SHABD GUPTA

s28gupta@uwaterloo.ca linkedin.com/in/ShabdGupta github.com/Shabd034

EDUCATION

University of Waterloo, BASc, Mechatronics Engineering

April 2027

- Academic average of 91.76% (3.94/4.00), Professor Igor Ivkovic Memorial Award, Dean's Honour List
- Relevant courses: Microprocessors, Sensor Interfacing, RTOS, Signals, Digital Logic, Controls, System Modelling

SKILLS

Languages: C/C++, Python, C#, Bash/shell, GLSL, MATLAB, VHDL, Verilog/SystemVerilog

Platforms: Linux (Desktop/Embedded), Bare metal (Xilinx/STM32), Windows (.NET/Win32), FPGA (Xilinx)

Libraries/Tools: NumPy, openCV, gRPC, MQTT, Redis, OpenGL, Git, Petalinux/Yocto, AWS, Docker, Jira, Vitis, STM IDE

EXPERIENCE

Factory Software Intern | Formlabs

May 2025 – August 2025

- Developed calibration and manufacturing routines for SLS/SLA 3D printers to support production and NPI cycles.
- Utilized **Python** including packages like **OpenCV**, **NumPy**, and **SciPy** to implement **15%** of final test and calibration suite.
- Implemented system-critical calibration for multi-pixel IR sensors accounting for external optics and assembly.
- Updated process control software using Python backend and React to parallelize routines, reducing cycle time.
- Wrote thread-safe libraries and drivers to interact with MQTT broadcasts, RTSP streams, DAQs and PID controllers.
- Integrated various sub-system tests on the assembly line collaborating with R&D, manufacturing and embedded teams.

Sensor Software Developer Intern | Lumentum

January 2024 - December 2024

- Contributed to the development of a high-speed LIDAR sensor for precision metrology applications.
- Utilized C++ to Develop thread safe modules and features for the kernel and user-space in an embedded Linux system.
- Updated Xilinx FSBL and U-Boot code to implement boot redundancy and upgrades for Ultrascale+ platform.
- Created internal tooling for the embedded system and python packages for R&D and process automation.
- Developed a Windows user-space driver using COM, gRPC, and Win32 for communication with multiple sensors.
- Designed and implemented a graph generator library in C++ to visualize sensor scan plan with a runtime under 3ms.
- Implemented Redis as on sensor database, created BitBake files, Linux init scripts, utilized Hiredis for C++ interfacing.
- Integrated Xilinx Verification IP for AXI4, AXI lite, and AXI stream protocols into simulation using Verilog.

Manufacturing Software Development Intern | Ford Motor Company

May 2023 – August 2023

- Implemented UDS over DoIP protocol to support module factory deliverables in C# using .NET, NUnit, Moq.
- Created first unit tests using GTest to test C++ device deployment code for the manufacturing team.
- Updated BitBake recipes to facilitate build automation for QEMU and device platform through Jenkins.
- Automated chip image loading in EDL mode onto multi-chip devices, verify boot-up and collect logs using QPST.

PROJECTS

Ball Balancing Game

August 2025

- Built an interactive Stewart platform simulation with kinematics and contact physics for a real-time ball balancing game.
- Used C++, OpenGL and GLSL for graphics and simulation, and GLFW for window management and input handling.

Graphics Rendering Engine using OpenGL/GLSL

August 2024

- Developed a graphics engine to render STLs with lighting using Physically Based Lighting and Blinn-Phong techniques.
- Leveraged GLSL to implement vertex and fragment shaders to form a graphics pipeline and GLFW for user control.

Course Projects

- Two-axis gantry fine control using ADC inputs on an STM board and utilizing SPI based stepper motor driver.
- Real Time Operating system with multithreading capabilities implemented for a Cortex M4 chip on an STM32.
- Robotic chess player to precisely pick up and place pieces using a pulley system, various sensors and RobotC.
- Analysis in topics like signals, machine dynamics, numerical methods, calculus using MATLAB/Python.