

§ 4.2 实标量场量子化

一. 经典场的正则量子化.

1. 经典标量场

$$\mathcal{L}_\phi = \frac{1}{2} \partial^\mu \phi \partial_\mu \phi - \frac{1}{2} m^2 \phi^2 = \frac{1}{2} (\dot{\phi}^2 - (\nabla \phi)^2) - \frac{1}{2} m^2 \phi^2$$

拉氏方程. $(\square + m^2) \phi(x) = 0$. 或 $(\frac{\partial^2}{\partial t^2} - \nabla^2 + m^2) \phi(x) = 0$.

2. 正则量子化.

引入正则动量

$$\pi(x) = \frac{\partial \mathcal{L}}{\partial \dot{\phi}(x)} = \dot{\phi}(x),$$

哈密顿量

$$H \equiv \int (\pi \dot{\phi} - \mathcal{L}) d^3x = \int [\pi^2 - \frac{1}{2} (\pi^2 - (\nabla \phi)^2) + \frac{1}{2} m^2 \phi^2] d^3x$$

$$\therefore H = \int \mathcal{H} d^3x, \quad \mathcal{H} = \frac{1}{2} [\pi^2(\vec{x}, t) + (\nabla \phi(\vec{x}, t))^2 + m^2 \phi^2(\vec{x}, t)]$$

假定中, π 为厄米算符, 满足正则对易关系.

$$[\phi(\vec{x}, t), \pi(\vec{x}', t)] = i \delta^3(\vec{x} - \vec{x}')$$

$$[\phi(\vec{x}, t), \phi(\vec{x}', t)] = [\pi(\vec{x}, t), \pi(\vec{x}', t)] = 0.$$

则可推出海森堡方程 (H 为哈密顿算符)

$$\begin{aligned} [H, \phi(\vec{x}, t)] &= \int d^3\vec{x}' \frac{1}{2} [\pi^2(\vec{x}', t) + (\nabla' \phi(\vec{x}', t))^2 + m^2 \phi^2(\vec{x}', t), \phi(\vec{x}, t)] \\ &= \int d^3\vec{x}' \pi(\vec{x}', t) [\pi(\vec{x}', t), \phi(\vec{x}', t)] = -i \pi(\vec{x}, t) = -i \dot{\phi}(\vec{x}, t). \end{aligned}$$

$$\therefore \dot{\phi}(\vec{x}, t) = i [H, \phi(\vec{x}, t)]$$

$$\begin{aligned} [H, \pi(\vec{x}, t)] &= \int d^3\vec{x}' \frac{1}{2} [\pi^2(\vec{x}', t) + (\nabla' \phi(\vec{x}', t))^2 + m^2 \phi^2(\vec{x}', t), \pi(\vec{x}, t)] \\ &= \int d^3\vec{x}' \{ \nabla' \phi(\vec{x}', t) [\nabla' \phi(\vec{x}', t), \pi(\vec{x}', t)] + m^2 \phi(\vec{x}', t) [\phi(\vec{x}', t), \pi(\vec{x}', t)] \} \\ &= \int d^3\vec{x}' \nabla' \phi(\vec{x}', t) \nabla' [\phi(\vec{x}', t), \pi(\vec{x}', t)] + \int d^3\vec{x}' m^2 \phi(\vec{x}', t) i \delta^3(\vec{x}' - \vec{x}') \\ &= \int d^3\vec{x}' \nabla' \phi(\vec{x}', t) \nabla' (i \delta^3(\vec{x}' - \vec{x})) + i m^2 \phi(\vec{x}, t) \\ &= -\nabla \int d^3\vec{x}' \nabla' \phi(\vec{x}', t) i \delta^3(\vec{x}' - \vec{x}) + i m^2 \phi(\vec{x}, t) \\ &= -\nabla i \nabla \phi(\vec{x}, t) + i m^2 \phi(\vec{x}, t) = -i \nabla^2 \phi(\vec{x}, t) + i m^2 \phi(\vec{x}, t) \quad \text{利用 K-G 方程} \\ &= -i \dot{\phi}(\vec{x}, t) = -i \pi(\vec{x}, t) \quad \therefore \dot{\pi}(\vec{x}, t) = i [H, \pi(\vec{x}, t)] \end{aligned}$$

综上, 海森堡方程为 $\begin{cases} \dot{\phi}(\vec{x}, t) = i[H, \phi(\vec{x}, t)] \\ \dot{\pi}(\vec{x}, t) = i[H, \pi(\vec{x}, t)] \end{cases}$

又动量算符

$$\vec{P} = \int d^3x T^{0i} = \int d^3x (-g^{0i} \mathcal{L} + \partial^0 \phi \partial^i \phi) \stackrel{\partial^0 = (\frac{\partial}{\partial t}, -\nabla)}{\downarrow} \int d^3x (+\dot{\phi}(\nabla \phi)) = \int \pi(\nabla \phi) d^3x.$$

则

$$[\vec{P}, \phi(\vec{x}, t)] = \int d^3\vec{x}' [\pi(\vec{x}', t) \nabla' \phi(\vec{x}', t), \phi(\vec{x}, t)] = - \int d^3\vec{x}' [\pi(\vec{x}', t), \phi(\vec{x}, t)] \nabla' \phi(\vec{x}', t) \\ = - \int d^3\vec{x}' (-i \delta(\vec{x}' - \vec{x})) \nabla' \phi(\vec{x}', t) = i \nabla \phi(\vec{x}, t)$$

$$[\vec{P}, \pi(\vec{x}, t)] = - \int d^3\vec{x}' [\pi(\vec{x}', t) \nabla' \phi(\vec{x}', t), \pi(\vec{x}, t)] = - \int d^3\vec{x}' \pi(\vec{x}', t) \nabla' [\phi(\vec{x}', t), \pi(\vec{x}, t)] \\ = - \int d^3\vec{x}' \pi(\vec{x}', t) \nabla' (i \delta(\vec{x}' - \vec{x})) = i \nabla \int d^3\vec{x}' \pi(\vec{x}', t) \delta(\vec{x}' - \vec{x}) = i \nabla \pi(\vec{x}, t)$$

综上, $\begin{cases} \nabla \phi(\vec{x}, t) = i [\vec{P}, \phi(\vec{x}, t)] \\ \nabla \pi(\vec{x}, t) = i [\vec{P}, \pi(\vec{x}, t)] \end{cases}$

考虑到 $P_m = i \frac{\partial}{\partial x^m} = i \partial_m = i(\frac{\partial}{\partial t}, \nabla)$, 且 $P_m = (H, -\vec{P})$, 故

$$\therefore \begin{cases} \frac{\partial}{\partial x^m} \phi(\vec{x}, t) = i [P_m, \phi(\vec{x}, t)] \\ \frac{\partial}{\partial x^m} \pi(\vec{x}, t) = i [P_m, \pi(\vec{x}, t)] \end{cases} \quad \text{标量场在时空平移下变化性质}$$

可证, 上式的解为 $\phi(x) = e^{iPx} \phi(0) e^{-iPx}$, $\phi(x+b) = e^{ip_b} \phi(x) e^{-ip_b}$

证明:

法一(直接法): 利用 $e^A B e^{-A} = B + [A, B] + \frac{1}{2!} [A, [A, B]] + \dots$

将 $\phi(x)$ 在 $x=0$ 附近做泰勒展开

$$\begin{aligned} \phi(x) &= \phi(0) = \left. \frac{\partial \phi(x)}{\partial x^m} \right|_{x^m=0} x^m + \frac{1}{2!} \left. \frac{\partial}{\partial x^m} \frac{\partial \phi(x)}{\partial x^l} \right|_{x^m=0, x^l=0} x^m x^l + \dots \\ &= \phi(0) + [i P_m x^m, \phi(x)] \Big| + \frac{1}{2!} [i P_m x^m, [i P_l x^l, \phi(x)]] \Big| + \dots \\ &= e^{iPx} \phi(0) e^{-iPx} \quad \begin{matrix} \phi(0) = \phi(0) \\ \phi(x) = \phi(0) \end{matrix} \end{aligned}$$

法二(反向检验法)

$$\begin{aligned} \frac{\partial}{\partial x^m} \phi(x) &= \partial_m \phi(x) = \partial_m (e^{iPx} \phi(0) e^{-iPx}) = i P_m e^{iPx} \phi(0) e^{-iPx} + e^{iPx} \phi(0) e^{-iPx} (-i P_m) \\ &= i (P_m \phi(x) - \phi(x) P_m) = i [P_m, \phi(x)] \end{aligned}$$

3. 系统的动力学不变量.

Noether定理告诉我们，物理系统具有连续变换下的不变性时，一定存在相应的守恒量。如时间平移不变时具有能量守恒，空间平移不变时具有动量守恒，空间转动不变时具有角动量守恒。因而，对于一个具有四维时空平移不变性的系统，其四维动量 P^{μ} 守恒；具有正洛伦兹变换下的不变性的系统，其广义角动量 M^{rp} 守恒。而这些力学量不是别的，正是上述量子化过程中力学量算符；如能量对应于哈密顿量算符，动量对应于动量算符，类似，广义角动量对应于广义角动量算符，向动量对应于四动量算符，

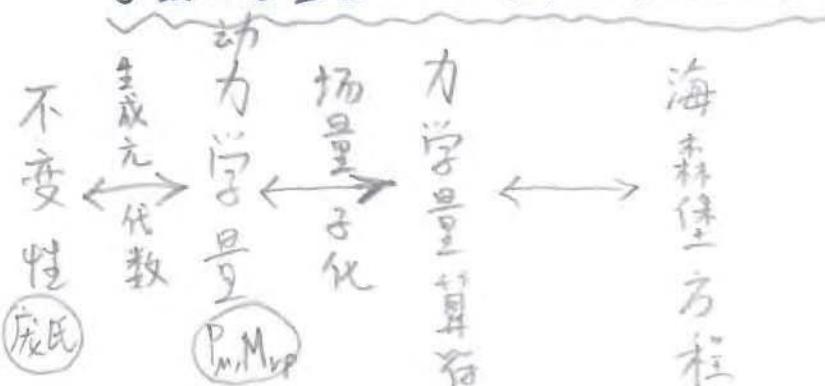
$$\begin{cases} P^{\mu} = \int d^3x T^{\mu\nu} = \int d^3x (-g^{\mu\nu} L + \partial^{\mu}\phi \partial^{\nu}\phi), \\ M^{rp} = \int d^3x (x^r T^{rp} - x^p T^{rv}) \end{cases}$$

类似于场量在四维时空平移下的变化，场量在四维时空广义转动下的变化为

$$\begin{cases} P_{\mu} = i\partial_{\mu}, & \left\{ \frac{\partial}{\partial x^{\mu}}\phi(\vec{x}, t) = i[P_{\mu}, \phi(\vec{x}, t)] \right. \\ M_{rp} = i(x_r \partial_p - x_p \partial_r), & \left. (x_r \partial_p - x_p \partial_r)\phi(\vec{x}, t) = i[M_{rp}, \phi(\vec{x}, t)] \right. \end{cases} \quad \text{解} \quad \left\{ \phi(\vec{x}) = e^{iP\vec{x}} \phi(0) e^{-iP\vec{x}} \right\}$$

系统的动力学量 P_{μ}, M_{rp} ，作为系统相应变换下的守恒量，同时也是相应变换的生成元，因而满足生成元代数关系。而目前，当场量量子化后，这些用场来表示的动力学量成为了力学量算符，可以证明，此时的动力学量算符仍然满足前述力学量生成元代数关系。因此说，

我们所进行的量子化正则（包括中、π的量子化假定，海森堡方程）与力学量生成元 P_{μ}, M_{rp} 是自洽的，进而量子化满足了庞加莱不变性。



二. 傅立叶变换/展开

下面, 利用在空间 V 内的系统中的场量 $\psi(x, t)$ 满足周期性边界条件.

厄米特和 Klein-Gordon 方程, 获得标量场 $\psi(x, t)$ 的傅立叶展开形式的解。

1. 波函数周期性边界条件下的平面波解.

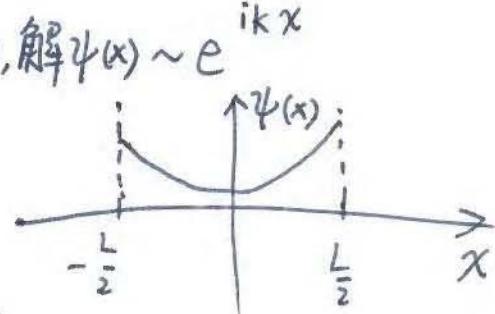
1). 一维平面波

对一维自由粒子波, $H\psi = k^2\psi$, $-\frac{d^2}{dx^2}\psi(x) = k^2\psi(x)$, 解 $\psi(x) \sim e^{ikx}$

2) 周期性边界条件.

函数周期为 L , $f(x) = f(x+L)$

波函数满足周期为 L , 则 $e^{-ik\frac{L}{2}} = e^{ik\frac{L}{2}}$, 即 $e^{ikL} = 1$.



∴ $KL = 2n\pi$, $K = n\frac{2\pi}{L}$ ($n=0, \pm 1, \pm 2, \dots$)

3) 本征函数
∴ 波函数 $\psi(x) \sim e^{ik_n x}$, $k_n = n\frac{2\pi}{L}$, x 连续, k_n 分立.

本征值 $H = k^2$: $\{0, (\frac{2\pi}{L})^2, (\frac{4\pi}{L})^2, (\frac{6\pi}{L})^2, \dots\}$, 有下限无上限

本征函数 $\{e^{in\frac{2\pi}{L}x} | n=0, \pm 1, \pm 2, \dots\}$, 正交归一, 完备.

$$\text{① 正交归一: } \int_{-L/2}^{L/2} dx e^{i(k-k')x} = L \delta_{nn'} \quad \xrightarrow{\text{三维}} \int_{-L/2}^{L/2} dx e^{i(k-k')x} = \sqrt{L} \delta_{nn'}$$

$$\text{证明: } \int_{-L/2}^{L/2} dx e^{i(k-k')x} = \int_{-L/2}^{L/2} dx e^{i(k-k')x} = \frac{e^{i(k-k')\frac{L}{2}} - e^{-i(k-k')\frac{L}{2}}}{i(k-k')} = 2 \frac{\sin[(k-k')\frac{L}{2}]}{k-k'}$$

$$\text{周期边界} \quad \underline{=} 2 \frac{\sin[(n-n')\frac{2\pi}{L}\frac{L}{2}]}{(n-n')\frac{2\pi}{L}} = L \frac{\sin(n-n')\pi}{(n-n')\pi} = \begin{cases} L & \text{当 } n=n' \\ 0 & \text{当 } n \neq n' \end{cases} = L \delta_{nn'}$$

$$\text{② 完备性: } \sum_{k=-\infty}^{\infty} e^{ik(x-x')} = L \delta(x-x') \quad \xrightarrow{\text{三维}} \sum_{n=-\infty}^{\infty} e^{in\frac{2\pi}{L}(x-x')} = \sqrt{L} \delta(x-x')$$

$$\lim_{N \rightarrow \infty} S_N = \lim_{N \rightarrow \infty} \sum_{n=-N}^N A^n$$

$$\text{证明: } \sum_{k=-\infty}^{\infty} \langle x | k \rangle \langle k | x' \rangle = \sum_{n=-\infty}^{\infty} e^{ikx} e^{-ikx'} = \sum_{n=-\infty}^{\infty} e^{in\frac{2\pi}{L}(x-x')} = \lim_{N \rightarrow \infty} \sum_{n=-N}^N (e^{in\frac{2\pi}{L}(x-x')})^n = \lim_{N \rightarrow \infty} \sum_{n=-N}^N A^n$$

$$\text{记 } S_N = A^{-N} + A^{-N+1} + \dots + A^{-1} + A + \dots + A^N \quad \therefore (A-1)S_N = A^{N+2} - A^{-N}$$

$$AS_N = A^{-N+1} + A^{-N+2} + \dots + 1 + A + A^2 + \dots + A^{N+1},$$

$$\therefore S_N = \frac{A^{N+2} - A^{-N}}{A-1} = \frac{A^{N+\frac{1}{2}} - A^{-N-\frac{1}{2}}}{A^{\frac{1}{2}} - A^{-\frac{1}{2}}} = \frac{(e^{i\frac{2\pi}{L}(x-x')})^{N+\frac{1}{2}} - (e^{i\frac{2\pi}{L}(x-x')})^{-N-\frac{1}{2}}}{e^{i\frac{2\pi}{L}(x-x')} - e^{-i\frac{2\pi}{L}(x-x')}} = \frac{\sin[(2N+1)\frac{\pi}{L}(x-x')]}{\sin[\frac{\pi}{L}(x-x')]} \quad 11$$

$$\therefore \sum_{k=-\infty}^{\infty} e^{ikx} e^{ikx'} = \lim_{N \rightarrow \infty} \frac{\pi(x-x')}{\sin \frac{\pi}{L}(x-x')} \frac{\sin[(2N+1)\frac{\pi}{L}(x-x')]}{\pi(x-x')}$$

$$\text{讨论: } \frac{\pi(x-x')}{\sin \frac{\pi}{L}(x-x')} = L \frac{\frac{\pi}{L}(x-x')}{\sin \frac{\pi}{L}(x-x')} = \begin{cases} L & x=x' \\ \text{自身有限} & x \neq x' \end{cases}$$

$$\text{由 } \lim_{N \rightarrow \infty} \frac{\sin N(x-x')}{\pi(x-x')} = \delta(x-x'), \text{ 得 } \lim_{N \rightarrow \infty} \frac{\sin(2N+1)\frac{\pi}{L}(x-x')}{\pi(x-x')} = \delta(x-x') = \begin{cases} \infty & x=x' \\ 0 & x \neq x' \end{cases}$$

综上. $\sum_{k=-\infty}^{\infty} e^{ikx} e^{ikx'} = L \delta(x-x')$

4). 满足周期性边界条件时, $f(x)$ 可傅立叶展开如下 (其实不满足时也可展开).

傅氏展开 $\left\{ f(x) = \sum_{n=-\infty}^{\infty} c_n e^{in\frac{2\pi}{L}x} / \sqrt{L} \right.$

定理 $\left\{ c_n = \frac{1}{\sqrt{L}} \int_{-L/2}^{L/2} dx e^{-in\frac{2\pi}{L}x} f(x) \right.$

2. 动量空间的本征函数性质.

上面在坐标空间中考察了满足周期性边界条件时的本征函数 $\{e^{ik_n x} | n=0, \pm 1, \dots\}$

这些函数在动量上是分立的 $k_n = n \frac{2\pi}{L}$, ($n=0, \pm 1, \pm 2, \dots$), 这一方法形式上较简单。

另一种方法是令上述空间体积 $V \rightarrow \infty$ (从而 $L \rightarrow \infty$), 则此时本征函数的动量间隔 $\Delta k \rightarrow 0$, 从而动量成为连续的。这一方法的优点是, 此时动力学力学量能量、动量的形式更为简洁清晰, 从而便于显示场的粒子特性。

当 $L \rightarrow \infty$ 时动量取值: $k_1 = n_1 \frac{2\pi}{L}, k_2 = n_2 \frac{2\pi}{L}, k_3 = n_3 \frac{2\pi}{L}$.

动量空间的最小线元 $\Delta k_1 = \frac{2\pi}{L}, \Delta k_2 = \frac{2\pi}{L}, \Delta k_3 = \frac{2\pi}{L}$.

当 $L \rightarrow \infty$ 时,

$$dk_{1,2,3} = \frac{2\pi}{L} \Big|_{L \rightarrow \infty}, \quad d^3k = \frac{(2\pi)^3}{V} \Big|_{V \rightarrow \infty}, \quad \therefore \int d^3k = \frac{(2\pi)^3}{V} \sum_{k=-\infty}^{\infty}$$

动量求和变为 $\sum_k = \int \frac{V d^3k}{(2\pi)^3}$

利用 $\delta(\vec{k} - \vec{k}')$ 性质: $\int d^3k \delta(\vec{k} - \vec{k}') = 1 = \frac{(2\pi)^3}{V} \sum_k \frac{V}{(2\pi)^3} \delta_{\vec{k}, \vec{k}'}, \text{ 得 } \delta(\vec{k} - \vec{k}') = \frac{V}{(2\pi)^3} \delta_{\vec{k}, \vec{k}'}$

分立德尓塔函数变为 $\delta_{\vec{k}, \vec{k}'} = \frac{(2\pi)^3}{V} \delta(\vec{k} - \vec{k}')$

动量分立 $\xrightarrow{L \rightarrow \infty}$ 动量连续

$$\left\{ \begin{array}{l} \text{正交} \\ \text{归一} \end{array} \right. \int_{-\infty}^{+\infty} d^3x e^{i(\vec{k} \cdot \vec{x})} = V \delta_{\vec{k}, \vec{k}'} \quad \left\{ \begin{array}{l} \text{正交} \\ \text{归一} \end{array} \right. \int_{-\infty}^{+\infty} d^3x e^{i(\vec{k} \cdot \vec{x})} = (2\pi)^3 \delta(\vec{k} - \vec{k}')$$

$$\left. \begin{array}{l} \text{完备性} \sum_{\vec{k}} e^{i\vec{k} \cdot (\vec{x} - \vec{x}')} = V \delta(\vec{x} - \vec{x}') \\ \text{完备性} \int d^3k e^{i\vec{k} \cdot (\vec{x} - \vec{x}')} = (2\pi)^3 \delta(\vec{x} - \vec{x}') \end{array} \right.$$

3. 场函数满足周期边界条件，傅立叶展开如下：

$$\left\{ \begin{array}{l} \phi(\vec{x}, t) = \sum_{\vec{k}} \frac{1}{\sqrt{V}} e^{i\vec{k} \cdot \vec{x}} q_{\vec{k}}(t) \\ \pi(\vec{x}, t) = \sum_{\vec{k}} \frac{1}{\sqrt{V}} e^{-i\vec{k} \cdot \vec{x}} p_{-\vec{k}}(t) \end{array} \right. \quad \text{其中} \quad \left\{ \begin{array}{l} q_{\vec{k}}(t) = \frac{1}{\sqrt{V}} \int d^3x e^{-i\vec{k} \cdot \vec{x}} \phi(\vec{x}, t) \\ p_{-\vec{k}}(t) = \frac{1}{\sqrt{V}} \int d^3x e^{i\vec{k} \cdot \vec{x}} \pi(\vec{x}, t) \end{array} \right.$$

由场量的厄米性，发现 $q_{\vec{k}}(t)$ 和 $p_{\vec{k}}(t)$ 并不是厄米的。

$$\left\{ \begin{array}{l} \phi^+(\vec{x}, t) = \phi(\vec{x}, t) \text{ 厄米} \\ \pi^+(\vec{x}, t) = \pi(\vec{x}, t) \end{array} \right. \rightarrow \left\{ \begin{array}{l} q_{\vec{k}}^+(t) = q_{-\vec{k}}(t) \text{ 不厄米} \\ p_{\vec{k}}^+(t) = p_{-\vec{k}}(t) \end{array} \right.$$

经过傅立叶展开，场量成为动量空间的函数，独立变量为 $\{q_{\vec{k}}(t), p_{\vec{k}}(t)\}$

① 产生、湮灭算符 动量算子 的表示。（下面为了简单， $q_{\vec{k}}(t), p_{\vec{k}}(t)$ 中的 t 省略）

定义 $b_{\vec{k}}(t) = \sqrt{\frac{w}{2}} (q_{\vec{k}}(t) + \frac{i}{w} p_{-\vec{k}}(t))$, 其中 $w = \sqrt{\vec{k}^2 + m^2}$

得 $b_{\vec{k}}^+(t) = \sqrt{\frac{w}{2}} (q_{-\vec{k}}(t) - \frac{i}{w} p_{\vec{k}}(t))$

从而有 $\begin{cases} b_{\vec{k}}(t) = \sqrt{\frac{w}{2}} (q_{\vec{k}}(t) + \frac{i}{w} p_{-\vec{k}}(t)) \\ b_{-\vec{k}}^+(t) = \sqrt{\frac{w}{2}} (q_{-\vec{k}}(t) - \frac{i}{w} p_{\vec{k}}(t)) \end{cases}$, 反变换 $\begin{cases} q_{\vec{k}}(t) = \frac{1}{\sqrt{2w}} (b_{\vec{k}}(t) + b_{-\vec{k}}^+(t)) \\ p_{-\vec{k}}(t) = \frac{-iw}{\sqrt{2w}} (b_{\vec{k}}(t) - b_{-\vec{k}}^+(t)) \end{cases}$

代入场展开式。

$$\phi(\vec{x}, t) = \sum_{\vec{k}=-\infty}^{\infty} \frac{1}{\sqrt{2wV}} (b_{\vec{k}}(t) e^{i\vec{k} \cdot \vec{x}} + b_{-\vec{k}}^+(t) e^{-i\vec{k} \cdot \vec{x}})$$

$$\pi(\vec{x}, t) = \sum_{\vec{k}=-\infty}^{\infty} \frac{-iw}{\sqrt{2wV}} (b_{\vec{k}}(t) e^{i\vec{k} \cdot \vec{x}} - b_{-\vec{k}}^+(t) e^{-i\vec{k} \cdot \vec{x}})$$

② 满足 K-G 方程的场量解

根据 K-G 方程, $(\square + m^2) \phi(\vec{x}, t) = 0$, $\square = \partial_t^2 - \nabla^2$,

将 $\phi(\vec{x}, t) = \frac{1}{\sqrt{V}} \sum_{\vec{k}} e^{i\vec{k} \cdot \vec{x}} g_{\vec{k}}(t)$ 代入, 引入 $\omega^2 = \vec{k}^2 + m^2$,

两边乘 $\int_{-\infty}^L d^3x e^{-i\vec{k} \cdot \vec{x}}$, 利用正交归一性分立, 得

$$\frac{1}{\sqrt{V}} \sum_{\vec{k}} (\omega^2 + \partial_t^2) g_{\vec{k}}(t) \sqrt{\delta_{\vec{k}, \vec{k}}} = 0$$

$\therefore (\omega^2 + \partial_t^2) g_{\vec{k}}(t) = 0$, 解为 $g_{\vec{k}}(t) \sim e^{i\omega t}, e^{-i\omega t}$

进一步, 结合场算符的产生湮灭算符表示, 得 $b_{\vec{k}}(t) = b_{\vec{k}} e^{-i\omega t}$, $b_{\vec{k}}^+ (t) = b_{\vec{k}}^+ e^{i\omega t}$

$$\therefore \left\{ \begin{array}{l} \phi(\vec{x}, t) = \sum_{\vec{k}=-\infty}^{\infty} \frac{1}{\sqrt{2\omega V}} (b_{\vec{k}} e^{-i\vec{k} \cdot \vec{x}} + b_{\vec{k}}^+ e^{+i\vec{k} \cdot \vec{x}}) \\ \pi(\vec{x}, t) = \sum_{\vec{k}=-\infty}^{\infty} \frac{-i\omega}{\sqrt{2\omega V}} (b_{\vec{k}} e^{-i\vec{k} \cdot \vec{x}} - b_{\vec{k}}^+ e^{+i\vec{k} \cdot \vec{x}}) \end{array} \right.$$

其中 $\vec{k} \cdot \vec{x} = \omega t - \vec{k} \cdot \vec{x}$

$$\left\{ \begin{array}{l} \phi(\vec{x}, t) = \sum_{\vec{k}=-\infty}^{\infty} \frac{1}{\sqrt{2\omega V}} (b_{\vec{k}} e^{-i\vec{k} \cdot \vec{x}} + b_{\vec{k}}^+ e^{+i\vec{k} \cdot \vec{x}}) \\ \pi(\vec{x}, t) = \sum_{\vec{k}=-\infty}^{\infty} \frac{-i\omega}{\sqrt{2\omega V}} (b_{\vec{k}} e^{-i\vec{k} \cdot \vec{x}} - b_{\vec{k}}^+ e^{+i\vec{k} \cdot \vec{x}}) \end{array} \right.$$

动量为分立量.

$$\vec{k} = \vec{k}_n = \vec{n} \frac{2\pi}{L}, \vec{n} = 0, \pm 1, \pm 2, \dots$$

③ 下面确定展开式中的不含时振幅算子 $b_{\vec{k}}, b_{\vec{k}}^+$

利用 $L \rightarrow \infty$

当 $L \rightarrow \infty$ 时, 动量由分立 \rightarrow 连续, 将 $\sum_{\vec{k}} \rightarrow \int \frac{V}{(2\pi)^3} d^3k$,

$$\phi(\vec{x}, t) = \sum_{\vec{k}=-\infty}^{\infty} \frac{1}{\sqrt{2\omega V}} (b_{\vec{k}} e^{-i\vec{k} \cdot \vec{x}} + b_{\vec{k}}^+ e^{+i\vec{k} \cdot \vec{x}})$$

$$\downarrow \quad \phi(\vec{x}, t) = \int d^3k \frac{V}{(2\pi)^3} \left(\frac{1}{\sqrt{2\omega V}} b_{\vec{k}} e^{-i\vec{k} \cdot \vec{x}} + \frac{1}{\sqrt{2\omega V}} b_{\vec{k}}^+ e^{+i\vec{k} \cdot \vec{x}} \right)$$

$$\text{令 } \alpha_{\vec{k}} / \sqrt{2\omega V} = \int d^3k \frac{1}{2\omega (2\pi)^3} (\sqrt{2\omega V} b_{\vec{k}} e^{-i\vec{k} \cdot \vec{x}} + \sqrt{2\omega V} b_{\vec{k}}^+ e^{+i\vec{k} \cdot \vec{x}})$$

$$\text{引入 } \overline{\alpha}_{\vec{k}} \equiv \sqrt{2\omega V} b_{\vec{k}}^+, \text{ 得 (记 } \omega_{\vec{k}} = \omega \text{)}$$

$$\phi(\vec{x}, t) = \int \frac{d^3k}{2\omega_{\vec{k}} (2\pi)^3} (\alpha_{\vec{k}} e^{-i\vec{k} \cdot \vec{x}} + \alpha_{\vec{k}}^+ e^{+i\vec{k} \cdot \vec{x}}), \text{ 其中 } \alpha_{\vec{k}} = \sqrt{2\omega V} b_{\vec{k}}$$

$\vec{k} = -\infty, \infty$ 动量连续

$$\pi(\vec{x}, t) = \int \frac{d^3k (-i\omega)}{2\omega_{\vec{k}} (2\pi)^3} (\alpha_{\vec{k}} e^{-i\vec{k} \cdot \vec{x}} - \alpha_{\vec{k}}^+ e^{+i\vec{k} \cdot \vec{x}})$$

黄涛

③ 下面, 确定展开式中不含时的振幅算子 $\{b_{\vec{k}}, b_{\vec{k}}^+\}$ 或 $\{a_{\vec{k}}, a_{\vec{k}}^+\}$.

$$b_{\vec{k}}(t) = b_{\vec{k}} e^{-i\omega t} = \frac{1}{\sqrt{2\omega V}} (g_{\vec{k}}(t) + i\omega P_{\vec{k}}(t)) = \frac{1}{\sqrt{2\omega V}} \int d^3x e^{-i\vec{k}\cdot\vec{x}} [\phi(\vec{x}, t) + i\pi(\vec{x}, t)]$$

$$= \frac{1}{\sqrt{2\omega V}} \int d^3x e^{-i\vec{k}\cdot\vec{x}} [w\phi(\vec{x}, t) + i\pi(\vec{x}, t)]$$

$$\therefore \begin{cases} b_{\vec{k}} = \frac{1}{\sqrt{2\omega V}} \int d^3x e^{i\vec{k}\cdot\vec{x}} [w\phi(\vec{x}, t) + i\pi(\vec{x}, t)] & \vec{k} \text{ 分立} \\ b_{\vec{k}}^+ = \frac{1}{\sqrt{2\omega V}} \int d^3x e^{-i\vec{k}\cdot\vec{x}} [w\phi(\vec{x}, t) - i\pi(\vec{x}, t)] & \vec{k} \text{ 连续} \end{cases}$$

当 $L \rightarrow \infty$ 时,

$$\begin{cases} a_{\vec{k}} = \sqrt{2\omega V} b_{\vec{k}} = \int d^3x e^{i\vec{k}\cdot\vec{x}} [w\phi(\vec{x}, t) + i\pi(\vec{x}, t)] & \vec{k} \text{ 连续} \\ a_{\vec{k}}^+ = \sqrt{2\omega V} b_{\vec{k}}^+ = \int d^3x e^{-i\vec{k}\cdot\vec{x}} [w\phi(\vec{x}, t) - i\pi(\vec{x}, t)] & \text{黄涛} \end{cases}$$

三. 动量空间的场算符

$$\phi(\vec{x}, t) = \sum_{\vec{k}=-\infty}^{\infty} \frac{1}{\sqrt{2\omega V}} (b_{\vec{k}} e^{-i\vec{k}\cdot\vec{x}} + b_{\vec{k}}^+ e^{i\vec{k}\cdot\vec{x}}), \quad \pi(\vec{x}, t) = \dot{\phi}(\vec{x}, t)$$

$$b_{\vec{k}} = \frac{1}{\sqrt{2\omega V}} \int d^3x e^{i\vec{k}\cdot\vec{x}} [w\phi(\vec{x}, t) + i\pi(\vec{x}, t)]$$

由于 $\phi(\vec{x}, t), \pi(\vec{x}, t)$ 可以量子化, 故由它们生成的 $b_{\vec{k}}, b_{\vec{k}}^+, H, \vec{P}$ 也可量子化.

予证: $[b_{\vec{k}}, b_{\vec{k}'}^+] = \delta_{\vec{k}, \vec{k}'}$

$$\vec{k} \left\{ \begin{array}{l} [b_{\vec{k}}, b_{\vec{k}'}] = [b_{\vec{k}}^+, b_{\vec{k}'}^+] = 0 \\ H = \sum_{\vec{k}} \omega [b_{\vec{k}}^+ b_{\vec{k}} + \frac{1}{2}] \\ \vec{P} = \sum_{\vec{k}} \vec{k} b_{\vec{k}}^+ b_{\vec{k}} \end{array} \right.$$

简单. 清晰

$$\text{引入 } P^M = \sum_{\vec{k}} P^M b_{\vec{k}}^+ b_{\vec{k}}, \quad N = \sum_{\vec{k}} b_{\vec{k}}^+ b_{\vec{k}}$$

自由场时 $[P^M, N] = 0$.

$$\vec{k} \left\{ \begin{array}{l} [a_{\vec{k}}, a_{\vec{k}'}^+] = (2\pi)^3 2\omega_k \delta^3(\vec{k} - \vec{k}') \\ [a_{\vec{k}}, a_{\vec{k}'}] = [a_{\vec{k}}^+, a_{\vec{k}'}^+] = 0 \\ H = \int \frac{d^3k}{(2\pi)^3} \frac{w_k}{2\omega_k} a_{\vec{k}}^+ a_{\vec{k}} \quad \begin{array}{l} \text{①本式若无粒子,} \\ \text{则总能量为0,} \end{array} \\ \vec{P} = \int \frac{d^3k}{(2\pi)^3} \frac{\vec{k}}{2\omega_k} a_{\vec{k}}^+ a_{\vec{k}} \quad \begin{array}{l} \text{②但由于已经将} \\ \text{一个无穷大能量} \\ \text{归入真空, 故此时} \\ \text{的真空中能量为正.} \end{array} \end{array} \right.$$

$$\text{引入 } P^M = \int \frac{d^3k}{(2\pi)^3} \frac{P^M}{2\omega_k} a_{\vec{k}}^+ a_{\vec{k}}, \quad N = \int \frac{d^3k}{(2\pi)^3} \frac{1}{2\omega_k} a_{\vec{k}}^+ a_{\vec{k}}$$

自由场时 $[P^M, N] = 0$

四. 粒子数表象.

场的能量和动量都包含有算符 $b_{\vec{k}}^\dagger b_{\vec{k}}$, 故引入 $N_{\vec{k}} = b_{\vec{k}}^\dagger b_{\vec{k}}$, $N = \sum_{\vec{k}} N_{\vec{k}}$
取 N 对角化的表象 $|n\rangle$, N 对角化的表象 $|n_{\vec{k}_1} n_{\vec{k}_2} \dots n_{\vec{k}_n} \dots\rangle$, $\langle n | n_{\vec{k}_1} n_{\vec{k}_2} \dots \rangle$

$$N|n\rangle = n|n\rangle, \quad N|n_{\vec{k}_1} n_{\vec{k}_2} \dots n_{\vec{k}_n} \dots\rangle = \sum_{\vec{k}} n_{\vec{k}} |n_{\vec{k}_1} n_{\vec{k}_2} \dots \rangle$$

则 $|n\rangle$ 是 N 的本征值为 n 的本征态, $|n_{\vec{k}_1} n_{\vec{k}_2} \dots n_{\vec{k}_n} \dots\rangle$ 是 N 的本征值为 $\sum n_{\vec{k}}$ 的本征态。

上一节的粒子数表象已经表明, 由 $b_{\vec{k}}, b_{\vec{k}}^\dagger$ 可以产生粒子数表象:

1) 真空态. $b_{\vec{k}} |0\rangle = 0, \quad \langle 0 | 0 \rangle = 1$, (\vec{k} 取所有分立动量)

2) 本征态 $b_{\vec{k}}^\dagger |0\rangle$ 一个4动量为 \vec{k} (或能量为 ω , 动量为 \vec{k}) 的单粒子态

$b_{\vec{k}}^{\dagger 2} |0\rangle$ 两个4动量均为 \vec{k} 的态 [双粒子]

$b_{\vec{k}_1}^\dagger b_{\vec{k}_2}^\dagger |0\rangle$ 一个4动量为 \vec{k}_1 、另一个4动量为 \vec{k}_2 的双粒子态.

\vdots
 $b_{\vec{k}_1}^\dagger b_{\vec{k}_2}^\dagger \dots b_{\vec{k}_n}^\dagger |0\rangle$ 4动量分别为 $\vec{k}_1, \vec{k}_2, \dots \vec{k}_n$ 的 n 粒子态.

这些态构成 Hilbert 空间的基矢, 称为 Fock 态.

这些态既是粒子数算符 $N = \sum_{\vec{k}} b_{\vec{k}}^\dagger b_{\vec{k}}$ 的本征态, (由于 $[N, P^M] = 0$) 又是 4动量 P^M 的本征态。

3) 由于 N 的本征值非负, 因此 $n_{\vec{k}_1}, n_{\vec{k}_2}, \dots n_{\vec{k}_n} \dots = 0, 1, 2, \dots$

从而 $E = \sum_{\vec{k}} \omega_{\vec{k}} (n_{\vec{k}} + \frac{1}{2})$ 非负, 即能量 H 的本征值非负, 故量子化后

K-G 场的负能量问题不复存在。不仅如此, 对一个粒子也不存在的真空态, 尽管场的动量为 0, 但是其能量为 $\sum_{\vec{k}} \frac{1}{2} \omega_{\vec{k}} \neq 0$, 这表明真空中储存有能量, 且是正的。真空具有能量, 是量子场的一个基本属性。

4). 正交归一性.

记 $|k\rangle \equiv a_{\vec{k}} |0\rangle$,

$$\langle \vec{k}' | \vec{k} \rangle = \delta_{\vec{k}', \vec{k}}, \dots, \langle \vec{k}'_1 \vec{k}'_2 \dots \vec{k}'_n | \vec{k}_1 \vec{k}_2 \dots \vec{k}_n \dots \rangle = \delta_{\vec{k}'_1, \vec{k}_1} \delta_{\vec{k}'_2, \vec{k}_2} \dots \delta_{\vec{k}'_n, \vec{k}_n} \dots$$

5) 完备性

$$\sum_{\vec{k}} |\vec{k}\rangle \langle \vec{k}| = 1, \dots, \sum_{\vec{k}_1, \vec{k}_2, \dots, \vec{k}_n} |\vec{k}_1 \vec{k}_2 \dots \vec{k}_n \dots \rangle \langle \vec{k}_1 \vec{k}_2 \dots \vec{k}_n \dots | = 1$$