DSC40B: Theoretical Foundations of Data Science II

Lecture 6: *Sorting, and more on recurrences*

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Previously

- Binary search operation in an array
 - Require that the array is already sorted!
- Today: the sorting problem
 - Input: given an arbitrary array of numbers
 - Output: convert them into an array where all elements are either in non-decreasing or non-increasing order.
 - from now on, unless otherwise specified, in this class, we will assume a sorted array is in non-decreasing order.



Motivation

- There are many reasons why we want to solve the sorting problem
 - Given a list of tasks with different priority values, the CPU may want to process them in decreasing order of priority
 - Sorting can also make other problems easy
 - ▶ E.g, the search problem discussed last lecture,
 - or more generally, range search in multidimensional databases etc.
- But we will just focus on the simplest version
 - where the input is just a list of real numbers stored in an array.



Part A:

- (1) A simple sorting algorithm: Selection sort
- (2) Correctness of algorithm via loop invariants

A simple idea

Start with input array:

- At each iteration, identify the smallest number in the remainder unsorted portion of the array
- Put it at the end of the already-sorted portion
- Iterate till the end

Example:

Input array A = [12, 4, -1, 9, 10]

- ▶ How to implement this idea using an algorithm
 - in-place selection sort
 - meaning that it will only operate on the same array
 - separate "good" / "bad" part of the array by a barrier-id
- ▶ How to prove the correctness of the algorithm
- Time complexity



Algorithm selection_sort

```
def selection_sort(A):
   n = len(A)
   if n <= 1:
       return
   for barrier_id in range(n-1):
       # find index of min in A[start:]
       min id = find_minimum(A, start=barrier_id)
       #swap
       A[barrier_id], A[min_id] = (
               A[min id], A[barrier id]
```



Subroutine find_minimum

```
def find_minimum(A, start):
"""Finds index of minimum from [start, len(A)). Assumes non-empty."""
    n = len(A)
     min_value = A[start]
     min_id = start
    for i in range(start + 1, n):
        if A[i] < min_value:</pre>
             min_value = A[i]
             min_id = i
     return min_id
```

Note that instead of using this sub-routine, selection_sort can be written by using a nested loop.

Correctness

- How to convince us that this algorithm is correct?
 - Using loop invariants
 - ▶ Similar to the inductive idea mentioned earlier
 - A loop invariant is a statement that holds at the end of each iteration
 - to show that it holds for each iteration, we first show it holds for the base case
 - then we argue that if it holds at the end of (i-1)-th iteration, which is the beginning of the i-th iteration, then it will also hold at the end of i-th iteration.
 - Using appropriate loop invariants, we can then argue the algorithm is correct after all iterations.



Algorithm selection_sort

```
def selection_sort(A):
   n = len(A)
   if n <= 1:
       return
   for barrier_id in range(n-1):
       # find index of min in A[start:]
       min id = find_minimum(A, start=barrier_id)
       #swap
       A[barrier_id], A[min_id] = (
               A[min id], A[barrier id]
```



Loop invariants for selection_sort

- ▶ Loop invariant: after k iterations,
 - The first k numbers in A are sorted, and are smaller than all the remainder n-k numbers.
 - $k = \text{barrier_id} + 1 \text{ in the code}$
- If this statement holds for any k, then after k=n-1 iterations, we will get a sorted array
 - ▶ as by the loop invariant, the first n-1 numbers are sorted, and the last one is the largest, meaning that all n numbers are sorted.



Base case:

k = 0: loop invariant holds trivially

Inductive step:

- if it holds for k-1
- then, we identify the smallest from the remainder n-k+1 numbers, which must be the k -th smallest of the original array
- \blacktriangleright so after this k -th iteration, the loop invariant holds for k.

▶ Thus the algorithm is correct in the end

 \blacktriangleright i.e., it returns sorted array after n-1 iterations.

Time complexity

Essentially nested for loops

$$T(n) = cn + c(n-1) + c(n-2) + \dots c \cdot 1$$

= $\Theta(n^2)$



Part B: A more efficient sorting algorithm: Merge sort

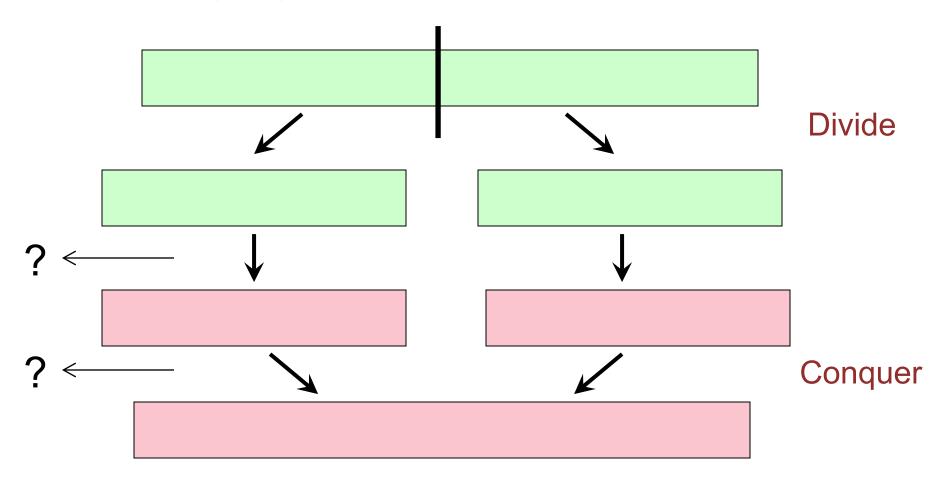
MergeSort

- ▶ A faster sorting algorithm
 - has the optimal worst-case time complexity under the so-called comparison model.
- Use an idea called
 - b divide-and-conquer to solve problems, which naturally leads to recursive algorithms.



Merge sort

Use divide-and-conquer paradigm





Pseudo-code

```
MergeSort ( A, l, r )

if (l \ge r) return;

mid = \lfloor (l+r)/2 \rfloor;

LeftA = MergeSort ( A, l, mid );

RightA = MergeSort ( A, mid+1, r );

B = Merge (LeftA, RightA);

return B;
```

Use recursive calls!

This is NOT in-place sorting!

- MergeSort (A, ℓ, r) sorts the subarray $A[\ell, r]$
- \blacktriangleright Input: an array A of length n
- Output: a new sorted array
- ▶ Call: MergeSort(A, 0, n-1)



Correctness

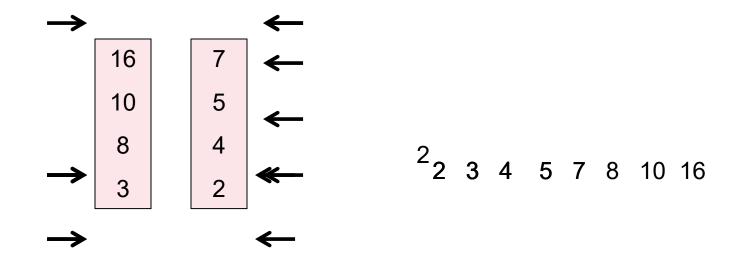
- ▶ Recall for a recursive algorithm:
 - ▶ (1) Make sure algorithm works in the base case.
 - (2) Check that all recursive calls are on smaller problems, and that it terminates
 - (3) Assuming that the recursive calls work, does the whole algorithm work?



- ► (I) Base case:
 - Portion of array to be inspected is of size at most 1
 - Obviously already sorted!
- ▶ (2) Work on smaller subproblems? Terminate?
 - Yes
- (3) If recursive calls return correct output, does the entire algorithm works?
 - Yes, as long as Merge (B, C) is correct.

Conquer: Merge(B, C)

- Input: Given two sorted arrays B and C
- Output: Merge into a single sorted array





Pseudo-code

```
Merge (B, C)
    n_b = len(B); n_c = len(C); n_o = n_b + n_c;
    init (outA, n_o); //initialize outA to be an array of size n_o
    id_{b} = 0; id_{c} = 0;
    for (i = 0; i < n_o; i + +) {
        if (B[id_b] > C[id_c]) or (id_b \ge n_b)
                outA[i] = C[id_c];
                id_c + +;
        else
                outA[i] = B[id_h];
                id_h + +;
     return outA;
```

Time complexity analysis

- First: worst case time complexity for Merge(B, C)
 - Let $n_b = len(B)$; $n_c = len(C)$
 - ▶ Then the time $T_{merge(B,C)} = \Theta(n_b + n_c)$

Pseudo-code

```
MergeSort ( A, l, r )

if (l \ge r) return;

mid = \lfloor (l + r) / 2 \rfloor;

LeftA = MergeSort ( A, l, mid );

RightA = MergeSort ( A, mid+1, r );

B = Merge (LeftA, RightA);

return B;
```

- ightharpoonup T(n):
 - lacktriangle the worst case time complexity of MergeSort performed on a subarray of size n
- $T(n) = T\left(\frac{n}{2}\right) + T\left(\frac{n}{2}\right) + cn = 2T\left(\frac{n}{2}\right) + cn$



Solving Recurrence relations

$$T(n) = 2T\left(\frac{n}{2}\right) + cn$$



Solving Recurrence

- One way is via the following strategy:
 - I."Unroll" several times to find a pattern.
 - ▶ 2. Write general formula for *k*th unroll.
 - > 3. Solve for # of unrolls needed to reach base case.
 - ▶ 4. Plug this number into general formula.



Solving Recurrence relations

$$T(n) = 2T\left(\frac{n}{2}\right) + cn$$

$$= 2\left(2T\left(\frac{n}{4}\right) + \frac{cn}{2}\right) + cn = 4T\left(\frac{n}{4}\right) + 2cn$$

$$= 4\left(2T\left(\frac{n}{8}\right) + \frac{cn}{4}\right) + 2cn = 8T\left(\frac{n}{8}\right) + 3cn$$

$$\dots = 2^k T\left(\frac{n}{2^k}\right) + kcn$$
Terminates when $\frac{n}{2^k} = 1 \Rightarrow 2^k = n \Rightarrow k = \log_2 n$
Thus: $T(n) = 2^k T\left(\frac{n}{2^k}\right) + kcn = n T(1) + cn \log_2 n$

$$= \Theta(n \lg n)$$



Sorting problem

- ▶ The sorting problem can be solved in $\Theta(n \lg n)$ worst-case time.
- It has the optimal asymptotic time complexity
 - if we assume the so-called comparison model.
 - So under the comparison model, we cannot have an asymptotically faster algorithm than the merge sort.
- ▶ This algorithm is not in-place.
 - in practice, quicksort tends to be rather popular



Part C: Three-way MergeSort, and more on solving recurrences

Another MergeSort

```
MergeSort ( A, l, r ) // sorting subarray A[\ell, r] if (l \ge r) return; m_l = l + (r - l) / 3; m_2 = l + 2(r - l) / 3; AI = MergeSort ( <math>A, l, m_l ); A2 = MergeSort ( <math>A, m_l + 1, m_2 ); A3 = MergeSort ( <math>A, m_2 + 1, r ); Merge (AI, A2, A3);
```

▶ Recurrence relation for MergeSort(A, ℓ , r) when $r - \ell + 1 = n$

$$T(n) = 3T(\frac{n}{3}) + cn$$



Solving recurrence

$$T(n) = 3T(\frac{n}{3}) + cn$$



Another example

$$T(n) = T(\frac{n}{3}) + cn$$



Part D: The Movie problem revisited

Recall

▶ The Movie problem

- Input: Given a list of length of movies available, stored in array movies, and a flight duration D
- ▶ Output: Return two movies whose total length = D; None otherwise.



Previously,

• we gave an algorithm with worst-case time complexity $\Theta(n^2)$

Can we do better?

Yes, if we first sort the input array of movie times.

Example:

- Flight time: 170
- Movie times (sorted): 60, 80, 95, 110, 130

Code

```
def optimize_entertainment(times, target):
    n = len(times)
    MergeSort(times, 0, n-1)
    shortest = 0
    longest = n - 1
    for i in range(n - 1):
         total_time = times[shortest] + times[longest]
         if total_time == target:
              return (shortest, longest)
         elif total_time < target:
              shortest += 1
         else: # total_time > target
              longest -= 1
    return None
```

Worst-case time complexity: $T(n) = \Theta(n \lg n) + \Theta(n)$ $= \Theta(n \lg n)$

Take-home messages

- Sorting can be done in $\Theta(n \lg n)$ time
- More examples on solving recurrences
- Using sorted structures can sometimes help solve other problems more efficiently
 - e.g, binary search, and the movie problems.



FIN

