

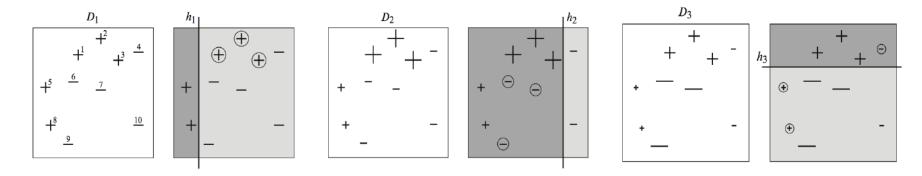
Ensemble Learning: Gradient Boosting Machine (GBM)

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Friedman (2001), Natekin and Knoll (2013)

Gradient Boosting = Gradient Descent + Boosting

Adaboost

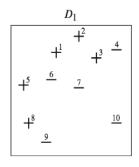


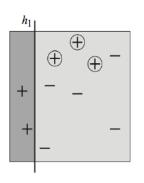
- \checkmark Fit an additive model (ensemble) $\sum_t \rho_t h_t(x)$ in a forward stage-wise manner.
- ✓ In each stage, introduce a weak leaner to compensate the shortcomings of existing weak leaners.
- √ In Adaboost, "shortcomings" are identified by high-weight data points.

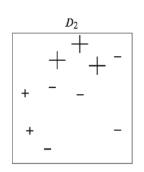


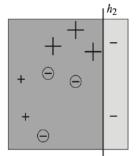


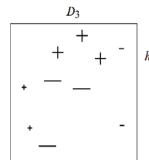
Adaboost



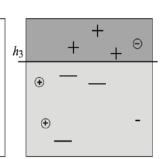








+0.92



$$H(x) = \sum_{t} \rho_t h_t(x)$$





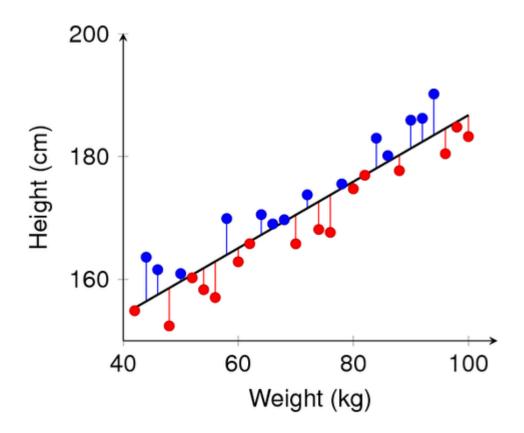
Gradient Boosting

- \checkmark Fit an additive model (ensemble) $\sum_t \rho_t h_t(x)$ in a forward stage-wise manner.
- ✓ In each stage, introduce a weak leaner to compensate the shortcomings of existing weak leaners.
- ✓ In Gradient Boosting, "shortcomings" are identified by gradients.
- ✓ Both high-weight data points and gradients tell us how to improve our model.
- Gradient Boosting for Different Problems
 - ✓ Difficulty: Regression < Classification < Ranking</p>
 - Associated with the complexity of the derivative of a loss function





- Motivation (for regression problem)
 - √ What if we attempt to predict the residuals with the additional regression model?







• Main idea

| ric | ınal | Dataset |
|-------|--------|---------|
| או וי | Jiiiai | Dataset |

| O | |
|-----------------|-----------------------|
| χl | уl |
| x ² | y ² |
| x³ | y ³ |
| x ⁴ | y ⁴ |
| x ⁵ | y ⁵ |
| × ⁶ | y ⁶ |
| x ⁷ | y ⁷ |
| x ₈ | y 8 |
| x ⁹ | y ⁹ |
| x ¹⁰ | y 10 |

Modified Dataset I

| ×I | $y^{l}-f_{l}(x^{l})$ |
|-----------------------|----------------------|
| x^2 | $y^2-f_1(x^2)$ |
| x^3 | $y^3 - f_1(x^3)$ |
| × ⁴ | $y^4 - f_1(x^4)$ |
| x ⁵ | $y^5 - f_1(x^5)$ |
| x ⁶ | $y^6 - f_1(x^6)$ |
| x ⁷ | $y^{7}-f_{1}(x^{7})$ |
| x ⁸ | $y^8 - f_1(x^8)$ |
| x ⁹ | $y^9 - f_1(x^9)$ |
| ×10 | $y^{10}-f_1(x^{10})$ |

Modified Dataset 2

| χ ^l | $y^{1}-f_{1}(x^{1})-f_{2}(x^{1})$ |
|-----------------------|--|
| x^2 | $y^2-f_1(x^2)-f_2(x^2)$ |
| x^3 | $y^3-f_1(x^3)-f_2(x^3)$ |
| × ⁴ | $y^4 - f_1(x^4) - f_2(x^4)$ |
| x ⁵ | $y^5 - f_1(x^5) - f_2(x^5)$ |
| × ⁶ | $y^6 - f_1(x^6) - f_2(x^6)$ |
| x ⁷ | $y^7 - f_1(x^7) - f_2(x^7)$ |
| x ₈ | $y^8 - f_1(x^8) - f_2(x^8)$ |
| x ⁹ | $y^9 - f_1(x^9) - f_2(x^9)$ |
| ×10 | y^{10} - $f_1(x^{10})$ - $f_2(x^{10})$ |



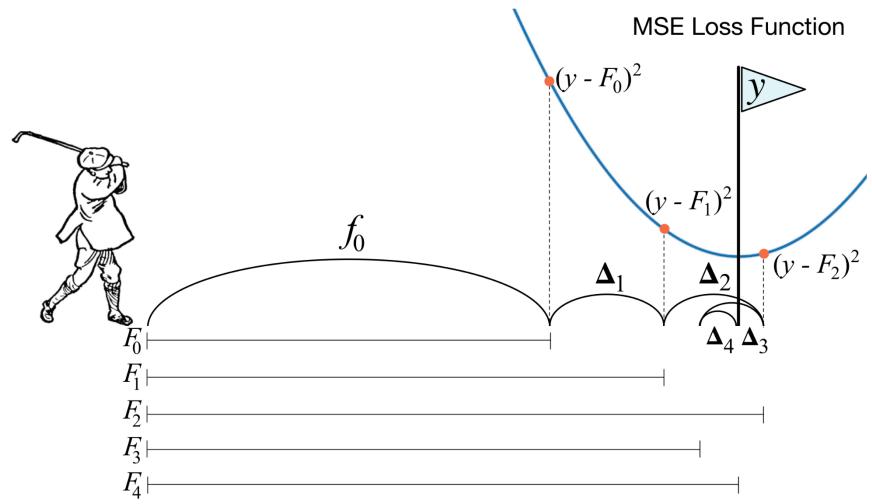


$$y = f_1(\mathbf{x})$$
 $y - f_1(\mathbf{x}) = f_2(\mathbf{x})$ $y - f_1(\mathbf{x}) - f_2(\mathbf{x}) = f_3(\mathbf{x})$





Illustrative Example







- How is this idea related to the gradient?
 - √ Loss function of the ordinary least square (OLS)

$$\min L = \frac{1}{2} \sum_{i=1}^{n} (y_i - f(\mathbf{x}_i))^2$$

✓ Gradient of the Loss function

$$\frac{\partial L}{\partial f(\mathbf{x}_i)} = f(\mathbf{x}_i) - y_i$$

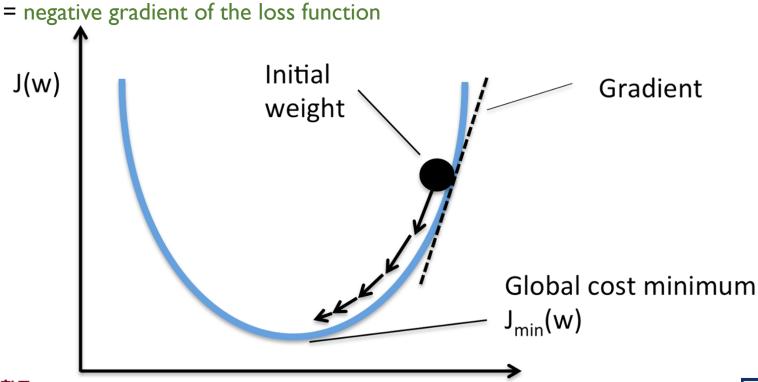
✓ Residuals are the negative gradient of the loss function

$$y_i - f(\mathbf{x}_i) = -\frac{\partial L}{\partial f(\mathbf{x}_i)}$$





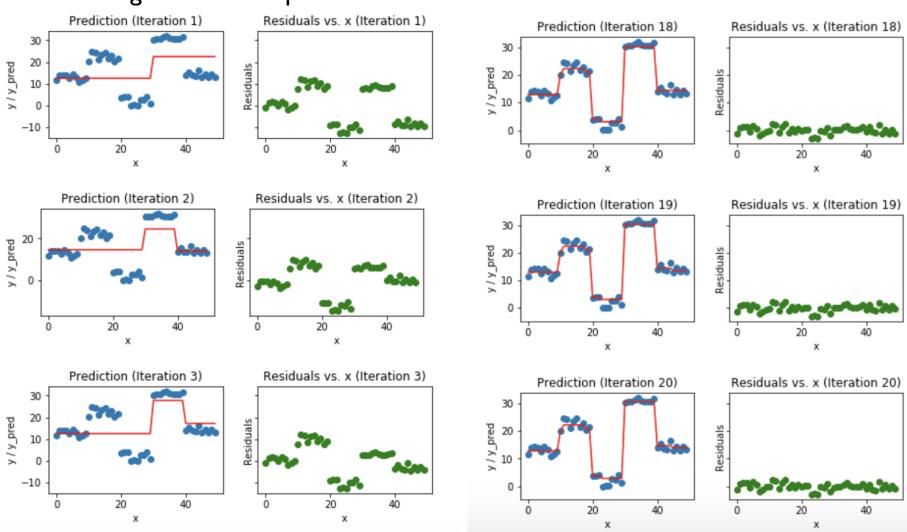
- Gradient Descent Algorithm
 - ✓ Blue line: value of loss function with a given parameter
 - ✓ Black point: current state
 - ✓ Arrows: the direction that the parameter should follow to minimize the loss function



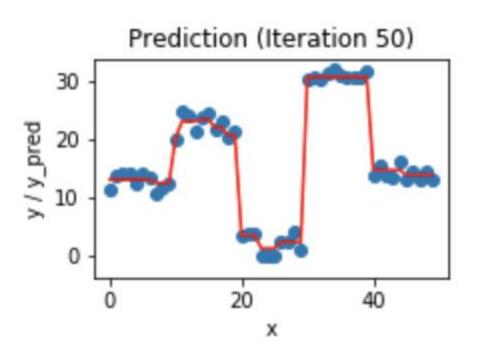


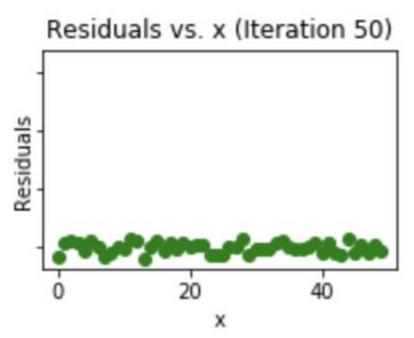


GBM Regression Example I



GBM Regression Example I



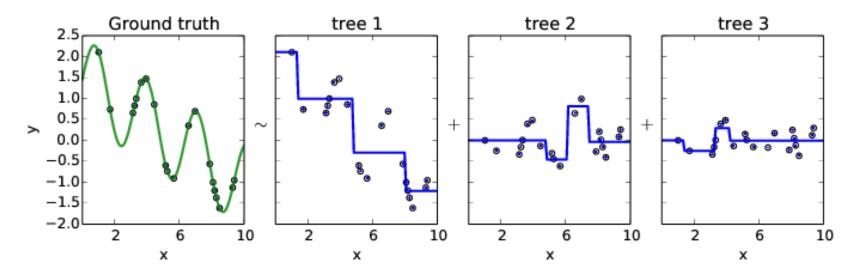


https://medium.com/mlreview/gradient-boosting-from-scratch-1e317ae4587d





• GBM Regression Example 2

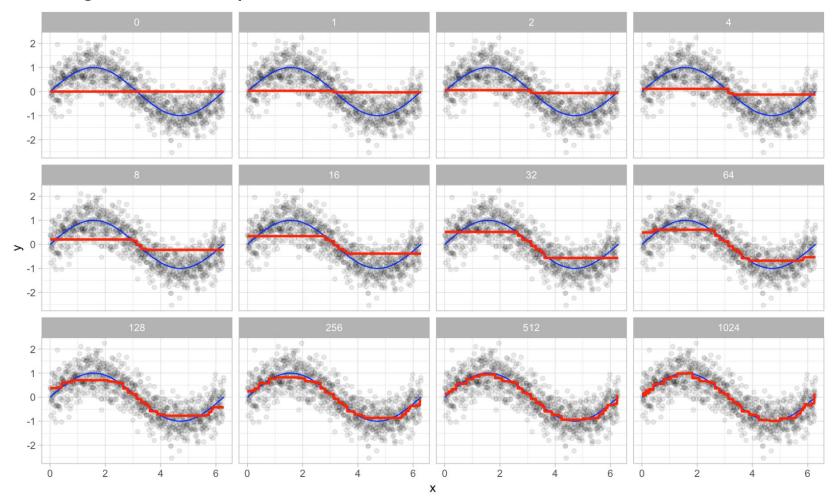


https://www.quora.com/How-would-you-explain-gradient-boosting-machine-learning-technique-in-no-more-than-300-words-to-non-science-major-college-students





• GBM Regression Example 3



https://docs.paperspace.com/machine-learning/wiki/gradient-boosting





- Gradient Boosting: Algorithm
 - 1. Initialize $f_0(x) = \arg\min_{\gamma} \sum_{i=1}^N L(y_i, \gamma)$.
 - 2. For m=1 to M:
 - 2.1 For $i = 1, \ldots, N$ compute

$$g_{im} = \left[\frac{\partial L(y_i, f(x_i))}{\partial f(x_i)}\right]_{f(x_i) = f_{m-1}(x_i)}$$

- 2.2 Fit a regression tree to the targets g_{im} giving terminal regions $R_{im}, j = 1, \dots, J_m$.
- 2.3 For $j = 1, \ldots, J_m$ compute

$$\gamma_{jm} = \arg\min_{\gamma} \sum_{x_i \in R_{jm}} L(y_i, f_{m-1}(x_i) + \gamma)$$

- 2.4 Update $f_m(x) = f_{m-1}(x) + \sum_{j=1}^{J_m} \gamma_{jm} I(x \in R_{jm})$
- 3. Output $\hat{f}(x) = f_M(x)$.





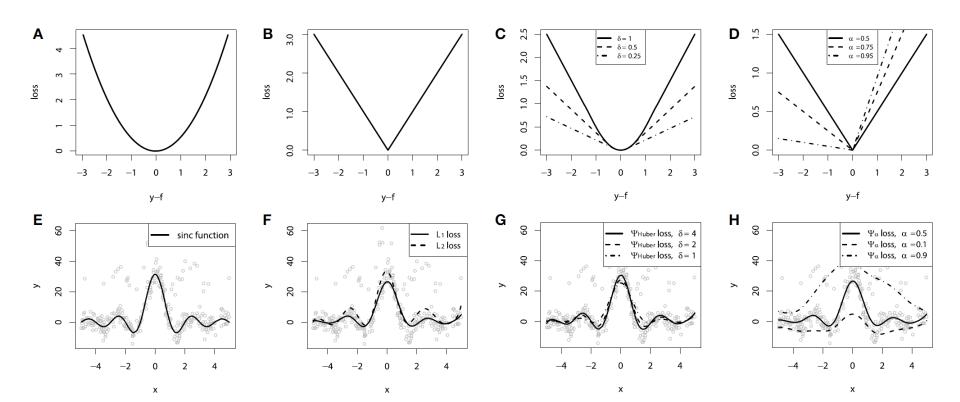
• Loss Functions for Regression

| Loss Function | Formula |
|---------------------------------|--|
| Squared loss (L ₂) | $\Psi(y,f)_{L_2} = \frac{1}{2}(y-f)^2$ |
| Absolute loss (L _I) | $\Psi(y,f)_{L_1} = y - f $ |
| Huber loss | $\Psi(y, f)_{\text{Huber, }\delta} = \begin{cases} \frac{1}{2}(y - f)^2 & y - f \le \delta \\ \delta(y - f - \delta/2) & y - f > \delta \end{cases}$ |
| Quantile loss | $\Psi(y,f)_{\alpha} = \begin{cases} (1-\alpha) y-f & y-f \le 0\\ \alpha y-f & y-f > 0 \end{cases}$ |





Loss Functions for Regression







Loss Functions for Classification

| Loss Function | Formula |
|----------------|---|
| Bernoulli loss | $\Psi(y, f)_{\text{Bern}} = \log(1 + \exp(-2\bar{y}f))$ |
| Adaboost loss | $\Psi(y, f)_{Ada} = \exp(-\bar{y}f)$ |

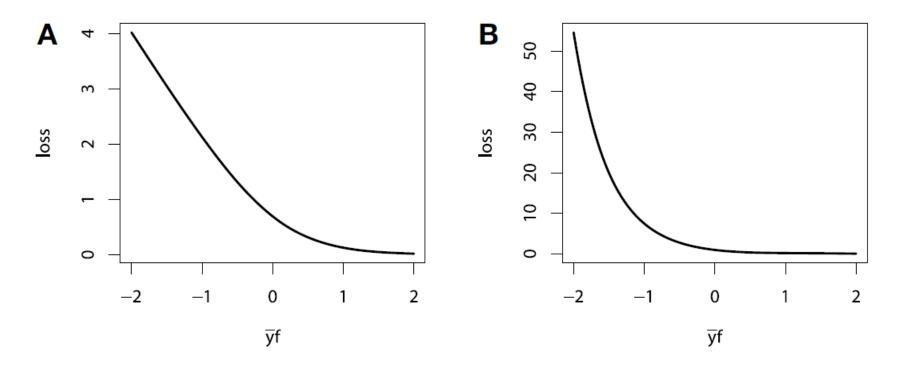
(Note)

In binary classification, the target is usually defined by $y \in \{0,1\}$, but here we define $\bar{y} = 2y - 1$ so that $\bar{y} \in \{-1,1\}$





Loss Functions for Classification



(A) Bernoulli loss function. (B) Adaboost loss function.





Overfitting problem in GBM

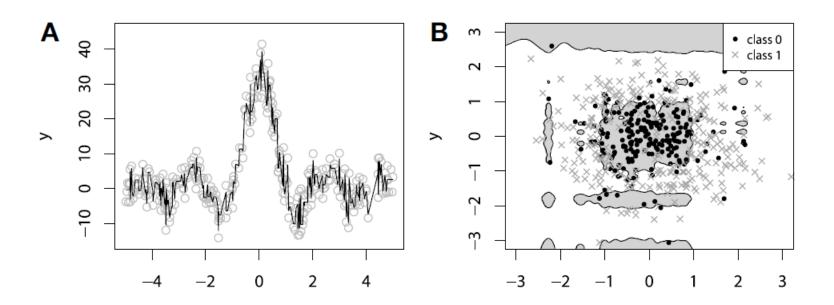


FIGURE 4 | Examples of overfitting in GBMs on: (A) regression task; (B) classification task. Demonstration of fitting a decision-tree GBM to a noisy sinc(x) data: (C) M = 100, $\lambda = 1$; (D) M = 1000, $\lambda = 1$; (E) M = 100, $\lambda = 0.1$; (F) M = 1000, $\lambda = 0.1$.





Regularization

√ Subsampling

- At each learning iteration, only a random part of the training data is used to fit a consecutive base-learner.
- The training data is typically sampled without replacement, but bagging can be also acceptable.



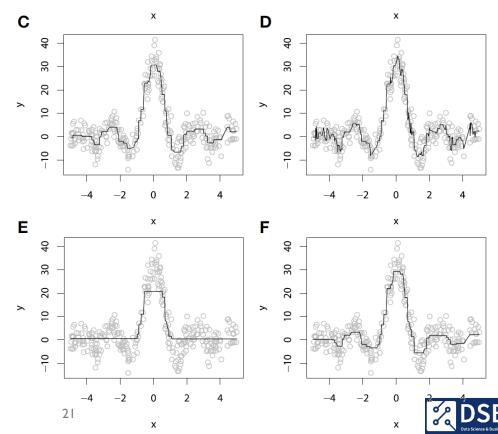


Regularization

√ Shrinkage

- Used for reducing/shrinking the impact of each additional fitted base-leaners.
- Better to improve a model by taking many small steps than by taking fewer large steps.

$$\widehat{f}_t \leftarrow \widehat{f}_{t-1} + \lambda o_t h(x, \theta_t)$$





- Regularization
 - ✓ Early Stopping
 - Use the validation error

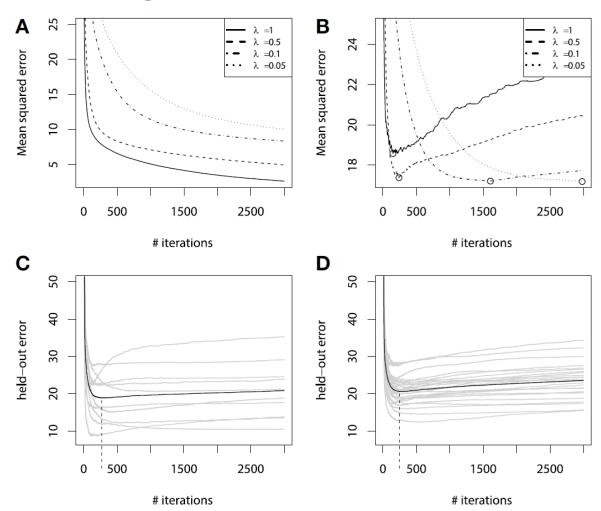


FIGURE 5 | Error curves for GBM fitting on sinc(x) data: (A) training set error; (B) validation set error. Error curves for learning simulations and number of base-learners M estimation: (C) error curves for cross-validation; (D) error curves for bootstrap estimates.



- Variable Importance in Tree-based Gradient Boosting
 - ✓ $Influence_i(T)$: importance of the variable j in a single tree T.
 - ✓ Assume that there are L terminal nodes $\rightarrow L-1$ splits.

$$Influence_{j}(T) = \sum_{i=1}^{L-1} (IG_{i} \times \mathbf{1}(S_{i} = j))$$

√ Variable importance of Gradient boosting

$$Influence_{j} = \frac{1}{M} \sum_{k=1}^{M} Influence_{j}(T_{k})$$









