

**Experimental Code and analysis:**1.1 Initialization to write code on MATLAB

clc;	Clear command window
close all;	Close one or more figures
clear all;	Remove items from workspace, freeing up system memory

1.2 Displaying image

image = imread('im1.jpg');	Read image from graphics file
figure (1), subplot(3,3,1),	
imshow( image),	Display image
title ('Original image');	
image=rgb2gray(image);	Convert RGB image or colormap to grayscale

1.3 Addition of noise

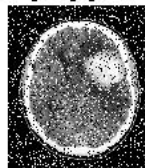
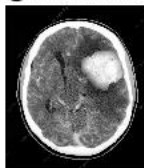
n1 = imnoise(image,'salt & pepper',0.2); subplot(3,3,2), imshow(n1), title('Salt & pepper noise');	Addition of Salt and pepper noise
n1 = imnoise(image,'gaussian',0.2,0.05); subplot(3,3,2), imshow(n1), title('Gaussian noise');	Addition of gaussian noise
n1 = imnoise(image,'poisson');	Addition of poisson noise
n1 = imnoise(image,'speckle',0.2); subplot(3,3,2), imshow(n1), title('Speckle noise');	Addition of speckle noise

1.4 Analysis SNR by using different filters on a noisy image

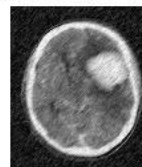
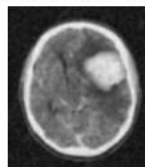
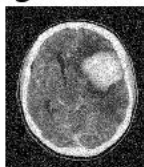
f1=fspecial('average',3) cf1=imfilter(n1,f1) subplot(3,3,4), imshow(cf1),	Average filter
f2=fspecial('disk',10) cf2=imfilter(n1,f2) subplot(3,3,5), imshow(cf2),	Disk filter
f3=fspecial('motion',20,45) cf3=imfilter(n1,f3) subplot(3,3,6), imshow(cf3), cf3=double(cf3(:));	Motion filter
f4= fspecial('laplacian',0.2) cf4=imfilter(n1,f4) subplot(3,3,7), imshow(cf4),	Gaussian filter
f5=fspecial('log',3,0.5)	Log filter

cf5=imfilter(n1,f5) subplot(3,3,8), imshow(cf5),	
f6= fspecial('gaussian',3,0.5) cf6=imfilter(n1,f6) subplot(3,3,7), imshow(cf6),	Laplacian filter
cf6=double(cf6(:)); imm=mean(cf6(:)); ims=std(cf6(:)); b6 = 10*log((imm)./ims) title(['Laplacian filter = ' num2str(round(b6,2))]);	SNR calculation

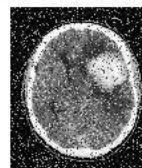
**Original image      Salt & pepper noise**



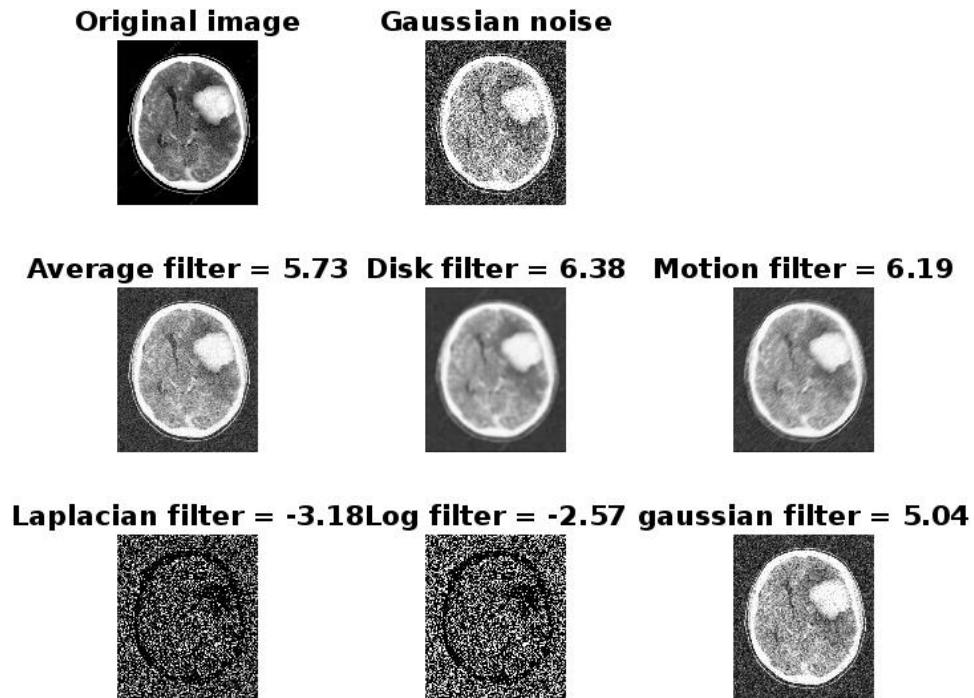
**Average filter = 2.3    Disk filter = 3.33    Motion filter = 3.02**



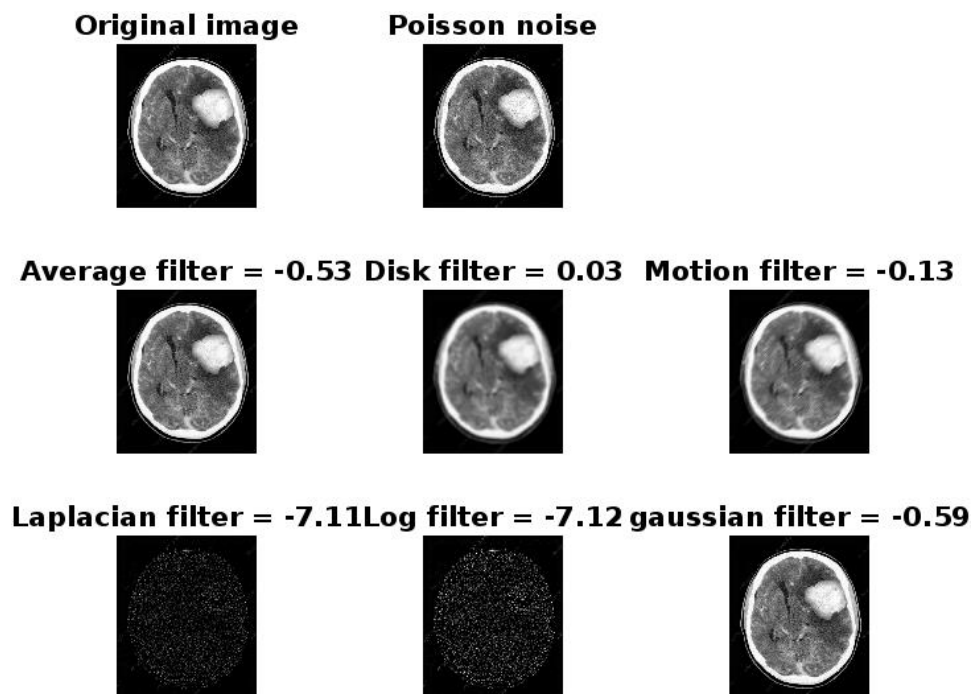
**Laplacian filter = -3.78    Log filter = -2.64    gaussian filter = 0.99**



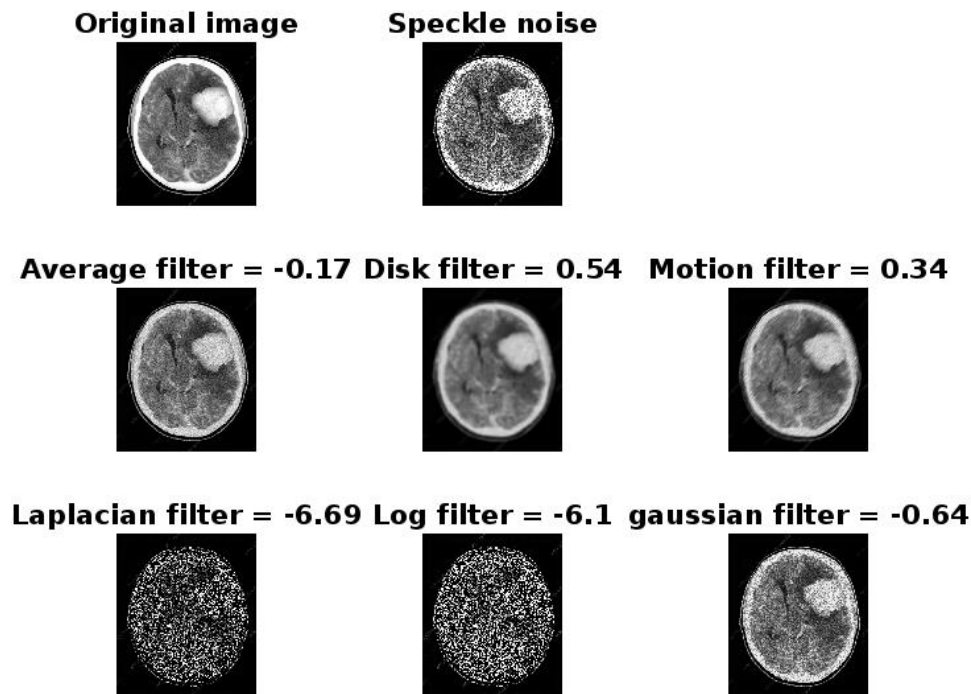
**Figure 1.4.1** Analysis SNR by using different filters on an image with salt and pepper noise



**Figure 1.4.2** Analysis SNR by using different filters on an image with gaussian noise



**Figure 1.4.3** Analysis SNR by using different filters on an image with Poisson noise



**Figure 1.4.4** Analysis SNR by using different filters on an image with Speckle noise

### 1.5 Detection of edge in image

image = imread('im2.jpg'), image=rgb2gray(image);	
[BW,threshOut] = edge(image)	It returns the threshold value
edge_prewitt=edge(image,'prewitt',threshOut) edge_sobel=edge(image,'sobel',threshOut) edge_roberts=edge(image,'roberts',threshOut) edge_canny=edge(image,'canny',threshOut)	It returns all edges that are stronger than threshold.
figure(1), imshow(image), title('Original image'); figure(2), imshow(edge_prewitt), title('Edge detection using prewitt operator'); figure(3), imshow(edge_sobel), title('Edge detection using sobel operator'); figure(4), imshow(edge_roberts), title('Edge detection using roberts operator'); figure(5), imshow(edge_canny), title('Canny edge detection');	

### Original image



Figure 1.5.1 Original Image

### Edge detection using prewitt operator



Figure 1.5.2 Edge detection using Prewitt operator

### Edge detection using sobel operator



Figure 1.5.3 Edge detection using Sobel operator

### Edge detection using roberts operator



Figure 1.5.4 Edge detection using Roberts operator

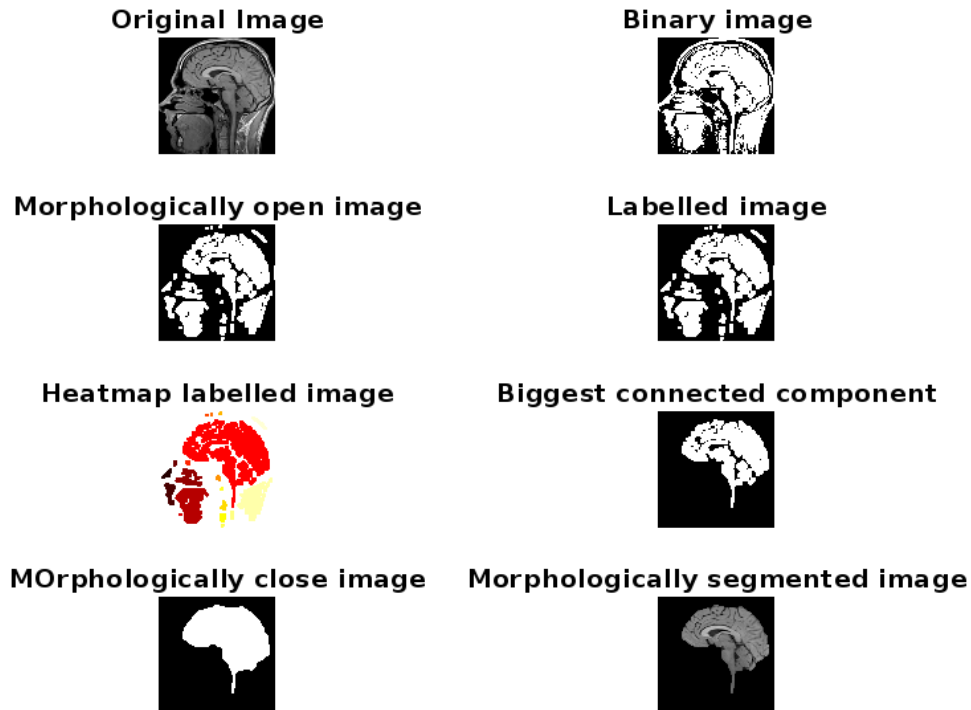
### Canny edge detection



Figure 1.5.5 Canny edge detection

#### 1.6 Image segmentation using morphological operations

<code>k=imread('im4.png');</code> <code>figure(1),</code> <code>subplot(4,2,1),imshow(k),title('Original Image');</code>	
<code>k1=im2bw(k,graythresh(k));</code> <code>subplot(4,2,2), imshow(k1); title('Binary image');</code>	It converts image to binary image, based on threshold
<code>SE=strel('disk',7,4);</code> <code>k2=imopen(k1,SE);</code> <code>subplot(4,2,3), imshow(k2), title('Morphologically open image');</code>	It converts small white portions or a bunch of bright pixels into dark portions without changing the size of a larger dark portion.
<code>b=bwlabel(k2);</code> <code>subplot(4,2,4), imshow(b), title('Labelled image');</code>	Label connected components in 2-D binary image
<code>b1=label2rgb(b,'hot','w')</code> <code>subplot(4,2,5), imshow(b1), title('Heatmap labelled image');</code>	It specifies the colormap cmap to be used in the RGB image and the RGB color of the background elements as white.
<code>b(b~=7)=0</code> <code>b(b==7)=1</code> <code>subplot(4,2,6), imshow(b), title('Biggest connected component');</code>	brain is component labeled as 7. Set all other component as 0 except brain.
<code>k3=imclose(b,strel('disk',18));</code> <code>subplot(4,2,7), imshow(k3), title('MORphologically close image');</code>	It converts small black portions or a bunch of dark pixels into bright portions without changing the size of the larger white portion.
<code>x=im2double(k)</code> <code>k4=k3.*x</code> <code>subplot(4,2,8), imshow(k4), title('Morphologically segmented image');</code>	Extract the brain image from original image



**Figure 1.6.1** Brain extracted from the original image using morphological operation

### 1.7 Image segmentation using K-means cluster

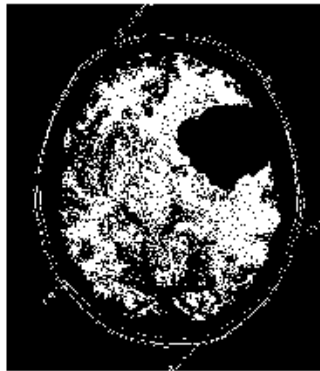
```
a=rgb2gray(imread('im1.jpg'))
imData = reshape(a,[],1);
imData = double(imData);
[IDX nn]=kmeans(imData,4);
imIDX=reshape(IDX,size(a));
figure(1),
subplot(2,2,1),imshow(imIDX==1,[], title('Observation 1'));
subplot(2,2,2),imshow(imIDX==2,[], title('Observation 2'));
subplot(2,2,3),imshow(imIDX==3,[], title('Observation 3'));
subplot(2,2,4),imshow(imIDX==4,[], title('Observation 4'));
```

```
bw=(imIDX==2);
se=ones(5);
bw=imopen(bw,se);
bw=bwareaopen(bw,100);
bw=~bw
figure(2),imshow(bw), title('K means clustering');
```

```
mask = false(size(a));
mask(25:end-25,25:end-25) = true;
a_new = activecontour(a, mask, 300);
similarity = dice(a_new, bw);
figure(3)
imshowpair(a_new, bw)
title(['Dice Index = ' num2str(similarity)])
```



**Observation 1**



**Observation 2**



**Observation 3**

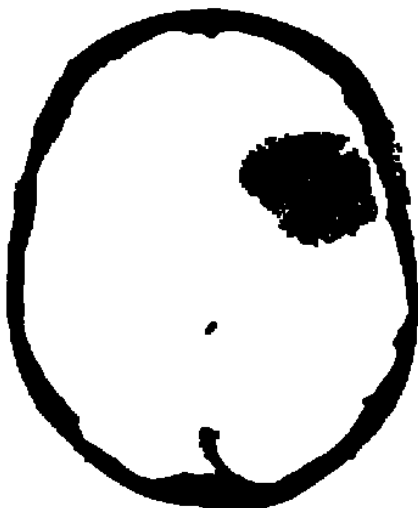


**Observation 4**



**Figure 1.7.1** Observative steps for K-means clustering

**K means clustering**



**Dice Index = 0.61721**

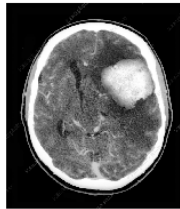


**Figure 1.7.2** Dice score of the segmented image for K-means clustering

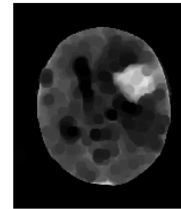
1.8 Image segmentation using watershed algorithm

<pre>img=imread("im1.jpg") img=rgb2gray(img) figure(1), subplot(3,2,1), imshow(img), title('Original image');</pre>	
<pre>se = strel('disk',20); tophatFiltered = imerode(img,se); subplot(3,2,2), imshow(tophatFiltered) , title('Eroded image');</pre>	Create the structuring element and perform erosion operation and display the image
<pre>c contrastAdjusted = imadjust(tophatFiltered); subplot(3,2,3), imshow(contrastAdjusted) , title(' Contrast adjusted image');</pre>	Use imadjust to improve the visibility of the result
<pre>level=0.6 bw = im2bw(contrastAdjusted,level) subplot(3,2,4), imshow(bw), title('Binary image');</pre>	Select the threshold level
<pre>c=~bw subplot(3,2,5), imshow(c),title('Altered image'); d=-bwdist(c) d(c)=-Inf l=watershed(d) wi=label2rgb(l,'hot','w') subplot(3,2,6), imshow(wi), title('Heatmap labeled watershed');</pre>	
<pre>im=img im(l==0)=0; figure(2), imshow(im),title('Image segmented using watershed algorithm');</pre>	
<pre>mask = false(size(img)); mask(25:end-25,25:end-25) = true; BW = activecontour(img, mask, 300); im=imbinarize(im); similarity = dice(BW, im); figure(3) imshowpair(BW, im) title(['Dice Index = ' num2str(similarity)])</pre>	

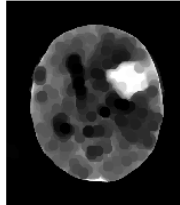
**Original image**



**Eroded image**



**Contrast adjusted image**



**Binary image**



**Altered image**

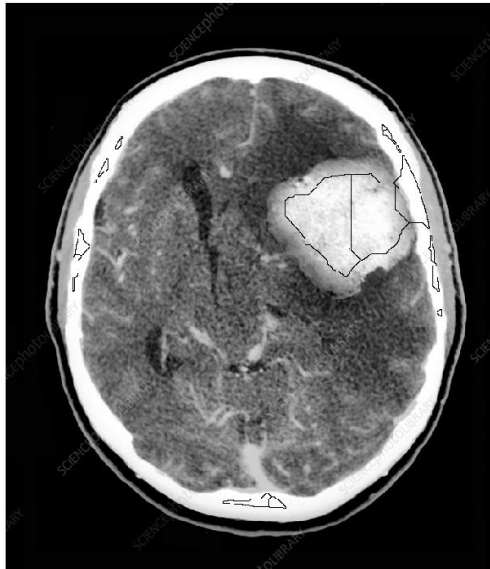


**Heatmap labeled watershed**

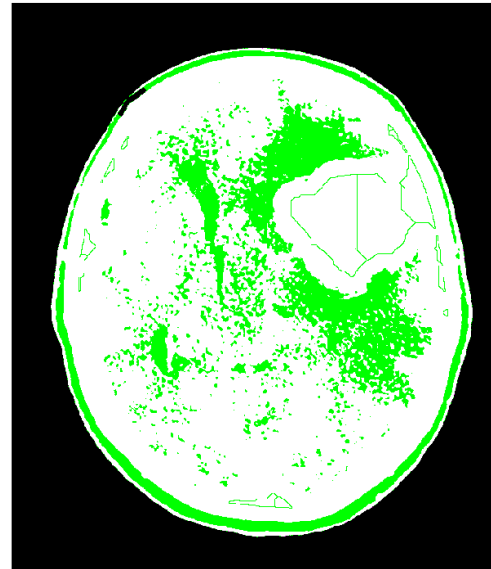


**Figure 1.8.1** Observative steps for watershed algorithm

**Image segmented using watershed algorithm**



**Dice Index = 0.87196**



**Figure 1.8.2** Dice score of the segmented image for watershed algorithm