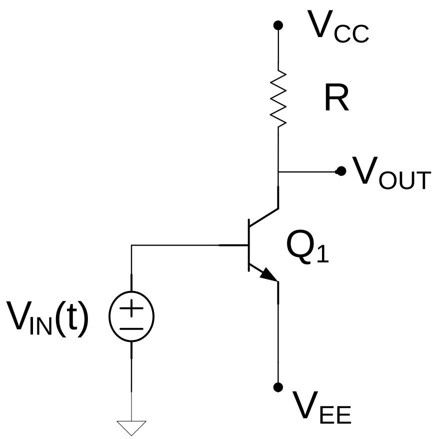
EE 330
Lecture 24

- Small Signal Analysis
- Small Signal Analysis of BJT Amplifier

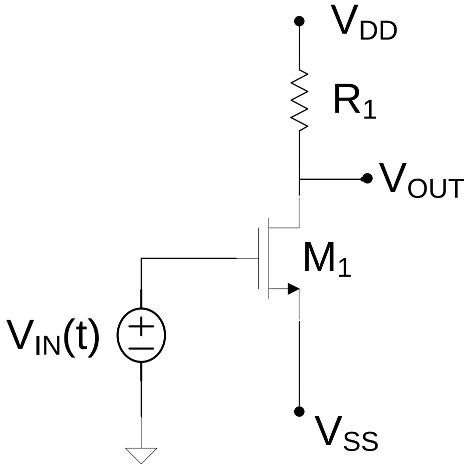
Review from Last Lecture

Comparison of Gains for MOSFET and BJT Circuits

BJT



MOSFET



$$A_{VB} = -\frac{I_{CQ}R_1}{V_t}$$

$$A_{VM} = \frac{2I_{DQ}R}{[V_{SS}+V_T]}$$

If $I_{DQ}R = I_{CQ}R_1 = 2V$, $V_{SS}+V_T = -1V$, $V_t = 25mV$

$$A_{VB} = -\frac{I_{CQ}R_1}{V_t} = -\frac{2V}{25mV} = -80$$

$$A_{VM} = \frac{2I_{DQ}R}{[V_{SS}+V_T]} = \frac{4V}{-1V} = -4$$

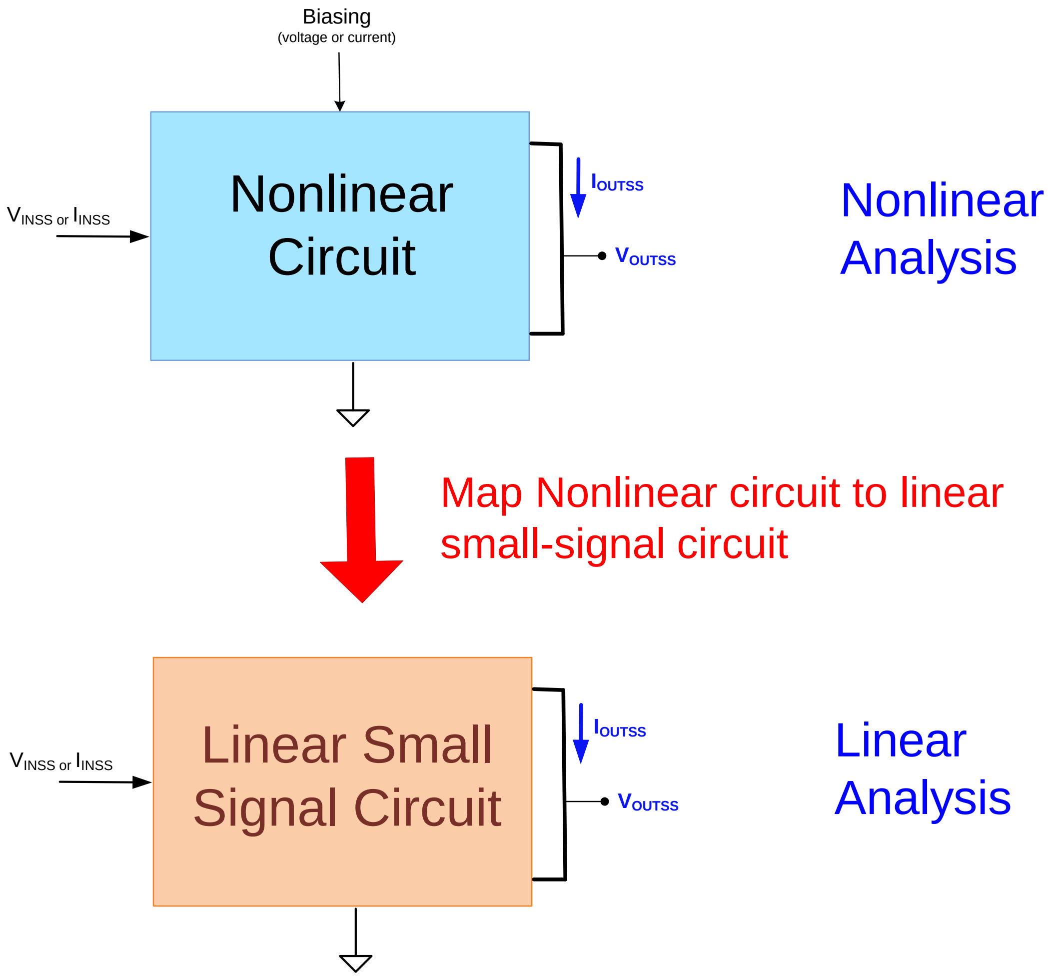
Observe $A_{VB} >> A_{VM}$

Due to exponential-law rather than square-law model

Operation with Small-Signal Inputs

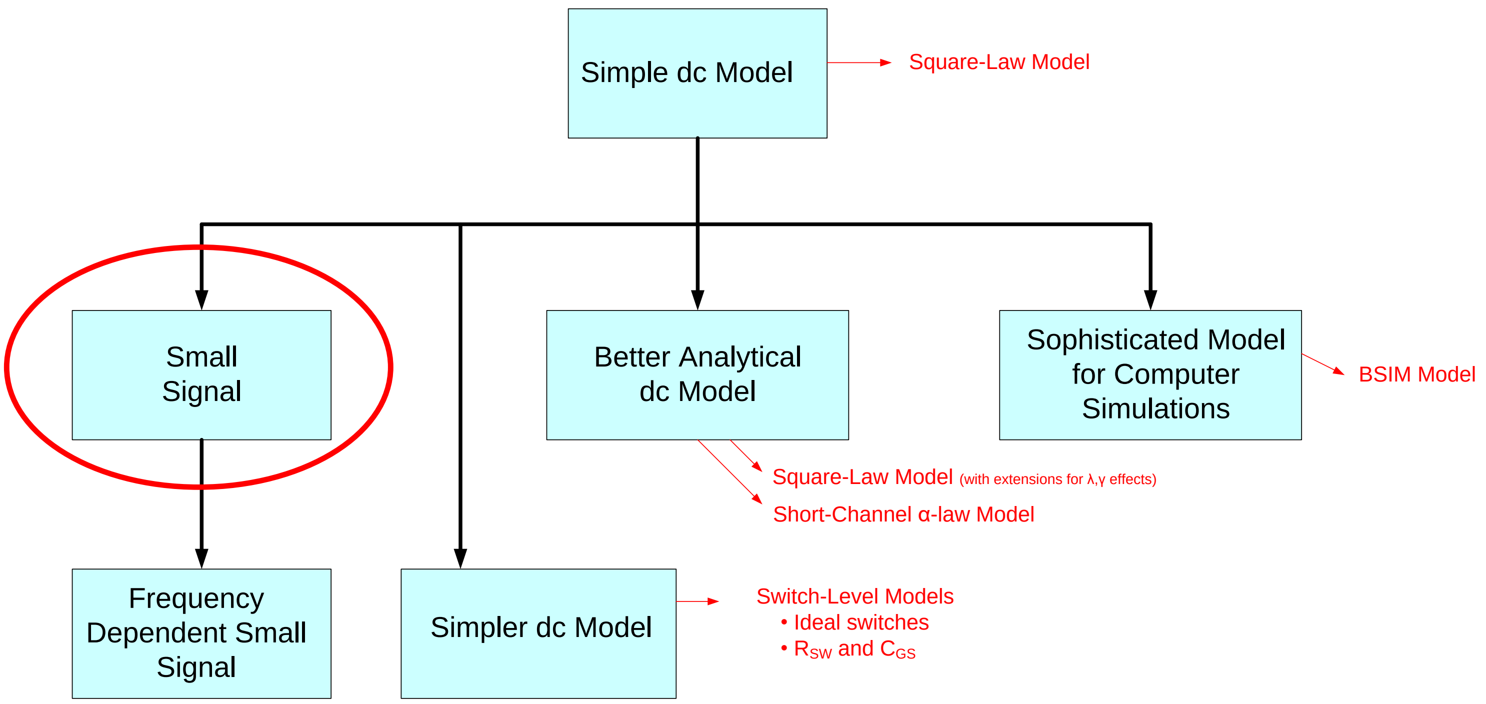
- Analysis procedure for these simple circuits was very tedious
- This approach will be unmanageable for even modestly more complicated circuits
- **Faster analysis method is needed !**

Small-Signal Analysis



- Will commit next several lectures to developing this approach
- Analysis will be MUCH simpler, faster, and provide significantly more insight
- Applicable to many fields of engineering

Small-Signal Analysis



Operation with Small-Signal Inputs

Why was this analysis so tedious?

Because of the nonlinearity in the device models

What was the key technique in the analysis that was used to obtain a simple expression for the output (and that related linearly to the input)?

$$V_{OUT} = V_{CC} - J_S A_E R_1 e^{\frac{V_{beQ}}{V_t}} e^{\frac{V_M \sin(\omega t)}{V_t}}$$

$$V_{OUT} \cong \left[V_{CC} - I_{CQ} R_1\right] - \left(\frac{I_{CQ} R_1}{V_t}\right) V_M \sin(\omega t)$$

Linearization of the nonlinear output expression at the operating point

Operation with Small-Signal Inputs

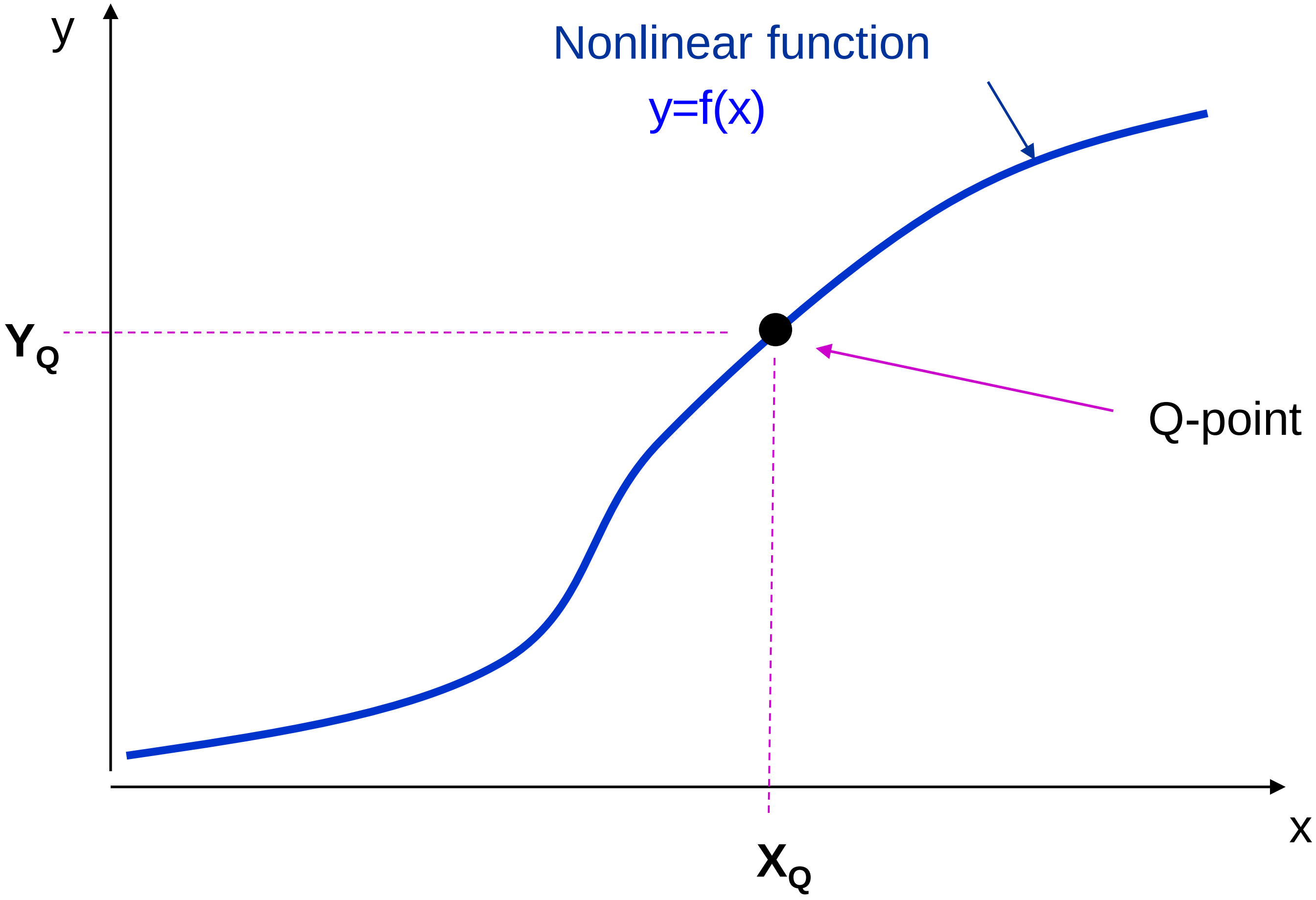
$$I_{CQ} = J_S A_E e^{\frac{V_{beQ}}{V_t}}$$

$$V_{OUT} \cong \underbrace{\boxed{\left[V_{CC} - I_{CQ} R_1\right]}}_{\textit{Quiescent Output}} - \underbrace{\boxed{\left(\frac{I_{CQ} R_1}{V_t}\right)}}_{\textit{ss Voltage Gain}} V_M \sin(\omega t)$$

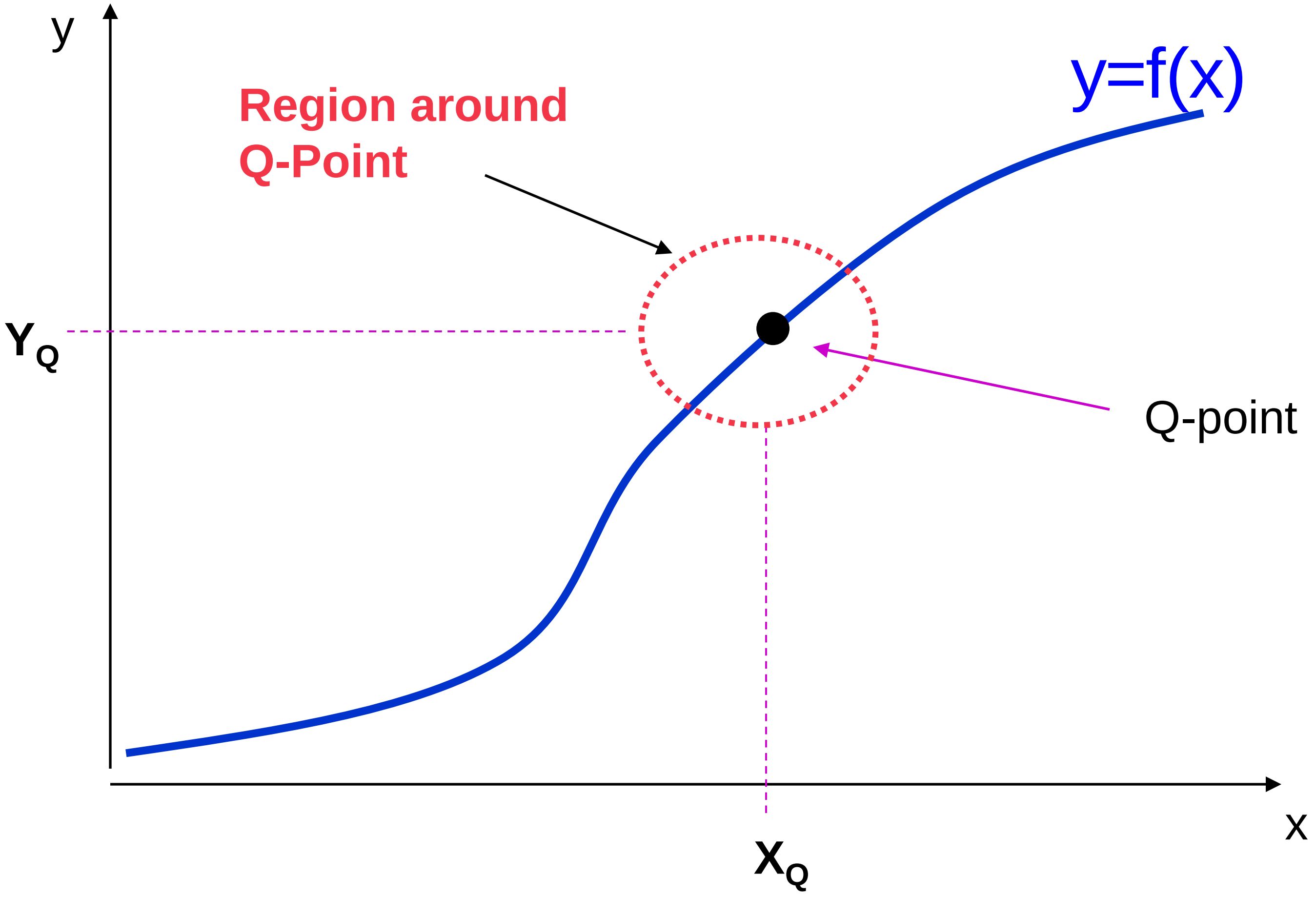
Small-signal analysis strategy

1. Obtain Quiescent Output (Q-point)
2. Linearize circuit at Q-point instead of linearize the nonlinear solution
 (this will be done by linearizing each component in the circuit)
1. Analyze linear “small-signal” circuit
2. Add quiescent and small-signal outputs to obtain good approximation
 to actual output

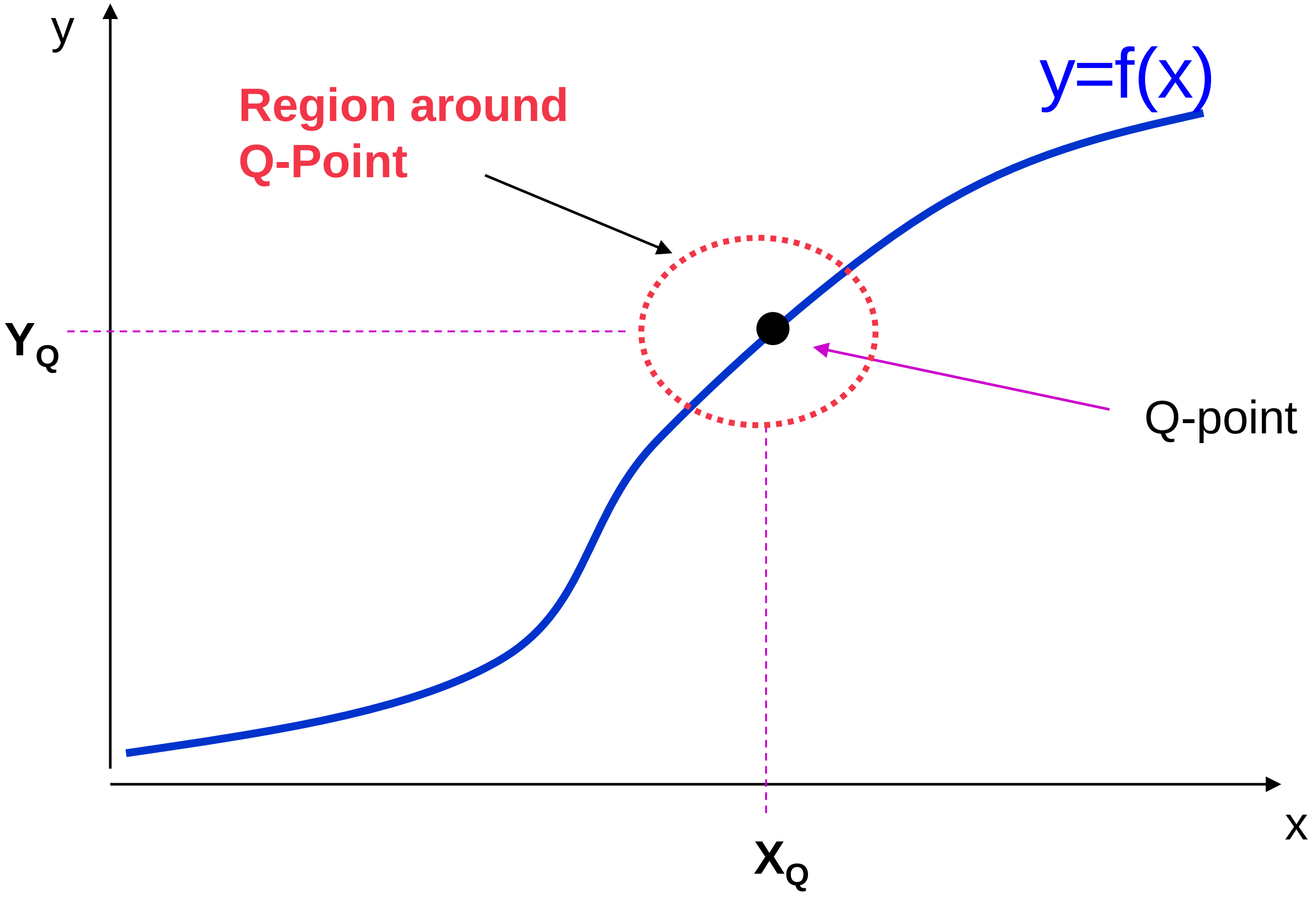
Small-Signal Principle



Small-Signal Principle

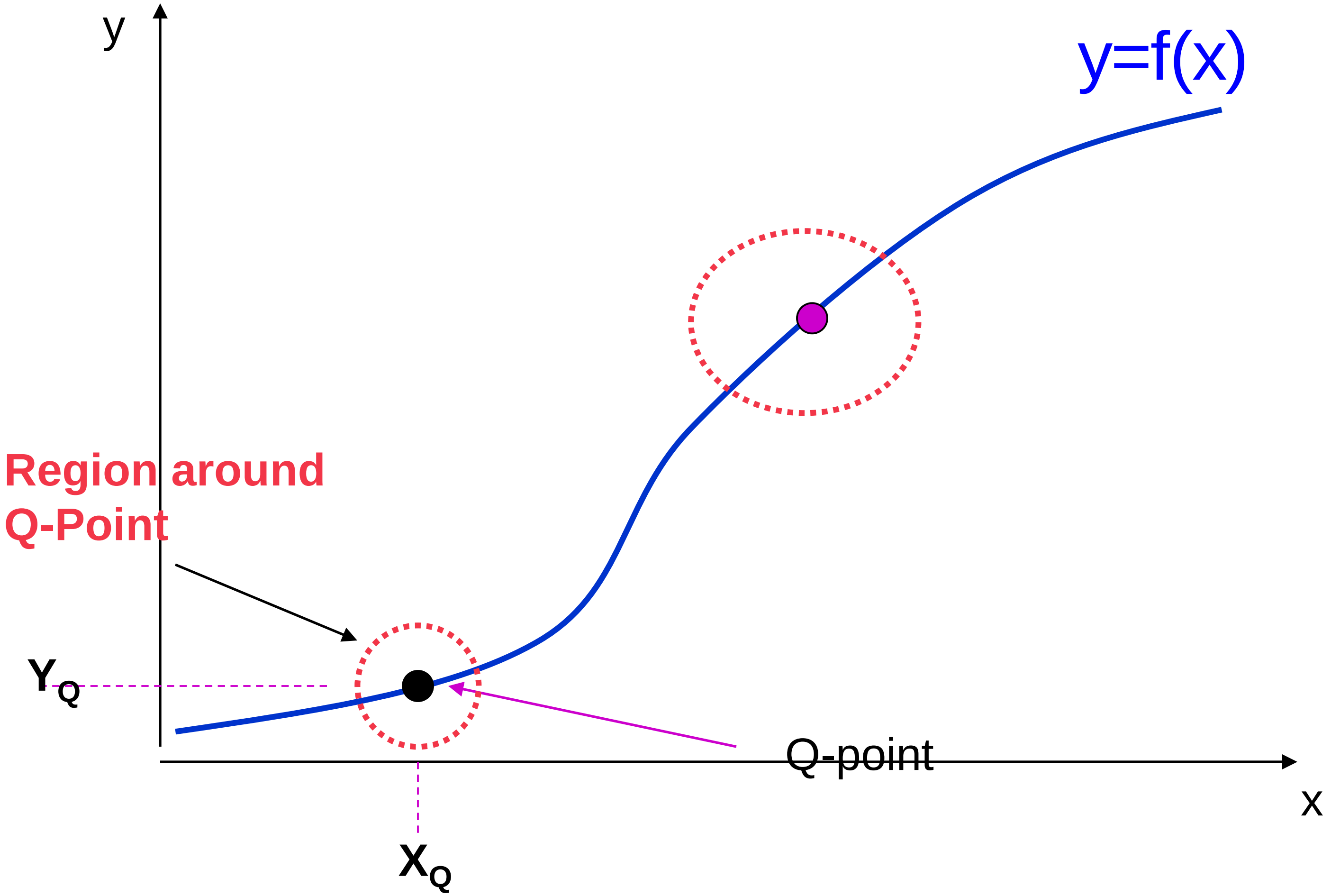


Small-Signal Principle



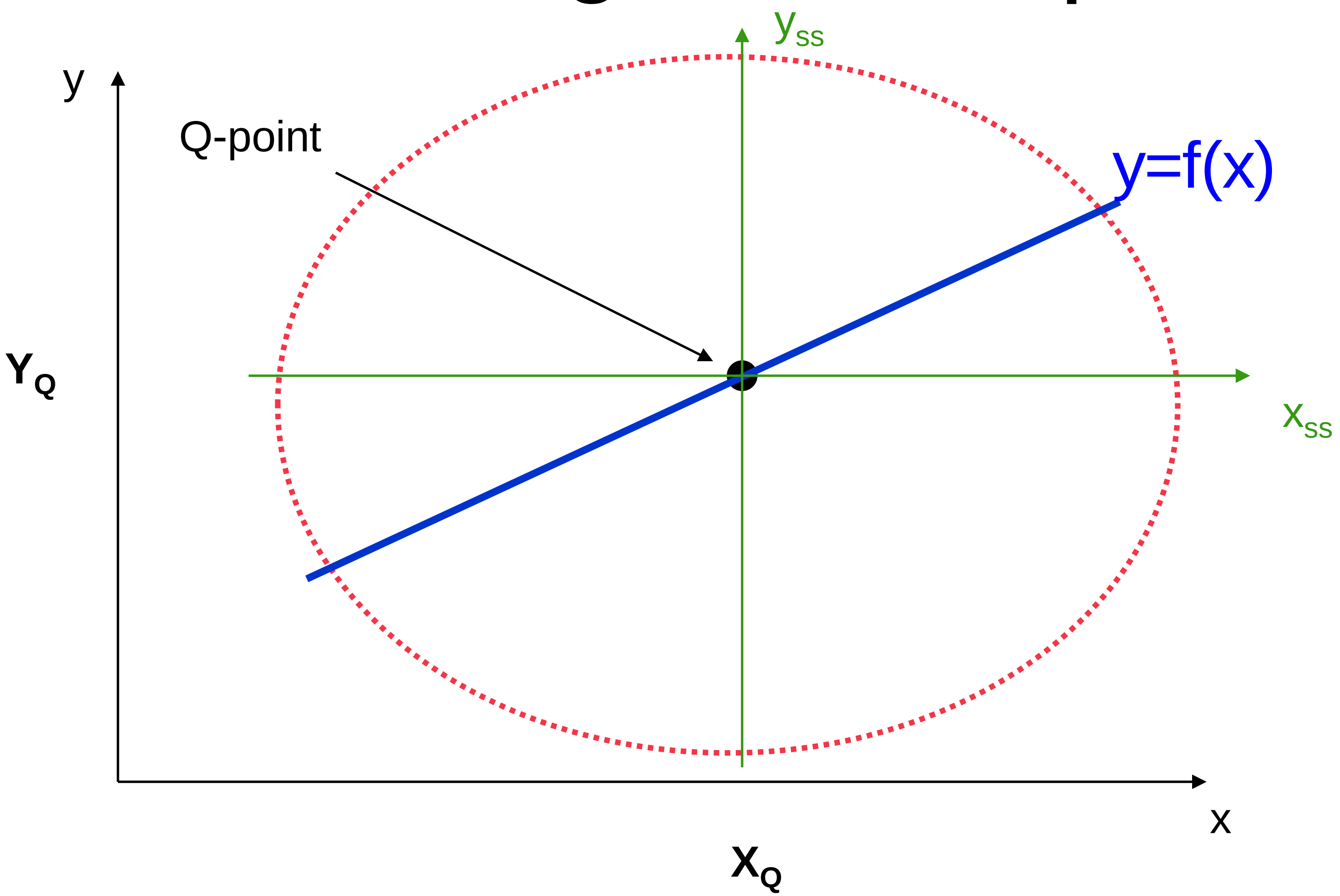
Relationship is nearly linear in a small enough region around Q-point
Region of linearity is often quite large
Linear relationship may be different for different Q-points

Small-Signal Principle



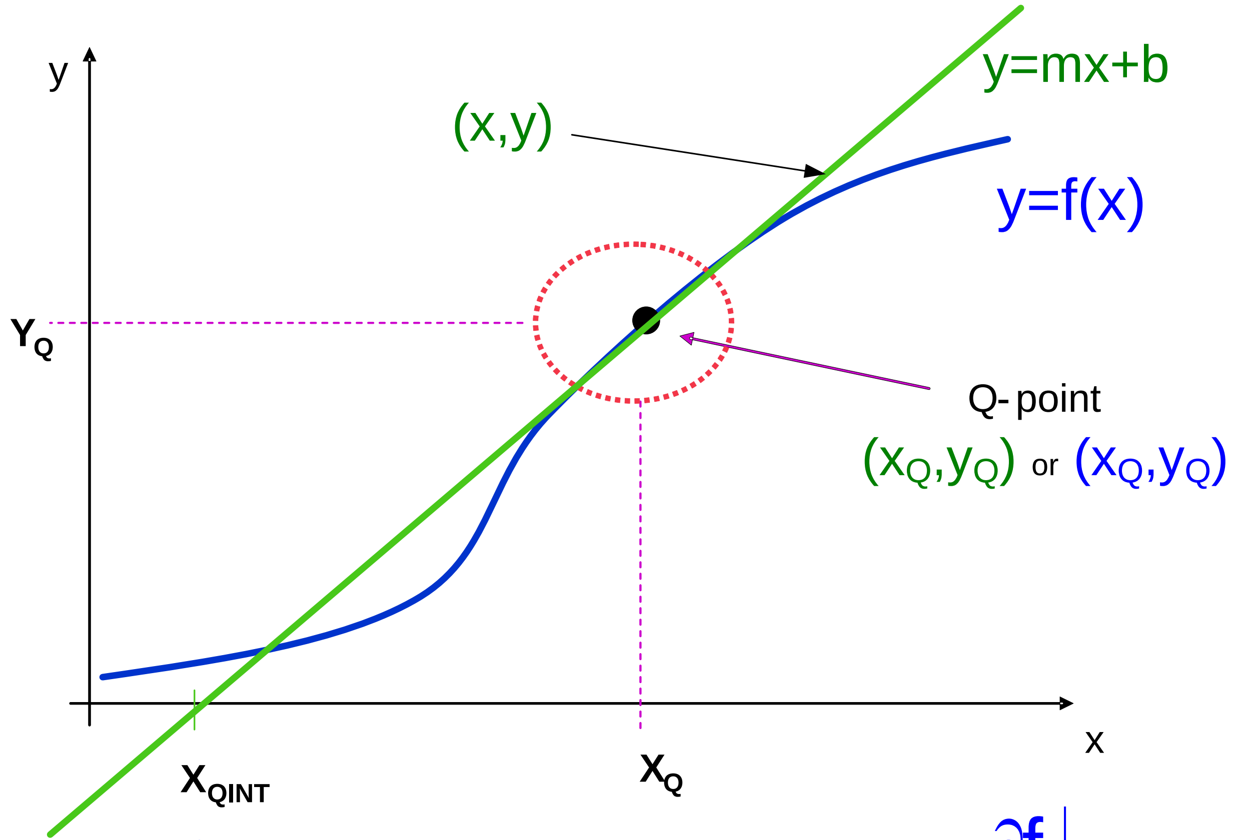
Relationship is nearly linear in a small enough region around Q-point
Region of linearity is often quite large
Linear relationship may be different for different Q-points

Small-Signal Principle



Device Behaves Linearly in Neighborhood of Q-Point
Can be characterized in terms of a small-signal coordinate system

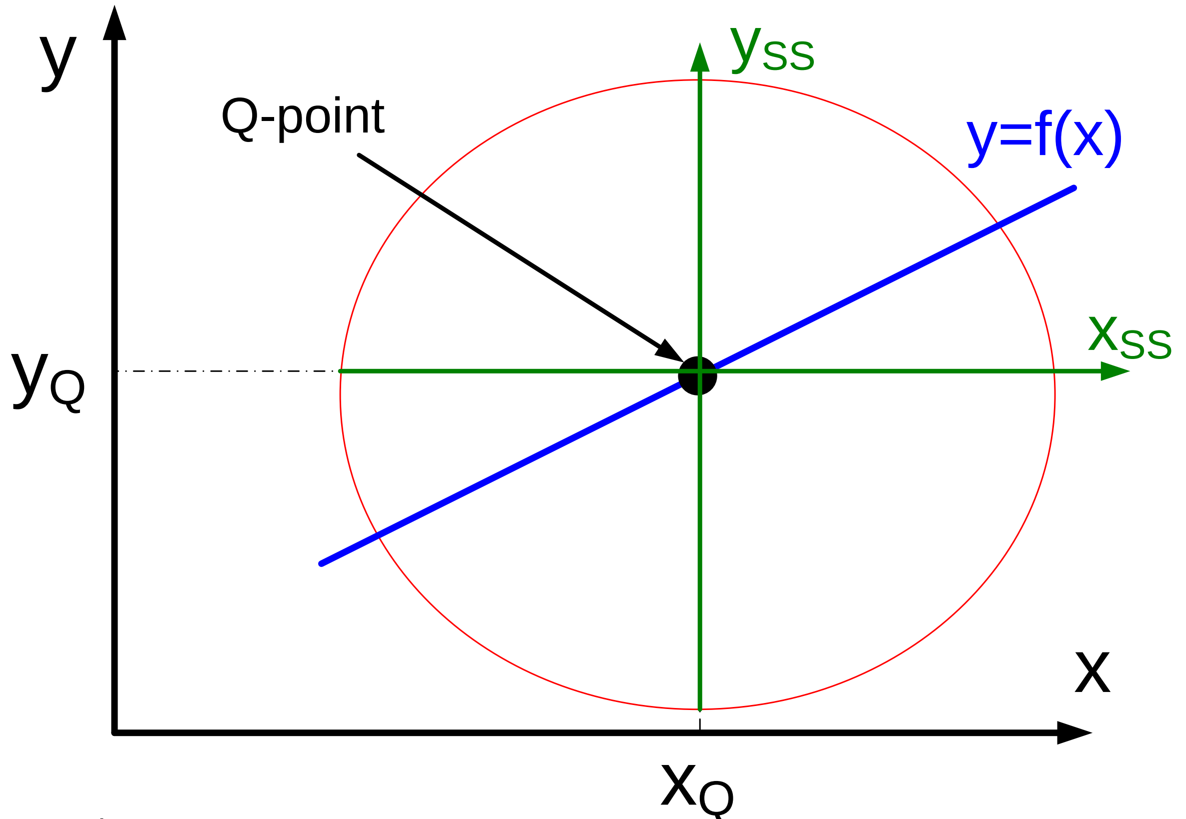
Small-Signal Principle



$$\frac{y-y_Q}{x-x_Q} = \left.\frac{\partial f}{\partial x}\right|_{x=x_Q} \quad\Rightarrow\quad y-y_Q = \left.\frac{\partial f}{\partial x}\right|_{x=x_Q}\left(x-x_Q\right)$$

$$y = \left[\left.\frac{\partial f}{\partial x}\right|_{x=x_Q}\right]x + \left[y_Q - x_Q \left.\frac{\partial f}{\partial x}\right|_{x=x_Q}\right] \qquad m = \left[\left.\frac{\partial f}{\partial x}\right|_{x=x_Q}\right] \qquad b = \left[y_Q - x_Q \left.\frac{\partial f}{\partial x}\right|_{x=x_Q}\right]$$

Small-Signal Principle



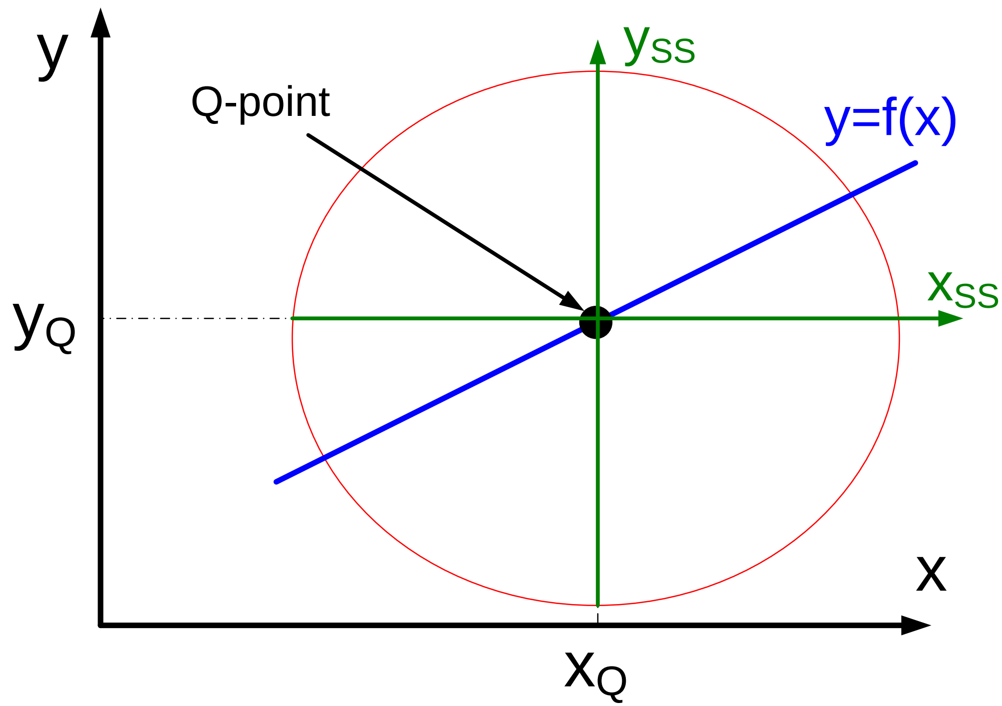
Changing coordinate systems:

$y_{SS}=y-y_Q$

$x_{SS}=x-x_Q$

$$y - y_Q = \left.\frac{\partial f}{\partial x}\right|_{x=x_Q} (x - x_Q) \longrightarrow y_{ss} = \left.\frac{\partial f}{\partial x}\right|_{x=x_Q} x_{ss}$$

Small-Signal Principle



Small-Signal Model:

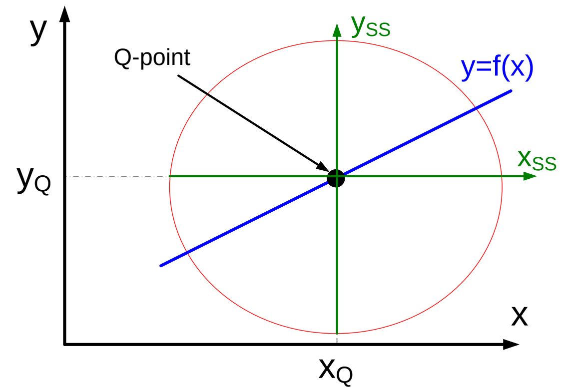
$$y_{ss} = \left.\frac{\partial f}{\partial x}\right|_{x=x_Q} x_{ss}$$

- *Linearized model for the nonlinear function y=f(x)*
- *Valid in the region of the Q-point*
- *Will show the small signal model is simply Taylor's series expansion of f(x) at the Q-point truncated after first-order terms*

Small-Signal Principle

Observe:

$$y - y_Q = \left.\frac{\partial f}{\partial x}\right|_{x=x_Q} (x - x_Q) \longrightarrow y_{ss} = \left.\frac{\partial f}{\partial x}\right|_{x=x_Q} x_{ss}$$



$$y_Q = f(x_Q)$$

$$y = f(x_Q) + \left.\frac{\partial f}{\partial x}\right|_{x=x_Q} (x - x_Q)$$

Recall Taylors Series Expansion of nonlinear function f at expansion point x_0

$$y=f(x_0)+\sum_{k=1}^{\infty}\left(\frac{1}{k!}\left.\frac{df}{dx}\right|_{x=x_0}(x-x_0)^k\right)$$

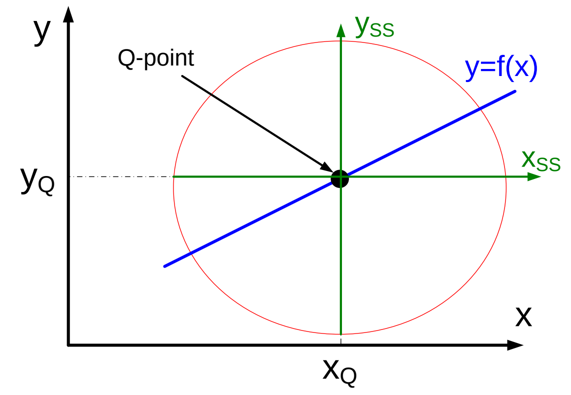
Truncating after first-order terms (and defining "o" as "Q"):

$$y \cong f(x_Q) + \left.\frac{\partial f}{\partial x}\right|_{x=x_Q} (x - x_Q) \longleftrightarrow y_{ss} = \left.\frac{\partial f}{\partial x}\right|_{x=x_Q} x_{ss}$$

Small-Signal Model:

Mathematically, linearized model is simply Taylor's series expansion of the nonlinear function f at the Q-point truncated after first-order terms with notation $x_Q=x_0$

Small-Signal Principle



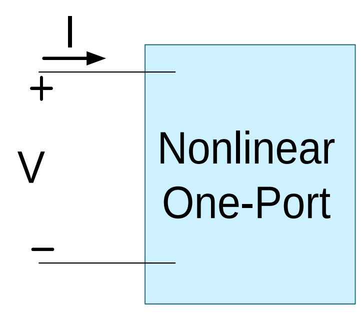
$$y = \boxed{f(x_Q)} + \boxed{\left.\frac{\partial f}{\partial x}\right|_{x=x_Q}} x_{ss}$$

Quiescent Output

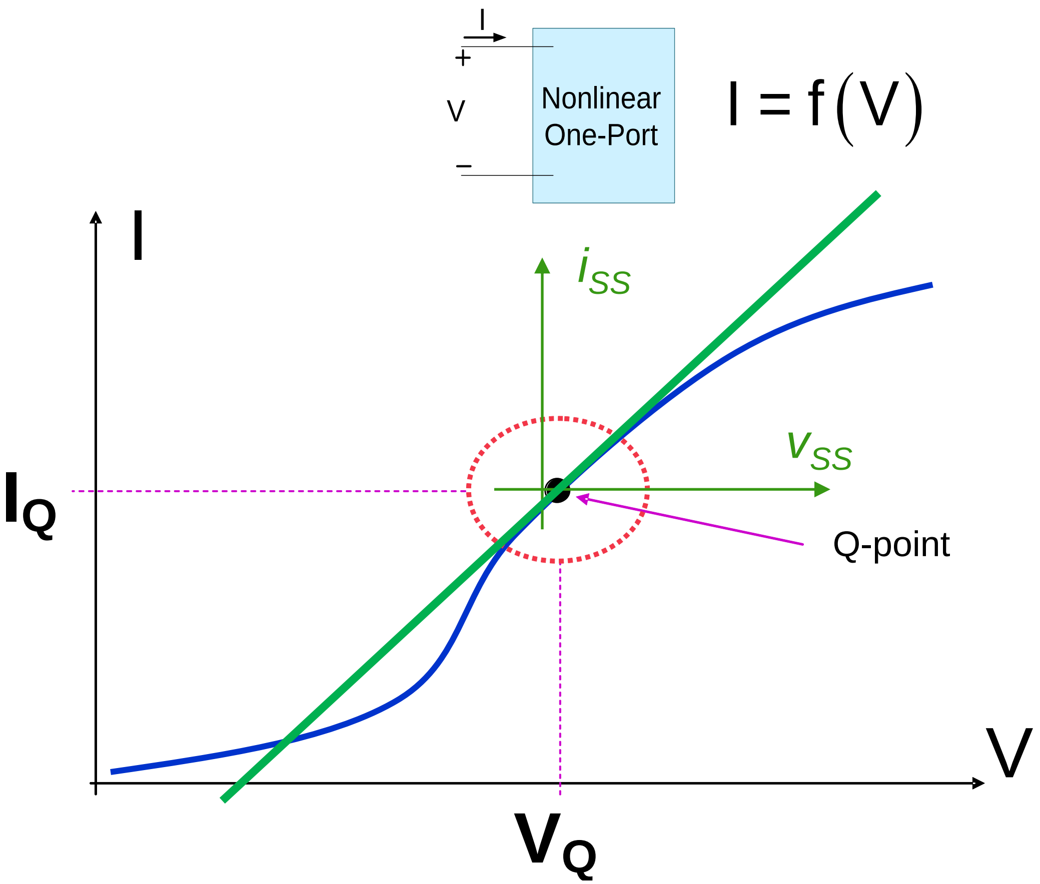
ss Gain

How can a **<u>circuit</u>** be linearized at an operating point as an alternative to linearizing a nonlinear function at an operating point?

Consider arbitrary nonlinear one-port network



Arbitrary Nonlinear One-Port



$$I = f(V)$$

$$i_{SS} = \left.\frac{\partial I}{\partial V}\right|_{V=V_Q} v_{SS}$$

$$i_{SS} \overset{\text{def}}{=} i$$

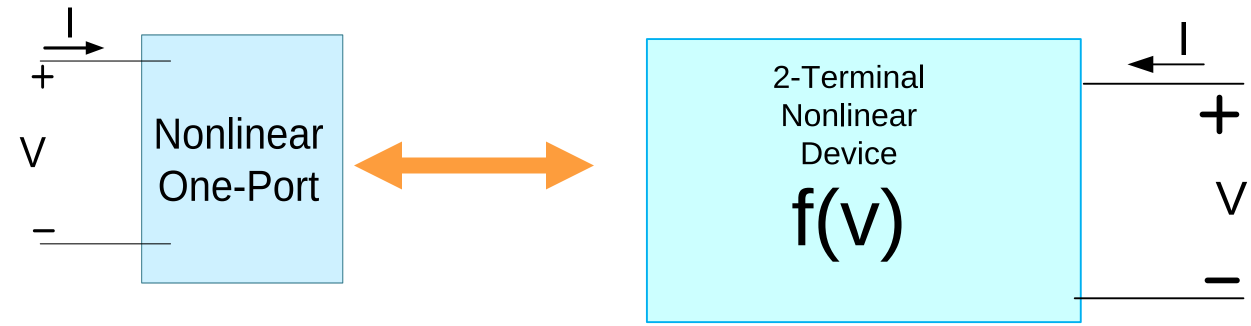
$$v_{SS} \overset{\text{def}}{=} v$$

$$y \overset{defn}{=} \left.\frac{\partial I}{\partial V}\right|_{V=V_Q}$$

Linear model of the nonlinear device at the Q-point

$$\boxed{i = y\,v}$$

Arbitrary Nonlinear One-Port

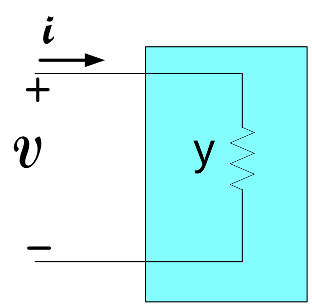


$$y = \left.\frac{\partial I}{\partial V}\right|_{V=V_Q}$$

Linear small-signal model:

$$\boxed{i = y\,v}$$

<u>A</u> Small Signal Equivalent Circuit:



- *The small-signal model of this 2-terminal electrical network is a resistor of value 1/y or a conductor of value y*
- ***One small-signal parameter*** *characterizes this one-port but it is dependent on Q-point*
- *This applies to* ***ANY*** *nonlinear one-port that is differentiable at a Q-point (e.g. a diode)*

Small-Signal Principle

Goal with small signal model is to predict performance of circuit or device in the vicinity of an operating point (Q-point)

Will be extended to functions of two and three variables (e.g. BJTs and MOSFETs)

Solution for the example of the previous lecture was based upon solving the nonlinear circuit for V_{OUT} and then linearizing the solution by doing a Taylor's series expansion

- *Solution of nonlinear equations very involved with two or more nonlinear devices*

- *Taylor's series linearization can get very tedious if multiple nonlinear devices are present*

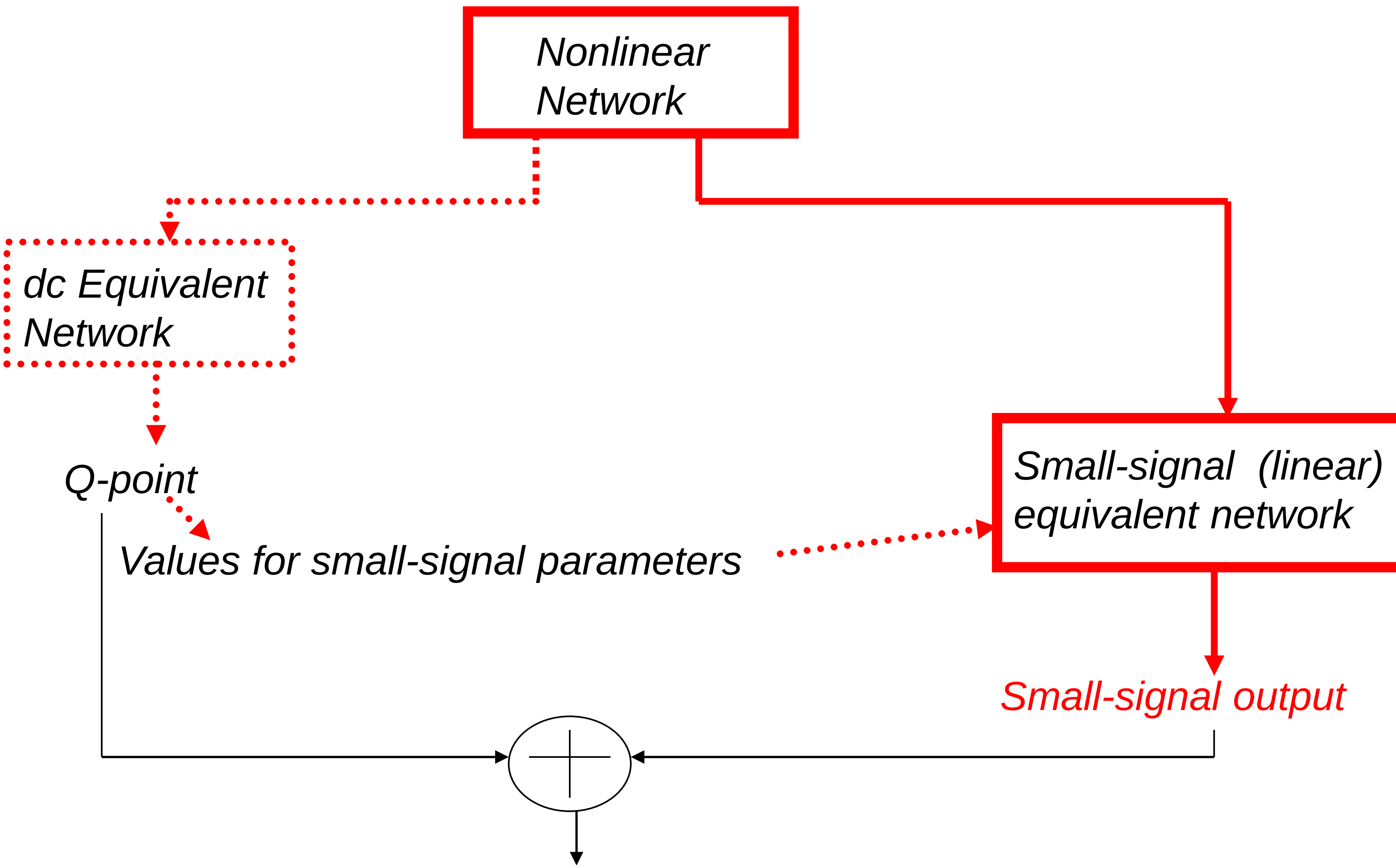
Natural approach to small-signal analysis of nonlinear networks

1. *Solve nonlinear network*
2. *Linearize solution*

Alternative Approach to small-signal analysis of nonlinear networks

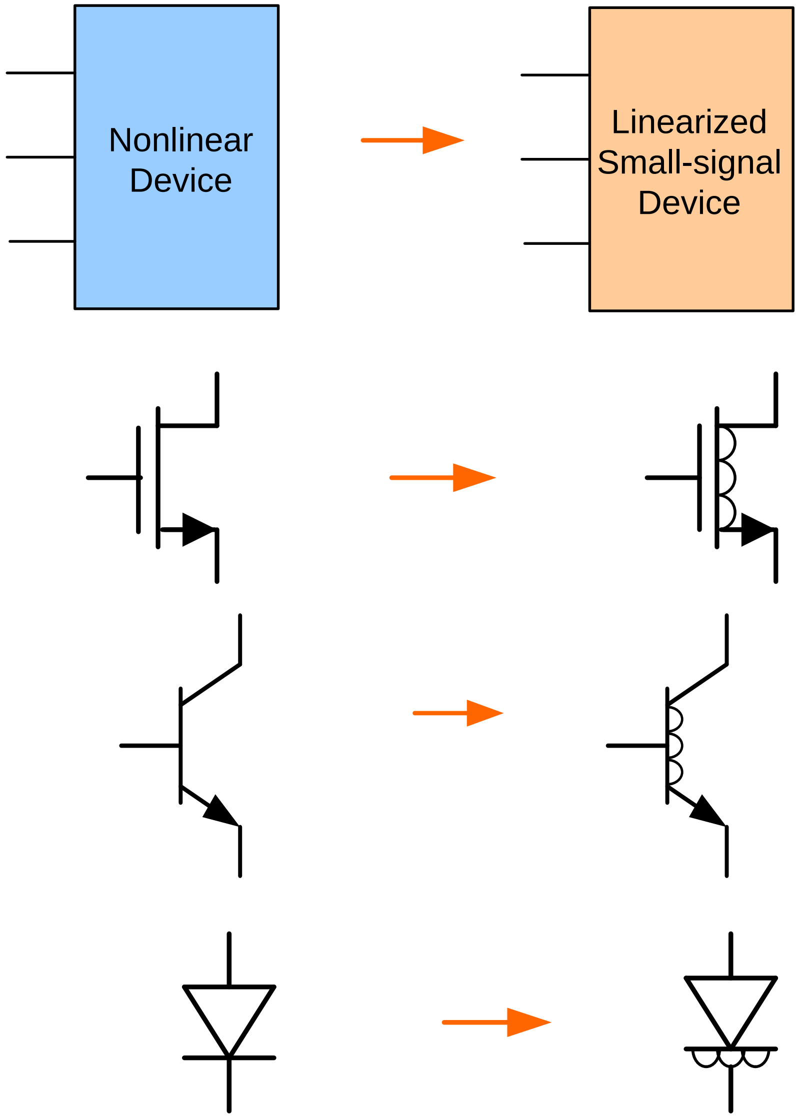
1. *Linearize nonlinear devices (all)*
2. *Obtain small-signal model from linearized device models*
3. *Replace all devices with small-signal equivalent*
4. *Solve linear small-signal network*

"Alternative" Approach to small-signal analysis of nonlinear networks



(good approximation)

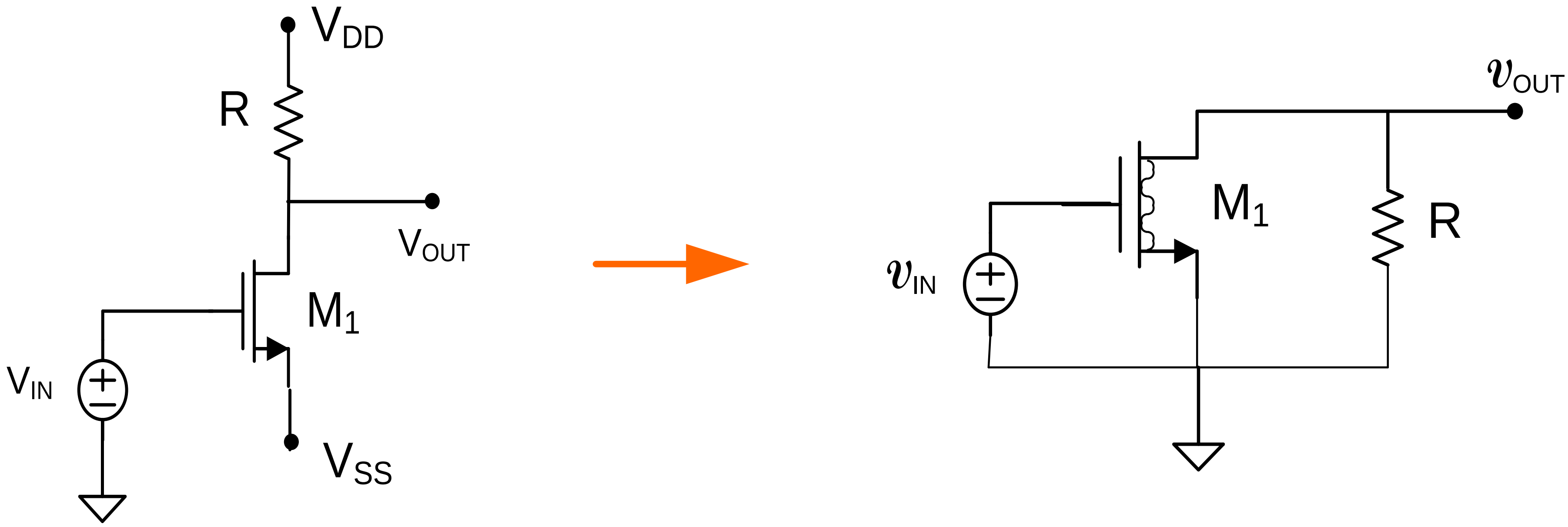
Linearized nonlinear devices



This terminology will be used in THIS course to emphasize difference between nonlinear model and linearized small signal model

Example:

It will be shown that the nonlinear circuit has the linearized small-signal network given

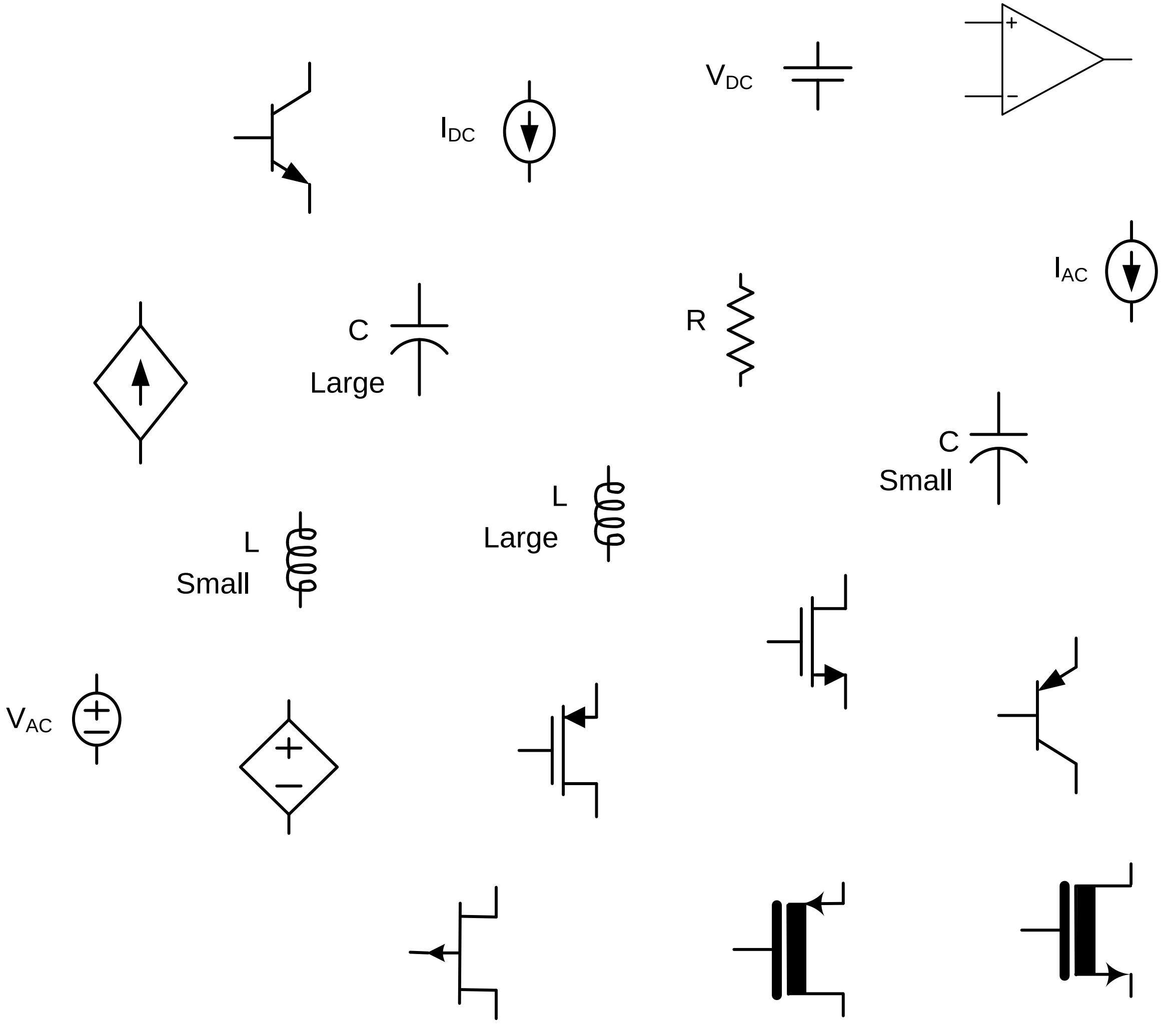


Nonlinear network

Linearized small-signal network

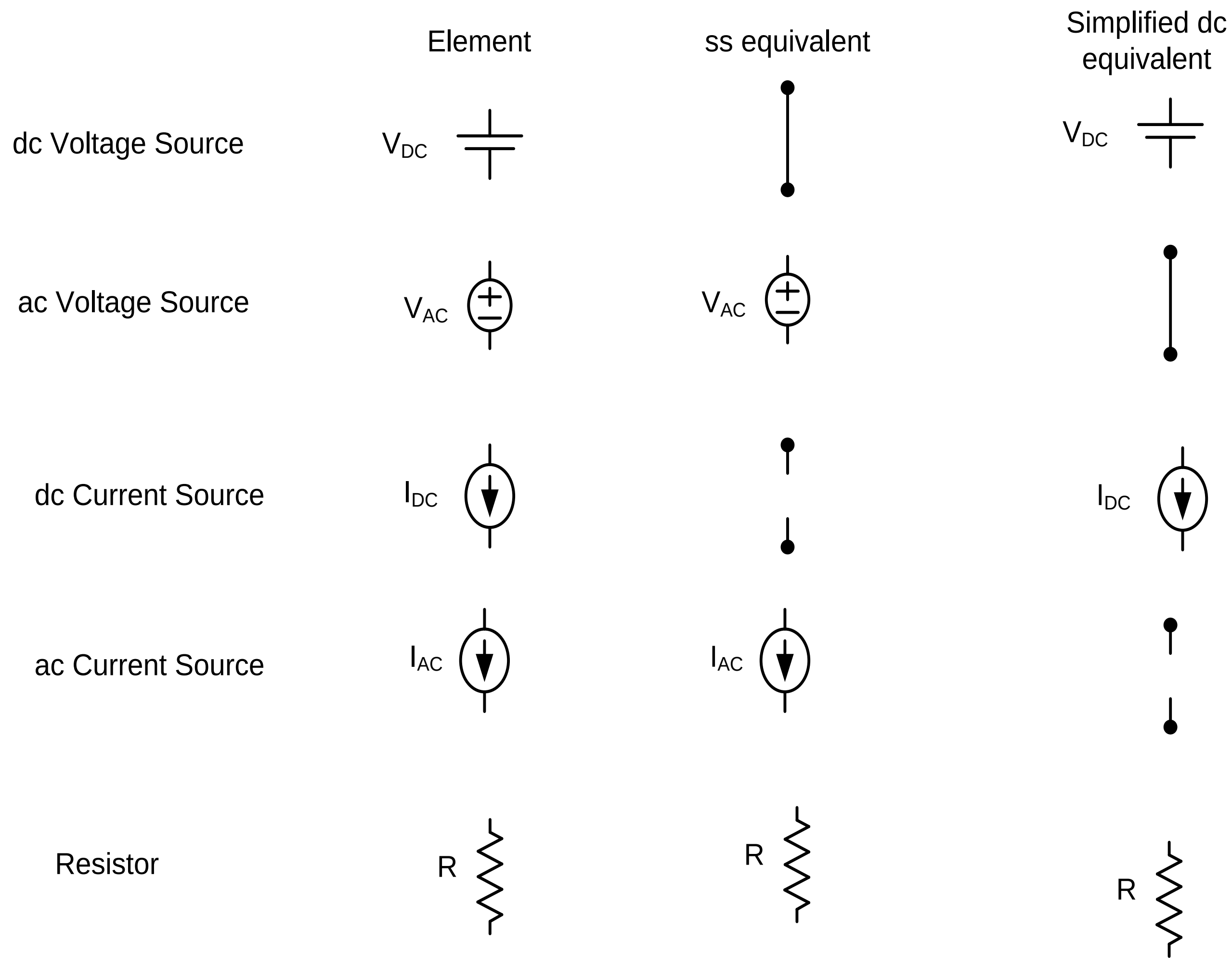
Linearized Small-Signal Circuit Elements

Must obtain the linearized small-signal circuit element for ALL linear and nonlinear circuit elements

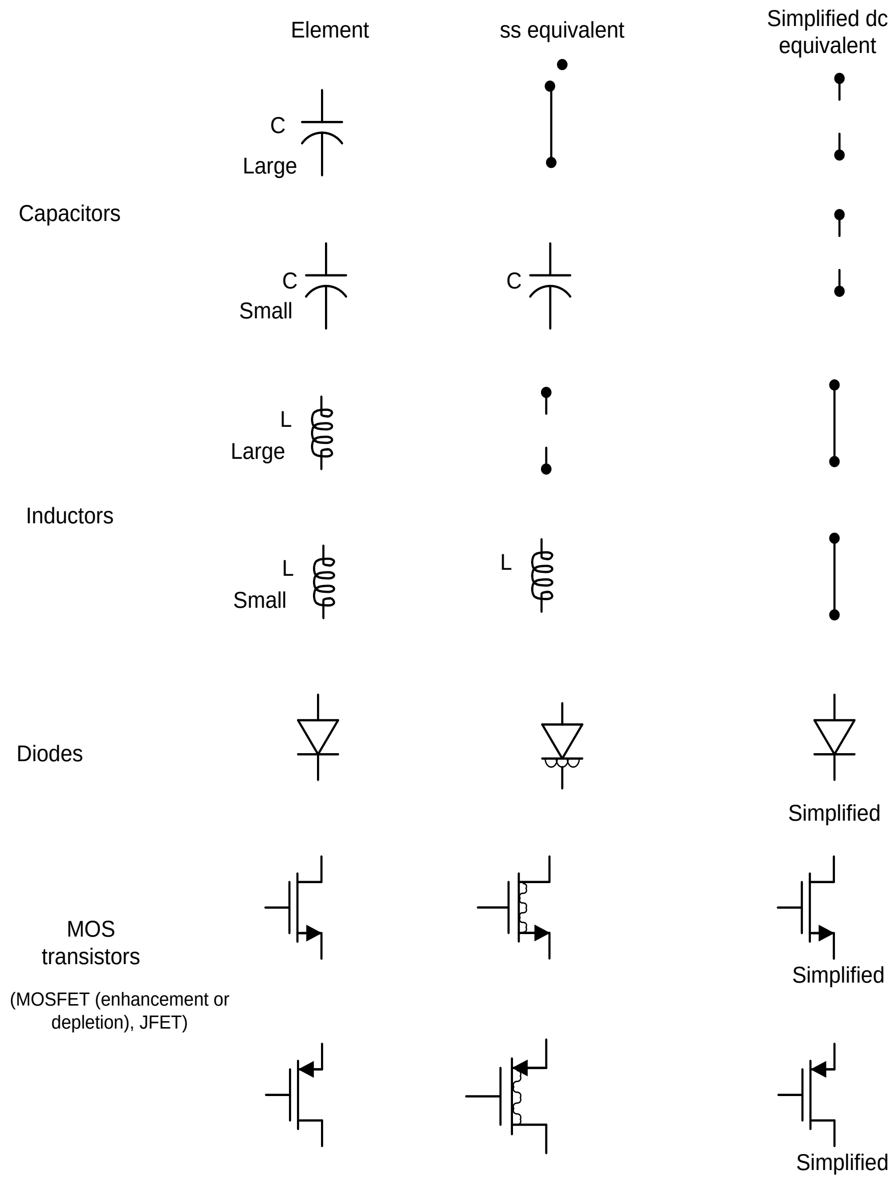


(Will also give models that are usually used for Q-point calculations : Simplified dc models)

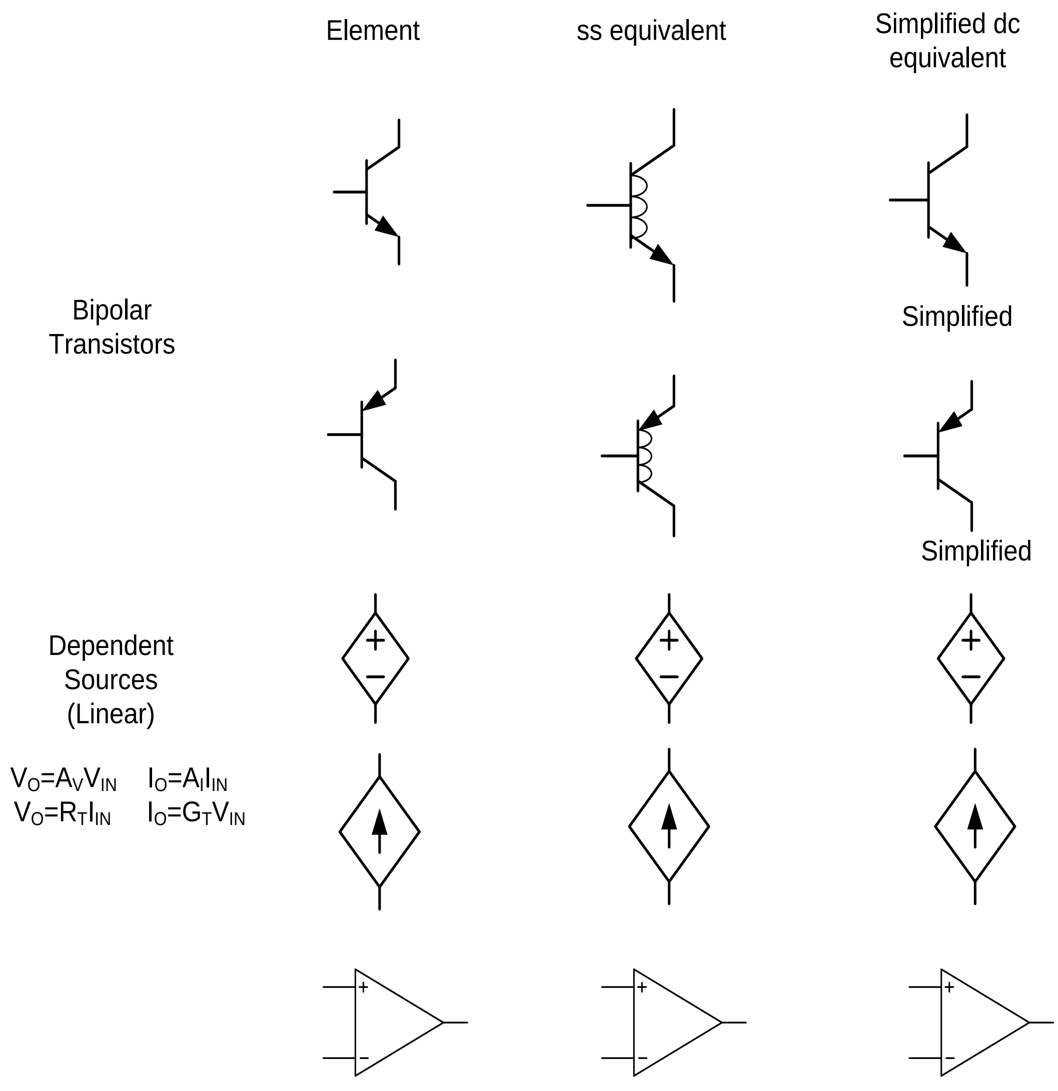
Small-signal and simplified dc equivalent elements



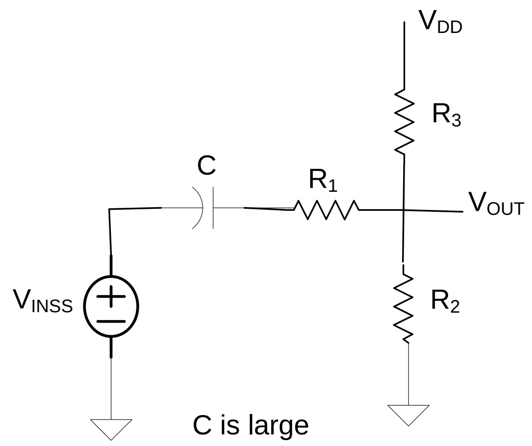
Small-signal and simplified dc equivalent elements

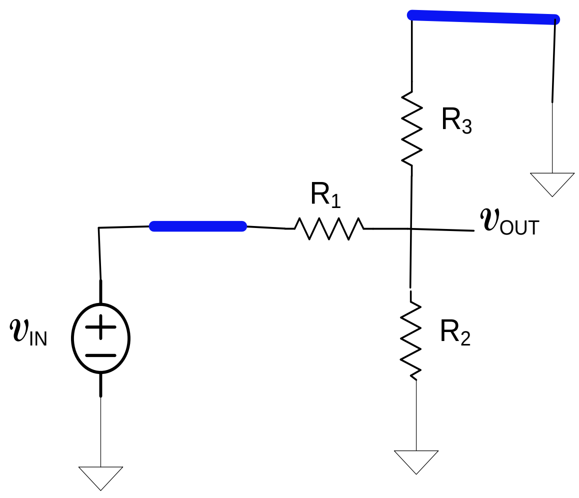


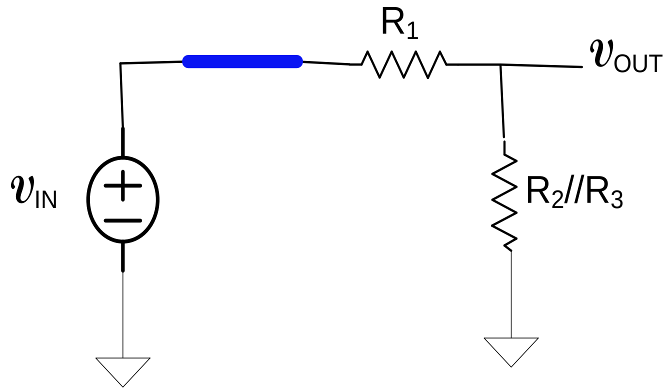
Small-signal and simplified dc equivalent elements



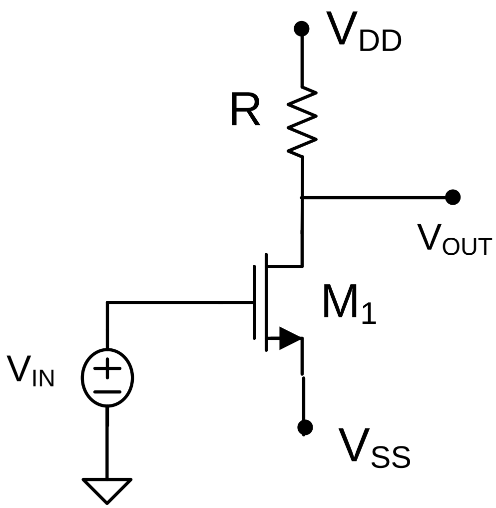
Example: Obtain the small-signal equivalent circuit

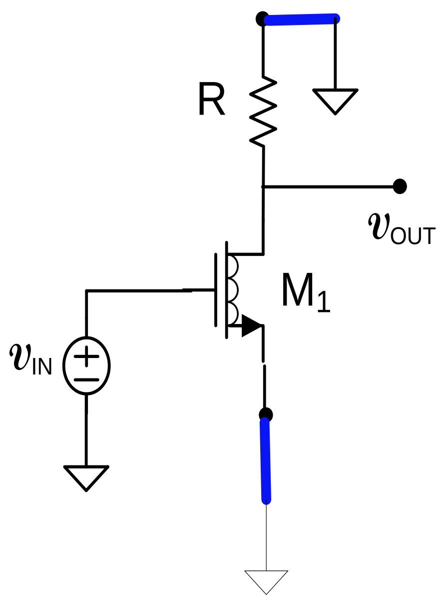


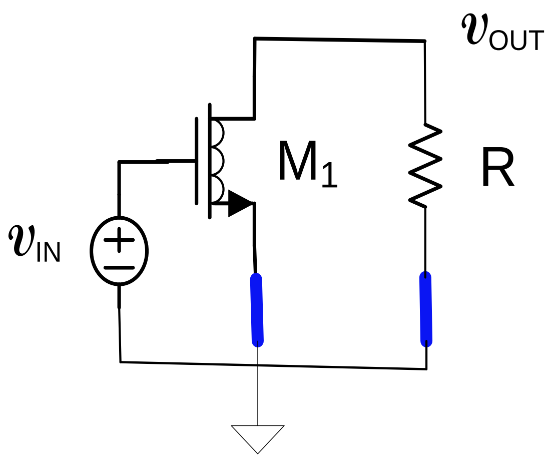




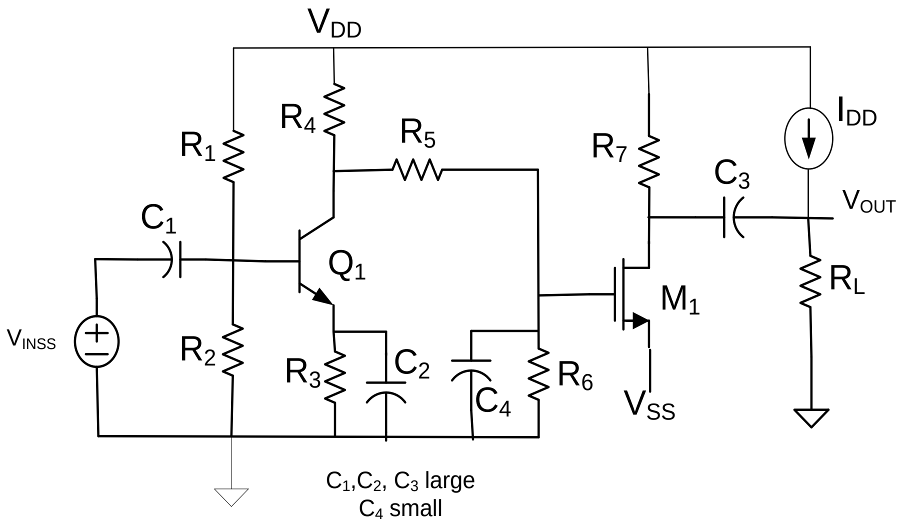
Example: Obtain the small-signal equivalent circuit

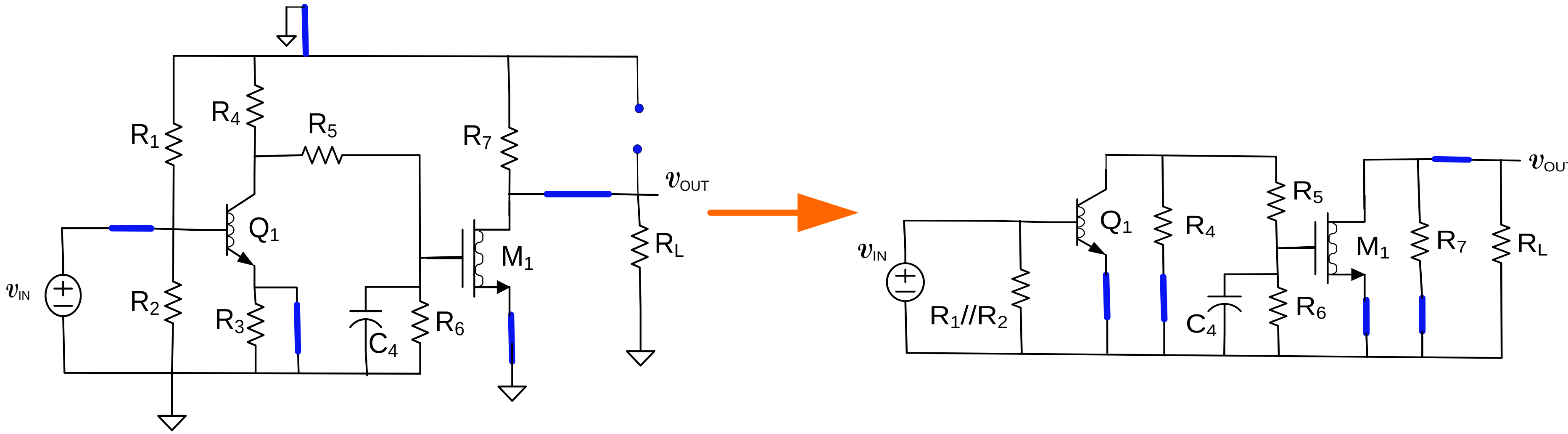






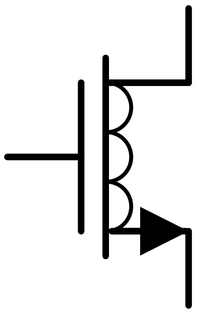
Example: Obtain the small-signal equivalent circuit

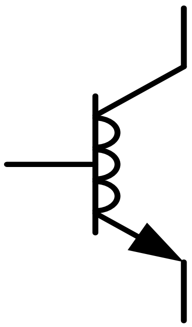


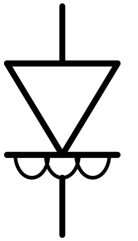


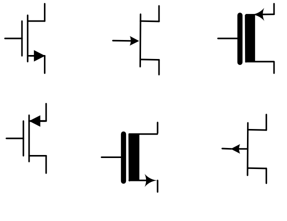
How is the small-signal equivalent circuit obtained from the nonlinear circuit?

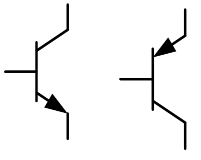
What is the small-signal equivalent of the MOSFET, BJT, and diode ?



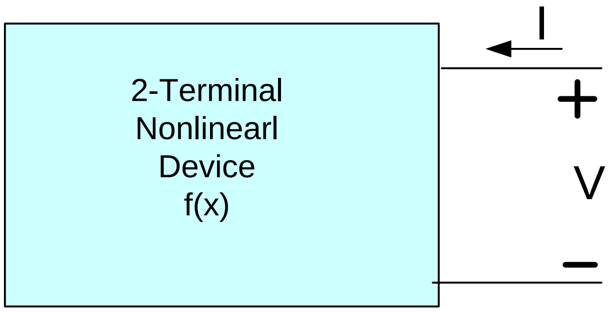








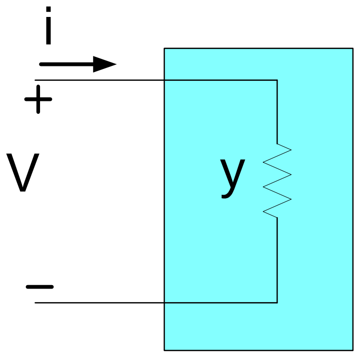
Small-Signal Diode Model



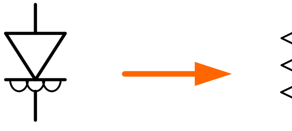
$$y = \left.\frac{\partial I}{\partial V}\right|_{V=V_Q}$$

$$\boldsymbol{i} = y\,\boldsymbol{v}$$

A Small Signal Equivalent Circuit



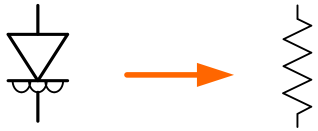
Thus, for the diode



$$R_d = \left(\frac{\partial I_D}{\partial V_D}\right)_Q^{-1}$$

Small-Signal Diode Model

For the diode



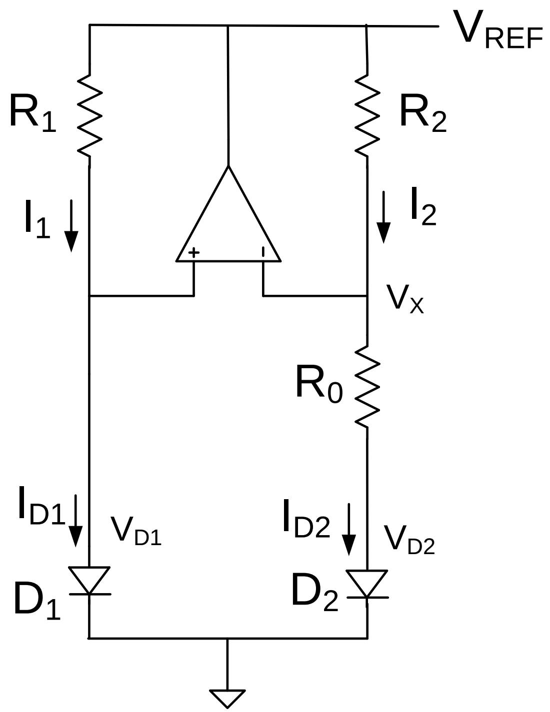
$$R_d = \left(\frac{\partial I_D}{\partial V_D}\right)_Q^{-1}$$

$$I_D = I_S e^{V_D / V_t}$$

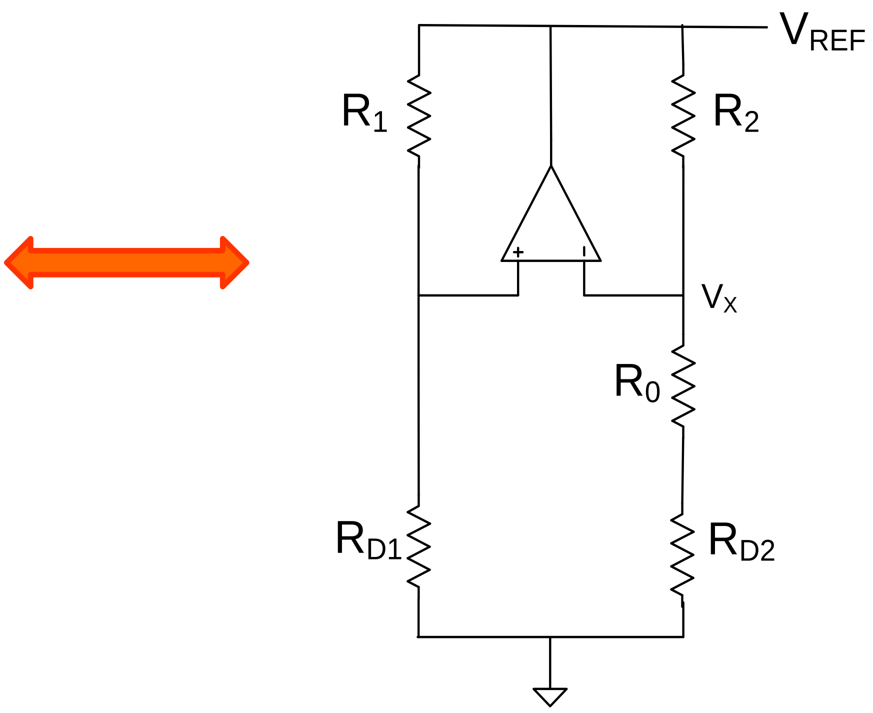
$$\left.\frac{\partial I_D}{\partial V_D}\right|_Q = \left[\left(I_S e^{V_D / V_t}\right)\frac{1}{V_t}\right]_Q = \frac{I_{DQ}}{V_t}$$

$$R_d = \frac{V_t}{I_{DQ}}$$

Example of diode circuit where small-signal diode model is useful



Voltage Reference



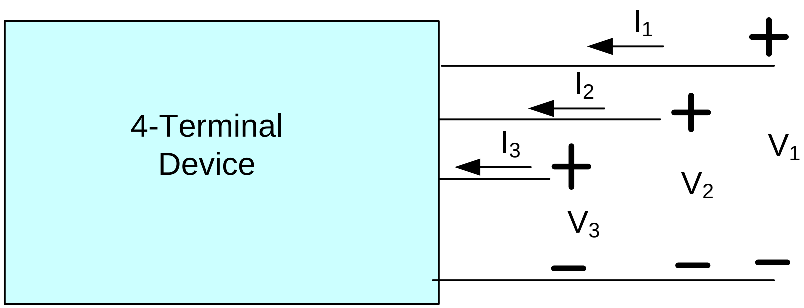
Small-signal model of Voltage Reference

(useful for compensation when parasitic Cs included)

Small-Signal Model of BJT and MOSFET

Consider 4-terminal network

(3-terminal and 2-terminal and 1-terminal devices then become special cases)



$$\left.\begin{aligned} I_1 &= f_1(V_1, V_2, V_3) \\ I_2 &= f_2(V_1, V_2, V_3) \\ I_3 &= f_3(V_1, V_2, V_3) \end{aligned}\right\}$$

4 different ways to choose reference terminal

Six port electrical variables $\{I_1, I_2, I_3, V_1, V_2, V_3\}$

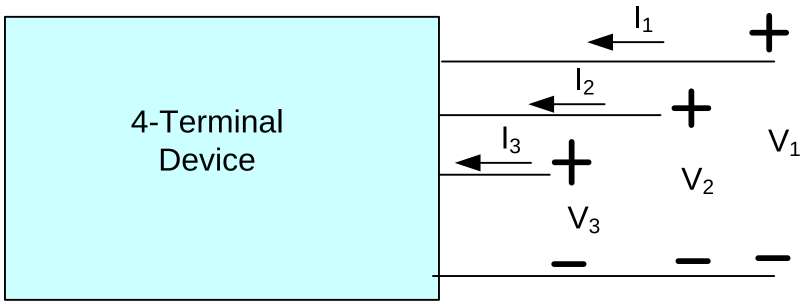
Number of ways to choose independent variables $\quad \binom{6}{3} = \dfrac{6!}{(6-3)!3!} = 20$

Number of potentially different ways to represent same device $\quad$ 80

We will choose one of these 80 which uses port voltages as independent variables

Small-Signal Model of BJT and MOSFET

Consider 4-terminal network



$$\left.\begin{aligned} I_1 &= f_1(V_1, V_2, V_3) \\ I_2 &= f_2(V_1, V_2, V_3) \\ I_3 &= f_3(V_1, V_2, V_3) \end{aligned}\right\}$$

Define

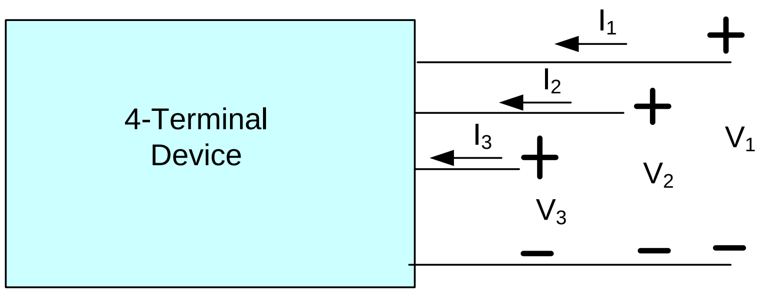
$$i_1 = I_1 - I_{1Q} \qquad v_1 = V_1 - V_{1Q}$$

$$i_2 = I_2 - I_{2Q} \qquad v_2 = V_2 - V_{2Q}$$

$$i_3 = I_3 - I_{3Q} \qquad v_3 = V_3 - V_{3Q}$$

Small signal model is that which represents the relationship between the small signal voltages and the small signal currents

Small-Signal Model of 4-Terminal Network



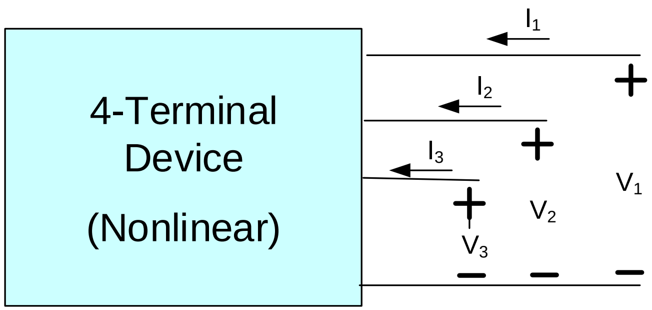
$$
\left.
\begin{aligned}
i_1 &= g_1(v_1, v_2, v_3) \\
i_2 &= g_2(v_1, v_2, v_3) \\
i_3 &= g_3(v_1, v_2, v_3)
\end{aligned}
\right\}
$$

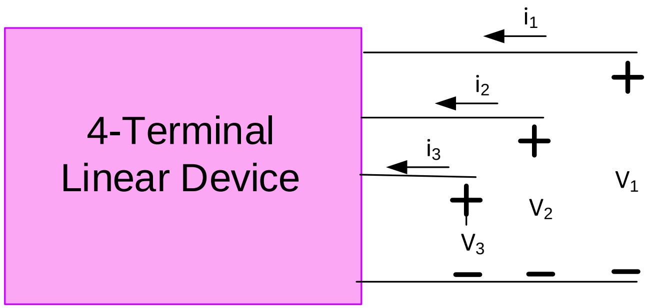
Small signal model is that which represents the relationship between the small signal voltages and the small signal currents

For small signals, this relationship should be linear

Can be thought of as a change in coordinate systems from the large signal coordinate system to the small-signal coordinate system

Small-Signal Model of 4-Terminal Network

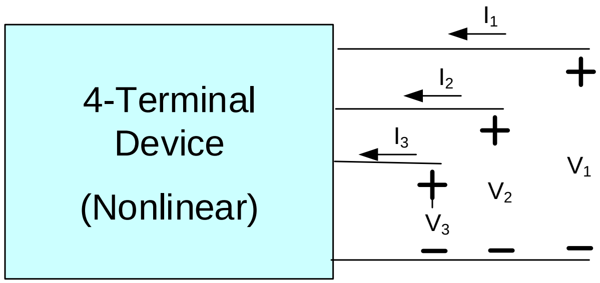


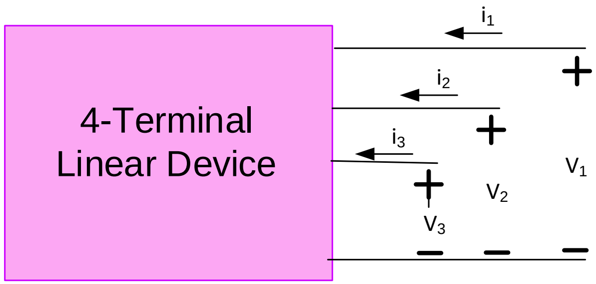


$$\left.\begin{aligned} \mathbf{I_1} &= \mathbf{f_1}(\mathbf{V_1},\mathbf{V_2},\mathbf{V_3}) \\ \mathbf{I_2} &= \mathbf{f_2}(\mathbf{V_1},\mathbf{V_2},\mathbf{V_3}) \\ \mathbf{I_3} &= \mathbf{f_3}(\mathbf{V_1},\mathbf{V_2},\mathbf{V_3}) \end{aligned}\right\} \qquad \left.\begin{aligned} i_1 &= g_1(v_1,v_2,v_3) \\ i_2 &= g_2(v_1,v_2,v_3) \\ i_3 &= g_3(v_1,v_2,v_3) \end{aligned}\right\}$$

Mapping is unique (with same models)

Small-Signal Model of 4-Terminal Network





$$\left.\begin{aligned} \mathbf{I_1} &= \mathbf{f_1}(\mathbf{V_1},\mathbf{V_2},\mathbf{V_3}) \\ \mathbf{I_2} &= \mathbf{f_2}(\mathbf{V_1},\mathbf{V_2},\mathbf{V_3}) \\ \mathbf{I_3} &= \mathbf{f_3}(\mathbf{V_1},\mathbf{V_2},\mathbf{V_3}) \end{aligned}\right\}$$

$$\left.\begin{aligned} i_1 &= g_1(v_1,v_2,v_3) \\ i_2 &= g_2(v_1,v_2,v_3) \\ i_3 &= g_3(v_1,v_2,v_3) \end{aligned}\right\}$$

Does inverse mapping exist? Yes

Is it unique (with same models)? No

Multiple nonlinear circuits can have same small-signal circuit

Recall for a function of one variable

$$y = f(x)$$

Taylor's Series Expansion about the point x_0 (x_0 is termed the expansion point or the Q-point)

$$y = f(x) = f(x)\Big|_{x=x_0} + \frac{\partial f}{\partial x}\bigg|_{x=x_0}(x - x_0) + \frac{\partial^2 f}{\partial x^2}\bigg|_{x=x_0}\frac{1}{2!}(x - x_0)^2 + \ldots$$

If x-x_0 is small

$$y \cong f(x)\Big|_{x=x_0} + \frac{\partial f}{\partial x}\bigg|_{x=x_0}(x - x_0)$$

$$y \cong y_0 + \frac{\partial f}{\partial x}\bigg|_{x=x_0}(x - x_0)$$

Recall for a function of one variable

$$y = f(x)$$

If $x - x_0$ is small

$$y \cong y_0 + \left.\frac{\partial f}{\partial x}\right|_{x=x_0} (x - x_0)$$

$$y - y_0 = \left.\frac{\partial f}{\partial x}\right|_{x=x_0} (x - x_0)$$

If we define the small signal variables as

$$\boldsymbol{y} = y - y_0$$

$$\boldsymbol{x} = x - x_0$$

Recall for a function of one variable

$$y = f(x)$$

If $x\text{-}x_0$ is small

$$y \cong y_0 + \left.\frac{\partial f}{\partial x}\right|_{x=x_0} (x - x_0)$$

$$y - y_0 = \left.\frac{\partial f}{\partial x}\right|_{x=x_0} (x - x_0)$$

If we define the small signal variables as

$$\boldsymbol{y} = y - y_0$$

$$\boldsymbol{x} = x - x_0$$

Then

$$\boldsymbol{y} = \left.\frac{\partial f}{\partial x}\right|_{x=X_Q} \bullet \boldsymbol{x}$$

This relationship is linear !

Consider now a function of n variables

$$y = f(x_1, \ldots x_n) = f(\vec{x})$$

If we consider an arbitrary expansion point $\vec{X}_0 = \{x_{10}, x_{20}, \ldots x_{n0}\}$

The multivariate Taylor's series expansion around the point $\vec{X}_0$ is given by

$$y = f(\vec{x}) = f(\mathrm{x})\Big|_{\vec{x}=\vec{x}_0} + \sum_{k=1}^{n} \left(\left.\frac{\partial f}{\partial \mathrm{x}_k}\right|_{\vec{x}=\vec{x}_0} (\mathrm{x}_k - \mathrm{x}_{k0}) \right)$$

$$+ \sum_{\substack{k=1 \\ j=1}}^{n,n} \left.\frac{\partial^2 f}{\partial \mathrm{x}_j \partial \mathrm{x}_k}\right|_{\vec{x}=\vec{x}_0} \frac{1}{2!} (\mathrm{x}_j - \mathrm{x}_{j0})(\mathrm{x}_k - \mathrm{x}_{k0}) + ..(\mathrm{H.O.T.})$$

Truncating after first-order terms, we obtain the approximation

$$y - y_0 \cong \sum_{k=1}^{n} \left(\left.\frac{\partial f}{\partial \mathrm{x}_k}\right|_{\vec{x}=\vec{x}_0} (\mathrm{x}_k - \mathrm{x}_{k0}) \right)$$

where $y_0 = f(\mathrm{x})\Big|_{\vec{x}=\vec{x}_0}$

Multivariate Taylors Series Expansion

$$y = f(x_1, \ldots x_n) = f(\vec{x})$$

Linearized approximation

$$\text{y-y}_0 \cong \sum_{k=1}^{n} \left(\left. \frac{\partial f}{\partial \text{x}_\text{k}} \right|_{\vec{x}=\vec{x}_0} (\text{x}_\text{k} - \text{x}_{\text{k}0}) \right)$$

This can be expressed as

$$\text{y}_{ss} \cong \sum_{k=1}^{n} \text{a}_\text{k} \text{x}_{ss_k} \qquad \left(\boldsymbol{y} \cong \sum_{k=1}^{n} \text{a}_\text{k} \boldsymbol{x}_k \right)$$

where

$$\text{y}_{ss} = \text{y} - \text{y}_0 \qquad (\boldsymbol{y} = \text{y} - \text{y}_0)$$

$$\text{x}_{ss_k} = \text{x}_\text{k} - \text{x}_{\text{k}0} \qquad (\boldsymbol{x}_k = \text{x}_\text{k} - \text{x}_{\text{k}0})$$

$$\text{a}_k = \left. \frac{\partial f}{\partial \text{x}_\text{k}} \right|_{\vec{x}=\vec{x}_0}$$

In the more general form[1], the multivariate Taylor's series expansion can be expressed as

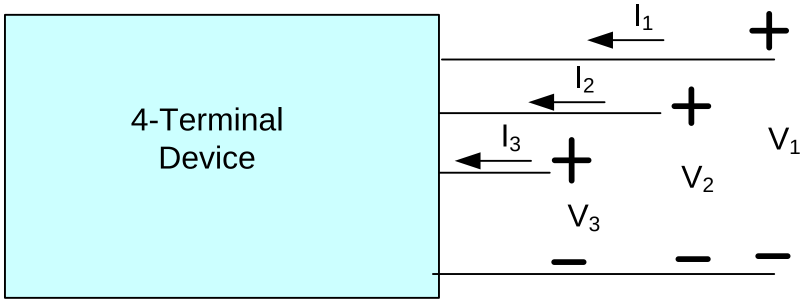
$$f(x_1,\ldots,x_n) = \boldsymbol{\alpha}_o + \sum_{m=1}^{\infty}\left(\sum_{\substack{k_1,\cdots,k_n \\ \left(\sum_j k_j = m\right)}} \boldsymbol{\alpha}_{k_1,\ldots,k_n;m}\left(x_1 - x_{1,o}\right)^{k_1}\cdots\left(x_n - x_{n,o}\right)^{k_n}\right) \quad \textbf{(7)}$$

$$\boldsymbol{\alpha}_o = f\left(x_{1o},\ldots,x_{no}\right)$$

$$\boldsymbol{\alpha}_{k_1,\ldots,k_n;m} = \frac{1}{k_1!\cdots k_n!}\left.\frac{\partial^m f}{\partial^{k_1}x_1\cdots\partial^{k_n}x_n}\right|_{x_{1o},\ldots,x_{no}} \quad \textbf{(8)}$$

[1] http://www.chem.mtu.edu/~tbco/cm416/taylor.html

Consider 4-terminal network



$$\left.\begin{aligned} I_1 &= f_1(V_1, V_2, V_3) \\ I_2 &= f_2(V_1, V_2, V_3) \\ I_3 &= f_3(V_1, V_2, V_3) \end{aligned}\right\}$$

Nonlinear network characterized by 3 functions each functions of 3 variables

Consider now 3 functions each functions of 3 variables

$$\left.\begin{aligned} \mathbf{I}_1 &= \mathbf{f}_1(\mathbf{V}_1, \mathbf{V}_2, \mathbf{V}_3) \\ \mathbf{I}_2 &= \mathbf{f}_2(\mathbf{V}_1, \mathbf{V}_2, \mathbf{V}_3) \\ \mathbf{I}_3 &= \mathbf{f}_3(\mathbf{V}_1, \mathbf{V}_2, \mathbf{V}_3) \end{aligned}\right\}$$

Define

$$\vec{V}_Q = \begin{bmatrix} V_{1Q} \\ V_{2Q} \\ V_{3Q} \end{bmatrix}$$

In what follows, we will use $\vec{V}_Q$ as an expansion point in a Taylor's series expansion.

Consider now 3 functions each functions of 3 variables

$$\left.\begin{aligned} \mathbf{I_1} &= \mathbf{f_1}\left(\mathbf{V_1},\mathbf{V_2},\mathbf{V_3}\right) \\ \mathbf{I_2} &= \mathbf{f_2}\left(\mathbf{V_1},\mathbf{V_2},\mathbf{V_3}\right) \\ \mathbf{I_3} &= \mathbf{f_3}\left(\mathbf{V_1},\mathbf{V_2},\mathbf{V_3}\right) \end{aligned}\right\}$$

Define

$$\vec{V}_Q = \begin{bmatrix} V_{1Q} \\ V_{2Q} \\ V_{3Q} \end{bmatrix}$$

Consider first the function I_1

The multivariate Taylors Series expansion of I_1, around the operating point $\vec{V}_Q$. when truncated after first-order terms, can be expressed as:

$$\mathbf{I_1} = \mathbf{f_1}\left(\mathbf{V_1},\mathbf{V_2},\mathbf{V_3}\right) \cong \mathbf{f_1}\left(\mathbf{V_{1Q}},\mathbf{V_{2Q}},\mathbf{V_{3Q}}\right) +$$

$$\left.\frac{\partial \mathbf{f_1}\left(\mathbf{V_1},\mathbf{V_2},\mathbf{V_3}\right)}{\partial \mathbf{V_1}}\right|_{\vec{V}=\vec{V}_Q}\left(\mathbf{V_1}-\mathbf{V_{1Q}}\right) + \left.\frac{\partial \mathbf{f_1}\left(\mathbf{V_1},\mathbf{V_2},\mathbf{V_3}\right)}{\partial \mathbf{V_2}}\right|_{\vec{V}=\vec{V}_Q}\left(\mathbf{V_2}-\mathbf{V_{2Q}}\right) + \left.\frac{\partial \mathbf{f_1}\left(\mathbf{V_1},\mathbf{V_2},\mathbf{V_3}\right)}{\partial \mathbf{V_3}}\right|_{\vec{V}=\vec{V}_Q}\left(\mathbf{V_3}-\mathbf{V_{3Q}}\right)$$

or equivalently as:

$$\mathbf{I_1} - \mathbf{I_{1Q}} = \left.\frac{\partial \mathbf{f_1}\left(\mathbf{V_1},\mathbf{V_2},\mathbf{V_3}\right)}{\partial \mathbf{V_1}}\right|_{\vec{V}=\vec{V}_Q}\left(\mathbf{V_1}-\mathbf{V_{1Q}}\right) + \left.\frac{\partial \mathbf{f_1}\left(\mathbf{V_1},\mathbf{V_2},\mathbf{V_3}\right)}{\partial \mathbf{V_2}}\right|_{\vec{V}=\vec{V}_Q}\left(\mathbf{V_2}-\mathbf{V_{2Q}}\right) + \left.\frac{\partial \mathbf{f_1}\left(\mathbf{V_1},\mathbf{V_2},\mathbf{V_3}\right)}{\partial \mathbf{V_3}}\right|_{\vec{V}=\vec{V}_Q}\left(\mathbf{V_3}-\mathbf{V_{3Q}}\right)$$

repeating from previous slide:

$$I_1 - I_{1Q} = \left.\frac{\partial f_1(V_1,V_2,V_3)}{\partial V_1}\right|_{\vec{V}=\vec{V}_Q}(V_1 - V_{1Q}) + \left.\frac{\partial f_1(V_1,V_2,V_3)}{\partial V_2}\right|_{\vec{V}=\vec{V}_Q}(V_2 - V_{2Q}) + \left.\frac{\partial f_1(V_1,V_2,V_3)}{\partial V_3}\right|_{\vec{V}=\vec{V}_Q}(V_3 - V_{3Q})$$

Make the following definitions

$$y_{11} = \left.\frac{\partial f_1(V_1,V_2,V_3)}{\partial V_1}\right|_{\vec{V}=\vec{V}_Q}$$

$$y_{12} = \left.\frac{\partial f_1(V_1,V_2,V_3)}{\partial V_2}\right|_{\vec{V}=\vec{V}_Q}$$

$$y_{13} = \left.\frac{\partial f_1(V_1,V_2,V_3)}{\partial V_3}\right|_{\vec{V}=\vec{V}_Q}$$

$$i_1 = I_1 - I_{1Q}$$

$$i_2 = I_2 - I_{2Q}$$

$$i_3 = I_3 - I_{3Q}$$

$$v_1 = V_1 - V_{1Q}$$

$$v_2 = V_2 - V_{2Q}$$

$$v_3 = V_3 - V_{3Q}$$

It thus follows that

$$i_1 = y_{11}v_1 + y_{12}v_2 + y_{13}v_3$$

This is a linear relationship between the small signal electrical variables !

Small Signal Model Development

Nonlinear Model

$$I_1 = f_1(V_1, V_2, V_3)$$
$$I_2 = f_2(V_1, V_2, V_3)$$
$$I_3 = f_3(V_1, V_2, V_3)$$

Linear Model at $\vec{V}_Q$
(alt. small signal model)

$$i_1 = y_{11}v_1 + y_{12}v_2 + y_{13}v_3$$

Extending this approach to the two nonlinear functions I_2 and I_3

$$i_2 = y_{21}v_1 + y_{22}v_2 + y_{23}v_3$$
$$i_3 = y_{31}v_1 + y_{32}v_2 + y_{33}v_3$$

where

$$\mathbf{y_{ij}} = \left.\frac{\partial \mathbf{f_i}(\mathbf{V_1}, \mathbf{V_2}, \mathbf{V_3})}{\partial \mathbf{V_j}}\right|_{\vec{\mathbf{V}} = \vec{\mathbf{V}}_{\mathbf{Q}}}$$

Small Signal Model Development

Nonlinear Model

Linear Model at $\vec{V}_Q$
(alt. small signal model)

$$I_1 = f_1(V_1, V_2, V_3) \rightarrow i_1 = y_{11} v_1 + y_{12} v_2 + y_{13} v_3$$

$$I_2 = f_2(V_1, V_2, V_3) \rightarrow i_2 = y_{21} v_1 + y_{22} v_2 + y_{23} v_3$$

$$I_3 = f_3(V_1, V_2, V_3) \rightarrow i_3 = y_{31} v_1 + y_{32} v_2 + y_{33} v_3$$

where

$$\mathbf{y_{ij}} = \left.\frac{\partial \mathbf{f_i}(\mathbf{V_1}, \mathbf{V_2}, \mathbf{V_3})}{\partial \mathbf{V_j}}\right|_{\vec{\mathbf{V}} = \vec{\mathbf{V}}_\mathbf{Q}}$$

Small Signal Model

$$i_1 = y_{11}v_1 + y_{12}v_2 + y_{13}v_3$$
$$i_2 = y_{21}v_1 + y_{22}v_2 + y_{23}v_3$$
$$i_3 = y_{31}v_1 + y_{32}v_2 + y_{33}v_3$$

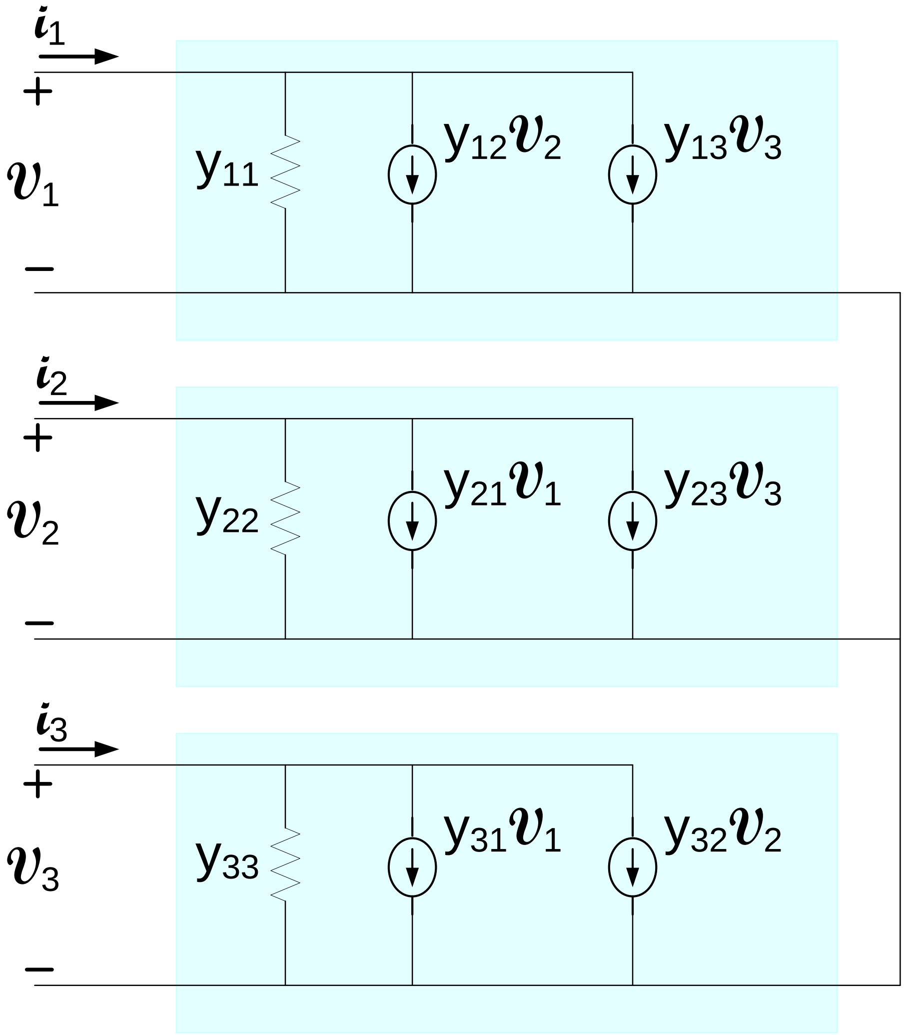
where

$$\mathbf{y_{ij}} = \left.\frac{\partial \mathbf{f_i}(\mathbf{V_1},\mathbf{V_2},\mathbf{V_3})}{\partial \mathbf{V_j}}\right|_{\vec{\mathbf{V}}=\vec{\mathbf{V}}_{\mathbf{Q}}}$$

- This is a small-signal model of a 4-terminal network and it is linear
- 9 small-signal parameters characterize the linear 4-terminal network
- Small-signal model parameters dependent upon Q-point !
- Termed the y-parameter model or “admittance” –parameter model

A small-signal equivalent circuit of a 4-terminal nonlinear network

(equivalent circuit because has exactly the same port equations)

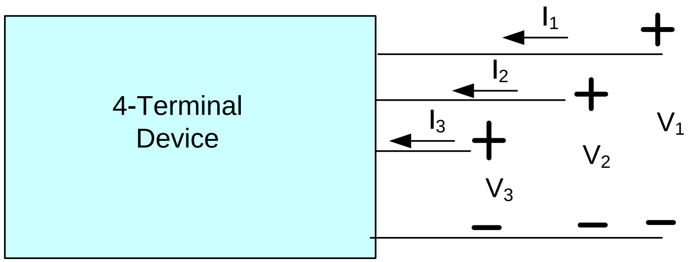


$$\mathbf{y_{ij}} = \left.\frac{\partial \mathbf{f_i}(\mathbf{V_1},\mathbf{V_2},\mathbf{V_3})}{\partial \mathbf{V_j}}\right|_{\vec{\mathbf{V}}=\vec{\mathbf{V}}_{\mathbf{Q}}}$$

Equivalent circuit is not unique

Equivalent circuit is a three-port network

4-terminal small-signal network summary

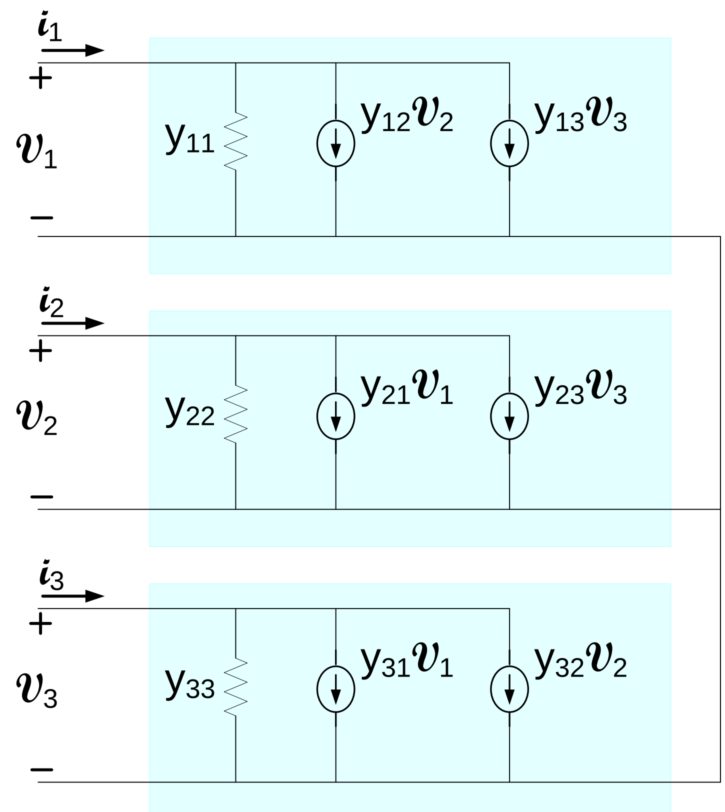


$$\left.\begin{aligned} I_1 &= f_1(V_1, V_2, V_3) \\ I_2 &= f_2(V_1, V_2, V_3) \\ I_3 &= f_3(V_1, V_2, V_3) \end{aligned}\right\}$$

Small signal model:

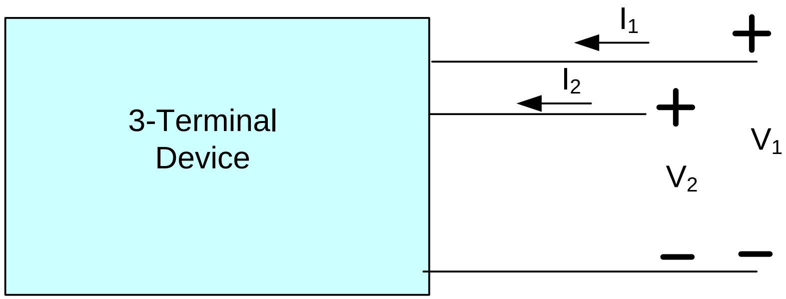
$$\begin{aligned} i_1 &= y_{11} v_1 + y_{12} v_2 + y_{13} v_3 \\ i_2 &= y_{21} v_1 + y_{22} v_2 + y_{23} v_3 \\ i_3 &= y_{31} v_1 + y_{32} v_2 + y_{33} v_3 \end{aligned}$$

$$y_{ij} = \left.\frac{\partial f_i(V_1, V_2, V_3)}{\partial V_j}\right|_{\vec{V} = \vec{V}_Q}$$



Consider 3-terminal network

Small-Signal Model



$$\left.\begin{aligned} I_1 &= f_1(V_1, V_2) \\ I_2 &= f_2(V_1, V_2) \end{aligned}\right\}$$

Define

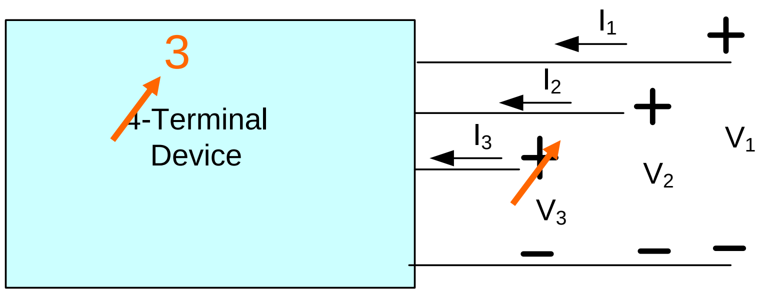
$$i_1 = I_1 - I_{1Q} \qquad v_1 = V_1 - V_{1Q}$$

$$i_2 = I_2 - I_{2Q} \qquad v_2 = V_2 - V_{2Q}$$

Small signal model is that which represents the relationship between the small signal voltages and the small signal currents

Consider 3-terminal network

Small-Signal Model



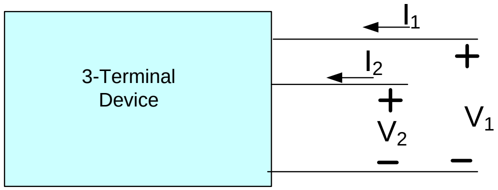
$$i_1 = g_1(v_1, v_2, v_3)$$
$$i_2 = g_2(v_1, v_2, v_3)$$
$$i_3 = g_3(v_1, v_2, v_3)$$

$$i_1 = y_{11}v_1 + y_{12}v_2 + y_{13}v_3$$
$$i_2 = y_{21}v_1 + y_{22}v_2 + y_{23}v_3$$
$$i_3 = y_{31}v_1 + y_{32}v_2 + y_{33}v_3$$

$$\mathbf{y_{ij}} = \left.\frac{\partial \mathbf{f_i}(\mathbf{V_1}, \mathbf{V_2}, \mathbf{V_3})}{\partial \mathbf{V_j}}\right|_{\vec{\mathbf{V}} = \vec{\mathbf{V}}_\mathbf{Q}}$$

Consider 3-terminal network

Small-Signal Model

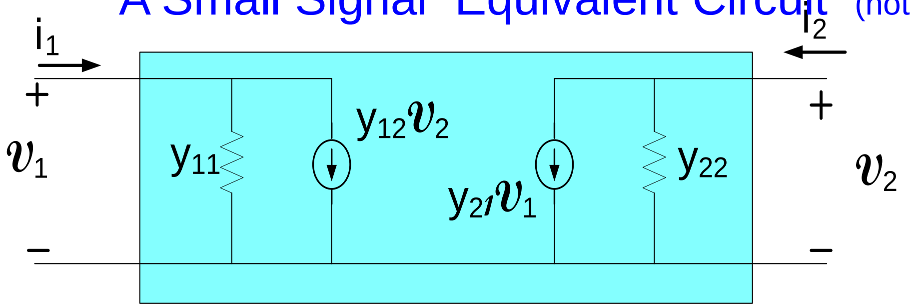


$$\begin{aligned} i_1 &= y_{11} v_1 + y_{12} v_2 \\ i_2 &= y_{21} v_1 + y_{22} v_2 \end{aligned}$$

$$y_{ij} = \left. \frac{\partial f_i(V_1, V_2)}{\partial V_j} \right|_{\vec{V} = \vec{V}_Q}$$

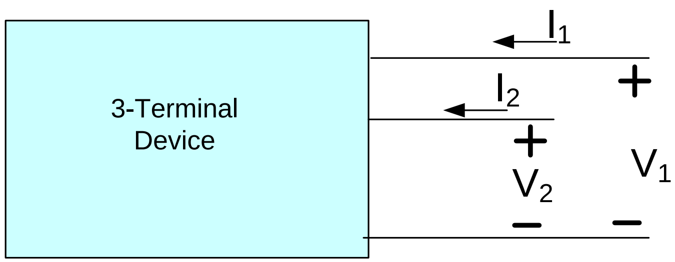
$$\vec{V} = \begin{pmatrix} V_{1Q} \\ V_{2Q} \end{pmatrix}$$

A Small Signal Equivalent Circuit (not unique)



- *Small-signal model is a "two-port"*
- *4 small-signal parameters characterize this 3-terminal linear network*
- *Small signal parameters dependent upon Q-point*

3-terminal small-signal network summary

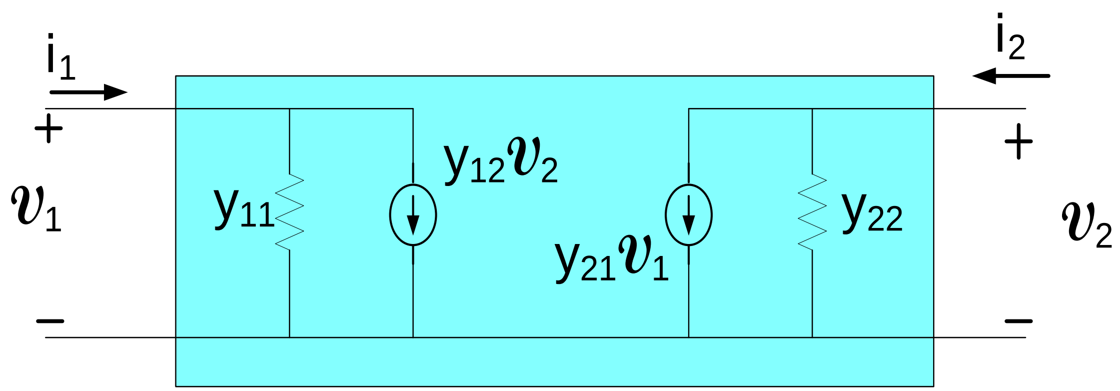


$$\left.\begin{aligned} \mathbf{I_1} &= \mathbf{f_1}(\mathbf{V_1}, \mathbf{V_2}) \\ \mathbf{I_2} &= \mathbf{f_2}(\mathbf{V_1}, \mathbf{V_2}) \end{aligned}\right\}$$

Small signal model:

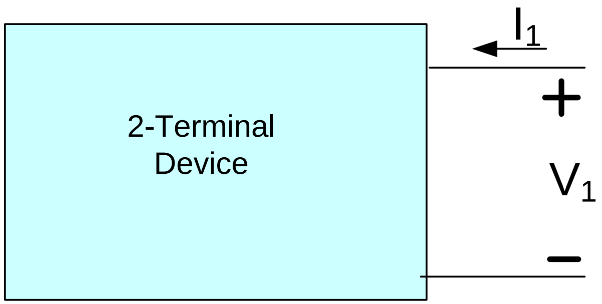
$$\boxed{\begin{aligned} i_1 &= y_{11} v_1 + y_{12} v_2 \\ i_2 &= y_{21} v_1 + y_{22} v_2 \end{aligned}}$$

$$\mathbf{y_{ij}} = \left.\frac{\partial \mathbf{f_i}(\mathbf{V_1}, \mathbf{V_2})}{\partial \mathbf{V_j}}\right|_{\vec{\mathbf{V}} = \vec{\mathbf{V}}_{\mathbf{Q}}}$$



Consider 2-terminal network

Small-Signal Model



$$I_1 = f_1(V_1)$$

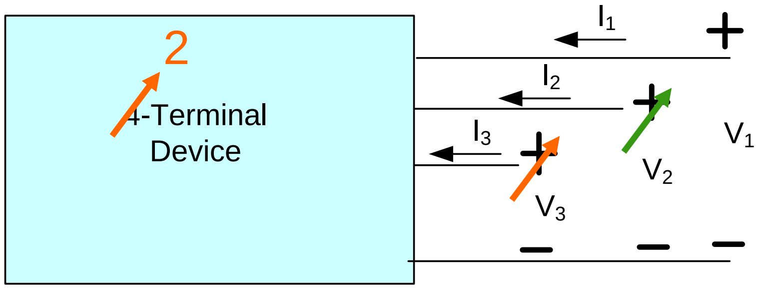
Define

$$\boldsymbol{i}_1 = I_1 - I_{1Q}$$
$$\boldsymbol{v}_1 = V_1 - V_{1Q}$$

Small signal model is that which represents the relationship between the small signal voltages and the small signal currents

Consider 2-terminal network

Small-Signal Model



$$\left.\begin{aligned} i_1 &= g_1(v_1, v_2, v_3) \\ i_2 &= g_2(v_1, v_2, v_3) \\ i_3 &= g_3(v_1, v_2, v_3) \end{aligned}\right\}$$

$$i_1 = y_{11}v_1 + y_{12}v_2 + y_{13}v_3$$

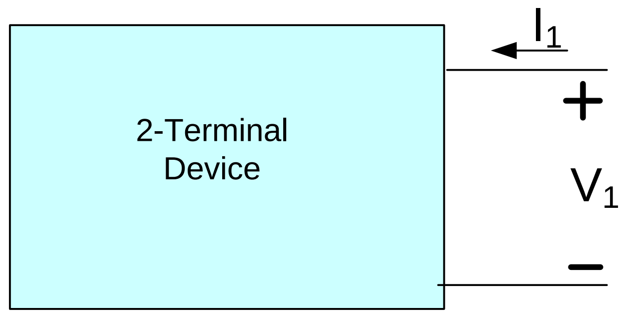
$$i_2 = y_{21}v_1 + y_{22}v_2 + y_{23}v_3$$

$$i_3 = y_{31}v_1 + y_{32}v_2 + y_{33}v_3$$

$$\mathbf{y_{ij}} = \left.\frac{\partial \mathbf{f_i}(\mathbf{V_1}, \mathbf{V_2}, \mathbf{V_3})}{\partial \mathbf{V_j}}\right|_{\vec{\mathbf{V}} = \vec{\mathbf{V}}_{\mathbf{Q}}}$$

Consider 2-terminal network

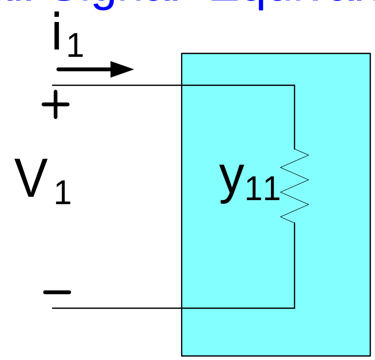
Small-Signal Model



$$\boxed{i_1 = y_{11} v_1}$$

$$y_{11} = \left.\frac{\partial f_1(V_1)}{\partial V_1}\right|_{\vec{V}=\vec{V}_Q} \qquad \vec{V} = V_{1Q}$$

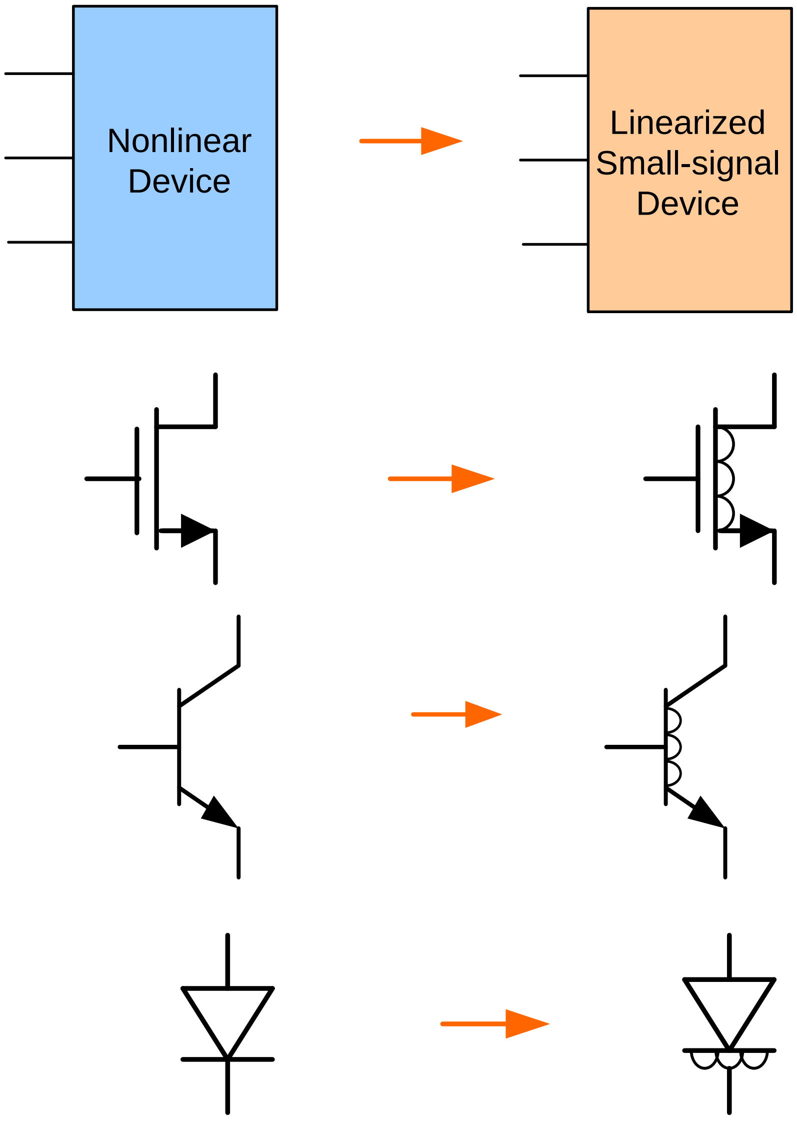
A Small Signal Equivalent Circuit



Small-signal model is a one-port

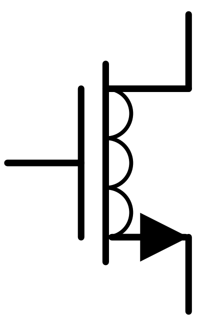
This was actually developed earlier !

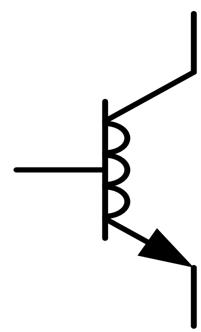
Linearized nonlinear devices

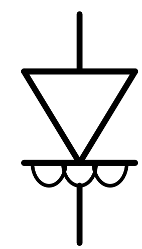


How is the small-signal equivalent circuit obtained from the nonlinear circuit?

What is the small-signal equivalent of the MOSFET, BJT, and diode ?







End of Lecture 24