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ECEN 380

1/18/2025

PS02:

1/4

1.64(b), 1.64(h), 1.75(b),  
1.77(b), 1.78(b), 1.95

1.64b

Determine whether

- 1.) memoryless
- 2.) stable
- 3.) causal
- 4.) linear
- 5.) time variant

b.)  $y[n] = 2x[n]u[n]$  \* unit step

Doesn't depend on past or future → Memoryless

Depends only on present → Causal

Output is finite → Stable

$$x[n] = ax_1[n] + bx_2[n]$$

$$y[n] = 2(ax_1[n] + bx_2[n])u[n]$$

$$x_1[n] = ax_1[n] \rightarrow y_1[n] = 2ax_1[n]u[n]$$

$$x_2[n] = bx_2[n] \rightarrow y_2[n] = 2bx_2[n]u[n]$$

$$2ax_1[n]u[n] + 2bx_2[n]u[n]$$

$$2u[n](ax_1[n] + bx_2[n])$$

→ Linear

$$y_2[n] = 2x_1[n-n_0]u[n]$$

$$y_1[n-n_0] = 2x_1[n-n_0]u[n-n_0] \quad y_1[n-n_0] \neq y_2[n]$$

→ Time Variant

1.6.7h

Determine:

2/4

- 1.) Memoryless
- 2.) Stable
- 3.) Causal
- 4.) Linear
- 5.) Time Variant

$$y(t) = \frac{d}{dt} x(t)$$

Relies on past & future

→ NOT Memoryless

$$|x(t)| \leq M < \infty \rightarrow x(t) = \sin(t^2) \rightarrow y(t) = 2t \cos(t^2) \rightarrow \text{UN-stable}$$

Relies on future

→ NOT Causal

$$x(t) = a x_1(t) + b x_2(t)$$

$$\mathcal{H}\{x(t)\} \rightarrow y(t) = \frac{d}{dt}(a x_1(t) + b x_2(t)) \\ = \frac{d}{dt} a x_1(t) + \frac{d}{dt} b x_2(t)$$

$$\mathcal{H}\{a x_1(t)\} \rightarrow y(t) = \frac{d}{dt} a x_1(t)$$

$$\mathcal{H}\{b x_2(t)\} \rightarrow y(t) = \frac{d}{dt} b x_2(t)$$

$$\mathcal{H}\{x(t)\} = \mathcal{H}\{a x_1(t)\} + \mathcal{H}\{b x_2(t)\}$$

→ Linear

$$y_1(t) = \frac{d}{dt} x(t)$$

$$y_1(t-t_0) = \frac{d}{dt} x(t-t_0)$$

$$\mathcal{H}\{x(t-t_0)\} \rightarrow y(t) = \frac{d}{dt} x(t-t_0) \rightarrow \text{Time Invariant}$$



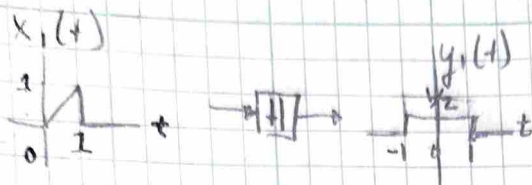
1.75b

3/4

A system  $H$  has input-output pairs given. Determine:

- 1.) Memoryless
- 2.) Causal
- 3.) Linear
- 4.) Time variant

a.)



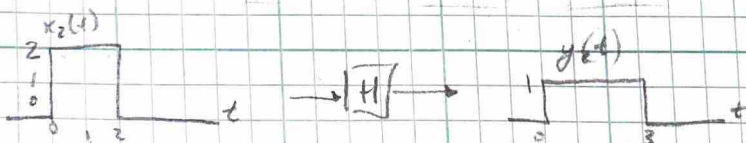
NOT Memoryless: Output ends after input ends

NOT Causal: Output starts before input starts

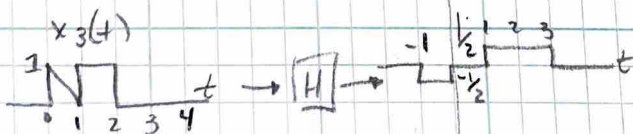
NOT Time Variant: b.) & d.), output b shifted  $\neq$  output d

Could be Linear: No proof that it isn't

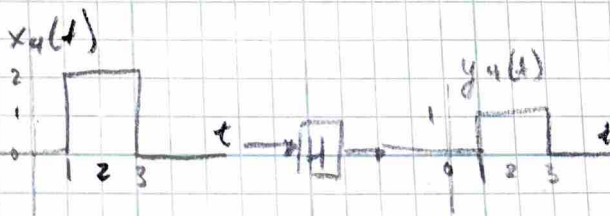
b.)



c.)



d.)



1.77 b

4/4

A discrete-time system is both linear and in-variant.

Input:  $x[n] = \delta[n]$

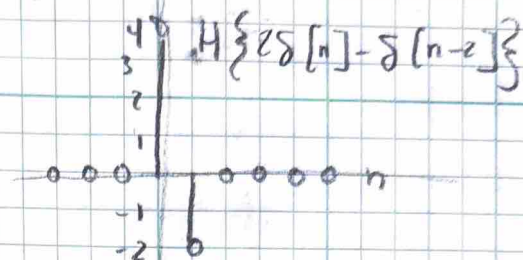
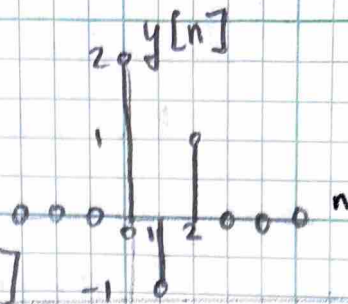
Find output due to input:

$$x[n] = 2\delta[n] - \delta[n-2]$$

$$x[0] = 2(2) - 0 = 4$$

$$x[1] = 2(1) - 0 = 2$$

$$x[2] = 2(1) - 2 = 0$$



1.78 b

$$x(t) = x_e(t) + x_o(t)$$

even and odd components of  $x(t)$ , For all  $t, -\infty < t < \infty$

$$x[n] = x_e[n] + x_o[n]$$

show that:

$$\sum_{n=-\infty}^{\infty} x^2[n] = \sum_{n=-\infty}^{\infty} x_e^2[n] + \sum_{n=-\infty}^{\infty} x_o^2[n]$$

$$(x[n])^2 = (x_e[n] + x_o[n])^2$$

$$x^2[n] = x_e^2[n] + 2x_e[n]x_o[n] + x_o^2[n]$$

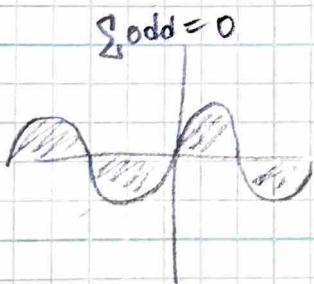
$$y[n] = 2x_e[n]x_o[n]$$

$$y[-n] = 2x_e[-n]x_o[-n]$$

$$= 2x_e[n](-x_o[n])$$

$$= -2x_e[n]x_o[n] = -y[n] \rightarrow \text{odd}$$

\* Sum of odd of y-axis symmetric function  $\rightarrow 0$



$$x^2[n] = x_e^2[n] + x_o^2[n]$$

$$\sum_{n=-\infty}^{\infty} x^2[n] = \sum_{n=-\infty}^{\infty} x_e^2[n] + \sum_{n=-\infty}^{\infty} x_o^2[n]$$



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homework1.m MATLAB\_review.m Homework2.mlx

## Problem 1.95:

Write a set of MATLAB commands for approximating the following continuous-time periodic waveforms:

(a) Square wave of amplitude 5 volts, fundamental frequency 20 Hz, and duty cycle 0.6

(b) Sawtooth wave of amplitude 5 volts and fundamental frequency of 20 Hz

Plot five cycles of each of the waveforms.

```

1 %% Part (a)
2 amplitude = 5; % Volts
3 fund_freq = 20; % Hz
4 duty_cycle = 0.6; % Duty cycle
5 t = 0:0.001:5 * 1/fund_freq + 1; % Time
6 squarewave = amplitude * square(2 * pi * fund_freq * t, duty_cycle * 100);
7 plot(t, squarewave);
8 axis([0 0.26 -6 6])
9 title('Problem 1.95a: Seth Ricks');
10 xlabel('Time (seconds)');
11 ylabel('Amplitude (V)');
12 grid on
13
14 %% Part (b)
15 amplitude = 5; % Volts
16 fund_freq = 20; % Hz
17 t = 0:0.001:5 * 1/fund_freq + 1; % Time
18 Sawtooth = amplitude * sawtooth(2 * pi * fund_freq * t);
19 plot(t, Sawtooth);
20 axis([0 0.26 -6 6])
21 title('Problem 1.95b: Seth Ricks');
22 xlabel('Time (seconds)');
23 ylabel('Amplitude (V)');
24 grid on

```

