

```
1 ComponentDefinition SmartINJoystickNavigation {
2   CoordinationSlavePort CoordinationPort implements
  CommBasicObjects.DefaultCoordinationService {
3
4   }
5
6   InputPort JoystickServiceIn implements CommBasicObjects.JoystickService
  {
7   }
8
9   Activity JoystickNavTask
10  {
11    InputPortLink JoystickServiceIn { oversampling0k undersampling0k }
12    DefaultTrigger InputPortTrigger JoystickServiceIn;
13  }
14  OutputPort NavVelServiceOut implements
  CommNavigationObjects.NavigationVelocityService realizedBy JoystickNavTask
  {
15  }
16
17  ComponentParameters SmartINJoystickNavigationParameters slave
  CoordinationPort;
18  Activity ComplianceManager
19  {
20    InputPortLink EnforcementInstruction_Push { oversampling0k
undersampling0k }
21  }
22  InputPort EnforcementInstruction_Push implements
  SmartInstitutionsServiceRepository.SmartIN_EnforcementInstructionPackage_P
  ush {
23  }
24  OutputPort EnforcementReply_Send implements
  SmartInstitutionsServiceRepository.SmartIN_EnforcementReplyPackage_Send
realizedBy ComplianceManager {
25  }
26 }
```