### Constraint Satisfaction Problems (CSPs)

#### Outline

- I. Definition of a CSP
- II. Map coloring
- III. Job shop scheduling
- IV. The diet problem and linear programming

<sup>\*</sup> Figures/images are from the <u>textbook site</u> (or by the instructor). Otherwise, the source is cited unless such citation would make little sense due to the triviality of generating the image.

### I. Definition of a CSP

• A set of variables  $\mathcal{X} = \{X_1, ..., X_n\}$ .

• A set of domains  $\mathcal{D} = \{D_1, \dots, D_n\}$ .

Domain  $D_i = \{v_1, ..., v_{k_i}\}$  is the set of allowable values for the variable  $X_i$ . e.g.,  $\{true, false\}$  for a Boolean variable.

• A set of constraints  $C = \{C_1, ..., C_m\}$  that specifies allowable combination of values.

### Relation

•  $C_j$ :  $\langle (v_i, v_j), \text{ relation} \rangle$ 

lacktriangle a set of tuple of values for  $v_i$  and  $v_j$ 

If  $D_1 = D_2 = \{1, 2, 3\}$ , the relation " $X_1$  is greater than  $X_2$ ":

$$\langle (X_1, X_2), \{(3,1), (3,2), (2,1)\} \rangle$$

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a function that checks if a tuple satisfies the relation

$$\langle (X_1, X_2), X_1 > X_2 \rangle$$

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- consistent if no constraint is violated.
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- partial if some variables are unassigned.

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A *solution* to a CSP is a consistent, complete assignment.

A partial solution is a partial assignment that is consistent.

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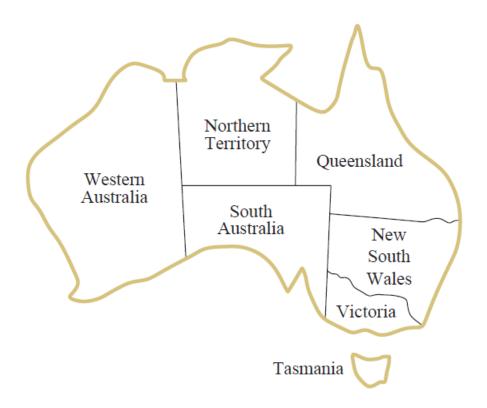
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Solving a CSP is NP-complete in general!

## II. Example 1: Map Coloring

Color the regions of Australia in red, green, or blue such that no two neighboring regions share the same color.

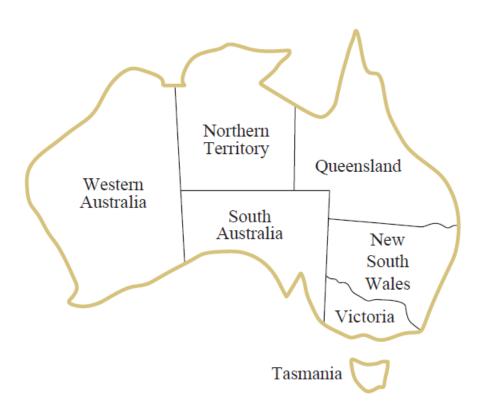


Variables:  $X = \{WA, NT, Q, NSW, V, SA, T\}$ 

Domains:  $D_i = \{red, green, blue\}$ 

## Map Coloring (cont'd)

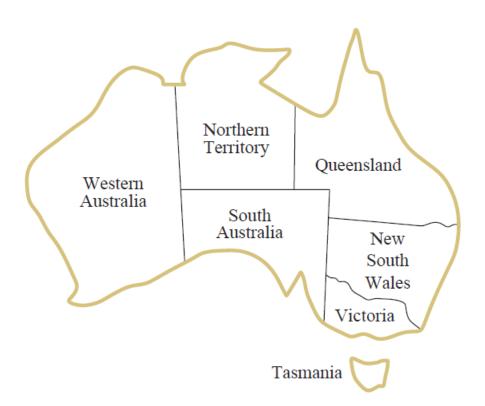
Constraints:  $C = \{SA \neq WA, SA \neq NT, SA \neq Q, SA \neq NSW, SA \neq V \\ WA \neq NT, NT \neq Q, Q \neq NSW, NSW \neq V\}$ 



## Map Coloring (cont'd)

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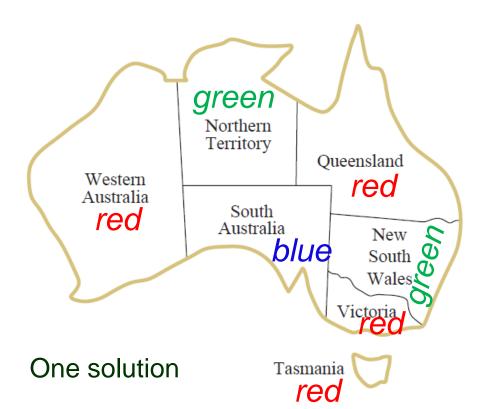
SA≠WA by enumeration: { (red, green), (red, blue), (green, red), (green, blue), (blue, red), (blue, green)}



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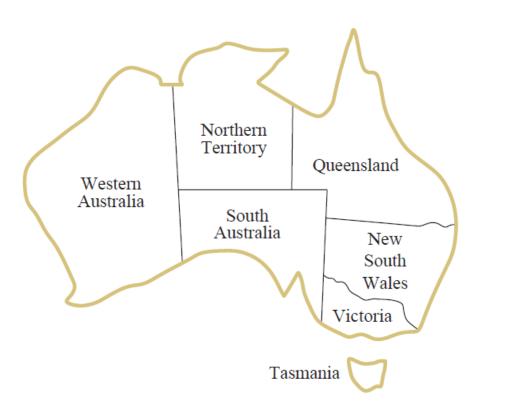
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## **Constraint Graph**

Binary constraints only.

variable ↔ vertex constraint ↔ edge



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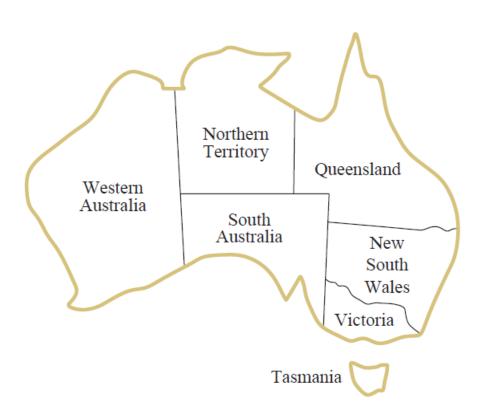
Northern Territory Queensland Western Australia South Australia New South Wales Victoria Tasmania

Constraint graph

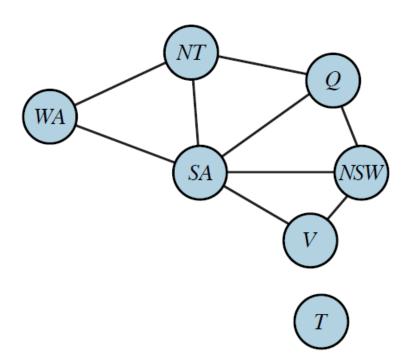
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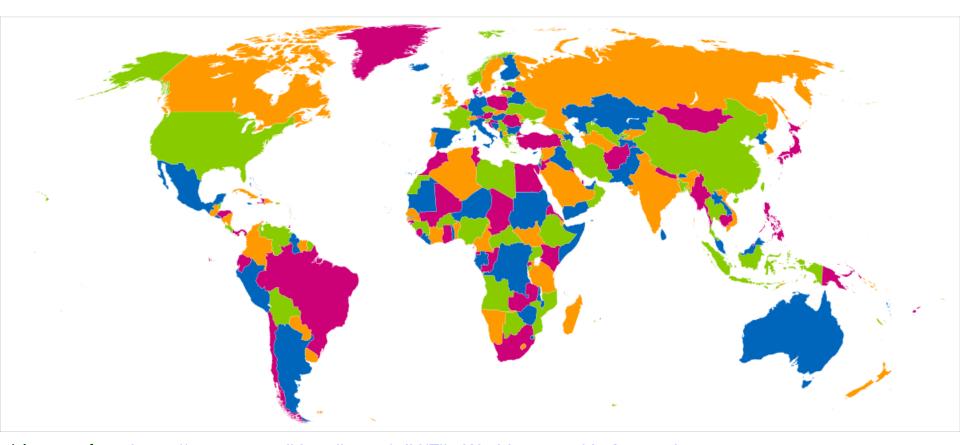


#### Constraint graph



## Four-Color Theorem

**Theorem** Any map in a plane can be colored using four colors in such a way that regions sharing a common boundary (other than a single point) do not share the same color.



<sup>\*</sup> Images from <a href="https://commons.wikimedia.org/wiki/File:World\_map\_with\_four\_colours.svg">https://commons.wikimedia.org/wiki/File:World\_map\_with\_four\_colours.svg</a> and <a href="https://geology.com/world/the-united-states-of-america-satellite-image.shtml">https://geology.com/world/the-united-states-of-america-satellite-image.shtml</a>.

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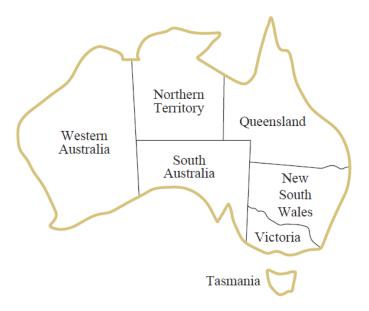


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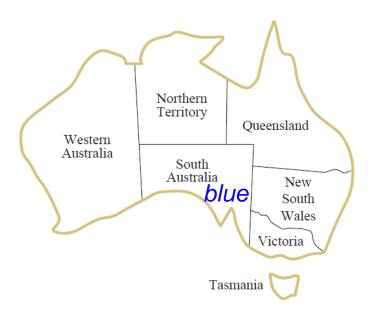
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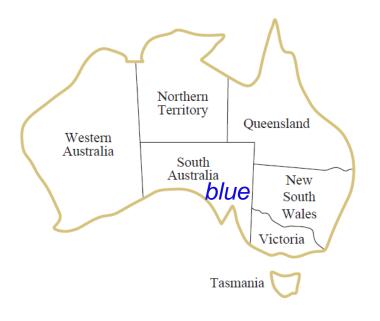


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 $2^5 = 32$  assignments to the five regions.

A reduction from  $3^5 = 243$  assignments by a search procedure not using the constraint.

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Atomic state-space search

Is this specific state a goal? If not, what about this one?

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#### Car assembly with 15 tasks:

- install axles (front and back): 2
- affix wheels (right and left, front and back): 4
- tighten nuts for each wheel: 4
- affix hubcaps: 4
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```
 \mathcal{X} = \{Axle_F, Axle_B, Wheel_{RF}, Wheel_{LF}, Wheel_{RB}, Wheel_{LB}, Nuts_{RF}, \\ Nuts_{LF}, Nuts_{RB}, Nuts_{LB}, Cap_{RF}, Cap_{LF}, Cap_{RB}, Cap_{LB}, Inspect\}.
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 $\mathcal{D}$ : time space for each variable.

 $Axle_F$  = starting time for installation of the front axle.

### **Precedence Constraints**

$$\begin{array}{c|c} T_1+d_1 \leq T_2 \\ & | & | \\ \text{starting time of task } T_1 & \text{duration of task } T_1 \end{array}$$

### **Precedence Constraints**

$$T_1 + d_1 \leq T_2$$
 
$$\mid \quad \quad \mid$$
 starting time of task  $T_1$  duration of task  $T_1$ 

♣ The axles have to be in place before the wheels are put on (axle installation takes 10 minutes).

$$Axle_F + 10 \le Wheel_{RF}$$
  $Axle_F + 10 \le Wheel_{LF}$   
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Affix each wheel (1 minutes), then tighten the nuts (2 minutes), and finally attach the hubcap (1 minute, not represented)

$$Wheel_{RF} + 1 \le Nuts_{RF}$$
  $Nuts_{RF} + 2 \le Cap_{RF}$   
 $Wheel_{LF} + 1 \le Nuts_{LF}$   $Nuts_{LF} + 2 \le Cap_{LF}$   
 $Wheel_{RB} + 1 \le Nuts_{RB}$   $Nuts_{RB} + 2 \le Cap_{RB}$   
 $Wheel_{LB} + 1 \le Nuts_{LB}$   $Nuts_{LB} + 2 \le Cap_{LB}$ 

### **More Constraints**

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 for every  $X \in \mathcal{X}$  duration of task  $X$ 

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Limit the domain of all variables (discretization)

$$\mathcal{D} = \{1, 2, \dots, 27\}$$

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 $(Axle_F + 10 \le Axle_B)$  or  $(Axle_B + 10 \le Axle_F)$ 

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Map coloring, 8-queens, scheduling (with time limits).

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Continuous domains:

Scheduling of experiments on the Hubble Telescope,

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#### IV. The Diet Problem\*

How much money to spend in order to get what Polly needs every day?

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		Energy	Protein	Calcium	Price per serving
Food	Serving size	(kcal)	(g)	(mg)	(cents)
Oat meal	28 g	110	4	2	3
$\operatorname{Chicken}$	$100~\mathrm{g}$	205	32	12	24
Eggs	2  large	160	13	54	13
Whole milk	$237   \mathrm{cc}$	160	8	285	9
Cherry pie	$170~\mathrm{g}$	420	4	22	20
Pork with beans	$260~\mathrm{g}$	260	14	80	19

<sup>\*</sup> V. Chvatal. *Linear Programming*. W. H. Freeman and Company, 1983.

# **Daily Serving Limits**

	Servings at most per day
Oatmeal	4
Chicken	3
Eggs	2
$\operatorname{Milk}$	8
Cherry pie	2
Pork with beans	2

Task: Design the most economical menu.

 $x_1$ : servings of oatmeal

 $x_3$ : servings of eggs

 $x_5$ : servings of cherry pie

 $x_2$ : servings of chicken

 $x_4$ : servings of whole milk

 $x_6$ : servings of pork with beans

	Price per serving
Food	(cents)
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subject to 
$$0 \le x_1 \le 4$$

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Servings-per-day limits

and

energy  $110x_1 + 205x_2 + 160x_3 + 160x_4 + 420x_5 + 260x_6 \ge 2000$ 

protein  $4x_1 + 32x_2 + 13x_3 + 8x_4 + 4x_5 + 14x_6 \ge 55$ 

calcium  $2x_1 + 12x_2 + 54x_3 + 285x_4 + 22x_5 + 80x_6 \ge 800$ 

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#### **Linear Program!**

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Constraints (linear)

$$\begin{array}{ll} \text{Max} & c_1x_1+c_2x_2+\cdots+c_d\ x_d \\ \\ \text{subject to} & a_{11}x_1+a_{12}x_2+\cdots+a_{1d}x_d \leq b_1 \\ & a_{21}x_1+a_{22}x_2+\cdots+a_{2d}x_d \leq b_2 \\ \\ & \vdots \\ & a_{n1}x_1+a_{n2}x_2+\cdots+a_{nd}x_d \leq b_n \end{array}$$

Max 
$$c_1x_1 + c_2x_2 + \dots + c_d x_d$$
 subject to  $a_{11}x_1 + a_{12}x_2 + \dots + a_{1d}x_d \le b_1$   $a_{21}x_1 + a_{22}x_2 + \dots + a_{2d}x_d \le b_2$   $\vdots$   $a_{n1}x_1 + a_{n2}x_2 + \dots + a_{nd}x_d \le b_n$   $\mathbf{x} = (x_1, x_2, \dots, x_d)$   $\mathbf{c} = (c_1, c_2, \dots, c_d)$   $\mathbf{b} = (b_1, b_2, \dots, b_n)$ 

Max 
$$c_1x_1 + c_2x_2 + \dots + c_d x_d = cx^T$$
 subject to  $a_{11}x_1 + a_{12}x_2 + \dots + a_{1d}x_d \le b_1$   $a_{21}x_1 + a_{22}x_2 + \dots + a_{2d}x_d \le b_2$   $\vdots$   $a_{n1}x_1 + a_{n2}x_2 + \dots + a_{nd}x_d \le b_n$   $x = (x_1, x_2, \dots, x_d)$   $c = (c_1, c_2, \dots, c_d)$   $b = (b_1, b_2, \dots, b_n)$ 

$$\begin{array}{ll} \text{Max} & c_1x_1+c_2x_2+\dots+c_d \ x_d & = \boldsymbol{c}\boldsymbol{x}^T \\ \\ \text{subject to} & a_{11}x_1+a_{12}x_2+\dots+a_{1d}x_d \leq b_1 \\ & a_{21}x_1+a_{22}x_2+\dots+a_{2d}x_d \leq b_2 \\ & \vdots \\ & a_{n1}x_1+a_{n2}x_2+\dots+a_{nd}x_d \leq b_n \end{array} \right\} \quad \boldsymbol{A}\boldsymbol{x}^T \leq \boldsymbol{b}^T \\ \boldsymbol{x} = (x_1,x_2,\dots,x_d) \\ \boldsymbol{c} = (c_1,c_2,\dots,c_d) \\ \boldsymbol{b} = (b_1,b_2,\dots,b_n)$$

$$\begin{array}{ll} \text{Max} & c_1x_1 + c_2x_2 + \cdots + c_d \; x_d \\ \\ \text{subject to} & a_{11}x_1 + a_{12}x_2 + \cdots + a_{1d}x_d \leq b_1 \\ & a_{21}x_1 + a_{22}x_2 + \cdots + a_{2d}x_d \leq b_2 \\ & \vdots \\ & a_{n1}x_1 + a_{n2}x_2 + \cdots + a_{nd}x_d \leq b_n \end{array} \right] \quad A \pmb{x}^T \leq \pmb{b}^T$$

$$\mathbf{x} = (x_1, x_2, ..., x_d)$$
  
 $\mathbf{c} = (c_1, c_2, ..., c_d)$   
 $\mathbf{b} = (b_1, b_2, ..., b_n)$ 

Solvable in time polynomial in d.

$$\begin{array}{ll} \text{Max} & c_1x_1 + c_2x_2 + \cdots + c_d \; x_d \\ \\ \text{subject to} & a_{11}x_1 + a_{12}x_2 + \cdots + a_{1d}x_d \leq b_1 \\ & a_{21}x_1 + a_{22}x_2 + \cdots + a_{2d}x_d \leq b_2 \\ & \vdots \\ & a_{n1}x_1 + a_{n2}x_2 + \cdots + a_{nd}x_d \leq b_n \end{array} \right] \quad A \pmb{x}^T \leq \pmb{b}^T$$

$$\mathbf{x} = (x_1, x_2, ..., x_d)$$
  
 $\mathbf{c} = (c_1, c_2, ..., c_d)$   
 $\mathbf{b} = (b_1, b_2, ..., b_n)$ 

Solvable in time polynomial in d.

$$\text{Max} \quad c_1 x_1 + c_2 x_2 + \dots + c_d \; x_d \qquad \qquad = \boldsymbol{c} \boldsymbol{x}^T$$
 subject to 
$$\begin{array}{l} a_{11} x_1 + a_{12} x_2 + \dots + a_{1d} x_d \leq b_1 \\ a_{21} x_1 + a_{22} x_2 + \dots + a_{2d} x_d \leq b_2 \\ \vdots \\ a_{n1} x_1 + a_{n2} x_2 + \dots + a_{nd} x_d \leq b_n \end{array} \right] \quad \boldsymbol{A} \boldsymbol{x}^T \leq \boldsymbol{b}^T$$
 
$$\boldsymbol{x} = (x_1, x_2, \dots, x_d)$$
 
$$\boldsymbol{c} = (c_1, c_2, \dots, c_d)$$

 $\mathbf{b} = (b_1, b_2, ..., b_n)$ 

Solvable in time polynomial in *d*.

Simplex method  $O(2^d)$  (best performance in practice)

$$\text{Max} \quad c_1 x_1 + c_2 x_2 + \dots + c_d \; x_d \qquad \qquad = \boldsymbol{c} \boldsymbol{x}^T$$
 subject to 
$$\begin{array}{l} a_{11} x_1 + a_{12} x_2 + \dots + a_{1d} x_d \leq b_1 \\ a_{21} x_1 + a_{22} x_2 + \dots + a_{2d} x_d \leq b_2 \\ \vdots \\ a_{n1} x_1 + a_{n2} x_2 + \dots + a_{nd} x_d \leq b_n \end{array} \right] \quad \boldsymbol{A} \boldsymbol{x}^T \leq \boldsymbol{b}^T$$
 
$$\boldsymbol{x} = (x_1, x_2, \dots, x_d)$$
 
$$\boldsymbol{c} = (c_1, c_2, \dots, c_d)$$

 $\mathbf{b} = (b_1, b_2, ..., b_n)$ 

Simplex method  $O(2^d)$  (best performance in practice)

Solvable in time polynomial in d.