

§ 3.5 旋量场双线性协变量

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一. 旋量场双线性协变量.

1. $\bar{\psi}(x)$ 的洛伦兹变换.

$$x^\mu \rightarrow x'^\mu = a^\mu_\nu x^\nu$$

$$\psi(x) \rightarrow \psi'(x') \equiv S \psi(x) = e^{-\frac{i}{4} \omega^{\rho\sigma} \sigma_{\rho\sigma}} \psi(x)$$

$$\bar{\psi}(x) \rightarrow \bar{\psi}'(x') \equiv \psi'^\dagger(x') \gamma^0 = \psi^\dagger(x) \gamma^0 \gamma^0 e^{\frac{i}{4} \omega^{\rho\sigma} \sigma_{\rho\sigma}^\dagger} \gamma^0$$

$$= \bar{\psi}(x) \gamma^0 \sum_{n=0}^{\infty} \frac{1}{n!} \left(\frac{i}{4} \omega^{\rho\sigma}\right)^n (\sigma_{\rho\sigma}^\dagger)^n \gamma^0$$

$$= \bar{\psi}(x) \sum_{n=0}^{\infty} \frac{1}{n!} \left(\frac{i}{4} \omega^{\rho\sigma}\right)^n \underbrace{(\gamma^0 \sigma_{\rho\sigma}^\dagger \gamma^0)(\gamma^0 \sigma_{\rho\sigma}^\dagger \gamma^0) \cdots (\gamma^0 \sigma_{\rho\sigma}^\dagger \gamma^0)}_{n \text{ 个相乘}}$$

$$\because \gamma_i^\dagger = -\gamma_i, \gamma_0^\dagger = \gamma_0,$$

$$\because \gamma_0 \gamma_i^\dagger \gamma_0 = -\gamma_0 \gamma_i \gamma_0 = \gamma_i \gamma_0 \gamma_0 = \gamma_i, \gamma_0 \gamma_0^\dagger \gamma_0 = \gamma_0 \gamma_0 \gamma_0 = \gamma_0, \text{ 即 } \gamma_0 \gamma_\rho^\dagger \gamma_0 = \gamma_\rho$$

$$\begin{aligned} \because \gamma_0 \sigma_{\rho\sigma}^\dagger \gamma_0 &= \gamma_0 \left(\frac{i}{2} [\sigma_\rho, \sigma_\sigma]\right)^\dagger \gamma_0 = -\frac{i}{2} \gamma_0 (\sigma_\rho \sigma_\sigma - \sigma_\sigma \sigma_\rho)^\dagger \gamma_0 = -\frac{i}{2} (\gamma_0 \sigma_\sigma^\dagger \gamma_0 \gamma_\rho^\dagger \gamma_0 - \gamma_0 \sigma_\rho^\dagger \gamma_0 \gamma_\sigma^\dagger \gamma_0) \\ &= -\frac{i}{2} (\gamma_\sigma \sigma_\rho - \sigma_\rho \sigma_\sigma) = \frac{i}{2} (\sigma_\rho \sigma_\sigma - \sigma_\sigma \sigma_\rho) = \sigma_{\rho\sigma} \end{aligned}$$

$$\text{则 } \bar{\psi}'(x') = \bar{\psi}(x) \sum_{n=0}^{\infty} \frac{1}{n!} \left(\frac{i}{4} \omega^{\rho\sigma}\right)^n (\sigma_{\rho\sigma})^n = \bar{\psi}(x) e^{\frac{i}{4} \omega^{\rho\sigma} \sigma_{\rho\sigma}} = \bar{\psi}(x) S^{-1}$$

$$\therefore \bar{\psi}(x) \rightarrow \bar{\psi}'(x') = \bar{\psi}(x) S^{-1}, \text{ 其中 } S = e^{-\frac{i}{4} \omega^{\rho\sigma} \sigma_{\rho\sigma}}, S^\dagger = e^{\frac{i}{4} \omega^{\rho\sigma} \sigma_{\rho\sigma}}$$

2. 由 $\psi(x), \bar{\psi}(x)$ 可以构造的双线性协变量.

(1) 洛伦兹标量: $\bar{\psi}(x) \psi(x)$.

$$\bar{\psi}(x) \psi(x) \rightarrow \bar{\psi}'(x') \psi'(x') = \bar{\psi}(x) S^{-1} S \psi(x) = \bar{\psi}(x) \psi(x), \text{ 不变.}$$

(2) 洛伦兹矢量: $\bar{\psi}(x) \gamma^\mu \psi(x)$

$$\text{① 洛伦兹, } \bar{\psi}(x) \gamma^\mu \psi(x) \rightarrow \bar{\psi}'(x') \gamma^\mu \psi'(x') = \bar{\psi}(x) S^{-1} \gamma^\mu S \psi(x)$$

$$\text{又对于洛伦兹变换, } \boxed{S \gamma^\mu S^{-1} = (a^{-1})^\mu_\nu \gamma^\nu},$$

$$\text{左乘 } S^{-1}, \text{ 右乘 } S, \quad \gamma^\mu = (a^{-1})^\mu_\nu S^{-1} \gamma^\nu S,$$

$$\text{乘 } a^\rho_\mu \text{ 并对 } \mu \text{ 求和. } a^\rho_\mu \gamma^\mu = a^\rho_\mu (a^{-1})^\mu_\nu S^{-1} \gamma^\nu S = \delta^\rho_\nu S^{-1} \gamma^\nu S = S^{-1} \gamma^\rho S$$

$$\therefore \boxed{S^{-1} \gamma^\mu S = a^\mu_\nu \gamma^\nu}$$

$$\text{则 } \bar{\psi}'(x') \gamma^\mu \psi'(x') = a^\mu_\nu \bar{\psi}(x) \gamma^\nu \psi(x)$$

$$\therefore \bar{\psi}(x) \gamma^\mu \psi(x) \rightarrow \bar{\psi}'(x') \gamma^\mu \psi'(x') = a^\mu_\nu \bar{\psi}(x) \gamma^\nu \psi(x) \quad \text{类似矢量变换}$$

3.4 空间反射

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1) 旋量场的空间反射变换.

$$(\vec{x}, t) \rightarrow (\vec{x}', t') = (-\vec{x}, t)$$

$$\psi(x, t) \rightarrow \psi'(\vec{x}', t') = \psi(-\vec{x}, t) \equiv \eta_p P \psi(\vec{x}, t), \quad \bar{\psi}(x, t) \rightarrow \bar{\psi}'(\vec{x}', t') = \eta_p^* \psi^\dagger(\vec{x}, t) P^\dagger \gamma^0$$

其中 η_p 是相因子, P 是 4×4 矩阵, 由拉氏密度在洛变下不变来确定.

$$\text{旋量场 Dirac 方程: } \begin{cases} (i \gamma^\mu \partial_\mu - m) \psi(x) = 0 & (*) \\ \bar{\psi}(x) (i \gamma^\mu \partial_\mu + m) = 0 & (**) \end{cases}$$

$$\text{相应拉氏密度 } \mathcal{L} = \bar{\psi} (i \gamma^\mu \partial_\mu - m) \psi, \quad \text{拉氏 } \frac{\partial \mathcal{L}}{\partial \phi} - \partial_\mu \frac{\partial \mathcal{L}}{\partial (\partial_\mu \phi)} = 0. (*)$$

$$\frac{\partial \mathcal{L}}{\partial \bar{\psi}} = (i \gamma^\mu \partial_\mu - m) \psi, \quad \frac{\partial \mathcal{L}}{\partial (\partial_\mu \bar{\psi})} = 0 \xrightarrow{*} (*)$$

$$\frac{\partial \mathcal{L}}{\partial \psi} = -m \bar{\psi}, \quad \frac{\partial \mathcal{L}}{\partial (\partial_\mu \psi)} = i \gamma^\mu \bar{\psi} \xrightarrow{**} (**)$$

在空间反射变换下.

$$\mathcal{L}(x) = \bar{\psi}(\vec{x}, t) (i \gamma^\mu \partial_\mu - m) \psi(\vec{x}, t) = \bar{\psi}(\vec{x}, t) (i \gamma^0 \partial_0 + i \vec{\gamma} \cdot \nabla - m) \psi(\vec{x}, t)$$

$$\downarrow$$

$$\mathcal{L}'(x') = \bar{\psi}'(-\vec{x}, t) (i \gamma^\mu \partial'_\mu - m) \psi'(-\vec{x}, t) = \bar{\psi}'(-\vec{x}, t) (i \gamma^0 \partial_0 - i \vec{\gamma} \cdot \nabla - m) \psi'(-\vec{x}, t)$$

$$= \psi^\dagger(-\vec{x}, t) \gamma_0 (i \gamma^0 \partial_0 - i \vec{\gamma} \cdot \nabla - m) \eta_p P \psi(\vec{x}, t)$$

$$= \psi^\dagger(\vec{x}, t) P^\dagger \gamma_0^\dagger \gamma_0 (i \gamma^0 \partial_0 - i \vec{\gamma} \cdot \nabla - m) \eta_p P \psi(\vec{x}, t)$$

$$= |\eta_p|^2 \bar{\psi}(\vec{x}, t) \gamma_0 P^\dagger \gamma_0 (i \gamma^0 \partial_0 - i \vec{\gamma} \cdot \nabla - m) P \psi(\vec{x}, t)$$

$$\stackrel{\text{令}}{=} \mathcal{L}(x) = \bar{\psi}(\vec{x}, t) (i \gamma^0 \partial_0 + i \vec{\gamma} \cdot \nabla - m) \psi(\vec{x}, t)$$

$\therefore |\eta_p|^2 = 1 \Rightarrow \eta_p = \pm 1$, η_p 称为宇称. $\eta = +1$ 为正宇称, $\eta = -1$ 为负宇称.
如质子, 中子.

由含 ∂_0 的项相等

$$\gamma_0 P^\dagger \gamma_0 \gamma^0 P = \gamma^0, \text{ 即 } \gamma_0 P^\dagger P = \gamma^0, \text{ 得 } \underline{P^\dagger = P^{-1}}, P \text{ 为么正矩阵.}$$

由含 m 的项相等

$$\gamma_0 P^\dagger \gamma_0 P = 1, \text{ 即 } \underline{\underline{\gamma_0 P^\dagger \gamma_0 = P^{-1}}}$$

由含 ∇ 的项相等

$$\gamma_0 P^\dagger \gamma_0 \vec{\gamma} P = -\vec{\gamma}, \text{ 结合上式, 得 } \underline{\underline{P^{-1} \vec{\gamma} P = -\vec{\gamma}}}$$

$$\text{综上, } P = \gamma_0 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\therefore \text{空间反射: } \psi(\vec{x}, t) \rightarrow \psi'(\vec{x}', t') = \underline{\psi(-\vec{x}, t)} \eta_p \gamma_0 \psi(\vec{x}, t) = \pm \gamma_0 \psi(\vec{x}, t)$$

$$\bar{\psi}(\vec{x}, t) \rightarrow \bar{\psi}'(\vec{x}', t') = \underline{\bar{\psi}(-\vec{x}, t)} \eta_p^* \bar{\psi}(\vec{x}, t) \gamma_0 = \pm \bar{\psi}(\vec{x}, t) \gamma_0$$

$$\bar{\psi}'(-\vec{x}, t)$$

洛伦兹矢量的空间反射变换

在空间反射变换下.

$$\begin{aligned}\bar{\psi}(\vec{x},t)\gamma^\mu\psi(\vec{x},t) &\rightarrow \bar{\psi}'(\vec{x}',t')\gamma^\mu\psi'(\vec{x}',t') \\ &= \gamma_p^\dagger \gamma_p \bar{\psi}(\vec{x},t)\gamma_0\gamma^\mu\gamma_0\psi(\vec{x},t) = \begin{cases} \bar{\psi}(\vec{x})\gamma^\mu\psi(\vec{x}) & \mu=0 \\ -\bar{\psi}(\vec{x})\gamma^\mu\psi(\vec{x}) & \mu=1,2,3 \end{cases}\end{aligned}$$

3) 故 $\bar{\psi}(\vec{x},t)\gamma^\mu\psi(\vec{x},t)$ 为洛伦兹矢量

(3) 洛伦兹标量.

$$\begin{aligned}\bar{\psi}(x)\gamma^5\psi(x) &\rightarrow \bar{\psi}'(x')\gamma^5\psi'(x') \\ &= \bar{\psi}(x)\gamma_0\gamma^5\gamma_0\psi(x) = -\bar{\psi}(x)\gamma^5\psi(x)\end{aligned}$$

4) 故 $\bar{\psi}(x)\gamma^5\psi(x)$ 的洛伦兹标量.

(4) 洛伦兹轴矢量.

$$\begin{aligned}\bar{\psi}(x)\gamma^\mu\gamma^5\psi(x) &\rightarrow \bar{\psi}'(x')\gamma^\mu\gamma^5\psi'(x') \\ &= \bar{\psi}(x)\gamma_0\gamma^\mu\gamma^5\gamma_0\psi(x) = \begin{cases} -\bar{\psi}(x)\gamma^\mu\gamma^5\psi(x) & \mu=0 \\ \bar{\psi}(x)\gamma^\mu\gamma^5\psi(x) & \mu=1,2,3 \end{cases}\end{aligned}$$

故 $\bar{\psi}(x)\gamma^\mu\gamma^5\psi(x)$ 为洛伦兹轴矢量.

一般双线性协变量

一般地讲,在 ψ 与 $\bar{\psi}$ 之间插入任意的 4×4 矩阵可以构成双线性协变量.可以证明,旋量空间的 4×4 矩阵可以按照 16 个基矩阵展开 (因为 4×4 矩阵含 16 个元素,故 4×4 矩阵一定可以用 16 个基矩阵展开),所以独立的双线性协变量有 16 个.

(1)* 下面证明,这 16 个基矩阵可由 γ 矩阵生成.

引入 16 个 γ 矩阵

$$\begin{cases} \Gamma^S \equiv 1, \\ \Gamma^\mu \equiv \gamma_\mu, \\ \Gamma_{\mu\nu} \equiv \sigma_{\mu\nu} = \frac{1}{2}[\gamma_\mu, \gamma_\nu], \\ \Gamma^A \equiv \gamma_5 \gamma_\mu, \\ \Gamma^P \equiv i\gamma_5 \end{cases}$$

证 Γ^a ($a = S, V, T, A, P$) 有如下性质:

- (1) $(\Gamma^a)^2 = \pm 1$.
- (2) 对任意 Γ^a ($\Gamma^a \neq \Gamma^S = 1$), 存在一个 Γ^b , 使 $\Gamma^a \Gamma^b = -\Gamma^b \Gamma^a$.
- (3) 由此,除 Γ^S 外,所有 Γ^a 的迹为 0. 因为 $\forall \Gamma^a$, 可找到 Γ^b , $\text{Tr}(\Gamma^a(\Gamma^b)^2) = \text{Tr}(\Gamma^b \Gamma^a \Gamma^b) = -\text{Tr}((\Gamma^b)^2 \Gamma^a)$ 无论 $(\Gamma^b)^2 = \pm 1$, 皆有 $\text{Tr} \Gamma^a = 0$.
- (4) 封闭性. 对任意一对 (Γ^a, Γ^b) ($a \neq b$), 存在 $\Gamma^c \neq \Gamma^S = 1$, 使得 $\Gamma^a \Gamma^b = \Gamma^c$ (前面可差相因子 $\pm 1, \pm i$).
- (5) 集合 $\{\Gamma^a\}$ ($a = S, V, T, A, P$) 线性无关. 设 $\sum_a \lambda_a \Gamma^a = 0$ (λ_a 为常数), 由 Γ^a 相继乘并迹, 可证 $\lambda_a = 0$.

$$\begin{aligned}\sum_a \lambda_a \text{Tr}(\Gamma^a \Gamma^b) \\ = \lambda_S \text{Tr}(\Gamma^S \Gamma^b) + \lambda_V \text{Tr}(\Gamma^V \Gamma^b) + \lambda_T \text{Tr}(\Gamma^T \Gamma^b) \\ + \lambda_A \text{Tr}(\Gamma^A \Gamma^b) + \lambda_P \text{Tr}(\Gamma^P \Gamma^b)\end{aligned}$$

① 当 $\Gamma^b = \Gamma^S = 1$ 时, 后 4 项为 0, 第 1 项为 λ_S , 故 $\lambda_S = 0$.
 ② 当 $\Gamma^b \neq \Gamma^S = 1$ 时, 对于 $b \neq a$ 情况时, 存在 $\Gamma^c \neq 1$, 使 $\Gamma^a \Gamma^b = \Gamma^c$, $\text{Tr} \Gamma^c = 0$, 故由此可得此时的 $\lambda_a = 0$, 改变 Γ^b , 可得所有 $\lambda_a = 0$.
 综上, $\lambda_a \equiv 0$, 对于 $b = a$ 情况时, $\text{Tr}(\Gamma^b \Gamma^a) \neq 0$.
 故 $\{\Gamma^a\}$ 线性无关.

(2) 16个独立的双线性协变量

$S: \bar{\psi}(x)\psi(x)$; $V: \bar{\psi}(x)\gamma^\mu\psi(x)$; $T: \bar{\psi}(x)\gamma^{\mu\nu}\psi(x)$; $A: \bar{\psi}(x)\gamma_5\gamma^\mu\psi(x)$; $P: i\bar{\psi}(x)\gamma_5\psi(x)$

在洛伦兹变换下, 上述双线性协变量变换为

$$x^\mu \rightarrow x'^\mu = \Lambda^\mu_\nu x^\nu$$

$$\bar{\psi}(x)\psi(x) \rightarrow \bar{\psi}'(x')\psi(x') = \bar{\psi}(x)\psi(x) \quad \text{标量}$$

$$\bar{\psi}(x)\gamma^\mu\psi(x) \rightarrow \bar{\psi}'(x')\gamma^\mu\psi'(x') = \Lambda^\mu_\nu \bar{\psi}(x)\gamma^\nu\psi(x) \quad \text{矢量}$$

$$\bar{\psi}(x)\gamma^{\mu\nu}\psi(x) \rightarrow \bar{\psi}'(x')\gamma^{\mu\nu}\psi'(x') = \Lambda^\mu_\rho \Lambda^\nu_\sigma \bar{\psi}(x)\gamma^{\rho\sigma}\psi(x) \quad \text{反对称张量}$$

$$\bar{\psi}(x)\gamma_5\gamma^\mu\psi(x) \rightarrow \bar{\psi}'(x')\gamma_5\gamma^\mu\psi'(x') = \det(\Lambda) \Lambda^\mu_\nu \bar{\psi}(x)\gamma_5\gamma^\nu\psi(x) \quad \text{轴矢量}$$

$$i\bar{\psi}(x)\gamma_5\psi(x) \rightarrow i\bar{\psi}'(x')\gamma_5\psi'(x') = i\det(\Lambda)\bar{\psi}(x)\gamma_5\psi(x) \quad \text{赝标量}$$

空间反射时
 $\det(\Lambda) = -1$

基于双线性协变量, 可写出 Dirac 旋量场构造的洛伦兹不变量:

$$\bar{\psi}\psi, \bar{\psi}\gamma^\mu\partial_\mu\psi, \partial_\mu\bar{\psi}\gamma^\mu\psi, \dots$$

二. ~~拉氏密度~~ 旋量场的拉氏量, 守恒流, 守恒荷.

1. 拉氏密度: $\mathcal{L} = i\bar{\psi}\gamma^\mu\partial_\mu\psi - m\bar{\psi}\psi = \bar{\psi}(i\not{\partial} - m)\psi$

$[\mathcal{L}] = 4, [\partial_\mu] = 1, \text{ 故 } [\psi] = \frac{3}{2}, \text{ 代入 } E-L \text{ 方程, 得 } \begin{cases} (i\not{\partial} - m)\psi = 0 \\ \bar{\psi}(i\overleftarrow{\not{\partial}} + m) = 0 \end{cases}$

2. 洛伦兹变换下的守恒流, 守恒荷.

(1) 时空平移无穷小变换.

$$x^\mu \rightarrow x'^\mu = x^\mu + \epsilon^\mu$$

作业

$\therefore T_{\mu\nu} = i\bar{\psi}\gamma_\mu\partial_\nu\psi$, 满足 $\partial^\mu T_{\mu\nu} = 0$, $T_{\mu\nu}$ 称为旋量场能量-动量张量密度

相应守恒荷

$$P_\nu = \int d^3x T_{0\nu} = i \int d^3x \psi^\dagger \partial_\nu \psi$$

P_ν 称为旋量场的四动量.

(2) 无穷小洛伦兹变换.

$$x^\mu \longrightarrow x'^\mu = x^\mu + \varepsilon^{\mu\nu} x_\nu$$

$$\psi(x) \longrightarrow \psi'(x) = (1 - \frac{i}{4} \varepsilon^{\rho\sigma} \sigma_{\rho\sigma}) \psi(x).$$

$J_{\mu\nu\rho} = x_\nu T_{\mu\rho} - x_\rho T_{\mu\nu} + \bar{\psi} \gamma_\mu \frac{\sigma_{\nu\rho}}{2} \psi$, 满足 $\partial^\mu J_{\mu\nu\rho} = 0$, $J_{\mu\nu\rho}$ 称为广义角动量张量密度, 相应守恒荷.

$$M_{\nu\rho} = \int d^3x J_{0\nu\rho} = \int d^3x (x_\nu T_{0\rho} - x_\rho T_{0\nu} + \bar{\psi} \gamma_0 \frac{\sigma_{\nu\rho}}{2} \psi), \quad M_{\nu\rho} \text{ 称为广义角动量}$$

δx_ν 轨道角动量, $\delta \psi$ 之自旋角动量

(3) 整体规范变换 (坐标 x 不变)

$$\psi(x) \longrightarrow \psi'(x) = e^{i\alpha} \psi, \quad \delta\psi = +i\alpha\psi$$

$$\bar{\psi}(x) \longrightarrow \bar{\psi}'(x) = \bar{\psi} e^{-i\alpha}, \quad \delta\bar{\psi} = -\bar{\psi}i\alpha$$

$$j_a^\mu = - \left[\mathcal{L} g_a^\mu - \frac{\partial \mathcal{L}}{\partial(\partial_\mu \phi)} \partial_\rho \phi \right] \frac{\partial x^\rho}{\partial \theta^a} - \frac{\partial \mathcal{L}}{\partial(\partial_\mu \phi)} \frac{\delta \phi}{\delta \theta^a},$$

对整体规范变换, $\frac{\partial x^\rho}{\partial \theta^a} = 0$, $\frac{\partial \mathcal{L}}{\partial(\partial_\mu \psi)} = \bar{\psi} i \gamma^\mu$, $\frac{\delta \psi}{\delta \theta^a} = \frac{\delta \psi}{\delta \alpha} = i\psi$.

$$j^\mu = - \frac{\partial \mathcal{L}}{\partial(\partial_\mu \psi)} \frac{\delta \psi}{\delta \theta^a} = -\bar{\psi} i \gamma^\mu i\psi = \bar{\psi} \gamma^\mu \psi.$$

$$\therefore J^\mu = \bar{\psi} \gamma^\mu \psi, \text{ 满足 } \partial_\mu J^\mu = 0.$$

J^μ 称为旋量场矢量流. 如 eJ^μ 为电荷电流密度.

相应守恒荷.

$$Q = \int d^3x J^0 = \int d^3x \bar{\psi} \gamma^0 \psi.$$

Q 称为守恒荷. 如 eQ 为电荷, Q 对应费米数守恒.

§ 3.6 零质量旋量场

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上节讨论了自旋为 $\frac{1}{2}$ 的粒子,当这类粒子质量为0时,它们具有一些特殊的性质。这类粒子如:中微子,电子,轻质量夸克。

一. 零质量粒子的手征变换

1. 手征变换

自旋 $\frac{1}{2}$ 粒子: $\mathcal{L} = \bar{\psi}(x)(i\gamma^\mu \partial_\mu - m)\psi(x)$,

$m=0$ 时: $\mathcal{L} = \bar{\psi}(x)i\gamma^\mu \partial_\mu \psi(x)$.

考虑整体手征变换(x 不变).

$$\psi(x) \longrightarrow \psi'(x) = e^{i\theta\gamma_5} \psi(x)$$

$$\bar{\psi}(x) \longrightarrow \bar{\psi}'(x) = \psi'^{\dagger}(x) \gamma_0 = \psi^{\dagger}(x) \gamma_0 e^{-i\theta\gamma_5} = \bar{\psi}(x) e^{i\theta\gamma_5}$$

$$\therefore \bar{\psi}'(x) = \bar{\psi}(x) e^{i\theta\gamma_5}$$

$$\mathcal{L}(x) = \bar{\psi}(x)i\gamma^\mu \partial_\mu \psi(x) \longrightarrow \mathcal{L}'(x) = \bar{\psi}'(x)i\gamma^\mu \partial_\mu \psi'(x)$$

$$= \bar{\psi}(x) e^{i\theta\gamma_5} i\gamma^\mu \partial_\mu e^{i\theta\gamma_5} \psi(x) \leftarrow \{\gamma^\mu, \gamma_5\} = 0$$

$$= \bar{\psi}(x) i\gamma^\mu \partial_\mu e^{-i\theta\gamma_5} e^{i\theta\gamma_5} \psi(x)$$

$$= \bar{\psi}(x) i\gamma^\mu \partial_\mu \psi(x)$$

$$\therefore \mathcal{L}'(x) = \mathcal{L}(x). \quad \text{拉氏量具有手征对称性} \quad \swarrow$$

2. 手征变换下的守恒流, 守恒荷

(但质量项 $m\bar{\psi}\psi$ 破坏手征对称性)

$$j^\mu_a = -\left[\mathcal{L} g^\mu_a - \frac{\partial \mathcal{L}}{\partial(\partial_\mu \phi)} \partial_\mu \phi\right] \frac{\partial \chi^a}{\partial \theta^a} - \frac{\partial \mathcal{L}}{\partial(\partial_\mu \phi)} \frac{\delta \phi}{\delta \theta^a}$$

1) 对手征变换, $\frac{\partial \chi^a}{\partial \theta^a} = 0$, $\frac{\partial \mathcal{L}}{\partial(\partial_\mu \psi)} = \bar{\psi}(x) i\gamma^\mu$,

$$\psi(x) \longrightarrow \psi'(x) = e^{i\theta\gamma_5} \psi(x)$$

$$\therefore \text{无穷小变换时 } \delta\psi(x) = \psi'(x) - \psi(x) = i\theta\gamma_5\psi(x), \quad \frac{\delta\psi(x)}{\delta\theta} = i\gamma_5\psi(x)$$

$$\therefore \text{守恒流 } j^\mu_5 = -\frac{\partial \mathcal{L}}{\partial(\partial_\mu \psi)} \frac{\delta\psi}{\delta\theta^5} = -\bar{\psi}(x) i\gamma^\mu i\gamma_5 \psi(x) = \bar{\psi}(x) \gamma^\mu \gamma_5 \psi(x)$$

满足 $\partial_\mu j^\mu_5 = 0$. "轴矢量流守恒"

(质量项)

2) 守恒荷

$$Q_5 = \int d^3x j^0_5 = \int d^3x \bar{\psi} \gamma^0 \gamma_5 \psi = \int d^3x \psi^\dagger \gamma_5 \psi$$

二. 手征变换与螺旋度变换的关系.

1. $\vec{\Sigma} \cdot \vec{p}$ 与 γ_5 有共同本征态.

$m=0$ 时运动方程 $\not{p}\psi=0$, 左乘 $\gamma_5 \gamma^\mu$

$$\gamma_5 \not{p} \psi = \gamma_5 \gamma^\mu \gamma^\mu p_\mu \psi = \gamma_5 \gamma^\mu \gamma^\mu p^\mu \psi - \gamma_5 \gamma^\mu \vec{\gamma} \cdot \vec{p} \psi = 0.$$

当 $m=0$ 时, $p^0=|\vec{p}|$ 而 $\vec{\Sigma} = \gamma_5 \gamma^\mu \vec{\gamma}$, 故 $\vec{\Sigma} \cdot \vec{p} \psi \stackrel{\text{red}}{=} \gamma_5 p^0 \psi$, 故

$$\vec{\Sigma} \cdot \frac{\vec{p}}{|\vec{p}|} = \gamma_5 \varepsilon(p^0),$$

这表明

$$\gamma_5 = \begin{cases} + \vec{\Sigma} \cdot \frac{\vec{p}}{|\vec{p}|} & (\text{正能解 } p^0 > 0) \\ - \vec{\Sigma} \cdot \frac{\vec{p}}{|\vec{p}|} & (\text{负能解 } p^0 < 0) \end{cases}$$

即 γ_5 与 $\vec{\Sigma} \cdot \frac{\vec{p}}{|\vec{p}|}$ 具有共同的本征态, 对于正能解时, 二者本征值相同; 对于负能解时, 二者本征值相反. 由此, 可以由 $\vec{\Sigma} \cdot \frac{\vec{p}}{|\vec{p}|}$ 的本征态确定 γ_5 的本征态.

	螺旋度	手征性 (验证)
$\vec{\Sigma} \cdot \vec{p} u_+ = u_+$ $u_+(p)$	$h_a = +1$ 右旋态 $\uparrow \vec{p}$	$\varepsilon_a = -1$ $\gamma_5 u_+(p) = u_+(p)$ 右手征态.
$\vec{\Sigma} \cdot \vec{p} u_- = -u_-$ $u_-(p)$	$h_a = -1$ 左旋态 $\leftarrow \vec{p}$	$\varepsilon_a = +1$ $\gamma_5 u_-(p) = -u_-(p)$ 左手征态.
$\vec{\Sigma} \cdot \vec{p} v_+ = v_+$ $v_+(p)$	$h_a = +1$ 右旋态 $\downarrow \vec{p}$	$\varepsilon_a = -1$ $\gamma_5 v_+(p) = -v_+(p)$ 左手征态.
$\vec{\Sigma} \cdot \vec{p} v_- = -v_-$ $v_-(p)$	$h_a = -1$ 左旋态 $\downarrow \vec{p}$	$\varepsilon_a = +1$ $\gamma_5 v_-(p) = +v_-(p)$ 右手征态.

上述性质概括为

$$\begin{cases} \vec{\Sigma} \cdot \vec{p} u_a(p) = h_a u_a(p) \\ \vec{\Sigma} \cdot \vec{p} v_a(p) = h_a v_a(p) \end{cases}$$

$$\begin{cases} \gamma_5 u_a(p) = \varepsilon_a u_a(p), & \varepsilon_a = +h_a \\ \gamma_5 v_a(p) = \varepsilon_a v_a(p), & \varepsilon_a = -h_a \end{cases}$$

螺旋度与手征性的这种关系是正洛伦兹变换下不变的.

- 说明:
- ① 当 $m=0$ 时, 在正洛伦兹变换下, 粒子动量 $\vec{p} \rightarrow \vec{p}'$, 但它的螺旋性保持不变.
 - ② 当 $m \neq 0$ 时, 对任意给定 \vec{p} , 我们总可以沿 \vec{p} 但以比 $\frac{p}{E_p}$ 大的速度作一洛伦兹变换. 于是粒子动量将改变方向, 但自旋方向仍是一样的. 结果, 粒子的螺旋性 h_a 改变为 $-h_a$. (但这种洛伦兹变换在 $m=0$ 时是不可能的) 报道
 - ③ 对于手征性, 无论 $m=0$ 或 $m \neq 0$, 在正洛伦兹变换下, 粒子的手征性均保持不变.
 - ④ 从而对于 $m=0$ 粒子, 粒子的螺旋性与手征性有上表关系, 且在 LT 时保持不变.
- $m \neq 0$ 粒子, 粒子的螺旋性与手征性没有上表关系, 在 LT 时关系会改变.

2. u_a 与 v_a 互为电荷共轭态.

$u_a(p)$ 和 $v_a(p)$ 同为 γ_5 和 $\vec{\alpha} \cdot \vec{p}$ 的本征态, 本征值相互联系, 故二者不独立.

1). 电荷共轭旋量.

引入矩阵 $C \equiv i\gamma^2\gamma^0 = i \begin{pmatrix} 0 & \sigma^2 \\ -\sigma^2 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} 0 & -i\sigma^2 \\ -i\sigma^2 & 0 \end{pmatrix}$

定义电荷共轭旋量 $\psi^c \equiv C\psi^\dagger = i\gamma^2\psi^*$

由旋量场 Dirac 方程,

$$\begin{cases} (\not{p} - m)u(p) = 0 \\ (\not{p} + m)v(p) = 0 \end{cases}$$

可证 $u(p)$ 与 $v(p)$ 互为电荷共轭旋量.

$$\begin{cases} v(p) = C \bar{u}^\dagger(p) \\ u(p) = C \bar{v}^\dagger(p) \end{cases}$$

1/2 1/2 =

三. 手征旋量场.

1. 手征旋量场定义.

当 $m=0$ 时, 旋量场哈密顿量 $H = \vec{\alpha} \cdot \vec{p} + \beta m = -i\vec{\alpha} \cdot \nabla$, 且 $[H, \gamma_5] = 0$, 故可以对旋量场进行变换.

$$\psi(x) \longrightarrow \psi'(x) = \gamma_5 \psi(x).$$

利用 $\gamma_5 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$, 将 ψ 分解为 $\psi = \psi_L + \psi_R$, 称 ψ_L, ψ_R 为左右手手征旋量场.

$$\begin{cases} \psi_L = \frac{1}{2}(1 - \gamma_5)\psi \\ \psi_R = \frac{1}{2}(1 + \gamma_5)\psi \end{cases}$$

它们是 γ_5 本征态 $\begin{cases} \gamma_5 \psi_L = -\psi_L, \text{ 本征值 } -1 \\ \gamma_5 \psi_R = +\psi_R, \text{ 本征值 } +1 \end{cases}$

引入投影算符 $\begin{cases} P_L = \frac{1}{2}(1 - \gamma_5) \\ P_R = \frac{1}{2}(1 + \gamma_5) \end{cases} \begin{cases} P_L \psi = \psi_L \\ P_R \psi = \psi_R \end{cases}$ 其它为 0.

2. Weyl 表象下的手征旋量场

1) Dirac 表象下

$$\gamma^0 = \beta = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \gamma^i = \begin{pmatrix} 0 & \sigma^i \\ -\sigma^i & 0 \end{pmatrix}, \gamma_5 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \psi = \begin{pmatrix} \psi_1 \\ \psi_2 \\ \psi_3 \\ \psi_4 \end{pmatrix}$$

引入 $P_L = \frac{1}{2}(1 - \gamma_5) = \frac{1}{2} \begin{pmatrix} 1 & -1 \\ 0 & 0 \end{pmatrix}, P_R = \frac{1}{2}(1 + \gamma_5) = \frac{1}{2} \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$

$\Rightarrow \begin{cases} \psi_L = \frac{1}{2} \begin{pmatrix} 1 & -1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} \psi_1 \\ \psi_2 \\ \psi_3 \\ \psi_4 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} \psi_1 - \psi_2 \\ 0 \\ 0 \\ 0 \end{pmatrix}$ 2 分量是复旋量.
 $\psi_R = \frac{1}{2} \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} \psi_1 \\ \psi_2 \\ \psi_3 \\ \psi_4 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 0 \\ 0 \\ \psi_3 + \psi_4 \\ \psi_3 - \psi_4 \end{pmatrix}$ 2 分量是复旋量.

2). Weyl 表象下.

$$\gamma^0 = \beta = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \gamma^i = \begin{pmatrix} 0 & \sigma^i \\ -\sigma^i & 0 \end{pmatrix}, \gamma_5 = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}, \psi = \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix}$$

引入 $P_L = \frac{1}{2}(1 - \gamma_5) = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, P_R = \frac{1}{2}(1 + \gamma_5) = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$

对 Dirac 表象做么正变换, $\gamma_{\text{Weyl}}^\mu = U \gamma_{\text{Dirac}}^\mu U^\dagger, U = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}$

可得 Weyl 表象下的各种 γ 矩阵

$\begin{cases} \psi_L = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} \psi_1 \\ \psi_2 \\ \psi_3 \\ \psi_4 \end{pmatrix} = \begin{pmatrix} \psi_1 \\ \psi_2 \\ 0 \\ 0 \end{pmatrix} \psi \text{ 的前两个分量} \\ \psi_R = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} \psi_1 \\ \psi_2 \\ \psi_3 \\ \psi_4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ \psi_3 \\ \psi_4 \end{pmatrix} \psi \text{ 的后两个分量} \end{cases}$

3. 手征变换

$$\psi \rightarrow \psi' = e^{i\theta\gamma_5} \psi,$$

$$\gamma_5 = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}, \quad \gamma_5^n = \begin{pmatrix} (-1)^n & 0 \\ 0 & 1 \end{pmatrix}, \quad P_L \psi_L = \psi_L, \quad P_R \psi_R = \psi_R$$

Weyl表象下.

$$\begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix} \rightarrow \begin{pmatrix} \psi'_L \\ \psi'_R \end{pmatrix} = e^{i\theta\gamma_5} \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix} = \sum \frac{(i\theta)^n}{n!} \gamma_5^n \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix} = \sum \frac{(i\theta)^n}{n!} \begin{pmatrix} (-1)^n & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix} = \sum \frac{(i\theta)^n}{n!} \begin{pmatrix} (-1)^n \psi_L \\ \psi_R \end{pmatrix}$$

$$\therefore \psi_L \rightarrow \psi'_L = \sum \frac{(i\theta)^n}{n!} \psi_L = \sum \frac{(-i\theta)^n}{n!} \left(\frac{1-\gamma_5}{2}\right)^n \psi_L = e^{-\frac{i}{2}\theta(1-\gamma_5)} \psi_L$$

$$\psi_R \rightarrow \psi'_R = \sum \frac{(i\theta)^n}{n!} \psi_R = \sum \frac{(i\theta)^n}{n!} \left(\frac{1+\gamma_5}{2}\right)^n \psi_R = e^{\frac{i}{2}\theta(1+\gamma_5)} \psi_R$$

即 $\begin{cases} \psi_L \rightarrow \psi'_L = e^{\frac{i}{2}\theta_L(1-\gamma_5)} \psi_L \\ \psi_R \rightarrow \psi'_R = e^{\frac{i}{2}\theta_R(1+\gamma_5)} \psi_R \end{cases}$, 可证此式在Dirac表象下也成立。

4. 运动方程

Weyl表象下, $\psi = \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix}$, 零质量旋量场拉氏密度.

$\mathcal{L} = \bar{\psi} i \gamma^\mu \partial_\mu \psi =$ 在Weyl表象下,

$$\psi = \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix}, \quad \bar{\psi} = \psi^\dagger \gamma^0 = (\psi_L^\dagger \psi_R^\dagger) \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = (\psi_R^\dagger \psi_L^\dagger)$$

$$\gamma^\mu \partial_\mu = \gamma^0 \partial_0 + \vec{\gamma} \cdot \nabla = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \partial_0 + \begin{pmatrix} 0 & \vec{\sigma} \\ -\vec{\sigma} & 0 \end{pmatrix} \cdot \nabla = \begin{pmatrix} 0 & \partial_0 + \vec{\sigma} \cdot \nabla \\ \partial_0 - \vec{\sigma} \cdot \nabla & 0 \end{pmatrix}$$

则零质量旋量场拉氏密度.

$$\begin{aligned} \mathcal{L} = \bar{\psi} i \gamma^\mu \partial_\mu \psi &= (\psi_R^\dagger \psi_L^\dagger) i \begin{pmatrix} 0 & \partial_0 + \vec{\sigma} \cdot \nabla \\ \partial_0 - \vec{\sigma} \cdot \nabla & 0 \end{pmatrix} \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix} = i (\psi_R^\dagger \psi_L^\dagger) \begin{pmatrix} (\partial_0 + \vec{\sigma} \cdot \nabla) \psi_R \\ (\partial_0 - \vec{\sigma} \cdot \nabla) \psi_L \end{pmatrix} \\ &= i \psi_L^\dagger (\partial_0 - \vec{\sigma} \cdot \nabla) \psi_L + i \psi_R^\dagger (\partial_0 + \vec{\sigma} \cdot \nabla) \psi_R \end{aligned}$$

即 $\mathcal{L} = \mathcal{L}_L + \mathcal{L}_R$, 其中.

$$\begin{cases} \mathcal{L}_L = i \psi_L^\dagger \bar{\sigma}^\mu \partial_\mu \psi_L, & \bar{\sigma}^\mu = (1, -\vec{\sigma}) \\ \mathcal{L}_R = i \psi_R^\dagger \sigma^\mu \partial_\mu \psi_R, & \sigma^\mu = (1, +\vec{\sigma}) \end{cases}$$

$$\bar{\sigma}^\mu \equiv (1, -\vec{\sigma})$$

运动方程若用 ψ_L 表示: $\frac{\partial \mathcal{L}}{\partial \psi_L^\dagger} = i \bar{\sigma}^\mu \partial_\mu \psi_L, \quad \partial_\mu \left(\frac{\partial \mathcal{L}}{\partial (\partial_\mu \psi_L)} \right) = 0 \Rightarrow \begin{cases} i \bar{\sigma}^\mu \partial_\mu \psi_L = 0 \text{ 或 } (P_0 - \vec{\sigma} \cdot \vec{p}) \psi_L = 0 \\ \text{运动方程若用 } \psi_R \text{ 表示: } \frac{\partial \mathcal{L}}{\partial \psi_R^\dagger} = i \sigma^\mu \partial_\mu \psi_R, \quad \partial_\mu \left(\frac{\partial \mathcal{L}}{\partial (\partial_\mu \psi_R)} \right) = 0 \Rightarrow \begin{cases} i \sigma^\mu \partial_\mu \psi_R = 0 \text{ 或 } (P_0 + \vec{\sigma} \cdot \vec{p}) \psi_R = 0 \end{cases} \end{cases}$

= 分量 Weyl 方程描述无质量, 具有确定螺旋度的粒子:

- ① $i \bar{\sigma}^\mu \partial_\mu \psi_L = 0$ 或 $(P_0 - \vec{\sigma} \cdot \vec{p}) \psi_L = 0$
 - 若 $P^0 > 0$ (正能粒子), 左手性 (手征性 = 螺旋度 = -1) 得左旋, 左旋粒子, 如左旋中微子
 - 即若假设 $m_\nu \approx 0$, 则正中微子用左手场 ψ_L 描述, $\gamma_5 = \vec{\Sigma} \cdot \frac{\vec{p}}{|\vec{p}|}$, 本征值为 -1
 - 若 $P^0 < 0$, 左手性得 (手征性 = -螺旋度 = -1) 得右旋, 右旋反粒子, 如右旋反中微子, $\gamma_5 = -\vec{\Sigma} \cdot \frac{\vec{p}}{|\vec{p}|}$, 本征值为 +1
- ② $i \sigma^\mu \partial_\mu \psi_R = 0$ 或 $(P_0 + \vec{\sigma} \cdot \vec{p}) \psi_R = 0$
 - 若 $P^0 > 0$ (正能粒子), 右手性 (手征性 = +螺旋度 = +1) 得右旋, 右旋粒子, 但与实验不符合.
 - 若 $P^0 < 0$ (负能粒子), 右手性 (手征性 = -螺旋度 = +1) 得左旋, 左旋反粒子, 但与实验不符合.

综上:

- ① Dirac 方程对零质量粒子在 Weyl 表象中分解为一对二分量 Weyl 方程, 左旋和右旋粒子分别遵从 $i\bar{\sigma}^\mu \partial_\mu \psi_L = 0$ 和 $i\bar{\sigma}^\mu \partial_\mu \psi_R = 0$.
- ② 零质量粒子具有确定的螺旋度, 即为左旋或右旋。
- ③ 由于左旋态和右旋态互为空间反射态, 故具有确定螺旋度的态没有空间反射不变性, 即不是宇称 P 的本征态。
- ④ 可以证明, 上述一对二分量 Weyl 方程在空间反射 P 变换下互相转变, 故每方程不是单独空间反射变换 P 不变的, 同样它们也不是 C 不变的, 但在 CP 变换下是不变的。

5. 宇征变换的守恒流, 守恒荷.

$$J_5^\mu = \bar{\psi} \gamma^\mu \gamma_5 \psi.$$

$$Q_5 = \int d^3x \bar{\psi} \gamma^0 \gamma_5 \psi = \int d^3x \psi^\dagger \gamma_5 \psi = \begin{cases} \int d^3x (\psi_L^\dagger \psi_R + \psi_R^\dagger \psi_L) & \text{Dirac 表象.} \\ \int d^3x (\psi_R^\dagger \psi_R - \psi_L^\dagger \psi_L) & \text{Weyl 表象.} \end{cases}$$

IV. Majorana 旋量 (马约纳旋量).

1. Majorana 旋量.

若电荷共轭旋量 ψ^c 满足 $\psi^c = \psi$, 则称 ψ 为 Majorana 旋量

由定义, 它的自由度只有 Dirac 旋量的一半(?), 故可等价于二分量 Weyl 复旋量场, 从而零质量自旋 $\frac{1}{2}$ 粒子也可用 ψ 描写。

动能项: $\mathcal{L}_M = \frac{i}{2} \bar{\psi}_M \gamma^\mu \partial_\mu \psi_M, \quad (\psi_M)^c = \psi_M$

质量项: $\mathcal{L}_M^m = -\frac{1}{2} m \bar{\psi}_M \psi_M$

质量项能够由单一的手征场如 ψ_L 构成。在 Weyl 表象下, $C = i\gamma^2 \gamma^0 = i \begin{pmatrix} 0 & \sigma^2 \\ \sigma^2 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} i\sigma^2 & 0 \\ 0 & -i\sigma^2 \end{pmatrix}$ 可以证明, 例如 $\psi_M = \begin{pmatrix} \psi_L \\ -i\sigma^2 \psi_L^* \end{pmatrix}$ 满足 Majorana 旋量条件 $(\psi_M)^c = \psi_M$, 质量项此时为

$$\mathcal{L}_M^m = \frac{i}{2} (\psi_L^\dagger \sigma^2 \psi_L^* - \psi_L^T \sigma^2 \psi_L) \quad \sigma_2^+ = \sigma_2$$

证: $\bar{\psi}_M = \psi_M^\dagger \gamma^0 = (\psi_L^\dagger \quad \psi_L^{*\dagger} i\sigma_2) \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = (\psi_L^\dagger i\sigma_2 \quad \psi_L^{*\dagger})$

$$-\frac{1}{2} m \bar{\psi}_M \psi_M = -\frac{m}{2} (\psi_L^\dagger \quad \psi_L^T i\sigma_2 \psi_L^*) \begin{pmatrix} \psi_L \\ -i\sigma^2 \psi_L^* \end{pmatrix} = -\frac{m}{2} (\psi_L^\dagger \psi_L$$

$$- \psi_L^T i\sigma_2 \psi_L^*) = -\frac{m}{2} (\psi_L^\dagger i\sigma_2 \psi_L - \psi_L^T i\sigma_2 \psi_L^*) = \frac{im}{2} (\psi_L^\dagger \sigma_2 \psi_L^* - \psi_L^T \sigma_2 \psi_L)$$

此式表明: ① \mathcal{L}_M^m 仅含 ψ_L 不含 ψ_R , 因此仅有手征场并不能完全保证费米子无质量。仅有手征场梅黎式 Dirac 质量项并不排除马约纳质量项。(仅保留 $\psi_L \rightarrow \psi_L' = -\psi_L$ 的对称性)
② \mathcal{L}_M^m 破坏整体相位不变性 $\psi_L \rightarrow \psi_L' = e^{i\theta} \psi_L$, 从而手征费米子数 (左手费米子数) 不守恒。

§3.7. 自由电磁场

一. 麦克斯维方程

1867年, 英国麦克斯韦(Maxwell)建立了描述电磁场运动的方程, 后经德国赫兹(Hertz)提炼, 得到我们今天的麦方。1905年, 爱因斯坦创立了狭义相对论, 实现了时间与空间、电场与磁场的统一, 得到了麦克斯维方程的四维协变形式。1926年, 量子力学问世, 人们认识到麦方不但是经典电磁场的方程, 也是光子的相对论性波动方程。1927年, 狄拉克提出将电磁场作为一个具有无穷维自由度的系统进行量子化的方案, 将电磁场傅里叶分解为一系列基本的振动模式。这一方案将经典电磁场量子化, 从而统一描述了光子的产生和湮灭的波动性和粒子性, 由此, 经典电磁场量子化的方案就成功地描述了光子的产生和湮灭的高速微观现象。

1. 经典麦克斯维方程.

1) 经典麦方. $\left\{ \begin{array}{l} \nabla \cdot \vec{E} = \rho \\ \nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \\ \nabla \cdot \vec{B} = 0 \\ \nabla \times \vec{B} = \vec{j} + \frac{\partial \vec{E}}{\partial t} \end{array} \right.$ 引入 $\vec{B} = \nabla \times \vec{A}$ $\rightarrow \nabla \times (\vec{E} + \frac{\partial \vec{A}}{\partial t}) = 0$ 势形式的麦方 $\left\{ \begin{array}{l} \nabla^2 \vec{A} - \frac{\partial^2 \vec{A}}{\partial t^2} - \nabla(\nabla \cdot \vec{A} + \frac{\partial \phi}{\partial t}) = -\vec{j} \quad (*) \\ \nabla^2 \phi + \frac{\partial}{\partial t}(\nabla \cdot \vec{A}) = -\rho \quad (**) \end{array} \right.$

2) 引入四维势矢量. $A^\mu = (\phi, \vec{A})$ 或 $A_\mu = (\phi, -\vec{A})$; $j^\mu = (\rho, \vec{j})$ 或 $j_\mu = (\rho, -\vec{j})$ 则

$$\partial_\nu (\partial^\mu A^\nu - \partial^\nu A^\mu) = -j^\mu$$

证明:

$$\partial_\nu (\partial^\mu A^\nu - \partial^\nu A^\mu) = \partial^\mu \partial_\nu A^\nu - \partial_\nu \partial^\nu A^\mu = \partial^\mu (\frac{\partial \phi}{\partial t} + \nabla \cdot \vec{A}) - (\frac{\partial^2}{\partial t^2} - \nabla^2) A^\mu = -j^\mu.$$

当 $\mu=0$ 时, $\frac{\partial}{\partial t} (\frac{\partial \phi}{\partial t} + \nabla \cdot \vec{A}) - (\frac{\partial^2}{\partial t^2} - \nabla^2) \phi = -\rho,$

即 $\nabla^2 \phi + \frac{\partial}{\partial t}(\nabla \cdot \vec{A}) = -\rho \quad (**)$

当 $\mu=1, 2, 3$ 时,

$$-\nabla(\frac{\partial \phi}{\partial t} + \nabla \cdot \vec{A}) - (\frac{\partial^2}{\partial t^2} - \nabla^2) \vec{A} = -\vec{j}$$

即 $\nabla^2 \vec{A} - \frac{\partial^2 \vec{A}}{\partial t^2} - \nabla(\nabla \cdot \vec{A} + \frac{\partial \phi}{\partial t}) = -\vec{j} \quad (*)$

3) 电磁场张量形式的麦方

引入 $F_{\mu\nu} = \partial_\mu A_\nu - \partial_\nu A_\mu$, 则 $\left\{ \begin{array}{l} F^{0i} = \partial^i A^0 - \partial^0 A^i = -\nabla^i \phi - \frac{\partial A^i}{\partial t} = E^i \\ F^{ij} = \partial^i A^j - \partial^j A^i = -\nabla^i A^j - (-\nabla^j A^i) = -\epsilon^{ijk} B^k \end{array} \right.$

$$\partial_\nu F^{\mu\nu} = -j^\mu$$

其中 $F_{i0} = \partial_i A_0 - \partial_0 A_i = \partial_i \phi + \frac{\partial A_i}{\partial t} = -E_i \leftrightarrow F^{i0} = E^i$ $F = \begin{pmatrix} 0 & -E^1 & -E^2 & -E^3 \\ E^1 & 0 & -B^3 & B^2 \\ E^2 & B^3 & 0 & -B^1 \\ E^3 & -B^2 & B^1 & 0 \end{pmatrix}$

$F_{ij} = \partial_i A_j - \partial_j A_i = \epsilon_{ijk} B^k \leftrightarrow F^{ij} = \epsilon^{ijk} B^k$

2. 拉格朗日形式

由拉氏密度满足洛伦兹不变性, 设

$$\mathcal{L} = -\frac{1}{2} [a \partial_\mu A^\nu \partial^\mu A_\nu + b \partial_\mu A^\nu \partial_\nu A^\mu + c (\partial_\mu A^\mu)^2 + d A_\mu A^\mu]$$

系数a, b, c, d为实数, 待定。利用E-L方程与麦氏方程比较可以定出。

E-L方程 $a \partial^\nu \partial_\nu A^\mu + (b+c) \partial^\mu \partial^\nu A_\nu - d A^\mu = 0$ (★)

真空中麦氏: ① $\nabla \cdot \vec{E} = 0, \nabla \times \vec{B} = \frac{\partial \vec{E}}{\partial t}$ 或 $\partial_\mu F^{\mu\nu} = 0$. 其中 $F^{i0} = E^i, F^{ij} = -\epsilon^{ijk} B^k$

② $\nabla \cdot \vec{B} = 0, \nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$ 或 $\partial_\mu \tilde{F}^{\mu\nu} = 0$. 其中 $\tilde{F}^{\mu\nu} = \frac{1}{2} \epsilon^{\mu\nu\rho\sigma} F_{\rho\sigma}$ $\left\{ \begin{aligned} \tilde{F}^{0i} &= B^i \\ \tilde{F}^{ij} &= +\epsilon^{ijk} E^k \end{aligned} \right.$

满足 $F^{\mu\nu} \rightarrow \tilde{F}^{\mu\nu}$ 时有 $\begin{cases} E^i \leftrightarrow B^i \\ B^i \leftrightarrow -E^i \end{cases}$. 且 $\partial_\mu \tilde{F}^{\mu\nu} = 0$ 与 $\partial_\mu F^{\mu\nu} = 0$ 并不独立。

真空中麦氏为 $\partial_\nu F^{\mu\nu} = 0$, 即 $\partial_\nu (\partial^\nu A^\mu - \partial^\mu A^\nu) = 0$ 或

$$\partial_\nu \partial^\nu A^\mu - \partial^\mu \partial_\nu A^\nu = 0 \quad (*)$$

(★)与(*)对比, 可得

$$a=1, \quad b+c=-1, \quad d=0.$$

$$\tilde{F}^{\mu\nu} = \begin{pmatrix} 0 & -B^1 & -B^2 & -B^3 \\ B^1 & 0 & E^3 & -E^2 \\ B^2 & -E^3 & 0 & E^1 \\ B^3 & E^2 & -E^1 & 0 \end{pmatrix}$$

$$\therefore \mathcal{L} = -\frac{1}{2} (\partial_\mu A^\nu \partial^\mu A_\nu - \partial_\mu A^\nu \partial_\nu A^\mu) = -\frac{1}{4} F_{\mu\nu} F^{\mu\nu}$$

拉氏密度中, A^μ 的量纲为1, 质量为0。

二 规范变换下的不变性

电磁理论中, \vec{E}, \vec{B} 被认为是基本的, 而 \vec{A} 认为是辅助场; 由于 $F^{\mu\nu}$ 由 \vec{E}, \vec{B} 构成, 所以是基本的, 而 A^μ 是辅助的。

1. 规范变换

对于给定的 $F^{\mu\nu}(x), A^\mu(x)$ 具有很大的任意性。对 A^μ 做变换 ($\alpha(x)$ 为时空上标量函数)

$$A^\mu(x) \rightarrow A'^\mu(x) = A^\mu(x) + \partial^\mu \alpha(x).$$

$$\begin{aligned} F^{\mu\nu}(x) &\rightarrow F'^{\mu\nu}(x) = \partial^\mu A'^\nu(x) - \partial^\nu A'^\mu(x) = \partial^\mu (A^\nu + \partial^\nu \alpha(x)) - \partial^\nu (A^\mu + \partial^\mu \alpha(x)) \\ &= \partial^\mu A^\nu(x) - \partial^\nu A^\mu(x) = F^{\mu\nu}(x) \quad \text{保持不变, 故 } \mathcal{L}(x) \text{ 也不变。} \end{aligned}$$

由于 $\frac{1}{2} m^2 A_\mu A^\mu$ 不满足上述规范变换下的不变性, 故电磁场质量为0。

2. 库仑规范(辐射规范)

由于规范变换带来的任意性, 对 A^μ 可作不同的选择。不同的选择对应不同的规范。

$$\text{取 } \begin{cases} \nabla \cdot \vec{A} = 0 \\ A^0 = 0 \end{cases}$$

$$\begin{aligned} \text{令 } A^\mu(x) &= A^\mu e^{i\vec{P} \cdot \vec{x}} \\ \vec{A}(x) &= \vec{A} e^{i\vec{P} \cdot \vec{x}} \end{aligned} \quad \text{则 } -i\vec{P} \cdot \vec{A} = 0 \quad \therefore \vec{P} \perp \vec{A}, \quad A^0 = 0.$$

电磁场 A^μ 中只留下垂直于运动方向的两个横分量(左旋右旋), 没有非物理自由度。但库仑规范无洛伦兹协变性。

3. 洛伦兹规范

$$\partial_\mu A^\mu(x) = 0$$

即使最初 A^μ 不满足该条件, 对 A^μ 作规范变换
 $A^\mu \rightarrow A'^\mu = A^\mu - \partial^\mu \alpha$, 只需选择 α 使 $\square \alpha = \partial_\mu A^\mu$, 则
 A'^μ 一定能满足条件 $\partial_\mu A'^\mu(x) = 0$.

在洛伦兹规范下, 表式简化为 $\square A^\mu(x) = 0$ 。由 ~~于此~~ 此时 $A^\mu(x)$ 仍有规范任意性。
 对 A^μ 再作规范变换 $A^\mu \rightarrow A'^\mu = A^\mu + \partial^\mu \alpha$, 为使 A'^μ 满足表式 $\square A'^\mu(x) = 0$,
 只需标量函数满足 $\square \alpha = 0$ 即可, 此时 α 仍然有无限多。

洛伦兹规范 $\partial_\mu A^\mu(x) = 0$ 具有协变性, 但它不能消除所有非物理的自由度

洛伦兹条件可以利用一个拉格朗日乘子 λ 纳入拉氏密度和运动方程来实现。

$$\mathcal{L} = -\frac{1}{4} F_{\mu\nu} F^{\mu\nu} - \frac{\lambda}{2} (\partial_\mu A^\mu)^2$$

一方面, $-\frac{\lambda}{2} (\partial_\mu A^\mu)^2$ 在规范变换 $A^\mu \rightarrow A'^\mu = A^\mu + \partial^\mu \alpha$ 下仍然保持不变, 只要其中
 α 满足 $\square \alpha = 0$ 即可。

另一方面, 相应 E-L 方程为

$$\square A^\mu + (\lambda - 1) \partial^\mu (\partial_\nu A^\nu) = 0$$

可以证明, 这个方程若在 $t=0$ 时满足洛伦兹条件 $\partial_\mu A^\mu = 0$ 且 $\frac{\partial}{\partial t} \partial_\mu A^\mu = 0$, 则 t 时刻也有 $\partial_\mu A^\mu = 0$
 即运动方程也满足洛伦兹条件。

[证明: 对 E-L 方程取四散度, $\square \partial_\mu A^\mu + (\lambda - 1) \square (\partial \cdot A) = \lambda \square (\partial \cdot A) = 0$,

$$\text{即 } \square \partial_\mu A^\mu = 0 \quad (\lambda \neq 0)$$

若 $t=0$ 时, $\chi \equiv \partial_\mu A^\mu = 0$, $\frac{\partial}{\partial t} \chi = 0$, 则 t 时刻时, 将 χ 对 t 作展开

$$\chi = \chi|_{t=0} + \frac{\partial \chi}{\partial t} \Big|_{t=0} t + \frac{1}{2} \frac{\partial^2 \chi}{\partial t^2} \Big|_{t=0} t^2 + \dots$$

由初始条件, 第一、二项为 0, 由 $\square \partial_\mu A^\mu \equiv \square \chi = 0$, 得 $\chi \sim e^{i(\mathbf{k} \cdot \mathbf{r} - \omega t)}$, 是平面波之叠加,
 其中 \mathbf{r} 和 t 的依赖部分相互独立, 从而

$$\frac{\partial^2}{\partial t^2} \chi|_{t=0} = \nabla^2 \chi|_{t=0} = \nabla^2 (\chi|_{t=0}) = 0$$

$$\frac{\partial^3}{\partial t^3} \chi|_{t=0} = \nabla^2 \frac{\partial \chi}{\partial t} \Big|_{t=0} = \nabla^2 \left(\frac{\partial \chi}{\partial t} \Big|_{t=0} \right) = 0$$

故 χ 展开式中所有更高次项均为 0。

综上, 若 $t=0$ 时, $\chi \equiv \partial_\mu A^\mu = 0$, 则 t 时刻洛伦兹条件 $\chi \equiv \partial_\mu A^\mu = 0$ 也满足。

三. 守恒流. 守恒荷.

$$j^{\mu\alpha} = - \left[\mathcal{L} g^{\mu\lambda} - \frac{\partial \mathcal{L}}{\partial (\partial_\mu A_\rho)} \partial^\lambda A_\rho \right] \frac{\delta x_\lambda}{\delta \theta_\alpha} - \frac{\partial \mathcal{L}}{\partial (\partial_\mu A_\lambda)} \frac{\delta A_\lambda}{\delta \theta_\alpha}$$

$$\mathcal{L} = -\frac{1}{4} F_{\rho\sigma} F^{\rho\sigma} - \frac{\lambda}{2} (\partial_\rho A^\rho)^2 = -\frac{1}{4} (\partial_\rho A_\sigma - \partial_\sigma A_\rho) (\partial^\rho A^\sigma - \partial^\sigma A^\rho) - \frac{\lambda}{2} (\partial_\rho A^\rho) (\partial_\sigma A^\sigma)$$

$$\frac{\partial \mathcal{L}}{\partial (\partial_\mu A_\nu)} = \frac{\partial}{\partial (\partial_\mu A_\nu)} \left\{ -\frac{1}{4} (\partial_\rho A_\sigma - \partial_\sigma A_\rho) (\partial^\rho A^\sigma - \partial^\sigma A^\rho) - \frac{\lambda}{2} (\partial_\rho A^\rho) (\partial_\sigma A^\sigma) \right\}$$

$$= \frac{-1}{4} \{ (\delta_\rho^\mu \delta_\sigma^\nu - \delta_\sigma^\mu \delta_\rho^\nu) (\partial^\rho A^\sigma - \partial^\sigma A^\rho) + (\partial_\rho A_\sigma - \partial_\sigma A_\rho) (\delta^{\mu\rho} \delta^{\nu\sigma} - \delta^{\mu\sigma} \delta^{\nu\rho}) \}$$

$$- \frac{\lambda}{2} \{ \delta_\rho^\mu \delta_\sigma^\nu \partial_\sigma A^\rho + \partial_\rho A^\rho \delta_\sigma^\mu \delta^\nu{}^\sigma \}$$

$$= -\frac{1}{4} \{ [\partial^\mu A^\nu - \partial^\nu A^\mu - \partial^\mu A^\nu + \partial^\mu A^\nu] + [\partial^\mu A^\nu - \partial^\nu A^\mu - \partial^\mu A^\nu + \partial^\mu A^\nu] \} - \frac{\lambda}{2} \{ \delta^{\mu\nu} \partial_\sigma A^\sigma \}$$

$$= -(\partial^\mu A^\nu - \partial^\nu A^\mu) - \lambda g^{\mu\nu} \partial_\sigma A^\sigma = -F^{\mu\nu} - \lambda g^{\mu\nu} \partial_\rho A^\rho.$$

$$\therefore j^{\mu\nu} = - \left[\mathcal{L} g^{\mu\lambda} + (F^{\mu\rho} + \lambda g^{\mu\rho} \partial \cdot A) \partial^\lambda A_\rho \right] \frac{\delta x_\lambda}{\delta \theta_\nu} + (F^{\mu\lambda} + \lambda g^{\mu\lambda} \partial \cdot A) \frac{\delta A_\lambda}{\delta \theta_\nu}$$

1. 平移无穷小变换 ($\delta A_\lambda = 0$)

$$\begin{cases} x_\mu \rightarrow x'_\mu = x_\mu + \epsilon_\mu \\ \delta \theta_\nu = \epsilon_\nu \end{cases} \rightarrow \frac{\delta x_\mu}{\delta \theta_\nu} = g_\mu^\sigma \frac{\epsilon_\sigma}{\epsilon_\nu} = g_\mu^\sigma \delta_\sigma^\nu = g_\mu^\nu$$

$$T^{\mu\nu} = - \left[-\frac{1}{4} F_{\rho\sigma} F^{\rho\sigma} - \frac{\lambda}{2} (\partial \cdot A)^2 \right] g^{\mu\nu} - (F^{\mu\rho} + \lambda g^{\mu\rho} \partial \cdot A) \partial^\lambda A_\rho g_\lambda^\nu$$

$$\therefore \text{守恒流} \quad T^{\mu\nu} = \left[\frac{1}{4} F^2 + \frac{\lambda}{2} (\partial \cdot A)^2 \right] g^{\mu\nu} - [F^{\mu\rho} + \lambda g^{\mu\rho} (\partial \cdot A)] \partial^\lambda A_\rho \quad \text{能量动量张量密度}$$

$$\text{守恒荷} \quad P^\nu = \int d^3x T^{0\nu}, \quad \text{四动量密度.}$$

由于 $T^{\mu\nu}$ 不满足对 μ, ν 的对称性和规范不变性, 常对它作一个相差全散度的变换,

$$T^{\mu\nu} \rightarrow T^{\mu\nu} + \partial_\rho (F^{\mu\rho} A^\nu), \quad \text{此时满足对 } \mu, \nu \text{ 的对称性和规范不变性, 而不被}$$

2. 无穷小洛伦兹变换.

$$\begin{cases} x_\mu \rightarrow x'_\mu = x_\mu + \epsilon_{\mu\nu} x^\nu \\ \delta \theta_\alpha = \delta \theta_{\nu\rho} = \epsilon_{\nu\rho} \end{cases} \rightarrow \frac{\delta x_\lambda}{\delta \theta_{\mu\rho}} = \frac{1}{2} (g_\lambda^\nu x_\rho^\rho - g_\lambda^\rho x_\mu^\nu), \quad \text{另外} \quad \begin{cases} A_\lambda \rightarrow A'_\lambda = A_\lambda + \epsilon_{\lambda\nu} A^\nu \\ \delta A_\lambda = \epsilon_{\lambda\nu} A^\nu \end{cases}$$

$$j^{\mu\nu\rho} = - \left[-\frac{1}{4} F_{\alpha\beta} F^{\alpha\beta} - \frac{\lambda}{2} (\partial \cdot A)^2 \right] g^{\mu\nu} \cdot \frac{1}{2} (g_\lambda^\nu x_\rho^\rho - g_\lambda^\rho x_\mu^\nu) - (F^{\mu\alpha} + \lambda g^{\mu\alpha} \partial \cdot A) \partial_\alpha A_\lambda \cdot \frac{1}{2} (g_\lambda^\nu x_\rho^\rho - g_\lambda^\rho x_\mu^\nu)$$

$$\text{守恒流} \quad j^{\mu\nu\rho} = x^\nu T^{\mu\rho} - x^\rho T^{\mu\nu} + A^\nu (F^{\mu\rho} + \lambda g^{\mu\rho} \partial \cdot A) - A^\rho (F^{\mu\nu} + \lambda g^{\mu\nu} \partial \cdot A) \quad \text{广义角动量张量密度}$$

$$\text{守恒荷} \quad M^{\nu\rho} = \int d^3x j^{0\nu\rho} \quad \text{广义角动量}$$

对空间各向同性情况, 只考虑空间分量.

守恒荷 $M^{jk} = \int d^3x j^{0jk} = \int d^3x \left[x^j T^{0k} - x^k T^{0j} + A^j (F^{0k} + \lambda g^{0k} \partial \cdot A) - A^k (F^{0j} + \lambda g^{0j} \partial \cdot A) \right]$

其中 $j, k=1, 2, 3$, 进一步, 可引入宇称的角动量.

$$J_i \equiv \frac{1}{2} \epsilon_{ijk} M^{jk} = \int d^3x \frac{1}{2} \epsilon_{ijk} j^{0jk}$$

$$= \int d^3x \frac{1}{2} \epsilon_{ijk} \left[x^j T^{0k} - x^k T^{0j} + A^j (F^{0k} + \lambda g^{0k} \partial \cdot A) - A^k (F^{0j} + \lambda g^{0j} \partial \cdot A) \right]$$

定义 $J_i = L_i + S_i$.

则由 δx_λ 改变引起的轨道角动量

$$L_i = \frac{1}{2} \epsilon_{ijk} \int d^3x (x^j T^{0k} - x^k T^{0j})$$

由 δA_λ 改变引起的电磁场的自旋角动量.

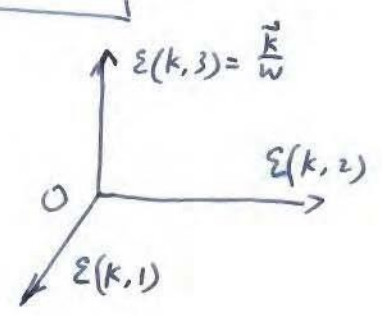
$$S_i = \int d^3x \frac{1}{2} \epsilon_{ijk} \left[A^j (F^{0k} + \lambda g^{0k} \partial \cdot A) - A^k (F^{0j} + \lambda g^{0j} \partial \cdot A) \right]$$

$$= \epsilon_{ijk} \int d^3x \left[A^j (F^{0k} + \lambda g^{0k} \partial \cdot A) \right]$$

四. 电磁场的平面波解.

1. 三维极化矢量电磁波平面波解.

表为 $\square A^\mu = 0 \rightarrow \begin{cases} A_\mu^+(x) = A_\mu(k) e^{-ikx} & \text{正频解.} \\ A_\mu^-(x) = A_\mu(k) e^{ikx} & \text{负频解.} \end{cases}$



设电磁波频率 ω , 波矢 \vec{k} , 则

$$k^\mu = (\omega, \vec{k}), \quad k_\mu = (\omega, -\vec{k}).$$

由表为 $\square A^\mu = 0$ 由洛伦兹条件 $\partial_\mu A^\mu = 0$, 将正、负频解代入, 得.

$$k^2 = 0 \Rightarrow \omega^2 - |\vec{k}|^2 = 0 \Rightarrow \omega = |\vec{k}|, \quad E = \pm \omega, \text{ 能量有正负, 在量子化后可消除.}$$

2. 三维极化矢量

为描述光子的极化状态, 取三维空间三个正交单位矢量(如上图). $E(k, 3)$ 与 \vec{k} 平行,

$E(k, 1), E(k, 2), E(k, 3)$ 成右手螺旋关系, 将它们记为 $E(k, \lambda)$, ($\lambda=1, 2, 3$) 称极化矢量.

正交性 $E(k, \lambda) E(k, \lambda') = \delta_{\lambda\lambda'} \quad (\lambda, \lambda'=1, 2, 3).$

完备性 $\sum_{\lambda=1}^3 E^i(k, \lambda) E^j(k, \lambda) = \delta^{ij} \quad (i, j=1, 2, 3).$

其中 $E(k, \lambda)$ ($\lambda=1, 2$) 为横向极化矢量, $E(k, 3)$ 为纵向极化矢量.

库仑规范下, 完备性 $\sum_{\lambda=1}^3 E^i(k, \lambda) E^j(k, \lambda) = \delta^{ij} - \frac{k^i k^j}{|\vec{k}|^2}$