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Task01: Submit a comprehensive commented file of the original code.
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/*Shabrya Lott
* Tiva c Lab03
* Usage: This is a simple program that enables toggling on the TIVA C launchpad
* Input: NONE
* Output: Red, Blue and Green LED's lit in specified cycle
#include <stdint.h>
                                          //variable definitions for the C99 standard
#include <stdbool.h>
                                 //Boolean definitions for the C99 standard
#include "inc/hw memmap.h"
                                          //macros defining the memory map of Tiva C Series
#include "inc/hw types.h"
                                 //defines common types and macros
#include "driverlib/sysctl.h"
                                 //defines macros for System Control API of Driverlib
#include "driverlib/gpio.h"
                                 //defines macros for GPIO API of Driverlib
uint8 t ui8PinData=2;
                         //unsigned 8-bt int that is used to cycle through LEDs
int main(void)
        //sets clock: xtal = 16Mhz, 400MHz PLL divided by 10
        SysCtlClockSet(SYSCTL_SYSDIV_5|SYSCTL_USE_PLL|SYSCTL_XTAL_16MHZ|SYSCTL_OSC_M
AIN);
        //enables PORT F
        SysCtlPeripheralEnable(SYSCTL PERIPH GPIOF);
        //set 3 GPIO pins conneced to the LEDs as ouputs
        GPIOPinTypeGPIOOutput(GPIO PORTF BASE, GPIO PIN 1|GPIO PIN 2|GPIO PIN 3);
        while(1)
                //turn on the LED specified in ui8PinData
                 GPIOPinWrite(GPIO_PORTF_BASE, GPIO_PIN_1|GPIO_PIN_2|GPIO_PIN_3, ui8PinData);
                 SysCtlDelay(2000000); //delay = 2000000 * 3 = 6000000 CPU cycles
                // turn all LEDs off
                 GPIOPinWrite(GPIO_PORTF_BASE, GPIO_PIN_1|GPIO_PIN_2|GPIO_PIN_3, 0x00);
                SysCtlDelay(2000000); //delay = 2000000 * 3 = 6000000 CPU cycles
                //set ui8PinData to the next LED color in the sequence
                //0010 (red), 0100 (blue), 1000 (green), ...
                if(ui8PinData==8) {ui8PinData=2;} else {ui8PinData=ui8PinData*2;}
        }
}
Task 02: Change the delay of the LED blink (approx. 0.333 sec)
by changing the clock source and configuration
int main(void)
        //2000000 loop * 3 CPU CYCLES = 6000000 CPU CYCLE
        \frac{1}{6000000} \frac{\text{freq}}{\text{freq}} = 0.333 \text{sec} = \frac{\text{freq}}{\text{freq}} = 6000000/0.333 \frac{\text{sec}}{\text{sec}} = 18.18 \text{MHZ}
        //sets clock: xtal = 16Mhz, 400MHz PLL divided by 22
        SysCtlClockSet(SYSCTL_SYSDIV_11|SYSCTL_USE_PLL|SYSCTL_XTAL_16MHZ|SYSCTL_OSC_
MAIN);
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Task 03: a) Change the sequence of LED blinking
#include <stdint.h>
                                           //variable definitions for the C99 standard
#include <stdbool.h>
                                  //Boolean definitions for the C99 standard
#include "inc/hw_memmap.h"
                                           //macros defining the memory map of Tiva C Series
#include "inc/hw_types.h"
                                  //defines common types and macros
#include "driverlib/sysctl.h"
                                  //defines macros for System Control API of Driverlib
#include "driverlib/gpio.h"
                                  //defines macros for GPIO API of Driverlib
uint8_t ui8PinData=8;
                         //unsigned 8-bt int that is used to cycle through LEDs in reverse
int main(void)
        \mathbf{while}(1)
                  //1000 (green), 0100 (blue), 0010 (red), ...
                 if(ui8PinData==2) {ui8PinData=8;} else {ui8PinData=ui8PinData/2;}
}
Task 03: b) Blink two LEDs at an instance and with a sequence
#include <stdint.h>
                                           //variable definitions for the C99 standard
#include <stdbool.h>
                                  //Boolean definitions for the C99 standard
#include "inc/hw_memmap.h"
                                           //macros defining the memory map of Tiva C Series
#include "inc/hw_types.h"
                                  //defines common types and macros
#include "driverlib/sysctl.h"
                                  //defines macros for System Control API of Driverlib
#include "driverlib/gpio.h"
                                  //defines macros for GPIO API of Driverlib
                         //unsigned 8-bt int that is used to cycle through LEDs
uint8 t ui8PinData=6;
int main(void)
        while(1)
                 //blink two LEDs simultaneously in a sequence
                                                             // 0110 (BR-purple)
                 if(ui8PinData==6) {ui8PinData=10;}
                 else if (ui8PinData==10) {ui8PinData=12;} // 1010(RG-yellow)
                 else {ui8PinData=6;} // 1100(GB-aqua)
```