

Real Time Systems – SS2016

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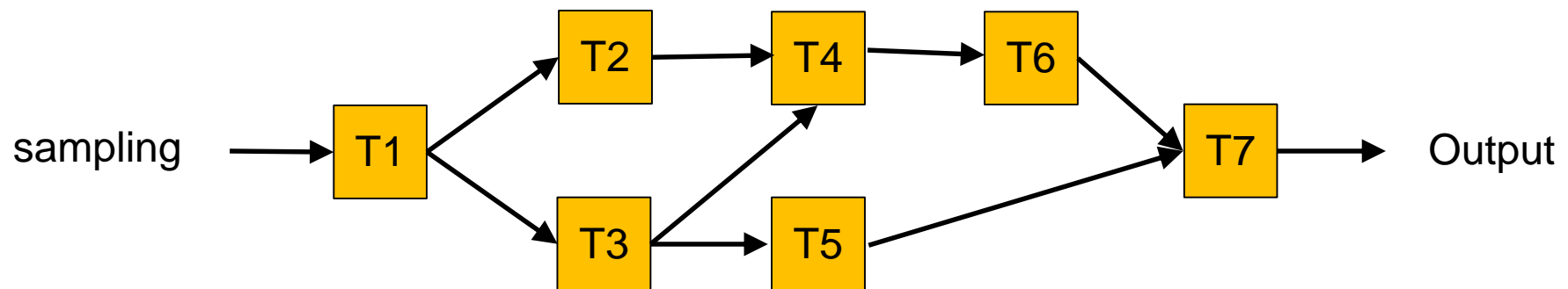
Dependent tasks

The assumption of independent tasks often does not meet reality.

- In practice, tasks are dependent.
We often have conditions or constraints e.g.
 - A must be computed before B
 - B must be computed before C and D
- Such conditions are called **precedence constraints** which can be represented as Directed Acyclic Graphs (DAG) known as **Precedence Graphs**
- Such graphs are also known as „**Task Graph**“

- **Input/output relation**

- Some task is waiting for output of the others: data flow diagrams



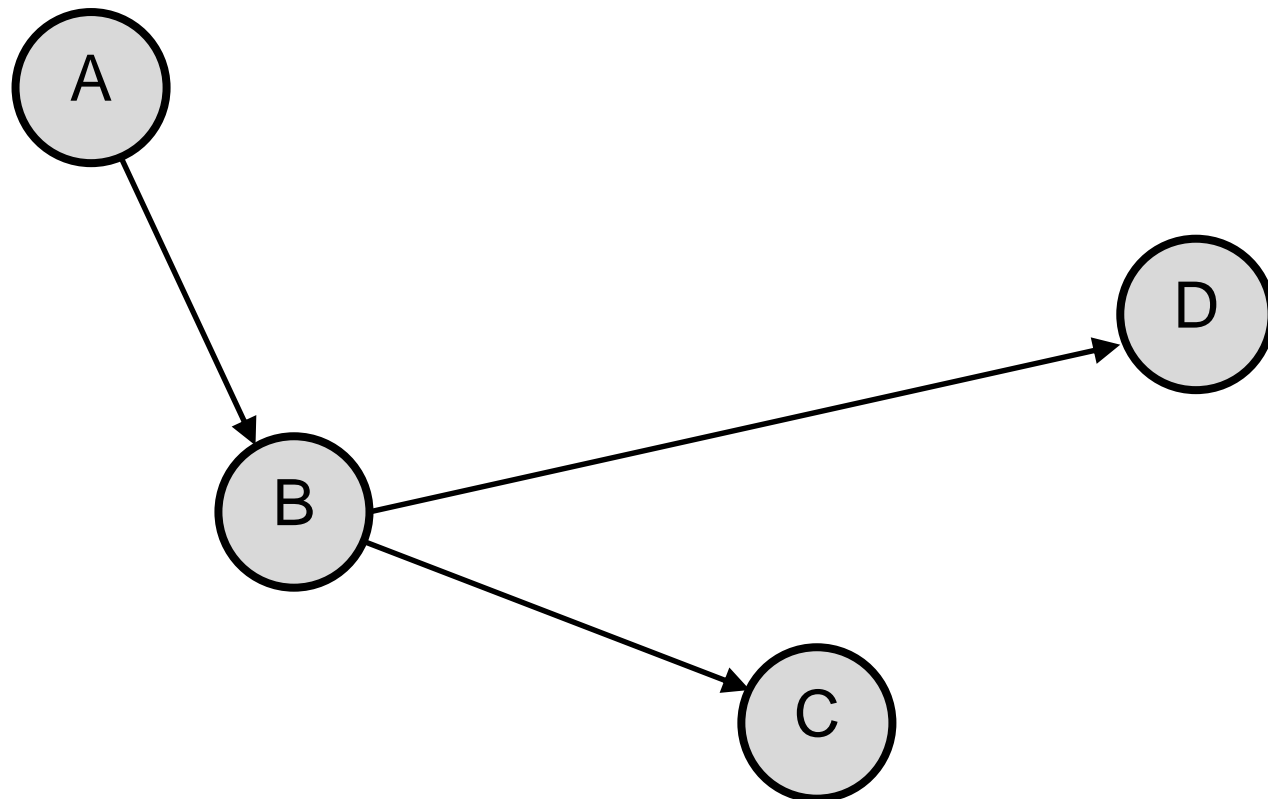
- **Synchronisation**

- Some task must be finished before the others e.g.
It is holding a shared resource

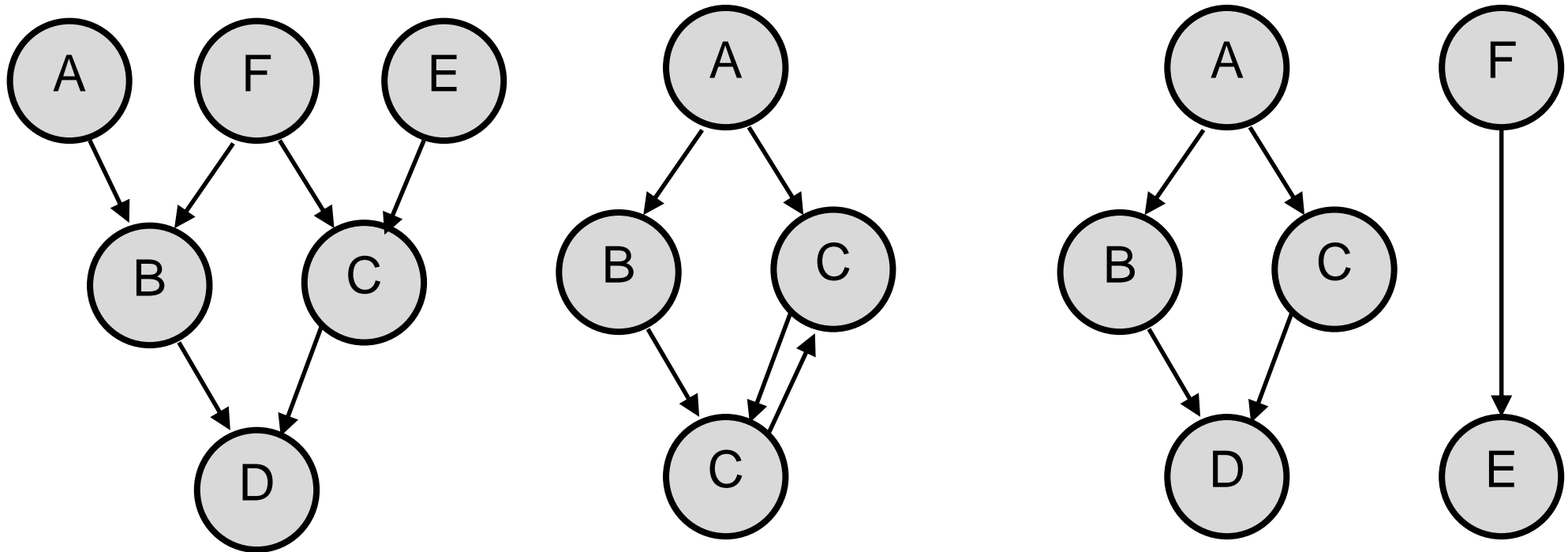
- **Other dependence relations (Resource lock, shared resources, etc.)**

Precedence graph: Example

- A must be computed before B
- B must be computed before C and D



Nodes(Knoten) and edges(Kanten)



Not a precedence graph

Conjunct and dishunct join (not considered)

- AND-node, all incoming edges must be finished first
- OR-node: at least one of the incoming edges must be finished

- Feasible schedules should meet
 - Timing constraints
 - Precedence constraints
- Overlapping area of blue and red is what we need
- Precedence constraints restrict the search area.

