

Propositional Model Checking

Outline

I. Horn Clauses

II. Effective Propositional Model Checking

III. Agents Based on Propositional Logic

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(cont'd)

- ♦ Inferences with Horn clauses are through forward- and backward-chaining algorithms.

Logic programming

(natural inference steps easy for humans to follow)

- ♦ Low computational complexity: deciding entailment with Horn clauses takes $O(n)$ time.

|
size of the KB

Forward Chaining

Question $KB \models q?$

|
single proposition
symbol

- Begins from positive literals (facts).
- If all the premises of an implications are known, then add its conclusion to KB (as a new fact).
- Continues until q is added or no further inferences can be made.

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function PL-FC-ENTAILS?(KB, q) **returns** *true* or *false*

inputs: KB , the knowledge base, a set of propositional definite clauses

q , the query, a proposition symbol

$count \leftarrow$ a table, where $count[c]$ is initially the number of symbols in clause c 's premise

$inferred \leftarrow$ a table, where $inferred[s]$ is initially *false* for all symbols

$queue \leftarrow$ a queue of symbols, initially symbols known to be true in KB

while $queue$ is not empty **do**

$p \leftarrow \text{POP}(queue)$

if $p = q$ **then return** *true*

if $inferred[p] = false$ **then**

$inferred[p] \leftarrow true$

for each clause c in KB where p is in c .PREMISE **do**

 decrement $count[c]$

if $count[c] = 0$ **then** add c .CONCLUSION to $queue$

return *false*

Example of Forward Chaining

KB:

$$P \Rightarrow Q$$

$$L \wedge M \Rightarrow P$$

$$B \wedge L \Rightarrow M$$

$$A \wedge P \Rightarrow L$$

$$A \wedge B \Rightarrow L$$

A

B

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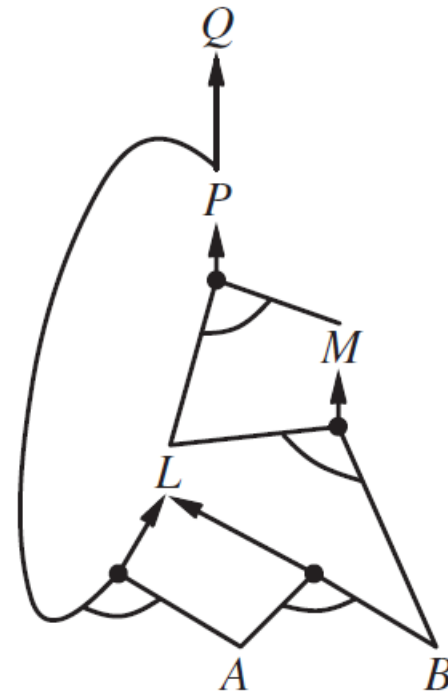
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AND-OR graph representation



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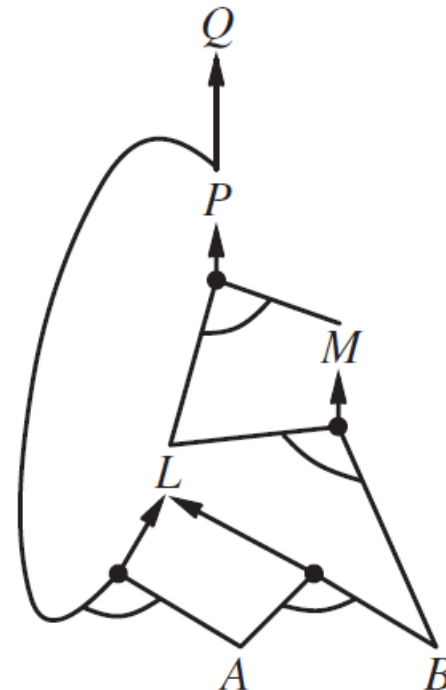
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Q. $KB \models Q$?

Execution

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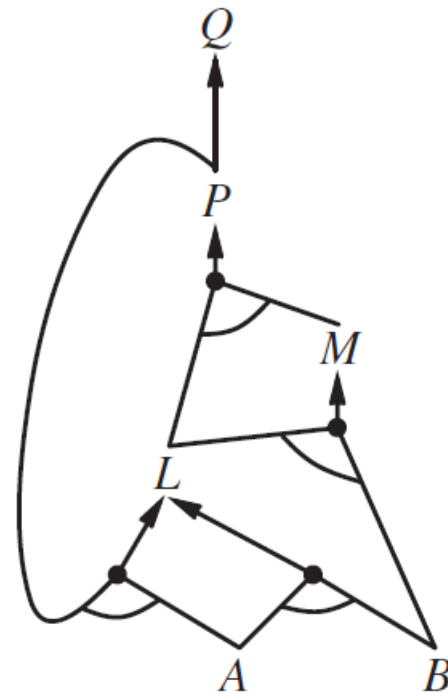
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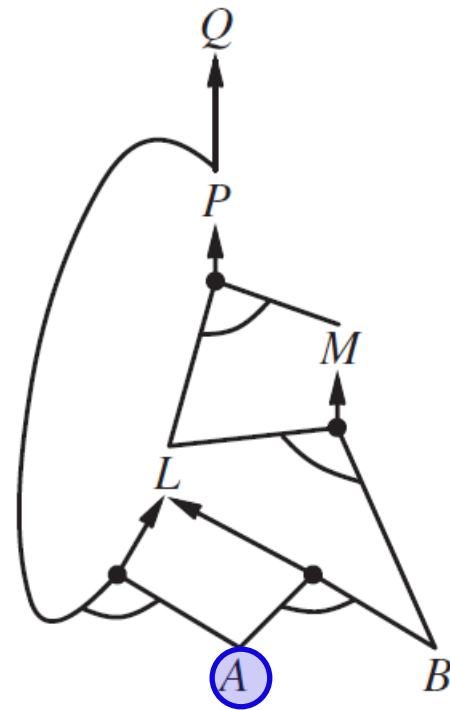
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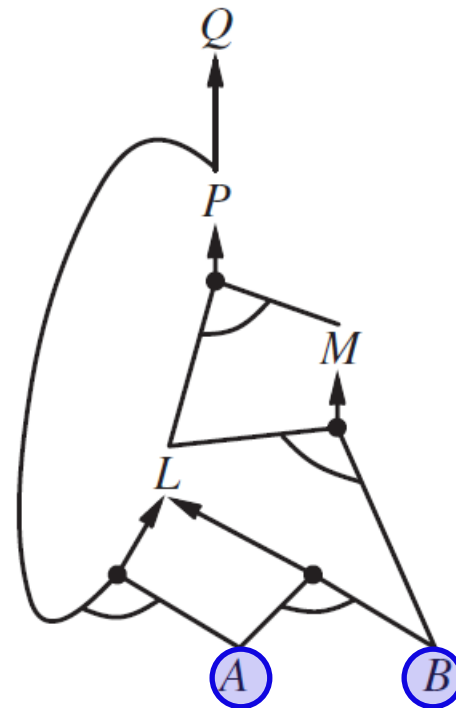
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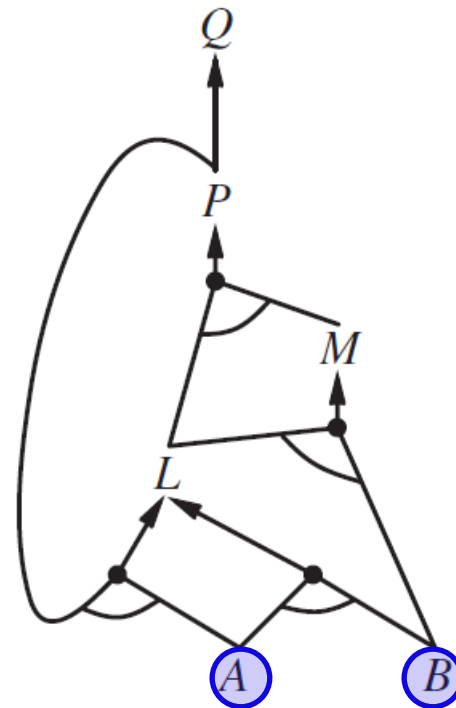
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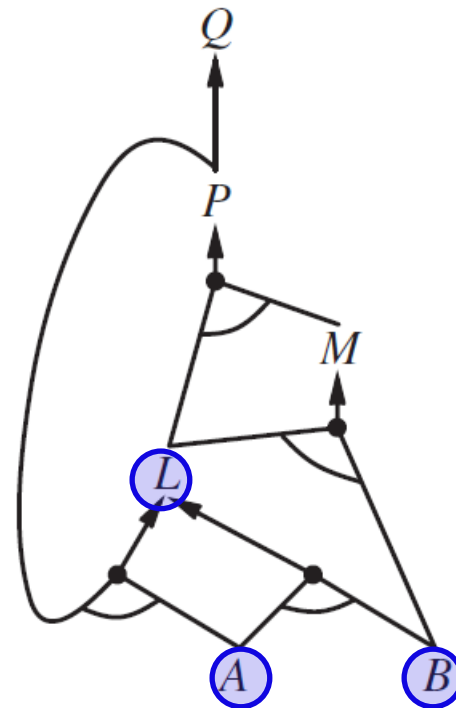
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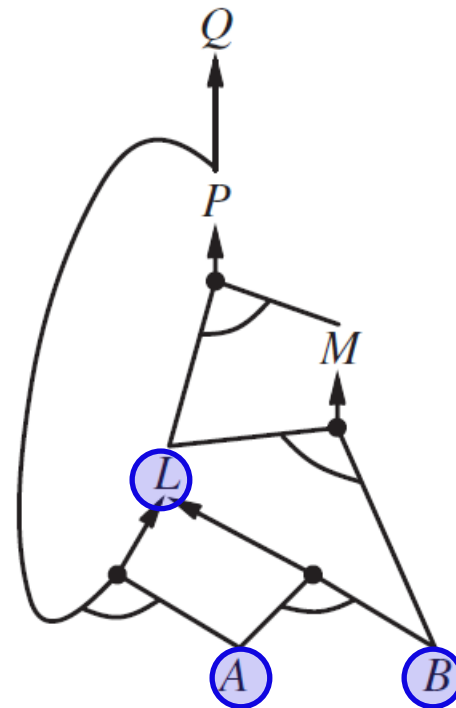
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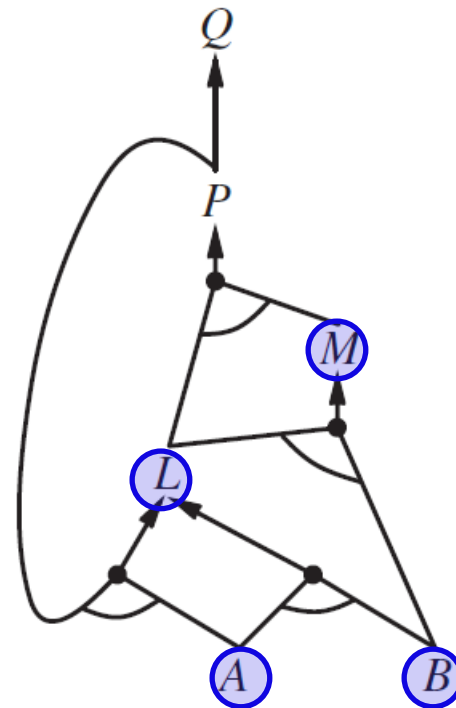
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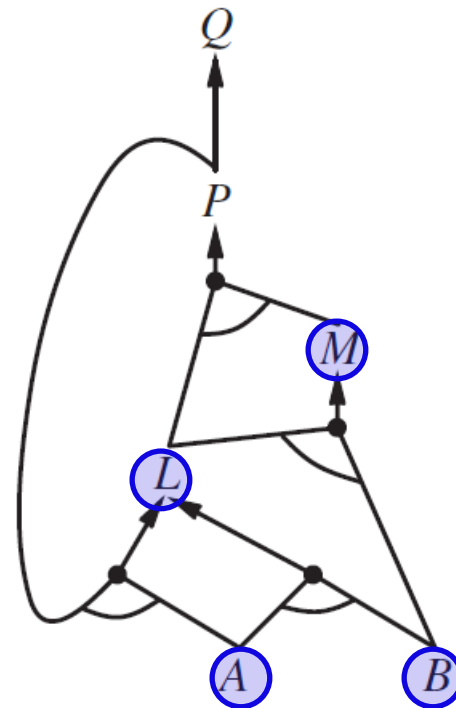
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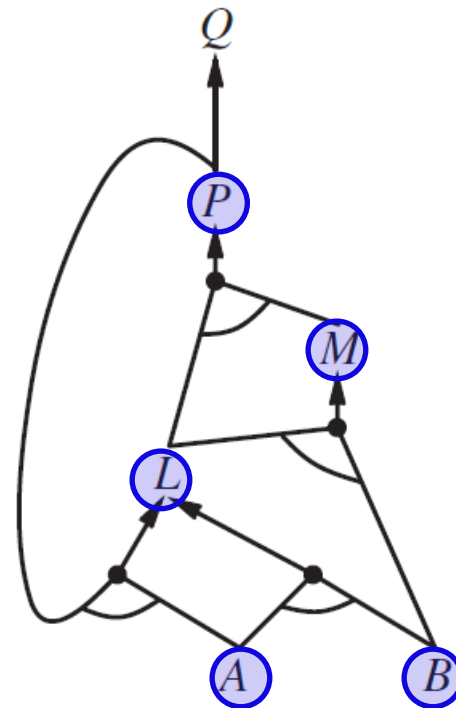
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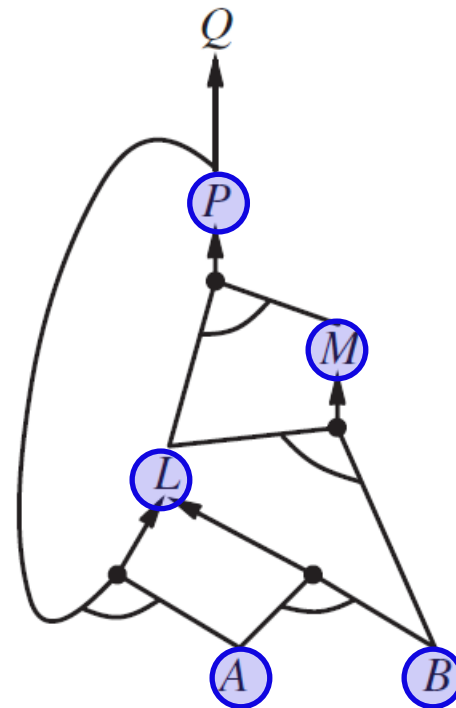
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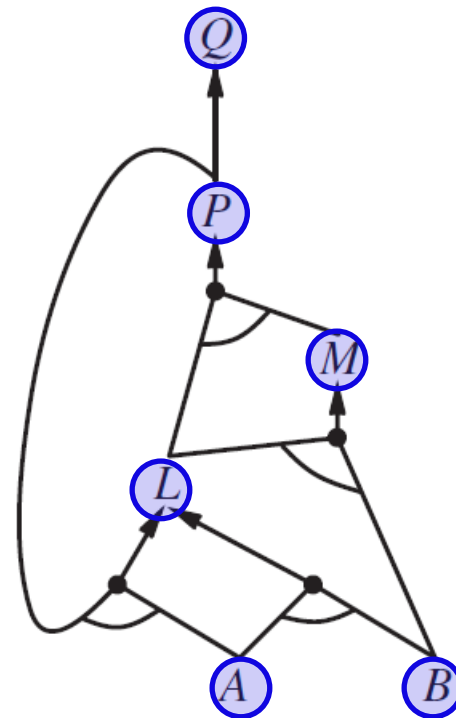
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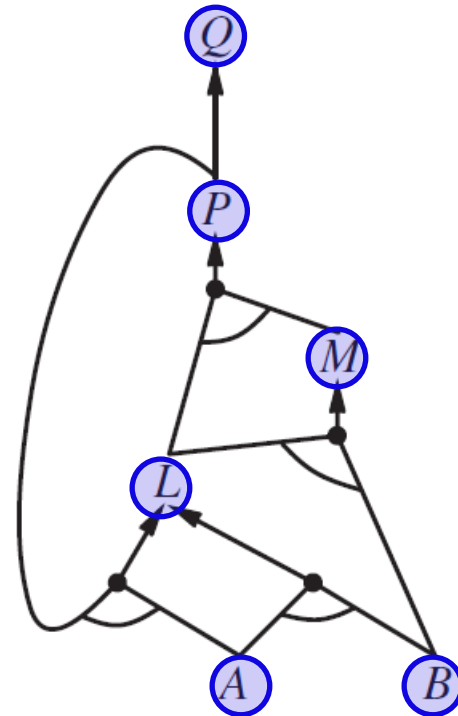
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Soundness of forward chaining: every inference is an application of Modus Ponens.

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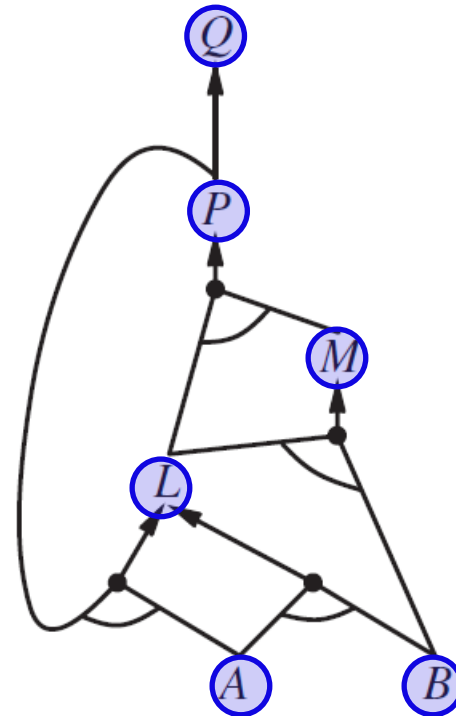
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Completeness: every entailed atomic sentences will be derived.

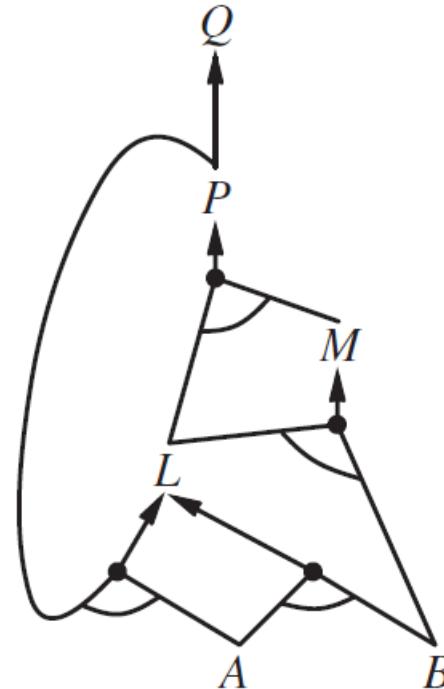
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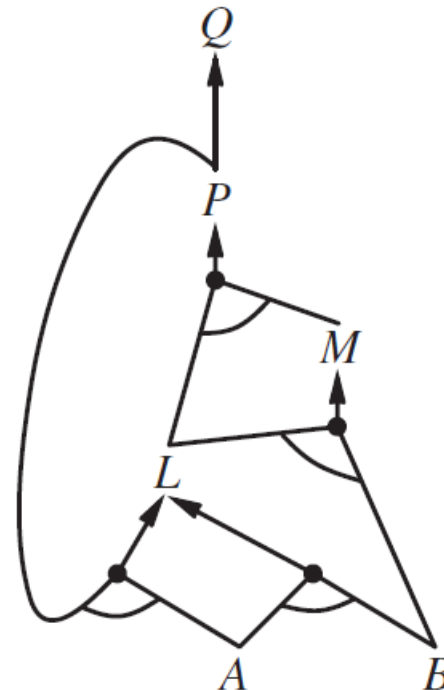


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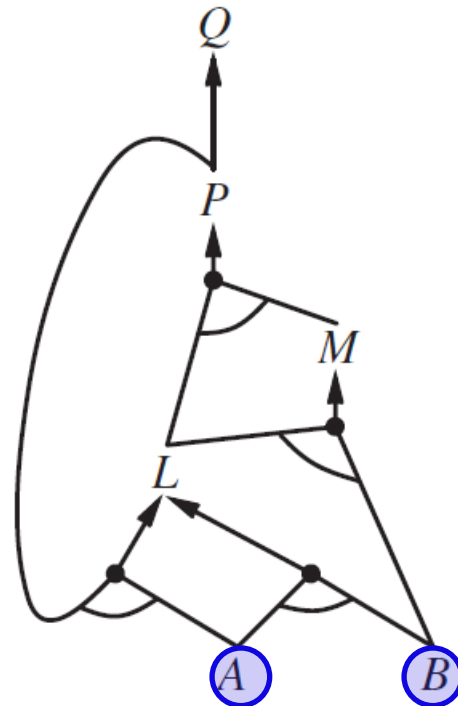


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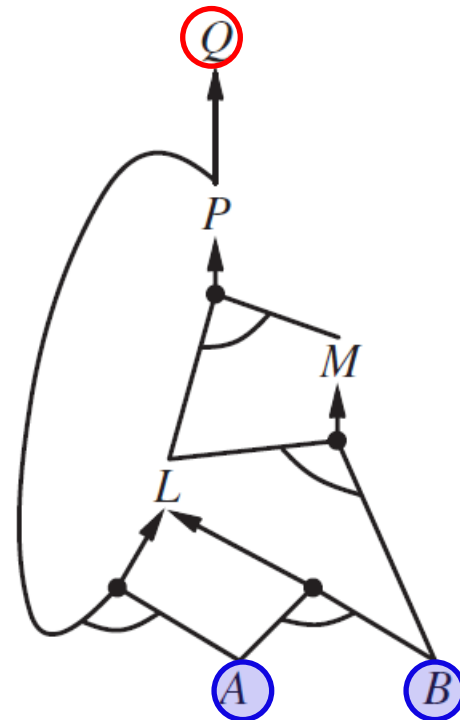
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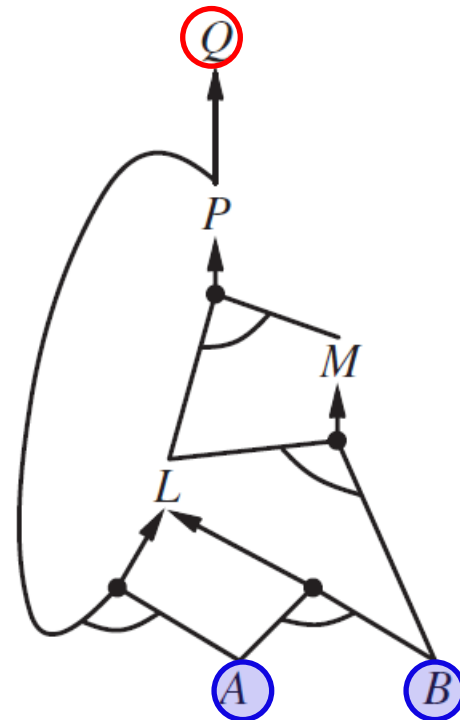
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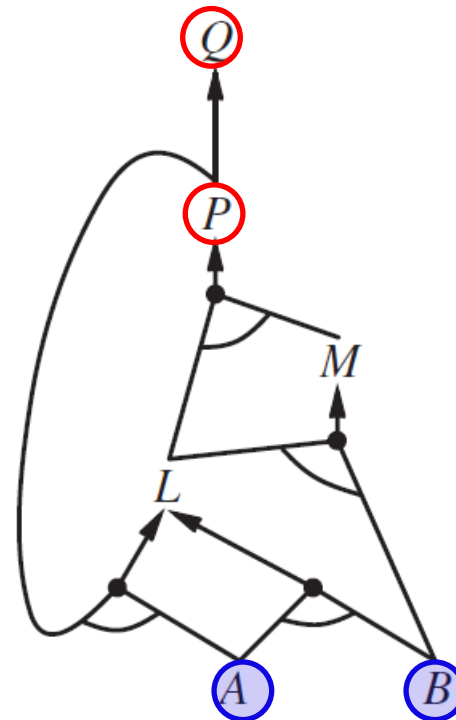
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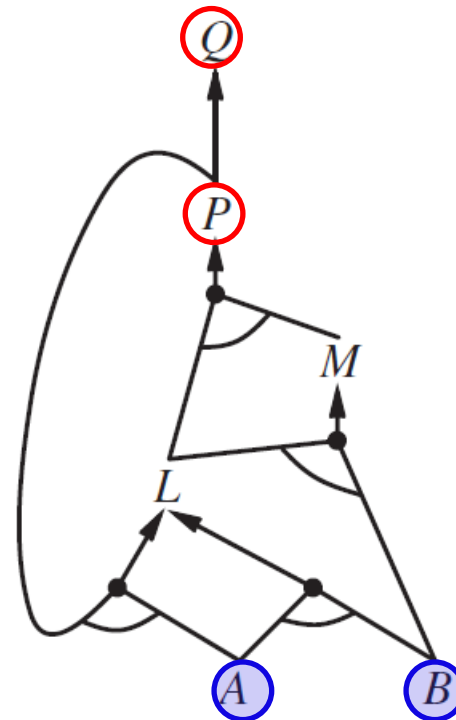
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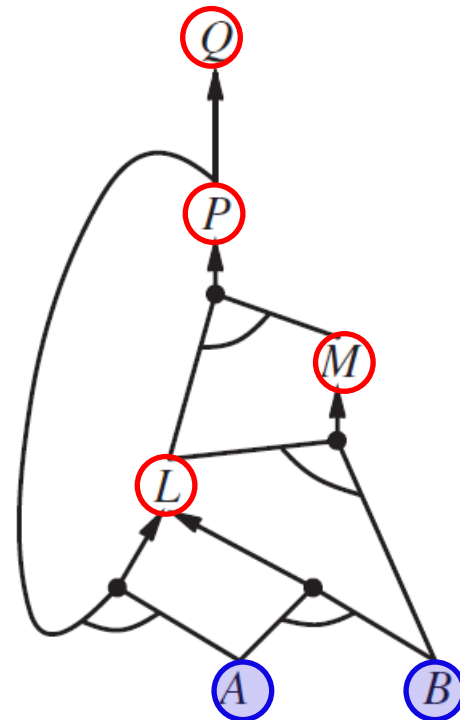
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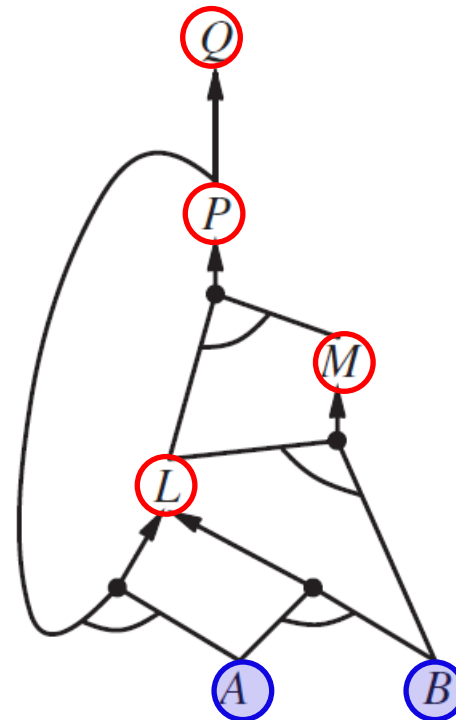


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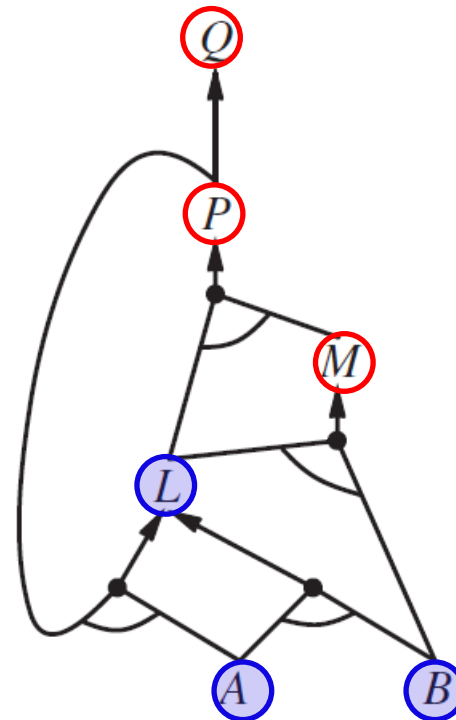


Backward Chaining

- If q is true, no work is needed.
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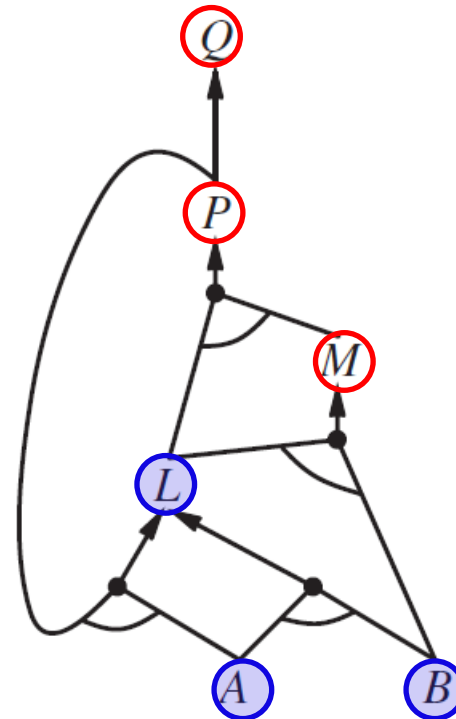


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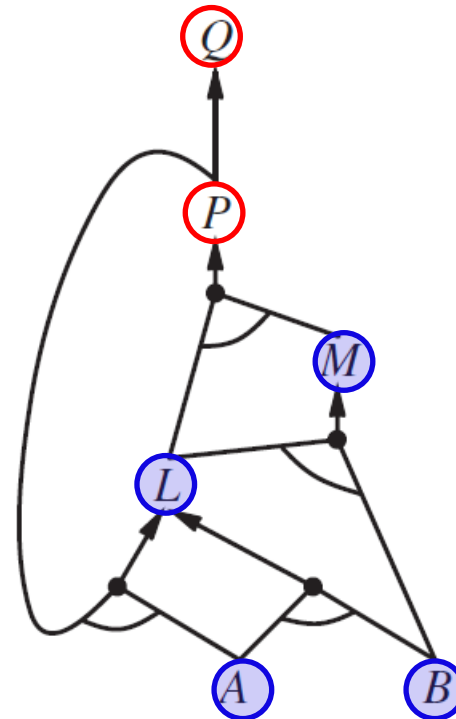


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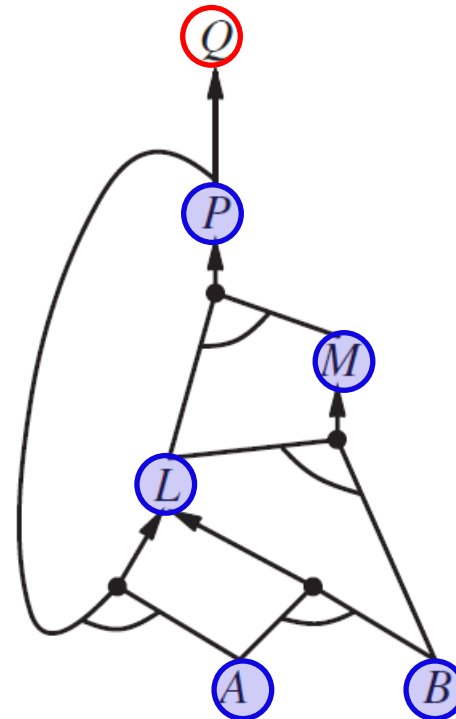


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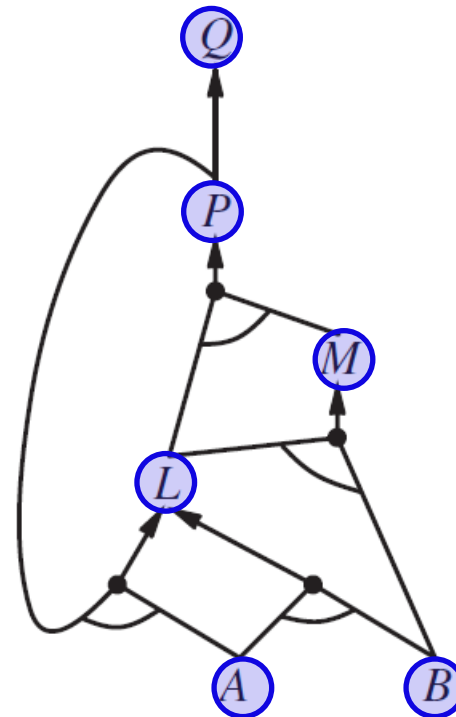


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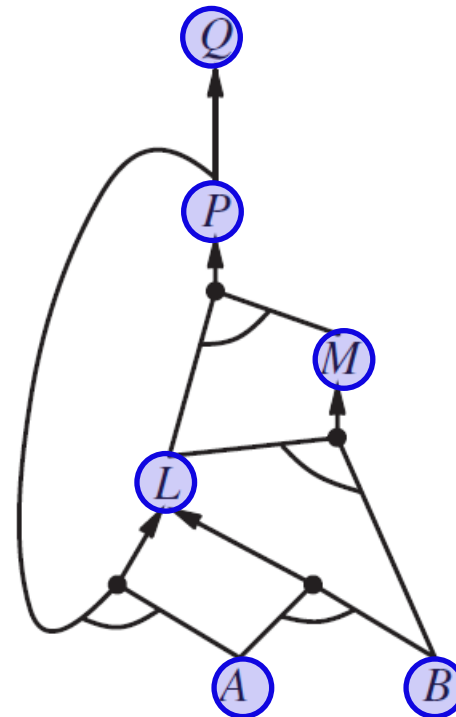


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AND-OR graph search!

Forward vs. Backward Chaining

- ◆ Forward chaining is *data-driven*, automatic, unconscious processing.
- ◆ It may perform a lot of work that is irrelevant to the goal.
- ◆ Backward chaining is *goal-driven*, and appropriate for problem solving.
- ◆ It may run in time sublinear in the size of KB, since it touches only relevant facts.

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II. Effective Propositional Model Checking

$KB \models \beta$ if and only if $KB \wedge \neg\beta$ is unsatisfiable.

- Cast the problem as one of constraint satisfaction.

Many combinatorial problems in computer science can be reduced to checking the satisfiability of a propositional sentence.

- ♦ Complete backtracking search (DPLL algorithm)
- ♦ Incomplete local search (WALKSAT algorithm)

DPLL Algorithm

Davis, Putnam, Logemann, and Loveland (1960, 1962)

With enhancements, modern solvers can handle a problem with a multiple of 10^7 variables.

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function DPLL-SATISFIABLE?(*s*) **returns** *true* or *false*

inputs: *s*, a sentence in propositional logic

clauses \leftarrow the set of clauses in the CNF representation of *s*

symbols \leftarrow a list of the proposition symbols in *s*

return DPLL(*clauses*, *symbols*, { })

function DPLL(*clauses*, *symbols*, *model*) **returns** *true* or *false*

if every clause in *clauses* is true in *model* **then return** *true*

if some clause in *clauses* is false in *model* **then return** *false*

P, *value* \leftarrow FIND-PURE-SYMBOL(*symbols*, *clauses*, *model*)

if *P* is non-null **then return** DPLL(*clauses*, *symbols* – *P*, *model* \cup {*P*=*value*})

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Unit clause propagation on a clause in which all literals but one are assigned **false**. E.g., $\neg B \vee \neg C$ simplifies to the unit clause $\neg C$ if *B* = **true**.

Local Search Algorithms

- Take steps in the space of complete assignments, flipping the truth value of one symbol at a time.
- Use an evaluation that counts the number of unsatisfied clauses.
- Escape local minima using various forms of randomness.
- Find a good balance between greediness and randomness.

The WALKSAT Algorithm

function WALKSAT(*clauses*, *p*, *max_flips*) **returns** a satisfying model or *failure*
inputs: *clauses*, a set of clauses in propositional logic
 p, the probability of choosing to do a “random walk” move, typically around 0.5
 max_flips, number of value flips allowed before giving up

model \leftarrow a random assignment of *true/false* to the symbols in *clauses*
for each *i* = 1 **to** *max_flips* **do**
 if *model* satisfies *clauses* **then return** *model*
 clause \leftarrow a randomly selected clause from *clauses* that is false in *model*
 if RANDOM(0, 1) $\leq p$ **then**
 flip the value in *model* of a randomly selected symbol from *clause*
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III. Agent Based on Propositional Logic

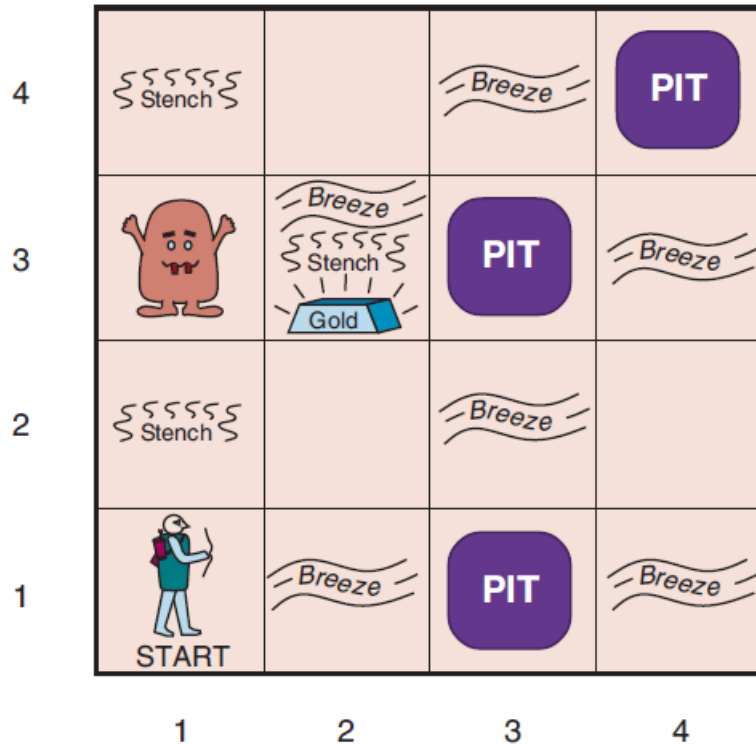
- Write down a complete **logical model** of the effects of action.
- How **logical inference** can be used by an agent?.
- How to keep track of the world without resorting to **inference** history?
- How to use **logical inference** to construct plans based on the KB?

Knowledge base (KB):

♣ general knowledge about how the world works

♣ percept sentences obtained in a particular world

Current State in the Wumpus World



Axioms:

$$\neg P_{1,1}$$

$$\neg W_{1,1}$$

$$B_{1,1} \Leftrightarrow (P_{1,2} \vee P_{2,1})$$

// 16 rules of this type

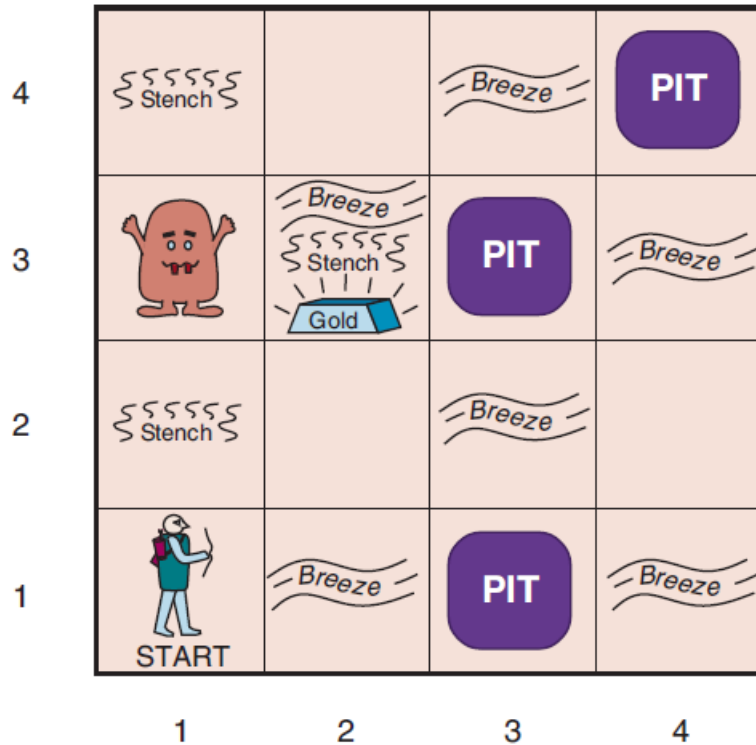
$$S_{1,1} \Leftrightarrow (W_{1,2} \vee W_{2,1})$$

// 16

...

- $P_{x,y} = \text{true}$ if there is a pit in $[x, y]$.
- $W_{x,y} = \text{true}$ if there is a wumpus in $[x, y]$, dead or alive.
- $B_{x,y} = \text{true}$ if the agent perceives a breeze in $[x, y]$.
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...

♦ Exactly one wumpus

$$W_{1,1} \vee W_{1,2} \vee \dots \vee W_{4,3} \vee W_{4,4}$$

// ≥ 1 wumpus

$$\neg W_{i,j} \vee \neg W_{k,l}$$

$$1 \leq i, j, k, l \leq 4 \text{ and } (i, j) \neq (k, l)$$

// ≤ 1 Wumpus;

$$// \frac{16 \times 15}{2} = 120 \text{ rules}$$

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Representing Percepts

A percept asserts something only about the current time.

- $Stench^4$: the agent senses stench at time step 4 (in square A).
- $\neg Stench^3$: the agent senses no stench at time step 3 (in square B).

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(aspect changing with time) $L_{x,y}^t \Rightarrow (Stench^t \Leftrightarrow S_{x,y})$

Describing a Transition Model

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Effect axioms specify outcome of an action at the next time step.

$$L_{1,1}^0 \wedge FacingEast^0 \wedge Forward^0 \Rightarrow (L_{2,1}^1 \wedge \neg L_{1,1}^1)$$

// if the agent is at [1,1] facing east at time 0 and goes forward,
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$O(mn)$ frame axioms for m actions and n fluents

Axioms for Successor States

Successor-state axiom, one for every fluent F , states that

- either the action at t causes F to be true at $t + 1$,
- or F was already true at t and the action does not cause it to be false.

$$F^{t+1} \Leftrightarrow \text{ActionCauses}F^t \vee (F^t \wedge \neg \text{ActionCausesNot}F^t)$$

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$$L_{1,1}^{t+1} \Leftrightarrow (L_{1,1}^t \wedge (\neg \text{Forward}^t \vee \text{Bump}^{t+1})) \vee (L_{1,2}^t \wedge (\text{FacingSouth}^t \vee \text{Forward}^t)) \\ \vee (L_{2,1}^t \wedge (\text{FacingWest}^t \vee \text{Forward}^t))$$

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Square-OK axiom asserts that a square is free of a pit or live Wumpus.

$$OK_{x,y}^t \Leftrightarrow \neg P_{x,y} \wedge \neg (W_{x,y} \wedge \text{WumpusAlive}^t)$$

Initial Percepts and Actions

$\neg \text{Stench}^0 \wedge \neg \text{Breeze}^0 \wedge \neg \text{Glitter}^0 \wedge \neg \text{Bump}^0 \wedge \neg \text{Scream}^0$; *Forward*⁰
 $\neg \text{Stench}^1 \wedge \text{Breeze}^1 \wedge \neg \text{Glitter}^1 \wedge \neg \text{Bump}^1 \wedge \neg \text{Scream}^1$; *TurnRight*¹
 $\neg \text{Stench}^2 \wedge \text{Breeze}^2 \wedge \neg \text{Glitter}^2 \wedge \neg \text{Bump}^2 \wedge \neg \text{Scream}^2$; *TurnRight*²
 $\neg \text{Stench}^3 \wedge \text{Breeze}^3 \wedge \neg \text{Glitter}^3 \wedge \neg \text{Bump}^3 \wedge \neg \text{Scream}^3$; *Forward*³
 $\neg \text{Stench}^4 \wedge \neg \text{Breeze}^4 \wedge \neg \text{Glitter}^4 \wedge \neg \text{Bump}^4 \wedge \neg \text{Scream}^4$; *TurnRight*⁴
 $\neg \text{Stench}^5 \wedge \neg \text{Breeze}^5 \wedge \neg \text{Glitter}^5 \wedge \neg \text{Bump}^5 \wedge \neg \text{Scream}^5$; *Forward*⁵
 $\text{Stench}^6 \wedge \neg \text{Breeze}^6 \wedge \neg \text{Glitter}^6 \wedge \neg \text{Bump}^6 \wedge \neg \text{Scream}^6$

Query the knowledge base:

$\text{Ask}(KB, L_{1,2}^6) = \text{true}$

$\text{Ask}(KB, W_{1,3}) = \text{true}$

$\text{Ask}(KB, P_{3,1}) = \text{true}$

$\text{Ask}(KB, OK_{2,2}^6) = \text{true}$

// the square [2,2] is OK to move into.

1,4	2,4 P?	3,4	4,4
1,3 W!	2,3 <div style="border: 1px solid black; display: inline-block; padding: 2px;">A</div> S G B	3,3 P?	4,3
1,2 S V OK	2,2 V OK	3,2	4,2
1,1 V OK	2,1 B V OK	3,1 P!	4,1

Initial Percepts and Actions

$\neg \text{Stench}^0 \wedge \neg \text{Breeze}^0 \wedge \neg \text{Glitter}^0 \wedge \neg \text{Bump}^0 \wedge \neg \text{Scream}^0$; *Forward*⁰
 $\neg \text{Stench}^1 \wedge \text{Breeze}^1 \wedge \neg \text{Glitter}^1 \wedge \neg \text{Bump}^1 \wedge \neg \text{Scream}^1$; *TurnRight*¹
 $\neg \text{Stench}^2 \wedge \text{Breeze}^2 \wedge \neg \text{Glitter}^2 \wedge \neg \text{Bump}^2 \wedge \neg \text{Scream}^2$; *TurnRight*²
 $\neg \text{Stench}^3 \wedge \text{Breeze}^3 \wedge \neg \text{Glitter}^3 \wedge \neg \text{Bump}^3 \wedge \neg \text{Scream}^3$; *Forward*³
 $\neg \text{Stench}^4 \wedge \neg \text{Breeze}^4 \wedge \neg \text{Glitter}^4 \wedge \neg \text{Bump}^4 \wedge \neg \text{Scream}^4$; *TurnRight*⁴
 $\neg \text{Stench}^5 \wedge \neg \text{Breeze}^5 \wedge \neg \text{Glitter}^5 \wedge \neg \text{Bump}^5 \wedge \neg \text{Scream}^5$; *Forward*⁵
 $\text{Stench}^6 \wedge \neg \text{Breeze}^6 \wedge \neg \text{Glitter}^6 \wedge \neg \text{Bump}^6 \wedge \neg \text{Scream}^6$

Query the knowledge base:

$\text{Ask}(KB, L_{1,2}^6) = \text{true}$

$\text{Ask}(KB, W_{1,3}) = \text{true}$

$\text{Ask}(KB, P_{3,1}) = \text{true}$

$\text{Ask}(KB, OK_{2,2}^6) = \text{true}$

// the square [2,2] is OK to move into.

1,4	2,4 P?	3,4	4,4
1,3 W!	2,3 <div style="border: 1px solid black; display: inline-block; padding: 2px;">A</div> S G B	3,3 P?	4,3
1,2 S V OK	2,2 V OK	3,2	4,2
1,1 V OK	2,1 B V OK	3,1 P!	4,1