# **Shaheer Rana**

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Mechatronics Engineering | University of Waterloo

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**SKILLS** 

**Software:** C, C<sub>++</sub>, CUDA, DMA, OpenMP, Python, Assembly, OpenCV, GCC **Embedded**: ARM Cortex-M/A, CAN, SPI, I<sup>2</sup>C, PCIe, Ethernet, TCP/IP, UDP **Hardware:** Signal Processing, Power Electronics, Motor Control, Digital Logic

OS: RTOS, Linux, ROS2, Kernel, Debug: OpenOCD/GDB, Valgrind PCB: Altium Designer, PSIM

#### **EXPERIENCE**

#### **Embedded Intern** | Collaborative Robotics (co.bot)

Santa Clara, CA | Sep 2023 – Present

- Assisting Cobot ship their initial product as their first dedicated embedded hire
- Writing cross-compiled device drivers, OS images, and ROS2 nodes in C, C++ for NVIDIA Jetson
- Programming a custom power distribution board interfacing with ADC, battery management, and hot-swap circuits through SPI, I<sup>2</sup>C, and CANFD
- Designing a high-speed carrier board for NVIDIA SoC supporting 10GbE over PCIe and a motor control sensing and interface PCB using Altium

**Software Algorithms Intern** | Institute for Quantum Computing

Waterloo, ON | Sep 2022 – Dec 2022

- Built a low-latency, multi-threaded control system for a <u>quantum simulator</u> with C++
- Parallelized the <u>memory block transfers</u> and wrote CUDA accelerated waveform generation algorithms, reducing execution time by 63.6%
- Created real-time atom detection and spatial configuration library using Python, OpenCV, OpenMP

#### **DSP Firmware Intern** | Dragonfly Systems

Ottawa, ON | Jan 2022 - Apr 2022

- Independently launched development of an ultra-low-power IoT node for audio signal processing
- Programmed EFR32 in **bare-metal C** to amplify and de-noise signals through 2<sup>nd</sup>-order filters
- Built an end-to-end **real-time data pipeline** by optimizing **DMA** buffer handling, 12-bit ADC sampling, and transmission frequency
- Validated signal integrity using logic analyzers, oscilloscopes, and graphically using PyQt and Python

#### **Robotics Intern** | VN Instruments (NASA Project)

Brockville, ON | May 2021 - Aug 2021

- Owned the development of a multi-axis linear actuator testing acoustic sensors for Mars
- Wrote PWM control algorithms in C on TI-RTOS Kernel, reduced interrupt handling time by 35%
- Built a telematics control unit and data logger for 8 motors using Python sockets
- Programmed and designed demultiplexing relay driver PCB for 4-speed motor control using Altium

### **PROJECTS**

# **Project Manager** | Waterloop

Sep 2020 – Dec 2022

- Making a faster world by leading 100 members building Canada's Hyperloop
- Established a firmware team developing code for custom motor controller, battery management system, and CAN Library
- Altium schematic capture and layout of a 4-layer 3-phase DC/AC motor controller powering a 48V\_linear induction motor, ripple and parasitic effects minimized with PSIM circuit simulations
- Programmed fault-tolerant <u>STM32 motor controller</u> in C with 15 sensors, SVPWM, and SPI
- Organized North America's only current Hyperloop competition, primary author of rulebook

# **Hack the North**

scaNFT (2021 Winner) A 3D-scanner that automates the process of minting NFTs

Secure Ethereum wallet and NFT authentication pipeline in JavaScript

instAd (2022) Al ad generator using multi-step stable diffusion Al and NLP in JavaScript

#### **Other Competitions**

Ontario Engineering Competition (2023 Winner)

ActInSpace Canada (2022 Winner)

Designed and built an autonomous robot in C++

Machine learning for urban development

### **EDUCATION**