

```
1 ComponentDefinition SmartJoystickServer {
2   CoordinationSlavePort CoordinationPort implements
  CommBasicObjects.DefaultCoordinationService { }
3   Activity JoystickTask
4   {
5     ActivationConstraints {
6       configurable = false
7       minActFreq = 1.0 Hz
8       maxActFreq = 50.0 Hz
9     }
10  }
11  OutputPort JoystickServcieOut implements
  CommBasicObjects.JoystickService realizedBy JoystickTask {
12    SupportedMiddleware default ACE_SmartSoft
13  }
14  ComponentParameters SmartJoystickServerParameters slave
  CoordinationPort;
15 }
```