## Project for undergraduate students registered in ELEC 444

Implement a line-finder using RANSAC. Submit one file called RansacLine.m (do not submit or modify Demo2.m). Call this function:

lines = RansacLine(edgeImageIn, noIter, fitDistance, noPts, minD)

lines is an n by 3 matrix parameterizing lines in the plane

edgeImageIn is a binary edge image

noIter is the number of iterations that you have to pick 2 points at random

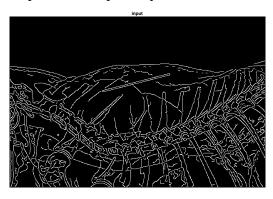
fitDistance is the maximum distance a pixel may lie from a line

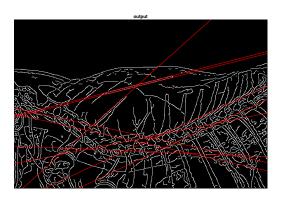
noPts is the minimum number of points that should vote for a line. Note that this is different from the implementation discussed in class where we pick the line with max votes. Here, we pick lines that have votes greater than noPts

minD is the minimum distance between the 2 randomly selected points. This improves RANSAC's performance because if the 2 original points are close, the line fitted can have inaccurate slope.

Hint hints for your RansacLine function: Use the matlab function "find" to get the coordinates of all of the pixel locations corresponding to an edge.

The input and output to your file are below.





And the following output is printed after running the code:

```
line #1: 0.0043569X + -0.00098433Y = 1
line #2: 0.0032443X + -0.00013411Y = 1
line #3: 0.0023285X + 0.0020893Y = 1
line #4: 0.0022508X + 0.0010309Y = 1
line #5: 0.0028469X + 0.0005698Y = 1
line #6: 0.0046447X + -0.001006Y = 1
line #7: 0.0020629X + 0.00097296Y = 1
line #8: 0.0041957X + 0.001061Y = 1
line #9: 0.0042487X + 0.001086Y = 1
```

Note that the number of lines can be different if you run the code again. For example, if we run the same code without changing anything, we might get 6 lines.

To make sure your code is correct, you can test your code with other images, such as:

```
inIM = imread('circuit.tif');
inIM = imread('gantrycrane.png');
```