A Medium-Grained Algorithm for Distributed Sparse Tensor Factorization

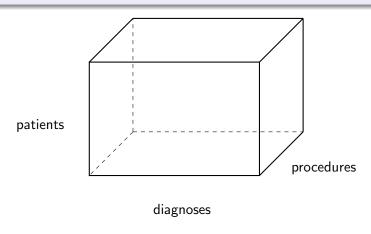
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- Preliminaries
- 2 Related Work: Coarse- and Fine-Grained Algorithms
- 3 A Medium-Grained Algorithm
- 4 Experiments
- Conclusions

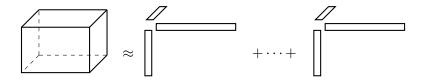
Tensor Introduction

- Tensors are the generalization of matrices to $\geq 3D$
- Tensors have m dimensions (or modes) and are $I_1 \times ... \times I_m$.
 - We'll stick to m = 3 in this talk and call dimensions I, J, K



Canonical Polyadic Decomposition (CPD)

- We compute matrices **A**, **B**, **C**, each with *F* columns
 - F is assumed to be small, on the order of 10 or 50



- Usually computed via alternating least squares (ALS)
- As a result, computations are mode-centric

CPD-ALS

Algorithm 1 CPD-ALS

1: while not converged do

2:
$$\mathbf{A}^{\mathsf{T}} = (\mathbf{C}^{\mathsf{T}}\mathbf{C} * \mathbf{B}^{\mathsf{T}}\mathbf{B})^{-1} (\mathbf{X}_{(1)}(\mathbf{C} \odot \mathbf{B}))^{\mathsf{T}}$$

3:
$$\mathbf{B}^{\mathsf{T}} = (\mathbf{C}^{\mathsf{T}}\mathbf{C} * \mathbf{A}^{\mathsf{T}}\mathbf{A})^{-1} (\mathbf{X}_{(2)}(\mathbf{C} \odot \mathbf{A}))^{\mathsf{T}}$$

4:
$$\mathbf{C}^{\mathsf{T}} = (\mathbf{B}^{\mathsf{T}}\mathbf{B} * \mathbf{A}^{\mathsf{T}}\mathbf{A})^{-1} (\mathbf{X}_{(3)}(\mathbf{B} \odot \mathbf{A}))^{\mathsf{T}}$$

5: end while

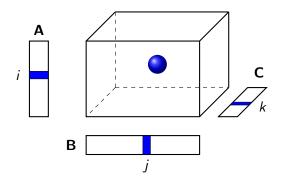
A Closer Look...

Algorithm 2 One mode of CPD-ALS

1:
$$\hat{\mathbf{A}} \leftarrow \mathbf{X}_{(1)}(\mathbf{C} \odot \mathbf{B})$$
 $\triangleright \mathcal{O}(F \cdot \mathsf{nnz}(\mathcal{X}))$
2: $\mathbf{L}\mathbf{L}^{\mathsf{T}} \leftarrow \mathsf{Cholesky}(\mathbf{C}^{\mathsf{T}}\mathbf{C} * \mathbf{B}^{\mathsf{T}}\mathbf{B})$ $\triangleright \mathcal{O}(F^3)$
3: $\mathbf{A}^{\mathsf{T}} = (\mathbf{L}\mathbf{L}^{\mathsf{T}})^{-1}\hat{\mathbf{A}}^{\mathsf{T}}$ $\triangleright \mathcal{O}(\mathit{IF}^2)$
4: Compute $\mathbf{A}^{\mathsf{T}}\mathbf{A}$ $\triangleright \mathcal{O}(\mathit{IF}^2)$

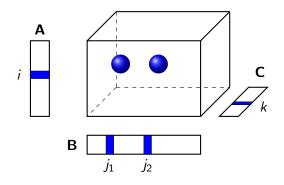
• Step 1 is the most expensive and the focus of this talk

Matricized Tensor Times Khatri-Rao Product (MTTKRP)



$$\hat{\mathbf{A}}(i,:) \leftarrow \hat{\mathbf{A}}(i,:) + \mathcal{X}(i,j,k) \left[\mathbf{B}(j,:) * \mathbf{C}(k,:) \right]$$

MTTKRP Communication

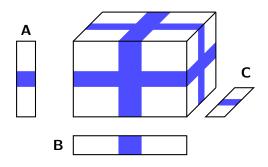


$$\hat{\mathbf{A}}(i,:) \leftarrow \hat{\mathbf{A}}(i,:) + \mathcal{X}(i,j_1,k) \left[\mathbf{B}(j_1,:) * \mathbf{C}(k,:) \right]$$

$$\hat{\mathbf{A}}(i,:) \leftarrow \hat{\mathbf{A}}(i,:) + \mathcal{X}(i,j_2,k) \left[\mathbf{B}(j_2,:) * \mathbf{C}(k,:) \right]$$

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Coarse-Grained Decomposition



[Choi & Vishwanathan 2014, Shin & Kang 2014]

- ullet Processes own complete slices of ${\mathcal X}$ and aligned factor rows
- ullet I/p rows communicated to $p{-}1$ processes after each update

Fine-Grained Decomposition

[Kaya & Uçar 2015]

- Most flexible: non-zeros individually assigned to processes
- Two communication steps
 - Aggregate partial computations after MTTKRP
 - Exchange new factor values
- Factors can be assigned to minimize communication

Finding a Fine-Grained Decomposition

Some options:

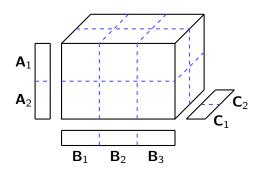
- Random assignment
- Hypergraph partitioning
- Multi-constraint hypergraph partitioning

In Practice: Hypergraph Model

- nnz(X) vertices and I+J+K hyperedges
- Tight approximation of communication and load balance
 - Distribution of factors must be considered: in practice a greedy solution works well

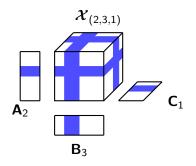
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Medium-Grained Decomposition



- Distribute over a grid of $p = q \times r \times s$ partitions
- ullet $r{ imes}s$ processes divide each ${f A}_1,\ldots,{f A}_q$
- Two communication steps like fine-grained
 - $\mathcal{O}(1/p)$ rows communicated to $r \times s$ processes

Medium-Grained Decomposition



- Each process owns roughly I/p rows of each factor
- Like before, a greedy algorithm works well

Finding a Medium-Grained Decomposition

Greedy Algorithm

- lacksquare Apply a random relabeling to modes of ${\mathcal X}$
- 2 Choose a decomposition dimension (algorithm in paper)
- Ompute 1D partitionings of each mode
 - Greedily chosen with load balance objective
- Intersect!
- Obstribute factors with objective of reducing communication

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Datasets

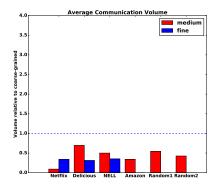
Dataset	1	J	K	nnz
Netflix	480K	18K	2K	100M
Delicious	532K	17M	3M	140M
NELL	3M	2M	25M	143M
Amazon	5M	18M	2M	1.7B
Random1	20M	20M	20M	1.0B
Random2	50M	5M	5M	1.0B

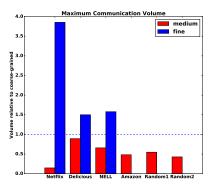
Load Balance

Table: Load imbalance with 64 and 128 processes.

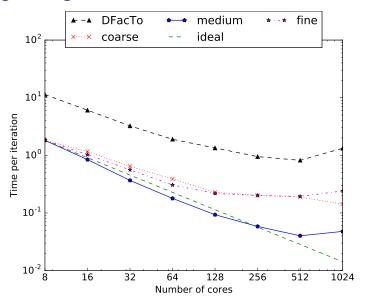
	coarse		medium		fine	
Dataset	64	128	64	128	64	128
Netflix	1.03	1.18	1.00	1.00	1.00	1.00
Delicious	1.21	1.41	1.01	1.06	1.00	1.05
NELL	1.12	1.29	1.01	1.01	1.00	1.00
Amazon	2.17	3.86	1.08	1.08	_	-

Communication Volume

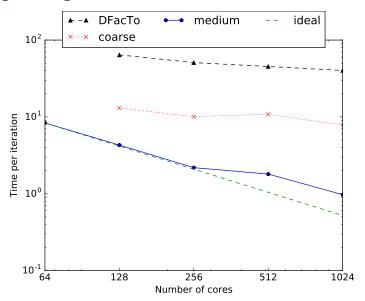




Strong Scaling: Netflix



Strong Scaling: Amazon



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Wrapping Up...

- Medium-grained decompositions are a good middle-ground
- 1.5 \times to 5 \times faster than fine-grained decompositions with hypergraph partitioning
- DMS is $40\times$ to $80\times$ faster than DFACTO, the fastest publicly available software

http://cs.umn.edu/~splatt/

Choosing the Shape of the Decomposition

Objective

- We need to find q, r, s such that $q \times r \times s = p$
- Tensors modes are often very skewed (480k Netflix users vs 2k days)
 - We want to assign processes proportionally
 - ▶ 1D decompositions actually work well for many tensors

Algorithm

- Start with a $1 \times 1 \times 1$ shape
- 2 Compute the prime factorization of p
- For each prime factor f, starting from the largest, multiply the most imbalanced mode by f