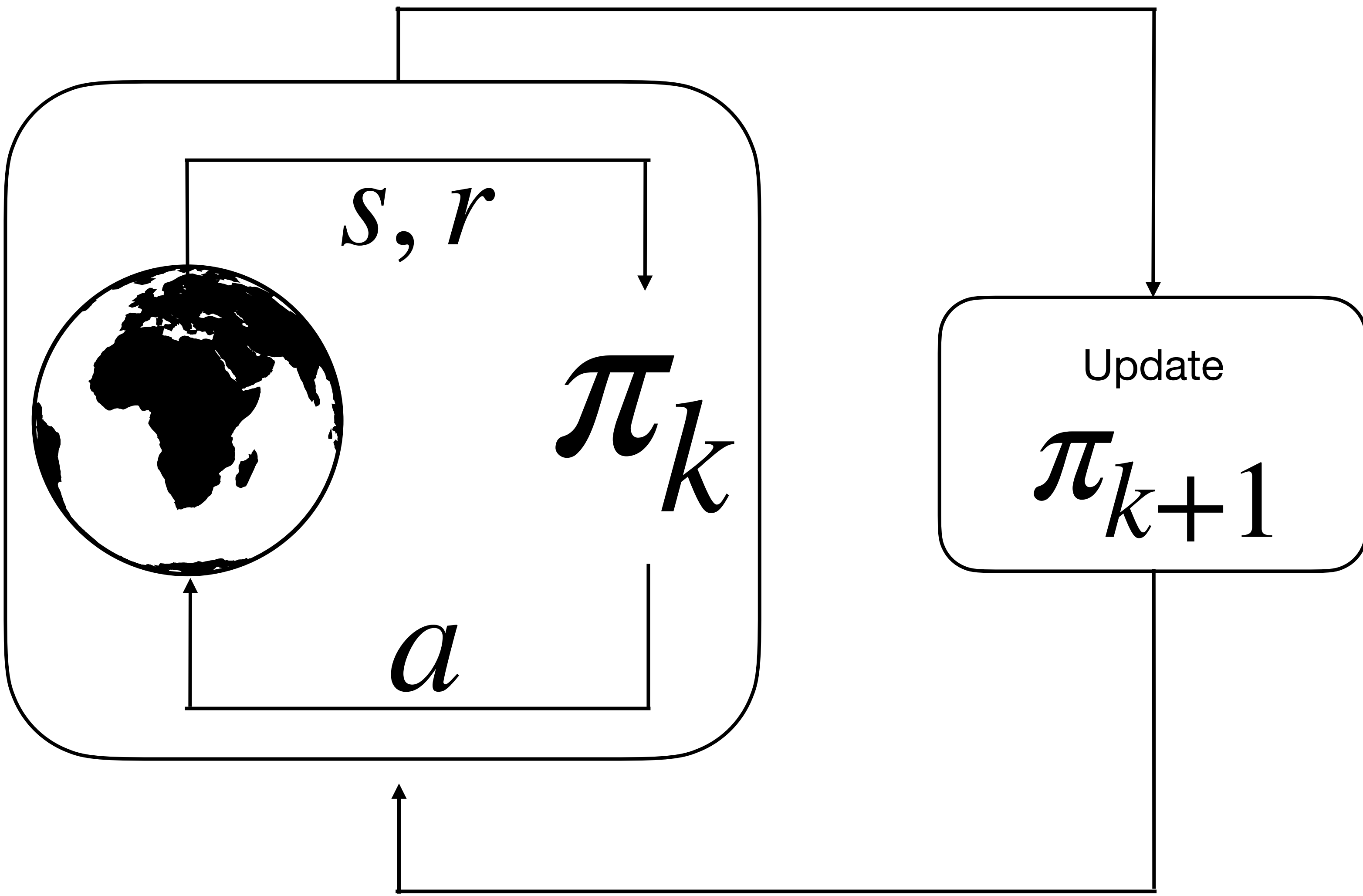
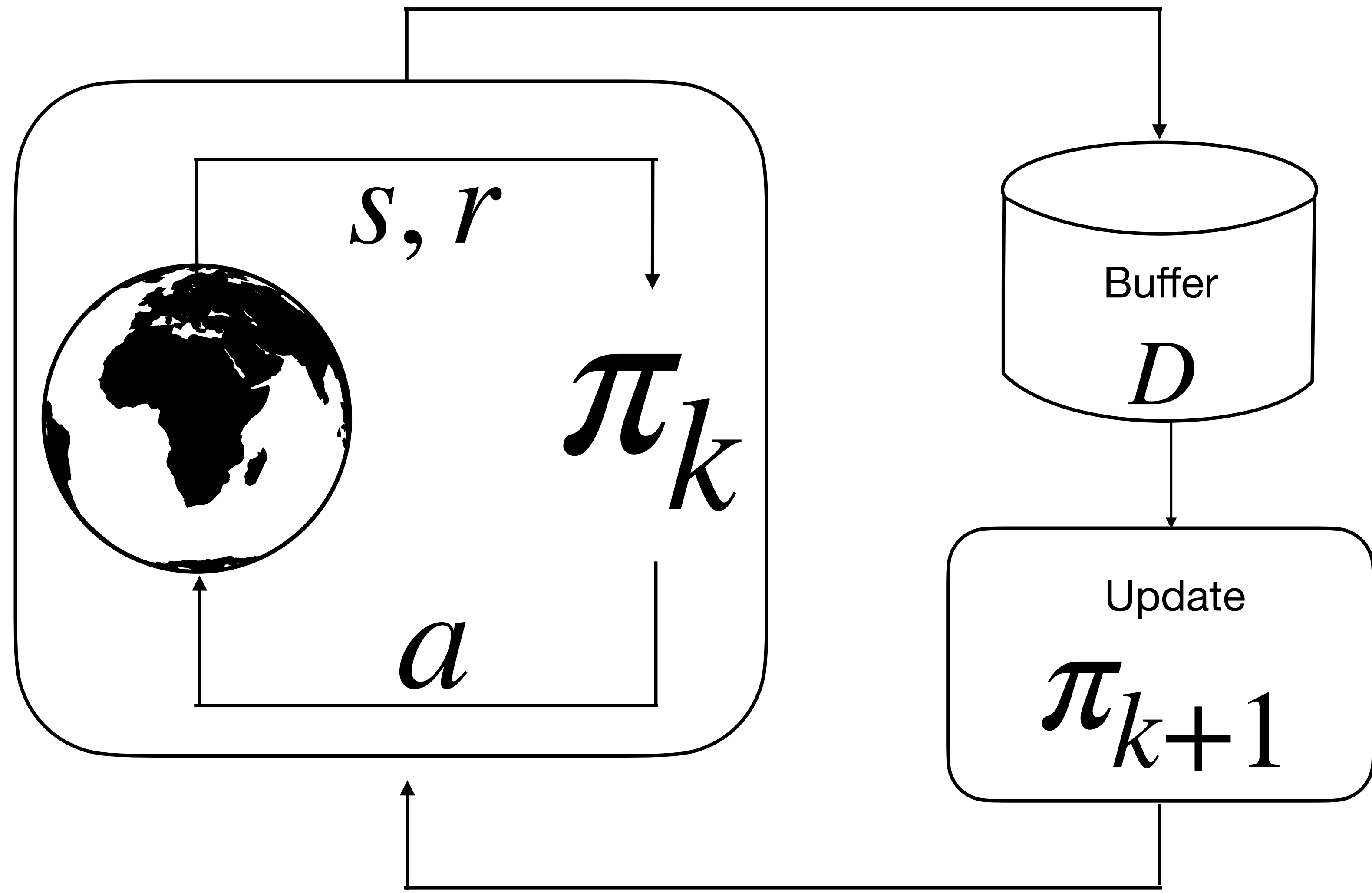


Rollout data $\{(s_i, a_i, s'_i, r_i)\}$



π_{k+1}

Rollout data $\{(s_i, a_i, s'_i, r_i)\}$



π_{k+1}