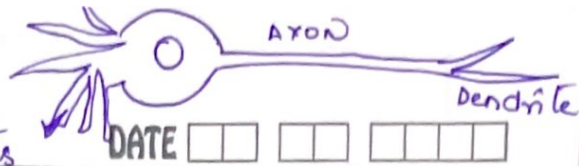
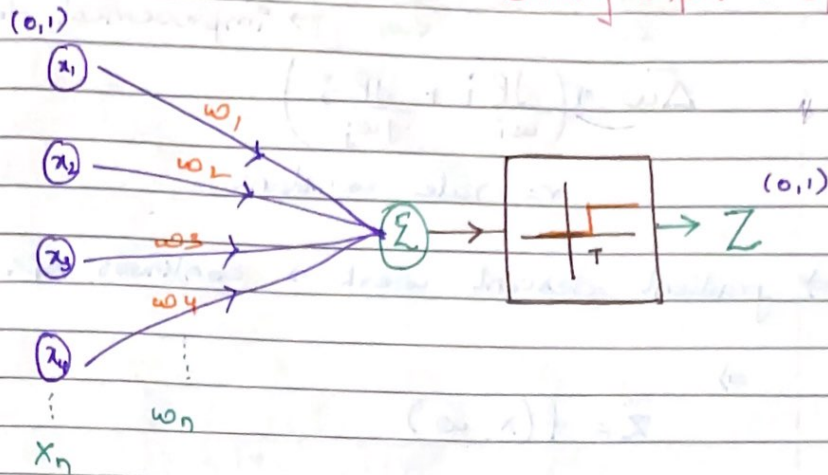


Neural Nets

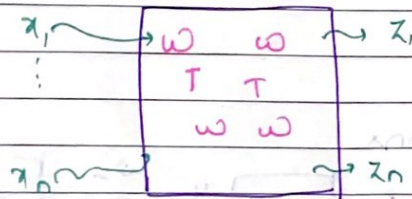


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Binary Input = 0/1

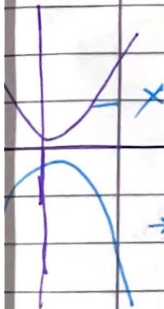


1. All or Non
2. Cumulative influence
3. SYNAPTIC weight
4. Refraction Period



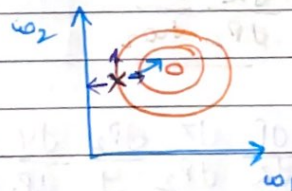
$$\bar{Z} = f(x, w, T) \rightarrow \text{function approximator}$$

$$\bar{d} = g(x)$$



$$P = \|\bar{d} - \bar{Z}\| \rightarrow \text{Performance function}$$

→ To get a uphill, instead of downhill



instead of taking step in every direction
Take some partial derivatives

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$$\frac{dP}{d\omega_1}, \frac{dP}{d\omega_2} \xrightarrow{\omega_2 > \omega_1} \text{improvement, done}$$

$$\Delta\omega = r \left(\frac{dP}{d\omega_1} + \frac{dP}{d\omega_2} \right)$$

$r =$ rate constant

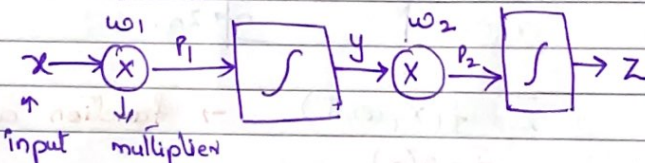
\Rightarrow gradient descent work \rightarrow continuous space

\Rightarrow

$$\bar{z} = f(x, \omega)$$

Sigmoid :-

\Rightarrow Two neurons



$$P = -\frac{1}{2}(d-z)^2$$

$d =$ desired o/p

$Z =$ actual o/p

Partial derivative using chain rule

$$\frac{dP}{d\omega_2} = \frac{dP}{dz} \frac{dz}{d\omega_2} \rightarrow \frac{dZ}{dP_2} \frac{dP_2}{d\omega_2}$$

$$\frac{dP_1}{d\omega_1} = \frac{dP}{dZ} \frac{dZ}{dP_2} \frac{dP_2}{dy} \frac{dy}{dP_1} \frac{dP_1}{d\omega_1}$$

$$\frac{dP_2}{d\omega_2} = \frac{dP_2^{(y)}}{d\omega_2} \frac{dZ}{dP_2} \frac{dP_1}{dZ} \frac{dP_1}{dZ}$$

$$\beta = \frac{1}{1+e^{-\alpha}} ; \text{ derivative with } \alpha$$

$$\frac{d\beta}{d\alpha} = \frac{d(1+e^{-\alpha})^{-1}}{d\alpha}$$

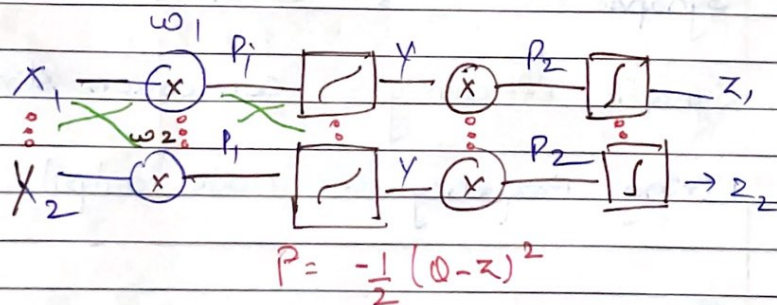
$$= (1+e^{-\alpha})^{-2} \cdot (-e^{-\alpha})$$

$$= \frac{1+e^{-\alpha}-1}{1+e^{-\alpha}} \times \frac{1}{1+e^{-\alpha}}$$

$$= \left(\frac{1+e^{-\alpha}}{1+e^{-\alpha}} - \frac{1}{1+e^{-\alpha}} \right) \left(\frac{1}{1+e^{-\alpha}} \right)$$

$$= \beta(1-\beta)$$

$\Rightarrow z(1-z) \rightarrow \text{O/p} \rightarrow \text{Sigmoid}$



\Rightarrow A repetition occurs

influences of fast fourier transform

1. Linear in depth
 2. w.r. width = $w/2$

\Rightarrow reuse principle:-

Presynaptic → neuron that Sends Signal
 Postsynaptic → neuron that receives

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Artificial Neuron

Synaptic contacts

1. Excitatory - asymmetrical membrane thickening → Postsynaptic
2. Inhibitory - symmetrical

Strength of connections = Efficiency of Synaptic Transmission

Threshold of Neuron = net excitation exceeds its inhibition by critical amount.

Refractory Period = Neuron is inactive

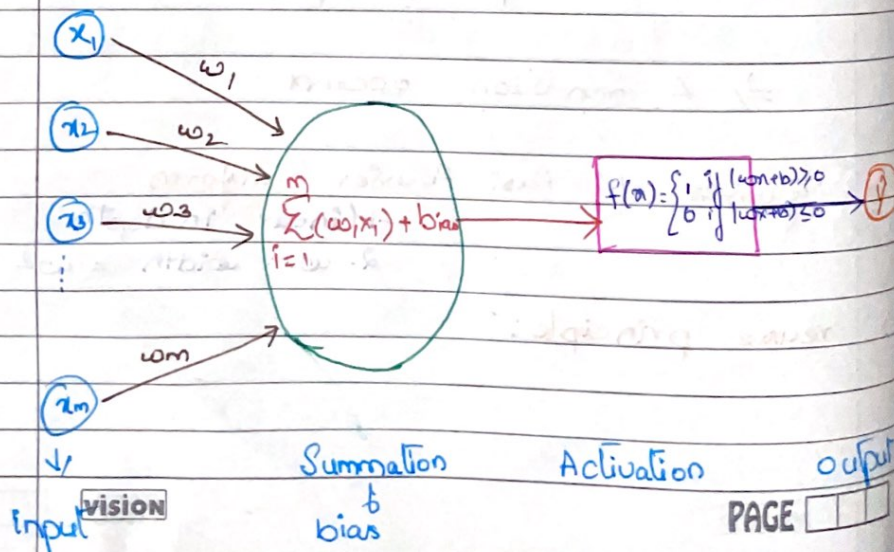
output of Neuron = 1. strong input
 2. strong frequency

Neuron = Node / cell / unit

Synapse = Connection

Synaptic Efficiency = Connection strength.

Firing frequency = Node output



Activation function :- o/p of neuron, given set of inputs.

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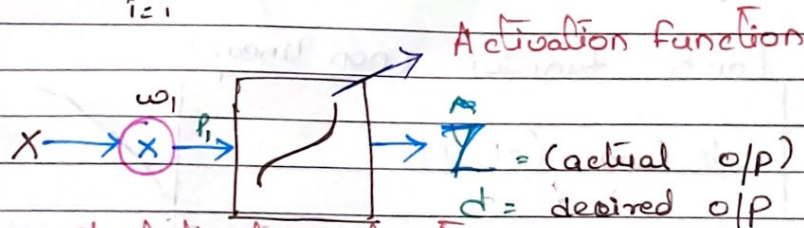
Back Propagation : Repeatedly adjust the weights to minimize difference between d and z

Hidden layers : Neuron nodes stacked in between inputs

$$W \cdot X = w_1 x_1 + w_2 x_2 + \dots + w_m x_m$$

$$= \sum_{i=1}^m w_i x_i$$

$$Z = \sum_{i=1}^m w_i x_i + \text{bias}$$



Types of Activation function

⇒ Sigmoid function =

Exclude

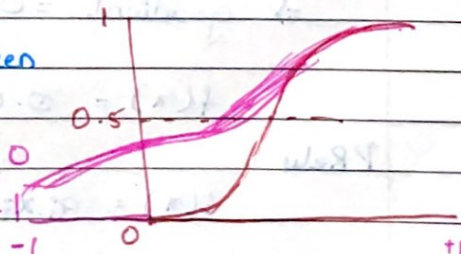
$$Z = \frac{1}{2} (d - z)$$

$$Z = \sum_{i=1}^m w_i x_i + b_i$$

$$\sigma(z) = \frac{1}{1 + e^{-z}} \Rightarrow \text{Sigmoid function}$$

⇒ Transform value between 0 to 1

⇒ if less than 0.5 - o/p = 0
more than 0.5 - o/p = 1



⇒ classification problem.

if i/p values are increased, o/p becomes
 stagnant (inactive)
 → Vanishing Gradient

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(2) Relu AF (Rectified Linear unit)

$$f(x) = \begin{cases} x_i, & \text{if } x_i > 0 \\ 0, & \text{if } x_i < 0 \end{cases}$$

$$\max(x, 0)$$

if x is -ve → $\max(-ve, 0)$

→ o/p = 0

if x is +ve → $\max(+ve, 0)$

→ o/p = +ve

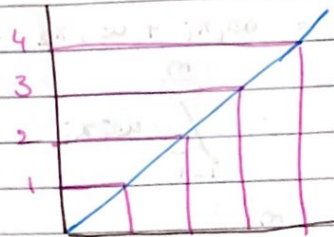
number

⇒ Regression

⇒ Problem use

Relu, less

computation

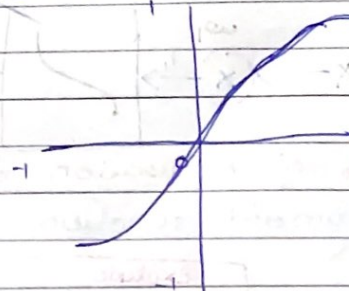


disadvantage :- if -ve, zero value, gets stuck

(3) tanh function (non-linear)

⇒ Range $(-1, 1)$

⇒ zero-centered



(4) Leaky ReLU

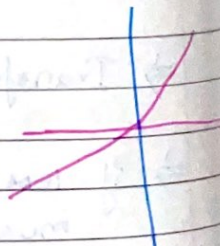
→ Dead Neurons (due to -ve value)

⇒ gradient = 0 if $x < 0$

$$f(x) = 0.01x, \quad x < 0$$

PReLU

$$f(x) = q_i x_i$$



Leaky Rectified Linear Unit, or Leaky ReLU, is a type of activation function based on a ReLU, but it has a small slope for negative values instead of a flat slope. ... This type of activation function is popular in tasks where we may suffer from sparse gradients, for example training generative adversarial networks.