Dynamic Programming 3

- Priyansh Agarwal

Removal gang (883) State desireil = mon sum the current Player can get from Eusarray (i toj)

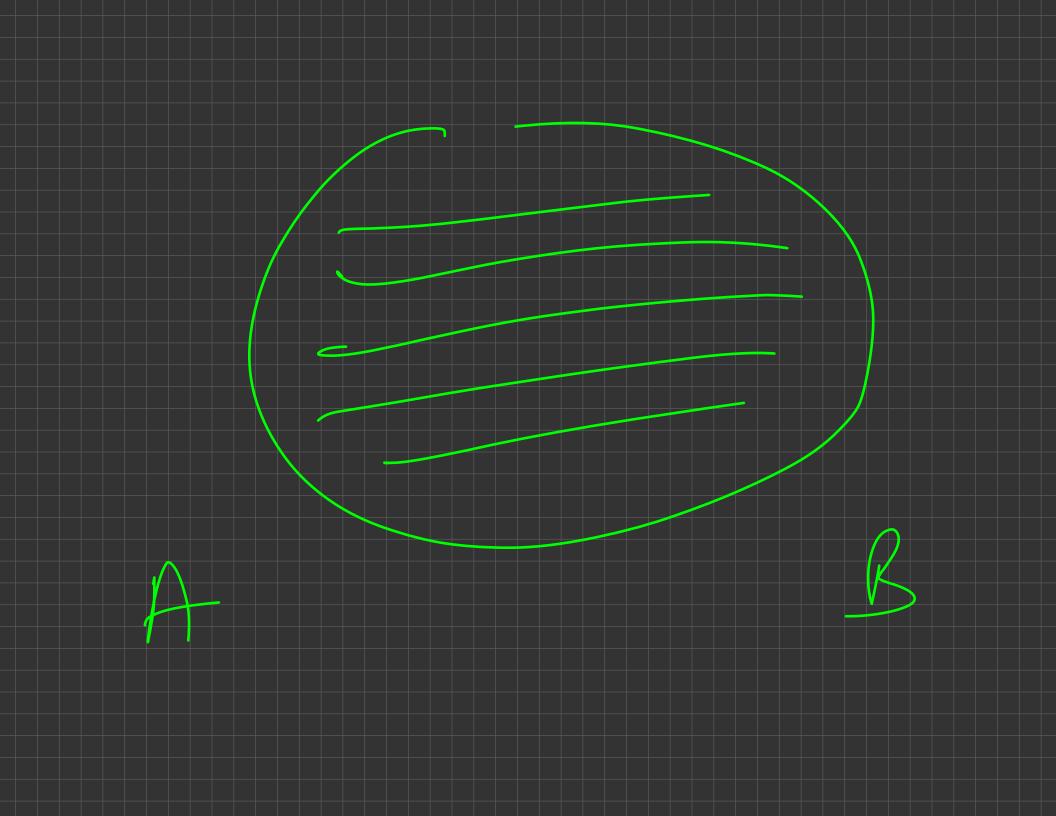
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arrived Sum (i+1) (s) -dp (i+1) (j) (i) (j-1) - de (i) (j-1) $\beta - c = glilli = osslil, fz = glesilli$

de (:)(:) man score that let player (on get from (i toj) de (0) (n-1)

arr (1) + de (1) (n-1) $\frac{1}{2} \left(\frac{1}{2} \left(\frac{1}{2} \left(\frac{1}{2} \left(\frac{1}{2} \right) \right) + \frac{1}{2}$ $\frac{dP(1)(n-1)}{min} = \frac{a88(1)}{a88(1)} + \frac{dP(2)(n-1)}{dP(1)(n-2)}$

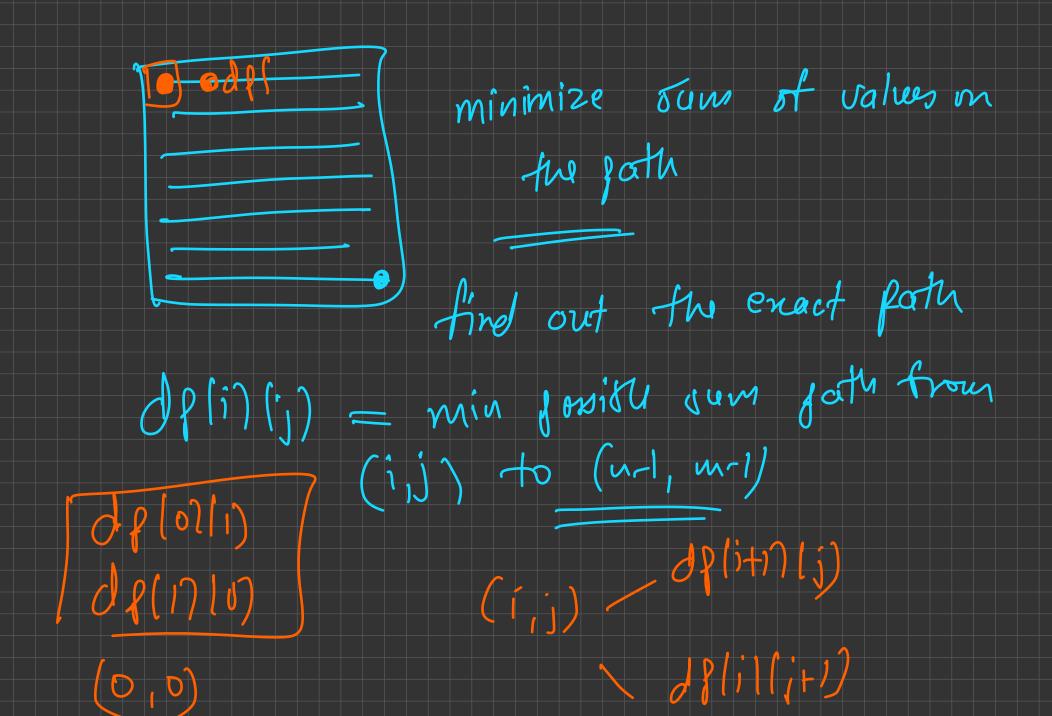
(D,S) --> 1st flages With it arey = 6 257 / Cayer (~~~ Ind flager odd lent of arry 2st pages odd ever

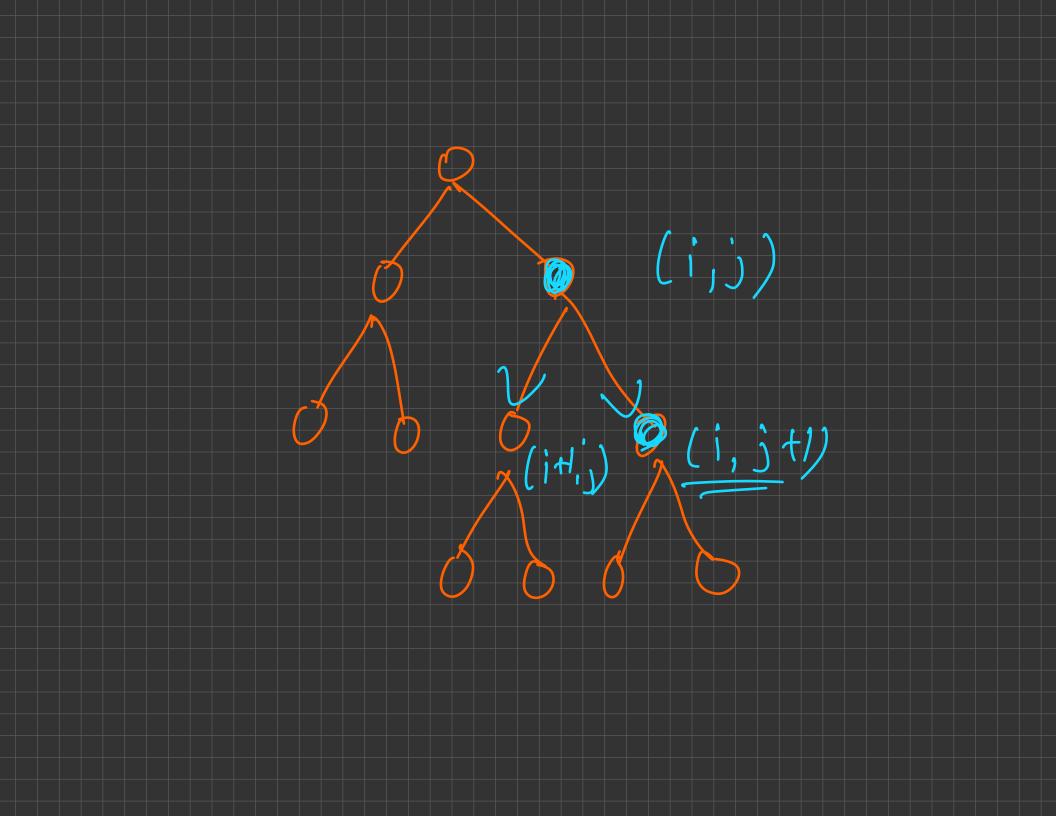


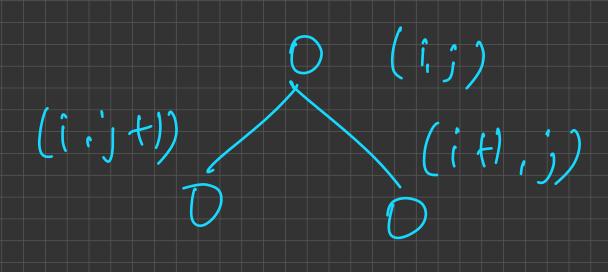
- Answer Construction Hard DP podern Spau optimisation optimisation State - Trawitton optimisation

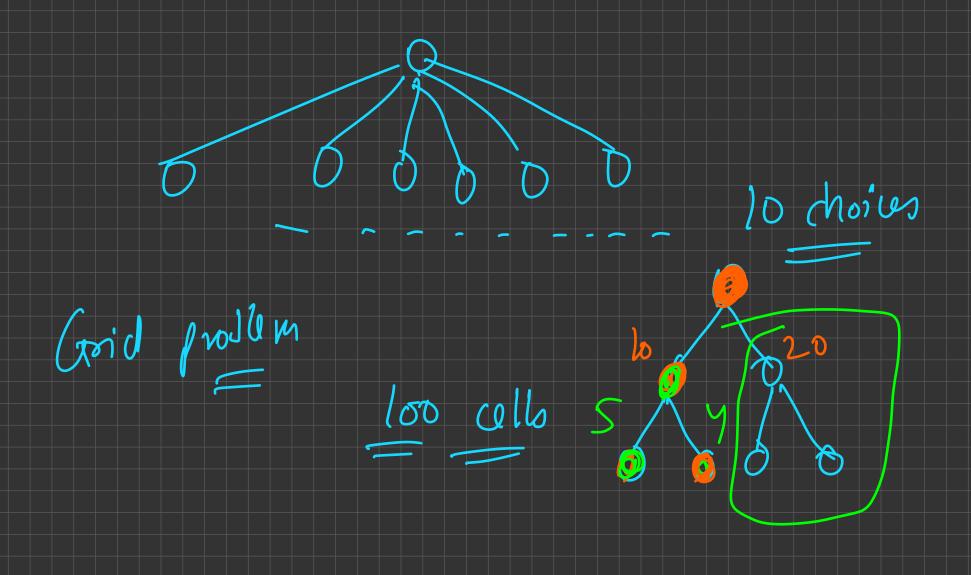


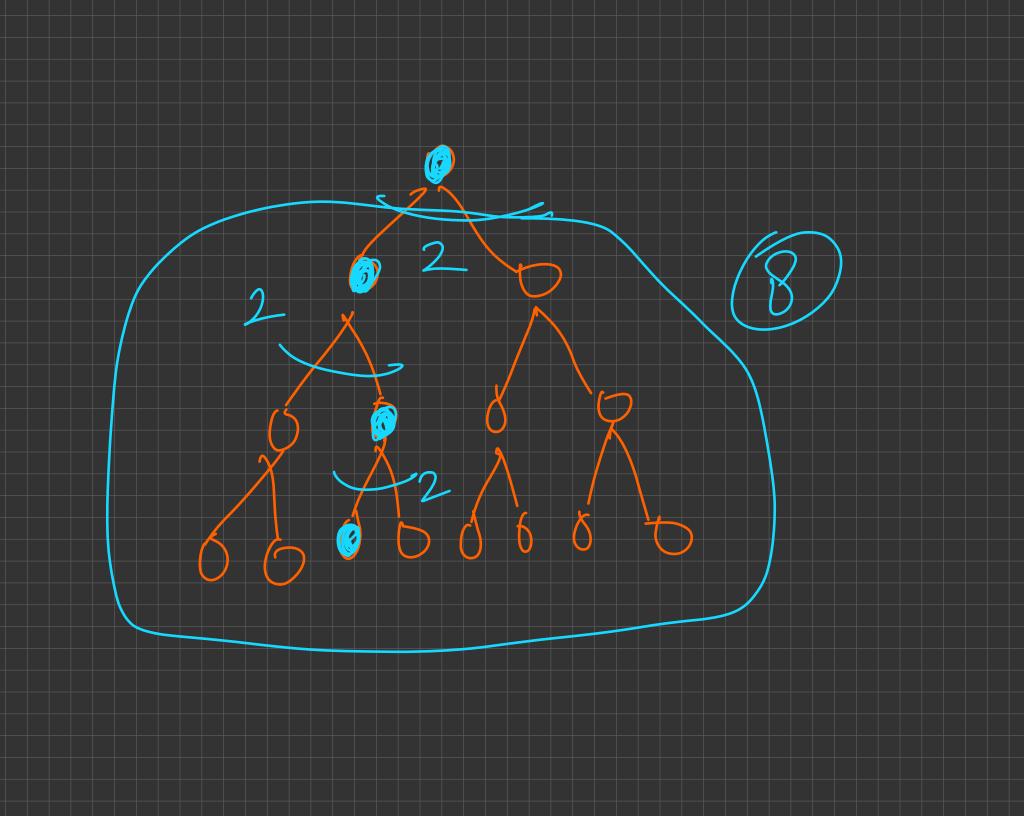
- At every state we are making some optimal choice.
 - If we store this choice, we can be sure that if we are at any state we know what is the best choice.
 - Start from the state that contains your final subproblem and keep making the best choice (which was already stored) until you reach the end.

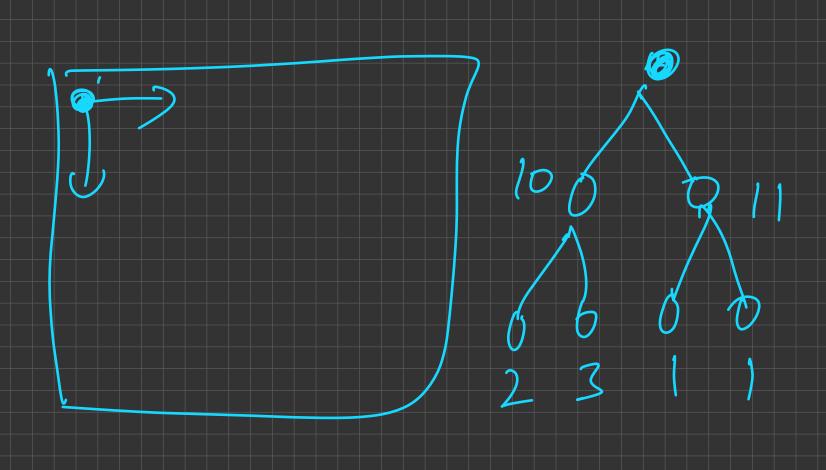


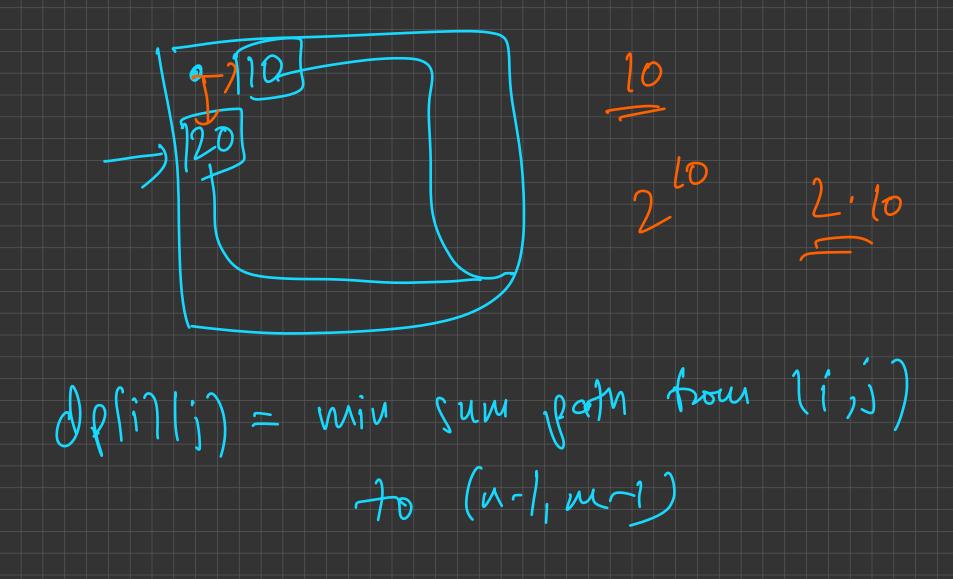


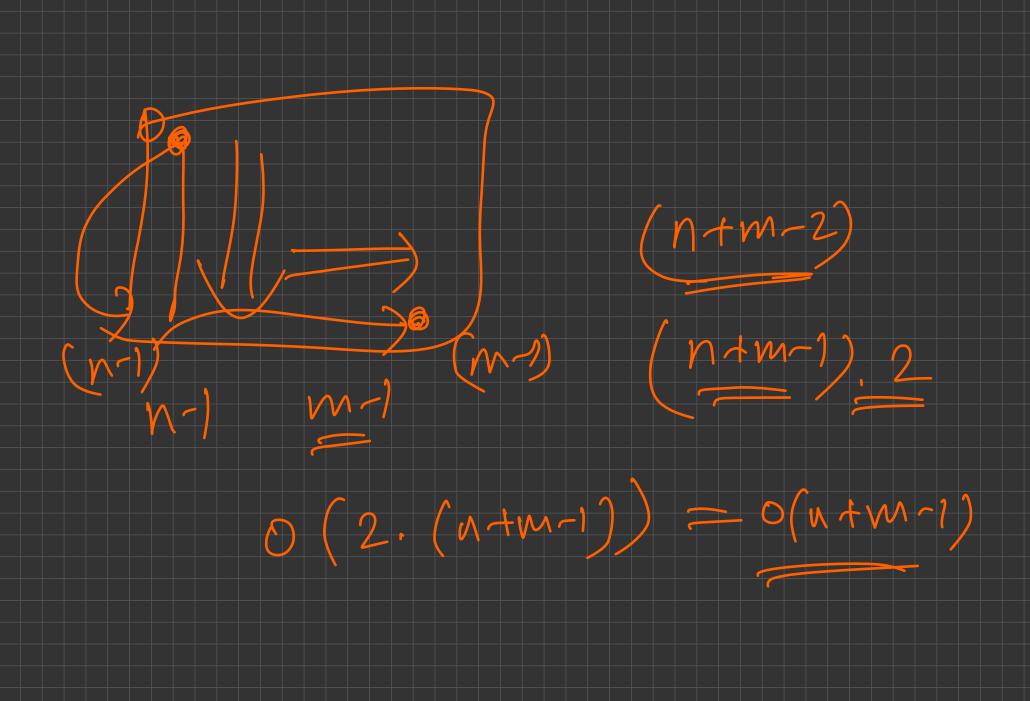


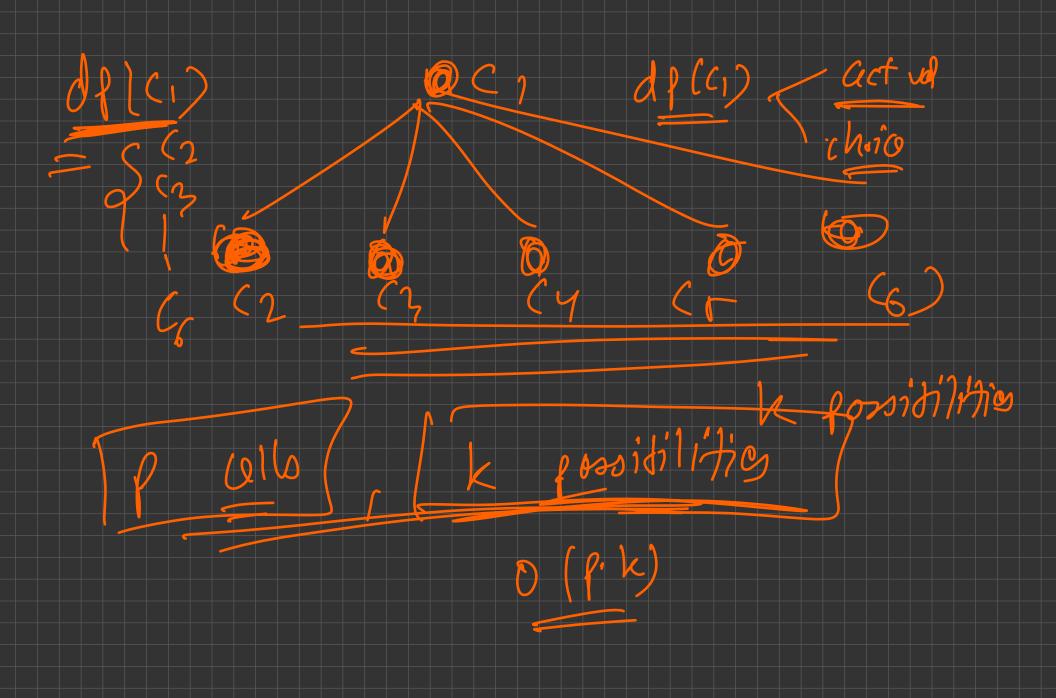


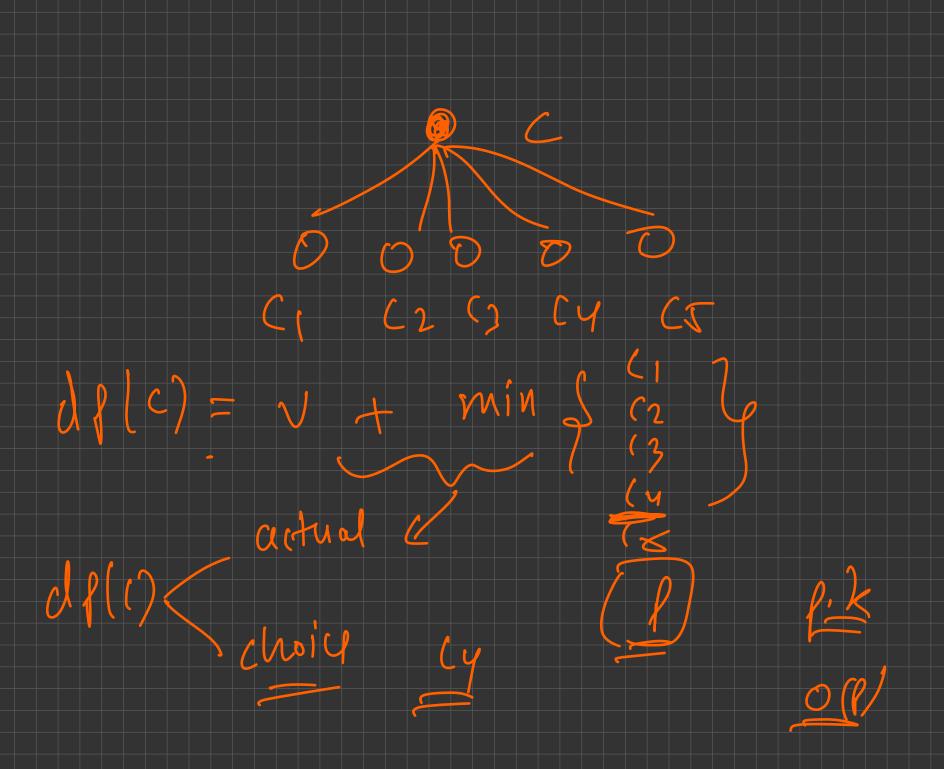












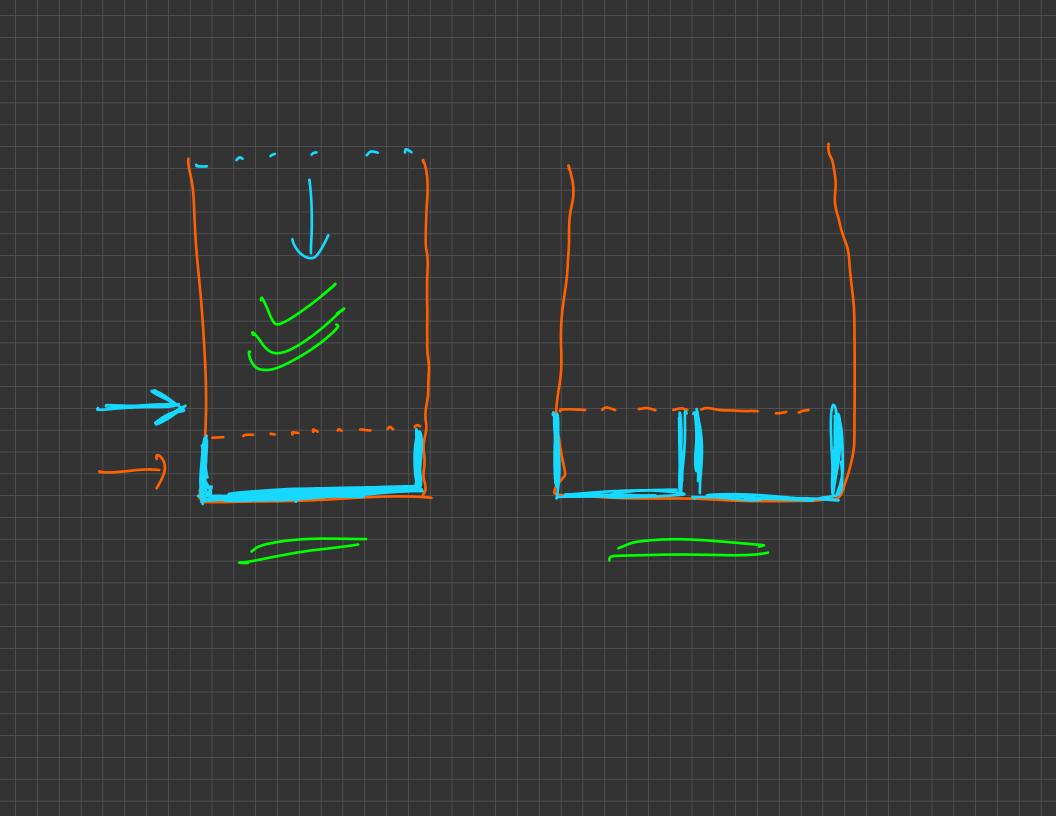
Answer Construction - Grid Problem

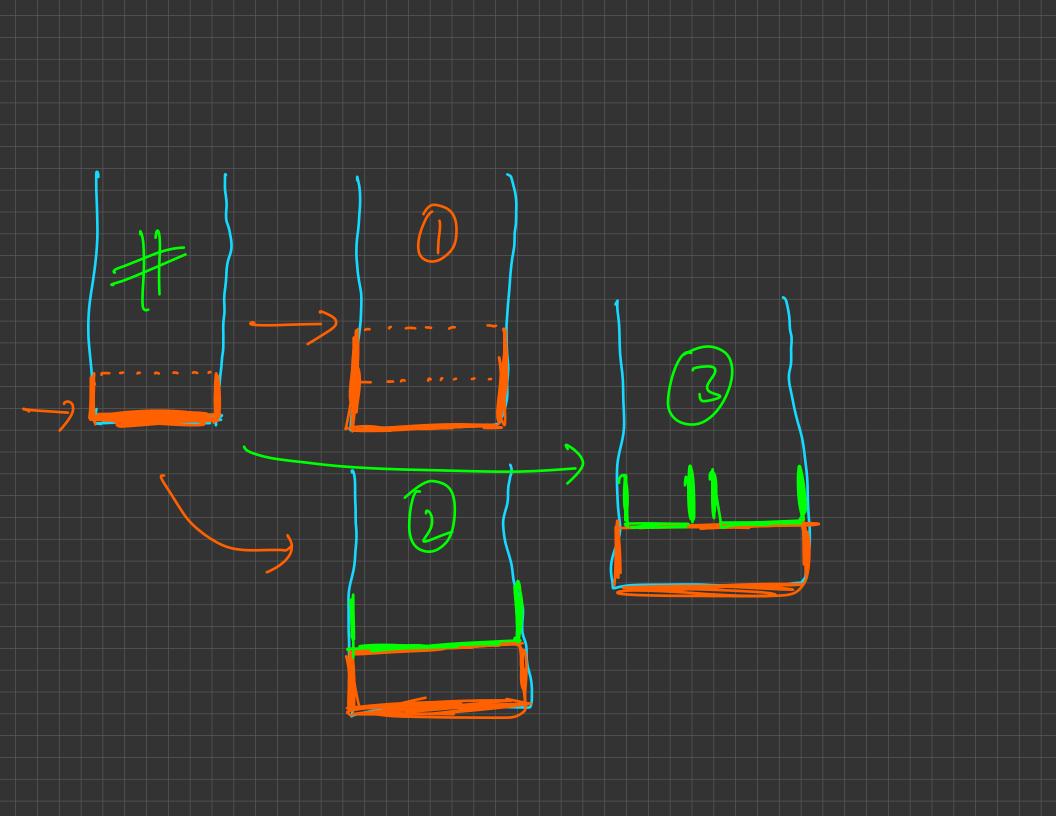
```
int n = 3, m = 3;
vector<vector<int>> grid(3, vector<int>(3));
vector<vector<pair<int, int>>>> dp(n, vector<pair<int, int>>>(m, {-1, 0}));
  0 -> take a down direction
// 1 -> take a right direction
int f(int i, int j){
    if(i == n \mid\mid j == m)
        return 1e9:
                                            dp[i][j]. tool - sval
dp[i][j]. sec - s choice
    if(i == n - 1 \&\& j == m - 1)
        return grid[n-1][m-1];
    if(dp[i][j].first != -1)
        return dp[i][j].first;
    int ans1 = f(i + 1, j);
    int ans2 = f(i, j + 1);
    if(ans1 < ans2){
        dp[i][j].second = 0;
    lelse{
        dp[i][j].second = 1; ____
    return dp[i][j].first = grid[i][j] + min(ans1, ans2);
```

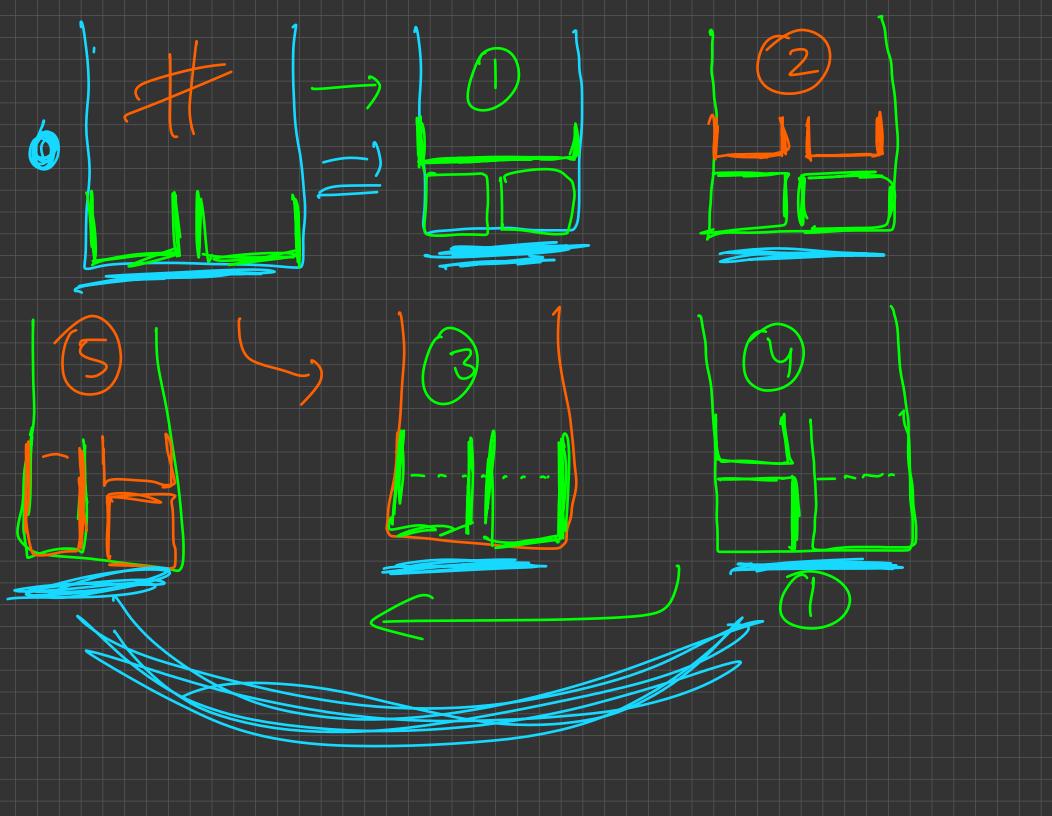
Answer Construction - Grid Problem

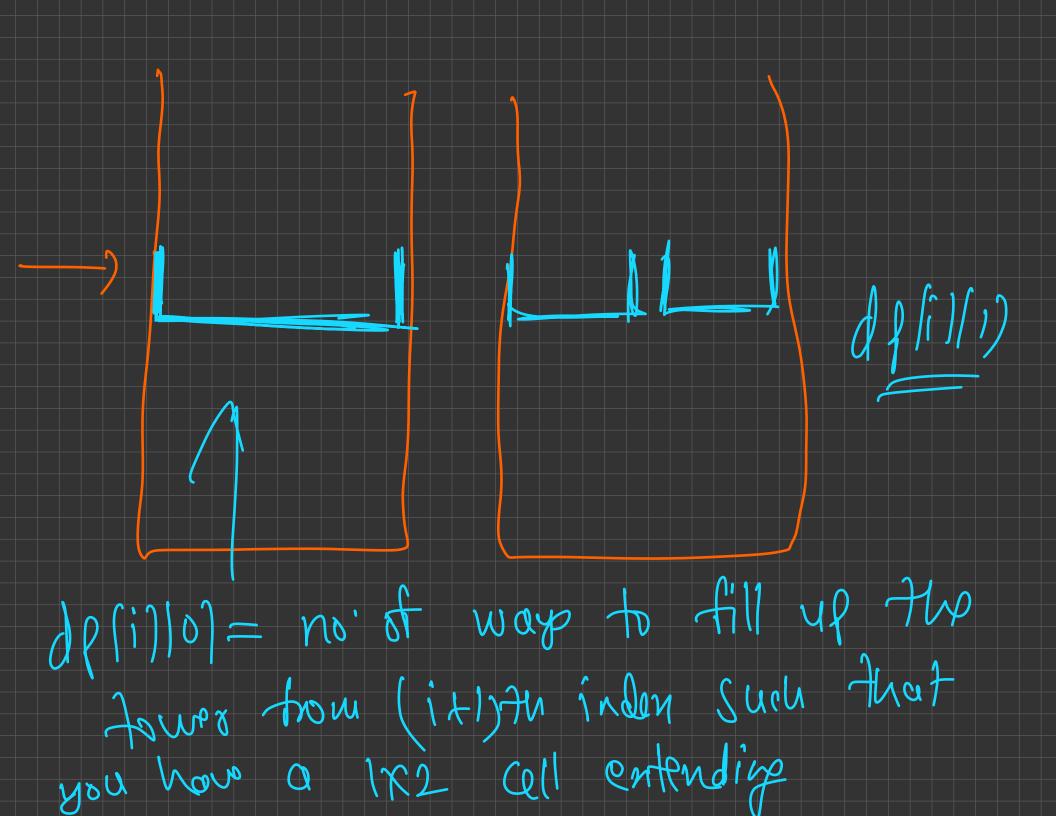
```
void solve(){
   for(int i = 0; i < 3; i++){
        for(int j = 0; j < 3; j++){
                                               evaluate
            cin >> grid[i][j];
   cout \ll f(0, 0) \ll nline;
    pair<int, int> current = {0, 0};
   while(current != mp(n - 1, m - 1)){
        cout << current.first << " " << current.second << nline;</pre>
        if(dp[current.first][current.second].second == 0)
            current.first++;
        else
            current.second++;
    cout << current.first << " " << current.second << nline;</pre>
```

Problem 1: Link

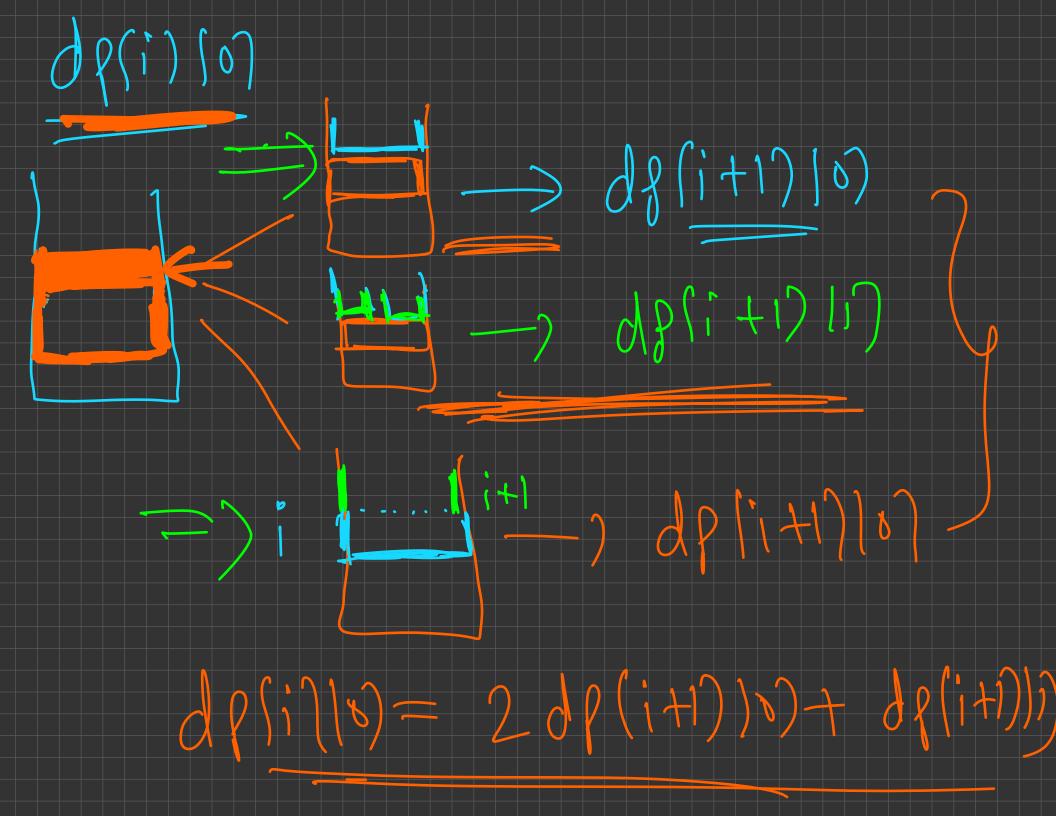


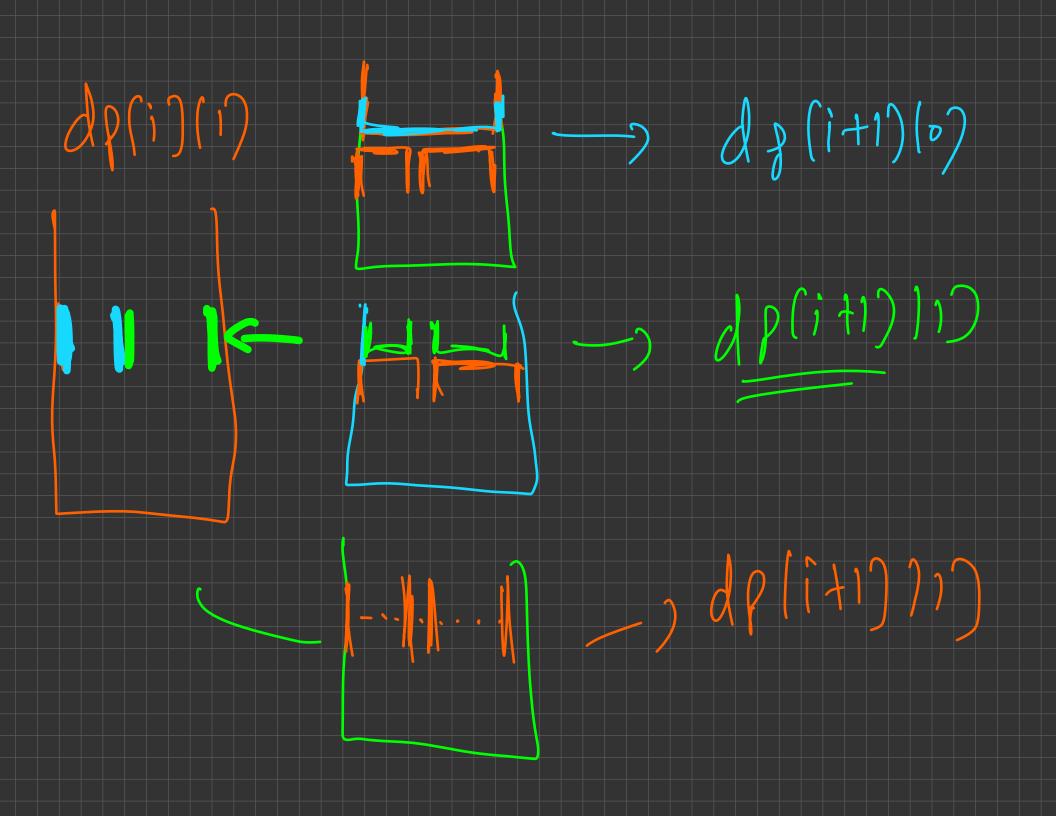


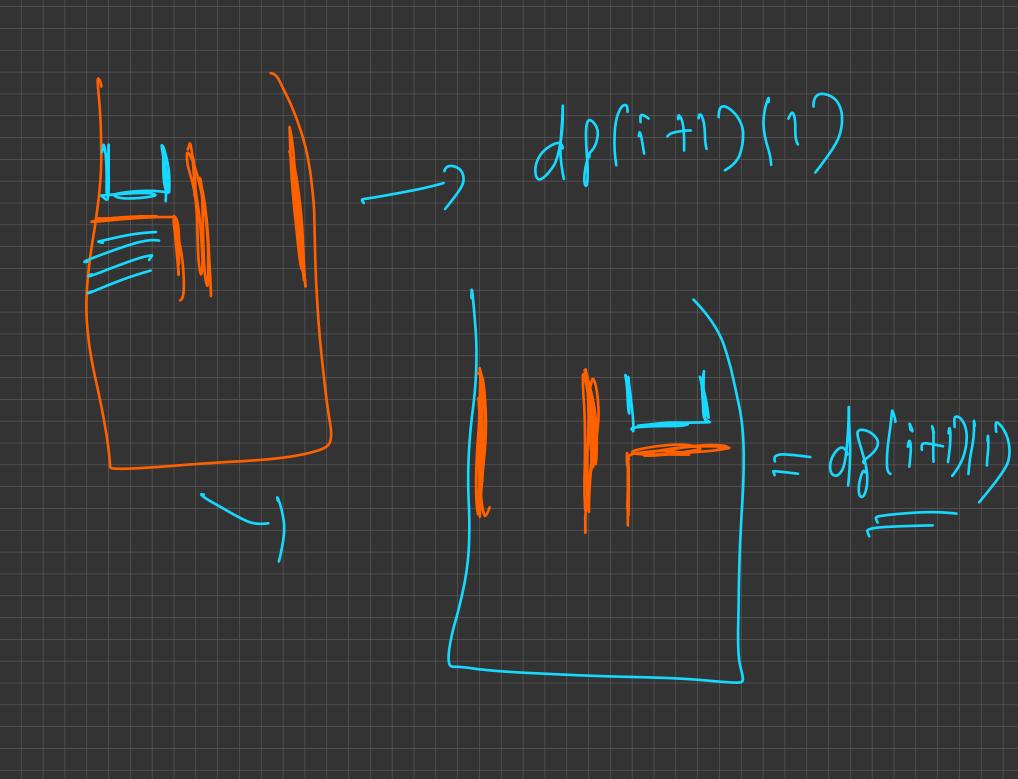


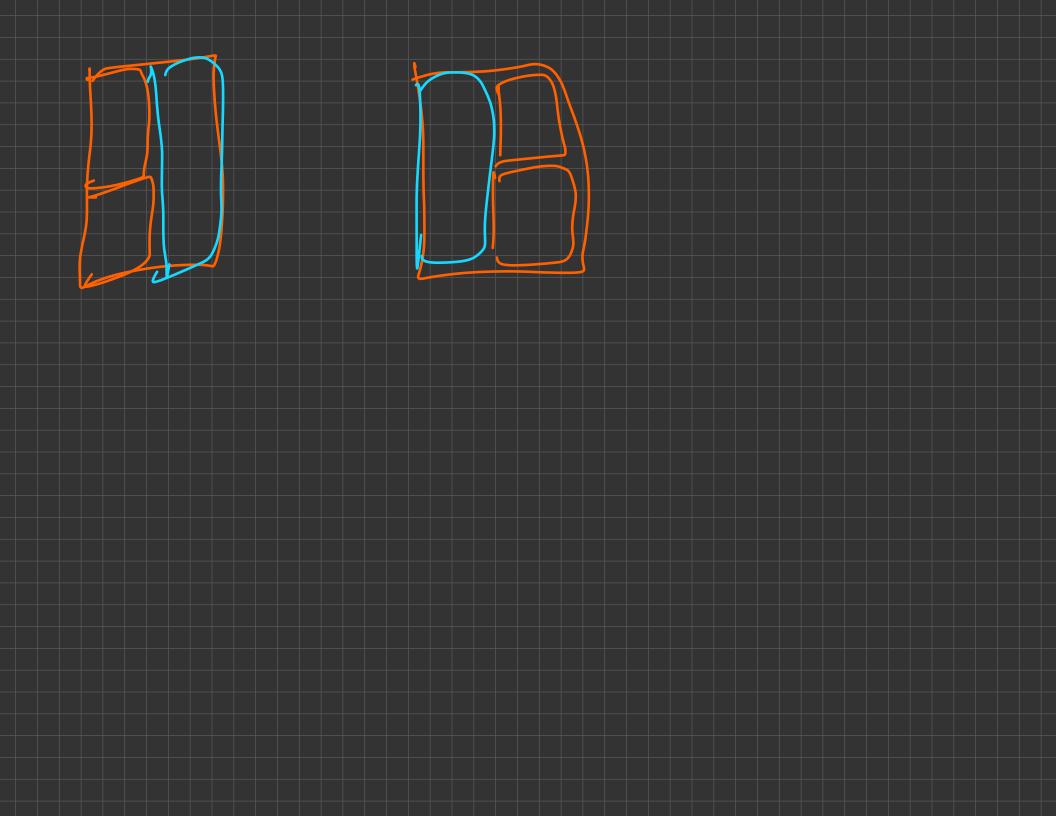


dp (i) 10) = no of ways to fill the tower from (i+1)th row to the for set you have a 7×2 lel) enpurise df(i)(1)= no of ways to till the tower from (i+1)+h vow to the for set you have 2 (x1) cells enterly

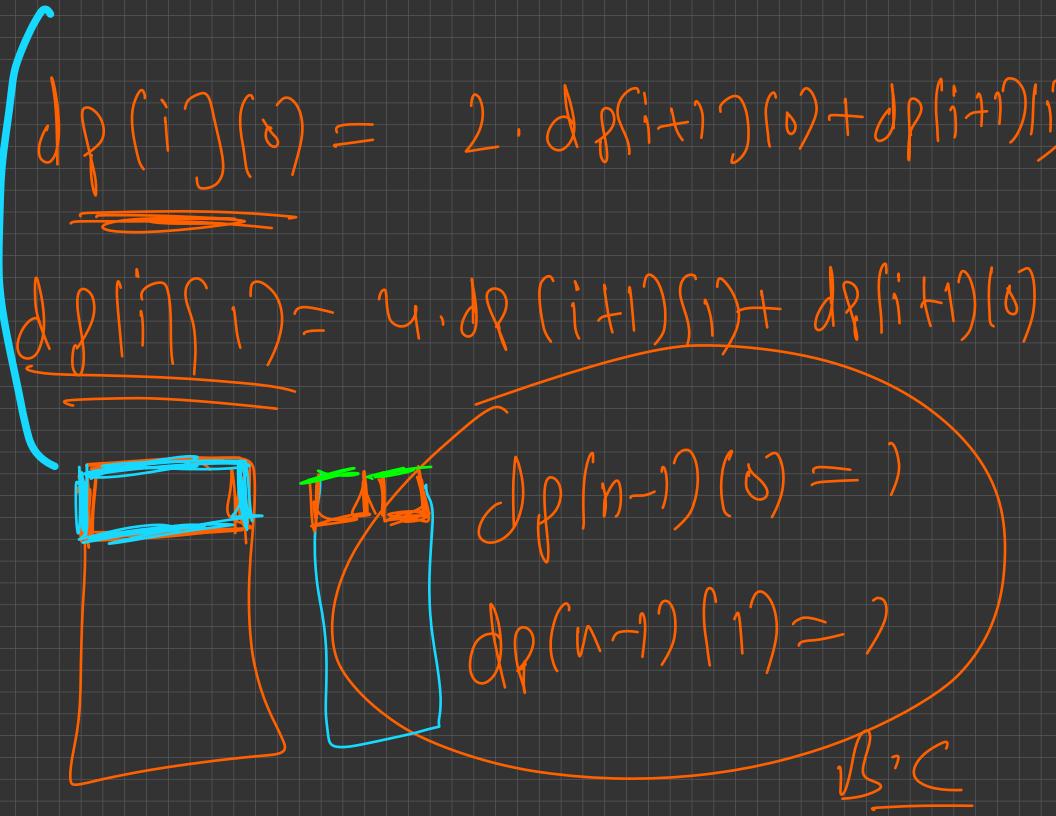


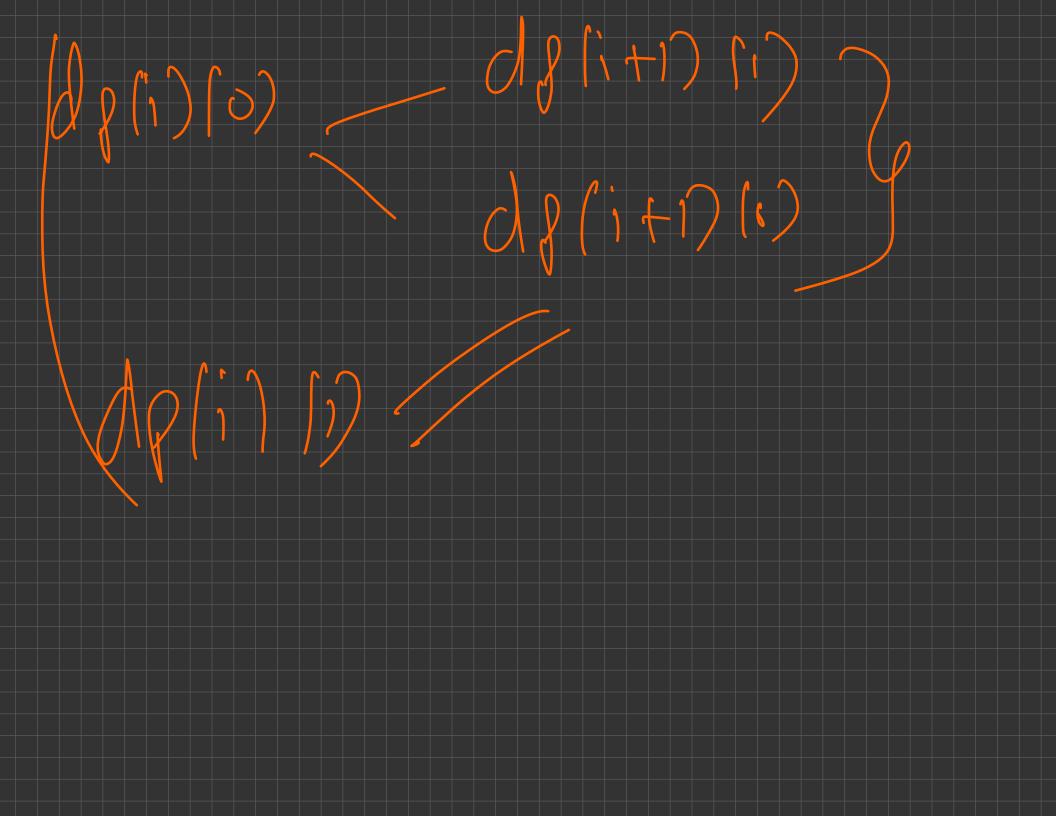


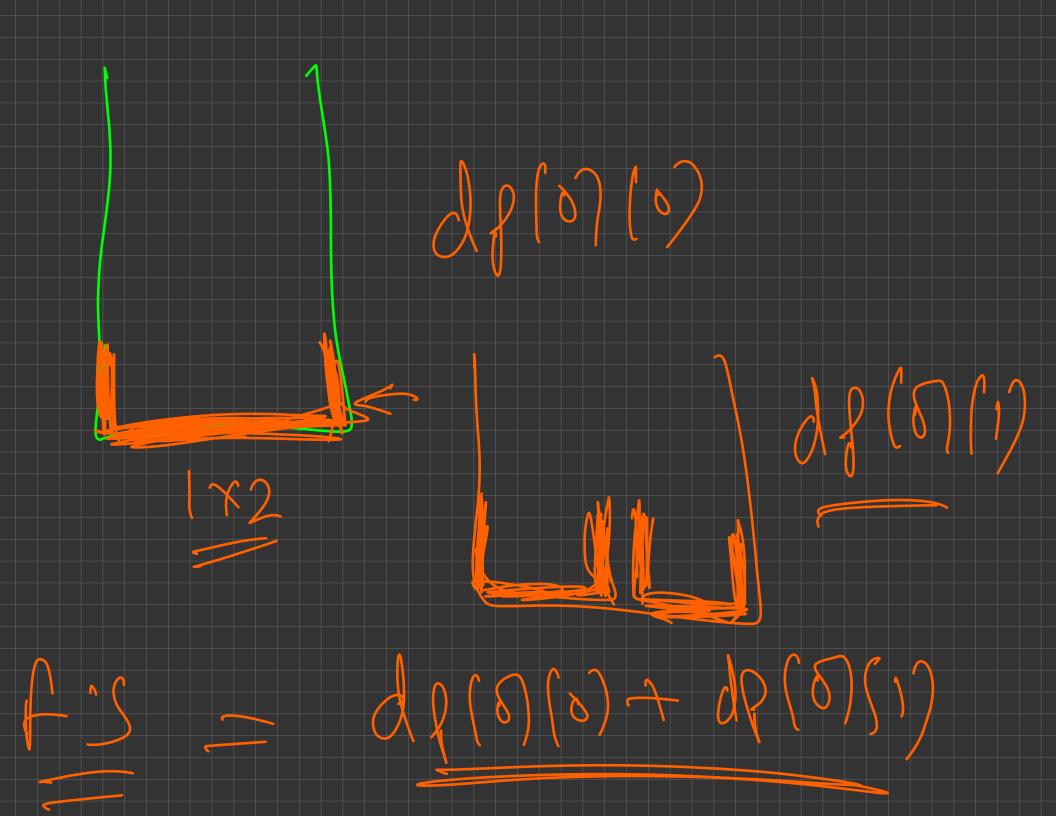


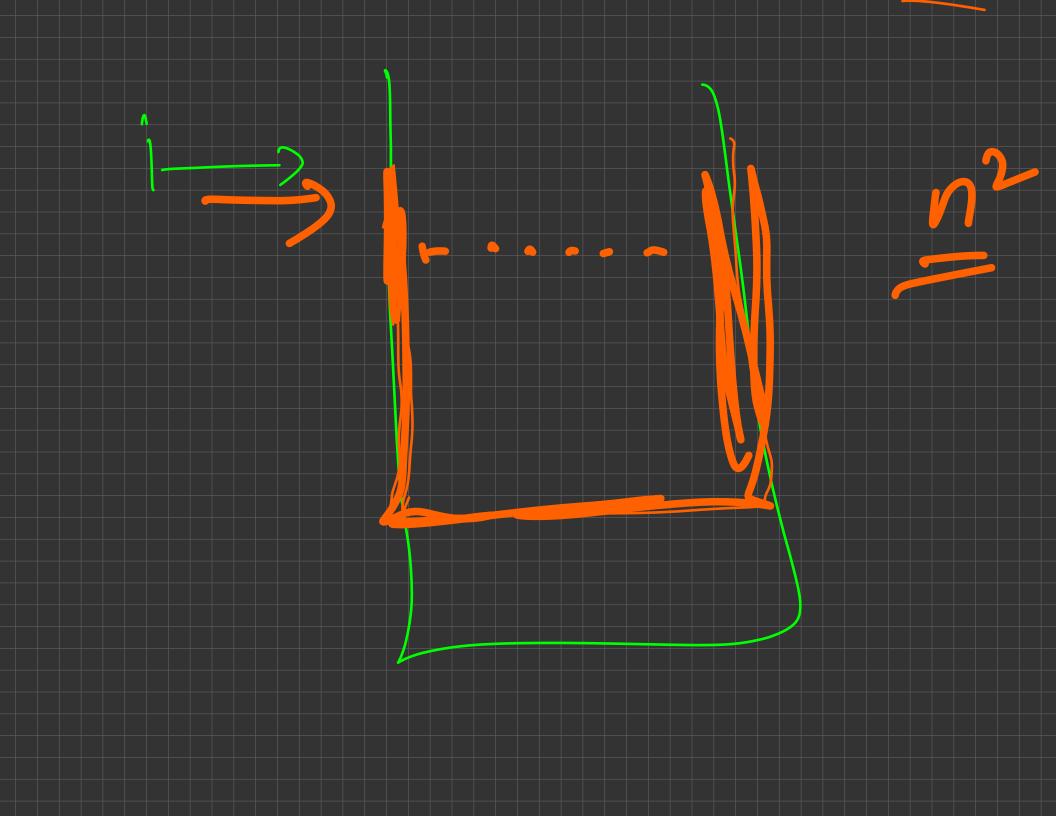


dP(i)(i) = dp(i+1)(i)+ 4. dg(i+1) O(1) $\leq C$ 0 (0) 7. (0(1)





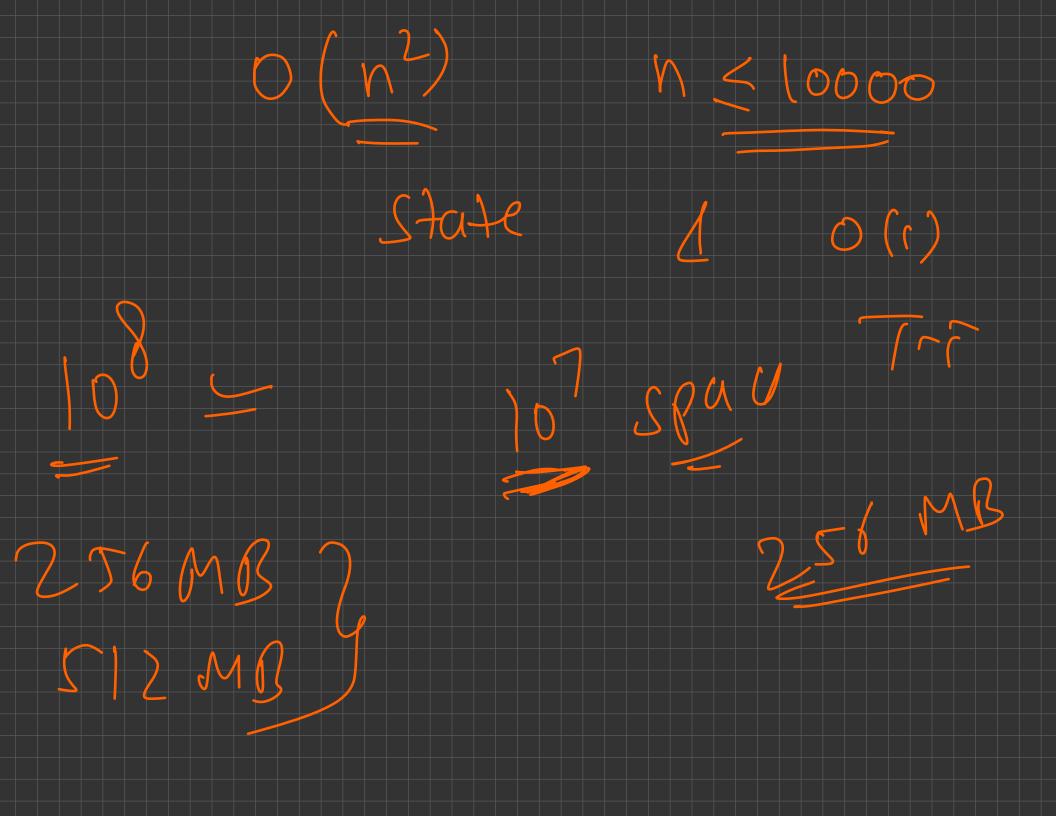




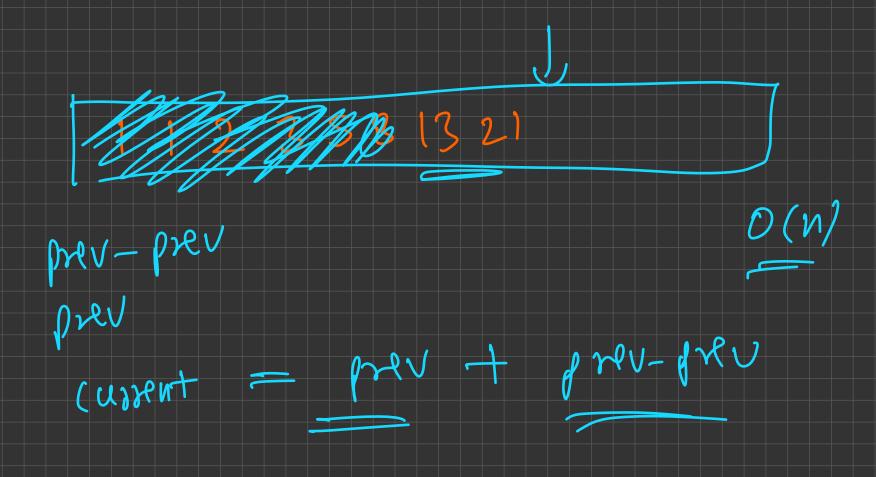
Space Optimization

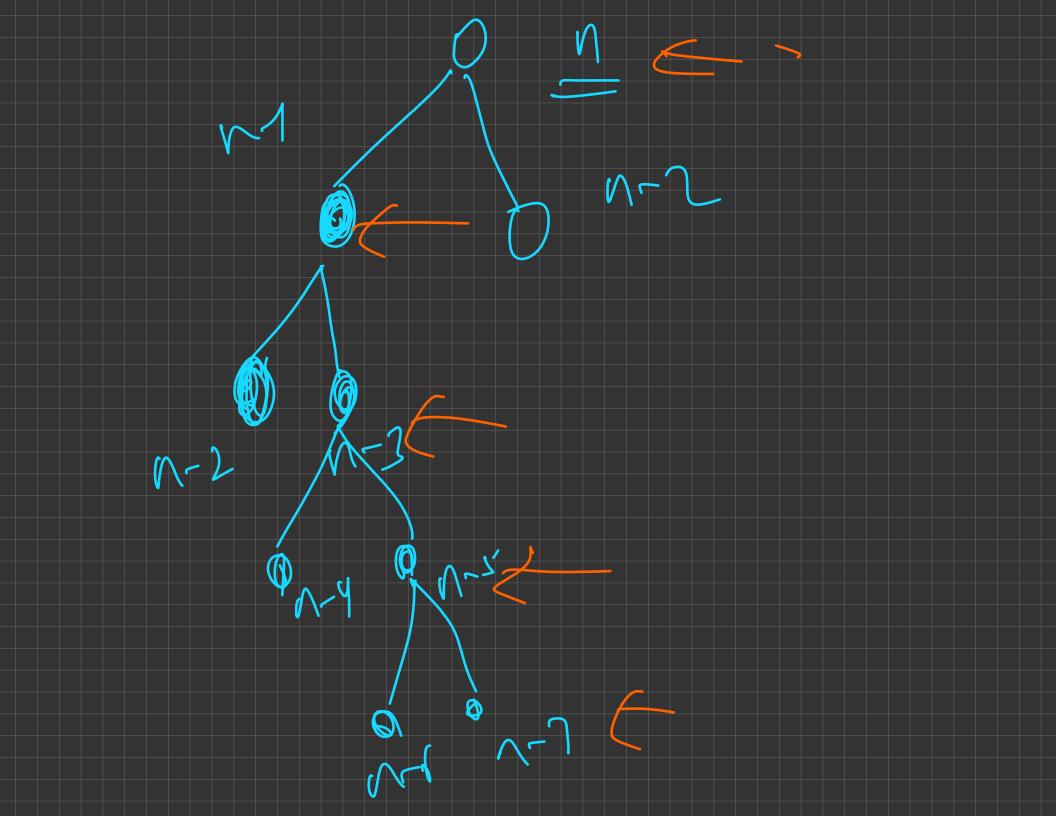
- What other state does our current state depend on?
- Do we need answers to all subproblems at all times?
- Well, let's store only relevant states then!
- But wait, does this always work?
 - What if the final subproblem requires all the states?
 - What if we need to backtrack? [more on this in later lectures]

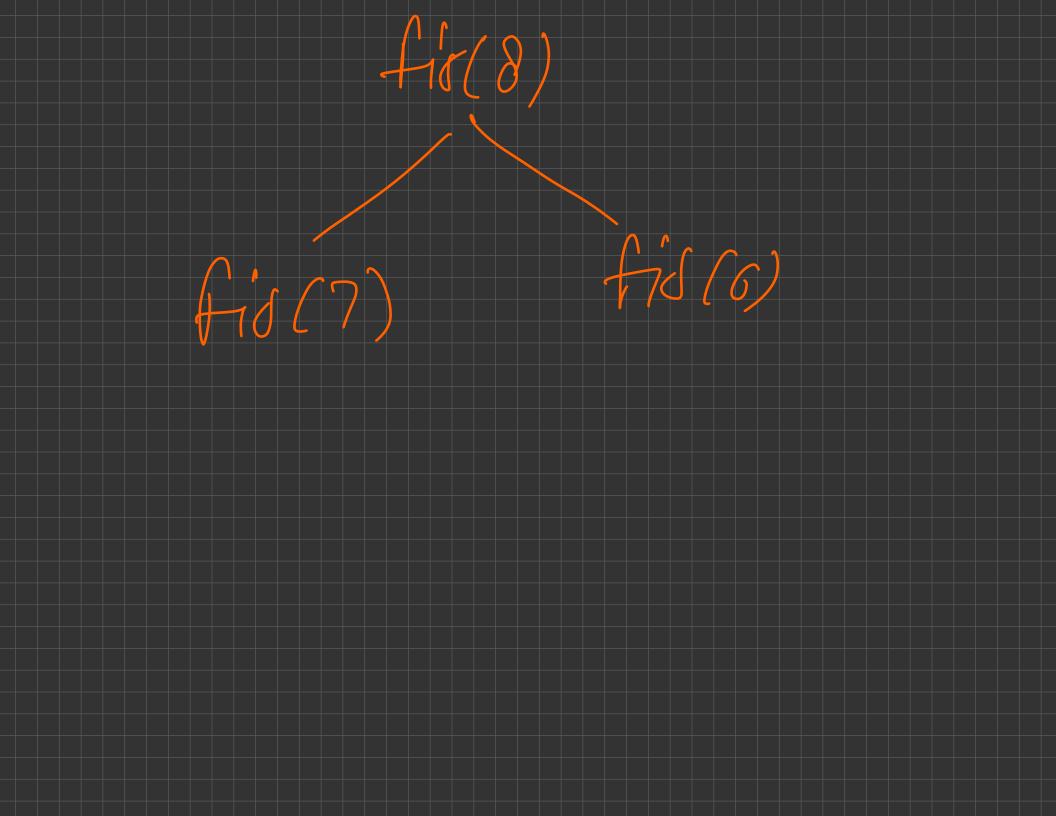
fis(n) = fis(n-1) + fis(n-2)Pi8 (n-3)

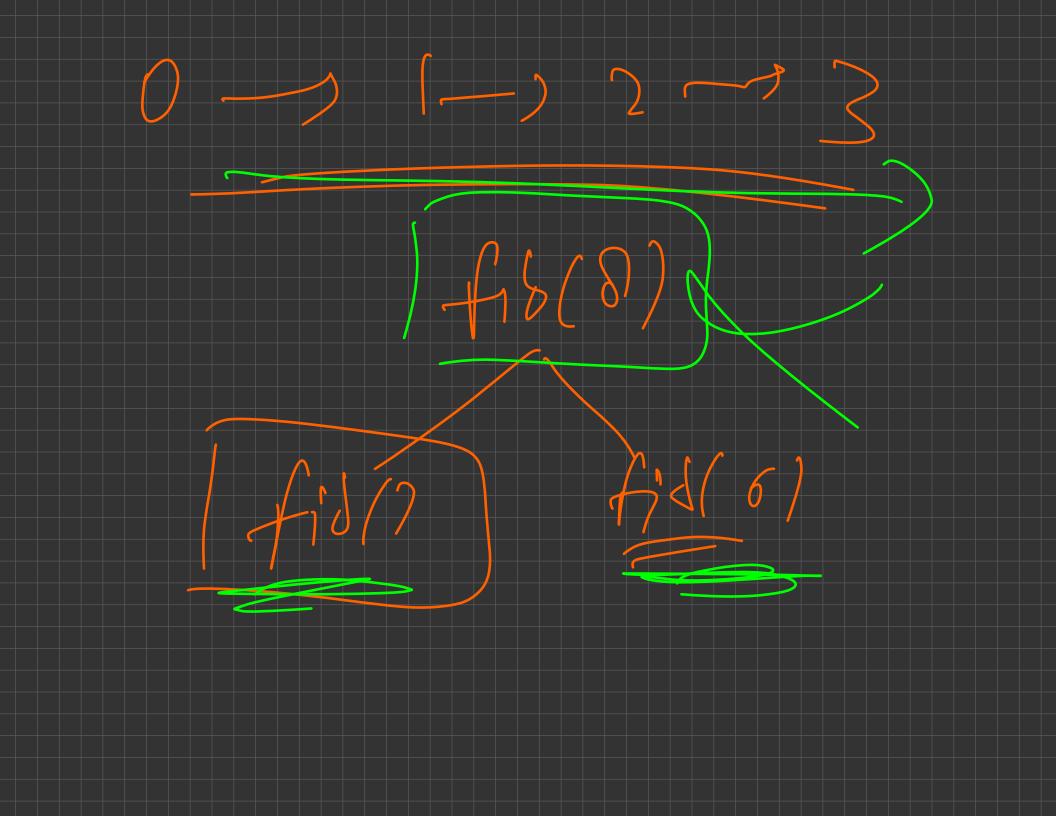


Him 0 (10) 3044 (n) state & 0(1) TrT 0 2 10 2 o(n) T-T S(n) Ctark









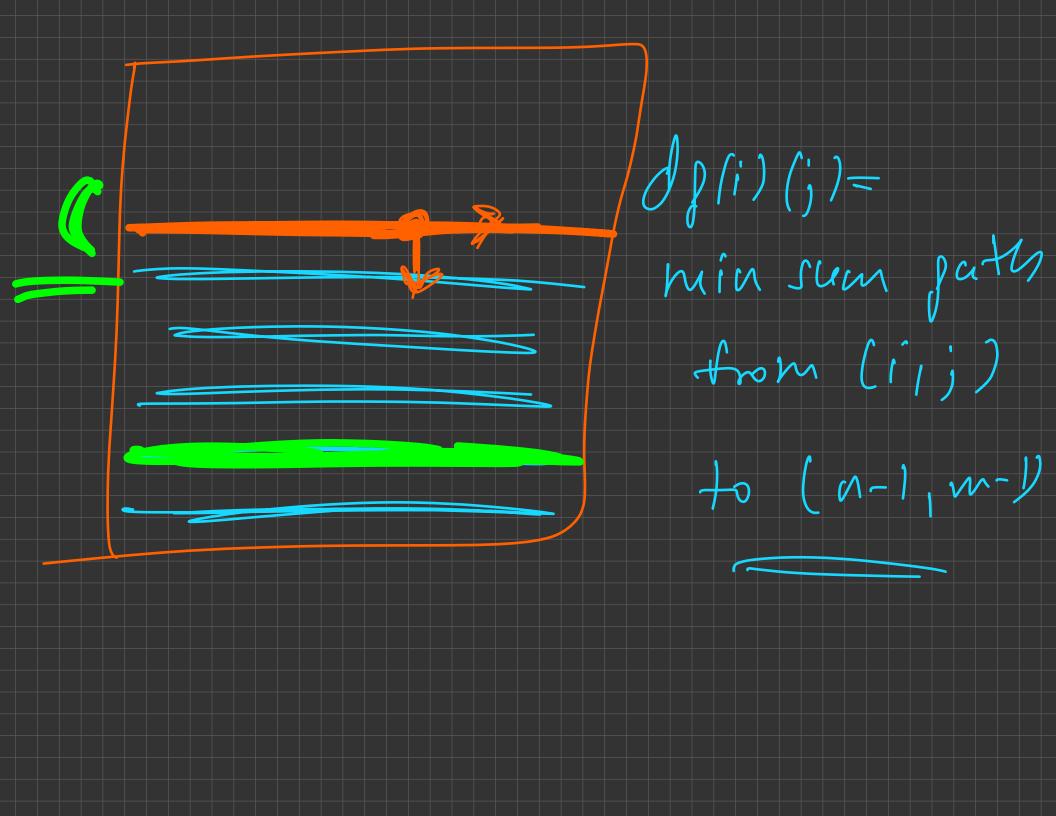
$$a = 1 \rightarrow fi(1)$$

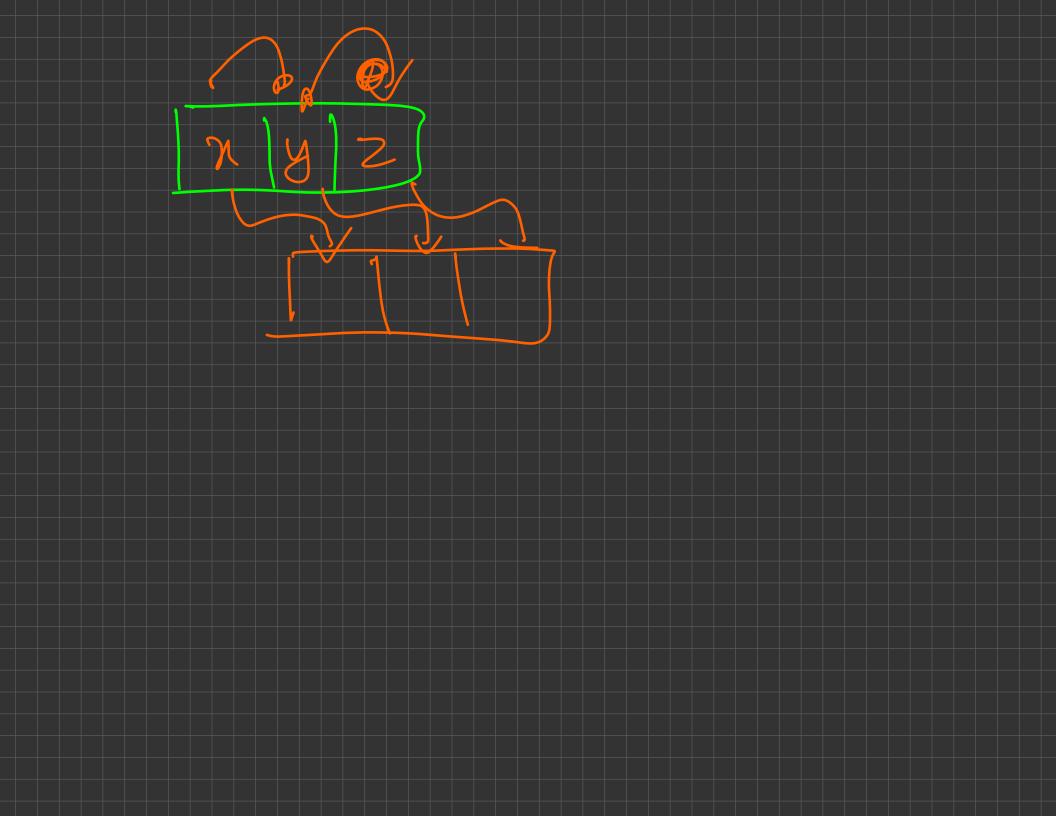
$$S = (-) \quad fi(1)$$

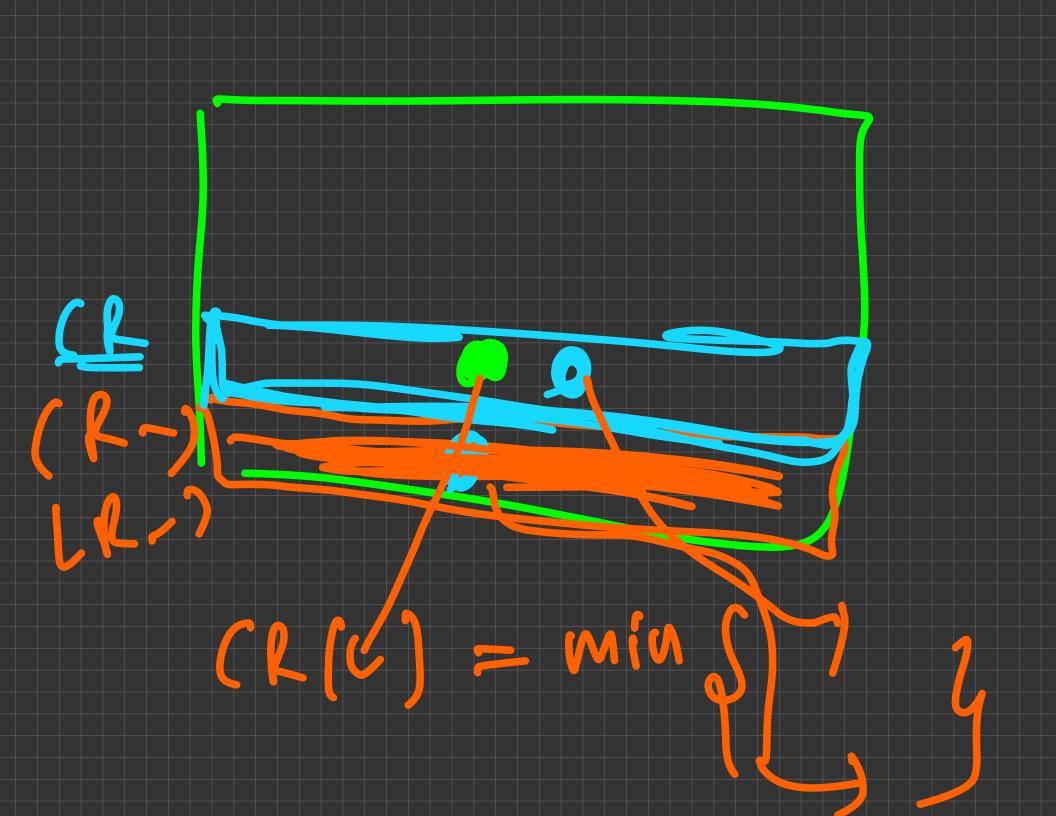
$$C = ? \rightarrow fi(1)$$

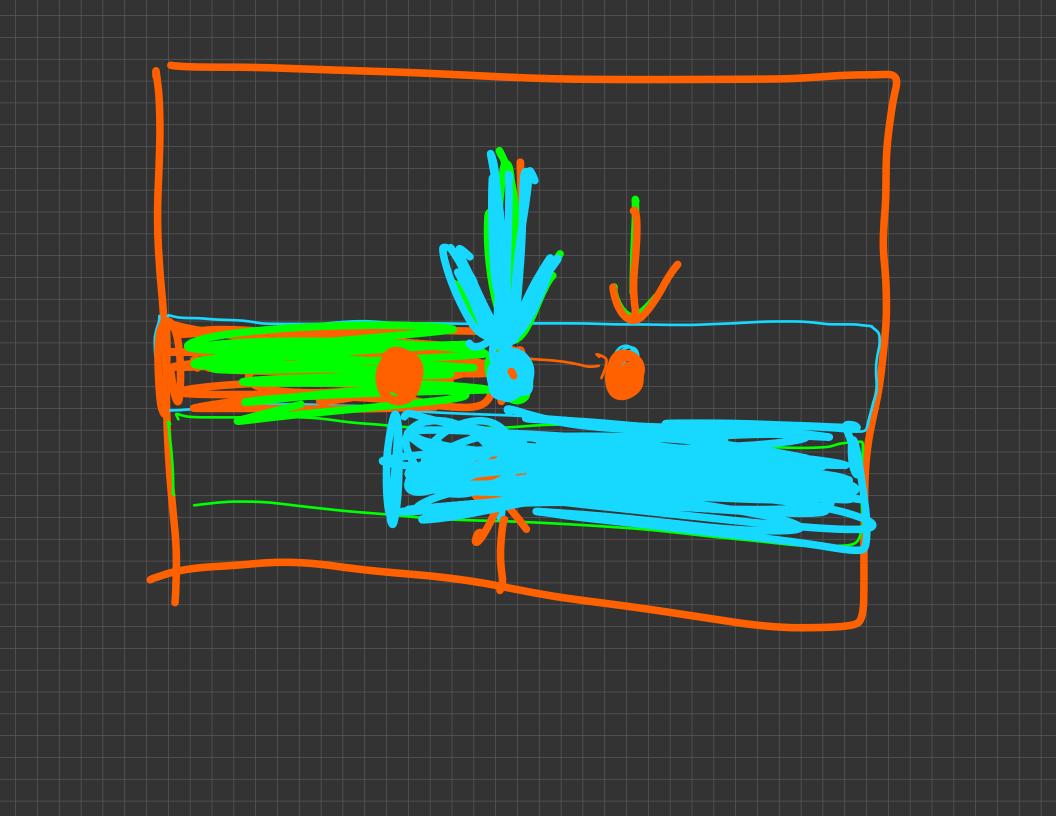
$$C = fi(1)$$

$$C$$









- Fibonacci Problem
 - dp[i] depends on dp[i 1], dp[i 2]
- Grid Problem
 - dp[i][j] depends on dp[i + 1][j], dp[i][j + 1]

State Optimization

- Ask yourself do you need all the parameters in the dp state?
- If you have dp[a][b][c], and a + b = c, do you need to store c as a parameter or can you just compute it on spot?
- If you can compute a parameter in dp state from other parameters,
 no need to store it.
- Which parameters should you remove? Highest

Transition Optimization

- Observe the transition equation.
- Can you do some pre-computation to evaluate the equation faster?
- Using clever observations.
- Using range query data structures