

# Sesha N. Charla

PhD Candidate · Estimation and Control Systems · Purdue University · seshacharla.github.io  
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## Education

*PhD in Mechanical Engineering*

**Purdue University** - West Lafayette, Indiana

*August, 2021 – December, 2025*

Thesis: Model-based Fault Diagnosis using Set Membership Filtering for Nonlinear Systems under Uncertainty.

Research Focus: Estimation Theory, Adaptive Robust Control, Nonlinear Systems, Fault Diagnosis.

*Masters in Aeronautics and Astronautics*

**Purdue University** - West Lafayette, Indiana

*August, 2019 – May, 2021*

Major: Autonomy and Controls, Minor: Machine Learning (Reinforcement Learning and Computational Statistics)

Research: Simplex chains as control barrier functions for control under polytopic uncertainties and constraints.

*Bachelor of Technology in Aerospace Engineering*

**Indian Institute of Space Science and Technology** - Thiruvananthapuram, India

*August, 2012 – May, 2016*

Thesis: Finite Element Dynamic Model using Modified Lagrangian for Launch Vehicle Bending: Trajectory Simulations.

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## Experience Summary

- 3 years of professional experience as Instrumentation and Control Systems Engineer for Satellite Systems. Internships at Virgin Hyperloop and SC Solutions.
  - More than 2 years of industry (Cummins) collaboration during PhD research.
  - 2 years of experience in training students and developing control and estimation algorithms on embedded systems (STM32 (C), NI-MyRio (LabView)).
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## Technical Skills

**Control and Estimation:** Robust, Adaptive, Optimal & Nonlinear Control Design | Convex Optimization | Mathematical Modelling | Estimation & Detection (Kalman and Set-membership filtering) | System Identification | Signal Processing | Motion Planning and Trajectory Generation | Reinforcement Learning (MDPs and Dynamic Programming)

**Programming:** Python | MATLAB & Simulink | C | C++ (CMake, eigen) | LabView

**Embedded Systems:** NI-RIO systems (LabView (FPGA, NI Real-time module), C++) | STM-32 (C, C++)

**OS & Tools:** Linux | Git | Jira | L<sup>A</sup>T<sub>E</sub>X | EPICS Framework (Control System)

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## Work Experience

*Research Engineer - Estimation and Control Systems (Internship)*

**SC Solutions** - Portland, Oregon

*May, 2023 – August, 2023*

- Developed auto-regressive estimation models for computer vision-based fat estimation in meat (USDA-funded project).
- Designed state and parameter estimation algorithms using vision data; implemented OpenCV-based real-time estimation software in C++.

*Motion Control Engineer* (Internship)

**Virgin Hyperloop** - Los Angeles, California

*June, 2022 – August, 2022*

- Designed and demonstrated supervisory control to minimize force mismatch across bogies, improving EM engine efficiency.
- Refined control architecture for EM engine using MATLAB/Simulink, demonstrating linear control limitations.
- Developed a MIMO model for guidance bogie engine assembly and analyzed robust stability and control performance w.r.t suspension parameters.

*Scientist/Engineer 'SC', Test Instrumentation and Controls, Thermal Systems Group* (Full-time role)

**Indian Space Research Organization (ISRO)** - Bengaluru, India

*July, 2016 – July, 2019*

- Led thermal instrumentation and control for 15 satellite systems, including Chandrayaan-2 (orbiter, lander, rover).
- Developed a Python-based SCADA interface, doubling satellite test productivity and enabling simultaneous testing.
- Designed an optimal heater control and design tool with a web-based front-end, preventing burnout and saturation faults.
- Demonstrated the use of the EPICS framework on a test setup as a proof of concept for a unified SCADA system, as part of the proposed technology development program.

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## R&D and Academic Experience

*Diesel Engine Aftertreatment System Diagnostics*

*August, 2023– Ongoing*

- Developed a discrete nonlinear hybrid model for  $NO_x$  process dynamics in SCR-ASC systems; validated with test-cell & truck data.
- Formulated an aging diagnostics framework using set-membership filtering & parameter detection.

*Actuator Fault diagnosis and robust control in Multi-rotors*

*August, 2021– Ongoing*

- Designed an RPM measurement system using back-EMF commutation signals (MECC'22) and developed a nonlinear model considering the ESC dynamics (ACC'24).
- Implemented Adaptive Robust Control for uncertainty rejection & fault-tolerant RPM tracking (MECC'24).
- Created a set-membership filtering & adaptive control-based fault-diagnostics framework.

*Instructor/TA for Control Lab Courses*

*August, 2020 – May, 2023*

- Taught C, Assembly, and LabView programming for closed-loop control of mechanical systems (e.g., inverted pendulum, DC motors, thermal systems).
- **Course Development:** Developed coursework on parameter estimation & robust control for a refrigeration system (ME 586) using STM32 Discovery board.

**Relevant Course Work:** Multivariable Systems and Robust Control | Adaptive Control | Detection & Estimation Theory | System Identification | Computational Statistics (EM algorithm) | Reinforcement Learning (Bandit problems and MDPs) | Nonlinear Systems | Vehicle Dynamics.

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## Honors, Scholarships & Service

- Reviewer for MECC, ACC and IFAC Journal of Mechatronics
  - Graduate Research Assistantship from Cummins. Aging diagnostics of diesel engine after-treatment systems. [**Aug. 2023 - present**]
  - Graduate Research Assistantship from NASA-ULI. Fault-diagnostics in urban air mobility systems. [**Aug. 2020 - 2021**]
  - DOS-ISRO fellowship, Department of Space, India. Scholarship for undergraduate studies. [**Aug. 2012 - May. 2016**]
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