

Lab Assignment 8 - State Space Model

1. Obtain the State Space model of the system on paper and using Python.
 - Consider the state variable as current i and voltage across the capacitor v_c .
 - Obtain the output state equations such that it would be possible to monitor output across capacitor and output across the resistor
 - Take $R = 240\Omega$, $C = 1mF$, $L = 40H$

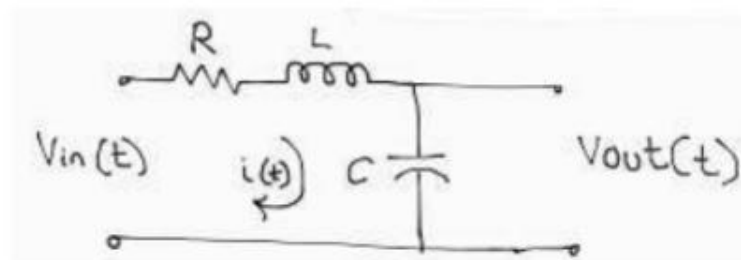


Figure 1: RLC circuit

- Python code in comments should have student's name, GR No., Roll No., Date of Lab, Lab assignment title, problem statement.
- At the end the conclusion, learning outcomes of the lab are to be written
- Hand written matter, Code, plots, Conclusion, learning outcomes should be in one single PDF file for submission

```
In [3]: """
Name:- Abhijeet Shivachary
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"""
```

Out[3]: '\nName:- Abhijeet Shivachary\nroll no:- 48\nGr. No. 11911048\nLAB-8\nDiv :- IC-C Batch 2\n\n'

```
In [ ]:
```

```
In [3]: import numpy as np
import control
from matplotlib import pyplot as plt

R = 240
L = 40
C1 = 0.001

A = [[0,1/C1],[-1/L,-R/L]]
B = [[0],[1/L]]
C = [[1,0],[0,R]]
D = [[0],[0]]

S = control.ss(A,B,C,D)
print(S)

tf = control.ss2tf(S)
print(tf)

T,y= control.step_response(tf[0,0])
plt.plot(T,y)
plt.xlabel("Time")
plt.ylabel("Vout")
plt.show()
```

```
A = [[ 0.0e+00  1.0e+03]
      [-2.5e-02 -6.0e+00]]

B = [[0.   ]
      [0.025]]

C = [[ 1.   0.]
      [ 0. 240.]]

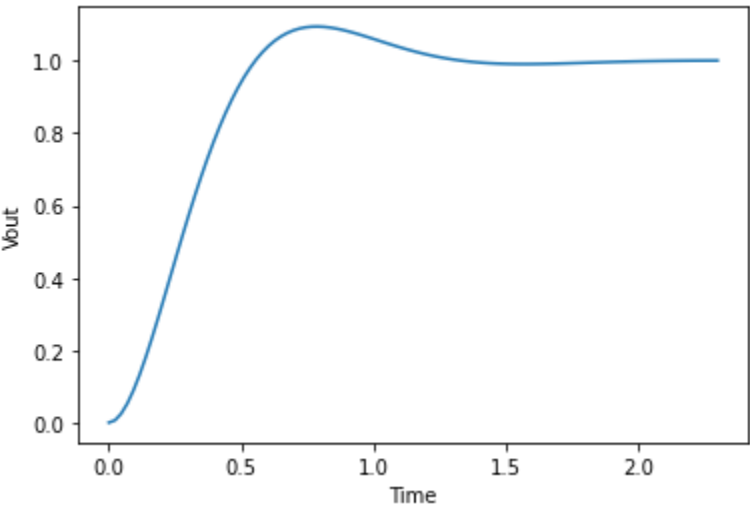
D = [[0.]
      [0.]
```

Input 1 to output 1:
25

s^2 + 6 s + 25

Input 1 to output 2:
6 s

s^2 + 6 s + 25



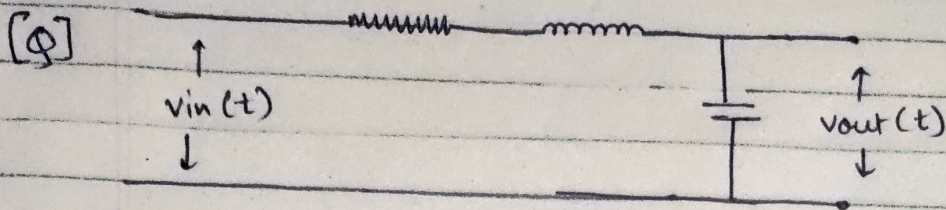
Conclusion:

In this lab we learn how to derive transfer function of given system and also how to derive State Space Model from Differential Equation

Learning Outcomes:

1)In this lab we learnt state space model from differential equation and their transfer function. 2)And also, we plot the step response of that function.

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In [ ]:
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$$v_{out}(t) = v_c(t)$$

by KVL, @

$$v_i(t) = Ri(t) + L \frac{di(t)}{dt} + v_c(t)$$

$$\therefore \frac{di(t)}{dt} = -\frac{Ri(t)}{L} - \frac{v_c(t)}{L} + \frac{v_i(t)}{L}$$

The voltage across the capacitor,

$$v_c(t) = \frac{1}{C} \int i(t) dt$$

$$\therefore \frac{dv_c(t)}{dt} = \frac{i(t)}{C} \quad [\because \text{differentiate}]$$

state vector

$$X = \begin{bmatrix} i(t) \\ v_c(t) \end{bmatrix}$$

diff state vect,

$$\dot{X} = \begin{bmatrix} di(t)/dt \\ dv_c(t)/dt \end{bmatrix}$$

$$\therefore \dot{X} = \begin{bmatrix} -R/L & -1/L \\ 1/C & 0 \end{bmatrix} \begin{bmatrix} i(t) \\ v_c(t) \end{bmatrix} + \begin{bmatrix} 1/L \\ 0 \end{bmatrix} v_i(t)$$

$$Y = \begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} i(t) \\ v_c(t) \end{bmatrix}$$

where,

$$A = \begin{bmatrix} -R/L & -1/L \\ 1/C & 0 \end{bmatrix} \quad B = \begin{bmatrix} 1/L \\ 0 \end{bmatrix}, \quad C = \begin{bmatrix} 0 & 1 \end{bmatrix} \\ D = \begin{bmatrix} 0 \end{bmatrix}$$