



PMPH project

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Introduction and OpenMP

- Optimized CUDA
- A Results



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Introduction and OpenMP High level code structure:

```
for each i in outer { // parallel loop
    init.Glob
    initOperator dxx
    initOperator dyy
    setPayoff
    for each t in time { // sequential loop
        updateParams
        explicitX
        explicitY
        implicitX
        tridag
        implicitY
        tridag
```

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Loop distribution

```
for each i in outer { // parallel loop
    init.Glob
    initOperator dxx
    initOperator dyy
    setPayoff
    for each t in time { // sequential loop
        updateParams
        explicitX
        explicitY
        implicitX
        tridag
        implicitY
        tridag
```



Loop distribution

```
deviceInit.Glob
deviceInitOperator dxx
deviceInitOperator dyy
deviceSetPayoff
for each i in outer { // parallel loop
    for each t in time { // sequential loop
        updateParams
        explicitX
        explicitY
        implicitX
        tridag
        implicitY
        tridag
```



Loop interchange

```
deviceInit.Glob
deviceInitOperator dxx
deviceInitOperator dyy
deviceSetPayoff
for each i in outer { // parallel loop
      updateParams
      explicitX
      explicitY
      implicitX
      tridag
      implicitY
      tridag
```



Loop distribution

```
deviceInit.Glob
deviceInitOperator dxx
deviceInitOperator dyy
deviceSetPayoff
for each t in time {
                            // sequential loop
    deviceUpdateParams
    deviceExplicitX
    deviceExplicitY
    deviceImplicitX
    tridag solver
    deviceImplicitY
    tridag solver
```



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Memory coalescing

```
deviceExplicitX // computes the transpose of u
deviceExplicitY // writes directly to the transpose of u
deviceImplicitX // computes the transpose of a, b and c
transpose u, a, b and c
tridag_solver
transpose u
deviceImplicitY // reads from the transpose of u
tridag solver
```



Other optimizations

· Re-usage of shared memory (tridag)

Reduction of global memory accesses

Reduction of floating point operations



ExplicitX naïve

```
// u[outer][numY][numX]
int uindex = i*numY*numX + k*numX + j;
// myVarX [outer][numX][numY]
int mvVarXindex = i*numX*numY + i * numY + k;
// myResult[outer][numX][numY]
u[uindex] = dtInv * myResult[myVarXindex];
// Dxx [outer][numX][4]
int Dxxindex = i*numX*4 + j*4;
REAL varX = myVarX[myVarXindex];
if (j > 0) {
   u[uindex] += 0.5*(0.5*varX*myDxx[Dxxindex])
                     * myResult[i*numX*numY + (j-1)*numY + k];
u[uindex] += 0.5*(0.5*varX*myDxx[Dxxindex+1])
                     * myResult[myVarXindex];
if (i < numX) {
   u[uindex] += 0.5*(0.5*varX*myDxx[Dxxindex+2])
                     * myResult[i*numX*numY + (j+1)*numY + k];
```



ExplicitX coalesced



ExplicitX optimized

```
// u[outer][numX][numY]
int idx0 = i*numX*numY;
int idx = idx0 + j*numY + k;
// mvResult[outer][numX][numY]
REAL uval;
uval = dtInv * myResult[idx];
// Dxx [outer][numX][4]
int Dxxindex = i*numX*4 + j*4;
REAL varX = 0.25*myVarX[idx];
if (j > 0) {
   uval += (varX*myDxx[Dxxindex])
                    * myResult[idx0 + (j-1)*numY + k];
nval +=
            (varX*myDxx[Dxxindex+1])
                    * myResult[idx];
if (i < numX) {
   uval += (varX*myDxx[Dxxindex+2])
                    * myResult[idx0 + (j+1)*numY + k];
u[idx] = uval:
```



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Results

- All versions validate on the small and large datasets
- Results obtained by executing on one of the APL GPU machines

Version	Total execution	on time (microseconds) Large
Sequential CPU	2,297,659	216,305,907
OpenMP CPU	213,948	10,132,446
Naïve CUDA	92,787	6,975,193
Optimized CUDA	60,867	3,647,836

Table: Results of the three different implementations.

