

# 16:960:665 - Syllabus

Pranav Tikkawar

December 9, 2025

## Contents

<b>1 Notes</b>	<b>2</b>
1.1 9/2/2025 Lecture 1 . . . . .	2
1.2 9/9/2025 Lecture 2 . . . . .	4
1.3 9/11/2025 Lecture 3 . . . . .	6
1.4 9/16/2025 Lecture 4 . . . . .	8
1.5 9/18/2025 Lecture 5 . . . . .	11
1.6 9/23/2025 Lecture 6 . . . . .	13
1.7 9/25/2025 Lecture 7 . . . . .	15
1.8 9/30/2025 Lecture 8 . . . . .	17
1.9 10/2/2025 Lecture 9 . . . . .	19
1.10 10/7/2025 Lecture 10 . . . . .	21
1.11 10/9/2025 Lecture 11 . . . . .	24
1.12 10/14/2025 Lecture 12 . . . . .	25
1.13 10/16/2025 Lecture 13 . . . . .	27
1.14 10/21/2025 Lecture 14 . . . . .	29
1.15 10/23/2025 Lecture 15 . . . . .	31
1.16 10/28/2025 Lecture 16 . . . . .	33
1.17 10/30/2025 Lecture 17 . . . . .	35
1.18 11/04/2025 Lecture 18 . . . . .	37
1.19 11/06/2025 Lecture 19 . . . . .	39
1.20 11/11/2025 Lecture 20 . . . . .	41
1.21 11/13/2025 Lecture 21 . . . . .	43
1.22 11/18/2025 Lecture 22 . . . . .	45
1.23 11/20/2025 Lecture 23 . . . . .	47
1.24 11/25/2025 Lecture 24 . . . . .	49
1.25 12/02/2025 Lecture 25 . . . . .	51
1.26 12/04/2025 Lecture 26 . . . . .	52
1.27 12/09/2025 Lecture 27 . . . . .	53

# Syllabus

Time Series: Theory and Methods. Brockwell and Davis  
Asymtotic Theory of Weakly dependent Random Process  
Martingale Limit Theory

Durret - Probability Theory and Examples

## Acronyms

R.V. - Random Variable

S.P. - Stochastic Process

fn - Function

dist - Distribution

G.P. - Gaussian Process

iid - independent and identically distributed

a.s. - Almost Surely

w.p 1 - with probability 1

## 1 Notes

### 1.1 9/2/2025 Lecture 1

We use Stochastic Process to model time series data

**Definition** (Stochastic Process). A stochastic process is a family of random variables  $\{X_t : t \in \mathcal{T}\}$  defined on a common probability space  $(\Omega, \mathcal{F}, \mathbb{P})$ .

$\mathcal{T} = \mathbb{N}, \mathbb{Z}$  Discrete Time

$\mathcal{T} = \mathbb{R}$  Continuous Time (not focusing on this)

$\mathcal{T} \subseteq \mathbb{R}^n$  Geospatial, with location and time, (not focusing on this)

$\mathcal{T} \subseteq \mathbb{S}^3$  Unit Sphere w/Geophysics.

**Definition** (Realization of a S.P.). The functions  $\{X(\omega), \omega \in \Omega\}(\mathcal{T} \rightarrow \mathbb{R})$  are realizations or sample passes of the process.

- Fix  $t$ ,  $X_t$  is a fn of  $\Omega$
- Fix an outcome  $\omega \in \Omega$ ,  $X(\omega)$  is a fn on  $\mathcal{T}$
- The time series we observe is a realization of the S.P.
- Conventionally the observed time series is indexed by  $\{1, 2, \dots, n\}$  ie  $\{X_1, X_2, \dots, X_n\}$  (known as the lens/sample size)

**Example** (1.2.1 from book). Suppose  $A \geq 0$  is a R.V and given by  $\Theta \sim Uniform(0, 2\pi)$ . and they are independent. and  $v > 0$  is a known constant

Then  $X_t = A \cos(vt + \Theta), t \in \mathbb{Z}$

For every  $\omega \in \Omega$ ,  $A(\omega), \Theta(\omega)$  are fixed

$$X_t(\omega) = A(\omega) \cos(vt + \Theta(\omega))$$

$A$  determines the amplitude and  $\Theta$  determines the phase.

What we do is we take a model, and have the data as a realization, and solve the inverse problem of determining the parameters of the model.

**Example** (1.2.2 from the book). Consider  $X_1, X_2, X_3, \dots$  are IID and take value  $1, -1$  with probability  $1/2$

I'm considering to use some binomial theorem thing...

**Example** (1.2.3 from the book). Suppose  $X_t$  coming from prior question.

$S_t = \sum_{i=1}^t X_i = X_1 + X_2 + \dots + X_t$   $S_t : t \in \mathbb{N}$  is a S.P. called a simple symmetric random walk

Consider a man in 1D who starts at 0, and takes a random draw to walk left or right. The path of this miserable guys is  $S_t$

The realization is a plot of  $S_t(\omega)$  against  $t$ .

**Definition** (The Distribution of a Stochastic Process). Let  $\mathcal{I}$  be the collection of all tuples  $\{\mathbf{t} = (t_1, t_2, \dots, t_n)' \in \mathcal{T}, t_1 < t_2 < \dots < t_n\}$  The finite dimensional dist. fns of  $\{X_t, t \in \mathcal{T}\}$  are the collection of fns  $\{F_t(\cdot) : \mathbf{t} \in \mathcal{I}\}$  where

$$F_{\mathbf{t}}(\mathbf{x}) = P(X_{t_1} = x_1, X_{t_2} = x_2, \dots, X_{t_n} = x_n)$$

$$\mathbf{x} = (x_1, x_2, \dots, x_n)' \in \mathbb{R}^n$$

ie  $F_{\mathbf{t}}(\mathbf{x})$  is the joint distribution of the process of the R.V.  $\mathbf{x}$ .

**Theorem 1** (Kolmogorov (consistency) Theorem). *The prob. distribution fns  $\{F_{\mathbf{t}}(\cdot) : \mathbf{t} \in \mathcal{I}\}$  are the distribution functions of some S.P.  $\iff$  for any  $n \in \mathbb{N}$ ,  $\mathbf{t} = (t_1, t_2, \dots, t_n)' \in \mathcal{T}$  and  $1 \leq i \leq n$*

$$\lim_{x_i \rightarrow \infty} F_{\mathbf{t}}(\mathbf{x}) = F_{\mathbf{t}_i}(\mathbf{x}_i)$$

Where  $\mathbf{x} = (x_1, x_2, \dots, x_n)'$ ,

$\mathbf{t}_i = (t_1, t_2, \dots, t_{i-1}, t_{i+1}, \dots, t_n)'$  and  $\mathbf{x}_i = (x_1, x_2, \dots, x_{i-1}, x_{i+1}, \dots, x_n)'$   
essentially the  $i$  are the missing ones

$$\begin{aligned} F(x_1, x_2) &= \mathbb{P}(X_1 \leq x_1, X_2 \leq x_2) \\ \lim_{x_2 \rightarrow \infty} F(x_1, x_2) &= \mathbb{P}(X_1 \leq x_1) \end{aligned}$$

"[https://en.wikipedia.org/wiki/Kolmogorov\\_extension\\_theorem](https://en.wikipedia.org/wiki/Kolmogorov_extension_theorem)"

We essentially only need to specify the consistency of the finite dimensional distributions to define a S.P.

## 1.2 9/9/2025 Lecture 2

**Definition** (Autocovariance function). If  $X_t, t \in \mathcal{T}$  is a S.P. s.t  $E(X_t^2) < \infty$ , then for every  $t \in \mathcal{T}$  the autocovariance function is defined as

$$\gamma_x(r, s) = Cov(X_r, X_s), r, s \in \mathcal{T}$$

**Definition** (Autocorrelation function). If  $X_t, t \in \mathcal{T}$  is a S.P. s.t  $E(X_t^2) < \infty$ , then for every  $t \in \mathcal{T}$  the autocorrelation function is defined as

$$\rho_x(r, s) = Corr(X_r, X_s) = \frac{\gamma_x(r, s)}{\sqrt{\gamma_x(r, r)\gamma_x(s, s)}}, r, s \in \mathcal{T}$$

**Definition** (Stationary S.P.). A stochastic process  $X_t, t \in \mathcal{T}$  is said to be stationary

- $E(X_t^2) < \infty$  for all  $t \in \mathcal{T}$
- $E(X_t) = \mu$  for all  $t \in \mathcal{T}$
- $\gamma_x(r, s) = \gamma_x(r + h, s + h)$  for all  $r, s, h \in \mathcal{T}$

Weakly Stationary/Covariance Stationary/Wide Sense Stationary/Second Order Stationary

**ASK: If our  $\mathcal{T}$  is a non convex set, does this still hold?**

Also if  $X_t$  is stationary, then  $\gamma_x(r, s) = \gamma_x(0, s - r) = \gamma_x(s - r)$  ie we can define the autocovariance as a fn of the one variable: the lag  $h = s - r$

Similarly  $\rho_x(h) = \frac{\gamma_x(h)}{\gamma_x(0)}$

**Definition** (Strict Stationarity). A stochastic process  $X_t, t \in \mathcal{T}$  is said to be strictly stationary if for every  $n \in \mathbb{N}$ ,  $t_1, t_2, \dots, t_n \in \mathcal{T}$  and  $h \in \mathcal{T}$  the random vectors  $(X_{t_1}, X_{t_2}, \dots, X_{t_n})'$  and  $(X_{t_1+h}, X_{t_2+h}, \dots, X_{t_n+h})'$  have the same distribution.

ie the finite dimensional distributions are shift invariant.

If Strict Stationarity with finite second moments  $\Rightarrow$  Weak Stationarity.

**Definition** (Gaussian Time Series (S.P.)). A Gaussian S.P. is a S.P.  $X_t, t \in \mathcal{T}$  if all the finite dimensional distributions fns of  $\{X_t\}$  are multivariate normal.

ie for every  $n \in \mathbb{N}$  and  $t_1, t_2, \dots, t_n \in \mathcal{T}$  the random vector  $(X_{t_1}, X_{t_2}, \dots, X_{t_n})'$  has a multivariate normal distribution. - IF a G.P. is stationary, then it is strictly stationary.

**Definition** (Stationarity of IID). IID variables are strictly stationary.

**Definition** (White Noise). A S.P.  $X_t$  is said to be white noise if can also be written as  $WN(0, \sigma^2)$

- $E(X_t) = 0$  for all  $t$
- $Var(X_t) = \sigma^2 < \infty$  for all  $t$
- $Cov(X_t, X_s) = 0$  for all  $t \neq s$

It is a weakly stationary S.P.

**Example** (Example of White Noise not Strictly Stationary). Let  $X_t$  with  $t = \text{even}$  be  $N(0, 1)$  and  $X_t$  with  $t = \text{odd}$  be  $\text{Rademacher}(0, 1)$ . Then  $X_t$  is white noise but not strictly stationary.

**Example** (1.3.1).  $X_t = A \cos(\Theta t) + B \sin(\Theta t)$  where  $E(A) = E(B) = 0$ ,  $\text{Var}(A) = \text{Var}(B) = 1$ ,  $\text{Cov}(A, B) = 0$

- $E(X_t) = 0$
- $\text{Var}(X_t) = E(A^2 \cos^2(\Theta t) + B^2 \sin^2(\Theta t)) = \cos^2(\Theta t) + \sin^2(\Theta t) = 1$
- $\text{Cov}(X_t, X_s) = E(X_t X_s) = E[(A \cos(\Theta t) + B \sin(\Theta t))(A \cos(\Theta s) + B \sin(\Theta s))] = E[A^2] \cos(\Theta t) \cos(\Theta s) + E[B^2] \sin(\Theta t) \sin(\Theta s) = \cos(\Theta t) \cos(\Theta s) + \sin(\Theta t) \sin(\Theta s) = \cos(\Theta(t - s))$

Note that the  $\text{Cov}(X_t, X_s)$  is only a fn of  $t - s$   
Thus  $X_t$  is weakly stationary.

**Example** (1.3.2). Let  $Z_t, t \in \mathbb{Z}$  be IID( $0, \sigma^2$ )

$$X_t = Z_t + \Theta Z_{t-1}$$

- $E(X_t) = 0$
- $\text{Var}(X_t) = \text{Var}(Z_t) + \Theta^2 \text{Var}(Z_{t-1}) = (1 + \Theta^2)\sigma^2$
- $\text{Cov}(X_t, X_s) = E(X_t X_s) = E[(Z_t + \Theta Z_{t-1})(Z_s + \Theta Z_{s-1})] = \Theta\sigma^2 \text{ if } |t - s| = 1, (1 + \Theta^2)\sigma^2 \text{ if } t = s, 0 \text{ otherwise}$

Thus  $X_t$  is weakly stationary.

**Example** (1.3.4). Assume  $X_t$  is IID( $0, \sigma^2$ )

$$S_t = X_1 + X_2 + \dots + X_t \quad t \geq 1$$

- $E(S_t) = 0$
- $\text{Var}(S_t) = t\sigma^2$  Not constant
- $\text{Cov}(S_r, S_t) = E(S_r S_t) = r\sigma^2$  WLOG  $r \leq t$
- $\text{Cov}(S_r, S_t) = (r \wedge t)\sigma^2$

**Proposition 1** (1.5.1). Suppose  $X_t$  is weakly stationary with  $\gamma_x(h), \rho_x(h)$  as the autocovariance and autocorrelation fns. Then

- $\gamma_x(0) \geq 0$
- $|\gamma_x(h)| \leq \gamma_x(0)$  for all  $h \in \mathcal{T}$

- $\gamma_x(h) = \gamma_x(-h)$  for all  $h \in \mathcal{T}$

**Remark** (Some Statistics...). Observe  $\{X_t\}, t = 1, 2, \dots, n$  Want to estimate  $\mu, \gamma(0), \gamma(1), \dots, \gamma(n-1)$

$$\begin{aligned}\hat{\mu} &= \frac{1}{n} \sum_{i=1}^n X_i := \bar{X} \\ \hat{\gamma}(0) &= \frac{1}{n} \sum_{i=1}^n (X_i - \bar{X})^2 \\ \hat{\gamma}(1) &= \frac{1}{n} \sum_{i=1}^{n-1} (X_i - \bar{X})(X_{i+1} - \bar{X}) \\ \hat{\gamma}(h) &= \frac{1}{n} \sum_{i=1}^{n-h} (X_i - \bar{X})(X_{i+h} - \bar{X})\end{aligned}$$

The reason why we divide by  $n$  we want to shrink it. intuition is that we want to make autocorrelation smaller as  $n$  increases.

### 1.3 9/11/2025 Lecture 3

**Remark** (Matrix Form of Autocovariance). Observe  $X_1, X_2, \dots, X_n$   
 $\hat{\gamma}(h) = \frac{1}{n} \sum_{i=1}^{n-h} (X_i - \bar{X})(X_{i+h} - \bar{X})$ .

$$\Gamma_n = \text{Cov} \begin{bmatrix} X_1 \\ X_2 \\ \vdots \\ X_n \end{bmatrix} = \begin{bmatrix} \gamma_x(0) & \gamma_x(1) & \gamma_x(2) & \dots & \gamma_x(n-1) \\ \gamma_x(1) & \gamma_x(0) & \gamma_x(1) & \dots & \gamma_x(n-2) \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \gamma_x(n-1) & \gamma_x(n-2) & \gamma_x(n-3) & \dots & \gamma_x(0) \end{bmatrix}$$

This is a Toeplitz matrix. ie constant along the diagonals. It is also positive semidefinite. ie  $a' \Gamma_n a \geq 0$  for all  $a \in \mathbb{R}^n$ .

For the Sample version, we have

$$\hat{\Gamma}_n = \begin{bmatrix} \hat{\gamma}(0) & \hat{\gamma}(1) & \hat{\gamma}(2) & \dots & \hat{\gamma}(n-1) \\ \hat{\gamma}(1) & \hat{\gamma}(0) & \hat{\gamma}(1) & \dots & \hat{\gamma}(n-2) \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \hat{\gamma}(n-1) & \hat{\gamma}(n-2) & \hat{\gamma}(n-3) & \dots & \hat{\gamma}(0) \end{bmatrix}$$

We use  $n$  as a common denominator to ensure that  $\hat{\Gamma}_n$  is positive semidefinite.

$\Gamma_n$  is called the order- $n$  autocovariance matrix of the process.

$\hat{\Gamma}_n$  is called the order- $n$  sample autocovariance

**Theorem 2.** A real valued fn defined on the integers is the autocovariance fn of a weakly stationary Time Series iff

- It is even. ie  $\gamma(h) = \gamma(-h)$  for all  $h \in \mathcal{T}$
- It is non-negative definite. ie for every  $n \in \mathbb{N}$  and  $a_1, a_2, \dots, a_n \in \mathbb{R}$

$I\mathbb{E} \sum_{i,j}^n a_i k(t_i - t_j) a_j \geq 0$  for all  $n \geq 1$ ,  $\mathbf{t} = (t_1, t_2, \dots, t_n)' \in \mathbb{N}^n$ , and  $\mathbf{a} = (a_1, a_2, \dots, a_n)' \in \mathbb{R}^n$

*Proof.* **LOOK MORE INTO THIS THEOREM**

$\implies$

It is straightforward to see that  $\gamma_x(h)$  is even.

Let  $n \in \mathbb{N}$ ,  $\mathbf{t} = (t_1, t_2, \dots, t_n)' \in \mathbb{N}^n$ , and  $\mathbf{a} = (a_1, a_2, \dots, a_n)' \in \mathbb{R}^n$

$$\sum_{i,j}^n a_i \gamma_x(t_i - t_j) a_j = \sum_{i,j}^n a_i \text{Cov}(X_{t_i}, X_{t_j}) a_j = \text{Cov}\left(\sum_{i=1}^n a_i X_{t_i}, \sum_{j=1}^n a_j X_{t_j}\right) = \text{Var}\left(\sum_{i=1}^n a_i X_{t_i}\right) \geq 0$$

$\Leftarrow$

Let  $k(h)$  be a real valued fn defined on the integers which is even and non-negative definite.

Let  $n \in \mathbb{N}$ ,  $\mathbf{t} = (t_1, t_2, \dots, t_n)' \in \mathbb{N}^n$ , and  $\mathbf{a} = (a_1, a_2, \dots, a_n)' \in \mathbb{R}^n$

Define  $\Gamma_n = [k(t_i - t_j)]_{i,j=1}^n$

Then  $\Gamma_n$  is a non-negative definite matrix. ie  $a' \Gamma_n a \geq 0$  for all  $a \in \mathbb{R}^n$ .

Thus by the spectral theorem, there exists a random vector  $\mathbf{X} = (X_{t_1}, X_{t_2}, \dots, X_{t_n})'$  with mean 0 and covariance matrix  $\Gamma_n$ . ie  $E(\mathbf{X}) = 0$  and  $\text{Cov}(\mathbf{X}) = \Gamma_n$ .

ie  $\text{Cov}(X_{t_i}, X_{t_j}) = k(t_i - t_j)$  for all  $1 \leq i, j \leq n$

By Kolmogorov's theorem, there exists a S.P.  $X_t, t \in \mathbb{Z}$  with autocovariance fn  $k(h)$ .

□

**Example.** Suppose  $k(h) = \begin{cases} 1 & h = 0 \\ \rho & h = \pm 1 \\ 0 & otherwise \end{cases}$

When is  $k$  an autocovariance fn of a weakly stationary S.P.?

- $|\rho| \leq .5$  then

Remember  $Z_t$  is IID( $0, \sigma^2$ ),  $X_t = Z_t + \Theta Z_{t-1}$  with acovf  $\gamma_x(h) = \begin{cases} (1 + \Theta^2)\sigma^2 & h = 0 \\ \Theta\sigma^2 & h = \pm 1 \\ 0 & otherwise \end{cases}$

$\rho(1) = \frac{\Theta}{1+\Theta^2}$  then  $1 + \Theta^2 \leq 2\theta$  ie  $|\rho| \leq .5$

- If  $.5 < \rho \leq 1$  then  $k(h)$  is not an acovf.

Then you can find a  $n$  s.t.

$$\sum_{i,j}^{2n} a_i a_j k(i - j) = 2n - 2(n - 1)\rho < 0$$

**Where does this formula on the RHS come from?**

- If  $-1 \leq \rho < -.5$  then  $k(h)$  is not an acovf.

**Definition** (Mixing Conditions). Suppose  $\mathcal{G}$  and  $\mathcal{H}$  are two sub  $\sigma$ -fields on the same probability space  $(\Omega, \mathcal{F}, \mathbb{P})$ .  $\mathcal{G} \subset \mathcal{F}$  and  $\mathcal{H} \subset \mathcal{F}$ .

**Definition** ( $\alpha$ -mixing:).  $\alpha$ -mixing:  $\alpha(\mathcal{G}, \mathcal{H}) = \sup_{G \in \mathcal{G}, H \in \mathcal{H}} |\mathbb{P}(G \cap H) - \mathbb{P}(G)\mathbb{P}(H)|$   
 $X_1$  and  $X_2$  are independent  $\mathcal{G} = \sigma(X_1) = \sigma([X_1 \leq c], c \in \mathbb{R})$  and  $\mathcal{H} = \sigma(X_2)$

- $\alpha(\mathcal{G}, \mathcal{H}) = 0$  iff  $\mathcal{G}$  and  $\mathcal{H}$  are independent
- $0 \leq \alpha(\mathcal{G}, \mathcal{H}) \leq .25$  for all  $\mathcal{G}, \mathcal{H}$  sub  $\sigma$ -fields of  $\mathcal{F}$
- $\mathbb{P}(G \cap H) - \mathbb{P}(G)\mathbb{P}(H) = \mathbb{E}[I_G I_H] - \mathbb{E}[I_G]\mathbb{E}[I_H] = Cov(I_G, I_H)$

$$|Cov(c_1 I_G, c_2 I_H)| \leq c_1 c_2 \alpha(\mathcal{G}, \mathcal{H})$$

**Definition** ( $\phi$ -mixing:).  $\phi$ -mixing:  $\phi(\mathcal{G}, \mathcal{H}) = \sup_{G \in \mathcal{G}, H \in \mathcal{H}, \mathbb{P}(G) > 0} |\mathbb{P}(H|G) - \mathbb{P}(H)|$

- $\phi(\mathcal{G}, \mathcal{H}) = 0$  iff  $\mathcal{G}$  and  $\mathcal{H}$  are independent
- $0 \leq \phi(\mathcal{G}, \mathcal{H}) \leq 1$  for all  $\mathcal{G}, \mathcal{H}$  sub  $\sigma$ -fields of  $\mathcal{F}$
- $\alpha(\mathcal{G}, \mathcal{H}) \leq \frac{1}{2}\phi(\mathcal{G}, \mathcal{H})$

**Example.**  $X$  is  $G$ -measureable and  $Y$  is  $H$ -measureable,  $|X| \leq C_1$  and  $|Y| \leq C_2$  a.s.  
Then  $|\text{Cov}(X, Y)| \leq 4C_1 C_2 \alpha(\mathcal{G}, \mathcal{H})$

## 1.4 9/16/2025 Lecture 4

**Remark** (Last Class Review). Mixing Conditions:

Suppose  $\mathcal{G}$  and  $\mathcal{H}$  are two sub  $\sigma$ -fields on the same probability space  $(\Omega, \mathcal{F}, \mathbb{P})$ .  $\mathcal{G} \subset \mathcal{F}$  and  $\mathcal{H} \subset \mathcal{F}$ . LOOK INTO TEXTBOOK ASSIGNMENTS

- $\alpha$ -mixing:  $\alpha(\mathcal{G}, \mathcal{H}) = \sup_{G \in \mathcal{G}, H \in \mathcal{H}} |\mathbb{P}(G \cap H) - \mathbb{P}(G)\mathbb{P}(H)|$
  - $\phi$ -mixing:  $\phi(\mathcal{G}, \mathcal{H}) = \sup_{G \in \mathcal{G}, H \in \mathcal{H}, \mathbb{P}(G) > 0} |\mathbb{P}(H|G) - \mathbb{P}(H)|$
1.  $\alpha(\mathcal{G}, \mathcal{H}) = 0 \iff \mathcal{G}$  and  $\mathcal{H}$  are independent
  2.  $0 \leq \alpha(\mathcal{G}, \mathcal{H}) \leq .25$  for all  $\mathcal{G}, \mathcal{H}$  sub  $\sigma$ -fields of  $\mathcal{F}$ ,  $0 \leq \phi(\mathcal{G}, \mathcal{H}) \leq 1$  for all  $\mathcal{G}, \mathcal{H}$  sub  $\sigma$ -fields of  $\mathcal{F}$
  3.  $\alpha(\mathcal{G}, \mathcal{H}) \leq \frac{1}{2}\phi(\mathcal{G}, \mathcal{H})$

Equal definition:  $\alpha(X, Y) = \sup_{c_1, c_2 \in \mathbb{R}} |\mathbb{P}(X \leq c_1, Y \leq c_2) - \mathbb{P}(X \leq c_1)\mathbb{P}(Y \leq c_2)|$   
Equal definition:  $\phi(X, Y) = \sup_{c_1, c_2 \in \mathbb{R}, \mathbb{P}(X \leq c_1) > 0} |\mathbb{P}(Y \leq c_2 | X \leq c_1) - \mathbb{P}(Y \leq c_2)|$

**Theorem 3** (Ibragimov 1962).  $\mathbb{P}(G \cap H) - \mathbb{P}(G)\mathbb{P}(H) = \text{Cov}(I_G, I_H)$

$$|\text{Cov}(c_1 I_G, c_2 I_H)| \leq c_1 c_2 \alpha(\mathcal{G}, \mathcal{H})$$

Sup.  $|X| \leq C_1$  and  $|Y| \leq C_2$  a.s.

Then  $|E(XY) - E(X)E(Y)| \leq 4c_1 c_2 \alpha(\mathcal{G}, \mathcal{H})$

*Proof.*

$$\begin{aligned} E(XY) - E(X)E(Y) &= E[X(Y - E(Y))] \\ &= E[X(E(Y|X) - E(Y))] \\ &= E[E(XY|X) - E(Y)] \\ |E(XY) - E(X)E(Y)| &= |E[X(E(Y|X) - E(Y))]| \\ &\leq c_1 E|E(Y|X) - E(Y)| \end{aligned}$$

Define  $\eta = \text{sign}(E(Y|X) - E(Y))$

$$\begin{aligned} &= c_1 E[\eta(E(Y|X) - E(Y))] \\ \eta E(Y|X) &= E(\eta Y|X) \\ c_1 E[E(\eta Y|X) - \eta E(Y)] &= c_1 [E(\eta Y) - E(\eta)E(Y)] \\ E(\eta Y) - E(\eta)E(Y) &\leq E[Y[E(\eta|Y) - E(\eta)]] \end{aligned}$$

Let  $\xi = \text{sign}(E(\eta|Y) - E(\eta))$

$$\begin{aligned} E(\eta Y) - E(\eta)E(Y) &\leq c_2 (E[\xi\eta] - E(\xi)E(\eta)) \\ E(XY) - E(X)E(Y) &\leq c_1 c_2 (E[\xi\eta] - E(\xi)E(\eta)) \\ \eta = I_{\eta=1} - I_{\eta=-1}, \xi &= I_{\xi=1} - I_{\xi=-1} \\ \text{Cov}(\xi, \eta) &= \text{Cov}(I_{\xi=1} - I_{\xi=-1}, I_{\eta=1} - I_{\eta=-1}) \\ &= \text{Cov}(I_{\xi=1}, I_{\eta=1}) + \text{Cov}(I_{\xi=-1}, I_{\eta=-1}) \\ &\quad - \text{Cov}(I_{\xi=1}, I_{\eta=-1}) - \text{Cov}(I_{\xi=-1}, I_{\eta=1}) \\ \implies |\text{Cov}(\xi, \eta)| &\leq 4\alpha(\mathcal{G}, \mathcal{H}) \\ |E(XY) - E(X)E(Y)| &\leq 4c_1 c_2 \alpha(\mathcal{G}, \mathcal{H}) \end{aligned}$$

□

Why are we doing this?

Consider  $X_1, X_2, \dots$  IID( $0, \sigma^2$ )

$$\frac{X_1 + X_2 + \dots + X_n}{n} \xrightarrow{d} N(0, \sigma^2)$$

Now how do we get CLT?

Consider  $X_1, X_2, \dots$  is a weakly stationary S.P, with  $E(X_t) = 0$

$$\frac{X_1 + X_2 + \dots + X_n}{n} \xrightarrow{d} N(0, \sigma^2)$$

We can see this is the variance  $S_n = X_1 + X_2 + \dots + X_n$

$$\text{Var}(S_n) = \sum_{i=1}^n \text{Var}(X_i) + 2 \sum_{1 \leq i < j \leq n} \text{Cov}(X_i, X_j)$$

$$= n\gamma_x(0) + 2 \sum_{1 \leq i < j \leq n} (\gamma_x(j-i))$$

$$= n\gamma_x(0) + 2 \sum_{h=1}^{n-1} (n-h)\gamma_x(h)$$

$$\text{Var}\left(\frac{S_n}{\sqrt{n}}\right) = \gamma_x(0) + 2 \sum_{h=1}^{n-1} \left(1 - \frac{h}{n}\right) \gamma_x(h)$$

$$\lim_{n \rightarrow \infty} \text{Var}\left(\frac{S_n}{\sqrt{n}}\right) = \gamma_x(0) + 2 \sum_{h=1}^{\infty} \gamma_x(h)$$

We want this infinite series to converge. ie  $\sum_{h=1}^{\infty} |\gamma_x(h)| < \infty$ .

Consider  $X_1, X_2, \dots$  is a strictly stationary S.P.

Define  $\alpha_0 = \frac{1}{2}$ , and  $\alpha_n = \alpha(X_0, X_n)$  for  $n \geq 1$

Assume  $E|X_0|^p < \infty$  for some  $p > 2$

Then  $|\gamma_x(k)| = |\text{Cov}(X_0, X_k)| \leq 8\|X_0\|_p^2 \alpha_k^{1-\frac{2}{p}}$

**Corollary** (Only  $Y$  is bounded). Suppose  $E[X^2] < \infty$  for some  $p > 1$  and  $|Y| \leq C$  a.s.

Then  $E(XY) - E(X)E(Y) \leq 6C\|X\|_p[\alpha(X, Y)]^{1-\frac{1}{p}}$  where  $\|X\|_p = (E|X|^p)^{\frac{1}{p}}$

*Proof.* Through Truncation:

$X_1 = XI_{|X| \leq C_1}$  and  $X_2 = X - X_1$

$$\begin{aligned} |E(XY) - E(X)E(Y)| &\leq |E(X_1Y) - E(X_1)E(Y)| + |E(X_2Y) - E(X_2)E(Y)| \\ &\leq 4CC_1\alpha(X, Y) + 2CE|X_2| \\ E|X_2| &= E|XI_{|X| > C_1}| \leq \frac{E|X|^p}{C_1^{p-1}} \\ I_{|X| > C_1} &< \frac{|X|^p}{C_1^{p-1}} \\ &= \frac{\|X\|_p^p}{C_1^{p-1}} \end{aligned}$$

Thus  $|E(XY) - E(X)E(Y)| \leq 4CC_1\alpha(X, Y) + \frac{\|X\|_p^p}{C_1^{p-1}}$ .

Take  $C_1 = \alpha^{-\frac{1}{p}}\|X\|_p$  to get best bound.

Then the corollary follows.

Look into bernstein inequality

□

**Corollary** (No bounded (Davydov 1968)). Suppose  $E|X|^p < \infty$  and  $E|Y|^q < \infty$  for some  $p, q > 1$  and  $\frac{1}{p} + \frac{1}{q} < 1$  then

$$|E(XY) - E(X)E(Y)| \leq 8\|X\|_p\|Y\|_q[\alpha(X, Y)]^{1-\frac{1}{p}-\frac{1}{q}}$$

## Review of Hilbert Spaces

**Definition** (Inner Product Space). A vector space  $\mathcal{V}$  over the field  $\mathbb{F}$  is called an inner product space if there exists a fn  $\langle \cdot, \cdot \rangle$

- $\langle u, v \rangle = \overline{\langle v, u \rangle}$  for all  $u, v \in \mathcal{V}$
- $\langle u + v, w \rangle = \langle u, w \rangle + \langle v, w \rangle$  for all  $u, v, w \in \mathcal{V}$
- $\langle cu, v \rangle = c\langle u, v \rangle$  for all  $u, v \in \mathcal{V}$  and  $c \in \mathbb{F}$

- $\langle u, u \rangle \geq 0$  for all  $u \in \mathcal{V}$
- $\langle u, u \rangle = 0$  iff  $u = 0$

We will see that for the prob space  $\langle X, Y \rangle = E[XY]$  but this only holds a.s.

## 1.5 9/18/2025 Lecture 5

**Definition** (Inner Product Space).  $\mathcal{H}$  is an inner product space with inner product  $\langle \cdot, \cdot \rangle$

**Example** (2.2.2).  $L^2(\Omega, \mathcal{F}, \mathbb{P}) = \{X : \Omega \rightarrow \mathbb{R} | X \text{ is measurable and } E(X^2) < \infty\}$

$$\langle X, Y \rangle = E(XY) = \int_{\Omega} X(\omega)Y(\omega)d\mathbb{P}(\omega)$$

$$\langle X, X \rangle = E(X^2) = 0 \implies X = 0 \text{ a.s.}$$

Define an equivalence relation  $X \sim Y$  if  $X = Y$  a.s.

- The elements of  $L^2$  are equivalence classes
- $\|X\| = \sqrt{\langle X, X \rangle} = \sqrt{E(X^2)}$  is a norm on  $L^2$

**Remark.** IP Properties:

- $|\langle x, y \rangle| \leq \|x\| \|y\|$  (Cauchy-Schwarz Inequality)
- $\|x + y\| \leq \|x\| + \|y\|$  (Triangle Inequality)
- If  $\|x_n - x\| \rightarrow 0$  and  $\|y_n - y\| \rightarrow 0$  then  $\langle x_n, y_n \rangle \rightarrow \langle x, y \rangle$  (Continuity of Inner Product)

**Definition** (Limit of a Sequence in Hilbert Space). Let  $\mathcal{H}$  be a Hilbert Space and  $\{x_n\}$  be a sequence in  $\mathcal{H}$

We say that  $x_n \rightarrow x$  if  $\|x_n - x\| \rightarrow 0$  as  $n \rightarrow \infty$ .

Suppose  $\{X_n\}$  is a sequence of random variables in  $L^2(\Omega, \mathcal{F}, \mathbb{P})$  which converges to  $X$ . Then consider the RV 1 (constant)

Consider  $\langle X_n, 1 \rangle \rightarrow \langle X, 1 \rangle$

ie  $E(X_n) \rightarrow E(X)$

$$\begin{aligned} X_n &\rightarrow X \\ \langle X_n, X_n \rangle &\rightarrow \langle X, X \rangle \text{ ie } E(X_n^2) \rightarrow E(X^2) \end{aligned}$$

$$X_n \rightarrow X, Y_n \rightarrow Y$$

$$\langle X_n, Y_n \rangle \rightarrow \langle X, Y \rangle$$

$$\text{ie } E(X_n Y_n) \rightarrow E(XY)$$

**Definition** (Cauchy Sequence). A sequence of elements  $\{x_n\}$  in an inner product space  $\mathcal{H}$  is called a Cauchy sequence if for every  $\epsilon > 0$  there exists  $N \in \mathbb{N}$  such that  $\|x_n - x_m\| < \epsilon$  for all  $n, m \geq N$ .

**Definition** (Hilbert Space). An inner product space  $\mathcal{H}$  is called a Hilbert Space if every Cauchy sequence in  $\mathcal{H}$  converges to an element in  $\mathcal{H}$ .

**Example.** Consider  $\mathcal{M}(\Omega, \mathcal{F}, \mathbb{P}) = \{X : |X| \leq C, C > 0\}$

$$\langle X, Y \rangle = E(XY)$$

$$X \sim N(0, 1)$$

$$X_n = XI_{|X| \leq n}$$

$$E|X - X_n|^2 = E[X^2 I_{|X| > n}] \rightarrow 0 \text{ by DCT (Dominated Convergence Theorem)}$$

So  $X_n \rightarrow X$  in  $L^2$  but  $X \notin \mathcal{M}$

Thus  $\mathcal{M}$  is not a Hilbert Space.

**Definition** (Complex Random Variable). A complex random variable is a fn  $Z : \Omega \rightarrow \mathbb{C}$  such that  $Z = X + iY$  where  $X, Y$  are real random variables.

**Definition** (Closed Subspace). A linear subspace of a Hilbert Space  $\mathcal{H}$  is called a closed subspace if  $\mathcal{M}$  contains its limit points. ie if  $\{x_n\} \subset \mathcal{M}$  and  $x_n \rightarrow x$  in  $\mathcal{H}$  then  $x \in \mathcal{M}$ .

**Proposition 2** (2.3.1). Review the definition If  $\mathcal{M}$  is a closed subset of a H.S  $\mathcal{H}$  then the orthogonal compliment  $\mathcal{M}^\perp = \{x \in \mathcal{H} : x \perp y, \forall y \in \mathcal{M}\}$  closed linear subspace of  $\mathcal{H}$ .

**Theorem 4** (2.3.1 Projection Theorem). If  $\mathcal{M}$  is a closed linear subspace of a H.S  $\mathcal{H}$  and  $x \in \mathcal{H}$  then

- (i) there is a unique element  $\hat{x} \in \mathcal{M}$  such that  $\|x - \hat{x}\| = \inf_{y \in \mathcal{M}} \|x - y\|$
- (ii)  $\hat{x} \in \mathcal{M}$  and  $\|x - \hat{x}\| = \inf_{y \in \mathcal{M}} \|x - y\|$  iff  $\hat{x} \in \mathcal{M}$  and  $x - \hat{x} \in \mathcal{M}^\perp$

**Definition** (2.4.1 Closed Span). The closed span  $\overline{\text{sp}}\{X_t, t \in \mathcal{T}\}$  of any subset  $\{X_t, t \in \mathcal{T}\}$  of a H.S  $\mathcal{H}$  is the smallest closed linear subspace of  $\mathcal{H}$  containing  $\{X_t, t \in \mathcal{T}\}$ .

**Definition** (Orthonormal Set). A set  $\{e_t : t \in \mathcal{T}\}$  of element of an IP space is said to be

$$\text{orthonormal if } \langle e_s, e_t \rangle = \begin{cases} 1 & s = t \\ 0 & s \neq t \end{cases} \text{ for all } s, t \in \mathcal{T}$$

**Definition** (Complete Orthonormal Set). An orthonormal set  $\{e_t : t \in \mathcal{T}\}$  in a H.S  $\mathcal{H}$  is said to be complete if  $\overline{\text{sp}}\{e_t, t \in \mathcal{T}\} = \mathcal{H}$

**Definition** (Seperability). The HS is separable if it has a finite or countable infinite complete orthonormal set.

**Example** (Separable HS). 1.  $\mathbb{R}^d$

2.  $L^2(\Omega, \mathcal{F}, \mathbb{P})$

**Theorem 5** (2.4.2). If  $\mathcal{H}$  is a separable H.S and  $\mathcal{H} = \overline{\text{sp}}\{e_t : t \in \mathcal{T}\}$  where  $\{e_t : t \in \mathcal{T}\}$  is an orthonormal set then

- The set of all finite linear combinations of  $\{e_t : t \in \mathcal{T}\}$  is dense in  $\mathcal{H}$ . ie for every  $x \in \mathcal{H}$  and  $\epsilon > 0$  there exists  $y = \sum_{j=1}^n a_j e_{t_j}$  such that  $\|x - y\| < \epsilon$

- $x = \sum_{i=1}^{\infty} \langle x, e_i \rangle e_i$  for each  $x \in \mathcal{H}$  ie  $\|x - \sum_{i=1}^n \langle x, e_i \rangle e_i\| \rightarrow 0$  as  $n \rightarrow \infty$
- $\|x\|^2 = \sum_{i=1}^{\infty} |\langle x, e_i \rangle|^2$  for each  $x \in \mathcal{H}$  (Parseval's Identity)
- $\langle x, y \rangle = \sum_{i=1}^{\infty} \langle x, e_i \rangle \langle y, e_i \rangle$  for all  $x, y \in \mathcal{H}$
- $x = 0 \iff \langle x, e_i \rangle = 0$  for all  $i \geq 1$

## 1.6 9/23/2025 Lecture 6

**Definition** (ARMA models: ARMA( $p, q$ )). Let  $\{Z_t\} \sim WN(0, \sigma^2)$ . The process  $\{X_t, t \in \mathbb{Z}\}$  is said to be an *ARMA*( $p, q$ ) process if

- $\{X_t\}$  is stationary for all  $t \in \mathbb{Z}$
- $X_t - \phi_1 X_{t-1} - \dots - \phi_p X_{t-p} = Z_t + \theta_1 Z_{t-1} + \dots + \theta_q Z_{t-q}$  for all  $t \in \mathbb{Z}$  where  $\phi_1, \dots, \phi_p, \theta_1, \dots, \theta_q$  are real constants with  $\phi_p, \theta_q \neq 0$ .

**Remark.** There are a few special cases of the *ARMA*( $p, q$ ) model:

- When  $q = 0$  we can write the model as  $X_t - \phi_1 X_{t-1} - \dots - \phi_p X_{t-p} = Z_t$  and call it an *AR*( $p$ ) model.
- When  $p = 0$  we can write the model as  $X_t = Z_t + \theta_1 Z_{t-1} + \dots + \theta_q Z_{t-q}$  and call it a *MA*( $q$ ) model.
- When  $p = 0$  and  $q = 0$  we have  $X_t = Z_t$  and call it a white noise model.
- $\{X_t\}$  is defined relative to the white noise process  $\{Z_t\}$ .
- Stationarity is a critical requirement for the *ARMA*( $p, q$ ) model.
- AR polynomial:  $\phi(z) = 1 - \phi_1 z - \dots - \phi_p z^p$
- MA polynomial:  $\theta(z) = 1 + \theta_1 z + \dots + \theta_q z^q$
- Backshift operator:  $BX_t = X_{t-1}, B^2X_t = X_{t-2}, \dots, B^kX_t = X_{t-k}$
- AR( $p$ ) model:  $\phi(B)X_t = Z_t$
- MA( $q$ ) model:  $X_t = \theta(B)Z_t$
- ARMA( $p, q$ ) model:  $\phi(B)X_t = \theta(B)Z_t$
- More general model with a mean:  $\{X_t + \mu : t \in \mathbb{Z}\}$
- Can also be characterized by  $X_t = \phi_0 + \phi_1 X_{t-1} + \dots + \phi_p X_{t-p} + Z_t + \theta_1 Z_{t-1} + \dots + \theta_q Z_{t-q}$  where  $\phi_0 = \mu(1 - \phi_1 - \dots - \phi_p)$

**Example** (Staitionary solution to AR(1)).

$$\begin{aligned}
X_t &= \phi X_{t-1} + Z_t \\
&= Z_t + \phi(Z_{t-1} + \phi X_{t-2}) = Z_t + \phi Z_{t-1} + \phi^2 X_{t-2} \\
&= Z_t + \phi Z_{t-1} + \phi^2(Z_{t-2} + \phi X_{t-3}) = Z_t + \phi Z_{t-1} + \phi^2 Z_{t-2} + \phi^3 X_{t-3} \\
&\vdots \\
&= Z_t + \phi Z_{t-1} + \phi^2 Z_{t-2} + \dots + \phi^k Z_{t-k} + \phi^{k+1} X_{t-(k+1)}
\end{aligned}$$

If  $|\phi| < 1$  then  $\phi^{k+1} X_{t-(k+1)} \rightarrow 0$  as  $k \rightarrow \infty$

Thus the stationary solution is  $X_t = \sum_{j=0}^{\infty} \phi^j Z_{t-j}$

If  $|\phi| \geq 1$  then there is no stationary solution since we can see that  $X_{t+1} = \phi X_t + Z_{t+1} \iff X_t = -\frac{1}{\phi} Z_{t+1} + \frac{1}{\phi} X_{t+1}$

$$\begin{aligned}
X_t &= \phi^{-1} X_{t+1} - \phi^{-1} Z_{t+1} \\
&= \phi^{-1}(\phi^{-1} X_{t+2} - \phi^{-1} Z_{t+2}) - \phi^{-1} Z_{t+1} \\
&= \phi^{-2} X_{t+2} - \phi^{-1} Z_{t+1} - \phi^{-2} Z_{t+2} \\
&\vdots \\
&= \phi^{-k} X_{t+k} - \sum_{j=1}^k \phi^{-j} Z_{t+j} \\
&= - \sum_{j=1}^{\infty} \phi^{-j} Z_{t+j}
\end{aligned}$$

We will see later that why this is the unique stationary solution when  $|\phi| < 1$

**Remark.** Uniqueness of stationary solution to AR(1):

- If  $X_t = \phi X_{t-1} + Z_t$ , where  $|\phi| > 1$  then we can rewrite this as  $X_t = \phi^* X_{t-1} + Z_t^*$  with  $\phi^* < 1$  and  $Z_t^* \sim WN(0, \sigma^2)$  [Homework problem]

**Definition** (3.1.3: Causality). An ARMA( $p, q$ ) process  $\phi(B)X_t = \theta(B)Z_t$  is said to be causal if ther exists a sequence of constants  $\{\psi_j\}$  such that  $\sum_{j=0}^{\infty} |\psi_j| < \infty$  and  $X_t = \sum_{j=0}^{\infty} \psi_j Z_{t-j}$  for all  $t \in \mathbb{Z}$ .

**Proposition 3** (3.1.1). *If  $\{X_t, t \in \mathbb{Z}\}$  is a sequence of rv st.  $\sup_t E|X_t| < \infty$  and if  $\{\psi_j\}_{j \geq 0}$  is a sequence of numbers s.t  $\sum_{j=0}^{\infty} |\psi_j| < \infty$  then the series  $\psi(B)X_t = \left(\sum_{j=0}^{\infty} \psi_j B^j\right) X_t = \sum_{j=0}^{\infty} \psi_j X_{t-j}$  converges absolutely w.p 1*

*If in addition  $\sup_t E(X_t^2) < \infty$  then the series converges in  $L^2$  to the same limit.*

*Proof.* • Consider  $\sum_{j=0}^{\infty} |\psi_j| |X_{t-j}|$ , which always exists (may be infinite)

- Monotone Convergence Theorem implies  $E\left(\sum_{j=0}^{\infty} |\psi_j| |X_{t-j}|\right) = \sum_{j=0}^{\infty} |\psi_j| E|X_{t-j}| \leq (\sup_t E|X_t|) \sum_{j=0}^{\infty} |\psi_j| < \infty \implies \sum_{j=0}^{\infty} |\psi_j| |X_{t-j}| < \infty$  w.p 1
- $\implies \sum_{j=0}^{\infty} \psi_j X_{t-j}$  converges absolutely w.p 1, call the limit  $W_t$ .
- Verify  $\sum_{j=0}^n \psi_j X_{t-j}$  is a Cauchy sequence in  $L^2$ : We do this by showing  $\|\sum_{j=n}^m \psi_j X_{t-j}\|_2 \rightarrow 0$  as  $n, m \rightarrow \infty$ .
- So it converges in  $L^2$  to some limit  $S_t$ .
- $E(S_t - W_t)^2 = E[\liminf_n (S - \sum_{j=0}^n \psi_j X_{t-j})^2]$  by Fatou's Lemma  
 $\leq \liminf_n E(S - \sum_{j=0}^n \psi_j X_{t-j})^2 = 0$   
 $\implies S_t = W_t$  a.s. since the second moment is 0.

□

## 1.7 9/25/2025 Lecture 7

**Remark** (Review). Review of last week:

- ARMA( $p, q$ ) process:  $\phi(B)X_t = \theta(B)Z_t$  where  $\{Z_t\} \sim WN(0, \sigma^2)$
- MA( $q$ ) process:  $X_t = \theta(B)Z_t$

**Proposition 4** (3.1.2). *If  $\{X_t\}$  is a stationary process with autocovariance function  $\gamma_x(\cdot)$  and if  $\{\psi_j\}_{j \geq 0}$ ,  $\sum_{j=0}^{\infty} |\psi_j| < \infty$ , define  $Y_t = \sum_{j=0}^{\infty} \psi_j X_{t-j}$  (converges absolutely, w.p 1). Then  $Y_t$  is also stationary with autocovariance function  $\gamma_y(h) = \sum_{j=-\infty}^{\infty} \sum_{k=-\infty}^{\infty} \psi_j \psi_k \gamma_x(h + j - k)$  where  $\psi_j = 0$  for  $j < 0$ .*

*Proof.* We need to show that  $E(Y_t)$  is constant and  $\text{Cov}(Y_{t+h}, Y_t)$  depends only on  $h$ .

$$\begin{aligned}
E(Y_t) &= E\left(\sum_{j=0}^{\infty} \psi_j X_{t-j}\right) = \sum_{j=0}^{\infty} \psi_j E(X_{t-j}) = \mu_x \sum_{j=0}^{\infty} \psi_j \text{ (constant)} \\
\text{Cov}(Y_{t+h}, Y_t) &= E[(Y_{t+h} - E(Y_{t+h}))(Y_t - E(Y_t))] \\
&= E\left[\left(\sum_{j=0}^{\infty} \psi_j (X_{t+h-j} - \mu_x)\right) \left(\sum_{k=0}^{\infty} \psi_k (X_{t-k} - \mu_x)\right)\right] \\
&= E\left[\sum_{j=0}^{\infty} \sum_{k=0}^{\infty} \psi_j \psi_k (X_{t+h-j} - \mu_x)(X_{t-k} - \mu_x)\right] \\
&= \sum_{j=0}^{\infty} \sum_{k=0}^{\infty} \psi_j \psi_k E[(X_{t+h-j} - \mu_x)(X_{t-k} - \mu_x)] \\
&= \sum_{j=0}^{\infty} \sum_{k=0}^{\infty} \psi_j \psi_k \gamma_x(h + j - k) \\
&= \sum_{j=-\infty}^{\infty} \sum_{k=-\infty}^{\infty} \psi_j \psi_k \gamma_x(h + j - k) \text{ where } \psi_j = 0 \text{ for } j < 0
\end{aligned}$$

□

**Remark.** Let  $\alpha(B) = \sum_{j=0}^{\infty} \alpha_j B^j$  and  $\beta(B) = \sum_{j=0}^{\infty} \beta_j B^j$ . Then  $\sum_{j=0}^{\infty} |\alpha_j| < \infty$  and  $\sum_{j=0}^{\infty} |\beta_j| < \infty$ . Then the product  $\psi(B) = \alpha(B)\beta(B) = \sum_{j=0}^{\infty} \psi_j B^j$  then  $\sum_{j=0}^{\infty} |\psi_j| < \infty$

**Theorem 6** (3.1.1.a). If  $\phi(z)$  and  $\theta(z)$  have no common zeros, if  $\phi(z) \neq 0$  for  $|z| = 1$  and if  $\{Z_t\} \sim WN(0, \sigma^2)$  then exists a unique stationary solution given by

$$X_t = \sum_{j=0}^{\infty} \psi_j Z_{t-j} \text{ where } \psi(z) = \frac{\theta(z)}{\phi(z)} = \sum_{j=0}^{\infty} \psi_j z^j$$

and  $\sum_{j=0}^{\infty} |\psi_j| < \infty$ . so that  $X_t$  is well-defined and causal.

*Proof.* (i) Find Solution

If  $\phi(z) \neq 0$  for  $|z| = 1$  then  $\exists \epsilon > 0$  such that

$$\begin{aligned}
\frac{1}{\phi(z)} &:= \sum_{j=0}^{\infty} \zeta_j z^j =: \zeta(z), |z| \leq 1 + \epsilon \\
\implies |\zeta_j| &\leq (1 + \epsilon/2)^{-j} \text{ for some } K > 0
\end{aligned}$$

Consider  $\frac{1}{1-z} = \sum_{j=0}^{\infty} z^j$  for  $|z| < 1$

Consider  $\frac{1}{1-0.5z} = \sum_{j=0}^{\infty} (0.5z)^j$  for  $|z| < 2$

$\phi(z) = \prod_{j=1}^p (1 - w_j z)$ , ie each of the roots are  $\frac{1}{w_j}$ .

Then  $\frac{1}{\phi(z)} = \prod_{j=1}^p \frac{1}{1-w_j z}$

$$\implies \frac{1}{\phi(z)} = \sum_{j=0}^{\infty} \zeta_j z^j \text{ for } |z| < \min_{1 \leq j \leq p} |w_j|^{-1}$$

We know that  $\forall j, |w_j| < 1$  and then if we take  $\epsilon = \min_{1 \leq j \leq p} |w_j|^{-1} - 1 > 0$  then we are done.

(ii) Find Stationary Solution

Define  $X_t = \frac{\theta(B)}{\phi(B)} Z_t$  which is stationary

$$\phi(B)X_t = \theta(B)Z_t$$

(iii) Uniqueness of Stationary Solution

Suppose  $\{W_t\}$  is another stationary solution to  $\phi(B)W_t = \theta(B)Z_t$

$$\begin{aligned} \phi(B)W_t &= \theta(B)Z_t \\ \zeta(B[\phi(B)W_t]) &= \zeta(B[\theta(B)Z_t]) \\ \implies W_t &= \zeta(B)[\theta(B)Z_t] = \frac{\theta(B)}{\phi(B)}Z_t = X_t \end{aligned}$$

□

**Theorem 7** (3.1.1.b). Assume  $\phi(z)$  and  $\theta(z)$  have no common zeros. If there exists a stationary solution which is also causal then  $\phi(z) \neq 0$  for  $|z| \leq 1$ .

## 1.8 9/30/2025 Lecture 8

**Remark** (Review). Prior class review:

- ARMA( $p, q$ ) process:  $\phi(B)X_t = \theta(B)Z_t$  where  $\{Z_t\} \sim WN(0, \sigma^2)$   
 $\phi(z)$  and  $\theta(z)$  have no common zeros.

**Theorem 8** (3.1.1.a & .b). (a) If  $\phi(z) \neq 0$  for all  $|z| \leq 1$  then there exists a unique stationary solution given by

$$X_t = \sum_{j=0}^{\infty} \psi_j Z_{t-j} \text{ where } \psi(z) = \frac{\theta(z)}{\phi(z)} = \sum_{j=0}^{\infty} \psi_j z^j$$

and they satisfy  $\sum_{j=0}^{\infty} |\psi_j| < \infty$ .

(b) If there exists a stationary solution which is also causal then  $\phi(z) \neq 0$  for all  $|z| \leq 1$ .

**Remark.** Not proving

- If  $\phi(z) \neq 0$  for all  $|z| = 1$  then there a unique stationary solution.
- If  $\phi(z) = 0$  for some  $|z| = 1$  then there is no stationary solution.
- If  $\phi(z) \neq 0$  for all  $|z| = 1$  and  $\{X_t\}$  is the unique staitionary solution then one can find  $\hat{\phi}(z)$  and  $WN\{Z_t^*\}$  st  $\hat{\phi}(z)X_t = \phi(B)Z_t^*$  and  $\hat{\phi}(z) \neq 0$  for all  $|z| \leq 1$ .
- Only Focus on Causal and Invertable ARMA models

**Definition** (3.1.4). Suppose  $\{X_t\}$  is a stationary solution of  $\phi(B)X_t = \theta(B)Z_t$ , it is said to be invertible if  $\exists \pi_j$  such that  $\sum_{j=0}^{\infty} |\pi_j| < \infty$  and  $Z_t = \sum_{j=0}^{\infty} \pi_j X_{t-j}$  for all  $t \in \mathbb{Z}$ .

**Theorem 9** (3.1.2). Suppose  $X_t$  is the unique stationary solution of  $\phi(B)X_t = \theta(B)Z_t$ , then it is invertible iff  $\theta(z) \neq 0$  for all  $|z| \leq 1$ .

When the condition holds  $\{\pi_j\}$  are determined by  $\pi(z) = \frac{\phi(z)}{\theta(z)} = \sum_{j=0}^{\infty} \pi_j z^j$ .

**Remark.** IF the definition of invertability is relaxed to:

$$Z_t \in \overline{sp}\{X_t, X_{t-1}, \dots\}$$

then the condition relaxed to  $\theta(z) \neq 0$  for all  $|z| < 1$

**Definition** (3.2.1). Suppose  $\{Z_t\} \sim WN(0, \sigma^2)$ , we say  $\{X_t\}$  is an infinite order moving average denoted by  $MA(\infty)$  if

$$\exists \{\psi_j\} \text{ such that } \sum_{j=0}^{\infty} |\psi_j| < \infty \text{ and } X_t = \sum_{j=0}^{\infty} \psi_j Z_{t-j}$$

May relax condition to  $\sum_{j=0}^{\infty} \psi_j^2 < \infty$  then take  $X_t$  as the  $L^2$  limit.

Sometimes  $MA(\infty)$  is called the linear process.

This is related to the Wold Decomposition Theorem.

**Proposition 5** (3.2.1). If  $\{X_t\}$  is a zero-mean stationary process with autocovariance function  $\gamma_x(\cdot)$  such that  $\gamma_x(h) = 0$  for  $|h| > q$  and  $\gamma_x(q) \neq 0$  then  $\{X_t\}$  is an  $MA(q)$  process.

IE:  $\exists WN\{Z_t\}$  s.t.  $X_t = Z_t + \theta_1 Z_{t-1} + \dots + \theta_q Z_{t-q}$  where  $\theta_q \neq 0$ .

*Proof.* • Find the WN  $\{Z_t\}$

- Show that  $X_t = Z_t + \theta_1 Z_{t-1} + \dots + \theta_q Z_{t-q}$  for some  $\theta_1, \dots, \theta_q$  with  $\theta_q \neq 0$

□

**Definition** (Linear Predictor). Suppose  $Y \in \mathbb{R}$ ,  $E[Y] = 0$ ,  $\mathbf{X} \in \mathbb{R}^d$ ,  $E[\mathbf{X}] = \mathbf{0}$ .

$$\text{Cov}(\begin{bmatrix} Y \\ \mathbf{X} \end{bmatrix}) = \begin{bmatrix} \sigma_Y^2 & \sigma'_{\mathbf{YX}} \\ \sigma_{\mathbf{YX}} & \Sigma_X \end{bmatrix}$$

A linear predictor takes the form  $C^T \mathbf{X}$  where  $C \in \mathbb{R}^d$ .

The best linear predictor (BLP) of  $Y$  based on  $\mathbf{X}$  is the linear predictor  $\hat{Y} = C^T \mathbf{X}$  that minimizes the mean squared error  $\min_{C \in \mathbb{R}^d} E[(Y - C^T \mathbf{X})^2]$ .

$$\begin{aligned} E[(Y - C^T \mathbf{X})^2] &= E[Y^2] - 2C^T E[Y \mathbf{X}] + C^T E[\mathbf{X} \mathbf{X}^T] C \\ &= \sigma_Y^2 - 2C^T \sigma_{\mathbf{YX}} + C^T \Sigma_X C \end{aligned}$$

The best solution is given taking the partial derivative and setting it to 0:

$$\begin{aligned} \frac{\partial}{\partial C} E[(Y - C^T \mathbf{X})^2] &= -2\sigma_{\mathbf{YX}} + 2\Sigma_X C = 0 \\ \implies \hat{C} &= \Sigma_X^{-1} \sigma_{\mathbf{YX}} \\ \implies \hat{Y} &= \hat{C}^T \mathbf{X} = \sigma'_{\mathbf{YX}} \Sigma_X^{-1} \mathbf{X} \end{aligned}$$

$$E[(Y - \hat{Y})^2] = \sigma_Y^2 - \sigma'_{\mathbf{YX}} \Sigma_X^{-1} \sigma_{\mathbf{YX}}$$

**Remark.**  $\{X_t\}$  is a mean-zero stationary process.

Want to predict  $X_{k+1}$  based on  $\{X_1, \dots, X_k\}$ .

$$\min_{\phi_1, \dots, \phi_k} E[(X_{k+1} - \hat{X}_{k+1})^2]$$

Where  $\hat{X}_{k+1} = \sum_{j=1}^k \phi_j X_{k+1-j}$

$$Gamma_{k+1} = Cov\left(\begin{bmatrix} X_{k+1} \\ X_k \\ \vdots \\ X_1 \end{bmatrix}\right) = \begin{bmatrix} \gamma(0) & \gamma(\mathbf{k})' \\ \gamma(\mathbf{k}) & \Gamma_k \end{bmatrix}$$

Where  $\mathbf{gamma}(\mathbf{k}) = [\gamma(1), \dots, \gamma(k)]'$  and  $\Gamma_k = [\gamma(i-j)]_{i,j=1}^k$

$$\begin{bmatrix} \hat{\phi}_1 \\ \hat{\phi}_2 \\ \vdots \\ \hat{\phi}_k \end{bmatrix} = \Gamma_k^{-1} \gamma(\mathbf{k})$$

## 1.9 10/2/2025 Lecture 9

**Proposition 6** (3.2.1). IF  $\{X_t\}$  is a zero-mean stationary process with autocovariance function  $\gamma_x(\cdot)$  such that  $\gamma_x(h) = 0$  for  $|h| > q$  and  $\gamma_x(q) \neq 0$  then  $\{X_t\}$  is an MA( $q$ ) process.

*Proof.* Need to show

- Find  $WN\{Z_t\}$
- Show that  $X_t = Z_t + \theta_1 Z_{t-1} + \dots + \theta_q Z_{t-q}$  for some  $\theta_1, \dots, \theta_q$  with  $\theta_q \neq 0$

Linear prediction problem: Predict  $X_{k+1}$  using  $X_1, \dots, X_k$

$$\begin{aligned} \underline{\phi}_k &= \arg \min_{\phi_1, \dots, \phi_k} E[(X_{k+1} - \hat{X}_{k+1})^2] \\ \hat{X}_{k+1} &= \sum_{j=1}^k \phi_j X_{k+1-j} \end{aligned}$$

$$\underline{\phi}_k = \Gamma_k^{-1} \underline{\gamma}(k) \text{ where } \underline{\gamma}(k) = [\gamma(1), \dots, \gamma(k)]'$$

$$E[(X_{k+1} - \underline{\phi}_k \underline{X}_k)^2] = \gamma(0) - \underline{\gamma}(k)' \Gamma_k^{-1} \underline{\gamma}(k) = \nu_k$$

Note that if we want

$$\begin{aligned} X_t &= Z_t + \theta_1 Z_{t-1} + \dots + \theta_q Z_{t-q} \\ Z_t &= \sum_{j=0}^{\infty} \psi_j X_{t-j} \\ Z_{t-1}, \dots, Z_{t-q} &\in \overline{sp}\{X_{t-1}, X_{t-2}, \dots\} \end{aligned}$$

**Proof:**

Define  $\mathcal{M}_t = \overline{sp}\{X_t, X_{t-1}, \dots\}$  and  $Z_t = X_t - \mathcal{P}_{\mathcal{M}_{t-1}}(X_t)$ . Notice that  $Z_t \in \mathcal{M}_t$  and  $Z_t \perp \mathcal{M}_{t-1}$ .

- $E[Z_s Z_t] = 0$  if  $s \neq t$   $s > t$ .

$$\begin{aligned}
 Z_t &\in \mathcal{M}_t \subset \mathcal{M}_{s-1} \\
 Z_s &:= X_s - \mathcal{P}_{\mathcal{M}_{s-1}}(X_s) \\
 Z_s \perp \mathcal{M}_{s-1} &\implies Z_s \perp Z_t \\
 X_t &= Z_t + \phi_1 Z_{t-1} + \dots + \phi_q Z_{t-q} \text{ for some } \phi_1, \dots, \phi_q \\
 Z_t &= \sum_{j=0}^{\infty} \psi_j X_{t-j} \text{ for some } \psi_j \\
 Z_{t-1}, \dots, Z_{t-q} &\in \overline{sp}\{X_{t-1}, X_{t-2}, \dots\}
 \end{aligned}$$

and  $\mathcal{P}_{\overline{sp}\{X_{t-1}, X_{t-2}, \dots\}}(X_t) \rightarrow \mathcal{P}_{\mathcal{M}_t} X_t$  in  $L^2$  as  $k \rightarrow \infty$ .

- $\|Z_t\| = \lim_{n \rightarrow \infty} \|X_t - \mathcal{P}_{\overline{sp}\{X_{t-1}, \dots, X_{t-n}\}}(X_t)\|$   
 $= \lim_{n \rightarrow \infty} E[(X_{t-1} - \mathcal{P}_{\overline{sp}\{X_{t-2}, \dots, X_{t-n-1}\}}(X_t))] = \|Z_{t-1}\|$   
Denote  $\sigma^2 = \|Z_t\|^2$  then  $\{Z_t\} \sim WN(0, \sigma^2)$
- $\mathcal{M}_{t-1} = \overline{sp}\{X_{t-1}, X_{t-2}, \dots\} = \overline{sp}\{Z_{t-1}, \dots, Z_{t-q}, \dots, X_{t-q-1}, X_{t-q-2}, \dots\}$   
Also  $\overline{sp}\{Z_{t-1}, \dots, Z_{t-q}\} \perp \overline{sp}\{X_{t-q-1}, X_{t-q-2}, \dots\}$   
So  $\mathcal{M}_{t-1} = \overline{sp}\{Z_{t-1}, \dots, Z_{t-q}\} \oplus \mathcal{M}_{t-q-1}$

$$\begin{aligned}
 \mathcal{P}_{\mathcal{M}_{t-1}}(X_t) &= \mathcal{P}_{\overline{sp}\{Z_{t-1}, \dots, Z_{t-q}\}}(X_t) + \mathcal{P}_{\mathcal{M}_{t-q-1}}(X_t) \\
 &= \frac{\langle X_t, Z_{t-1} \rangle}{\langle Z_{t-1}, Z_{t-1} \rangle} Z_{t-1} + \dots + \frac{\langle X_t, Z_{t-q} \rangle}{\langle Z_{t-q}, Z_{t-q} \rangle} Z_{t-q} + \mathcal{P}_{\mathcal{M}_{t-q-1}}(X_t)
 \end{aligned}$$

Note that  $\gamma_x(h) = 0$  for  $|h| > q \implies \mathcal{P}_{\mathcal{M}_{t-q-1}}(X_t) = 0$

$$\implies X_t = Z_t + \sum_{j=1}^q \frac{\langle X_t, Z_{t-j} \rangle}{\sigma^2} Z_{t-j}$$

□

**Proposition 7** (5.2.1 Durbin Levinson Algorithm). Suppose  $\{X_t\}$  is a zero-mean stationary process with autocovariance function  $\gamma(\cdot)$ . Such that  $\gamma(0) > 0$  and  $\gamma(h) \rightarrow 0$  as  $h \rightarrow \infty$ .

Then  $\phi_{11} = \rho(1)$  and  $\nu_1 = \gamma(0)(1 - \rho(1)^2)$

$\phi_{nn} = [\gamma(n) - \sum_{j=1}^{n-1} \phi_{n-1,j} \gamma(n-j)] \nu_{n-1}^{-1}$  for  $n \geq 2$

$$\begin{bmatrix} \phi_{n1} \\ \phi_{n2} \\ \vdots \\ \phi_{n,n-1} \end{bmatrix} = \begin{bmatrix} \phi_{n-1,1} \\ \phi_{n-1,2} \\ \vdots \\ \phi_{n-1,n-1} \end{bmatrix} - \phi_{nn} \begin{bmatrix} \phi_{n-1,n-1} \\ \phi_{n-1,n-2} \\ \vdots \\ \phi_{n-1,1} \end{bmatrix} \text{ for } n \geq 2$$

$$\nu_n = \nu_{n-1}(1 - \phi_{nn}^2)$$

Given  $\phi_{n-1}$  and  $\nu_{n-1}$  How do we get  $\phi_n$  and  $\nu_n$ ?

The complexity is  $O(n^2)$  instead of  $O(n^3)$ .

*Proof.* (1)  $\phi_{11} = \rho(1)$  and  $\nu_1 = \gamma(0)[1 - \rho(1)^2]$

Suppose we have  $\underline{\phi}_{n-1}$  and  $\nu_{n-1}$ , we want to find  $\underline{\phi}_n$  and  $\nu_n$ .

Want:  $\mathcal{P}_{\overline{sp}\{X_1, \dots, X_n\}}(X_{n+1})$

Let  $w_1 = X_1 - \mathcal{P}_{\overline{sp}\{X_2, \dots, X_n\}}(X_1)$  then  $\begin{cases} w_1 \perp \overline{sp}\{X_n, \dots, X_{n-2}\} \\ \overline{sp}\{X_1, \dots, X_n\} = \overline{sp}\{w_1\} \oplus \overline{sp}\{X_2, \dots, X_n\} \end{cases}$

$$\mathcal{P}_{\overline{sp}\{X_n, \dots, X_2\}}(X_{n+1}) = \underline{\phi}_{n-1}' \begin{bmatrix} X_n \\ X_{n-1} \\ \vdots \\ X_2 \end{bmatrix} \text{ Then want } \frac{\langle X_{n+1}, w_1 \rangle}{\langle w_1, w_1 \rangle} w_1$$

$$\mathcal{P}_{\overline{sp}\{X_n, \dots, X_{n-2}\}}(X_1) = \underline{\phi}_{n-1}' \begin{bmatrix} X_1 \\ X_2 \\ \vdots \\ X_n \end{bmatrix}$$

$$w_1 = X_1 - \underline{\phi}_{n-1}' \begin{bmatrix} X_1 \\ X_2 \\ \vdots \\ X_n \end{bmatrix} \quad \|w_1\|^2 = \nu_{n-1} \quad \langle X_{n+1}, w_1 \rangle = \gamma(n) - \underline{\phi}_{n-1}' \begin{bmatrix} \gamma(n-1) \\ \gamma(n-2) \\ \vdots \\ \gamma(1) \end{bmatrix}$$

$$\mathcal{P}_{\overline{sp}_{w_1}}(X_{n+1}) = \frac{\langle X_{n+1}, w_1 \rangle}{\langle w_1, w_1 \rangle} w_1 = \phi_{nn} w_1 \underline{\phi}_n' \begin{bmatrix} X_n \\ X_{n-1} \\ \vdots \\ X_1 \end{bmatrix} - \phi_{nn} \begin{bmatrix} \phi_{n-1,n-1} \\ \phi_{n-1,n-2} \\ \vdots \\ \phi_{n-1,1} \end{bmatrix} \nu_n = \nu_{n-1} - \phi_{nn}^2 \nu_{n-1} = (1 - \phi_{nn}^2) \nu_{n-1}$$

□

PLEASE REVIEW THIS WHAT THE HELL IS THIS

## 1.10 10/7/2025 Lecture 10

**Remark.** Review of last class:

- Linear Predictor: Suppose  $Y \in \mathbb{R}$ ,  $E[Y] = 0$ ,  $\mathbf{X} \in \mathbb{R}^d$ ,  $E[\mathbf{X}] = \mathbf{0}$ .

$$\text{Cov}(\begin{bmatrix} Y \\ \mathbf{X} \end{bmatrix}) = \begin{bmatrix} \sigma_Y^2 & \Sigma_{YX} \\ \Sigma_{XY} & \Sigma_X \end{bmatrix}$$

The BLP is given by  $\hat{X} = \phi'_n X_n$  where  $\phi_n = \begin{bmatrix} \phi_{n1} \\ \phi_{n2} \\ \vdots \\ \phi_{nn} \end{bmatrix}$  and  $X_n = \begin{bmatrix} X_n \\ X_{n-1} \\ \vdots \\ X_1 \end{bmatrix}$

Suppose  $\{X_t\}$  follows causal AR( $p$ ) process:  $\phi(B)X_t = Z_t$  where  $\{Z_t\} \sim WN(0, \sigma^2)$

Predict  $X_t$  based on  $X_{t-1}, \dots, X_{t-p}$ . Then use  $\phi_p = \begin{bmatrix} \phi_1 \\ \phi_2 \\ \vdots \\ \phi_p \end{bmatrix}$

**Definition** (Partial Autocorrelation Function). Let  $\{X_t\}$  be a mean-zero stationary process. Its partial autocorrelation function (PACF)  $\alpha(\cdot)$  is a function on positive integers defined as follows:

- $\alpha(1) = \rho(1)$
- $\alpha(k) = \text{Cor}[X_{k+1} - \mathcal{P}_{\bar{s}\bar{p}\{X_k, \dots, X_2\}}(X_{k+1}), X_1 - \mathcal{P}_{\bar{s}\bar{p}\{X_2, \dots, X_1\}}(X_1)]$  for  $k \geq 2$

**Example** (3.4.1). AR(1) process:  $X_t = \phi X_{t-1} + Z_t$

$$\begin{aligned} \alpha(1) &= \rho(1) = \phi \\ \alpha(2) &= \text{Cor}[X_3 - \mathcal{P}_{\bar{s}\bar{p}\{X_2\}}(X_3), X_1 - \mathcal{P}_{\bar{s}\bar{p}\{X_2\}}(X_1)] \\ &= \text{Cor}[X_3 - \phi X_2, X_1 - \phi X_2] \\ &= \text{Cor}[Z_3, X_1 - \phi X_2] = 0 \\ \alpha(k) &= 0 \text{ for } k > 1 \end{aligned}$$

**Example** (3.4.2). MA(1) process:  $X_t = Z_t + \theta Z_{t-1}$  where  $\{Z_t\} \sim WN(0, \sigma^2)$

$$\begin{aligned} \alpha(1) &= \rho(1) = \frac{\theta}{1 + \theta^2} \\ \alpha(2) &= \text{Cor}[X_3 - \mathcal{P}_{\bar{s}\bar{p}\{X_2\}}(X_3), X_1 - \mathcal{P}_{\bar{s}\bar{p}\{X_2\}}(X_1)] \\ &= \text{Cor}[X_3 - \rho(1)X_2, X_1 - \rho(1)X_2] \\ &= \frac{-\theta^2}{1 + \theta^2 + \theta^4} \end{aligned}$$

**Definition** (Partial Least Squares). Model 1:  $y_i = \beta_0 + \sum_{j=1}^p \beta_j x_{ij} + \epsilon_i$  for  $i = 1, \dots, n$

Model 2:  $y_i = \beta_0 + \sum_{j=1}^k \beta_j z_{ij} + \epsilon_i$  for  $i = 1, \dots, n$

PLS procedure: Set LSE  $\hat{\beta}_{(p-1)}$  based on Model 2

- regress  $\underline{x}_p$  on  $\underline{x}_1, \dots, \underline{x}_{p-1}$  set the LSE to  $\hat{\gamma}$  ie  $\underline{x}_p = \sum_{j=1}^{p-1} \gamma_j \underline{x}_j + \underline{z}_p$
- Regress  $\underline{y}$  on  $\underline{z}_p$ , minimize  $\|\underline{y} - c\underline{z}_{p-1}\|$   $\hat{c} = \frac{\langle \underline{y}, \underline{z}_p \rangle}{\langle \underline{z}_p, \underline{z}_p \rangle}$
- get the LSE  $\hat{\beta}_p$  BA sed on Model 1

- See that  $\hat{c} = \hat{\beta}_p$

**Remark.** Prediction problem 1:

Predict  $X_k$  using  $X_2, \dots, X_{k-1}$

Prediction problem 2:

Predict  $X_k$  using  $X_{k-1}, \dots, X_2, X_1$

Question how much does  $X_1$  help in predicting  $X_k$  given  $X_2, \dots, X_{k-1}$

$$\text{use } \frac{\langle X_1 - \mathcal{P}_{\overline{sp}\{X_2, \dots, X_{k-1}\}}(X_1), X_{k+1} - \mathcal{P}_{\overline{sp}\{X_2, \dots, X_{k-1}\}}(X_{k+1}) \rangle}{\|X_1 - \mathcal{P}_{\overline{sp}\{X_2, \dots, X_{k-1}\}}(X_1)\|^2} w_1 = X_1 - \mathcal{P}_{\overline{sp}\{X_2, \dots, X_{k-1}\}}(X_1)$$

$$w_1 = X_1 - \phi_{k-1,1}X_2 - \dots - \phi_{k-1,k-1}X_k$$

$$\begin{aligned} \mathcal{P}_{\overline{sp}\{X_k \dots X_1\}}(X_{k+1}) &= \mathcal{P}_{\overline{sp}\{X_k \dots X_2\}}(X_k) + \mathcal{P}_{\overline{sp}\{w_1\}}(X_{k+1}) \text{ where } w_1 = X_1 - \mathcal{P}_{\overline{sp}\{X_2, \dots, X_{k-1}\}}(X_1) \\ &= \phi_{k-1,1}X_k + \dots + \phi_{k-1,k-1}X_2 + \hat{c}(X_1 - \phi_{k-1,1}X_2 - \dots - \phi_{k-1,k-1}X_k) \\ &= \hat{c}X_1 + \dots \\ &= \phi_{k,k}X_1 + \dots \end{aligned}$$

Thus  $\alpha(k) = \phi_{kk}$

**Example.** AR( $p$ ) process:  $\phi(B)X_t = Z_t$

$$\alpha(1) = \rho(1) = \phi_1$$

$$\alpha(p) = \phi_p$$

$$\alpha(k) = 0 \text{ for } k > p$$

Table 1: Theoretical behaviour of the ACF and PACF for common linear time series models

Model	ACF behaviour	PACF behaviour	Identification rule (sample)
AR( $p$ )	Tails off (exponential or damped sinusoid depending on roots).	Cuts off after lag $p$ (i.e. $\alpha(k) \approx 0$ for $k > p$ ).	If sample ACF decays and sample PACF shows a clear cutoff at lag $p$ , prefer AR( $p$ ).
MA( $q$ )	Cuts off after lag $q$ (theoretical autocorrelations $\rho_k = 0$ for $k > q$ ).	Tails off (no finite cutoff).	If sample ACF has significant spikes up to lag $q$ then $\approx 0$ afterwards, prefer MA( $q$ ).
ARMA( $p, q$ )	Tails off (mixture-shaped decay from both AR and MA parts).	Tails off (mixture-shaped).	If both sample ACF and PACF tail off (no short cutoff), try ARMA( $p, q$ ) and select $(p, q)$ by AIC/BIC.

## 1.11 10/9/2025 Lecture 11

**Remark** (Estimating The PACF). Assume  $\{X_t\}$  is a mean-zero stationary process .

Predict  $X_{k+1}$  based on  $X_k, \dots, X_1$

Then the coefficient of  $X_1$  is  $\alpha(k)$

**Method 1**  $\underline{\phi}_k = \Gamma_k^{-1} \underline{\gamma}_{k+1}$  where  $\underline{\gamma}_k = [\gamma(1), \dots, \gamma(k)]'$  and  $\Gamma_k = [\gamma(i-j)]_{i,j=1}^k$

Plug in the sample autocovariance function  $\hat{\gamma}(h)$  to get an estimated  $\hat{\phi}_{k+1}$  and take  $\hat{\alpha}(k) = \hat{\phi}_{kk}$

**Method 2**  $\min_{\phi_1, \dots, \phi_k} \sum_{t=k+1}^n (X_t - \mathcal{P}_{\bar{s}\bar{p}\{X_{k+1}, \dots, X_1\}}(X_t))^2$

$$= \sum_{t=k+1}^n (X_t - \phi_{k+1}X_{t-1} - \dots - \phi_kX_{t-k})^2$$

Then take  $\hat{\alpha}(k) = \hat{\phi}_k$

**Remark** (ACF and PACF Estimation for ARMA( $p, q$ )). Assume  $\{X_t\}$  is a mean-zero stationary process and a causal and invertible ARMA( $p, q$ ) process.

How to calculate the ACF?

- AR(1):  $X_t = \phi X_{t-1} + Z_t$   
 $\gamma(0) = \phi^2 \gamma(0) + \sigma^2 \implies \gamma(0) = \frac{\sigma^2}{1-\phi^2}$  note that it needs to be causal so  $|\phi| < 1$ .  
 $\gamma(h) = \phi \gamma(h-1)$  for  $h \geq 1$   
 $\implies \gamma(h) = \phi^{|h|} \gamma(0)$
- AR(2):  $X_t = \phi_1 X_{t-1} + \phi_2 X_{t-2} + Z_t$   
covariance with  $X_{t-1}$  is  $\gamma(1) = \phi_1 \gamma(0) + \phi_2 \gamma(1) \implies \rho(1) = \phi_1 + \phi_2 \rho(1) \implies \rho(1) = \frac{\phi_1}{1-\phi_2}$   
 $\gamma(h) = \phi_1 \gamma(h-1) + \phi_2 \gamma(h-2)$  for  $h \geq 2 \implies \rho(h) = \phi_1 \rho(h-1) + \phi_2 \rho(h-2)$  for  $h \geq 2$
- General ARMA( $p, q$ ):  
Method 1: Write  $X_t = \frac{\theta(B)Z_t}{\phi(B)} = \psi(B)Z_t = \sum_{j=0}^{\infty} \psi_j Z_{t-j}$   
 $\gamma(0) = \psi_0^2 \sigma^2 + \psi_1^2 \sigma^2 + \dots = \sigma^2 \sum_{j=0}^{\infty} \psi_j^2$   
 $\gamma(h) = \sigma^2 \sum_{j=0}^{\infty} \psi_j \psi_{j+h}$  for  $h \geq 1$

$$\psi(z) = \frac{\theta(z)}{\phi(z)} \implies \phi(z)\psi(z) = \theta(z)$$

$$(1 - \phi_1 z - \dots - \phi_p z^p)(\psi_0 + \psi_1 z + \psi_2 z^2 + \dots) = 1 + \theta_1 z + \dots + \theta_q z^q$$

Match the coefficients of  $z^j$  for  $j = 0, 1, 2, \dots$  to get  $\psi_0, \psi_1, \dots$

- $\psi_0 = 1$
- $\psi_1 - \phi_1 \psi_0 = \theta_1 \implies \psi_1 = \phi_1 + \theta_1$
- $\psi_2 - \phi_1 \psi_1 - \phi_2 \psi_0 = \theta_2 \implies \psi_2 = \phi_1 \psi_1 + \phi_2 + \theta_2$

Method 2: Example ARMA(2,2)  $X_t = \phi_1 X_{t-1} + \phi_2 X_{t-2} + Z_t + \theta_1 Z_{t-1} + \theta_2 Z_{t-2}$

Covariance with  $X_t$ :  $\gamma(0) = \phi_1\gamma(1) + \phi_2\gamma(2) + \sigma^2(1 + \theta_1\psi_1 + \theta_2\psi_2)$

Covariance with  $X_{t-1}$ :  $\gamma(1) = \phi_1\gamma(0) + \phi_2\gamma(1) + \sigma^2(\theta_1 + \theta_2\psi_1)$

Covariance with  $X_{t-2}$ :  $\gamma(2) = \phi_1\gamma(1) + \phi_2\gamma(0) + \sigma^2\theta_2$

Now we can solve for  $\gamma(0), \gamma(1), \gamma(2)$

Covariance with  $X_{t-h}$  for  $h \geq 3$ :  $\gamma(h) = \phi_1\gamma(h-1) + \phi_2\gamma(h-2)$

Method 2.1: Solve the Difference Equation

Method 2.2: Get  $\gamma(h)$  recursively

In general ARMA( $p, q$ ): make a system of  $p+1$  equations.

**Remark** (Statistical inference). Ask the questions: How do I know the order of the model? How do I estimate the parameters? How do I check if the model is good?

**Remark** (Spectral Representations of Stochastic Processes). New Chapter

**Definition** (Complex Random Variable).  $X = Re(X) + iIm(X)$  where  $Re(X), Im(X)$  are real random variables.

or  $X = X_1 + iX_2$  where  $X_1, X_2$  are real random variables on the same probability space.

**Properties**

$$E[X] = E[X_1] + iE[X_2]$$

Suppose  $Y = Y_1 + iY_2$  is another complex random variable.

$$\text{Cov}(X, Y) = E[(X - E[X])(Y - E[Y])]$$

$$\text{Cov}(X, Y) = \text{Cov}(Y, X)$$

Assume  $E[X] = 0$  then  $\text{Var}(X) = E[(X + iX_2)(X - iX_2)] = E[X_1^2 + X_2^2] \geq 0$

To get Properties of  $X_1, X_2$  from  $X$  use Variance and Second moment

$$L_c^2(\Omega, \mathcal{F}, P) = \{X : X = X_1 + iX_2, X_1, X_2 \in L^2(\Omega, \mathcal{F}, P)\}$$

**Definition** (Stationary Process for Complex Random Variables).  $\{X_t\}$  is a complex-valued process.

It is a complex valued stationary process if  $E[|X_t|^2] < \infty$  and  $E[X_t]$  does depend on  $t$  and  $E[X_{t+h}\bar{X}_t]$  does not depend on  $t$ .

Write  $X_t = X_{t1} + iX_{t2}$  where  $X_{t1}, X_{t2}$  are real-valued processes.

$$\begin{aligned} E[X_{t+h}\bar{X}_t] &= E[(X_{t+h,1} + iX_{t+h,2})(X_{t1} - iX_{t2})] \\ &= E[X_{t+h,1}X_{t1}] + E[X_{t+h,2}X_{t2}] + i(E[X_{t+h,2}X_{t1}] - E[X_{t+h,1}X_{t2}]) \end{aligned}$$

This means the sum of the auto and cross covariance functions do not depend on  $t$ .

If a process is complex-valued stationary process does it imply that the real and imaginary parts are stat-

## 1.12 10/14/2025 Lecture 12

**Remark.** Review of last class:

- $X = X_1 + iX_2$  where  $X_1, X_2$  are real random variables

- $E[X] = E[X_1] + iE[X_2]$
- $\langle X, Y \rangle = E[X\bar{Y}]$
- $\text{Cov}(X, Y) = E[(X - E[X])(\bar{Y} - E[\bar{Y}])] = \langle X, Y \rangle - \langle E[X], E[Y] \rangle$
- Complex  $L^2$  space
- Complex-valued stationary process:
  - $E[|X_t|^2] < \infty$
  - $E[X_t]$  does not depend on  $t$
  - $E[X_{t+h}\bar{X}_t]$  does not depend on  $t$
- the autocovariance of a complex-valued stationary process is  $\gamma(h) = E[X_{t+h}\bar{X}_t] = \langle X_{t+h}, X_t \rangle - \langle E[X_{t+h}], E[X_t] \rangle$ .
- $\gamma(h) = \overline{\gamma(-h)}$  it is hermitian

**Theorem 10** (4.1.1). *A function  $k(\cdot)$  defined on the integers is an autocovariance function of a complex valued stationary process if and only if it is non-negative definite.*

$$IE \sum_{j,k=1}^n a_j k(j-k) \bar{a_k} \geq 0 \text{ for all } n \geq 1 \text{ and } a_1, \dots, a_n \in \mathbb{C}$$

This also implies that the acf is also hermitian

*Proof.*  $\implies$  : Left As excrise

$\Leftarrow$  : NND when  $n = 1$   $a_1 = 1$  implies  $k(0) \geq 0$

NND when  $n = 2$  take  $a_1 = 1$ ,  $k(0) + k(0) \cdot |a_2|^2 + k(-1)\bar{a_2} + k(1)a_2 \geq 0$

it is always real  $\implies k(1) = -k(-1)$

for an arbitrary  $n$  take  $a_j = 0$  for  $j \neq 1, n$

$a_1 = 1, k(1-n) = -k(n-1)$

Suppose  $k(\cdot)$  is the acf of  $X_t = Y_t + iZ_t$  where  $Y_t, Z_t$  are real-valued stationary processes with mean 0

Let  $\underline{X} = (X_1, \dots, X_n)'$  and  $\underline{Y} = (Y_1, \dots, Y_n)'$

$$\text{Cov}(\underline{X}) = E[\underline{X}\underline{X}^*] = E[(\underline{Y} + i\underline{Z})(\underline{Y}' - i\underline{Z}')]$$

$$= \Sigma_{yy} + \Sigma_{zz} + i(\Sigma_{zy} - \Sigma_{yz})$$

$$\text{Cov}(\underline{X}) = \begin{bmatrix} k(0) & k(-1) & k(-2) & \dots & k(1-n) \\ k(1) & k(0) & k(-1) & \dots & k(2-n) \\ k(2) & k(1) & k(0) & \dots & k(3-n) \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ k(n-1) & k(n-2) & k(n-3) & \dots & k(0) \end{bmatrix} = K_1 + iK_2 \text{ where } K_1 \text{ and } K_2 \text{ are}$$

real matrices.

write  $\underline{a} = (a_1, \dots, a_n)' = \underline{b} + i\underline{c}$

$$\begin{aligned}
\sum_{j,k=1}^n a_j k(j-k) \overline{a_k} &= \underline{\mathbf{a}}' \underline{\mathbf{K}} \overline{\underline{\mathbf{a}}} \\
&= (\underline{\mathbf{b}} + i\underline{\mathbf{c}})'(K_1 + iK_2)(\underline{\mathbf{b}} - i\underline{\mathbf{c}}) \\
&= \underline{\mathbf{b}}' K_1 \underline{\mathbf{b}} + \underline{\mathbf{c}}' K_1 \underline{\mathbf{c}} + b' K_2 c - c' K_2 b \\
\text{same as } &= (b'_1 - c') \begin{bmatrix} k_1 & k'_2 \\ k_2 & k_1 \end{bmatrix} \begin{bmatrix} b \\ c \end{bmatrix} \geq 0
\end{aligned}$$

Take  $\Sigma_{yy} = \Sigma_{zz} = \frac{1}{2}K_1$  and  $\Sigma_{zy} = \frac{1}{2}K_2$ ,  $\Sigma_{yz} = \frac{1}{2}K'_2 = -\frac{1}{2}K_2$   
 $K'_1 - iK'_2 = K_1 + iK_2$  thus  $K'_2 = -K_2$

Construct  $\begin{bmatrix} \underline{\mathbf{Y}} \\ \underline{\mathbf{Z}} \end{bmatrix} \sim N(0, \frac{1}{2} \begin{bmatrix} K_1 & K'_2 \\ K_2 & K_1 \end{bmatrix})$

□

**Example.**  $X_t = \sum_{j=1}^n A_j e^{it\lambda_j}$

- $-\pi < \lambda_1 < \lambda_2 < \dots < \lambda_n = \pi$
- $A_j$  are complex-valued random variables
- $E[A_j] = 0$ ,  $E[A_j \overline{A_k}] = 0$  for  $j \neq k$ ,  $E[|A_j|^2] = \sigma_j^2 < \infty$

Write  $A_j = C_j + iD_j$  then

$$\begin{aligned}
(C_j + iD_j)e^{it\lambda_j} &= (C_j + iD_j)(\cos(t\lambda_j) + i \sin(t\lambda_j)) \\
&= (C_j \cos(t\lambda_j) - D_j \sin(t\lambda_j)) + i(C_j \sin(t\lambda_j) + D_j \cos(t\lambda_j))
\end{aligned}$$

We can see that this is a complex-valued stationary process, but if I want the  $X$  to be real then we require the condition that  $C_j \sin(t\lambda_j) + D_j \cos(t\lambda_j) = 0$

Want  $X_t$  to be real valued  $\begin{cases} \lambda_j = -\lambda_{n-j} \text{ for } j = 1, \dots, n-1 \\ A(\lambda_j) = \overline{A(\lambda_{n-j})} \text{ for } j = 1, \dots, n-1 \\ A_n \text{ is real} \end{cases}$

This

## 1.13 10/16/2025 Lecture 13

**Remark.** Review of what we are looking at

$$X_t = \sum_{j=1}^n A_j e^{it\lambda_j}$$

where  $\begin{cases} -\pi < \lambda_1 < \lambda_2 < \dots < \lambda_n = \pi \\ A_j \text{ are uncorrelated complex-valued random variables} \\ E[A_j] = 0, E[A_j \overline{A_k}] = 0 \text{ for } j \neq k, E[|A_j|^2] = \sigma_j^2 < \infty \end{cases}$

When is  $X_t$  real-valued?  $\begin{cases} \lambda_j = -\lambda_{n-j} & 1 \leq j \leq n-1 \\ A_j = \overline{A_{n-j}} & 1 \leq j \leq n-1 \\ A_n \text{ is real} \end{cases}$  Is  $X_t$  stationary?

$$\begin{aligned} E(X_{t+h} \overline{X_t}) &= E \left[ \left( \sum_{j=1}^n A_j e^{i(t+h)\lambda_j} \right) \left( \sum_{k=1}^n \overline{A_k} e^{-it\lambda_k} \right) \right] = E [A_1 \overline{A_1} e^{ih\lambda_1} + A_2 \overline{A_2} e^{ih\lambda_2} + \dots + A_n \overline{A_n} e^{ih\lambda_n}] \\ &= \sum_{j=1}^n \sigma_j^2 e^{ih\lambda_j} \end{aligned}$$

This does not depend on  $t$  so it is stationary.

$\gamma(h) = \int_{-\pi}^{\pi} e^{ih\nu} dF(\nu)$  where  $F(\nu) = \sum_{j:\lambda_j \leq \nu} \sigma_j^2$  This is the Riemann-Stieltjes integral. This is a step function with jumps of size  $\sigma_j^2$  at  $\lambda_j$  for  $j = 1, \dots, n$ .

View  $F(\nu)$  as a measure on  $(-\pi, \pi]$  which assigns point measures  $m(\nu) = \sigma_j^2$ . The function  $e^{ih\nu}$  takes on values  $e^{ih\lambda_j}$  at the points  $\lambda_j$  with value  $\sigma_j^2$ . Every mean-zero stationary process  $\{X_t\}$  has a representation

$$X_t = \int_{-\pi}^{\pi} e^{it\nu} dZ(\nu)$$

If we have a continuous path, everywhere differentiable, how is this different from the Riemann-Stieltjes integral where  $Z(\nu)$  is a complex-valued process with the following properties:

- $E[dZ(\nu)] = 0$
- $E[|dZ(\nu)|^2] = dF(\nu)$  where  $F(\nu)$  is a non-decreasing function on  $(-\pi, \pi]$  with  $F(-\pi) = 0$  and  $F(\pi) = \gamma(0)$
- $E[dZ(\nu) \overline{dZ(\lambda)}] = 0$  for  $\nu \neq \lambda$

Correspondingly  $\gamma_X(h) = \int_{-\pi}^{\pi} e^{ih\nu} dF(\nu)$  **Riemann integral:**  $\int_a^b g(x) dx$  where  $g(x)$  is a function on  $[a, b]$

$$\lim_{\max |a_j - a_{j-1}| \rightarrow 0} \sum_{j=1}^n g(a_j)(a_j - a_{j-1})$$

$$\lim_{\max |\lambda_j - \lambda_{j-1}| \rightarrow 0} \sum_{j=1}^n e^{ih\lambda_j} Z(\lambda_j) - Z(\lambda_{j-1})$$

$F(\cdot)$  is called the spectral distribution function of  $\{X_t\}$ .  
 $F$  is increasing and caddlag,  $F(-\pi) = 0, F(\pi) = \gamma(0)$

**Theorem 11** (4.3.1 Herglotz Theorem). A complex Values fn  $\gamma(\cdot)$  defined on the integers is NND if and only if

$$\gamma(h) = \int_{-\pi}^{\pi} e^{ih\nu} dF(\nu) \quad h \in \mathbb{Z}$$

Where  $F(\cdot)$  is a distribution function supported on  $(-\pi, \pi]$  with  $F(-\pi) = 0$  and  $F(\pi) \leq \infty$

Note: Corresponding Bocher's for the characteristic function of a random variable

If  $F(\cdot)$  is absolutely Continuous w.r.t the Lebesgue measure, (ie they are related but not the same) ie  $F(\lambda) = \int_{-\pi}^{\lambda} f(\nu)d\nu$  then  $f(\lambda)$  is called the spectral density function of  $\{X_t\}$

*Proof.*  $\Leftarrow$

$$\begin{aligned} \sum_{j,k=1}^n a_j \gamma(j-k) \overline{a_k} &= \sum_{j,k=1}^n a_j \int_{-\pi}^{\pi} e^{i(j-k)\nu} dF(\nu) \overline{a_k} \\ &= \int_{-\pi}^{\pi} \sum_{j,k=1}^n a_j e^{i(j)\nu} e^{-ik\nu} \overline{a_k} dF(\nu) \\ &= \int_{-\pi}^{\pi} \left( \sum_{j=1}^n a_j e^{ij\nu} \right) \left( \sum_{k=1}^n \overline{a_k e^{ik\nu}} \right) dF(\nu) \\ &= \int_{-\pi}^{\pi} \left| \sum_{j=1}^n a_j e^{ij\nu} \right|^2 dF(\nu) \geq 0 \end{aligned}$$

□

## 1.14 10/21/2025 Lecture 14

**Remark** (Spectral Representation of Complex Stationary Process). Every zero-mean stationary process has a representation:

$$X_t = \int_{-\pi}^{\pi} e^{it\nu} dZ(\nu)$$

Correspondingly  $\gamma_X(h) = \int_{-\pi}^{\pi} e^{ih\nu} dF(\nu)$  F is cadlag, increasing,  $F(-\pi) = 0$ ,  $F(\pi) = \gamma(0)$  where  $Z(\nu)$  is a complex-valued process with the following properties:

If  $F(\cdot)$  is absolutely continuous w.r.t the Lebesgue measure, ie  $F(\lambda) = \int_{-\pi}^{\lambda} f(\nu)d\nu$  then  $\gamma_X(h) = \int_{-\pi}^{\pi} e^{ih\nu} f(\nu)d\nu$  where  $f(\nu)$  is called the spectral density function of  $\{X_t\}$   
F is the spectral distribution function of  $\{X_t\}$  f is the spectral density function of  $\{X_t\}$

**Theorem 12** (4.3.1 Herglotz). A complex valued fn  $\gamma(\cdot)$  defined on  $\mathbb{Z}$  is NND if and only if

$$\gamma(h) = \int_{-\pi}^{\pi} e^{ih\nu} dF(\nu) \quad h \in \mathbb{Z}$$

Where  $F(\cdot)$  is a distribution function supported on  $(-\pi, \pi]$  with  $F(-\pi) = 0$  and  $F(\pi) \leq \infty$

*Proof.*  $\implies$  Define  $f_n(\nu) = \frac{1}{2\pi N} \sum_{j,k=1}^N \gamma(j-k) e^{-ij\nu} e^{ik\nu}$

$$\begin{aligned} f_n(\nu) &= \frac{1}{2\pi N} \sum_{j,k=1}^N \gamma(j-k) e^{-ij\nu} e^{ik\nu} \\ &= \frac{1}{2\pi N} \sum_{m=1-N}^{N-1} \left(1 - \frac{|m|}{N}\right) \gamma(m) e^{im\nu} \end{aligned}$$

Fejer Kernel Then  $f_n(\nu) \geq 0$  and  $\int_{-\pi}^{\pi} f_n(\nu) d\nu = \gamma(0)$

Next Define  $F_N(\lambda) = \int_{-\pi}^{\lambda} f_n(\nu) d\nu$  Then  $F_N(\lambda)$  is a distribution function on  $(-\pi, \pi]$  with  $F_N(-\pi) = 0$  and  $F_N(\pi) = \gamma(0)$

And

$$\begin{aligned} \int_{-\pi}^{\pi} e^{ih\nu} dF_N(\nu) &= \int_{-\pi}^{\pi} e^{ih\nu} f_n(\nu) d\nu \\ &= \begin{cases} \gamma(h) \left(1 - \frac{|h|}{N}\right) & |h| < N \\ 0 & |h| \geq N \end{cases} \end{aligned}$$

By Helly's Theorem: there exists a subsequence  $\{N_k\}$  s.t.  $F_{N_k}(\cdot) \rightarrow F(\cdot)$  and  $\lim_{k \rightarrow \infty} \int_{-\pi}^{\pi} e^{ih\nu} dF_{N_k}(\nu) = \int_{-\pi}^{\pi} e^{ih\nu} dF(\nu)$

$$\lim_{k \rightarrow \infty} \int_{-\pi}^{\pi} e^{ih\nu} dF_{N_k}(\nu) = \lim_{k \rightarrow \infty} \gamma(h) \left(1 - \frac{|h|}{N_k}\right) = \gamma(h)$$

□

**Remark.**  $F$  as the limit might have a point mass at  $-\pi$  so an additital step transfer it to  $\pi$   
It can be proven that  $F_N(\cdot) \rightarrow F(\cdot)$

This also ensure the spectral distribution function is unique ie if  $\exists$  another distribution function  $G(\cdot)$  s.t  $\gamma(h) = \int_{-\pi}^{\pi} e^{ih\nu} dG(\nu)$  then  $F(\cdot) = G(\cdot)$  at all continuity points of both  $F$  and  $G$

**Theorem 13** (4.3.2). Suppose  $K(\cdot)$  is a function defined on  $\mathbb{Z}$  s.t.  $\sum_{h=-\infty}^{\infty} |K(h)| < \infty$  then

$$f(\lambda) := \frac{1}{2\pi} \sum_{h=-\infty}^{\infty} K(h) e^{-ih\lambda}$$

is well -defined and  $K(n) = \int_{-\pi}^{\pi} e^{in\lambda} f(\lambda) d\lambda$  for all  $n \in \mathbb{Z}$

**Corollary.** Suppose  $\gamma(\cdot)$  is a function defined on  $\mathbb{Z}$  and it  $\sum_{h=-\infty}^{\infty} |\gamma(h)| < \infty$  then  $\gamma(\cdot)$  is the acf of a stationary process iff  $f(\lambda) := \frac{1}{2\pi} \sum_{h=-\infty}^{\infty} \gamma(h) e^{-ih\lambda} \geq 0$  for all  $\lambda \in [-\pi, \pi]$

*Proof.*  $\Leftarrow$ :  $f$  is a density, can define  $F(\lambda) = \int_{-\pi}^{\lambda} f(\nu) d\nu$  which is a distribution function on  $(-\pi, \pi]$

$$\Rightarrow f_N(\lambda) = \frac{1}{2\pi} \sum_{m=-1-N}^{N-1} (1 - \frac{|m|}{N}) \gamma(m) e^{-im\lambda} \geq 0 \text{ for all } \lambda \in [-\pi, \pi]$$

□

**Example (4.3.1).**  $K(h) = \begin{cases} 1 & h = 0 \\ \rho & h = \pm 1 \\ 0 & \text{otherwise} \end{cases}$  where  $|\rho| < \frac{1}{2}$

We can look at the spectral density function:

$$\begin{aligned} f(\lambda) &= \frac{1}{2\pi} \sum_{h=-\infty}^{\infty} K(h) e^{-ih\lambda} \\ &= \frac{1}{2\pi} (1 + \rho e^{-i\lambda} + \rho e^{i\lambda}) \\ &= \frac{1}{2\pi} (1 + 2\rho \cos(\lambda)) \end{aligned}$$

**Remark.** If the acf is real, then the spectral density function is also real-valued.

$$f(\lambda) = \frac{1}{2\pi} [1 + \sum_{n=1}^{\infty} 2\gamma(n) \cos(n\lambda)]$$

In general the spectral distribution function is stne=netruc in the sense  $F_X(\lambda) = F_X(\pi^-) - F_X(-\lambda^-)$

[HW]

## 1.15 10/23/2025 Lecture 15

**Remark.** If  $\gamma(\cdot)$  is a complex valued acg then there exists a unique spectral distribution  $F$  s.t.  $\gamma(h) = \int_{-\pi}^{\pi} e^{ih\nu} dF(\nu)$

If  $F(\cdot)$  is absolutely continuous w.r.t the Lebesgue measure ie  $F(\lambda) = \int_{-\pi}^{\lambda} f(\nu) d\nu$  then  $\gamma(h) = \int_{-\pi}^{\pi} e^{ih\nu} f(\nu) d\nu$  where  $f(\nu)$  is called the spectral density function of  $\{X_t\}$

If  $\sum_{h=-\infty}^{\infty} |\gamma(h)| < \infty$  then he spectral density eists and is given by  $f(\lambda) = \frac{1}{2\pi} \sum_{h=-\infty}^{\infty} \gamma(h) e^{-ih\lambda}$

Consider a  $WN(0, \sigma^2)$ , the acf is  $\gamma(h) = \begin{cases} \sigma^2 & h = 0 \\ 0 & h \neq 0 \end{cases}$

The spectral density function is  $f(\lambda) = \frac{1}{2\pi} \sigma^2$  for  $\lambda \in [-\pi, \pi]$

**Theorem 14 (4.4.1).** If  $\{Y_t\}$  is zero-mean complex valued stationary process with the spectral denisty  $F_Y(\cdot)$  and if  $\{X_t\}$  is defined by  $X_t = \sum_{j=-\infty}^{\infty} \psi_j Y_{t-j}$  where  $\sum_{j=-\infty}^{\infty} |\psi_j| < \infty$  then  $\{X_t\}$  is staitionary with acf  $\gamma_X(h) = \sum_{j,k=-\infty}^{\infty} \psi_j \overline{\psi_k} \gamma_Y(h-j+k)$  AAnd the spectral distribution:  $F_X(\lambda) = \int_{-\pi}^{\lambda} |\sum_{j=-\infty}^{\infty} \psi_j e^{-ij\nu}|^2 dF_Y(\nu)$

This a Radon-Nikodym derivative

*Proof.*

$$\begin{aligned}
\gamma_X(h) &= \sum_{j,k=-\infty}^{\infty} \psi_j \overline{\psi_k} \int_{-\pi}^{\pi} e^{i(h-j+k)\nu} dF_Y(\nu) \\
&= \int_{-\pi}^{\pi} e^{ih\nu} \left[ \sum_{j,k=-\infty}^{\infty} \psi_j e^{-ij\nu} \overline{\psi_k e^{-ik\nu}} \right] dF_Y(\nu) \\
&= \int_{-\pi}^{\pi} e^{ih\nu} \left| \sum_{j=-\infty}^{\infty} \psi_j e^{-ij\nu} \right|^2 dF_Y(\nu) \\
&= \int_{-\pi}^{\lambda} e^{ih\nu} dF_X(\nu) \quad \text{where } F_X(\lambda) = \int_{-\pi}^{\lambda} \left| \sum_{j=-\infty}^{\infty} \psi_j e^{-ij\nu} \right|^2 dF_Y(\nu)
\end{aligned}$$

□

**Theorem 15** ( 3.1.3). Consider ARMA( $p, q$ )  $\phi(B)X_t = \theta(B)Z_t$  If  $\phi(z) \neq 0$  for  $|z| = 1$  then there is a unique stationary solution given by  $X_t = \sum_{j=-\infty}^{\infty} \psi_j Z_{t-j}$  where  $\psi(z) = \frac{\theta(z)}{\phi(z)} = \sum_{j=-\infty}^{\infty} \psi_j z^j$  for  $|z| \leq 1$

note:

$$\phi(z) = (1 - .5z)(1 - 2z)$$

$$1/\phi(z) = 1/(1 - .5z) \cdot 1/(1 - 2z)$$

$$\frac{1}{1-2z} = \frac{1}{z} \cdot \frac{1}{\frac{1}{z}-2}$$

**Theorem 16** (4.4.2). Consider the ARMA( $p, q$ )  $\phi(B)X_t = \theta(B)Z_t$  Assume that  $\phi, \theta$  have no common zeros and that  $\phi(z) \neq 0$  for  $|z| = 1$  then  $\{X_t\}$  has a spectral density function given by

$$f_X(\lambda) = \frac{\sigma^2}{2\pi} \cdot \frac{|\theta(e^{-i\lambda})|^2}{|\phi(e^{-i\lambda})|^2} \quad \lambda \in [-\pi, \pi]$$

$$\text{since } dF_Z(\lambda) = \frac{\sigma^2}{2\pi} d\nu$$

*Proof.* Define  $U_t = \phi(B)X_t = \theta(B)Z_t$

$$f_U(\lambda) = |\theta(e^{-i\lambda})|^2 f_Z(\lambda) = \frac{\sigma^2}{2\pi} |\theta(e^{-i\lambda})|^2$$

$$\text{And thus } \implies f_X(\lambda) = \frac{\sigma^2}{2\pi} \cdot \frac{|\theta(e^{-i\lambda})|^2}{|\phi(e^{-i\lambda})|^2}$$

□

**Example.** AR(1) :  $X_t = \phi X_{t-1} + Z_t$  where  $|\phi| \neq 1$

$$f_X(\lambda) = \frac{\sigma^2}{2\pi} \cdot \frac{1}{|1-\phi e^{-i\lambda}|^2} = \frac{\sigma^2}{2\pi} \cdot \frac{1}{1-2\phi \cos(\lambda)+\phi^2}$$

Suppose  $|\phi| > 1$  We want to have  $(1 - \frac{1}{\phi}B)X_t = Z_t^*$  ?.

$$(1 - \frac{1}{\phi}B)(1 - \phi B)X_t = (1 - \frac{1}{\phi}B)Z_t$$

$$(1 - \frac{1}{\phi}B)X_t = \frac{(1 - \frac{1}{\phi}B)}{(1 - \phi B)}Z_t = Z_t^*$$

Thus by Theorem 4.4.2 the spectral density function is  $f_{Z^*}(\lambda) = \left| \frac{1 - \frac{1}{\phi}e^{-i\lambda}}{1 - \phi e^{-i\lambda}} \right|^2 \frac{\sigma^2}{2\pi}$ . We can verify that this is a constant by

$$|e^{i\lambda}e^{-i\lambda} - \frac{1}{\phi}e^{i\lambda}|^2 = |e^{i\lambda} - \frac{1}{\phi}|^2$$

$$= \frac{1}{\phi^2} |- \phi e^{-i\lambda} + 1|^2 \quad \text{Which cancels with the denominator}$$

Thus  $f_{Z^*}(\lambda) = \frac{\sigma^2}{2\pi\phi^2}$  for  $\lambda \in [-\pi, \pi]$   
IE  $Z_t^* \sim WN(0, \frac{\sigma^2}{\phi^2})$

**Example.**  $MA(1) : X_t = Z_t + \theta Z_{t-1}$  where  $Z_t \sim WN(0, \sigma^2)$ ,  $|\theta| > 1$

$$X_t = (1 + \theta B)Z_t = (1 + \frac{1}{\theta}B)Z_t^*$$

$$\implies Z_t^* = \frac{(1+\theta B)}{(1+\frac{1}{\theta}B)}Z_t$$

$$\text{Thus } Z_t^* \sim WN(0, \sigma^2\theta^2)$$

**Remark.** Suppose  $\{X_t\}$  is causal and invertible. Let  $\mathcal{H}_t = \overline{sp}\{X_t, X_{t-1}, \dots\}$ .

$$X_t - \mathcal{P}_{\mathcal{H}_{t-1}}X_t = Z_t$$

Since

Causality implies that  $\mathcal{H}_{t-1} \subset \overline{sp}\{Z_{t-1}, Z_{t-2}, \dots\} \implies Z_t \perp \mathcal{H}_{t-1}$

Invertability implies that  $Z_{t-1}, Z_{t-2}, \dots \in \mathcal{H}_{t-1}$

## 1.16 10/28/2025 Lecture 16

**Remark.** Suppose  $\phi(B)X_t = \theta(B)Z_t$   $\phi, \theta$  have no common zeros and  $\phi(z) \neq 0$  for  $|z| = 1$   
The spectral of  $X_t$  is given by  $f_X(\lambda) = \frac{\sigma^2}{2\pi} \cdot \frac{|\theta(e^{-i\lambda})|^2}{|\phi(e^{-i\lambda})|^2}$

**Example (AR(1) Spectral density).**  $X_t = \phi X_{t-1} + Z_t$  where  $|\phi| > 1$  then  $X_t = \frac{1}{\phi}X_{t-1} + Z_t^*$   
where  $Z_t^* \sim WN(0, \frac{\sigma^2}{\phi^2})$

$$\text{And } Z_t^* = \frac{(1 - \frac{1}{\phi}B)}{(1 - \phi B)}Z_t$$

**Example** (MA(1) Spectral density).  $X_t = Z_t + \theta Z_{t-1}$  where  $|\theta| > 1$  then  $X_t = (1 + \frac{1}{\theta}B)Z_t^*$  where  $Z_t^* \sim WN(0, \sigma^2 \theta^2)$   
 And  $Z_t^* = \frac{(1+\theta B)}{(1+\frac{1}{\theta}B)} Z_t$

**Definition.** Suppose  $\phi(B)X_t = \theta(B)Z_t$  is causal and invertable  $\mathcal{M}_t = \overline{sp}\{X_t, X_{t-1}, \dots\}$

The BLP  $\mathcal{P}_{\mathcal{M}_{t-1}}X_t$  what is  $X_t - \mathcal{P}_{\mathcal{M}_{t-1}}X_t$ ?

Causal -  $Z_t \perp M_{t-1}$

Invertable -  $Z_{t-1}, Z_{t-2}, \dots \in \mathcal{M}_{t-1}$

Thus  $X_t - \mathcal{P}_{\mathcal{M}_{t-1}}X_t = Z_t$  Consequently  $\|X_t - \mathcal{P}_{\mathcal{M}_{t-1}}X_t\|^2 = E[|Z_t|^2] = \sigma^2$

Thus for AR(1) with  $|\phi| > 1$ , the BLP error variance is  $\sigma^2/\phi^2$

For MA(1) with  $|\theta| > 1$ , the BLP error variance is  $\sigma^2\theta^2$

**Remark.** How do you make an ARMA that is not causal or invertable into one that is?

More generally write  $\phi(z) = \prod_{j=1}^m (1 - a_j^{-1}z)$  where  $|a_j| > 1$  for  $1 < j < r$  and  $|a_j| < 1$  for  $r+1 < j < m$

$$(1 - a_1^{-1}z)(1 - a_2^{-1}z) \dots (1 - a_r^{-1}z)(1 - a_{r+1}^{-1}z) \dots (1 - a_m^{-1}z)$$

The left part is the  $(1 - a_{r+1}^{-1}z)/(1 - a_{r+1}^{-1})z$

$$\frac{1 - \overline{a_{r+1}}B}{1 + a_{r+1}^{-1}B} \phi(B)X_t = \frac{1 - \overline{a_{r+1}}B}{1 - a_{r+1}^{-1}B} \theta(B)Z_t$$

$a_{r+1} = ce^{i\theta}$  for  $c < 1$

Can verify that  $\frac{1 - \overline{a_{r+1}}B}{1 - a_{r+1}^{-1}B} Z_t \sim WN(0, |\overline{a_{r+1}}|^2 \sigma^2)$  Then do the same thing for every  $r+1 \leq j \leq m$  ie replace  $a_{r+1}$  with something that makes it causal and invertable

Thus

$$\hat{\phi}(z) = \frac{j=r+1}{p} \frac{1 - \overline{a_j}B}{1 - a_j^{-1}B} \phi(z)$$

Thus

$$Z_t^* = \prod_{j=r+1}^p \frac{1 - \overline{a_j}B}{1 - a_j^{-1}B} Z_t \sim WN(0, \sigma^2 \prod_{j=r+1}^p |a_j|^2)$$

Also

$$\theta(z) = \prod_{j=1}^q (1 - b_j^{-1}z) \text{ where } |b_j| > 1 \text{ for } 1 \leq j \leq s \text{ and } |b_j| < 1 \text{ for } s+1 \leq j \leq q$$

Then

$$\hat{\theta}(z) = \prod_{j=s+1}^q \frac{1 - \bar{b}_j B}{1 - b_j^{-1} B} \theta(z)$$

More Generally  $\phi(B)X_t = \theta(B)Z_t$  When converted

$$\text{Var}(Z_t^*) = \sigma^2 \frac{\prod_{j=r+1}^p |a_j|^2}{\prod_{j=s+1}^q |b_j|^2}$$

This is a theorem in the Book.

Whenever there is a root that is bad, we can flip it by taking the conjugate reciprocal and adjusting the variance accordingly.

**Proposition 8** (4.4.1). Assume ARMA as usual. and  $\theta(z) \neq 0$  for  $|z| < 1$  then  $Z_t \in \overline{\text{sp}}\{X_t, X_{t-1}, \dots\}$

*Proof.* First: Factorize  $\theta(z) = \theta^+(z)\theta^*(z)$  where  $\theta^+(z) = \prod_{j=1}^s (1 - b_j^{-1}z)$  with  $|b_j| > 1$  and  $\theta^*(z) = \prod_{j=s+1}^q (1 - b_j^{-1}z)$  with  $|b_j| = 1$

Define  $Y_t = \theta^*(B)Z_t$  then  $\phi(B)X_t = \theta^+(B)Y_t$

Using the earlier proof on invertability,  $\implies Y_t \in \overline{\text{sp}}\{X_t, X_{t-1}, \dots\}$

So it suffices to show that  $Z_t \in \overline{\text{sp}}\{Y_t, Y_{t-1}, \dots\}$

Define  $U_t = Y_t - \mathcal{P}_{\overline{\text{sp}}\{Y_k, k \leq t-1\}} T_t$

Then by Prop 3.2.1:

$$\begin{aligned} Y_t &= U_t + \alpha_1 U_{t-1} + \alpha_2 U_{t-2} + \dots + \alpha_{q-s} U_{t-(q-s)} \\ \implies f_Y(\lambda) &= \frac{\sigma^2}{2\pi} |\alpha(e^{-i\lambda})|^2 = \frac{\sigma^2}{2\pi} |\theta^*(e^{-i\lambda})|^2 \end{aligned}$$

Both  $\alpha(z)$  and  $\theta^*(z)$  are real polynomials of the same degree  $q - s$

Factoring  $\alpha(z) = \prod_{j=1}^{q-s} (1 - c_j^{-1}z)$  And  $\theta^*(z) = \prod_{j=s+1}^q (1 - b_j^{-1}z)$

We see that they must have the same roots ie  $\{c_j\} = \{b_j\}$  as multisets

And they are the same everywhere

Thus  $\alpha(z) = \theta^*(z)$

Then using this we can show that  $Z_t = U_t$

□

## 1.17 10/30/2025 Lecture 17

**Proposition 9** (4.4.1 cont). Consider the ARMA( $p, q$ )  $\phi(B)X_t = \theta(B)Z_t$  where  $\theta(z) \neq 0$  for  $|z| < 1$

Then  $Z_t \in \overline{\text{sp}}\{X_t, X_{t-1}, \dots\}$

*Proof.* WLOG: assume  $\theta(z) \neq 0$  for  $|z| \neq 1$

Define  $Y_t = \theta(B)Z_t$  then  $\phi(B)X_t = Y_t$

$$\implies \overline{sp}\{Y_t, k \leq t\} \subset \overline{sp}\{X_t, k \leq t\}$$

So it suffices to show that  $Z_t \in \overline{sp}\{Y_t, Y_{t-1}, \dots\}$

Define  $U_t = Y_t - \mathcal{P}_{\overline{sp}\{Y_k, k \leq t-1\}}Y_t$

Then by Prop 3.2.1:

$$\begin{aligned} Y_t &= U_t + \alpha_1 U_{t-1} + \alpha_2 U_{t-2} + \dots + \alpha_q U_{t-q} \\ \implies f_Y(\lambda) &= \frac{\sigma^2}{2\pi} |\alpha(e^{-i\lambda})|^2 = \frac{\sigma^2}{2\pi} |\theta(e^{-i\lambda})|^2 \end{aligned}$$

Both  $\alpha(z)$  and  $\theta(z)$  are real polynomials of the same degree  $q$

And they have the same roots ie  $\{c_j\} = \{b_j\}$  as multisets

And they are the same everywhere

Thus  $\alpha(z) = \theta(z)$

And  $\sigma^2 = \sigma_n^2$

$\implies$  that  $(U_t, Y_t, Y_{t-1}, \dots, Y_{t-q})$  and  $(Z_t, Y_t, Y_{t-1}, \dots, Y_{t-q})$  have the same covariance matrix

$\implies \mathcal{P}_{\overline{sp}\{Y_k, k \leq t-1\}}U_t = \mathcal{P}_{\overline{sp}\{Y_k, k \leq t-1\}}Z_t$

$\implies U_t = \lim_{n \rightarrow \infty} \mathcal{P}_{\overline{sp}\{Y_t, Y_{t-1}, \dots, Y_{t-n}\}}U_t = \lim_{n \rightarrow \infty} \mathcal{P}_{\overline{sp}\{Y_t, Y_{t-1}, \dots, Y_{t-n}\}}Z_t$

Bescuase  $\sigma_n^2 = \sigma^2$  it holds that  $Z_t = U_t$

If you show that two projections are equal with the same variance then the two random variables are equal.  $\square$

**Proposition 10** (4.4.3). Assume the ARMA( $p, q$ )  $\phi(B)X_t = \theta(B)Z_t$  where  $\phi(z) \neq 0$  for  $|z| < 1$

If  $\theta(z) = 0$  for some  $|z| \leq 1$  then  $Z_t \notin \overline{sp}\{X_t, X_{t-1}, \dots\}$

**Definition** (Wold Decomposition). **Aside:** Crimea-Wold Device to prove the multivariate CLT

**Setup:**  $X_t, t \in \mathbb{Z}$  is a zero-mean stationary process.

Define  $\mathcal{M}_n = \overline{sp}\{X_t, t \leq n\}$ ,  $\mathcal{M} = \overline{\bigcup_{n \in \mathbb{Z}} \mathcal{M}_n} = \overline{sp}\{X_t, t \in \mathbb{Z}\}$

Define  $\mathcal{M}_{-\infty} = \bigcap_{n \in \mathbb{Z}} \mathcal{M}_n$

Look into Durrett and Billinsley

**Definition** (Mean Squared Error).  $\sigma^2 = E[X_{n+1}^2 - \mathcal{P}_{\mathcal{M}_n}X_{n+1}]$  is the mean squared error of the BLP of  $X_{n+1}$  based on  $\mathcal{M}_n$

AKA the one step ahead prediction error variance

**Definition** (Determinisitic Process). A stationary process  $\{X_t\}$  is deterministic if  $\sigma^2 = 0$  ie  $X_{n+1} \in \mathcal{M}_n$  for all  $n \in \mathbb{Z}$

ie  $X_{n+1}$  can be perfectly predicted based on the infinite past  $\{X_n, X_{n-1}, \dots\}$

Note that for all Process  $\sum_{j=1}^n A_j e^{-i\lambda_j t}$  is deterministic for  $A_j$  uncorrelated mean zero random variables

**Theorem 17** (3.7.1 Wold Decomposition Theorem). If  $\sigma^2 > 0$  then  $X_t$  can be expressed as  $X_t = \sum_{j=0}^{\infty} \psi_j Z_{t-j} + V_t$  where

1.  $\psi_0 = 1, \sum_{j=0}^{\infty} |\psi_j|^2 < \infty$
2.  $Z_t \sim WN(0, \sigma^2)$
3.  $Z_t \in \mathcal{M}_t, \forall t \in \mathbb{Z}$
4.  $E[Z_t V_s] = 0, \forall t, s \in \mathbb{Z}$
5.  $V_t \in \mathcal{M}_{-\infty}, \forall t \in \mathbb{Z}$
6.  $V_t$  is deterministic stationary process

*Proof.* Define  $Z_t = X_t - \mathcal{P}_{\mathcal{M}_{t-1}} X_t$  Thus the  $Z_t \sim WN(0, \sigma^2)$  and  $Z_t \in \mathcal{M}_t$  which gives us number 2 and 3

Project  $X_t$  onto  $\overline{sp}\{Z_t, Z_{t-1}, \dots, Z_{t-n}\}$

$$\mathcal{P}_{\overline{sp}\{Z_t, Z_{t-1}, \dots, Z_{t-n}\}} X_t =: \sum_{j=0}^n \psi_j Z_{t-j}$$

Where  $\psi_j = \frac{\langle X_t, Z_{t-j} \rangle}{\langle Z_{t-j}, Z_{t-j} \rangle}$

In particular  $\psi_0 = 1$  thus We get number 1

Define  $V_t = X_t - \lim_{n \rightarrow \infty} \mathcal{P}_{\overline{sp}\{Z_t, Z_{t-1}, \dots, Z_{t-n}\}} X_t, V_t \in \mathcal{M}_t$

Then  $E[Z_s V_t] = 0$  for all  $s, t \in \mathbb{Z}$  which gives us number 4

□

## 1.18 11/04/2025 Lecture 18

**Remark** (Wold Decomposition). Recall the Linear Past:

$$\begin{aligned} \mathcal{M}_n &= \overline{sp}\{X_t, t \leq n\} \\ \mathcal{M} &= \overline{\bigcup_{n \in \mathbb{Z}} \mathcal{M}_n} = \overline{sp}\{X_t, t \in \mathbb{Z}\} \\ \mathcal{M}_{-\infty} &= \bigcap_{n \in \mathbb{Z}} \mathcal{M}_n \end{aligned}$$

$\sigma^2 = E[X_{n+1} - \mathcal{P}_{\mathcal{M}_n} X_{n+1}]$  is the one step ahead prediction error variance

**Definition** (Deterministic). A stationary process  $\{X_t\}$  is deterministic if  $\sigma^2 = 0$

**Theorem 18** (5.7.1 Wold Decomposition Theorem). If  $\sigma^2 > 0$  then  $X_t$  can be expressed as  $X_t = \sum_{j=0}^{\infty} \psi_j Z_{t-j} + V_t$  where

1.  $\psi_0 = 1, \sum_{j=0}^{\infty} |\psi_j|^2 < \infty$
2.  $Z_t \sim WN(0, \sigma^2)$
3.  $Z_t \in \mathcal{M}_t, \forall t \in \mathbb{Z}$
4.  $E[Z_t V_s] = 0, \forall t, s \in \mathbb{Z}$
5.  $V_t \in \mathcal{M}_{-\infty}, \forall t \in \mathbb{Z}$
6.  $V_t$  is deterministic stationary process

The sequences  $\{\psi_j\}$ ,  $\{Z_t\}$  and  $\{V_t\}$  are uniquely determined by the assumptions above.

*Proof.*  $Z_t = X_t - \mathcal{P}_{\mathcal{M}_{t-1}} X_t$

$$\psi_j = \frac{\langle X_t, Z_{t-j} \rangle}{\langle Z_{t-j}, Z_{t-j} \rangle} V_t = X_t - \sum_{j=0}^{\infty} \psi_j Z_{t-j}$$

$$\mathcal{M}_t = \mathcal{M}_{t-1} \oplus \overline{sp}\{Z_t\}, V_t \perp Z_t \implies V_t \in \mathcal{M}_{t-1}$$

$$\mathcal{M}_t = \mathcal{M}_{t-2} \oplus \overline{sp}\{Z_{t-1}, Z_t\}, V_t \perp Z_{t-1}, Z_t \implies V_t \in \mathcal{M}_{t-2}$$

Continuing this way we get  $V_t \in \mathcal{M}_{t-k}$  for all  $k \geq 0$  thus  $V_t \in \mathcal{M}_{-\infty}$

This shows properties 5.

Let  $\mathcal{M}_t^V = \overline{sp}\{V_t, V_{t-1}, \dots\}$

Need to show that  $V_t \in \mathcal{M}_{t-1}^V$  and thus will show that  $V_t \in \mathcal{M}_{-\infty}^V$

it suffices to show that  $\mathcal{M}_{-\infty}^V = \mathcal{M}_{-\infty}$

We know  $V_t \in \mathcal{M}_t \implies \mathcal{M}_t^V \subset \mathcal{M}_t \implies \mathcal{M}_{-\infty}^V \subset \mathcal{M}_{-\infty}$

Now we show the reverse inclusion.

$$\mathcal{M}_t = \overline{sp}\{Z_k, V_k, k \leq t\} = \overline{sp}\{Z_k, k \leq t\} \oplus \mathcal{M}_t^V$$

$$\mathcal{M}_{t-k} \perp \overline{sp}\{Z_t, \dots, Z_{t-k}\}$$

$$\implies \mathcal{M}_{-\infty} \perp \overline{sp}\{Z_t, Z_{t-1}, \dots\} \implies \mathcal{M}_{-\infty} \subset \mathcal{M}_t^V$$

Thus  $\mathcal{M}_{-\infty} \subset \mathcal{M}_{-\infty}^V$

□

*Proof of Uniqueness.* If  $X_t = \sum_{j=0}^{\infty} \eta_j W_{t-j} + G_t$  with the same properties as above.

(5) implies that  $E[G_t] \in \mathcal{M}_{-\infty}$

(3) implies that  $W_{t-1}, W_{t-2}, \dots \in \mathcal{M}_{t-1}$

$$X_t = W_t + \sum_{j=1}^{\infty} \eta_j W_{t-j} + G_t \in \mathcal{M}_{t-1}$$

And  $W_t \perp X_{t-k}$  for any  $k \geq 1$

Thus  $W_t = X_t - \mathcal{P}_{\mathcal{M}_{t-1}} X_t = Z_t$

□

**Theorem 19** (Kolmogorov or Doob). Let  $\{Y_{1t}\}$  and  $\{Y_{2t}\}$  be two zero-mean mutually orthogonal stationary processes and let  $X_t = Y_{1t} + Y_{2t}$ . Suppose  $F_1$  and  $F_2$  are the spectral distribution functions of  $\{Y_{1t}\}$  and  $\{Y_{2t}\}$  respectively.

Then  $\{Y_{1t}, Y_{2t}, t \in \mathbb{Z}\} \subset \mathcal{M}^X := \overline{\text{sp}}\{X_k, k \in \mathbb{Z}\}$

IFF

$F_1$  and  $F_2$  are mutually singular ie  $F_1$  corresponds to a measure that is on the space  $m_1$  and  $F_2$  corresponds to a measure that is on the space  $m_2$ . If there exists a measurable set  $A \subset (-\pi, \pi]$  such that,  $m_1(A^c) = 0$  and  $m_2(A) = 0$  then  $F_1$  and  $F_2$  are mutually singular.

**Theorem 20** (Rudin). IF  $\{c_n, n \leq 0\}$  are s.t.  $0 < \sum_{n=-\infty}^0 |c_n|^2 < \infty$  then  $\sum_{n=-\infty}^0 c_n e^{in\lambda} \in L^2(-\pi, \pi) := \{g : (-\pi, \pi] \rightarrow \mathbb{C} \mid \int_{-\pi}^{\pi} |g(\lambda)|^2 d\lambda < \infty\}$   
and  $\int_{-\pi}^{\pi} \log|ce^{i\theta}| d\theta > -\infty$

**Remark** (Back to Wold).  $\sigma^2 > 0$  let  $\psi(e^{-i\lambda}) = \sum_{n=0}^{\infty} \psi_j e^{-in\lambda}$

By Theorem Rudin  $\int_{-\pi}^{\pi} \log|\psi(e^{-i\lambda})| d\lambda > -\infty \implies \psi(e^{-i\lambda})$  is non-zero almost everywhere on  $(-\pi, \pi]$ . Let  $U_t = \sum_{j=0}^{\infty} \psi_j Z_{t-j}$  then  $U_t$  and  $V_t$  (deterministic part) are orthogonal.

Let  $f_U(\lambda)$  and  $f_V(\lambda)$  be the spectral density functions of  $U_t$  and  $V_t$  respectively.

Then  $f_X(\lambda) = f_U(\lambda) + f_V(\lambda)$  and  $f_U(\lambda)$  and  $f_V(\lambda)$  are mutually singular.

Can show that  $\frac{\sigma^2}{2\pi} |\psi(e^{-i\lambda})|^2$  is the spectral density function of  $U_t$

$\implies F_u$  is absolutely continuous almost everywhere with non-zero, non-negative density function.

$F_v$  is singular with respect to  $F_u$  and singular to the Lebesgue measure.

IE  $\exists$  a set  $A$  with Lebesgue measure 0 such that  $F_v(A^c) = 0$

## 1.19 11/06/2025 Lecture 19

**Theorem 21** (5.6.1 Wold Decomposition). If  $\sigma^2 > 0$  then  $X_t$  can be expressed as  $X_t = \sum_{j=0}^{\infty} \psi_j Z_{t-j} + V_t$  where

1.  $\psi_0 = 1, \sum_{j=0}^{\infty} |\psi_j|^2 < \infty$
2.  $Z_t \sim WN(0, \sigma^2)$
3.  $Z_t \in \mathcal{M}_t, \forall t \in \mathbb{Z}$
4.  $E[Z_t V_s] = 0, \forall t, s \in \mathbb{Z}$
5.  $V_t \in \mathcal{M}_{-\infty}, \forall t \in \mathbb{Z}$
6.  $V_t$  is deterministic stationary process

The sequences  $\{\psi_j\}$ ,  $\{Z_t\}$  and  $\{V_t\}$  are uniquely determined by the assumptions above.

**Remark.** 1. The spectral density function of  $U_t = \sum_{j=0}^{\infty} \psi_j Z_{t-j}$  is absolutely continuous wrt the Lebesgue measure ie  $F_U(\lambda) = \int_{-\pi}^{\lambda} f_U(\nu) d\nu$  and we know it is given by  $f_U(\lambda) = \frac{\sigma^2}{2\pi} |\psi(e^{-i\lambda})|^2$  where  $\psi(e^{-i\lambda}) = \sum_{j=0}^{\infty} \psi_j e^{-ij\lambda}$ . Furthermore  $\psi(e^{-i\lambda}) \neq 0$  almost everywhere on  $(-\pi, \pi]$ .

2.  $F_U$  and  $F_V$  are mutually singular ie  $\exists$  a set  $A$  with Lebesgue measure 0 such that  $F_V(A^c) = 0$  and  $F_U(A) = 0$

3.  $F_X = F_U + F_V$  is the Lebesgue decomposition of  $F_X$  wrt the Lebesgue measure.

Let  $F_X$  be the spectral distribution function of  $X_t$ . Let  $f_X(\theta)$  be its derivative, then we can write  $F_X(\lambda) = \int_{-\pi}^{\lambda} f_X(\theta)d\theta + F_s(\lambda)F_c(\lambda) + F_s(\lambda)$  where  $F_s$  is also a distribution functions

1.  $f_x(\theta) = 0$  on a set of positive measure

2.  $f_x(\theta) > 0$  almost everywhere  $\int_{-\pi}^{\pi} \log f_X(\theta)d\theta = -\infty$

3.  $f_x(\theta) > 0$  almost everywhere  $\int_{-\pi}^{\pi} \log f_X(\theta)d\theta > -\infty$

**Theorem 22** (Kolmogorov Formula).  $\sigma^2 > 0$  iff  $\int_{-\pi}^{\pi} \log f_X(\lambda)d\lambda > -\infty$

and  $\sigma^2 = 2\pi \exp\left(\frac{1}{2\pi} \int_{-\pi}^{\pi} \log f_X(\lambda)d\lambda\right)$

**Example.**

$$(1 - 0.5B)X_t = (1 + 0.3B)Z_t \quad Z_t \sim WN(0, 1)$$

$$f_x(\theta) = \frac{\sigma^2}{2\pi} \cdot \frac{|1+0.3e^{-i\theta}|^2}{|1-0.5e^{-i\theta}|^2}$$

$$\begin{aligned} \log(f_x(\theta)) &= \log\left(\frac{\sigma^2}{2\pi}\right) + 2\log|1 + 0.3e^{-i\theta}| - 2\log|1 - 0.5e^{-i\theta}| \\ &\implies \int_{-\pi}^{\pi} \log(f_x(\theta))d\theta = 2\pi \log\left(\frac{\sigma^2}{2\pi}\right) \end{aligned}$$

**Remark.** Why? are we doing this.

$X_t = \sum_{j=1}^n A_j e^{i\lambda_j t}$  where  $A_j$  are uncorrelated mean zero random variables.

**Remark** (Infrence For ARMA Models). Not only we do we have coefficients  $\phi$  and  $\theta$  to estimate but we also have to determine the order of the model  $p$  and  $q$ .

Suppose we get data for ARMA(p,q):  $\phi(B)(X_t - \mu) = \theta(B)Z_t$  where  $Z_t \sim WN(0, \sigma^2)$

Assume  $p, q$  are known.

We estimate mean  $\mu$ , by  $\hat{\mu} = \bar{X}_n = \frac{1}{n} \sum_{t=1}^n X_t$

Suppose  $\{X_1 \dots X_n\}$  is a realization of a sp.

$$\begin{aligned} \hat{\mu} &= \bar{X}_n = \frac{1}{n} \sum_{t=1}^n X_t \\ \bar{X}_n &\xrightarrow{a.s.} E[X_0 | \mathcal{M}_{-\infty}] \text{ as } n \rightarrow \infty \end{aligned}$$

When  $\bar{X} \xrightarrow{a.s.} \mu$  then we call the process ergodic in the mean.

1. IID sequence with finite mean is ergodic
2. Suppose  $Z_t$  iid
3.  $X_t := g(Z_t, Z_{t-1}, \dots)$  and  $g$  is measurable and  $E[|X_t|] < \infty$  then  $X_t$  is ergodic.

## 1.20 11/11/2025 Lecture 20

**Remark** (Infrence for ARMA models). We need to look at Strictly stationary processes  
Suppose  $\{X_t\}$  is strictly stationary process with mean  $\mu$  and autocovariance function  $\gamma_X(h)$   
If  $\{X_t\}$  is ergoic then  $\bar{X}_n := \frac{1}{n} \sum_{t=1}^n X_t \xrightarrow{a.s.} \mu$  as  $n \rightarrow \infty$

This can be thought of as the time average converging to the space average.

IF  $\{Z_t\}$  is IID then it is ergodic.

If  $X_t = g(Z_t, Z_{t-1}, \dots)$  then  $X_t$  is ergodic and strictly stationary.

For the causal and invertable ARMA(p,q)  $\phi(B)(X_t - \mu) = \theta(B)Z_t$  where  $Z_t \sim WN(0, \sigma^2)$

Then  $X_t = \mu + \sum_{j=0}^{\infty} \psi_j Z_{t-j}$ , so it is strictly stationary and ergodic.

In particular  $\bar{X}_n \xrightarrow{a.s.} \mu$  as  $n \rightarrow \infty$

Sample Autocovariance Function:

$$\begin{aligned}\hat{\gamma}(h) &= \frac{1}{n} \sum_{t=h+1}^n (X_t - \bar{X}_n)(X_{t-h} - \bar{X}_n) \quad h \geq 0 \\ &= \frac{1}{n} \sum_{t=h+1}^n X_t X_{t-h} - \frac{n-h}{n} \bar{X}_n^2 - \bar{X}_n \cdot \frac{1}{n} \sum_{t=h+1}^n (X_t + X_{t-h}) \\ &= \frac{1}{n} \sum_{t=h+1}^n X_t X_{t-h} - \mu^2 - 2\mu^2 \quad \text{Note that } X_t X_{t-h} \text{ is ergodic}\end{aligned}$$

Therefore  $\frac{1}{n} \sum_{t=h+1}^n X_t X_{t-h} \xrightarrow{a.s.} E[X_t X_{t-h}] = \gamma(h) + \mu^2$

Thus  $\hat{\gamma}(h) \xrightarrow{a.s.} \gamma(h)$  as  $n \rightarrow \infty$

$$\begin{aligned}X_n &= \frac{1}{n}(X_1 + X_2 + \dots + X_n) \\ \text{If IID} \quad \sqrt{n}(\bar{X}_n - \mu) &\xrightarrow{d} N(0, \gamma_X(0)) \\ \text{Var}(\bar{X}_n) &= \frac{1}{n} \gamma_X(0) \text{Var}(n\bar{X}_n) = n\gamma_X(0) + 2 \sum_{h=1}^{n-1} \left(1 - \frac{h}{n}\right) \gamma_X(h) \\ \text{Var}(\sqrt{n}(\bar{X}_n - \mu)) &= \sum_{-\infty}^{\infty} \gamma_X(h) \text{ if converges}\end{aligned}$$

CLT for  $\bar{X}_n$ :

$$\sqrt{n}(\bar{X}_n - \mu) \xrightarrow{d} N\left(0, \tau^2 := \sum_{h=-\infty}^{\infty} \gamma_X(h)\right)$$

IF  $X_t = \mu + \sum_{j=0}^{\infty} \psi_j Z_{t-j}$  where  $Z_t \sim IID(0, \sigma^2)$  and  $\sum_{j=0}^{\infty} |\psi_j| < \infty$  then the CLT holds and the spectral density function is of the form:

$$f_X(\lambda) = \frac{\sigma^2}{2\pi} \sum_{h=-\infty}^{\infty} \gamma_X(h) e^{-ih\lambda}$$

$$f_X(0) = \frac{\sigma^2}{2\pi} \left( \sum_{j=0}^{\infty} \psi_j \right)^2 = \frac{1}{2\pi} \sum_{h=-\infty}^{\infty} \gamma_X(h)$$

$$\tau^2 := \sum_{h=-\infty}^{\infty} \gamma_X(h) = 2\pi f_X(0)$$

For  $\hat{\gamma}_X(h)$  we need to have  $E[X_t^4] < \infty$ . and for  $\hat{\rho}_X(h)$  we need  $E[X_t^2] < \infty$   
Book has information of these CLTs

In particular of  $\{X_t\}$  is IID then

$$\sqrt{n} \begin{bmatrix} \hat{\rho}(1) \\ \hat{\rho}(2) \\ \vdots \\ \hat{\rho}(m) \end{bmatrix} \xrightarrow{d} N(0, I_m)$$

**Remark.**  $X_t = \phi_0 + \phi_1 X_{t-1} + \dots + \phi_p X_{t-p} + Z_t + \theta_1 Z_{t-1} + \dots + \theta_q Z_{t-q}$   
where  $Z_t \sim IID(0, \sigma^2)$

$\phi_p \neq 0, \theta_q \neq 0$

$\phi(z)\theta(z) \neq 0$  for  $|z| = 1$

$$\mu = \frac{\phi_0}{1 - \phi_1 - \dots - \phi_p}$$

Center the data:  $X_t = X_t - \bar{X}_t$  and fit the model  $\phi(B)X_t = \theta(B)Z_t$

Parameter Space: Let  $\beta = (\phi_1, \dots, \phi_p, \theta_1, \dots, \theta_q) \in \mathbb{R}^{p+q}$

$\mathbb{C} = \{\beta \in \mathbb{R}^{p+q} | \phi(z) \neq 0, \theta(z) \neq 0 \text{ for } |z| \leq 1\}$

Consider AR(p):  $X_t = \phi_1 X_{t-1} + \dots + \phi_p X_{t-p} + Z_t$

$$X_{p+1} = \phi_1 X_p + \dots + \phi_p X_1 + Z_{p+1}$$

$$X_{p+2} = \phi_1 X_{p+1} + \dots + \phi_p X_2 + Z_{p+2}$$

$$\vdots$$

$$X_n = \phi_1 X_{n-1} + \dots + \phi_p X_{n-p} + Z_n$$

Now we can do least squares to estimate  $\phi_1, \dots, \phi_p$

$$\begin{bmatrix} X_{p+1} \\ X_{p+2} \\ \vdots \\ X_n \end{bmatrix} = \begin{bmatrix} X_p & X_{p-1} & \dots & X_1 \\ X_{p+1} & X_p & \dots & X_2 \\ \vdots & \vdots & \ddots & \vdots \\ X_{n-1} & X_{n-2} & \dots & X_{n-p} \end{bmatrix} \begin{bmatrix} \phi_1 \\ \phi_2 \\ \vdots \\ \phi_p \end{bmatrix} + \begin{bmatrix} Z_{p+1} \\ Z_{p+2} \\ \vdots \\ Z_n \end{bmatrix}$$

LSE of  $\phi = (\phi_1, \dots, \phi_p)$  is given by:

$$\hat{\phi}_{LSE} = (X^T X)^{-1} X^T Y$$

Where  $X$  is the design matrix and  $Y$  is the response vector.

**Remark** (Yule Walker Estimator). Also consider the Yule-Walker Estimator for AR(p)

$$\begin{aligned} \gamma(1) &= \phi_1\gamma(0) + \phi_2\gamma(-1) + \dots + \phi_p\gamma((p-1)) \\ \gamma(2) &= \phi_1\gamma(1) + \phi_2\gamma(0) + \dots + \phi_p\gamma((p-2)) \\ &\vdots \\ \gamma(p) &= \phi_1\gamma(p-1) + \phi_2\gamma(p-2) + \dots + \phi_p\gamma(0) \end{aligned}$$

$$\begin{aligned} \hat{\Gamma}_p \phi &= \hat{\gamma}_p \\ \hat{\phi}_{YW} &= \hat{\Gamma}_p^{-1} \hat{\gamma}_p \end{aligned}$$

## 1.21 11/13/2025 Lecture 21

**Remark.**  $\phi(B)X_t = \theta(B)Z_t$  where  $Z_t \sim IID(0, \sigma^2)$

$$\beta = (\phi_1, \dots, \phi_p, \theta_1, \dots, \theta_q) \in \mathbb{R}^{p+q}$$

$$\mathbb{C} = \{\beta \in \mathbb{R}^{p+q} | \phi(z) \neq 0, \theta(z) \neq 0 \text{ for } |z| \leq 1\}$$

$$\text{Consider AR}(p): X_t = \phi_1 X_{t-1} + \dots + \phi_p X_{t-p} + Z_t$$

Yule Walker Estimator:

$$\hat{\phi}_{YW} = \hat{\Gamma}_p^{-1} \hat{\gamma}_p$$

Where  $\hat{\Gamma}_p = [\hat{\gamma}(i-j)]_{i,j=1}^p$  and  $\hat{\gamma}_p = [\hat{\gamma}(1), \dots, \hat{\gamma}(p)]^T$   
LSE Estimator:

$$\hat{\phi}_{LSE} = (X^T X)^{-1} X^T Y$$

Where  $X$  is the design matrix and  $Y$  is the response vector.

Define  $Y = [X_{p+1}, X_{p+2}, \dots, X_n]^T$  and  $X$  is the matrix with rows  $[X_{t-1}, X_{t-2}, \dots, X_{t-p}]$  for

$$t = p + 1, \dots, n$$

Let  $Y^*$  and  $X^*$  be the time starting at 0 values.

$$\phi^* = (X^{*T} X^*)^{-1} X^{*T} Y^*$$

$$\text{Then } \hat{\phi}_{LSE} - \phi = \phi^* - \phi + o_p(1/\sqrt{n})$$

$$\text{Note: } \frac{1}{n} X^{*T} X^* \xrightarrow{a.s.} \Gamma_p \text{ as } n \rightarrow \infty$$

$$\implies (\frac{1}{n} X^{*T} X^*)^{-1} \xrightarrow{a.s.} \Gamma_p^{-1} \text{ as } n \rightarrow \infty$$

**Proposition 11.** IF  $\{X_t\}$  is a causal AR( $p$ ) with  $Z_T \sim IID(0, \sigma^2)$  then

$$\sqrt{n}(\phi^* - \phi) \xrightarrow{d} N(0, \sigma^2 \Gamma_p^{-1}) \text{ as } n \rightarrow \infty$$

This also does not depend on  $\sigma^2$

*Proof.*

$$\begin{aligned} \phi^* &= (X^{*T} X^*)^{-1} X^{*T} Y^* \\ &= (X^{*T} X^*)^{-1} (X^{*T} X^* \phi + X^{*T} Z) \\ &= \phi + (X^{*T} X^*)^{-1} X^{*T} Z \\ \implies \phi^* - \phi &= (\frac{1}{n} X^{*T} X^*)^{-1} \cdot \frac{1}{\sqrt{n}} X^{*T} Z \cdot \frac{1}{\sqrt{n}} \\ \sqrt{n}(\phi^* - \phi) &= (\frac{1}{n} X^{*T} X^*)^{-1} \cdot \frac{1}{\sqrt{n}} X^{*T} Z \end{aligned}$$

Will do CLT on  $\frac{1}{\sqrt{n}} X^{*T} Z$

Will apply Slutsky's Theorem

$$X^{*T} Z = \sum_{t=1}^n Z_t \begin{bmatrix} X_{t-1} \\ X_{t-2} \\ \vdots \\ X_{t-p} \end{bmatrix}$$

Let  $\mathcal{F}_t = \sigma(X_{1-p}, \dots, X_t)$

Then  $\mathcal{F}_t \subset \mathcal{F}_{t+1}$

$$\text{And } S_t := \sum_{k=1}^t Z_k \begin{bmatrix} X_{k-1} \\ X_{k-2} \\ \vdots \\ X_{k-p} \end{bmatrix} \in \mathcal{F}_t$$

Note that

$$\begin{aligned} E[S_t | \mathcal{F}_{t-1}] &= E[S_{t-1} + Z_t X_t | X_{1-p}, \dots, X_{t-1}] \\ &= S_{t-1} \end{aligned}$$

by the previous statements, this shows that  $\{S_t, \mathcal{F}_t\}$  is a martingale.

IE increasing sequence of sigma algebras and  $E[|S_t|] < \infty$  and  $E[S_t | \mathcal{F}_{t-1}] = S_{t-1}$

Apply Martingale CLT:

$$\begin{aligned} \frac{1}{n} \sum_{t=1}^n E[Z_t X_{t-i} X_{t-j} | \mathcal{F}_{t-1}] &= \frac{1}{n} \sum_{t=1}^n X_{t-i} X_{t-j} E[Z_t^2 | \mathcal{F}_{t-1}] \\ &= \sigma^2 \cdot \frac{1}{n} \sum_{t=1}^n X_{t-i} X_{t-j} \xrightarrow{a.s./p} \sigma^2 \gamma_X(i-j) \text{ as } n \rightarrow \infty \end{aligned}$$

Additionally, the Lindeburg condition holds since

$$\frac{1}{n} \sum_{t=1}^n E[Z_t^2 \|X_t\|^2 \cdot I(\|X_t\|^2 |Z_t|^2 > \epsilon n) | \mathcal{F}_{t-1}] \xrightarrow{a.s.} 0 \text{ as } n \rightarrow \infty$$

By the MCLT we have  $\frac{1}{\sqrt{n}} S_n \xrightarrow{d} N(0, \sigma^2 \Gamma_p)$  as  $n \rightarrow \infty$

By Slutsky's Theorem we have:

$$\sqrt{n}(\phi^* - \phi) = \left(\frac{1}{n} X^{*T} X^*\right)^{-1} \cdot \frac{1}{\sqrt{n}} X^{*T} Z \xrightarrow{d} N(0, \sigma^2 \Gamma_p^{-1}) \text{ as } n \rightarrow \infty$$

□

**Remark.** The LSE and Yule-Walker estimators are asymptotically equivalent ie

$$\sqrt{n}(\hat{\phi}_{LSE} - \hat{\phi}_{YW}) \xrightarrow{p} 0 \text{ as } n \rightarrow \infty$$

## 1.22 11/18/2025 Lecture 22

**Remark.** AR(p)  $\phi(B)X_t = Z_t$  where  $Z_t \sim IID(0, \sigma^2)$

Let  $\hat{\phi}$  be either the LSE or Yule-Walker estimator.

Then  $\sqrt{n}(\hat{\phi} - \phi) \xrightarrow{d} N(0, \sigma^2 \Gamma_p^{-1})$  as  $n \rightarrow \infty$

Remark: sure fits an AR(m) with  $m > p$  and get the estimator  $\hat{\phi}_m$

Then we can say that  $\hat{\phi}_m \xrightarrow{p} \phi_m$  as  $n \rightarrow \infty$ .

And  $\sqrt{n}(\hat{\phi}_m - \phi_m) \xrightarrow{d} N(0, \sigma^2 \Gamma_m^{-1})$  as  $n \rightarrow \infty$

If  $m > p$  then the  $(m, m)$  entry of  $\Gamma_m^{-1}$  is 1

**Remark (PACF).** For any stationary process  $\{X_t\}$  solve

$$\min_{c_1, \dots, c_p} E \left[ \left( X_t - \sum_{j=1}^p c_j X_{t-j} \right)^2 \right]$$

then  $\hat{C}_p$  is the lag-p partial autocorrelation coefficient ie the coefficient of  $X_{t-p}$  in the above minimization problem.

$$c^* = \Gamma_p^{-1} \gamma_p$$

Estimator  $\hat{\phi}_{p,p}$  is the last element of  $\hat{\Gamma}_p^{-1}\hat{\gamma}_p$

Now back to the AR(p) model if we fit AR(m) to the data then  $\hat{\phi}_{m,m}$  satisfy:  $\sqrt{n}\hat{\phi}_{m,m} \xrightarrow{d} N(0, 1)$  as  $n \rightarrow \infty$

I applied timer seireis: plot data, plot acf, plot pacf

**Remark.** ARMA(p,q):  $\phi(B)X_t = \theta(B)Z_t$  where  $Z_t \sim IID(0, \sigma^2)$

$$\begin{aligned} \mathbb{C} = \{ \beta = (\phi_1, \dots, \phi_p, \theta_1, \dots, \theta_q) : \\ \phi(z)\theta(z) \neq 0 \text{ for } |z| \leq 1; \\ \phi(z)\theta(z) \neq 0 \text{ for } |z| \leq 1; \\ \phi_p\theta_q \neq 0; \\ \phi(z) \text{ and } \theta(z) \text{ have no common zeros} \} \end{aligned}$$

We cannot use LSE or Yule-Walker to estimate parameters.

Instead we use Maximum Likelihood Estimation (MLE) with the prior that  $Z_t \sim N(0, \sigma^2)$   
Then  $X_t$  is a Gaussian process.

We can also consider the Quasi-Maximum Likelihood Estimation (QMLE) where we still use the Gaussian likelihood even if  $Z_t$  is not Gaussian.

**Definition** (Gaussian likelihood). Let  $\Gamma_n(\beta)$  be the  $n \times n$  autocovariance matrix of  $\mathbf{X}_n = (X_1, \dots, X_n)^T$  where  $X_t$  is the ARMA(p,q) process with parameter  $\beta \in \mathbb{C}$ .

Then the Gaussian likelihood function is given by:

$$L(\mathbf{X}, \beta) := (2\pi)^{-\frac{n}{2}} |\Gamma_n(\beta)|^{-\frac{1}{2}} \exp\left(-\frac{1}{2} \mathbf{X}_n^T \Gamma_n(\beta)^{-1} \mathbf{X}_n\right)$$

The QMLE finds the  $\hat{\beta}$  and  $\hat{\sigma}^2$  that maximize the Gaussian likelihood function.

Can write  $\Gamma_n(\beta, \sigma^2) = \sigma^2 \cdot G_n(\beta)$  where  $G_n(\beta)$  is the correlation matrix of  $\mathbf{X}_n$ .  
then

$$L(\mathbf{X}_n, \beta, \sigma^2) := (2\pi\sigma^2)^{-\frac{n}{2}} |G_n(\beta)|^{-\frac{1}{2}} \exp\left(-\frac{1}{2\sigma^2} \mathbf{X}_n^T G_n(\beta)^{-1} \mathbf{X}_n\right)$$

We can maximize wrt  $\sigma^2$  first to get  $\hat{\sigma}^2(\beta) = \frac{1}{n} \mathbf{X}_n^T G_n(\beta)^{-1} \mathbf{X}_n$

Then we can maximize the profile likelihood:

$$l(\mathbf{X}_n, \beta) = -\frac{n}{2} \log \left[ \frac{1}{n} \mathbf{X}_n^T G_n(\beta)^{-1} \mathbf{X}_n \right] - \frac{1}{2} \log |G_n(\beta)|$$

**Remark** (How to find QMLE). minimize

$$\min_{\beta \in \mathbb{C}} \frac{1}{n} \log |G_n(\beta)| + \log \left[ \frac{1}{n} \mathbf{X}_n^T G_n(\beta)^{-1} \mathbf{X}_n \right]$$

And also take  $\hat{\sigma}^2 = \frac{1}{n} \mathbf{X}_n^T G_n(\hat{\beta})^{-1} \mathbf{X}_n$

**Method 1:**

Predict  $X_1$  using no data, predict  $X_2$  using  $X_1$ , predict  $X_3$  using  $X_1, X_2$  and so on.  
let  $v_{n-1}$  be the predictor of the next step using  $n - 1$  observations, i.e.,  $v_{n-1} = E[X_n | X_1, \dots, X_{n-1}] / \sigma^2$ .

$$\begin{bmatrix} X_1 - \hat{X}_1 \\ X_2 - \hat{X}_2 \\ \vdots \\ X_n - \hat{X}_n \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ -\phi_{11} & 1 & 0 & \dots & 0 \\ -\phi_{21} & -\phi_{22} & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ -\phi_{n-1,1} & -\phi_{n-1,2} & -\phi_{n-1,3} & \dots & 1 \end{bmatrix} \begin{bmatrix} X_1 \\ X_2 \\ \vdots \\ X_n \end{bmatrix}$$

$$\hat{X}_{j+1} = \hat{\phi}_j \begin{bmatrix} X_j \\ X_{j-1} \\ \vdots \\ X_1 \end{bmatrix}$$

## 1.23 11/20/2025 Lecture 23

**Remark.** ARMA(p,q):  $\phi(B)X_t = \theta(B)Z_t$  where  $Z_t \sim IID(0, \sigma^2)$

Find the BLP of  $X_{n+1}$  using  $X_1, \dots, X_n$

Ler  $v_n = E[X_{n+1} - \hat{X}_{n+1}]^2$  be the mean squared error of the predictor and  $r_j = \frac{v_j}{\sigma^2}$

- $X_{j+1} - \hat{X}_{j+1}$  is independent across j
- The joint densities of  $\mathbf{X}_n$  and  $[X_{n+1} - \hat{X}_{n+1}]$  are the same

$$L(X_n, \beta, \sigma^2) = \prod_{j=1}^n \frac{1}{2\pi\sqrt{\sigma^2 r_{j-1}}} \exp\left(-\frac{(X_j - \hat{X}_j)^2}{2\sigma^2 r_{j-1}}\right)$$

$$L(X_n, \beta, \sigma^2) = (2\pi\sigma^2)^{-\frac{n}{2}} \left(\prod_{j=0}^{n-1} r_j\right)^{-\frac{1}{2}} \exp\left(-\frac{1}{2\sigma^2} \sum_{j=1}^n \frac{(X_j - \hat{X}_j)^2}{r_{j-1}}\right)$$

Maximize wrt  $\sigma^2$  first to get  $\hat{\sigma}^2(\beta) = \frac{1}{n} \sum_{j=1}^n \frac{(X_j - \hat{X}_j)^2}{r_{j-1}}$

Then we can maximize the log likelihood: (Let  $S_n(\beta) = \sum_{j=1}^n \frac{(X_j - \hat{X}_j)^2}{r_{j-1}}$ )

$$l(X_n, \beta) = -\frac{n}{2} \log \left[ \frac{1}{n} S_n(\beta) \right] - \frac{1}{2} \sum_{j=0}^{n-1} \log r_j$$

To find MLE we minimize:

$$\min_{\beta \in \mathbb{C}} \frac{1}{n} \sum_{j=1}^n \frac{(X_j - \hat{X}_j)^2}{r_{j-1}} + \frac{1}{n} \sum_{j=0}^{n-1} \log r_j$$

And we can instead take the minimization problem:

$$\min_{\beta \in \mathbb{C}} S_n(\beta) = \sum_{j=1}^n \frac{(X_j - \hat{X}_j)^2}{r_{j-1}}$$

**Remark. Method 2** Periodogram Method

Suppose we have data  $X_1, \dots, X_n$  from a mean zero stationary process.

**Definition** (10.1.2). The periodogram function is defined as:

$$\omega_j = \frac{2\pi j}{n}$$

$$I(\omega_j) = \frac{1}{n} \left| \sum_{t=1}^n X_t e^{-i\omega_j t} \right|^2 \quad -\pi < \omega_j \leq \pi, j = 1, 2, \dots, n$$

The set  $F_n := \{j \in \mathbb{Z} : -\pi < \omega_j \leq \pi, j = 1, 2, \dots, n\}$  are called the Fourier frequencies.  
 $|F_n| = n$

**Proposition 12** (10.1.2). For each  $j \in F_n$

$$I(\omega_j) = \sum_{k=-(n-1)}^{n-1} \hat{\gamma}(k) e^{-ik\omega_j}$$

where  $\hat{\gamma}(k)$  is the sample autocovariance function. We can see that the periodogram is a good estimator for the spectral density function since:

$$f(\lambda) = \frac{1}{2\pi} \sum_{k=-\infty}^{\infty} \gamma(k) e^{-ik\lambda}$$

$$I(\omega_j) = \sum_{k=-(n-1)}^{n-1} \hat{\gamma}(k) e^{-ik\omega_j}$$

$I(\omega_j)$  corresponds to an estimation of the Spectral Density Function at the Fourier frequencies.

$E[I(\omega_j)] = 2\pi f(\omega_j)$  as  $n \rightarrow \infty$

Let  $\alpha(\omega_j) = \frac{1}{\sqrt{n}} \sum_{t=1}^n X_t \cos(\omega_j t)$  and  $\beta(\omega_j) = \frac{1}{\sqrt{n}} \sum_{t=1}^n X_t \sin(\omega_j t)$

Then  $I(\omega_j) = \alpha(\omega_j)^2 + \beta(\omega_j)^2$

Note that  $\alpha(\omega_j)$  and  $\beta(\omega_j)$  are asymptotically independent

Let  $G(\lambda, \beta) = \frac{1}{2\pi} \left| \frac{\theta(e^{-i\lambda})}{\phi(e^{-i\lambda})} \right|^2 = \frac{1}{\sigma^2} f(\lambda, \beta)$

Then  $\alpha(\omega_j) \approx N(0, \frac{\sigma^2}{2} g(\omega_j, \beta))$  We then reach to the whittle likelihood function:

$$\min_{\beta \in \mathbb{C}} \sum_{j \in F_n} \left[ \frac{I(\omega_j)}{2\pi g(\omega_j, \beta)} + \log g(\omega_j, \beta) \right]$$

## 1.24 11/25/2025 Lecture 24

**Theorem 23.** Let  $\{X_1, \dots, X_n\}$  be a realization of a strictly stationary ARMA( $p, q$ ) model with  $Z_t \sim IID(0, \sigma^2)$  and  $\beta \in \mathbb{C}$  be the parameters of the model.

Then let  $\hat{\beta}$  be the MLE, LSE, or Whittle Estimator then

$$\sqrt{n}(\hat{\beta} - \beta) \xrightarrow{d} N(0, V(\beta)) \text{ as } n \rightarrow \infty$$

Where  $V(\beta) = \sigma^2 \begin{bmatrix} E[U_t U_t^T] & E[U_t V_t^T] \\ E[V_t U_t^T] & E[V_t V_t^T]^{-1} \end{bmatrix}$  With  $U_t = (U_{t-1}, \dots, U_{t-p})^T$  and  $V_t = (V_{t-1}, \dots, V_{t-q})^T$

and  $\phi(\beta)U_t = Z_t$  and  $\theta(\beta)V_t = Z_t$  with the same  $Z_t$  for both equations.

Equivalently

$$\begin{aligned} \sqrt{n}(\hat{\beta} - \beta) &\xrightarrow{d} N(0, W^{-1}(\beta)) \\ W(\beta) &= \frac{1}{4\pi} \int_{-\pi}^{\pi} [\nabla \log g(\lambda, \beta)] [\nabla \log g(\lambda, \beta)]^T d\lambda \\ g(\lambda, \beta) &= \frac{\sigma^2}{2\pi} \left| \frac{\theta(e^{-i\lambda}, \beta)}{\phi(e^{-i\lambda}, \beta)} \right|^2 \end{aligned}$$

**Remark.** Suppose  $\{X_t\}$  is a SS process with mean  $\mu$

$$\sqrt{n}(\bar{X}_n - \mu) \xrightarrow{d} N(0, \tau^2) \text{ as } n \rightarrow \infty$$

Where  $\tau^2 = \sum_{h=-\infty}^{\infty} \gamma_X(h)$

$\hat{\tau} = \sum_{k=-h_n}^{h_n} \hat{\gamma}_X(k)$  where  $h_n \rightarrow \infty$  and  $\frac{h_n}{n} \rightarrow 0$  as  $n \rightarrow \infty$

Then

**Remark** (batch estimator). Suppose  $n = bm$  choose  $m_n \rightarrow \infty$  and  $\frac{m_n}{n} \rightarrow 0$  as  $n \rightarrow \infty$  let

$$\begin{aligned} &X_1, \dots, X_m \\ &X_{m+1}, \dots, X_{2m} \\ &\vdots \\ &X_{(b-1)m+1}, \dots, X_{bm} \end{aligned}$$

Let  $\bar{X}_k = \frac{1}{m} \sum_{t=(k-1)m+1}^{km} X_t$  for  $k = 1, 2, \dots, b$

Then

$$\sqrt{m}(\bar{X}_k - \bar{X}) \xrightarrow{d} N(0, \tau^2) \text{ as } m \rightarrow \infty$$

$$\hat{\tau}^2 = \frac{1}{b} \sum_{k=1}^b m(\bar{X}_k - \bar{X})^2$$

**Remark** (Spectral Approach).

$$\begin{aligned}\tau^2 &= \sum_{h=-\infty}^{\infty} \gamma_X(h) = 2\pi f_X(0) \\ f_X(\lambda) &= \frac{1}{2\pi} \sum_{h=-\infty}^{\infty} \gamma_X(h) e^{-ih\lambda}\end{aligned}$$

The periodogram:

$$I(\omega_j) = \frac{1}{n} \left| \sum_{t=1}^n X_t e^{-i\omega_j t} \right|^2 \quad \text{where } \omega_j = \frac{2\pi j}{n}, j = 1, 2, \dots, n \quad -\pi < \omega_j \leq \pi$$

$E[I(\omega_j)] \approx 2\pi f_X(\omega_j)$  as  $n \rightarrow \infty$

$\frac{1}{2\pi 2B_n + 1} \sum_{j:|\omega_j| \leq B_n} I(\omega_j) \approx \hat{\tau}_3^2$  smoothing the periodogram

**Remark** (multivariate Time Series).  $\{\underline{X}_t : t \in \mathbb{Z}\}$  where  $\underline{X}_t = (X_{t,1}, X_{t,2}, \dots, X_{t,m})^T$  is an  $m$ -dimensional vector.

$$\begin{aligned}E[\underline{X}_t^2] &\leq \infty \text{ for all } t \in \mathbb{Z} \\ \mu_{ti} &= E[X_{t,i}] \quad i = 1, 2, \dots, m \\ \gamma_{ij}(t+h, t) &= Cov(X_{t+h,i}, X_{t,j}) = E[(X_{t+h,i} - \mu_{t+h,i})(X_{t,j} - \mu_{t,j})] \\ \Gamma(t+h, t) &= [\gamma_{ij}(t+h, t)]_{i,j=1}^m \text{ is the autocovariance/crosscovariance matrix}\end{aligned}$$

**Definition.** The time series  $\{\underline{X}_t\}$  is said to be stationary if

- $E[\underline{X}_t] = \underline{\mu_0}$  for all  $t \in \mathbb{Z}$  Time Invariant Mean
- $\Gamma(t+h, t) = \Gamma(h, 0) = \Gamma(h)$  for all  $t, h \in \mathbb{Z}$  Time Invariant Covariance

Also consider  $R(h) = [\rho_{ij}(h)]_{i,j=1}^m$  where  $\rho_{ij}(h) = \frac{\gamma_{ij}(h)}{\sqrt{\gamma_{ii}(0)\gamma_{jj}(0)}}$  is the autocorrelation/crosscorrelation matrix.

- $\gamma_{ii}(0)$  is the autocovariance fn of the univariate sereis  $\{X_{t,i}\}$
- $|\gamma_{ij}(h)| \leq \sqrt{\gamma_{ii}(0)\gamma_{jj}(0)}$  by Cauchy-Schwarz Inequality
- $\Gamma(h) = [\Gamma(-h)]^T$  for all  $h \in \mathbb{Z}$
- $\sum_{j,k=1}^n a_j^T \Gamma(j-k) a_k \geq 0$  for all  $n \in \mathbb{N}$  and  $a_1, \dots, a_n \in \mathbb{R}^m$  (non-negative definite)
- Strict Staitonarity is defined the same

## 1.25 12/02/2025 Lecture 25

**Definition** (11.3.1 Multivariate ARMA(p,q) Models).  $\{\underline{X}_t, t \in \mathbb{Z}\}$  is an  $m$ -variate ARMA(p,q) process if  $\{\underline{X}_t\}$  is the stationary solution of the difference equations:

$$X_t - \Phi_1 X_{t-1} - \dots - \Phi_p X_{t-p} = Z_t + \Theta_1 Z_{t-1} + \dots + \Theta_q Z_{t-q}$$

$$\Phi(B)\underline{X}_t = \Theta(B)\underline{Z}_t$$

Where  $\Phi_i$  and  $\Theta_j$  are  $m \times m$  coefficient matrices for  $i = 1, \dots, p$  and  $j = 1, \dots, q$

And  $\{\underline{Z}_t\} \sim WN(0, \Sigma_Z)$  is a multivariate white noise process with  $E[\underline{Z}_t] = 0$  and  $Cov(\underline{Z}_t, \underline{Z}_s) = \Sigma_Z$  for all  $t \in \mathbb{Z}$

$\Phi(z) = I_m - \Phi_1 z - \dots - \Phi_p z^p$  and  $\Theta(z) = I_m + \Theta_1 z + \dots + \Theta_q z^q$

Consider the example: for an  $m = 2$  variate ARMA(2,2) process:

$$\underline{X}_t = \begin{bmatrix} 0.3 & 0.1 \\ 0.1 & 0.5 \end{bmatrix} \underline{X}_{t-1} + \begin{bmatrix} 0.1 & 0.05 \\ 0.03 & 0.1 \end{bmatrix} \underline{X}_{t-2} + \underline{Z}_t + \begin{bmatrix} 0.5 & 0.1 \\ 0.1 & 0.6 \end{bmatrix} \underline{Z}_{t-1} + \begin{bmatrix} 0.2 & 0.1 \\ 0.1 & 0.3 \end{bmatrix} \underline{Z}_{t-2}$$

This is a system of question with the cross terms.

**Example** (MV AR(1)).  $X_t = \Phi X_{t-1} + Z_t$  where  $Z_t \sim WN(0, \Sigma_Z)$

$\Phi = UDV'$   $P(\Phi) = \max(|\lambda_i| : |\lambda I - \Phi| = 0)$

$\Phi^k \rightarrow 0$  as  $k \rightarrow \infty$  iff  $P(\Phi) < 1$

Equivalently  $|\Phi(z)| = |I - \Phi z|$  for  $|z| \leq 1$

**Theorem 24** (11.3.1). If  $\det \Phi(z) \neq 0$  for  $|z| \leq 1$  then  $\{\underline{X}_t\}$  has the unique stationary solution of the form

$$X_t = \sum_{j=0}^{\infty} \Psi_j Z_{t-j}$$

where  $\Psi(z) = \sum_{j=0}^{\infty} \Psi_j z^j = \Phi^{-1}(z)\Theta(z)$  for  $|z| \leq 1$

We can do a fast inversion of  $\Phi(z)$  by taking a ton of determinants

Similarly we can see for invertability if  $\det \Theta(z) \neq 0$  for  $|z| \leq 1$  then  $X_t$  is invertible in the sense that  $Z_t = \sum_{j=0}^{\infty} \Pi_j X_{t-j}$  where  $\sum_{j=0}^{\infty} \|\Pi_j\| < \infty$  and  $\Pi(z) = \sum_{j=0}^{\infty} \Pi_j z^j = \Theta^{-1}(z)\Phi(z)$  for  $|z| \leq 1$

**Example.** If  $Z_t \sim IIDN(0, \Sigma_Z)$  then  $\{\underline{X}_t\}$  is a Gaussian process.

If  $\{\underline{X}_t\}$  is gaussian with autocovariance function  $\Gamma_X(h)$  and  $\underline{Y}_t$  is another gaussian process with autocovariance function  $\Gamma_Y(h)$  and  $\Gamma_X(h) = \Gamma_Y(h)$  for all  $h \in \mathbb{Z}$  then  $\{\underline{X}_t\}$  and  $\{\underline{Y}_t\}$  have the same distribution and same cooefficients

Note we cannot have the same "no same roots" condition as the univariate case since the determinant of a matrix polynomial can have multiple roots even if the matrix polynomial does not.

**Remark** (Estimation). Mean:  $\underline{\mu} = E[X_t]$  can be estimated by  $\bar{X}_n = \frac{1}{n} \sum_{t=1}^n X_t$   
 Autocovariance:  $\Gamma(h) = Cov(X_{t+h}, X_t)$  can be estimated by

$$\hat{\Gamma}(h) = \frac{1}{n} \sum_{t=1}^{n-|h|} (X_{t+|h|} - \bar{X}_n)(X_t - \bar{X}_n)^T$$

For  $VAR(p)$  model:  $X_t = \Phi_1 X_{t-1} + \dots + \Phi_p X_{t-p} + Z_t$  where  $Z_t \sim WN(0, \Sigma_Z)$   
 We can use LSE or Yule-Walker to estimate the parameters.

For VARMA(p,q) model we can use MLE or QMLE to estimate the parameters.

## 1.26 12/04/2025 Lecture 26

**Definition** (Factor Models).  $X_i = AF_i + e_i$  where

- $X_i$  is the observed  $p$ -variate time series
- $F_i$  is the unobserved  $r$ -variate factor time series with  $r < p$
- $A$  is the  $p \times r$  loading matrix
- $e_i$  is the  $p$ -variate noise vector

$$X_{ij} = \sum_{k=1}^r a_{jk} f_{ik} + e_{ij} \text{ for } j = 1, 2, \dots, p$$

**Example** (Model 1). Assume  $f_t$  are iid normal with mean 0 and covariance  $I_r$   
 Assume  $e_t$  are iid normal with mean 0 and covariance  $\Sigma_e$  where  $\Sigma_e$  is diagonal.

$F_t$  and  $e_t$  are independent for all  $t$

Assume  $A'\sigma A$  is a diagonal matrix with distinct eigenvalues.

Then

$$\begin{aligned} \text{Cov}(X_t) &= A \text{Cov}(F_t) A^T + \text{Cov}(e_t) \\ &= AA^T + \Sigma_e \end{aligned}$$

Thus  $X_T = AQQ'f_t + e_t$  for any orthogonal matrix  $Q$  since  $QQ' = I_r$   
 $Q'A'\Sigma_e A Q$  is also diagonal with distinct eigenvalues.

Also  $m$  is fixed

This is the classical factor model

**Example** (Model 2: High Dimensional Factor Model).  $M$  is large,  $m \rightarrow \infty$  as  $n \rightarrow \infty$   
 $r$  is fixed

Assume  $f_t$  are iid normal with mean 0 and covariance  $I_r$

Assume  $e_t$  are iid normal with mean 0 and covariance  $\Sigma_e$  for a general covariance matrix  $\Sigma_e$   
 $A = UDV'$

## 1.27 12/09/2025 Lecture 27

**Remark.** consider  $X_i = U\Lambda f_i + Z_i$  with  $r$  factors where

- $X_i$  is the observed  $p$ -variate time series
- $f_i$  is the unobserved  $r$ -variate factor time series with  $r < p$
- $U$  is the  $p \times r$  loading matrix with orthonormal columns
- $\Lambda$  is a  $r \times r$  diagonal matrix with positive diagonal entries
- $Z_i$  is the  $p$ -variate noise vector with covariance  $\sigma^2 I_p$

Metric between two subspaces.

Let  $U$  and  $\hat{U}$  be two  $p \times r$  orthonormal matrices.

Then the distance between the column spaces of  $U$  and  $\hat{U}$  is defined as:

$$d(U, \hat{U}) = \|UU' - \hat{U}\hat{U}'\|_2$$

**Theorem 25** (Wedins theorem). Suppose  $X = UDV' + Z$  and  $\hat{X} = \hat{U}\hat{D}\hat{V}' + \hat{Z}$  where

- $U$  and  $\hat{U}$  are  $p \times r$  orthonormal matrices
- $V$  and  $\hat{V}$  are  $n \times r$  orthonormal matrices
- $D$  and  $\hat{D}$  are  $r \times r$  diagonal matrices with positive diagonal entries
- $Z$  and  $\hat{Z}$  are noise matrices

Then

$$\|U'_\perp \hat{U}\|_2 \leq \frac{Z\|Z\|}{\sigma_r}$$

**Remark** (Operator Norm: of Gaussian RM). Sudokov-Fermque Inequality:

Let  $\{X\}$  and  $\{Y\}$  be mean zero Gaussian random vectors.

Assume  $E(X_t - X_s)^2 \leq E(Y_t - Y_s)^2$  for all  $s, t$  in the index set  $T$ .

Then

$$E \left[ \sup_{t \in T} X_t \right] \leq E \left[ \sup_{t \in T} Y_t \right]$$

**Theorem 26** (7.3.1). Let  $A$  be  $d_1 \times d_2$  matrix with entries  $A_{ij} \sim N(0, \sigma^2)$  iid.

such that  $E[\alpha' \text{vec}(A)] \leq \|\alpha\|$  for all  $\alpha \in \mathbb{R}^{d_1 d_2}$

Then

$$E[\|A\|] \leq (\sqrt{d_1} + \sqrt{d_2})$$

*Proof.*

□