# Shadi Haddad

#### PHD CANDIDATE · APPLIED MATHEMATICS

Santa Cruz, CA

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### **Education**

### University of California, Santa Cruz

Santa Cruz, CA

PHD IN APPLIED MATHEMATICS

Expected graduation in Aug 2023

- Chancellor's Fellowship (2019)
- Applied Mathematics Research Award (2022)

### University of Tehran, College of Mechanical Engineering

Tehran, Iran

M.Sc. in Mechanical Engineering

January 2018

- Thesis: "Second Order Sliding Mode Tracking Control of a Piezoelectric Tapered Micro Actuator with Axial Deflection and System Nonlinearity"
- Full Tuition Merit Scholarship

#### Chamran University of Ahvaz, College of Mechanical Engineering

Ahvaz, Iran

July 2015

B.Sc. IN MECHANICAL ENGINEERINGFull Tuition Merit Scholarship

## **Work & Research**

#### Graduate Student Researcher with the University of California at Santa Cruz

Santa Cruz, CA

2019-Present

- Optimization for control and machine learning
- Set-based reachability analysis
- · Stochastic control and model predictive control

### Teaching Assistant with the University of California at Santa Cruz

Convex optimization

Fall 2022

• Introduction to Dynamical Systems

Mathematical Methods for Engineering II
 Winter 2021

#### **Graduate Student Researcher with the University of Tehran**

Tehran, Iran

• Micro-beam mechanical design and vibration control

2015-2018

# **Expertise and Skills**

- Optimization and semidefinite programming (SDP), Machine learning (ML)
- Optimal Control, Stochastic Control, Model Predictive Control (MPC)
- Reachability analysis

#### **Programming**

• MATLAB and Simulink, CVX, Python, Data Structure, Matplotlib, TensorFlow, MAPLE, C++, Numerical Methods, Physical Simulations, Scientific Visualization

#### **Engineering, Modelling, and Simulation**

· SOLIDWORKS, ABAQUS, LabVIEW

#### **Technical Writing and Documentation**

• LTFX, Jupyter Notebook, Keynote

**Publications IEEE Transactions on Automatic** The Curious Case of Integrator Reach Sets, Part I: Basic Theory CONTROL Shadi Haddad, Abhishek Halder 2023 Convex and Nonconvex Sublinear Regression with Application to Data-driven Learning of Reach Sets AMERICAN CONTROL CONFERENCE Shadi Haddad, Abhishek Halder Hausdorff Distance between Norm Balls and their Linear Maps ARXIV:2206.12012 Shadi Haddad, Abhishek Halder 2022 Certifying the Intersection of Reach Sets of Integrator Agents with Set-valued Input Uncertainties **IEEE CONTROL SYSTEMS LETTERS** Shadi Haddad, Abhishek Halder IEEE TRANSACTIONS ON CONTROL Density-Based Stochastic Reachability Computation for Occupancy Prediction in Automated Driving SYSTEMS TECHNOLOGY Shadi Haddad, Abhishek Halder, and Baljeet Singh 2022 Boundary and Taxonomy of Integrator Reach Sets AMERICAN CONTROL CONFERENCE Shadi Haddad, Abhishek Halder Anytime Ellipsoidal Over-approximation of Forward Reach Sets of Uncertain Linear Systems **CPS IOT WEEK WORKSHOP** Shadi Haddad, Abhishek Halder Prediction and Optimal Feedback Steering of Probability Density Functions for Safe Automated Driving IFFF CONTROL SYSTEMS LETTERS Shadi Haddad, Kenneth F Caluya, Abhishek Halder, Baljeet Singh 2020

The Convex Geometry of Integrator Reach Sets AMERICAN CONTROL CONFERENCE Shadi Haddad, Abhishek Halder

INTERNATIONAL JOURNAL OF

Observer Based Fault Reconstruction Schemes Using Terminal Sliding Modes CONTROL M. Mousavi, M. Rahnavard, S. Haddad 2018

Analytical Study on Nonlinear 3D Coupled Deformations of Tapered FG Micro-beams Accounting for Size

**IRANIAN JOURNAL OF SCIENCE AND Effects TECHNOLOGY** S. Haddad, M. Baghani 2018

# **Talks and Presentations**

**IEEE Conference on Decision and Control** Cancún, Mexico

JOURNAL PAPER AND CONFERENCE TALK 2022

"Certifying the Intersection of Reach Sets of Integrator Agents with Set-valued Input Uncertainties"

**American Control Conference** Atlanta, GA JOURNAL PAPER AND CONFERENCE TALK 2022

"Boundary and Taxonomy of Integrator Reach Sets"

**American Control Conference** Virtual JOURNAL PAPER AND CONFERENCE TALK 2021

"Prediction and Optimal Feedback Steering of Probability Density Functions for Safe Automated Driving"

3rd NorCal Control Workshop Virtual

CONFERENCE TALK

"The Convex Geometry of Integrator Reach Sets"

**American Control Conference** Virtual CONFERENCE PAPER AND TALK 2020

"The Convex Geometry of Integrator Reach Sets"

**Bay Area Robotics Symposium** University of California at Berkeley SPOTLIGHT TALK AND POSTER PRESENTATION 2019

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"Understanding the Geometry of Integrator Reach Sets for Robotics Applications"

## Professional Activities\_\_\_\_\_

- 2023 Reviewer for 2023 American Control conference
- 2022 Reviewer for 2022 IEEE Conference on Decision and Control
- 2022 Reviewer for 2022 American Control conference
- 2021 Reviewer for 2021 IEEE Control Systems Letters
- 2021 Reviewer for 2021 IEEE Conference on Decision and Control
- 2021 Reviewer for 2021 CPS IoT Week Workshop on Computation-Aware Algorithmic Design for Cyber-Physical Systems
- 2020 Reviewer for 2020 IEEE Conference on Decision and Control

## Honors & Awards

2022	Applied Mathematics Research Award, University of California at Santa Cruz	Santa Cruz, CA
2022	Student Travel Award, IEEE Control Systems Society, American Control Conference	Atlanta, GA
2022	Advancement to Ph.D Candidacy with Honors, University of California at Santa Cruz	Santa Cruz, CA
2021	Student Travel Award, IEEE Control Systems Society, American Control Conference	New Orleans, LA (Virtual)
2020	Student Travel Award, IEEE Control Systems Society, American Control Conference	Denver, CO (Virtual)
2019	Chancellor's Fellowship, University of California at Santa Cruz	Santa Cruz, CA
2015	Full Tuition Merit Scholarship, University of Tehran	Tehran, Iran
2011	Full Tuition Merit Scholarship, Chamran University of Ahvaz	Ahvaz, Iran

## Selected Graduate Courses \_\_\_\_\_

Machine Learning, Convex Optimization, Nonlinear Control Theory, Applied Optimal Control, Finite Element Method

UC Santa Cruz University of Tehran