

4.1 Higher Order DEs- Linear Equations

Homogeneous Equations. Recall a linear n^{th} order DE has general form:

$$a_n(x) \frac{d^n y}{dx^n} + a_{n-1} \frac{d^{n-1} y}{dx^{n-1}} + \cdots + a_1(x) \frac{dy}{dx} + a_0 y = g(x) \quad (*)$$

We say this equation is homogeneous if $g(x) \equiv 0$, and non-homogeneous when $g(x) \neq 0$.

Differential Operators (Notation). Define $D := \frac{d}{dx}$

- $D(y) = dy/dx = y'$
- $D^2(y) = D(D(y)) = y''$
- $(D^2 + D)(y) = D^2 y + D y = y'' + y'$
- $(\sin x D^2 + x^2 + 1)y = (\sin x) y'' + (x^2 + 1)y$
- $(xD - \sin x)(\ln x) = x(\ln x)' - (\sin x)(\ln x) = x(\frac{1}{x}) - \sin x \ln x = 1 - (\sin x)(\ln x)$

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We can use then a more compact notation (using operator notation) to write differential equations. For instance we can write equation (*) as:

$$[a_n(x)D^n + a_{n-1}(x)D^{n-1} + \cdots + a_1(x)D + a_0(x)](y) = g(x)$$

More over we can define/call the left hand side L , thus the equation can be abbreviated as

$$L(y) = g(x).$$

Example

The equation $y'' + 5y' + 6y = 5x - 3$ can be written $L(y) = 5x - 3$

where $L = D^2 + 5D + 6$

Since differentiation is linear, so is L (a linear combination of differential operators). That is $L(\alpha f + \beta g) = \alpha L(f) + \beta L(g)$

$\left(\begin{array}{l} \alpha, \beta = \text{constants} \\ f, g = \text{functions of } x. \end{array} \right)$

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Theorem (The Superposition Principle)

Let y_1, y_2, \dots, y_k be solutions of the homogeneous equation (*) on an interval I . Then the linear combination

$$y = c_1 y_1 + c_2 y_2 + \dots + c_k y_k$$

where c_1, c_2, \dots, c_k are arbitrary constants, is also a solution on I .

Proof.

We show only second order case with $k = 2$. (Order also 2).

then $\Leftrightarrow L(y) = 0$. We assume y_1 and y_2 are solutions, that mean $L(y_1) = 0$ and $L(y_2) = 0$. Consider $c_1 y_1 + c_2 y_2$ and evaluate $L(c_1 y_1 + c_2 y_2) = c_1 L(y_1) + c_2 L(y_2) = c_1 \cdot 0 + c_2 \cdot 0 = 0$
 $\therefore c_1 y_1 + c_2 y_2$ is a solution.

Definition

A set of functions y_1, y_2, \dots, y_n is said to be linearly dependent on an interval I if there exist constants c_1, c_2, \dots, c_n (not all zero) such that:

$$c_1 y_1 + c_2 y_2 + \dots + c_n y_n = 0 \quad \text{for all } x \text{ on } I.$$

In other words we can write any y_i in terms of the other y_j 's

If no such constants exist, then y_1, y_2, \dots, y_n are linearly independent

*FACT: An n^{th} order linear DE has exactly n linearly independent (l.i.) solutions.

Example: Let $y_1 = x$ and $y_2 = x^2$, are linearly independent because

$$c_1 x + c_2 x^2 = 0 \quad \text{if and only if} \quad c_1 = c_2 = 0.$$

$$\begin{aligned} c_1 x + c_2 x^2 &= 0 \cdot x + 0 \cdot x^2 \\ \Leftrightarrow c_1 &= c_2 = 0 \end{aligned}$$

Example: (# 5 pg. 123) Let $y_1 = \sin^2 x$, $y_2 = \cos^2 x$, $y_3 = \tan^2 x$ and $y_4 = \sec^2 x$. These are linearly dependent because we

can write $c_1 (\sin^2 x) + c_2 (\cos^2 x) + c_3 (\tan^2 x) + c_4 (\sec^2 x) = 0$, with

$$c_1 = c_2 = c_3 = 1 \text{ \& } c_4 = -1 \Rightarrow \underbrace{\sin^2 x + \cos^2 x + \tan^2 x - \sec^2 x}_{= -1} = 1 - 1 = 0$$

Definition

The Wronskian of y_1, y_2, \dots, y_n is defined as

$$W(y_1, \dots, y_n) = \det \begin{pmatrix} y_1 & y_2 & \cdots & y_n \\ y_1' & y_2' & \cdots & y_n' \\ \vdots & \vdots & \ddots & \vdots \\ y_1^{(n-1)} & y_2^{(n-1)} & \cdots & y_n^{(n-1)} \end{pmatrix}$$

Recall $\det \begin{bmatrix} y_1 & y_2 \\ y_1' & y_2' \end{bmatrix} = y_1 y_2' - y_2 y_1'$

Theorem

Let y_1, y_2, \dots, y_n be n solutions of the homogeneous n^{th} order DE $(*)$ on I ($g(x) \equiv 0$). Then the set of solutions is linearly independent if and only if $W(y_1, \dots, y_n) \neq 0$ for all x on I .

Examples

1) (Ex 7. p126) The equation $y'' - 9y = 0$ has solutions $y_1 = e^{3x}, y_2 = e^{-3x}$

$$W(y_1, y_2) = \det \begin{bmatrix} e^{3x} & e^{-3x} \\ 3e^{3x} & -3e^{-3x} \end{bmatrix} = -\underbrace{3e^{3x}e^{-3x}}_{=1} - \underbrace{3e^{-3x}e^{3x}}_{=1} = -6 \neq 0 \text{ for all } x \text{ on } I$$

($I = (-\infty, \infty)$ in this problem). $\therefore y_1$ & y_2 are l.i.

2) The equation $y'' + 9y = 0$ has solution $y_1 = \sin(3x)$ and $y_2 = \cos(3x)$

($I = (-\infty, \infty)$).

$$W(y_1, y_2) = \det \begin{bmatrix} \sin 3x & \cos 3x \\ 3 \cos 3x & -3 \sin 3x \end{bmatrix} = -3 \sin^2(3x) - 3 \cos^2(3x) = -3(\sin^2(3x) + \cos^2(3x)) = -3 \neq 0 \text{ for all } x \text{ on } I.$$

$\therefore y_1 = \sin 3x$ & $y_2 = \cos 3x$ are l.i.

Definition

Any set y_1, y_2, \dots, y_n of l.i. solutions of the equation $(*)$ (homogeneous case, $g = 0$) is called a fundamental set (of solutions).

Theorem

Let $\{y_1, y_2, \dots, y_n\}$ be a fundamental set for the homogeneous equation $(*)$, then its general solution is

$$y = c_1 y_1 + c_2 y_2 + \dots + c_n y_n$$

where the c_i s are arbitrary constants.

Theorem

Let y_p be any particular solution of the non-homogeneous equation $(*)$ on I . And let $\{y_1, y_2, \dots, y_n\}$ be a fundamental set to the associated homogeneous equation. Then the general solution to $(*)$ is:

$$y = \underbrace{c_1 y_1 + c_2 y_2 + \dots + c_n y_n}_{y_c} + y_p$$

where the c_i s are arbitrary constants. We call y_c , complementary function.

Example: To solve the non-homogeneous equation $y'' + 9y = 27$, we need the solutions y_1, y_2 of $y'' + 9y = 0$. In this case $y_1 = \sin 3x, y_2 = \cos 3x$.

Also note that a particular solution is: $y_p = 3$

$$y_c = c_1 \sin 3x + c_2 \cos 3x$$

$$\Rightarrow \text{General Sol is } y = c_1 \sin 3x + c_2 \cos 3x + 3.$$

In general for $ay'' + by' + cy = g(x)$, to find a particular solution y_p by inspection, it is recommendable to look at functions resembling $g(x)$.

Theorem (Superposition principle (Non-homogeneous equations))

Let $y_{p_1}, y_{p_2}, \dots, y_{p_k}$ be k particular solutions (respectively) to

$$a_n y^{(n)} + a_{n-1} y^{(n-1)} + \dots + a_1 y' + a_0 y = g_i(x), \quad i = 1, \dots, k$$

Then $y_p = y_{p_1} + y_{p_2} + \dots + y_{p_k}$ is a solution to:

$$a_n y^{(n)} + a_{n-1} y^{(n-1)} + \dots + a_1 y' + a_0 y = g_1(x) + g_2(x) + \dots + g_k(x)$$