# Numpy

Lingua franca for data exchange

Muhammad Shahid Arshad

# Numpy

- Numerical Python
- Developed in 2005 by Travis Oliphant
- Lingua franca for data exchange
- ndarray a n-dimensional array
- Fast operations on entire arrays
- Reading/writing array data
- Linear algebra operations



**Travis Oliphant** 

### Vectorized operations

#### not vectorized

a

b



6

\* 7



8

9

\*

10

5 operations

#### vectorized

a

b

1

6

2

\*

\*

4

3

8

9

5 \*

10

2 operations

#### Installation

- Prepackaged with Anaconda
- Using pip
  - pip install numpy

C:1.

C:\Windows\system32\cmd.exe

```
Microsoft Windows [Version 6.3.9600]
(c) 2013 Microsoft Corporation. All rights reserved.
```

C:\Users\Noman>pip install numpy

# Numpy Vs Python list

```
In [7]: import numpy as np
In [8]: my arr = np.arange(1000000)
In [9]: my list = list(range(1000000))
In [10]: %time for _ in range(10): my_arr2 = my_arr * 2
CPU times: user 20 ms, sys: 50 ms, total: 70 ms
Wall time: 72.4 ms
In [11]: %time for _ in range(10): my_list2 = [x * 2 for x in my_list]
CPU times: user 760 ms, sys: 290 ms, total: 1.05 s
Wall time: 1.05 s
```

#### nd-array

- A fast, flexible container for large datasets in Python
- Homogeneous data i.e. all of the elements must be the same type

## Creating ndarray

- np.array(): convert input data to an ndarray
- np.zeros(): produces arrays of 0s
- np.ones(): produces arrays of 1s
- np.empty(): create new arrays by allocating new memory, but do not populate with any values
- np.arange(): like the built-in range but returns an ndarray instead of a list

#### Examples

#### Summary of array creation functions

Table 4-1. Array creation functions

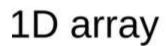
Function	Description	
аггау	Convert input data (list, tuple, array, or other sequence type) to an ndarray either by inferring a dtype or explicitly specifying a dtype; copies the input data by default	
asarray	Convert input to ndarray, but do not copy if the input is already an ndarray	
arange	Like the built-in range but returns an ndarray instead of a list	
ones, ones_like	Produce an array of all 1s with the given shape and dtype; ones_like takes another array and produces a ones array of the same shape and dtype	
zeros, zeros_like	Like ones and ones_like but producing arrays of 0s instead	
empty, empty_like	Create new arrays by allocating new memory, but do not populate with any values like ones and zeros	
full,	Produce an array of the given shape and dtype with all values set to the indicated "fill value"	
full_like	full_like takes another array and produces a filled array of the same shape and dtype	
eye, identity	Create a square $N \times N$ identity matrix (1s on the diagonal and 0s elsewhere)	

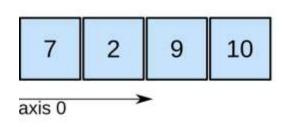
### Attributes of numpy array

- shape: a tuple indicating the size of each dimension
- dtype: an object describing the data type of the array
- ndim: the number of dimensions of the array

#### shape attribute

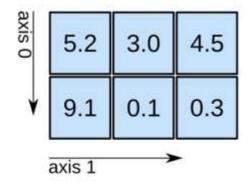
#### 3D array



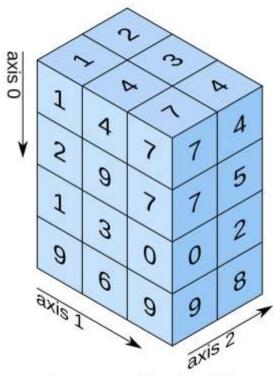


shape: (4,)

2D array



shape: (2, 3)



shape: (4, 3, 2)

# Numpy data types

Туре	Type code	Description
int8, uint8	i1, u1	Signed and unsigned 8-bit (1 byte) integer types
int16, uint16	i2, u2	Signed and unsigned 16-bit integer types
int32, uint32	i4, u4	Signed and unsigned 32-bit integer types
int64, uint64	i8, u8	Signed and unsigned 64-bit integer types
float16	f2	Half-precision floating point
float32	f4 or f	Standard single-precision floating point; compatible with C float
float64	f8 or d	Standard double-precision floating point; compatible with C double and Python float object
float128	f16 or g	Extended-precision floating point
complex64, complex128, complex256	c8, c16, c32	Complex numbers represented by two 32, 64, or 128 floats, respectively
bool	?	Boolean type storing True and False values
object	0	Python object type; a value can be any Python object
string_	S	Fixed-length ASCII string type (1 byte per character); for example, to create a string dtype with length 10, use 'S10'
unicode_	U	Fixed-length Unicode type (number of bytes platform specific); same specification semantics as string_(e.g., 'U10')

#### Vectorization

- Express batch operations on data without writing any for loops
- Any arithmetic operations between equal-size arrays applies the operation element-wise
- Arithmetic operations with scalars propagate the scalar argument to each element in the array
- Comparisons between arrays of the same size yield boolean arrays
- Operations between differently sized arrays is called broadcasting

#### Operations on two matrices

```
In [51]: arr = np.array([[1., 2., 3.], [4., 5., 6.]])
In [52]: arr
Out[52]:
array([[ 1., 2., 3.],
      [4., 5., 6.]
In [53]: arr * arr
Out[53]:
array([[ 1., 4., 9.],
      [ 16., 25., 36.]])
In [54]: arr - arr
Out[54]:
array([[ 0., 0., 0.],
      [0., 0., 0.]
```

#### Operations between matrix and scalar

#### Comparison between matrices

# Array indexing

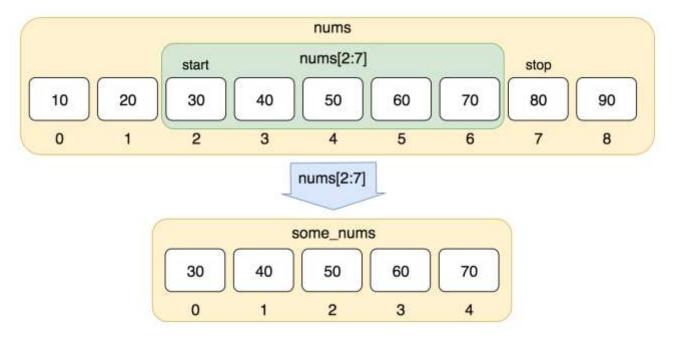
```
In [2]: x=np.array([1,7,9,8,5])
In [3]: x[4]
Out[3]: 5
```

# Fancy indexing

```
In [120]: arr[[4, 3, 0, 6]]
```

# Slicing

- Array slices are views on the original array
- Format
  - start: end: step



# Element-wise array functions

Function	Description		
abs, fabs	Compute the absolute value element-wise for integer, floating-point, or complex values		
sqrt	Compute the square root of each element (equivalent to arr ** 0.5)		
square	Compute the square of each element (equivalent to arr ** 2)		
exp	Compute the exponent ex of each element		
log, log10, log2, log1p	Natural logarithm (base $e$ ), log base 10, log base 2, and log(1 + x), respectively		
sign	Compute the sign of each element: 1 (positive), 0 (zero), or $-1$ (negative)		
ceil	Compute the ceiling of each element (i.e., the smallest integer greater than or equal to that number)		
floor	Compute the floor of each element (i.e., the largest integer less than or equal to each element)		
rint	Round elements to the nearest integer, preserving the dtype		
modf	Return fractional and integral parts of array as a separate array		
isnan	Return boolean array indicating whether each value is NaN (Not a Number)		
isfinite, isinf	Return boolean array indicating whether each element is finite (non-inf, non-NaN) or infinite respectively		
cos, cosh, sin, sinh, tanh	Regular and hyperbolic trigonometric functions		
arccos, arccosh, arcsin, arcsinh, arctan, arctanh	Inverse trigonometric functions		
logical not	Compute truth value of not x element-wise (equivalent to ~arr).		

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### np.where()

```
np.where (condition, option A, option B)

The condition

What to do with entries for which the condition is true

What to do with entries for which the condition is false
```

```
In [3]: salary=np.array([0,-1,100000,50000])
In [4]: np.where(salary<=0,25000,salary)
Out[4]: array([ 25000, 25000, 100000, 50000])</pre>
```

#### Transpose of a matrix

```
In [128]: arr.T
Out[128]:
array([[ 0, 5, 10],
       [ 1, 6, 11],
       [2, 7, 12],
       [3, 8, 13],
       [4, 9, 14]])
In [134]: arr.transpose((1, 0, 2))
Out[134]:
array([[[ 0, 1, 2, 3],
       [8, 9, 10, 11]],
      [[4, 5, 6, 7],
       [12, 13, 14, 15]]])
```

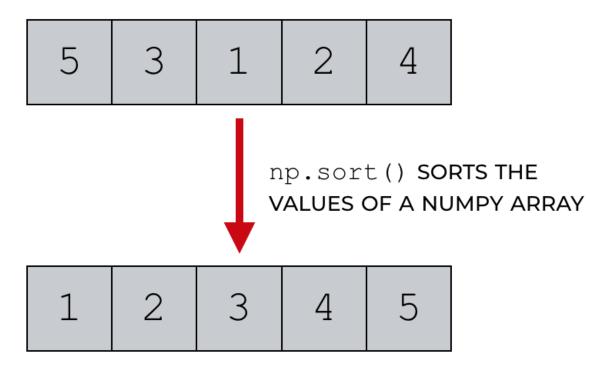
#### Mathematical and Statistical Methods

- mean(): returns the mean value computed over the array
- <u>cumsum()</u>: returns the cumulative sum of array elements
- <u>cumprod()</u>: returns the cumulative product of array elements

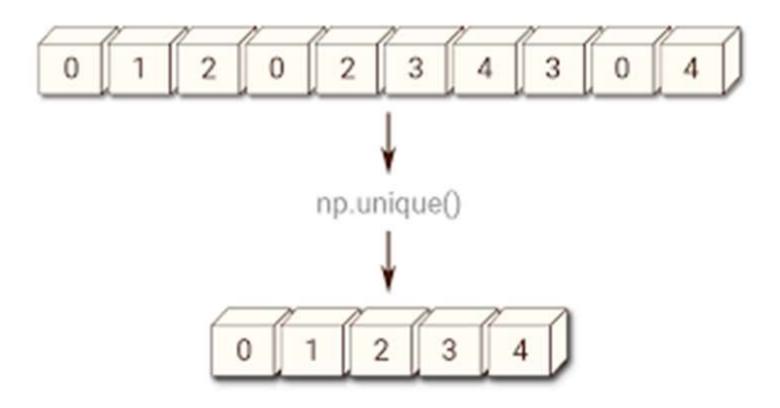
#### Methods for boolean arrays

- sum(): counting True values in a boolean array
- <u>any():</u> tests whether one or more values in an array is True
- <u>all()</u>: checks if every value is True

# Sorting



# Unique



### File Input Output

- np.save(filename.npy, array)
- np.load(filename.npy)
- np.savez(filename.npz,array1,array2)
- When loading an .npz file, you get back a dict-like object

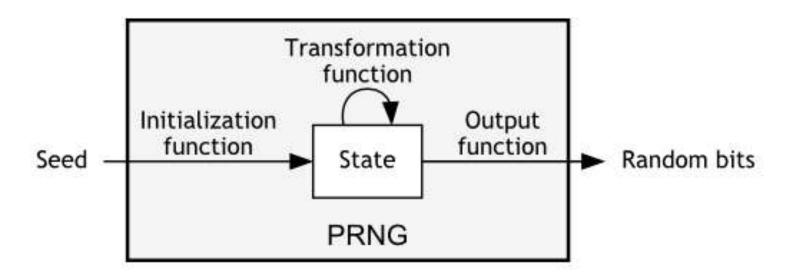
# Linear algebra functions

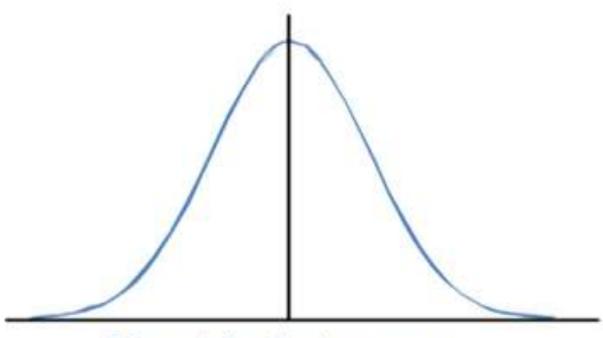
Function	Description	
diag	Return the diagonal (or off-diagonal) elements of a square matrix as a 1D array, or convert a 1D array into a square matrix with zeros on the off-diagonal	
dot	Matrix multiplication	
trace	Compute the sum of the diagonal elements	
det	Compute the matrix determinant	
eig	Compute the eigenvalues and eigenvectors of a square matrix	
inv	Compute the inverse of a square matrix	
pinv	Compute the Moore-Penrose pseudo-inverse of a matrix	
qr	Compute the QR decomposition	
svd	Compute the singular value decomposition (SVD)	
solve	Solve the linear system $Ax = b$ for x, where A is a square matrix	
lstsq	Compute the least-squares solution to $Ax = b$	

#### Pseudo-random number generation

- normal()
- seed()
- gamma()
- uniform()

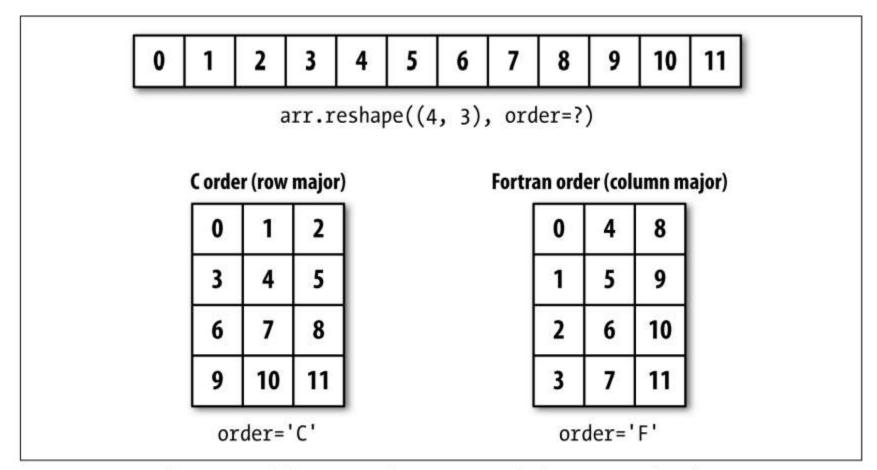
#### Pseudo random number generator





Normal distribution curve.

### Reshape



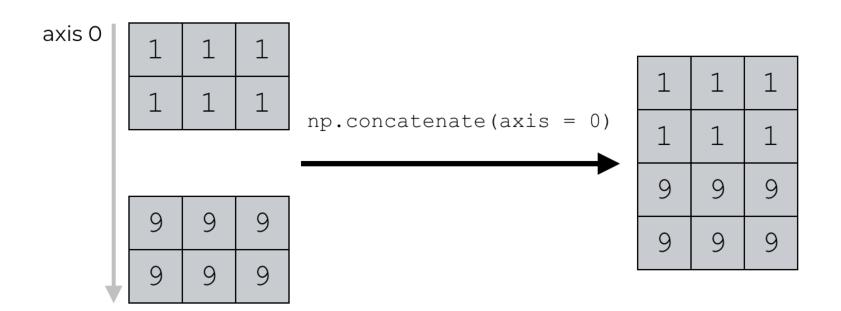
Reshaping in C (row major) or Fortran (column major) order

# Converting to 1D array

- flatten()
- ravel()

#### concatenate

Setting axis=0 concatenates along the row axis



#### Convenience functions

- vstack: stack arrays row-wise (along axis 0)
- hstack: stack arrays column-wise (along axis 1)

## Stacking helpers

- np.r\_[arr1, arr2]
- np.c\_[np.r\_[arr1, arr2], arr]

# Splitting an array

