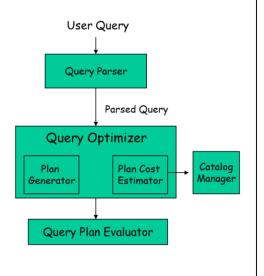
### Overview of Query Evaluation

- A user query is expressed using SQL or other languages, ideally natural languages
- A parsed query is essentially treated as a relational algebra expression
  - Selection (б)
  - Join (⋈)
  - Project(Π)
  - Union, intersection and difference, cross product
- · Query optimizer
  - Enumerates the possible plans to evaluate expression,
  - Select a small subset of these plans and estimate their cost



### Query Blocks: Units of Optimization

- An SQL query is parsed into a collection of *query blocks*, and these are optimized one block at a time.
  - A query block is an SQL query with no nesting and exactly one SELECT clause and one FROM clause and at most one WHERE clause, etc.
- Nested blocks are usually treated as calls to a subroutine, made once per outer tuple.
  - This is an over-simplification, but serves for now.

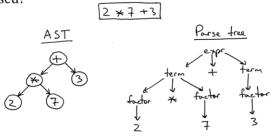
SELECT S.sname
FROM Sailors S
WHERE S.age IN
(SELECT MAX (S2.age)
FROM Sailors S2
GROUP BY S2.rating)

Outer block

Nested block

#### Relational Algebra Tree and Evaluation Plan

- A plan consists of an extended relational algebra tree
  - Similar to a parse tree for an arithmetic expression
- Additional annotations are used to indicated the access and/or implementation method
  - Plan with/without indexes, etc.
- Problems
  - Which access method should be used for an operation?
  - Which plan should be used?



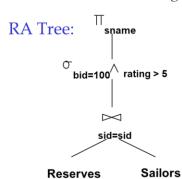
- 1) query block
- 2) each block is translated into a relational algbraic expression
- 3) each expresison is represented by a tree
- 4) each tree can have a number of execution plans because of relational algebra equivalence
- 5) The number of plans is large
- 6) Estimating each plan needs to sovle these issues: estimate the cost each operator and the output size
- 7) General strategy is 1) do selection as early as possible; 2) do projection as early as possible; 3) do join last
- 8) when do join, consider only left-deep plans

Sailors(<u>sid</u>, sname, rating, age) Boats(<u>bid</u>, bname, color) Reserve(<u>sid</u>, <u>bid</u>, <u>day</u>)

Find the names of sailors who reserve a boat with bid = 100 and whose rating is greater than 5

SELECT S.sname
FROM Reserves R, Sailors S
WHERE R.sid=S.sid AND
R.bid=100 AND S.rating>5

 $\Pi_{sname}(\sigma_{bid=100 \land rating>5}(\text{Re}\,serve \, \triangleright \triangleleft_{sid=sid} \, Sailors)$ 

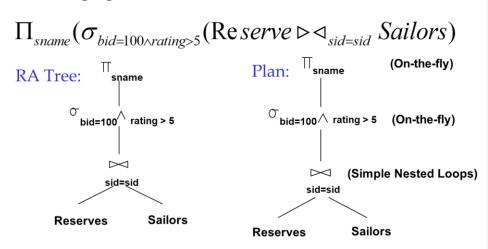


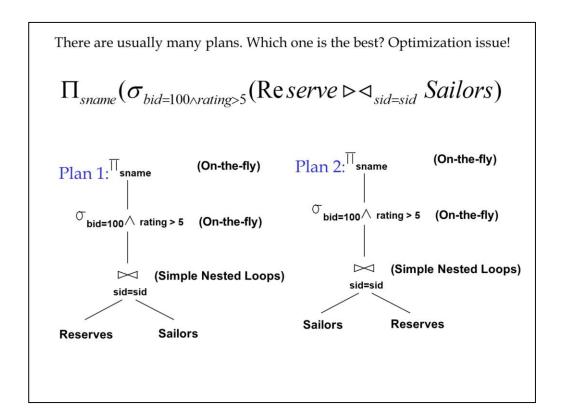
A plan is a tree with annotations that specify the access method for each operator

Sailors(<u>sid</u>, sname, rating, age) Boats(<u>bid</u>, bname, color) Reserve(<u>sid</u>, <u>bid</u>, <u>day</u>)

Find the names of sailors who reserve a boat with bid = 100 and whose rating is greater than 5

SELECT S.sname
FROM Reserves R, Sailors S
WHERE R.sid=S.sid AND
R.bid=100 AND S.rating>5





Question 1: are they the same?

Question 2: which one might be faster?

There are usually many plans. Which one is the best? Optimization issue!  $\Pi_{\mathit{sname}}(\sigma_{\mathit{bid}=100 \land \mathit{rating} > 5}(\mathsf{Re}\,\mathit{serve} \, \triangleright \, \triangleleft_{\mathit{sid}=\mathit{sid}}\, \mathit{Sailors})$ Plan: Tsname (On-the-fly) Plan 3: ∏<sub>sname</sub> (On-the-fly) O bid=100 A rating > 5 (On-the-fly) (Simple Nested Loops) sid=sid (Simple Nested Loops) O bid=100 rating > 5 sid=sid (On-the-fly) (On-the-fly) Sailors Reserves Sailors Reserves

### Relational Algebra Equivalences

- Allow us to choose different join orders and to `push' selections and projections ahead of joins
- Selections  $\sigma_{c1\wedge...\wedge cn}(R) \equiv \sigma_{c1}(\ldots \sigma_{cn}(R))$  (Cascade)  $\sigma_{c1}(\sigma_{c2}(R)) \equiv \sigma_{c2}(\sigma_{c1}(R))$  (Commute)
- Projections:  $\pi_{a1}(R) \equiv \pi_{a1}(\dots(\pi_{an}(R)))$  (Cascade)
- Joins:  $R \bowtie (S \bowtie T) \equiv (R \bowtie S) \bowtie T$  (Associative)  $(R \bowtie S) \equiv (S \bowtie R)$  (Commute)
  - Show that:  $R \bowtie (S \bowtie T) \equiv (T \bowtie R) \bowtie S$

Question 1: think about what those symbols mean

Question 2: think about why they are the same

## More Equivalences To Explore

$$\sigma_{C \text{ AND } C'}(R) = \sigma_{C}(\sigma_{C'}(R)) = \sigma_{C}(R) \cap \sigma_{C'}(R)$$

$$\sigma_{C \text{ OR } C'}(R) = \sigma_{C}(R) \cup \sigma_{C'}(R)$$

$$\sigma_{C}(R \bowtie S) = \sigma_{C}(R) \bowtie S$$

Example: R(A, B, C, D), S(E, F, G) 
$$\sigma_{F=3}(R \bowtie_{D=E} S) = ?$$
 
$$\sigma_{A=5 \text{ AND } G=9}(R \bowtie_{D=E} S) = ?$$

### More Equivalences

- A projection commutes with a selection that only uses attributes retained by the projection
- Selection between attributes of the two arguments of a cross-product converts cross-product to a join
- A selection on just attributes of R commutes with  $R \bowtie S$  (i.e.,  $\sigma(R \bowtie S) \equiv \sigma(R) \bowtie S$ )
- Similarly, if a projection follows a join R ⋈ S, we can `push' it by retaining only attributes of R (and S) that are needed for the join or are kept by the projection

# Challenges of Query Optimization

- Two main issues:
  - For a given query, what plans are considered?
    - Search space is huge
  - How to estimate the cost of a plan?
- Solutions
  - Ideally: find best plan
  - Practically: avoid worst plans

### Highlights of IBM System R Optimizer (1979)

- Impact
  - Most widely used currently; works well for < 10 joins
- Cost estimation
  - Statistics, maintained in system catalogs, used to estimate cost of operations and result sizes
  - Considers combination of CPU and I/O costs
- Plan Space
  - Only the space of left-deep plans is considered
    - Left-deep plans allow output of each operator to be *pipelined* into the next operator without storing it in a temporary relation
  - Cartesian products avoided

#### **Cost Estimation**

- Given a plan, we need to
  - Estimate *cost* of each operation in plan tree
    - Use the information recorded in statistics and system catalogs
    - Depends on input cardinalities
    - We've already discussed how to estimate the cost of operations (sequential scan, index scan, joins, etc.)
  - Estimate *size of result* for each operation in tree
    - Use information about the input relations
    - For selections and joins, assume independence of predicates

## **System Catalogs**

- For each relation:
  - name, file name, file structure (e.g., Heap file)
  - attribute name and type, for each attribute
  - index name, for each index
  - integrity constraints
- For each index:
  - structure (e.g., B+ tree) and search key fields
- · For each view:
  - view name and definition
- Plus statistics, authorization, buffer pool size, etc.

Catalogs are themselves stored as relations!

### Statistics stored in Catalog

- Cardinality
  - Number of tuples/rows NTuples(R) for each relation R
- Size
  - Number of pages NPages(R) for each relation R
- · Index Cardinality
  - Number of distinct key values NKeys(I) for each index I
- Index Size
  - Number of pages INPages(I) for each index I
  - For example, for a B+ tree index, we take the number of leaf pages to be the index size
- Index Height
  - Number of nonleaf levels IHeight(I) for each tree index I
- Index Range
  - The minimum present key value ILow(I) and the maximum present key value IHigh(I) for each index I

These statistics are updated periodically

#### Size Estimation and Reduction Factors

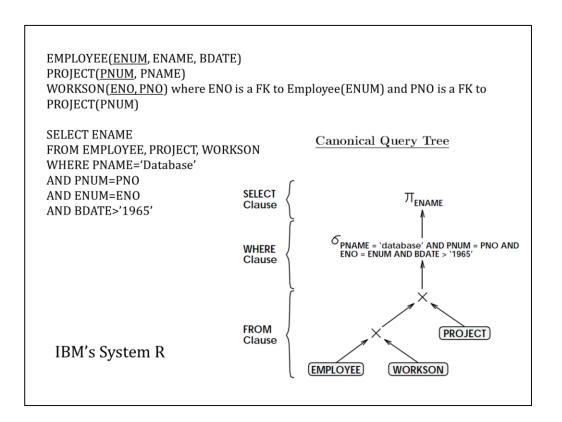
• Consider a query block:

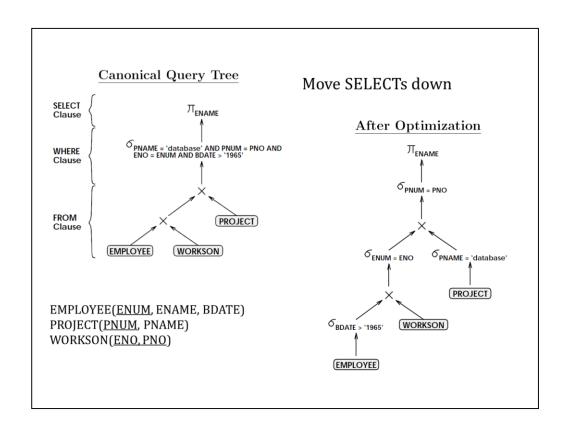
SELECT attribute list
FROM relation list
WHERE term1 AND ... AND termk

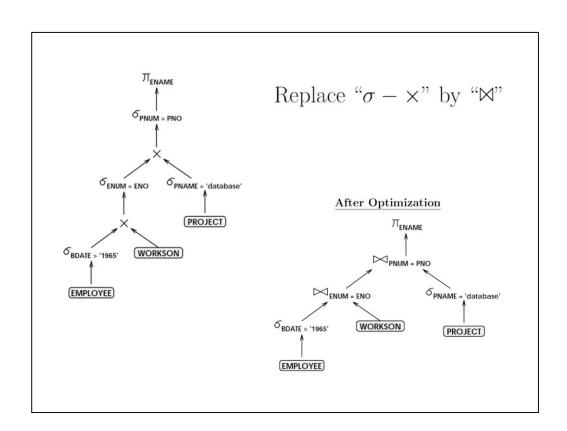
- Maximum # tuples in result is the product of the cardinalities of relations in the FROM clause
- Reduction factor (RF) associated with each term reflects the impact of the term in reducing result size
- Result cardinality = Max # tuples \* product of all RF's.
  - Implicit assumption that terms are independent!
  - Term col=value has RF 1/NKeys(I), given index I on col
  - Term col1=col2 has RF 1/MAX(NKeys(I1), NKeys(I2))
  - Term col>value has RF (High(I)-value)/(High(I)-Low(I))

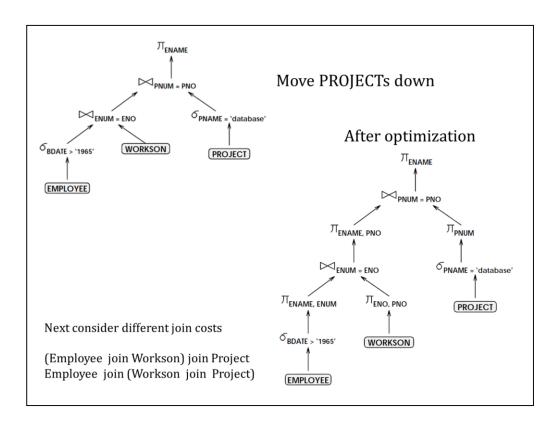
### **Optimization Strategies**

- Move SELECTs and PROJECTS as far down as possible
- Among the SELECTs, order them such that the lowest selectivity factor is performed first
- Among Joins, order them such that the join with the lowest join selectivity factor is performed first









Question: Can you recall the cost of join?

### Join Optimization

• Consider just three relations R, S, and T

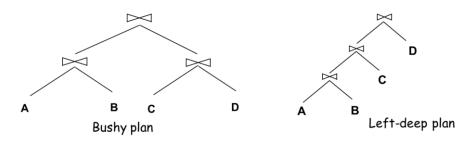
The number of different join orderings of n relations is exponentially large !!!

(Because the number of permutations is exponentially large)

- The number of *possible* join trees to consider is just *too* large
- We need to reduce the search space....

#### Plans to consider

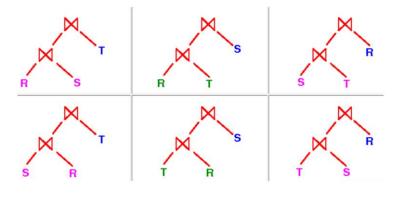
- Fundamental decision in System R: <u>only left-deep</u> <u>join trees</u> are considered.
  - As the number of joins increases, the number of alternative plans grows rapidly; we need to restrict the search space.
  - Left-deep trees allow us to generate all *fully pipelined* plans.
    - Intermediate results not written to temporary files.



# Three-way Join



• Possible left-deep join trees:



### **Enumeration of Left-Deep Plans**

- Left-deep plans differ only in the order of relations, the access method for each relation, and the join method for each join
- Enumerated using N passes (if N relations joined):
  - Pass 1: Find best 1-relation plan for each relation
  - Pass 2: Find best way to join result of each 1-relation plan (as outer) to another relation (All 2-relation plans)
  - Pass N: Find best way to join result of a (N-1)-relation plan (as outer) to the N'th relation *(All N-relation plans)*
- For each subset of relations, retain only:
  - Cheapest plan overall, plus
  - Cheapest plan for each interesting order of the tuples
- In spite of pruning plan space, this approach is still exponential in the #
  of tables. (works well for most queries with less than 15 tables)
- ORDER BY, GROUP BY, aggregates etc. handled as a final step, using either an `interestingly ordered' plan or an additional sorting operator.

Pass 1 question: what access methods should be used for this selection? (B+ tree? Hash index? Sequential scan?)

Pass2 question: which two relations should join? How to join?

### Summary

- Two parts to optimize a query
  - Consider a set of alternative plans, typically, left-deep plans only
  - Must estimate cost of each plan that is considered
    - Must estimate size of result and cost for each plan node
    - Key issues: Statistics, indexes, operator implementations
- Single-relation queries
  - All access paths considered, cheapest is chosen
  - Issues: Selections that match index, whether index key has all needed fields and/or provides tuples in a desired order
- Multiple-relation queries
  - All single-relation plans are first enumerated
    - Selections/projections considered as early as possible
  - For each 1-relation plan, all ways of joining another relation are considered
  - For each 2-relation plan that is `retained', all ways of joining another relation are considered, etc.