First version: built with cameraBracket\_beta1 and panBracket\_alpha1:

* Excessive clearance in y axis of gimbal but camera assy is also nose heavy. Will shift cameraBracket motor mounting point forward by 5mm and reduce vertical clearance by 10mm
* Camera is mounted slightly crooked in yaw axis, will move vertical holes at front of camera assy away from motor by with 1mm
* Gimbal controller does not seem capable of yaw even though yaw circuitry is there. May need to fool it into thinking that yaw is roll but no solution is planned as of right now – FIXED

jaguarBracketV1 🡪 bracket that connects gimbal to top two spars within Jaguar body. Will have small space between spar links and edges of section to prevent too much stress from being transferred to bracket. LOOK INTO SPRINGS FOR THIS (0.5 inch on either side of bracket)