Report

Lab1(gdb&Makefile)

Lab2(Startup.s&Startup.c)

Lab1(gdb&Makefile) :

- First we will open gdb circuit in qemo tool for board that we debug on called versatilepb using this command :

```
IP@DESKTOP-RR69RMG MINGW64 ~/Desktop/lab1 with makefile
$ /c/qemu/qemu-system-arm.exe -M versatilepb -m 128M -nographic -kernel learn-in
-depth.elf
learn-in-depth:shady_mamdouh
IP@DESKTOP-RR69RMG MINGW64 ~/Desktop/lab1 with makefile
$  /c/qemu/qemu-system-arm.exe -M versatilepb -m 128M -nographic -s -S -kernel l
earn-in-depth.elf
```

- As we know to connect to gdb server on board you must have IP address and port number
- In our case we use qemu tool to virtually debug our code so the IP address will be our localhost address and port number is :1234

```
(gdb) target remote localhost:1234
Remote debugging using localhost:1234
reset () at startup.s:4
4               ldr sp, =stack_top
(gdb)
```

- There is command show us 3 assembly instructions starting with line we stand , the arrow points to reset symbol in startup.s file :

```
(gdb) display/3i $pc
1: x/3i $pc
=> 0x10000 <reset>:     ldr     sp, [pc, #4]    ; 0x1000c <stop+4>
   0x10004 <reset+4>:   bl      0x10010 <main>
   0x10008 <stop>:      b       0x10008 <stop>
(gdb) |
```

If we want to make breaking point at main

The main function at address 0x10010 :

```
(gdb) b main
Breakpoint 1 at 0x10018: file APP.c, line 8.
(gdb) b *0x10010
Breakpoint 2 at 0x10010: file APP.c, line 7.
(gdb) |
```

We found out that real address of main symbol is at 0x10018

Notice : the address of 0x10010 is related with context instructions it is about creating stack and store PC in lR

- If we want to step one instruction in assembly we can use “si” command but if we debug in C level we can use “s” command that step one C line that may contains many assembly instructions :

```
(gdb) si
reset () at startup.s:5
5               bl main
1: x/3i $pc
=> 0x10004 <reset+4>:   bl      0x10010 <main>
   0x10008 <stop>:      b       0x10008 <stop>
   0x1000c <stop+4>:    andeq   r1, r1, r8, lsl #4
(gdb)
```

-if we want to print a specific variable we can use

“ print var_name “ .

-If we want to watch a specific variable that debugger will stand if their value has been changed , we can use command “watch var_name” :

```
(gdb) watch string_buffer
Hardware watchpoint 3: string_buffer
(gdb) print string_buffer
$1 = "Learn-in-depth:shady_mamdouh", '\000' <repeats 71 times>
(gdb)
```

-If we want to know where are we , we can use this command “where”

-if we want to know information about breaking points and their number we use command “info breakpoints”

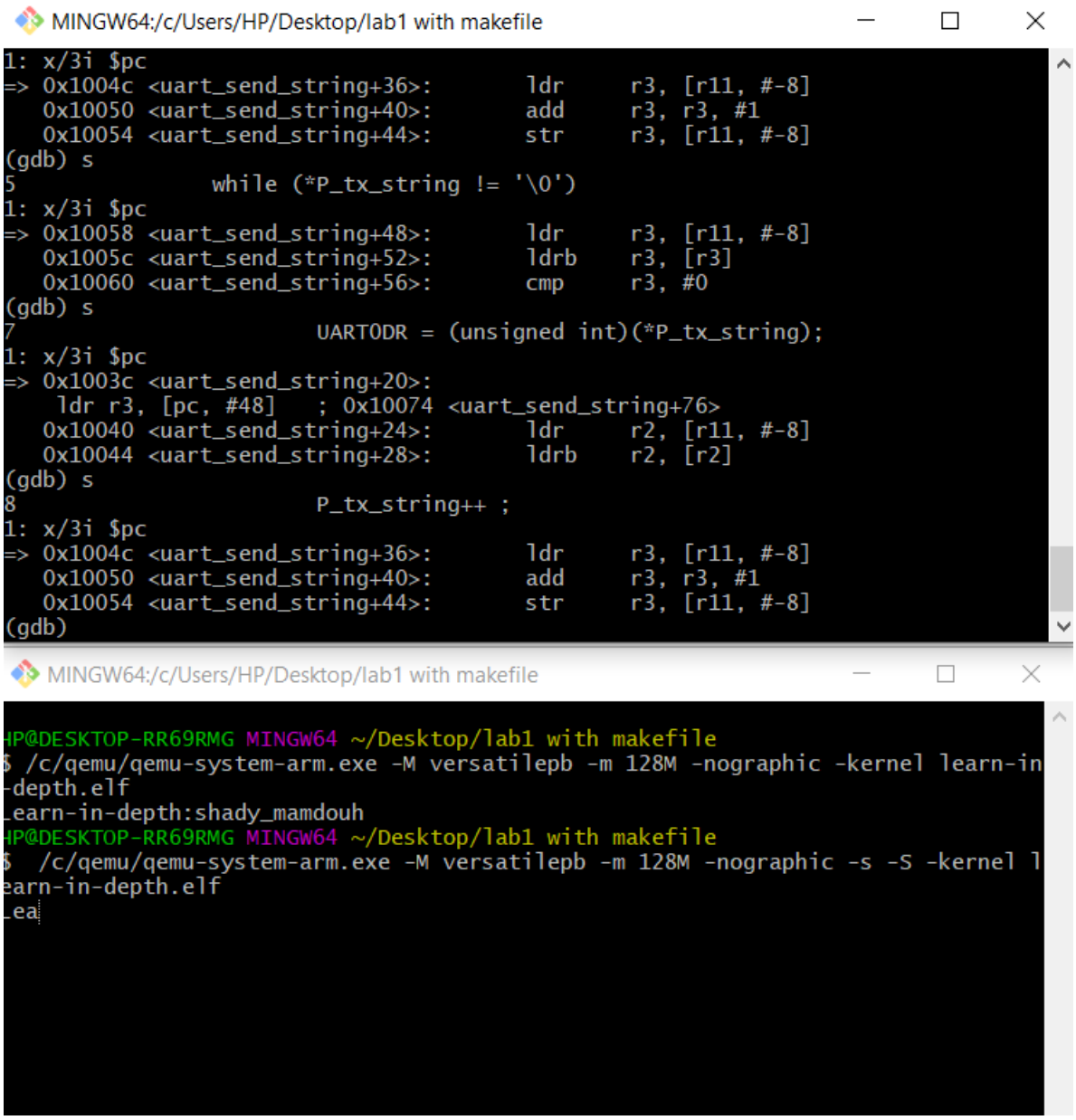
-if we want to delete some breakpoint we can use

“delete b_name” :

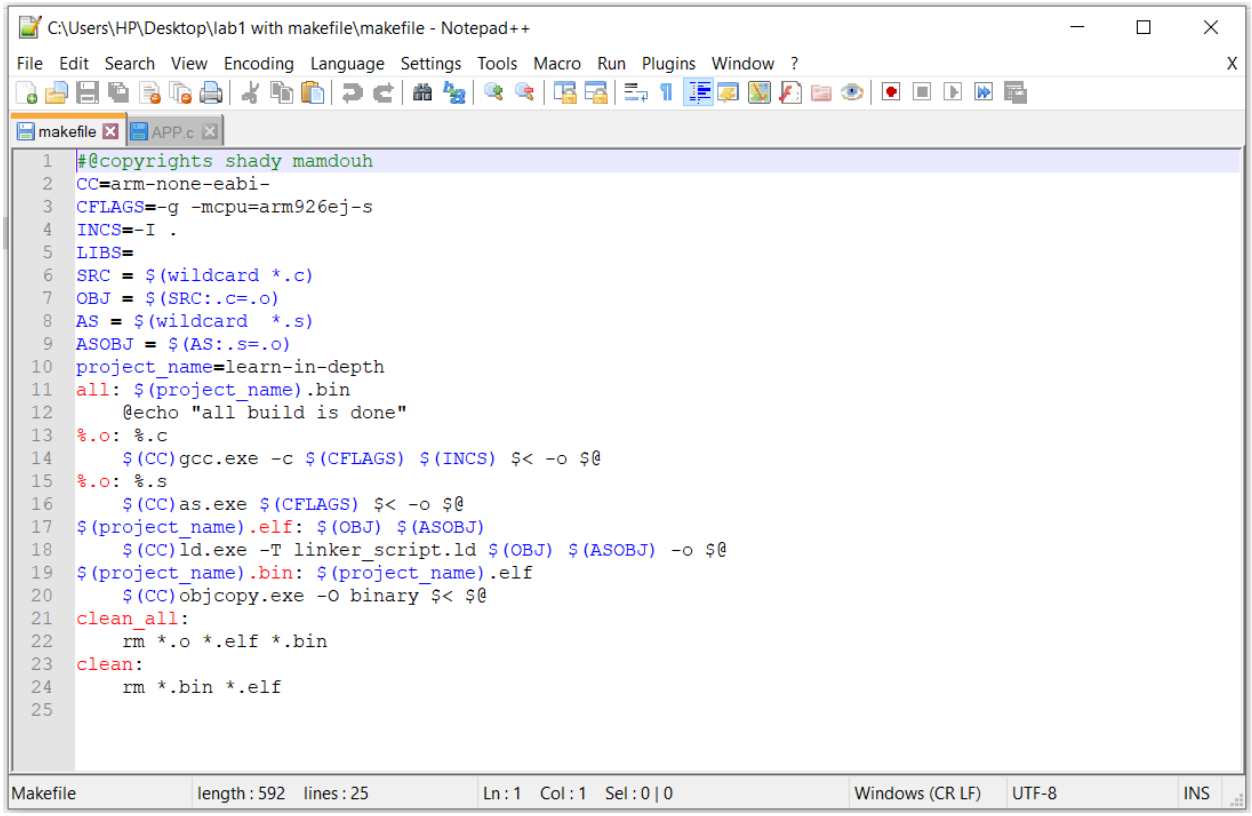
```
(gdb) where
#0  reset () at startup.s:5
(gdb) info breakpoints
Num     Type           Disp Enb Address    What
1       breakpoint     keep y   0x00010018 in main at APP.c:8
2       breakpoint     keep y   0x00010010 in main at APP.c:7
3       hw watchpoint  keep y              string_buffer
(gdb) delete main
(gdb)
```

- If we want to tell gdb to continue till closest breaking point We can use command “c”

- We will step in C until uart.c and we will find that the string will printed character by character on the qemo terminal :



Makefile of lab 1 :



Lab2(Startup.s&Startup.c)

Startup.s

Board name : STM32f103c8t6

Notice: Entry point of this cortex-m3 based is 0x0800000

It must contain SP value of address that points to in sram

main.c :

```c
// Eng.Shady mamdouh
#include "stdint.h"
#define RCC_BASE 0x40021000
#define GPIO_BASE 0x40010800
typedef union{  uint32_t all_pins;
                struct{
                    uint32_t pin0:1;
                    uint32_t pin1:1;
                    uint32_t pin2:1;
                    uint32_t pin3:1;
                    uint32_t pin4:1;
                    uint32_t pin5:1;
                    uint32_t pin6:1;
                    uint32_t pin7:1;
                    uint32_t pin8:1;
                    uint32_t pin9:1;
                    uint32_t pin10:1;
                    uint32_t pin11:1;
                    uint32_t pin12:1;
                    uint32_t pin13:1;
                    uint32_t pin14:1;
                    uint32_t pin15:1;
                    uint32_t pin16:1;
                    uint32_t pin17:1;
                    uint32_t pin18:1;
                    uint32_t pin19:1;
                    uint32_t pin20:1;
                    uint32_t pin21:1;
                    uint32_t pin22:1;
                    uint32_t pin23:1;
                    uint32_t pin24:1;
                    uint32_t pin25:1;
                    uint32_t pin26:1;
                    uint32_t pin27:1;
                    uint32_t pin28:1;
                    uint32_t pin29:1;
                    uint32_t pin30:1;
                    uint32_t pin31:1;
                      };
} reg_pin;
```

```c
} reg_pin;
volatile reg_pin *APB2ENR=(volatile reg_pin*)(RCC_BASE+0x18);
volatile reg_pin *CRH=(volatile reg_pin*)(GPIO_BASE+0x04);
volatile reg_pin *PORTA=(volatile reg_pin*)(GPIO_BASE+0x0C);
unsigned char g_variables[3] = {1,2,3};
unsigned char const const_variables[3]={1,2,3};
int main(void)
{    volatile int i ;
    APB2ENR->pin2=1;
    CRH->all_pins=0;
    CRH->pin21=1;
    while(1)
    {    for(i=0;i<50000;i++){};
        PORTA->pin13=1;
        for(i=0;i<50000;i++);
        PORTA->pin13=0;
    }

}
```

Startup.s :

We gave command to assembler to make section called vectors

And we defined first word as a value of SP is 0x20001000

Within range of sram

According to specs the interrupt vector table must start after SP assigning , so we make vector_handler to handle any interrupt

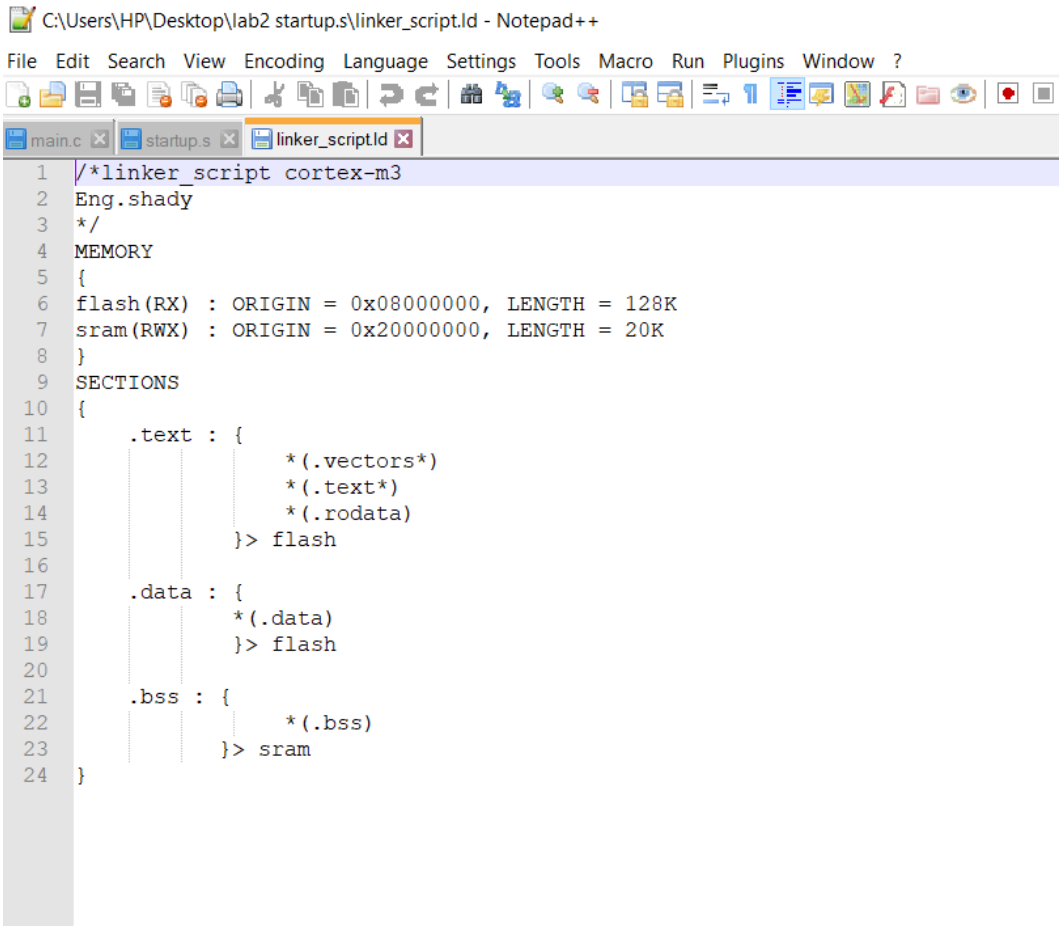
```
/* startup_cortexM3.s
Eng.Shady
 */
.section .vectors
.word  0x20001000
.word   _reset
.word    vector_handler
.word    vector_handler
.word    vector_handler
.word    vector_handler
.word    vector_handler
.word    vector_handler
.word    vector_handler
.word    vector_handler
.word    vector_handler
.word    vector_handler
.word    vector_handler
.word    vector_handler
.word    vector_handler
.word    vector_handler
.word    vector_handler
.word    vector_handler
.word    vector_handler
.word    vector_handler


.section .text

_reset:
    bl main
    b .
vector_handler:

        b  _reset

```

Linker script :

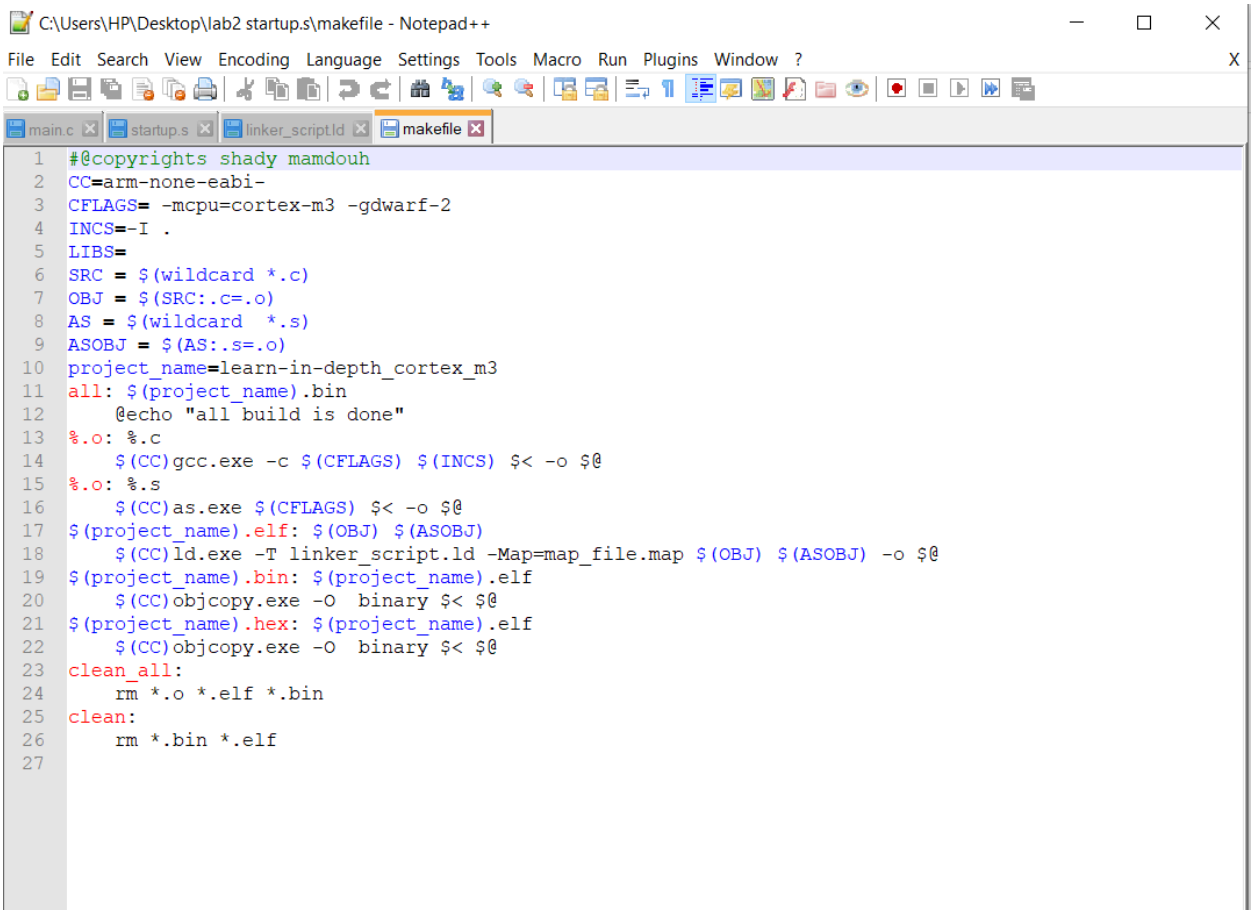
According to specs flash memory starts with 0x08000000

And sram starts with 0x20000000

-we make vector section at the start of sections to be located at the start of flash memory



Make file : somethings will be edited compared with lab1 such as project name and board name :

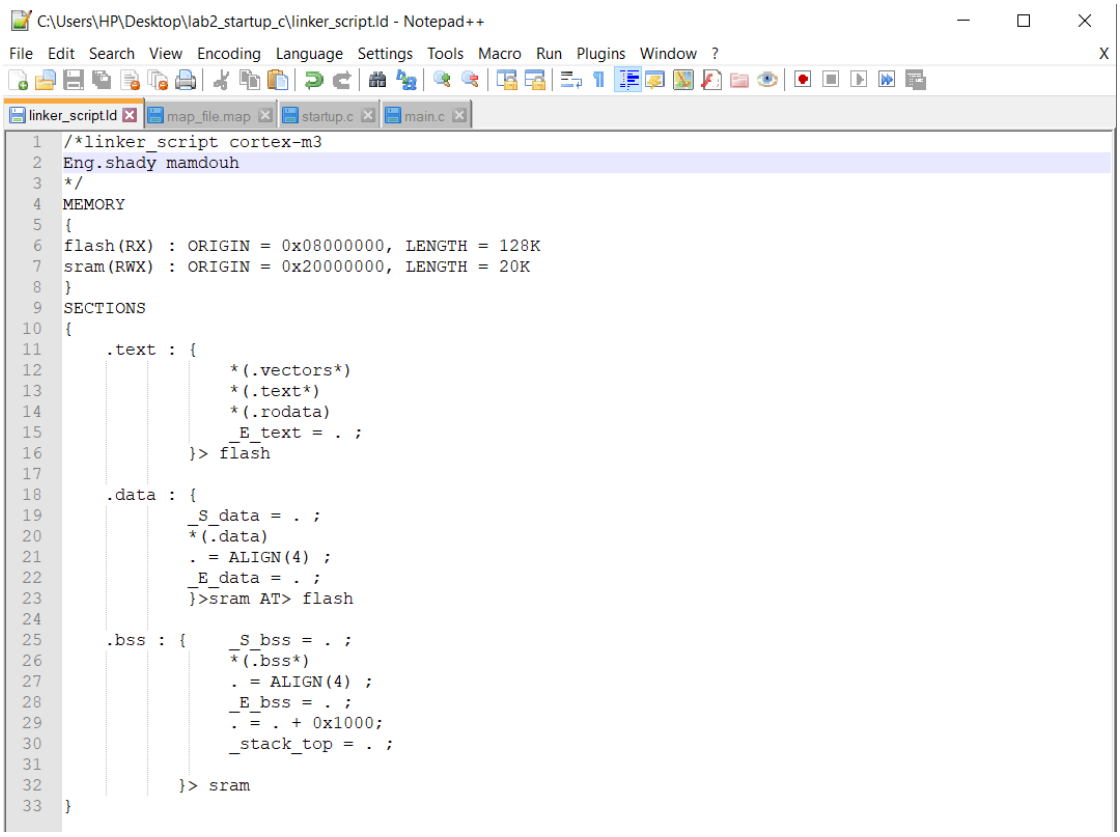


Lab2,part2

Startup.c

- As we mentioned before the reason that stop you from coding Startup.c is initializing stack because c codes use stack , so some boards have a feature allow you to initialize stack with just write the address that you want SP to point in the entry point of processor
- Board name : STM32f103c8t6 arm-cortex-m3 based .
- Flash starts with 0x08000000
- Sram starts with 0x20000000
- We want to make . text section starts with start of flash
  And contains . vectors section as a first section then other .text sections from all files
- .vectors section will contain SP and interrupt vector table
  So the first symbol in .vectors will be relative to the start of flash memory as we target .
- We want to copy .data section from flash to sram and initialize .bss section in sram.
- In linker script we will define some variables to make memory boundary at start and end of each section to help us to calculate the size of sections and to copy .data and create .bss in sram

Linker script :



- We made padding by 0x1000 memory locations in sram between .bss and stack top that will be used to create function stacks to avoid any crash .

Starup.c :

- We use attribute to pass commands to compiler to create section called .vectors and we make array of addresses that we want to be in this section
  This addresses represent SP and all interrupts vector table

- We use attribute of weak and alias vector handler to make all vectors point to default symbol and allow user to override with his own handler

```c
// startup.c
// Eng.Shady
#include <stdint.h>
extern int main(void);
extern unsigned int _E_text ;
extern unsigned int _S_data ;
extern unsigned int _E_data ;
extern unsigned int _S_bss ;
extern unsigned int _E_bss ;
extern unsigned int _stack_top ;
void Reset_Handler()
{    int i ;
    //we need to copy data section from flash to ram
    unsigned int DATA_size = (unsigned char*)&_E_data - (unsigned char*)&_S_data; // casting to
    unsigned char* p_src = (unsigned char*)&_E_text ;
    unsigned char* p_dst = (unsigned char*)&_S_data ;
    for (i=0; i< DATA_size; i++)
    {
        *((unsigned char*)p_dst++) = *((unsigned char*)p_src++);
    }
    // init .bss section in sram = 0
    unsigned int BSS_size = (unsigned char*)&_E_bss - (unsigned char*)&_S_bss;
    p_dst = (unsigned char*)&_S_bss;
    for (i=0; i< BSS_size; i++)
    {
        *((unsigned char*)p_dst++) = (unsigned char)0;
    }
    // jump main
    main();
}
void Default_handler()
{
    Reset_Handler();
}
void NMI_Handler() __attribute__ ((weak,alias("Default_handler")));;
void H_fault_Handler() __attribute__ ((weak,alias("Default_handler")));;
void MM_Fault_Handler() __attribute__ ((weak,alias("Default_handler")));;
void Bus_Fault() __attribute__ ((weak,alias("Default_handler")));;
void Usage_Fault_Handler() __attribute__ ((weak,alias("Default_handler")));;
uint32_t vectors[] __attribute__((section(".vectors")))= {
    (uint32_t) &_stack_top,
    (uint32_t) &Reset_Handler,
    (uint32_t) &NMI_Handler,
    (uint32_t) &H_fault_Handler,
    (uint32_t) &MM_Fault_Handler,
    (uint32_t) &Bus_Fault,
    (uint32_t) &Usage_Fault_Handler
};
```

Main.c :

- In main we defined H_fault_handler() to prove concept of overriding the default symbol and change the symbol address
- We defined uninitialized global variable to represent .bss section

linker_script.ld | map_file.map | startup.c | main.c

```
                    uint32_t pin20:1;
                    uint32_t pin21:1;
                    uint32_t pin22:1;
                    uint32_t pin23:1;
                    uint32_t pin24:1;
                    uint32_t pin25:1;
                    uint32_t pin26:1;
                    uint32_t pin27:1;
                    uint32_t pin28:1;
                    uint32_t pin29:1;
                    uint32_t pin30:1;
                    uint32_t pin31:1;

                    };

} reg_pin;
volatile reg_pin *APB2ENR=(volatile reg_pin*)(RCC_BASE+0x18);
volatile reg_pin *CRH=(volatile reg_pin*)(GPIO_BASE+0x04);
volatile reg_pin *PORTA=(volatile reg_pin*)(GPIO_BASE+0x0C);
unsigned char g_variables[3] = {1,2,3};
unsigned char const const_variables[3]={1,2,3};
unsigned char bss_var[3] ;
extern void H_fault_Handler()
{

}
int main(void)
{    volatile int i ;
    APB2ENR->pin2=1;
    CRH->all_pins=0;
    CRH->pin21=1;
    while(1)
    {    for(i=0;i<50000;i++){};
        PORTA->pin13=1;
        for(i=0;i<50000;i++);
        PORTA->pin13=0;
    }

}
```

C source file | length : 1,634 lines : 65 | Ln : 1 Col : 1 Sel : 0 | 0 | Windows (CR LF) | UTF-8 | INS

- lets make sure that everything is correct
  .text section has LMA equal VMA starts with 0x08000000
  As we want
  Because it hasn't been copied from flash to ram

- .data section has LMA within flash range and it will be copied to sram so it has VMA within start of sram as we want

- .bss section has VMA within sram range .

```
HP@DESKTOP-RR69RMG MINGW64 ~/Desktop/lab2_startup_c
$ arm-none-eabi-objdump.exe -h learn-in-depth_cortex_m3.elf

learn-in-depth_cortex_m3.elf:     file format elf32-littlearm

Sections:
Idx Name          Size      VMA       LMA       File off  Algn
  0 .text         00000133  08000000  08000000  00010000  2**2
                  CONTENTS, ALLOC, LOAD, READONLY, CODE
  1 .data         00000010  20000000  08000133  00020000  2**2
                  CONTENTS, ALLOC, LOAD, DATA
  2 .bss          00001004  20000010  08000143  00020010  2**2
                  ALLOC
  3 .debug_info   0000055f  00000000  00000000  00020010  2**0
                  CONTENTS, READONLY, DEBUGGING, OCTETS
  4 .debug_abbrev 000001e8  00000000  00000000  0002056f  2**0
                  CONTENTS, READONLY, DEBUGGING, OCTETS
  5 .debug_loc    000000f8  00000000  00000000  00020757  2**0
                  CONTENTS, READONLY, DEBUGGING, OCTETS
  6 .debug_aranges 00000040  00000000  00000000  0002084f  2**0
                  CONTENTS, READONLY, DEBUGGING, OCTETS
  7 .debug_line   00000304  00000000  00000000  0002088f  2**0
                  CONTENTS, READONLY, DEBUGGING, OCTETS
  8 .debug_str    00000277  00000000  00000000  00020b93  2**0
                  CONTENTS, READONLY, DEBUGGING, OCTETS
  9 .comment      0000004d  00000000  00000000  00020e0a  2**0
                  CONTENTS, READONLY
 10 .ARM.attributes 0000002d  00000000  00000000  00020e57  2**0
                  CONTENTS, READONLY
 11 .debug_frame  0000009c  00000000  00000000  00020e84  2**2
                  CONTENTS, READONLY, DEBUGGING, OCTETS
```

Lets see map file to get more details :

- H_fault_handler has address of 0x0800001c
  That is different from the default address of other handlers 0x08000124 to prove concept of overriding

- .vectors section at the start of flash

```
Memory Configuration

Name             Origin             Length             Attributes
flash            0x08000000         0x00020000         xr
sram             0x20000000         0x00005000         xrw
*default*        0x00000000         0xffffffff

Linker script and memory map


.text           0x08000000      0x133
 *(.vectors*)
 .vectors       0x08000000       0x1c startup.o
                0x08000000                vectors
 *(.text*)
 .text          0x0800001c       0x84 main.o
                0x0800001c                H_fault_Handler
                0x08000028                main
 .text          0x080000a0       0x90 startup.o
                0x080000a0                Reset_Handler
                0x08000124                MM_Fault_Handler
                0x08000124                Bus_Fault
                0x08000124                Usage_Fault_Handler
                0x08000124                Default_handler
                0x08000124                NMI_Handler
```

- .data section has load address of 0x08000133 in flash and 0x20000000 at the start of sram as we want
- .bss section starts with 0x20000010 and end at 0x20000013 And there is memory aligning occurred with 1 byte