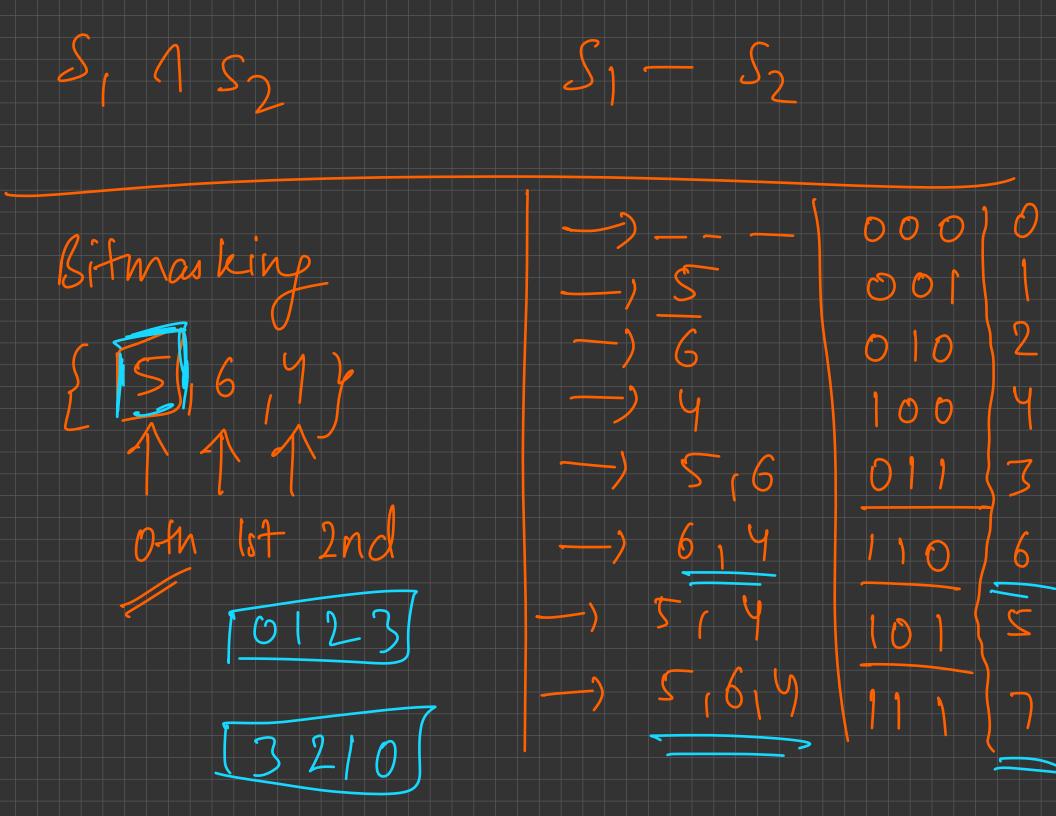
DP with Sitmasking

Dynamic Programming 5 Bitmasking & Results

- Priyansh Agarwal

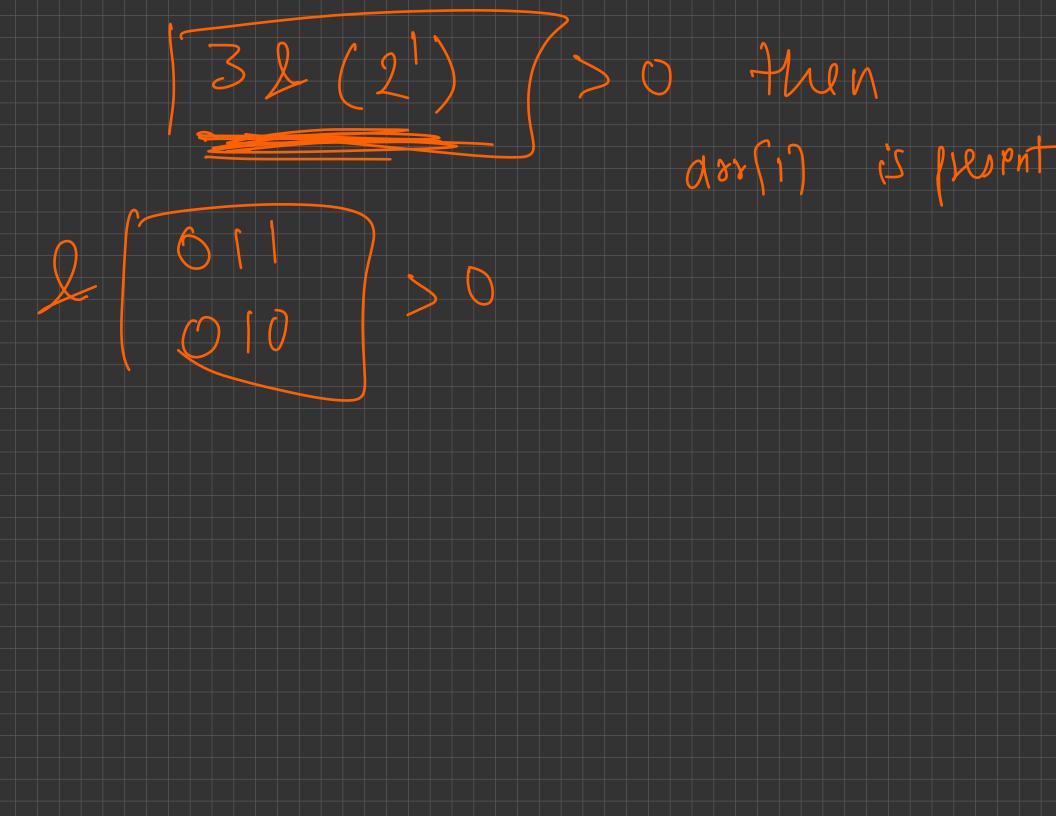
Space -> 2n.n Time to search in susset = o(n) **-**) 5, 6 insert in susset = o(1) -) 6, Y **-)** 5, 4 delete -> o(n) -) 5, 6, 4

Set Space Vector Search o(n) = -) 2^n , no(logn) = O(logn) _ Insert o (1) = Belefe O(n) o(logn) O (nlogn) 95,64 S, U Sz 7 256,44 56,437 0 (n) 95,6,43 50,0,03



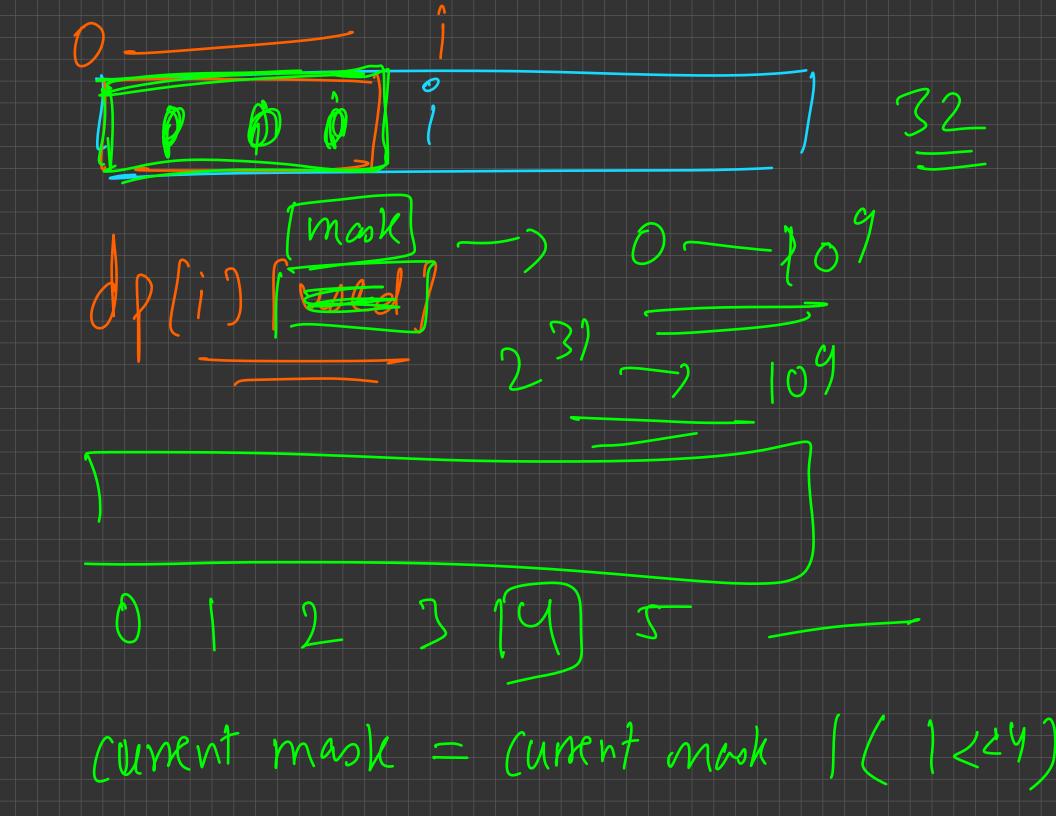
an element in susset Search 25,6,9 ass (1) present in

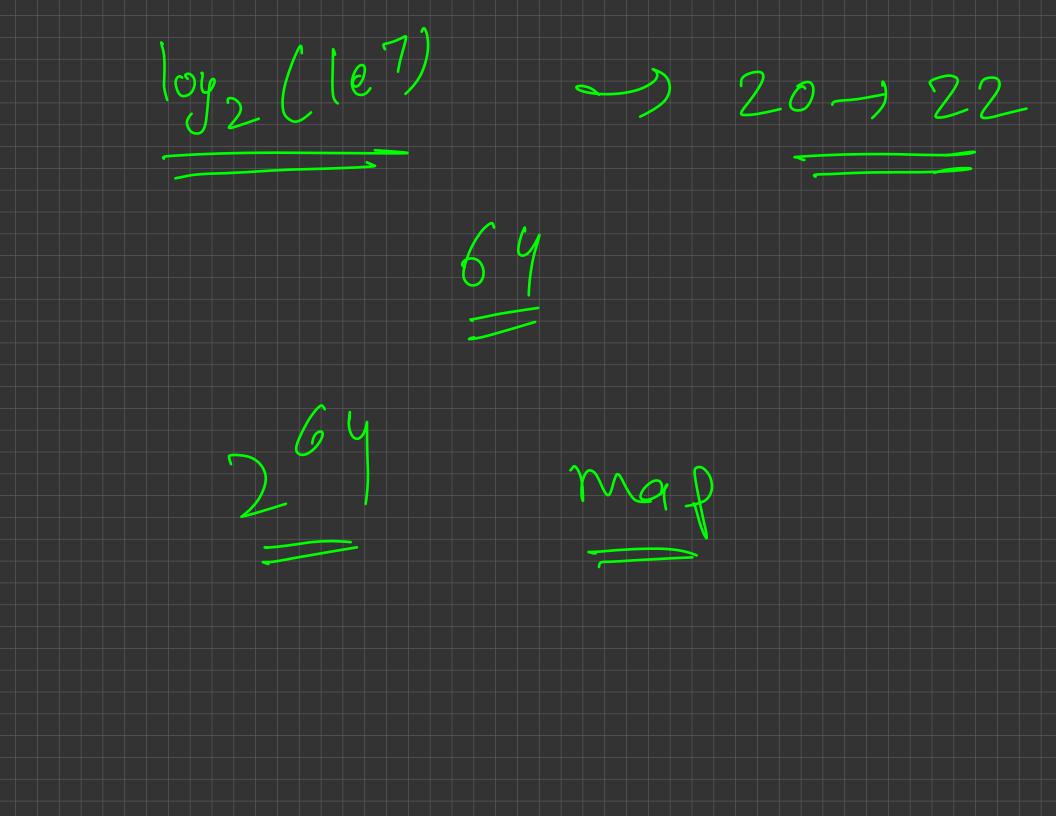
Subjet or not



Susset -) ith elevent of anag is greent or Search 5,6, Deletion

ecement present take xoo if # (D & C / Z c i) D 1 (125) Unio D₁ D₂ Interoction





array

DP with Bitmasking

- Bitmasks
- Basic operations on Bitmasks
- Limitations on "N" (You will need 2ⁿ integers to represent all the subsets)

Problem 1:

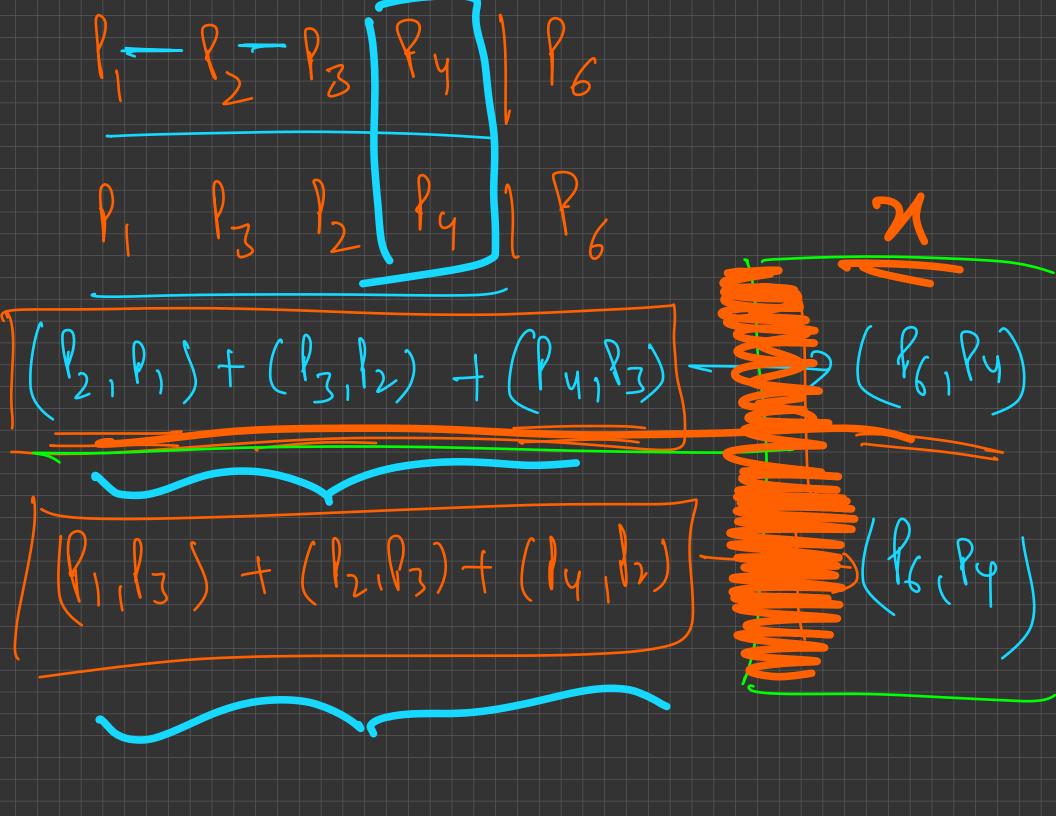
Given a list of points on a 2D plane, rearrange these points in any way such that in the final permutation of points, the sum of distances of the adjacent elements is minimized.

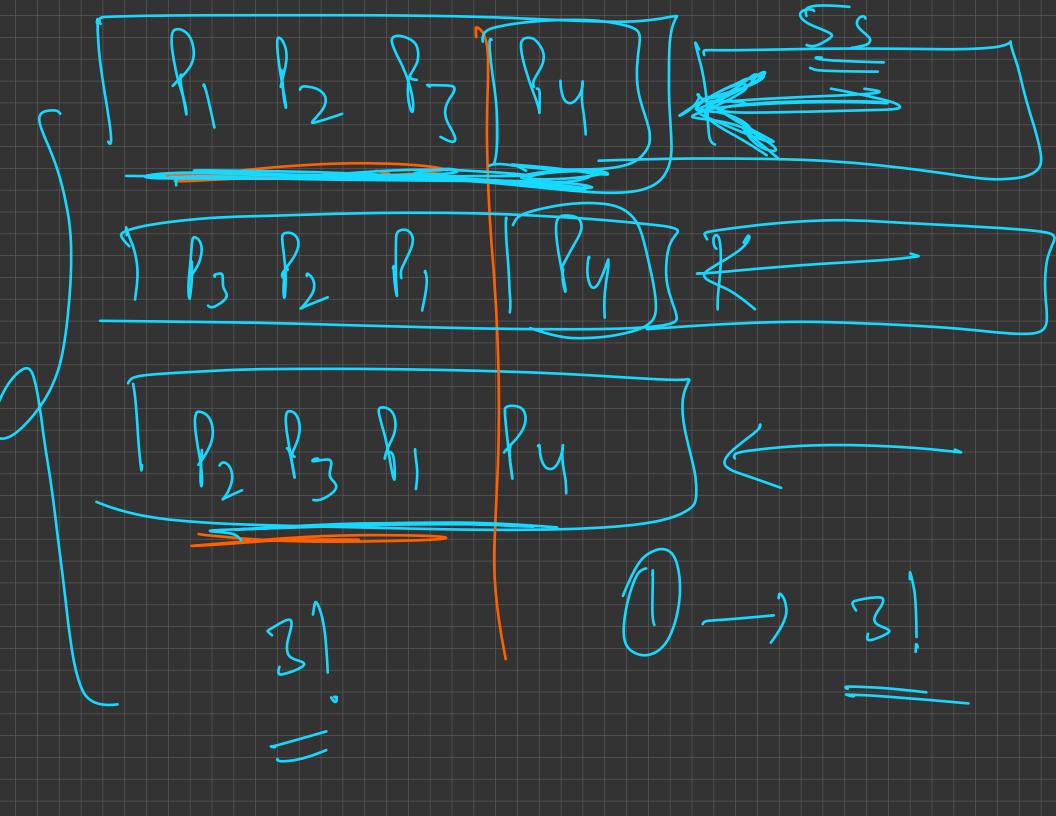
Points: [{0, 0}, {5, 6}, {1, 2}]

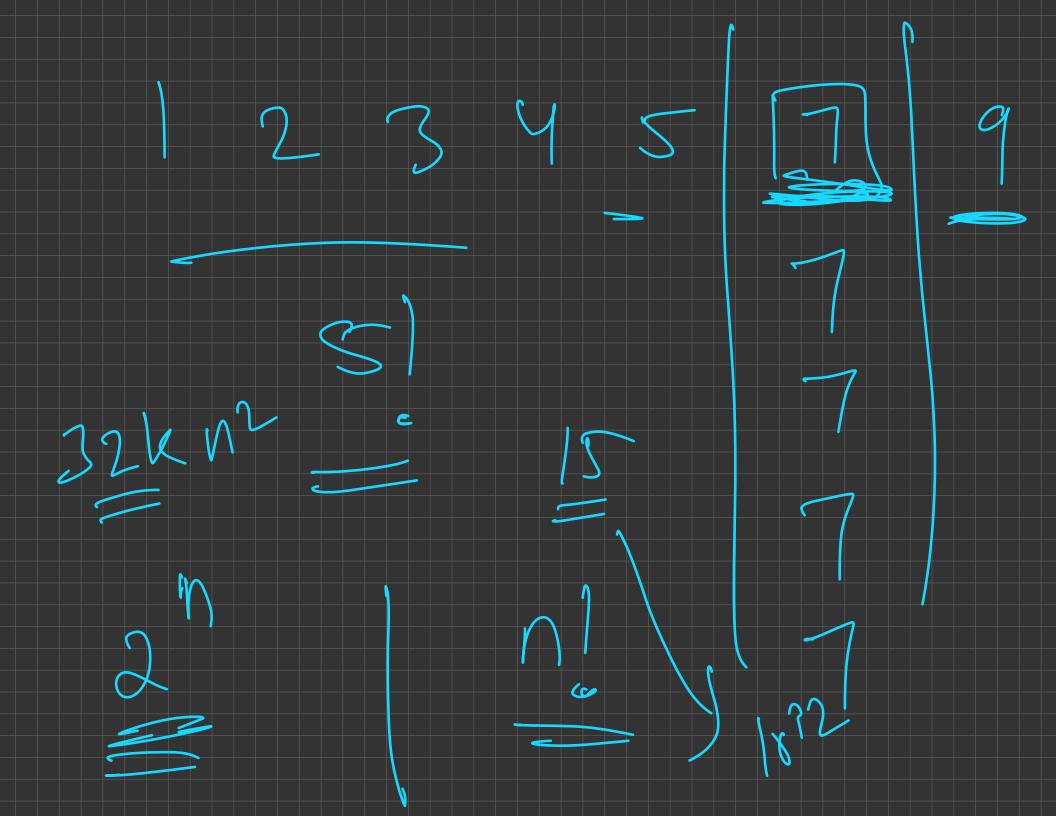
Best permutation -> [{0, 0}, {1, 2}, {5, 6}]]

Ans = Dist(P1, P3) + Dist(P3, P2)

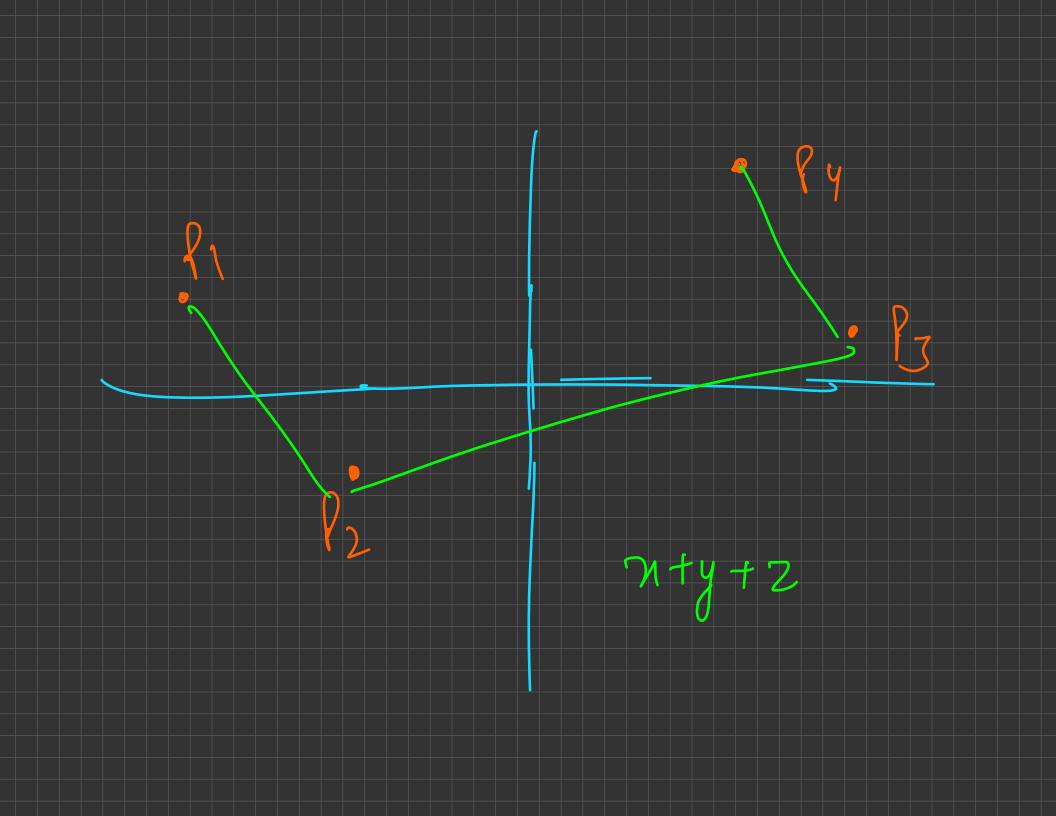
(0,0) (5,6) (1,2) (1,2) (1,2) (1,2)Dist [{5,64,40py) + Dist {5,64,41,24} Dist [\(\lambda \) 1,24,20,04) + Dist [\(\lambda \),054,25,64)



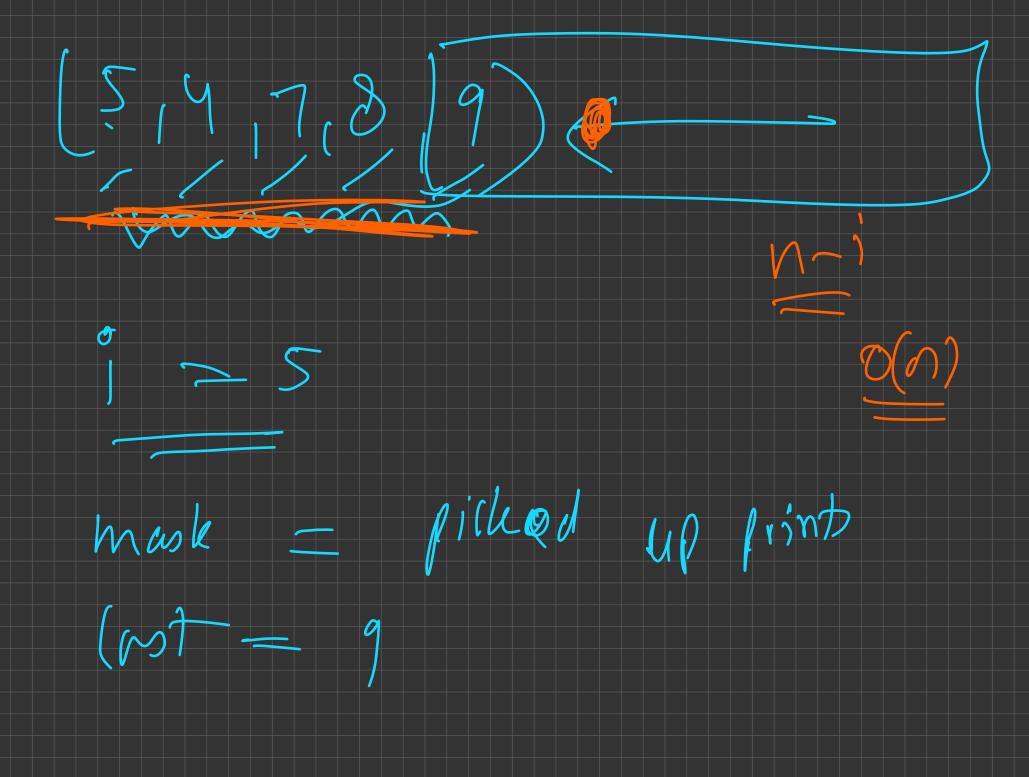


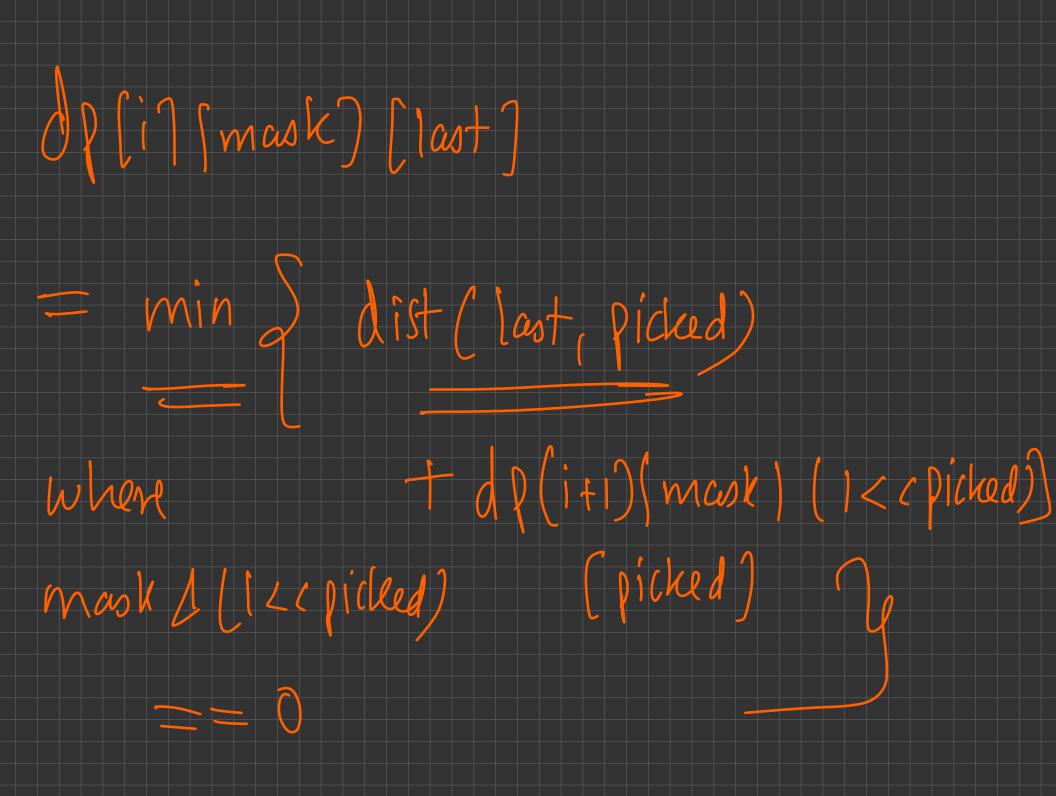






dp [i] [mask] [last] = you have already fixed i points so for , in which mask seprents the Enact points you have used and last offerent last element graced. - min sum of distances from ith point to (n-1) the foint provided the boint





Problem 1: TC: O(n³2ⁿ), SC: O(n²2ⁿ)

```
state:
    dp[i][bitmask][last element] = minimum sum of distances in the suffix [i... n - 1]
    such tha bitmask represents the elements in the first i - 1 elements and last elements
    represents the last point
transition:
    check for jth point from (0 \text{ to } n-1)
    can you pick the jth point as the ith element in the final array or not
    if(bitmask & (1 << j)){ whether jth bit is set or not
        continue:
    }else{
        dp[i][bitmask][last element] = min(dp[i][bitmask][last element],
        (bitmask != 0 ? dist(j, last element) : 0) + dp[i + 1][bitmask | (1 << j)][j]
base case:
    dp[n][(1 << n) - 1][anything] = 0
final subproblem
    dp[0][0][anything]
```

Problem 1: TC: O(n²2ⁿ), SC: O(n*2ⁿ)

```
state:
   dp[bitmask][last element]
    i = set_bits(bitmask)
    = minimum sum of distances in the suffix [i... n-1] such tha bitmask represents the
    elements in the first i - 1 elements and last elements represents the last point
transition:
    check for jth point from (0 \text{ to } n-1)
    can you pick the jth point as the ith element in the final array or not
    if(bitmask & (1 << j)){ whether jth bit is set or not
        continue:
    }else{
        dp[bitmask][last element] = min(dp[bitmask][last element],
        (bitmask != 0 ? dist(j, last element) : 0) + dp[bitmask | (1 << j)][j]</pre>
base case:
   dp[(1 << n) - 1][anything] = 0
final subproblem
    dp[0][anything]
```

Permitation proscerns Bitmasking permutations

Problem 2: <u>Link</u> (Homework)

State

0

Transition

0

Base Case

0

• Final Subproblem

0

Trick to identify a DP problem?

Repeating subtasks:

- If I have the answer of state, then why should I calculate it again and waste time

Pro Tips for contests:

- Number of ways problems -> DP, Brute Force or some formula
- Look for small constraints in the problem. (Most probably it would be dp and not greedy)
- Identify states and transition time for each state.
- Calculate time complexity as (number of states * transition time for each state).
- If this number fits into your Time limit (Great), if not, try to see if you can skip some states and still get the right answer.
- Try to reduce the transition time by using some Data Structure or some clever observation if transition time is the bottleneck
- Never try to over optimize. If your current states and transition time fit into your Time Limit, just code it and do not optimize it further.

Common states and transitions with constraints

```
total operations <= 1e8
√ <= 125 :
   state: O(n^3), transition: O(1), [n <= 100 O(logn) is possible]
   state: O(n^2), transition: O(n), [n \ll 100 O(n \log n) \text{ is possible}]
   state: U(n), transition: O(n^2)
             de proton or or loute force
n <= 5000:
   state: O(n^2), transition: O(1) [n <= 1000 then O(logn) is possible]
   state: O(n), transition: O(n) [n <= 1000 then O(nlogn) is possible]
n <= 1e6:
   state: O(n), transition: O(1), O(logn)
1 second <= operations <= 4 * 1e8
4 second = operations <= 1e9
```