

## 1. Description

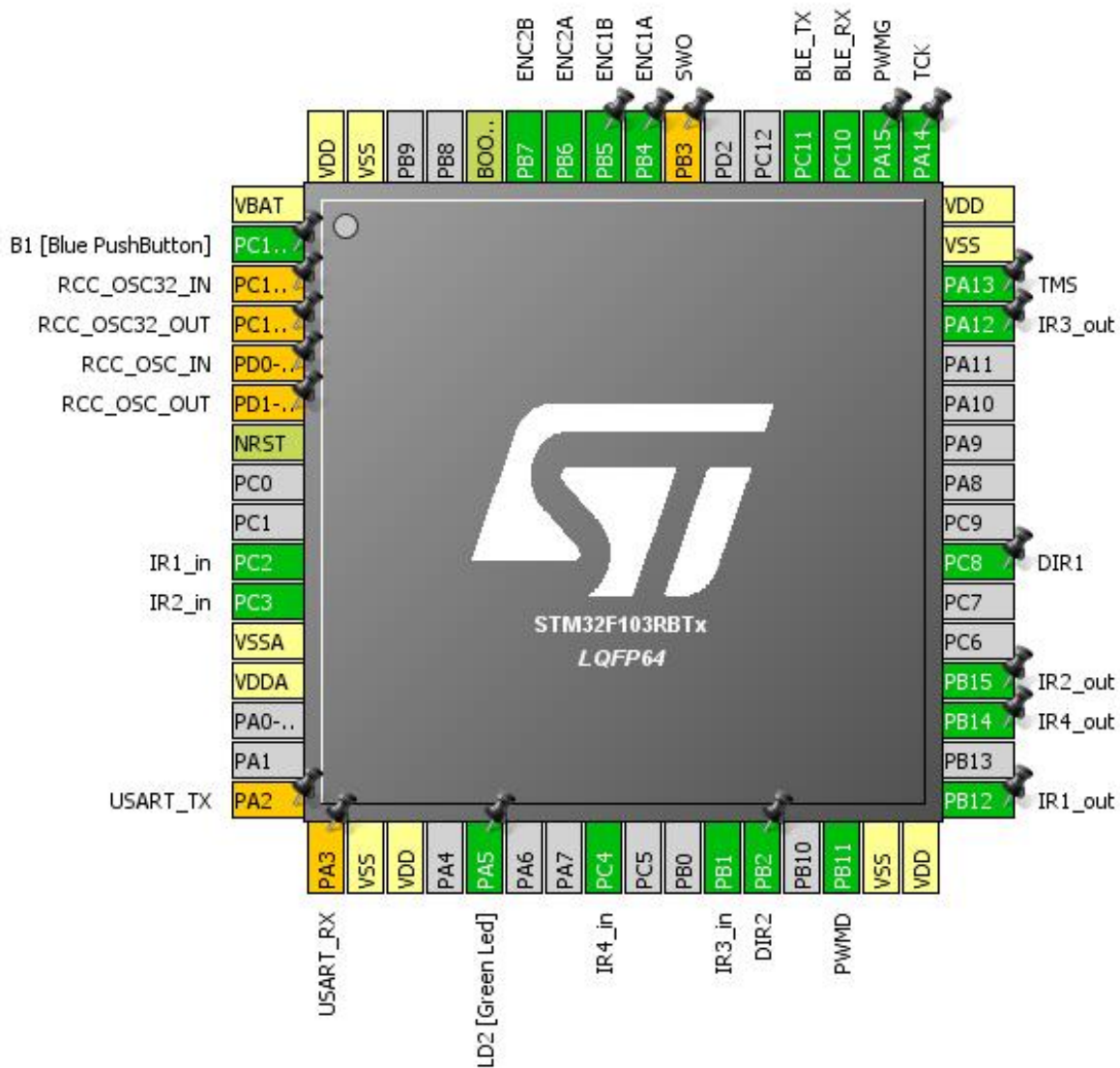
### 1.1. Project

Project Name	Robot3_F103RB_origin
Board Name	NUCLEO-F103RB
Generated with:	STM32CubeMX 4.24.0
Date	12/17/2019

### 1.2. MCU

MCU Series	STM32F1
MCU Line	STM32F103
MCU name	STM32F103RBTx
MCU Package	LQFP64
MCU Pin number	64

## 2. Pinout Configuration



### 3. Pins Configuration

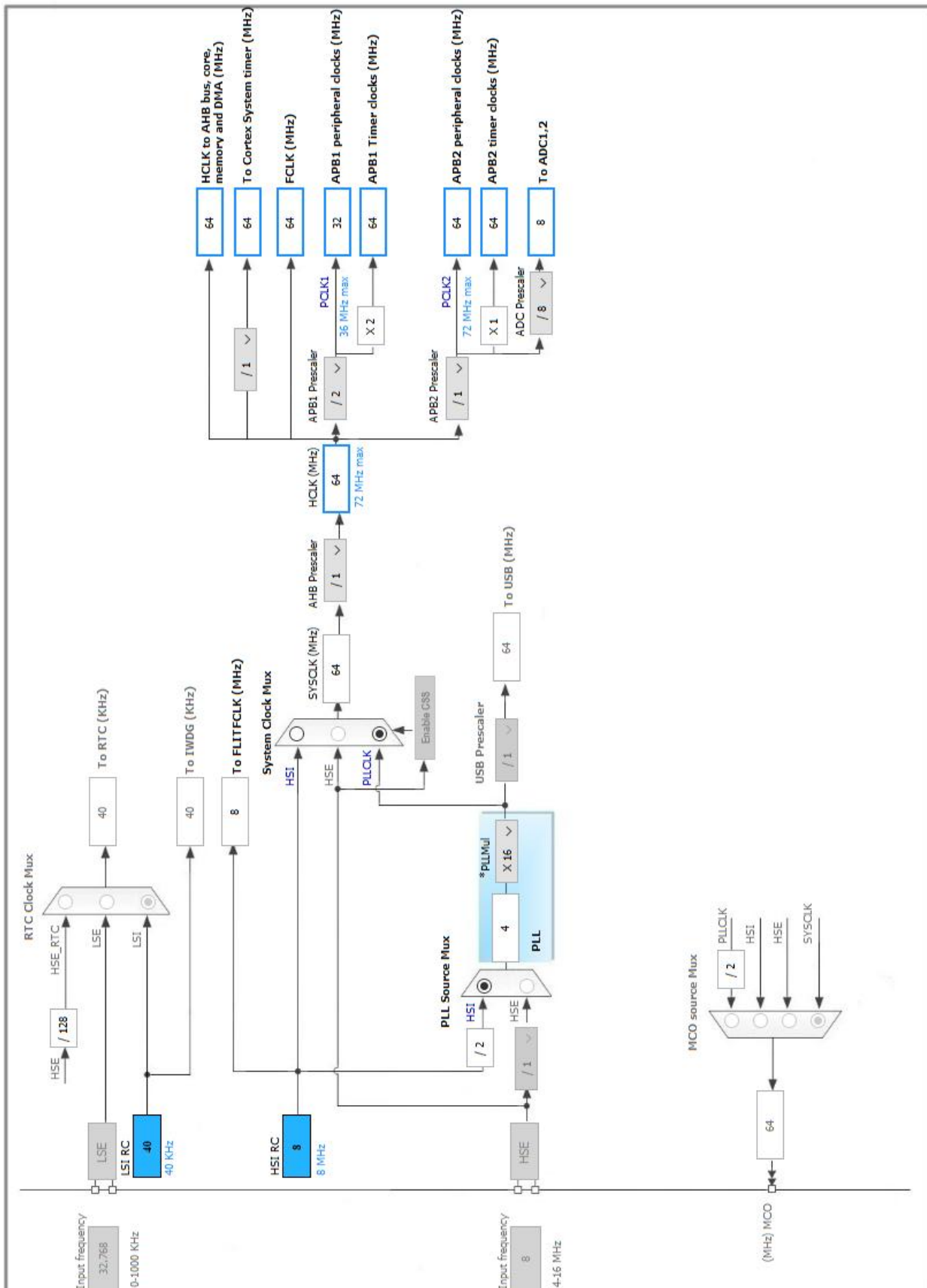
Pin Number LQFP64	Pin Name (function after reset)	Pin Type	Alternate Function(s)	Label
1	VBAT	Power		
2	PC13-TAMPER-RTC	I/O	GPIO_EXTI13	B1 [Blue PushButton]
3	PC14-OSC32_IN *	I/O	RCC_OSC32_IN	
4	PC15-OSC32_OUT *	I/O	RCC_OSC32_OUT	
5	PD0-OSC_IN *	I/O	RCC_OSC_IN	
6	PD1-OSC_OUT *	I/O	RCC_OSC_OUT	
7	NRST	Reset		
10	PC2	I/O	ADC1_IN12	IR1_in
11	PC3	I/O	ADC1_IN13	IR2_in
12	VSSA	Power		
13	VDDA	Power		
16	PA2 *	I/O	USART2_TX	USART_TX
17	PA3 *	I/O	USART2_RX	USART_RX
18	VSS	Power		
19	VDD	Power		
21	PA5 **	I/O	GPIO_Output	LD2 [Green Led]
24	PC4	I/O	ADC1_IN14	IR4_in
27	PB1	I/O	ADC1_IN9	IR3_in
28	PB2 **	I/O	GPIO_Output	DIR2
30	PB11	I/O	TIM2_CH4	PWMD
31	VSS	Power		
32	VDD	Power		
33	PB12 **	I/O	GPIO_Output	IR1_out
35	PB14 **	I/O	GPIO_Output	IR4_out
36	PB15 **	I/O	GPIO_Output	IR2_out
39	PC8 **	I/O	GPIO_Output	DIR1
45	PA12 **	I/O	GPIO_Output	IR3_out
46	PA13	I/O	SYS_JTMS-SWDIO	TMS
47	VSS	Power		
48	VDD	Power		
49	PA14	I/O	SYS_JTCK-SWCLK	TCK
50	PA15	I/O	TIM2_CH1	PWMG
51	PC10	I/O	USART3_TX	BLE_RX
52	PC11	I/O	USART3_RX	BLE_TX
55	PB3 *	I/O	SYS_JTDO-TRACESWO	SWO
56	PB4	I/O	TIM3_CH1	ENC1A

Pin Number LQFP64	Pin Name (function after reset)	Pin Type	Alternate Function(s)	Label
57	PB5	I/O	TIM3_CH2	ENC1B
58	PB6	I/O	TIM4_CH1	ENC2A
59	PB7	I/O	TIM4_CH2	ENC2B
60	BOOT0	Boot		
63	VSS	Power		
64	VDD	Power		

\*\* The pin is affected with an I/O function

\* The pin is affected with a peripheral function but no peripheral mode is activated

## 4. Clock Tree Configuration



## 5. IPs and Middleware Configuration

### 5.1. ADC1

mode: IN9

mode: IN12

mode: IN13

mode: IN14

#### 5.1.1. Parameter Settings:

##### ADCs\_Common\_Settings:

Mode Independent mode

##### ADC\_Settings:

Data Alignment Right alignment

Scan Conversion Mode Enabled

Continuous Conversion Mode Disabled

Discontinuous Conversion Mode Disabled

##### ADC\_Regular\_ConversionMode:

Enable Regular Conversions Enable

Number Of Conversion **4 \***

External Trigger Conversion Source Regular Conversion launched by software

Rank 1

Channel Channel 9

Sampling Time **239.5 Cycles \***

Rank **2 \***

Channel **Channel 12 \***

Sampling Time **239.5 Cycles \***

Rank **3 \***

Channel **Channel 13 \***

Sampling Time **239.5 Cycles \***

Rank **4 \***

Channel **Channel 14 \***

Sampling Time **239.5 Cycles \***

##### ADC\_Injected\_ConversionMode:

Number Of Conversions 0

##### WatchDog:

Enable Analog WatchDog Mode                      false

## 5.2. SYS

**Debug: Serial Wire**

**Timebase Source: SysTick**

## 5.3. TIM2

**Clock Source : Internal Clock**

**Channel1: PWM Generation CH1**

**Channel4: PWM Generation CH4**

### 5.3.1. Parameter Settings:

#### Counter Settings:

Prescaler (PSC - 16 bits value)	1 *
Counter Mode	Up
Counter Period (AutoReload Register - 16 bits value )	64000 *
Internal Clock Division (CKD)	No Division
auto-reload preload	Disable

#### Trigger Output (TRGO) Parameters:

Master/Slave Mode (MSM bit)	Disable (Trigger input effect not delayed)
Trigger Event Selection	Reset (UG bit from TIMx_EGR)

#### PWM Generation Channel 1:

Mode	PWM mode 1
Pulse (16 bits value)	0
Fast Mode	Disable
CH Polarity	High

#### PWM Generation Channel 4:

Mode	PWM mode 1
Pulse (16 bits value)	0
Fast Mode	Disable
CH Polarity	High

## 5.4. TIM3

## Combined Channels: Encoder Mode

### 5.4.1. Parameter Settings:

#### Counter Settings:

Prescaler (PSC - 16 bits value)	0
Counter Mode	Up
Counter Period (AutoReload Register - 16 bits value )	<b>0xFFFF *</b>
Internal Clock Division (CKD)	No Division
auto-reload preload	<b>Enable *</b>

#### Trigger Output (TRGO) Parameters:

Master/Slave Mode (MSM bit)	Disable (Trigger input effect not delayed)
Trigger Event Selection	Reset (UG bit from TIMx_EGR)

#### Encoder:

Encoder Mode	<b>Encoder Mode TI1 and TI2 *</b>
____ Parameters for Channel 1 ____	
Polarity	Rising Edge
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter	<b>8 *</b>
____ Parameters for Channel 2 ____	
Polarity	Rising Edge
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter	<b>8 *</b>

## 5.5. TIM4

## Combined Channels: Encoder Mode

### 5.5.1. Parameter Settings:

#### Counter Settings:

Prescaler (PSC - 16 bits value)	0
Counter Mode	Up
Counter Period (AutoReload Register - 16 bits value )	<b>0xFFFF *</b>
Internal Clock Division (CKD)	No Division
auto-reload preload	<b>Enable *</b>



### Trigger Output (TRGO) Parameters:

Master/Slave Mode (MSM bit)	Disable (Trigger input effect not delayed)
Trigger Event Selection	Reset (UG bit from TIMx_EGR)

### Encoder:

Encoder Mode

\_\_\_\_ Parameters for Channel 1 \_\_\_\_

Polarity

IC Selection

Prescaler Division Ratio

Input Filter

\_\_\_\_ Parameters for Channel 2 \_\_\_\_

Polarity

IC Selection

Prescaler Division Ratio

Input Filter

### Encoder Mode TI1 and TI2 \*

Rising Edge

Direct

No division

**8 \***

Rising Edge

Direct

No division

**8 \***

## 5.6. USART3

**Mode: Asynchronous**

### 5.6.1. Parameter Settings:

#### Basic Parameters:

Baud Rate	<b>9600 *</b>
Word Length	8 Bits (including Parity)
Parity	None
Stop Bits	1

#### Advanced Parameters:

Data Direction	Receive and Transmit
Over Sampling	16 Samples

**\* User modified value**

## 6. System Configuration

### 6.1. GPIO configuration

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
ADC1	PC2	ADC1_IN12	Analog mode	n/a	n/a	IR1_in
	PC3	ADC1_IN13	Analog mode	n/a	n/a	IR2_in
	PC4	ADC1_IN14	Analog mode	n/a	n/a	IR4_in
	PB1	ADC1_IN9	Analog mode	n/a	n/a	IR3_in
SYS	PA13	SYS_JTMS-SWDIO	n/a	n/a	n/a	TMS
	PA14	SYS_JTCK-SWCLK	n/a	n/a	n/a	TCK
TIM2	PB11	TIM2_CH4	Alternate Function Push Pull	n/a	Low	PWMD
	PA15	TIM2_CH1	Alternate Function Push Pull	n/a	Low	PWMG
TIM3	PB4	TIM3_CH1	Input mode	No pull-up and no pull-down	n/a	ENC1A
	PB5	TIM3_CH2	Input mode	No pull-up and no pull-down	n/a	ENC1B
TIM4	PB6	TIM4_CH1	Input mode	No pull-up and no pull-down	n/a	ENC2A
	PB7	TIM4_CH2	Input mode	No pull-up and no pull-down	n/a	ENC2B
USART3	PC10	USART3_TX	Alternate Function Push Pull	n/a	High *	BLE_RX
	PC11	USART3_RX	Input mode	No pull-up and no pull-down	n/a	BLE_TX
Single Mapped Signals	PC14-OSC32_IN	RCC_OSC32_IN	n/a	n/a	n/a	
	PC15-OSC32_OUT	RCC_OSC32_OUT	n/a	n/a	n/a	
	PD0-OSC_IN	RCC_OSC_IN	n/a	n/a	n/a	
	PD1-OSC_OUT	RCC_OSC_OUT	n/a	n/a	n/a	
	PA2	USART2_TX	Alternate Function Push Pull	n/a	Low	USART_TX
	PA3	USART2_RX	*	No pull-up and no pull-down	n/a	USART_RX
	PB3	SYS_JTDO-TRACESWO	n/a	n/a	n/a	SWO
GPIO	PC13-TAMPER-RTC	GPIO_EXTI13	External Interrupt Mode with Falling edge trigger detection	No pull-up and no pull-down	n/a	B1 [Blue PushButton]
	PA5	GPIO_Output	Output Push Pull	n/a	Low	LD2 [Green Led]
	PB2	GPIO_Output	Output Push Pull	n/a	Low	DIR2
	PB12	GPIO_Output	Output Push Pull	n/a	Low	IR1_out

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
	PB14	GPIO_Output	Output Push Pull	n/a	Low	IR4_out
	PB15	GPIO_Output	Output Push Pull	n/a	Low	IR2_out
	PC8	GPIO_Output	Output Push Pull	n/a	Low	DIR1
	PA12	GPIO_Output	Output Push Pull	n/a	Low	IR3_out

## 6.2. DMA configuration

DMA request	Stream	Direction	Priority
ADC1	DMA1_Channel1	Peripheral To Memory	Low

### ADC1: DMA1\_Channel1 DMA request Settings:

Mode: **Circular \***  
Peripheral Increment: Disable  
Memory Increment: **Enable \***  
Peripheral Data Width: Half Word  
Memory Data Width: Half Word

### 6.3. NVIC configuration

Interrupt Table	Enable	Preenmption Priority	SubPriority
Non maskable interrupt	true	0	0
Hard fault interrupt	true	0	0
Memory management fault	true	0	0
Prefetch fault, memory access fault	true	0	0
Undefined instruction or illegal state	true	0	0
System service call via SWI instruction	true	0	0
Debug monitor	true	0	0
Pendable request for system service	true	0	0
System tick timer	true	0	0
DMA1 channel1 global interrupt	true	0	0
TIM2 global interrupt	true	0	0
USART3 global interrupt	true	0	0
EXTI line[15:10] interrupts	true	0	0
PVD interrupt through EXTI line 16	unused		
Flash global interrupt	unused		
RCC global interrupt	unused		
ADC1 and ADC2 global interrupts	unused		
TIM3 global interrupt	unused		
TIM4 global interrupt	unused		

\* User modified value

## ***7. Power Consumption Calculator report***

### 7.1. Microcontroller Selection

Series	STM32F1
Line	STM32F103
MCU	STM32F103RBTx
Datasheet	13587_Rev17

### 7.2. Parameter Selection

Temperature	25
Vdd	3.3

## 8. Software Project

### 8.1. Project Settings

Name	Value
Project Name	Robot3_F103RB_origin
Project Folder	C:\EMSE\2A\Projet robot\Rover_5_F103RB_Origin\Rover_5_F103RB_Origin
Toolchain / IDE	TrueSTUDIO
Firmware Package Name and Version	STM32Cube FW_F1 V1.6.1

### 8.2. Code Generation Settings

Name	Value
STM32Cube Firmware Library Package	Copy all used libraries into the project folder
Generate peripheral initialization as a pair of '.c/.h' files	Yes
Backup previously generated files when re-generating	Yes
Delete previously generated files when not re-generated	Yes
Set all free pins as analog (to optimize the power consumption)	Yes

## ***9. Software Pack Report***