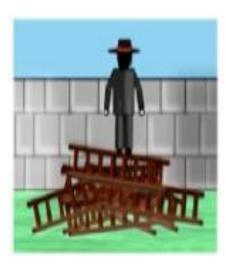
Platforms to handle Big data

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Objective of the lecture

- Right platform
- Need of the application/algorithm
- Right decision



- How quickly do we need to get the results?
- How big is the data to be processed?
- Does the model building require several iterations or single iteration?

System/platform level requirements

- Will there be a need for more data processing capability in the future?
- Is the rate of data transfer critical for this application?
- Is there a need for handling hardware failures within the application?

Horizontal Scaling

- It involves distributing the workload across many servers which may be even commodity machines.
- It is also known as "scale out", where multiple independent machines are added together in order to improve the processing capability.
- Typically, multiple instances of the operating system are running on separate machines.

Vertical Scaling

- Vertical Scaling involves installing more processors, more memory and faster hardware, typically, within a single server.
- It is also known as "scale up" and it usually involves a single instance of an operating system.

Table 1 A comparison of advantages and drawbacks of horizontal and vertical scaling

Scaling	Advantages	Drawbacks
Horizontal scaling	→ Increases performance in small steps as needed	→ Software has to handle all the data distribution and parallel processing complexities
	→ Financial investment to upgrade is relatively less	→ Limited number of software are available that can take advantage of horizontal scaling
	→ Can scale out the system as much as needed	
Vertical scaling	→ Most of the software can easily take advantage of vertical scaling	→ Requires substantial financial investment
	→ Easy to manage and install hardware within a single machine	→ System has to be more powerful to handle future workloads and initially the additional performance in not fully utilized
		→ It is not possible to scale up vertically after a certain limit

Financial Investment : low - high Limit of scalling : not fixed - fixed

Software handling: complex, limited can do - easily, most of can do performance: increase in small step - initially not fully utilized

Horizontal Scaling Platforms

- Peer-to-Peer Network
- Apache Hadoop
- Apache Spark

Vertical Scaling Platforms

- High performance computing clusters
- Multicore CPU
- Graphics Processing Unit(GPU)
- Field Programmable gate arrays(FPGA)

Peer-to-Peer networks

- involve millions of machines connected in a network
- <u>decentralized</u> and <u>distributed</u> network architecture where the nodes in the networks (known as peers) serve as well as consume resources.
- oldest distributed computing platforms
- Message Passing Interface (MPI) for communication scheme used in such a setup to communicate and exchange the data between peers.
- Each node can store the data instances and the scale out is practically unlimited (can be millions of nodes).

Apache Hadoop

- open source framework for storing and processing large datasets using <u>clusters of commodity</u> hardware.
- Hadoop is designed to scale up to hundreds
- highly <u>fault tolerant</u>
- The Hadoop platform contains the following two important

```
components: (1) HDFS (2) YARN
```

Scalability
Compatibility
Cluster Utilization
Multi-tenancy

Apache Spark

- developed by researchers at the University of California at Berkeley. designed to overcome the disk I/O limitations
- ability to perform in-memory computations.
- allows the data to be cached in memory, thus eliminating the
- Hadoop's disk overhead limitation for iterative tasks.
- supports Java, Scala and Python and for certain tasks
- it is tested to be up to 100× faster than Hadoop MapReduce

HPC clusters

- Known as blades or <u>supercomputers</u>, are machines with thousands of cores.
- They can have a different variety of disk organization, cache,
 communication mechanism etc.
- powerful hardware which is optimized for speed and throughput.
- They are not as scalable as Hadoop or Spark clusters but they are still capable of processing terabytes of data.

Multicore CPU

- Multicore refers to one machine having dozens of processing cores
 They usually have shared memory but only one disk.
- the number of cores per chip and the number of
- operations that a core can perform has increased significantly.
 Newer breeds of motherboards allow multiple CPUs within a single machine thereby increasing the <u>parallelism</u>.
- Until the last few years, CPUs were mainly responsible for accelerating the algorithms for big data analytics.

GPU

- It is designed to accelerate the <u>creation of images</u> in a frame buffer intended for display output
- GPUs were primarily used for graphical operations such as video and image editing, accelerating graphics-related processing etc. due to their massively <u>parallel</u> <u>architecture</u>, recent developments in GPU hardware and related programming frameworks have given rise to <u>GPGPU</u>
- In addition to the processing cores, GPU has its own high throughput <u>DDR5</u> memory which is many times faster than a typical DDR3 memory.

FPGA

- highly specialized hardware units for specific applications
- FPGAs can be highly optimized for <u>speed</u> and can be orders of magnitude faster compared to other platforms for certain applications.
- Due to customized hardware, the <u>development cost is typically</u> much higher compared to other platforms.
- On the software side, coding has to be done in HDL with a lowlevel knowledge of the hardware which increases the algorithm development cost.

Comparison of platforms

System/Platform Level characteristics

- Scalability Horizontal scaling application boosts
- Data I/O performance Vertical scaling boosts
- Fault Tolerance Only peer to peer is worst otherwise all are good

Scalability

Platform	Scalability
Peer-to-Peer	* * * *
Virtual Clusters (MapReduce/MPI)	* * * *
Virtual Clusters(Spark)	* * * *
HPC clusters (MPI/MapReduce)	* * *
Multicore(Multithreading)	* *
GPU(CUDA)	* *
FPGA(HDL)	*

Data I/O Performance

Platform	Data I/O performance
Peer-to-Peer	*
Virtual Clusters(MapReduce/MPI)	* *
Virtual Clusters(Spark)	* * *
HPC clusters (MPI/MapReduce)	* * * *
Multicore(Multithreading)	* * * *
GPU(CUDA)	* * * *
FPGA(HDL)	* * * *

Fault Tolerance

Platform	Fault Tolerance
Peer-to-Peer	*
Virtual Clusters (MapReduce/MPI)	* * * *
Virtual Clusters(Spark)	* * * *
HPC clusters (MPI/MapReduce)	* * * *
Multicore(Multithreading)	* * * *
GPU(CUDA)	* * * *
FPGA(HDL)	* * * *

Comparison of platforms

Application/Algorithm Level characteristics

Real time processing Vertical is good and s

Vertical is good and specifically GPU and FPGA

Data size supported

Horizontal is good and peer to peer best as it contains billion of nodes resulting in an infinite amount of storage

Iterative task support

Vertical is good

Real Time Processing

Platform	Real Time Processing
Peer-to-Peer	*
Virtual Clusters(MapReduce/MPI)	* *
Virtual Clusters(Spark)	* *
HPC clusters (MPI/MapReduce)	* * *
Multicore(Multithreading)	* * *
GPU(CUDA)	* * * *
FPGA(HDL)	* * * *

Data Size supported

Platform	Data Size supported
Peer-to-Peer	* * * *
Virtual Clusters(MapReduce/MPI)	* * * *
Virtual Clusters(Spark)	* * * *
HPC clusters (MPI/MapReduce)	* * * *
Multicore(Multithreading)	* *
GPU(CUDA)	* *
FPGA(HDL)	* *

Iterative Task Support

Platform	Iterative task support
Peer-to-Peer	* *
Virtual Clusters(MapReduce/MPI)	* *
Virtual Clusters(Spark)	* * *
HPC clusters (MPI/MapReduce)	* * * *
Multicore(Multithreading)	* * * *
GPU(CUDA)	* * * *
FPGA(HDL)	* * * *

Peer-to-Peer

ADVANTAGES

·Handle huge data.

DISADVANTAGES

- Communication is Slower.
- •Not suitable for iterative algorithms.
- ·Fault-intolerant.

Virtual Clusters using Map/Reduce:

ADVANTAGES

- ·Fault-Tolerant.
- Scalable.

DISADVANTAGES

- •Takes time to handle large amount of data.
- Not suitable for iterative algorithms.

Virtual Clusters using Spark:

ADVANTAGES

DISADVANTAGES

In-memory computations.

Not optimal for real time processing tasks.

Data is cached in the memory.

High Performance Computing Cluster

ADVANTAGES

DISADVANTAGES

·Fault tolerance.

•Expensive.

Multicore CPU's

ADVANTAGES

·Parallel operations.

DISADVANTAGES

- *DDR3 slower.
- *Limited number of cores in CPU.

Graphics Processing Unit's

ADVANTAGES

- High throughput memory.
- DDR5 memory faster.
- Well suited for real-time applications.

DISADVANTAGES

- Limited software that supports GPU.
- *Limited algorithms that are portable to GPU's.
- •Memory Constraints, less likely to be scalable.

Field Programmable Gate Arrays(FPGA)

ADVANTAGES

·Highly optimized speed, faster.

DISADVANTAGES

- Limited number of applications.
- Limited amount of memory.
- Expensive and Complex.

How will you choose one of platform for a particular criteria?

Amount of Time

Criterion: 'Amount of time'

Choice Made: GPU

Reasons:

- 1) Optimized for Speed
- 2) Thousands of processing cores
- 3) High memory bandwidth, uses DDR5
- 4) Widely used in many machine learning Algorithms

Number of Iterations

Choice Made: GPU

Reasons:

1) Elimination of Data to be read/write from disc.

2) Data is processed in threads, multi core processing.

Practically proved with k-means algorithm.

Fault Tolerance

Definition: Fault tolerance is the ability of the system to perform properly in case of any of its components failure.

- Virtual Clusters (Map Reduce & Spark): Built-in fault tolerance mechanism.
- *Multicore CPU, GPU, FPGA: Very rarely prone to hardware failures.
- Peer-to-Peer: No built-in fault tolerance mechanism, Uses commodity machines which are highly probable for hardware failures.

Scalability

- Definition: Scalability is defined as the ability of the system to cope up with the increased demands in data processing.
- Virtual clusters, Peer-to-Peer networks: Easy to scale out.
- •High performance Computing Cluster, FPGA: Once deployed, expensive to scale up.
- •GPU: Limitations on # of GPU's a machine can have makes it not effectively scalable.

Choice of platform

- Data size
- Speed/Throughput
- Training /Applying a model

K means clustering

The k-means Clustering Algorithm

Input: Data points D, Number of clusters k

Step 1: Initialize k centroids randomly

Step 2: Associate each data point in D with the nearest centroid. This will divide the data points into k clusters.

Step 3: Recalculate the position of centroids.

Repeat steps 2 and 3 until there are no more changes in the membership of the data points

Output: Data points with cluster memberships

K-means on MapReduce

k-means::Map

Input: Data points D, number of clusters k and centroids

1: for each data point d € D do

Assign d to the closest centroid

Output: centroids with associated data points

k-means::Reduce

Input: Centroids with associated data points

1: Compute the new centroids by calculating the average of data points in cluster

2: Write the global centroids to the disk

Output: New centroids

K-means on MPI

k-means::MPI

Input: Data points D, number of clusters k

1: Slaves read their part of data

2: do until global centroids converge

Master broadcasts the centroids to the slaves

4: Slaves assign data instances to the closest centroids

5: Slaves compute the new local centroids and local cluster sizes

Slaves send local centroids and cluster sizes to the master

7: Master aggregates local centroids weighted by local cluster sizes into global centroids.

Output: Data points with cluster memberships

K-means on GPU

k-means::GPU

Input: Data points D, number of clusters k

1: do until global centroids converge

2: Upload data points to each multiprocessor and centroids to the shared memory

 Multiprocessor works with one data vector at a time and associate it with the closest centroid

4: Centroid recalculation is done on CPU