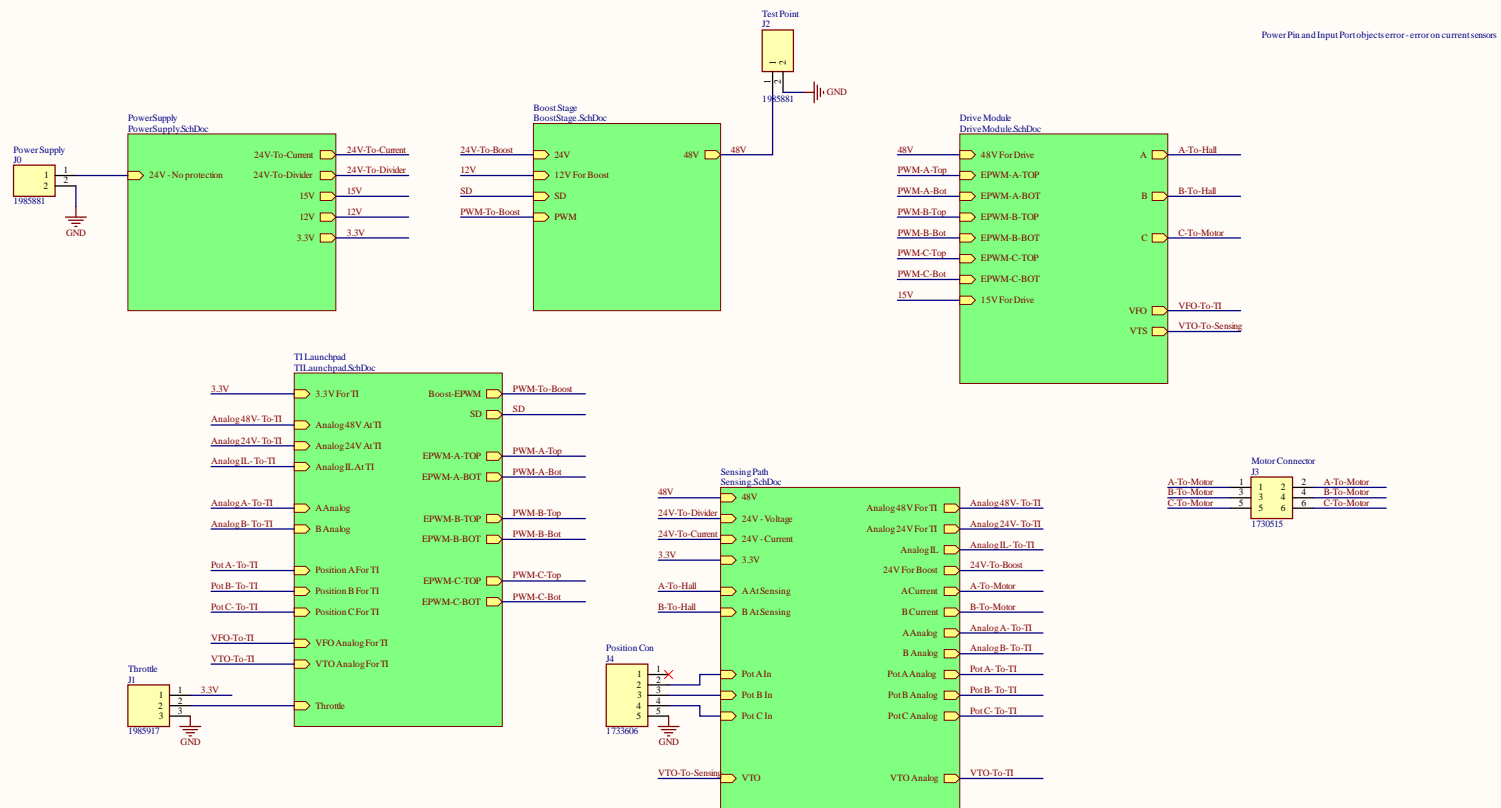
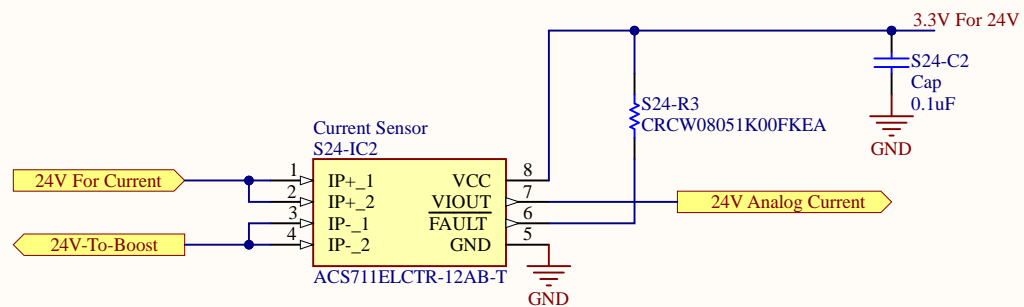
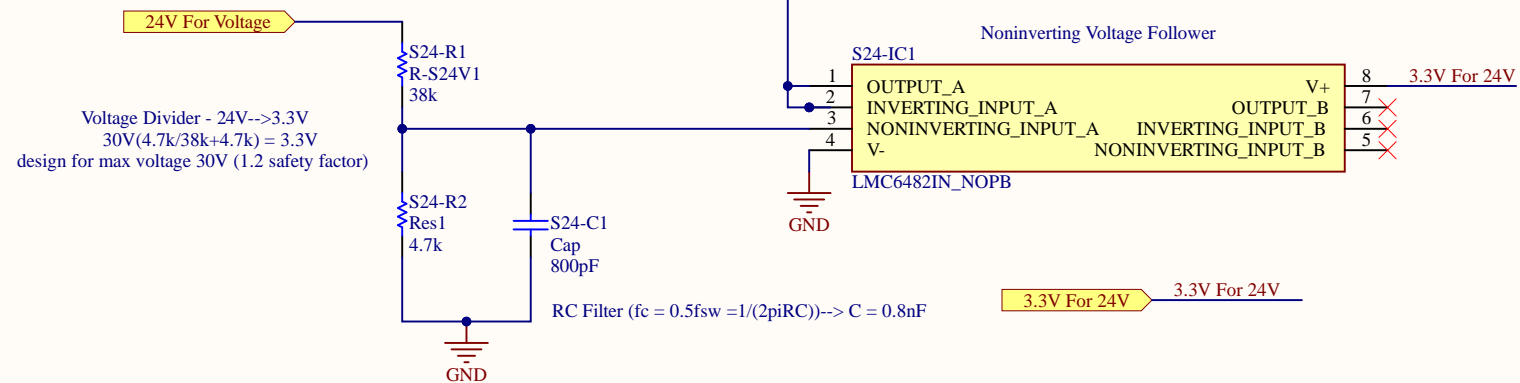


EE 453 Electric Bike PCB
Nolan, Bennett, Seth



Takes current and voltage measurements from circuit after protection and before the boost converter for Boost FeedFwd control

Takes current and voltage measurements from circuit after protection and before the boost converter for Boost FeedFwd control

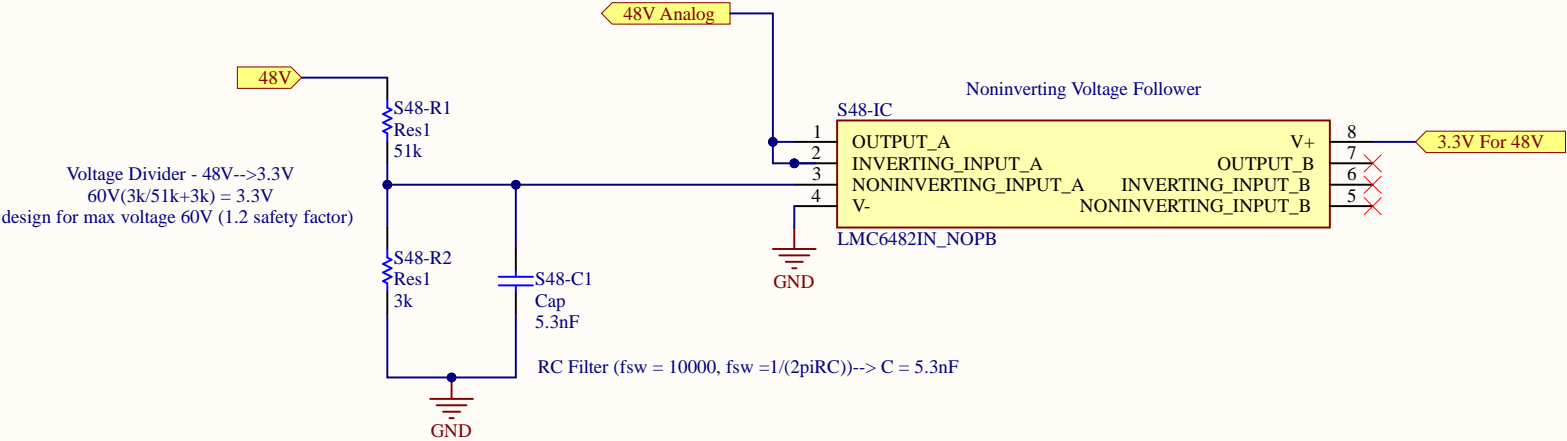


S24-R3 for fault sensing
measuring not implemented
added just in case we decide otherwise

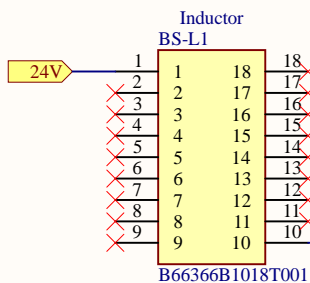
Title		
Size A	Number	Revision
Date:	4/11/2021	Sheet of
File:	C:\Users\...\24V\Sensing.SchDoc	Drawn By:

48V Sensing

Takes voltage measurements from the boost stage after protection before the integrated power module.



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File:	C:\Users\...\48VSensing.SchDoc	Drawn By:



Inductance calcs
 $L = (V_L * D * T_s) / (2 * \Delta i)$
 $L = (24 * 0.5 * 1 * 10^{-4}) / (0.6)$
 $L = 2mH$

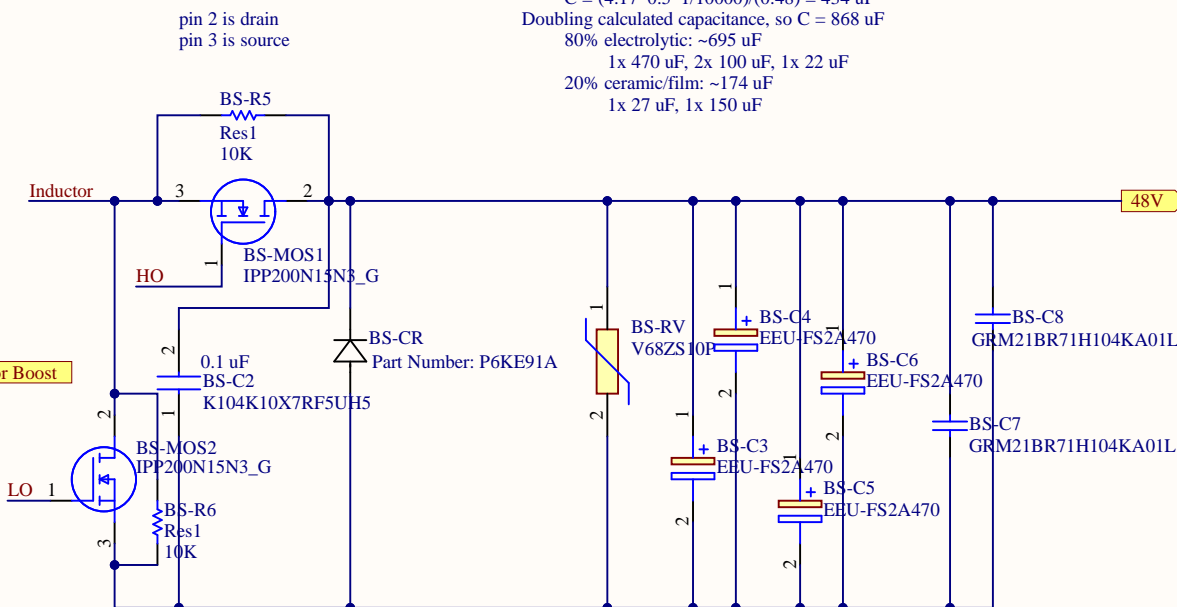
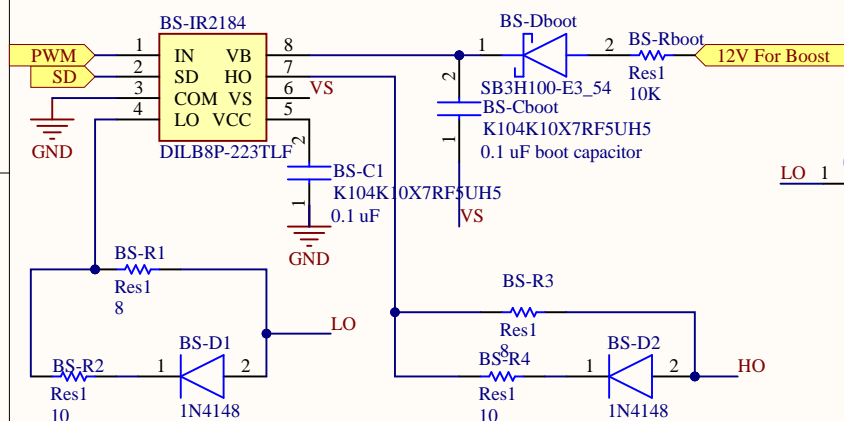
Inductor

Inductor Calcs

Chose a switching freq of 10kHz
 Assume $D=0.5$, $T_s = 1/f_s = 1/10,000kHz$
 $V_L = V_g - (V_{RL} + V_{Ron}) = 24 - (\text{a really small number})$
 $2 * \Delta i = 15/100 * i_L = 15/100 * 4 = 0.6$
 * Note: Assume 15% ripple desired

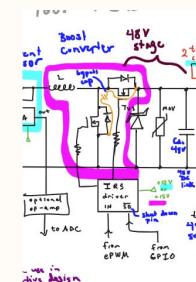
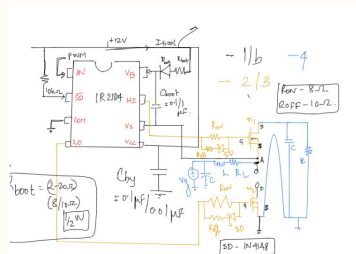
Capacitor Calcs
 assume 1% ripple, $D = 0.5$, double capacitance after calculating
 $C = (i_c * D * T_s) / (2 * \Delta v)$
 $i_c = \text{Power/Voltage} = 200W/48V = 4.17A$
 $2 * \Delta v = 0.01 * 48 = 0.48V$
 $C = (4.17 * 0.5 * 1/10000) / (0.48) = 434 \mu F$
 Doubling calculated capacitance, so $C = 868 \mu F$
 80% electrolytic: $\sim 695 \mu F$
 1x 470 μF , 2x 100 μF , 1x 22 μF
 20% ceramic/film: $\sim 174 \mu F$
 1x 27 μF , 1x 150 μF

Gate Driver

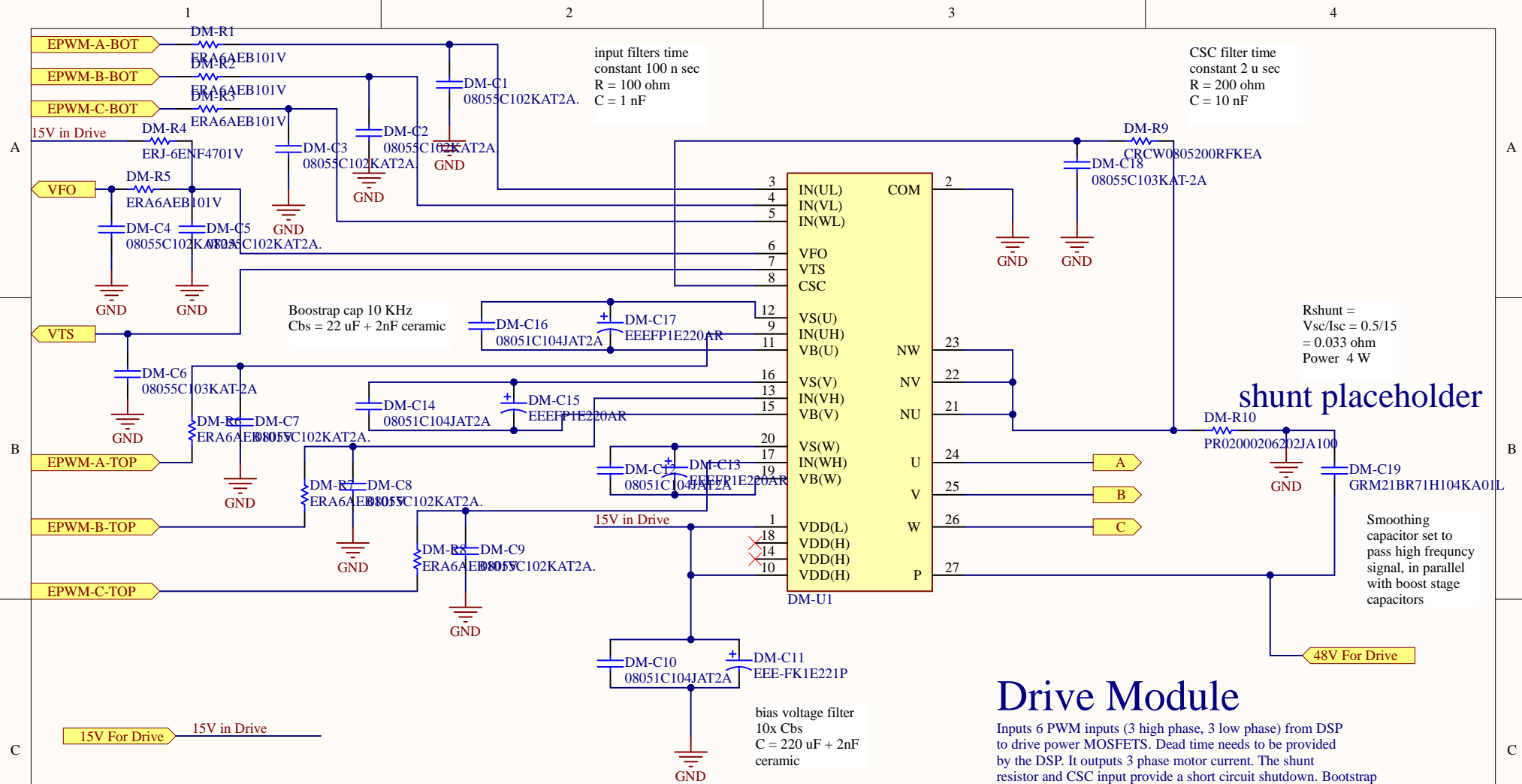


Boost Stage

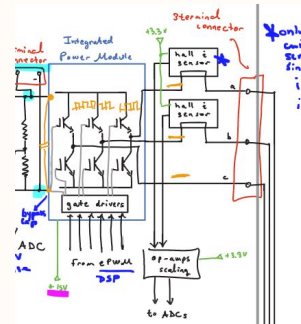
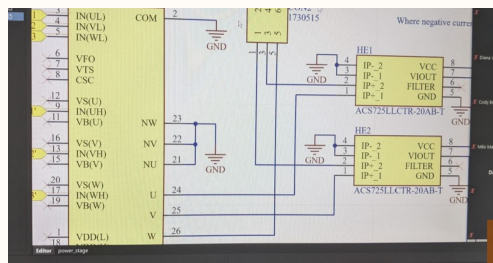
Takes a 24V input and converts the voltage to a 48V output by using the architecture of a boost converter. There is a gate driver to control the MOSFET switching. There is a protection scheme that follows the boost stage, and a DC link of ceramic and electrolytic capacitors are added for smoothing. Operates at a 10 kHz switching freq.



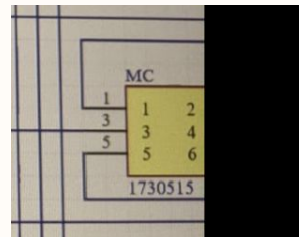
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Date:	4/11/2021	Sheet of
File:	C:\Users\...\BoostStage.SchDoc	Drawn By:



Stolen screenshot for reference



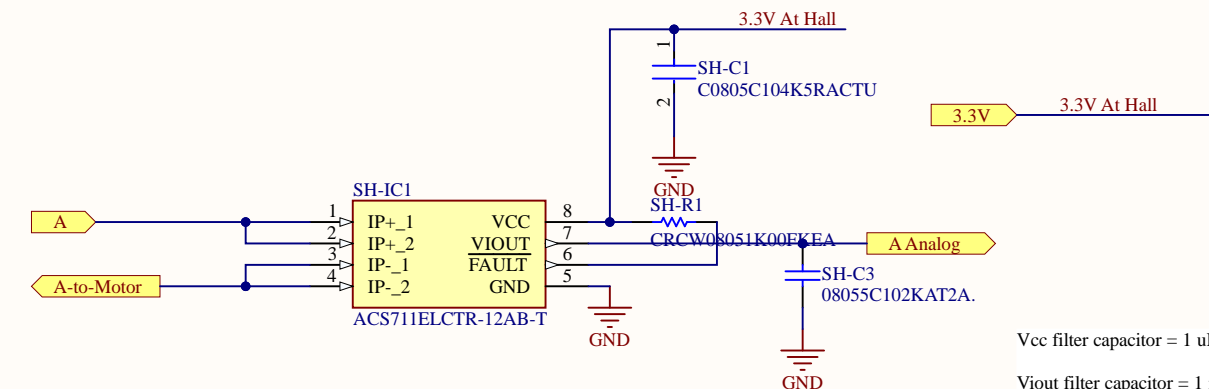
3 terminal connector 1 shorts 2, 5 shorts 6, stolen from pranavs OH



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Hall Sensing

Provides motor current sensing and DSP protection for temperature sensing signals. Takes inline current and temperature signal from Motor drive circuit. Outputs 0-3.3V signal to DSP.

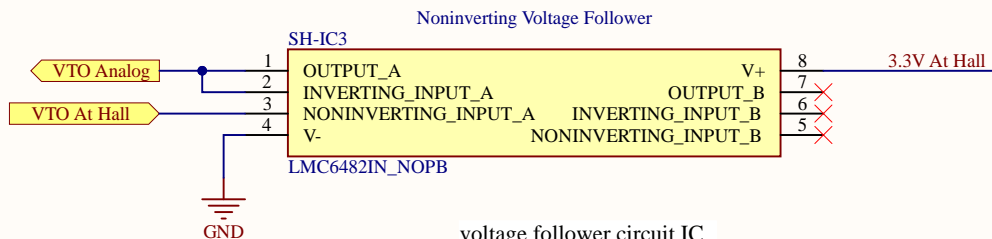
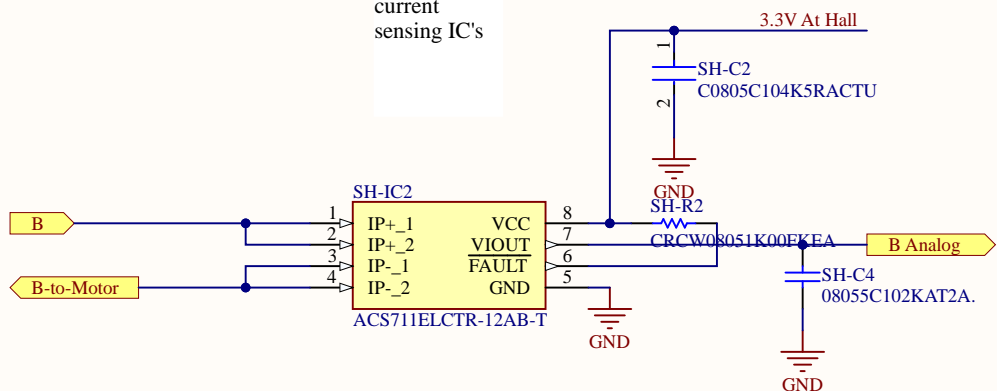


Hall effect
current
sensing IC's

Vcc filter capacitor = 1 uF

Viout filter capacitor = 1 nF

fault signal pull up resistor = 1 kohm

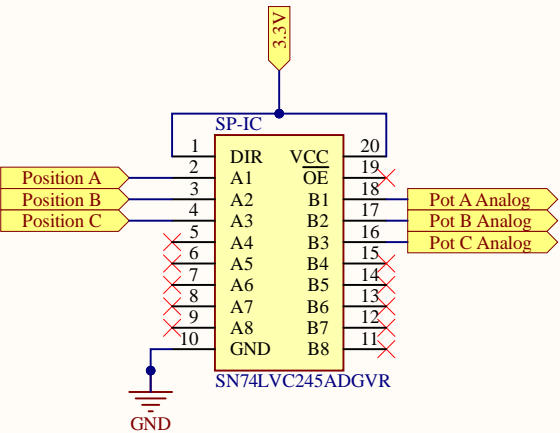


voltage follower circuit IC
to protect DSP from
temperature signal high
voltage

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File:	C:\Users\...\hallsensing.SchDoc	Drawn By:

Position Sensing

Implements a level shifter IC that takes position signals from the motor hal sensors and limits the signals from 5V to 3.3V to be processed by the DSP.

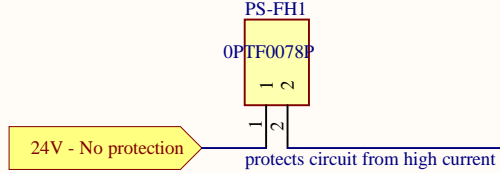


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Size	Number	Revision
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Date:	4/11/2021	Sheet of
File:	C:\Users\...\positionsensing.SchDoc	Drawn By:

Power Supply

Takes power input from battery and provides protection and step down for ICs and motor

24V Series Fuse Holder (FH1)



24V goes to Voltage Divider

24V-To-Divider

24V After Fuse

MOV

PS-D2
EZA-EG2A50AX
Max DC Volts: 30V

TVS

PS-D1
SMBJ28A
Breakdown 31V
Clamping 45V

DC Link

DC Link

$C = Q/V$, $Q = \text{ripple} * T_s / V(\text{dc} * 1\%)$

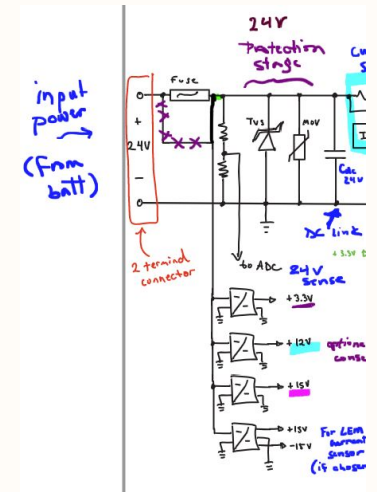
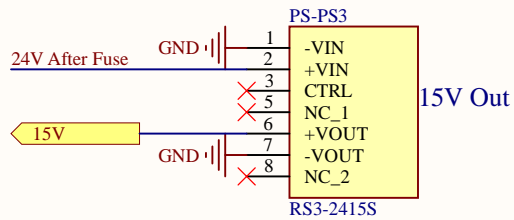
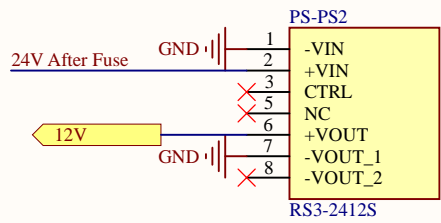
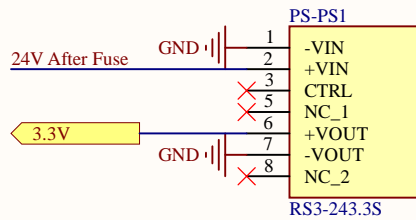
$i = 8.3A$, $T_s = 10\text{kHz}$, ripple = 0.6A(7% max, assume 0.1A normal), $\Delta V = 0.01 * 24$

$C = 40\mu F$, choose $C = 47\mu F$ with 0.6A rating

don't care about harmonics for input so only electrolytic is fine

47uF Electrolytic
PS-C1
EEU-FS2A470

Varistor and Transient voltage suppression to protect against high voltages



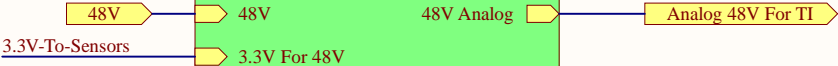
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File:	C:\Users\...\PowerSupply.SchDoc	Drawn By:

Sensing

Landing Page for all sensing ICs
for safe inputs for ADCs and gpio

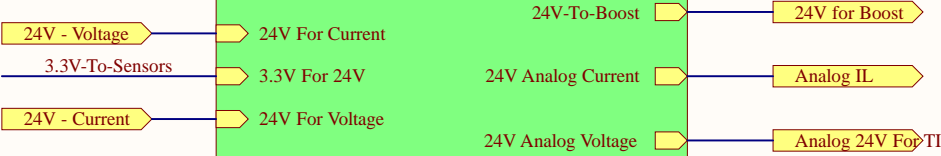
Designator
48VSensing

Nolan



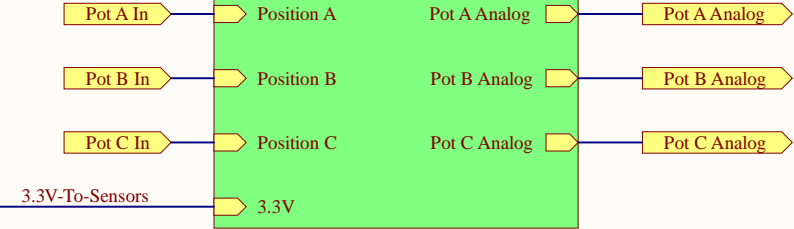
Designator
24VSensing

Seth



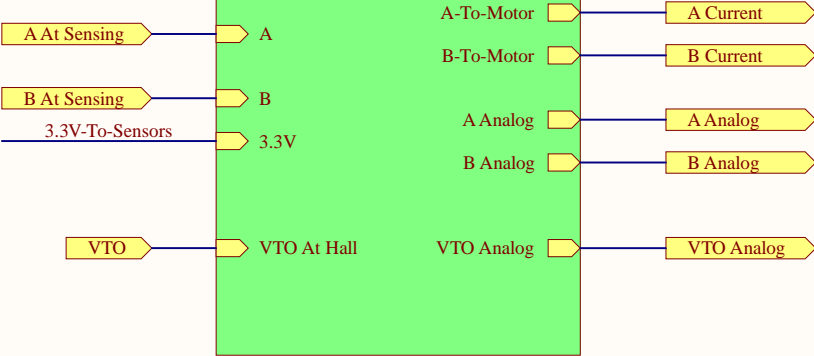
Designator
positionsensing

Nolan



Designator
hallsensing

Bennett



Title		
Size	Number	Revision
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File:	C:\Users\...\Sensing.SchDoc	Drawn By:

TI Launchpad

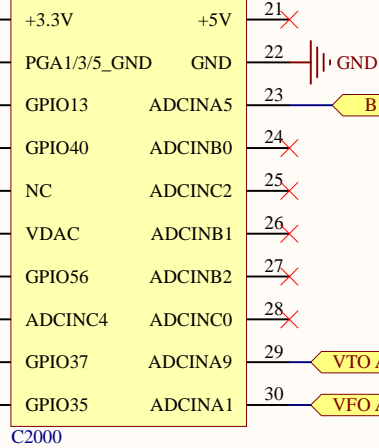
Contains all launchpad connections to the rest of the circuit

3.3V For TI

3.3V At TI

3.3V At TI

TI-U1A



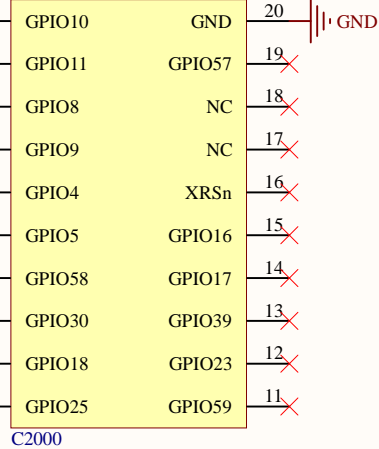
B Analog

VTO Analog For TI

VFO Analog For TI

Position C For TI

TI-U3C

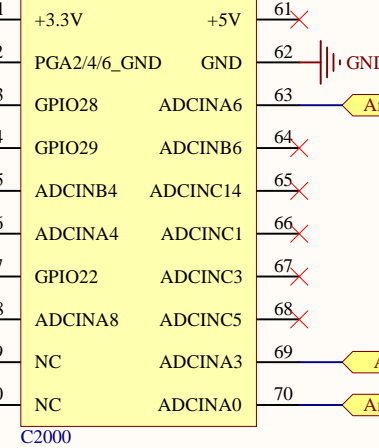


EPWM-B-TOP

EPWM-B-BOT

TI-U2B

3.3V At TI

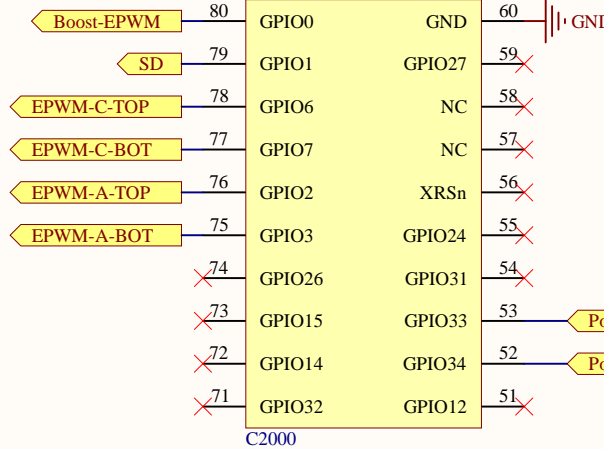


Analog 48V At TI

A Analog

Analog IL At TI

TI-U4D



Boost-EPWM

SD

EPWM-C-TOP

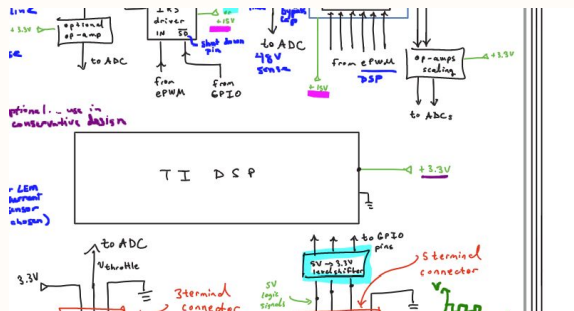
EPWM-C-BOT

EPWM-A-TOP

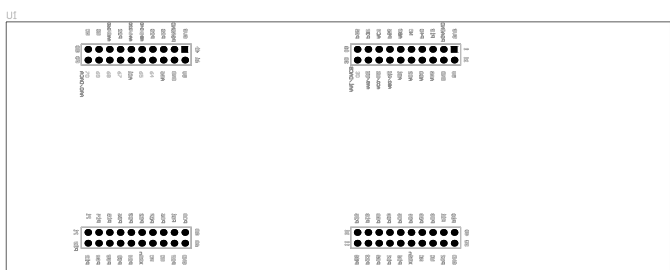
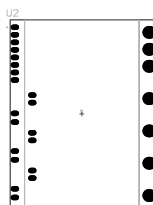
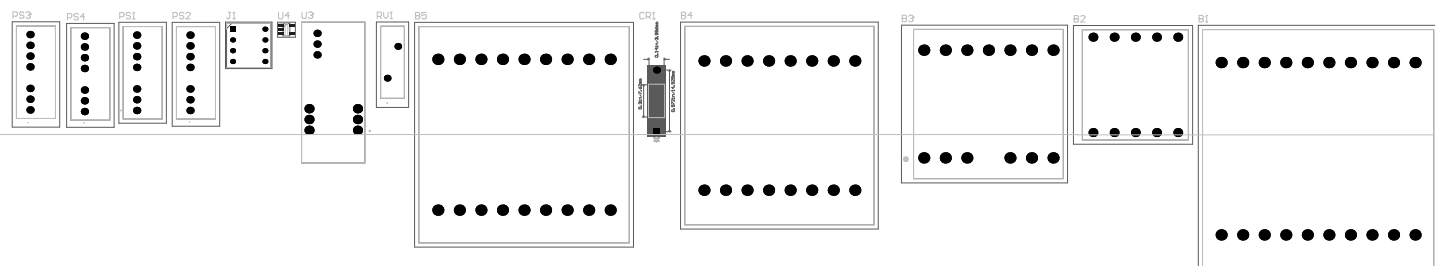
EPWM-A-BOT

Position A For TI

Position B For TI



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File:	C:\Users\...\TILaunchpad.SchDoc	Drawn By:



Board Stack Report