

Shadi Haddad

PHD CANDIDATE · APPLIED MATHEMATICS

Santa Cruz, CA

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Education

University of California, Santa Cruz " " "

Santa Cruz, CA

PHD IN APPLIED MATHEMATICS

Expected graduation in Aug 2023

- Chancellor's Fellowship (2019)
- Applied Mathematics Research Award (2022)

University of Tehran, College of Mechanical Engineering

Tehran, Iran

M.SC. IN MECHANICAL ENGINEERING

January 2018

- Thesis: "Second Order Sliding Mode Tracking Control of a Piezoelectric Tapered Micro Actuator with Axial Deflection and System Nonlinearity"
- Full Tuition Merit Scholarship

Chamran University of Ahvaz, College of Mechanical Engineering

Ahvaz, Iran

B.SC. IN MECHANICAL ENGINEERING

July 2015

- Full Tuition Merit Scholarship

Work & Research

Graduate Student Researcher with the University of California at Santa Cruz

Santa Cruz, CA

2019-Present

- Optimization for control and machine learning
- Set-based reachability analysis
- Stochastic control and model predictive control

Teaching Assistant with the University of California at Santa Cruz

- Convex optimization
- Introduction to Dynamical Systems
- Mathematical Methods for Engineering II

Fall 2022

Fall 2021

Winter 2021

Graduate Student Researcher with the University of Tehran

Tehran, Iran

2015-2018

- Micro-beam mechanical design and vibration control

Expertise and Skills

- Optimization and semidefinite programming (SDP), Machine learning (ML)
- Optimal Control, Stochastic Control, Model Predictive Control (MPC)
- Reachability analysis

Programming

- MATLAB and Simulink, CVX, Python, Data Structure, Matplotlib, TensorFlow, MAPLE, C++, Numerical Methods, Physical Simulations, Scientific Visualization

Engineering, Modelling, and Simulation

- SOLIDWORKS, ABAQUS, LabVIEW

Technical Writing and Documentation

- \LaTeX , Jupyter Notebook, Keynote

Publications

The Curious Case of Integrator Reach Sets, Part I: Basic Theory	IEEE TRANSACTIONS ON AUTOMATIC CONTROL
Shadi Haddad, Abhishek Halder	2023
Convex and Nonconvex Sublinear Regression with Application to Data-driven Learning of Reach Sets	AMERICAN CONTROL CONFERENCE
Shadi Haddad, Abhishek Halder	2023
Hausdorff Distance between Norm Balls and their Linear Maps	ARXIV:2206.12012
Shadi Haddad, Abhishek Halder	2022
Certifying the Intersection of Reach Sets of Integrator Agents with Set-valued Input Uncertainties	IEEE CONTROL SYSTEMS LETTERS
Shadi Haddad, Abhishek Halder	2022
Density-Based Stochastic Reachability Computation for Occupancy Prediction in Automated Driving	IEEE TRANSACTIONS ON CONTROL SYSTEMS TECHNOLOGY
Shadi Haddad, Abhishek Halder, and Baljeet Singh	2022
Boundary and Taxonomy of Integrator Reach Sets	AMERICAN CONTROL CONFERENCE
Shadi Haddad, Abhishek Halder	2022
Anytime Ellipsoidal Over-approximation of Forward Reach Sets of Uncertain Linear Systems	CPS IOT WEEK WORKSHOP
Shadi Haddad, Abhishek Halder	2021
Prediction and Optimal Feedback Steering of Probability Density Functions for Safe Automated Driving	IEEE CONTROL SYSTEMS LETTERS
Shadi Haddad, Kenneth F Caluya, Abhishek Halder, Baljeet Singh	2020
The Convex Geometry of Integrator Reach Sets	AMERICAN CONTROL CONFERENCE
Shadi Haddad, Abhishek Halder	2020
Observer Based Fault Reconstruction Schemes Using Terminal Sliding Modes	INTERNATIONAL JOURNAL OF CONTROL
M. Mousavi, M. Rahn timer, S. Haddad	2018
Analytical Study on Nonlinear 3D Coupled Deformations of Tapered FG Micro-beams Accounting for Size Effects	IRANIAN JOURNAL OF SCIENCE AND TECHNOLOGY
S. Haddad, M. Baghani	2018

Talks and Presentations

IEEE Conference on Decision and Control	Cancún, Mexico
JOURNAL PAPER AND CONFERENCE TALK	2022
“Certifying the Intersection of Reach Sets of Integrator Agents with Set-valued Input Uncertainties ”	
American Control Conference	Atlanta, GA
JOURNAL PAPER AND CONFERENCE TALK	2022
“Boundary and Taxonomy of Integrator Reach Sets”	
American Control Conference	Virtual
JOURNAL PAPER AND CONFERENCE TALK	2021
“Prediction and Optimal Feedback Steering of Probability Density Functions for Safe Automated Driving”	
3rd NorCal Control Workshop	Virtual
CONFERENCE TALK	2021
“The Convex Geometry of Integrator Reach Sets”	
American Control Conference	Virtual
CONFERENCE PAPER AND TALK	2020
“The Convex Geometry of Integrator Reach Sets”	
Bay Area Robotics Symposium	University of California at Berkeley
SPOTLIGHT TALK AND POSTER PRESENTATION	2019
“Understanding the Geometry of Integrator Reach Sets for Robotics Applications”	

Professional Activities

- 2023 **Reviewer for 2023 American Control conference**
- 2022 **Reviewer for 2022 IEEE Conference on Decision and Control**
- 2022 **Reviewer for 2022 American Control conference**
- 2021 **Reviewer for 2021 IEEE Control Systems Letters**
- 2021 **Reviewer for 2021 IEEE Conference on Decision and Control**
- 2021 **Reviewer for 2021 CPS IoT Week Workshop on Computation-Aware Algorithmic Design for Cyber-Physical Systems**
- 2020 **Reviewer for 2020 IEEE Conference on Decision and Control**

Honors & Awards

- 2022 **Applied Mathematics Research Award**, University of California at Santa Cruz *Santa Cruz, CA*
- 2022 **Student Travel Award**, IEEE Control Systems Society, American Control Conference *Atlanta, GA*
- 2022 **Advancement to Ph.D Candidacy with Honors**, University of California at Santa Cruz *Santa Cruz, CA*
- 2021 **Student Travel Award**, IEEE Control Systems Society, American Control Conference *New Orleans, LA (Virtual)*
- 2020 **Student Travel Award**, IEEE Control Systems Society, American Control Conference *Denver, CO (Virtual)*
- 2019 **Chancellor's Fellowship**, University of California at Santa Cruz *Santa Cruz, CA*
- 2015 **Full Tuition Merit Scholarship**, University of Tehran *Tehran, Iran*
- 2011 **Full Tuition Merit Scholarship**, Chamran University of Ahvaz *Ahvaz, Iran*

Selected Graduate Courses

**Machine Learning, Convex Optimization, Nonlinear Control Theory, Applied Optimal Control,
Finite Element Method**

*UC Santa Cruz
University of Tehran*