

§ 3.5 旋量场双线性协变量

一. 旋量场双线性协变量

1. $\bar{\psi}(x)$ 的洛伦兹变换

$$x'' \rightarrow x'' = \alpha^m v^x$$

$$\psi(x) \rightarrow \bar{\psi}'(x') \equiv S \psi(x) = e^{-\frac{i}{4} w^{\rho\sigma} \bar{G}_{\rho\sigma}} \psi(x)$$

$$\bar{\psi}(x) \rightarrow \bar{\psi}'(x') \equiv \bar{\psi}(x') \gamma^0 = \bar{\psi}(x) \gamma^0 \gamma^0 e^{\frac{i}{4} w^{\rho\sigma} \bar{G}_{\rho\sigma}^+} \gamma^0$$

$$= \bar{\psi}(x) \gamma^0 \sum_{n=0}^{\infty} \frac{1}{n!} \left(\frac{i}{4} w^{\rho\sigma}\right)^n (\bar{G}_{\rho\sigma}^+)^n \gamma^0$$

$$= \bar{\psi}(x) \sum_{n=0}^{\infty} \frac{1}{n!} \left(\frac{i}{4} w^{\rho\sigma}\right)^n \underbrace{(\gamma_0 \bar{G}_{\rho\sigma}^+ \gamma_0) (\gamma_0 \bar{G}_{\rho\sigma}^+ \gamma_0) \dots (\gamma_0 \bar{G}_{\rho\sigma}^+ \gamma_0)}_{n \text{ 个相乘}}$$

$$\because \gamma_i^+ = -\gamma_i, \quad \gamma_0^+ = \gamma_0,$$

$$\therefore \gamma_0 \gamma_i^+ \gamma_0 = -\gamma_0 \gamma_i \gamma_0 = \gamma_i \gamma_0 \gamma_0 = \gamma_i, \quad \gamma_0 \gamma_0^+ \gamma_0 = \gamma_0 \gamma_0 \gamma_0 = \gamma_0, \text{ 即 } \gamma_0 \gamma_0^+ \gamma_0 = \gamma_0$$

$$\therefore \gamma_0 \bar{G}_{\rho\sigma}^+ \gamma_0 = \gamma_0 \left(\frac{i}{2} [\gamma_\rho, \gamma_\sigma] \right)^+ \gamma_0 = -\frac{i}{2} \gamma_0 (\gamma_\rho \gamma_\sigma - \gamma_\sigma \gamma_\rho)^+ \gamma_0 = -\frac{i}{2} (\underbrace{\gamma_0 \gamma_6^+ \gamma_0 \gamma_0^+ \gamma_0}_{} \gamma_0 - \underbrace{\gamma_0 \gamma_0^+ \gamma_0 \gamma_6^+ \gamma_0}_{} \gamma_0)$$

$$= -\frac{i}{2} (\gamma_6 \gamma_\rho - \gamma_\rho \gamma_6) = \frac{i}{2} (\gamma_\rho \gamma_6 - \gamma_6 \gamma_\rho) = \bar{G}_{\rho\sigma}$$

$$\text{则 } \bar{\psi}'(x') = \bar{\psi}(x) \sum_{n=0}^{\infty} \frac{1}{n!} \left(\frac{i}{4} w^{\rho\sigma}\right)^n (\bar{G}_{\rho\sigma})^n = \bar{\psi}(x) e^{\frac{i}{4} w^{\rho\sigma} \bar{G}_{\rho\sigma}} = \bar{\psi}(x) S^{-1}$$

$$\therefore \bar{\psi}(x) \rightarrow \bar{\psi}'(x') = \bar{\psi}(x) S^{-1}, \quad \text{其中 } S = e^{-\frac{i}{4} w^{\rho\sigma} \bar{G}_{\rho\sigma}}, \quad S^{-1} = e^{\frac{i}{4} w^{\rho\sigma} \bar{G}_{\rho\sigma}}$$

2. 由 $\psi(x), \bar{\psi}(x)$ 可以构造的双线性协变量

(1) 洛伦兹协量: $\bar{\psi}(x) \psi(x)$.

$$\bar{\psi}(x) \psi(x) \rightarrow \bar{\psi}'(x') \psi'(x') = \bar{\psi}(x) S^{-1} S \psi(x) = \bar{\psi}(x) \psi(x) \text{ 不变.}$$

(2) 洛伦兹矢量: $\bar{\psi}(x) \gamma^m \psi(x)$

$$\text{①} \text{ 洛伦兹, } \bar{\psi}(x) \gamma^m \psi(x) \rightarrow \bar{\psi}'(x') \gamma^m \psi'(x') = \bar{\psi}(x) S^{-1} \gamma^m S \psi(x)$$

$$\text{又对于洛伦兹变换, } [S \gamma^m S^{-1} = (\alpha^m)_v \gamma^v],$$

$$\text{左乘 } S^{-1}, \text{ 右乘 } S, \quad \gamma^m = (\alpha^m)_v S^{-1} \gamma^v S,$$

$$\text{乘 } \alpha^\rho_m \text{ 并对 } m \text{ 求和.} \quad \alpha^\rho_m \gamma^m = \alpha^\rho_m (\alpha^{-1})^m_v S^{-1} \gamma^v S = \delta^\rho_v S^{-1} \gamma^v S = S^{-1} \gamma^\rho S$$

$$\therefore [S^{-1} \gamma^m S = \alpha^m_v \gamma^v]$$

$$\text{则 } \bar{\psi}'(x') \gamma^m \psi'(x') = \bar{\psi}(x) \gamma^m \psi(x)$$

$$\therefore \bar{\psi}(x) \gamma^m \psi(x) \rightarrow \bar{\psi}'(x') \gamma^m \psi'(x') = \alpha^m_v \bar{\psi}(x) \gamma^v \psi(x)$$

类似矢量变换

3. 空间反射

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1) ② 旋量场的空间反射变换.

$$(\vec{x}, t) \rightarrow (\vec{x}', t') = (-\vec{x}, t)$$

$$\psi(x, t) \rightarrow \psi'(\vec{x}', t') = \gamma_p P \psi(\vec{x}, t), \quad \bar{\psi}(x, t) \rightarrow \bar{\psi}'(\vec{x}', t') = \gamma_p^* \bar{\psi}(\vec{x}, t) P^\dagger \gamma$$

其中 γ_p 是相因子, P 是 4×4 矩阵, 由拉氏密度在洛伦兹不变下确定.

$$\text{旋量场 Dirac 方程. } \begin{cases} (i \gamma^\mu \partial_\mu - m) \psi(x) = 0 & (*) \\ \bar{\psi}(x) (i \gamma^\mu \partial_\mu + m) = 0 & (**) \end{cases}$$

$$\text{相应拉氏密度 } \mathcal{L} = \bar{\psi}(i \gamma^\mu \partial_\mu - m) \psi, \quad \text{拉方 } \frac{\partial \mathcal{L}}{\partial \phi} - \frac{\partial}{\partial(\partial_\mu \phi)} \frac{\partial \mathcal{L}}{\partial(\partial_\mu \phi)} = 0. \quad (*)$$

$$\frac{\partial \mathcal{L}}{\partial \bar{\psi}} = (i \gamma^\mu \partial_\mu - m) \psi, \quad \frac{\partial \mathcal{L}}{\partial(\partial_\mu \bar{\psi})} = 0, \xrightarrow{*} (*)$$

$$\frac{\partial \mathcal{L}}{\partial \psi} = -m \bar{\psi}, \quad \frac{\partial \mathcal{L}}{\partial(\partial_\mu \psi)} = \cancel{\bar{\psi} \gamma^\mu} \bar{\psi} i \gamma^\mu \xrightarrow{*} (**)$$

在空间反射变换下.

$$\mathcal{L}(x) = \bar{\psi}(\vec{x}, t) (i \gamma^\mu \partial_\mu - m) \psi(\vec{x}, t) = \bar{\psi}(\vec{x}, t) (i \gamma^\mu \partial_\mu + i \vec{\gamma} \cdot \nabla - m) \psi(\vec{x}, t)$$

$$\downarrow \\ \mathcal{L}'(x') = \bar{\psi}'(-\vec{x}, t) (i \gamma^\mu \partial_\mu - m) \psi'(-\vec{x}, t) = \bar{\psi}'(-\vec{x}, t) (i \gamma^\mu \partial_\mu - i \vec{\gamma} \cdot \nabla - m) \psi'(-\vec{x}, t)$$

$$= \bar{\psi}'(-\vec{x}, t) \gamma_0 (i \gamma^\mu \partial_\mu - i \vec{\gamma} \cdot \nabla - m) \gamma_p P \psi(\vec{x}, t)$$

$$= \bar{\psi}'(-\vec{x}, t) P^\dagger \gamma_p^+ \gamma_0 (i \gamma^\mu \partial_\mu - i \vec{\gamma} \cdot \nabla - m) \gamma_p P \psi(\vec{x}, t)$$

$$= |\gamma_p|^2 \bar{\psi}(\vec{x}, t) \gamma_0 P^\dagger \gamma_0 (i \gamma^\mu \partial_\mu - i \vec{\gamma} \cdot \nabla - m) P \psi(\vec{x}, t)$$

$$\stackrel{?}{=} \mathcal{L}(x) = \bar{\psi}(\vec{x}, t) (i \gamma^\mu \partial_\mu + i \vec{\gamma} \cdot \nabla - m) \psi(\vec{x}, t)$$

$$\therefore |\gamma_p|^2 = 1 \Rightarrow \gamma_p = \pm 1, \quad \gamma_p \text{ 称为字称. } \gamma_p = +1 \text{ 为正字称, } \gamma_p = -1 \text{ 为负字称.}$$

由含 ∂_μ 的项相等

$$\gamma_0 P^\dagger \gamma_0 \gamma^\mu P = \gamma^\mu, \quad \text{即 } \gamma_0 P^\dagger P = \gamma^\mu, \quad \text{得 } \underline{P^\dagger = P^{-1}}, \quad P \text{ 为么正矩阵.}$$

由含 m 的项相等

$$\gamma_0 P^\dagger \gamma_0 P = 1, \quad \text{即 } \underline{\gamma_0 P^\dagger \gamma_0 = P^{-1}}$$

由含 ∇ 的项相等

$$\underline{\gamma_0 P^\dagger \gamma_0 \vec{\gamma} P = -\vec{\gamma}}, \quad \text{结合上式, 得 } \underline{P^{-1} \vec{\gamma} P = -\vec{\gamma}}.$$

$$\text{综上, } P = \gamma_0 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\therefore \text{空间反射: } \psi(\vec{x}, t) \rightarrow \psi'(\vec{x}', t') = \cancel{\pm \gamma_0 \psi(-\vec{x}, t)} \gamma_p \gamma_0 \psi(\vec{x}, t) = \pm \gamma_0 \psi(\vec{x}, t)$$

$$\bar{\psi}(\vec{x}, t) \rightarrow \bar{\psi}'(\vec{x}', t') = \cancel{\bar{\psi}'(-\vec{x}, t)} = \gamma_p^* \bar{\psi}(\vec{x}, t) \gamma_0 = \pm \bar{\psi}(\vec{x}, t) \gamma_0$$

$$\bar{\psi}'(-\vec{x}, t)$$

③ 洛伦兹矢量的空间反射变换

在空间反射变换下。

$$\bar{\psi}(\vec{x}, t) \gamma^\mu \psi(\vec{x}, t) \rightarrow \bar{\psi}'(\vec{x}', t') \gamma^\mu \psi'(\vec{x}', t')$$

$$= \gamma_p^* \gamma_p \bar{\psi}(\vec{x}, t) \gamma_\mu \gamma_\nu \psi(\vec{x}, t) = \begin{cases} \bar{\psi}(\vec{x}) \gamma^\mu \psi(\vec{x}) & \mu=0 \\ -\bar{\psi}(\vec{x}) \gamma^\mu \psi(\vec{x}) & \mu=1, 2, 3 \end{cases}$$

故 $\bar{\psi}(\vec{x}, t) \gamma^\mu \psi(\vec{x}, t)$ 为洛伦兹矢量

(3) 洛伦兹赝标量。

$$\bar{\psi}(\vec{x}) \gamma^5 \psi(\vec{x}) \rightarrow \bar{\psi}'(\vec{x}') \gamma^5 \psi'(\vec{x}')$$

$$= \bar{\psi}(\vec{x}) \gamma_0 \gamma^5 \gamma_0 \psi(\vec{x}) = -\bar{\psi}(\vec{x}) \gamma^5 \psi(\vec{x})$$

故 $\bar{\psi}(\vec{x}) \gamma^5 \psi(\vec{x})$ 为洛伦兹赝标量。

(4) 洛伦兹轴矢量。

$$\bar{\psi}(\vec{x}) \gamma^\mu \gamma^5 \psi(\vec{x}) \rightarrow \bar{\psi}'(\vec{x}') \gamma^\mu \gamma^5 \psi'(\vec{x}')$$

$$= \bar{\psi}(\vec{x}) \gamma_0 \gamma^\mu \gamma^5 \gamma_0 \psi(\vec{x}) = \begin{cases} -\bar{\psi}(\vec{x}) \gamma^\mu \gamma^5 \psi(\vec{x}) & \mu=0 \\ \bar{\psi}(\vec{x}) \gamma^\mu \gamma^5 \psi(\vec{x}) & \mu=1, 2, 3 \end{cases}$$

故 $\bar{\psi}(\vec{x}) \gamma^\mu \gamma^5 \psi(\vec{x})$ 为洛伦兹轴矢量。

A 一般双线性协变量。

一般地讲，在 $\bar{\psi}$ 与 ψ 之间插入任意的 4×4 矩阵可以构成双线性协变量。可以证明，旋量空间的 4×4 矩阵可以按照 16 个基矩阵展开（因为 4×4 矩阵含 16 个元素，故 4×4 矩阵一定可以用 16 个基矩阵展开），所以独立的双线性协变量有 16 个。

(1) 下面证明，这 16 个基矩阵可由 7 矩阵生成。

引入 16 个 Γ 矩阵

$$\left\{ \begin{array}{l} \Gamma^S \equiv 1, \\ \Gamma_\mu^V \equiv \gamma_\mu, \\ \Gamma_{\mu\nu}^T \equiv \delta_{\mu\nu} = \frac{i}{2} [\gamma_\mu, \gamma_\nu], \\ \Gamma_\mu^A \equiv \gamma_5 \gamma_\mu, \\ \Gamma^P \equiv i \gamma_5 \end{array} \right.$$

任 Γ^a ($a = S, V, T, A, P$) 有如下性质：

$$(1) (\Gamma^a)^2 = \pm 1.$$

$$(2) \text{对任意 } \Gamma^a (\Gamma^a \neq \Gamma^S = 1), \text{ 存在一个 } \Gamma^b, \text{ 使 } \Gamma^a \Gamma^b = -\Gamma^b \Gamma^a$$

$$(3) \text{由此, 除 } \Gamma^S \text{ 外, 所有 } \Gamma^a \text{ 的迹为 } 0. \text{ 因为 } \text{Tr } \Gamma^a, \text{ 可找到 } \Gamma^b,$$

$$\text{Tr}(\Gamma^a (\Gamma^b)^2) = \text{Tr}(\Gamma^b \Gamma^a \Gamma^b) = -\text{Tr}((\Gamma^b)^2 \Gamma^a)$$

$$\text{无论 } (\Gamma^b)^2 = \pm 1, \text{ 皆有 } \text{Tr } \Gamma^a = 0$$

$$(4) \text{封闭性。对任意一对 } (\Gamma^a, \Gamma^b) (a \neq b), \text{ 存在 } \Gamma^c \neq \Gamma^S, \text{ 使得 } \Gamma^a \Gamma^b = \Gamma^c \text{ (前面已证相因子 } \pm 1, \pm i).$$

$$(5) \text{集合 } \{\Gamma^a\} (a = S, V, T, A, P) \text{ 线性无关。}$$

$$\text{设 } \sum_a \lambda_a \Gamma^a = 0 \quad (\lambda_a \text{ 为常数}), \text{ 由 } \Gamma^a \text{ 相继乘并求逆, 证 } \lambda_a = 0.$$

$$\begin{aligned} & \sum_a \lambda_a \text{Tr}(\Gamma^a \Gamma^b) \\ &= \lambda_S \text{Tr}(\Gamma^S \Gamma^b) + \lambda_V \text{Tr}(\Gamma^V \Gamma^b) + \lambda_T \text{Tr}(\Gamma^T \Gamma^b) \\ &+ \lambda_A \text{Tr}(\Gamma^A \Gamma^b) + \lambda_P \text{Tr}(\Gamma^P \Gamma^b) \end{aligned}$$

① 当 $\Gamma^b = \Gamma^S = 1$ 时, 第 4 项为 0, 第 1 项为 λ_S , 故 $\lambda_S = 0$.

② 当 $\Gamma^b \neq \Gamma^S = 1$ 时, 对于 $b \neq a$ 情况时, 存在 $\Gamma^c \neq 1$, 使 $\Gamma^a \Gamma^b = \Gamma^c$, $\text{Tr } \Gamma^c = 0$, 故由此可得此时的 $\lambda_a = 0$, 改变 Γ^b , 可得所有 $\lambda_a = 0$.

综上, $\lambda_a = 0$, $\{\Gamma^a\}$ 线性无关。

(2) 16个独立的双线性协变量

$$S: \bar{\psi}(x)\psi(x); \quad V: \bar{\psi}(x)\gamma^m\psi(x); \quad T: \bar{\psi}(x)\gamma^m\gamma^\nu\psi(x); \quad A: \bar{\psi}(x)\gamma_5\gamma^m\psi(x); \quad P: i\bar{\psi}(x)\gamma_5\psi(x)$$

在洛伦兹变换下，上述双线性协变量变换为

$$x^m \rightarrow x'^m = \alpha^m_n x^n$$

$$\bar{\psi}(x)\psi(x) \rightarrow \bar{\psi}'(x')\psi(x) = \bar{\psi}(x)\psi(x) \quad \text{标量}$$

$$\bar{\psi}(x)\gamma^m\psi(x) \rightarrow \bar{\psi}'(x')\gamma^m\psi(x) = \alpha^m_n \bar{\psi}(x)\gamma^m\psi(x) \quad \text{矢量}$$

$$\bar{\psi}(x)\gamma^m\gamma^\nu\psi(x) \rightarrow \bar{\psi}'(x')\gamma^m\gamma^\nu\psi(x) = \alpha^m_n \alpha^\nu_\rho \bar{\psi}(x)\gamma^m\gamma^\nu\psi(x) \quad \text{反对称张量}$$

$$\bar{\psi}(x)\gamma_5\gamma^m\psi(x) \rightarrow \bar{\psi}'(x')\gamma_5\gamma^m\psi(x) = \det(\alpha) \alpha^m_n \bar{\psi}(x)\gamma_5\gamma^m\psi(x) \quad \text{轴矢量} \quad \begin{matrix} \nearrow \text{空间反射时} \\ \nearrow \det(\alpha) = -1 \end{matrix}$$

$$i\bar{\psi}(x)\gamma_5\psi(x) \rightarrow i\bar{\psi}'(x')\gamma_5\psi(x) = i\det(\alpha) \bar{\psi}(x)\gamma_5\psi(x) \quad \text{赝标量} \quad \begin{matrix} \nearrow \text{空间反射时} \\ \nearrow \det(\alpha) = -1 \end{matrix}$$

基于双线性协变量，可写出 Dirac 旋量场构造的洛伦兹不变量：

$$\bar{\psi}\psi, \bar{\psi}\gamma^m\partial_m\psi, \partial_m\bar{\psi}\gamma^m\psi, \dots$$

二、拉氏密度旋量场的拉氏量、守恒流、守恒荷。

1. 拉氏密度： $\mathcal{L} = i\bar{\psi}\gamma^m\partial_m\psi - m\bar{\psi}\psi = \bar{\psi}(i\not{D} - m)\psi$

$$[\mathcal{L}] = 4, [\partial_m] = 1, \text{故} [\psi] = \frac{3}{2}, \text{代入 E-L 方程, 得} \begin{cases} (i\not{D} - m)\psi = 0 \\ \bar{\psi}(i\not{D} + m) = 0 \end{cases}$$

2. 洛伦兹变换下的守恒流、守恒荷。

(1) 时空平移无穷小变换。

$$x^m \rightarrow x'^m = x^m + \xi^m.$$

作业

$\therefore T_{\mu\nu} = i\bar{\psi}\gamma_\mu\partial_\nu\psi, \text{满足 } \partial^\mu T_{\mu\nu} = 0, T_{\mu\nu} \text{ 称为旋量场能量-动量张量密度}$

相应守恒荷

$$P_\nu = \int d^3x T_{0\nu} = i \int d^3x \bar{\psi}^\dagger \partial_\nu \psi$$

P_ν 称为旋量场的回动量。

(2) 无穷小洛伦兹变换.

$$x^m \rightarrow x'^m = x^m + \varepsilon^{mn} \chi_n$$

$$\psi(x) \rightarrow \psi'(x) = (1 - \frac{i}{4} \partial^\rho \partial_{\rho\sigma}) \psi(x).$$

$$J_{mnp} = x_n T_{mp} - x_p T_{mn} + \bar{\psi} \gamma_m \frac{G_{np}}{2} \psi, \quad \text{满足 } \partial^m J_{mnp} = 0, \quad J_{mnp} \text{ 称为广义角动量张量密度}$$

相应守恒荷.

$$M_{rp} = \int d^3x J_{orp} = \int d^3x (x_n T_{op} - x_p T_{on} + \bar{\psi} \gamma_o \frac{G_{rp}}{2} \psi), \quad M_{rp} \text{ 称为广义角动量}$$

δx 轨道角动量, $\delta \psi$ 自旋角动量

(3) 整体规范变换(坐标 x 不变)

$$\psi(x) \rightarrow \psi'(x) = e^{i\alpha} \psi, \quad \delta \psi = +i\alpha \psi$$

$$\bar{\psi}(x) \rightarrow \bar{\psi}'(x) = \bar{\psi} e^{-i\alpha}, \quad \delta \bar{\psi} = -i\alpha \bar{\psi}$$

$$j_a^m = -[\partial \partial_p^m - \frac{\partial \mathcal{L}}{\partial(\partial_m \phi)} \partial_p \phi] \frac{\partial x^p}{\partial \theta^a} - \frac{\partial \mathcal{L}}{\partial(\partial_m \phi)} \frac{\delta \phi}{\delta \theta^a},$$

对整体规范变换, $\frac{\partial x^p}{\partial \theta^a} = 0$, $\frac{\partial \mathcal{L}}{\partial(\partial_m \phi)} = \bar{\psi} i \gamma^m$, $\frac{\delta \phi}{\delta \theta^a} = \frac{\delta \psi}{\delta \alpha} = i \psi$.

$$j^m = -\frac{\partial \mathcal{L}}{\partial(\partial_m \psi)} \frac{\delta \psi}{\delta \theta^a} = -\bar{\psi} i \gamma^m i \psi = \bar{\psi} \gamma^m \psi.$$

$\therefore J^m = \bar{\psi} \gamma^m \psi$, 满足 $\partial_m J^m = 0$. J^m 称为旋量场矢量流. 如 $e J^m$ 为电流密度.
相应守恒荷.

$$Q = \int d^3x J^0 = \int d^3x \bar{\psi} \gamma^0 \psi.$$

Q 称为守恒荷. 如 $e Q$ 为电荷, Q 对应费米数守恒.

§ 3.6 零质量旋量场

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上节讨论了自旋为 $\frac{1}{2}$ 的粒子，当这类粒子质量为0时，它们具有
一些特殊的性质。这类粒子如：中微子，电子，轻质量夸克。

一. 零质量粒子的手征变换

1. 手征变换

自旋 $\frac{1}{2}$ 粒子： $\mathcal{L} = \bar{\psi}(x)(i\gamma^m \partial_m - m)\psi(x)$,

$m=0$ 时： $\mathcal{L} = \bar{\psi}(x)i\gamma^m \partial_m \psi(x)$.

考虑整体手征变换(x 不变)。

$$\psi(x) \rightarrow \psi'(x) = e^{i\theta r_s} \psi(x)$$

$$\bar{\psi}(x) \rightarrow \bar{\psi}'(x) = \bar{\psi}(x) \gamma^0 \gamma^5 e^{-i\theta r_s} \gamma^0 = \bar{\psi}(x) \gamma^0 e^{i\theta r_s}$$

$$\therefore \bar{\psi}'(x) = \bar{\psi}(x) e^{i\theta r_s}.$$

$$\mathcal{L}(x) = \bar{\psi}(x)i\gamma^m \partial_m \psi(x) \rightarrow \mathcal{L}'(x) = \bar{\psi}'(x)i\gamma^m \partial_m \psi'(x)$$

$$= \bar{\psi}(x) e^{i\theta r_s} i\gamma^m \partial_m e^{i\theta r_s} \psi(x) \quad \{ \gamma^m, r_s \} = 0$$

$$= \bar{\psi}(x)i\gamma^m \partial_m e^{-i\theta r_s} e^{i\theta r_s} \psi(x)$$

$$= \bar{\psi}(x)i\gamma^m \partial_m \psi(x)$$

$$\therefore \mathcal{L}'(x) = \mathcal{L}(x). \quad \text{拉氏量具有手征对称性} \downarrow$$

2. 手征变换下的守恒流，守恒荷

(但质量项 $m\bar{\psi}\psi$ 破坏手征对称性)

$$j_a^m = -\left[\mathcal{L} g^m_{\rho} - \frac{\partial \mathcal{L}}{\partial(\partial_m \phi)} \partial_\rho \phi \right] \frac{\partial x^\rho}{\partial \theta^a} - \frac{\partial \mathcal{L}}{\partial(\partial_m \phi)} \frac{\delta \phi}{\delta \theta^a}.$$

$$1) \text{对手征变换, } \frac{\partial x^\rho}{\partial \theta^a} = 0, \quad \frac{\partial \mathcal{L}}{\partial(\partial_m \psi)} = \bar{\psi}(x)i\gamma^m,$$

$$\psi(x) \rightarrow \psi'(x) = e^{i\theta r_s} \psi(x)$$

$$\therefore \text{无穷小变换时 } \delta \psi(x) = \psi'(x) - \psi(x) = i\theta r_s \psi(x), \quad \frac{\delta \psi(x)}{\delta \theta} = i\theta r_s \psi(x)$$

$$1) \text{守恒流 } j_5^m = -\frac{\partial \mathcal{L}}{\partial(\partial_m \psi)} \frac{\delta \psi}{\delta \theta^a} = -\bar{\psi}(x)i\gamma^m i\theta r_s \psi(x) = \bar{\psi}(x)\gamma^m r_s \psi(x)$$

满足 $\partial_m j_5^m = 0$. “轴矢量流守恒”

(无质量项)

2) 守恒荷

$$Q_5 = \int d^3x j_5^0 = \int d^3x \bar{\psi} \gamma^0 r_s \psi = \int d^3x \bar{\psi}^+ r_s \psi$$

二. 手征变换与螺旋度变换的关系.

1. $\vec{\Sigma} \cdot \hat{P}$ 与 γ_5 有共同本征态.

$m=0$ 时运动方程 $\vec{\nabla} \psi = 0$, 左乘 $\gamma_5 \gamma^0$

$$\gamma_5 \gamma^0 \vec{\nabla} \psi = \gamma_5 \gamma^0 \gamma^m P_m \psi = \gamma_5 \gamma^0 \gamma^0 P^0 \psi - \gamma_5 \gamma^0 \vec{\nabla} \cdot \vec{P} \psi = 0.$$

当 $m=0$ 时, $P^0 = |\vec{P}|$ 而 $\vec{\Sigma} = \gamma_5 \gamma^0 \vec{r}$, 故 $\vec{\Sigma} \cdot \vec{P} \psi \downarrow = \gamma_5 P^0 \psi$, 故

$$\vec{\Sigma} \cdot \frac{\vec{P}}{|\vec{P}|} = \gamma_5 \epsilon(P^0),$$

这表明

$$\gamma_5 = \begin{cases} +\vec{\Sigma} \cdot \frac{\vec{P}}{|\vec{P}|} & (\text{正能解 } P^0 > 0) \\ -\vec{\Sigma} \cdot \frac{\vec{P}}{|\vec{P}|} & (\text{负能解 } P^0 < 0) \end{cases}$$

即 γ_5 与 $\vec{\Sigma} \cdot \frac{\vec{P}}{|\vec{P}|}$ 具有共同的本征态, 对于正能解时, 二者本征值相同; 对于负能解时, 二者本征值相反。由此, 可以由 $\vec{\Sigma} \cdot \frac{\vec{P}}{|\vec{P}|}$ 的本征态确定 γ_5 的本征态。

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螺旋度	手征性
$\vec{\Sigma} \cdot \hat{P} U_+ = U_+$ $U_+(P)$	$\epsilon_a = +1$ 右旋态 $\uparrow \vec{P}$
$\vec{\Sigma} \cdot \hat{P} U_- = U_-$ $U_-(P)$	$\epsilon_a = -1$ 左旋态 $\leftarrow \vec{P}$
$\vec{\Sigma} \cdot \hat{P} V_+ = V_+$ $V_+(P)$	$\epsilon_a = +1$ 右旋态 $\uparrow \vec{P}$
$\vec{\Sigma} \cdot \hat{P} V_- = -V_-$ $V_-(P)$	$\epsilon_a = -1$ 左旋态 $\downarrow \vec{P}$

上述性质概括为

$$\begin{cases} \vec{\Sigma} \cdot \hat{P} U_a(P) = h_a U_a(P) \\ \vec{\Sigma} \cdot \hat{P} V_a(P) = h_a V_a(P) \end{cases} \quad \begin{cases} \gamma_5 U_a(P) = \epsilon_a U_a(P), \quad \epsilon_a = +h_a \\ \gamma_5 V_a(P) = \epsilon_a V_a(P), \quad \epsilon_a = -h_a \end{cases}$$

螺旋度与手征性的这种关系是正洛伦兹变换下不变的。

- 说明: ① 当 $m=0$ 时, 在正洛伦兹变换下, 粒子动量 $\vec{P} \rightarrow \vec{P}'$, 但它的螺旋性保持不变。
- ② 当 $m \neq 0$ 时, 对任意给定 \vec{P} , 我们总可以沿 \vec{P} 但以比 \vec{P} 大的速度作-洛伦兹变换。于是粒子动量将改变方向, 但自旋方向仍是一样的。结果, 粒子的螺旋性 h_a 改变为 $-h_a$ 。(但这种洛伦兹变换在 $m=0$ 时是不可能的)
- ③ 对于手征性, 无论 $m=0$ 或 $m \neq 0$, 在正洛伦兹变换下, 粒子的手征性均保持不变。
- ④ 从而对于 $m=0$ 粒子, 粒子的螺旋性与手征性有上表关系, 且在 LT 时保持不变。对于 $m \neq 0$ 粒子, 粒子的螺旋性与手征性没有上表关系, 在 LT 时关系会改变。

2. U_a 与 U_a 互为电荷共轭旋量.

$U_a(P)$ 和 $U_a(P)$ 同为 γ_5 和 $\vec{\gamma} \cdot \vec{P}$ 的本征态, 本征值相互联系, 故二者不独立.

1). 电荷共轭旋量.

$$\text{引入矩阵 } C = i\gamma^2\gamma^0 = i\begin{pmatrix} 0 & \gamma^2 \\ -\gamma^2 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} 0 & -i\gamma^2 \\ -i\gamma^2 & 0 \end{pmatrix}$$

$$\text{定义电荷共轭旋量 } \psi^c \equiv C \bar{\psi}^T = i\gamma^2\psi^*$$

由旋量场 Dirac 方程,

$$\begin{cases} (\not{p} - m) U(P) = 0 \\ (\not{p} + m) U(P) = 0 \end{cases}$$

可证 $U(P)$ 与 $U(P)$ 互为电荷共轭旋量.

作业二

$$\begin{cases} U(P) = C \bar{U}^T(P) \\ U(P) = C \bar{U}^T(P) \end{cases}$$

三. 手征旋量场.

1. 手征旋量场定义.

当 $m=0$ 时, 旋量场哈密顿量 $H = \vec{\alpha} \cdot \vec{p} + \beta m = -i\vec{\alpha} \cdot \nabla$, 且 $[H, \gamma_5] = 0$, 故可以对旋量场进行变换.

$$\psi(x) \rightarrow \psi'(x) = \gamma_5 \psi(x).$$

利用 $\gamma_5 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$, 将 ψ 分解为 $\psi = \psi_L + \psi_R$, 称 ψ_L, ψ_R 为左右手征旋量场.

$$\begin{cases} \psi_L = \frac{1}{2}(1-\gamma_5)\psi, & \text{它们是 } \gamma_5 \text{ 本征态, } \gamma_5 \psi_L = -\psi_L, \text{ 本征值 } -1 \\ \psi_R = \frac{1}{2}(1+\gamma_5)\psi. & \gamma_5 \psi_R = +\psi_R, \text{ 本征值 } +1. \end{cases} \quad \begin{array}{l} \text{引入投影算符 } P_L \\ P_L = \frac{1}{2}(1-\gamma_5), P_L \psi_L = \psi_L \\ P_R = \frac{1}{2}(1+\gamma_5), P_R \psi_R = \psi_R \\ \text{其它为 } 0. \end{array}$$

2. Weyl 表象下的手征旋量场

1) Dirac 表象下

$$\gamma^0 = \beta \equiv \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \gamma^i \equiv \begin{pmatrix} 0 & \sigma^i \\ -\sigma^i & 0 \end{pmatrix}, \gamma^5 \equiv \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \psi = \begin{pmatrix} \psi_1 \\ \psi_2 \\ \psi_3 \\ \psi_4 \end{pmatrix}$$

$$\text{引入 } P_L \equiv \frac{1}{2}(1-\gamma_5) = \frac{1}{2}\begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}, P_R \equiv \frac{1}{2}(1+\gamma_5) = \frac{1}{2}\begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$$

$$\Rightarrow \begin{cases} \psi_L = \frac{1}{2}\begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} \psi_1 \\ \psi_2 \\ \psi_3 \\ \psi_4 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} \psi_1 - \psi_3 \\ \psi_2 + \psi_4 \\ \psi_3 - \psi_1 \\ \psi_4 - \psi_2 \end{pmatrix} \\ \psi_R = \frac{1}{2}\begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} \psi_1 \\ \psi_2 \\ \psi_3 \\ \psi_4 \end{pmatrix} = \begin{pmatrix} \psi_1 + \psi_3 \\ \psi_2 + \psi_4 \\ \psi_3 + \psi_1 \\ \psi_4 + \psi_2 \end{pmatrix} \end{cases}$$

2). Weyl 表象下.

$$\begin{cases} \gamma^0 = \beta \equiv \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \gamma^i \equiv \begin{pmatrix} 0 & \sigma^i \\ -\sigma^i & 0 \end{pmatrix}, \gamma_5 \equiv \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}, \psi = \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix} \end{cases} \Leftrightarrow \begin{cases} \psi_L = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} \psi_1 \\ \psi_2 \\ \psi_3 \\ \psi_4 \end{pmatrix} = \begin{pmatrix} \psi_1 \\ \psi_2 \\ 0 \\ 0 \end{pmatrix} \psi \text{ 的前两个分量} \\ \psi_R = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} \psi_1 \\ \psi_2 \\ \psi_3 \\ \psi_4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ \psi_3 \\ \psi_4 \end{pmatrix} \psi \text{ 的后两个分量} \end{cases}$$

从 Dirac 表象做么正变换,

$$\gamma_{\text{Weyl}}^{\mu} = U \gamma^{\mu} \text{Dirac} U, \quad U = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$$

可得 Weyl 表象下的各种 γ 矩阵

3. 手征变换

$$\psi \rightarrow \psi' = e^{i\theta T_5} \psi, \quad T_5 = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}, \quad T_5^n = \begin{pmatrix} (-1)^n & 0 \\ 0 & 1 \end{pmatrix}, \quad P_L \psi = \psi_L, \quad P_R \psi = \psi_R$$

Weyl 表象下.

$$\begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix} \rightarrow \begin{pmatrix} \psi'_L \\ \psi'_R \end{pmatrix} = e^{i\theta T_5} \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix} = \sum \frac{(i\theta)^n}{n!} T_5^n \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix} = \sum \frac{(i\theta)^n}{n!} \begin{pmatrix} (-1)^n & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix} = \sum \frac{(i\theta)^n}{n!} \begin{pmatrix} (-1)^n \psi_L \\ \psi_R \end{pmatrix}$$

$$\therefore \begin{cases} \psi_L \rightarrow \psi'_L = \sum \frac{(-i\theta)^n}{n!} \psi_L = \sum \frac{(-i\theta)^n}{n!} \left(\frac{1-\gamma_5}{2} \right)^n \psi_L = e^{-\frac{i}{2}\theta(1-\gamma_5)} \psi_L \\ \psi_R \rightarrow \psi'_R = \sum \frac{(i\theta)^n}{n!} \psi_R = \sum \frac{(i\theta)^n}{n!} \left(\frac{1+\gamma_5}{2} \right)^n \psi_R = e^{\frac{i}{2}\theta(1+\gamma_5)} \psi_R \end{cases}$$

即 $\begin{cases} \psi_L \rightarrow \psi'_L = e^{\frac{i}{2}\theta_L(1-\gamma_5)} \psi_L \\ \psi_R \rightarrow \psi'_R = e^{\frac{i}{2}\theta_R(1+\gamma_5)} \psi_R \end{cases}$, 可证此式在 Dirac 表象下也成立。

4. 运动方程

Weyl 表象下, $\psi = \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix}$, 密度质量旋量场拉氏密度.

$L = \bar{\psi} i \gamma^\mu \partial_\mu \psi$ 在 Weyl 表象下,

$$\psi = \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix}, \quad \bar{\psi} = \psi^\dagger \gamma^0 = (\psi_L^\dagger \psi_R^\dagger) \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = (\psi_R^\dagger \psi_L^\dagger), \quad \boxed{\psi}$$

$$\gamma^\mu \partial_\mu = \gamma^0 \partial_0 + \vec{\gamma} \cdot \nabla = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \partial_0 + \begin{pmatrix} 0 & \vec{\gamma} \cdot \nabla \\ \vec{\gamma} \cdot \nabla & 0 \end{pmatrix}$$

则密度质量旋量场拉氏密度.

$$\begin{aligned} L = \bar{\psi} i \gamma^\mu \partial_\mu \psi &= (\psi_R^\dagger \psi_L^\dagger) i \begin{pmatrix} 0 & \vec{\gamma} \cdot \nabla \\ \vec{\gamma} \cdot \nabla & 0 \end{pmatrix} \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix} = (\psi_R^\dagger \psi_L^\dagger) \begin{pmatrix} (\partial_0 + \vec{\gamma} \cdot \nabla) \psi_R \\ (\partial_0 + \vec{\gamma} \cdot \nabla) \psi_L \end{pmatrix} \\ &= i \psi_L^\dagger (\partial_0 + \vec{\gamma} \cdot \nabla) \psi_L + i \psi_R^\dagger (\partial_0 + \vec{\gamma} \cdot \nabla) \psi_R. \end{aligned}$$

即 $L = L_L + L_R$, 其中.

$$\begin{cases} L_L = i \psi_L^\dagger \vec{\gamma}^\mu \partial_\mu \psi_L, & \vec{\gamma}^\mu = (1, -\vec{\gamma}) \\ L_R = i \psi_R^\dagger \vec{\gamma}^\mu \partial_\mu \psi_R, & \vec{\gamma}^\mu = (1, +\vec{\gamma}) \end{cases}$$

$$\vec{\gamma}^\mu \equiv (1, -\vec{\gamma})$$

二分之一 Weyl 方程

运动方程若用 ψ_L 表示: $\frac{\partial \mathcal{L}}{\partial \psi_L^\dagger} = i \vec{\gamma}^\mu \partial_\mu \psi_L, \partial_\mu \left(\frac{\partial \mathcal{L}}{\partial (\partial_\mu \psi_L^\dagger)} \right) = 0 \Rightarrow i \vec{\gamma}^\mu \partial_\mu \psi_L = 0$ 或 $(P^0 \vec{\gamma} \cdot \vec{P}) \psi_L = 0$

运动方程若用 ψ_R 表示: $\frac{\partial \mathcal{L}}{\partial \psi_R^\dagger} = i \vec{\gamma}^\mu \partial_\mu \psi_R, \partial_\mu \left(\frac{\partial \mathcal{L}}{\partial (\partial_\mu \psi_R^\dagger)} \right) = 0 \Rightarrow i \vec{\gamma}^\mu \partial_\mu \psi_R = 0$ 或 $(P^0 \vec{\gamma} \cdot \vec{P}) \psi_R = 0$

二分之一 Weyl 方程描述无质量具有确定螺旋度的粒子:

- ① $i \vec{\gamma}^\mu \partial_\mu \psi_L = 0$. 若 $P^0 > 0$ (正能粒子), 左手性 (手征性 = 螺旋度 = +1) 得左旋, 左旋粒子, 如左旋中微子
 或 $(P^0 \vec{\gamma} \cdot \vec{P}) \psi_L = 0$. 即若假设 $M_\nu \approx 0$, 则正中微子用左手场 ψ_L 描述, $T_5 = \sum \frac{\vec{P}_i}{|\vec{P}_i|}$, 本征值为 -1
 若 $P^0 < 0$, 左手性 (手征性 = -螺旋度 = -1) 得右旋, 右旋反粒子, 如右旋中微子, $T_5 = -\sum \frac{\vec{P}_i}{|\vec{P}_i|}$, 本征值 +1
- ② $i \vec{\gamma}^\mu \partial_\mu \psi_R = 0$. 若 $P^0 > 0$ (正能粒子), 右手性 (手征性 = +螺旋度 = +1) 得右旋, 右旋粒子, 但与实验不相符.
 ③ $(P^0 \vec{\gamma} \cdot \vec{P}) \psi_R = 0$. 若 $P^0 < 0$ (负能粒子), 右手性 (手征性 = -螺旋度 = +1) 得左旋, 左旋反粒子, 但与实验不相符.

综上：

① Dirac 方程对零质量粒子在 Weyl 表象中分解为一对二分量 Weyl 方程，

左旋和右旋粒子分别遵从 $i\bar{\psi}^m \partial_m \psi_L = 0$ 和 $i\bar{\psi}^m \partial_m \psi_R = 0$ 。

② 零质量粒子具有确定的螺旋度，即为左旋或右旋。

③ 由于左旋态和右旋态互为空间反射态，故具有不确定螺旋度的态没有空间反射不变性，即不是宇称 P 的本征态。

④ 可以证明，上述一对二分量 Weyl 方程在空间反射 P 变换下互相转变，故该方程不是宇称空间反射变换 P 不变的，同样它们也不是 C 不变的，但在 CP 变换下是不变的。

5. 手征变换的手征流，守恒荷。

$$J_5^m = \bar{\psi} \gamma^m \gamma_5 \psi.$$

$$Q_5 = \int d^3x \bar{\psi} \gamma^0 \gamma_5 \psi = \int d^3x \bar{\psi}^+ \gamma_5 \psi = \begin{cases} \int d^3x (\bar{\psi}_L^+ \psi_R + \bar{\psi}_R^+ \psi_L) & \text{Dirac 表象.} \\ \int d^3x (\bar{\psi}_R^+ \psi_R - \bar{\psi}_L^+ \psi_L) & \text{Weyl 表象.} \end{cases}$$

四. Majorana 旋量（马拉约纳旋量）。

1. Majorana 旋量。

若电荷共轭旋量 ψ^c 满足 $\overline{\psi_m^c} = \psi_m$ ，则称 ψ_m 为 Majorana 旋量

由定义，它的自由度只有 Dirac 旋量的一半（？），故等价于二分量 Weyl 复旋量场，从而零质量自旋 $\frac{1}{2}$ 粒子也可用 ψ_m 描述。

动能项：

$$\mathcal{L}_M = \frac{i}{2} \bar{\psi}_M \gamma^m \partial_m \psi_M, \quad (\psi_M)^c = \psi_M$$

质量项：

$$\mathcal{L}_M^m = -\frac{1}{2} m \bar{\psi}_M \psi_M$$

质量项能包含单一的手征场如 ψ_L 构成。在 Weyl 表象下， $C = i\gamma^3 \gamma^0 = i \begin{pmatrix} 0 & \sigma^2 \\ \sigma^2 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} i\sigma^2 & 0 \\ 0 & -i\sigma^2 \end{pmatrix}$

可以证明，例如 $\psi_M = \begin{pmatrix} \psi_L \\ -i\sigma^2 \psi_L^* \end{pmatrix}$ 满足 Majorana 旋量条件 $(\psi_M)^c = \psi_M$ ，质量项此时为

$$\mathcal{L}_M^m = \frac{i}{2} (\bar{\psi}_L^+ \sigma^2 \psi_L^* - \bar{\psi}_L^T \sigma^2 \psi_L) \quad \sigma^2 = \sigma_2^+$$

$$\text{证: } \bar{\psi}_M = \bar{\psi}_M^+ \gamma^0 = (\bar{\psi}_L^+ \quad \bar{\psi}_L^{*+}; \sigma_2^+ \psi_L^*) \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = (\bar{\psi}_L^{*+} \sigma_2^+ \psi_L^* \quad \bar{\psi}_L^+)$$

$$\frac{1}{2} m \bar{\psi}_M \psi_M = \left(\bar{\psi}_L^+ \quad \bar{\psi}_L^{*+}; \sigma_2^+ \psi_L^* \right) \begin{pmatrix} \bar{\psi}_L^+ \\ -i\sigma^2 \psi_L^* \end{pmatrix} = -\frac{m}{2} (\bar{\psi}_L^+ \psi_L)$$

$$-\frac{1}{2} m \bar{\psi}_M \psi_M = -\frac{m}{2} (\bar{\psi}_L^+ \sigma_2^+ \psi_L^* \quad \bar{\psi}_L^+) \begin{pmatrix} \bar{\psi}_L^+ \\ -i\sigma^2 \psi_L^* \end{pmatrix} = -\frac{m}{2} (\bar{\psi}_L^+ \sigma_2^+ \psi_L^* - \bar{\psi}_L^+ i\sigma^2 \psi_L^*)$$

$$= \frac{im}{2} (\bar{\psi}_L^+ \sigma_2^+ \psi_L^* - \bar{\psi}_L^+ \sigma_2^+ \psi_L^*)$$

此式表明：① \mathcal{L}_M^m 仅含 ψ_L 不含 ψ_R ，因此仅有手征场并不能完全保证费米子质量。仅有手征场

将禁戒 Dirac 质量项并不排除马拉约纳质量项。（仅保留 $\psi_L \rightarrow \psi_L' = -\psi_L$ 的对称性）

② \mathcal{L}_M^m 破坏整体相位不变性 $\psi_L \rightarrow \psi_L' = e^{i\alpha} \psi_L$ ，从而手征费米子数（左手手征费米子数）不守恒。

§3.7. 自由电磁场

一. 麦克斯维方程

1867年，英国麦克斯韦(Maxwell)建立了描述电磁场运动的方程，后经德国赫兹(Hertz)提炼，得到我们今天的麦方。1905年，爱因斯坦创立了狭义相对论实现了时间与空间、电场与磁场的统一，得到了麦克斯维方程的四维协变形式。1926年，量子力学问世，人们认识到麦方不但是经典电磁场的方程，也是光子的相对论性波动方程。1927年，狄拉克提出将电磁场作为一个具有无穷维自由度的系统进行量子化的方案，将电磁场傅里叶分解为一系列基本的振动模式。这一方案将经典电磁场量子化，从而统一描述了光子的波动性和粒子性，由此经典电磁场量子化的方案就成功地描述了光子的产生和湮灭的高速微观现象。

1. 经典麦克斯维方程。

$$\begin{cases} \text{经典麦方: } \\ \nabla \cdot \vec{E} = \rho \\ \nabla \times \vec{B} = -\frac{\partial \vec{B}}{\partial t} \\ \nabla \cdot \vec{B} = 0 \\ \nabla \times \vec{E} = \vec{j} + \frac{\partial \vec{E}}{\partial t} \end{cases} \quad \begin{cases} \text{势形式的麦方} \\ \vec{B} = \nabla \times \vec{A} \\ \nabla \times (\vec{E} + \frac{\partial \vec{A}}{\partial t}) = 0 \\ \vec{E} + \frac{\partial \vec{A}}{\partial t} = -\nabla \phi \\ \nabla \cdot \vec{E} + \frac{\partial \vec{A}}{\partial t} = -\nabla^2 \phi \end{cases} \quad \begin{cases} \nabla^2 \vec{A} - \frac{\partial^2}{\partial t^2} \vec{A} - \nabla(\nabla \cdot \vec{A} + \frac{\partial \phi}{\partial t}) = -\vec{j} \\ \nabla^2 \phi + \frac{\partial^2}{\partial t^2}(\nabla \cdot \vec{A}) = -\rho \end{cases} \quad (*) \quad (**)$$

$$2) \text{ 引入四维势矢量: } A^\mu = (\phi, \vec{A}) \text{ 或 } A_\mu = (\phi, -\vec{A}); j^\mu = (\rho, \vec{j}) \text{ 或 } j_\mu = (\rho, -\vec{j})$$

则

$$\partial_\nu (\partial^\mu A^\nu - \partial^\nu A^\mu) = -j^\mu$$

证明:

$$\partial_\nu (\partial^\mu A^\nu - \partial^\nu A^\mu) = \partial^\mu \partial_\nu A^\nu - \partial_\nu \partial^\nu A^\mu = \partial^\mu (\frac{\partial \phi}{\partial t} + \nabla \cdot \vec{A}) - (\frac{\partial^2}{\partial t^2} - \nabla^2) A^\mu = -j^\mu.$$

$$\text{当 } \mu=0 \text{ 时, } \frac{\partial}{\partial t} (\frac{\partial \phi}{\partial t} + \nabla \cdot \vec{A}) - (\frac{\partial^2}{\partial t^2} - \nabla^2) \phi = -\rho,$$

$$\text{即 } \nabla^2 \phi + \frac{\partial^2}{\partial t^2} (\nabla \cdot \vec{A}) = -\rho \quad (**)$$

当 $\mu=1,2,3$ 时,

$$-\nabla (\frac{\partial \phi}{\partial t} + \nabla \cdot \vec{A}) - (\frac{\partial^2}{\partial t^2} - \nabla^2) \vec{A} = -\vec{j}$$

$$\text{即 } \nabla^2 \vec{A} - \frac{\partial^2}{\partial t^2} \vec{A} - \nabla(\nabla \cdot \vec{A} + \frac{\partial \phi}{\partial t}) = -\vec{j} \quad (*)$$

3) 电磁场张量形式的麦方

引入 $F_{\mu\nu} = \partial_\mu A_\nu - \partial_\nu A_\mu$, 则

$$\partial_\nu F^{\mu\nu} = -j^\mu$$

$$\partial^\mu (\partial_\mu, \nabla) \quad F^{i0} = \partial^i A_0 - \partial_0 A^i = -\nabla^i \phi - \frac{\partial}{\partial t} A^i = E^i$$

$$\partial_\mu (\partial_\mu, \nabla) \quad F^{ij} = \partial^i A_j - \partial^j A_i = -\nabla^i A^j - (-\nabla^j A^i) = -\epsilon^{ijk} B^k$$

$$\text{其中 } F_{i0} = \partial_i A_0 - \partial_0 A_i = \partial_i \phi + \frac{\partial}{\partial t} A_i = -E_i \leftrightarrow F^{i0} = E^i \quad F^{ij} = \begin{pmatrix} 0 & -E^1 & -E^2 & -E^3 \\ E^1 & 0 & -B^3 & B^2 \\ E^2 & B^3 & 0 & -B^1 \\ E^3 & -B^2 & B^1 & 0 \end{pmatrix}$$

$$F_{ij} = \partial_i A_j - \partial_j A_i = \epsilon_{ijk} B^k$$

$$\leftrightarrow F^{ij} = \epsilon^{ijk} B^k$$

2. 拉格朗日形式

由拉氏密度满足洛伦兹不变性，设

$$\mathcal{L} = -\frac{1}{2} [a \partial_\mu A^\nu \partial^\mu A_\nu + b \partial_\mu A^\nu \partial_\nu A^\mu + c (\partial_\mu A^\mu)^2 + d A_\mu A^\mu]$$

系数 a, b, c, d 为实数，待定。利用 E-L 方程与麦方比较可以定出。

$$\text{E-L 方程 } a \partial^\nu \partial_\nu A^\mu + (b+c) \partial^\mu \partial^\nu A_\nu - d A^\mu = 0 \quad (\star)$$

真空中麦方. ① $\nabla \cdot \vec{E} = 0$, $\nabla \times \vec{B} = \frac{\partial \vec{E}}{\partial t}$ 或 $\partial_\mu F^{\mu\nu} = 0$. 其中 $F^{i0} = E^i$, $F^{ij} = -\epsilon^{ijk} B^k$
 ② $\nabla \cdot \vec{B} = 0$, $\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$ 或 $\partial_\mu \tilde{F}^{\mu\nu} = 0$. 其中 $\tilde{F}^{\mu\nu} = \frac{1}{2} \epsilon^{\mu\nu\rho\sigma} F_{\rho\sigma}$, $\begin{cases} \tilde{F}^{00} = B^i \\ \tilde{F}^{ij} = +\epsilon^{ijk} E^k \end{cases}$

满足 $F^{\mu\nu} \rightarrow \tilde{F}^{\mu\nu}$ 时有 $\begin{cases} E^i \leftrightarrow +B^i \\ B^i \leftrightarrow -E^i \end{cases}$ 。且 $\partial_\mu \tilde{F}^{\mu\nu} = 0 \Rightarrow \partial_\mu F^{\mu\nu} = 0$ 并不独立。

真空中麦方 1 为 $\partial_\nu F^{\nu\mu} = 0$, 即 $\partial_\nu (\partial^\nu A^\mu - \partial^\mu A^\nu) = 0$ 或

$$\partial_\nu \partial^\nu A^\mu - \partial^\mu \partial_\nu A^\nu = 0 \quad (\times)$$

(\star) 与 (\times) 对比, 可得

$$a=1, \quad b+c=-1, \quad d=0.$$

$$\tilde{F}^{\mu\nu} = \begin{pmatrix} 0 & -B^1 & -B^2 & -B^3 \\ B^1 & 0 & E^3 & -E^2 \\ B^2 & -E^3 & 0 & E^1 \\ B^3 & E^2 & -E^1 & 0 \end{pmatrix}$$

$$\therefore \mathcal{L} = -\frac{1}{2} (\partial_\mu A^\nu \partial^\mu A_\nu - \partial_\mu A^\nu \partial_\nu A^\mu) = -\frac{1}{4} F_{\mu\nu} F^{\mu\nu}$$

拉氏密度中, A^μ 的量纲为 1, 质量为 0。

二 规范变换下的不变性

电磁理论中, \vec{E}, \vec{B} 被认为是基本的, 而 \vec{A} 认为是辅助场; 由于 $F^{\mu\nu}$ 由 \vec{E}, \vec{B} 构成, 所以是基本的, 而 A^μ 是辅助的。

1. 规范变换

对于给定的 $F^{\mu\nu}(x), A^\mu(x)$ 具有很大的任意性。对 A^μ 做变换 ($\alpha(x)$ 为时空中标量函数)

$$A^\mu(x) \rightarrow A'^\mu(x) = A^\mu(x) + \partial^\mu \alpha(x).$$

$$\begin{aligned} F'^{\mu\nu}(x) &\rightarrow F'^{\mu\nu}(x) = \partial^\mu A'^\nu(x) - \partial^\nu A'^\mu(x) = \partial^\mu (A^\nu + \partial^\nu \alpha(x)) - \partial^\nu (A^\mu + \partial^\mu \alpha(x)) \\ &= \partial^\mu A^\nu(x) - \partial^\nu A^\mu(x) = F^{\mu\nu}(x) \quad \text{保持不变, 故 } \mathcal{L}(x) \text{ 也不变。} \end{aligned}$$

由于 $\frac{1}{2} m^2 A_\mu A^\mu$ 不满足上述规范变换下的不变性, 故电磁场质量为 0。

2. 库仑规范(辐射规范)

由于规范变换带来的任意性, 对 A^μ 可作不同的选择。不同的选择对应不同的规范。

取 $\begin{cases} \nabla \cdot \vec{A} = 0 \\ A^0 = 0 \end{cases}$

$$\begin{cases} A^\mu(x) = A^\mu e^{i\vec{P} \cdot \vec{x}} \\ \vec{A}(x) = \vec{A} e^{i\vec{P} \cdot \vec{x}} \end{cases} \quad \text{则 } -i\vec{P} \cdot \vec{A} = 0 \quad \therefore \vec{A} \perp \vec{P}, A^0 = 0.$$

电场强度 A^μ 中只留下垂直于运动方向的两个横向分量(左旋、右旋), 没有物理自由度。但库仑规范失洛伦兹协变性。

3. 洛伦兹规范

$$\partial_\mu A^\mu(x) = 0.$$

即使最初 A^μ 不满足该条件，对 A^μ 作规范变换。
 $A^\mu \rightarrow A'^\mu = A^\mu - \partial^\mu \alpha$, 只需选择 α 使 $\square \alpha = \partial_\mu A^\mu$, 则
 A'^μ 一定能满足条件 $\partial_\mu A'^\mu(x) = 0$.

在洛伦兹规范下，麦方简化为 $\square A^\mu(x) = 0$ 。由 ~~此~~ 此时 $A^\mu(x)$ 仍有规范任意性。
 对 A^μ 再作规范变换 $A^\mu \rightarrow A'^\mu = A^\mu + \partial^\mu \alpha$, 为使 A'^μ 满足麦方 $\square A'^\mu(x) = 0$ ，
 只需补充函数满足 $\square \alpha = 0$ 即可，此时 α 仍然有无限多。

洛伦兹规范 $\partial_\mu A^\mu(x) = 0$ 具有协变性，但它不能消除所有非物理的自由度。
 洛伦兹条件可以利用一个拉格朗日乘子 λ 纳入拉氏密度和运动方程来实现。

$$\mathcal{L} = -\frac{1}{4} F_{\mu\nu} F^{\mu\nu} - \frac{\lambda}{2} (\partial_\mu A^\mu)^2$$

一方面， $-\frac{\lambda}{2} (\partial_\mu A^\mu)^2$ 在规范变换 $A^\mu \rightarrow A'^\mu = A^\mu + \partial^\mu \alpha$ 下仍然保持不变，只要其中 α 满足 $\square \alpha = 0$ 即可。

另一方面，相应 E-L 方程为

$$\square A^\mu + (\lambda - 1) \partial^\mu (\partial_\mu A^\mu) = 0.$$

可以证明，这个方程若在 $t=0$ 时满足洛伦兹条件 $\partial_\mu A^\mu = 0$ 且 $\frac{\partial}{\partial t} \partial_\mu A^\mu = 0$ ，则 t 时刻也有 $\partial_\mu A^\mu = 0$ ，即运动方程也满足洛伦兹条件。

[证明：对 E-L 方程取四散度， $\square \partial_\mu A^\mu + (\lambda - 1) \square(\partial \cdot A) = \lambda \square(\partial \cdot A) = 0$ ，

$$\text{即 } \square \partial_\mu A^\mu = 0 \quad (\lambda \neq 0)$$

若 $t=0$ 时， $X \equiv \partial_\mu A^\mu = 0$, $\frac{\partial}{\partial t} X = 0$ ，则 t 时刻时，将 X 对 t 展开

$$X = X|_{t=0} + \frac{\partial X}{\partial t}|_{t=0} t + \frac{1}{2} \frac{\partial^2 X}{\partial t^2}|_{t=0} t^2 + \dots$$

由初始条件，第一、二项为 0，由 $\square \partial_\mu A^\mu \equiv \square X = 0$ ，得 $X \sim e^{i(k^0 t - \vec{k} \cdot \vec{x})}$ ，是平面波之叠加，
 其中 \vec{x} 和 t 的依赖部分相互独立，从而

$$\frac{\partial^2 X}{\partial t^2}|_{t=0} = \nabla^2 X|_{t=0} = \nabla^2 (X|_{t=0}) = 0.$$

$$\frac{\partial^3 X}{\partial t^3}|_{t=0} = \nabla^2 \frac{\partial X}{\partial t}|_{t=0} = \nabla^2 \left(\frac{\partial X}{\partial t}|_{t=0} \right) = 0$$

故 X 展开式中所有更高次项均为 0。

综上，若 $t=0$ 时， $X \equiv \partial_\mu A^\mu = 0$ ，则 t 时刻洛伦兹条件 $X \equiv \partial_\mu A^\mu = 0$ 也满足。]

三. 守恒流、守恒荷.

$$j^{\mu\alpha} = - \left[\partial g^{\mu\lambda} - \frac{\partial \mathcal{L}}{\partial (\partial_\mu A_\rho)} \partial^\lambda A_\rho \right] \frac{\delta X_\lambda}{\delta \theta_\alpha} - \frac{\partial \mathcal{L}}{\partial (\partial_\mu A_\lambda)} \frac{\delta A_\lambda}{\delta \theta_\alpha}$$

$$\mathcal{L} = -\frac{1}{4} F_{\mu\nu} F^{\mu\nu} - \frac{\lambda}{2} (\partial_\mu A^\mu)^2 = -\frac{1}{4} (\partial_\mu A_\nu - \partial_\nu A_\mu) (\partial^\mu A^\nu - \partial^\nu A^\mu) - \frac{\lambda}{2} (\partial_\mu A^\mu) (\partial_\nu A^\nu)$$

$$\frac{\partial \mathcal{L}}{\partial (\partial_\mu A_\nu)} = \frac{\partial}{\partial (\partial_\mu A_\nu)} \left\{ -\frac{1}{4} (\partial_\mu A_\nu - \partial_\nu A_\mu) (\partial^\mu A^\nu - \partial^\nu A^\mu) - \frac{\lambda}{2} (\partial_\mu A^\mu) (\partial_\nu A^\nu) \right\}$$

$$= -\frac{1}{4} \{ (\delta_\mu^\mu \delta_\nu^\nu - \delta_\nu^\mu \delta_\mu^\nu) (\partial^\mu A^\nu - \partial^\nu A^\mu) + (\partial_\mu A_\nu - \partial_\nu A_\mu) (\delta^\mu_\nu \delta^\nu - \delta^\nu_\mu \delta^\mu) \}$$

$$- \frac{\lambda}{2} \{ \delta_\mu^\mu \delta_\nu^\nu \partial_\nu A^\mu + \partial_\mu A^\mu \delta_\nu^\nu \delta^\mu \}$$

$$= -\frac{1}{4} \{ [\partial^\mu A^\nu - \partial^\nu A^\mu - \partial^\nu A^\mu + \partial^\mu A^\nu] + [\partial^\mu A^\nu - \partial^\nu A^\mu - \partial^\nu A^\mu + \partial^\mu A^\nu] \} - \frac{2\lambda}{2} \{ \delta^{\mu\nu} \partial_\nu A^\mu \}$$

$$= -(\partial^\mu A^\nu - \partial^\nu A^\mu) - \lambda g^{\mu\nu} \partial_\nu A^\mu = -F^{\mu\nu} - \lambda g^{\mu\nu} \partial_\mu A^\nu.$$

$$\therefore j^{\mu\nu} = - \left[\partial g^{\mu\lambda} + (F^{\mu\rho} + \lambda g^{\mu\rho} \partial_\rho A^\lambda) \partial^\lambda A_\rho \right] \frac{\delta X_\lambda}{\delta \theta_\nu} + (F^{\mu\lambda} + \lambda g^{\mu\lambda} \partial_\lambda A^\nu) \frac{\delta A_\lambda}{\delta \theta_\nu}$$

1. 平移无穷小变换 ($\delta A_\lambda = 0$)

$$\begin{cases} X_m \rightarrow X'_m = X_m + \varepsilon_m \\ \delta \theta_\nu = \varepsilon_\nu \end{cases} \rightarrow \frac{\delta X_m}{\delta \theta_\nu} = g_m^\nu \frac{\varepsilon_\nu}{\varepsilon_m} = g_m^\nu \delta_\nu^\nu = g_m^\nu$$

$$T^{\mu\nu} = - \left[-\frac{1}{4} F_{\mu\nu} F^{\mu\nu} - \frac{\lambda}{2} (\partial_\mu A^\mu)^2 \right] g^{\mu\nu} - (F^{\mu\rho} + \lambda g^{\mu\rho} \partial_\rho A^\nu) \partial^\nu A_\rho g_\nu^\nu$$

$$\therefore \text{守恒流 } T^{\mu\nu} = \left[\frac{1}{4} F^2 + \frac{\lambda}{2} (\partial_\mu A^\mu)^2 \right] g^{\mu\nu} - [F^{\mu\rho} + \lambda g^{\mu\rho} (\partial_\rho A^\nu)] \partial^\nu A_\rho \quad \text{能量动量张量密度}$$

$$\text{守恒荷 } P^\nu = \int d^3x T^{0\nu}, \quad \text{四动量密度.}$$

由于 $T^{\mu\nu}$ 不满足对 μ, ν 的对称性和规范不变性, 常对它做一个相位全散度的变换,

$$T^{\mu\nu} \rightarrow T^{\mu\nu} + \partial_\rho (F^{\mu\rho} A^\nu), \quad \text{此时满足对 } \mu, \nu \text{ 的对称性和规范不变性, 而 } P^\nu \text{ 不变.}$$

2. 无穷小洛伦兹变换

$$\begin{cases} X_m \rightarrow X'_m = X_m + \varepsilon_{\mu\nu} X^\nu \\ \delta \theta_\nu = \varepsilon_{\nu\rho} = \varepsilon_{\nu\rho} \end{cases} \rightarrow \frac{\delta X_\lambda}{\delta \theta_\nu} = \frac{1}{2} (g_\lambda^\nu X_\rho^\rho - g_\lambda^\rho X_\nu^\nu), \quad \text{另外 } A_\lambda \rightarrow A'_\lambda = A_\lambda + \varepsilon_{\lambda\nu} A^\nu$$

$$j^{\mu\nu\rho} = - \left[-\frac{1}{4} F_{\mu\nu} F^{\mu\nu} - \frac{\lambda}{2} (\partial_\mu A^\mu)^2 \right] g^{\mu\nu} \cdot \frac{1}{2} (g_\lambda^\nu X_\rho^\rho - g_\lambda^\rho X_\nu^\nu) - (F^{\mu\rho} + \lambda g^{\mu\rho} \partial_\rho A^\nu) \partial^\nu A_\lambda \cdot \frac{1}{2} (g_\lambda^\nu X_\rho^\rho - g_\lambda^\rho X_\nu^\nu)$$

$$\text{守恒流 } j^{\mu\nu\rho} = X^\nu T^{\mu\rho} - X^\rho T^{\mu\nu} + A^\nu (F^{\mu\rho} + \lambda g^{\mu\rho} \partial_\rho A^\nu) - A^\rho (F^{\mu\nu} + \lambda g^{\mu\nu} \partial_\nu A^\rho) \quad \text{广义角动量张量密度}$$

$$M^{\nu\rho} = \int d^3x j^{\nu\rho} \quad \text{广义角动量}$$

对空间各向同性情况，只考虑空间分量。

$$\text{守恒荷} M^{jk} = \int d^3x j^{ijk} = \int d^3x [x^j T^{0k} - x^k T^{0j} + A^j (F^{0k} + \lambda g^{0k} \partial \cdot A) - A^k (F^{0j} + \lambda g^{0j} \partial \cdot A)]$$

其中 $j, k = 1, 2, 3$, 进一步可引入守恒的角动量。

$$\begin{aligned} J_i &\equiv \frac{1}{2} \varepsilon_{ijk} M^{jk} = \int d^3x \frac{1}{2} \varepsilon_{ijk} j^{0jk} \\ &= \int d^3x \frac{1}{2} \varepsilon_{ijk} [x^j T^{0k} - x^k T^{0j} + A^j (F^{0k} + \lambda g^{0k} \partial \cdot A) - A^k (F^{0j} + \lambda g^{0j} \partial \cdot A)] \end{aligned}$$

定义 $J_i = L_i + S_i$.

则由 δX_λ 改变引起的轨迹角动量

$$L_i = \frac{1}{2} \varepsilon_{ijk} \int d^3x (x^j T^{0k} - x^k T^{0j})$$

由 δA_λ 改变引起的电磁场的自旋角动量。

$$\begin{aligned} S_i &= \int d^3x \frac{1}{2} \varepsilon_{ijk} [A^j (F^{0k} + \lambda g^{0k} \partial \cdot A) - A^k (F^{0j} + \lambda g^{0j} \partial \cdot A)] \\ &= \varepsilon_{ijk} \int d^3x [A^j (F^{0k} + \lambda g^{0k} \partial \cdot A)] \end{aligned}$$

四、电磁场的平面波解

1. 二维极化矢量电磁波平面波解。

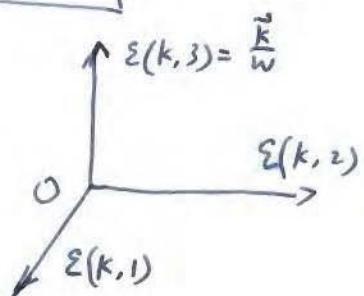
$$\text{麦方 } \square A^m = 0 \rightarrow \begin{cases} A_m^+(x) = A_m(k) e^{-ikx} & \text{正频解。} \\ A_m^-(x) = A_m(k) e^{ikx} & \text{负频解。} \end{cases}$$

设电磁波频率 ω , 波矢 \vec{k} , 则

$$k^m = (\omega, \vec{k}), \quad k_m = (\omega, -\vec{k}).$$

~~由麦方 $\square A^m = 0$~~ 将正、负频解代入得。

$$k^2 = 0 \Rightarrow \omega^2 - |\vec{k}|^2 = 0 \Rightarrow \omega = |\vec{k}|, \quad E = \pm \omega, \text{ 能量有正负，在量子化后可消除。}$$



2. 三维极化矢量

为描述光子的极化状态，取三维空间三个正交单位矢量（如上图）。 $\epsilon(k, 3)$ 与 \vec{k} 平行， $\epsilon(k, 1), \epsilon(k, 2), \epsilon(k, 3)$ 成右手螺旋关系，将它们记为 $\epsilon(k, \lambda)$ ，($\lambda = 1, 2, 3$) 称极化矢量。

$$\text{正交性 } \epsilon(k, \lambda) \cdot \epsilon(k, \lambda') = \delta_{\lambda \lambda'} \quad (\lambda, \lambda' = 1, 2, 3).$$

其中 $\epsilon(k, \lambda)$ ($\lambda = 1, 2$) 为横向极化矢量。
 $\epsilon(k, 3)$ 为纵向极化矢量。

$$\text{完备性 } \sum_{\lambda=1}^3 \epsilon^i(k, \lambda) \epsilon^j(k, \lambda) = \delta^{ij} \quad (i, j = 1, 2, 3).$$

$$\text{摩尔规范下完备性: } \sum_{\lambda=1}^3 \epsilon^i(k, \lambda) \epsilon^j(k, \lambda) = \delta^{ij} - \frac{k^i k^j}{|\vec{k}|^2}$$