

Dimensionality Reduction: t-SNE

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Hinton and Roweis (2002)

- Stochastic Neighbor Embedding (SNE)
 - √ It is more important to get local distances right than non-local ones
 - √ SNE has a probabilistic way of deciding if a pairwise distance is local
 - ✓ Convert each high-dimensional similarity into the probability that one data point will
 pick the other data point as its neighbor
 - Probability of picking j given in high D
 - Probability of picking j given in low D

$$p_{j|i} = \frac{e^{-\frac{||\mathbf{x}_i - \mathbf{x}_j||^2}{2\sigma_i^2}}}{\sum_{k \neq i} e^{-\frac{||\mathbf{x}_i - \mathbf{x}_k||^2}{2\sigma_i^2}}}$$

$$q_{j|i} = \frac{e^{-||\mathbf{y}_i - \mathbf{y}_j||^2}}{\sum_{k \neq i} e^{-||\mathbf{y}_i - \mathbf{y}_k||^2}}$$





- Picking the Radius of the Gaussian in p
 - √ We need to use different radii in different parts of the space so that we keep the
 effective number of neighbors about constant
 - ✓ A big radius leads to a high entropy for the distribution over neighbors of i, whereas a
 small radius leads to a low entropy
 - ✓ Decide what entropy you want and then find the radius that produces that entropy

$$Perplexity(P_i) = 2^{H(P_i)}$$

$$H(P_i) = \sum_{j} p_{j|i} log_2 p_{j|i}$$

$$p_{j|i} = \frac{e^{-\frac{||\mathbf{x}_i - \mathbf{x}_j||^2}{2\sigma_i^2}}}{\sum_{k \neq i} e^{-\frac{||\mathbf{x}_i - \mathbf{x}_k||^2}{2\sigma_i^2}}}$$

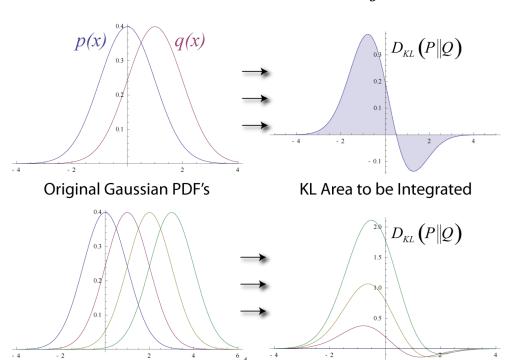
✓ The performance of SNE is fairly robust to changes in the perplexity (5~50)





- Cost Function for a Low-dimensional Representation
 - √ Kullback-Leibler divergence
 - A non-symmetric measure of the difference between two probability distribution P and Q

$$Cost = \sum_{i} KL(\underline{P_i}||Q_i) = \sum_{i} \sum_{j} \underline{p_{j|i}} log \frac{\underline{p_{j|i}}}{q_{j|i}}$$







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- √ Gradient
 - Differencing Cost is tedious because \mathbf{y}_k affect \mathbf{q}_{ij} via the normalized term in Eq. (3), but the result is simple Hinton and Roweis (2002)
 - The gradient has a surprisingly simple form Maaten and Hinton (2008)

$$\frac{\partial C}{\partial \mathbf{y}_i} = 2\sum_{j} (\mathbf{y}_j - \mathbf{y}_i)(p_{j|i} - q_{j|i} + p_{i|j} - q_{i|j})$$





- Cost Function for a Low-dimensional Representation
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$$Cost = \sum_{i} KL(P_i||Q_i) = \sum_{i} \sum_{j} p_{j|i} log \frac{p_{j|i}}{q_{j|i}}$$





지금부터 내가 자세히 설명한다.





Gradient of the cost function

$$C = \sum_{i} KL(\underline{P_i}||\underline{Q_i}) = \sum_{i} \sum_{j} \underline{p_{j|i}} log \frac{\underline{p_{j|i}}}{q_{j|i}}$$

$$C = \sum_{i} \sum_{j} p_{j|i} log p_{j|i} - \sum_{i} \sum_{j} p_{j|i} log q_{j|i}$$

$$C' = -\sum_{i} \sum_{j} p_{j|i} log q_{j|i} \qquad \left(\frac{\partial C}{\partial y_t} = \frac{\partial C'}{\partial y_t}\right)$$

$$C' = -\sum_{i} p_{t|i} log q_{t|i} - \sum_{j} p_{j|t} log q_{j|t} - \sum_{i \neq t} \sum_{j \neq t} p_{i|j} log q_{i|j}$$











Gradient of the cost function

$$d_{ti} = exp(-||\mathbf{y}_t - \mathbf{y}_i||^2) = d_{it}$$

$$\frac{\partial d_{ti}}{\partial \mathbf{v_t}} = d'_{ti} = -2(\mathbf{y_t} - \mathbf{y_i})exp(-||\mathbf{y_t} - \mathbf{y_i}||^2) = -2(\mathbf{y_t} - \mathbf{y_i})d_{ti}$$

$$q_{t|i} = \frac{exp(-||\mathbf{y}_i - \mathbf{y}_t||^2)}{\sum_{k \neq i} exp(-||\mathbf{y}_i - \mathbf{y}_k||^2)} = \frac{d_{it}}{\sum_{k \neq i} d_{ik}}$$

$$q_{j|t} = \frac{exp(-||\mathbf{y}_t - \mathbf{y}_j||^2)}{\sum_{k \neq t} exp(-||\mathbf{y}_t - \mathbf{y}_k||^2)} = \frac{d_{tj}}{\sum_{k \neq t} d_{tk}}$$

$$q_{i|j} = \frac{exp(-||\mathbf{y}_j - \mathbf{y}_i||^2)}{\sum_{k \neq j} exp(-||\mathbf{y}_j - \mathbf{y}_k||^2)} = \frac{d_{ji}}{\sum_{k \neq j} d_{jk}}$$





• Gradient of the cost function (1)

$$\frac{\partial}{\partial y_t} \left(-\sum_{i} p_{t|i} log q_{t|i} \right) = -\sum_{i} p_{t|i} \cdot \frac{1}{q_{t|i}} \cdot \frac{\partial q_{t|i}}{\partial y_t}$$

$$= -\sum_{i} p_{t|i} \cdot \frac{1}{q_{t|i}} \cdot \frac{d'_{it} \cdot (\sum_{k \neq i} d_{ik}) - d_{it} \cdot d'_{it}}{(\sum_{k \neq i} d_{ik})^{2}}$$

$$= -\sum_{i} p_{t|i} \cdot \frac{1}{q_{t|i}} \cdot \frac{-2(\mathbf{y}_t - \mathbf{y}_i) \cdot d_{it} \cdot (\sum_{k \neq i} d_{ik}) + 2(\mathbf{y}_t - \mathbf{y}_i) \cdot d_{it}^2}{(\sum_{k \neq i} d_{ik})^2}$$

$$= -\sum_{i} \frac{p_{t|i}}{q_{t|i}} \cdot \frac{1}{q_{t|i}} \cdot \left(-2(\mathbf{y}_t - \mathbf{y}_i) \cdot q_{t|i} + 2(\mathbf{y}_t - \mathbf{y}_i) \cdot q_{t|i}^2\right)$$

$$= \sum p_{t|i} \cdot 2(\mathbf{y}_t - \mathbf{y}_i)(1 - q_{t|i})$$





• Gradient of the cost function (2)

$$\frac{\partial}{\partial y_t} \left(-\sum_{j} p_{j|t} log q_{j|t} \right) = -\sum_{j} p_{j|t} \cdot \frac{1}{q_{j|t}} \cdot \frac{\partial q_{j|t}}{\partial y_t}$$

$$= -\sum_{j} p_{j|t} \cdot \frac{1}{q_{j|t}} \cdot \frac{d'_{tj} \cdot (\sum_{k \neq t} d_{tk}) - d_{tj} \cdot (\sum_{k \neq t} d'_{tk})}{(\sum_{k \neq t} d_{tk})^2}$$

$$= -\sum_{j} p_{j|t} \cdot \frac{1}{q_{j|t}} \cdot \frac{-2(\mathbf{y}_t - \mathbf{y}_j) \cdot d_{tj} \cdot (\sum_{k \neq t} d_{tk}) - d_{tj} \cdot (\sum_{k \neq t} d'_{tk})}{(\sum_{k \neq t} d_{tk})^2}$$

$$= 2\sum_{j} p_{j|t} \cdot (\mathbf{y}_{t} - \mathbf{y}_{j}) + \sum_{j} p_{j|t} \cdot \frac{\sum_{k \neq t} d'_{tk}}{\sum_{k \neq t} d_{tk}} \qquad (d'_{tt} = 0, \sum_{j} p_{j|t} = 1)$$

$$=2\sum_{\substack{j \text{ TICKERSITY}}} p_{j|t} \cdot (\mathbf{y_t} - \mathbf{y_j}) + \sum_{j} \cdot \frac{d'_{tj}}{\sum_{k \neq t} d_{tk}}$$



• Gradient of the cost function (2)

$$=2\sum_{j} p_{j|t} \cdot (\mathbf{y}_{t} - \mathbf{y}_{j}) + \sum_{j} \cdot \frac{d'_{tj}}{\sum_{k \neq t} d_{tk}}$$

$$=2\sum_{j} p_{j|t} \cdot (\mathbf{y_t} - \mathbf{y_j}) - 2\sum_{j} (\mathbf{y_t} - \mathbf{y_j}) \cdot \frac{d_{tj}}{\sum_{k \neq t} d_{tk}}$$

$$=2\sum_{j} p_{j|t} \cdot (\mathbf{y}_{t} - \mathbf{y}_{j}) - 2\sum_{j} (\mathbf{y}_{t} - \mathbf{y}_{j}) \cdot q_{j|t}$$

$$=2\sum_{j}(\mathbf{y}_{t}-\mathbf{y}_{j})(p_{j|t}-q_{j|t})$$





• Gradient of the cost function (3)

$$\frac{\partial}{\partial y_t} \left(-\sum_{i \neq t} \sum_{j \neq t} \frac{p_{i|j}}{p_{i|j}} log \mathbf{q_{i|j}} \right) = -\sum_{i \neq t} \sum_{j \neq t} \frac{p_{i|j}}{p_{i|j}} \cdot \frac{1}{\mathbf{q_{i|j}}} \cdot \frac{\partial \mathbf{q_{i|j}}}{\partial y_t}$$

$$= -\sum_{i \neq t} \sum_{j \neq t} \mathbf{p}_{i|j} \cdot \frac{1}{\mathbf{q}_{i|j}} \cdot \frac{d'_{ji} \cdot \sum_{k \neq j} d_{jk} - d_{ji} \cdot d'_{jt}}{(\sum_{k \neq j} d_{jk})^2}$$

$$= -\sum_{i \neq t} \sum_{j \neq t} p_{i|j} \cdot \frac{1}{q_{i|j}} \cdot \frac{2(\mathbf{y_t} - \mathbf{y_j}) \cdot d_{ji} \cdot d_{jt}}{(\sum_{k \neq j} d_{jk})^2}$$

$$= -\sum_{i \neq t} \sum_{j \neq t} \frac{p_{i|j}}{q_{i|j}} \cdot \frac{1}{q_{i|j}} \cdot 2(\mathbf{y}_t - \mathbf{y}_j) \cdot q_{i|j} \cdot q_{t|j}$$

$$= -\sum_{i \neq t} \sum_{j \neq t} 2(\mathbf{y}_t - \mathbf{y}_j) \cdot p_{i|j} \cdot q_{t|j}$$





 $(d'_{ii} = 0)$

• Gradient of the cost function (1) + (3)

$$\sum_{i} p_{t|i} \cdot 2(\mathbf{y}_t - \mathbf{y}_i)(1 - q_{t|i}) - \sum_{i \neq t} \sum_{j \neq t} 2(\mathbf{y}_t - \mathbf{y}_j) \cdot p_{i|j} \cdot q_{t|j}$$

Replace the subscript i with j

$$=2\sum_{j}(\mathbf{y}_{t}-\mathbf{y}_{j})\cdot p_{t|j}-2\sum_{j}(\mathbf{y}_{t}-\mathbf{y}_{j})\cdot p_{t|j}\cdot q_{t|j}-2\sum_{i\neq t}\sum_{j\neq t}(\mathbf{y}_{t}-\mathbf{y}_{j})\cdot p_{i|j}\cdot q_{t|j}$$

$$=2\sum_{j}(\mathbf{y}_{t}-\mathbf{y}_{j})\cdot p_{t|j}-2\sum_{i}\sum_{j}(\mathbf{y}_{t}-\mathbf{y}_{j})\cdot p_{i|j}\cdot q_{t|j}$$

$$=2\sum_{j}(\mathbf{y}_{t}-\mathbf{y}_{j})\cdot p_{t|j}-2\sum_{j}\sum_{i}p_{i|j}\cdot(\mathbf{y}_{t}-\mathbf{y}_{j})\cdot q_{t|j} \qquad (\sum_{i}p_{i|j}=1)$$

$$=2\sum_{j}(\mathbf{y}_{t}-\mathbf{y}_{j})\cdot p_{t|j}-2\sum_{j}(\mathbf{y}_{t}-\mathbf{y}_{j})\cdot q_{t|j}=2\sum_{j}(\mathbf{y}_{t}-\mathbf{y}_{j})(p_{t|j}-q_{t|j})$$





• Gradient of the cost function 1 + 2 + 3

$$2\sum_{j}(\mathbf{y}_{t}-\mathbf{y}_{j})(p_{j|t}-q_{j|t})+2\sum_{j}(\mathbf{y}_{t}-\mathbf{y}_{j})(p_{t|j}-q_{t|j})$$

$$=2\sum_{j}(\mathbf{y}_{t}-\mathbf{y}_{j})(p_{t|j}-q_{t|j}+p_{j|t}-q_{j|t})$$

- Update the coordinate in the lower dimension to minimize the cost function
 - √ Gradient update with a momentum term

$$\mathcal{Y}^{(t+1)} = \mathcal{Y}^{(t)} + \eta \frac{\partial C}{\partial \mathcal{Y}} + \alpha(t) \left(\mathcal{Y}^{(t)} - \mathcal{Y}^{(t-1)} \right)$$



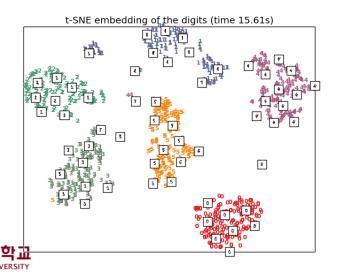


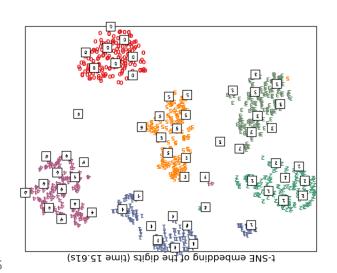
From the original paper

$$\frac{\partial C}{\partial \mathbf{y}_i} = 2\sum_j (\mathbf{y}_j - \mathbf{y}_i)(p_{j|i} - q_{j|i} + p_{i|j} - q_{i|j})$$

In this lecture note

$$\frac{\partial C}{\partial \mathbf{y}_t} = 2\sum_{j} (\mathbf{y}_t - \mathbf{y}_j)(p_{t|j} - q_{t|j} + p_{j|t} - q_{j|t})$$







Symmetric SNE

• Turning conditional probabilities into pairwise probabilities

$$p_{ij} = \frac{e^{-\frac{||\mathbf{x}_i - \mathbf{x}_j||^2}{2\sigma_i^2}}}{\sum_{k \neq l} e^{-\frac{||\mathbf{x}_k - \mathbf{x}_l||^2}{2\sigma_i^2}}} \triangleright p_{ij} = \frac{p_{j|i} + p_{i|j}}{2n} \qquad \sum_{j} p_{ij} > \frac{1}{2n}$$

✓ Cost function and gradient

$$Cost = \sum_{i} KL(\underline{P_i}||\underline{Q_i}) = \sum_{i} \sum_{j} \underline{p_{ij}} log \frac{p_{ij}}{q_{ij}}$$

$$\frac{\partial C}{\partial \mathbf{y_i}} = 4\sum_{j} (\mathbf{y_j} - \mathbf{y_i})(p_{ij} - q_{ij})$$

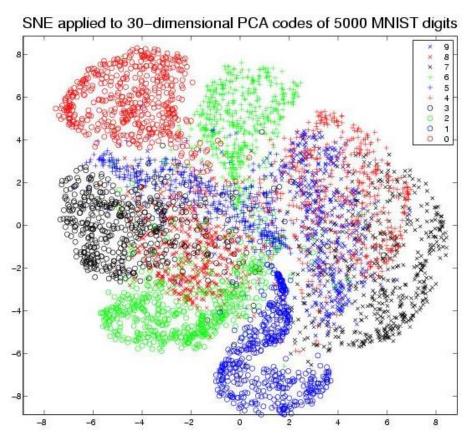




Symmetric SNE

Crowding problem

✓ The area accommodating moderately distant data points is not large enough compared with the area accommodating nearby data points





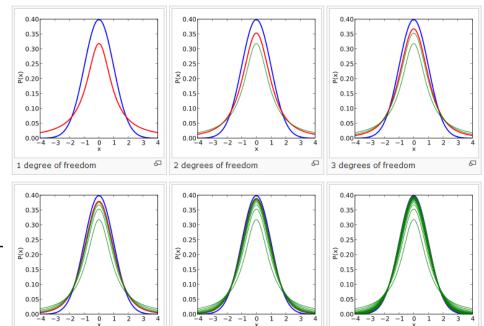


- Resolution to the Crowding Problem
 - ✓ Use a probability distribution that has much heavier tails than a Gaussian to convert distances into probabilities in the low-dimensional map
 - ✓ Student's t-distribution with one degree of freedom

$$f(t) = \frac{\Gamma(\frac{\nu+1}{2})}{\sqrt{\nu\pi}\Gamma(\frac{\nu}{2})} \left(1 + \frac{t^2}{\nu}\right)^{-\frac{\nu+1}{2}}$$

$$\Gamma(n) = (n-1)!$$

$$q_{j|i} = \frac{(1 + ||\mathbf{y}_i - \mathbf{y}_j||^2)^{-1}}{\sum_{k \neq l} (1 + ||\mathbf{y}_k - \mathbf{y}_l||^2)^{-1}}$$



10 degrees of freedom





30 degrees of freedom

5 degrees of freedom

t-SNE

Optimization of t-SNE

$$p_{ij} = \frac{e^{-\frac{||\mathbf{x}_{i} - \mathbf{x}_{j}||^{2}}{2\sigma_{i}^{2}}}}{\sum_{k \neq l} e^{-\frac{||\mathbf{x}_{k} - \mathbf{x}_{l}||^{2}}{2\sigma_{i}^{2}}}} \qquad q_{ji} = \frac{(1 + ||\mathbf{y}_{i} - \mathbf{y}_{j}||^{2})^{-1}}{\sum_{k \neq l} (1 + ||\mathbf{y}_{k} - \mathbf{y}_{l}||^{2})^{-1}}$$

✓ Gradient:

$$\frac{\partial C}{\partial \mathbf{y}_i} = 4\sum_{j} (\mathbf{y}_j - \mathbf{y}_i)(p_{ij} - q_{ij})(1 + ||\mathbf{y}_i - \mathbf{y}_j||^2)^{-1}$$





t-SNE

• t-SNE algorithm

```
Algorithm 1: Simple version of t-Distributed Stochastic Neighbor Embedding.
```

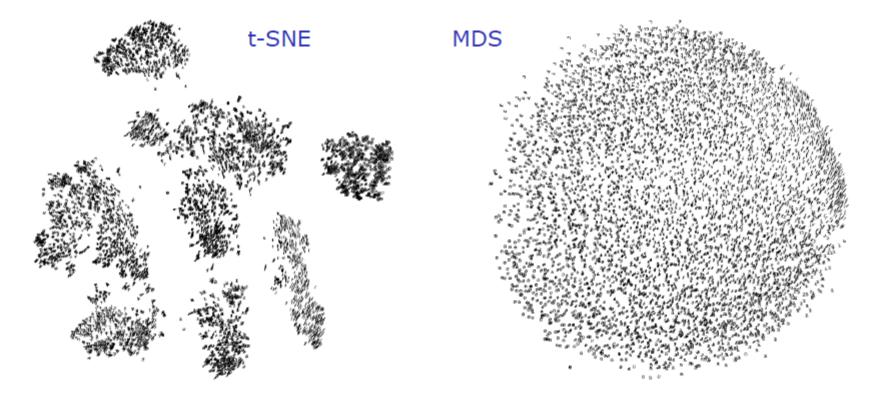
```
Data: data set X = \{x_1, x_2, ..., x_n\},
cost function parameters: perplexity Perp,
optimization parameters: number of iterations T, learning rate \eta, momentum \alpha(t).
Result: low-dimensional data representation \mathcal{Y}^{(T)} = \{y_1, y_2, ..., y_n\}.
begin
     compute pairwise affinities p_{i|i} with perplexity Perp (using Equation 1)
     set p_{ij} = \frac{p_{j|i} + p_{i|j}}{2n}
     sample initial solution \mathcal{Y}^{(0)} = \{y_1, y_2, ..., y_n\} from \mathcal{N}(0, 10^{-4}I)
     for t=1 to T do
          compute low-dimensional affinities q_{ij} (using Equation 4)
          compute gradient \frac{\delta C}{\delta \gamma} (using Equation 5)
          set \mathcal{Y}^{(t)} = \mathcal{Y}^{(t-1)} + \eta \frac{\delta C}{\delta \mathcal{Y}} + \alpha(t) \left( \mathcal{Y}^{(t-1)} - \mathcal{Y}^{(t-2)} \right)
     end
end
```





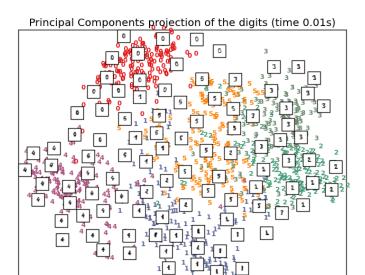
t-SNE vs. MDS

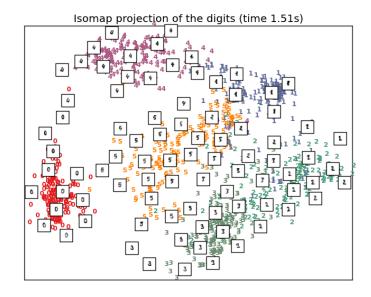
MNIST dataset

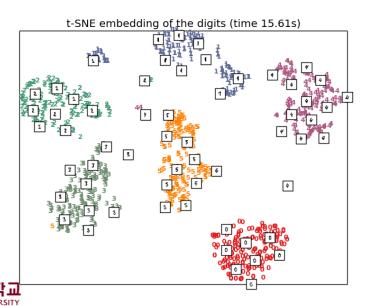




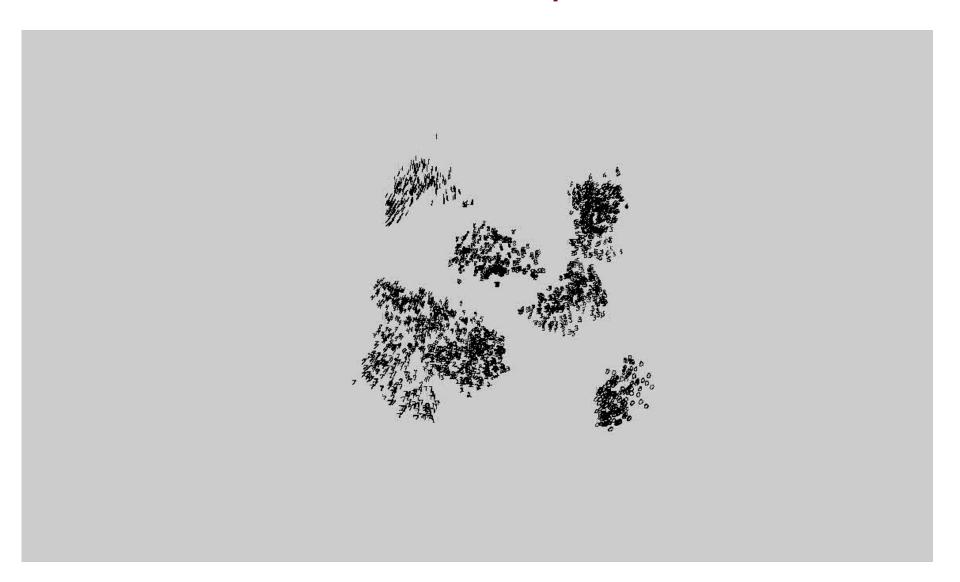








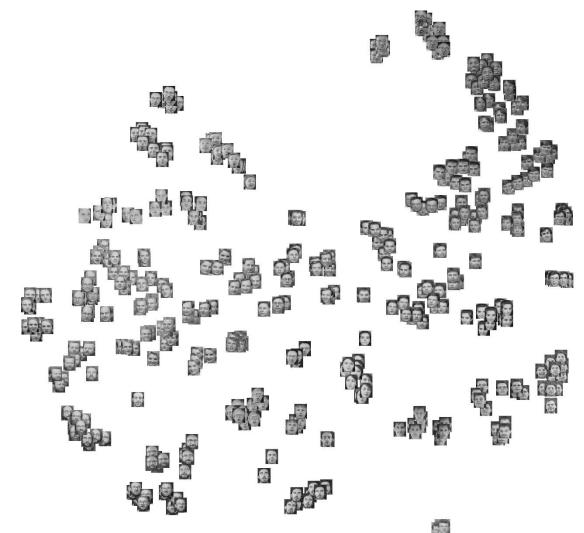








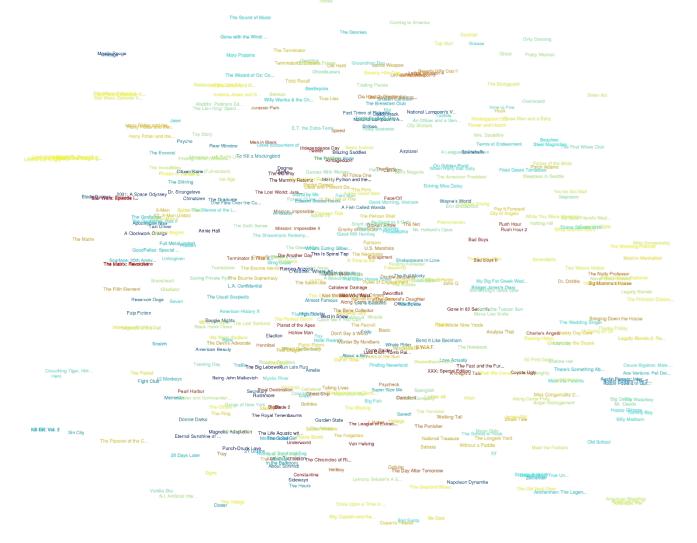
Olivetti faces datasets







Netflix dataset

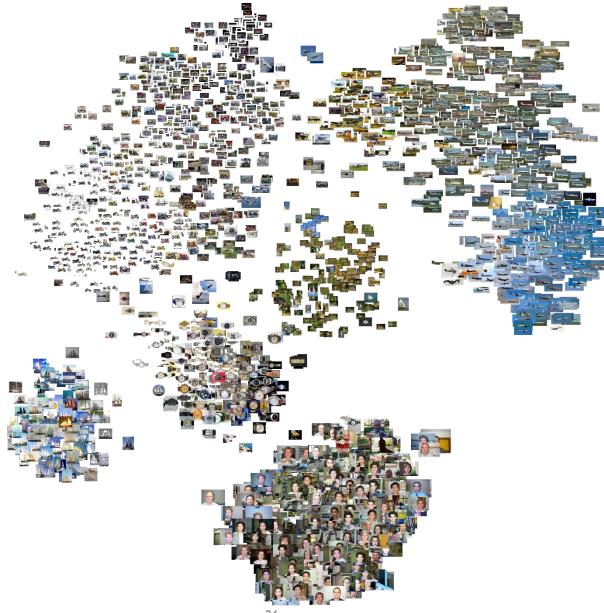






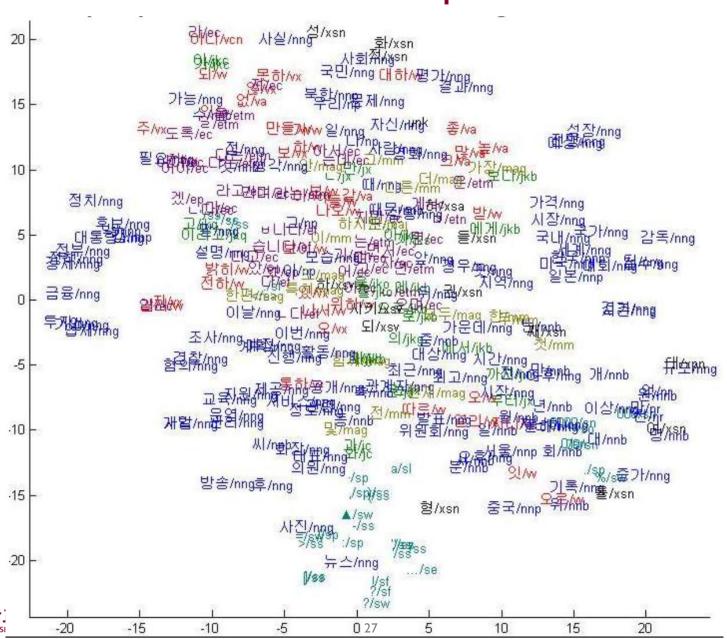
Bawingsin Solumbine

• CalTech-101

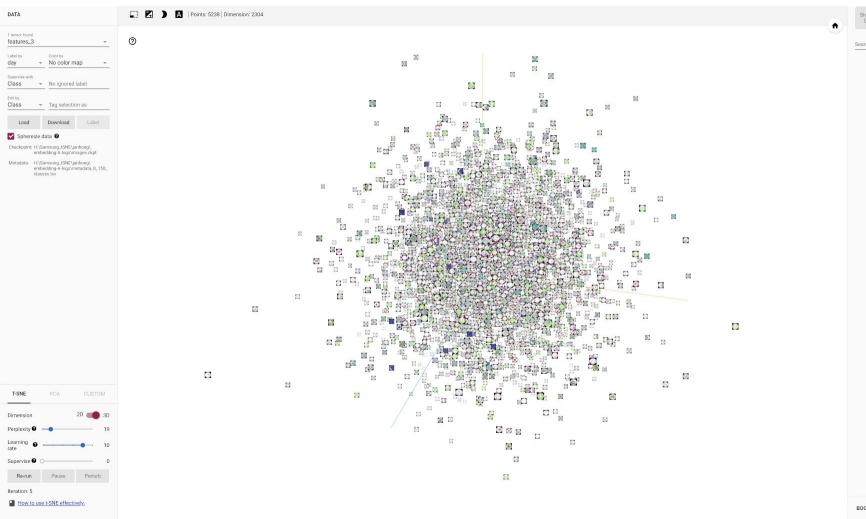






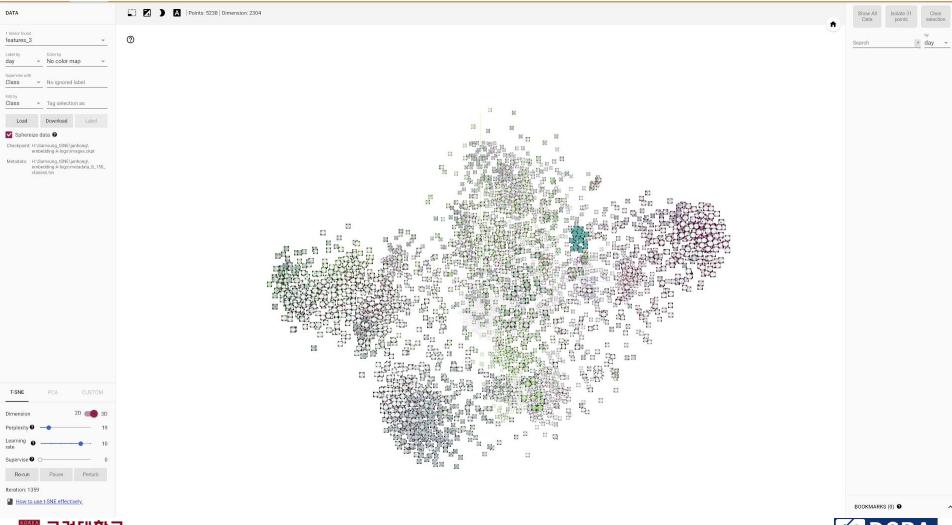


• Wafer Bin Map (WBM) in Semiconductor Manufacturing





• Wafer Bin Map (WBM) in Semiconductor Manufacturing











References

Research Papers

• van der Maaten, L.J.P. and Hinton, G.E. (2008). Visualizing high-dimensional data using t-SNE. Journal of Machine Learning Research 9: 2579-2605.

Other materials

• Figure in the title page: https://nlml.github.io/in-raw-numpy/in-raw-numpy-t-sne/



