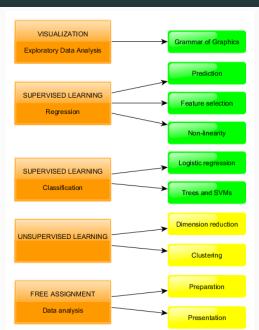
Supervised Learning: Classification

Tree-based methods and Support Vector Machines

Maarten Cruyff

Program

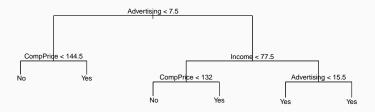


Content

- 1. Classification trees
- 2. Pruning
- 3. Bagging, random forests
- 4. Boosting
- 5. Support Vector Machines

Classification trees

- 1. Recursive binary splitting algorithm
- 2. Splits on basis of node purity
 - Gini index
 - deviance



Recusrsive binary splitting

Algorithm

- 1. Divide feature space in non-overlapping, rectangular regions
- 2. Choose splits that minimize *node impurity* (homogeneity of nodes)
- 3. Assign region to class with highest mode
- 4. Stop when node purity no longer increases

Algorithm is top-down and greedy, so

high variance

Package tree

Growing and plotting trees with function tree()

```
train_tree <- tree(formula, data, split = c("deviance", "gini"))
plot(train_tree)
text(train_tree)</pre>
```

- minimization of deviance or gini impurity
- text() for adding labels to nodes

Methods to reduce variance:

1. Pruning

cross-validation with regularization

2. Bagging

bootstrapping

3. Random forests

bagging with random set of predictor at each split

4. Boosting

weighted combination of weak classifiers

Pruning

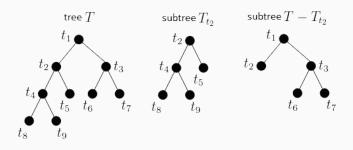
Cost-complexity pruning (package 'tree)

- 1. Cross-validate the tree
- 2. Shows deviance/misclassification as function of nodes
- 3. Obtain predictions test set

```
cv.tree(fit_tree, method = c("deviance", "misclass"))
pruned_tree <- prune.tree(fit_tree, best = <number>)
predict(pruned_tree, newdata, type = "class")
```

- cv.tree() deviance/misclassification as function number of nodes
- best in prune.tree() is optimal number of nodes in cv.tree()
- default type yields predicted probabilities

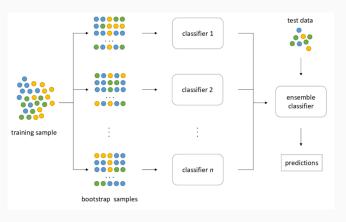
Pruning example



Bagging, random forests

Algorithm

- 1. Fit classification trees to B bootstrap samples
- 2. Average the predictions
- 3. OOB as estimate validation error



Bagging vs random forests

Bagging

- considers all predictor at each split
- best predictors turn up in each tree
- highly correlated trees
- high variance

Random forests

- considers 1/3 of predictors at each step
- all predictors get a fair chance
- decorrelated trees
- lower variance

Out-of-bag error rate

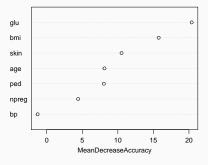
On average 1/3 of observations not in bootstrap (out of bag)

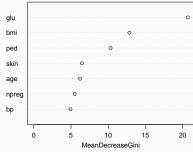
- OOB cases used to compute validation error
- no need for cross validation
- computationally very efficient

Variable importance

When averaging trees the tree structure is lost

- how to interpret solution then?
- effect predictors averaged over trees
- visualize with _variable importance plots___





Package randomForest

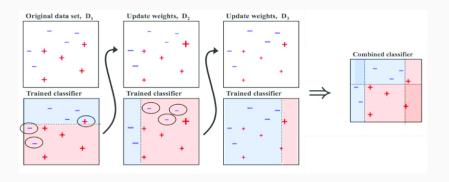
Training and prediction with bagging/random forest

- mtry: default random forest (bagging total number predictors)
- ntree is tuning parameter (overfitting when too large)
- importance = TRUE necessary for varImpPlot()
- default type yields predicted class

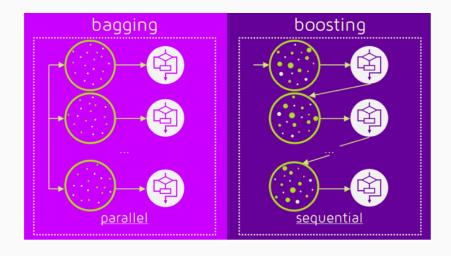
Boosting

Algorithm

- 1. Apply a weak classifier (e.g. stump) to training data
- 2. Increase weights for incorrect classifications, and repeat
- 3. Classifier is linear combination of weak classifiers



Boosting vs bagging/random forest



Boosting with package fastAdaboost

Boosting a single model

• nIter is number of weak classifiers

```
ada <- adaboost(formula, data, nIter)
predict(ada, newdata)</pre>
```

- nIter is tuning parameter (overfitting when too large)
- predictions include classes, probabilities and misclassification error

Boosting with package caret

Determine nIter with cross validation (caret)

- "Adaboost.M1" restricts search to one of two methods
- default type yields predicted class

Support Vector Machines (SVM)

SVM for binary classification

Classifiers using support vectors

- 1. maximal margin classifier
 - classes perfectly separable by hyperplane

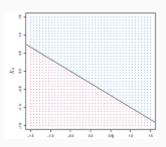
- 2. support vector classifier
 - allows for non-separable cases

- 3. support vector machine
 - allows for non-linear boundaries

Hyperplane

Divides the feature space in two

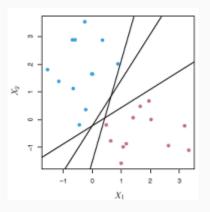
• in two dimensions hyperplane is simply a line



Separating hyperplane

Perfectly separates the two classes of the outcome variable

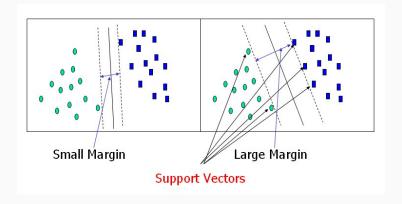
- hyperplane not uniquely identified
- high variance



Maximal Margin Classifier

Identifies hyperplane by specification of a maximal marging

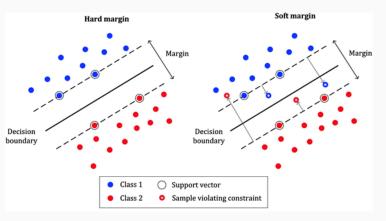
- points on margin are support vectors
- only works idf cases are *separable*



Support Vector Classifier (SVC)

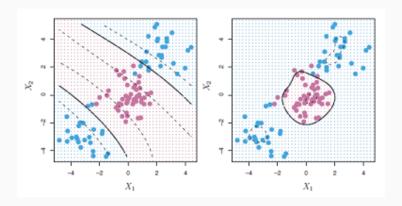
Allows for violations of the margin (soft margin)

- budget for violations is called cost (C)
- cases the wrong side of hyperplane contribute to the cost



Support Vector Machines (SVM)

Allows for nonlinear hyperplanes, e.g. polynomial and radial



SVM with pacakge e1071

Training and prediction

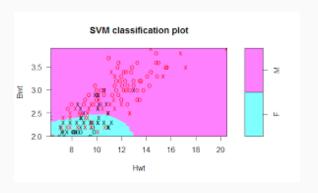
```
svm_train <- tune(svm, formula, data,</pre>
                   degree = 3, #default
                   coef0 = 0, #default
                   cost = 1, #default
                   kernel = c("linear", "polynomial", "radial"),
                   ranges = list(cost = <sequence>), etc.)
svm_train$best.model # performance summary
svm_class <- predict(svm_train, newdata, probability = TRUE)</pre>
svm_prob <- attr(svm_class, "probabilities")</pre>
```

- cost, degree and coef0 are tuning parameters
- ranges works similar as tuneGrid()

SVM classification plot

Compression hyperplane two dimensions

```
plot(...$best.model, data, x1 ~ x2)
```



Pro's and con's classifiers

BLR

robust against outliers but potentially unstable

LDA

better stability but sensitive to normality violations

Tree-based methods

- top-down and greedy, so bias-variance control needed
- boosting considered as one of the best methods

SVM

similar to BLR (same loss function), but allow for non-linearity