

Battle for Middle Earth

1. INTRODUCTION

Peace, that seemed everlasting after the destruction of the ring, has once again been shattered. Tales of Dark Forces, foul alliances between Orc and Goblin Armies drift to the peacelands from the South. Despite this, the Peace of Middle Earth is threatened by the interracial tensions, stirred up by cunning diplomats, who seek out war to profit themselves.

You are the last hope; you are a group of rebels, who seek to unite the three races again and face the menace brewing in the South. To re-engage the Alliances of old, you should reignite the doused fires of Minas Tirith. These shall, like the flames themselves, put fires in the bellies of Men, in the eyes of the Elves, and in the arms of the Dwarves. But the Darkness, all knowing in its nature, hunts you down. It has rallied its armies in your pursuit, and have cornered you around the gates of Minas Tirith.

CAN YOU IGNITE THE FLAMES AND UNITE THE FREE WORLD?



2. ARENA DESCRIPTION

Fig.1

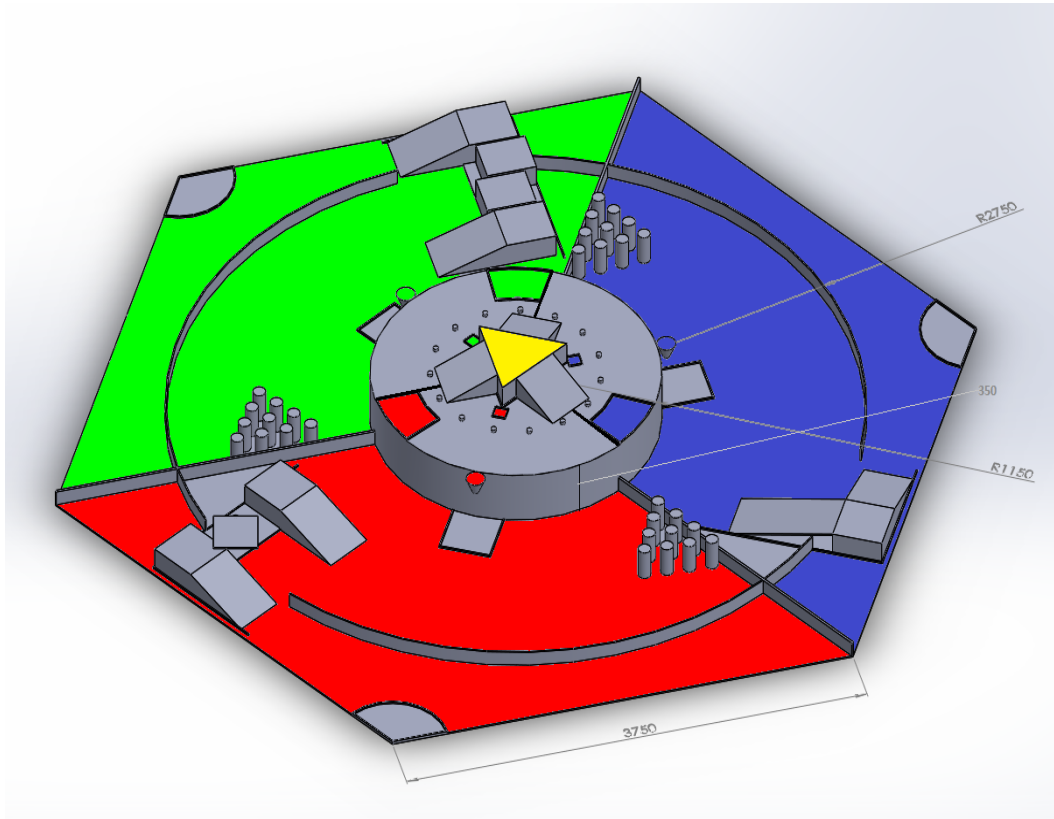


Fig.2



2.5 Starting zone for robot A in Zone B, Zone G and Zone R is denoted by SZ B, SZ G AND SZ R respectively.

2.6 Starting zone and check point for robot B are both same and are denoted in Zone B, Zone G and Zone R is denoted by CP B, CP G and CP R respectively.

2.7 The outer zone and intermediate zone are connected by path P, path Q and path R in the three zones as shown in the figure.

Fig.3

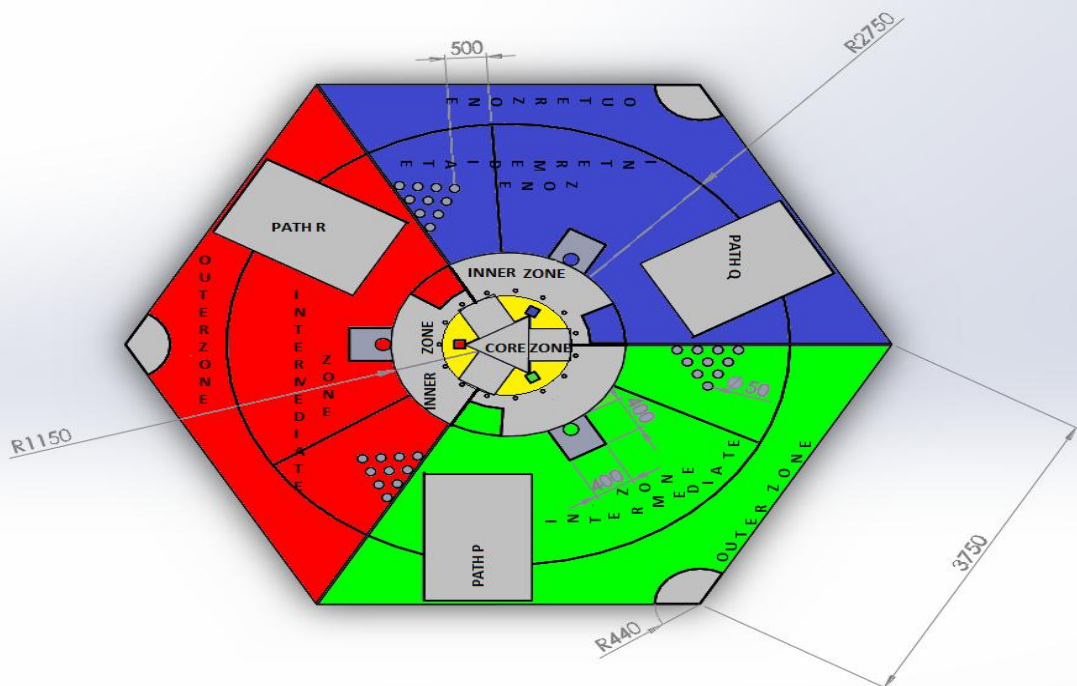
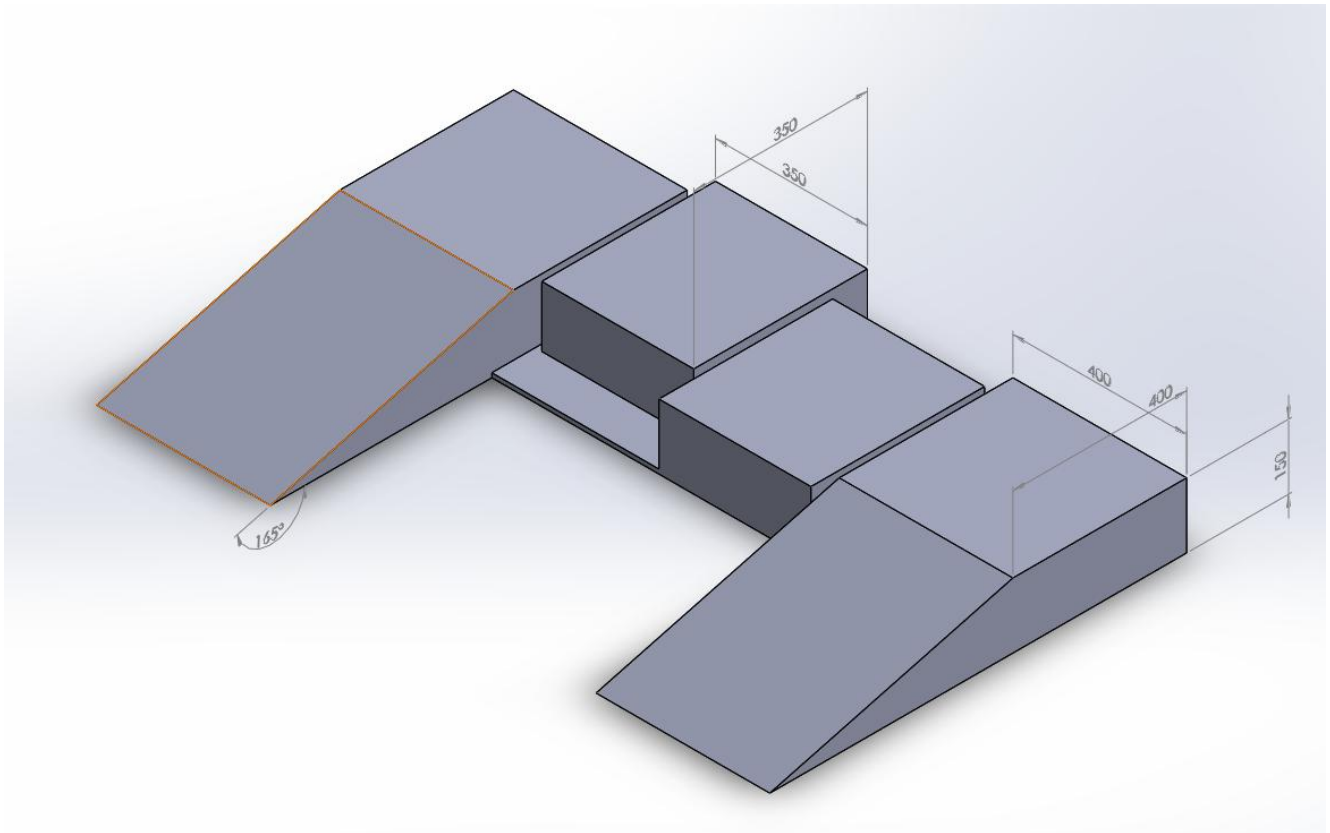


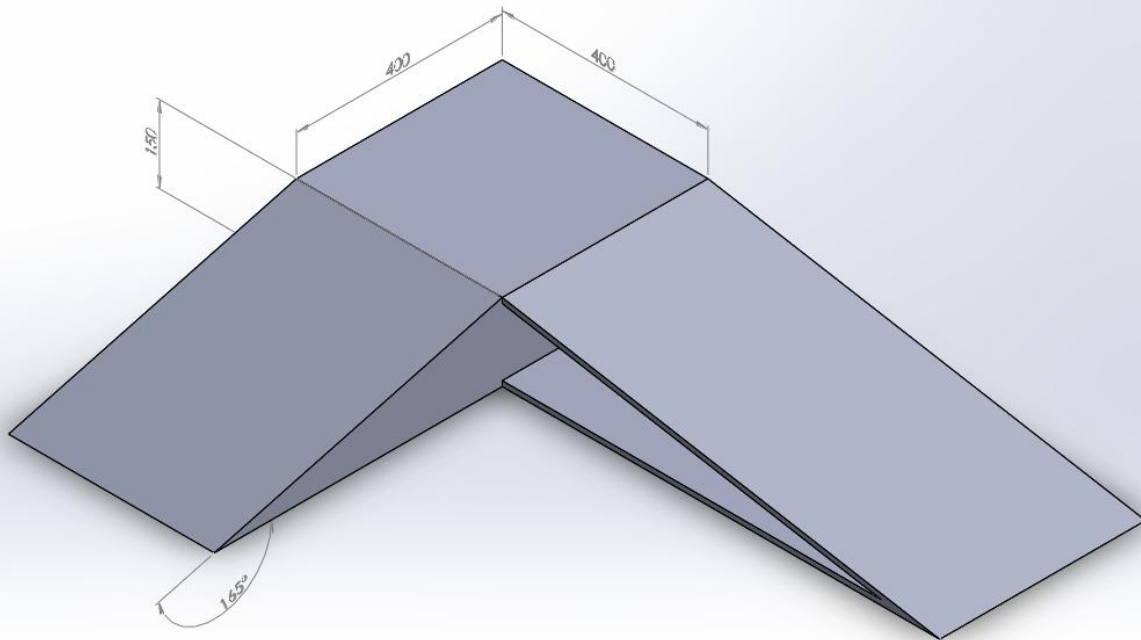
Fig.4 (Path P)



2.8 Description of Path P:

This dynamic obstacle consists of two ramps of inclination 15 degrees and a height of 15mm.
 Two moving platforms of size 350*350mm each are placed between the ramps.
 The ramps and the moving platforms are at same elevation.

Fig.5 (Path Q)



2.9 Description of Path Q:

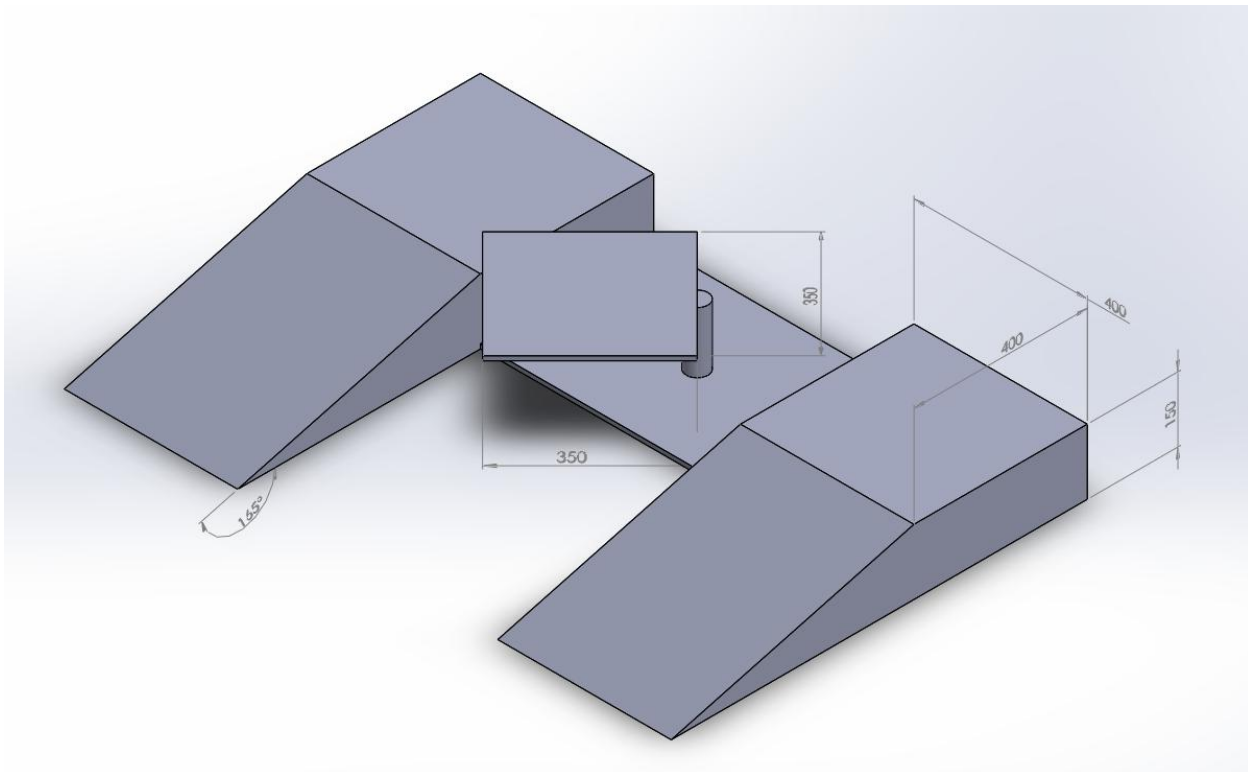
The dynamic obstacle consists of a ramp of 15 degrees and height of 150mm.

The ramp ascends into a platform of 400*400 mm which descends into a variable ramp.

The variable ramp is an inclined plank with a varying inclination controlled by a piston.

The height of the ramp varies from a minimum of 150mm to a maximum of 300mm.

Fig.6 (Path R)



2.10 Description of Path R:

It consists of two ramps of inclination 15 degrees and height 150mm. There is a platform between the two ramps of size 350*350mm which is rotating continuously in the horizontal plane.

2.11 Loading zone:

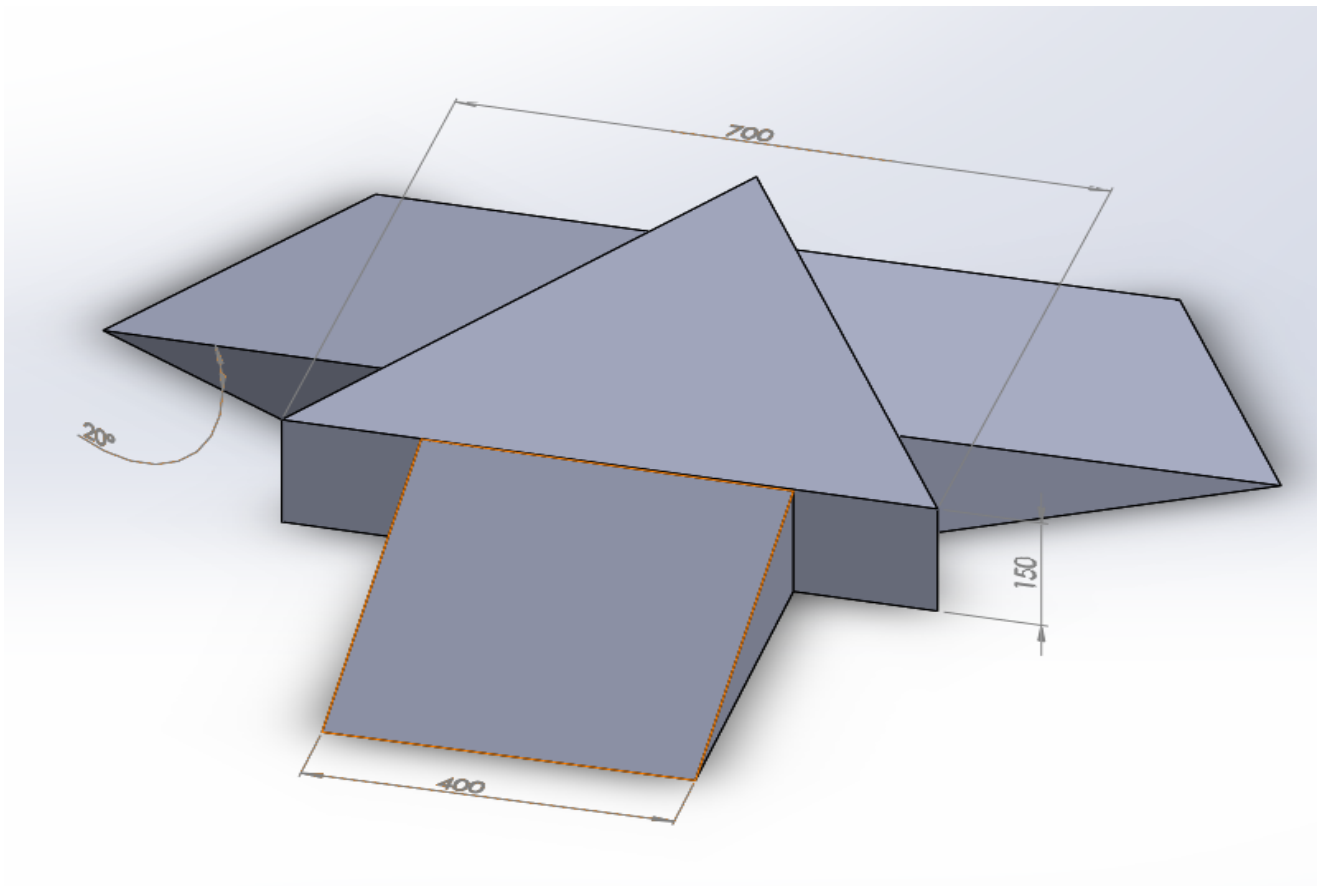
The ball is transferred from inner zone to intermediate zone between the robots in the loading zone. Each loading zone consists of a funnel of height of 100mm and the tip of the funnel at height of 250mm above the ground level.

2.12 The targets are arranged in triangular fashion as denoted in Fig.2. Throwing zone is denoted in Fig.2. The minimum distance between the throwing zone and the first target is 500mm as shown in Fig.3.

2.13 Pick-up zone for every colour zone consists of 5 balls of diameter 67mm of weight 120 grams are placed on PVC pipes of height 15mm.

2.14 Core zone is represented by the yellow coloured circular region in the inner zone in Fig.3. The flame cubes of dimensions 100*100*100mm are placed in the core region between the ramps as denoted by the colored rectangular region in Fig.3.

Fig.7 (TRI-RAMP)



2.15 Tri-ramp in the Core Zone:

It consists of three ramps one for each robot which ascend into a triangular platform of length of all sides 700mm. Each ramp has an inclination of 20 degrees and height of 150mm and a width of 400mm.

3. MISSION

Mission is to finish at top of Minas Tirith (the Tri-Ramp) completing certain tasks/challenges along the way.

3.1 Each team has to build two Manual Robots Robot A and Robot B for completing the challenge.

3.2 Tasks of robot A:

3.2.1 The robot must navigate to the entrance to the intermediate zone

3.2.2 The robot must proceed to the intermediate zone from its respective home zone via the specified respective path.

3.2.3 In the intermediate zone, the robot A must progress to the ball loading sub-zone.

3.2.4 It must load the ball falling from the channel placed in the ball loading sub-zone.

3.2.5 The loaded ball should be used to knock over targets placed in the throwing zone.

3.3 Tasks of robot B:

3.3.1 The robot B must enter its respective pick up zone and pick up the balls placed.

3.3.2 The robot B must transfer the balls it picked, to robot A using the transfer funnel.

3.3.3 Following the successful transfer of all balls in its home zone (the 120 degree sector corresponding to its colour), the robot must enter the foreign zone (opponents' home zone), pick up and transfer balls to robot A, in order to gain bonus points.

3.3.4 Once all the balls (total 15 in number) are transferred, then the robot is to enter the core zone (sub-zone of the robot's home zone) and take the flame cube

3.3.5 The flame cube should then be taken up the hill and placed above the hill plane.

3.3.6 The bot must also ensure that all its wheels rest atop the hill plane at the end of the challenge.

4. PROCEDURE

4.1 Tasks for robot A

4.1.1 Each team gets one of the three equally difficult start zones - P,Q,R by random allocation.

4.1.2 The bot then proceeds to the intermediate zone from their respective home zone. The path to the intermediate zone varies with their home zone as below :

Path P:

- The robot must climb a ramp.
- The robot must move across two mobile platforms which translates to and fro in the direction perpendicular to the path.
- The robot must get down a ramp to enter its intermediate zone.

Path Q:

- The robot must climb a ramp.
- The robot must move across a landing(plane area)
- The robot must get down a ramp of variable inclination (swaying up and down) to enter its intermediate zone.

Path R:

- The robot must climb a ramp.
- The robot must get onto a rotating platform and get down at the opposite side.
- The robot must get down a ramp to enter its intermediate zone.

4.1.3 After the successful entry into its intermediate zone, the robot A must proceed to the ball loading sub-zone (40cmx40cm) of its intermediate zone.

4.1.4 It must successfully obtain a ball falling from a tube at a height of 10cm and may load it for the next task of throwing the ball.

4.1.5 The ball obtained from the ball loading area must be used to knock over bowling pins placed in the bowling zone in order to gain extra points. The robot must not leave the its intermediate zone while doing so.

4.2 Tasks of robot B:

4.2.1 The robot B must enter the pick-up sub-zone in its home-zone.

4.2.2 The robot B must pick up balls placed on its holder.

4.2.3 The robot B must coordinate with robot A so as to transfer the balls from the inner zone to the intermediate zone via the transfer funnel.

4.2.4 Once all the 5 balls of its own zone is transferred, only then the robot is permitted to enter the foreign zone (opponents' home zone) and may pick up and transfer balls from it to maximise its points.

4.2.5 The robot cannot enter a foreign zone if the robot corresponding to that zone is present in that zone.

4.2.6 The robot cannot enter its home zone if any other robot is already present in its home zone.

4.2.7 The robot cannot stay in its home zone or foreign zone for more than a continuous stretch of 30 seconds.

4.2.8 If two robots touch each other in a foreign zone, then both the robots must be reset to their corresponding starting point in its intermediate zone.

4.2.9 Once the all the pick up zones are evacuated, then the robot is permitted to enter the core zone (sub-zone of the robot's home zone).

4.2.10 In the core zone the robot must pick up the flame cube, climb the ramp and place the mystery cube on top of the hill.

4.2.11 After the flame cube is loaded on the robot, it is considered to be a part of the robot.

4.2.12 If there is a robot already present on top of the hill, then no other robot is permitted to enter the top of the hill.

4.2.13 A robot will be considered to be on the top of the hill if all parts of the robot are above the hill plane.

4.2.14 If two robots touch each other when none of them are on top of the hill, then they must be reset from the location where its flame cube was placed.

5. SCORING

Task Completed	Points awarded
Robot A	
Climbing the ramp in the path to intermediate zone	10
Overcoming the obstacle and reaching the intermediate zone	20
Loading of the ball into the robot	10
Launching of the ball into the bowling zone (only if no pin is knocked during that launch)	5
For each pin knocked	10
Robot B	
Picking up balls from holder in its home-zone	5
Picking up balls from holder in foreign-zone	10
Pushing the ball into the funnel successfully(only if the ball is not loaded into robot A)	5
Collecting the mystery box and placing it on the ramp	60

6. VIOLATIONS

- 6.1 At any point during the match, the bot should not purposely hit the funnel in the intermediate area.
- 6.2 Bots are not allowed to cross over the walls or damage them.
- 6.3 The operator shouldn't disturb the arrangement of the balls in the ball zone.
- 6.4 The operator should not enter into the core zone(elevated zone).
- 6.5 For every Violation, the team responsible shall have to take a restart from the last checkpoint.
- 6.5 Operator should not touch robot other than at the time of retry.
- 6.6 Operator shouldn't disturb the arrangement of ball in the ball zone.

7. PENALTIES

- 7.1 Any damage to the dynamic obstacles will yield 10 negative points.
- 7.2 Time penalty of 60 seconds when skipping dynamic obstacles

	Points Penalty	Time Penalty
Skipping Dynamic Obstacles		-60
Damage to arena/Dynamic obstacles	-10	
Operator hits the balls intentionally	-10	
Operator pulling the bot intentionally using wires	-10	
Robot going outside the arena	-10	

NOTE: Penalties will be given by coordinators and coordinator's decision will be final.

8. RETRIES

- 8.1 In case of any technical issues in any of the robot, the robot can be taken to the boundary of the arena with the consent of co-ordinators.
- 8.2 A retry can be opted at any time in the match. This retry can be opted for as many times as necessary without any penalty.
- 8.3 The referee needs to be informed before going for a retry.
- 8.4 All retries should be from the last checkpoint.

9. ROBOT SPECIFICATIONS

- 9.1 Each team shall use only two manual robots.
- 9.2 Maximum dimensions of the robots at the start of the game are **300mm x 300mm x 300mm**.
- 9.3 The robots can extend after the start of the match.
- 9.4 Maximum allowable weights of the robots combined are **20 kgs**.
- 9.5 The robots must not use ready-made parts and shall be designed and constructed by the students themselves, failing which the team will be disqualified.
- 9.6 Manual robots have to be operated by means of cable connection. The length of the cables should be atleast 2 m. Wireless radio control is also permitted.
- 9.7 The manual robots can be powered with eliminator or a DC battery. The maximum voltage between any two points should not exceed 12V.
- 9.8 Hydraulics or chemical energy should not be used for any mechanism.
- 9.9 Pneumatics can be used and in case of use the pressure should be less than 6 bars.
- 9.10 If a team is using LiPo or Li-ion batteries, it is the team's responsibility to make sure there is no risk involved in its usage.
- 9.11 The bots shouldn't exceed the dimensional and weight constraints mentioned above.

10. RULES AND REGULATIONS

- 10.1 The Game is three way match in which three teams compete simultaneously.
- 10.2 Each trial lasts for 6 minutes.
- 10.3 At the end of 6 minutes game will be ended by a blow of whistle.
- 10.4 1 minute shall be provided for setting up of Robots before the match.
- 10.5 Only two members of each team will be allowed to enter the game arena .
- 10.6 Only one team member is allowed to control one robot.
- 10.7 The robots shall be placed in their respective starting zones at the beginning of the match.
- 10.8 A robot cannot split into two or more subparts. Subpart implies a robot which has a drive mechanism of its own.
- 10.9 The manual robot operator can walk on the arena but should not disrupt any part of the arena and other the opponent team.
- 10.10 The two operators are allowed to touch their corresponding robots only during a retry & before the match starts.
- 10.11 All the statements written in this Problem Statement form the official framework of the rules to be followed by the teams. Violation of any statement in the Problem Statement may lead to disqualification.
- 10.12 Damage to arena is unacceptable and will lead to instant disqualification.

10.13 The robot exceeding the weight constraints shall be disqualified.

10.14 Referees have all rights to ask the teams to produce the additional explanations on design issues. Also the referees can ask for additional explanation on the safety of the bots if required anytime during the event.

10.15 Participating robots will be checked and tested, according to these rules and regulations.

NOTE :

1) Game field dimensions are subject to a tolerance of $\pm 5\%$. No tolerances will be given in case of maximum bot dimensions.

2) The authenticity of any action not provided in this problem statement shall be subject to discretion of Coordinators.

For any further queries feel free to contact the coordinators:

Name	Phone No	E-mail ID
Palash Phirke	9445964881	palash.phirke@gmail.com
Aditi Khot	9043810282	khot.adya@gmail.com
Sibi George	8903988370	sibihere94@gmail.com
TK Bala	9840892717	balatk95@gmail.com
Naga Sowjanya	9043886339	nagasowjanya936@gmail.com