- Male and female are disjoint categories:
  - $\forall x \, \mathsf{Male}(x) \Leftrightarrow \neg \mathsf{Female}(x)$

- A sibling is another child of one's parent:
  - $\forall x,y \text{ Sibling}(x,y) \Leftrightarrow x\neq y \land \exists p \text{ Parent}(p,x) \land \text{ Parent}(p,y)$

a) Some students took French in spring 2001.

 $\exists x \; Student(x) \land Takes(x, F, Spring2001).$ 

b) Every student who takes French passes it.

 $\forall$  x, s Student(x)  $\land$  Takes(x, F, s)  $\Rightarrow$  Passes(x, F, s).

c) Only one student took Greek in spring 2001.

 $\exists x \; Student(x) \land Takes(x,G, Spring2001) \land \forall y \; y \neq x \Rightarrow \ \ \, Takes(y,G,Spring2001).$ 

d) The best score in Greek is always higher than the best score in French.

 $\forall s \exists x \forall y \ Score(x,G,s) > Score(y,F,s).$ 

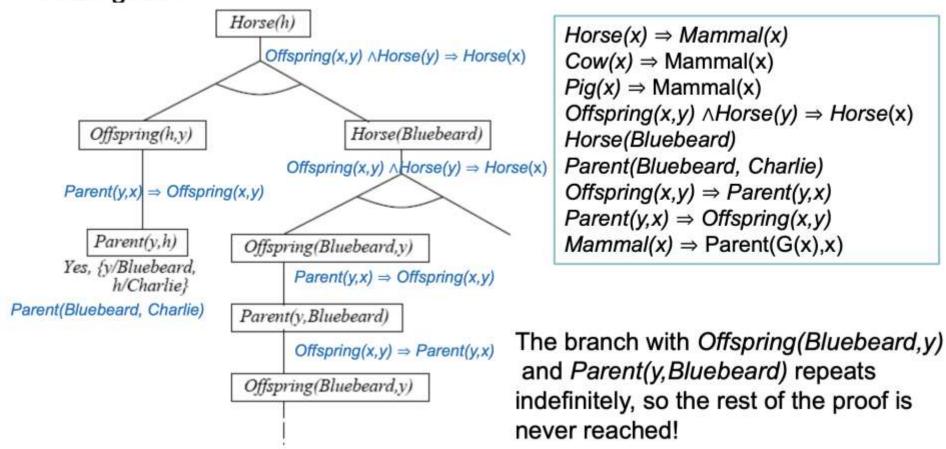
- AsHighAs(Kilimanjaro, Everest)
- AsHighAs(Kilimajaro, Everest) and AsHighAs(BenNevis, Everest)

• It's fine as long as you don't reuse an existing constant

- 1. x = A, y = B, z = B
- 2. Doesn't exist
- 3. X = John, y = John
- 4. Doesn't exist

- a. Horse, cows, and pigs are mammals.
  - Horse(x) ⇒ Mammal(x)
  - Cow(x)  $\Rightarrow$  Mammal(x)
  - Pig(x)  $\Rightarrow$  Mammal(x)
- b. An offspring of a horse is a horse.
  - Offspring(x,y)  $\land$ Horse(y)  $\Rightarrow$  Horse(x)
- c. Bluebeard is a horse.
  - Horse(Bluebeard)
- d. Bluebeard is Charlie's parent.
  - Parent(Bluebeard, Charlie)
- e. Offspring and parent are inverse relations.
  - Offspring(x,y) ⇒ Parent(y,x)
  - Parent(y,x) ⇒ Offspring(x,y)
- f. Every mammal has a parent.
  - Mammal(x) ⇒ Parent(G(x),x)

Draw the proof tree generated by an exhaustive backward-chaining algorithm for the query ∃h Horse(h), where clauses are matched in the order given.



### #11.1

Operators: **Initial State:** Go(x,y)At(Monkey,A) Precond: At(Monkey,x) AND Height(Monkey,Low) At(Bananas,B) Effect: At(Monkey,y) AND NOT At(Monkey,x) At(Box,C)Height(Monkey,Low) Push(b,x,y)Height(Box,Low) Precond: At(Monkey,x) AND Height(Monkey,Low) AND At(b,x) AND Pushable(b) AND Height(b,Low) Height(Bananas, High) Effect: At(b,y) AND At(Monkey,y) AND NOT At(b,x) AND NOT At(Monkey,x) Pushable(Box) Climbable(Box) ClimbUp(b) Graspable(Bananas)

Goal State:

Have(Monkey, Bananas) Grasp(b)

Precond: At(Monkey,x) AND Height(Monkey,h) AND At(b,x) AND Graspable(b) AND Height(b,h)

Effect: On(Monkey,b) AND NOT Height(Monkey,Low) AND Height(Monkey,High)

Precond: At(Monkey,x) AND Height(Monkey,Low) AND At(b,x) AND Climbable(x) AND Height(b,Low)

Effect: Have(Monkey,b)

Plan: Go(A, C), Push(Box, C, B), ClimbUp(Box), Grasp(Banana)

#11.2

• See pages 6-7 of our planning lecture notes.

## #11.3

• Removing negative effects will not remove any positive states in the world, and thus make the goal easier to achieve.