

Introduction to Trees

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Introduction to Trees

- Why Trees ? The limitation of Linear Data Structures
- Scenario 1 : Searching in a database
 - You have 1 million records in an array
 - Linear search: $O(n)$ - potentially 1 million comparisons
 - Even with binary search: $O(\log n)$ - but insertion/deletion is $O(n)$
- Scenario 2 : Organizing a File System
 - How to represent folders and subfolders in an array or linked list ?
 - How do you efficiently represent hierarchy ?
 - How do you navigate parent-child relationships ?

Why Trees ?

- Scenario 3 : Auto-complete in Search Engines
 - As you type "prog", it suggests "program", "programming", "progress"
 - Linear structures would require scanning all words
 - Need something that can branch based on prefixes

The Problem & the Solution

Linear data structures (arrays, linked lists, stacks, queues) are excellent for sequential access but struggle with:

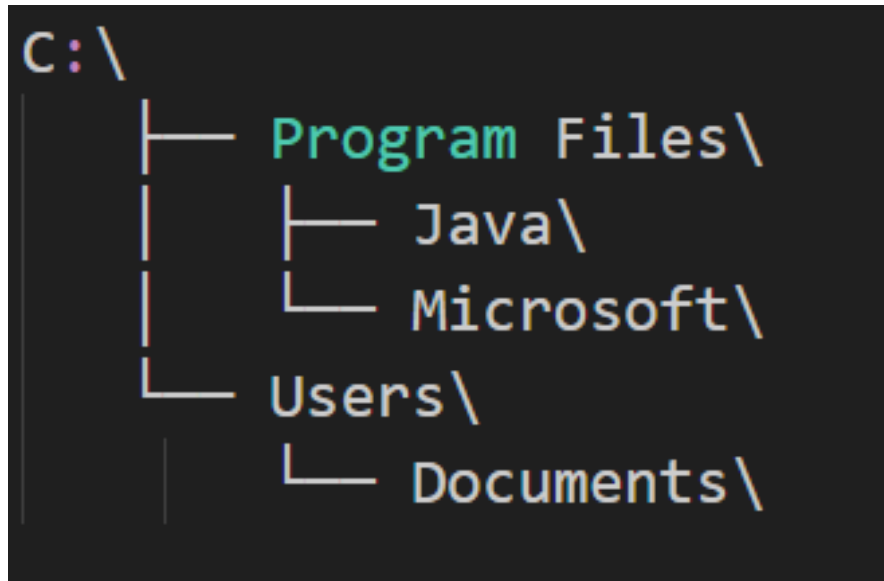
- Hierarchical relationships
- Efficient searching with dynamic data
- Representing multi-way branching
- Balancing speed of insertion and search

The Solution: Trees - a non-linear, hierarchical data structure.

Trees : Real World Analogies

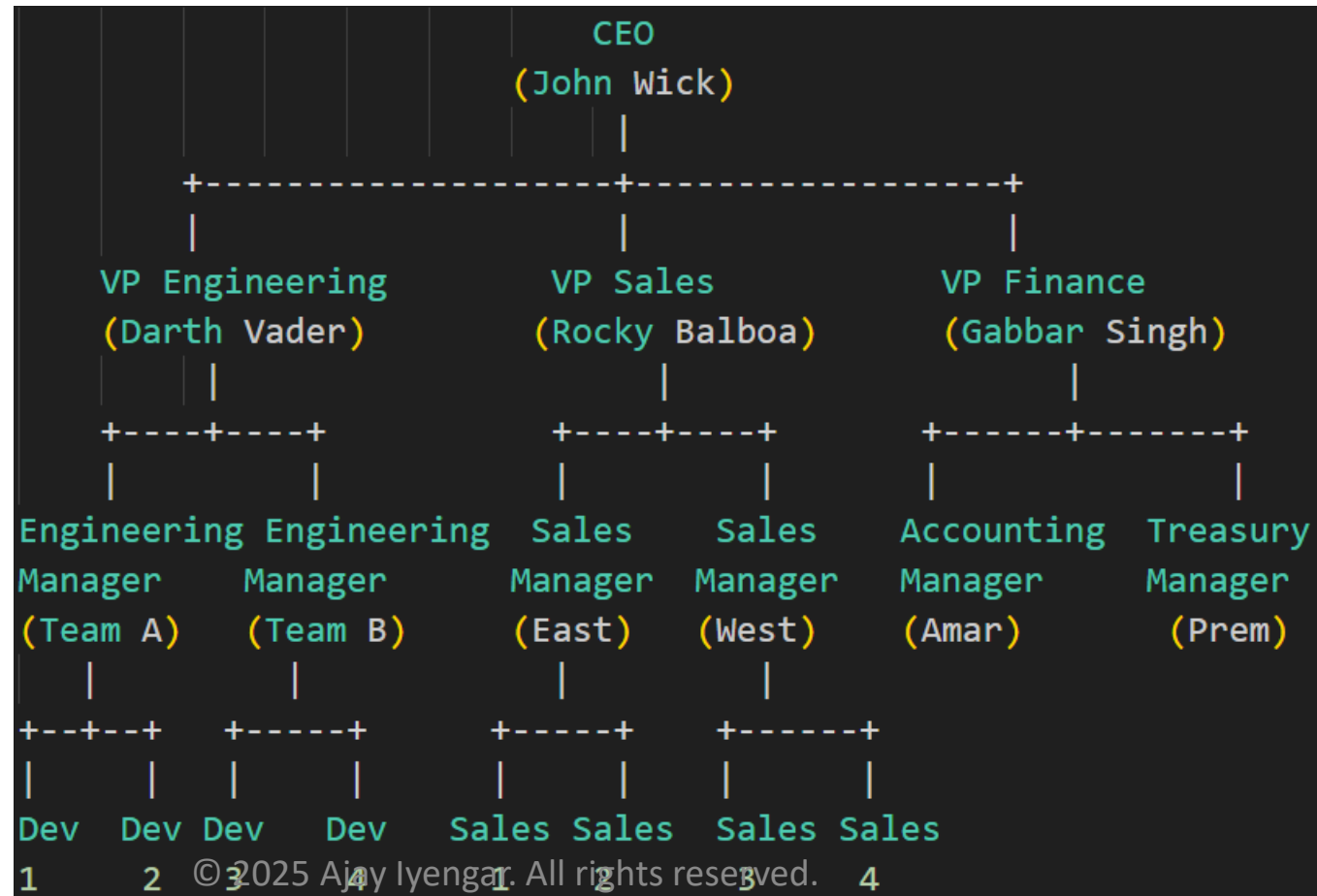
Trees are everywhere in computing and real life –

1. File System : Computer's folder structure



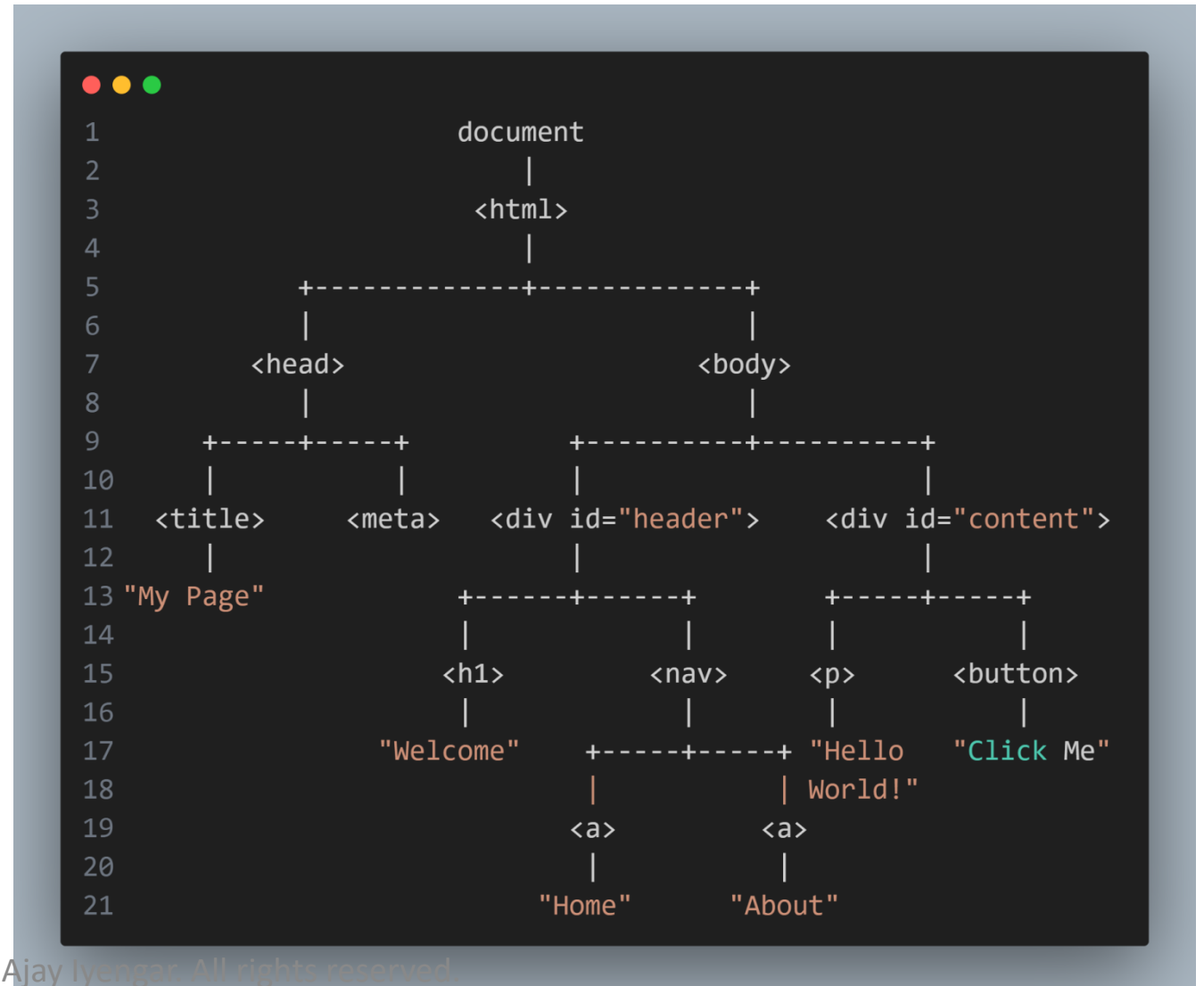
Trees : Real World Analogies

Organizational Hierarchy : Company Structures(CEO - VP's – Managers - Developers)



Trees : Real World Analogies

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<!DOCTYPE html>
<html>
  <head>
    <title>My Page</title>
    <meta charset="UTF-8">
  </head>
  <body>
    <div id="header">
      <h1>Welcome</h1>
      <nav>
        <a href="/">Home</a>
        <a href="/about">About</a>
      </nav>
    </div>
    <div id="content">
      <p>Hello World!</p>
      <button>Click Me</button>
    </div>
  </body>
</html>
```



Dom as a Tree

Trees : Real World Analogies

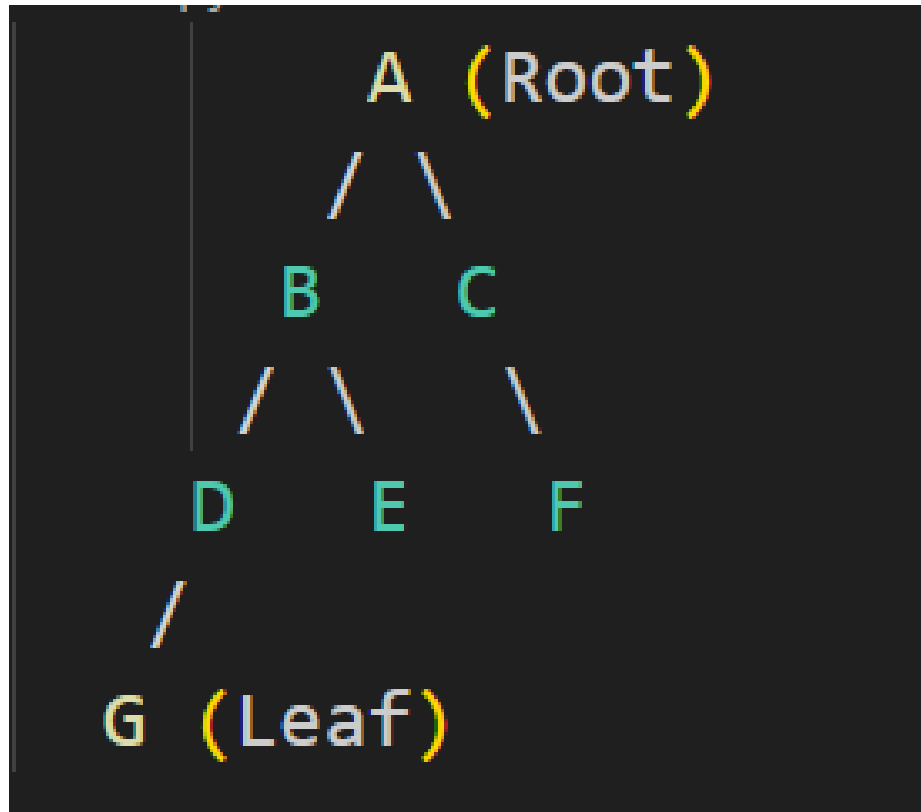
Decision Tree – AI/ML, Game Theory

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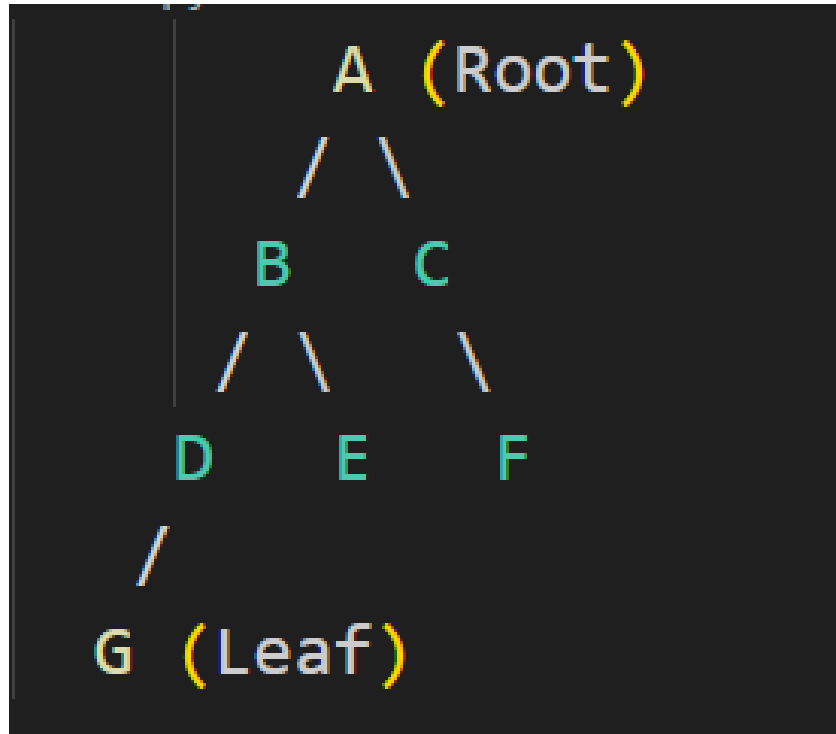
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Basic Tree Terminology



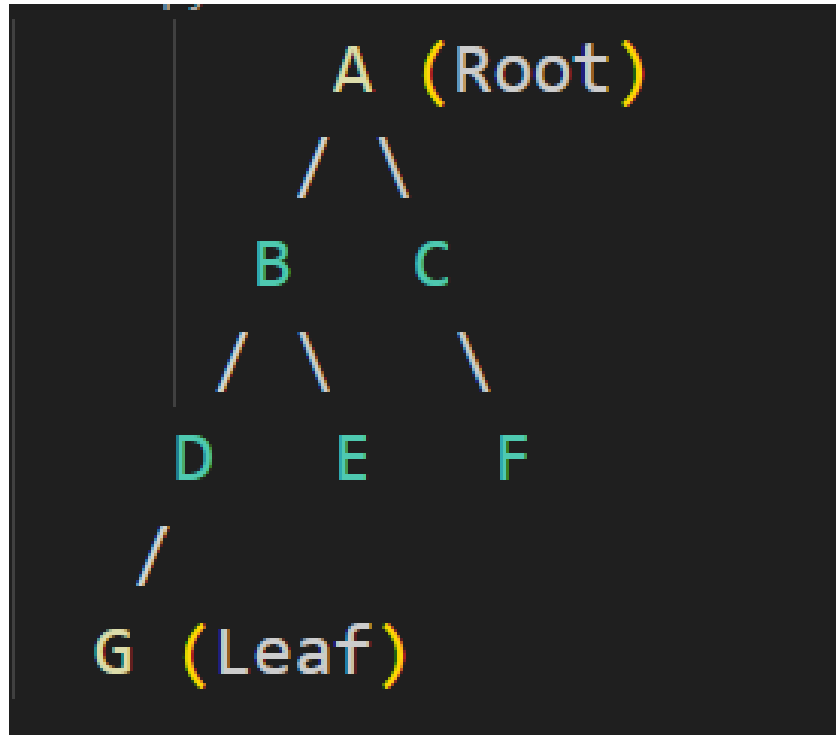
- **Node:** Each element in the tree (A, B, C, D, E, F, G)
- **Root:** The topmost node with no parent (A)
- **Parent:** Node that has children (A is parent of B and C)
- **Child:** Node that has a parent (B and C are children of A)

Basic Tree Terminology



- **Siblings:** Nodes with the same parent (B and C are siblings)
- **Leaf/External Node:** Node with no children (E, F, G)
- **Edge:** Connection between two nodes (there are 6 edges above)

Basic Tree : Measurement terms

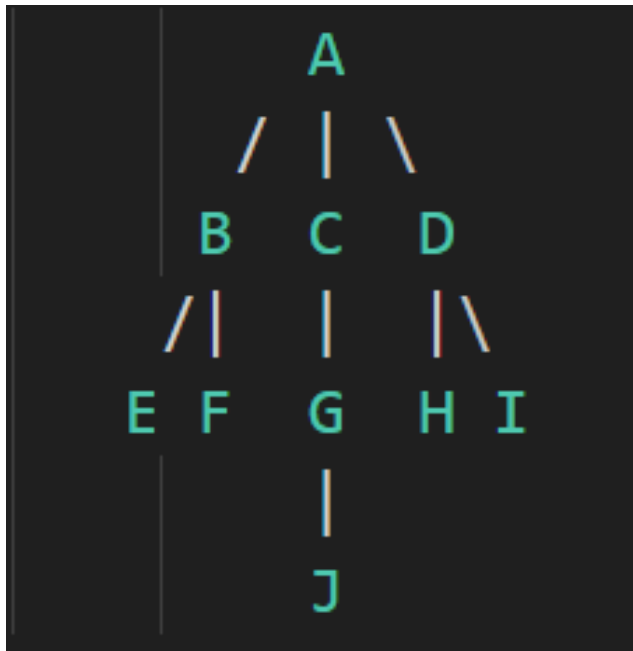


- **Depth of a Node:** Number of edges from root to that node
 - Depth of A = 0
 - Depth of B = 1
 - Depth of G = 3
- **Height of a Node:** Number of edges on longest path from that node to a leaf
 - Height of G = 0 (leaf)
 - Height of D = 1
 - Height of B = 2
 - Height of A = 3

Height of Tree: Height of the root node
(3 in above example)

Types of Trees : General Tree(N-ary Tree)

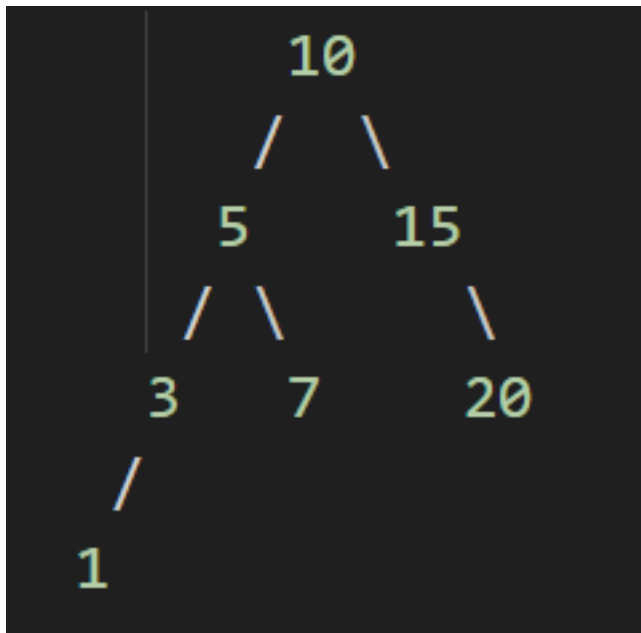
- A tree where each node can have any number of children (0 to N).



- **Properties:**
 - No restriction on number of children
 - Most flexible tree structure
 - Used in file systems, organizational charts
- **Use Case:** File system directories where a folder can contain any number of subfolders and files.

Binary Trees

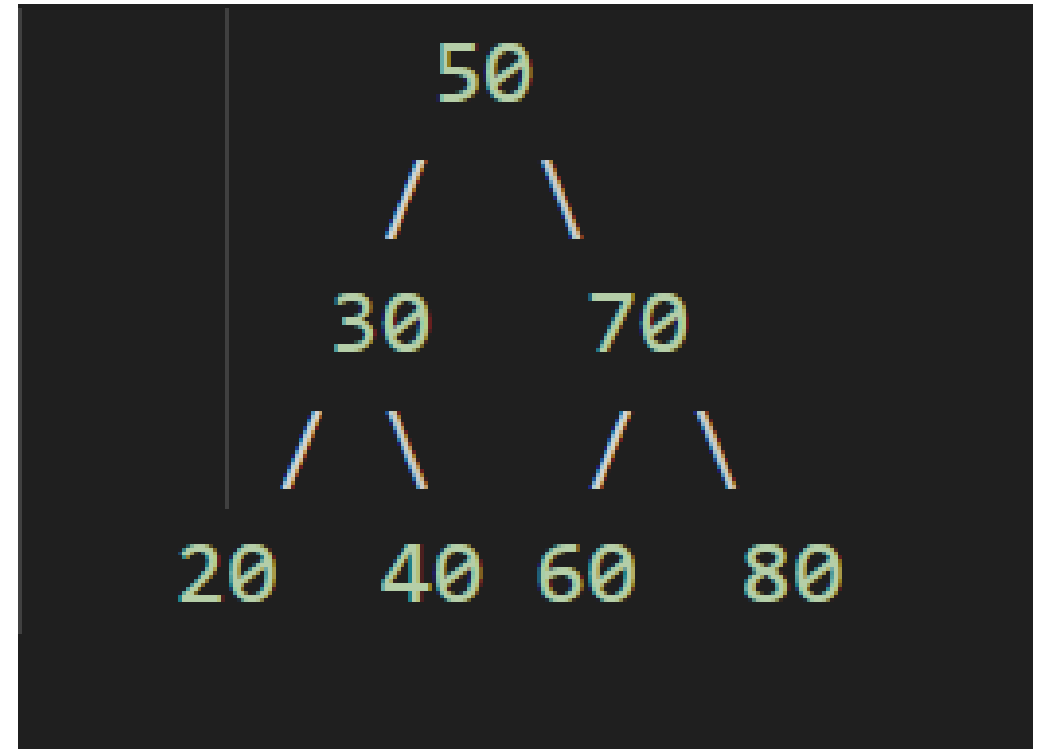
- A tree where each node has at most 2 children (left child and right child).



- **Properties:**
 - Each node has 0, 1, or 2 children
 - Children are labeled as left and right
 - Order matters: left \neq right
- **Use Case:** Expression trees, Huffman coding trees, basic tree operations learning.

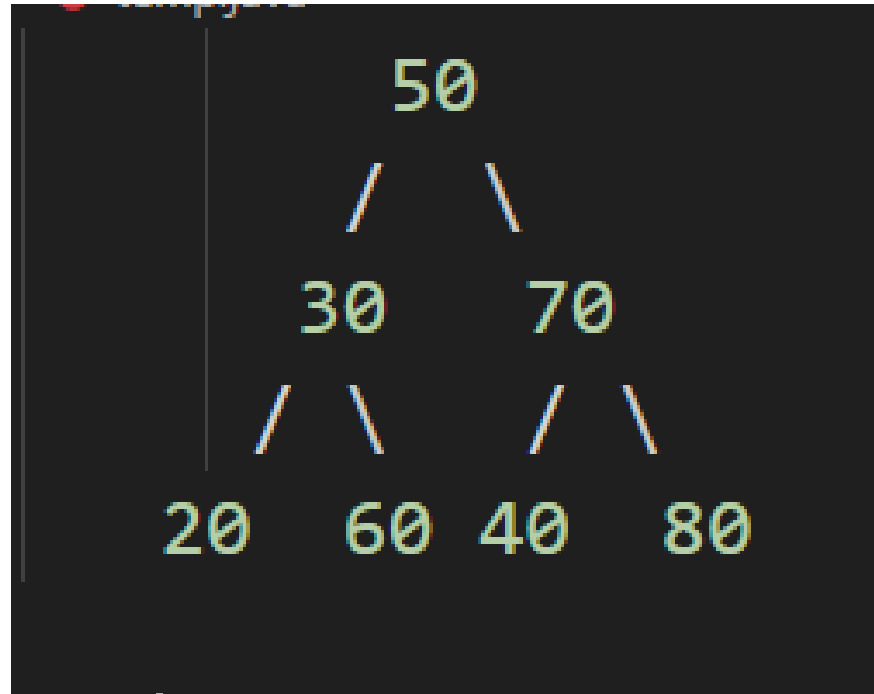
Binary Search Trees*

- A binary tree where for each node:
 - All values in the left subtree are less than the node's value
 - All values in the right subtree are greater than the node's value
 - Both left and right subtrees are also BSTs



Use cases: Databases indexing, searching with dynamic insertions/deletions, symbol tables in compilers.

Not A Binary Search Tree (BST)

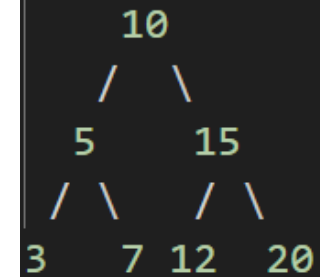


60 in left subtree but $60 > 50$ - violates BST property &
40 in right subtree – violates BST property

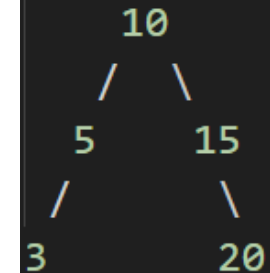
Full Binary Tree (Strict Binary Tree)

- A binary tree where every node has either 0 or 2 children. No node has exactly 1 child
- **Properties**
 - Every internal node has exactly 2 children
 - All leaves can be at different levels
 - If there are L leaves, there are $(L-1)$ internal nodes

Valid Full Binary Tree:



Not a Full Binary Tree:

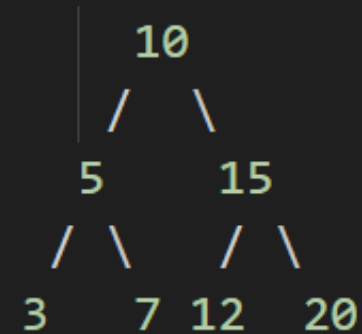


(Nodes 5 and 15 have only 1 child each - violates full binary tree property)

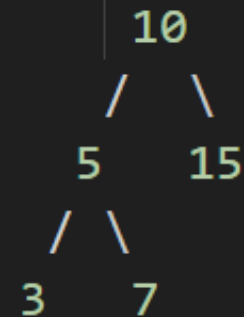
Perfect Binary Tree

- A binary tree where all internal nodes have exactly 2 children **AND** all leaf nodes are at the same level.
- **Properties**
 - Most restrictive binary tree type
 - All Perfect trees are also Full and Complete
 - Perfectly balanced

Perfect Binary Tree:



NOT Perfect (but Full):



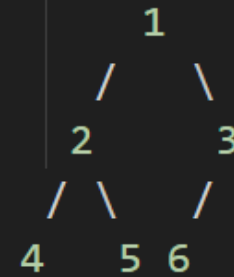
(This is Full but not Perfect - leaves at different levels)

Complete Binary Tree

- A binary tree where **all levels are completely filled except possibly the last level**, and the last level is filled from left to right.

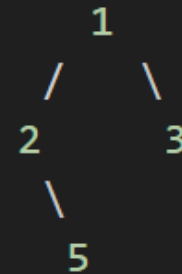
Some books & articles may refer to the Same as Almost Complete Binary Trees

Complete Binary Tree:



Last level filled from left to right

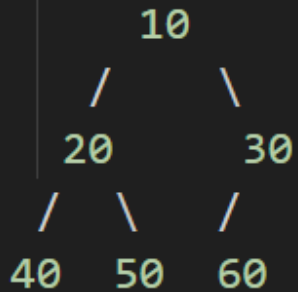
Not a Complete Binary Tree:



Left child missing, right child exists

Array representation : Complete Binary Trees

Complete Binary Tree:



Stored in Array (level order):

Index: 0 1 2 3 4 5
Array: [10, 20, 30, 40, 50, 60]

1. Root first
2. Then its children
3. Then grandchildren
4. Exactly how arrays store data

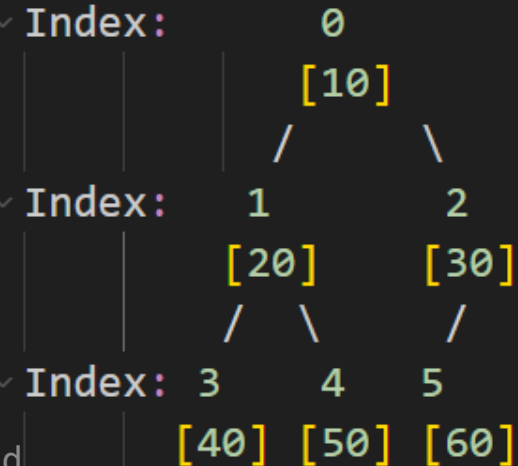
Index relationship:

Left child = $2*i + 1$

Right child = $2*i + 2$

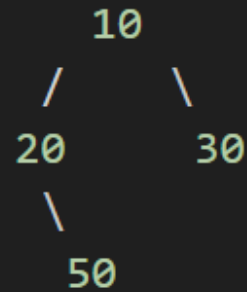
Parent = $(i - 1) / 2$

Index: 0 1 2 3 4 5
Array: [10, 20, 30, 40, 50, 60]



Array representation : Works only for Complete Binary Trees

Not Complete:



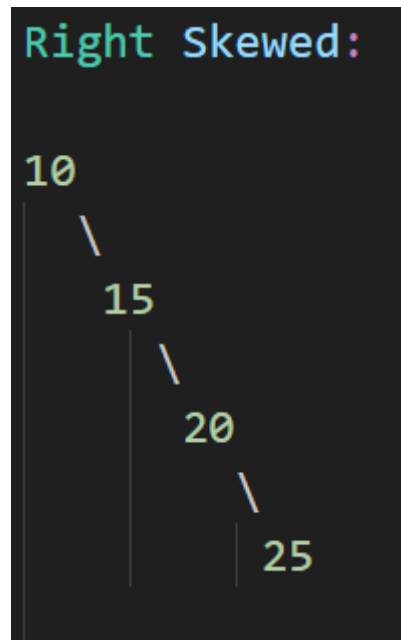
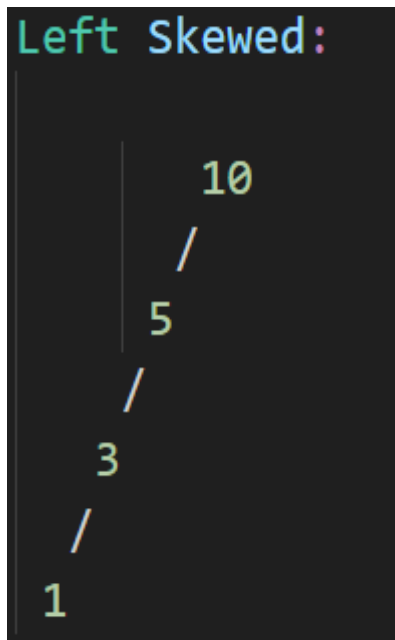
Attempted Array:

Index:	0	1	2	3	4
Array:	[10,	20,	30,	?,	50]

1. Gap at index 3
2. Index formulas break
3. Wasted space

Skewed Tree

- A tree where each parent node has only one child. Essentially becomes a linked list.



- **Properties:**
 - Worst case scenario for search operations
 - $O(n)$ time complexity for all operations
 - Height = Number of nodes - 1

This is what happens to an unbalanced BST when you insert sorted data. Understanding this motivates the need for self-balancing trees.

Balanced Trees

- Balanced trees maintain height $\approx \log(n)$ to ensure $O(\log n)$ operations even in worst case.



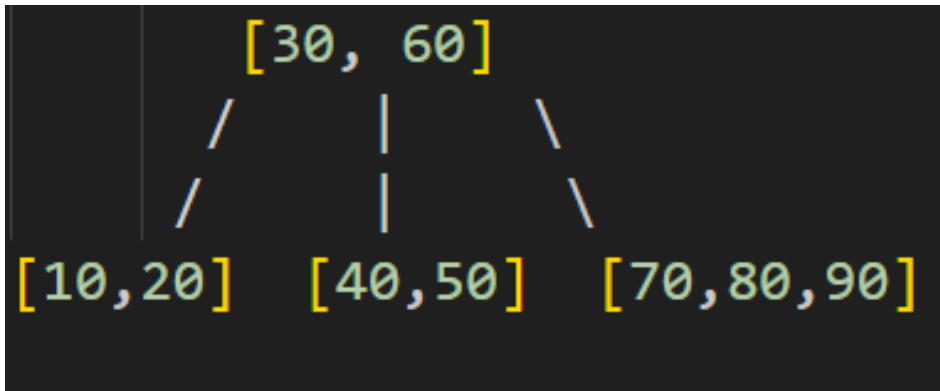
- AVL Tree:**
 - Self-balancing BST where the height difference between left and right subtrees (balance factor) is at most 1 for every node
 - Each node's $|\text{height}(\text{left}) - \text{height}(\text{right})| \leq 1$

Balanced Trees

- **Red-Black Tree:**
 - Self-balancing BST with color properties (red/black nodes) ensuring tree remains approximately balanced
- **Use Cases:**
 - Java's TreeMap, TreeSet, Linux kernel scheduling, C++ STL map.
- **Properties**
 - Every node is either red or black
 - Root is always black
 - Red nodes cannot have red children
 - Every path from root to leaf has same number of black nodes

B-Tree

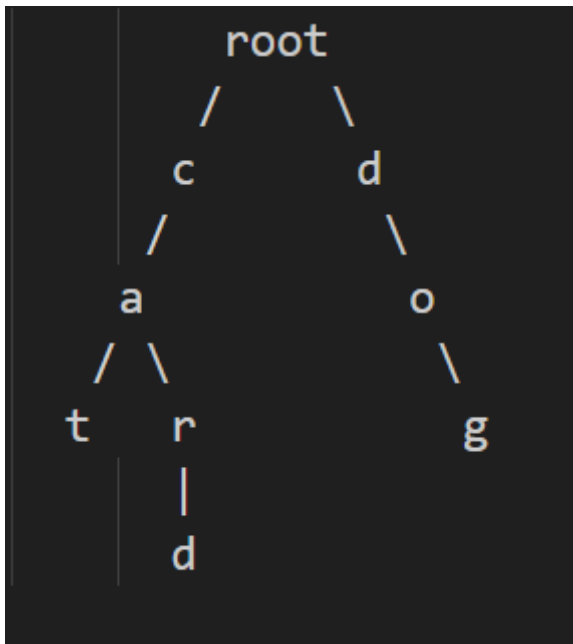
- Self-balancing search tree where nodes can have multiple keys and more than 2 children. Designed for disk storage systems



- **Properties**
 - Each node can contain multiple keys (not just one)
 - All leaves at the same level
 - Optimized for systems that read/write large blocks of data
 - Minimizes disk I/O operations
- **Use cases:** Database indexing (MySQL, PostgreSQL use B+ Trees), file systems (NTFS, ext4)

Trie

- Tree structure where each node represents a character, used for efficient string storage and retrieval
- Storing "cat", "car", "card", "dog":



- **Properties**
 - Each path from root to node represents a prefix
 - Common prefixes share paths
 - Fast string lookup: $O(L)$ where L is string length
- **Use cases :** Auto-complete, spell checkers, dictionary implementations.

BST Operations

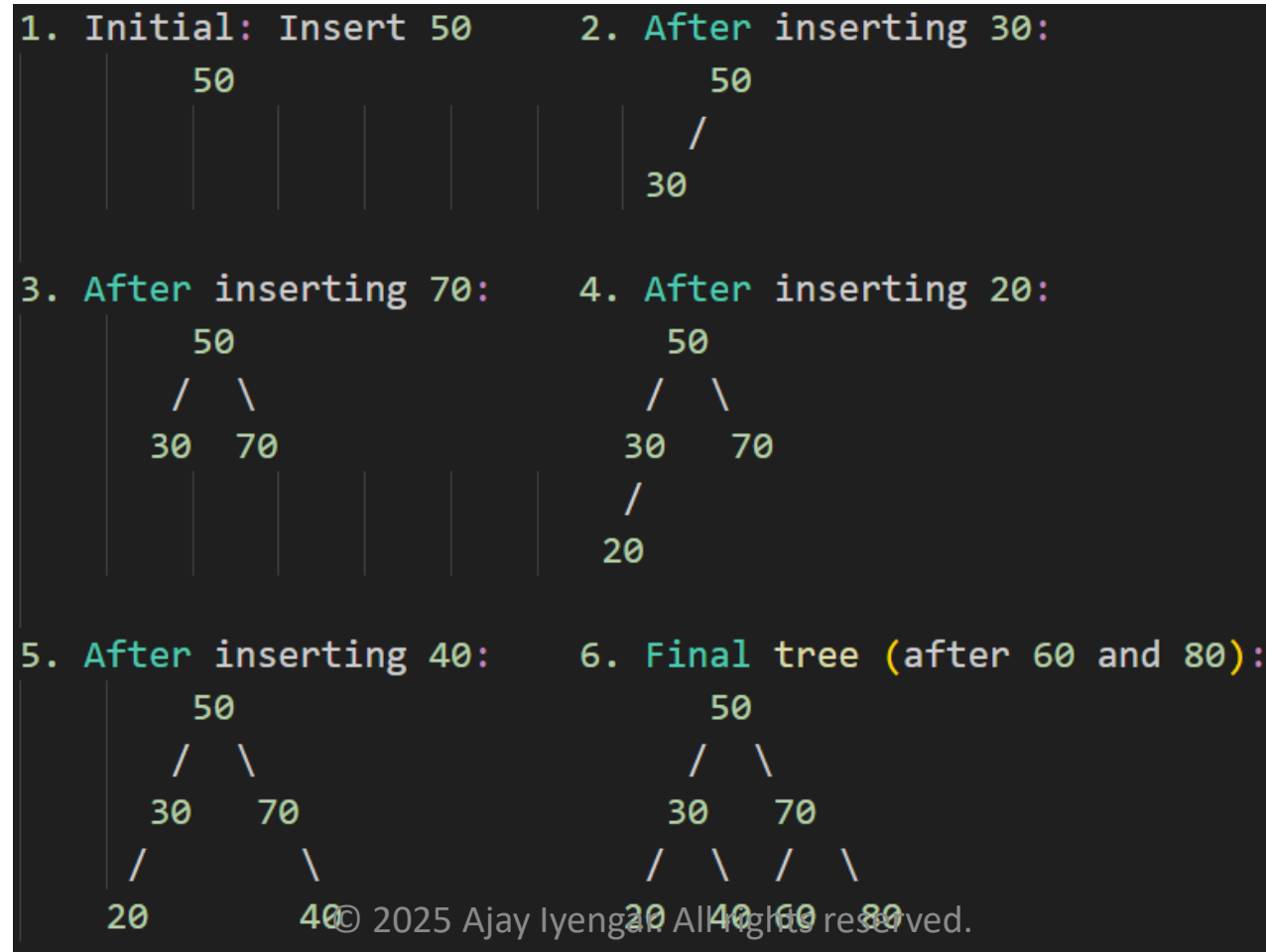
- A **Binary Search Tree (BST)** is a special type of binary tree where each node follows a simple rule:

Left child < Parent node < Right child

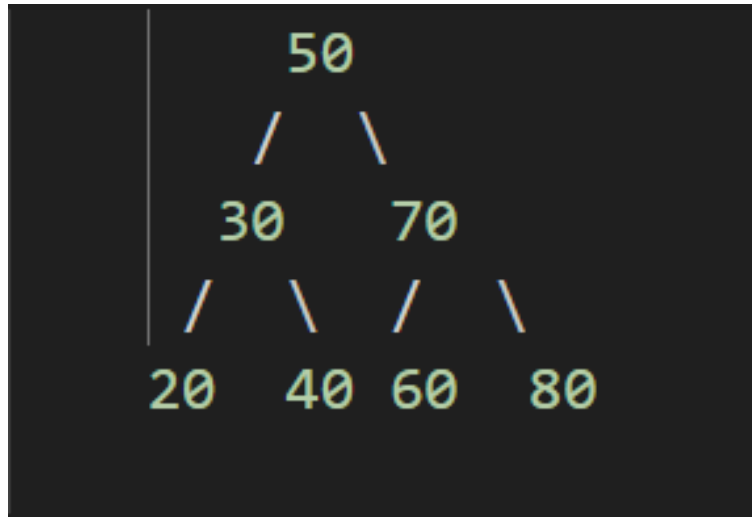
- This property must be true for **every node** in the tree
- This makes BSTs incredibly efficient for searching, insertion, and deletion operations.
- Unlike arrays or linked lists where searching takes $O(n)$ time, a well-balanced BST allows you to search for elements in $O(\log n)$ time - similar to binary search!

Creating a BST

Let's say we want to insert these numbers in order: 50, 30, 70, 20, 40, 60, 80



Creation of BST : Node class

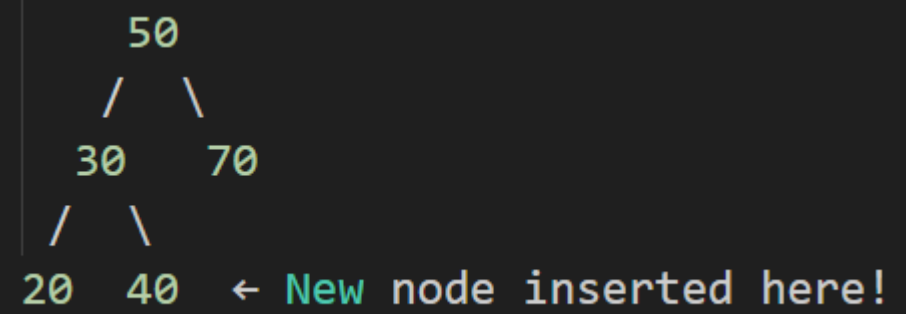
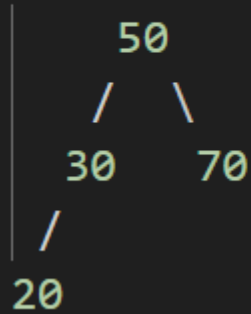


```
class Node {  
    int data;  
    Node left;  
    Node right;  
  
    // Constructor to create a new node  
    public Node(int data) {  
        this.data = data;  
        this.left = null;  
        this.right = null;  
    }  
}
```

Notice how smaller values always go left, larger values always go right!

Example of how iterative insertion works

Inserting 40 into the following Binary Search Tree (BST):



Step-by-step:

1. Create newNode with value 40
2. Start at root (50)
3. $40 < 50 \rightarrow$ Move to left child (30)
4. $40 > 30 \rightarrow$ Move to right child (null)
5. Found empty spot! Insert 40 as right child of 30

BST Creation : Time & Space Complexity

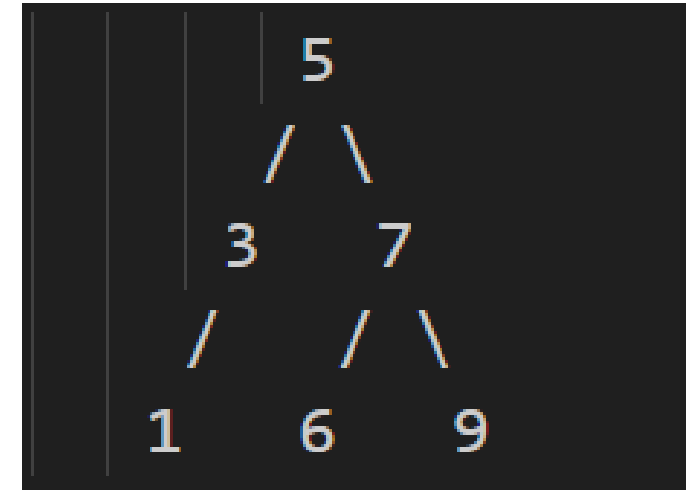
- **Time Complexity:**
 - **Best Case:** $O(\log n)$ - when the tree is balanced
 - **Average Case:** $O(\log n)$
 - **Worst Case:** $O(n)$ - when the tree becomes a skewed line (e.g., inserting sorted data)
- **Space Complexity:**
 - **$O(1)$** - Iterative approach uses constant extra space (just a few pointers)
 - The tree itself uses $O(n)$ space for n nodes

BST : Inorder Traversal

- Inorder traversal visits nodes in this order:

Left → Root → Right

- For a BST, this gives us nodes in ****sorted order****!
- Inorder will visit the nodes in this order: 1 3 5 6 7 9



BST : Inorder traversal (*Recursion)

```
public void inorderTraversal(Node root) {  
    if (root == null) {  
        return;  
    }  
  
    inorderTraversal(root.left); // Visit left subtree  
    System.out.print(root.data + " "); // Process current node  
    inorderTraversal(root.right); // Visit right subtree  
}
```


Inorder using Recursion

How does it work ?

- Each function call executes ALL its lines
- Recursive calls PAUSE the current function
- Functions RESUME from where they paused
- The recursion naturally goes deep left first
- The call stack remembers where to return AND what to do next

Refer to [inorder-traversal-notes](#) for detailed step by step explanation

Inorder Recursion

Time & Space Complexity

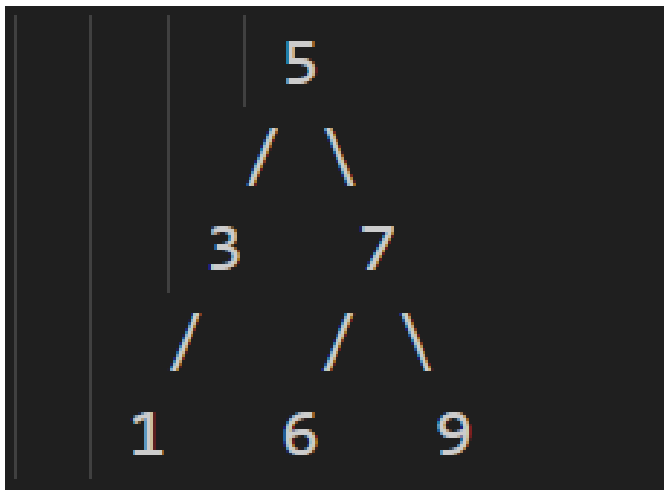
- **Time Complexity:** $O(n)$ - We visit each node exactly once
- **Space Complexity:** $O(h)$ - Maximum call stack depth is the height of the tree
 - Best case (balanced): $O(\log n)$
 - Worst case (skewed): $O(n)$

BST : Preorder Traversal

- Preorder traversal visits nodes in this order:

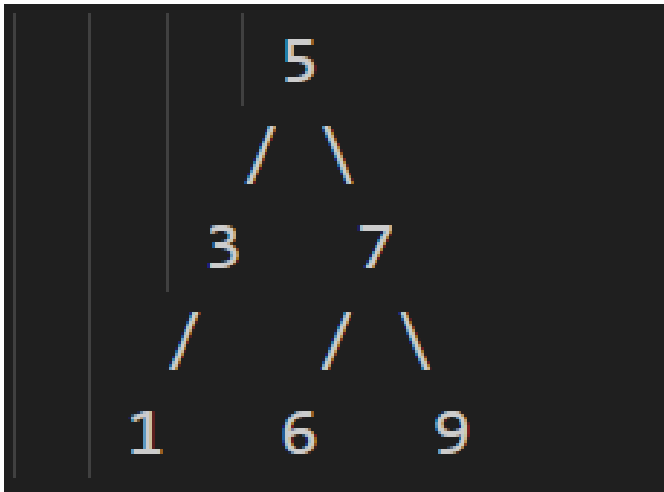
Root → Left → Right

- The key difference: we process the node first, followed by left subtree & then right subtree
- Preorder will visit the nodes in this order : 5 3 1 7 6 9



BST : Postorder Traversal

- Postorder traversal visits nodes in this order:
Left → Right → Root
- The key difference: we process the node LAST, after both subtrees
- Postorder will visit the nodes in this order : 1 3 6 9 7 5



BST : Postorder traversal (*Recursion)

```
public void postorderTraversal(Node root) {  
    if (root == null) {  
        return;  
    }  
  
    postorderTraversal(root.left); // Visit left subtree  
    postorderTraversal(root.right); // Visit right subtree  
    System.out.print(root.data + " "); // Process current node LAST  
}
```

Postorder using Recursion

How does it work ?

- The root prints LAST
- Each function waits through TWO recursive calls
- The "pause and resume" happens TWICE per node
- Children are always processed before parents
- The call stack manages the "waiting"

Refer to [postorder-traversal-notes](#) for detailed step by step explanation

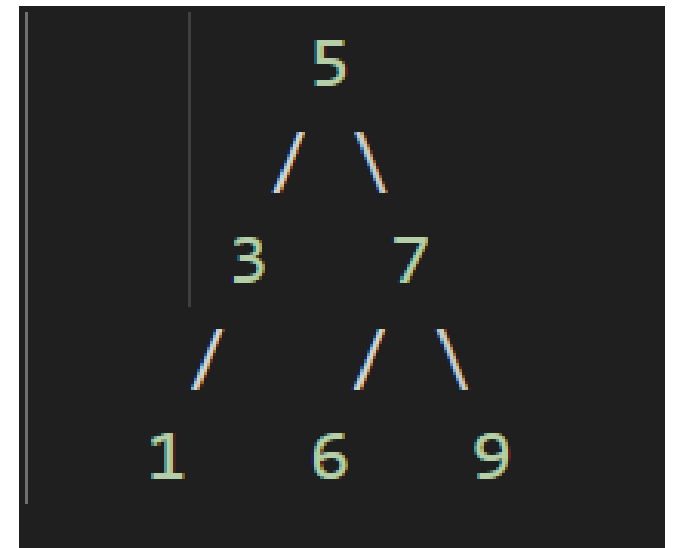
Postorder Recursion

Time & Space Complexity

- **Time Complexity:** $O(n)$ - We visit each node exactly once
- **Space Complexity:** $O(h)$ - Maximum call stack depth is the height of the tree
 - Best case (balanced): $O(\log n)$
 - Worst case (skewed): $O(n)$

Height of a Binary Tree

- The **height of a tree** is the longest path from the root to any leaf node (counting edges).
- This is a classic example of **bottom-up recursion** - we calculate heights from leaves and bubble up to the root!
- The height of the tree is 2



Code : Height of a Binary Tree

```
public int height(Node root) {  
    if (root == null) {  
        return -1; // Base case: null has height -1  
    }  
  
    int leftHeight = height(root.left); // Get left subtree height  
    int rightHeight = height(root.right); // Get right subtree height  
  
    return 1 + Math.max(leftHeight, rightHeight); // Current height  
}
```

The key insight: **Height = 1 + max(left height, right height)**

Why the formula works ?

```
return 1 + Math.max(leftHeight, rightHeight);
```

↑ ↑
| |
└─ Which path is longer?
└─ Add current edge/node

- If left is taller, we take that path and add 1 for current node
- If right is taller, we take that path and add 1 for current node
- If both equal (or both null), we take either and add 1

Height of a Binary Tree using Recursion

- **This is postorder recursion** - We process children FIRST, then use their results to calculate parent's value
- **Base case is critical** - $\text{height}(\text{null}) = -1$ makes the math work for leaf nodes ($1 + \max(-1, -1) = 0$)
- **The + 1 counts the current edge** - We add 1 for the edge from current node to its taller subtree
- **The max picks the taller path** - We want the LONGEST path, so we take the maximum height
- **Each node waits for BOTH children** - Just like postorder traversal, we need both recursive calls to complete

Height of Binary Tree : Time & Space Complexity

- **Time Complexity:** $O(n)$ - We visit each node exactly once
- **Space Complexity:** $O(h)$ – Call stack depth equals tree height
 - Best case (balanced): $O(\log n)$
 - Worst case (skewed): $O(n)$