

# A Case Study on Identifying Bifurcation and Chaos with CROCKER Plots

Ismail Güzel  
(join with Elizabeth Munch, Firas Khasawneh)

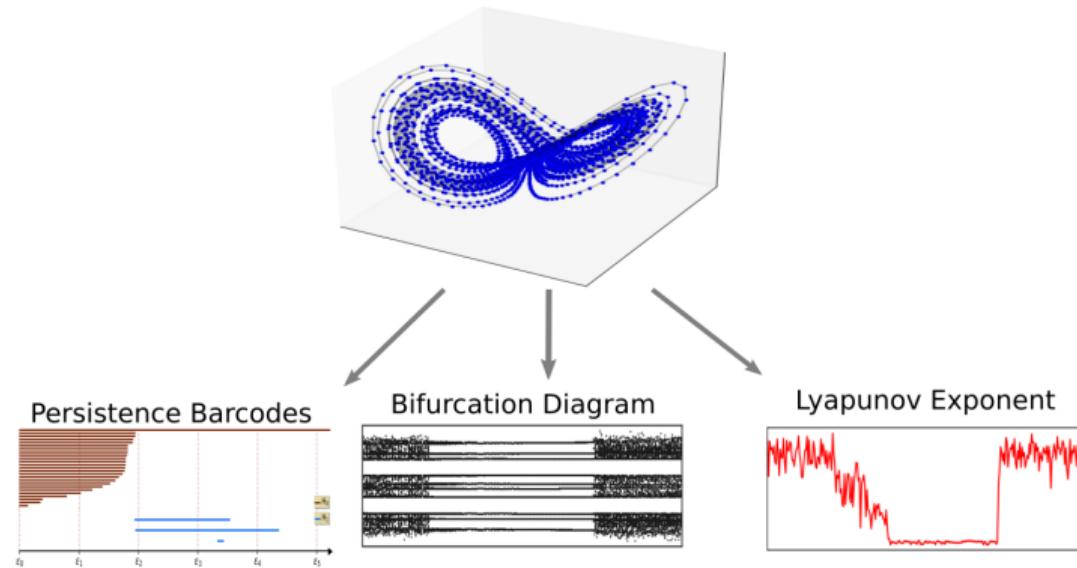
İTÜ-Math. & MSU-CMSE

April 28, 2022



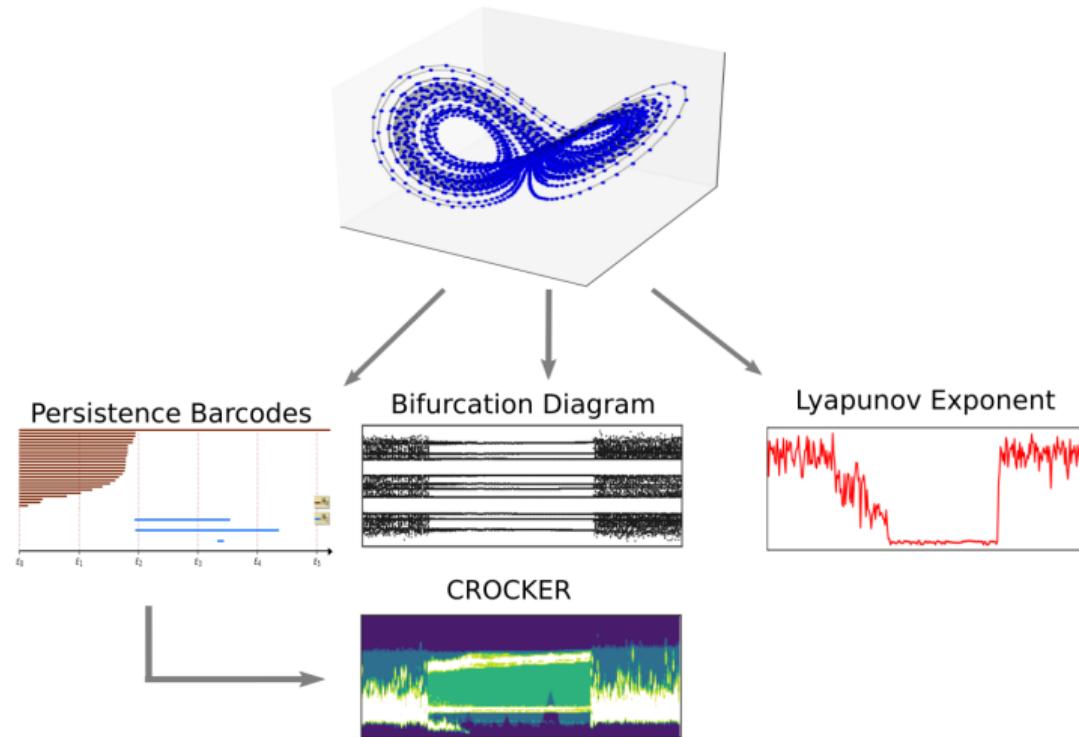
# Outline

- 1 **Dynamical System**
  - Bifurcation Diagram
  - Lyapunov Exponent
- 2 **Topological Features**
- 3 **CROCKER**
  - Norm of CROCKER
- 4 **Experiments**
  - Rössler System
  - Lorenz System



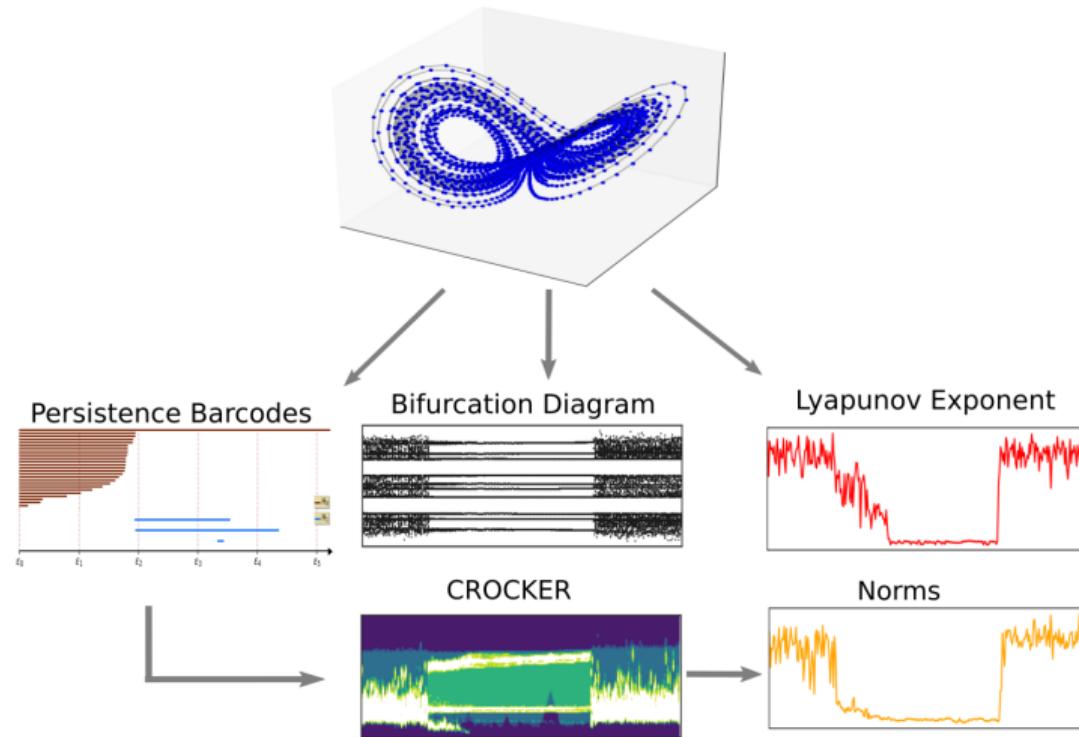
# Outline

- 1 Dynamical System
  - Bifurcation Diagram
  - Lyapunov Exponent
- 2 Topological Features
- 3 CROCKER
  - Norm of CROCKER
- 4 Experiments
  - Rössler System
  - Lorenz System



# Outline

- 1 **Dynamical System**
  - Bifurcation Diagram
  - Lyapunov Exponent
- 2 **Topological Features**
- 3 **CROCKER**
  - Norm of CROCKER
- 4 **Experiments**
  - Rössler System
  - Lorenz System



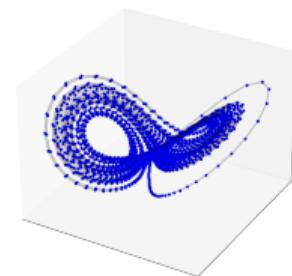
# Dynamical System

Dynamical system is a system that changes over time according to a set of fixed rules that determine how one state of the system moves to another state.

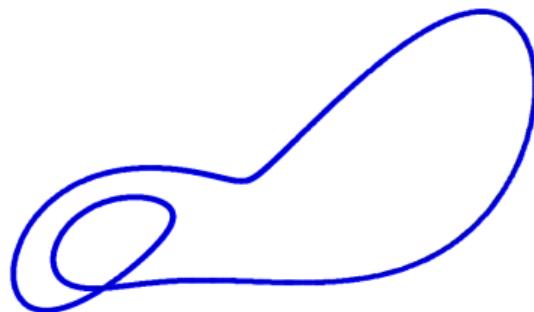
Lorenz system:

$$\dot{x} = \sigma(y - x), \quad \dot{y} = x(\rho - z) - y, \quad \dot{z} = xy - \beta z$$

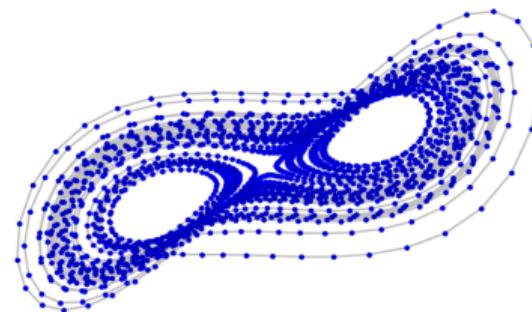
where  $\sigma = 10$ ,  $\beta = 8/3$  and  $\rho = 105$  with the initial conditions  $[0, 0, -1]$ .



Periodic



Chaotic



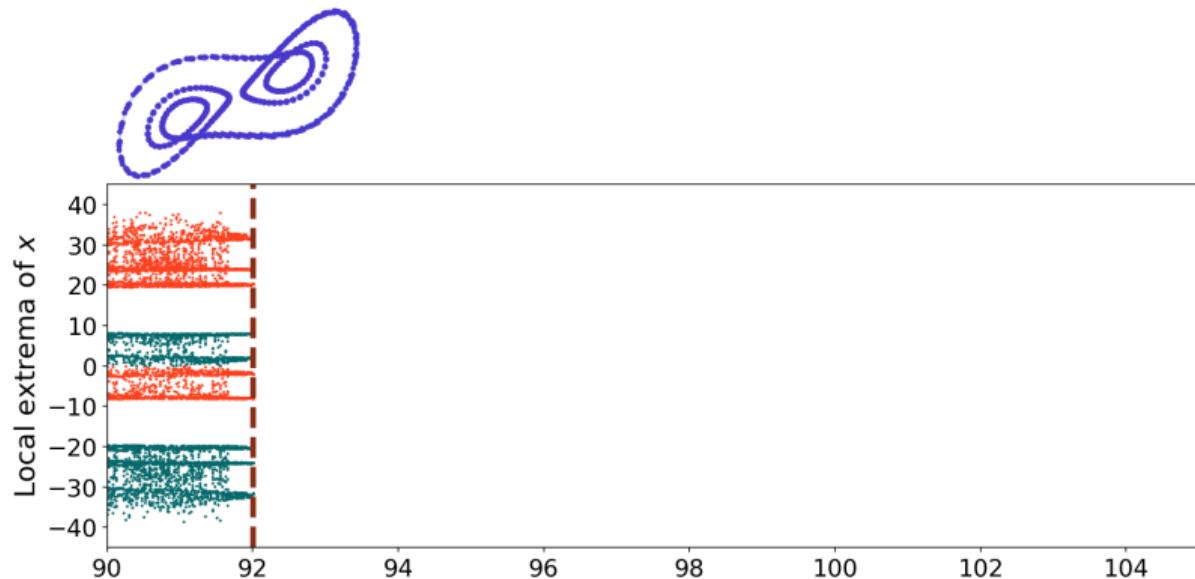
# Bifurcation Diagram

Bifurcation diagram is a way to study how a system depends on a parameter.

The Lorenz system is

$$\begin{aligned}\dot{x} &= \sigma(y - x), \\ \dot{y} &= x(\rho - z) - y, \\ \dot{z} &= xy - \beta z,\end{aligned}$$

where the fixed parameters  $\sigma = 10$ ,  $\beta = 8/3$  and varying  $\rho$ .



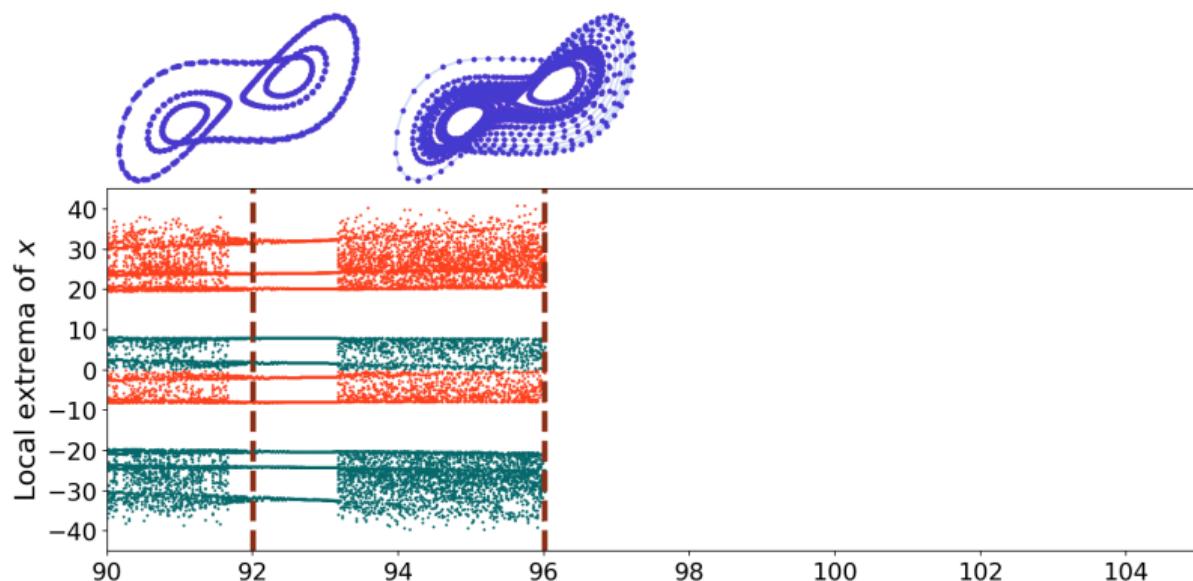
# Bifurcation Diagram

Bifurcation diagram is a way to study how a system depends on a parameter.

The Lorenz system is

$$\begin{aligned}\dot{x} &= \sigma(y - x), \\ \dot{y} &= x(\rho - z) - y, \\ \dot{z} &= xy - \beta z,\end{aligned}$$

where the fixed parameters  $\sigma = 10$ ,  $\beta = 8/3$  and varying  $\rho$ .



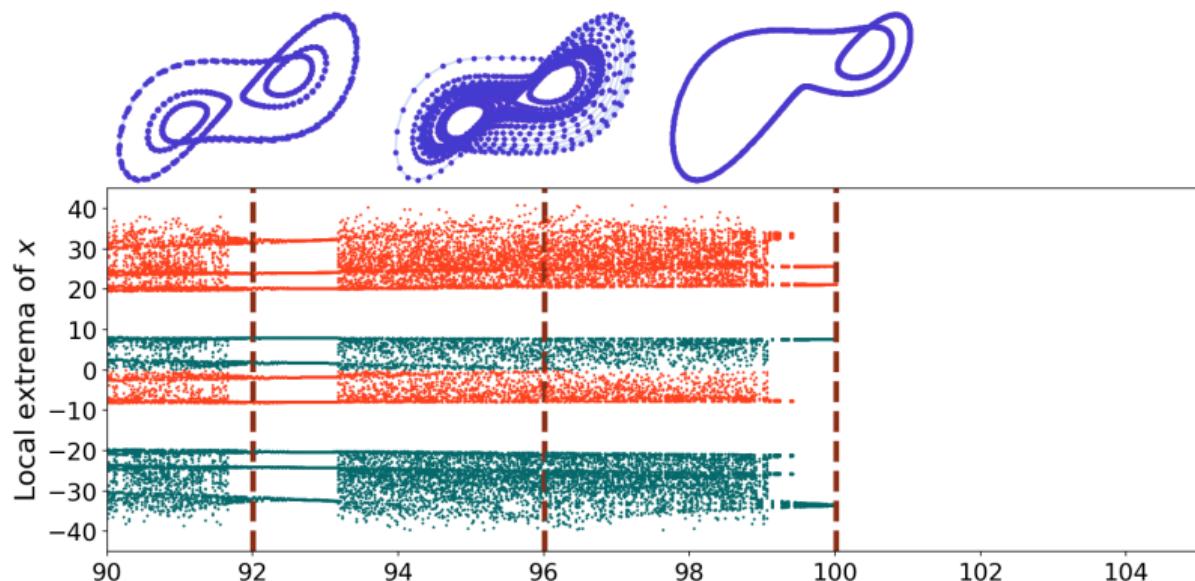
# Bifurcation Diagram

Bifurcation diagram is a way to study how a system depends on a parameter.

The Lorenz system is

$$\begin{aligned}\dot{x} &= \sigma(y - x), \\ \dot{y} &= x(\rho - z) - y, \\ \dot{z} &= xy - \beta z,\end{aligned}$$

where the fixed parameters  $\sigma = 10$ ,  $\beta = 8/3$  and varying  $\rho$ .



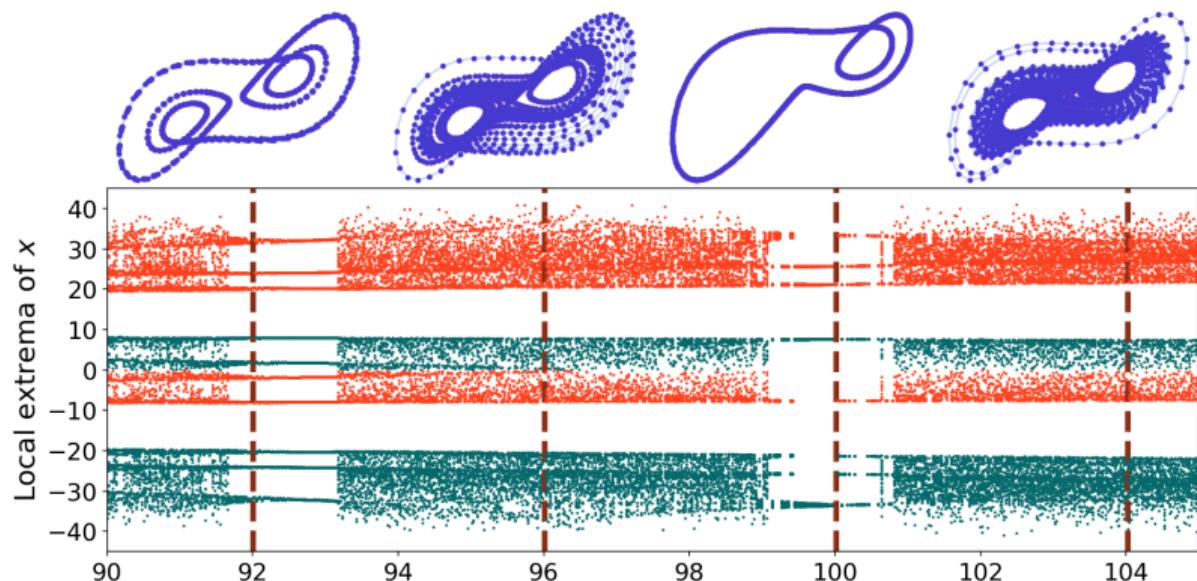
# Bifurcation Diagram

Bifurcation diagram is a way to study how a system depends on a parameter.

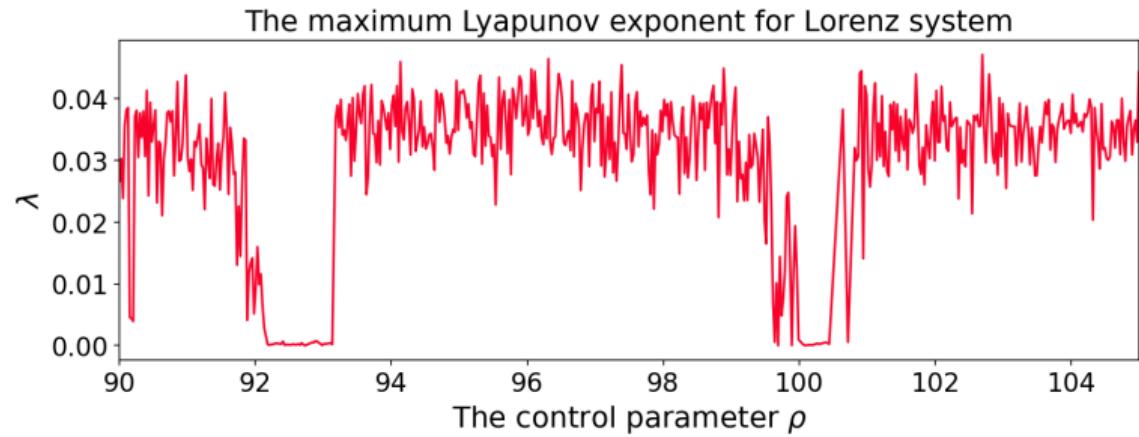
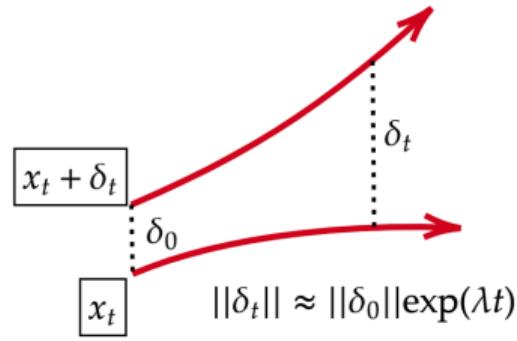
The Lorenz system is

$$\begin{aligned}\dot{x} &= \sigma(y - x), \\ \dot{y} &= x(\rho - z) - y, \\ \dot{z} &= xy - \beta z,\end{aligned}$$

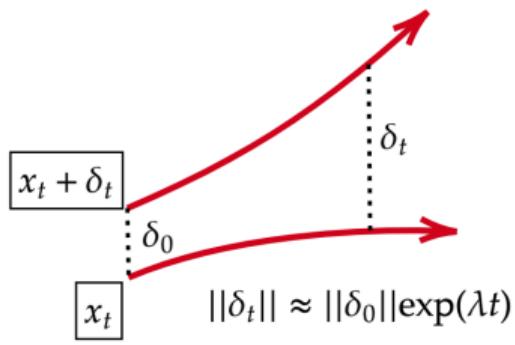
where the fixed parameters  $\sigma = 10$ ,  $\beta = 8/3$  and varying  $\rho$ .



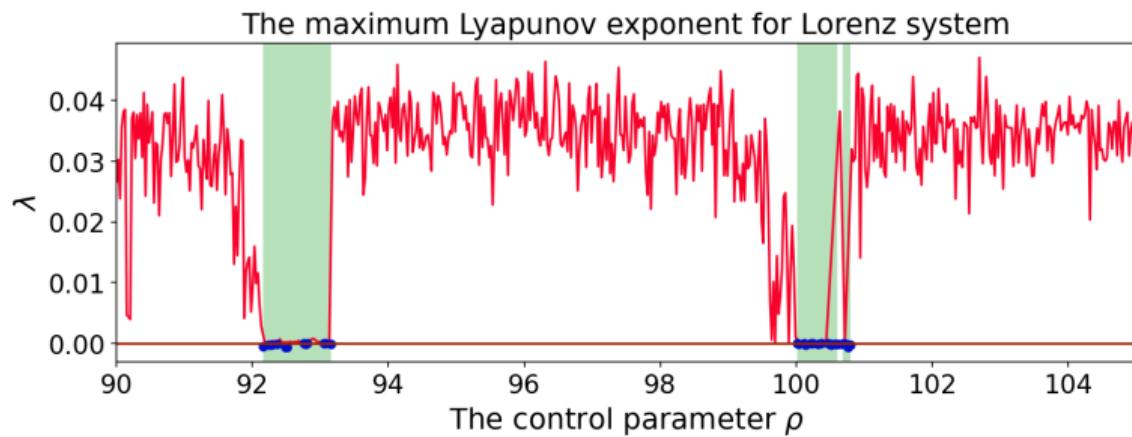
# Lyapunov exponent



# Lyapunov exponent



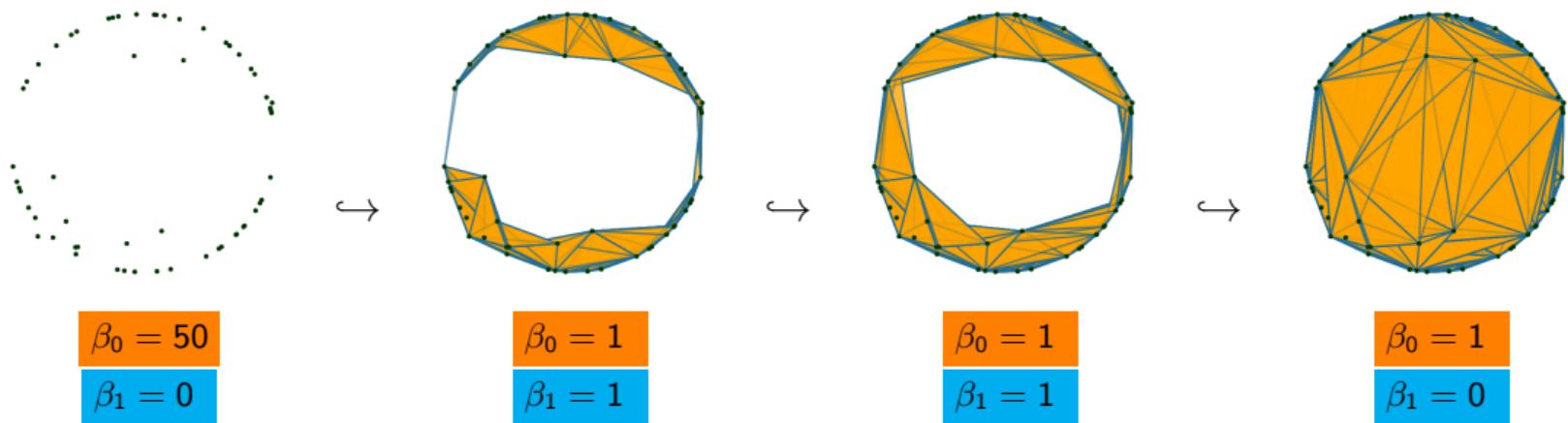
- chaotic if  $\lambda > 0$ ,
- periodic if  $\lambda = 0$ ,
- stable if  $\lambda < 0$ .



# Topological Structure

Given a point cloud  $X$ , the Vietoris-Rips is defined to be the simplicial complex whose simplices are built on vertices that are at most  $\varepsilon$  apart,

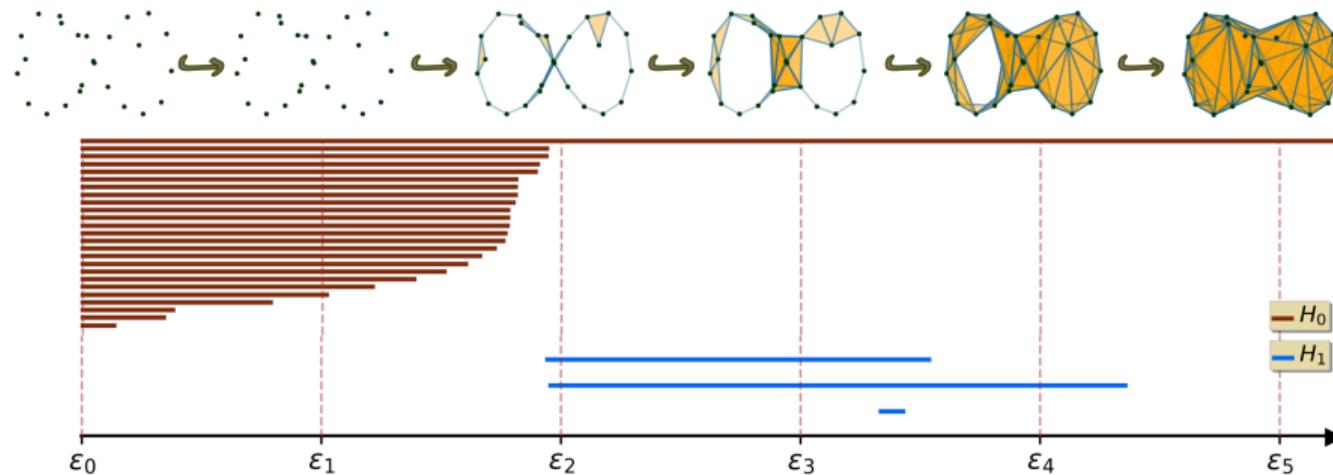
$$R_\varepsilon(X) = \{\sigma \subset X \mid d(x, y) \leq \varepsilon, \text{ for all } x, y \in \sigma\}.$$



# Betti Vector and Persistence Barcode

The  $p^{th}$  dimensional Betti vector is defined as

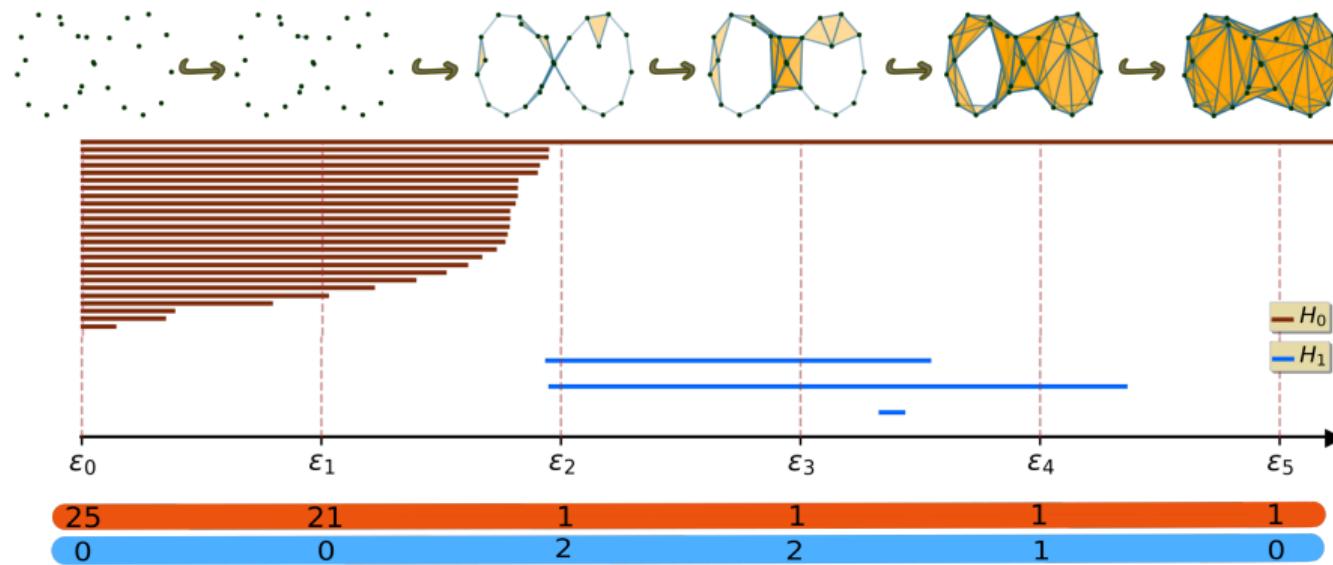
$$Bv_p(X; P) = (\beta_p(R_{\epsilon_0}), \beta_p(R_{\epsilon_1}), \dots, \beta_p(R_{\epsilon_N}))$$



# Betti Vector and Persistence Barcode

The  $p^{th}$  dimensional Betti vector is defined as

$$Bv_p(X; P) = (\beta_p(R_{\epsilon_0}), \beta_p(R_{\epsilon_1}), \dots, \beta_p(R_{\epsilon_N}))$$



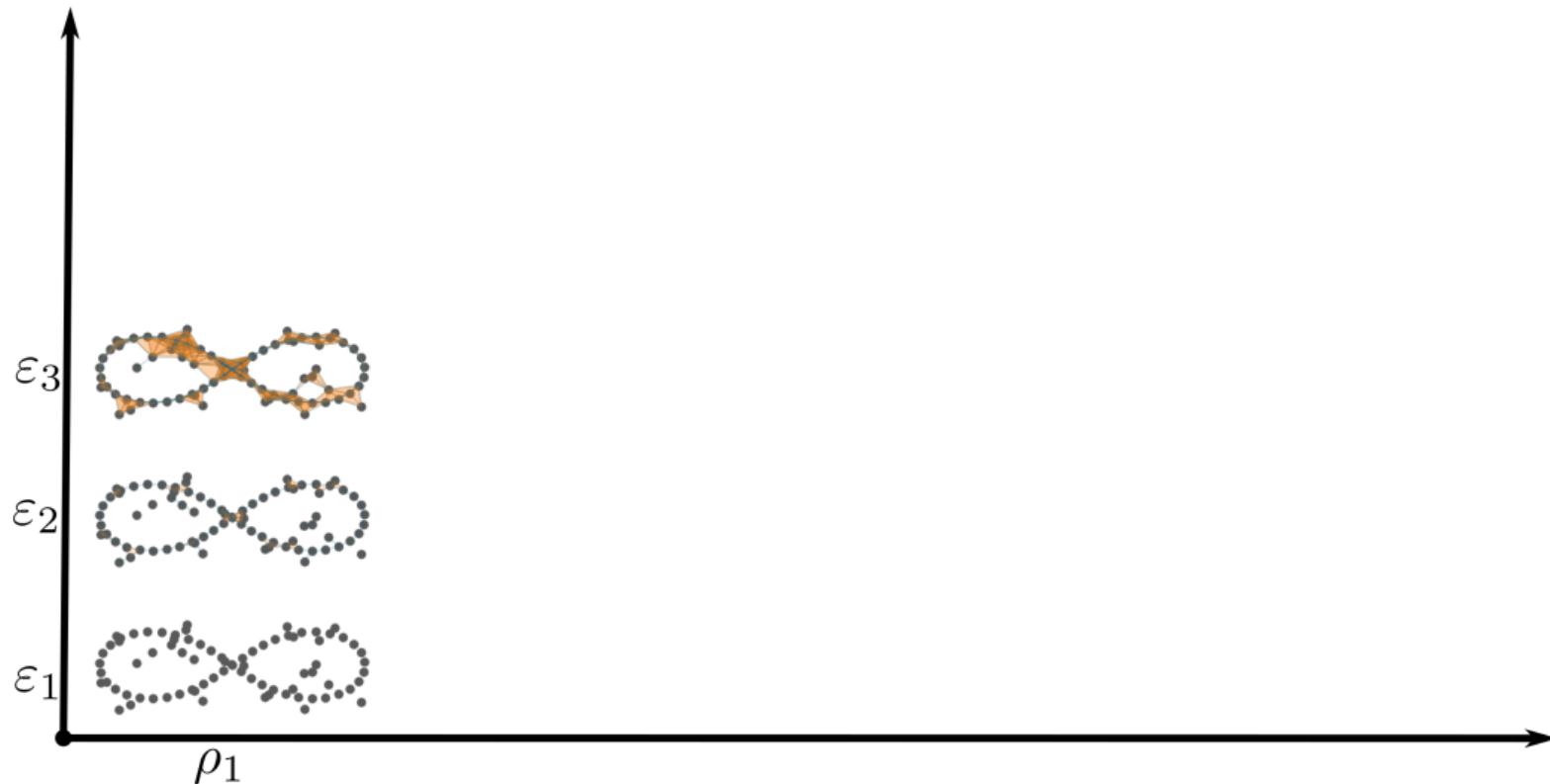
# Different But Same



# Different But Same



# Different But Same



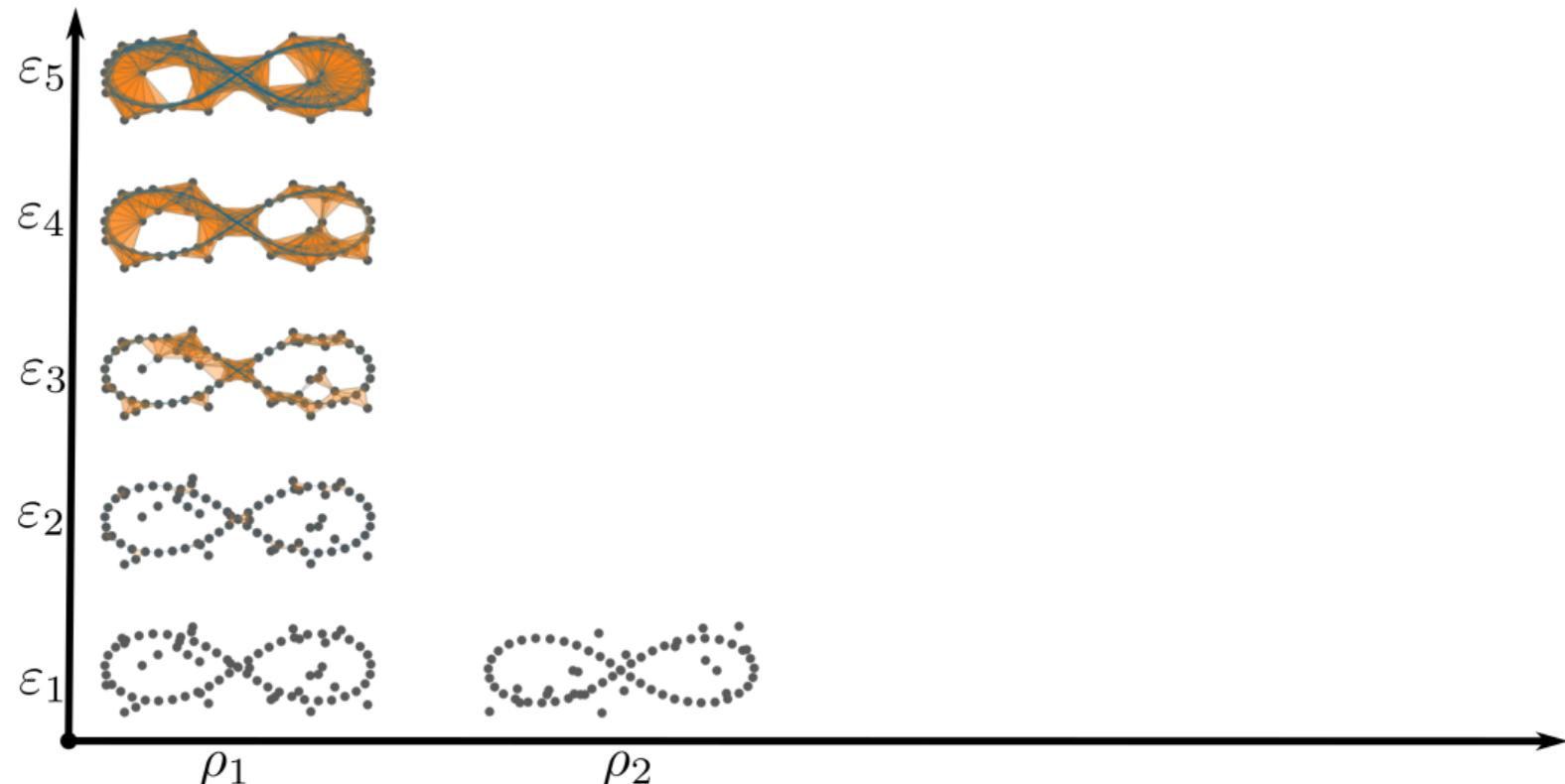
## Different But Same



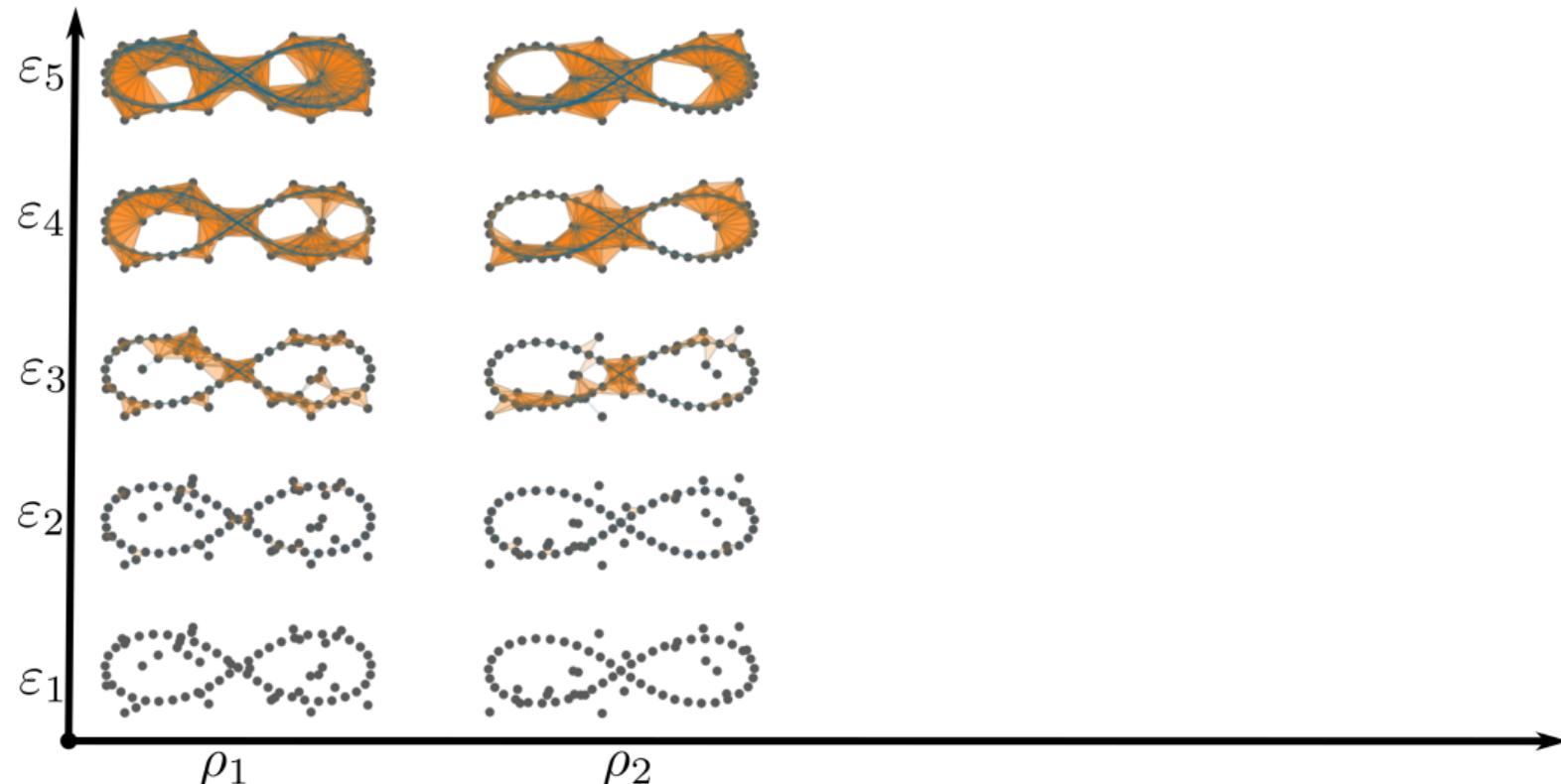
# Different But Same



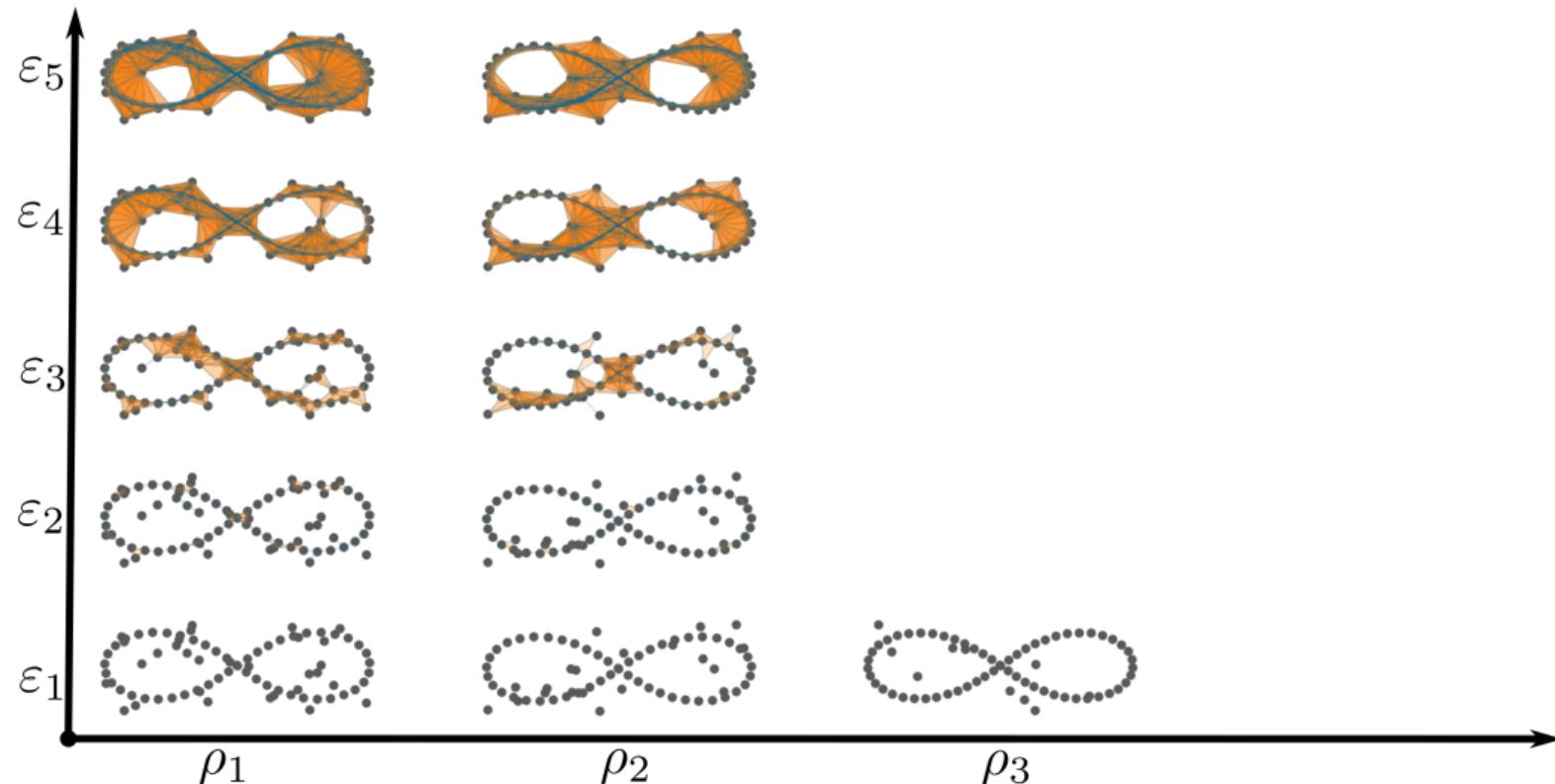
# Different But Same



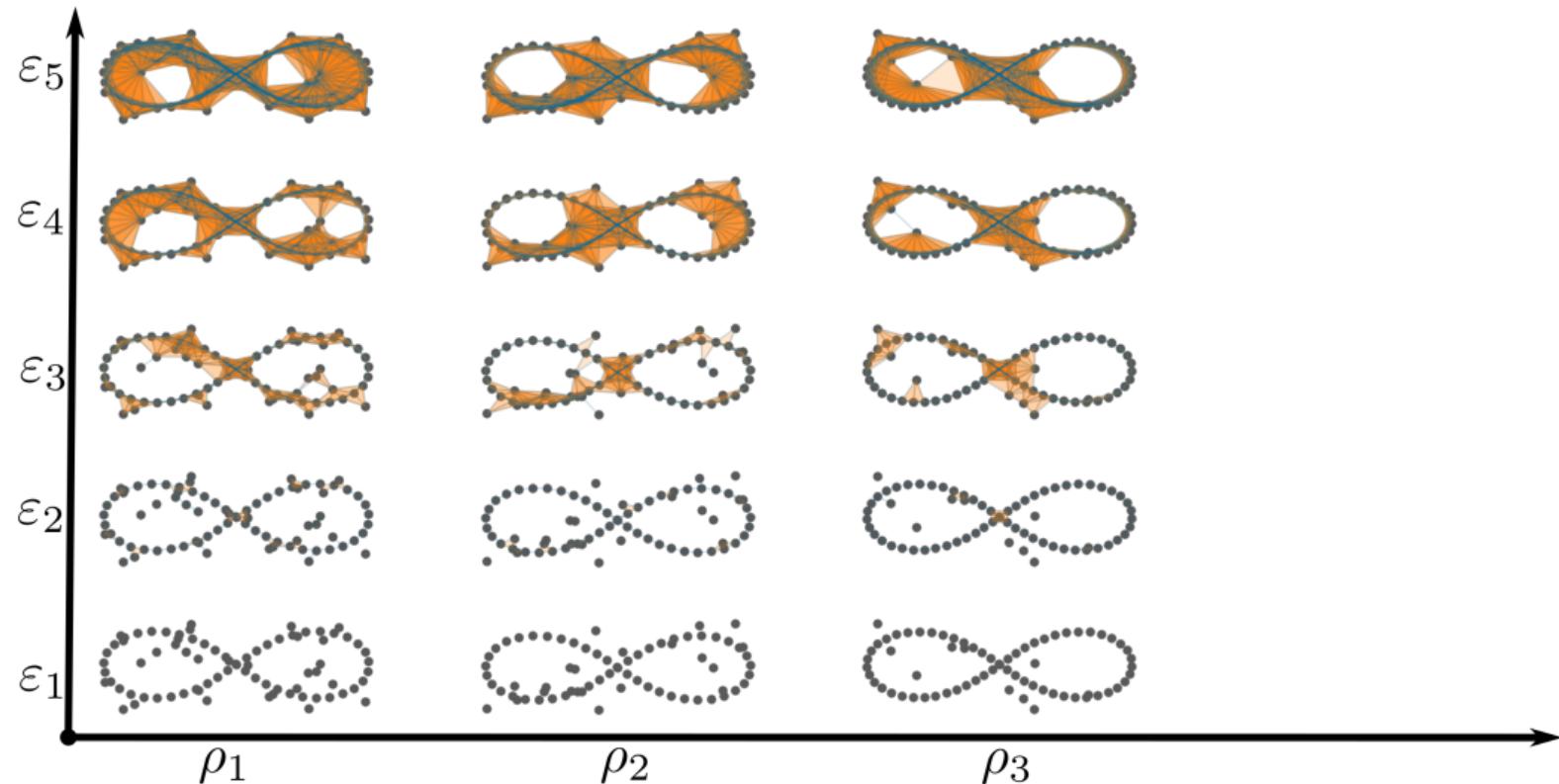
## Different But Same



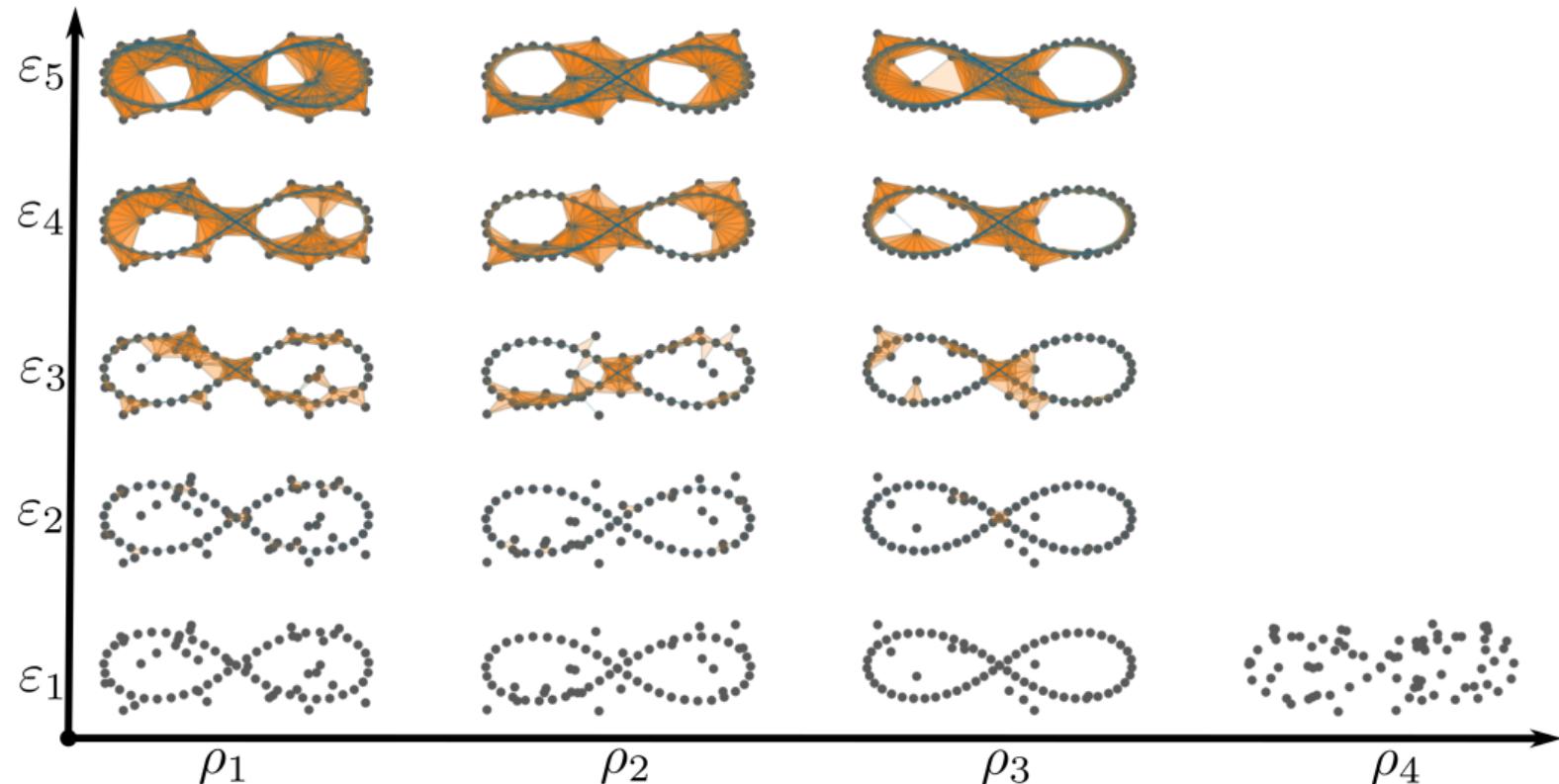
## Different But Same



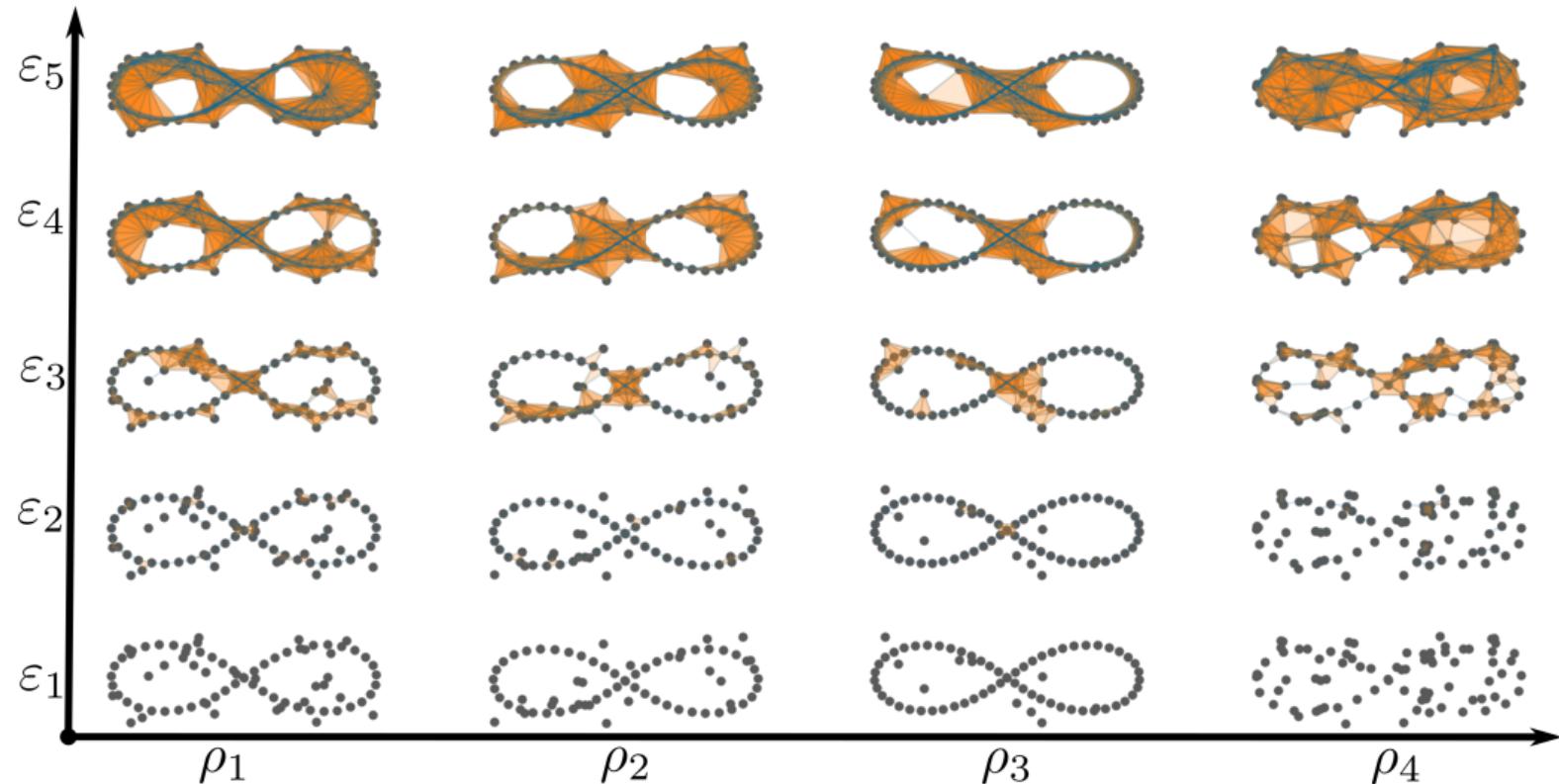
## Different But Same



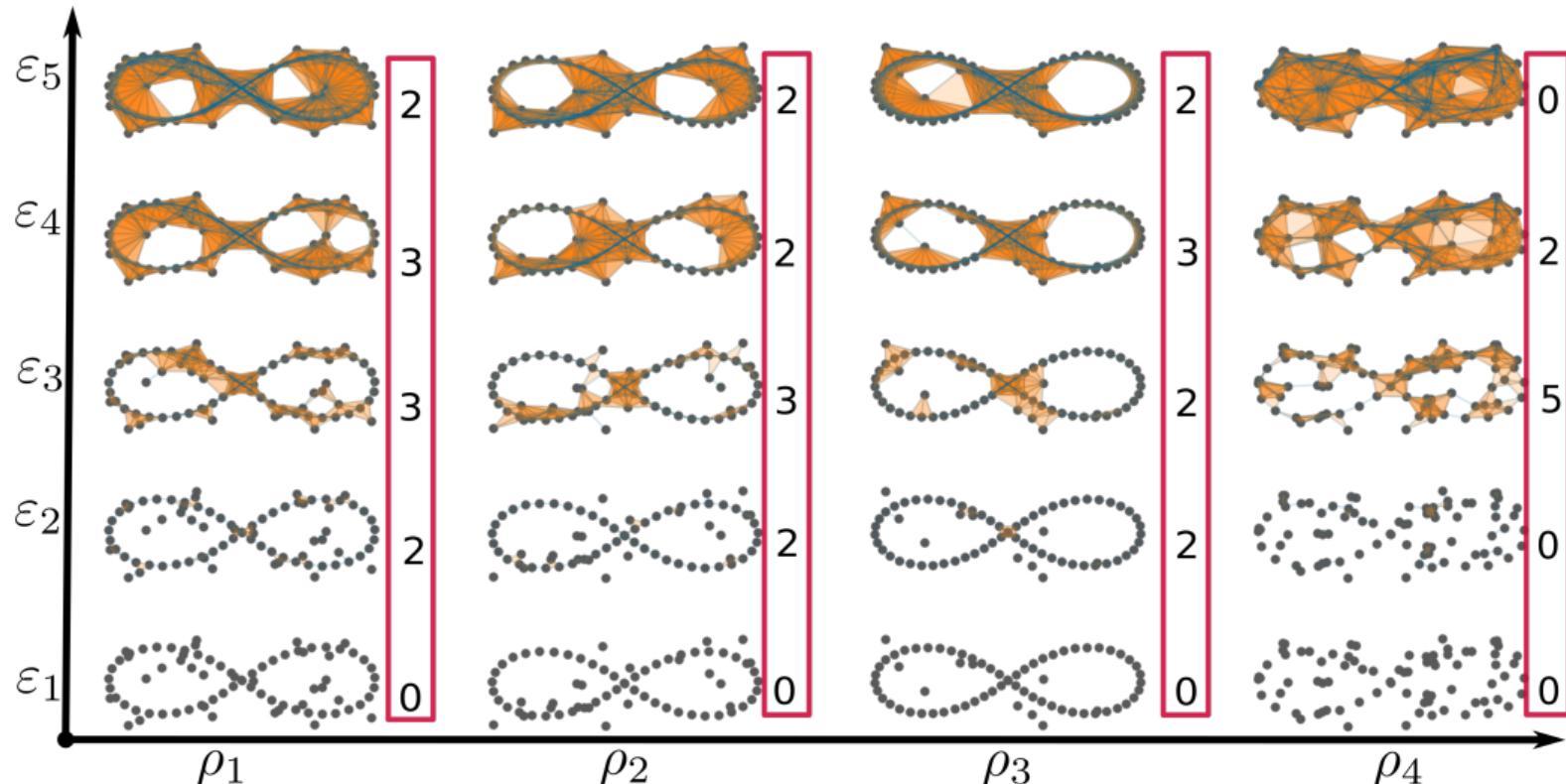
## Different But Same



## Different But Same



## Different But Same



# Contour Realization Of Computed k-dimensional hole Evolution in the Rips complex<sup>1</sup>

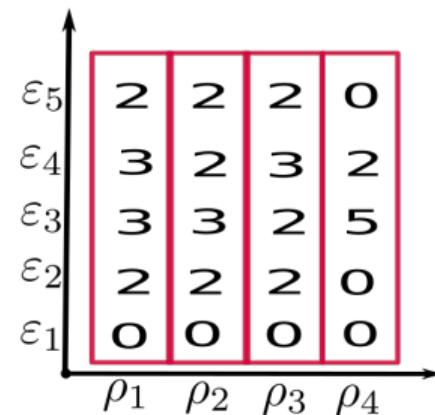
## CROCKER

For a given collection of point clouds

$\mathcal{X} = \{X_1, X_2, \dots, X_T\}$ , CROCKER of this collection can be given as

$$\text{CROCKER}(\mathcal{X}) = (Bv(X_1; P), Bv(X_2; P), \dots, Bv(X_T; P)),$$

where  $Bv(\bullet)$  is the  $p^{th}$  dimension Betti vector for the partition  $P = \{\epsilon_1, \epsilon_2, \dots, \epsilon_I\}$ .



[Topaz et al., 2015, Ulmer et al., 2019, Bhaskar et al., 2019, Xian et al., 2022]

# Algorithm

The Rössler system is

$$\dot{x} = -y - z,$$

$$\dot{y} = x + ay,$$

$$\dot{z} = b + z(x - c),$$

the fixed parameters  
 $b = 2$ ,  $c = 4$  and  
control parameter  $a$ .

- ➊ For each control parameter  $a$ ,
  - Obtain the states of the nonlinear system.
  - Calculate the full persistence barcode.
- ➋ Find the overall maximum death time  $d_{max}$  for each dimension  $p \in \{0, 1\}$ .
- ➌ Get 100 equally-spaced values of  $\varepsilon \in [0, d_{max}]$ .
- ➍ For each persistence barcodes,
  - Obtain Betti vectors for each dimension  $p \in \{0, 1\}$ .
- ➎ Create CROCKER

# Rössler System

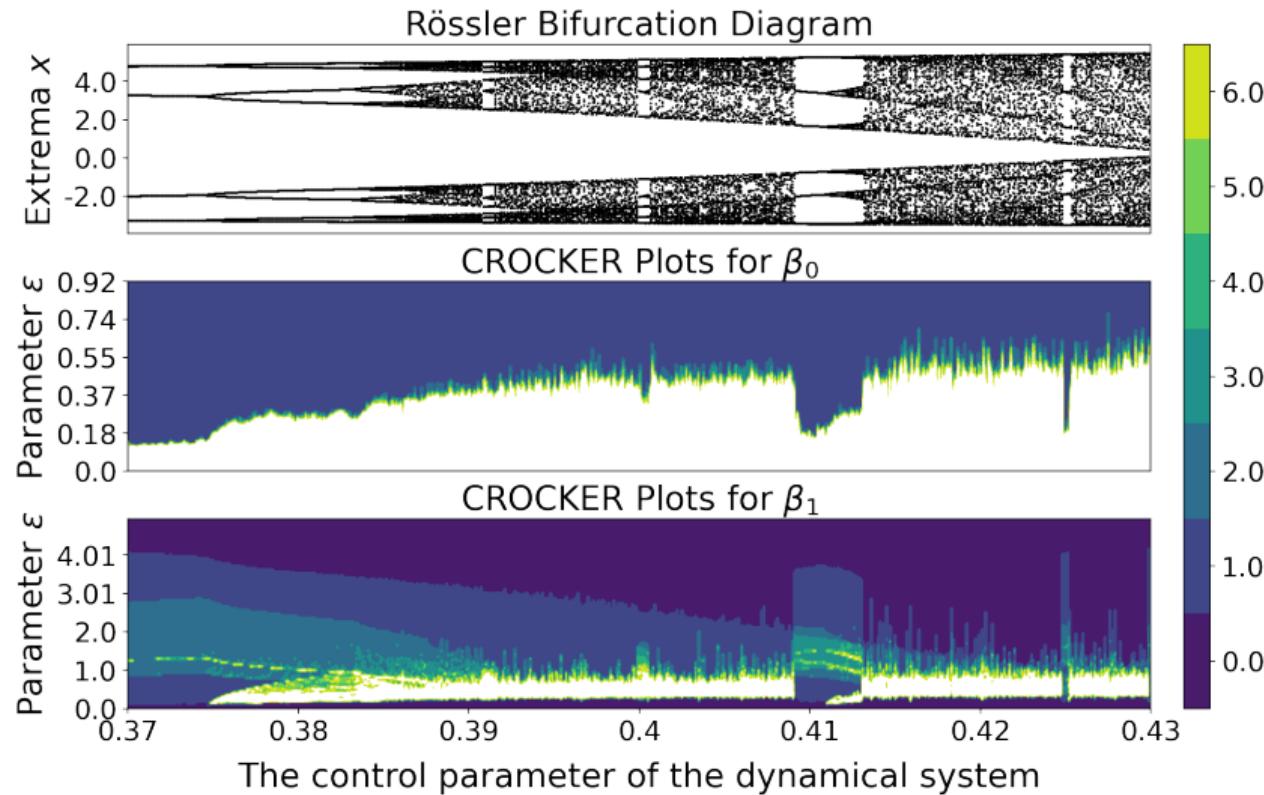
The Rössler system is

$$\dot{x} = -y - z,$$

$$\dot{y} = x + ay,$$

$$\dot{z} = b + z(x - c),$$

the fixed parameters  
 $b = 2$ ,  $c = 4$  and  
control parameter  $a$ .



# Rössler System

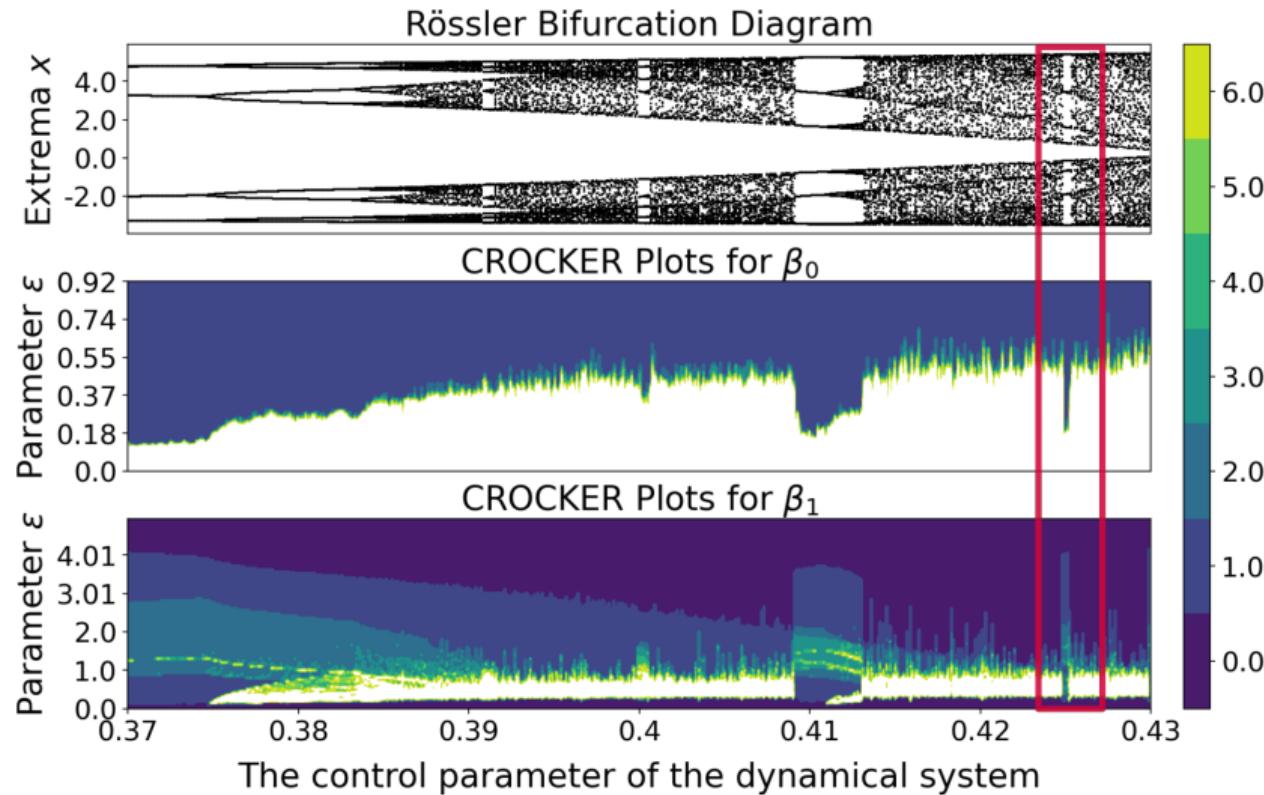
The Rössler system is

$$\dot{x} = -y - z,$$

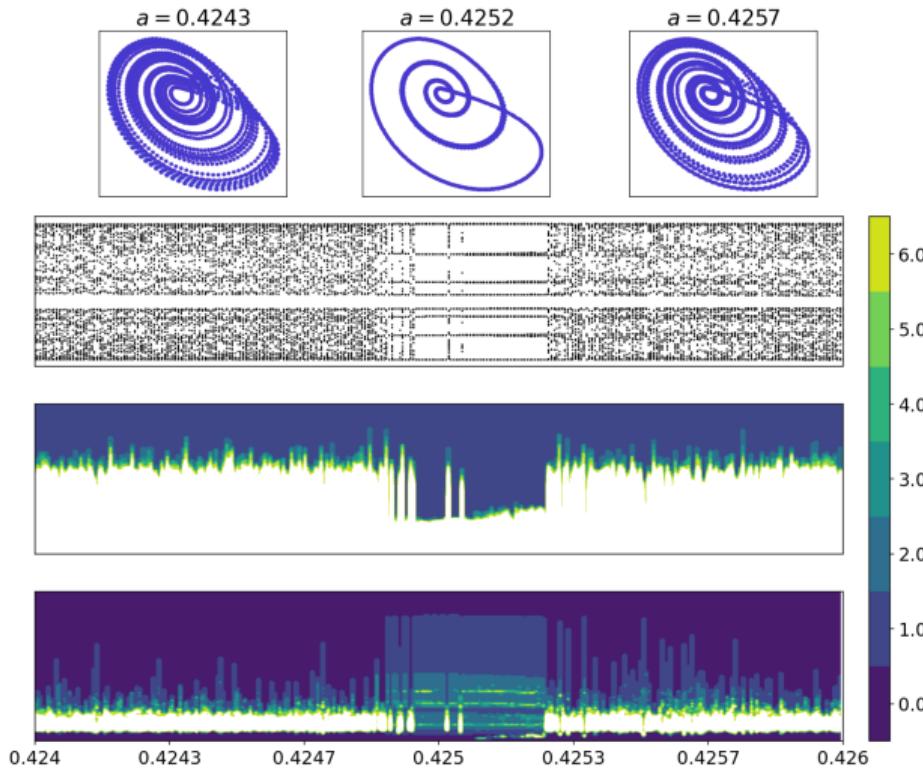
$$\dot{y} = x + ay,$$

$$\dot{z} = b + z(x - c),$$

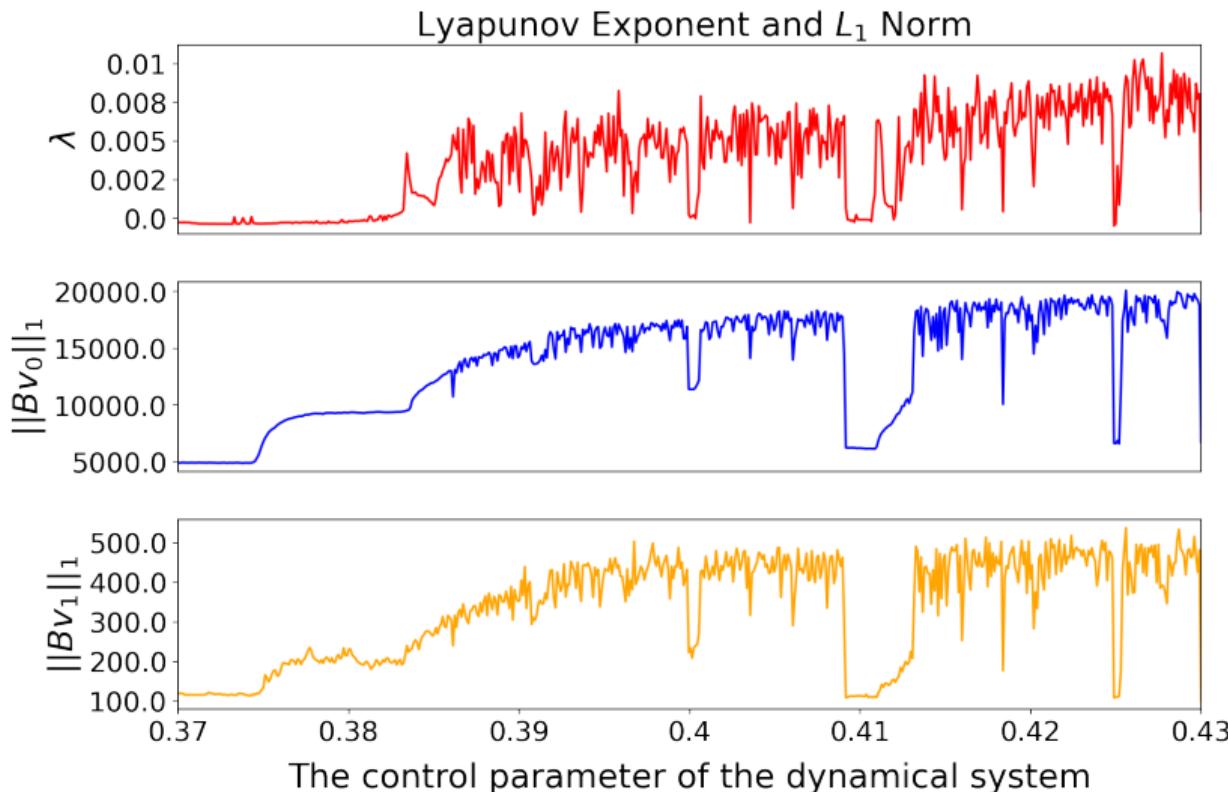
the fixed parameters  
 $b = 2$ ,  $c = 4$  and  
control parameter  $a$ .



# Rössler System

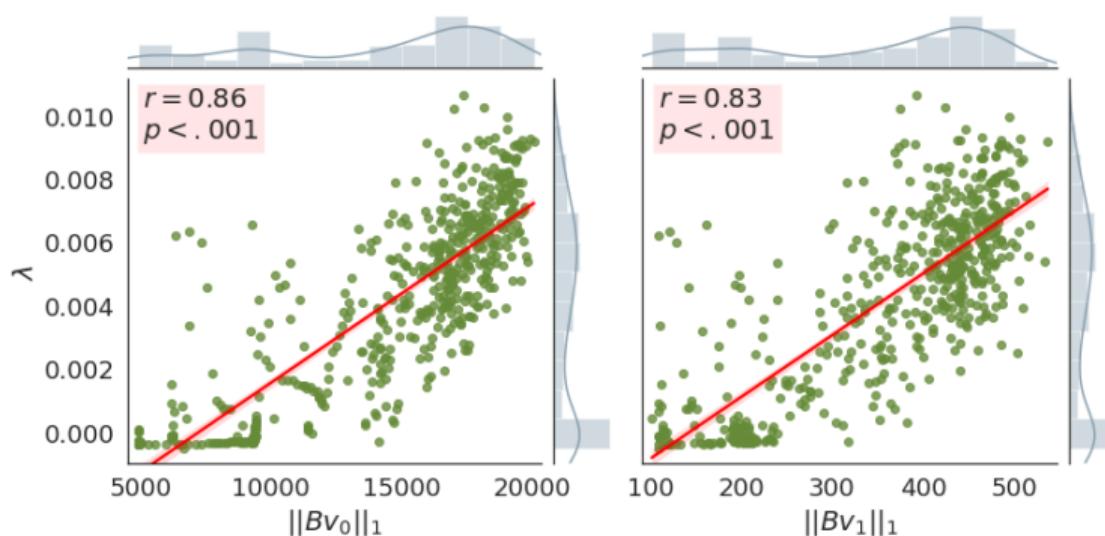


# Lyapunov exponent and $L_1$ norm



# Pearson correlation coefficient

	n	r	CI95%	p-val	BF10	power
$\beta_0$	600	0.857	[0.83, 0.88]	$10^{-173}$	$10^{169}$	1.0
$\beta_1$	600	0.832	[0.80, 0.85]	$10^{-154}$	$10^{150}$	1.0



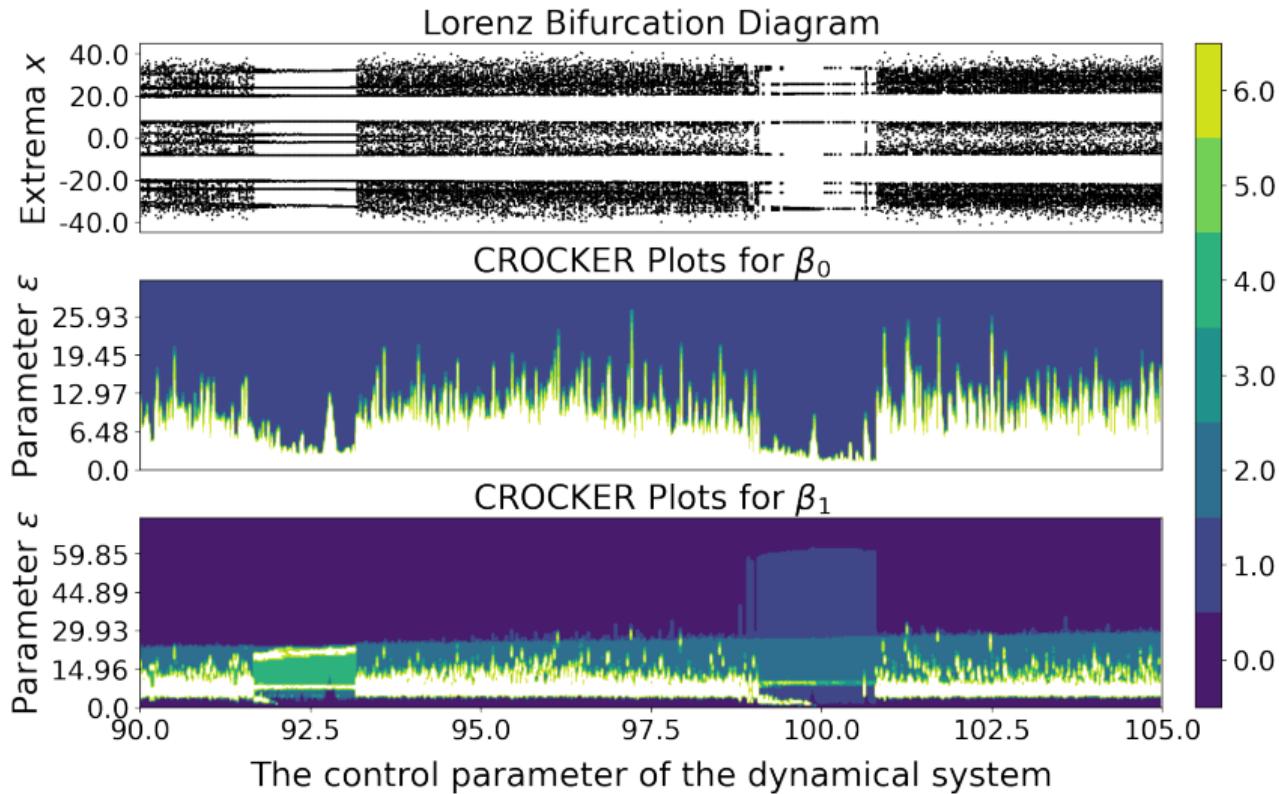
# Lorenz System

The Lorenz system is

$$\begin{aligned}\dot{x} &= \sigma(y - x), \\ \dot{y} &= x(\rho - z) - y, \\ \dot{z} &= xy - \beta z.\end{aligned}$$

The parameters

$\sigma = 10$ ,  $\beta = 8/3$  and varying  $\rho$ .



# Lorenz System

The Lorenz system is

$$\dot{x} = \sigma(y - x),$$

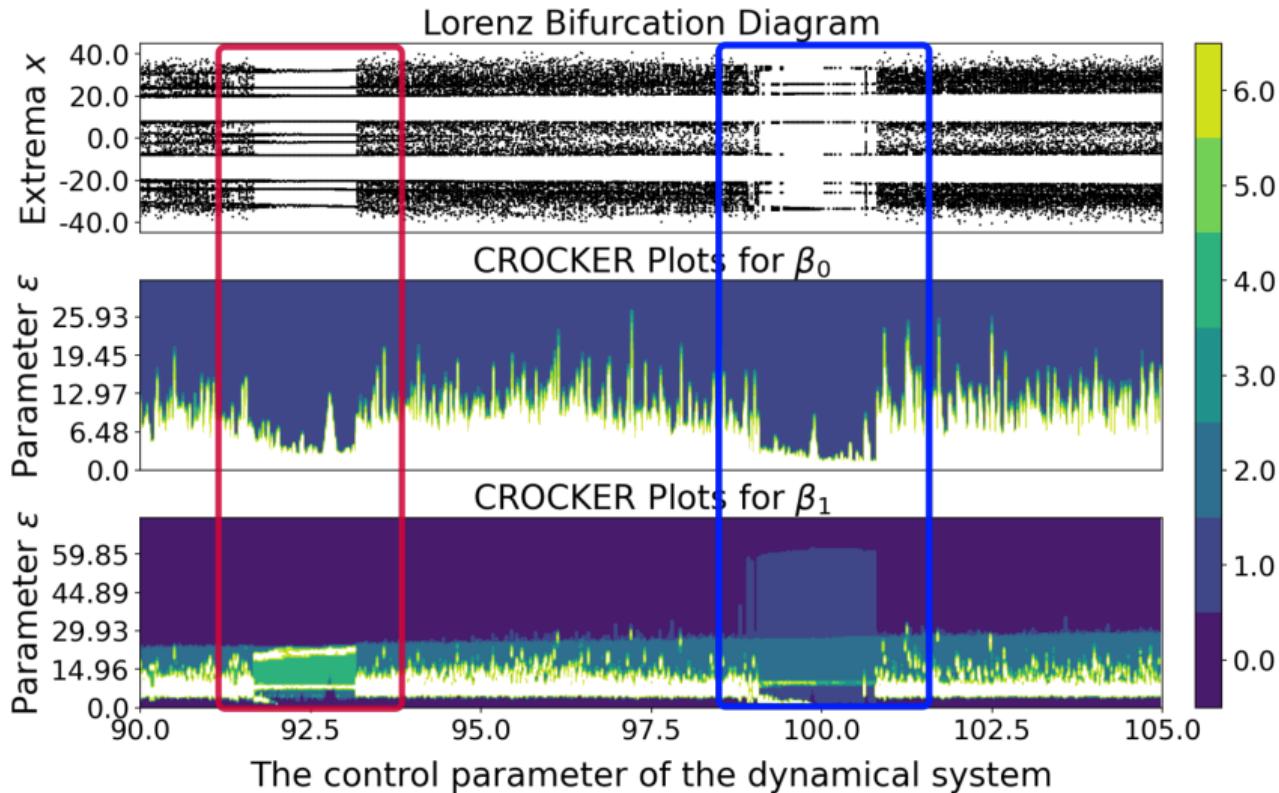
$$\dot{y} = x(\rho - z) - y,$$

$$\dot{z} = xy - \beta z.$$

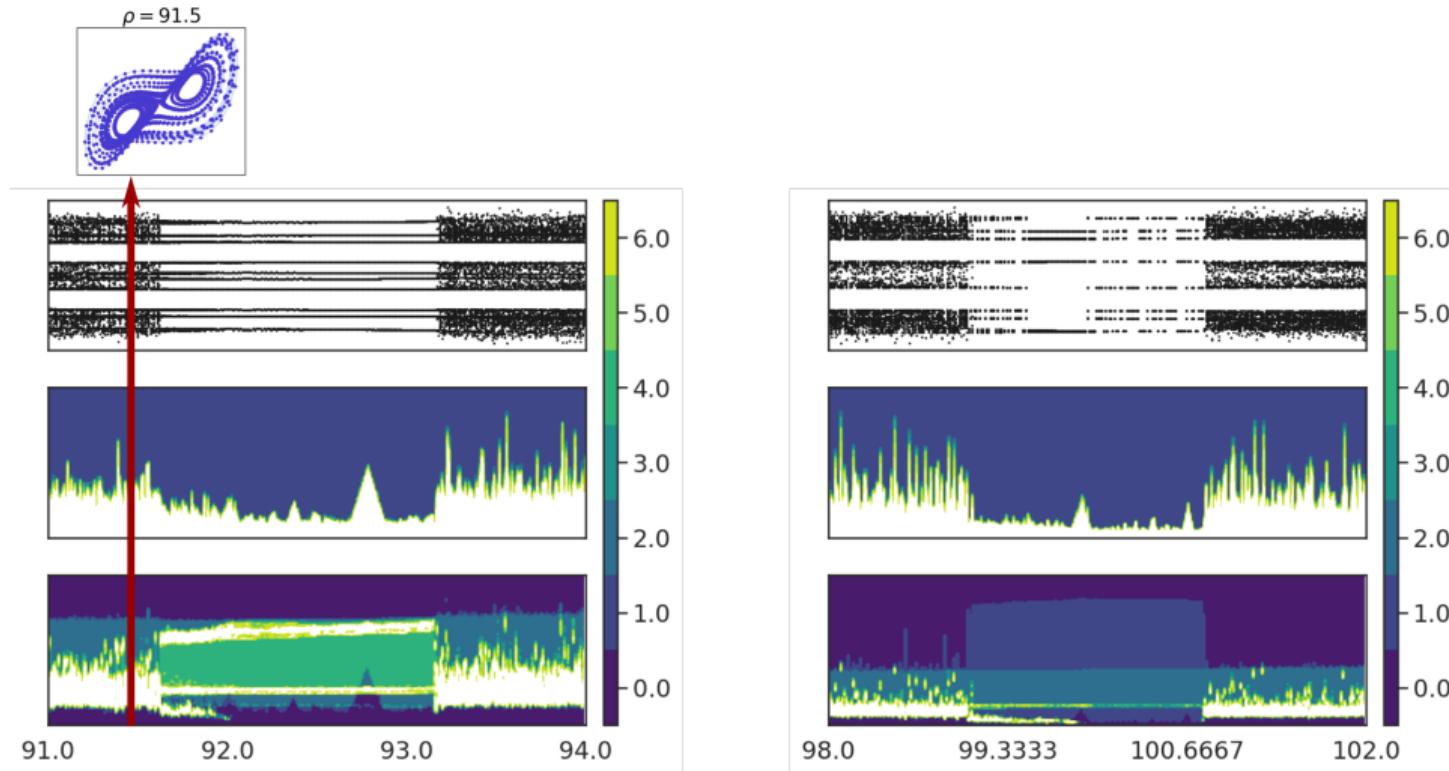
The parameters

$$\sigma = 10, \beta = 8/3 \text{ and}$$

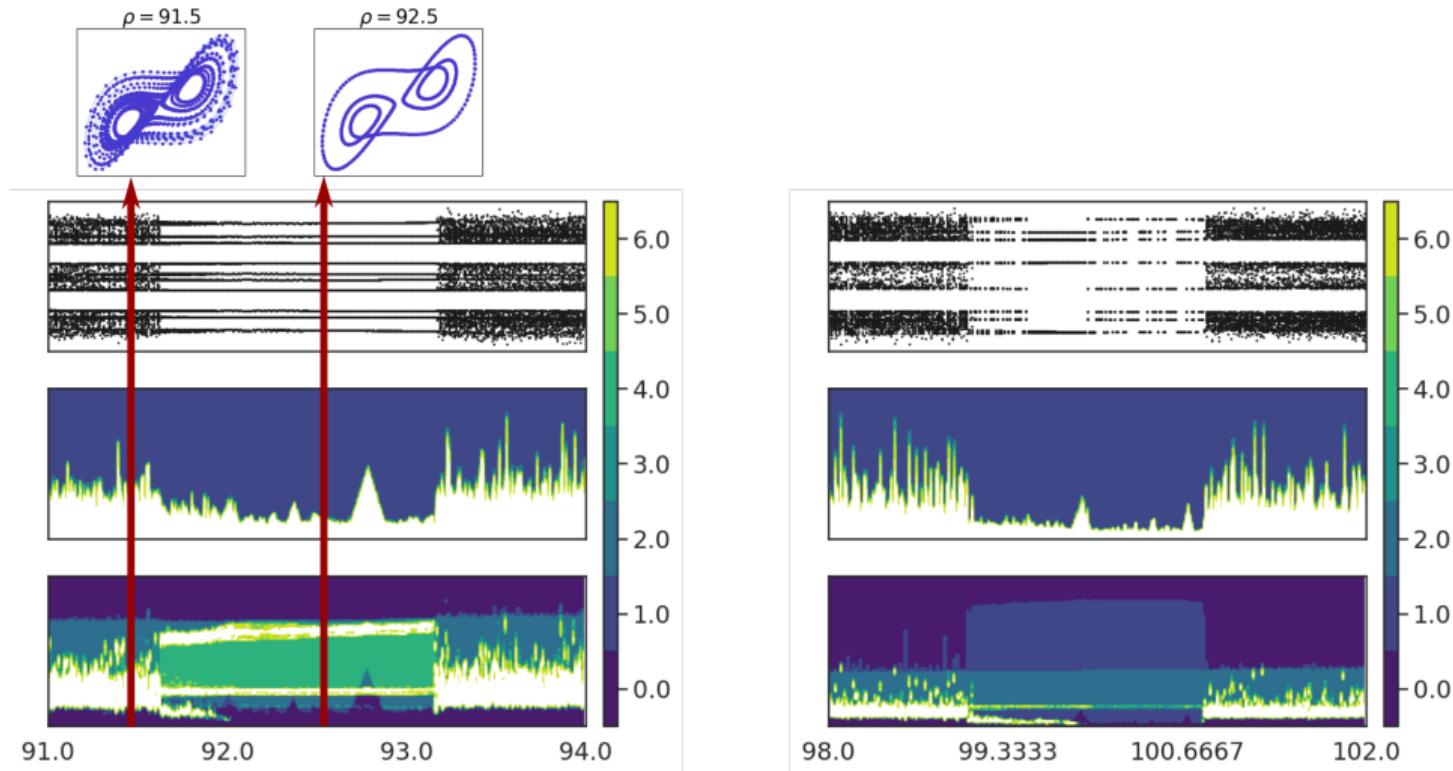
varying  $\rho$ .



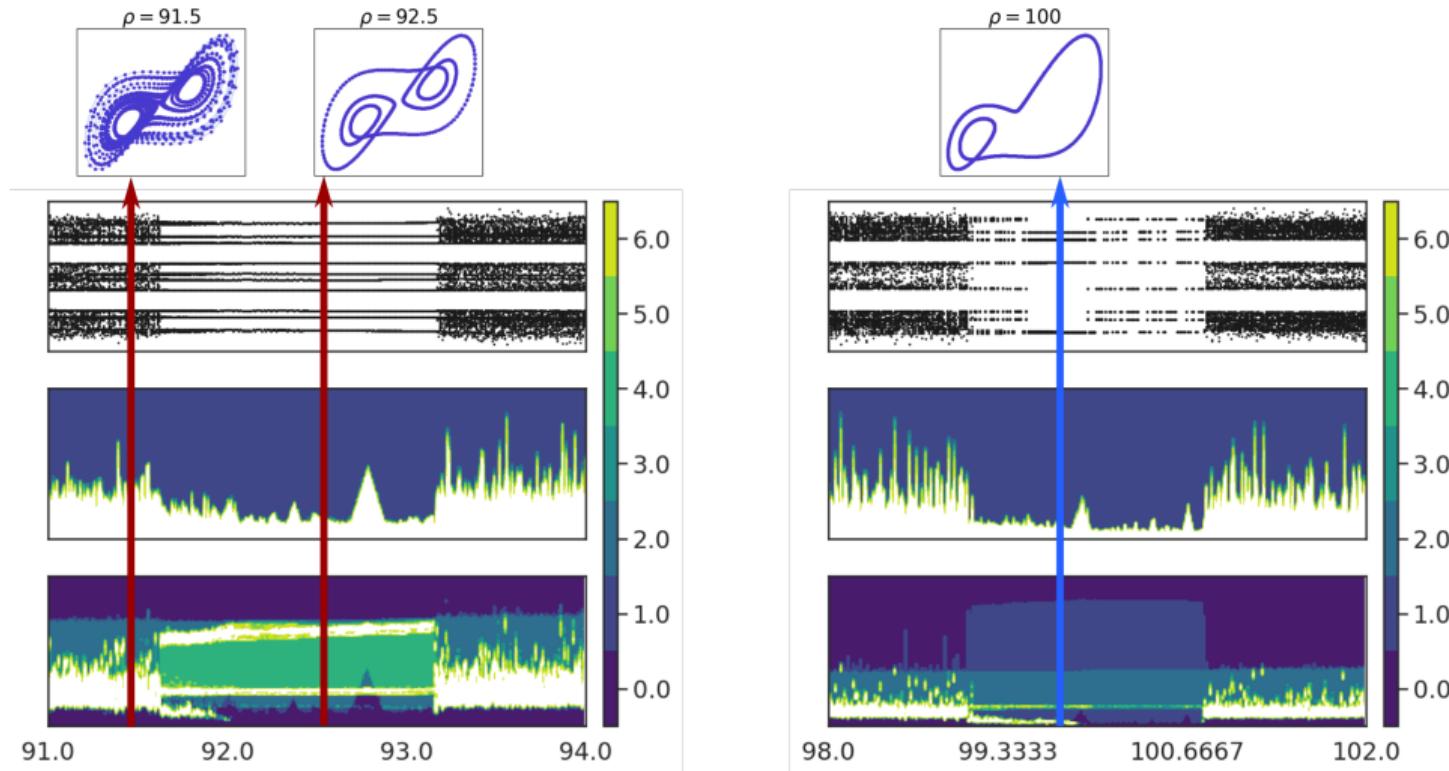
# Lorenz System



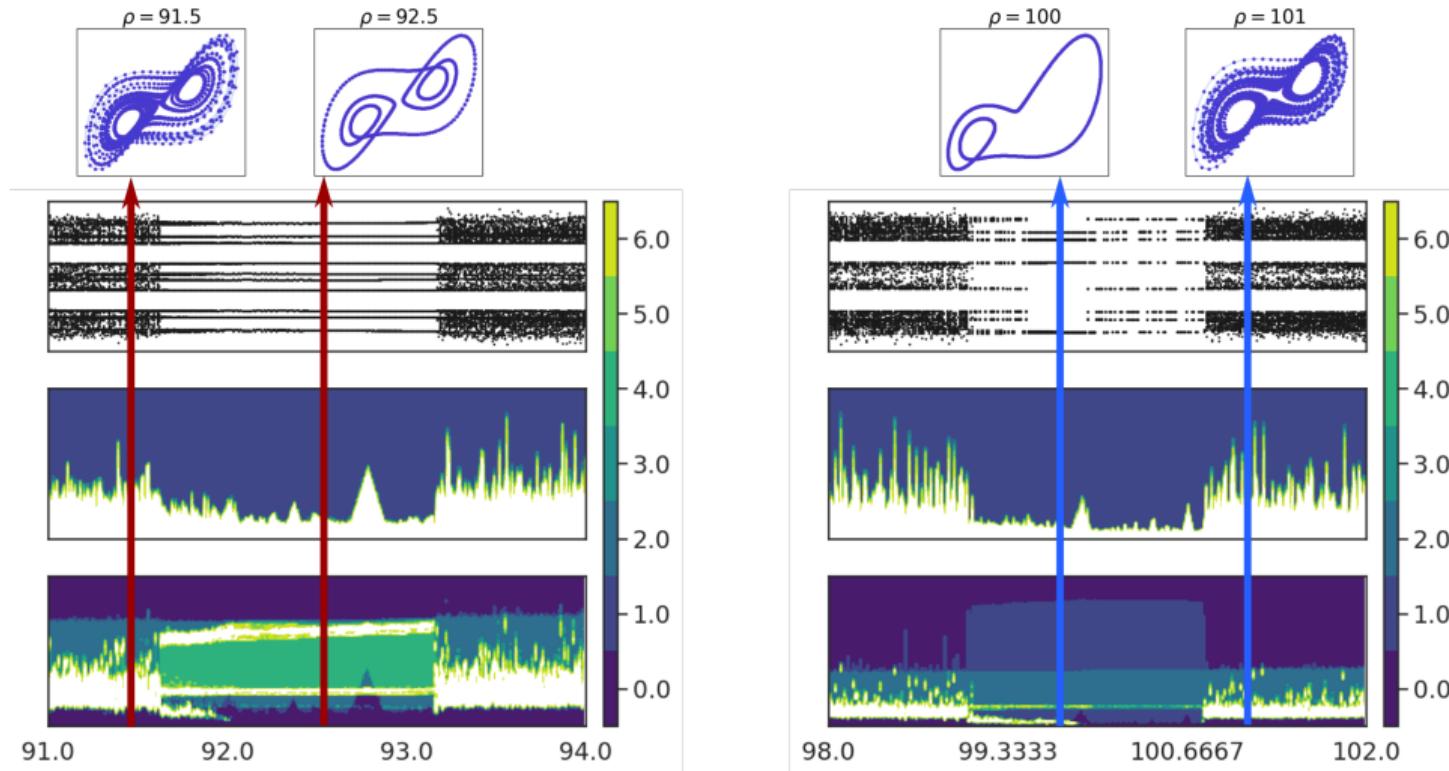
# Lorenz System



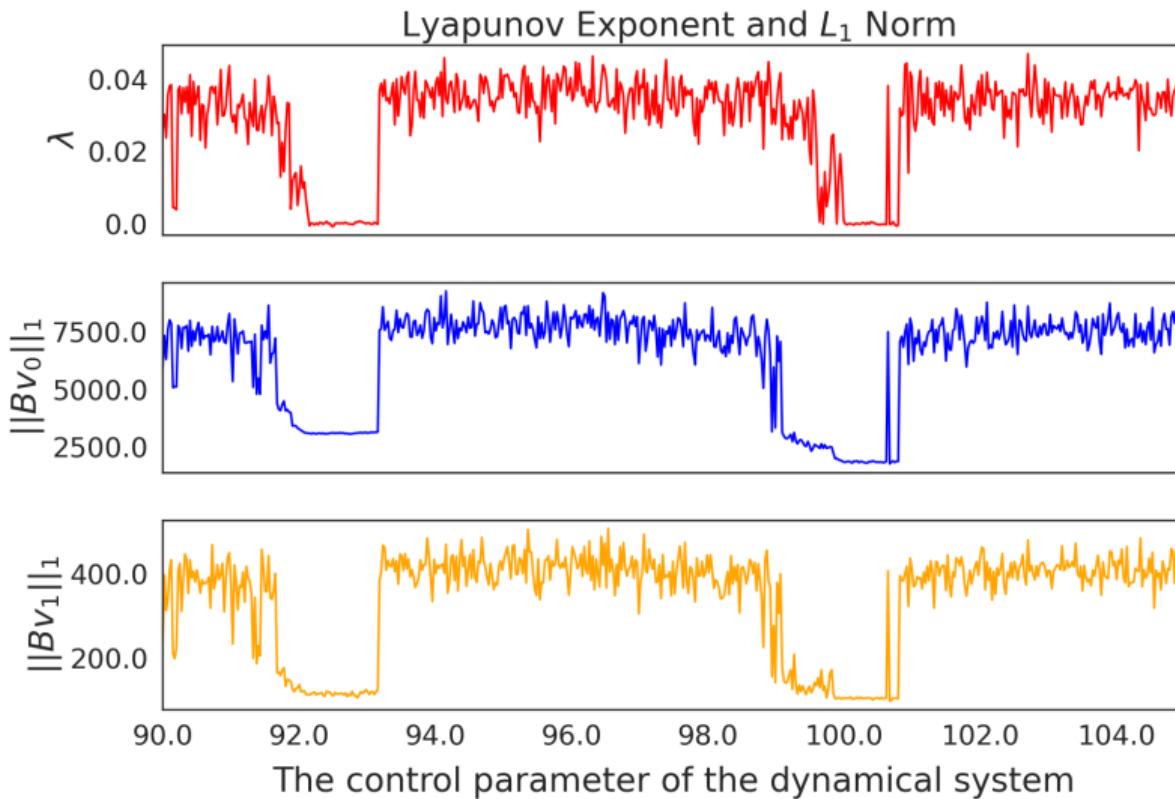
# Lorenz System



# Lorenz System

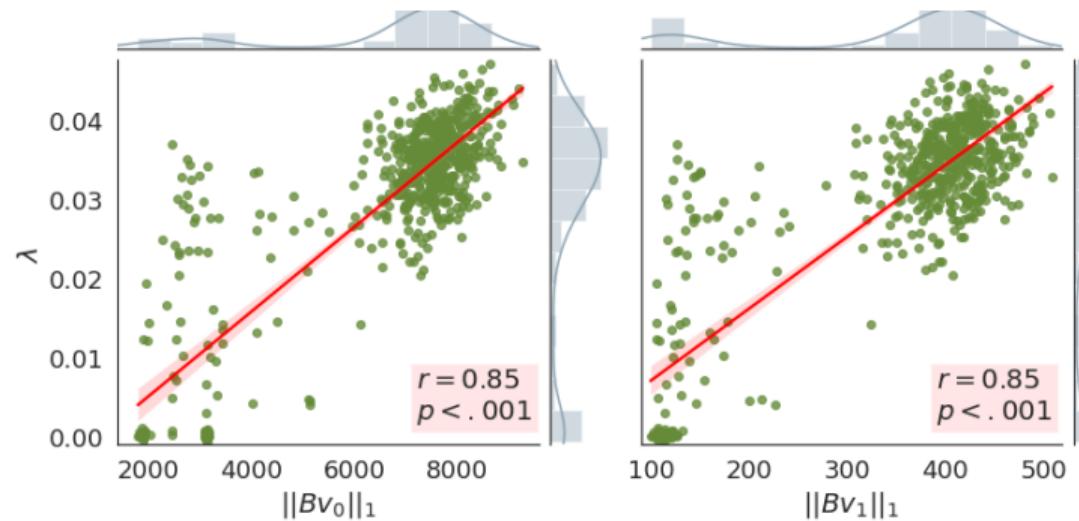


# Lyapunov exponent and $L_1$ norm



# Pearson correlation coefficient

	<b>n</b>	<b>r</b>	<b>CI95%</b>	<b>p-val</b>	<b>BF10</b>	<b>power</b>
$\beta_0$	600	0.852	[0.83, 0.87]	$10^{-171}$	$10^{166}$	1.0
$\beta_1$	600	0.853	[0.83, 0.87]	$10^{-165}$	$10^{163}$	1.0



# Future Work

- Calculate Betti vectors without full persistence barcodes.
- Nonlinear relation between the Lyapunov exponent and  $L_1$  norms.
- Two or more parameter bifurcations.

# References

-  Bhaskar, D., Manhart, A., Milzman, J., Nardini, J. T., Storey, K. M., Topaz, C. M., and Ziegelmeier, L. (2019).  
Analyzing collective motion with machine learning and topology.  
*Chaos: An Interdisciplinary Journal of Nonlinear Science*, 29(12):123125.
-  Topaz, C. M., Ziegelmeier, L., and Halverson, T. (2015).  
Topological data analysis of biological aggregation models.  
*PLOS ONE*, 10(5):1–26.
-  Ulmer, M., Ziegelmeier, L., and Topaz, C. M. (2019).  
A topological approach to selecting models of biological experiments.  
*PLOS ONE*, 14(3):1–18.
-  Xian, L., Adams, H., Topaz, C. M., and Ziegelmeier, L. (2022).  
Capturing dynamics of time-varying data via topology.  
*Foundations of Data Science*, 4(1):1–36.



**Thank You!**



MICHIGAN STATE  
UNIVERSITY