## Minicourse on information, complexity and organisation in multidimensional symbolic dynamics

# On the limit between the computable and the uncomputable

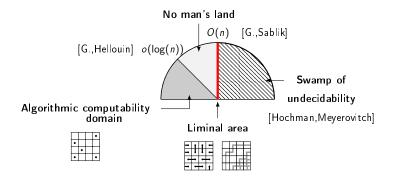
Silvere Gangloff

April 15, 2021

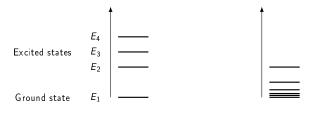
sgangloff@agh.edu.pl; silvere.gangloff@gmx.com

#### Multidimensional SFT: a computational 'transition':

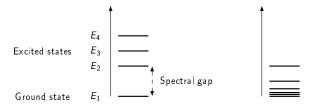
#### Reminder (third lecture):



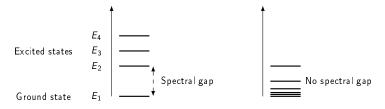
#### Energy states:



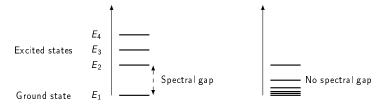
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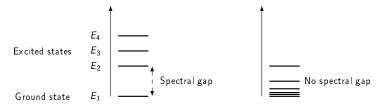


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Cubitt, Perez-Garcia, Wolf (2015): The spectral gap problem is undecidable.

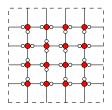
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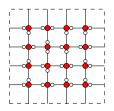
Cubitt, Perez-Garcia, Wolf (2015): The spectral gap problem is undecidable.

Kreinovich(2017): Why Some Physicists Are Excited About the Undecidability of the Spectral Gap Problem and Why Should We

Square ice model [Pauling(1935)]:

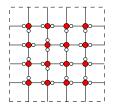


Square ice model [Pauling(1935)]:



**Lieb(1967):** The entropy of square ice is  $\frac{3}{2} \log(4/3)$  (incomplete proof).

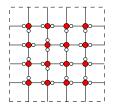
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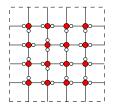
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!! Bidimensional SFT have uncomputable entropy in general!

#### Questions:

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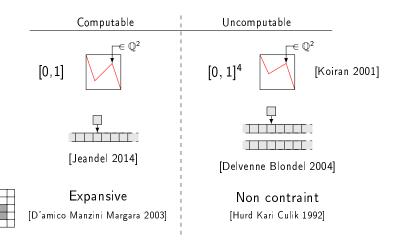
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#### Questions:

- 1. When does uncomputability phenomena appear in the classes of models considered?
- 2. How does 'organisation' emerge from simple interactions between elements of matter?
- 3. Are the models for which uncomputability occur physically significant? Can we formulate a restriction which ensures computability?

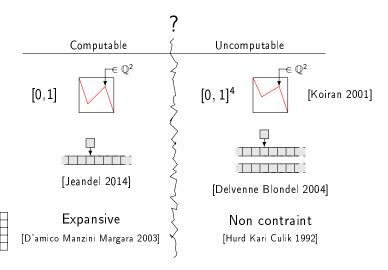
### Computability of (topological) entropy:

**Milnor (2002):** is the *entropy* of a dynamical system effectively computable ?



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#### Reminders:

Alphabet  $\mathcal{A}$  finite. Patterns:(d=1) elements of  $\mathcal{A}^{\mathbb{U}}$ ,  $\mathbb{U} \subset \mathbb{Z}$ .

**Subshifts**(d=1): set of patterns  $\mathcal{F}$ .

$$X_{\mathcal{F}} = \{ x \in \mathcal{A}^{\mathbb{Z}} : \forall \mathbb{U} \subset \mathbb{Z}, x_{|\mathbb{U}} \notin \mathcal{F} \}.$$

For every subshift X on alphabet A there exists F s.t.  $X = X_F$ .

When  $\mathcal{F}$  finite : of finite type; when  $\mathcal{F}$  recursively enumerable (set of outputs of a computing machine): effective.

#### Reminders:

**Language:**  $\mathcal{L}(X)$ : set of patterns which appear in some  $x \in X$ .

**Entropy**(d=1):  $N_n(X)$ : number of words  $w \in \mathcal{L}(X)$ , |w| = n.

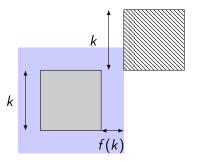
$$h(X) = \lim_{n \to +\infty} \frac{\log_2(N_n(X))}{n} = \inf_{\substack{T \in \mathbb{N} \\ T \in \mathbb{N}}} \frac{\log_2(N_n(X))}{n}$$

 $\Pi_1$ -computable:  $x \in \mathbb{R}$ : exists an algorithm  $n \mapsto r_n$  with  $r_n \downarrow x$ .

**Lemma:** when X is effective, h(X) is  $\Pi_1$ -computable.

#### Reminders:

### f-block gluing:

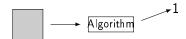


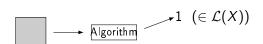
When d=1: square patterns  $\rightarrow$  words.

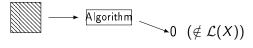
Decidable:

Algorithm









$$\longrightarrow \text{Algorithm} \longrightarrow 0 \ (\notin \mathcal{L}(X))$$

Assume 
$$\Sigma(f) = \sum_{Def} \frac{f(k)}{k^2}$$
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$$\Sigma(f) < +\infty$$
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  $\xrightarrow{\log(k)} \frac{\log(k)}{\kappa} \frac{\log(k)^{-\alpha}}{\log(k)^{\frac{1}{2}}} \sum_{k} \Sigma(f) = +\infty$ 

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 Set of entropies,  $f$ -block gluing decidable subshifts 
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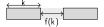
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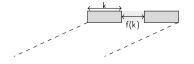
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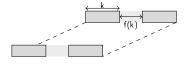
f-block gluing:  $N_k(X)^2 \leq N_{2k+f(k)}(X) \leq |\mathcal{A}|^{f(k)} \cdot N_{2k}(X)$ 

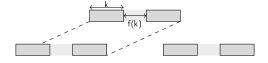


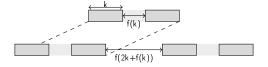
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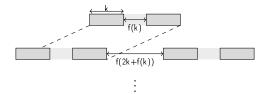
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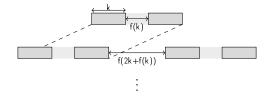






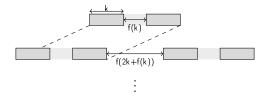






$$\frac{\log(N_k(X))}{k} - |\mathcal{A}| \cdot \sum_{l=1}^{+\infty} \frac{f(2^l)}{2^l} \le h \le \frac{\log(N_k(X))}{k}$$

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Since X is decidable,  $k \mapsto N_k(X)$  is computable, hence h is computable.

Known: obstruction  $\rightarrow$  let us prove realization

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Bounded density shifts.

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Bounded density shifts. Consider  $(p_k)_k \in \mathbb{N}^{\mathbb{N}}$  non-decreasing and computable.

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$$\boxed{0 | 1 | 0 | 1 | 1 | 0 | 0 | 1}$$

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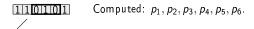
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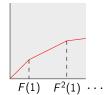
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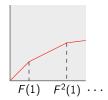
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$$\in \mathcal{L}(X_{\mathcal{F}})$$

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f-block gluing  $\Leftrightarrow \forall n, \ p_{F(n)} \geq 2p_n + 4$ 

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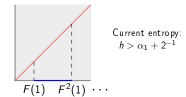
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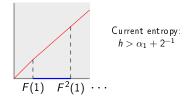
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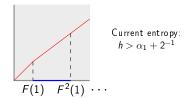
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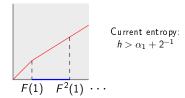
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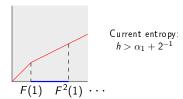
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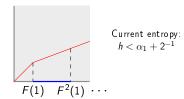
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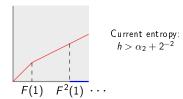
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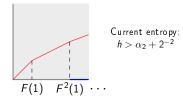
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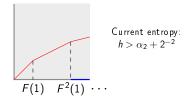
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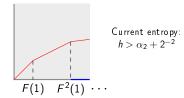
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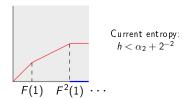
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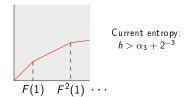
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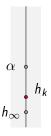


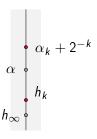
Entropy change:  $\beta = (\beta_1, \beta_2, ..)$  slopes:

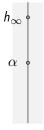
$$\beta' \ 0 \geq \Delta h \geq -H(1/F^N(1))$$

$$H(\epsilon) = \epsilon \log(\epsilon) + (1 - \epsilon) \log(1 - \epsilon)$$
(by bounding preimages of a transformation)

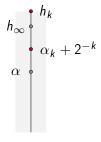




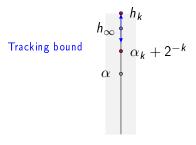






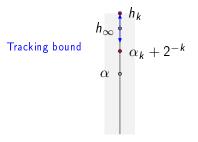


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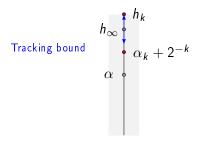
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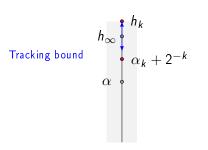
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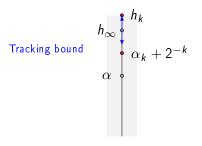
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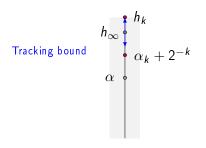


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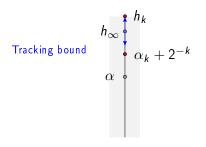


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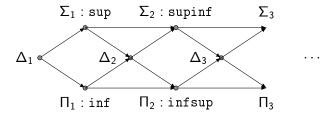
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#### Questions:

- 1. What happens when  $\Sigma(f)$  is not computable ?
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- 3. For other classes of dynamical systems ? [ $\rightarrow$  better understanding of the threshold phenomenon]

### Computability in general:

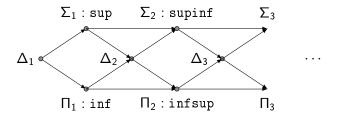
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Theorem: for all m,  $\Sigma_m \subsetneq \Delta_{m+1}$ ,  $\Pi_m \subsetneq \Delta_{m+1}$ ,  $\Delta_m \subsetneq \Sigma_m$ ,  $\Delta_m \subsetneq \Pi_m$ .

### General metric dynamics:

**Question**: Classification of classes of dynamical systems according to possible values of entropy ?

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### General metric dynamics:

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If in the arithmetical hierarchy, possible classes are:  $\Delta_1$ ,  $\Sigma_1$ ,  $\Pi_1$ ,  $\Delta_2$ ,  $\Sigma_2$ .

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**Definition:** A function  $f: X \to X$  is **computable** when there exists an algorithm which on input m enumerates  $I_m \subset \mathbb{N}$  such that

$$f^{-1}(B_m) = \bigcup_i B_n,$$

**Lemma**: a function  $\mathcal{A}^{\mathbb{N}} \to \mathcal{A}^{\mathbb{N}}$  is computable when there exists a non-decreasing computable function  $\varphi : \mathbb{N} \to \mathbb{N}$  and an algorithm which provided as input the  $\varphi(n)$  first elements of some  $x \in \mathcal{A}^{\mathbb{N}}$  outputs the n first elements of f(x).

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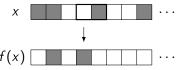
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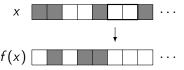
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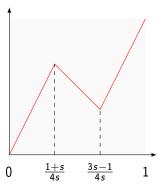
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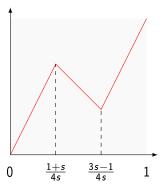
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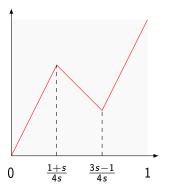
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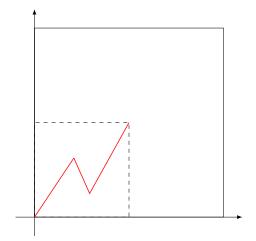
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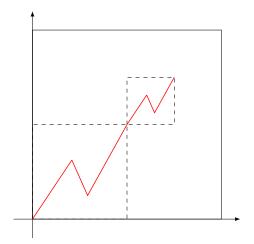
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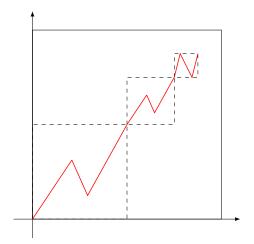


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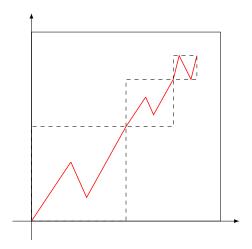
Thus for all  $s \in \mathbb{Q}$ , the entropy of  $([0,1], f_s)$  is s.







For  $s \in \Sigma_1$ :  $s = \sup_n s_n$ :



Computable map, entropy s.

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- 3. Do you have other ideas of classes of systems and dynamical constraints ?