# Assignment1

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### 1 1D case

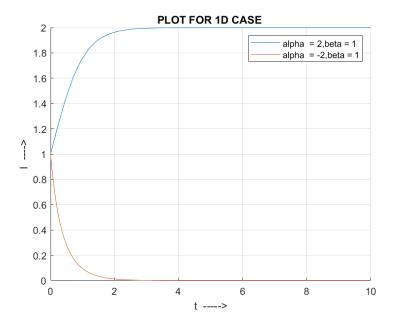
### 1.1 Equation

```
\dot{I} = (\alpha - \beta I)
```

#### 1.2 MATLAB code

```
clc;
clear all;
i0=1;
tspan=[0 10];
figure;
hold on;
a=2;
b=1;
[t,i]=ode45(@(t,i) (a-b*i)*i,tspan,i0);
plot(t,i);
labels1 = num2str([a,b],['alpha = %d,beta = %d']);
a=-2;
b=1;
[t,i]=ode45(@(t,i) (a-b*i)*i,tspan,i0);
plot(t,i);
labels2 = num2str([a,b],['alpha = %d,beta = %d']);
legend (labels1,labels2);
xlabel('t ---->');
ylabel('I --->');
title('PLOT FOR 1D CASE ');
grid on;
```

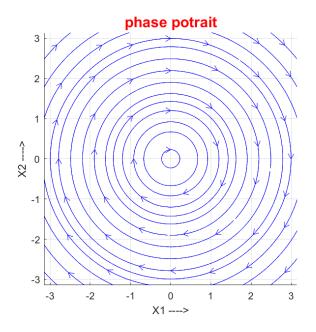
### 1.3 Plot



### 2 2D case

# 2.1 Example1

 $\dot{x}1 = x2$ 

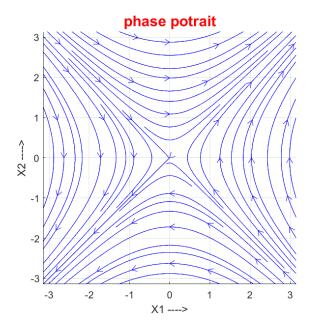


### 2.2 Example2

```
\begin{array}{l} \dot{x}1 = x2 \\ \dot{x}2 = x1 \end{array}
```

### MATLAB CODE

```
clear all;
clc;
[x,y]=meshgrid(-pi:0.01:pi);
u=y;
v=x;
streamslice(x,y,u,v);
title('phase potrait','FontSize',15,'Color','r');
xlabel('X1 ---->');
ylabel('X2 ---->');
axis tight square;
grid on;
PLOT
```



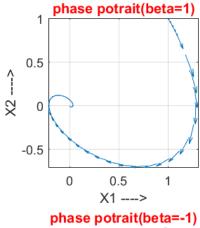
### 2.3 Example3

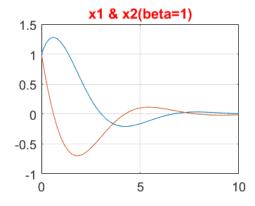
```
\dot{x}1 = x2
\dot{x}2 = -x1 - \beta x2
   MATLAB CODE
clc;
clear all;
b=1;
tspan=[0,10];
y0=[1;1];
plotarrow=@(m) \ quiver(m(:,1),m(:,2),gradient(m(:,1)),gradient(m(:,2)));
figure;
subplot(2,2,1);
[t,y] = ode45(@(t,y)f1(t,y,b),tspan,y0);
plotarrow(y);
title('phase potrait(beta=1)','FontSize',10,'Color','r');
xlabel('X1 --->');
ylabel('X2 --->');
axis tight square;
grid on;
subplot(2,2,2);
plot(t,y(:,1),t,y(:,2));
title('x1 & x2(beta=1)','FontSize',10,'Color','r');
grid on;
subplot(2,2,3);
b=-1;
[t,y] = ode45(@(t,y)f1(t,y,b),tspan,y0);
plotarrow(y);
title('phase potrait(beta=-1)', 'FontSize', 10, 'Color', 'r');
xlabel('X1 --->');
```

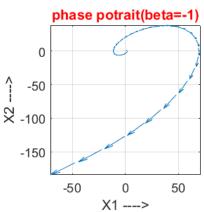
```
ylabel('X2 ---->');
grid on;
axis tight square;
subplot(2,2,4);
plot(t,y(:,1),t,y(:,2));
title('x1 & x2 (beta=-1)','FontSize',10,'Color','r');
grid on;

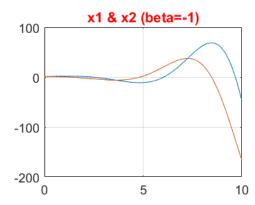
function d=f1(t,y,b)
d=zeros(2,1);
d(1)=y(2);
d(2)=-y(1)-b*y(2);
end
```

#### PLOT









# 2.4 Example4: Limit cycle

$$\begin{split} \ddot{x} + \dot{x} \left( x^2 + \dot{x}^2 - 1 \right) + x &= 0 \\ \text{Equivalent to two first order equation.} \\ \dot{x} &= y \\ \dot{y} &= -x - y (x^2 - y^2 - 1) \\ \text{MATLAB CODE:} \end{split}$$

%limit cycyle

clc;
clear;

```
tspan=[0:0.2:5*pi];
plotarrow=@(m) quiver(m(:,1),m(:,2),gradient(m(:,1)),gradient(m(:,2)));
figure;
subplot(2,2,1);
x0=[0;0.2];
[t,x] = ode45(@(t,y)f1(t,y),tspan,x0);
plotarrow(x);
title('phase potrait(initial point is inside)','Color','r');
xlabel('X1 --->');
ylabel('X2 ---->');
axis tight square;
grid on;
subplot(2,2,2);
plot(t,x(:,1),t,x(:,2));
grid on;
subplot(2,2,3);
y0=[2;0];
[t,y]=ode45(@(t,y)f1(t,y),tspan,y0);
plotarrow(y);
title('phase potrait(initial point is inside)','Color','r');
xlabel('X1 --->');
ylabel('X2 --->');
axis tight square;
grid on;
subplot(2,2,4);
plot(t,y(:,1),t,y(:,2));
grid on;
function d=f1(t,y)
d=zeros(2,1);
d(1)=y(2);
d(2)=-y(2)*(y(1)*y(1)+y(2)*y(2)-1)-y(1);
```

PLOT

