

Universitat Politècnica de Catalunya  
Facultat de Matemàtiques i Estadística

Master in Advanced Mathematics and Mathematical Engineering  
Master's thesis

# Why the non-monotonicity of excellence f\*\*\*\*\* up my life

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February, 2025



Thanks to...



## **Abstract**

This should be an abstract in english, up to 1000 characters.

## **Keywords**

regularity, stable graphs, graph theory, ...

# 1. Introduction

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## 2. Section 4

## 3. Section 4

## 4. Section 4

## References

- [1] S.K. Agrawal, J. Yan. 'A three-wheel vehicle with expanding wheels: differential flatness, trajectory planning, and control', *Proc. of the 2003 IEEE WRSJ, Intl. Conference on Intelligent Robots and Systems*, Las Vegas, 2003.
- [2] L. Ahlfors. *Complex analysis. An introduction to the theory of analytic functions of one complex variable*, 3rd ed. McGraw-Hill, 1978.
- [3] L. Ahlfors. *Lectures on quasiconformal mappings*, 2nd ed. University Lecture series **38**, American Mathematical Society, 2006.
- [4] L. Ahlfors and L. Bers. Riemann mapping's theorem for variable metrics, *Annals of Math.* **72** (1960), 385–404.
- [5] B. Charlet, J. Lévine, R. Marino. On dynamic feedback linearization, *System and Control Letters* **13** (1989), 143–151.

## A. Title of the appendix

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## B. Title of the appendix

Second appendix.