

# Lecture 16

## Stochastic Process & Markov Chain

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STAT 330 - Iowa State University

# Stochastic Process

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## Definitions

A *stochastic process* is a random variable that also depends on time. It is written as

$$X_t(\omega) = X(t, \omega) \text{ for } t \in \mathcal{T}, \omega \in \Omega$$

where  $\mathcal{T}$  is a set of possible times. e.g.  $[0, \infty), \{0, 1, 2, \dots\}$  and  $\Omega$  is the whole sample space.

- $X_t = X_t(\omega)$  is the random variable
- $t$  is time
- $\omega$  is the “state”
- The *state space* is the collection of values the R.V  $X_t$  can take on:  $\cup_{t \in \mathcal{T}} \text{Im}(X_t)$

# Types of Stochastic Processes

Types of Stochastic Processes:  $X_t(\omega)$  can be

- Continuous-time ( $t$ ) continuous-state ( $\omega$ )
- Discrete-time ( $t$ ) continuous-state ( $\omega$ )
- Continuous-time ( $t$ ), discrete-state ( $\omega$ )
- Discrete-time ( $t$ ), discrete-state ( $\omega$ )

# Types of Stochastic Processes

## Examples:

1. Let  $X_t$  be the result of tossing a fair coin ( $0 = \text{tails}$ ,  $1 = \text{heads}$ ) in the  $t^{\text{th}}$  trial.
  - The time (trial)  $t \in \mathcal{T}$  where  $\mathcal{T} = \{1, 2, 3, \dots\}$
  - $\text{Im}(X_t) = \{0, 1\}$
  - This is an example of \_\_\_\_\_ time, \_\_\_\_\_ state stochastic process.
2. Let  $X_t$  be the number of customers in a store at time  $t$ .
  - The time  $t \in \mathcal{T}$  where  $\mathcal{T} = (0, \infty)$
  - $\text{Im}(X_t) = \{0, 1, 2, 3, \dots\}$
  - This is an example of \_\_\_\_\_ time, \_\_\_\_\_ state stochastic process.

# Markov Chain

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# Markov Chain (MC) and Markov Property

## Markov Property

A stochastic process  $X_t$  satisfies the *Markov property* if for any  $t_1 < t_2 < \dots < t_n < t$  and any sets  $A; A_1, \dots, A_n$ :

$$P\{X_t \in A \mid X_{t_1} \in A_1, \dots, X_{t_n} \in A_n\} = P\{X_t \in A \mid X_{t_n} \in A_n\}.$$

- The probability distribution of  $X_t$  at time  $t$  only depends on its previous state.
- If the above is satisfied, then  $X_t$  is called a *Markov Chain*.

# Markov Property Examples

1. A (fair) coin is flipped over and over: If coin lands on “heads”, you win \$1. If coin lands on “tails”, you lose \$1. Let  $X_t$  be your profit after  $t$  flips.
  - $P(X_5 = 3 | X_4 = 2) =$
  - $P(X_5 = 3 | X_4 = 2, X_3 = 1, X_2 = 2, X_1 = 1) =$
2. An urn contains 2 red balls, and 1 green ball. A ball is drawn (without replacement) from the urn yesterday and today. Another ball will be drawn tomorrow. Suppose you drew a red ball yesterday, and a red ball today.
  - $P(\text{Red tomorrow} | \text{Red today}) =$
  - $P(\text{Red tomorrow} | \text{Red today, Red yesterday}) =$



## Discrete-Time Discrete-State MC

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# Discrete-Time Discrete-State Markov Chain (MC)

Suppose we have a Markov chain with time set  $\mathcal{T} = \{0, 1, 2, \dots\}$  and state space  $\{0, 1, 2, \dots\}$ . Two things we need to know about  $X_t$ :

1. **Initial distribution ( $P_0$ ):**  $P_0(x) = P(X_0 = x)$  usually given as a vector of probabilities for the initial states of  $X_t$ .

Ex: State space =  $\{0, 1, 2\}$ ;  $P_0 = \{0.3, 0.4, 0.3\}$

2. **Transition probabilities:**

**1-step** transition probability: probability of moving from state  $i$  to state  $j$  in 1 step.

$$p_{ij} = P(X_{t+1} = j | X_t = i)$$

**$h$ -step** transition probability: probability of moving from state  $i$  to state  $j$  in  $h$  steps.

$$p_{ij}^{(h)} = P(X_{t+h} = j | X_t = i)$$

# Discrete-Time Discrete-State Markov Chain (MC)

- We assume that the Markov Chain (MC) is *homogeneous*.  
(ie) transition probabilities  $p_{ij}$  are independent of  $t$ .  
→ For all times  $t_1, t_2 \in \mathcal{T}$ ,  $p_{ij}(t_1) = p_{ij}(t_2)$ .
- Then, the distribution of a homogeneous MC is completely determined by the initial distribution ( $P_0$ ) and one-step transition probability ( $p_{ij}$ ).

**Main Idea:** Start with an initial distribution  $P_0$ . Then use the one-step transition probability  $p_{ij}$  to “jump” forward to the next step. Then, we can keep going forward one step at a time.

## Examples

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## Example

Example 1: In the summer, each day in Ames is either sunny or rainy. A sunny day is followed by another sunny day with probability 0.7, whereas a rainy day is followed by a sunny day with probability 0.4. It rains on Monday. Make weather forecasts for Tuesday and Wednesday.

Let 1 = “Sunny” and 2 = “Rainy”.

To simplify and solve these types of problems, use transition matrices and matrix multiplication.









# 1-Step Transition Probability Matrix

For a homogeneous MC with state space  $\{1, 2, \dots, n\}$ , the *1-step transition probability matrix* is:

$$P = \begin{pmatrix} p_{11} & p_{12} & \cdots & p_{1n} \\ p_{21} & p_{22} & \cdots & p_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ p_{n1} & p_{n2} & \cdots & p_{nn} \end{pmatrix}.$$

The element from the  $i$ -th row and  $j$ -th column is  $p_{ij}$ , which is the transition probability from state  $i$  to state  $j$ .

## h-Step Transition Probability Matrix

Similarly, one can define a  $h$ -step transition probability matrix

$$P^{(h)} = \begin{pmatrix} p_{11}^{(h)} & p_{12}^{(h)} & \cdots & p_{1n}^{(h)} \\ p_{21}^{(h)} & p_{22}^{(h)} & \cdots & p_{2n}^{(h)} \\ \vdots & \vdots & \ddots & \vdots \\ p_{n1}^{(h)} & p_{n2}^{(h)} & \cdots & p_{nn}^{(h)} \end{pmatrix}.$$

Using the matrix notation the following results follow:

- 2-step transition matrix  $P^{(2)} = P \cdot P = P^2$
- $h$ -step transition matrix  $P^{(h)} = P^h$
- The initial distribution of  $X_0$  is written as row vector  $P_0$ .  
The distribution of  $X_h$  ( $h$ -steps in the future) is  $P_h = P_0 P^h$

## Example

Back to Example 1: We can solve the problem much more easily by using transition matrices . . . .

$$P = \begin{pmatrix} 0.7 & 0.3 \\ 0.4 & 0.6 \end{pmatrix}$$

$$P^{(2)} = P \cdot P = \begin{pmatrix} 0.7 & 0.3 \\ 0.4 & 0.6 \end{pmatrix} \cdot \begin{pmatrix} 0.7 & 0.3 \\ 0.4 & 0.6 \end{pmatrix} = \begin{pmatrix} 0.61 & 0.39 \\ 0.52 & 0.48 \end{pmatrix}$$

$$P^{(3)} = P \cdot P \cdot P = \begin{pmatrix} 0.61 & 0.39 \\ 0.52 & 0.48 \end{pmatrix} \cdot \begin{pmatrix} 0.7 & 0.3 \\ 0.4 & 0.6 \end{pmatrix} = \begin{pmatrix} 0.583 & 0.417 \\ 0.556 & 0.444 \end{pmatrix}$$

