# **Shaheer Rana**

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Mechatronics Engineering | University of Waterloo

# **SKILLS**

**Software:** C, C<sub>++</sub>, CUDA, DMA, Python, Assembly, OpenCV, Bash, Docker **Embedded**: ARM Cortex-M/A, CAN, SPI, I<sup>2</sup>C, PCIe, Ethernet, TCP/IP, UDP **Hardware:** Signal Processing, Power Electronics, Motor Control, Digital Logic

OS: Kernel, Linux, RTOS, ROS 2
Debug: OpenOCD/GDB, Valgrind
PCB: Altium Designer, PSIM

# **EXPERIENCE**

# **Embedded Intern** | Collaborative Robotics (co.bot)

Santa Clara, CA | Sep 2023 - Present

- Assisting Cobot ship their initial product as the first embedded hire
- Writing cross-compiled Linux device drivers (ioctl, hwmon, net), and ROS 2 nodes in C, C++
- Created a Docker build system and wrote Bash scripts for low-level kernel customization
- Programming a custom power distribution board with BMS and hot-swap circuits
- Designing a high-speed 10GbE carrier board for NVIDIA SoC and a motor control sensing PCB

### **Software Algorithms Intern** | Institute for Quantum Computing

Waterloo, ON | Sep 2022 – Dec 2022

- Built a low-latency, multi-threaded control system for a <u>quantum simulator</u>
- Parallelized the <u>memory block transfers</u> in C++ and wrote CUDA accelerated waveform generation algorithms, reducing execution time by 63.6%
- Created real-time atom detection and relocation Python library using OpenCV and OpenMP

## **DSP Firmware Intern** | Dragonfly Systems

Ottawa, ON | Jan 2022 – Apr 2022

- Independently built an end-to-end real-time data pipeline to prototype a new ultra-low-power IoT product
- Programmed filters in bare-metal C on EFR32 to amplify and de-noise audio
- Optimized DMA buffer handling, ADC sampling, and transmission frequency
- Validated audio quality using logic analyzers, oscilloscopes, and Python PyQT

#### **Robotics Intern** | VN Instruments (NASA Project)

Brockville, ON | May 2021 – Aug 2021

- Owned a multi-axis linear actuator testing acoustic sensors for Mars
- Wrote control algorithms in C on TI-RTOS Kernel, reduced interrupt handling time by 35%
- Built a telematics control unit and data logger for 8 motors over Python sockets
- Programmed and designed demultiplexing relay driver PCB

# **PROJECTS**

## **Technical Director | Waterloop**

Sep 2020 – Dec 2022

- Led 100 members competing in and organizing North America's only active Hyperloop competition, authored the <u>rulebook</u>
- Established an Agile firmware team developing custom motor controller, BMS, and CAN library
- Altium schematic capture and layout of a 4-layer 3-phase DC/AC motor controller powering a 48V linear induction motor, simulated in PSIM
- Programmed fault-tolerant <u>STM32 motor controller</u> in **C** with 15 sensors and SVPWM

#### **Hack the North**

scaNFT (2021 Winner) Automatic 3D NFT scanner, secure minting and Ethereum transactions

<u>instAd</u> (2022) Al ad generator using multi-step stable diffusion Al and NLP

#### **Other Competitions**

Ontario Engineering Competition (2023 Winner)

ActInSpace Canada (2022 Winner)

Built and programmed an autonomous mobile robot

Machine learning for urban development

# **EDUCATION**