

# Lab Report 8

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Question 1 done by Juann Jeon

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Q1 a)

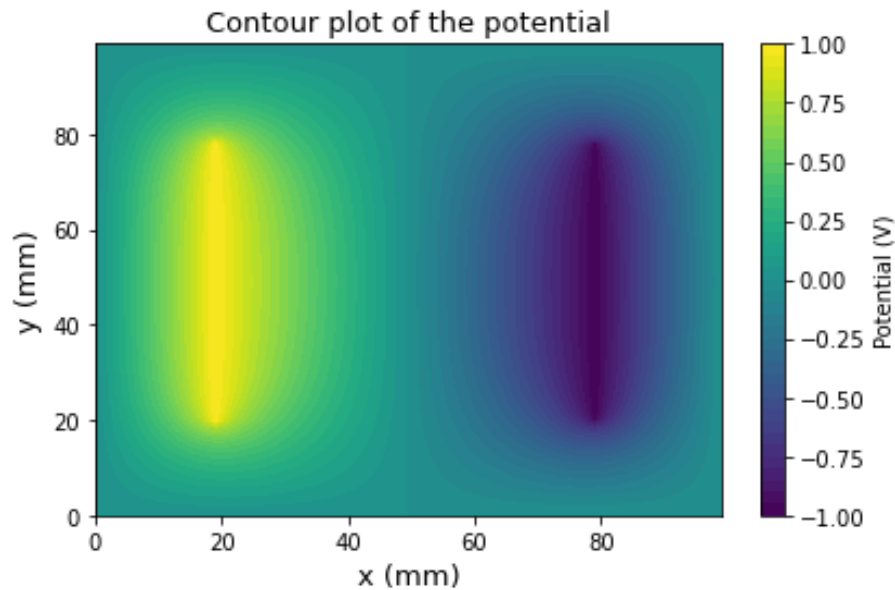


Figure 1: Contour plot of the potential of 2D electronic capacitor using Gauss-Seidel method

Q1 b)

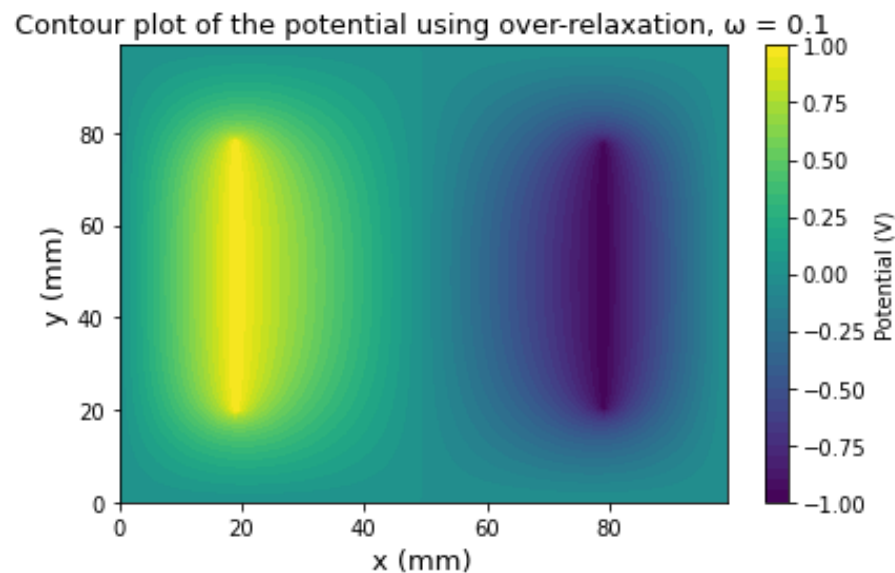


Figure 2: Contour plot of the potential of 2D electronic capacitor with over-relaxation  
 $\omega = 0.1$

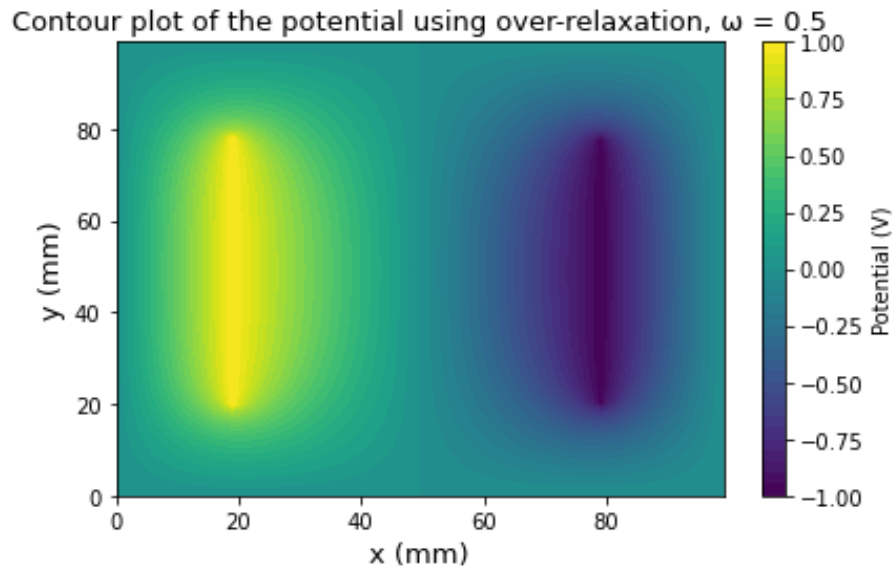


Figure 3: Contour plot of the potential of 2D electronic capacitor with over-relaxation  $\omega = 0.5$

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Total time it took for Q 1a) (in s): 15.919002532958984
Total time it took for omega = 0.1 (in s): 15.561467170715332
Total time it took for omega = 0.5 (in s): 6.342304944992065
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Figure 4: Calculation time it took for Figure 1, 2 and 3 in respective order

Figure 2 and 3 shows the contour map of the potential energy with overrelaxation  $\omega = 0.1$  (for Figure 2) and  $\omega = 0.5$  (for Figure 3). Notice that Figure 2 and 3 have the same contour map as Figure 1, which is without over relaxation. The difference is in the time it takes for calculation; over relaxation is used to shorten the time it takes for calculation. Figure 4 shows the total time it took for Figure 1, 2 and 3 in respective order. Notice that Figure 1 took  $\approx 15.92s$  to finish the calculation. Figure 2 took  $\approx 15.56s$  which is slightly less compared to the time it took for Figure 1, but by not much. Figure 3 took  $\approx 6.34s$  for calculation, which shows that overrelaxation indeed shortens the time it takes for calculation without deviating from the final result compared to without overrelaxation.

**Q2 a)**

Equation (6):

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = -g \frac{\partial \eta}{\partial x}$$

$$\frac{\partial \eta}{\partial t} + \frac{\partial (uh)}{\partial x} = 0$$

where

$$h = \eta - \eta_b, \quad \vec{F}(u, \eta) = \left[ \frac{1}{2}u^2 + g\eta, (\eta - \eta_b)u \right]$$

Take partial derivative respect to x,

$$\begin{aligned} \frac{\partial \vec{F}(u, \eta)}{\partial x} &= \left[ \frac{\partial}{\partial x} \left( \frac{1}{2}u^2 + g\eta \right), \frac{\partial}{\partial x} ((\eta - \eta_b)u) \right] \\ &= \left[ u \frac{\partial u}{\partial x} + g \frac{\partial \eta}{\partial x}, \frac{\partial (u(\eta - \eta_b))}{\partial x} \right] \end{aligned}$$

From equation (6),

$$\frac{\partial u}{\partial t} = - \left( u \frac{\partial u}{\partial x} + g \frac{\partial \eta}{\partial x} \right)$$

$$\begin{aligned} \frac{\partial \eta}{\partial t} &= - \frac{\partial (uh)}{\partial x} \\ &= - \frac{\partial (u(\eta - \eta_b))}{\partial x} \end{aligned}$$

Since  $\vec{u} = (u, \eta)$ ,

$$\frac{\partial \vec{u}}{\partial t} = \left[ \frac{\partial u}{\partial t}, \frac{\partial \eta}{\partial t} \right]$$

$$\frac{\partial \vec{u}}{\partial t} = \left[ - \left( u \frac{\partial u}{\partial x} + g \frac{\partial \eta}{\partial x} \right), - \frac{\partial (u(\eta - \eta_b))}{\partial x} \right]$$

$$\therefore \frac{\partial \vec{u}}{\partial t} = - \frac{\partial \vec{F}(u, \eta)}{\partial x}$$

The forward-time centred-space scheme is

$$\frac{\partial u}{\partial t} \Big|_j^n \approx \frac{1}{\Delta t} (u_j^{n+1} - u_j^n)$$

$$\frac{\partial F}{\partial x} \Big|_j^n \approx \frac{1}{2\Delta x} (F_{j+1}^n - F_{j-1}^n)$$

Substituting these approximations into the equation from previous part

$$\frac{\partial \vec{u}}{\partial t} = - \frac{\partial \vec{F}}{\partial x} (u, \eta),$$

then

$$u_j^{n+1} = u_j^n - \frac{\Delta t}{2\Delta x} (F(u)_{j+1}^n - F(u)_{j-1}^n)$$

$$\eta_j^{n+1} = \eta_j^n - \frac{\Delta t}{2\Delta x} (F(\eta)_{j+1}^n - F(\eta)_{j-1}^n)$$

$$\therefore u_j^{n+1} = u_j^n - \frac{\Delta t}{2\Delta x} \left( \frac{1}{2} (u_{j+1}^n)^2 + g\eta_{j+1}^n - \frac{1}{2} (u_{j-1}^n)^2 - g\eta_{j-1}^n \right)$$

$$\eta_j^{n+1} = \eta_j^n - \frac{\Delta t}{2\Delta x} (u_{j+1}^n (\eta_{j+1}^n - \eta_{b,j+1}) - (u_{j-1}^n (\eta_{j-1}^n - \eta_{b,j-1})))$$

**Q2 (b)**

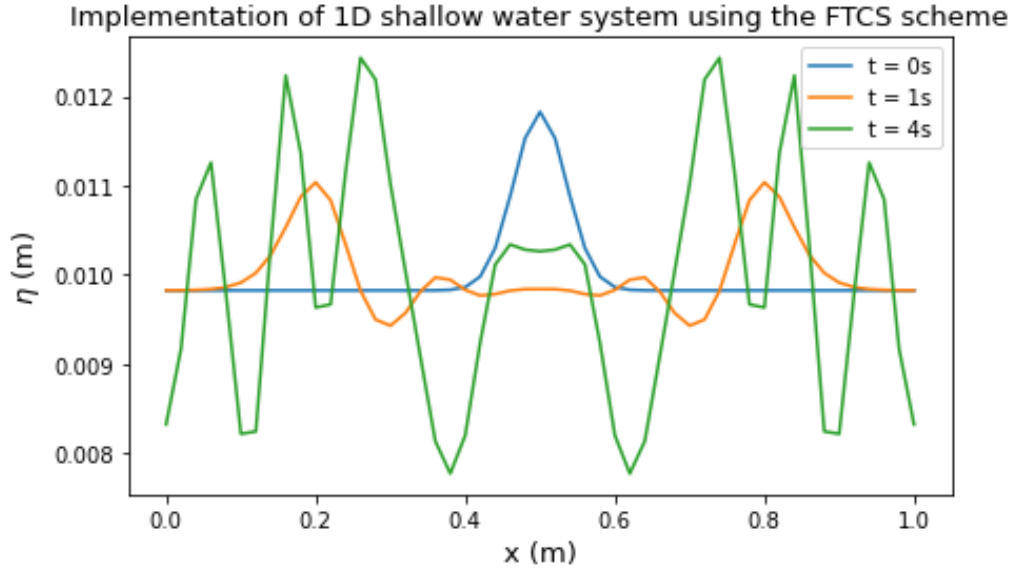


Figure 5: Implementation of the 1D shallow water system at given times using the FTCS scheme

**Q2 (c)**

Equation (6):

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = -g \frac{\partial \eta}{\partial x}$$

$$\frac{\partial \eta}{\partial t} + \frac{\partial(uh)}{\partial x} = 0$$

The linearized equation (6) about  $(u, \eta) = (0, H)$  with  $\eta_b = 0$  is

$$\frac{\partial u}{\partial t} = -g \frac{\partial \eta}{\partial x}$$

$$\frac{\partial \eta}{\partial t} + \frac{\partial(u(\eta - \eta_b))}{\partial x} = 0$$

$$\frac{\partial \eta}{\partial t} + (\eta - \eta_b) \frac{\partial u}{\partial x} + u \frac{\partial(\eta - \eta_b)}{\partial x} = 0$$

$$\frac{\partial \eta}{\partial t} = -H \frac{\partial u}{\partial x}$$

$$\therefore \frac{\partial u}{\partial t} = -g \frac{\partial \eta}{\partial x}$$

$$\frac{\partial \eta}{\partial t} = -H \frac{\partial u}{\partial x}$$

The spatial variation can be expressed in the form of a Fourier series.

$$u(x, t) = \sum_{k=1}^{\infty} c_u(t) e^{ikx}$$

$$\eta(x, t) = \sum_{k=1}^{\infty} c_\eta(t) e^{ikx}$$

Since the equation is linear, we can only study what happens to each term in the series.

$$u(x, t) = \sum_{k=1}^{\infty} c_u(t) e^{ikx}$$

$$u(x, t + h) = c_u(t + h) e^{ikx}$$

$$= c_u(t) e^{ikx} - \frac{\Delta t}{2\Delta x} (g c_\eta(t) e^{ik(x+\Delta x)} - g c_\eta(t) e^{ik(x-\Delta x)})$$

$$= c_u(t) e^{ikx} - \frac{g\Delta t}{2\Delta x} (c_\eta(t) e^{ik(x+\Delta x)} - c_\eta(t) e^{ik(x-\Delta x)})$$

$$= [c_u(t) - \frac{g\Delta t}{2\Delta x} c_\eta(t) (e^{ik\Delta x} - e^{-ik\Delta x})] e^{ikx}$$

$$\therefore c_u(t + h) = c_u(t) - \frac{g\Delta t}{2\Delta x} c_\eta(t) (e^{ik\Delta x} - e^{-ik\Delta x})$$

$$\eta(x, t) = \sum_{k=1}^{\infty} c_\eta(t) e^{ikx}$$

$$\eta(x, t + h) = c_\eta(t + h) e^{ikx}$$

$$= c_\eta(t) e^{ikx} - \frac{\Delta t}{2\Delta x} (H c_u(t) e^{ik(x+\Delta x)} - H c_u(t) e^{ik(x-\Delta x)})$$

$$= c_\eta(t) e^{ikx} - \frac{H\Delta t}{2\Delta x} (c_u(t) e^{ik(x+\Delta x)} - c_u(t) e^{ik(x-\Delta x)})$$

$$= [c_\eta(t) - \frac{H\Delta t}{2\Delta x} c_u(t) (e^{ik\Delta x} - e^{-ik\Delta x})] e^{ikx}$$

$$\therefore c_\eta(t + h) = c_\eta(t) - \frac{H\Delta t}{2\Delta x} c_u(t) (e^{ik\Delta x} - e^{-ik\Delta x})$$

$$\mathbf{c}(t + h) = \mathbf{A}\mathbf{c}(t)$$

Where  $\mathbf{c}(t)$  is the vector  $(c_u, c_\eta)$  and  $\mathbf{A}$  is the matrix

$$\mathbf{A} = \begin{pmatrix} 1 & -\frac{g\Delta t}{2\Delta x} (e^{ik\Delta x} - e^{-ik\Delta x}) \\ -\frac{H\Delta t}{2\Delta x} (e^{ik\Delta x} - e^{-ik\Delta x}) & 1 \end{pmatrix}$$

$$\mathbf{A} = \begin{pmatrix} 1 & -i \frac{g\Delta t}{\Delta x} \sin(k\Delta x) \\ -i \frac{H\Delta t}{\Delta x} \sin(k\Delta x) & 1 \end{pmatrix}$$

The determinant of the matrix  $\mathbf{A}$  is,

$$\det(\mathbf{A} - \lambda \mathbf{I}) = \begin{vmatrix} 1 - \lambda & -i \frac{g \Delta t}{\Delta x} \sin(k \Delta x) \\ -i \frac{H \Delta t}{\Delta x} \sin(k \Delta x) & 1 - \lambda \end{vmatrix} = 0$$

$$(1 - \lambda)^2 + gH \left( \frac{\Delta t}{\Delta x} \right)^2 \sin^2(k \Delta x) = 0$$

$$\lambda = 1 \pm \sqrt{gH \left( \frac{\Delta t}{\Delta x} \right)^2 \sin^2(k \Delta x)}$$

$$\therefore |\lambda| = \sqrt{1 + gH \frac{\Delta t^2}{\Delta x^2} \sin^2(k \Delta x)}$$

The magnitude of the eigenvalues  $\lambda$  is never less than one. This implies the Fourier component grows exponentially as it gets repeatedly multiplied by the same factor on each time-step. Therefore, the FTCS method is unstable for the 1D shallow water system.