## 4301 - HW1

#### September 2020

## Problem 1: Gradients & More

For each of the following functions: (1) Prove that they are convex, (2) compute gradients/subgradients, (3) write the updates for (sub)gradient descent with a fixed step size.

 $f(w) = \sum_{m=1}^{M} \max(0, 1 - y_m w^T x^{(m)})^2$  for  $w \in \mathbb{R}^n$  and fixed  $y_1, \dots, y_M \in \mathbb{R}$  and  $x^{(1)}, \dots, x^{(M)} \in \mathbb{R}^n$ 

- 1. Proof. For  $m \in \{1, ..., M\}$ , define  $g_m(w) = \max(0, 1 y_m w^T x^{(m)})$ . Based on what we have in the following, we will prove that  $f(w) = \sum_{m=1}^M g_m(w)^2$  is convex.
  - (a) Nonnegative weighted sum of convex functions is convex. (f(w)) is the summation over all  $g_m(w)^2$
  - (b) The composition of two convex functions is convex.  $(g_m(w))$  has been composited in  $w^2$ .)
    - $\rightarrow$  Therefore, showing that  $g_m(w)$  is convex for  $m \in \{1, ..., M\}$ , induces the desirable result.
  - (c) Pointwise Maximum of convex functions is convex.  $(h(w) = 0 \text{ and } p(w) = 1 y_m w^T x^{(m)} \text{ are both affine, hence they are convex.})$

So f(w) is convex.

2. f(w) is differentiable everywhere and its gradient is

$$\nabla f(w) = \sum_{m=1}^{M} \nabla g_m(w)$$

$$\nabla g_m(w) = \begin{cases} 0 & \text{if } 1 - y_m w^T x^{(m)} \le 0\\ 2(1 - y_m w^T x^{(m)})(-y_m x^{(m)}) & \text{if } 1 - y_m w^T x^{(m)} > 0 \end{cases}$$

3.  $w^{\text{new}} = w^{\text{old}} - \lambda \nabla f(w^{\text{old}})$ 

 $f(x) = \log[\sum_{i=1}^n \exp(a_i x_i)]$  for  $x \in \mathbb{R}^n$  and constaints  $a \in \mathbb{R}^n$ .

1. Proof. The Hessian matrix of a multivariate convex function is positive semi-definite. The Hessian matrix of  $f(x) = \log[\sum_{i=1}^{n} \exp(a_i x_i)]$  is

$$H = \begin{bmatrix} \frac{\partial^2 f(x)}{\partial x_1^2} & \frac{\partial^2 f(x)}{\partial x_1 \partial x_2} & \cdots & \frac{\partial^2 f(x)}{\partial x_1 \partial x_n} \\ \frac{\partial^2 f(x)}{\partial x_2 \partial x_1} & \frac{\partial^2 f(x)}{\partial x_2^2} & \cdots & \frac{\partial^2 f(x)}{\partial x_2 \partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 f(x)}{\partial x_n \partial x_1} & \frac{\partial^2 f(x)}{\partial x_n \partial x_2} & \cdots & \frac{\partial^2 f(x)}{\partial x_n^2} \end{bmatrix},$$

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while

$$\frac{\partial^2 f(x)}{\partial x_j^2} = \frac{a_j^2 \exp(a_j x_j) \sum_{i=1}^n \exp(a_i x_i)}{(\sum_{i=1}^n \exp(a_i x_i))^2} + \frac{-(a_j \exp(a_j x_j))(a_j \exp(a_i x_i))}{(\sum_{i=1}^n \exp(a_i x_i))^2}$$
$$\frac{\partial^2 f(x)}{\partial x_k \partial x_j} = \frac{-(a_j \exp(a_j x_j))(a_k \exp(a_k x_k))}{(\sum_{i=1}^n \exp(a_i x_i))^2}.$$

The denominator is a positive number. For the ease of notation, it is negligible.

$$\frac{\partial^2 f(x)}{\partial x_j^2} \approx a_j^2 \exp(a_j x_j) \sum_{i=1}^n \exp(a_i x_i) - (a_j \exp(a_j x_j))(a_j \exp(a_j x_j))$$
$$\frac{\partial^2 f(x)}{\partial x_k \partial x_j} \approx -(a_j \exp(a_j x_j))(a_k \exp(a_k x_k)).$$

Define diagonal matrix D such that for  $j \in \{1, \ldots, n\}$ ,  $D_{j,j} = a_j^2 \exp(a_j x_j) \sum_{i=1}^n \exp(a_i x_i)$ . In addition, define vector u such that  $u_j = a_j \exp(a_j x_j)$  for  $j \in \{1, \ldots, n\}$ . By definition  $H = D - uu^T$ . Now, in order to prove that f(x) is convex, we will show that  $H = D - uu^T$  is positive semidefinite. Matrix H is positive semidefinite if for any vector  $y \in \mathbb{R}^n$ :  $y^T H y \geq 0$ . Therefore,

$$y^{T}Hy = y^{T}(D - uu^{T})y$$

$$= y^{T}Dy - y^{T}uu^{T}y$$

$$= \sum_{j=1}^{n} \left(y_{j}^{2}a_{j}^{2} \exp(a_{j}x_{j}) \sum_{i=1}^{n} \exp(a_{i}x_{i})\right) - \left(\sum_{j=1}^{n} y_{j}a_{j} \exp(a_{j}x_{j})\right)^{2}$$

$$= \left(\sum_{i=1}^{n} \exp(a_{i}x_{i})\right) \left(\sum_{j=1}^{n} y_{j}^{2}a_{j}^{2} \exp(a_{j}x_{j})\right) - \left(\sum_{j=1}^{n} y_{j}a_{j} \exp(a_{j}x_{j})\right)^{2}$$

$$> 0.$$

The last inequality is based on Cauchy Schwarz inequality:  $(\sum a_i^2)(\sum b_i^2) \ge (\sum a_i b_i)^2$ . As a result, the Hessian matrix of f(x) is positive semidefinite, so f(x) is convex.

2. The function f(x) is differentiable everywhere. And for  $j \in \{1, \ldots, n\}$ 

$$\nabla f(x)_j = \frac{a_j \exp(a_j x_j)}{\sum_{i=1}^n \exp(a_i x_i)}$$

3.  $x^{\text{new}} = x^{\text{old}} - \lambda \nabla f(x^{\text{old}})$ 

$$f(x) = \max_{m \in \{1,\dots,M\}} [a^{(m)} x + b_m]$$
 for  $x \in \mathbb{R}^n$  and constants  $a^{(1)},\dots,a^{(M)} \in \mathbb{R}^n$  and  $b_1,\dots,b_M \in \mathbb{R}$ .

- 1. Proof. For  $m \in \{1, ..., M\}$  define  $g_m(x) = a^{(m)^T}x + b_m$ . Every  $g_m(x)$  is affine, so they are all convex. On the other hand, the pointwise maximum of convex functions is convex. So, in conclusion  $f(x) = \max_{m \in \{1, ..., M\}} [g_m(x)]$  is convex.
- 2. f(x) is not always differentiable, so we need to hire subgradient.

$$\left. \nabla f(x) \right|_{x^*} = \begin{cases} a^{(m^*)} : m^* \text{ is the unique answer to } \operatorname{argmax}_m a^{(m)^T} x^* + b_m \\ \operatorname{any \ convex \ combination \ of \ members \ of} \left\{ a^{(m)} : m \in \left\{ \operatorname{argmax}_m a^{(m)^T} x^* + b_m \right\} \right\} \end{cases}$$

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3. x^{\text{new}} = x^{\text{old}} - \lambda \nabla f(x^{\text{old}})
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Google Colab

For the next two questions, I am sharing with you two notebooks from Google Colab.

YouTube Intro to Google Colab

I strongly encourage you to submit your future homeworks via Colab. Because

- It is a highly promising platform that you will find quite useful in near future.
- It makes it easier to discuss your work during office hours.
- It makes it easier for you to submit without any additional document.
- And there might be bonus points for students who submit via Colab.

For submitting your homeworks, remember to share an editable link.

# Problem 2: Line Search vs. Fixed Step Size

Please find the answer to the second question in Colab Question 2

- You can add comments that everyone see. Please let us know if there is something wrong or confusing, and please ask all of your questions.
- You need to upload the file linreg.data (At the very left hand side: Files  $\rightarrow$  Upload to session storage)
- $\bullet$  My personal favorite: Runtime  $\to$  Restart and run all

#### **Problem 3: Numerical Gradients**

Please find the answer to the third question in Colab Question 3

- You can add comments. Please do.
- You do not need to upload the file cvxnum.py. It has been copy pasted there.