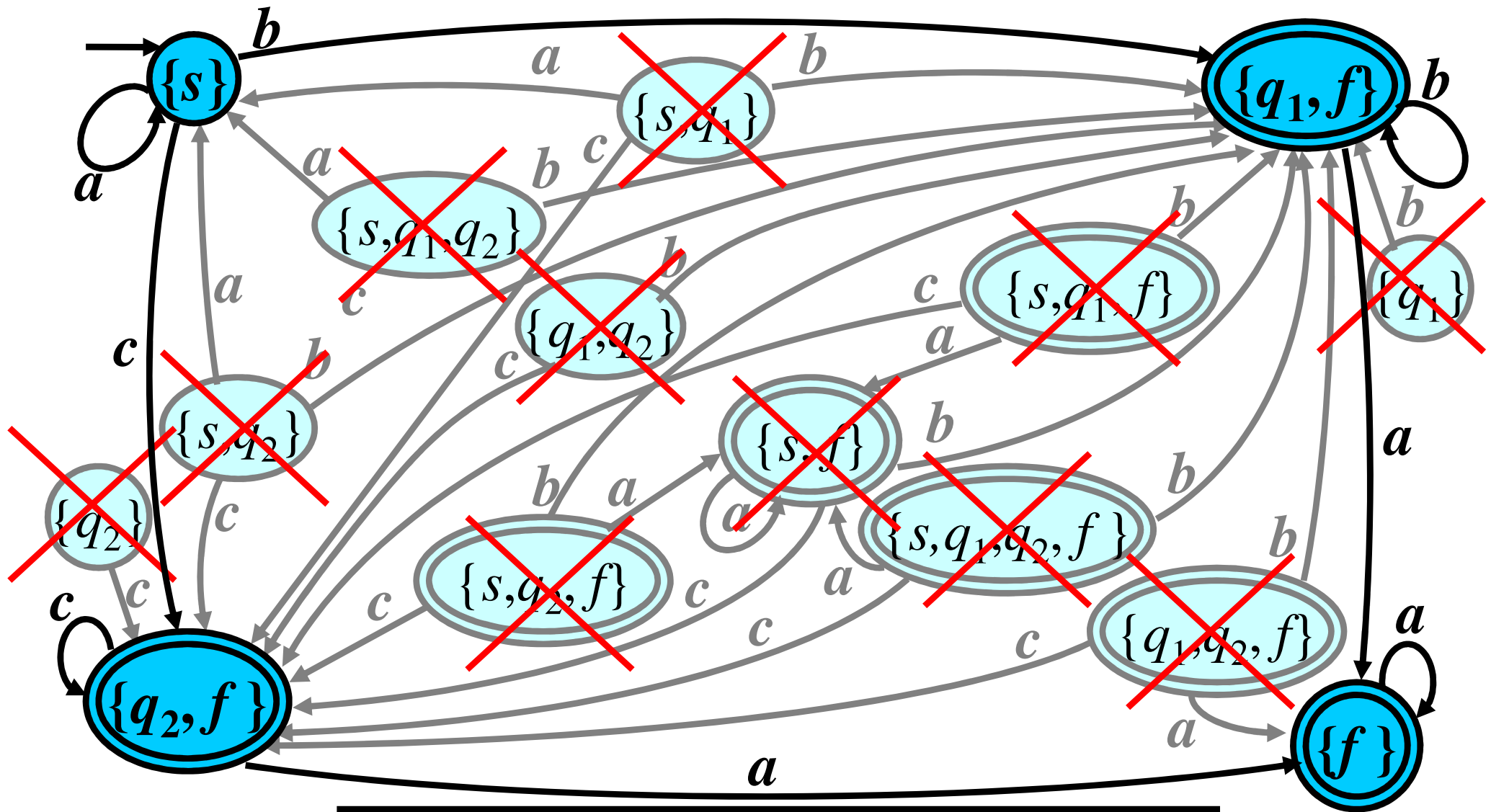
State  $f$  - accessible:  $w = ab$  :  $sab \vdash q_1 \vdash f$

State  $q_2$  - **inaccessible** (there is no  $w \in \Sigma^*$  such that  $sw \vdash^* q_2$ )

# Previous Example



# Previous Example



**Many inaccessible states**



## Algorithm II: $\epsilon$ -free FA to DFA 1/2

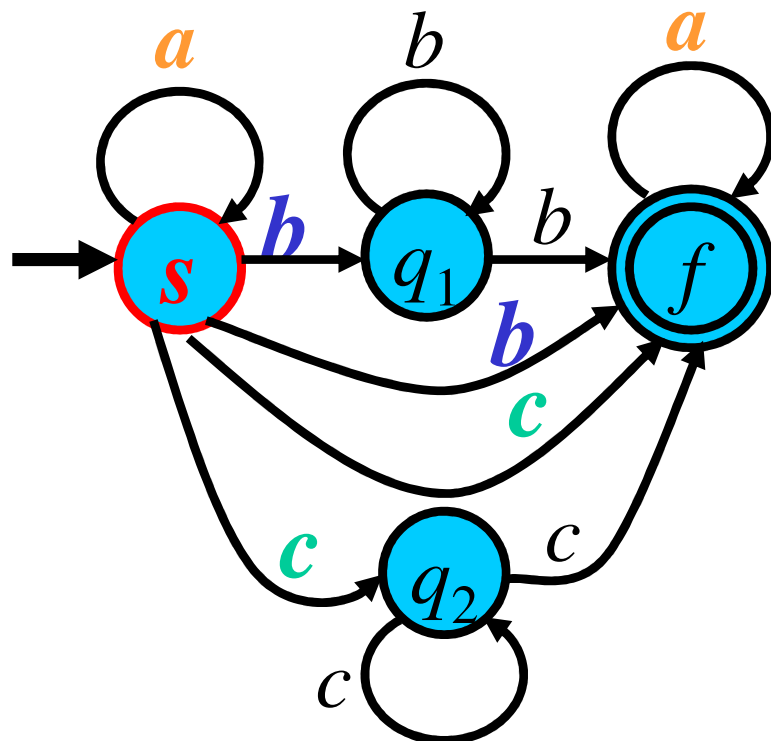
**Gist:** Analogy to the previous algorithm except that only sets of accessible states are introduced.

---

# Algorithm II: $\varepsilon$ -free FA to DFA 1/2

**Gist:** Analogy to the previous algorithm except that only sets of accessible states are introduced.

**Illustration:**

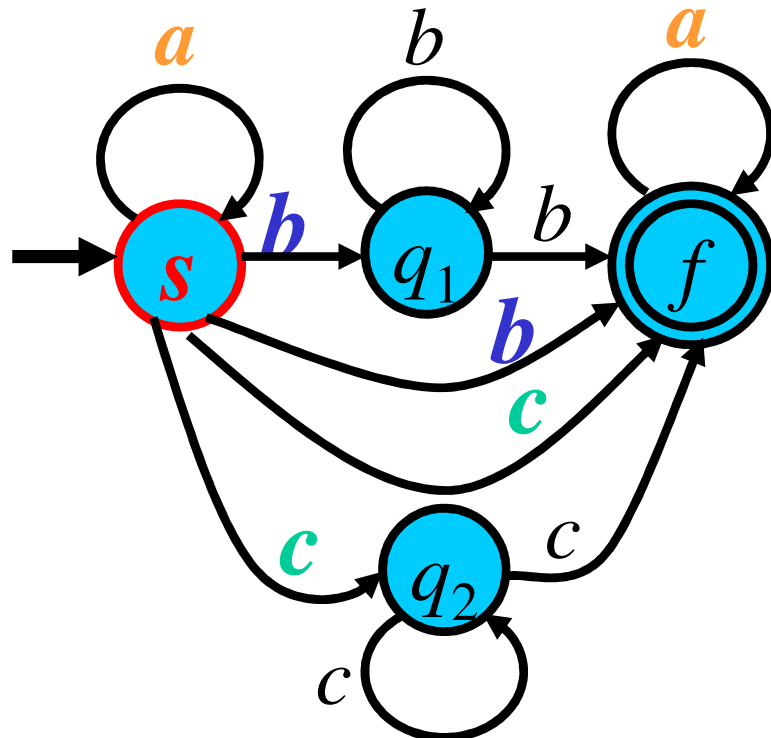


$$Q_{DFA} = \{\{s\}\}$$

# Algorithm II: $\epsilon$ -free FA to DFA 1/2

**Gist:** Analogy to the previous algorithm except that only sets of accessible states are introduced.

**Illustration:**



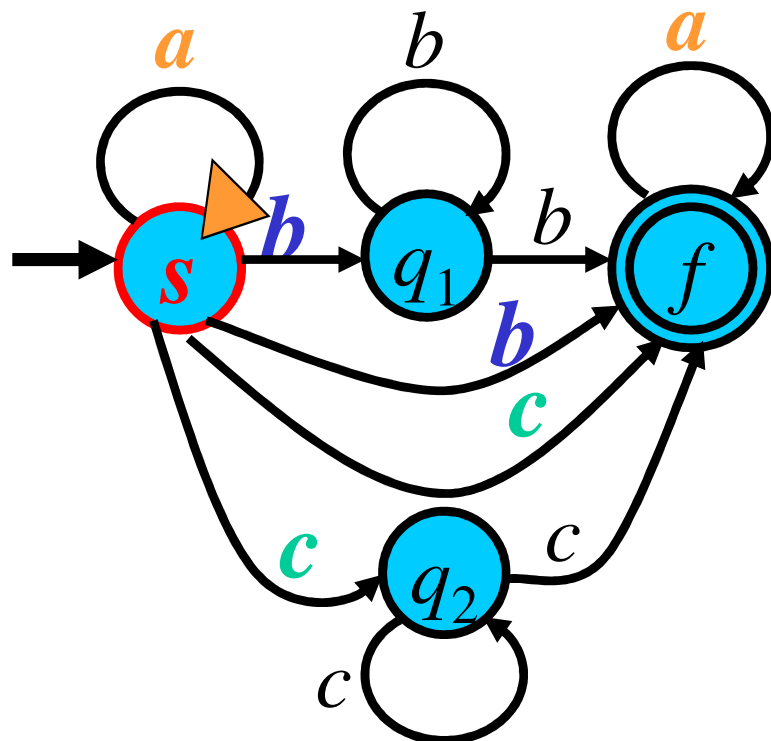
$$Q_{DFA} = \{\{s\}\}$$

For state  $\{s\}$ :  $\{s\}$

# Algorithm II: $\epsilon$ -free FA to DFA 1/2

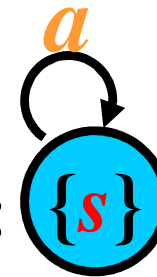
**Gist:** Analogy to the previous algorithm except that only sets of accessible states are introduced.

**Illustration:**



$$Q_{DFA} = \{\{s\}\}$$

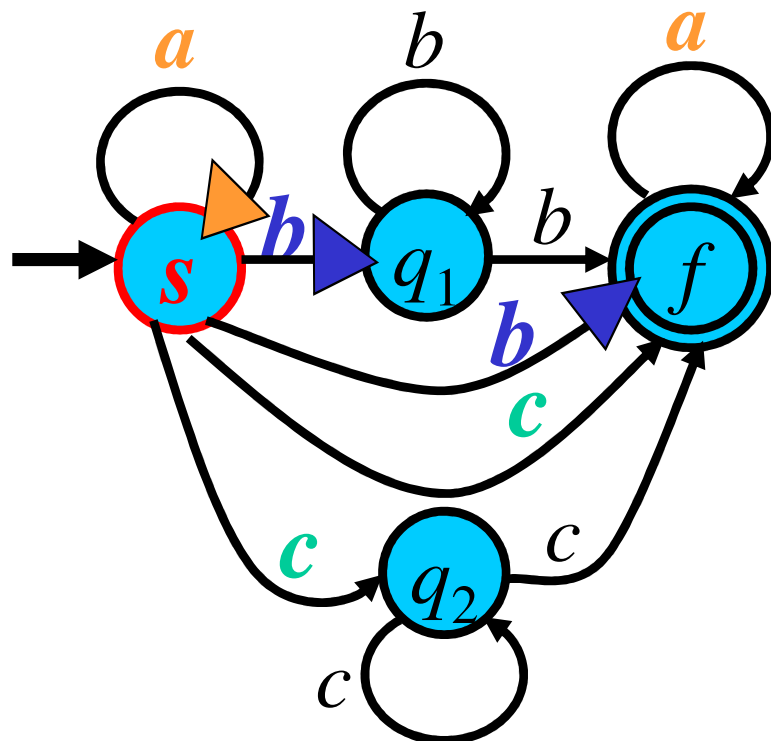
For state  $\{s\}$ :



# Algorithm II: $\epsilon$ -free FA to DFA 1/2

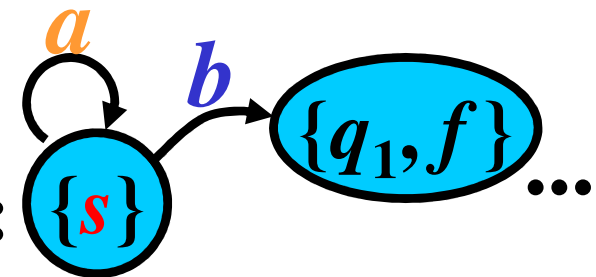
**Gist:** Analogy to the previous algorithm except that only sets of accessible states are introduced.

**Illustration:**



$$Q_{DFA} = \{\{s\}\}$$

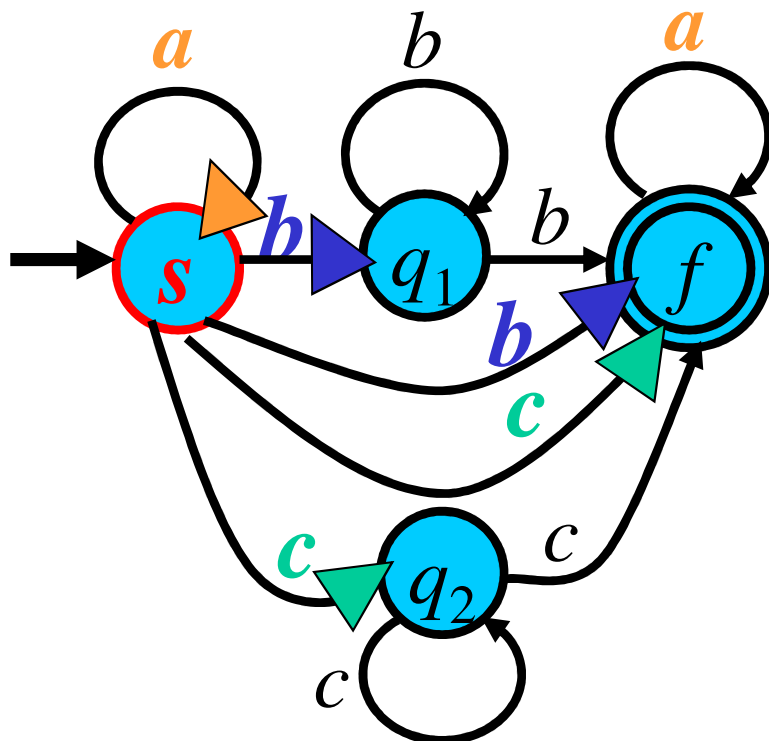
For state  $\{s\}$ :



# Algorithm II: $\epsilon$ -free FA to DFA 1/2

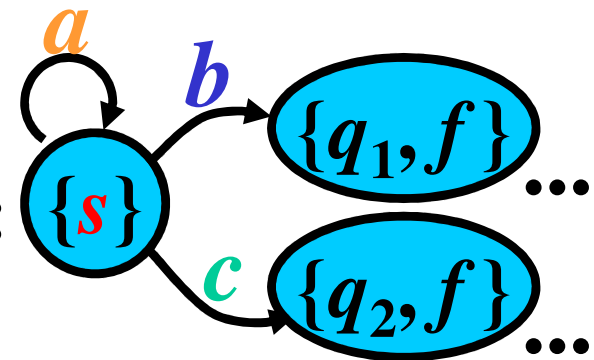
**Gist:** Analogy to the previous algorithm except that only sets of accessible states are introduced.

**Illustration:**



$$Q_{DFA} = \{\{s\}\}$$

For state  $\{s\}$ :

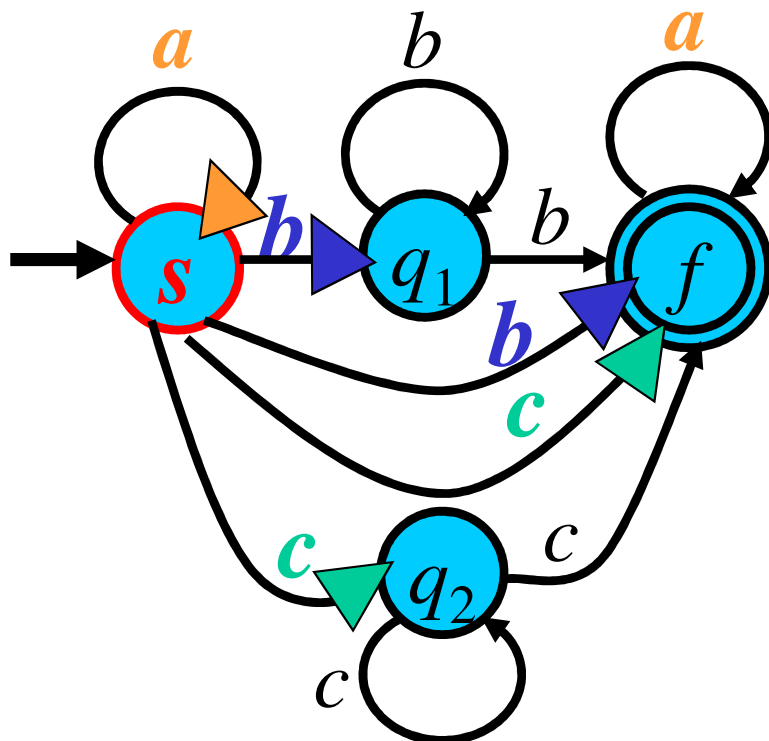


Add new states  $\{q_1, f\}$ ,  $\{q_2, f\}$  to  $Q_{DFA}$

# Algorithm II: $\epsilon$ -free FA to DFA 1/2

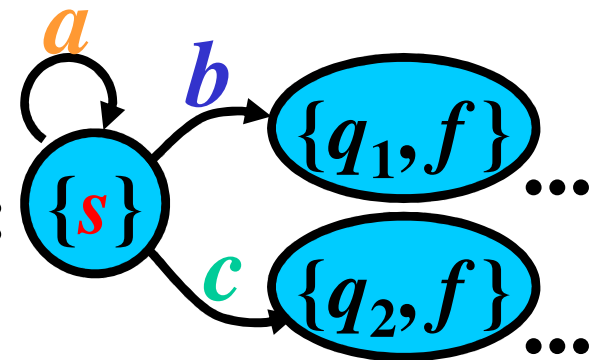
**Gist:** Analogy to the previous algorithm except that only sets of accessible states are introduced.

**Illustration:**



$$Q_{DFA} = \{\{s\}\}$$

For state  $\{s\}$ :



Add new states  $\{q_1, f\}$ ,  $\{q_2, f\}$  to  $Q_{DFA}$

For state  $\{q_1, f\}$ : ...

For state  $\{q_2, f\}$ : ...

Add new states ...

⋮

## Algorithm II: $\varepsilon$ -free FA to DFA 2/2

- **Input:**  $\varepsilon$ -free FA:  $M = (Q, \Sigma, R, s, F)$
- **Output:** DFA:  $M_d = (Q_d, \Sigma, R_d, s_d, F_d)$   
without any inaccessible states

---

• **Method:**

- $s_d := \{s\}; Q_{new} := \{s_d\}; R_d := \emptyset; Q_d := \emptyset; F_d := \emptyset;$
- **repeat**
  - let  $Q' \in Q_{new}; Q_{new} := Q_{new} - \{Q'\}; Q_d := Q_d \cup \{Q'\};$
  - for each**  $a \in \Sigma$  **do begin**
    - $Q'' := \{q: p \in Q', pa \rightarrow q \in R\};$
    - if**  $Q'' \neq \emptyset$  **then**  $R_d := R_d \cup \{Q'a \rightarrow Q''\};$
    - if**  $Q'' \notin Q_d \cup \{\emptyset\}$  **then**  $Q_{new} := Q_{new} \cup \{Q''\}$
  - end;**
  - if**  $Q' \cap F \neq \emptyset$  **then**  $F_d := F_d \cup \{Q'\}$
- until**  $Q_{new} = \emptyset.$



# $\epsilon$ -free FA to DFA: Example 1/3

$M = (Q, \Sigma, R, s, F)$ , where:

$Q = \{s, q_1, q_2, f\}; \Sigma = \{a, b, c\}; F = \{f\}$

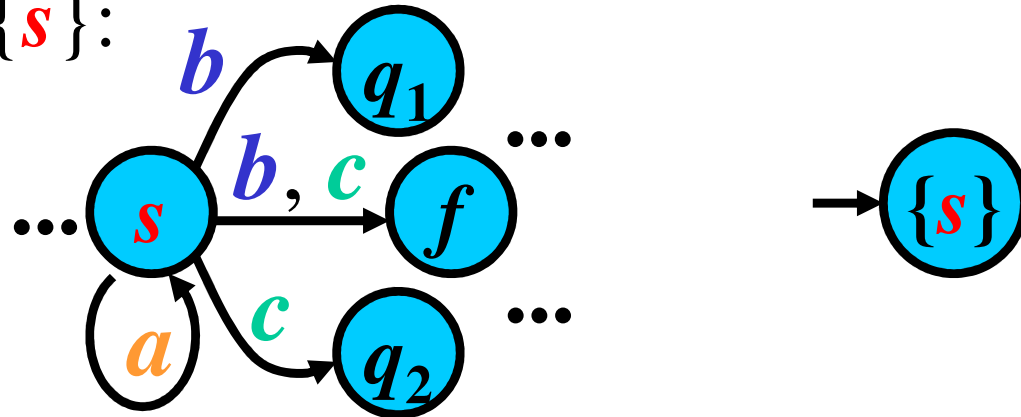
$R = \{sa \rightarrow s, sb \rightarrow q_1, sb \rightarrow f, sc \rightarrow q_2, sc \rightarrow f,$   
 $q_1b \rightarrow q_1, q_1b \rightarrow f, q_2c \rightarrow q_2, q_2c \rightarrow f, fa \rightarrow f\};$

---

$Q_{new} = \{\{s\}\}; R_d = \emptyset; Q_d = \emptyset; F_d = \emptyset$

---

for  $Q' = \{s\}$ :



# $\epsilon$ -free FA to DFA: Example 1/3

$M = (Q, \Sigma, R, s, F)$ , where:

$Q = \{s, q_1, q_2, f\}; \Sigma = \{a, b, c\}; F = \{f\}$

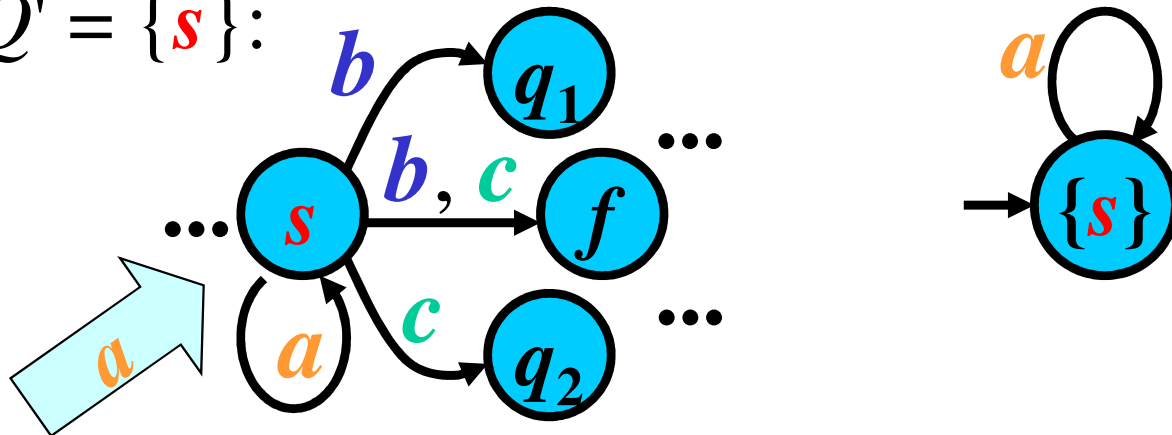
$R = \{sa \rightarrow s, sb \rightarrow q_1, sb \rightarrow f, sc \rightarrow q_2, sc \rightarrow f,$   
 $q_1b \rightarrow q_1, q_1b \rightarrow f, q_2c \rightarrow q_2, q_2c \rightarrow f, fa \rightarrow f\};$

---

$Q_{new} = \{\{s\}\}; R_d = \emptyset; Q_d = \emptyset; F_d = \emptyset$

---

for  $Q' = \{s\}$ :



# $\epsilon$ -free FA to DFA: Example 1/3

$M = (Q, \Sigma, R, s, F)$ , where:

$Q = \{s, q_1, q_2, f\}; \Sigma = \{a, b, c\}; F = \{f\}$

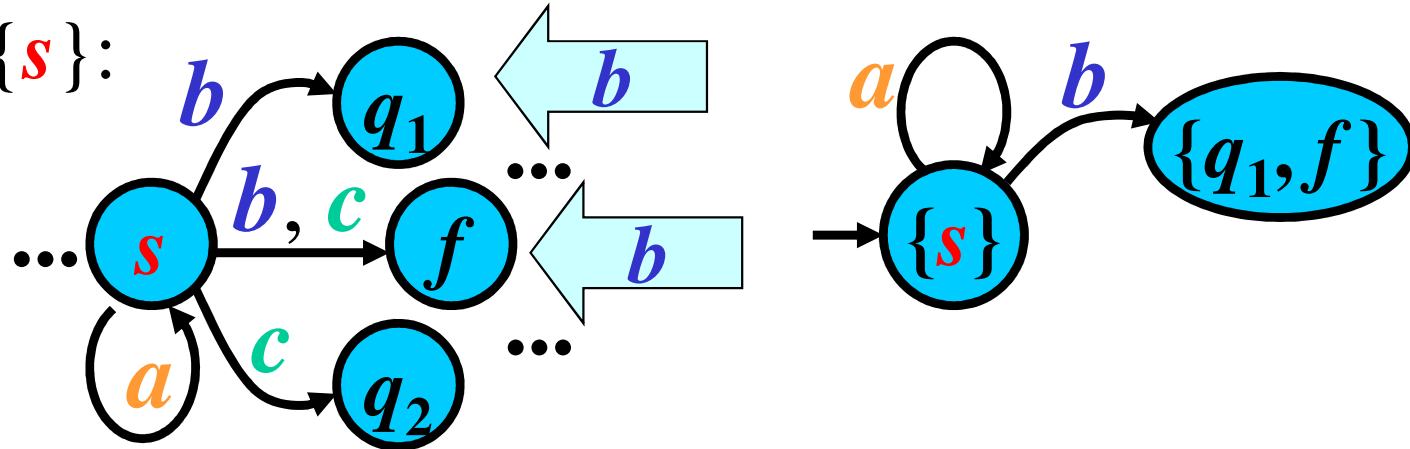
$R = \{sa \rightarrow s, sb \rightarrow q_1, sb \rightarrow f, sc \rightarrow q_2, sc \rightarrow f,$   
 $q_1b \rightarrow q_1, q_1b \rightarrow f, q_2c \rightarrow q_2, q_2c \rightarrow f, fa \rightarrow f\};$

---

$Q_{new} = \{\{s\}\}; R_d = \emptyset; Q_d = \emptyset; F_d = \emptyset$

---

for  $Q' = \{s\}$ :



# $\epsilon$ -free FA to DFA: Example 1/3

$M = (Q, \Sigma, R, s, F)$ , where:

$Q = \{s, q_1, q_2, f\}; \Sigma = \{a, b, c\}; F = \{f\}$

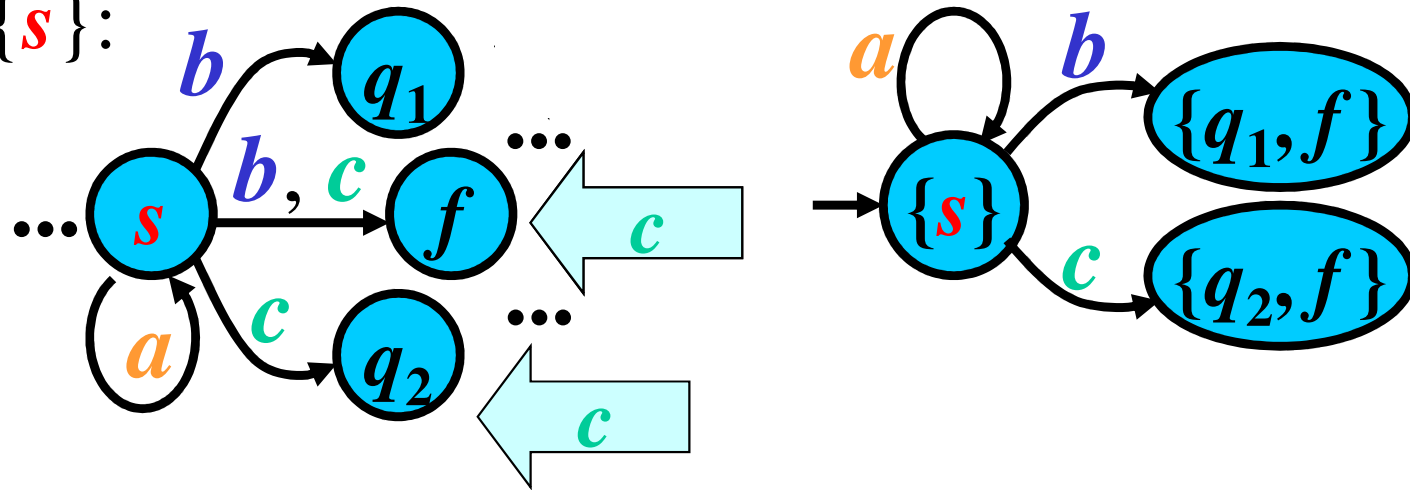
$R = \{sa \rightarrow s, sb \rightarrow q_1, sb \rightarrow f, sc \rightarrow q_2, sc \rightarrow f,$   
 $q_1b \rightarrow q_1, q_1b \rightarrow f, q_2c \rightarrow q_2, q_2c \rightarrow f, fa \rightarrow f\};$

---

$Q_{new} = \{\{s\}\}; R_d = \emptyset; Q_d = \emptyset; F_d = \emptyset$

---

for  $Q' = \{s\}$ :



# $\epsilon$ -free FA to DFA: Example 1/3

$M = (Q, \Sigma, R, s, F)$ , where:

$$Q = \{s, q_1, q_2, f\}; \Sigma = \{a, b, c\}; F = \{f\}$$

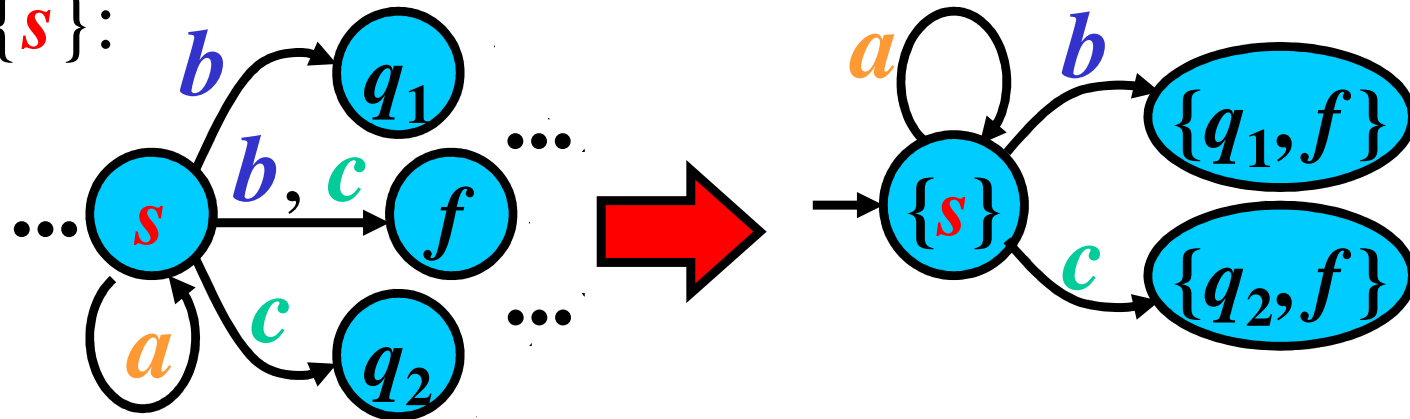
$$R = \{sa \rightarrow s, sb \rightarrow q_1, sb \rightarrow f, sc \rightarrow q_2, sc \rightarrow f, \\ q_1b \rightarrow q_1, q_1b \rightarrow f, q_2c \rightarrow q_2, q_2c \rightarrow f, fa \rightarrow f\};$$

---


$$Q_{new} = \{\{s\}\}; R_d = \emptyset; Q_d = \emptyset; F_d = \emptyset$$


---

for  $Q' = \{s\}$ :

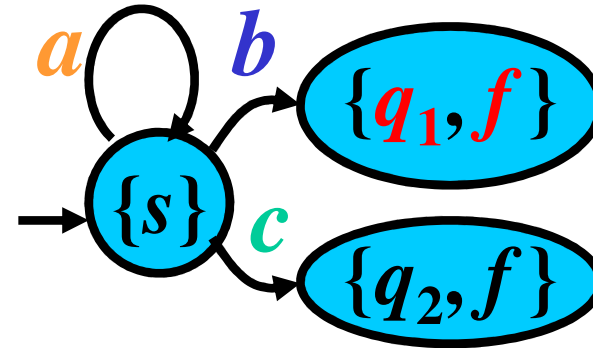
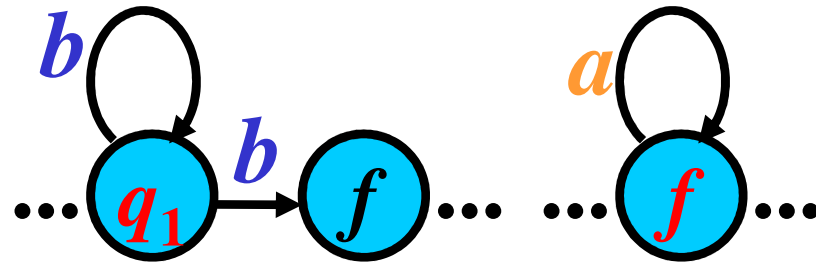


$$R_d := \emptyset \cup \{\{s\}a \rightarrow \{s\}, \{s\}b \rightarrow \{q_1, f\}, \{s\}c \rightarrow \{q_2, f\}\}$$

$$Q_{new} = \{\{q_1, f\}, \{q_2, f\}\}, Q_d = \emptyset \cup \{\{s\}\}, F_d = \emptyset$$

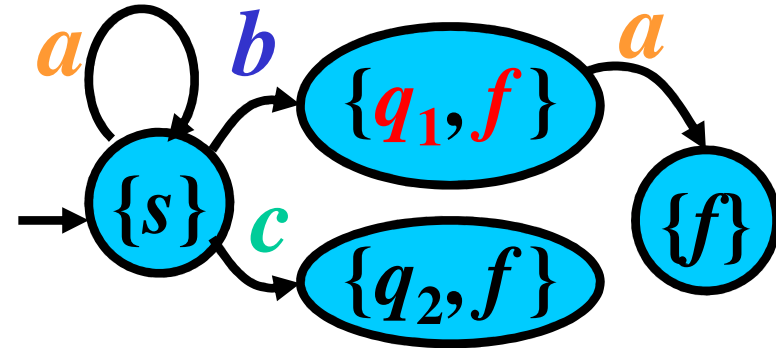
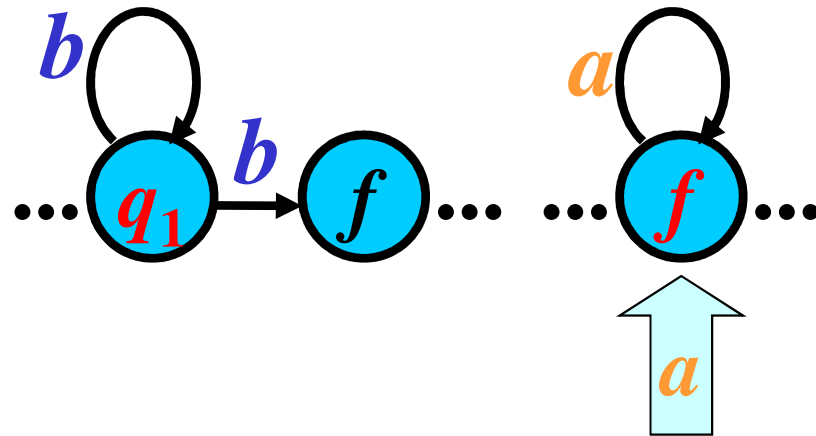
# $\epsilon$ -free FA to DFA: Example 2/3

for  $Q' = \{q_1, f\}$ :



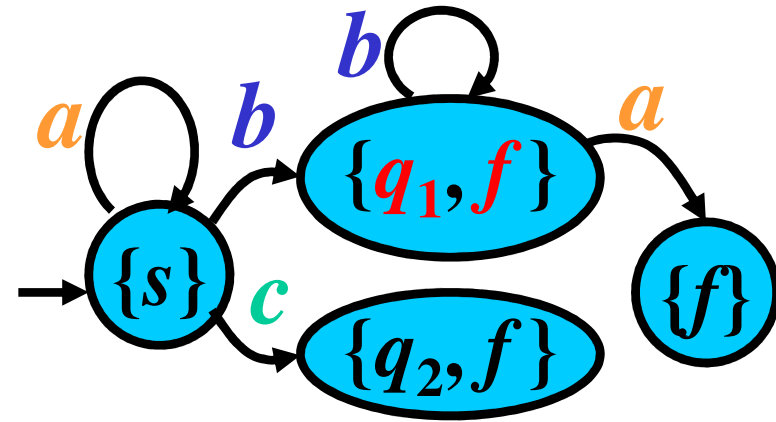
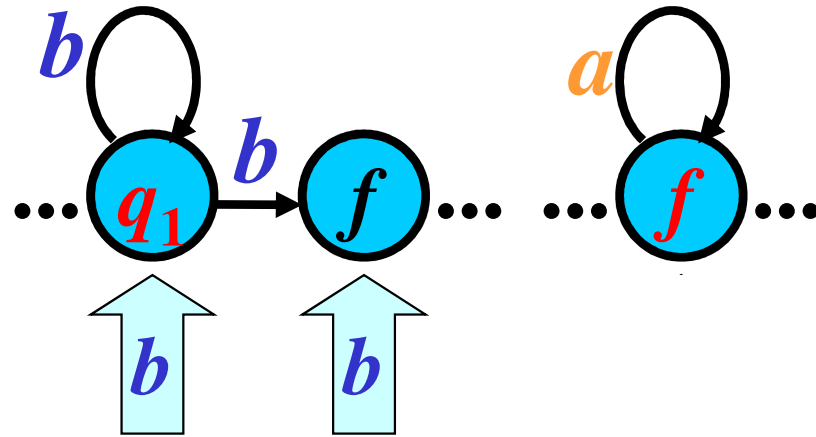
# $\epsilon$ -free FA to DFA: Example 2/3

for  $Q' = \{q_1, f\}$ :



# $\epsilon$ -free FA to DFA: Example 2/3

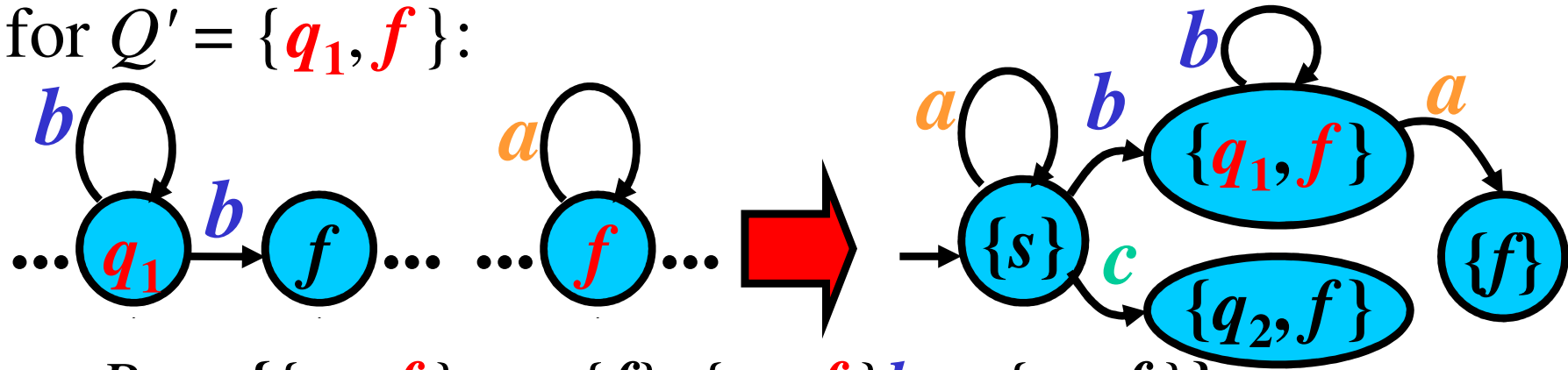
for  $Q' = \{q_1, f\}$ :





# $\epsilon$ -free FA to DFA: Example 2/3

for  $Q' = \{q_1, f\}$ :

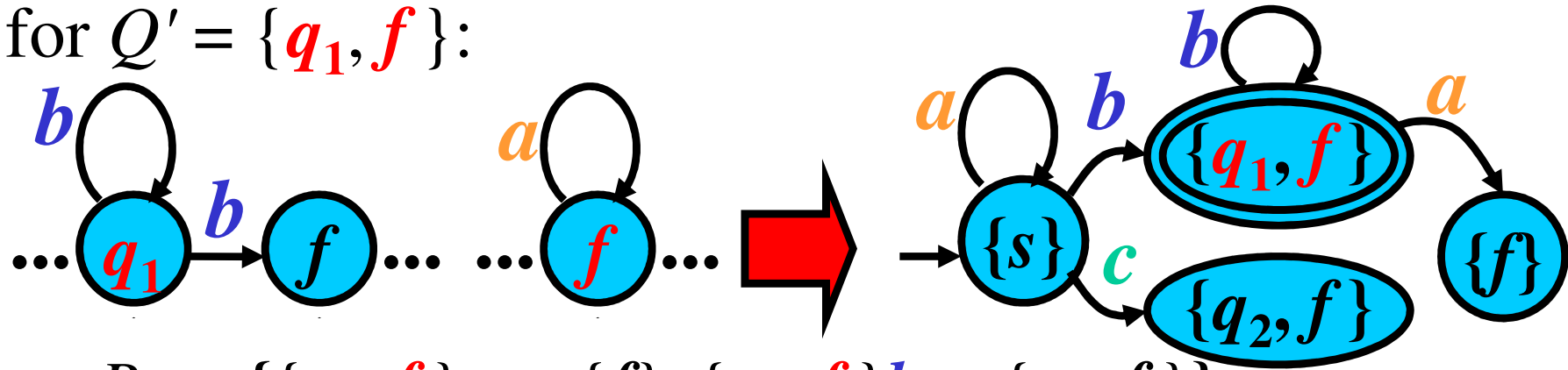


$$R_d := R_d \cup \{ \{q_1, f\} a \rightarrow \{f\}, \{q_1, f\} b \rightarrow \{q_1, f\} \}$$

$$Q_{new} = \{ \{q_2, f\}, \{f\} \}, Q_d = Q_d \cup \{ \{q_1, f\} \},$$

# $\epsilon$ -free FA to DFA: Example 2/3

for  $Q' = \{q_1, f\}$ :

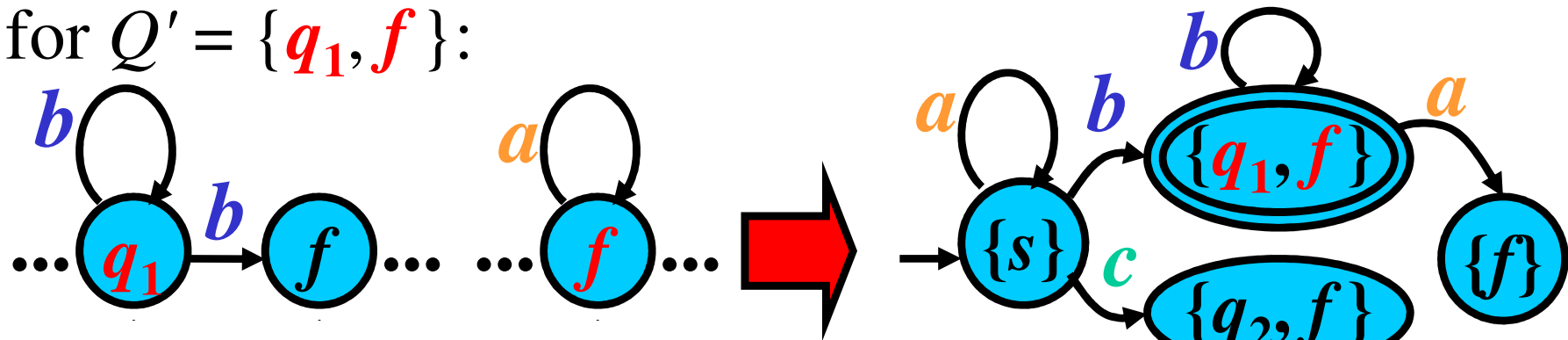


$$R_d := R_d \cup \{ \{q_1, f\} a \rightarrow \{f\}, \{q_1, f\} b \rightarrow \{q_1, f\} \}$$

$$Q_{new} = \{ \{q_2, f\}, \{f\} \}, Q_d = Q_d \cup \{ \{q_1, f\} \}, F_d := \emptyset \cup \{ \{q_1, f\} \}$$

# $\epsilon$ -free FA to DFA: Example 2/3

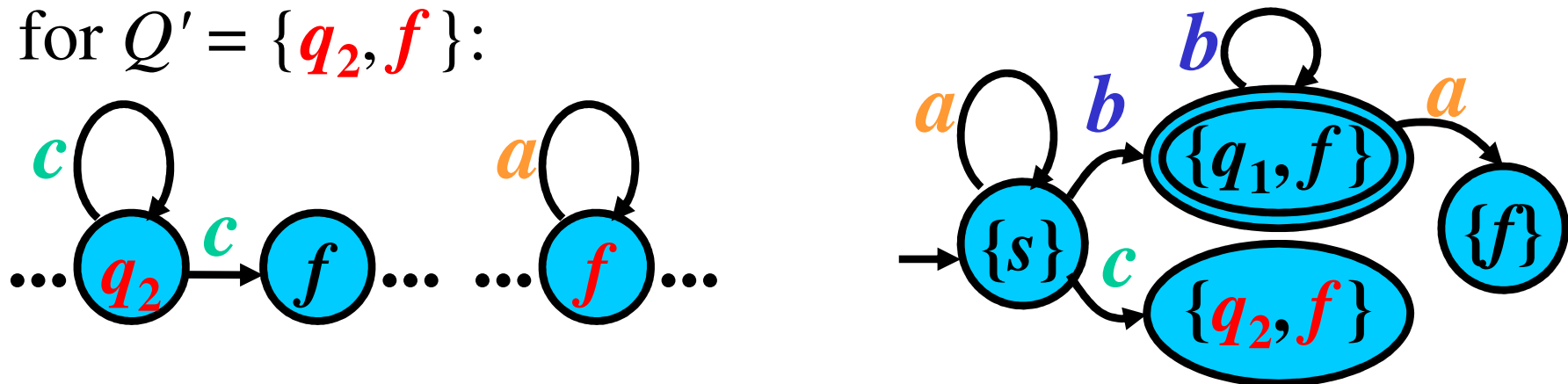
for  $Q' = \{q_1, f\}$ :



$$R_d := R_d \cup \{ \{q_1, f\} a \rightarrow \{f\}, \{q_1, f\} b \rightarrow \{q_1, f\} \}$$

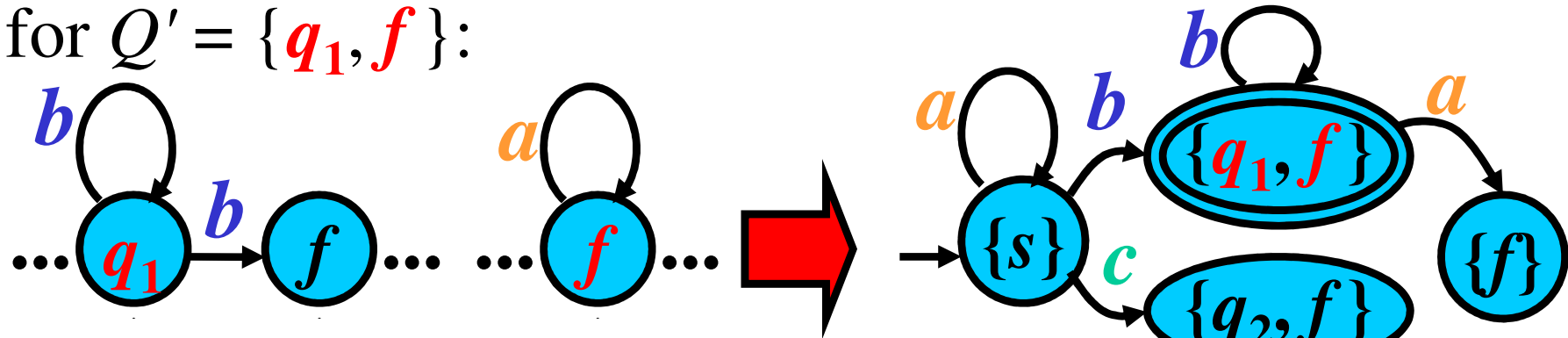
$$Q_{new} = \{ \{q_2, f\}, \{f\} \}, Q_d = Q_d \cup \{ \{q_1, f\} \}, F_d := \emptyset \cup \{ \{q_1, f\} \}$$

for  $Q' = \{q_2, f\}$ :



# $\epsilon$ -free FA to DFA: Example 2/3

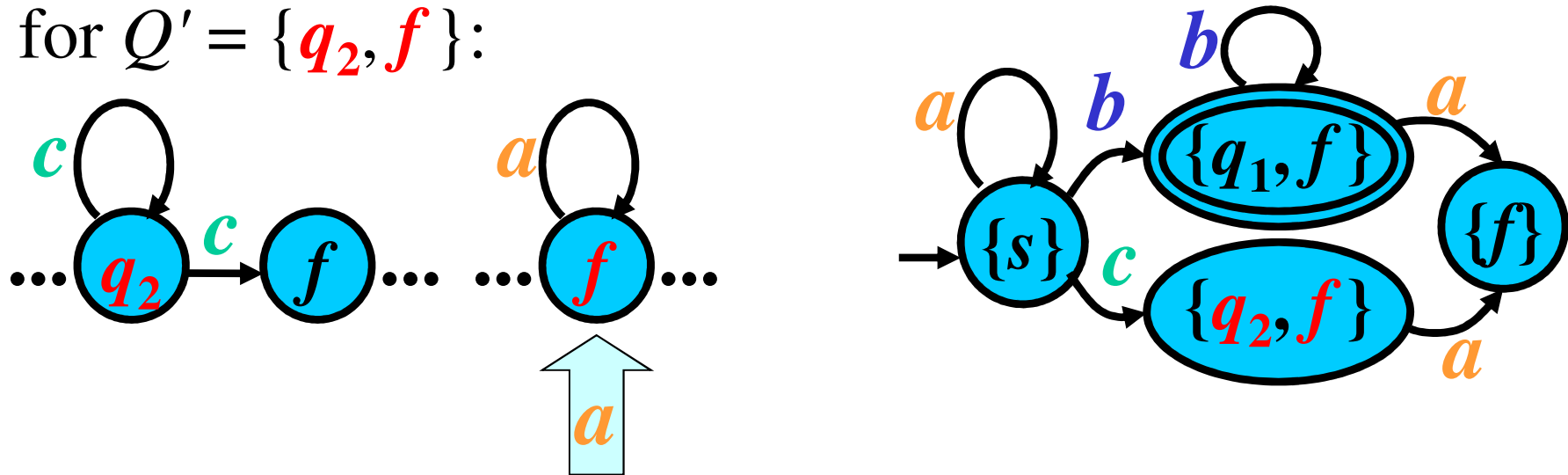
for  $Q' = \{q_1, f\}$ :



$$R_d := R_d \cup \{ \{q_1, f\} a \rightarrow \{f\}, \{q_1, f\} b \rightarrow \{q_1, f\} \}$$

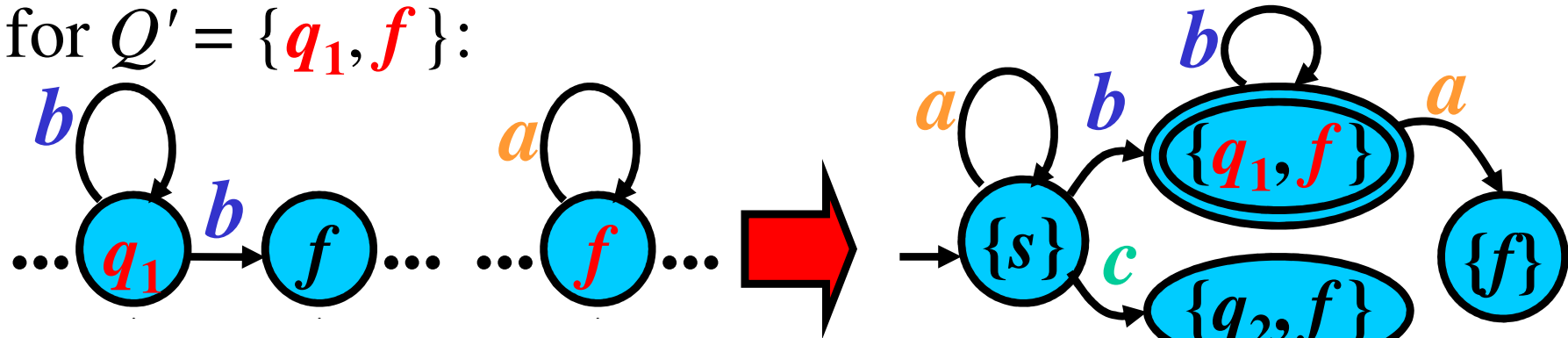
$$Q_{new} = \{ \{q_2, f\}, \{f\} \}, Q_d = Q_d \cup \{ \{q_1, f\} \}, F_d := \emptyset \cup \{ \{q_1, f\} \}$$

for  $Q' = \{q_2, f\}$ :



# $\epsilon$ -free FA to DFA: Example 2/3

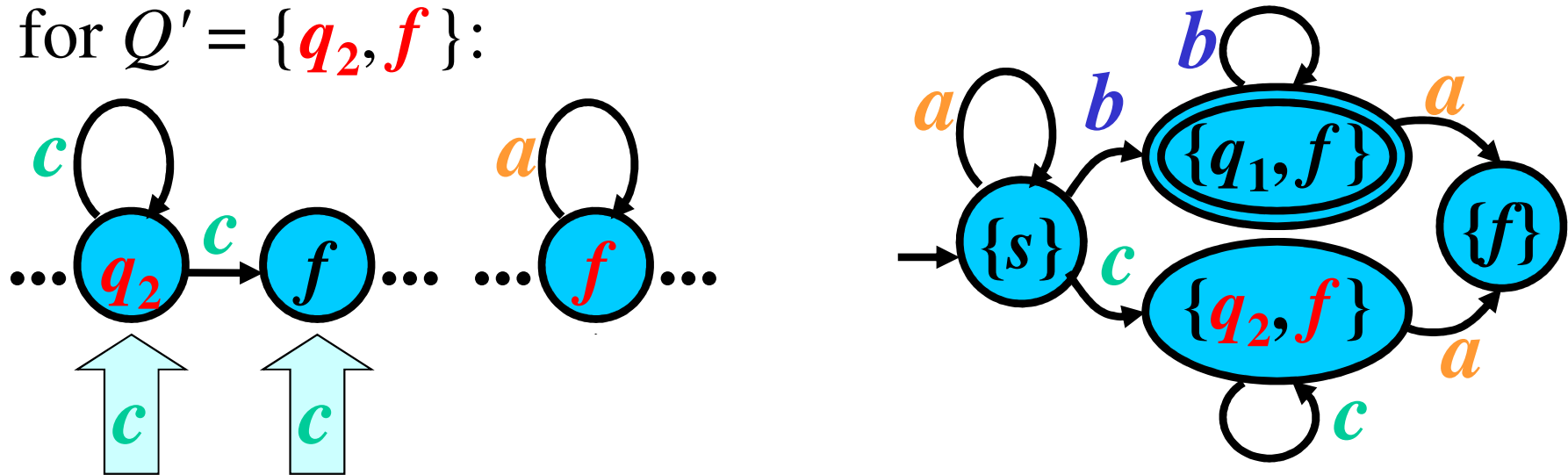
for  $Q' = \{q_1, f\}$ :



$$R_d := R_d \cup \{ \{q_1, f\} a \rightarrow \{f\}, \{q_1, f\} b \rightarrow \{q_1, f\} \}$$

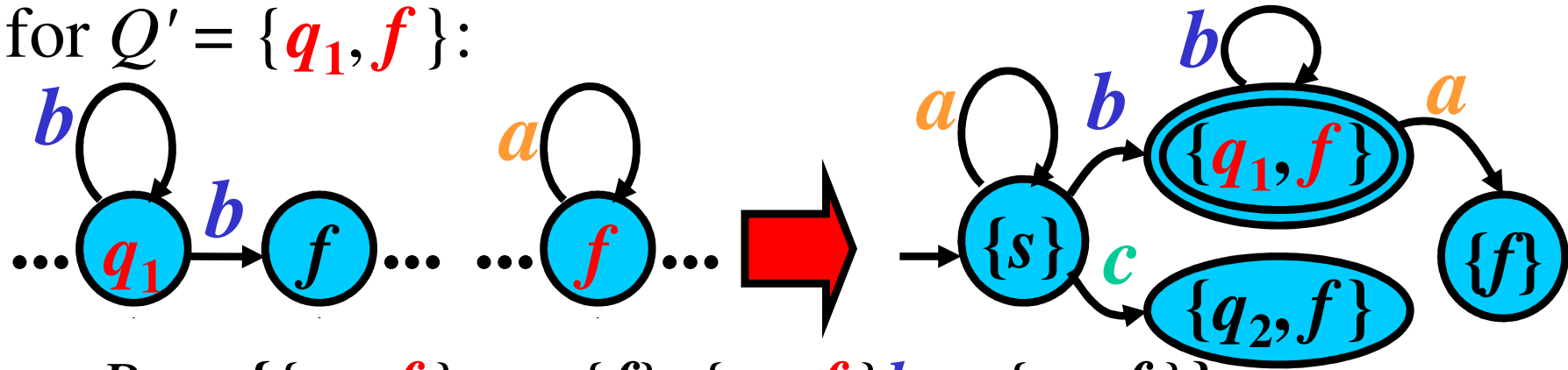
$$Q_{new} = \{ \{q_2, f\}, \{f\} \}, Q_d = Q_d \cup \{ \{q_1, f\} \}, F_d := \emptyset \cup \{ \{q_1, f\} \}$$

for  $Q' = \{q_2, f\}$ :



# $\epsilon$ -free FA to DFA: Example 2/3

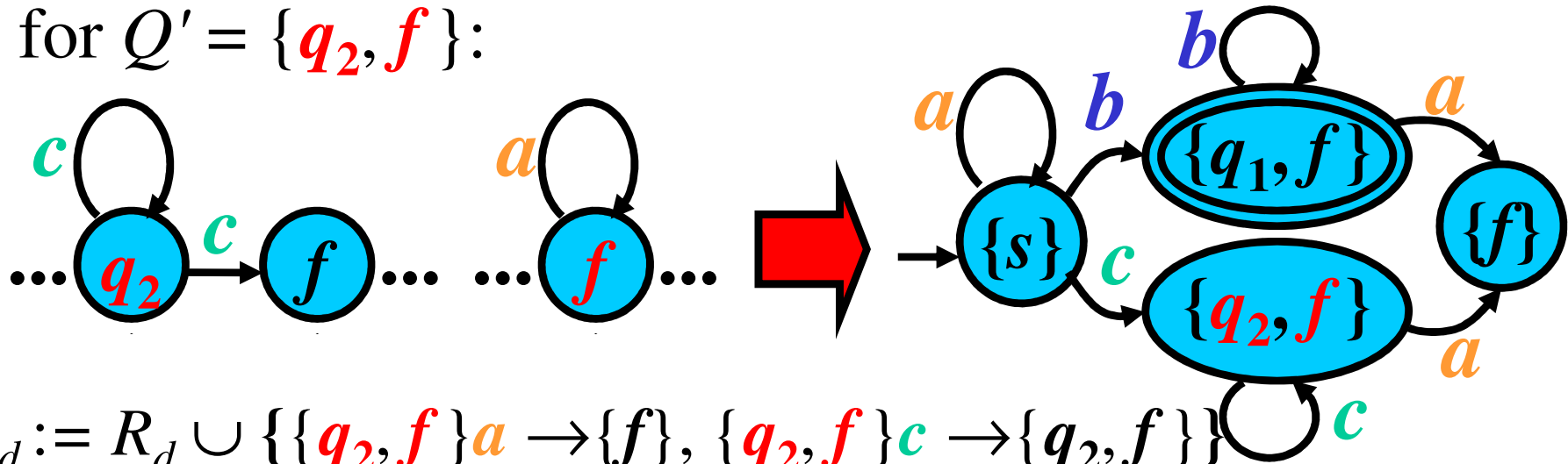
for  $Q' = \{q_1, f\}$ :



$$R_d := R_d \cup \{ \{q_1, f\} a \rightarrow \{f\}, \{q_1, f\} b \rightarrow \{q_1, f\} \}$$

$$Q_{new} = \{ \{q_2, f\}, \{f\} \}, Q_d = Q_d \cup \{ \{q_1, f\} \}, F_d := \emptyset \cup \{ \{q_1, f\} \}$$

for  $Q' = \{q_2, f\}$ :

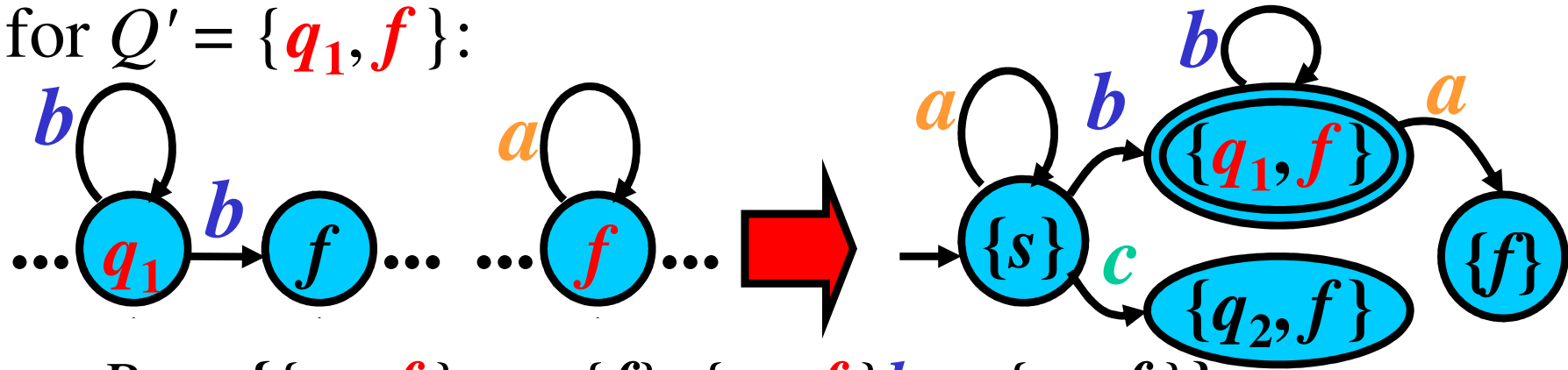


$$R_d := R_d \cup \{ \{q_2, f\} a \rightarrow \{f\}, \{q_2, f\} c \rightarrow \{q_2, f\} \}$$

$$Q_{new} = \{ \{f\} \}, Q_d = Q_d \cup \{ \{q_2, f\} \},$$

# $\epsilon$ -free FA to DFA: Example 2/3

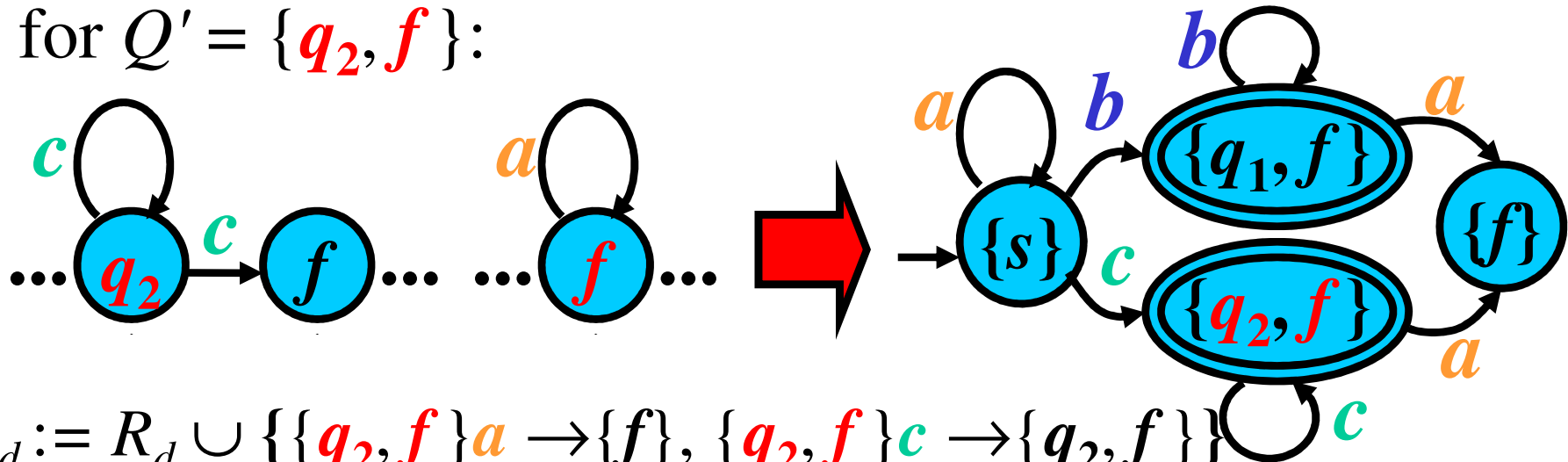
for  $Q' = \{q_1, f\}$ :



$$R_d := R_d \cup \{ \{q_1, f\} a \rightarrow \{f\}, \{q_1, f\} b \rightarrow \{q_1, f\} \}$$

$$Q_{new} = \{ \{q_2, f\}, \{f\} \}, Q_d = Q_d \cup \{ \{q_1, f\} \}, F_d := \emptyset \cup \{ \{q_1, f\} \}$$

for  $Q' = \{q_2, f\}$ :

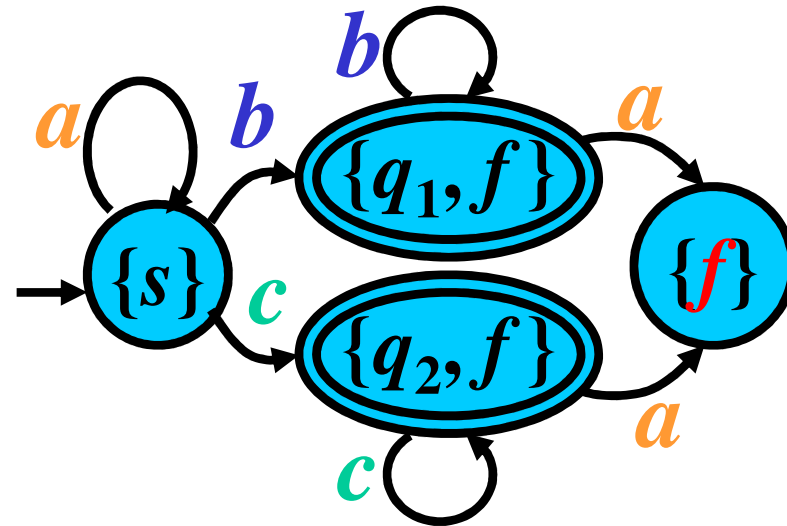
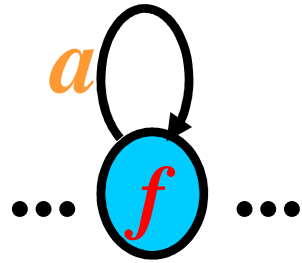


$$R_d := R_d \cup \{ \{q_2, f\} a \rightarrow \{f\}, \{q_2, f\} c \rightarrow \{q_2, f\} \}$$

$$Q_{new} = \{ \{f\} \}, Q_d = Q_d \cup \{ \{q_2, f\} \}, F_d := F_d \cup \{ \{q_2, f\} \}$$

# $\epsilon$ -free FA to DFA: Example 3/3

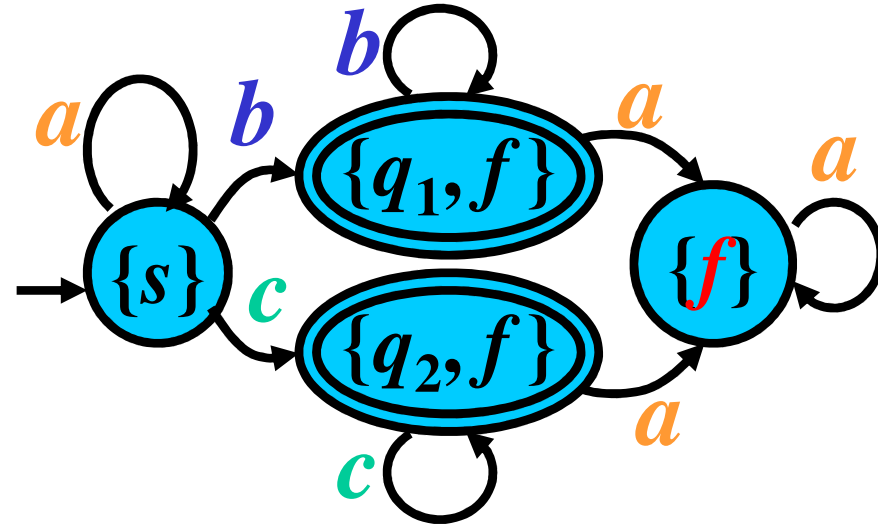
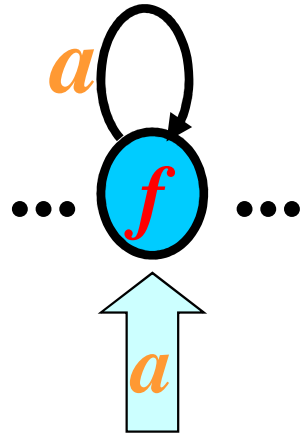
for  $Q' = \{f\}$ :





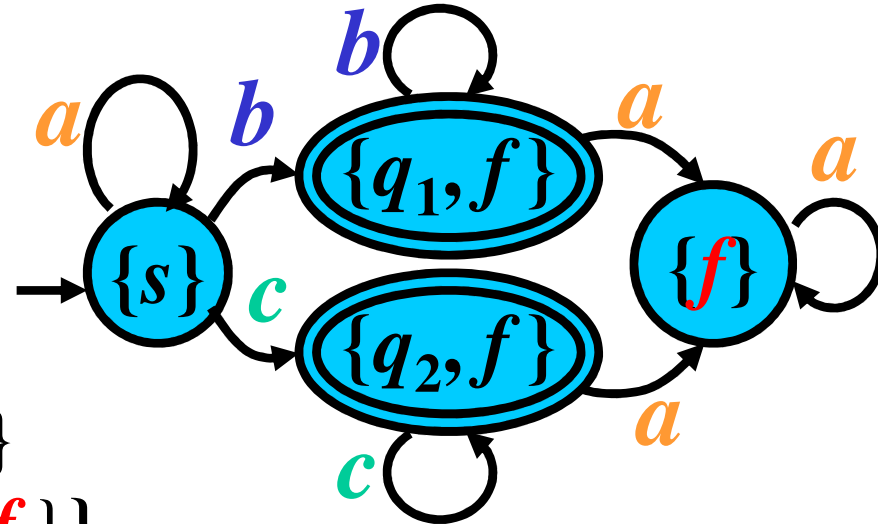
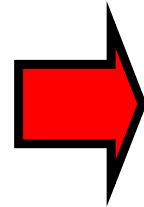
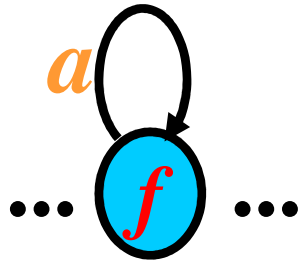
# $\epsilon$ -free FA to DFA: Example 3/3

for  $Q' = \{f\}$ :



# $\epsilon$ -free FA to DFA: Example 3/3

for  $Q' = \{f\}$ :

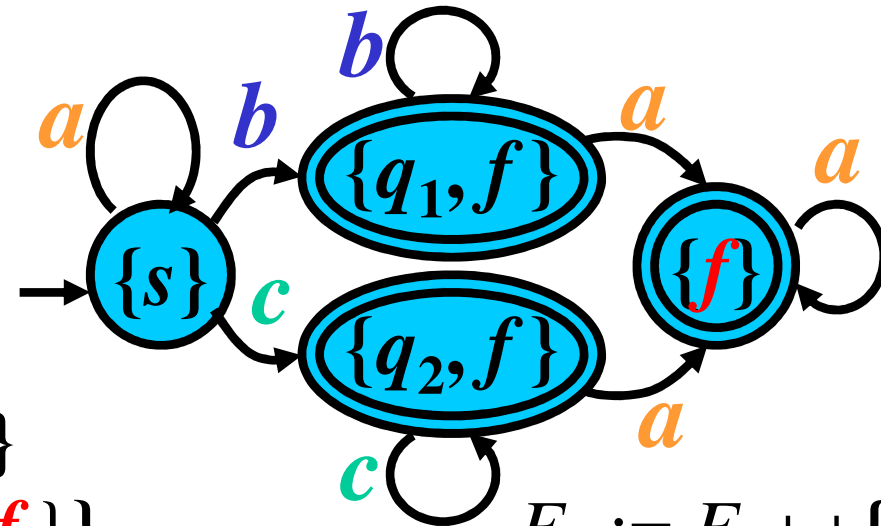
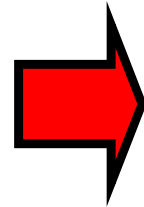
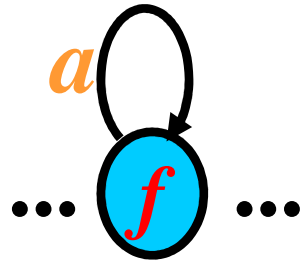


$$R_d := R_d \cup \{\{f\}a \rightarrow \{f\}\}$$

$$Q_{new} = \emptyset, Q_d = Q_d \cup \{\{f\}\},$$

# $\epsilon$ -free FA to DFA: Example 3/3

for  $Q' = \{f\}$ :



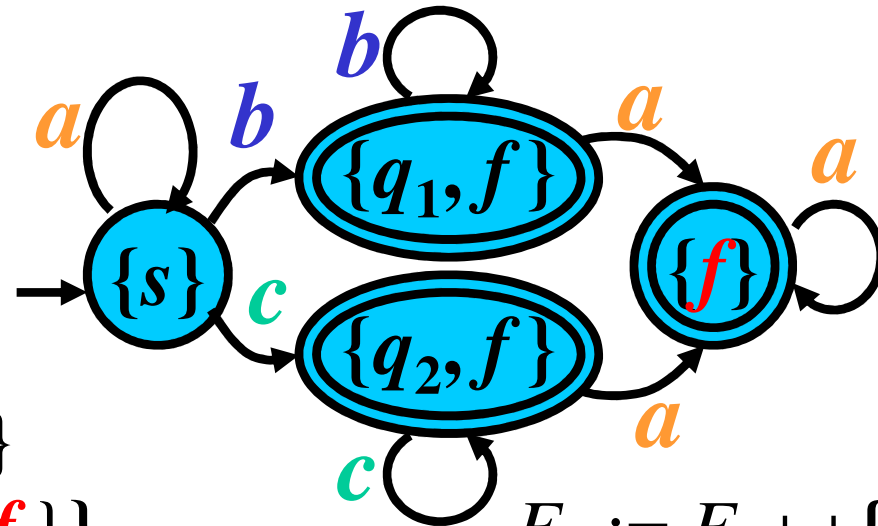
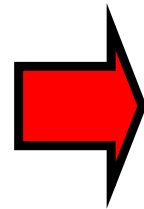
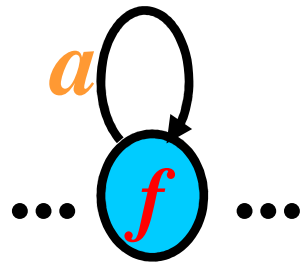
$$R_d := R_d \cup \{\{f\}a \rightarrow \{f\}\}$$

$$Q_{new} = \emptyset, Q_d = Q_d \cup \{\{f\}\},$$

$$F_d := F_d \cup \{\{f\}\}$$

# $\epsilon$ -free FA to DFA: Example 3/3

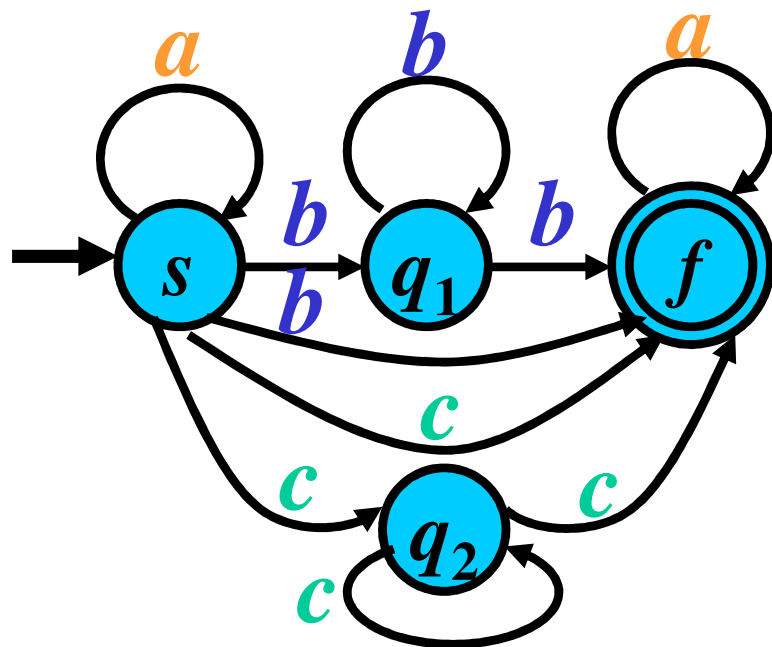
for  $Q' = \{f\}$ :



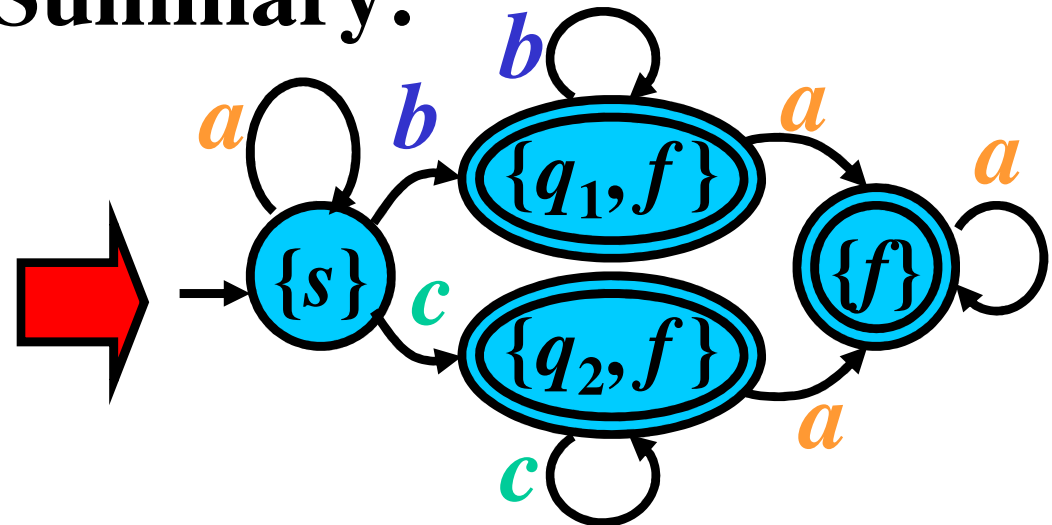
$$R_d := R_d \cup \{\{f\}a \rightarrow \{f\}\}$$

$$Q_{new} = \emptyset, Q_d = Q_d \cup \{\{f\}\},$$

$$F_d := F_d \cup \{\{f\}\}$$



Summary:



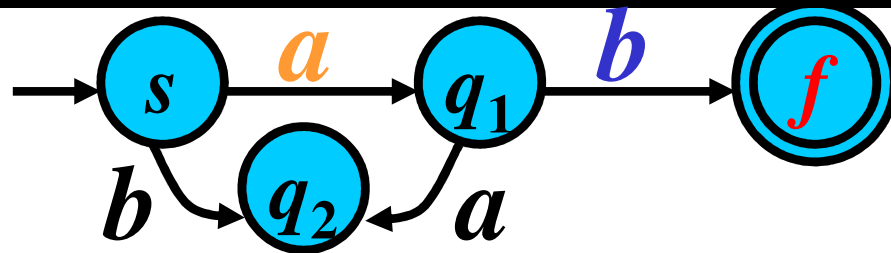
# Terminating States

**Gist:** State  $q$  is *terminating* if a string takes DFA from  $q$  to a final state.

**Definition:** Let  $M = (Q, \Sigma, R, s, F)$  be a DFA. A state  $q \in Q$  is *terminating* if there exists  $w \in \Sigma^*$  such that  $qw \vdash^* f$  with  $f \in F$ ; otherwise,  $q$  is *nonterminating*.

**Note:** Each nonterminating state can be removed from DFA

**Example:**

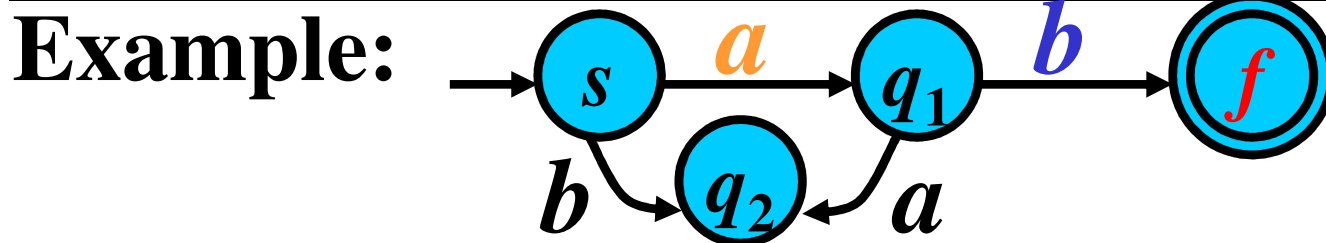


# Terminating States

**Gist:** State  $q$  is *terminating* if a string takes DFA from  $q$  to a final state.

**Definition:** Let  $M = (Q, \Sigma, R, s, F)$  be a DFA. A state  $q \in Q$  is *terminating* if there exists  $w \in \Sigma^*$  such that  $qw \vdash^* f$  with  $f \in F$ ; otherwise,  $q$  is *nonterminating*.

**Note:** Each nonterminating state can be removed from DFA



State  $s$  - terminating:  $w = ab$  :  $sab \vdash q_1b \vdash f$

State  $q_1$  - terminating:  $w = b$  :  $q_1b \vdash f$

State  $f$  - terminating:  $w = \varepsilon$  :  $f \vdash^0 f$

State  $q_2$  - **nonterminating** (there is no  $w \in \Sigma^*$   
such that  $q_2w \vdash^* q, q \in F$ )

# Algorithm: Removal of nont. states

- **Input:** DFA:  $M = (Q, \Sigma, R, s, F)$
  - **Output:** DFA:  $M_t = (Q_t, \Sigma, R_t, s, F)$
- 

- **Method:**

- $Q_0 := F; i := 0;$
- **repeat**
  - $i := i + 1;$
  - $Q_i := Q_{i-1} \cup \{q: qa \rightarrow p \in R, a \in \Sigma, p \in Q_{i-1}\};$
- until**  $Q_i = Q_{i-1};$
- $Q_t := Q_i;$
- $R_t := \{qa \rightarrow p: qa \rightarrow p \in R, p, q \in Q_t, a \in \Sigma\}.$

# Nonterminating States: Example

$M = (Q, \Sigma, R, s, F)$ , where:  $Q = \{s, q_1, q_2, f\}$ ,  $\Sigma = \{a, b\}$ ,  
 $R = \{sa \rightarrow q_1, sb \rightarrow q_2, q_1a \rightarrow q_2, q_1b \rightarrow f\}$ ,  $F = \{f\}$

---



# Nonterminating States: Example

$M = (Q, \Sigma, R, s, F)$ , where:  $Q = \{s, q_1, q_2, f\}$ ,  $\Sigma = \{a, b\}$ ,  
 $R = \{sa \rightarrow q_1, sb \rightarrow q_2, q_1a \rightarrow q_2, q_1b \rightarrow f\}$ ,  $F = \{f\}$

---

$Q_0 = \{f\}$

---

# Nonterminating States: Example

$M = (Q, \Sigma, R, s, F)$ , where:  $Q = \{s, q_1, q_2, f\}$ ,  $\Sigma = \{a, b\}$ ,  
 $R = \{sa \rightarrow q_1, sb \rightarrow q_2, q_1a \rightarrow q_2, q_1b \rightarrow f\}$ ,  $F = \{f\}$

---

$$Q_0 = \{f\}$$


---

1)  $qd \rightarrow f$ ;  $q \in Q$ ;  $d \in \Sigma$ :  $q_1b \rightarrow f$

$$Q_1 = \{f\} \cup \{q_1\} = \{f, q_1\}$$


---

# Nonterminating States: Example

$M = (Q, \Sigma, R, s, F)$ , where:  $Q = \{s, q_1, q_2, f\}$ ,  $\Sigma = \{a, b\}$ ,  
 $R = \{sa \rightarrow q_1, sb \rightarrow q_2, q_1a \rightarrow q_2, q_1b \rightarrow f\}$ ,  $F = \{f\}$

---


$$Q_0 = \{f\}$$


---

$$1) \quad qd \rightarrow f; q \in Q; d \in \Sigma: \quad q_1b \rightarrow f$$

$$Q_1 = \{f\} \cup \{q_1\} = \{f, q_1\}$$


---

$$2) \quad \begin{array}{ll} qd \rightarrow f; q \in Q; d \in \Sigma: & q_1b \rightarrow f \\ qd \rightarrow q_1; q \in Q; d \in \Sigma: & sa \rightarrow q_1 \end{array}$$

$$Q_2 = \{f, q_1\} \cup \{q_1, s\} = \{f, q_1, s\}$$


---

# Nonterminating States: Example

$M = (Q, \Sigma, R, s, F)$ , where:  $Q = \{s, q_1, q_2, f\}$ ,  $\Sigma = \{a, b\}$ ,  
 $R = \{sa \rightarrow q_1, sb \rightarrow q_2, q_1a \rightarrow q_2, q_1b \rightarrow f\}$ ,  $F = \{f\}$

---


$$Q_0 = \{f\}$$


---

$$1) qd \rightarrow f; q \in Q; d \in \Sigma: \quad q_1b \rightarrow f$$

$$Q_1 = \{f\} \cup \{q_1\} = \{f, q_1\}$$


---

$$2) \begin{array}{ll} qd \rightarrow f; q \in Q; d \in \Sigma: & q_1b \rightarrow f \\ qd \rightarrow q_1; q \in Q; d \in \Sigma: & sa \rightarrow q_1 \end{array}$$

$$Q_2 = \{f, q_1\} \cup \{q_1, s\} = \{f, q_1, s\}$$


---

$$3) \begin{array}{ll} qd \rightarrow f; q \in Q; d \in \Sigma: & q_1b \rightarrow f \\ qd \rightarrow q_1; q \in Q; d \in \Sigma: & sa \rightarrow q_1 \\ qd \rightarrow s; q \in Q; d \in \Sigma: & \text{none} \end{array}$$

$$Q_3 = \{f, q_1, s\} \cup \{q_1, s\} = \{f, q_1, s\} = Q_2 = Q_t$$


---

# Nonterminating States: Example

$M = (Q, \Sigma, R, s, F)$ , where:  $Q = \{s, q_1, q_2, f\}$ ,  $\Sigma = \{a, b\}$ ,  
 $R = \{sa \rightarrow q_1, sb \rightarrow q_2, q_1a \rightarrow q_2, q_1b \rightarrow f\}$ ,  $F = \{f\}$

---


$$Q_0 = \{f\}$$


---

$$1) qd \rightarrow f; q \in Q; d \in \Sigma: \quad q_1b \rightarrow f$$

$$Q_1 = \{f\} \cup \{q_1\} = \{f, q_1\}$$


---

$$2) qd \rightarrow f; q \in Q; d \in \Sigma: \quad q_1b \rightarrow f$$

$$qd \rightarrow q_1; q \in Q; d \in \Sigma: \quad sa \rightarrow q_1$$

$$Q_2 = \{f, q_1\} \cup \{q_1, s\} = \{f, q_1, s\}$$


---

$$3) qd \rightarrow f; q \in Q; d \in \Sigma: \quad q_1b \rightarrow f$$

$$qd \rightarrow q_1; q \in Q; d \in \Sigma: \quad sa \rightarrow q_1$$

$$qd \rightarrow s; q \in Q; d \in \Sigma: \quad \text{none}$$

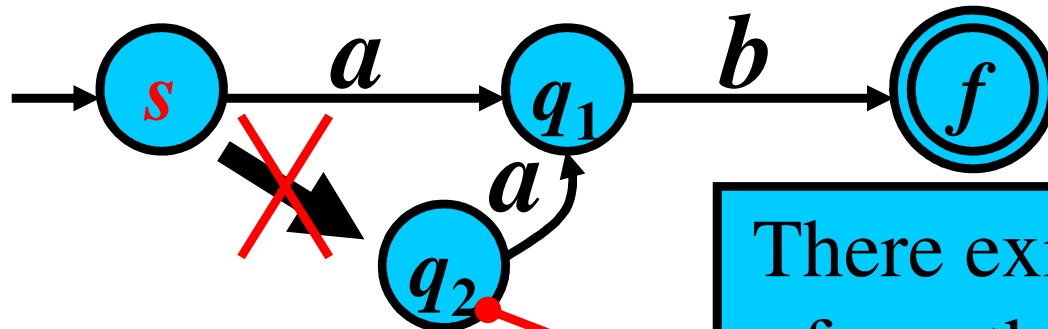
$$Q_3 = \{f, q_1, s\} \cup \{q_1, s\} = \{f, q_1, s\} = Q_2 = Q_t$$


---

$$R_t = \{sa \rightarrow q_1, sb \not\rightarrow q_2, q_1a \not\rightarrow q_2, q_1b \rightarrow f\}$$

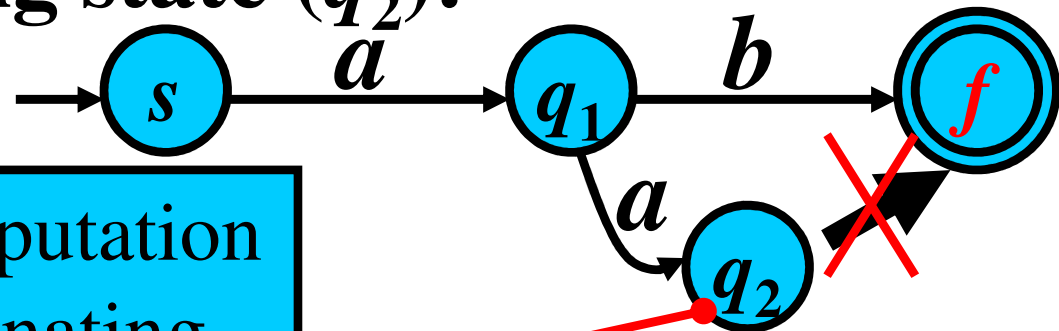
# Summary: States to Remove

## 1) Inaccessible state ( $q_2$ ):



There exists no computation from the start state to this inaccessible state.

## 2) Nonterminating state ( $q_2$ ):



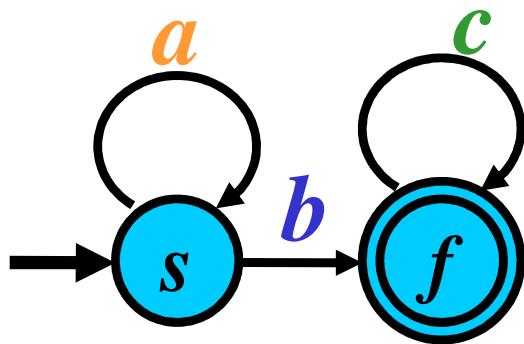
There exists no computation from this nonterminating state to a final state.

# Complete DFA

**Gist: Complete DFA cannot get stuck.**

**Definition:** Let  $M = (Q, \Sigma, R, s, F)$  be a **DFA**.  $M$  is *complete*, if for any  $p \in Q$ ,  $a \in \Sigma$  there is exactly one rule of the form  $pa \rightarrow q \in R$  for some  $q \in Q$ ; otherwise,  $M$  is *incomplete*

**Conversion:** Incomplete DFA



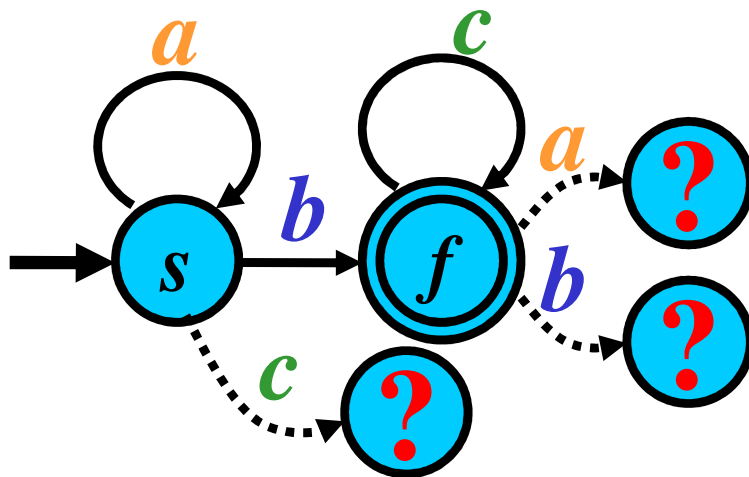
$$\Sigma = \{a, b, c\}$$

# Complete DFA

**Gist: Complete DFA cannot get stuck.**

**Definition:** Let  $M = (Q, \Sigma, R, s, F)$  be a **DFA**.  $M$  is *complete*, if for any  $p \in Q$ ,  $a \in \Sigma$  there is exactly one rule of the form  $pa \rightarrow q \in R$  for some  $q \in Q$ ; otherwise,  $M$  is *incomplete*

**Conversion:** Incomplete DFA



$$\Sigma = \{a, b, c\}$$



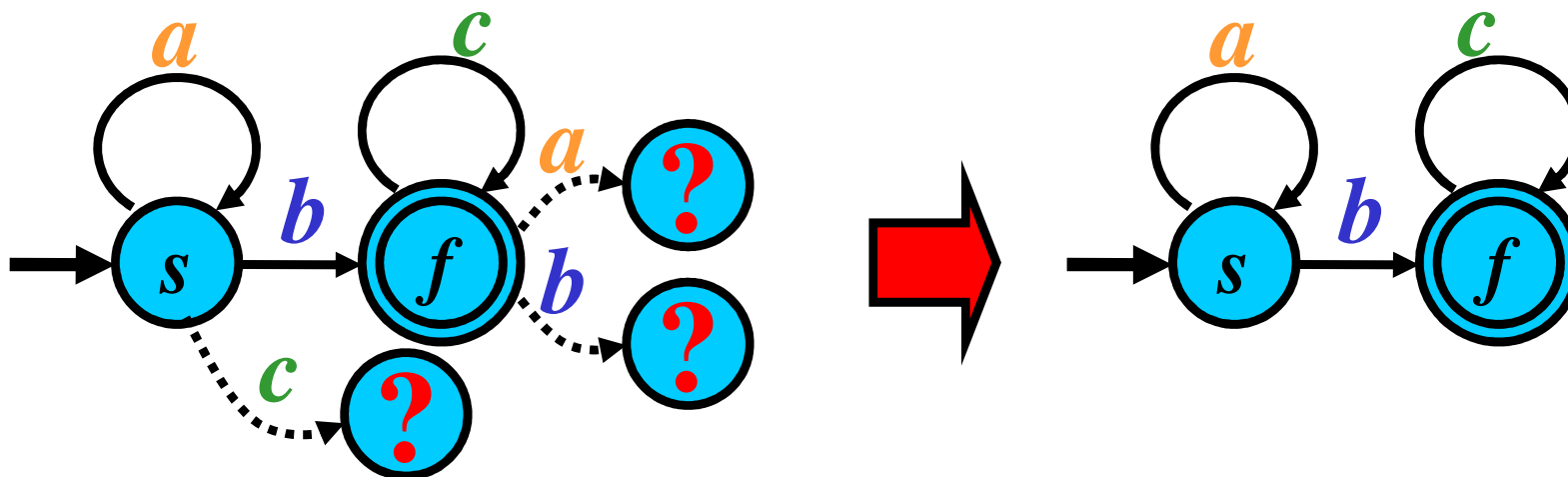
# Complete DFA

**Gist: Complete DFA cannot get stuck.**

**Definition:** Let  $M = (Q, \Sigma, R, s, F)$  be a **DFA**.  $M$  is *complete*, if for any  $p \in Q$ ,  $a \in \Sigma$  there is exactly one rule of the form  $pa \rightarrow q \in R$  for some  $q \in Q$ ; otherwise,  $M$  is *incomplete*

**Conversion:** Incomplete DFA

to Complete DFA



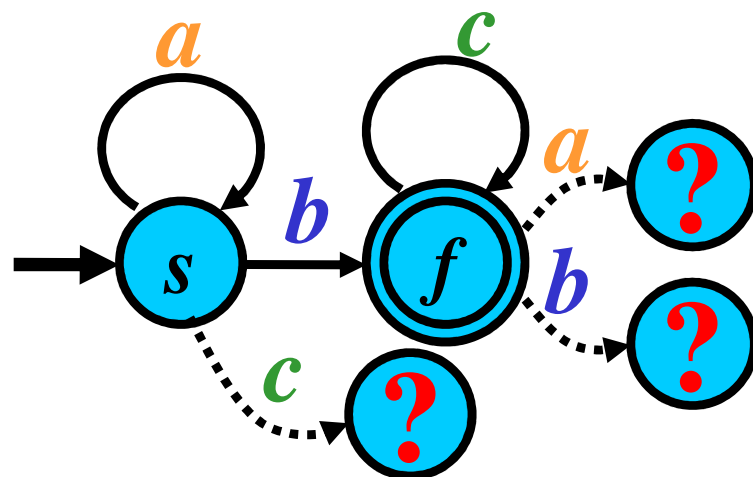
$$\Sigma = \{a, b, c\}$$

# Complete DFA

**Gist: Complete DFA cannot get stuck.**

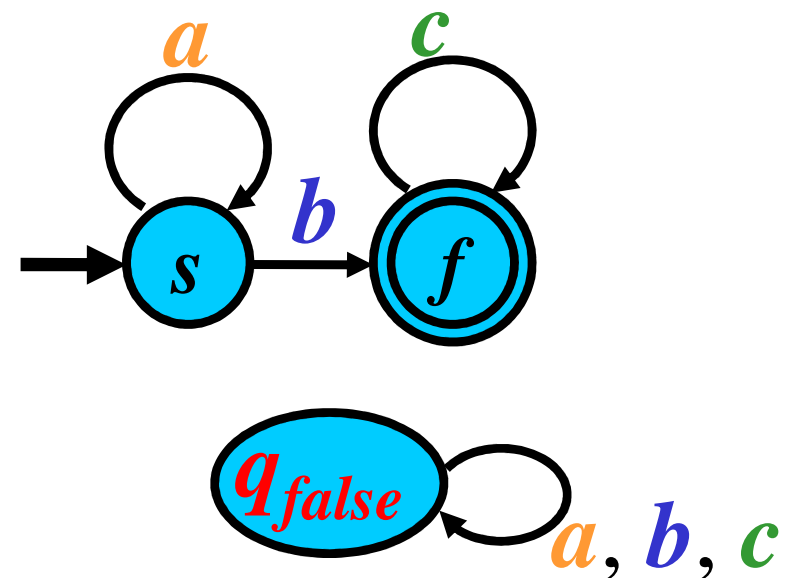
**Definition:** Let  $M = (Q, \Sigma, R, s, F)$  be a **DFA**.  $M$  is *complete*, if for any  $p \in Q$ ,  $a \in \Sigma$  there is exactly one rule of the form  $pa \rightarrow q \in R$  for some  $q \in Q$ ; otherwise,  $M$  is *incomplete*

**Conversion:** Incomplete DFA



$\Sigma = \{a, b, c\}$

to Complete DFA

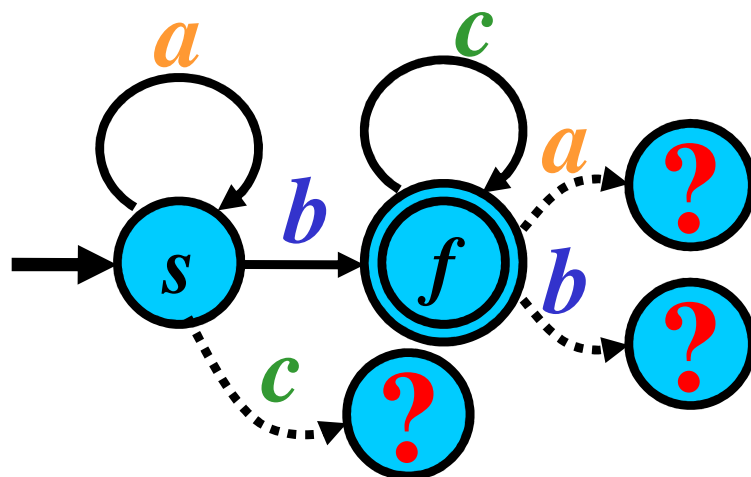


# Complete DFA

**Gist: Complete DFA cannot get stuck.**

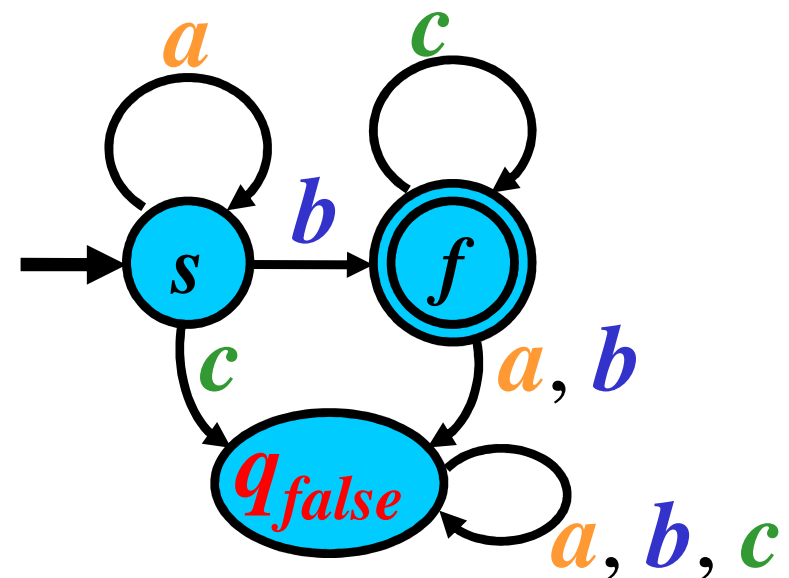
**Definition:** Let  $M = (Q, \Sigma, R, s, F)$  be a **DFA**.  $M$  is *complete*, if for any  $p \in Q$ ,  $a \in \Sigma$  there is exactly one rule of the form  $pa \rightarrow q \in R$  for some  $q \in Q$ ; otherwise,  $M$  is *incomplete*

**Conversion:** Incomplete DFA



$\Sigma = \{a, b, c\}$

to Complete DFA



# Algorithm: DFA to Complete DFA

**Gist: Add a “trap” state**

---

- **Input:** Incomplete DFA  $M = (Q, \Sigma, R, s, F)$
  - **Output:** Complete DFA  $M_c = (Q_c, \Sigma, R_c, s, F)$
- 

- **Method:**

- $Q_c := Q \cup \{q_{false}\};$
- $R_c := R \cup \{qa \rightarrow q_{false} : a \in \Sigma, q \in Q_c,$   
 $qa \rightarrow p \notin R, p \in Q\}.$

## Well-Specified FA

**Definition:** Let  $M = (Q, \Sigma, R, s, F)$  be a **complete DFA**. Then,  $M$  is *well-specified FA* (WSFA) if:

- 1)  $Q$  has no inaccessible state
- 2)  $Q$  has no more than one nonterminating state

---

**Note:** If well-specified FA has one nonterminating state, then it is  $q_{false}$  from the previous algorithm.

---

**Theorem:** For every FA  $M$ , there is an equivalent WSFA  $M_{ws}$ .

**Proof:** Use the next algorithm.

# Algorithm: FA to WSFA

- **Input:** FA  $M$
  - **Output:** WSFA  $M_{ws}$
- 
- **Method:**
    - convert a FA  $M$  to an equivalent  $\varepsilon$ -free FA  $M'$
    - convert a  $M'$  to an equivalent DFA  $M_d$  without any inaccessible state
    - convert  $M_d$  to an equivalent DFA  $M_t$  without any nonterminating state
    - convert  $M_t$  to an equivalent complete DFA  $M_c$
    - $M_{ws} := M_c$
- Note:** No more than one nonterminating state in  $M_{ws}$  —  $q_{false}$

# Variants of FA: Summary

|   | FA       | $\epsilon$ -free FA | DFA      | Complete FA | WSFA     |
|---|----------|---------------------|----------|-------------|----------|
| Number of rules of the form $p \rightarrow q$ ,<br>where $p, q \in Q$               | 0- $n$   | 0                   | 0        | 0           | 0        |
| Number of rules of the form $pa \rightarrow q$ ,<br>for any $p \in Q, a \in \Sigma$ | 0- $n$   | 0- $n$              | 0-1      | 1           | 1        |
| Number of inaccessible states   | 0- $n$   | 0- $n$              | 0- $n$   | 0- $n$      | 0        |
| Number of nonterminating states   | 0- $n$   | 0- $n$              | 0- $n$   | 0- $n$      | 0-1      |
| Number of this FAs for any regular<br>language.                                     | $\infty$ | $\infty$            | $\infty$ | $\infty$    | $\infty$ |