```
 1 ComponentDefinition SmartJoystickNavigation {
 2     CoordinationSlavePort CoordinationPort implements
   CommBasicObjects.DefaultCoordinationService {    }
 3     InputPort JoystickServiceIn implements CommBasicObjects.JoystickService
   {   }
 4     Activity JoystickNavTask
 5     {
 6         InputPortLink JoystickServiceIn { oversamplingOk undersamplingOk }
 7         DefaultTrigger InputPortTrigger JoystickServiceIn;
 8     }
 9     OutputPort NavVelServiceOut implements
   CommNavigationObjects.NavigationVelocityService realizedBy JoystickNavTask
   {   }
10     ComponentParameters SmartJoystickNavigationParameters slave
   CoordinationPort;
11 }
```