



SINDH MADRESSATUL ISLAM UNIVERSITY KARACHI

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## LAB MANUAL OF AGENTBASE MODELING

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**DEPARTMENT:** BS ARTIFICIAL INTELLIGENCE

**LAB INSTRUCTOR:** FURQAN AHMED

**FALL-2025**



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# CERTIFICATE

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## DEPARTMENT OF ARTIFICIAL INTELLIGENCE AGENT BASE MODELING

This is certified that Mr/Ms.**Muhammad Yahya** having Roll No.**BAI-23F-030** has successfully completed Laboratory work during FALL Semester 2025.

**LAB INSTRUCTOR:**  
FURQAN AHMED

**SIGNATURE**

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## LAB 1: INTRODUCTION TO NETLOGO AND INSTALLATION

### OBJECTIVE

- Understand what NetLogo is.
- Learn how to install NetLogo on Windows.
- Explore the NetLogo interface and run a built-in simulation.

### LANGUAGE/TOOL

- **Tool:** NetLogo 6.4.0 (or latest version)
- **Platform:** Windows (64-bit recommended)

**OFFICIAL SITE:** <https://ccl.northwestern.edu/netlogo/>

### THEORY

NetLogo is a multi-agent modeling environment used to simulate how simple rules at the individual level can lead to complex patterns at the system level.

#### Agents in NetLogo

1. Turtles – moving agents (cars, animals, people).
2. Patches – the background grid (environment).
3. Links – connections between turtles (roads, social ties).
4. Observer – the global controller.

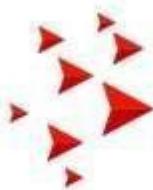
### WHY USE NETLOGO?

- Beginner-friendly, yet powerful.
- Large Models Library (ready-to-use simulations).
- Widely used in education, AI, biology, and social sciences.

### INSTALLATION ON WINDOWS

#### Step 1: Download

1. Open a browser and go to: <https://ccl.northwestern.edu/netlogo/>.

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# NetLogo

Simulate, Explore, Understand

Powerful yet easy-to-learn environment for agent-based modeling in both research and education.

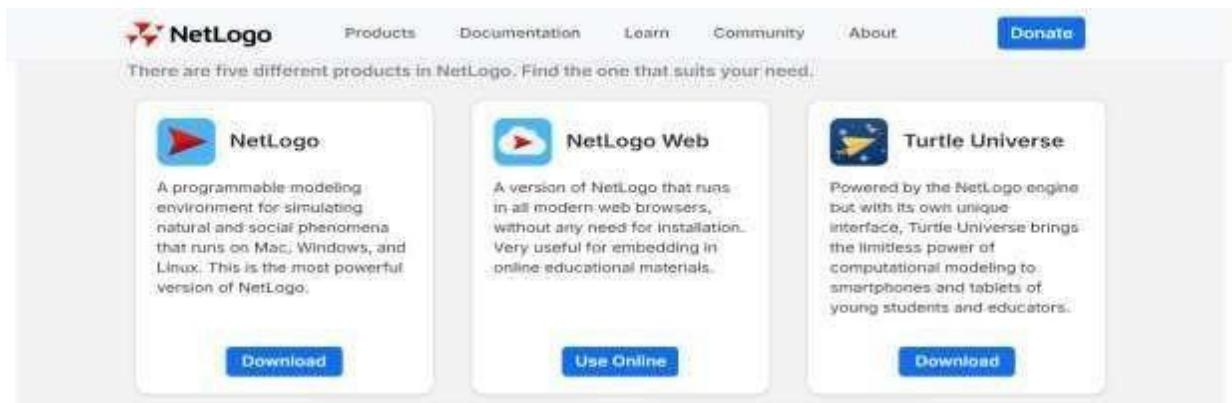
[GET NETLOGO](#)[Donate](#)

100% Free

[Understanding Emergence](#)[Scientific Research](#)[Learning](#)[Teaching](#)[Intuitive Code](#)

NetLogo is designed to model emergent phenomena in which large-scale patterns arise from the interactions of many individuals.

2. Click Download NetLogo.



3. Select Windows Installer (.exe).



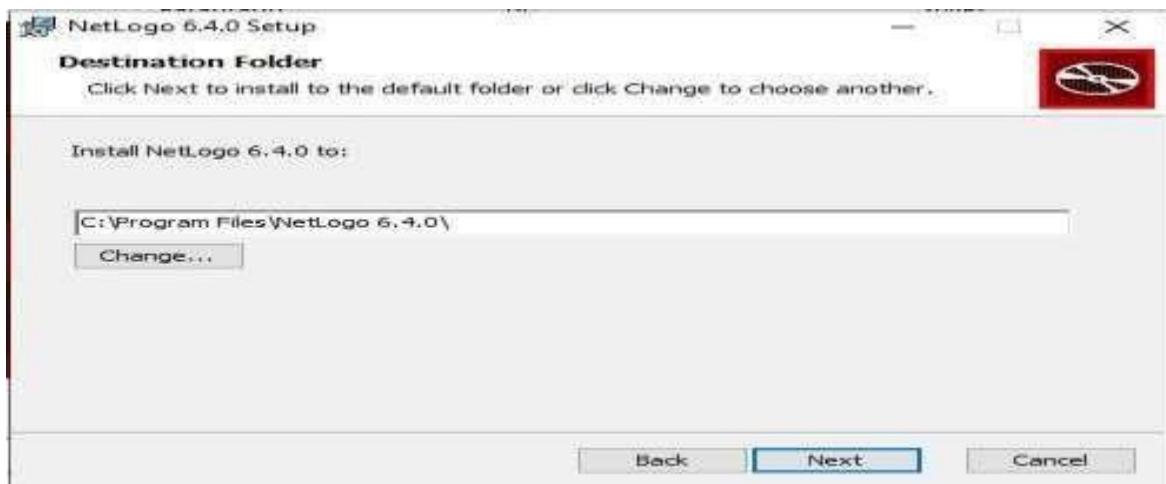
### Step 2: Install

1. Locate the downloaded .exe file (in *Downloads*).
2. Double-click the file → installation wizard opens.

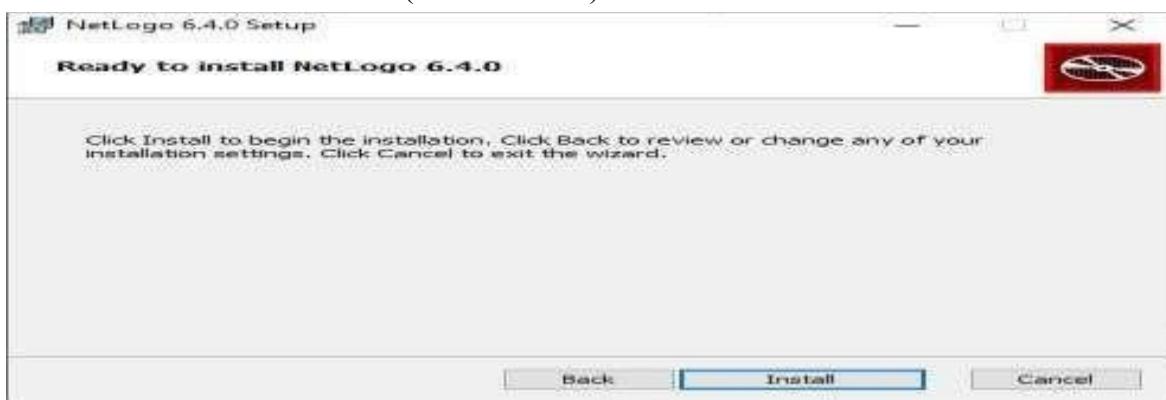
Follow the steps:



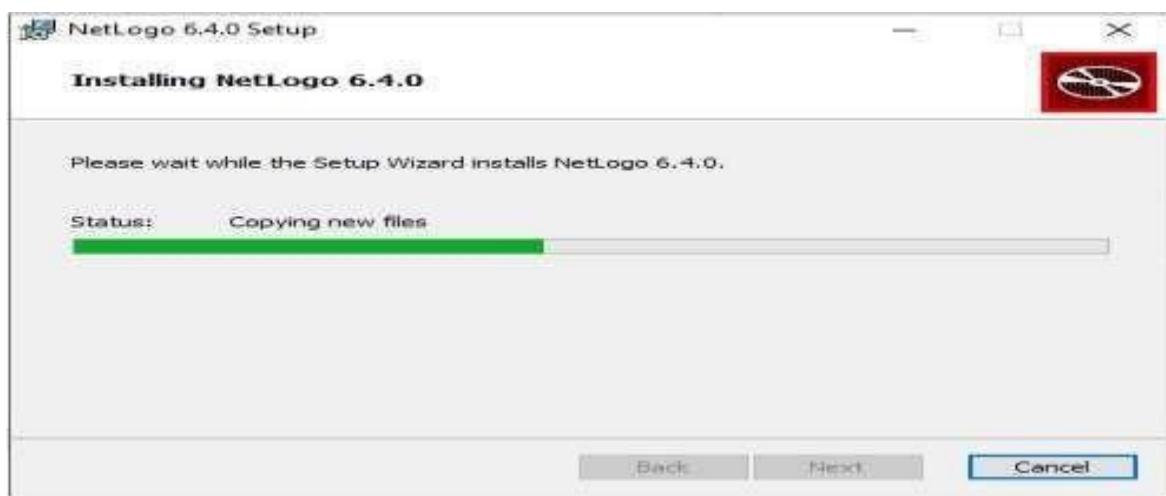
Click Next.



- Choose install location (default is fine).



- Click Install.



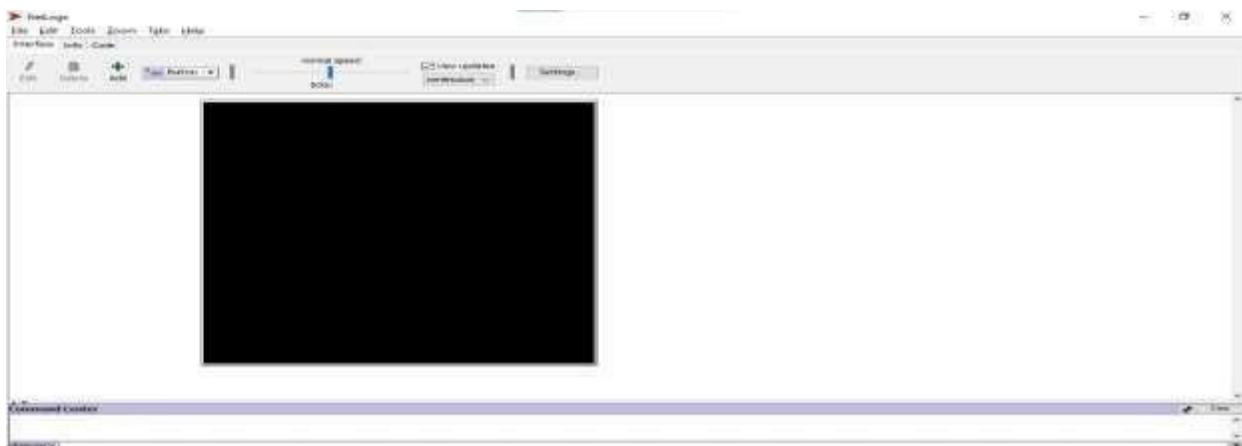
- Wait for installation to complete.



- Click Finish.

### Step 3: Verify Installation

1. Go to Start Menu and search NetLogo 6.4.0.
2. Open it.
3. You should see the NetLogo main window with:
  - Menu bar (File, Tools, etc.)
  - Tabs: *Interface, Info, Code*
  - Command Center at the bottom



- **Interface Tab:** Run models, adjust sliders, press buttons, see plots.



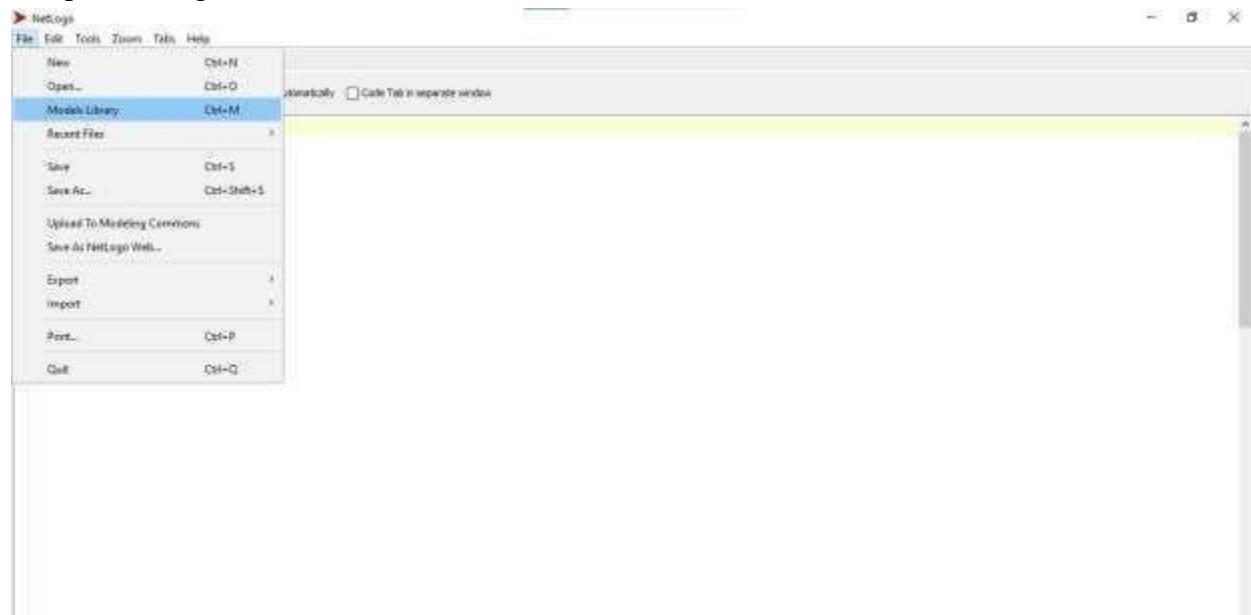
**Info Tab:** Description of the model and instructions.



- **Code Tab:** Where you write your own NetLogo programs.
- **Command Center:** For quick commands.

## PRACTICAL EXERCISE (FIRST RUN)

### 1. Open NetLogo.





## 2. Go to File Models Library.



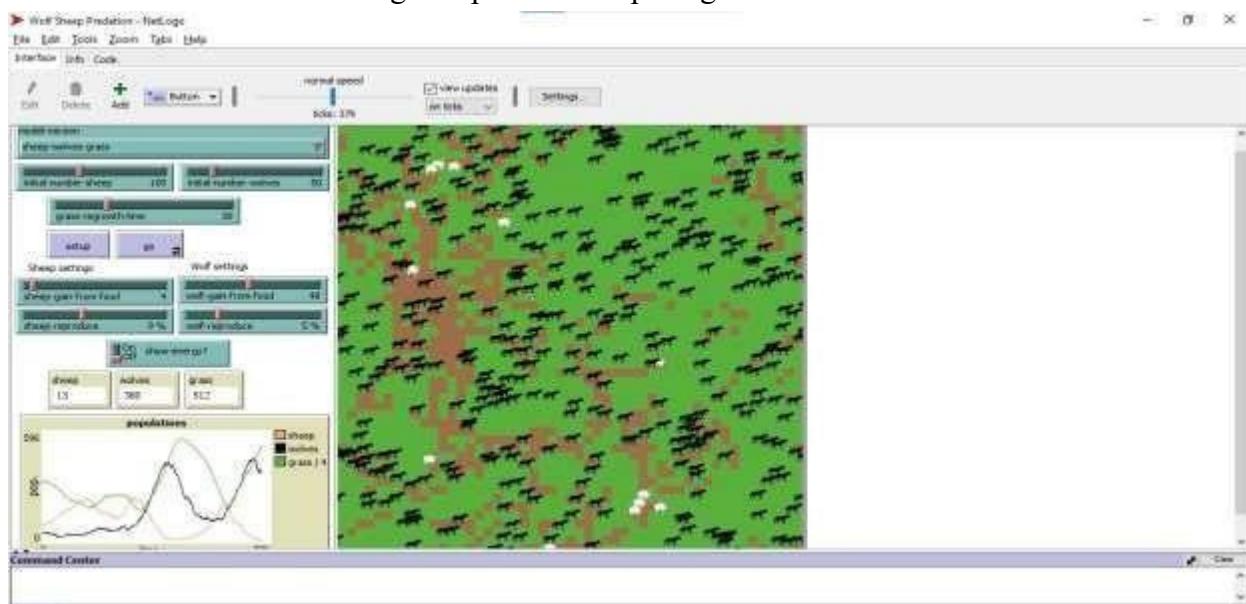
## 3. Select Biology Wolf Sheep Predation.



## 4. Click Setup, then go.



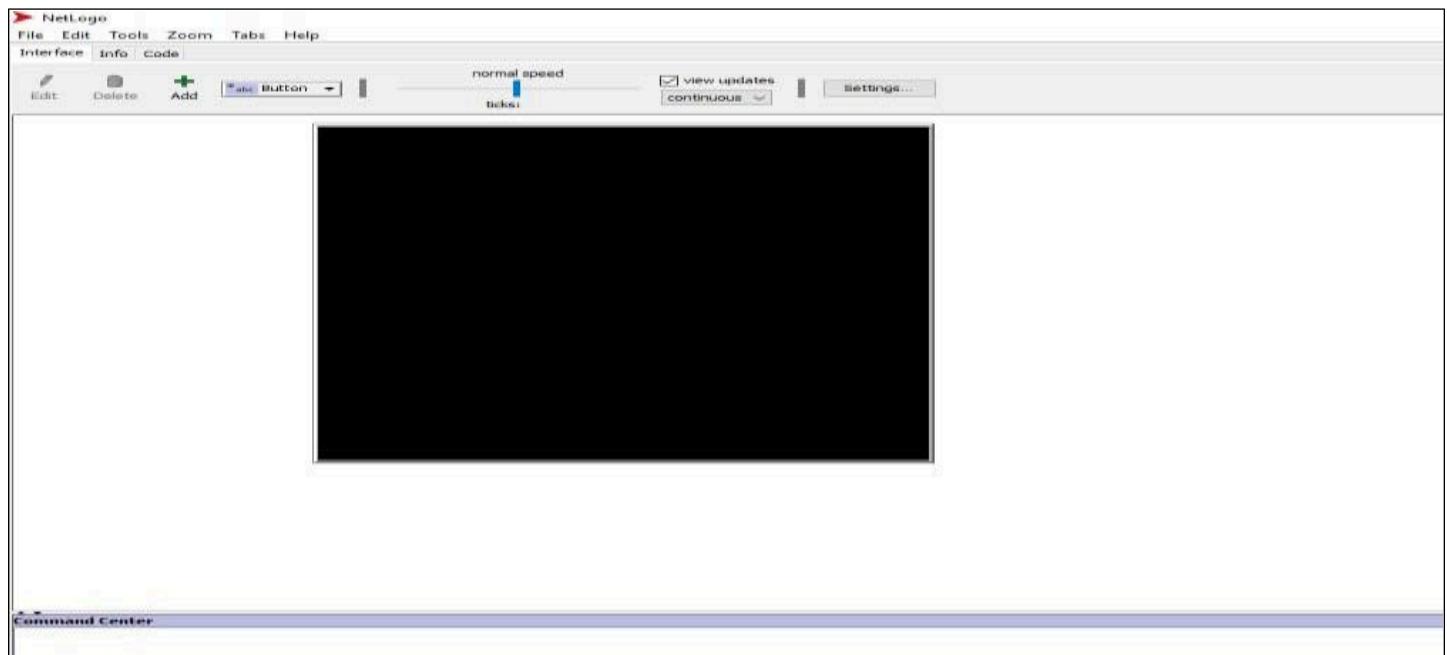
Observe wolves chasing sheep while sheep eat grass.



- Use the sliders to change parameters like "sheep-reproduce" or "wolf-gain-from-food" and see what happens.

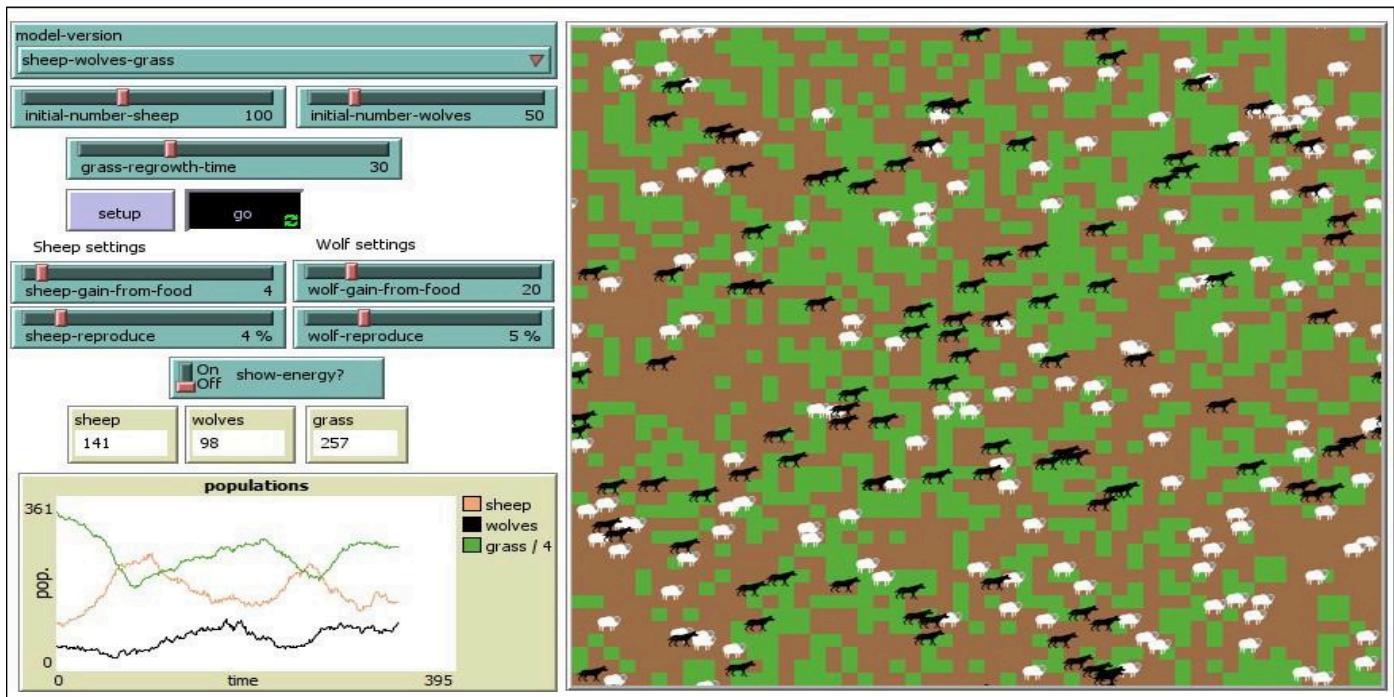
## STUDENT TASK

1. InstallNetLogo on Windows and take a screenshot of the main interface.

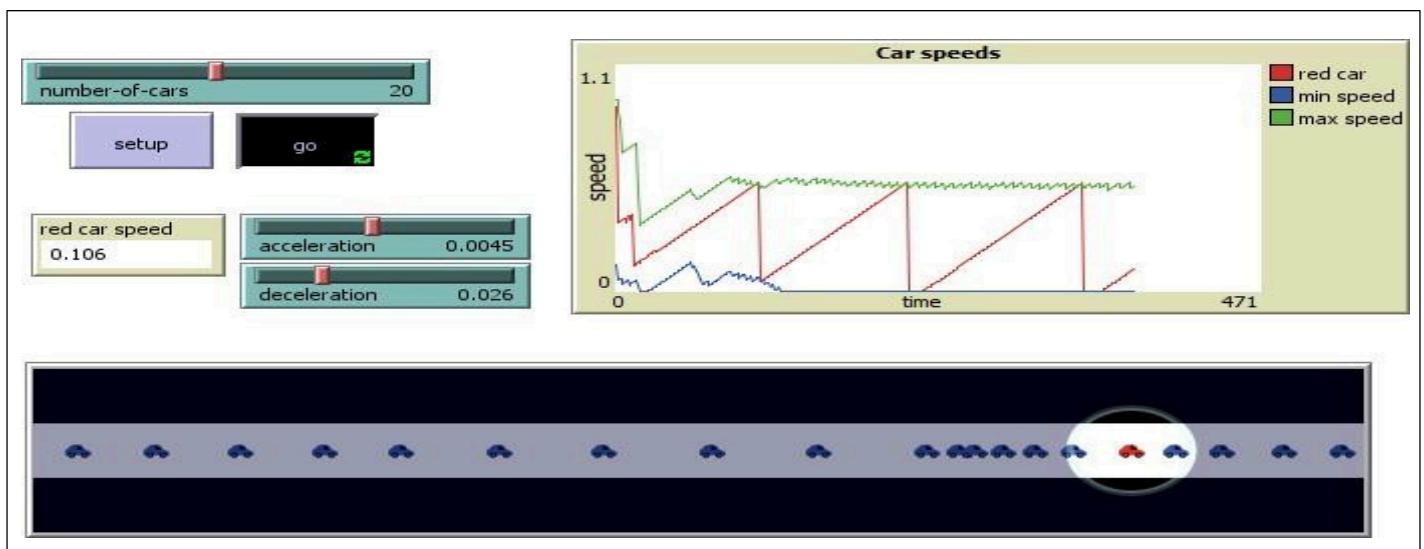


2. Open and run two different models from the library (e.g., Wolf Sheep Predation and Traffic Basic).

## WOLF SHEEP PREDATION MODEL



## TRAFFIC BASIC MODEL



**3.** Identify which agents are turtles, patches, links, and observer in those models.

- In the **Wolf-Sheep Predation model**, the turtles are the *wolves* and *sheep*, the patches represent the *grass* on which they move and feed, there are *no links* in this model, and the *observer* controls the simulation and observes the population changes.

In the **Traffic Basic model**, the turtles are the *cars*, the patches form the *road* on which the cars move, there are *no links* used, and the *observer* starts and monitors the movement of the cars.

**4.** Note down what happens when you change parameters (using sliders).

- In the **Wolf-Sheep Predation model**, changing sliders like the number of sheep, wolves, or grass regrowth rate changes how fast populations grow or decline.
- In the **Traffic Basic model**, changing sliders like car number, speed, or slowdown probability affects the traffic flow and congestion.

## **POST-LAB QUESTIONS & ANSWERS**

### **1. What is NetLogo used for?**

NetLogo is used for building and simulating **agent-based models (ABM)**. It helps study how individual agents (like animals, cars, or people) interact with each other and their environment to create overall system behavior.

### **2. Explain the four types of agents in NetLogo.**

- **Turtles:** Moving agents that represent individuals such as animals, cars, or people.
- **Patches:** The background grid cells on which turtles move; they can hold values like color or grass level.
- **Links:** Connections between turtles, used to show relationships like networks or roads.
- **Observer:** The overall controller that runs commands, starts or stops the simulation, and observes results.

### **3. Write the correct steps to install NetLogo on Windows.**

1. Go to the official NetLogo website (<https://ccl.northwestern.edu/netlogo/>).
2. Click **Download NetLogo** and choose the Windows version.
3. After downloading, open the installer file (.exe).
4. Follow the setup wizard and click **Next** to complete the installation.
5. Once installed, open NetLogo from the Start Menu or Desktop shortcut.

### **4. What are the three main tabs in the interface, and what is each used for?**

- **Interface Tab:** Used to run the model, view graphics, sliders, and buttons.
- **Info Tab:** Shows a description of the model, its purpose, and
- **Model Tab:** Contains the NetLogo programming code that defines the model's behavior.

### **5. Which models did you try, and what patterns did you observe?**

I tried the **Wolf-Sheep Predation** and **Traffic Basic** models.

In the Wolf-Sheep model, I observed cycles in population when sheep increase, wolves also increase, then both decrease alternately.

In the Traffic Basic model, I observed how traffic jams form when too many cars are added or when slowdown probability increases.

## LAB 2: WORKING WITH TURTLES IN NETLOGO

### OBJECTIVE

- To understand how to create and control turtles in NetLogo.
- To execute turtle commands using the Command Center.
- To visualize how simple movement rules lead to complex behaviors.

### LANGUAGE/TOOL

- **Tool:** NetLogo 6.4.0
- **Platform:** Windows
- **Location:** Command Center in the NetLogo interface

### THEORY

In NetLogo, turtles are moving agents that can perform actions such as moving, turning, changing color, or interacting with the environment.

Each turtle acts independently, but together they can form patterns or simulate real-world systems such as traffic, animal movement, or people in a crowd.

### KEY COMPONENTS

- **Observer:** The global controller that gives commands to all turtles or patches.
- **Turtles:** The moving agents created by the observer.
- **CommandCenter:** The area at the bottom where you type commands directly.

### COMMON TURTLECOMMANDS

Command	Description
create-turtles <i>n</i>	Creates <i>n</i> turtles at random locations
forward <i>n</i>	Moves the turtle forward <i>n</i> steps
back <i>n</i>	Moves the turtle backward <i>n</i> steps
left <i>n</i>	Turns the turtle left by <i>n</i> degrees
right <i>n</i>	Turns the turtle right by <i>n</i> degrees

set color colorname	Changes turtle color
set size n	Changes turtle size
set xcor value / set ycor value	Changes turtle position
random-xcor, random-ycor	Generates random coordinates
repeat [commands]	Repeats a set of commands multiple times
ask turtles [ ... ]	Tells all turtles to do the commands inside brackets

## LAB PROCEDURE

### Step 1: OpenNetLogo

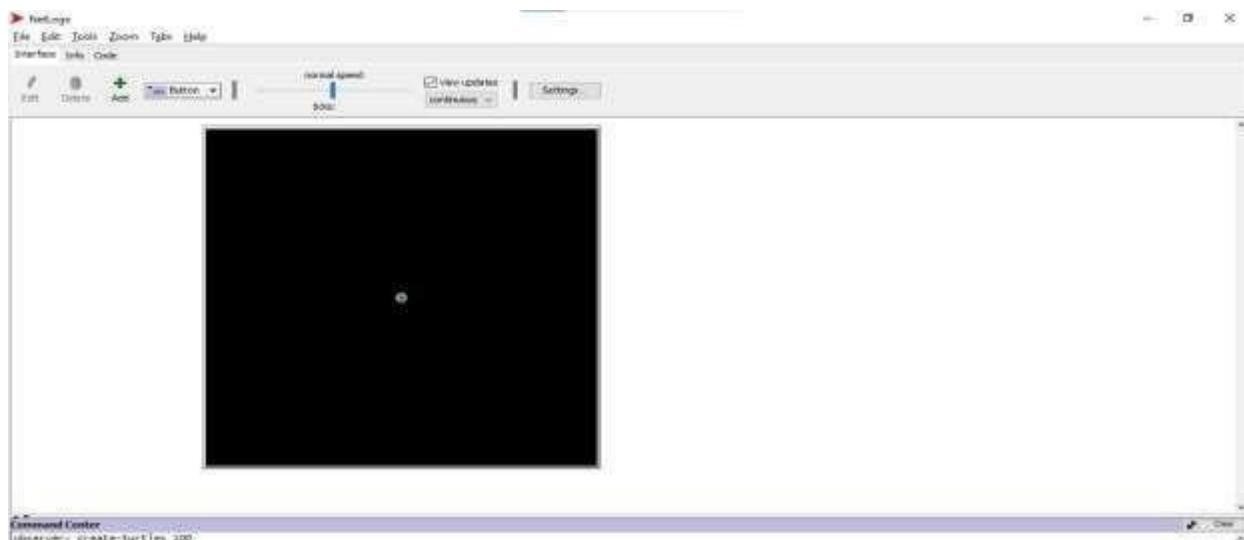
- Launch NetLogo on your Windows computer.
- You will see the Interface, Info, and Code tabs.
- At the bottom, locate the Command Center — this is where you will type commands.

### Step 2: Run EachCommand

#### OBSERVER COMMANDS

These are typed directly in the Command Center

1. observer> create-turtles 100

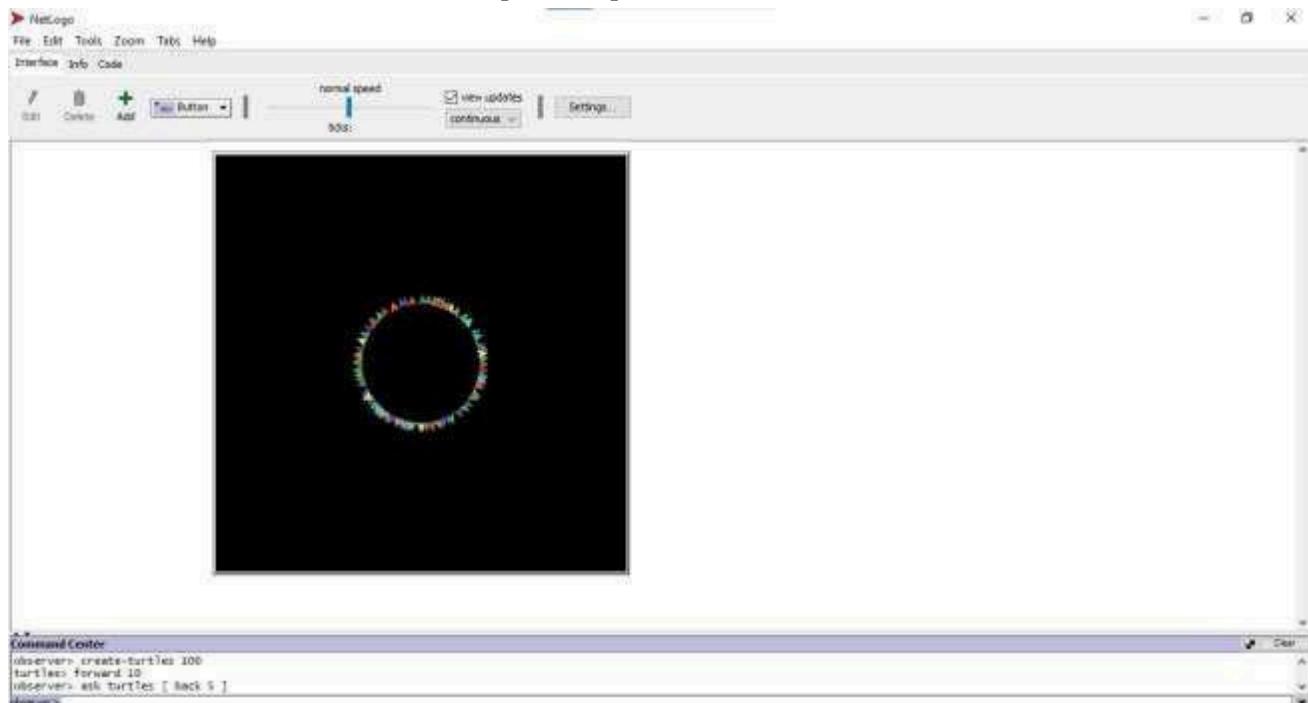


► Creates 100 turtles at the center of the world.

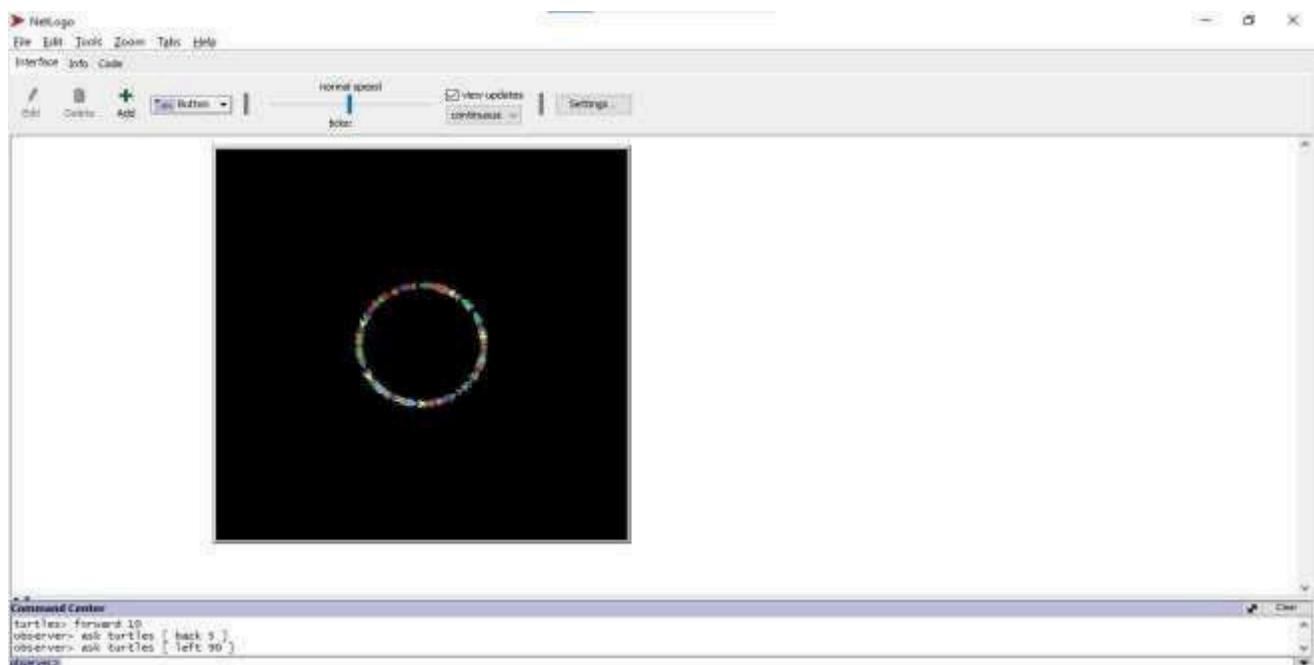
2. turtles> forward 10



- Moves all turtles 10 steps forward from their starting point.  
3. observer> ask turtles [ back 5 ]

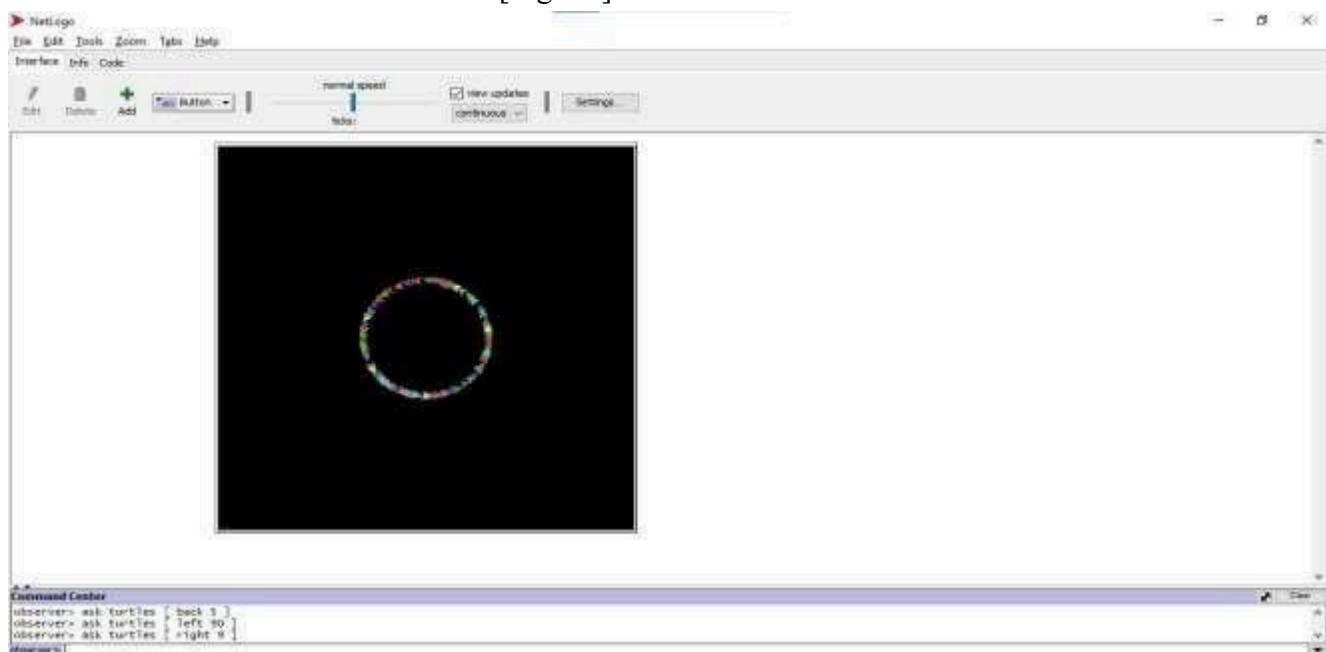


- Tells every turtle to move 5 steps backward.  
4. observer> ask turtles [ left 90]



► Turns every turtle 90° to the left.

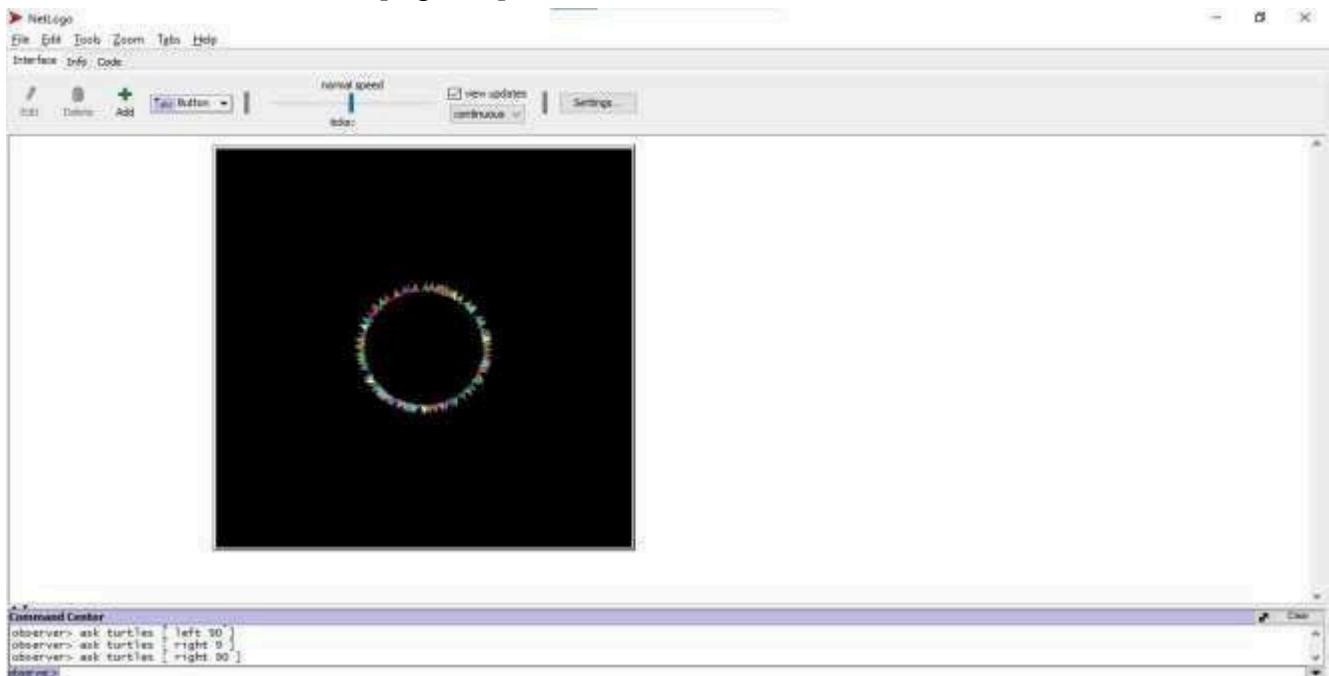
5. observer> ask turtles [ right 9 ]



□ Turns every turtle 90° to the right.

observer> ask turtles

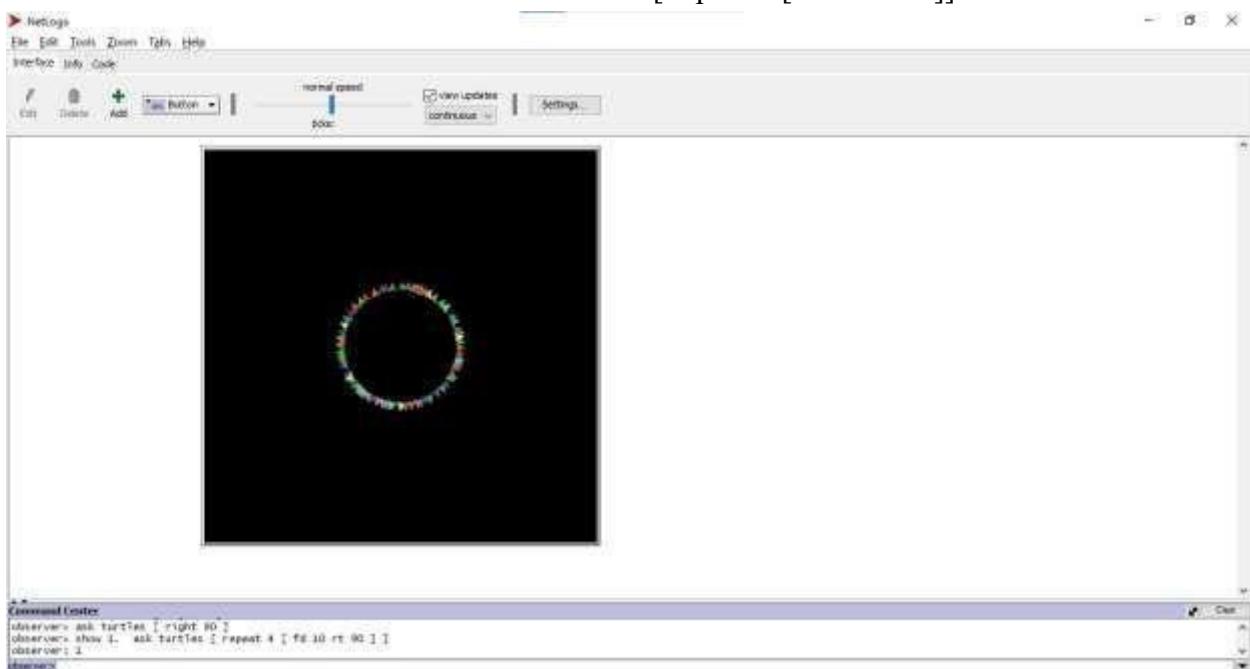
6. [ right 90]



- Turns every turtle 90° to the right again (back to original direction).

7.

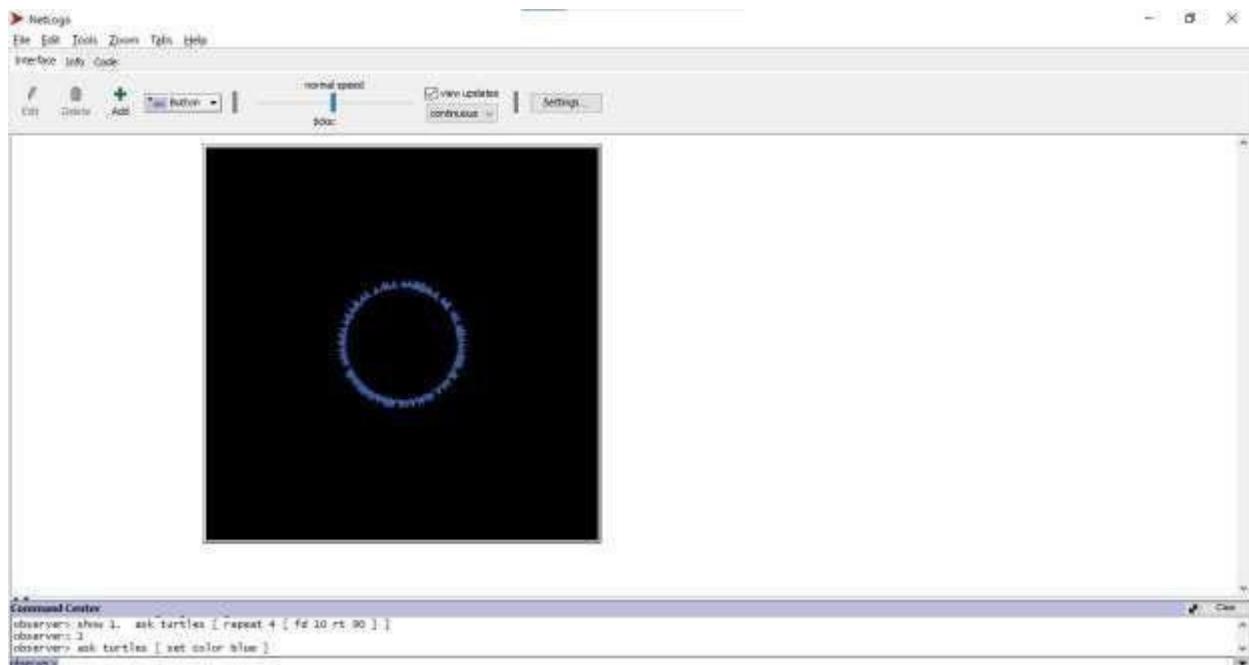
observer> ask turtles [ repeat 4 [ fd 10 rt 90]]



- Each turtle moves in a square pattern (4 sides × 10 steps each).

8. [ set color blue ]

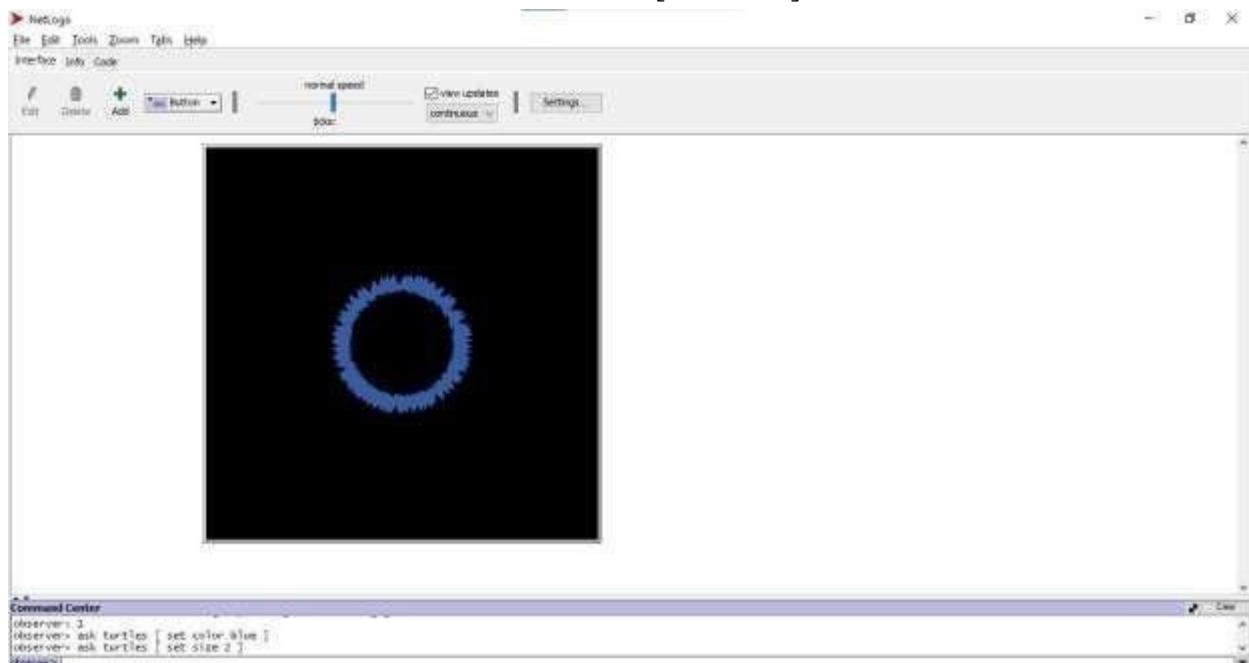
observer> ask turtles



- Changes the color of all turtles to blue.

9.

observer> ask turtles [ set size 2]

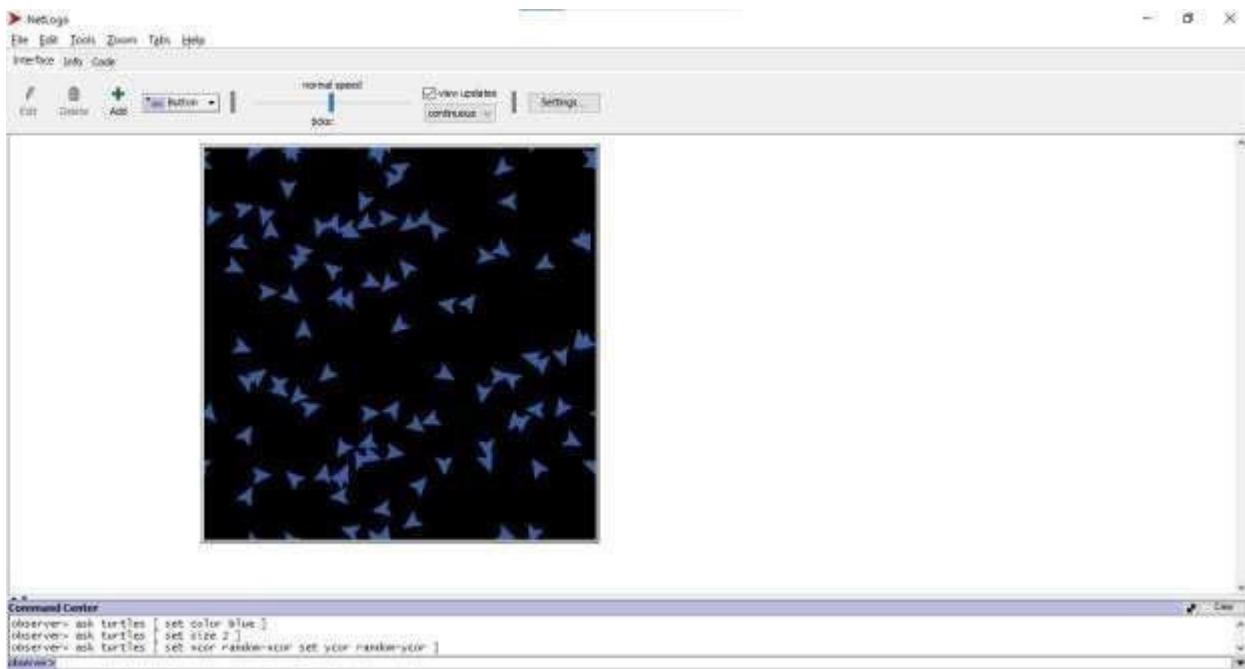


10.

Makes each turtle twice its normal size.

[ set xcor random-xcor set ycor random-ycor ]

observer> ask turtles



- Moves each turtle to a random location on the grid.

### Step 3: Observe the Results

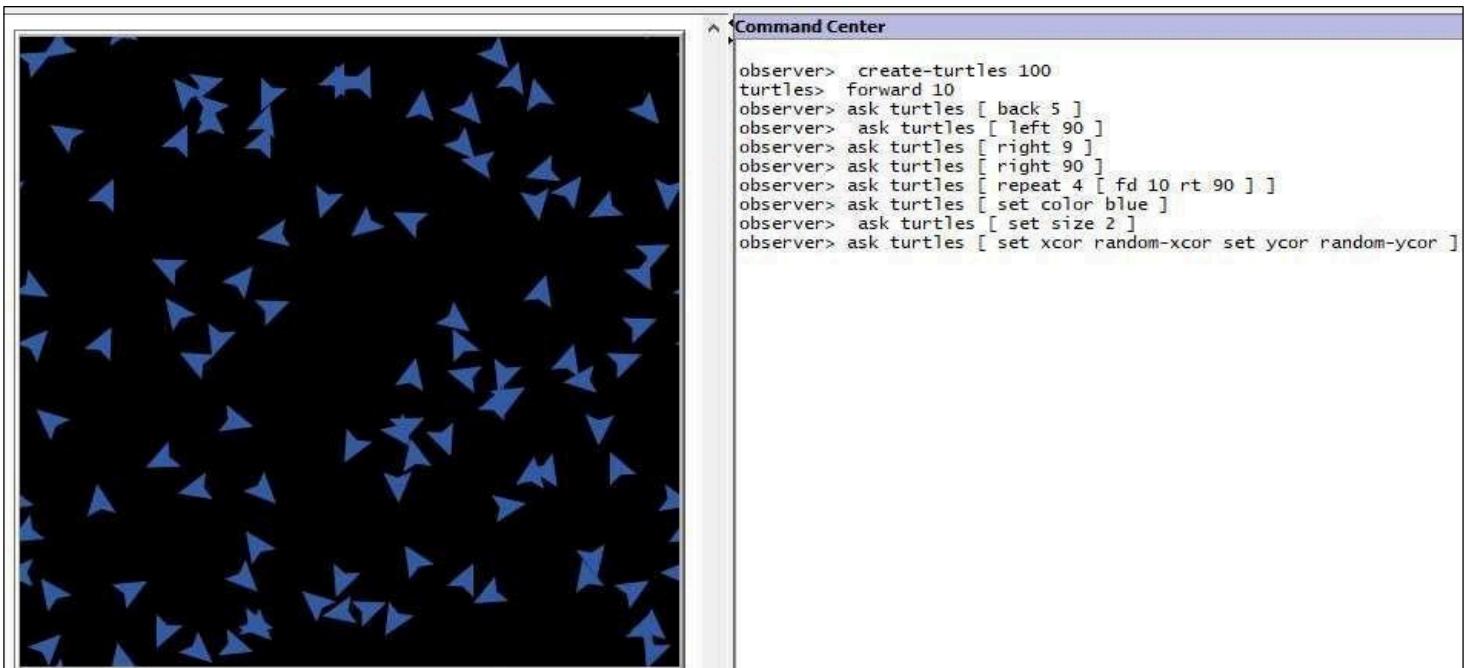
After running each command:

- Notice how the world changes visually.
- Observe movement, color, and size changes.
- Try running commands again with different numbers (e.g., create-turtles 200, fd 20).

### STUDENT TASK

observer> ask turtles

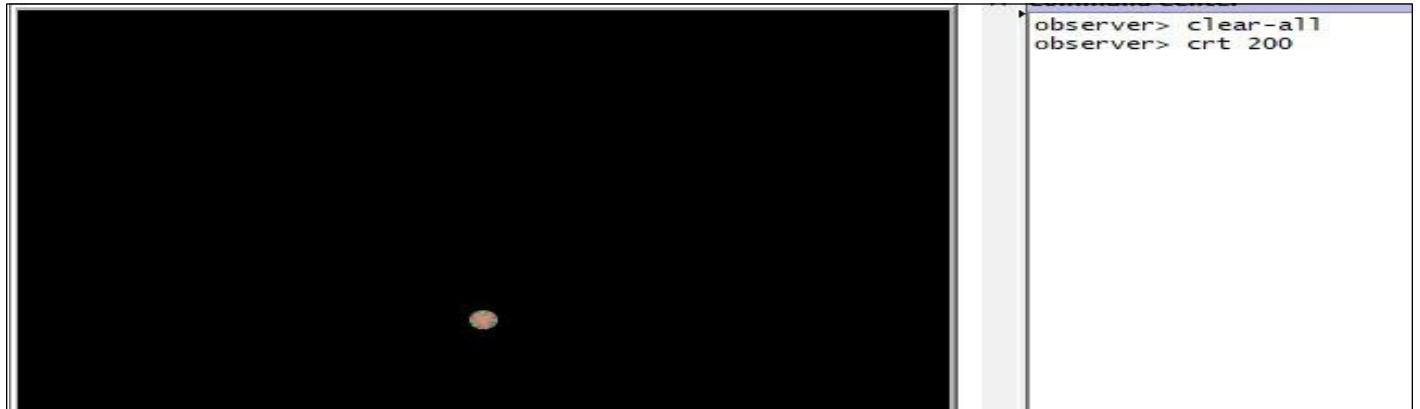
1. Execute each command listed in the procedure.



Command Center

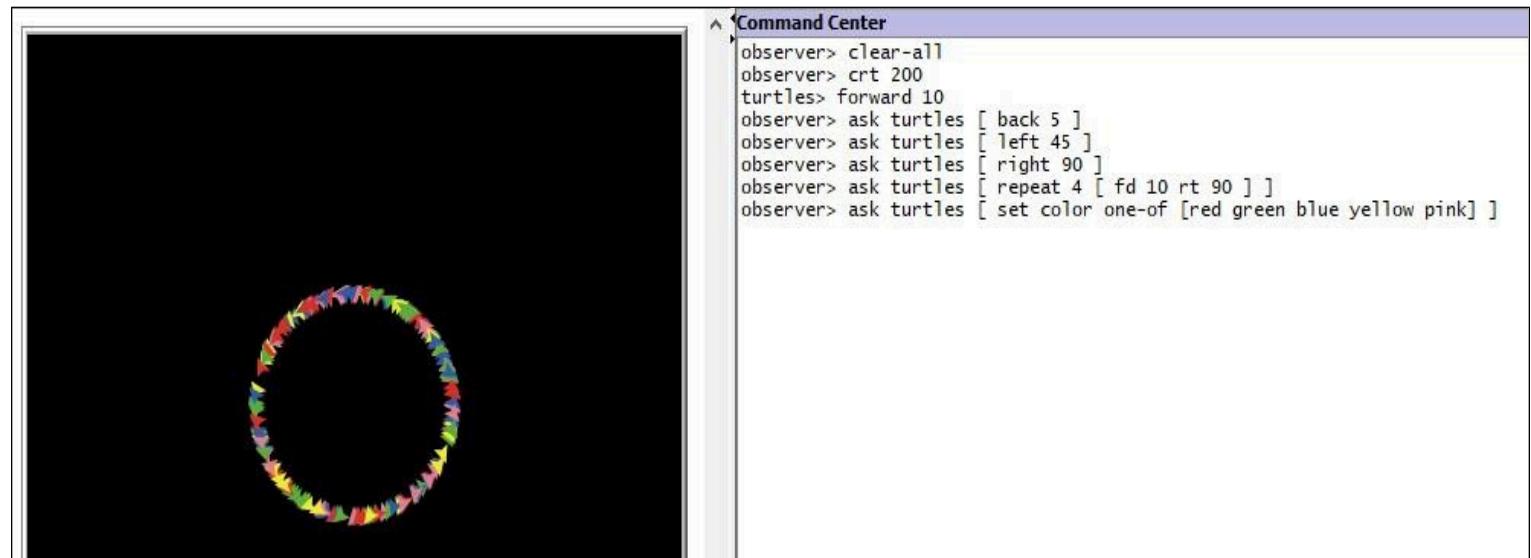
```
observer> create-turtles 100
turtles> forward 10
observer> ask turtles [ back 5 ]
observer> ask turtles [ left 90 ]
observer> ask turtles [ right 90 ]
observer> ask turtles [ right 90 ]
observer> ask turtles [ repeat 4 [ fd 10 rt 90 ] ]
observer> ask turtles [ set color blue ]
observer> ask turtles [ set size 2 ]
observer> ask turtles [ set xcor random-xcor set ycor random-ycor ]
```

2. Change the number of turtles (e.g., 50, 200) and observe behavior differences.



- 200 turtles created screen looks crowded with many overlapping dots.

3. Change colors using set color red, green, yellow, etc



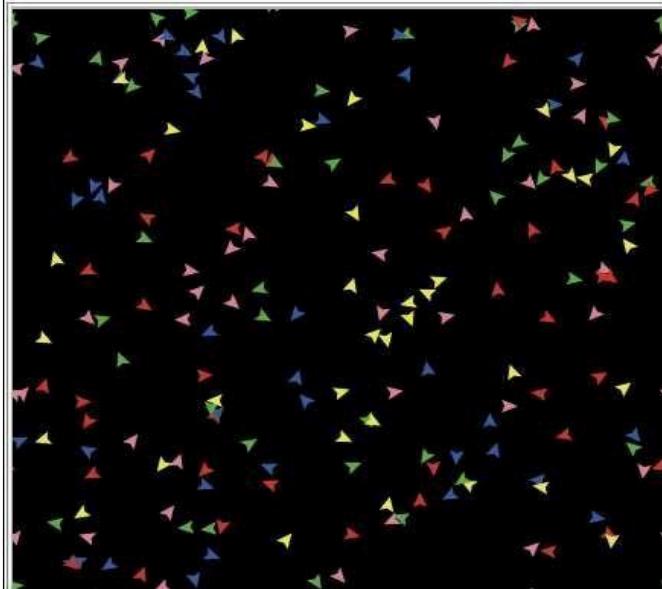
4. Try different movement patterns (e.g., repeat 6 [ fd 15 rt 60 ] for a hexagon).



```
observer> clear-all
observer> crt 200
turtles> forward 10
observer> ask turtles [ back 5 ]
observer> ask turtles [ left 45 ]
observer> ask turtles [ right 90 ]
observer> ask turtles [ repeat 4 [ fd 10 rt 90 ] ]
observer> ask turtles [ set color one-of [red green blue yellow pink] ]
observer> ask turtles [ repeat 4 [ fd 15 rt 90 ] ]
observer> ask turtles [ repeat 3 [ fd 20 rt 120 ] ]
observer> ask turtles [ repeat 6 [ fd 15 rt 60 ] ]
observer> ask turtles [ repeat 5 [ fd 25 rt 144 ] ]
```

patterns such as square, triangle, and hexagon.  
turned at specific angles.

## 5. Write observations in your lab notebook.



```
Command Center
observer> clear-all
observer> crt 200
turtles> forward 10
observer> ask turtles [ back 5 ]
observer> ask turtles [ left 45 ]
observer> ask turtles [ right 90 ]
observer> ask turtles [ repeat 4 [ fd 10 rt 90 ] ]
observer> ask turtles [ set color one-of [red green blue yellow pink] ]
observer> ask turtles [ repeat 4 [ fd 15 rt 90 ] ]
observer> ask turtles [ repeat 3 [ fd 20 rt 120 ] ]
observer> ask turtles [ repeat 6 [ fd 15 rt 60 ] ]
observer> ask turtles [ repeat 5 [ fd 25 rt 144 ] ]
observer> ask turtles [ set xcor random-xcor set ycor random-ycor ]
```

## OBSERVATION:

- 200 colorful turtles created successfully.
- Turtles moved forward, backward, and turned at different angles.
- Formed various geometric patterns like square, triangle, hexagon, and star.
- The world displayed a circular colorful pattern as turtles overlapped.

## POST-LAB QUESTIONS

**1. What is the purpose of the Command Center?**

The Command Center is used to type and run commands to control agents and the model.

**2. What does the command ask turtles [ ... ] do?**

The command ask turtles [ ... ] tells all turtles to perform the actions inside the brackets.

**3. How can you change a turtle's color and size?**

You can change a turtle's color with set color red and size with set size 2.

**4. What happens when you use random-xcor and random-ycor?**

Using random-xcor and random-ycor moves turtles to random positions on the world.

**5. What shape pattern is made by repeat 4 [ fd 10 rt 90 ]?**

The command repeat 4 [ fd 10 rt 90 ] makes a **square** pattern.

## LAB 3: DRAWING AND CONTROLLING TURTLES IN NETLOGO

### OBJECTIVE

- To learn how turtles can draw shapes using movement commands.
- To understand the use of pen, loops, and removing turtles (die).
- To practice giving multiple commands in a single line.

### LANGUAGE/TOOL

- **Tool:** NetLogo 6.4.0
- **Platform:** Windows
- **Environment:** Command Center

### THEORY

In NetLogo, turtles can move, draw, and erase on the world grid. When the pen is down, each turtle leaves a visible trail behind it, similar to drawing with a pen on paper. You can use loops such as repeat to create shapes and patterns. Finally, you can use the die command to remove turtles from the world.

### Important Concepts

Concept	Description
<b>Pen Control</b>	pen-down starts drawing; pen-up stops drawing.
<b>Repeat Loop</b>	Repeats a set of commands multiple times.
<b>clear-drawing</b>	Erases only the drawn lines (not the turtles).
<b>die</b>	Deletes a turtle from the simulation.
<b>Multiple Commands</b>	Can be written inside brackets [ ] separated by spaces.

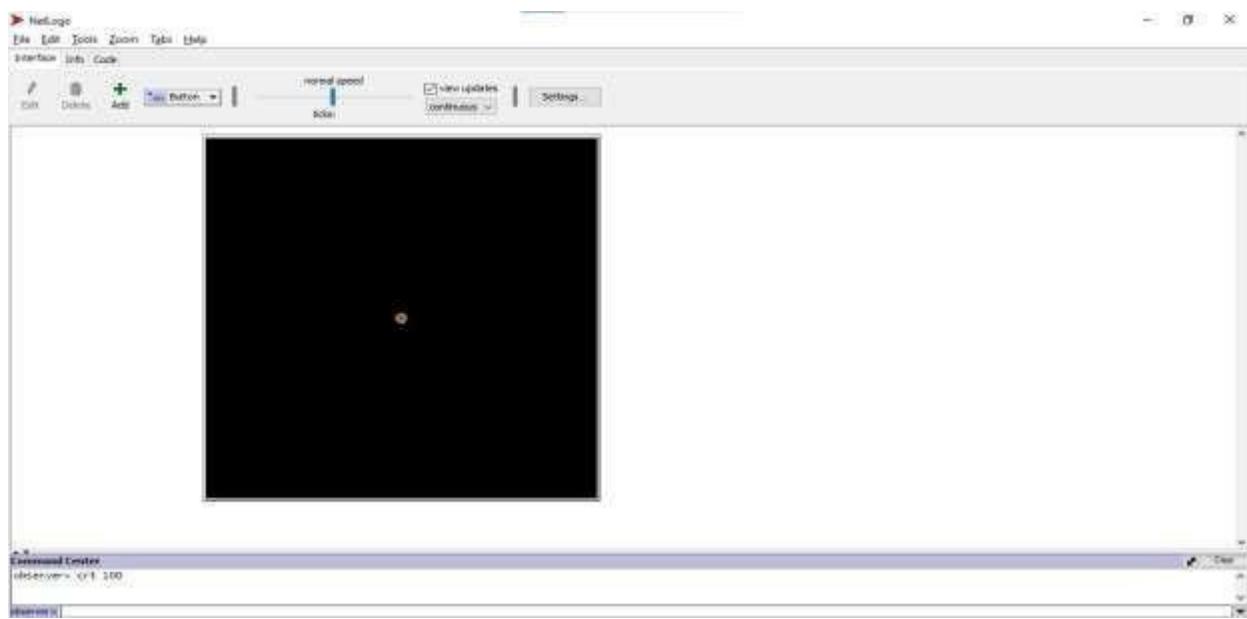
### LAB PROCEDURE

#### Step 1: Open NetLogo

1. Start NetLogo.
2. Make sure you are in the Command Center (bottom window).
3. Keep the default mode as observer.
- 4.

#### Step 2: Run Commands Step by Step

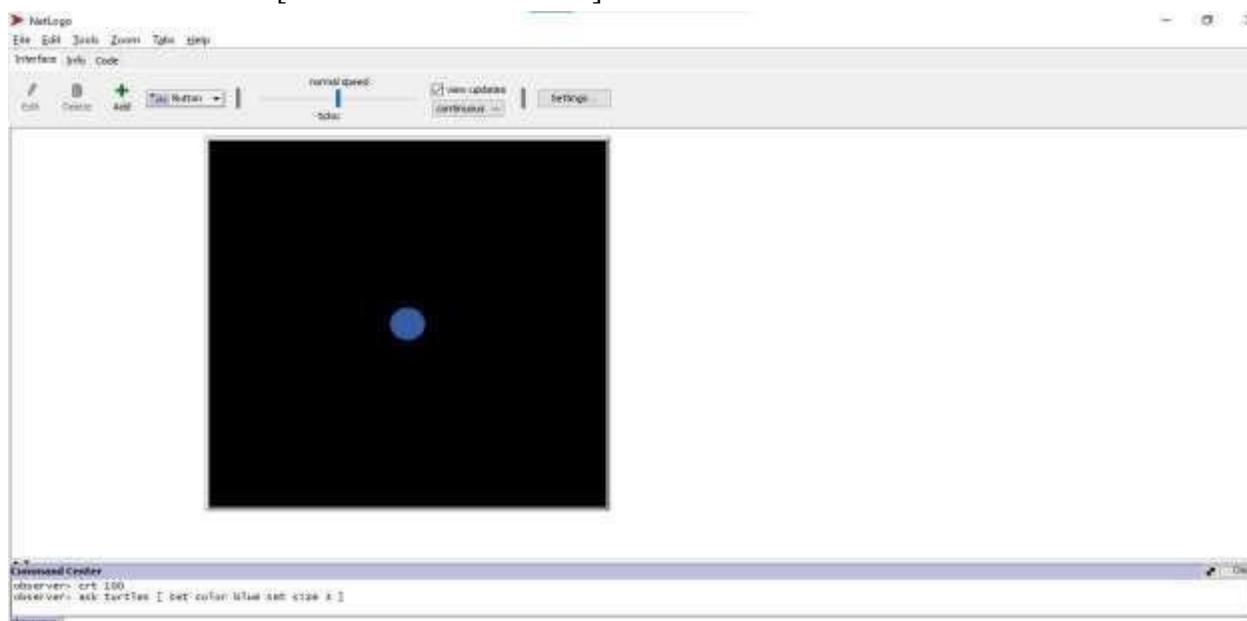
1. Create Turtles observer>crt100



► Creates 100 turtles at the center of the world.

## 2. Set Turtle Color and Size

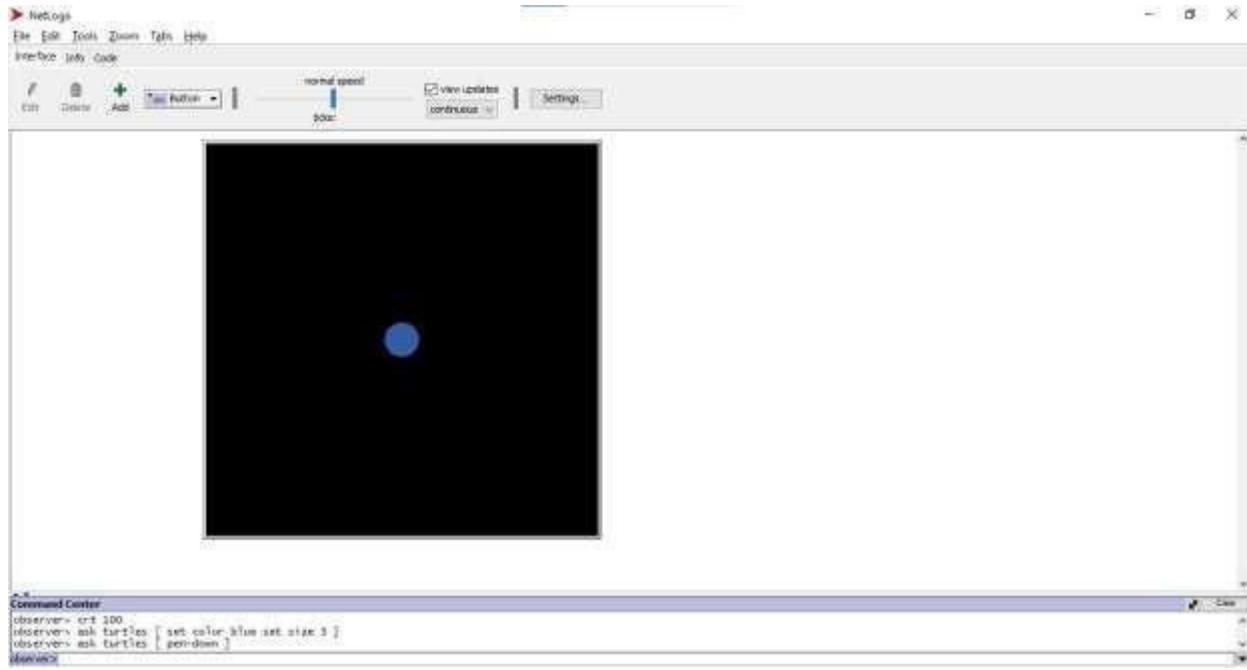
observer> ask turtles [ set color blue set size 3]



► Changes all turtles to blue and makes them larger (size 3).

## 3. Enable Pen Drawing

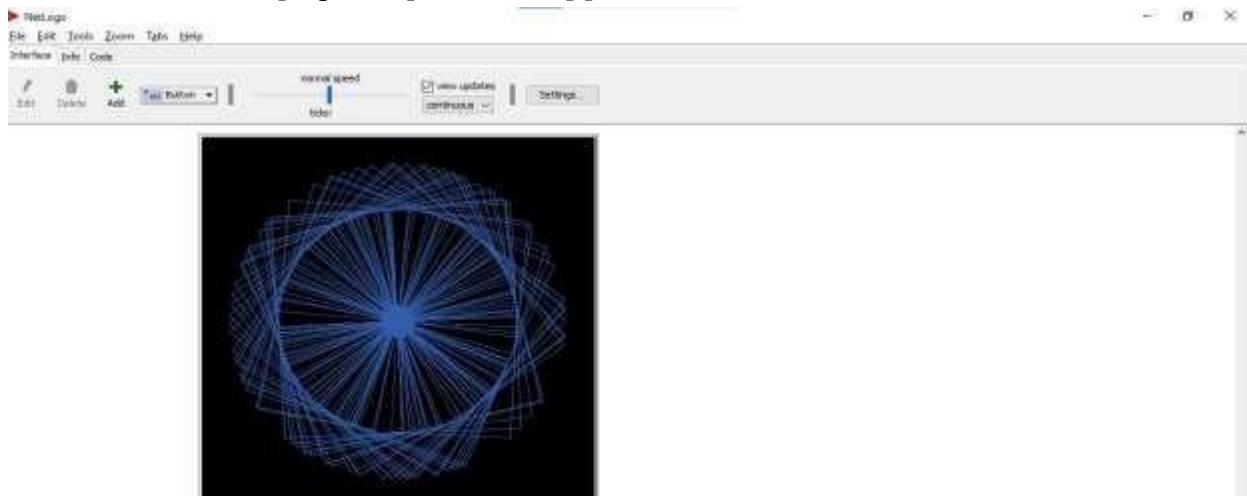
observer> ask turtles [ pen-down]



► Lowers the pen for all turtles — now their movement will leave trails.

#### 4. Draw a Square Shape

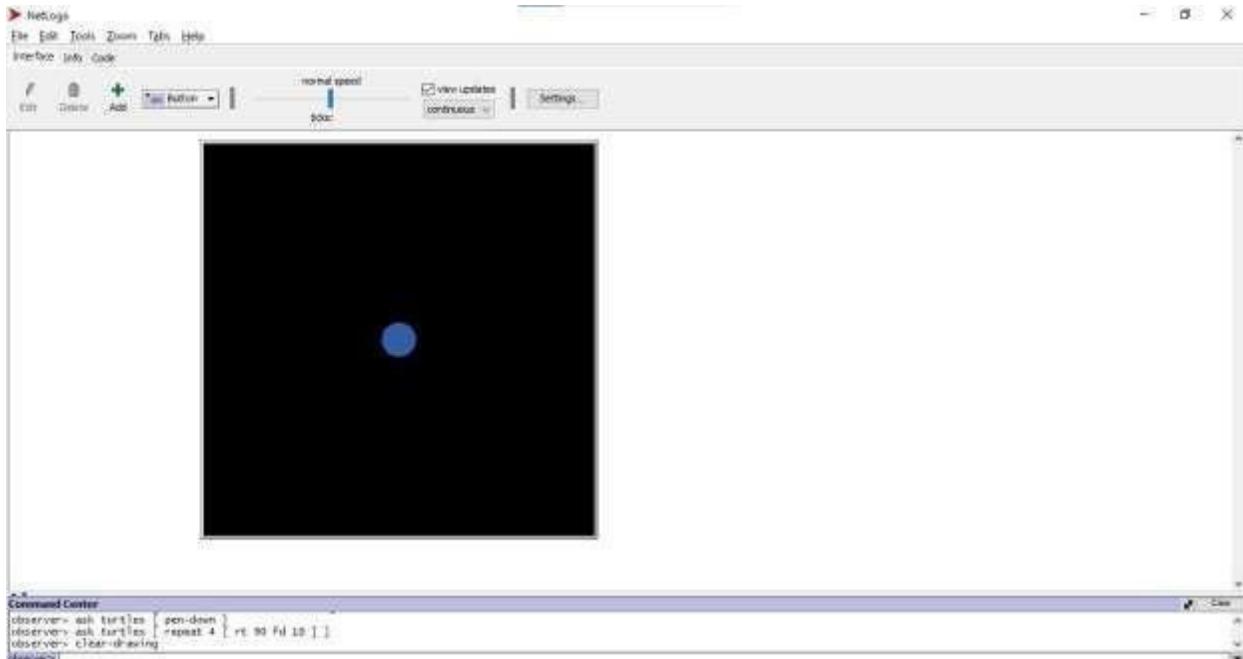
observer> ask turtles [ repeat 4 [ rt 90 fd 10 ] ]



observer> ask turtles [ set color blue set size 8 ]  
observer> ask turtles [ pen-down ]  
observer> ask turtles [ repeat 4 [ rt 90 fd 10 ] ]  
observer> clear-drawing

► Each turtle draws a small square by turning right 90° four times and moving forward 10 units each time.

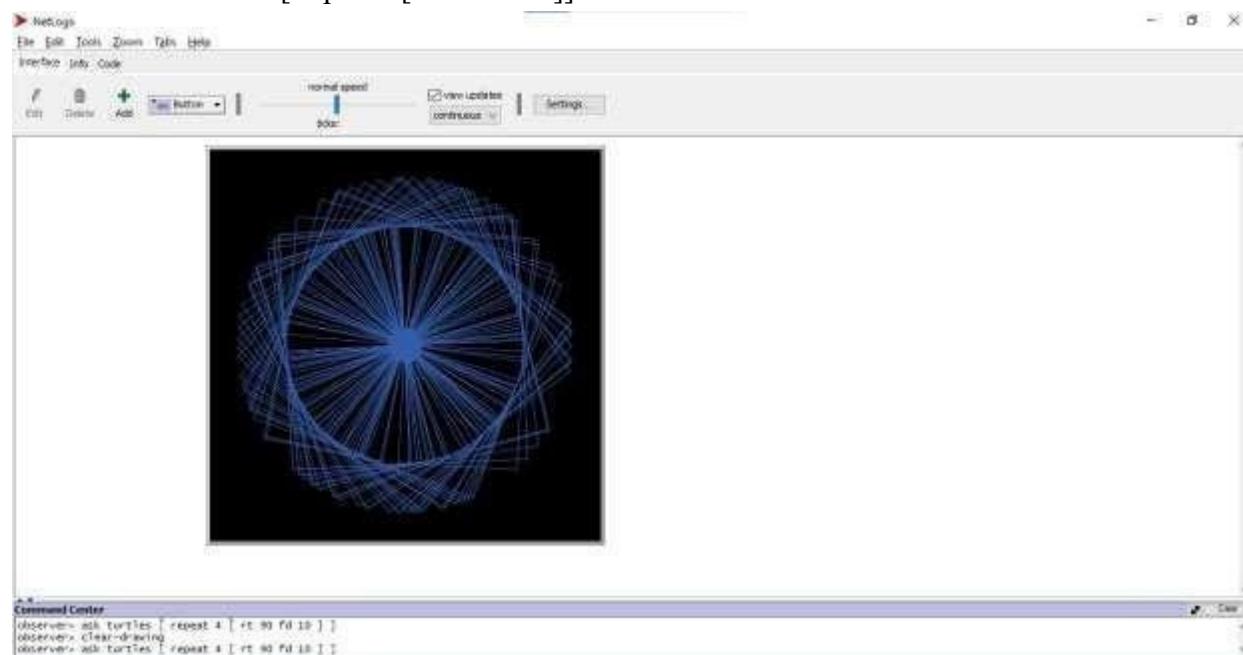
#### 5. Clear Only the Drawing observer> clear-drawing



- Erases all trails drawn by turtles but keeps the turtles themselves.

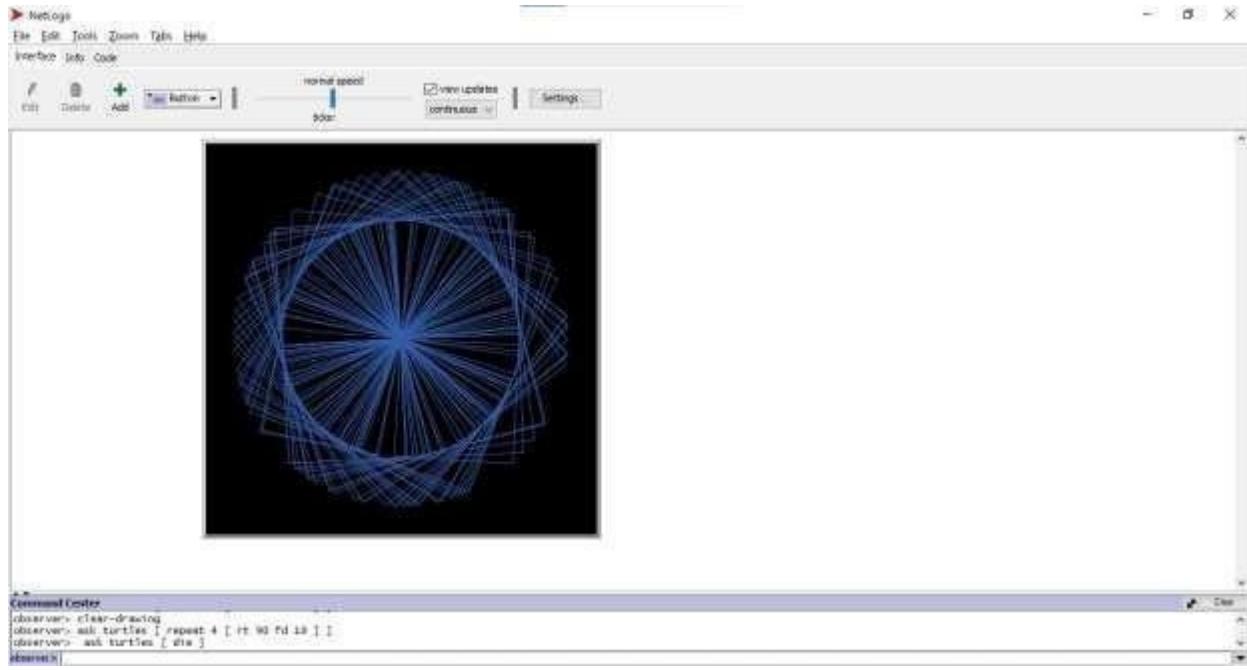
## 6. Redraw the Shape

observer> ask turtles [ repeat4 [ rt 90 fd 10]]



- Draws new squares again in the same way.

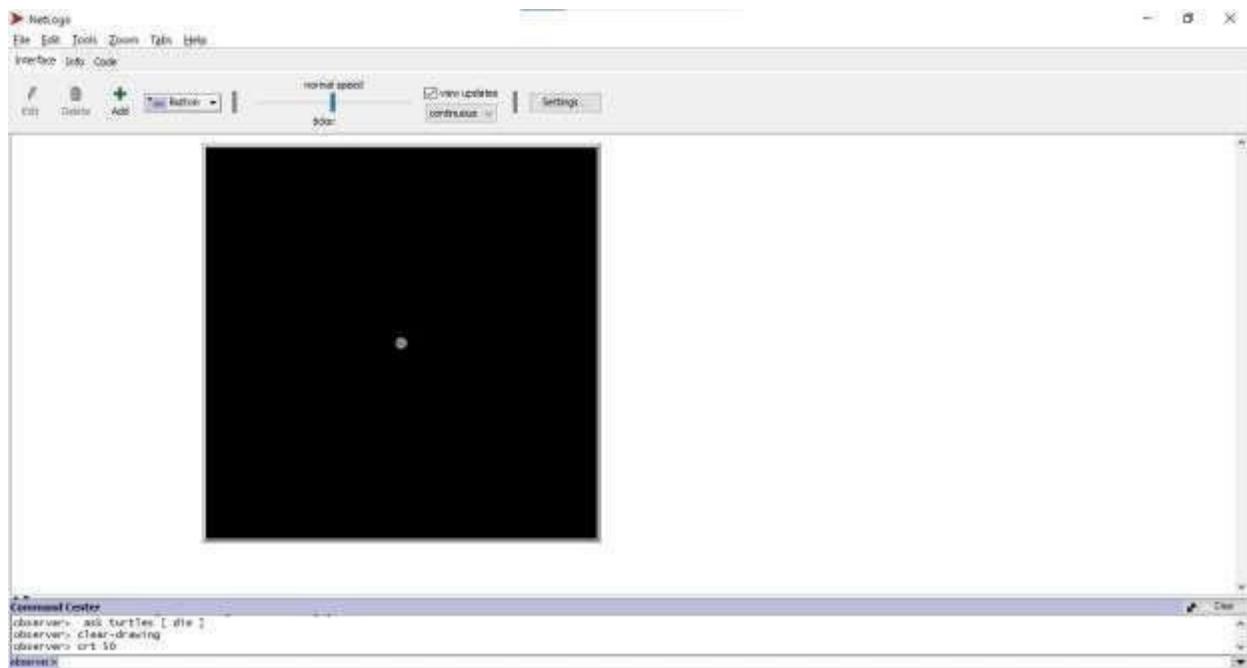
7. Delete All Turtles observer> ask turtles [ die]



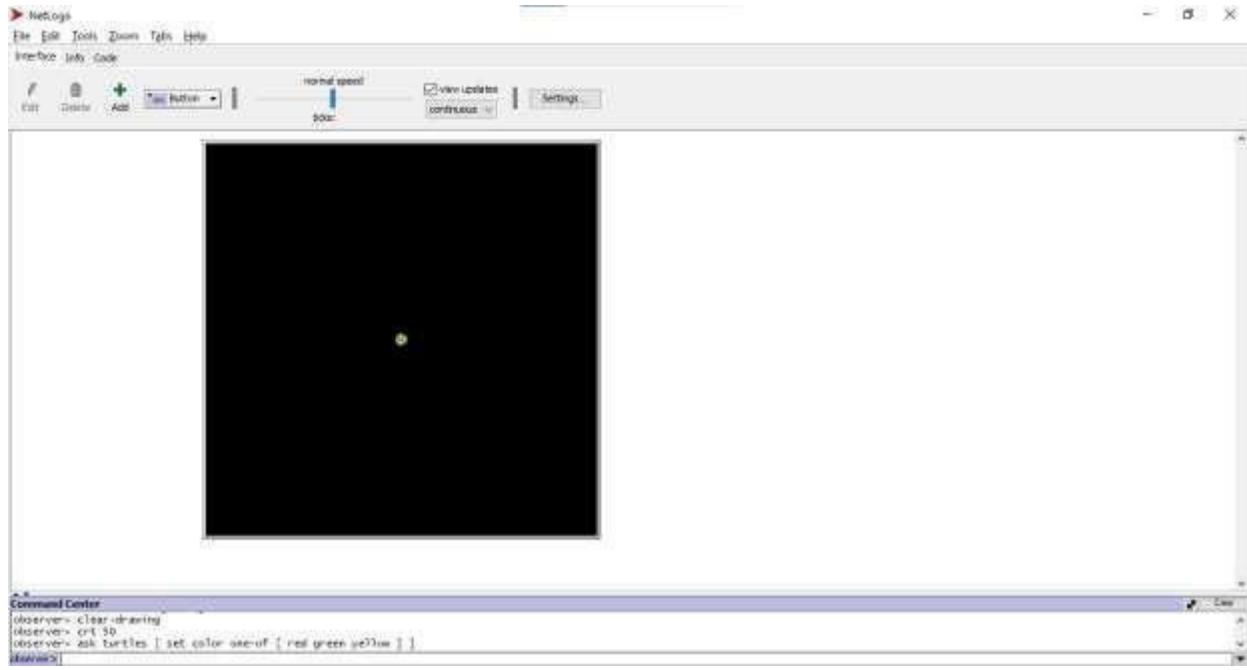
► Removes all turtles from the world.

## ADDITIONAL PRACTICE COMMANDS

### 8. Create New Colored Turtles

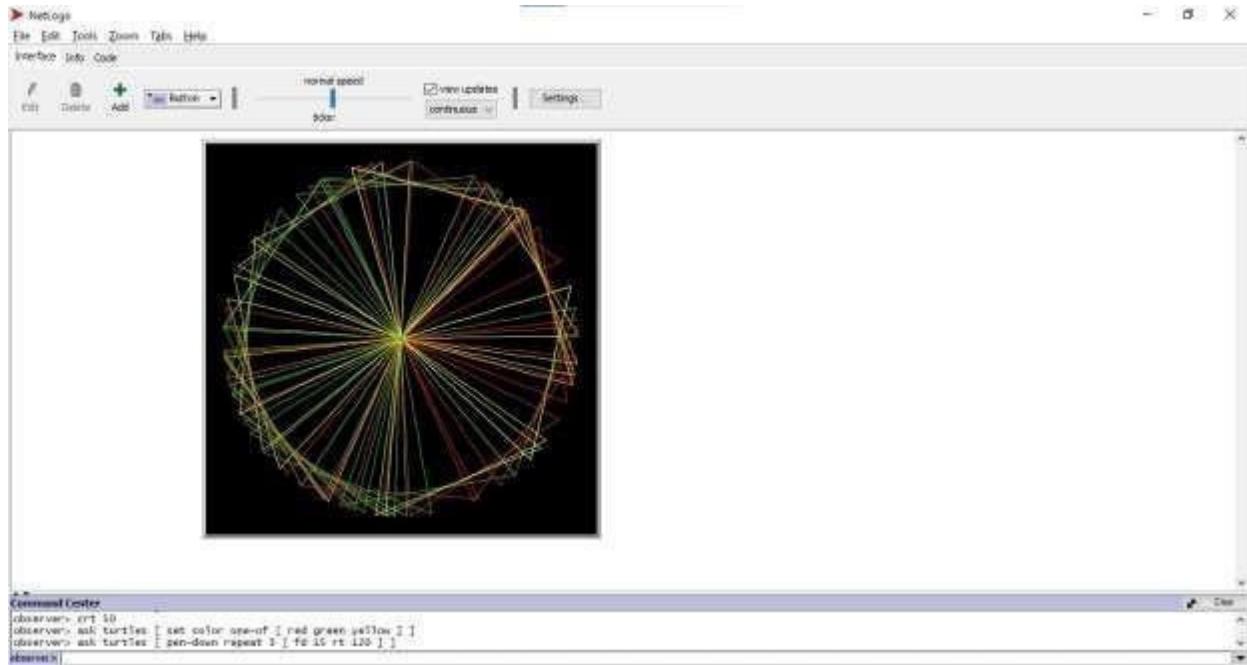


observer> ask turtles [ set color one-of [ red green yellow]]



► Creates 50 turtles with randomly selected colors.

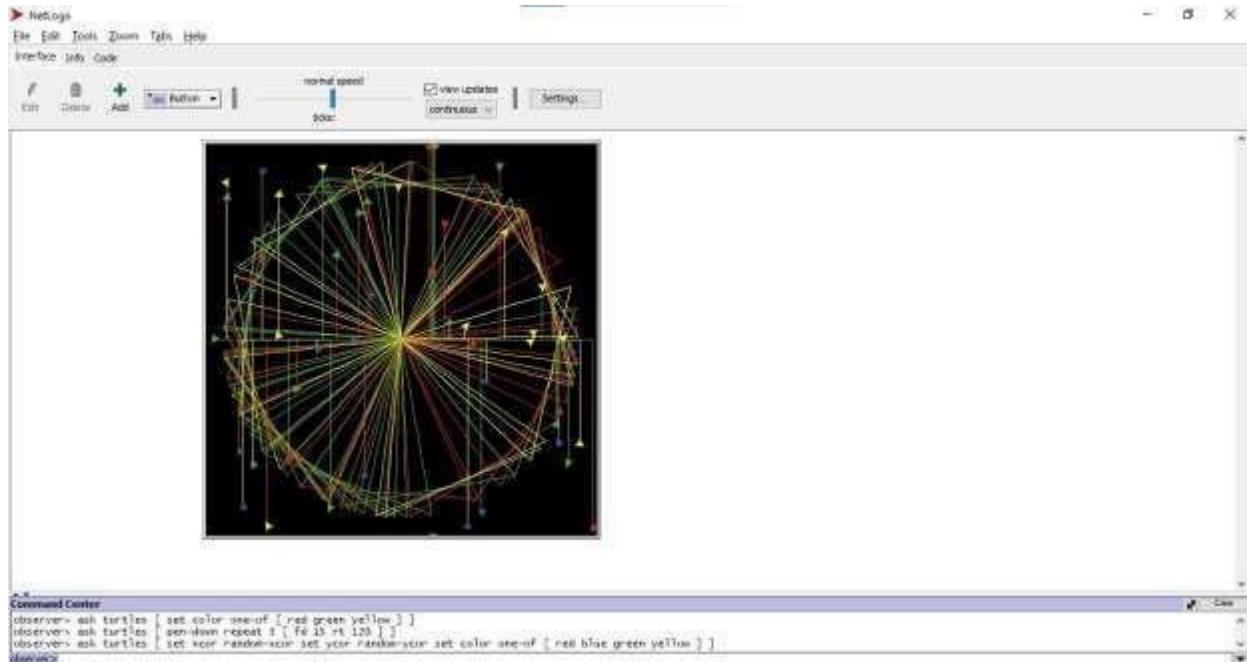
## 9. Draw Triangles observer> ask turtles [ pen-down repeat 3 [ fd 15 rt 120]]



► Each turtle draws a triangle.

## 10. Random Positions and Random Colors

observer> ask turtles [ set xcor random-xcor set ycor random-ycor set color one-of [ red blue green yellow ] ]



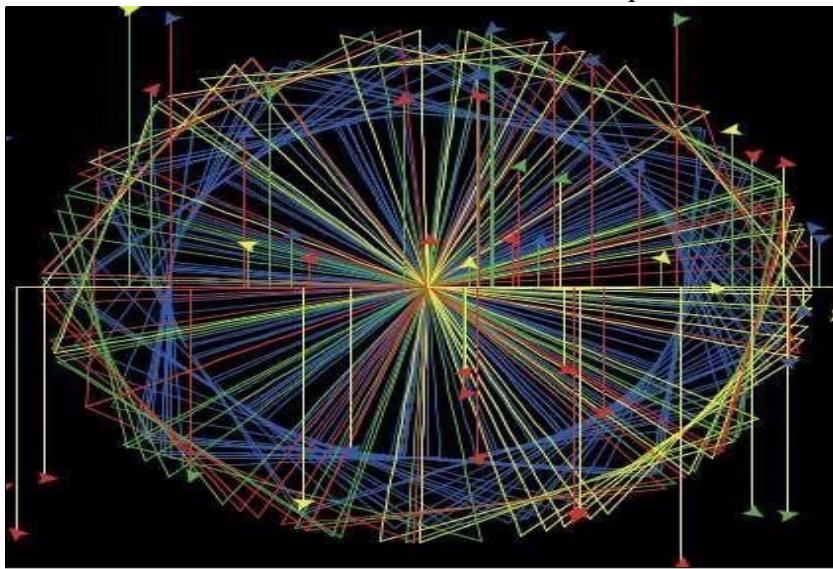
- Moves turtles to random locations and assigns them random colors.

## OBSERVATION

- Notice how each turtle draws its own figure.
- Observed differences when you clear the drawing vs. deleting turtles.
- Try running commands repeatedly and see how patterns form.

## STUDENT TASK

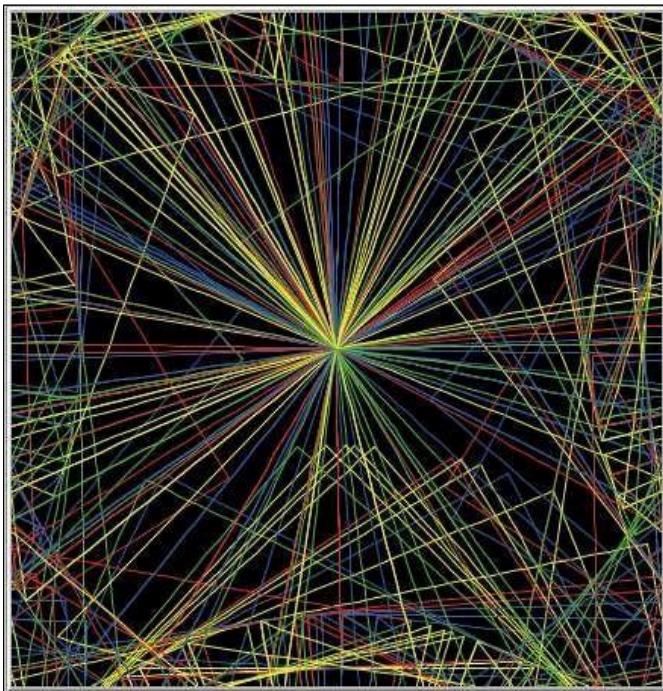
1. Execute all the commands listed above in sequence.



**Command Center**

```
observer> crt 100
observer> ask turtles [ set color blue set size 3 ]
observer> ask turtles [ pen-down ]
observer> ask turtles [ repeat 4 [ rt 90 fd 10 ] ]
observer> clear-drawing
observer> ask turtles [ repeat 4 [ rt 90 fd 10 ] ]
observer> ask turtles [ die ]
observer> crt 50
observer> ask turtles [ set color one-of [ red green yellow ] ]
observer> ask turtles [ pen-down repeat 3 [ fd 15 rt 120 ] ]
observer> ask turtles [ set xcor random-xcor set ycor random-ycor set color one-of [ red blue green yellow ] ]
```

2. Create your own pattern by combining commands (e.g., square + triangle).



```
observer> crt 50
observer> ask turtles [ set color one-of [red green blue yellow] set size 2 ]
observer> ask turtles [ pen-down ]
observer> ask turtles [ repeat 4 [ fd 20 rt 90 ] ]
observer> ask turtles [ repeat 3 [ fd 20 rt 120 ] ]
observer> ask turtles [ die ]
```

3. Use different colors and sizes for turtles.



4. Compare the effects of clear-all, clear-drawing, and ask turtles [ die ].

Command	Deletes Turtles?	Deletes Drawings?	Deletes Patches/World?
clear-all	Yes	Yes Yes No	Yes No No
clear-drawing	No		
ask turtles [ die ]	Yes		

5. Record your observations in your notebook.

**Turtle Pattern:** Custom pattern (square + triangle) created successfully.

**Colors & Sizes:** Different colors and sizes made turtles easily distinguishable.

**Spreading Turtles:** Turtles spread apart clearly, pattern visible.

**Clear Commands:**

- clear-all → Everything cleared.
- clear-drawing → Drawing erased, turtles remain.
- ask turtles [ die ] → Turtles gone, drawings remain.

## POST-LAB QUESTIONS ANSWERS

### 1. What is the purpose of the pen-down command?

It allows turtles to draw lines as they move. Without it, turtles move without leaving a trail.

### 2. What is the difference between clear-drawing and clear-all?

- clear-drawing → **erases only the drawings** , turtles and patches remain.

- clear-all → **resets everything** , including turtles, drawings, and patches.

### **3. How many times does the loop run in repeat 4 [ rt 90 fd 10 ]?**

The loop runs **4 times**, executing rt 90 fd 10 each time.

### **4. What happens when ask turtles [ die ] is executed?**

All turtles are removed from the world, but drawings and patches remain.

### **5. How can you make turtles draw a triangle or hexagon pattern?**

Use **loops** with fd (forward) and rt/lt (turn) commands:

o Triangle → repeat 3 [ fd length rt

120 ] o Hexagon → repeat 6 [ fd

length rt 60 ] **LAB4:WORKINGWITH**

**PATCHES, TURTLES, AND LINKS IN**

**NETLOGO**

## **OBJECTIVE**

- To learn how to manipulate patches and their colors.
- To explore turtle positioning using random coordinates.
- To understand how turtles can interact and connect using links.
- To practice combining multiple commands for complex visuals.

## **LANGUAGE/TOOL**

- **Tool:** NetLogo 6.4.0
- **Platform:** Windows
- **Environment:** Command Center

## **THEORY**

In NetLogo, the world is made up of patches (background cells) and turtles (moving agents).

Patches can change color or hold values, while turtles can move, draw, and form links to represent relationships between them.

- **Patches:** Stationary cells identified by coordinates (pxcor, pycor).
- **Turtles:** Mobile agents that can act independently or in groups.
- **Links:** Connections between turtles, useful for visualizing networks.

By using commands like set pc当地, setxy, and create-link-with, we can simulate real-world systems such as communication networks or spatial environments.

## **IMPORTANT CONCEPTS**

<b>Concept</b>	<b>Description</b>
<b>Patch Coloring</b>	Patches can be colored based on mathematical formulas or turtle interaction.
<b>Random Positioning</b>	<code>setxy random-xcor random-ycor</code> places turtles at random world coordinates.
<b>Links</b>	Connect turtles to form network structures.
<b>facexy</b>	Rotates turtles to face a specific coordinate point.
<b>MultipleCommands</b>	Combined inside [ ] for sequential execution.

## LAB PROCEDURE

### Step 1: Open NetLogo

1. Start NetLogo.
2. Ensure you are in the Command Center (bottom window).
3. Keep the mode as observer.

### Step 2: Run Commands Step by Step

#### 1. Color Patches by Coordinates

```
observer> ask patches [ set pcolor pxcor * pycor ]
```



- Colors each patch using the product of its X and Y coordinates, creating a gradient effect.

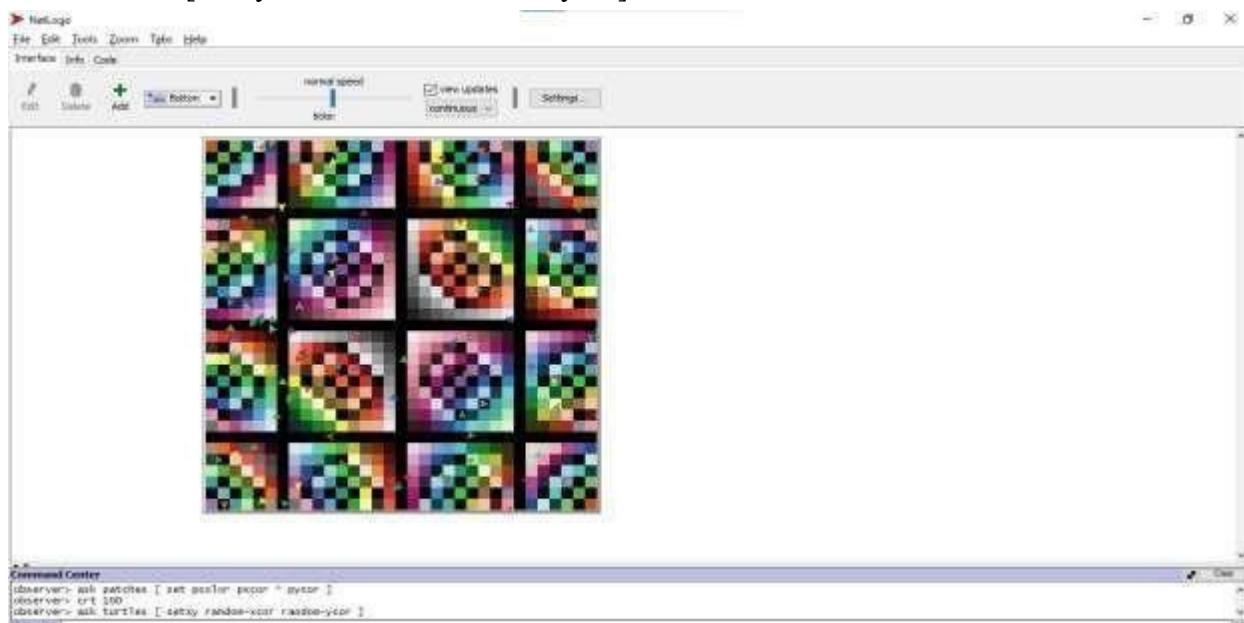
#### 2. Create 100 Turtle

```
observer> crt 100
```



► Generates 100 turtles at the center of the world.

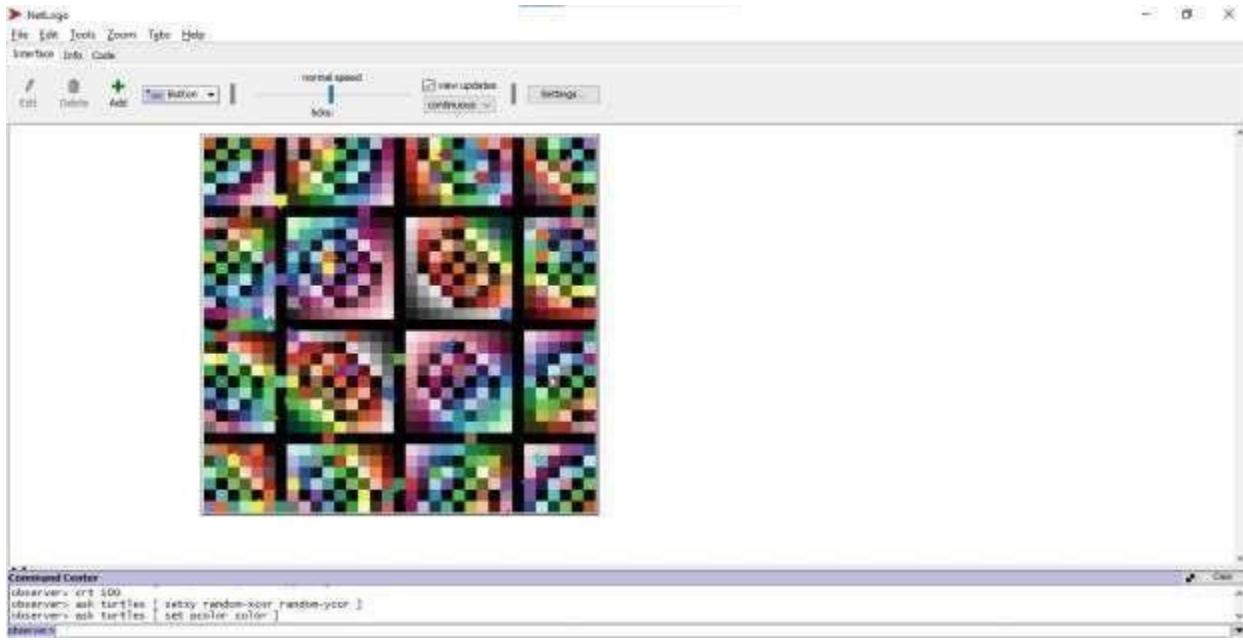
3. **Move Turtles to Random Locations** observer> ask turtles [ setxy random-xcor random-ycor]



► Randomly scatters turtles across the world.

4. **Change the Patch Color Under Each Turtle**

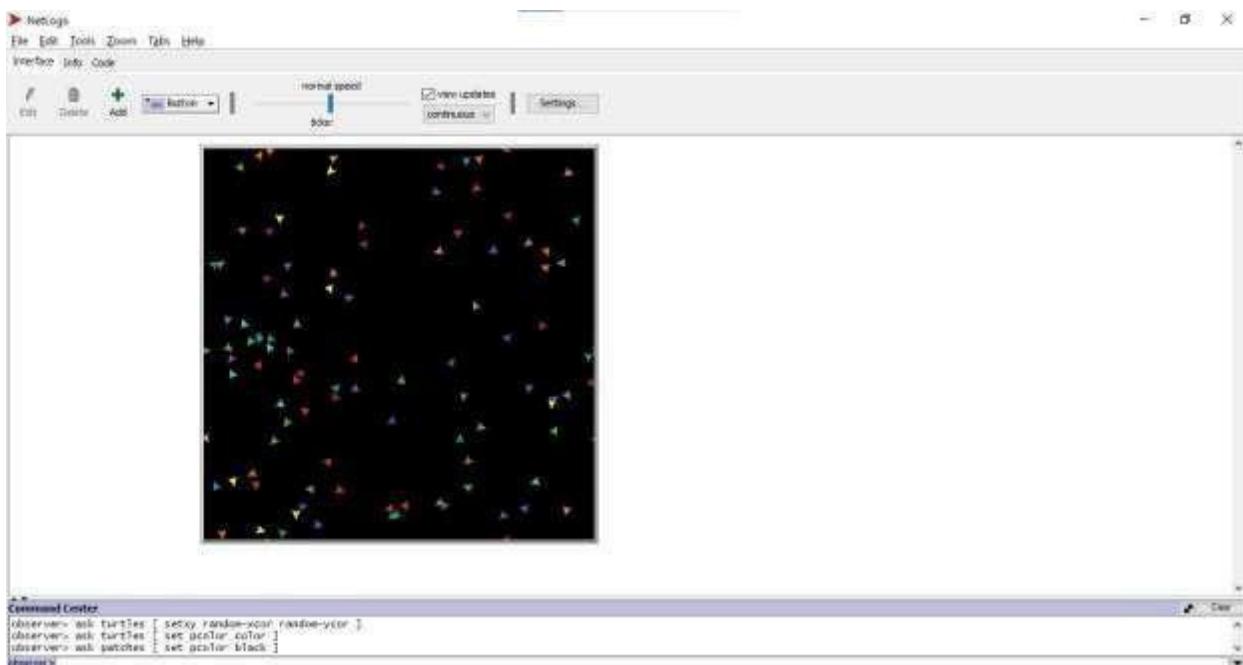
observer> ask turtles [ set pcolor color]



- Each turtle colors the patch it stands on using its own color.

## 5. Reset All Patches to Black

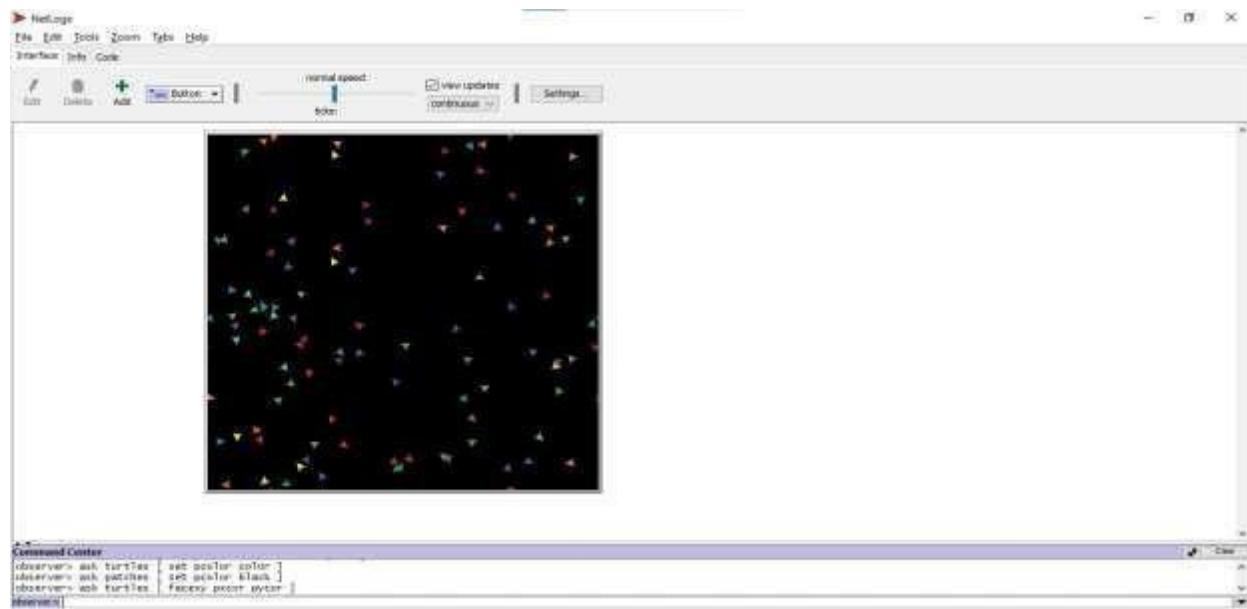
```
observer> ask patches [ set pcolor black ]
```



- Turns all patches black while turtles remain visible.

## 6. MakeTurtlesFaceTheirOwnCoordinates

```
observer> ask turtles [ facexy pxcor pycor ]
```



- Orients each turtle toward its own (x, y) location.

observer>

## 5. Create Links Between Turtles

ask turtles [ create-link-with one-of other turtles

]



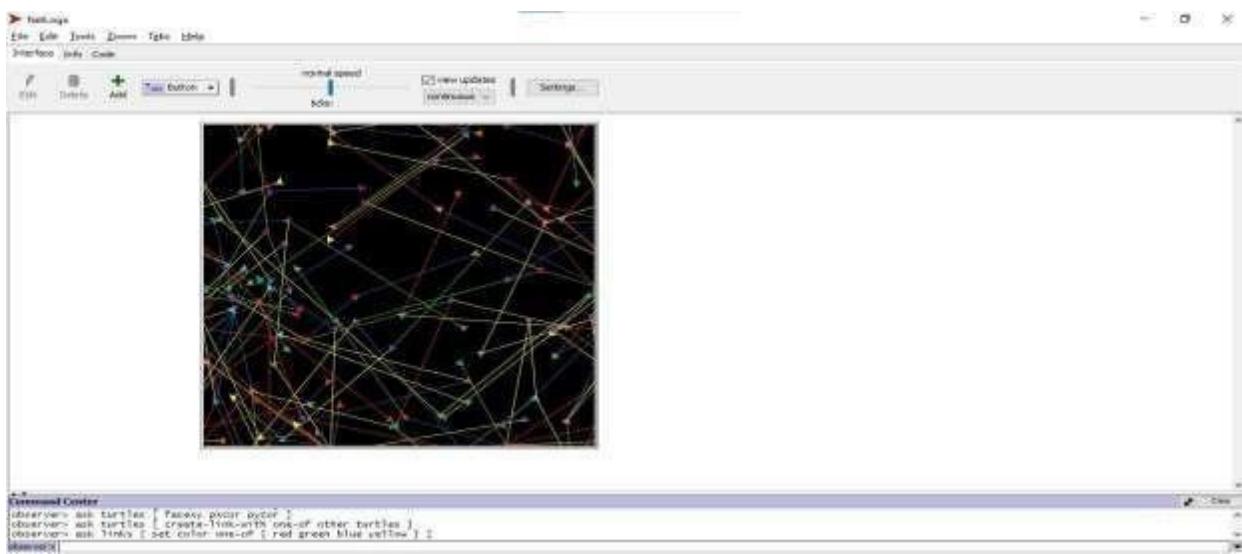
► Each turtle randomly connects to another turtle, forming a network pattern.

## Step 3: Additional Practice Commands 8. Color the Links

Randomly observer> ask links [ set color one-of [ red green

blue yellow ] ]

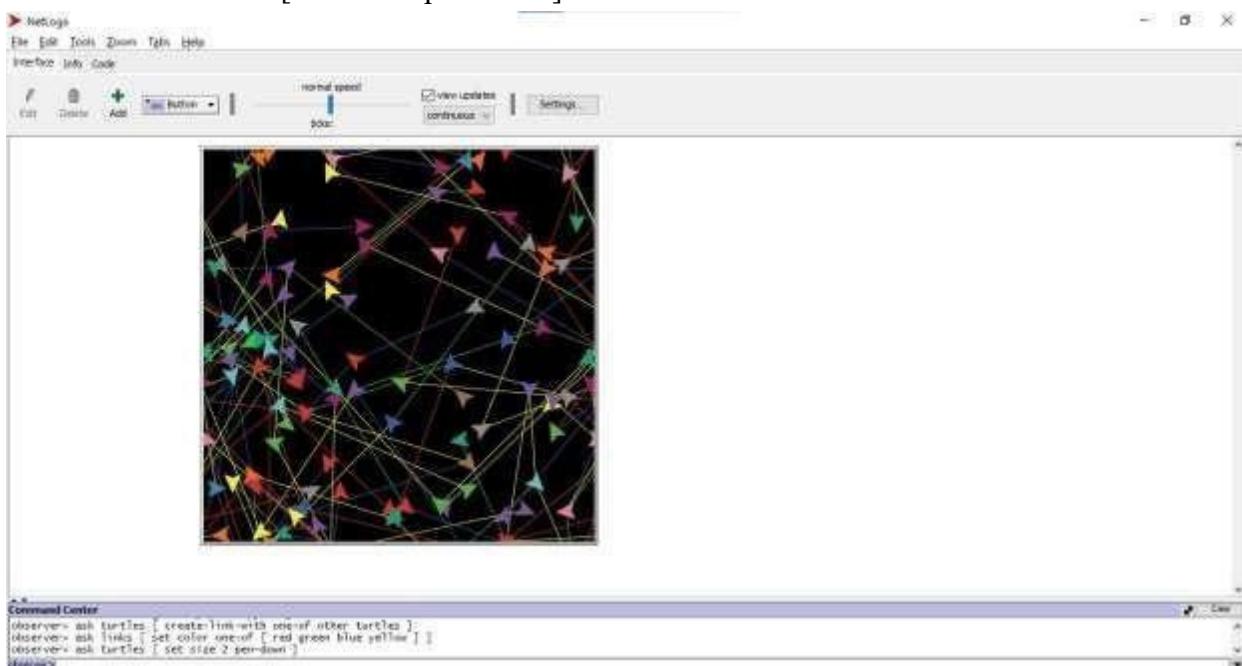
observer>



- Assigns random colors to all links.

## 9. Resize and Enable Drawing

ask turtles [ set size 2 pen-down]

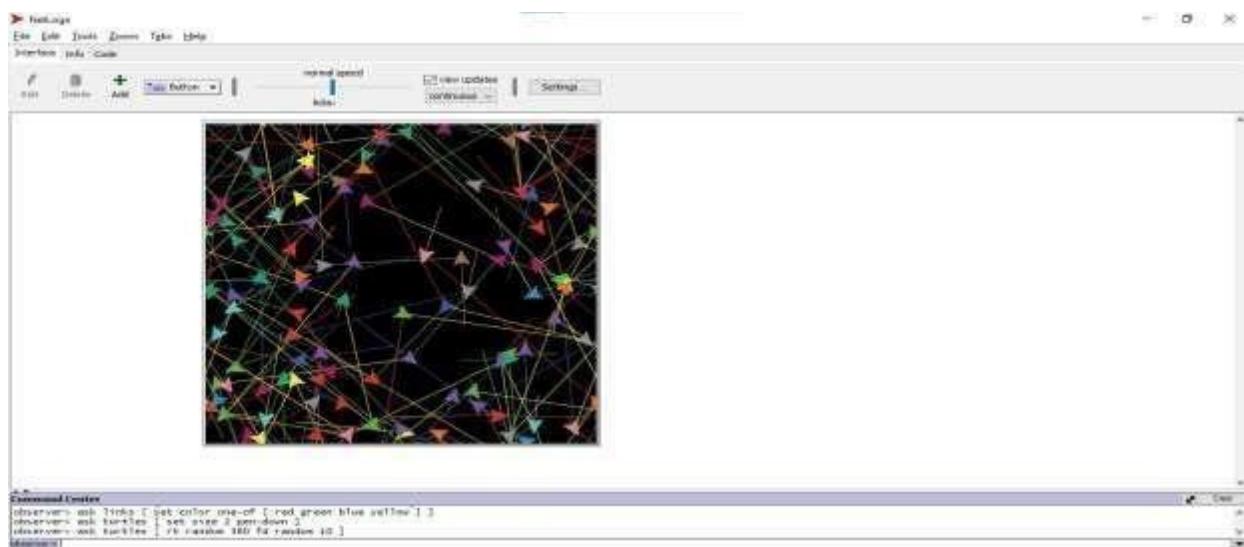


- Increases turtle size and allows drawing as they move.

## 10. Move Turtles Randomly

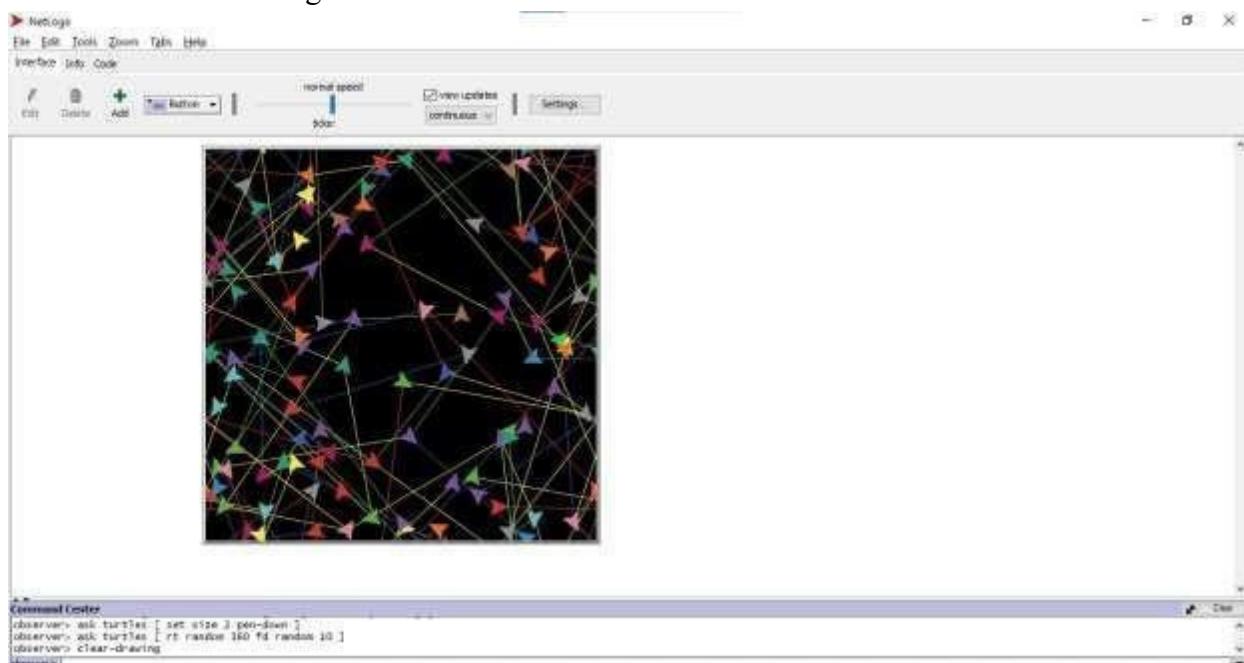
observer> ask turtles [ rt random 360 fd random 10 ]

observer>



- Moves each turtle forward randomly to create abstract drawings.

## 11. Clear Only the Drawing clear-drawing



- Erases trails but keeps turtles and links intact.

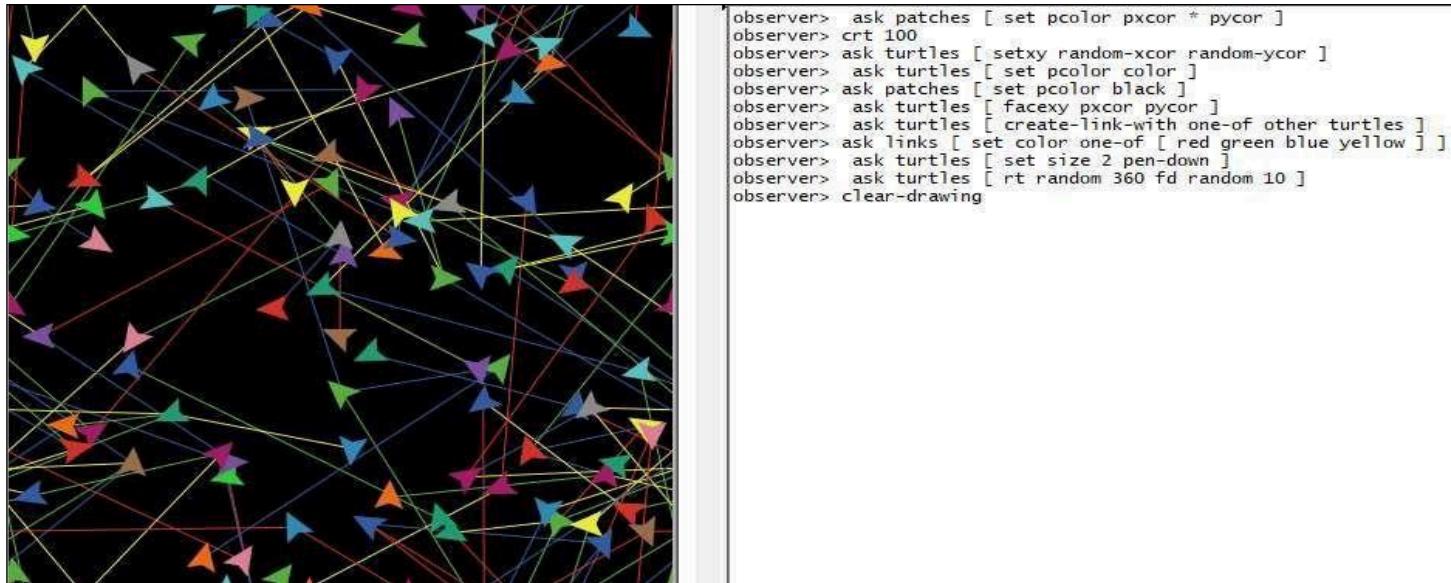
observer>

## OBSERVATION

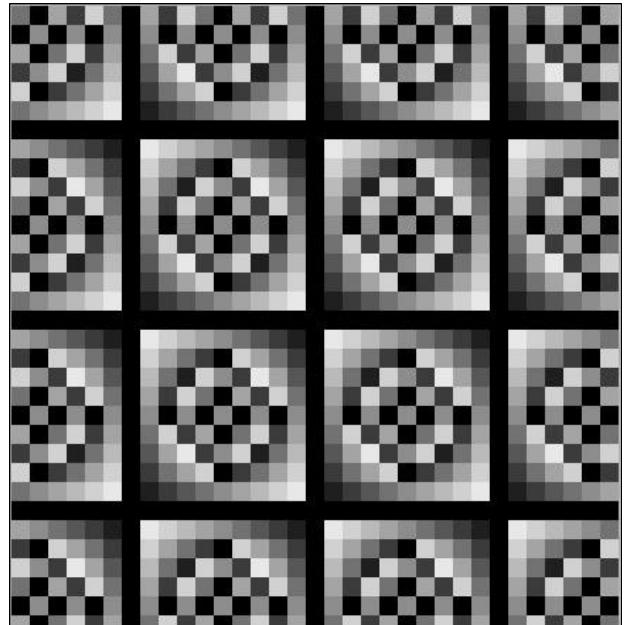
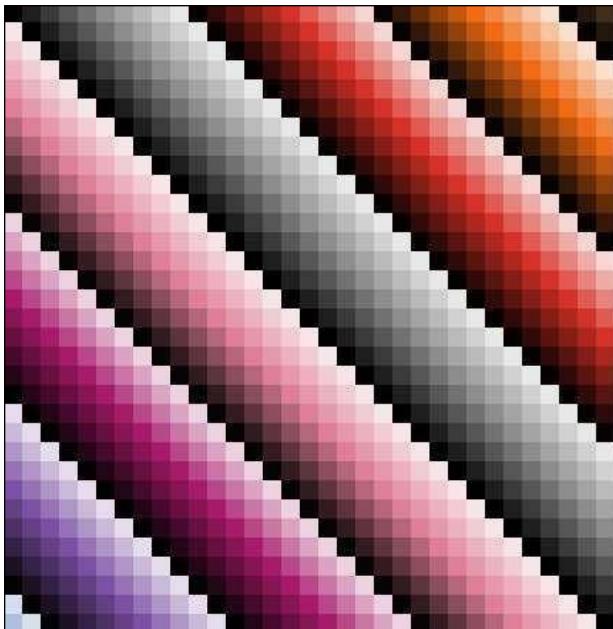
- Observe how patch color patterns change.
- Notice the random distribution of turtles and link formations.
- Experiment with the number of turtles (crt 50, crt 200) and observe the differences.

## STUDENT TASK

1. Run all the commands in sequence.

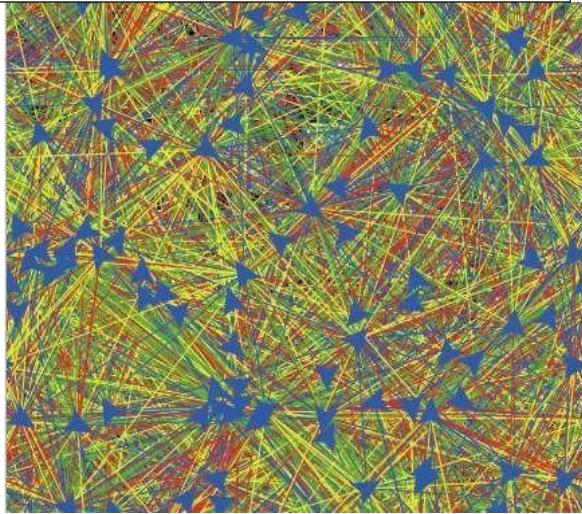


2. Modify patch coloring formulas (e.g., pxcor + pycor).



instead

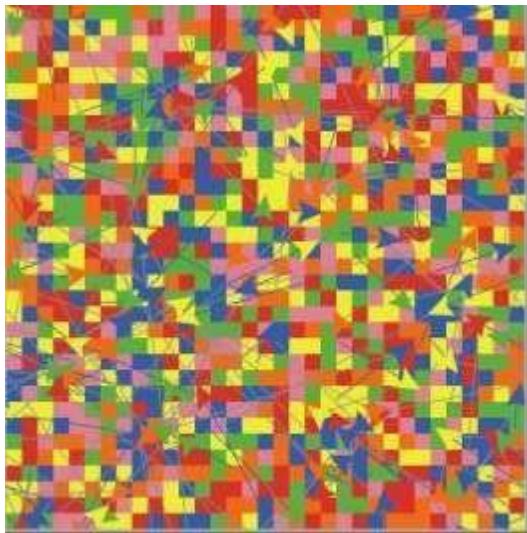
```
observer> ask patches [ set pcolor pxcor  
+ 3p.y Tcroyr c]onnecting turtles using  
create-links-with
```



```
observer> ask patches [ set pcolor (pxcor  
*pyacteo-rl)inmkowd i1th0.]  
ofcre
```

```
observer> crt 100  
observer> ask turtles [ setxy random-xcor random-ycor ]  
observer> ask turtles [set color blue]  
observer> ask turtles [set size 2]  
observer> ask turtles [ pen-down ]  
observer> ask turtles [rt random 360 fd random 10]  
observer> ask turtles [ create-links-with other turtles ]  
observer> ask links [ set color one-of [ red green blue yellow ] ]  
observer> clear-drawing
```

#### 4. Apply different colors to patches and links.

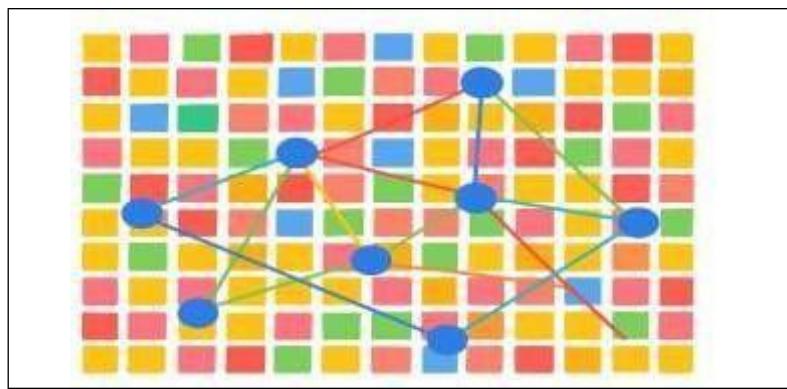


```
observer> ask patches [set pcolor one-of [ red green blue yellow orange pink ]]  
observer> crt 100  
turtles> setxy random-xcor random-ycor  
turtles> set color blue  
turtles> set size 2  
turtles> pen-down  
turtles> rt random 360 fd random 10  
turtles> create-link-with one-of other turtles  
turtles> set color one-of [ red green blue yellow orange ]
```

#### 5. Sketch and describe the final visual pattern.

##### Final Visual Pattern:

The patches form a diagonal color gradient based on their coordinates. Turtles are randomly scattered, varying in size and color, appearing as bright dots on the background. Any links between turtles create simple networks, resulting in a colorful, semi-random pattern across the NetLogo world.



## **POST-LAB QUESTIONS ANSWER**

### **1. What is the difference between a patch and a turtle?**

**Patch:** A stationary square in the NetLogo world; it forms the background grid and can have its own color and properties.

**Turtle:** A mobile agent that can move around the world, change color, size, and interact with other turtles or patches.

### **2. What does facexy do?**

It makes a turtle **face a specific coordinate** (x, y) in the world, so its heading points toward that location.

### **3. How are random-xcor and random-ycor useful?**

They give **random coordinates** within the world boundaries, which is useful for **placing turtles randomly** on the patches.

### **4. What is the effect of create-link-with?**

It creates a **link (line)** between two turtles, showing a connection or relationship.

This can be used to form networks or patterns.

### **5. How does clear-drawing differ from clear-all?**

**clear-drawing:** Removes only the **lines and shapes drawn** by turtles; turtles and patches remain.

**clear-all:** Resets the **entire world**, removing turtles, links, drawings, and resetting patches to default.

## **LAB 5: CREATIVE PATTERN GENERATION USING TURTLES AND PATCHES**

### **OBJECTIVE**

- To explore how turtles and patches can work together to create colorful and dynamic patterns.
- To understand advanced turtle commands including linking, color gradients, and movement control.
- To observe how randomization can produce visually unique simulations.

## LANGUAGE/TOOL

- **Tool:** NetLogo6.4.0
- **Platform:** Windows
- **Environment:** Command Center

## THEORY

In NetLogo, the world is made up of two main types of agents:

- **Turtles:** movable agents that can draw, move, and interact with each other.
- **Patches:** fixed squares that make up the background and can change color or display gradients.

By combining turtle movements, patch coloring, and linking commands, we can generate complex and attractive graphical patterns that help us understand agent-based interactions.

## IMPORTANT CONCEPTS

Concept	Description
<b>Randomization</b>	Adds variety to positions, colors, or directions.
<b>Links</b>	Connects turtles to show relationships or networks.
<b>scale-color</b>	Creates color gradients on patches or agents.
<b>Loops</b>	Repeats actions multiple times to form shapes or movements.
<b>Pen Control</b>	When down, turtles draw lines as they move.

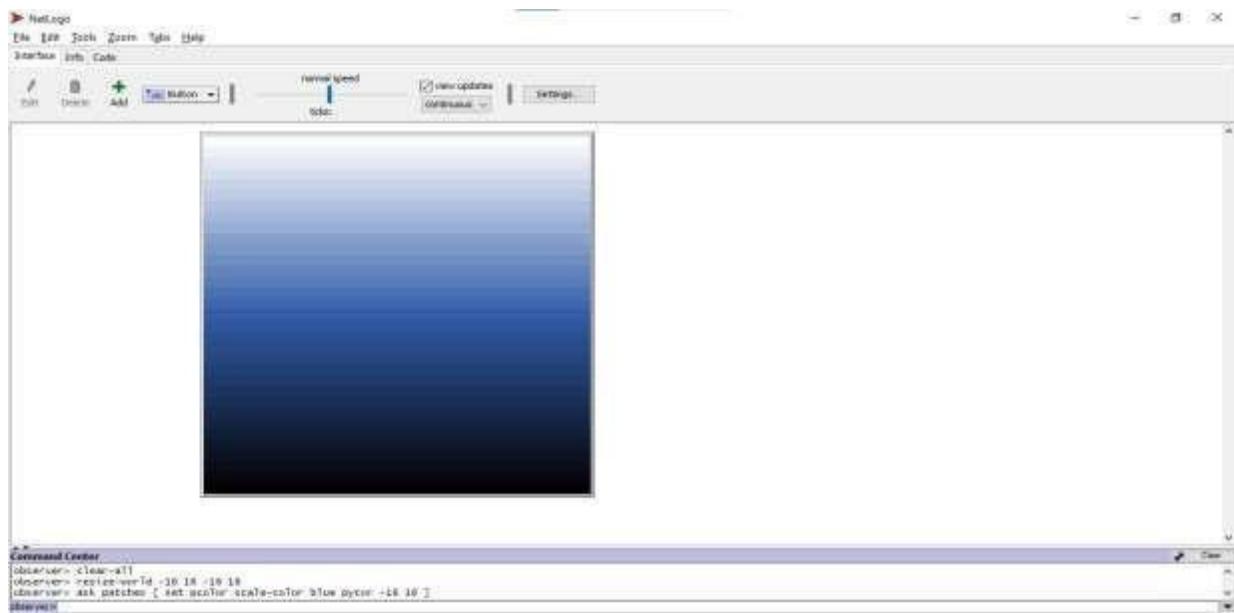
## LAB PROCEDURE

### Step 1: Open NetLogo

1. Launch **NetLogo**.
2. Go to the **Command Center** at the bottom of the screen.
3. Make sure you are in the **observer** view. **Step 2: Prepare the World**

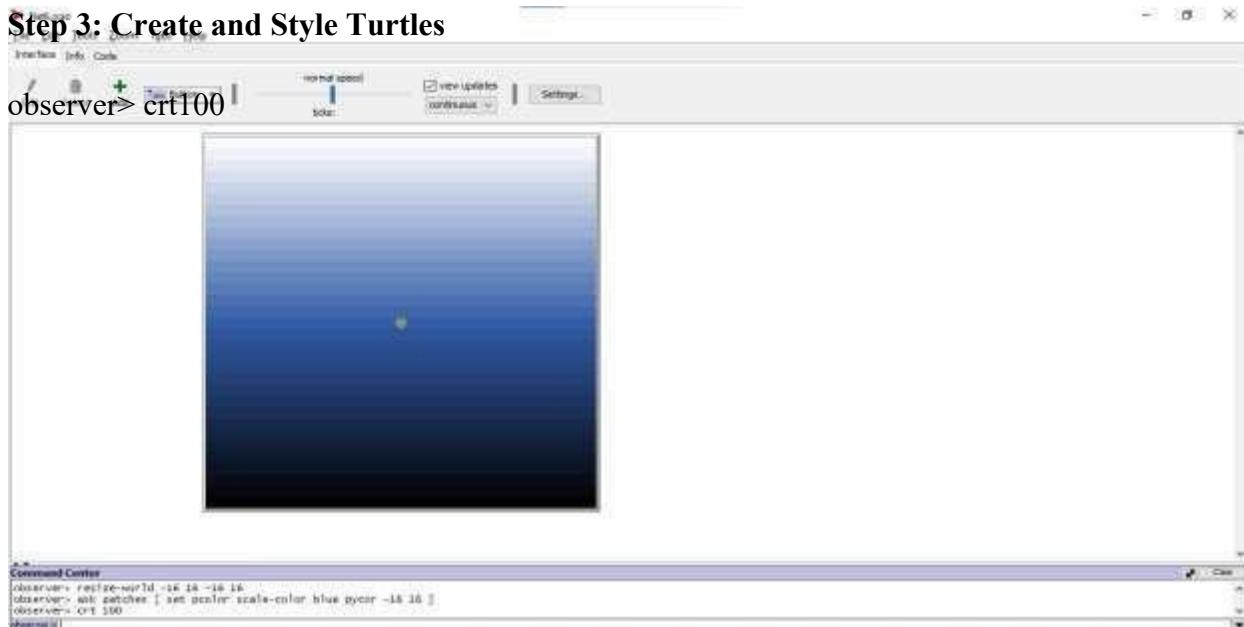
```
observer> clear-all
```

```
observer> resize-world -16 16 -16 16
```

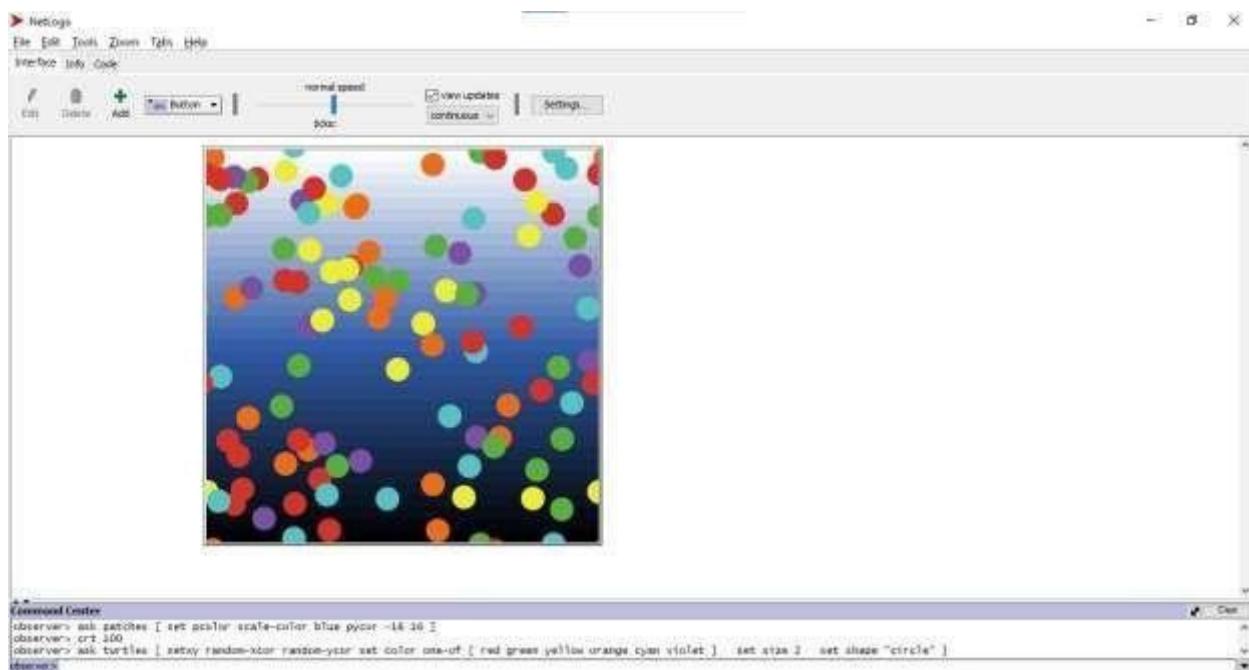


### Explanation:

Clears the world, sets the visible grid size, and creates a vertical blue gradient background.



```
observer> ask turtles [ setxy random-xcor random-ycor set color one-of [ red green yellow orange cyan violet ] set size 2 set shape "circle" ]
```



### Explanation:

Creates 100 turtles at random positions with varied colors and circular shapes.

## Step

**4: Draw Star-Like Patterns** observer> ask turtles

```
[ pen-down repeat 8 [ fd 8 rt 45 ] ]
```



Each turtle draws an 8-pointed star by repeatedly moving forward and turning right.

## Step 5: Random Movement and Color Change

observer> ask turtles [ repeat15 [ rrandom360 fd random 10 set color one-of [ red yellow blue green pink white ] ] ]



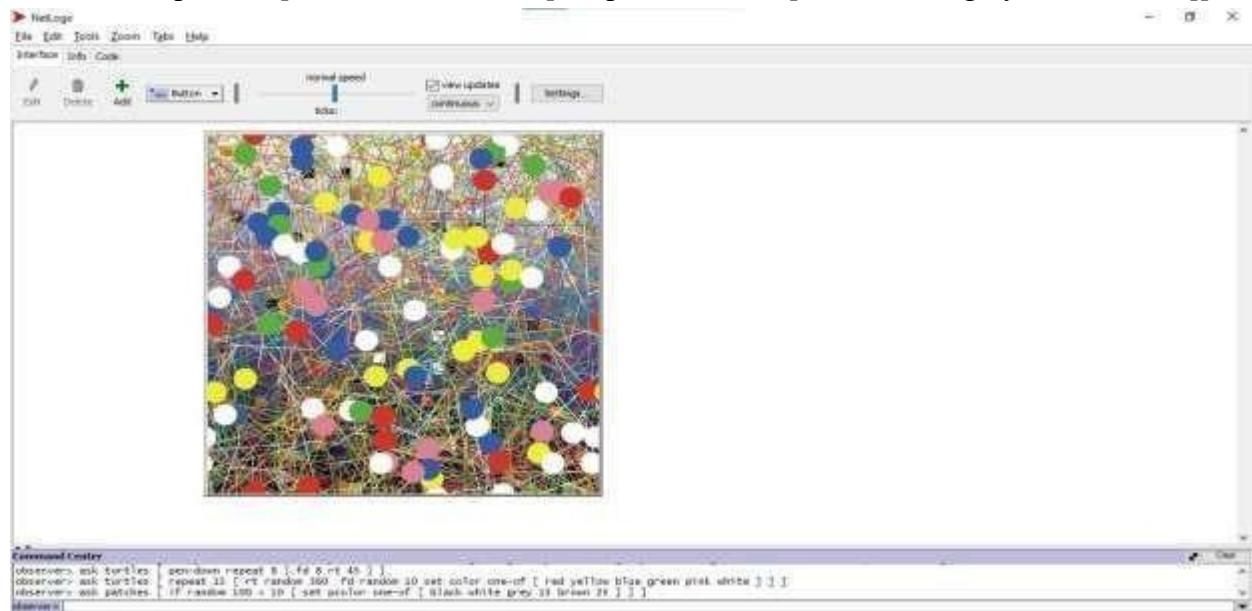
## Step

### Explanation:

Turtles move randomly and change colors, producing an animated colorful design.

#### 6: Recolor Background Patches

observer>ask patches [ ifrandom 100 < 10 [ set pcolor one-of [ black white grey 15 brown 25 ] ] ]



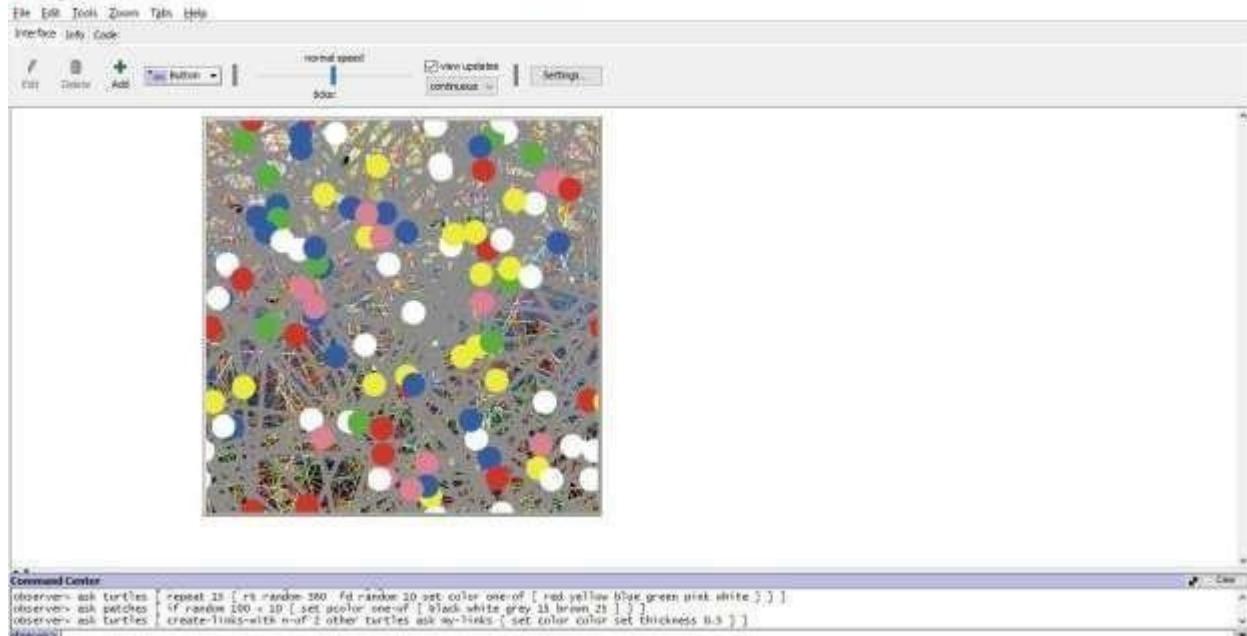
### Explanation:

Some patches change color randomly to make the background more artistic.

#### Step 7: Connect Turtles with Links

observer>ask turtles [ create-links-with n-of 2 other turtles ]

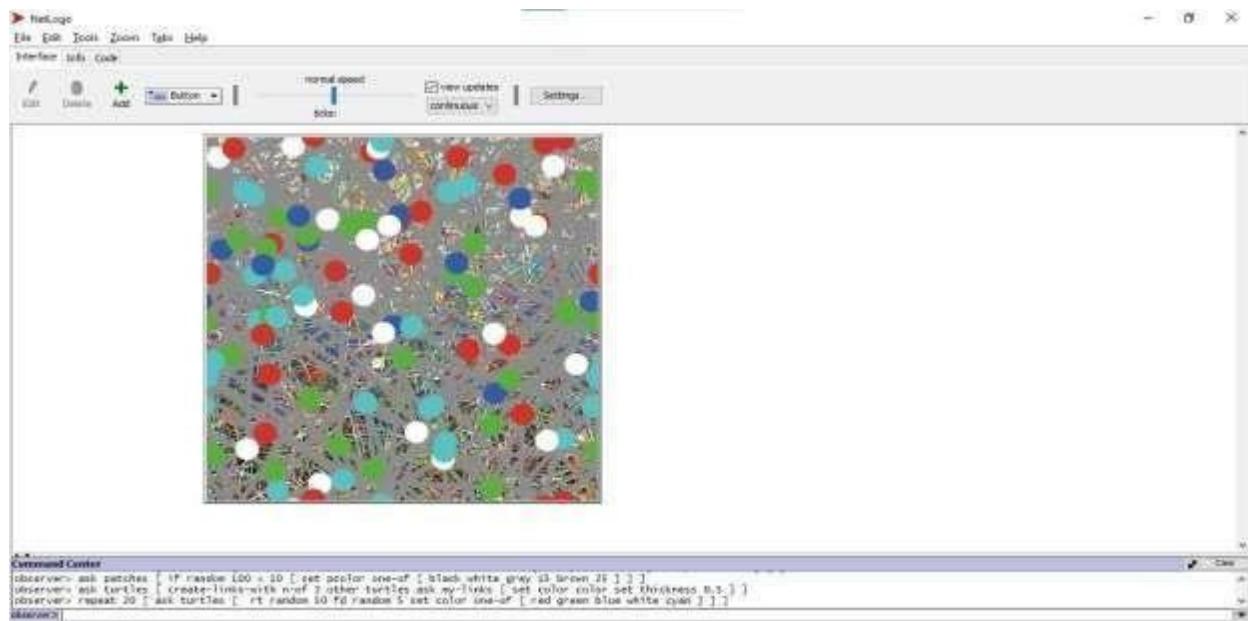
ask my-links [ set color color set thickness 0.5 ] ]



Each turtle connects with two others using colored lines, forming a network-like structure.

## Step

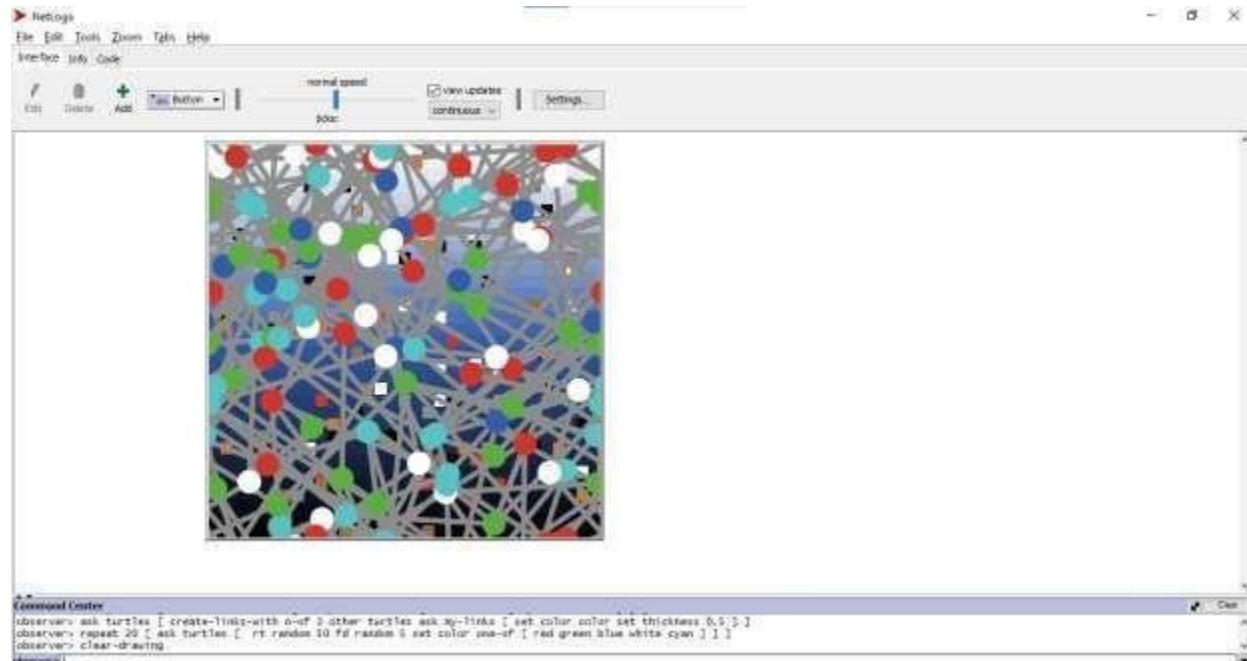
**8: Animate the Turtles** observer> repeat 20 [ ask turtles [ rt random 50 fd random 5 set color one-of[red green blue white cyan] ] ]



## Explanation:

Turtles move and change colors dynamically for 20 iterations, creating continuous motion.

**Step 9: Clear Drawing Without Deleting Turtles** observer> clear-drawing



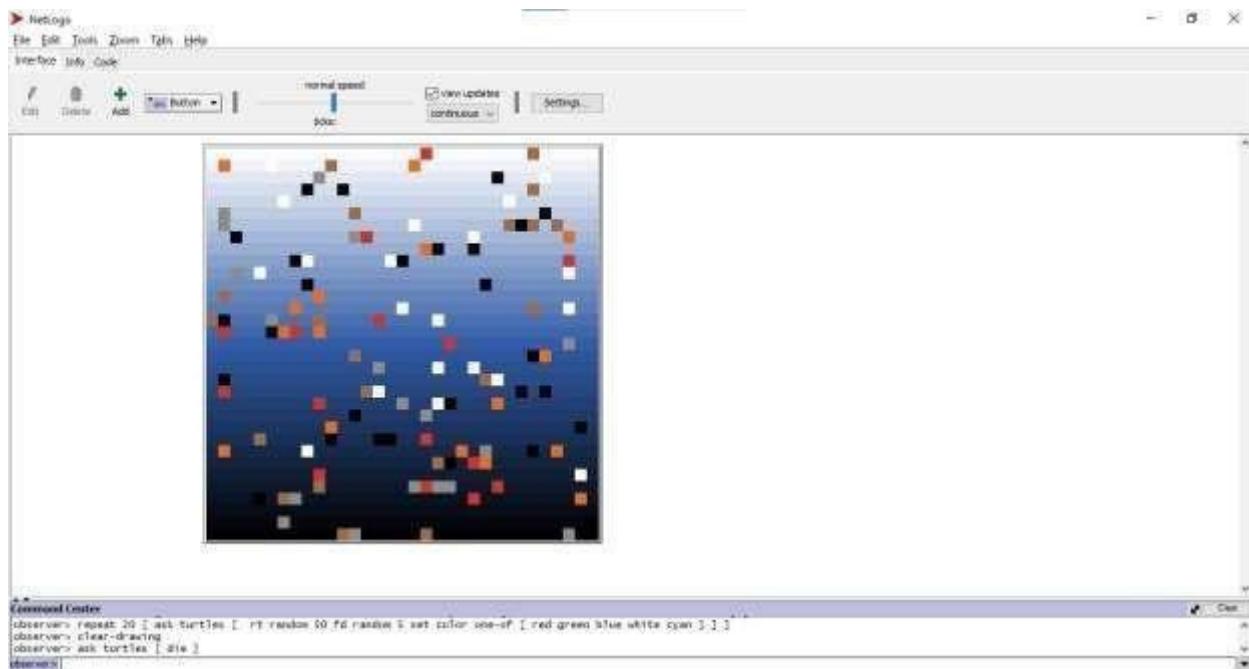
## Explanation:

Erases the trails drawn by turtles but keeps them visible on the screen.

## Step

**10: Delete All Turtles** observer> ask

turtles [ die]



Removes all turtles from the simulation, leaving only the background pattern.

## ADDITIONAL PRACTICE COMMANDS

Try these extra commands to explore more creativity: observer> ask patches [ set pcolor scale-color red pxcor -16 16 ] observer> ask turtles [ set shape "star" pen-down repeat 5 [ fd 12 rt 144 ] ] observer> ask turtles [ hatch 1 [ rt 180 fd 4 set color cyan ] ] observer> clear-drawing

## EXPLANATION:

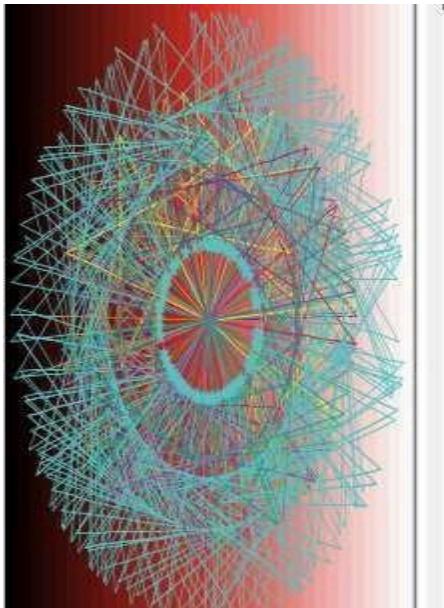
These commands introduce new gradients, star shapes, cloned turtles, and clear drawings for further experimentation.

## OBSERVATION

- Turtles can move and draw simultaneously to form complex designs.
- The combination of colors and random movement produces unique results every run.
- The use of links adds structure and connection between agents.

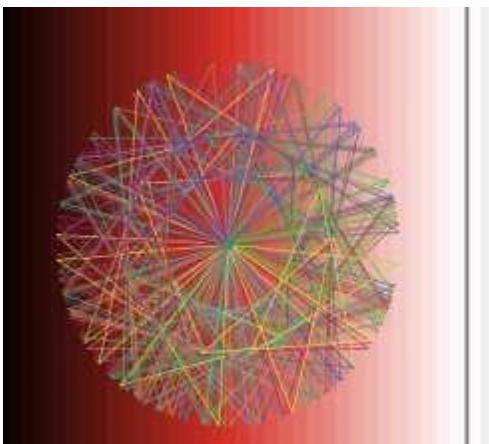
## STUDENT TASK

1. Execute all commands step by step in NetLogo.



```
observer> resize-world -16 16 -16 16
observer> ask patches [ set pcolor scale-color blue pxcor -16 16 ]
observer> crt 100
observer> ask turtles [ setxy random-xcor random-ycor set color one-of [ red green yellow orange cyan violet ] set size 1
observer> pen-down repeat 8 [ fd 8 rt 45 ] ]
observer> ask turtles [ repeat 15 [ rt random 360 fd random 10 set color one-of [ red yellow blue green pink white ] ] ]
observer> ask patches [ if random 100 < 10 [ set pcolor one-of [ black white grey 15 brown 25 ] ] ]
observer> ask turtles [ create-links-with n-of 2 other turtles ask my-links [ set color color set thickness 0.5 ] ]
observer> repeat 20 [ ask turtles [ rt random 50 fd random 5 set color one-of [ red green blue white cyan ] ] ]
observer> clear-drawing
observer> ask turtles [ die ]
observer> ask patches [ set pcolor scale-color red pxcor -16 16 ]
observer> ask turtles [ set shape "star" pen-down repeat 5 [ fd 12 rt 144 ] ]
observer> crt 100
observer> ask turtles [ set shape "star" pen-down repeat 5 [ fd 12 rt 144 ] ]
observer> ask turtles [ hatch 1 [ rt 180 fd 4 set color cyan ] ]
observer> clear-drawing
observer> ask turtles [ set shape "star" pen-down repeat 5 [ fd 12 rt 144 ] ]
observer> clear-drawing
observer> ask turtles [ set shape "star" pen-down repeat 5 [ fd 12 rt 144 ] ]
```

2. Modify the number of turtles and observe how the design changes.

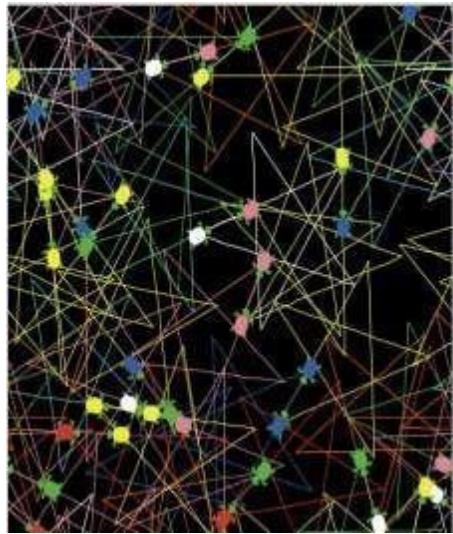


```
observer> ask patches [ set pcolor scale-color blue pxcor -16 16 ]
observer> crt 100
turtles> setxy random-xcor random-ycor
turtles> set color one-of [ red green yellow orange cyan violet ]
turtles> set size 2
turtles> set shape "circle"
turtles> pen-down repeat 8 [ fd 8 rt 45 ]
turtles> repeat 15 [ rt random 360 fd random 10 set color one-of [ red yellow blue green pink white ] ]
observer> ask patches [ if random 100 < 30 [ set pcolor one-of [ black white grey 15 brown 25 ] ] ]
observer> ask turtles [ create-links-with n-of 2 other turtles ask my-links [ set color color set thickness 0.5 ] ]
observer> repeat 20 [ ask turtles [ rt random 50 fd random 5 set color one-of [ red green blue white cyan ] ] ]
observer> clear-drawing
observer> ask turtles [ die ]
observer> ask patches [ set pcolor scale-color red pxcor -16 16 ]
observer> ask turtles [ set shape "star" pen-down repeat 5 [ fd 12 rt 144 ] ]
observer> crt 100
observer> ask turtles [ set shape "star" pen-down repeat 5 [ fd 12 rt 144 ] ]
```

**More turtles** → denser, complex, overlapping design

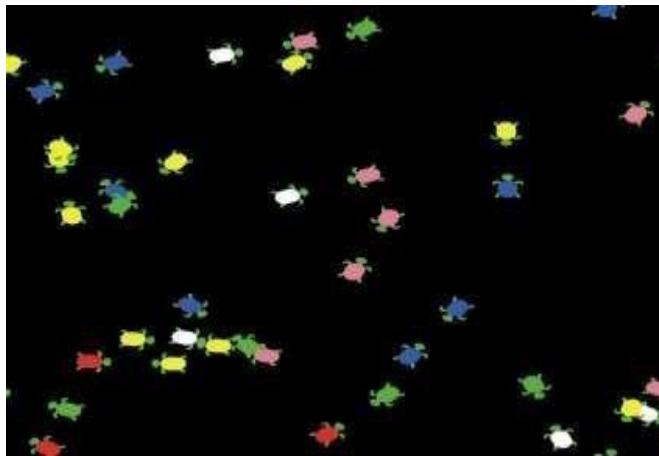
**Fewer turtles** → sparse, simple, clear design

3. Create your own pattern using loops and random colors.

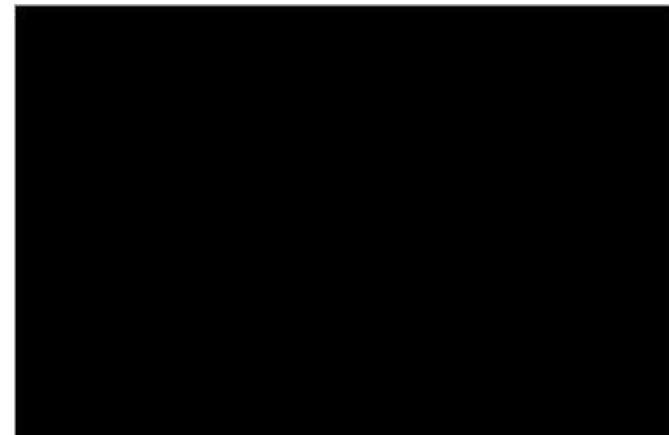


```
observer> crt 20
observer> ask turtles [setxy random-xcor random-ycor set size 2 set shape "turtle" set color one-of [ yellow orange white cyan turtles] pen-down]
observer> ask turtles [repeat 5 [fd 12 rt 144]]
observer> ask turtles [set color one-of [ red yellow blue green pink white ]]
observer> ask turtles [hatch 1 [fd 4 rt 180 set color one-of [ red yellow blue green pink white ] pen-down repeat 5 [ fd 12 rt
```

4. Test the difference between clear-all and clear-drawing.**clear-drawing:**  
clear all lines (links)



**Clear-all:** delete everything



5. Record your observations and screenshots of your patterns.

## OBSERVATION

In this lab, I learned how turtles and patches create different patterns using loops, colors, and movement. Changing the number of turtles affected the design's density, and I observed how clear-drawing and clear-all reset the world differently. Overall, it showed how simple commands can form creative patterns in NetLogo.

## **POST-LAB QUESTIONS ANSWERS**

### **1. What is the function of the scale-color command?**

It sets a color based on a numeric value, creating a gradient effect between two extremes (e.g., using coordinates to make smooth color transitions on patches).

### **2. How does randomization affect the pattern's appearance?**

Randomization makes each pattern unique and unpredictable by changing turtle positions, directions, and colors every time the code runs.

### **3. What happens if you change the value of n-of in the linking command?**

Changing the value of n-of increases or decreases how many other turtles each turtle links with, affecting how dense or connected the network appears.

### **4. Which command removes turtles completely from the world?**

The command ask turtles [ die ] removes all turtles from the world.

### **5. How can you make the turtles draw different shapes?**

By using loops (repeat) with movement and turning commands (like fd, rt, lt) and adjusting angles or steps, turtles can draw shapes such as stars, squares, or circles.

## **LAB 6: TURTLE MAZE AND OBSTACLE NAVIGATION IN NETLOGO OBJECTIVE**

- To learn how turtles can navigate around obstacles using simple conditional logic.
- To understand pen control, loops, and patch sensing for creating interactive paths.
- To explore dynamic turtle responses to patch colors or boundaries.

## **LANGUAGE/TOOL**

- **Tool:** NetLogo 6.4.0
- **Platform:** Windows

- **Environment:** CommandCenter

## THEORY

Turtles can sense the color of the patch they are on or nearby patches. By using if statements, turtles can avoid obstacles or change direction. This lab demonstrates how simple rules and conditions allow turtles to navigate environments and interact with patch-based obstacles.

## IMPORTANT CONCEPTS

Concept	Description
<b>Pen Control</b>	pen-down or pen-up determines whether movement leaves trails.
<b>Patch Awareness</b>	Turtles can read the color of the patch they are on.
<b>Conditional Logic</b>	if statements help turtles respond to obstacles.
<b>Loops</b>	repeat allows turtles to perform actions multiple times.
<b>Navigation</b>	Combining motion, sensing, and conditional decisions.

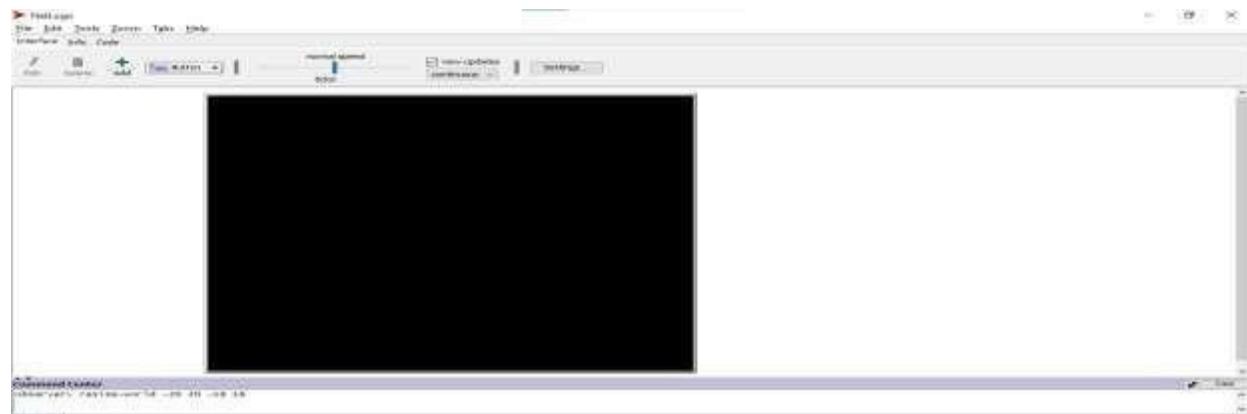
## LAB PROCEDURE

### Step 1: Open NetLogo

1. Start NetLogo.
2. Open the Command Center window.
3. Make sure you are in observer mode.

### Step 2: Prepare the World

observer> resize-world -20 20 -20 20



observer> ask patches [ set pcolor one-of [ green black]]



### Explanation:

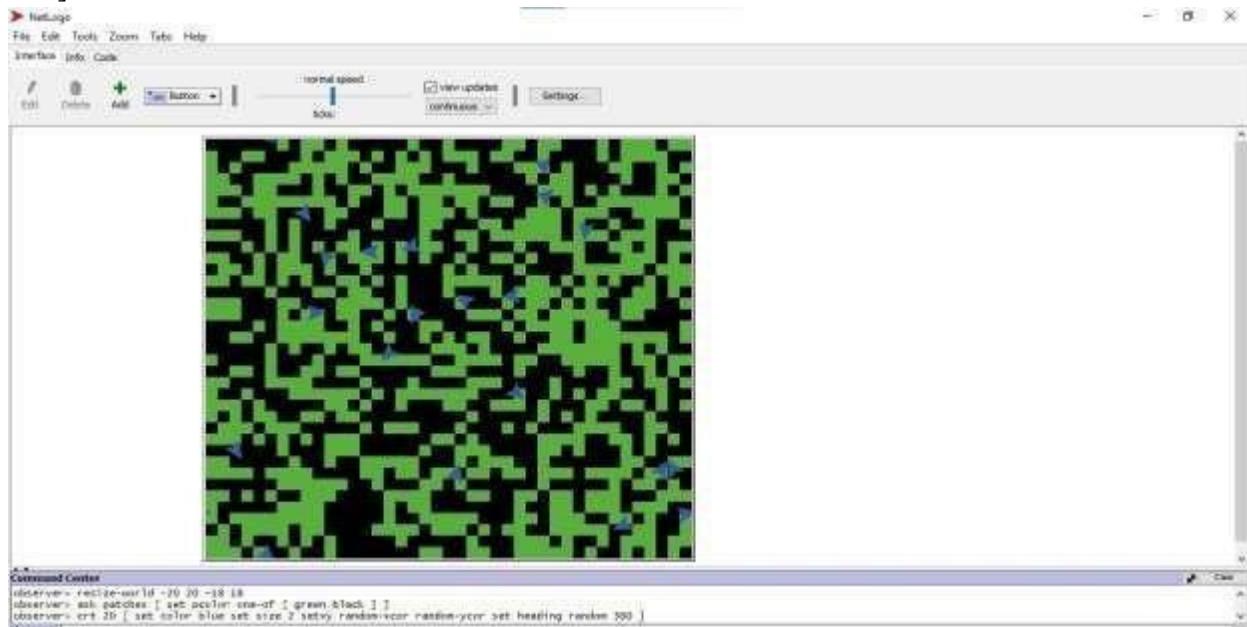
Clears the world, defines boundaries, and randomly colors patches green (open space) or black (obstacles).

### Step 3: Create Turtles

```

observer>crt20 [ setcolor blue set size 2 setxy random-xcor random-ycor set heading random 360 ]

```



### Explanation:

Creates 20 turtles at random positions with random headings.

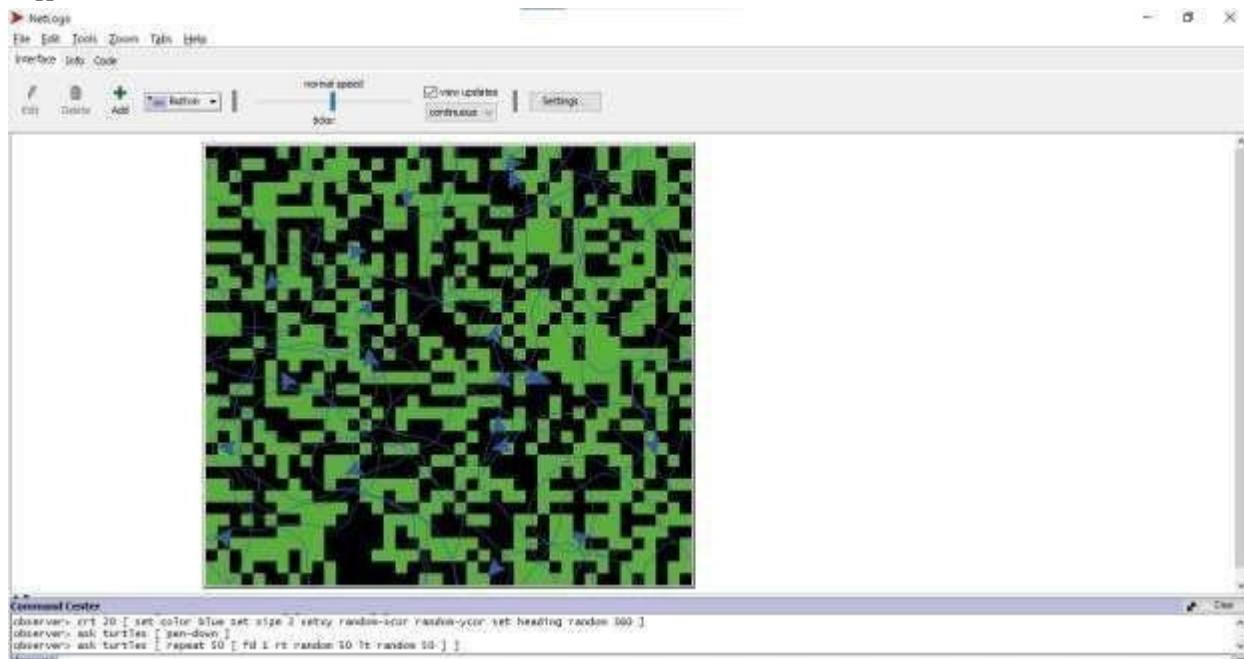
**Step 4: Enable Drawing** `observer> ask turtles [ pen-down ]`



### Explanation:

Turtles leave trails when moving, showing their path through the maze.

**Step5: Basic Random Motion** observer> ask turtles [ repeat 50 [ fd 1 rt random 50 lt random 50]]

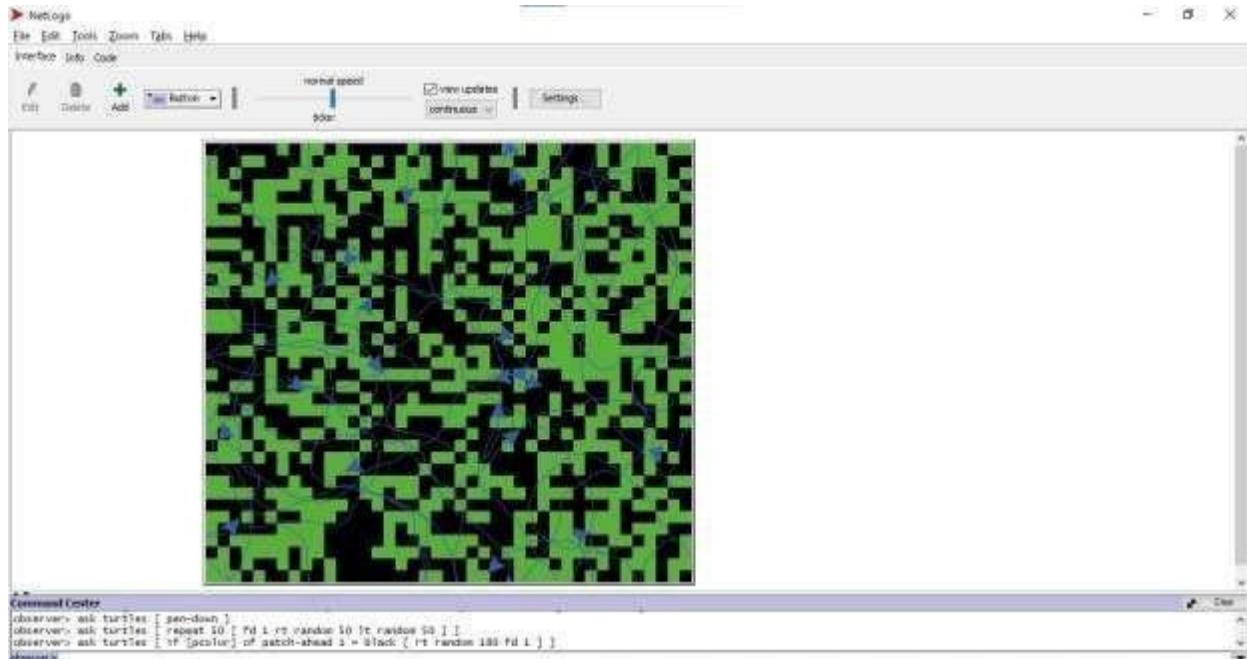


### Explanation:

Turtles move forward with slight random turns to explore the environment.

### Step 6: Obstacle Avoidance

observer>ask turtles [ if[pcolor] of patch-ahead 1 = black [ rt random 180 fd 1]]



### Explanation:

If a turtle sees a black patch ahead (obstacle), it turns randomly to avoid it.

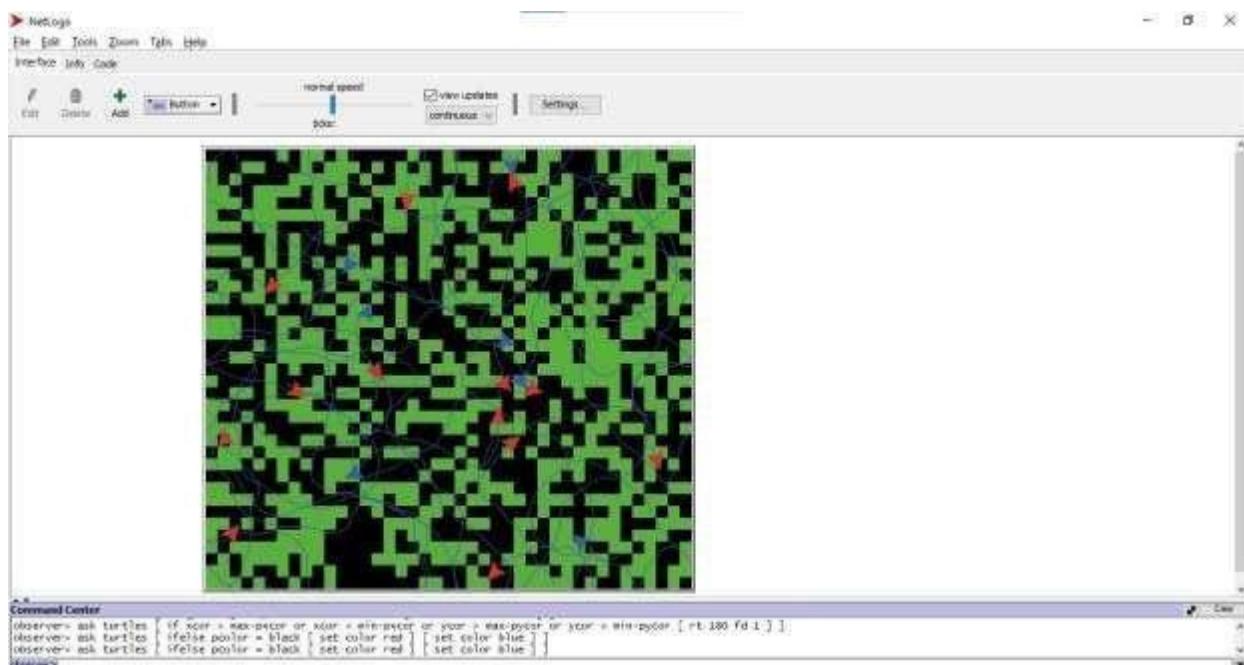
**Step 7: Boundary Control** observer> ask turtles [ if xcor > max-pxcor or xcor < min-pxcor or ycor > max-pycor or ycor < min-pycor [ rt 180 fd 1 ] ]



### Explanation:

Turtles detect world boundaries and turn back to stay inside the environment. **Step 8: Color Change on Encounter**

observer> ask turtles [ ifelse [color] = black [ set color red ] [ set color blue ] ]

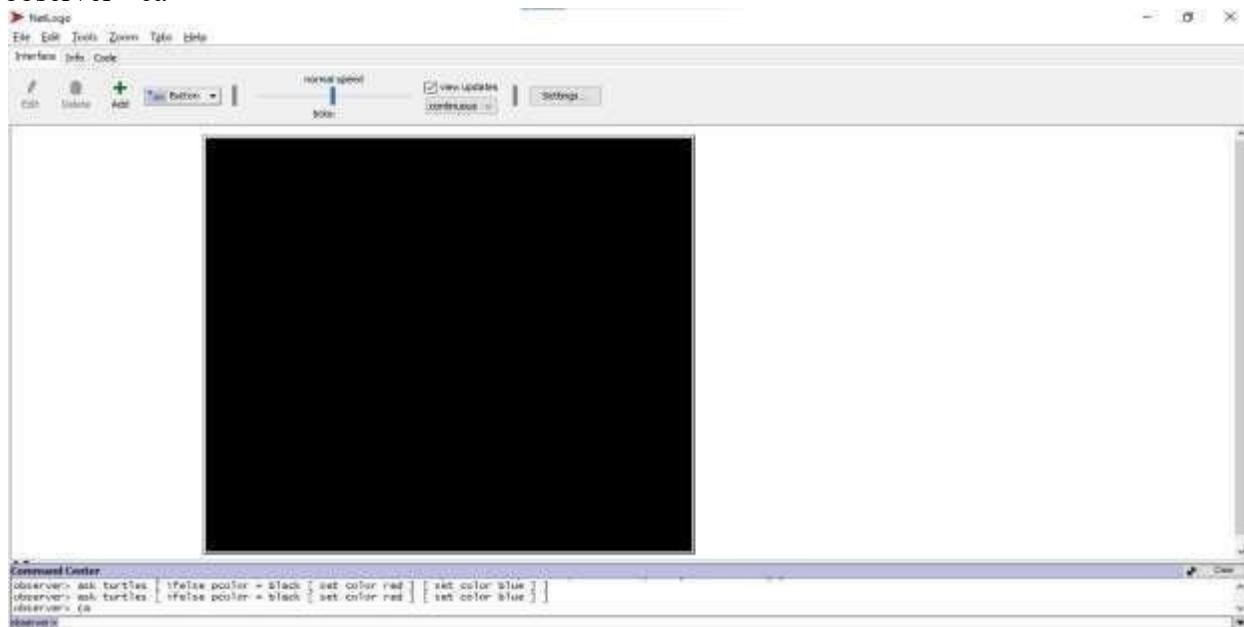


### Explanation:

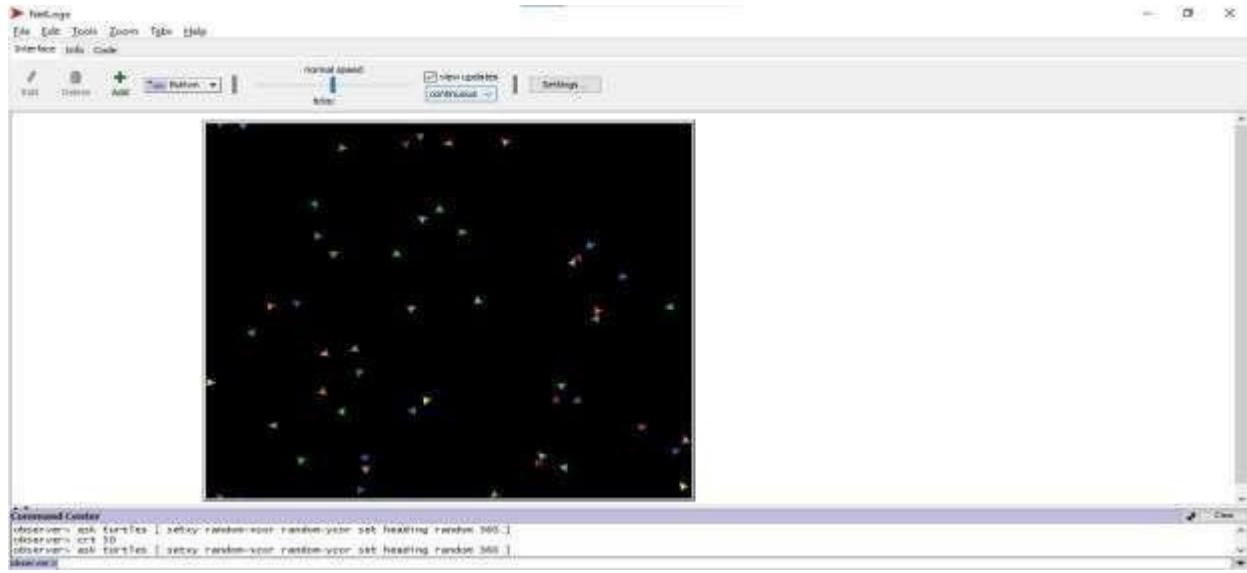
Turtlesturningred when on obstacles and blue on open paths provides visual feedback.

### Step 9: Clear Trails and Reset

observer> ca



observer> ask turtles [ setxy random-xcor random-ycor set heading random 360]



### Explanation:

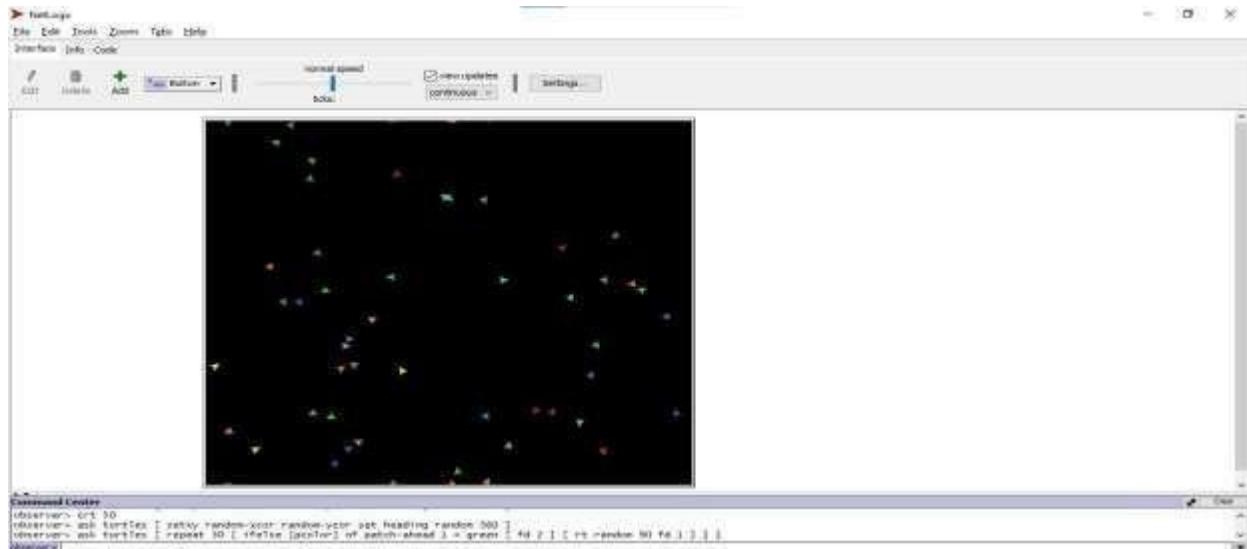
Cleartrailsandredistributes turtles for a new simulation run.

### Step 10: Advanced Movement

```

observer> ask turtles [ repeat30[if [pcolor] of patch-ahead 1 = green [ fd 2 ] else [ rt random 90 fd 1 ] ] ]

```



### Explanation:

Turtlesmovefaster through open space andcarefullynavigate around obstacles.

### ADDITIONAL PRACTICE COMMANDS

```

observer> ask turtles [ if xcor mod 2 = 0 [ setsize3]else [ set size 1.5 ]
] observer> ask turtles [ if color = red [ rt 90fd1]]observer> ask
patches [ if pycor mod 3 = 0 [ set pcolor grey]]observer> clear-
drawing

```

### EXPLANATION:

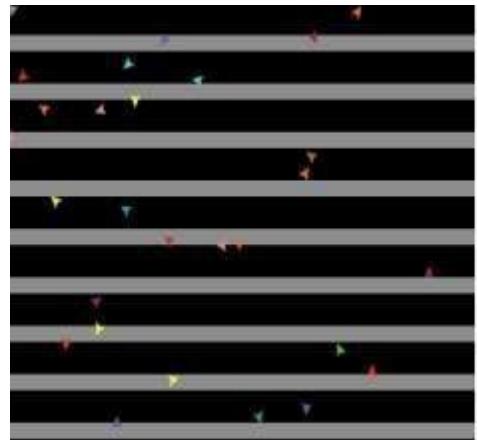
Students can experiment with turtle size, turning rules, and patterned obstacles.

## OBSERVATION

- Turtles avoid black patches and navigate green areas.
- Trails show how turtles move around obstacles.
- Random turns make navigation more natural.
- Adjusting turtle count or obstacle density changes navigation complexity.

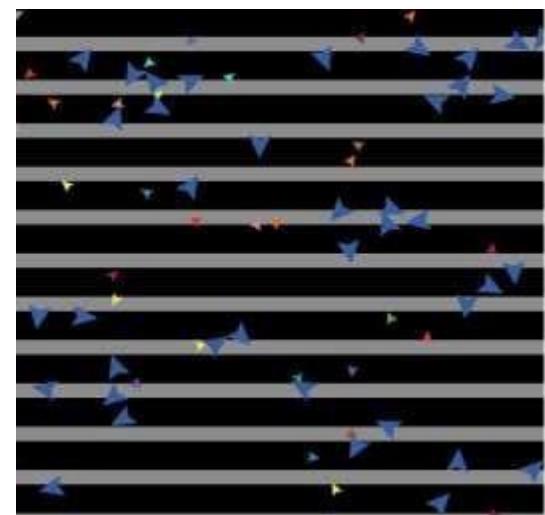
## STUDENT TASK

1. Execute all commands sequentially.



```
observer> resize-world -20 20 -20 20
observer> ask patches [ set pcolor one-of [ green black ] ]
observer> crt 20 [ set color blue set size 2 setxy random-xcor random-ycor set heading random 360 ]
observer> ask turtles [ pen-down ]
observer> ask turtles [ repeat 50 [ fd 1 rt random 50 lt random 50 ] ]
observer> ask turtles [ if [pcolor] of patch-ahead 1 = black [ rt random 180 fd 1 ] ]
observer> ask turtles [ if xcor > max-pxcor or xcor < min-pxcor or ycor > max-pycor or ycor < min-pycor [ rt 180 fd 1 ] ]
observer> ask turtles [ ifelse pcolor = black [ set color red ] [ set color blue ] ]
observer> ca
observer> crt 50
observer> ask turtles [ setxy random-xcor random-ycor set heading random 360 ]
observer> ask turtles [ if xcor mod 2 = 0 [ set size 3 ] ]
observer> ask turtles [ if color = red [ rt 90 fd 1 ] ]
observer> ask patches [ if pycor mod 3 = 0 [ set pcular grey ] ]
observer> clear-drawing
```

2. Increase turtle count to 30 or 40 and observe changes.



```
observer> resize-world -20 20 -20 20
observer> ask patches [ set pcolor one-of [ green black ] ]
observer> crt 20 [ set color blue set size 2 setxy random-xcor random-ycor set heading random 360 ]
observer> ask turtles [ pen-down ]
observer> ask turtles [ repeat 50 [ fd 1 rt random 50 lt random 50 ] ]
observer> ask turtles [ if [pcolor] of patch-ahead 1 = black [ rt random 180 fd 1 ] ]
observer> ask turtles [ if xcor > max-pxcor or xcor < min-pxcor or ycor > max-pycor or ycor < min-pycor [ rt 180 fd 1 ] ]
observer> ask turtles [ ifelse pcular = black [ set color red ] [ set color blue ] ]
observer> ca
observer> crt 50
observer> ask turtles [ setxy random-xcor random-ycor set heading random 360 ]
observer> ask turtles [ if xcor mod 2 = 0 [ set size 3 ] ]
observer> ask turtles [ if color = red [ rt 90 fd 1 ] ]
observer> ask patches [ if pycor mod 3 = 0 [ set pcular grey ] ]
observer> clear-drawing
observer> crt 50 [ set color blue set size 2 setxy random-xcor random-ycor set heading random 360 ]
```

## OBSERVATION

Increasing the turtle count made the pattern denser, with more overlaps and movements. More turtles changed color due to black patches, and the world appeared more crowded and colorful.

3. Modify obstacle density (pcolor black frequency) and see how turtles respond.



## OBSERVATION

When black patches(obstacles) increased, turtles had less space to move, turned more often, and their paths became irregular. With fewer black patches, their motion was smoother and more spread out.

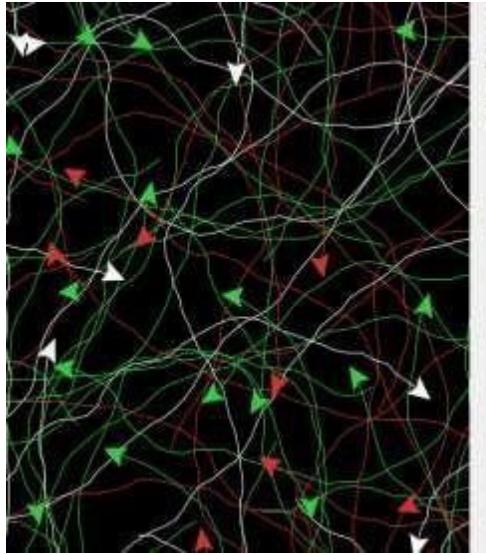
### 4. Test different random turn ranges for smoother navigation.



## OBSERVATION

Smaller random turnvalues made turtles move smoothly, while larger ones caused quick, random turns and irregularpaths.

### 5. Record how turtlesadapt to obstacles and boundaries.



```
observer> ask patches [ifelse random 100 < 40 [ set pcolor one-of [ blue violet cyan ] ] [ set pcolor one-of [ yellow green orange red ] ] ]
observer> crt 40
turtles> set color one-of [ red white lime ] set size 2 setxy random-xcor random-ycor set heading random 360
turtles> pen-down
turtles> repeat 60 [ fd 1 rt random 30 lt random 30 ]
observer> ask turtles [ if [pcolor] of patch-ahead 1 = black [ rt random 180 fd 1 ] ]
observer> ask turtles [ if xcor > max-pxcor or xcor < min-pxcor or ycor > max-pycor or ycor < min-pycor [ rt 180 fd 1 ] ]
observer> ask patches [ set pcolor black ]
```

## OBSERVATION

Turtles avoided black patches by turning away and bounced back when they reached the world boundaries, showing they can adapt their movement to stay within the area.

## POST-LAB QUESTIONS ANSWERS

### 1. How do turtles detect obstacles?

Turtles detect obstacles using the command **[pcolor] of patch-ahead 1**, which checks the color of the patch directly in front of them.

### 2. Why do we use patch-ahead instead of patch-here?

Because **patch-ahead** lets turtles sense what's *in front* of them, while **patch-here** only checks the patch they are *currently on*.

### 3. How does changing random turn angles affect navigation?

Smaller angles make movement smooth and curved, while larger angles cause sharp, random, or chaotic paths.

### 4. What happens when obstacle density increases?

Turtles face more collisions, turn more often, and their paths become tighter and less smooth.

### 5. How can turtle trails help understand pathfinding behavior?

Turtle trails show how turtles move around obstacles, revealing how effectively they navigate or adapt within the environment.

## Lab 7: Heroes and Cowards Model Setup and Agent Properties

### Objective

- To create a population of agents (people) with unique characteristics.
- To introduce personality differences using a chooser (Hero vs Coward).
- To assign friends, enemies, and personal attributes to each agent.
- To prepare the environment that will be used for behavioral simulation in Lab 9.

### Language/Tool

- **Tool:** NetLogo6.4.0
- **Platform:** Windows
- **Environment:** Interface + Command Center

## Theory

The Heroes & Cowards model is an *agent-based social simulation* where people behave differently based on personality:

- **Heroes** move toward conflict.
- **Cowards** avoid danger.

Before coding behaviors, we must prepare:

1. A population of agents.
2. Attributes such as age, personality, friends, and enemies.
3. A chooser that lets the user decide the percentage of heroes vs cowards.
4. Spatial setup for agents to appear in random positions.

This lab focuses on setting the foundation of the model. **Important Concepts**

Concept	Description
<b>Breeds</b>	Different categories of agents.
<b>Choosers</b>	Interface widget to select personality group.
<b>Agent Variables</b>	Properties like age, type, friend-list, enemy-list.
<b>Setup Procedure</b>	Run once to initialize the world.
<b>Lab Procedure</b>	

### Step 1: Define Agent Variables

In Code tab:

```
breed [ persons person ]
persons-own [ age
personality friends
enemies
]
]
```



The screenshot shows the NetLogo interface with the 'Interface' tab selected. In the top menu bar, 'File', 'Edit', 'Tools', 'Zoom', 'Tab', 'Help' are visible. Below the menu is a toolbar with icons for 'Find...', 'Check', 'Procedures', 'Indent automatically', and 'Code Tab in separate window'. The main area displays the following code:

```
breed [ persons person ]  
persons-own [  
  age  
  personality  
  friends  
  enemies  
]  
[
```

### ***Explanation:***

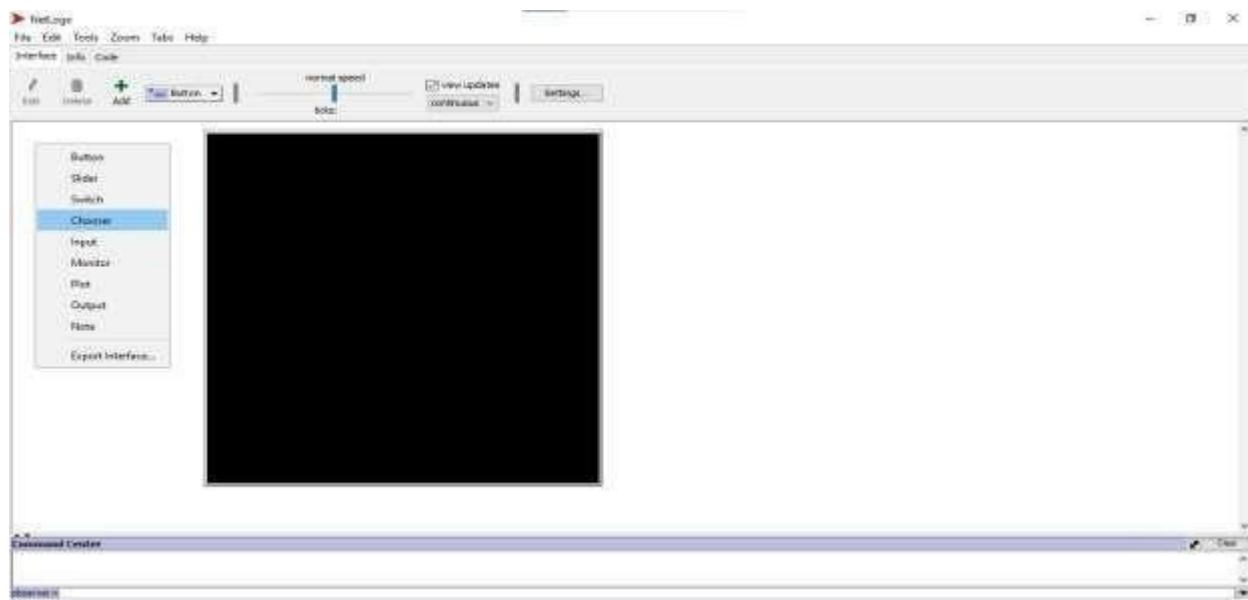
Each person will store an age, a personality label (hero or coward), and two lists of connections.

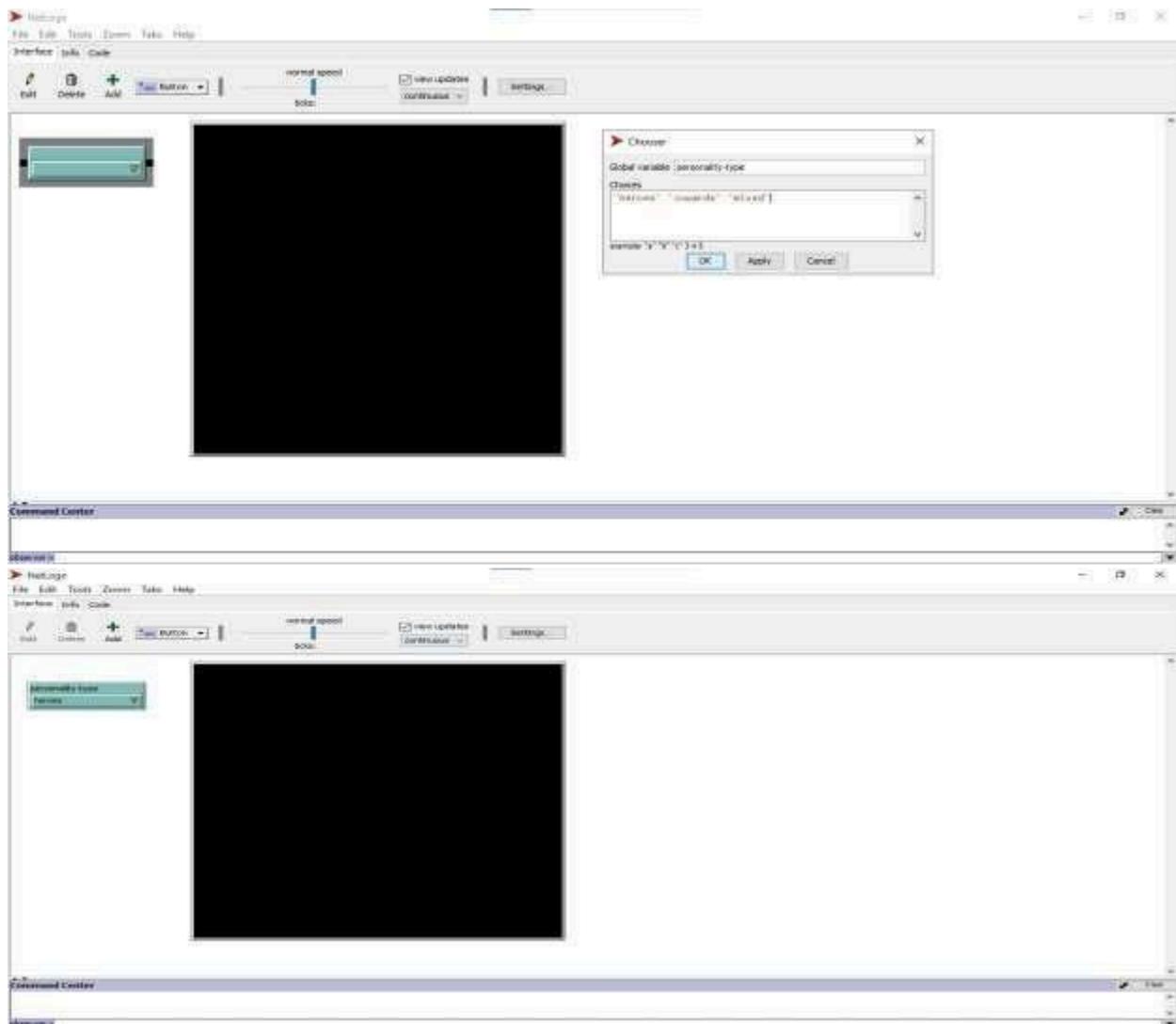
### **Step2: Add a Chooser and Button in Interface**

In the Interface tab:

#### **Add chooser**

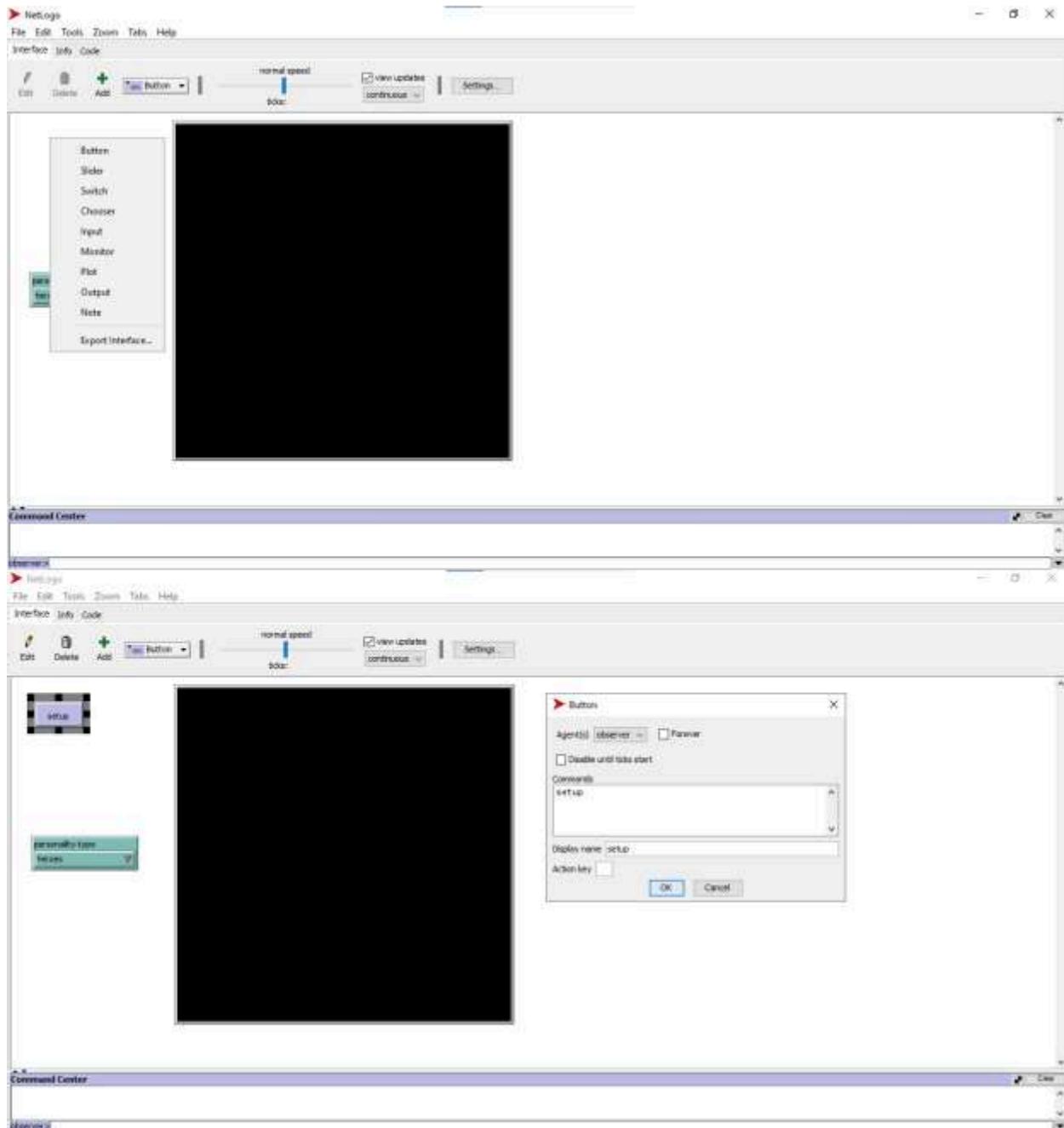
- Name: personality-type
- Choices: "heroes" "cowards"  
"mixed"





## Add Button

- **Button Name:** setup
- **Command:** setup
- **Forever:** unchecked



### Step 3: Write the Setup Procedure

```
setup clear-all create-persons 100 [  
  setxy random-xcor random-ycor  
  set size 2 set age random 50 assign-  
  personality  
]
```

```
assign-friends-and-enemies      reset-
```

```
ticks end
```

The screenshot shows the NetLogo interface with the code editor open. The title bar says "NetLogo". The menu bar includes "File", "Edit", "Tools", "Zoom", "Tab", and "Help". The toolbar has icons for "Interface", "Info", and "Code". A tab labeled "Code" is selected. The code area contains a "setup" procedure:

```
breed [ person person ]
persons-one [
  age
  personality
  friends
  enemies
]
to setup
  clear-all
  create-persons 100 [
    setxy random-xcor random-ycor
    set size 1
    set age random 10
    assign-personality
  ]
  assign-friends-and-enemies
  reset-ticks
end
```

#### ***Explanation:***

Creates 100 people with random age and position, then assigns personality and social relationships.

#### **Step 4: Assign Personality Based on Chooser to**

```
assign-personality if personality-type = "heroes"
```

```
[   set personality "hero" set color blue
```

```
]
```

```
if personality-type = "cowards" [ set
```

```
  personality "coward" set
```

```
  color green
```

```
]
```

```
if personality-type = "mixed" [      ifelse
```

```
  random 2 = 0
```

```
  [ set personality "hero" set color blue ]
```

```
  [ set personality "coward" set color green ]
```

```
]
```

```
End
```

The screenshot shows the NetLogo interface with the 'Code' tab selected. The code in the workspace is as follows:

```
friends  
enemies  
  
to setup  
  clear-all  
  create-persons 100 [  
    setxy random-xcor random-ycor  
    set size 2  
    set age random 10  
    assign-personality  
  ]  
  assign-friends-and-enemies  
  set ticks 0  
end  
  
to assign-personality  
  if personality-type = "heroes" [  
    set personality "hero"  
    set color blue  
  ]  
  if personality-type = "cowards" [  
    set personality "coward"  
    set color green  
  ]  
  if personality-type = "mixed" [  
    ifelse random 2 > 0 [  
      set personality "hero" set color blue  
    ] [  
      set personality "coward" set color green  
    ]  
  ]  
end
```

### **Explanation:**

- Heroes turn blue
  - Cowards turn green
  - Mixed society randomly assigns roles
- Step 5: Assign Friends and Enemies** to assign-friends-and-enemies ask persons [ let others other persons set friends n-of 3 others set enemies n-of 3 others ]
- end

▶ NetLogo

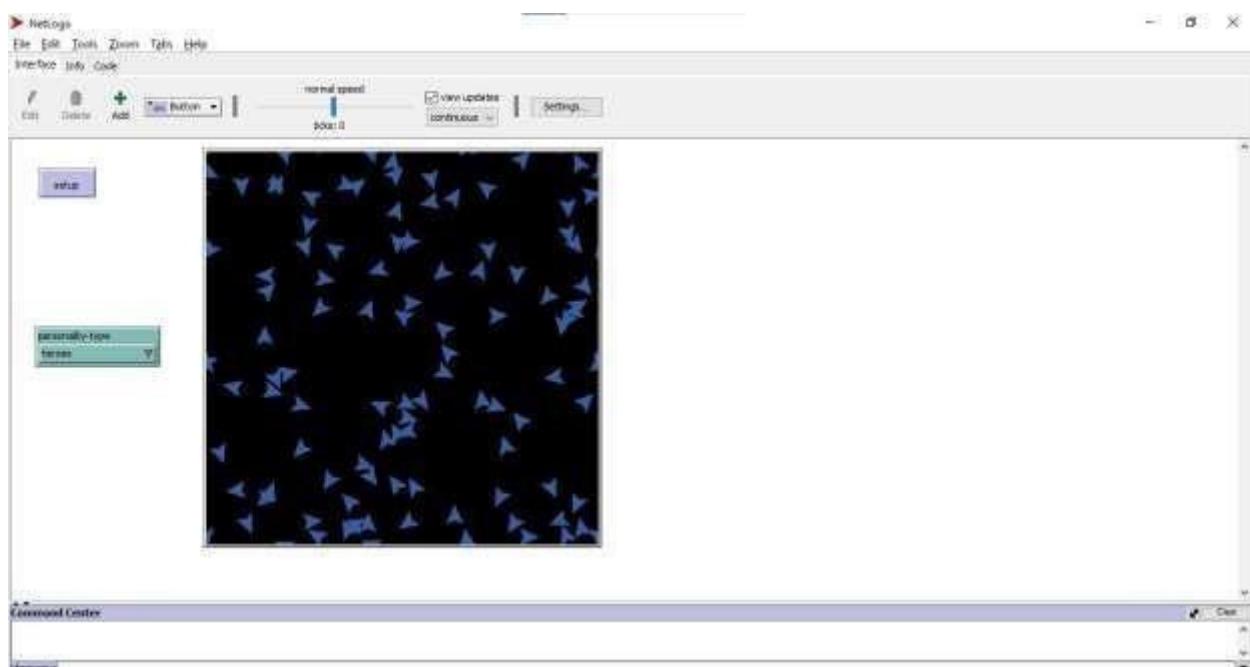
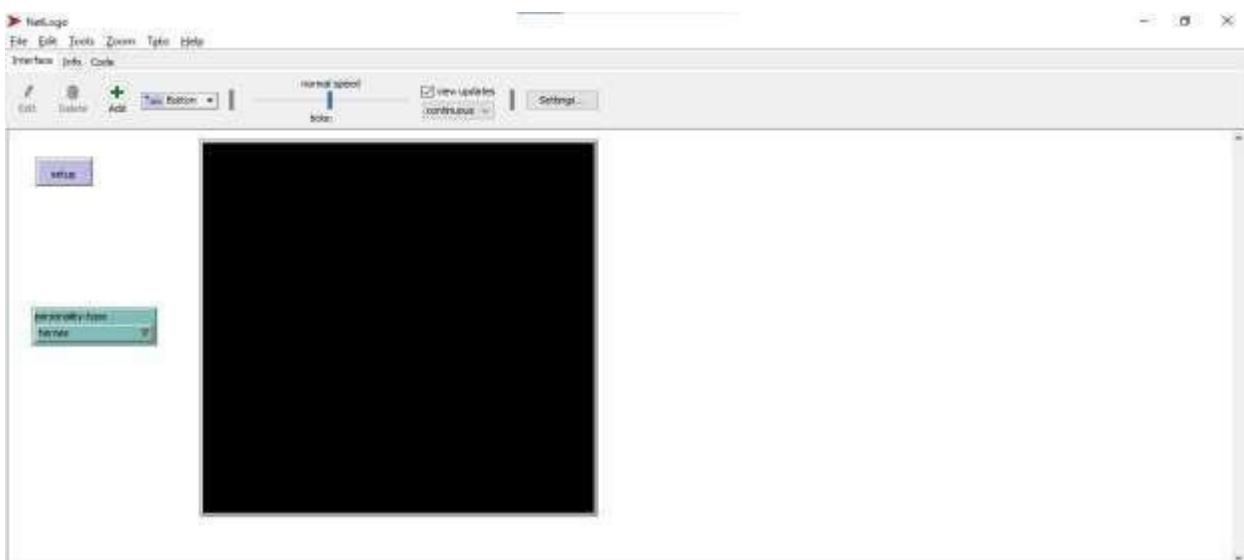
File Edit Tools Zoom Tabs Help

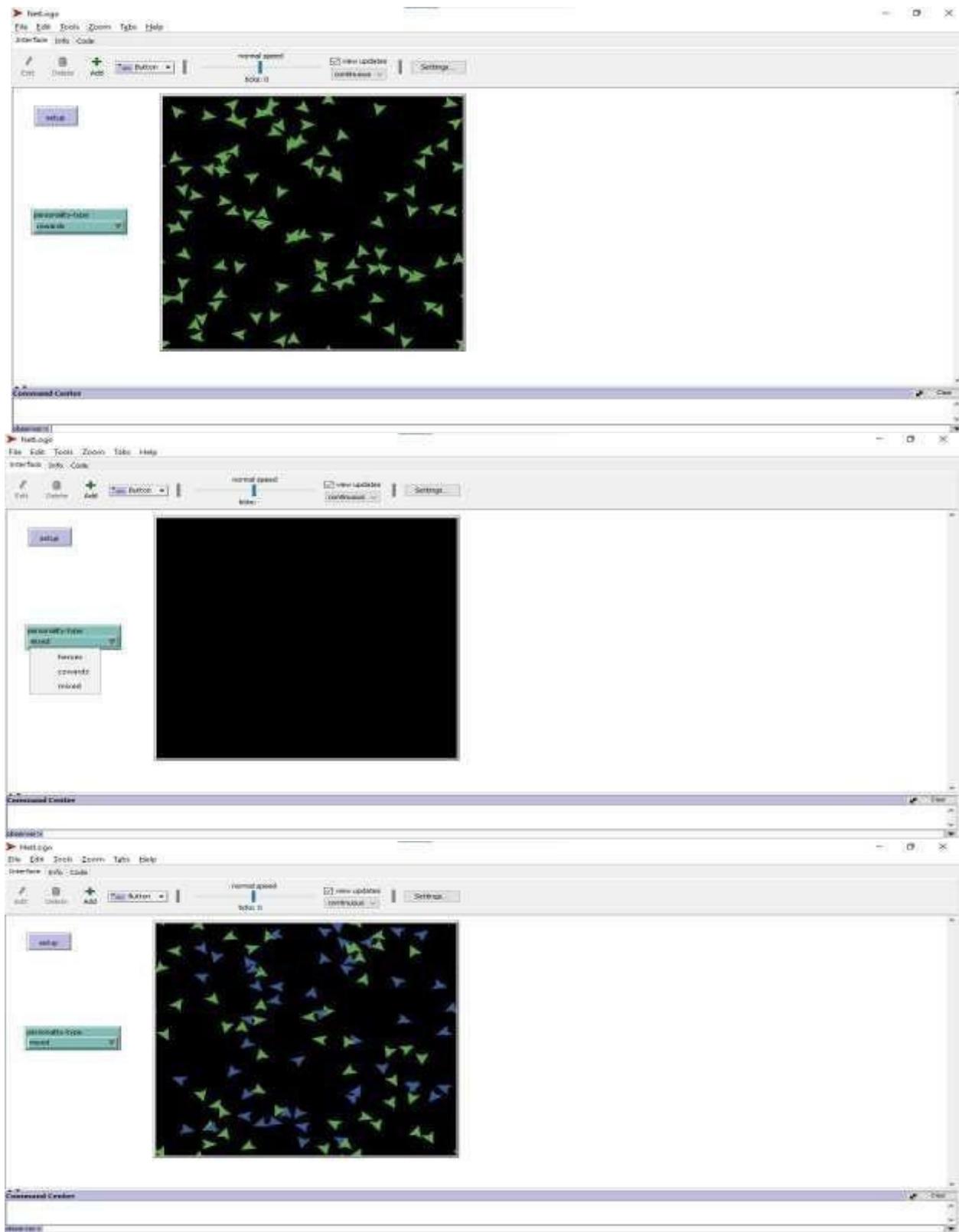
Interface Info Code

Run Check | Previous + |  Indent automatically  Code Tab in separate window

```
if personality-type = "kind" [
  ifelse random 1 > 0 [
    set personality "tern" set color blue ]
    [ set personality "coward" set color green ]
  ]
end

to assign-friends-and-enemies
  ask persons [
    let others other persons
    set friends n-of 3 others
    set enemies n-of 2 others
  ]
end
```





### ***Explanation:***

Each person gets 3 friends and 3 enemies randomly selected from the population.

## Additional Practice Commands

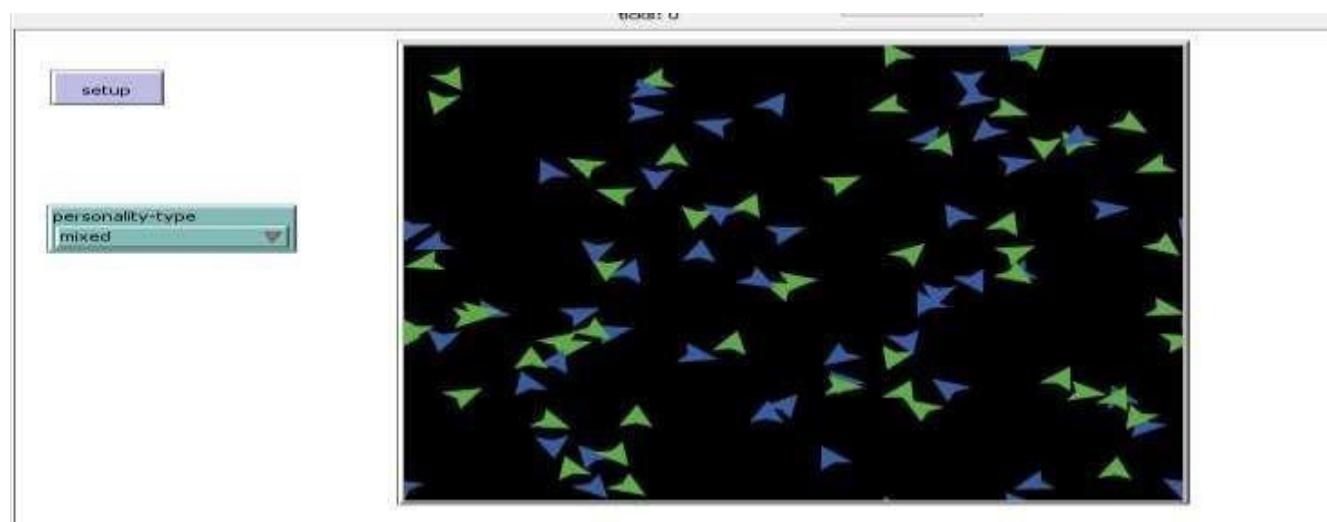
```
1. Changethenumber  
of persons:  
set-default-shape persons "person"create-persons  
200  
2. Assign age  
categories: askpersons [ if  
age<"circle"[ ] setage>40 [  
set shape "square"]  
]  
3. Highlightenemies: ask  
persons[askenemies [ set  
color red]]
```

## Observation

- Personalities appear as different colors.
- All people initialize with distinct ages and positions.
- Social structure (friends and enemies) is created even before movement begins.
- The system is now ready for advanced rules in Lab 9.

## STUDENT TASK

1. Run the complete setup procedure and observe the world.



```

Find... Check Procedures ▾ Indent automatically
breed [ persons person ]
persons-own [
age
personality
friends
enemies
]
to setup
clear-all
create-persons 100 [
setxy random-xcor random-ycor
set size 2
set age random 50
assign-personality
]
assign-friends-and-enemies
reset-ticks
end

to assign-personality
if personality-type = "heroes" [
set personality "hero"
set color blue
]
if personality-type = "cowards" [
set personality "coward"
set color green
]
if personality-type = "mixed" [
ifelse random 2 = 0
[ set personality "hero" set color blue ]
[ set personality "coward" set color green ]
]
end
to assign-friends-and-enemies
ask persons [
let others other persons
set friends n-of 3 others
set enemies n-of 3 others
]
end

```

2. Change  
**personality-type**  
compare the distribution of  
heroes and cowards.

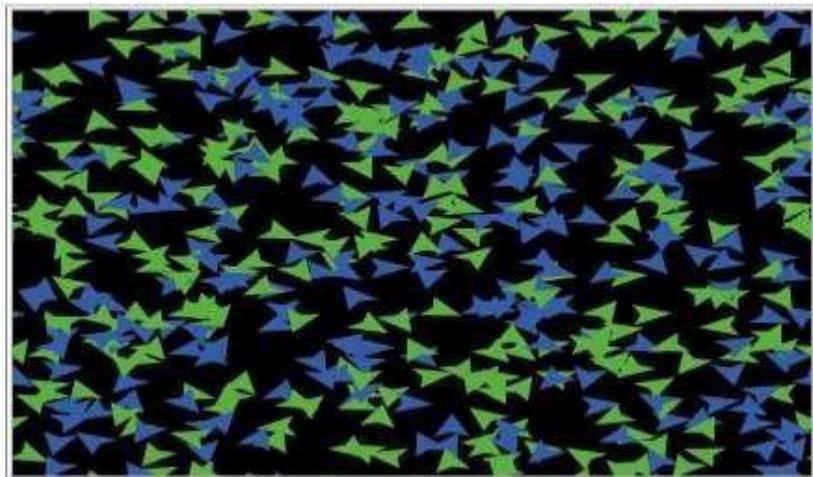
- When the personality-type was set to **hero**, most agents behaved bravely and moved toward threats, resulting in a population dominated by heroes.
- When the personality-type was set to **coward**, agents avoided danger and moved away, causing cowards to dominate the population.
- In the **mixed** setting, both heroes and cowards were present, showing a balanced distribution with different movement and interaction behaviors.

3. Increase or decrease the number of persons.

setup

personality-type

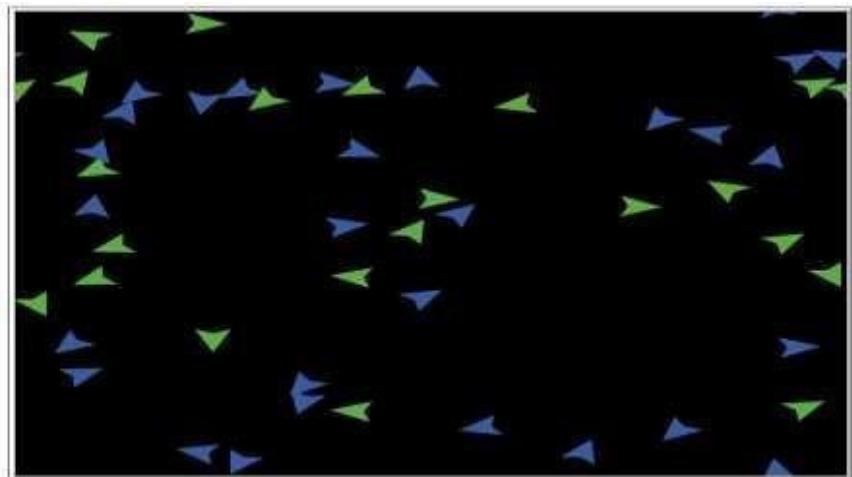
mixed



setup

personality-type

mixed



## Observation

When the number of persons was **increased**, the environment became more crowded, leading to more interactions between heroes and cowards. This increased the visibility of different behaviors.

When the number of persons was **decreased**, interactions were fewer, and agents moved more freely with less influence from others.

4. Modify the number of friends/enemies.

```
to assign-friends-and-enemies
ask persons [
let others other persons
set friends n-of 5 others
set enemies n-of 2 others
]
end
```

## **Observation**

When the number of **friends** was increased, agents showed more cooperative behavior and tended to stay closer to familiar agents.

When the number of **enemies** was increased, agents showed more avoidance and aggressive reactions, resulting in frequent movement changes.

Balanced values of friends and enemies produced mixed and dynamic interactions among agents.

### **5. Record visible changes in colors, structure, and initialization.**

During initialization, agents were randomly distributed across the environment. Heroes appeared in **blue** color, while cowards appeared in **green**, making personality types visually distinguishable.

Changes in model parameters affected the overall structure of the simulation, where crowding increased clustering and mixed personalities created visible variation in agent distribution.

## **Post-Lab Questions**

### **1. Why do we define persons-own variables before using them?**

Defining persons-own variables allows each agent to store its own properties, such as age, personality, friends, and enemies, which are used during the simulation to determine behavior.

### **2. What is the role of the chooser in this model?**

The chooser lets the user select the personality type (hero, coward, or mixed) without changing the code, allowing easy experimentation and observation of different behaviors.

### **3. How does assigning friends and enemies affect later simulation behavior?**

Friends and enemies influence interactions between agents, affecting movement, clustering, avoidance, and overall dynamics during the simulation.

### **4. Why is random placement useful in agent-based modeling?**

Random placement ensures a non-biased initial distribution of agents, allowing the simulation to reflect natural variability and explore different interaction patterns.

### **5. What is the purpose of using separate procedures like assign-personality?**

Separate procedures improve code organization, readability, and reusability, making it easier to manage complex behaviors and assign properties systematically.

## Lab 8: Strategy-Based Decision Making (El Farol Bar Model)

### Objective

- To understand how agents make decisions using prediction-based strategies.
- To model attendance behavior in a crowded bar using limited memory.
- To assign multiple strategies to each agent and evaluate which strategy performs best.
- To simulate decision-making under uncertainty using past attendance history.
- To explore emergent behavior when many individuals predict the same event.

### Tool / Environment

- **Software:** NetLogo 6.4.0
- **Platform:** Windows
- **Environment:** Interface + Code Tab

### Theory

The *ElFarol Bar* problem is a classic agent-based economics simulation. The situation is:

- If too many people visit the bar, it becomes overcrowded.
- People want to go only if fewer than a threshold attend.
- No agent knows what others will do.
- Each agent must predict attendance based on past data.

### Key Ideas

#### 1. Memory

Each agent stores a limited history of past attendance.

#### 2. Strategies

Each agent has several prediction strategies.

A strategy is a list of weights used to calculate a predicted attendance.

#### 3. Best Strategy Selection

After each tick, the agent checks which strategy would have given the most accurate prediction and adopts it for the next round.

#### 4. Decision Rule

An agent goes to the bar if predicted attendance  $\leq$  overcrowding threshold.

#### 5. Movement

- o Agents go to either home (green) or bar (blue) patches.
- o Only one turtle can occupy a patch at a time.

This leads to complex social behavior even though each agent follows simple rules.

### **Important Concepts**

<b>Concept</b>	<b>Description</b>
<b>Globals</b>	Shared information (attendance, history, bar/home areas).
<b>Strategies</b>	Weight-based prediction formulas.
<b>Memory-size</b>	How many past weeks an agent
<b>Prediction</b>	Estimated attendance for the next round.
<b>Overcrowding-threshold</b>	Maximum comfortable bar attendance.
<b>move-to-empty-one-of</b>	Ensures one turtle per patch (clean visualization).

### **LAB PROCEDURE**

#### **Step 1: Add Required Interface Elements**

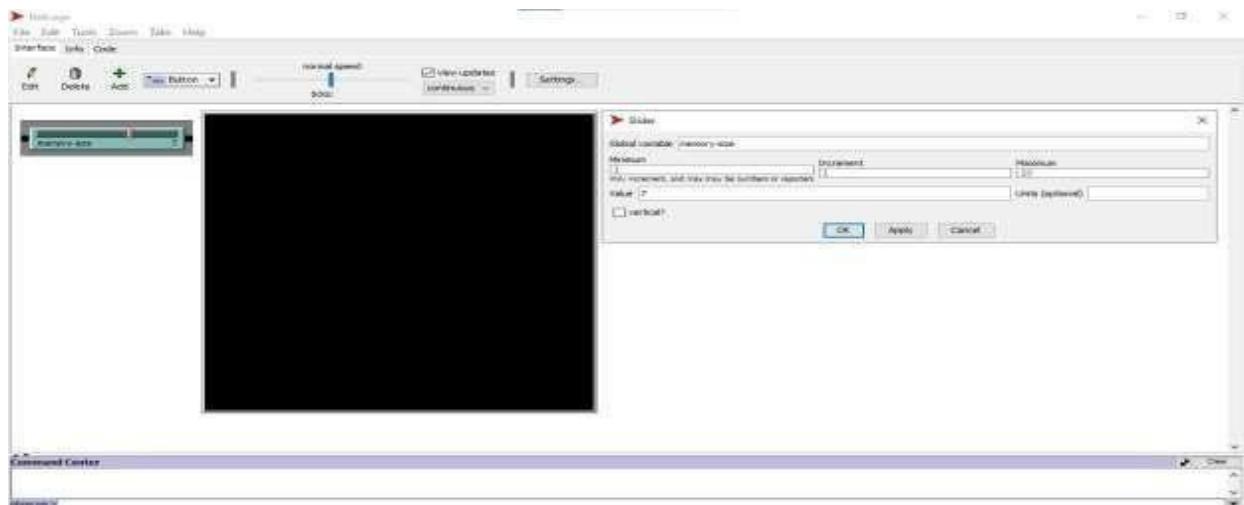
##### **Sliders**

Add these sliders in Interface:

###### 1. **memory-size** o

Min: 1 o Max: 10

o Initial: 7

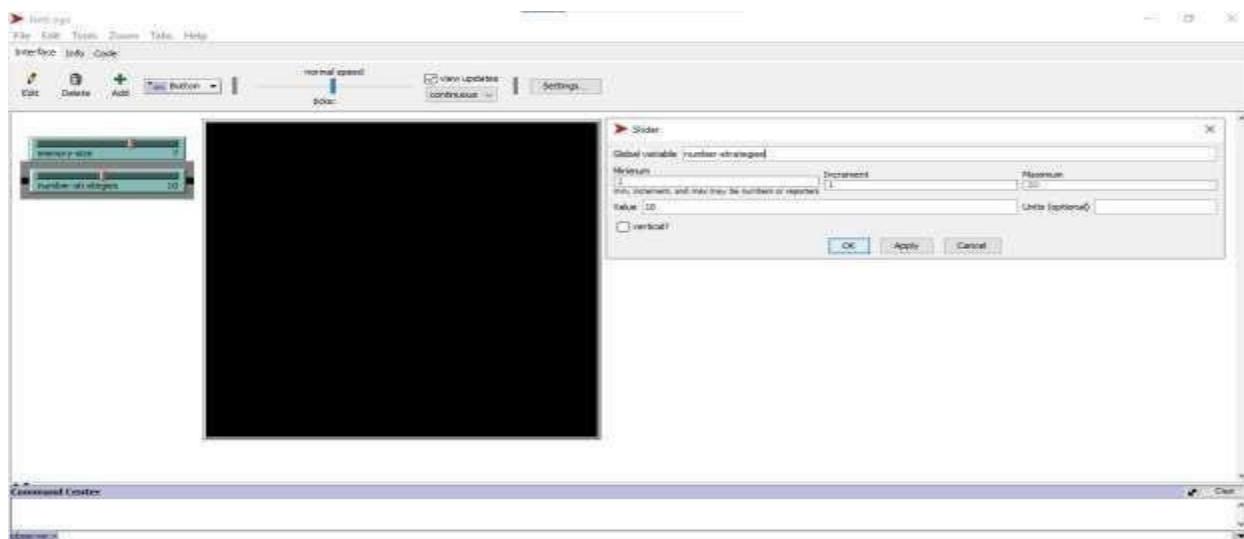


## 2. number-strategies

Min:

1 o Max: 20

o Initial: 10

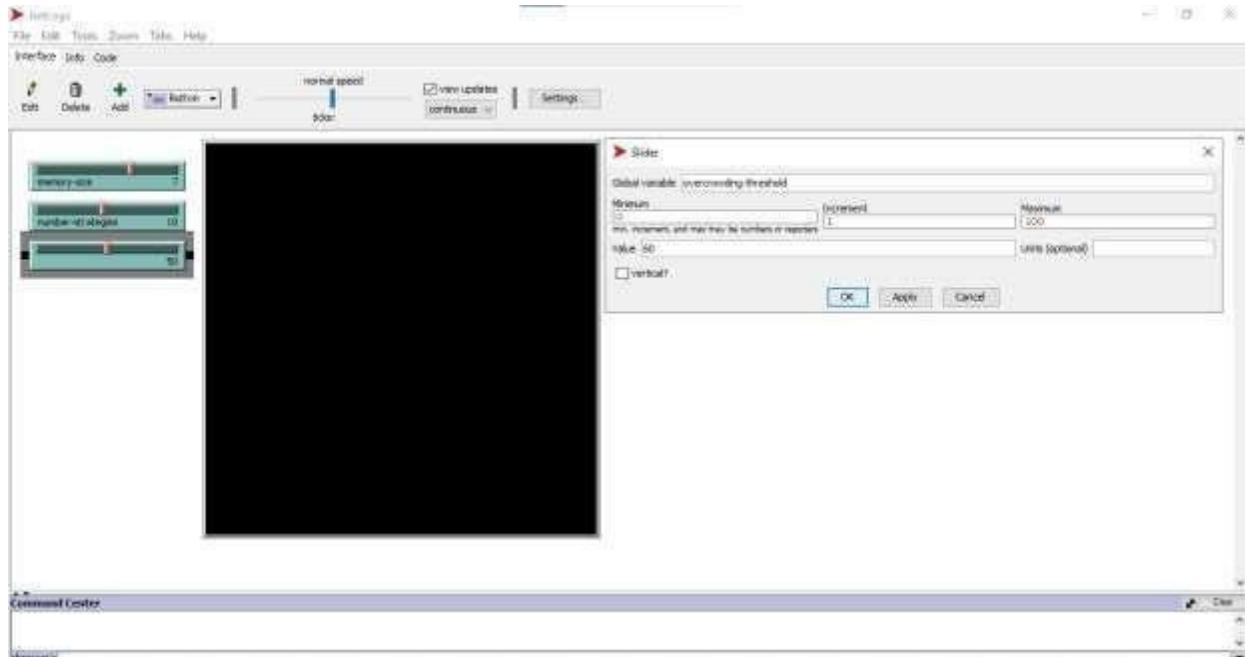


## 3. overcrowding-

**threshold** o Min:

0 o Max: 100 o

Initial: 60

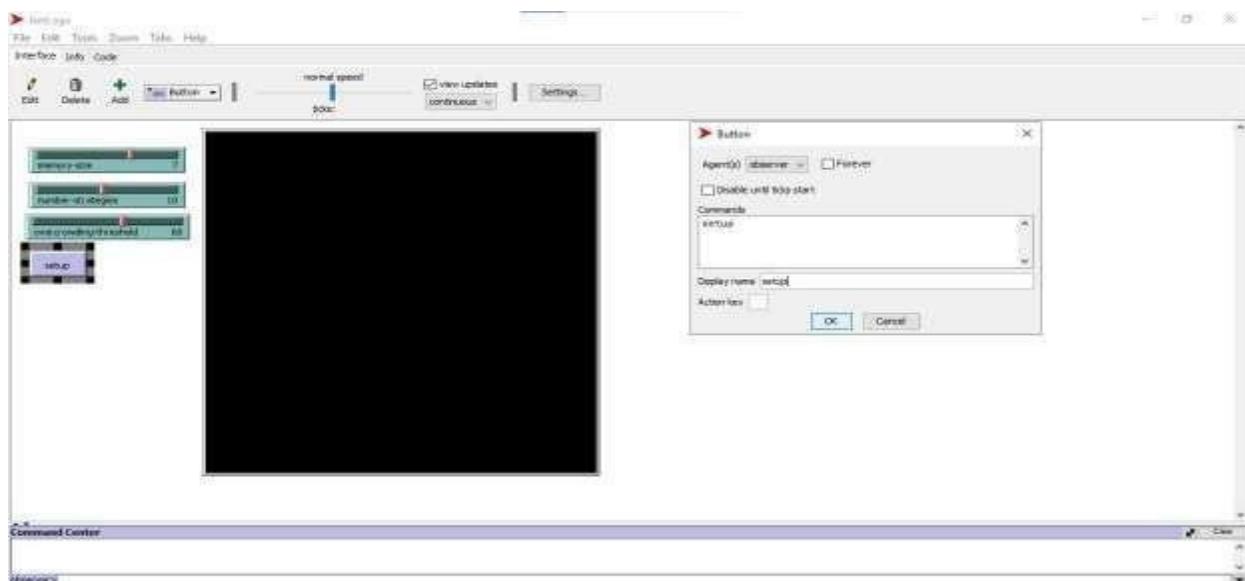


## Buttons

1. setup ◦

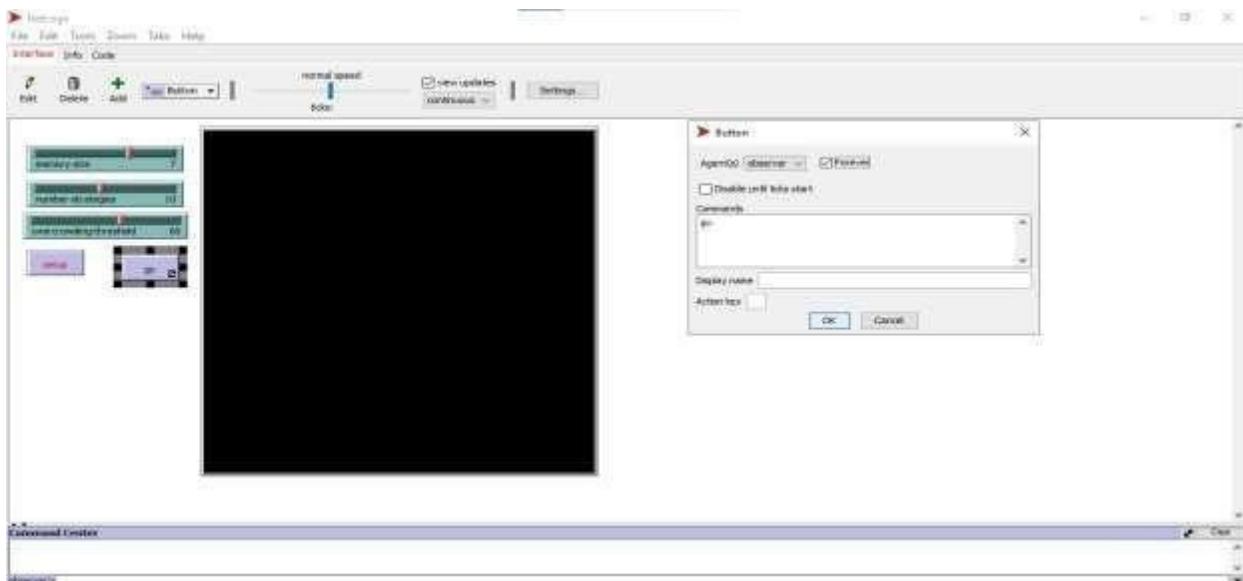
Command: setup ◦

Display name: setup



2. go ◦ Command: go ◦

Check: **Forever**



## Add a Plot

- Right-click → **Plot**
- **Name:** Bar Attendance
- **X axis label:** Time
- **Y axis label:** Attendance
- **X min:** 0
- **X max:** 10
- **Y min:** 0
- **Y max:** 100

### 1. Pen 1

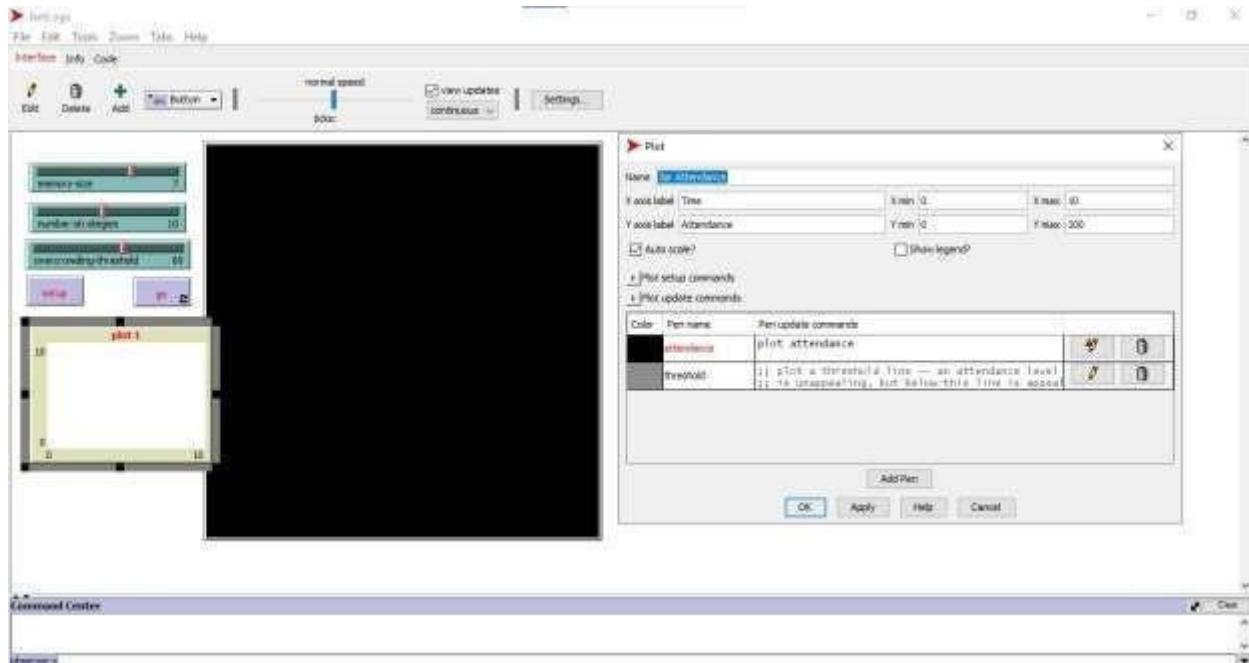
- **Pen name:** attendance
- **Pen update commands:** plot attendance

### 2. Pen 2

- **Pen name:** threshold
- **Pen update commands:**

;; plot a threshold line -- an attendance level above this line makes the bar

`;; is unappealing, but below this line is appealing`  
`plot-pen-reset plotxy 0 overcrowding-threshold`  
`plotxy plot-x-max overcrowding-threshold`



## Step 2: Add the Full Code in the Code Tab

```
globals [ attendance    ;; the current attendance at the bar history    ;; list of past
values of attendance
home-patches      ;; agentset of green patches
representing the residential area
bar-patches;; agentset of blue patches
representing the bar area
crowded-patch ;; patch where we show the
"CROWDED" label
]
```

```
turtles-own [
  strategies    ;; list of strategies
  best-strategy ; index of the
  current best strategy
  attend? ;; true if the agent currently plans to
  attend the bar prediction
  prediction-of-the-bar
  attendance
]
```

```
to setup
  clear-all
  set-default-
  shape turtles "person"
```

```

;; create the 'homes' set home-patches patches with [pycor < 0 or (pxcor <
0 and pycor >= 0)] ask home-patches [ set pcolor green ]

;; create the 'bar' set bar-patches patches with [pxcor > 0 and
pycor > 0] ask bar-patches [ set pcolor blue ]
;; initialize the previous attendance randomly so the agents have a history
;; to work with from the start set history n-values
(memory-size * 2) [random 100]
;; the history is twice the memory, because we need at least a memory worth of
history ;; for each point in memory to test how well the strategies would have worked
set attendance first history

;; use one of the patch labels to visually indicate whether or not the
;; bar is "crowded" ask patch (0.75 * max-pxcor)
(0.5 * max-pycor) [ set crowded-patch self set
plabel-color red
]

;; create the agents and give them random strategies
;; these are the only strategies these agents will ever have though they ;;
can change which of this "bag of strategies" they use every tick create-
turtles 100 [ set color white move-to-empty-one-of home- patches set
strategies n-values number-strategies [random-strategy] set best-
strategy first strategies
update-strategies
]
;; start the clock reset-ticks
end

```

```

to go
;; update the global variables ask crowded-patch
[ set plabel "" ]
;; each agent predicts attendance at the bar and decides whether or not to go ask
turtles [ set prediction predict-attendance best-strategy sublist history 0 memory-
size set attend? (prediction <= overcrowding-threshold) ;; true or false
]

```

```

;; depending on their decision, the agents go to the bar or stay at home
ask turtles [ ifelse attend? [ move-to-empty-one-of bar-patches set
attendance attendance + 1 ]
[ move-to-empty-one-of home-patches ]
]

;; if the bar is crowded indicate that in the view
set attendance count turtles-on bar-patches if
attendance > overcrowding-threshold [ ask
crowded-patch [ set plabel "CROWDED" ]
]

;; update the attendance history
;; remove oldest attendance and prepend latest attendance
  set history fput attendance but-last history ;; the agents
  decide what the new best strategy is ask turtles [ update-
strategies ]

;; advance the clock tick end

;; determines which strategy would have predicted the best results had it been used this round.
;; the best strategy is the one that has the sum of smallest differences between the
;; current attendance and the predicted attendance for each of the preceding
;; weeks (going back MEMORY-SIZE weeks)
;; this does not change the strategies at all, but it does (potentially) change the one
;; currently being used and updates the performance of all strategies to update-strategies
;; initialize best-score to a maximum, which is the lowest possible score let best-score
  memory-size * 100 + 1 foreach strategies [ the-strategy ->      let score 0      let week 1
  repeat memory-size [      set prediction predict-attendance the-strategy sublist history
  week (week + memory-size)      set score score + abs (item (week - 1) history -
  prediction) set week week + 1
]

if (score <= best-score) [      set
  best-score score      set best- strategy
  the-strategy
]

end

;; this reports a random strategy. a strategy is just a set of weights from -1.0 to 1.0 which
;; determines how much emphasis is put on each previous time period when making
;; an attendance prediction for the next time period to-report
random-strategy report n-values (memory-size + 1) [1.0 -
random-float 2.0] end

```

```

;; This reports an agent's prediction of the current attendance
;; using a particular strategy and portion of the attendance history. ;;
More specifically, the strategy is then described by the formula ;;
 $p(t) = x(t - 1) * a(t - 1) + x(t - 2) * a(t - 2) + \dots$ 
;; ... +  $x(t - \text{MEMORY-SIZE}) * a(t - \text{MEMORY-SIZE}) + c * 100$ ,
;; where  $p(t)$  is the prediction at time  $t$ ,  $x(t)$  is the attendance of the bar at time  $t$ ,
;;  $a(t)$  is the weight for time  $t$ ,  $c$  is a constant, and  $\text{MEMORY-SIZE}$  is an external parameter to-report
predict-attendance [strategy subhistory]
;; the first element of the strategy is the constant,  $c$ , in the prediction formula.
;; one can think of it as the the agent's prediction of the bar's attendance ;;
in the absence of any other data
;; then we multiply each week in the history by its respective weight report  $100 * \text{first} \text{ strategy}$ 
+ sum (map [ [weight week] -> weight * week ] butfirst strategy subhistory) end

```

```

;; In this model it doesn't really matter exactly which patch
;; a turtle is on, only whether the turtle is in the home area
;; or the bar area. Nonetheless, to make a nice visualization ;;
this procedure is used to ensure that we only have one ;;
turtle per patch.
to move-to-empty-one-of [locations] ;; turtle procedure
move-to one-of locations while [any? other turtles-
here] [ move-to one-of locations

```

```

]
end

```

The screenshot shows the NetLogo interface with the title bar "EPA Fair - NetLogo". The menu bar includes File, Edit, Tools, Zoom, Tabs, Help, and a separator line. Below the menu is a toolbar with icons for New, Open, Save, Undo, Redo, and a separator line. The "Procedures" tab is selected, indicated by a blue border. To the right of the tab are two checkboxes: "Indent automatically" and "Code Tab in separate window". The main workspace displays the following NetLogo code:

```

globals [
  attendance          ;;; the current attendance at the bar
  history             ;;; list of past values of attendance
  home-patches         ;;; agentset of green patches representing the residential area
  bar-patches          ;;; agentset of blue patches representing the bar area
  crowded-patch       ;;; patch where we view the "CROWDED" level
]

turtles-own [
  strategies          ;;; list of strategies
  best-strategy        ;;; index of the current best strategy
  attend?              ;;; true if the agent currently plans to attend the bar
  prediction           ;;; current prediction of the bar's attendance
]

to setup
  clear-all
  set-default-shape turtles "person"
  ; Create bar "home"
  set home-patches patches with [pxcor < 0 or (pxcor > 0 and pycor > 0)]
  ask home-patches [ set color green ]
  ; Create the "bar"
  set bar-patches patches with [pxcor > 0 and pycor < 0]
  ask bar-patches [ set color blue ]
  ; Initialize the previous attendance randomly as the agents have a history
  ; to work with from the start
  set history evalunes (memory-size * 2) [random 100]
  ; The history is twice the memory, because we need at least a memory worth of history
  ; for each point in memory to test how well the strategies would have worked

```

```

▶ ▶ ▶ Pavol - NetLogo
File Edit Tools Zoom Tabs Help
Interface Info Code
Find... Check Procedures □ Indent automatically □ CodeTab in separate window
set attendance first-history
; use one of the patch labels to visually indicate whether or not the
; bar is "crowded"
ask patch (0.75 * max-xcor) (0.5 * max-ycor) [
  set crowded-patch self
  set alabel "bar red"
]
; create the agents and give them custom strategies
; these are the only strategies these agents will ever have though they
; can change which of this "bag of strategies" they use every tick
create-turtles 100 [
  set color white
  move-to-empty-one-of home-patches
  set strategies c-values number-strategies [random-strategy]
  set best-strategy first strategies
  update-strategies
]
; start the clock
reset-ticks
end

```

```

▶ ▶ ▶ Pavol - NetLogo
File Edit Tools Zoom Tabs Help
Interface Info Code
Find... Check Procedures □ Indent automatically □ CodeTab in separate window
to go
; update the global variables
ask crowded-patch [ set alabel "" ]
; each agent predicts attendance at the bar and decides whether or not to go
ask turtles [
  set prediction predict-attendance best-strategy sublist history 0 memory-size
  set attendif (prediction > overcrowding-threshold) ; true or false
]
; depending on their decision, the agents go to the bar or stay at home
ask turtles [
  ifelse attendif [
    move-to-empty-one-of bar-patches
    set attendance attendance + 1
    [ move-to-empty-one-of home-patches ]
  ]
  ; If the bar is crowded indicate that in the size
  set attendance count turtles-on bar-patches
  if attendance > overcrowding-threshold [
    ask crowded-patch [ set alabel "OBNOX" ]
  ]
  ; update the attendance history
  ; remove oldest attendance and prepare latest attendance
  set history put attendance but-last history
  ; the agents decide what the new best strategy is
  ask turtles [ update-strategies ]
  ; advance the clock
  tick
]
end

```

```

▶ ▶ ▶ Pavol - NetLogo
File Edit Tools Zoom Tabs Help
Interface Info Code
Find... Check Procedures □ Indent automatically □ CodeTab in separate window
; determines which strategy would have predicted the best results had it been used this round.
; the best strategy is the one that has the sum of absolute differences between the
; current attendance and the predicted attendance for each of the preceding
; weeks (going back MEMORY-SIZE weeks)
; this does not change the strategies at all, but it does (potentially) change the way
; we currently keep track and update the performance of all strategies
; update-strategies
; initialize best-score to a maximum, which is the lowest possible score
let best-score memory-size * 100 + 1
foreach strategies [ the-strategy ]->
  let score 0
  let week 1
  repeat memory-size [
    set prediction predict-attendance the-strategy sublist history week (week + memory-size)
    set score score + abs (item (week + 1) history - prediction)
    set week week + 1
  ]
  if (score < best-score) [
    set best-score score
    set best-strategy the-strategy
  ]
]
; this reports a random strategy. a strategy is just a set of weights from -1.0 to 1.0 which
; determines how much emphasis is put, at each previous time period, on making
; an attendance prediction for the next time period.
; report-random-strategy
  report invalids (memory-size + 1) [1.0 - random-float 1.0]
end

```

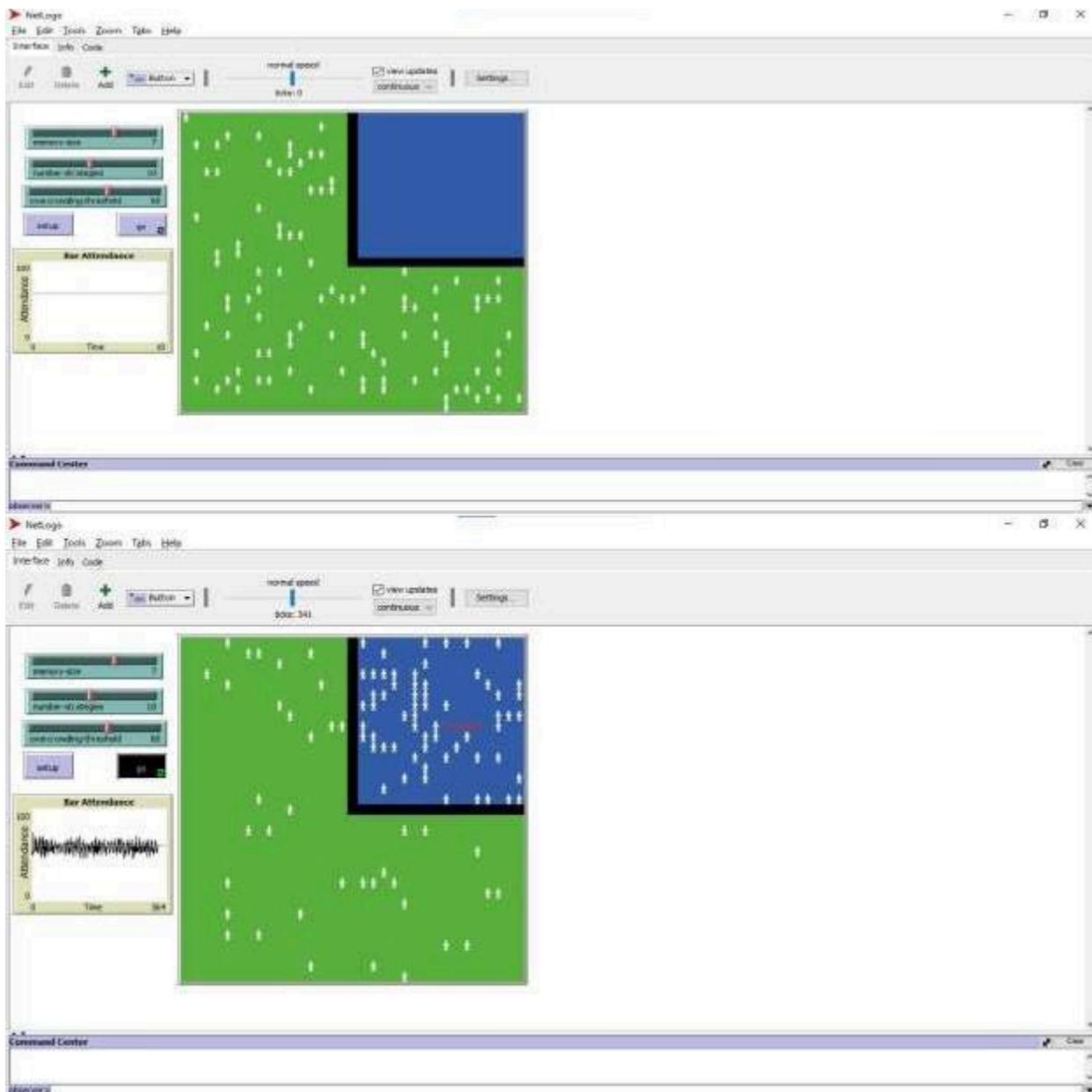
```

; This reports an agent's prediction of the current attendance
; using a particular strategy and portion of the attendance history.
; More specifically, the strategy is then described by the formula
;  $\hat{a}(t) = \hat{a}(t-1) + a(t-2) * a(t-3) * \dots * a(t-MEMORY-SIZE) * a(t-MEMORY-SIZE+1) * \dots * a(t)$ 
; where  $\hat{a}(t)$  is the prediction at time  $t$ ,  $a(t)$  is the attendance of the bar at time  $t$ ,
;  $a(t)$  is the weight for time  $t$ ,  $c$  is a constant, and MEMORY-SIZE is an external parameter.
; No-report predict-attendance [strategy subhistory]
; is the first element of the strategy is the constant,  $c$  is the predictive formula.
; One can think of it as the the agent's prediction of the bar's attendance.
; In the absence of any other data
; Then we multiply each week in the history by its respective weight.
; report 100 * first strategy + sum (w * [weight week] > weight * week) butfirst strategy subhistory
end.

; In this model it doesn't really matter exactly which patch
; a turtle is on, only whether the turtle is in the base area
; or the bar area. Nonetheless, to make a nice visualization
; this procedure is used to ensure that we only have one
; turtle per patch.
move-to-empty-one-of [locations] ;;; turtle procedure
move-to one-of locations
while [any? other turtles here] [
  move-to one-of locations
]
end.

```

## Results:

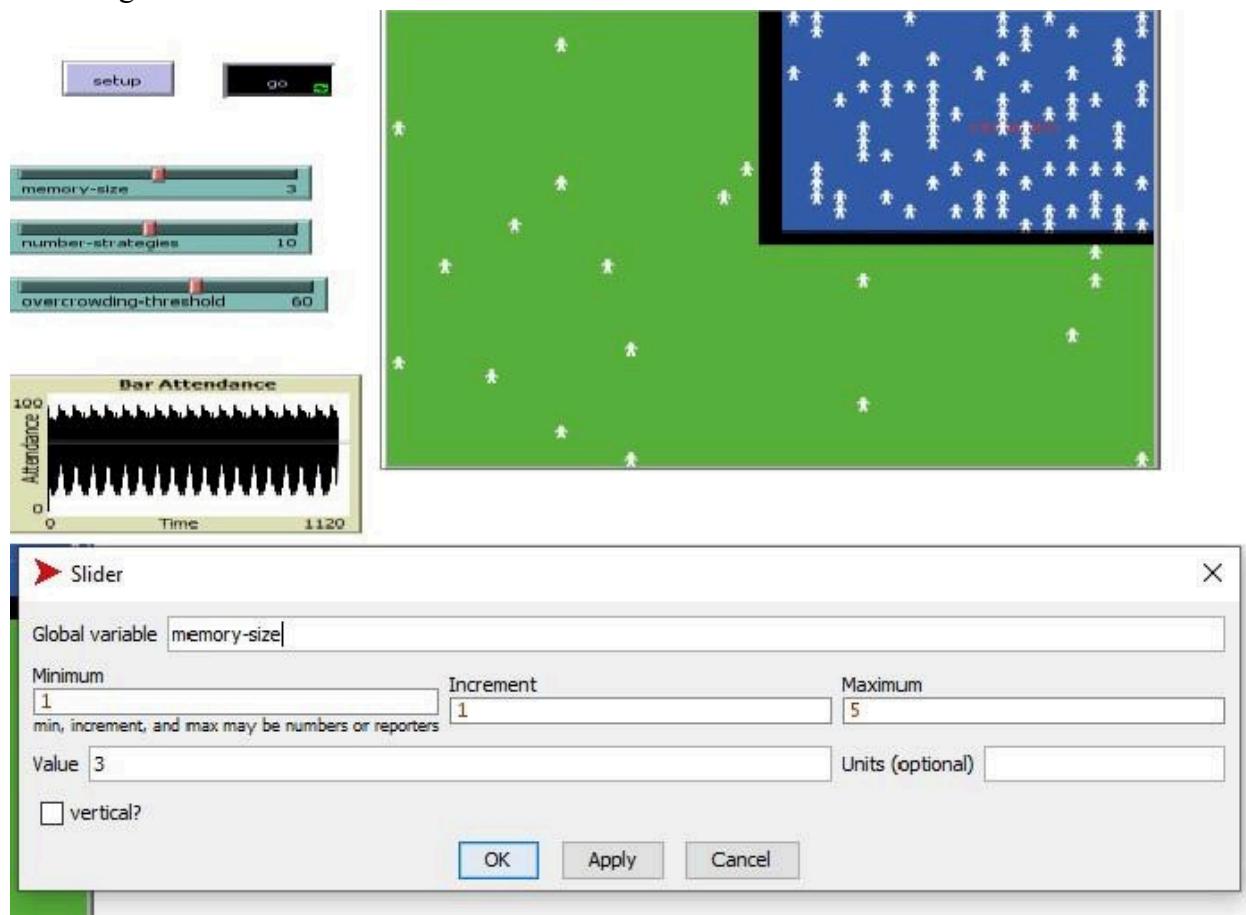


## Observation

- Attendance fluctuates each tick based on predictions.
- When too many agents guess low attendance, the bar becomes crowded.
- The model displays CROWDED when attendance exceeds the threshold.
- Agents adapt their strategies over time, improving predictions.
- Complex group behavior emerges from simple rules.

## STUDENT TASK

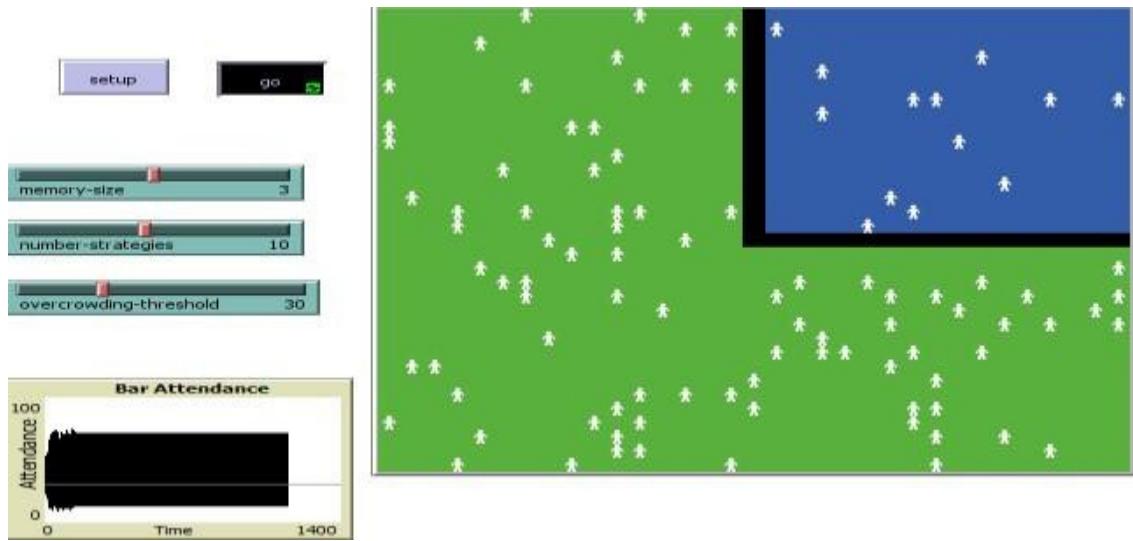
1. Run the model with different memory-size values and observe how prediction accuracy changes.



## Observation

With a **memory-size of 3**, agents used the past three rounds of attendance to predict the next. Predictions were moderately accurate, leading to some fluctuations in bar attendance, but overall the agents were able to avoid extreme overcrowding most of the time.

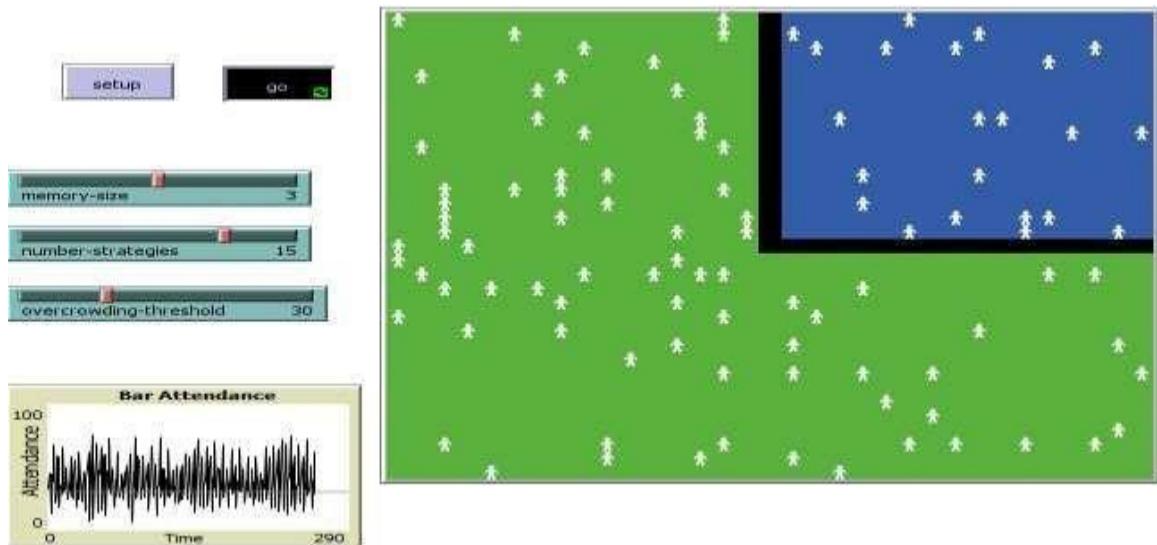
2. Change the overcrowding-threshold and analyze its effect on agent attendance.



## OBSERVATION

Low threshold → 30: Bar reaches "crowded" status quickly → fewer agents decide to attend → lower attendance.

3. Increase number-strategies and check if behavior becomes more stable.

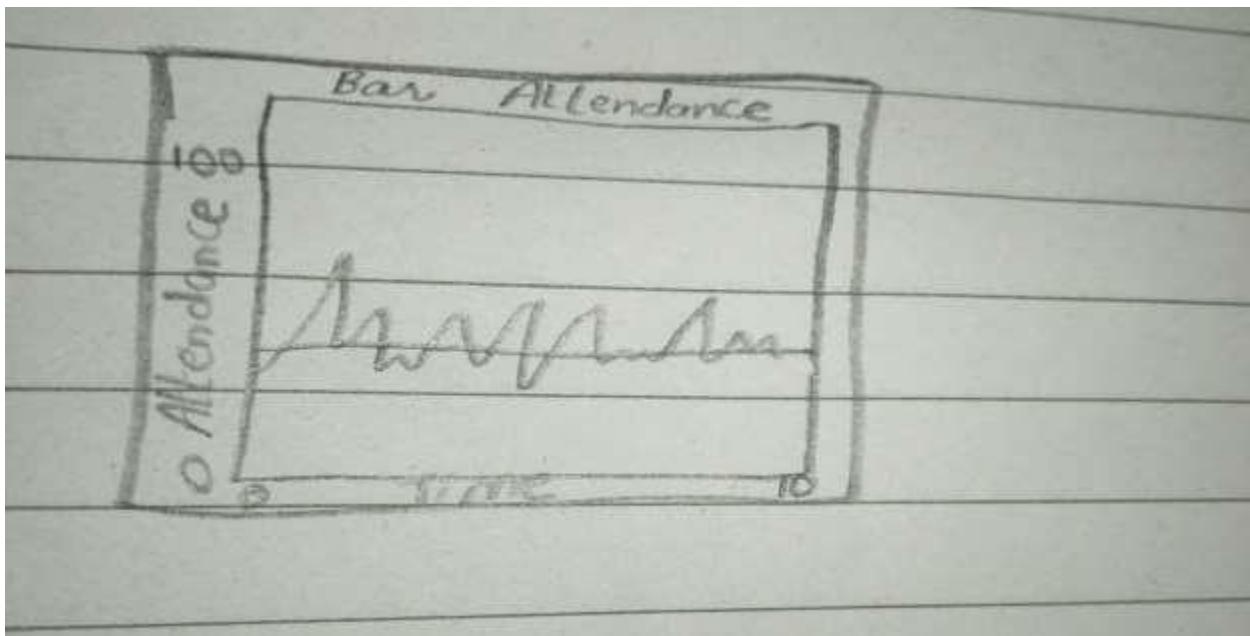


## OBSERVATION

With **15 strategies per agent**, the model allows agents to choose from when predicting bar attendance. This allowed agents to adapt better to past attendance patterns, resulting in more stable behavior and smoother attendance fluctuations compared to models with fewer strategies. 4. Compare early ticks vs late ticks — do predictions improve?

- In the **early ticks**, agents had limited history to base their predictions on, so attendance predictions were less accurate and fluctuated more.
- In the **late ticks**, as more attendance history accumulated, agents chose better-performing strategies, leading to more accurate predictions and smoother attendance patterns.

5. Draw a graph of attendance over time in your notebook.



### Post-Lab Questions

#### 1. Why does each agent need multiple prediction strategies?

Multiple prediction strategies allow agents to adapt to different situations and choose the most successful approach based on past outcomes.

#### 2. How does memory-size influence the agent's decision-making?

Memory-size determines how much past information an agent can use, affecting its ability to make accurate predictions and improve decisions over time.

#### 3. What is the importance of the overcrowding threshold?

The overcrowding threshold prevents too many agents from choosing the same option, promoting diversity in decisions and avoiding resource depletion.

#### 4. Why is it necessary to update the best strategy every tick?

Updating the best strategy each tick ensures agents adapt to changing conditions and continue using the most successful strategy.

## **5. How does the model demonstrate emergent behavior?**

The model shows emergent behavior as complex patterns arise from simple agent interactions, such as the overall distribution of heroes and cowards over time.

## Lab 9: Brave and Cowardly Behavior Simulation in NetLogo

### Objective

- To simulate two types of turtles: **brave** and **cowardly**.
- To assign each turtle a friend and an enemy.
- To program two different behaviors:
  - brave turtles move toward danger
  - cowardly turtles move away from danger
- To run the model using a continuous go loop.
- To introduce reproducible experiments using the preset procedure.

### Language/Tool

- **Tool:** NetLogo6.4.0
- **Platform:** Windows
- **Environment:** Interface + Command Center + Code Tab

### Theory

This model uses two simple ideas:

#### 1. Brave Behavior

- Brave turtles move towards the midpoint between their friend and enemy.
- This behavior simulates risk-taking or approaching danger.

#### 2. Cowardly Behavior

- Coward turtles use their friend as a shield.
- They move to a point behind their friend, away from the enemy.

#### 3. Friend and Enemy Selection

- Each turtle chooses:
  - 1 friend

- 1 enemy

- These relationships guide movement.

#### 4. Chooser-Based Personalities • The user selects from: brave, cowardly, or mixed

- Determines how turtles are colored and how they behave.

### Lab Procedure

#### Step 1: Add Interface Items

##### Add a Chooser:

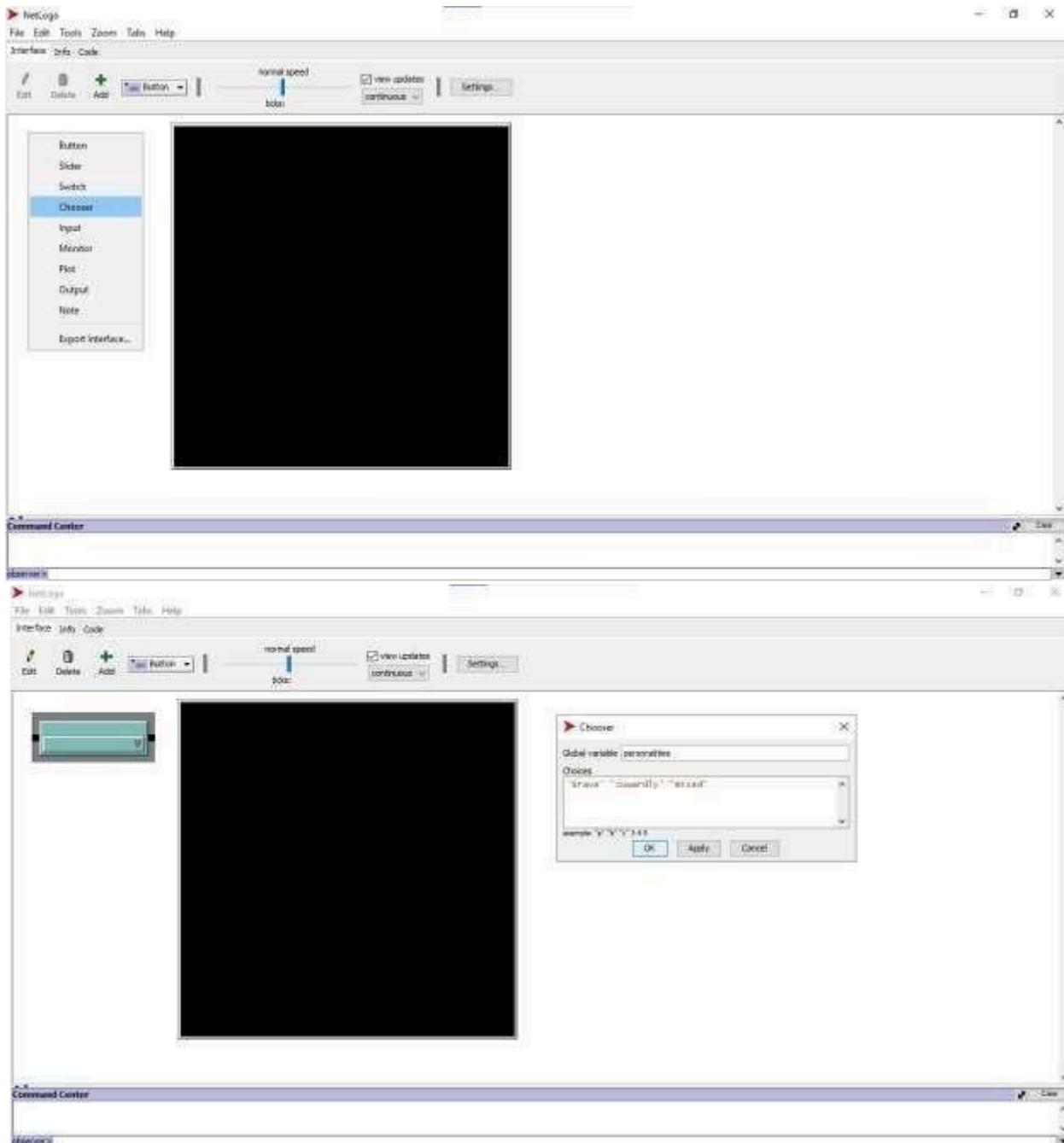
1. Go to the **Interface** tab.

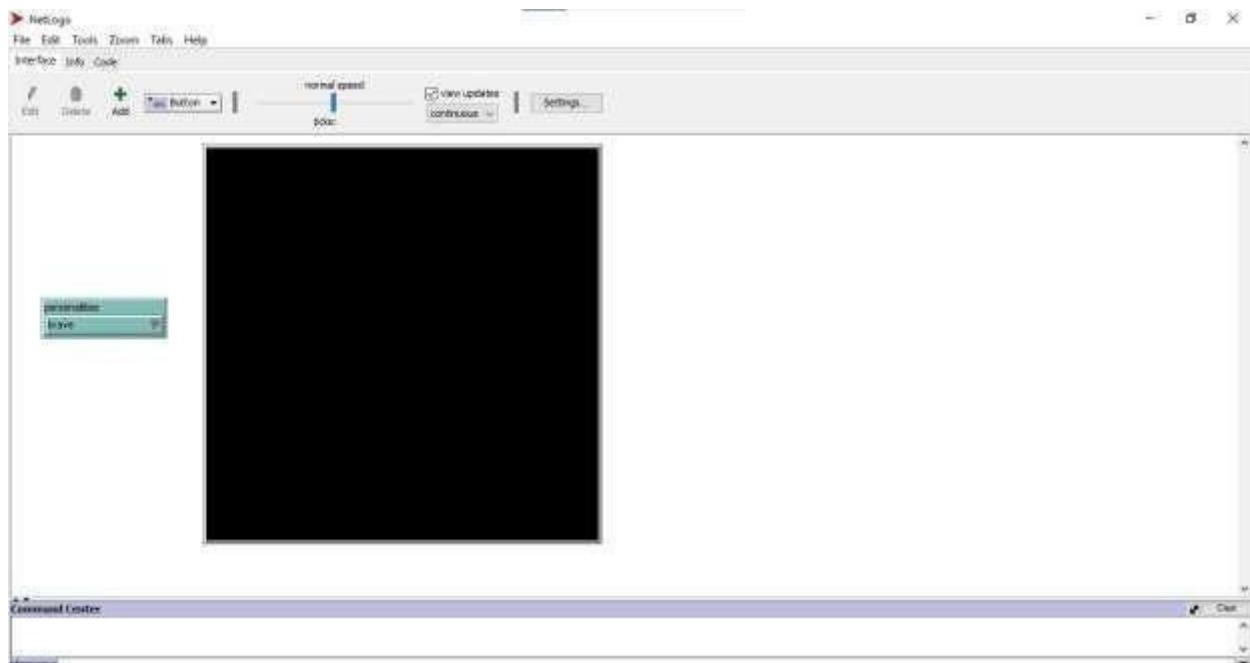
2. Right-click → select **Chooser**.

3. Set:

- o **Name:** personalities

- o **Choices:** "brave" "cowardly"  
"mixed"





**Add a Slider:** 1. Right-click →

### Slider

2. Set:

o **Name:**

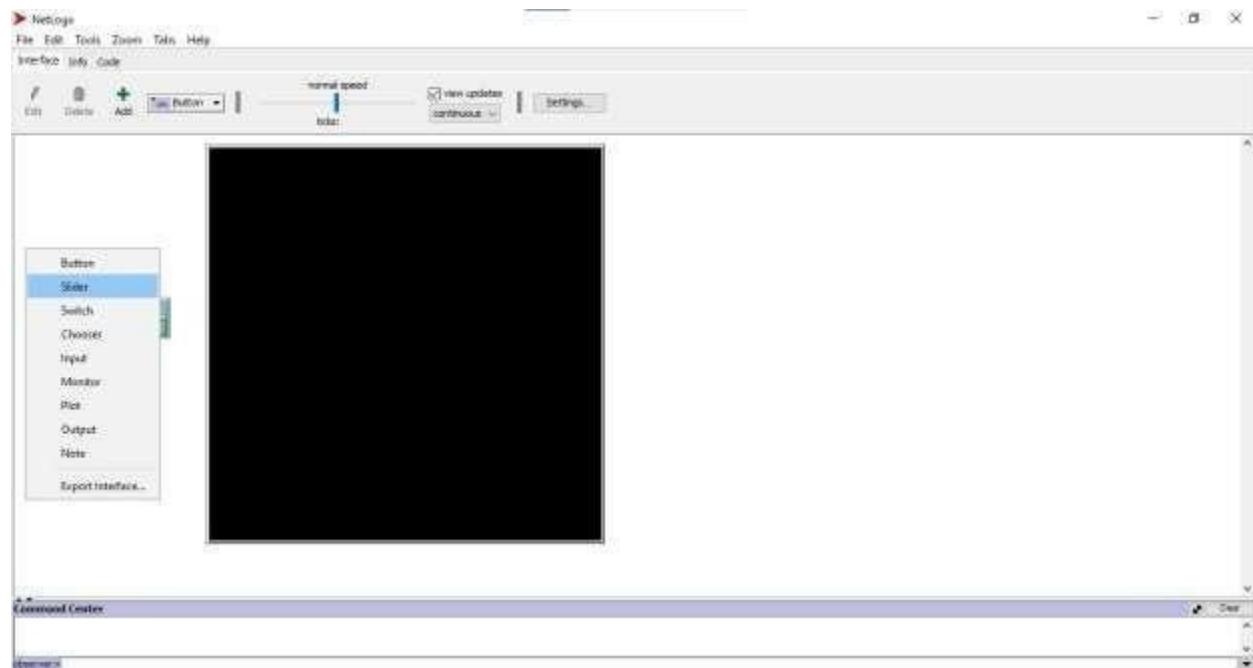
number o

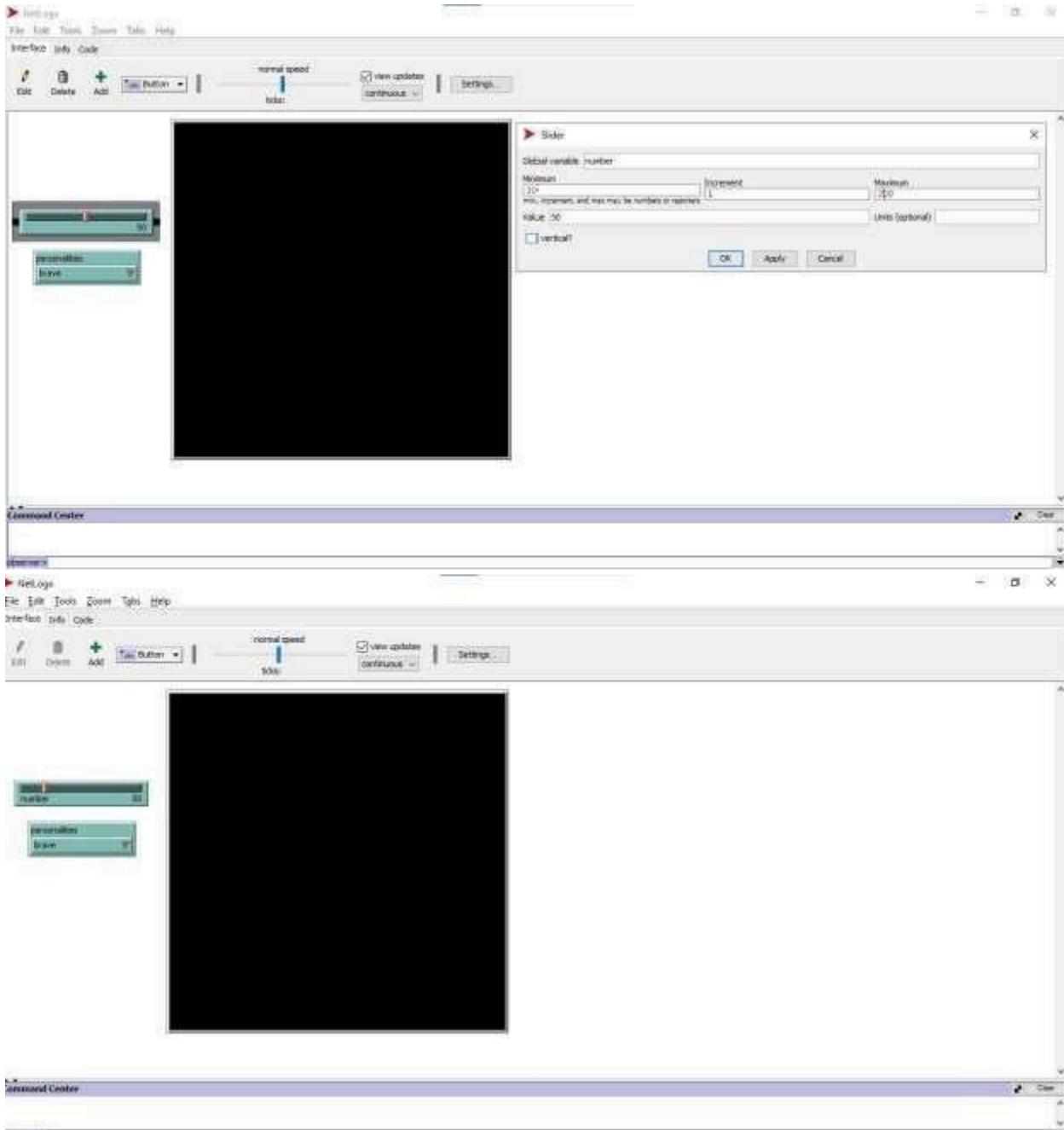
**Min:** 10 o

**Max:** 200

o **Initial**

**value:** 50

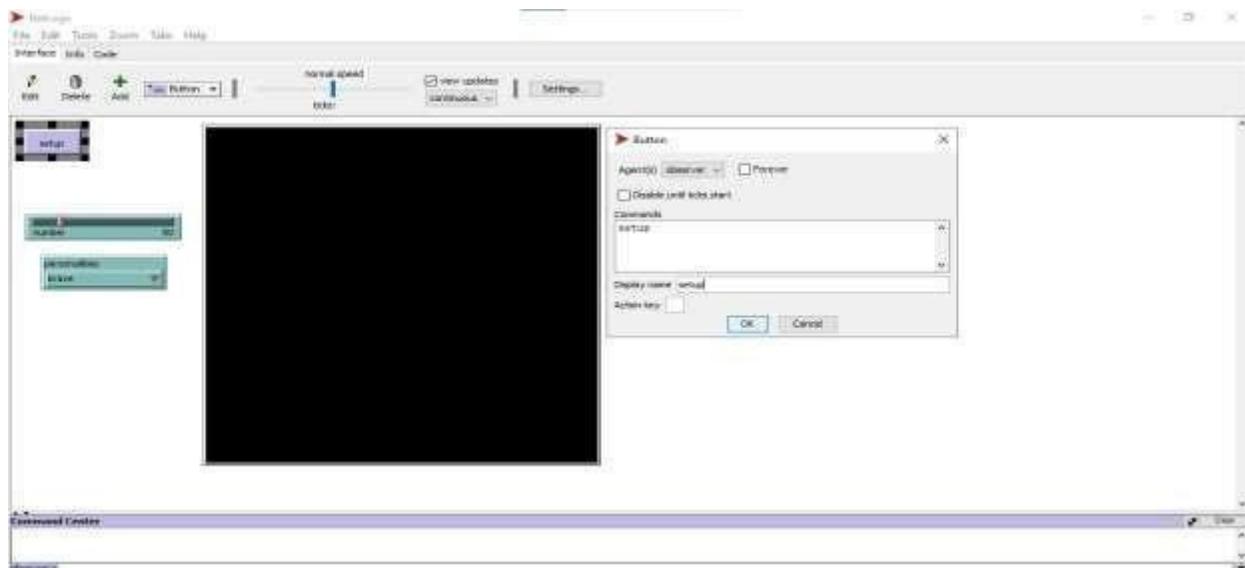




### Add Buttons:

#### 1. Button 1:

- o Comm  
and:  
setup
- o Name:  
setup

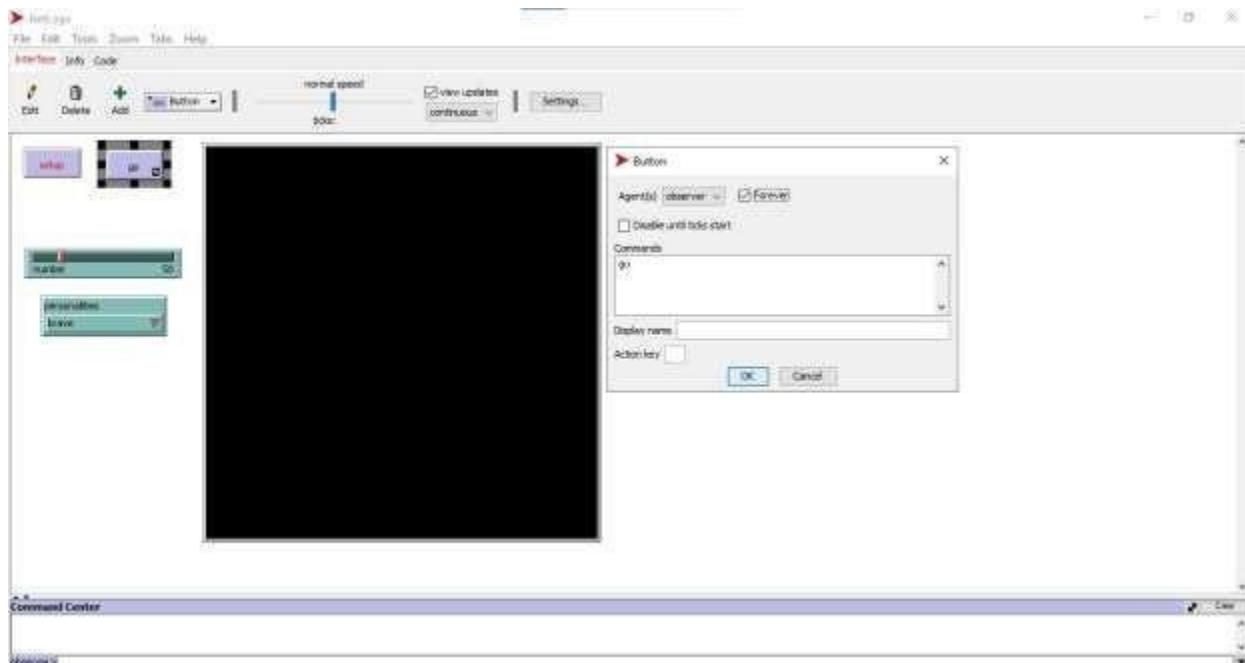


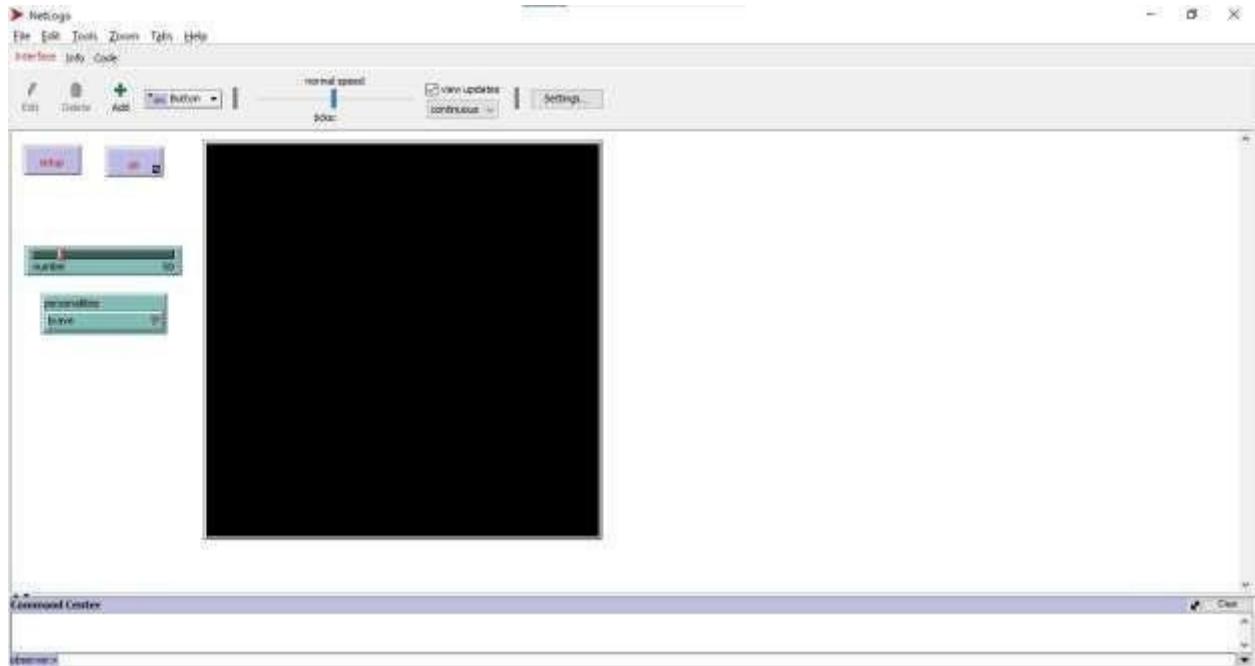
## 2. Button 2:

- Command: go ○

Check:

**Forever**





Your interface is now ready.

## Step 2: Add the Complete Code to the Code Tab

Now write below code the **Code Tab**:

turtles-own [ friend enemy]

to setup clear-all ask patches [ set pcolor white ] ;; create a blank

background create-turtles number [ setxy random-xcor  
random-ycor

;; set the turtle personalities based on chooser if

(personalities = "brave") [ set color blue ] if

(personalities = "cowardly") [ set color red ]

if (personalities = "mixed") [ set color one-of [ red blue]]

;; choose friend and enemy targets set

friend one-of other turtles

```

set enemy one-of other turtles
]
reset-ticks end to go ask turtles [ if
(color = blue) [ act-bravely ] if
(color
= red) [ act-cowardly ]
]
tick
end to act-
bravely
;; move toward the midpoint of your friend and enemy facexy
([xcor] of friend + [xcor] of enemy) / 2
([ycor] of friend + [ycor] of enemy) / 2 fd 0.1 end
to act-cowardly
;; put your friend between you and your enemy facexy [xcor]
of friend + ([xcor] of friend - [xcor] of enemy) / 2 [ycor] of friend
+ ([ycor] of friend - [ycor] of enemy) / 2 fd 0.1 end
to preset [ seed ]
;; sets up the model for use with a particular random seed and constant
;; model parameters, so that a particular pattern can be re-created. set
personalities "mixed" set number 68 random-seed seed setup end

```

```

> NetLogo
File Edit Tools Zoom Tabs Help
model-info Code
Find... Check | Procedures |  Indent automatically  Code Tab in separate window
turtles-on [ friend enemy ]
to setup
  clear-all
  ask patches [ set color white ] ;; create a blank background
  create-turtles number [
    setxy random-xcor random-ycor
    ;; set the turtle personalities based on sliders
    if (personality = "brave") [ set color blue ]
    if (personality = "cowardly") [ set color red ]
    if (personality = "mixed") [ set color green [ red blue ] ]
  ]
  ;; choose friend and enemy targets
  set friend one-of other-turtles
  set enemy one-of other-turtles
]
reset-ticks
end

to go
  ask turtles [
    if (color = blue) [ act-bravely ]
    if (color = red) [ act-cowardly ]
  ]
  tick
end

```

```

> NetLogo
File Edit Tools Zoom Tabs Help
model-info Code
Find... Check | Procedures |  Indent automatically  Code Tab in separate window
to act-bravely
  ;; move toward the midpoint of your friend and enemy
  facexy ([xcor] of friend + [xcor] of enemy) / 2
  ( [ycor] of friend + [ycor] of enemy) / 2
  fd 0.1
end

to act-cowardly
  ;; put your friend between you and your enemy
  facexy ([xcor] of friend + ([xcor] of friend - [xcor] of enemy) / 2
  ( [ycor] of friend + ([ycor] of friend - [ycor] of enemy) / 2
  fd 0.1
end

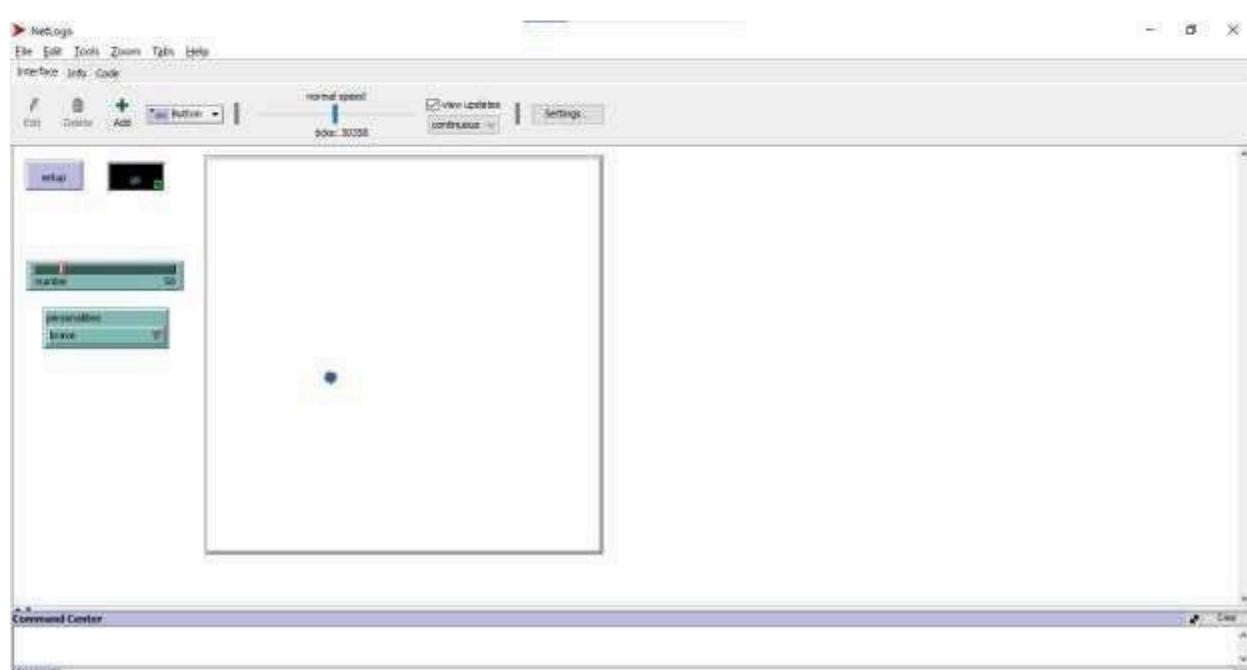
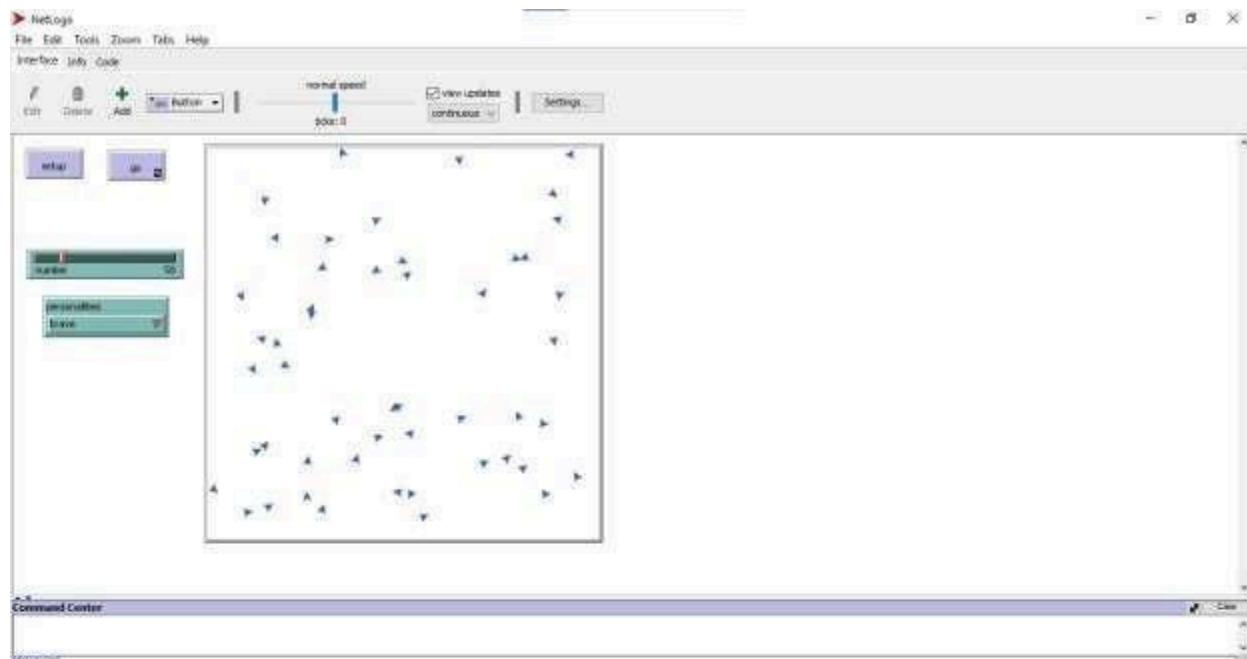
to preset [ seed ]
  ;; sets up the model to use with a particular random seed and constant
  ;; model parameters, so that a particular pattern can be re-created
  set personality "mixed"
  set number 48
  random-seed seed
  setup
end

```

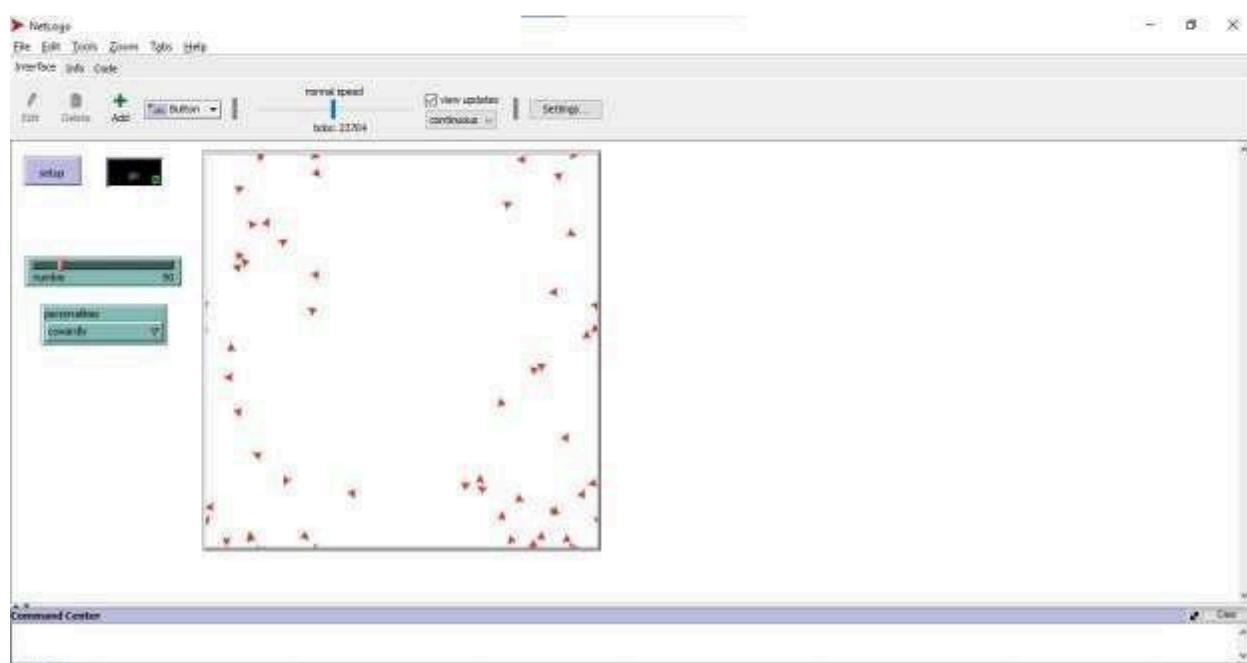
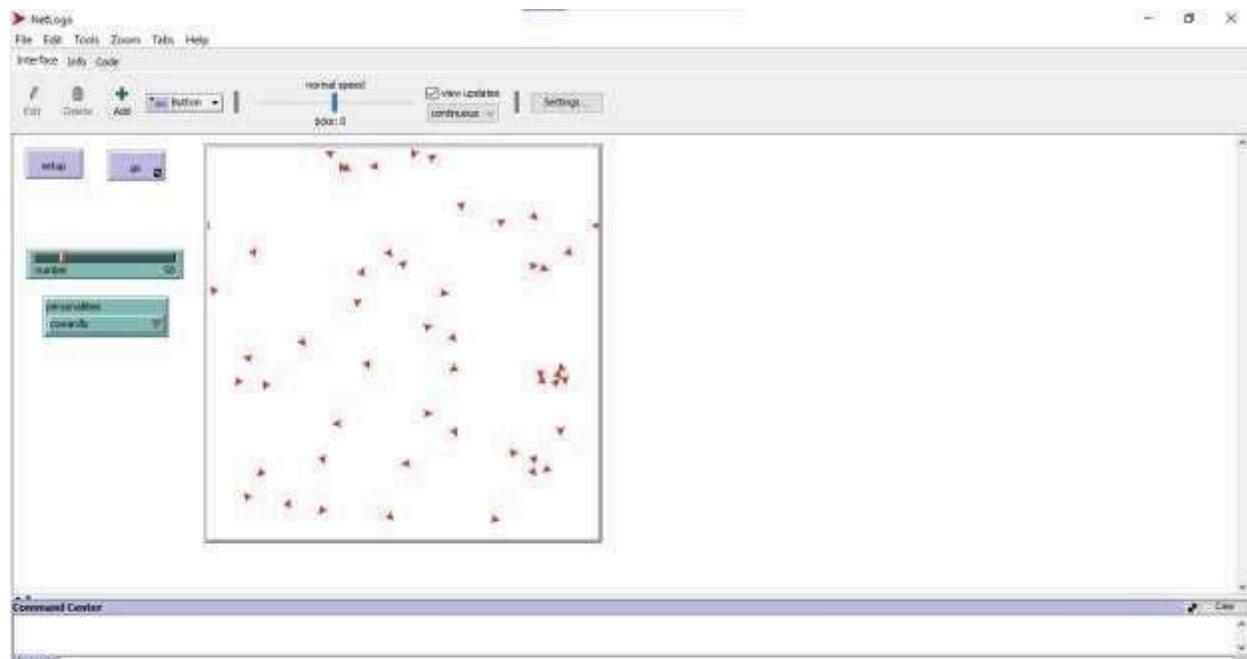
### Step 3: Run the Model

1. Select **brave**, **cowardly**, or **mixed** from chooser.
2. Set numberofturtles using the slider.
3. Click **setup**.
4. Click **go** (which runs forever).

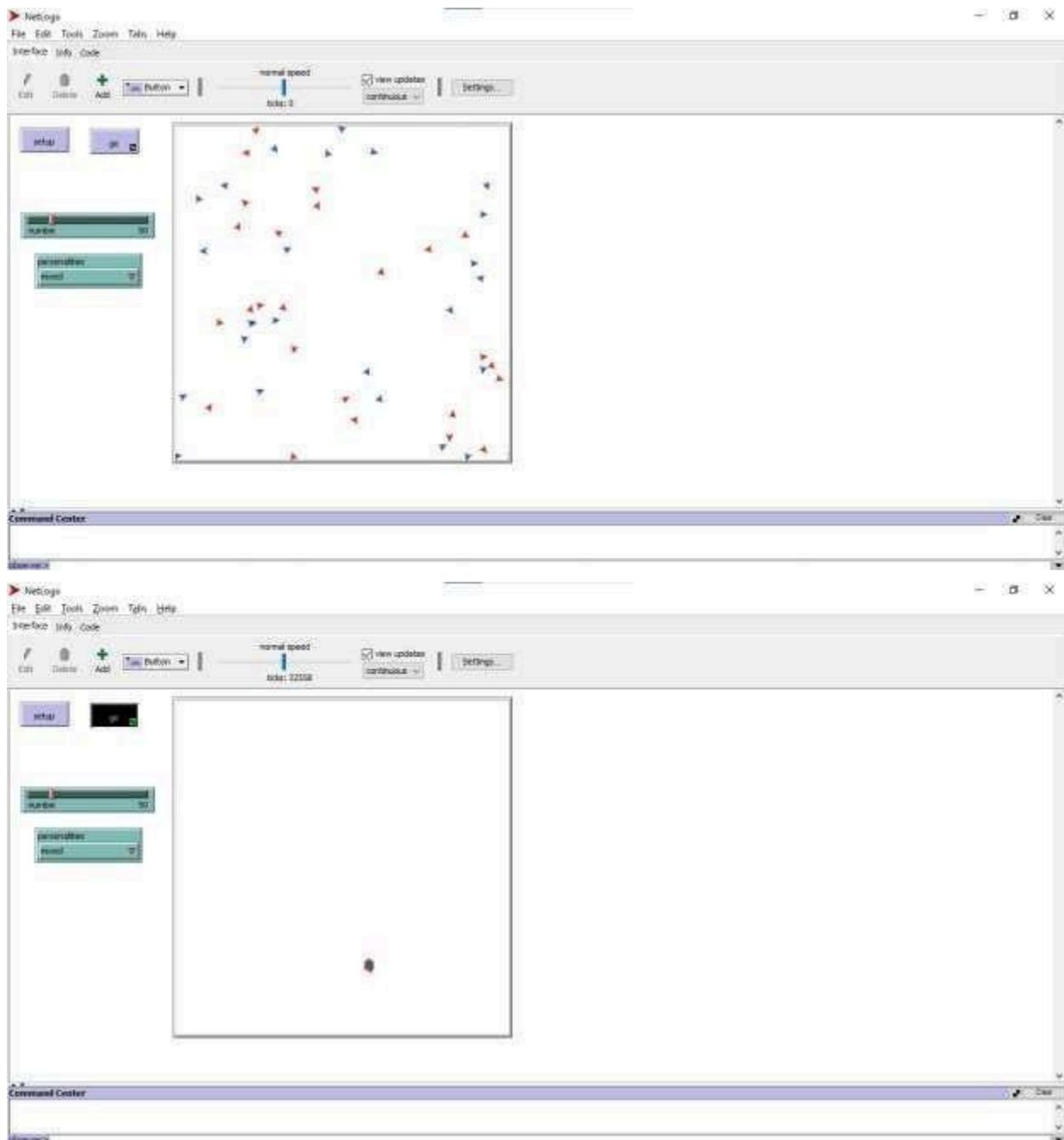
For **brave**



**For Cowardly**



For Mixed



You will see:

- Blue turtles (brave) move toward conflict.
- Red turtles (cowardly) hide behind their friends.
- Mixed mode creates a dynamic blend of behaviors.

#### Additional Practice Commands

Try these after setup:

**Highlight enemies** ask enemy [ set pcolor

yellow ] ] **Show friends in**

**green:**

ask turtles[ask friend [ set pcolor green]]

**Slow motion:** set speed

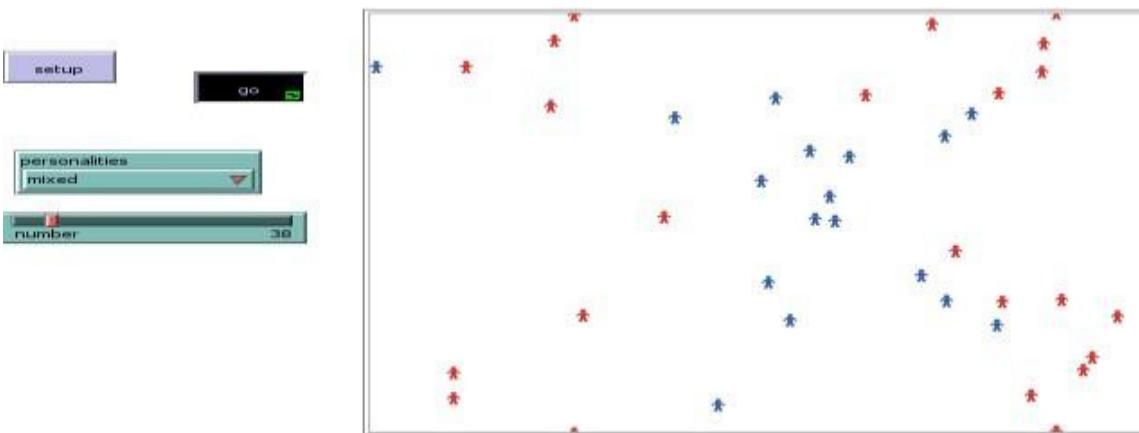
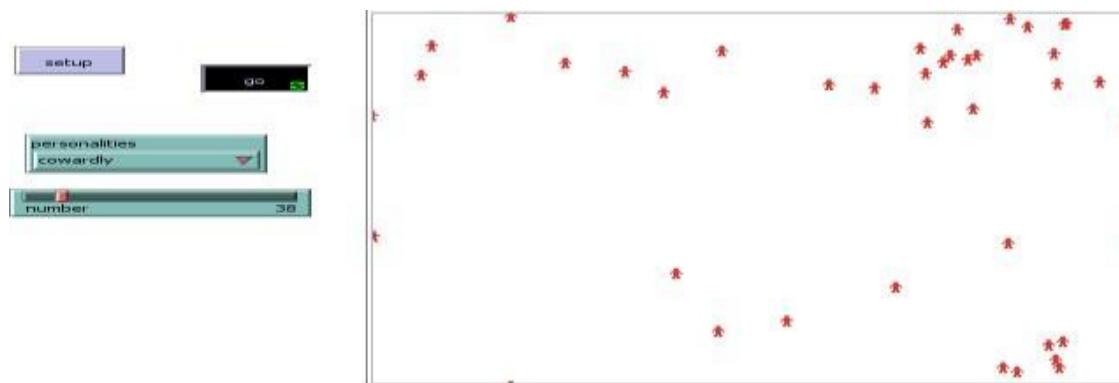
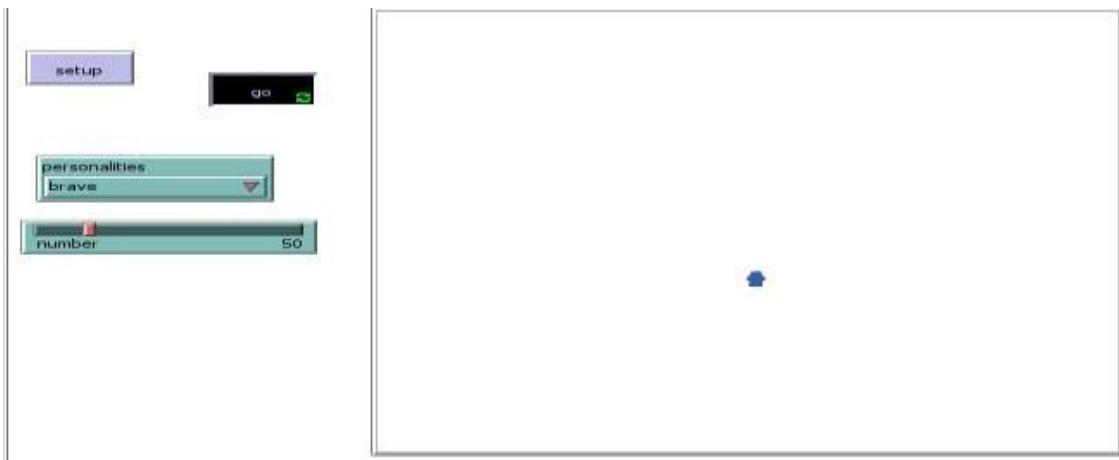
0.3

### **Observations**

- Blue turtles tend to cluster in zones of conflict.
- Red turtles form small groups behind stronger turtles.
- Movement is smooth because turtles use continuous turning (facexy).
- Friend–enemy relationships create interesting social dynamics.

## STUDENT TASK

1. Test brave-only, cowardly-only, and mixed models.



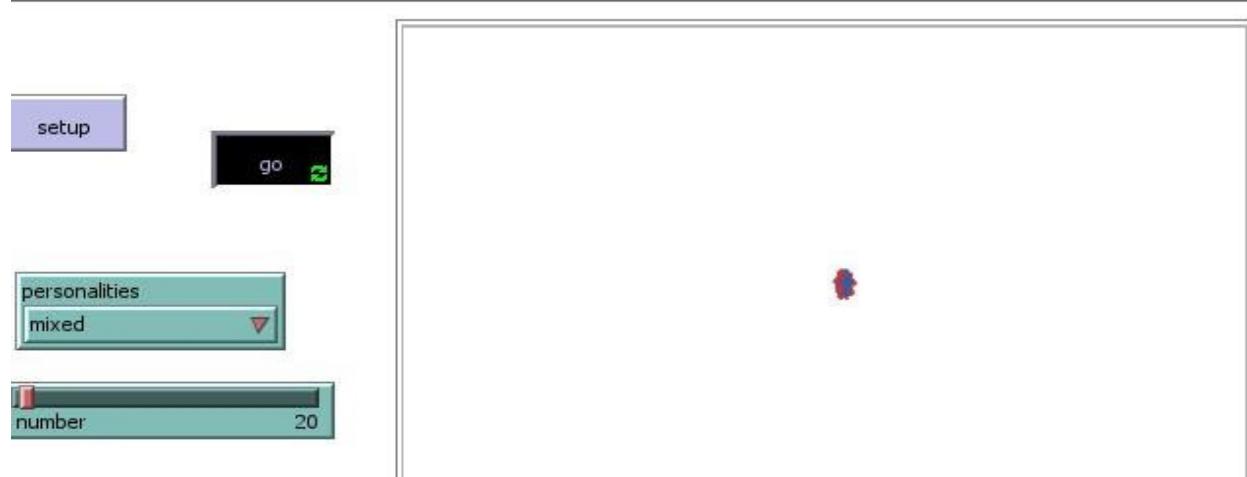
### Observation

**Brave-only:** All turtles move toward midpoints, leading to frequent clustering and interaction.

**Cowardly-only:** Turtles avoid direct encounters, spreading out more evenly.

**Mixed:** A combination of clustering (brave) and avoidance (cowardly) creates dynamic patterns that are more complex than single-type models.

2. Change turtle count and observe movement patterns.



## OBSERVATION

- **Low count (e.g., 20):** Turtles are spread out; interactions are fewer and clustering is minimal.

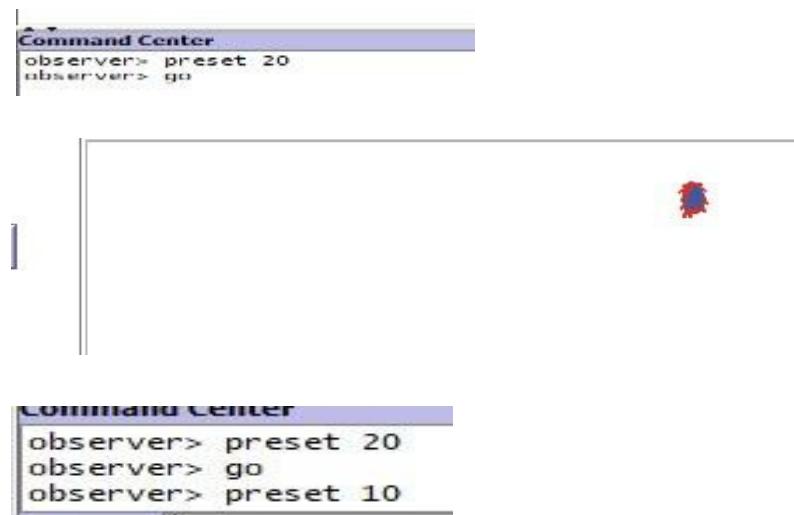
More interactions occur; small clusters may form among brave turtles.

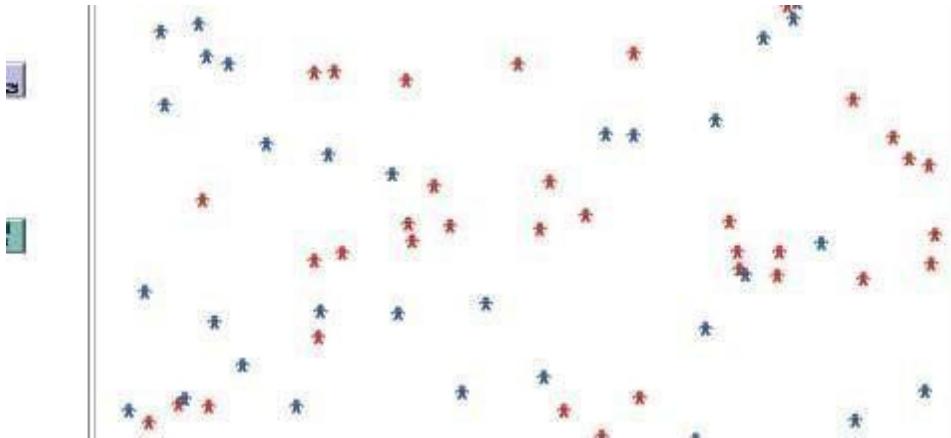
### Medium count (e.g., 50):

- turtles. Turtles are crowded; brave turtles form larger clusters, and cowardly turtles have more avoidance behavior.

### High count (e.g., 100):

3. Change random seeds using: preset 10, preset 20





### **Observation:**

Changing the random seed alters the initial positions of turtles and their friend/enemy assignments. With preset 10, turtles form certain clusters and movement patterns, while with preset 20, the distribution and interactions differ. This shows that randomness affects the simulation outcomes, even though the overall behavior rules remain the same.

#### **4. Note differences in clustering, spreading, and fleeing behavior.**

The model shows clear differences in behavior based on personality and settings:

- **Clustering:** Brave turtles (blue) tend to move toward midpoints with friends and enemies, forming visible clusters.
  - **Spreading:** Cowardly turtles (red) avoid enemies by positioning themselves between friends and enemies, resulting in more even spreading.
  - **Fleeing:** Cowardly turtles actively move away from potential threats, while brave turtles approach interactions, showing contrasting movement strategies.
- These differences demonstrate how personality types influence spatial patterns and interactions in the model.

### **Post-Lab Questions**

#### **1. How do brave and cowardly behaviors differ in logic?**

Brave turtles move toward the midpoint of their friend and enemy, seeking interaction, while cowardly turtles position themselves between friend and enemy to avoid conflict.

#### **2. Why does each turtle choose a friend and enemy?**

Assigning a friend and enemy gives each turtle reference points to determine movement and interaction strategies, creating dynamic behavior patterns.

#### **3. How does facexy help turtles navigate?**

The `facexy` command directs a turtle to face a specific coordinate, allowing precise movement toward or away from targets.

**4. What role does the chooser play in this model?**

The chooser lets the user select turtle personalities(brave, cowardly, mixed), determining the overall behavior dynamics of the simulation.

**5. Why does random-seed create reproducible patterns?**

Setting a random-seed ensures that all random choices (positions, friend/enemy selection) are the same each time, allowing experiments to be repeated with identical outcomes.

## Lab 10: Reward-Based Strategy Decision Model (El Farol Variant)

### Objective

- To simulate how agents use prediction strategies to decide whether to attend a bar.
- To understand how rewards influence learning and color visualization.
- To record past attendance and use it for future decision-making.
- To implement strategy evaluation and selection based on performance.
- To model adaptive behavior in a competitive environment.

### Tool / Environment

- **Software:** NetLogo 6.4.0
- **Platform:** Windows
- **Environment:** Interface + Code Tab

### Theory

This model is an extension of the **El Farol Bar Problem**.

Agents predict attendance using a “bag” of strategies.

Each strategy provides an attendance estimate based on a weighted memory of past attendance data.

Agents use this logic:

1. Predict attendance based on past history
2. Compare prediction with overcrowding threshold
3. Decide:
  - o Go to the bar
  - o Stay home
4. Receive reward if they attend on a non-crowded day
5. Learn to choose the strategy that predicts best
6. Turtle color becomes darker red as reward increases

### Key Components

#### Component Description

**attendance** number of turtles currently in the bar

**history** last several weeks of attendance

**strategies** prediction formulas (weights)

**reward** increases when agent attends a non-crowded bar

**best-strategy** current most accurate strategy

**crowded-patch** patch displaying “CROWDED” message

## Lab Procedure

### Step 1: Add Required Interface Elements

#### Sliders

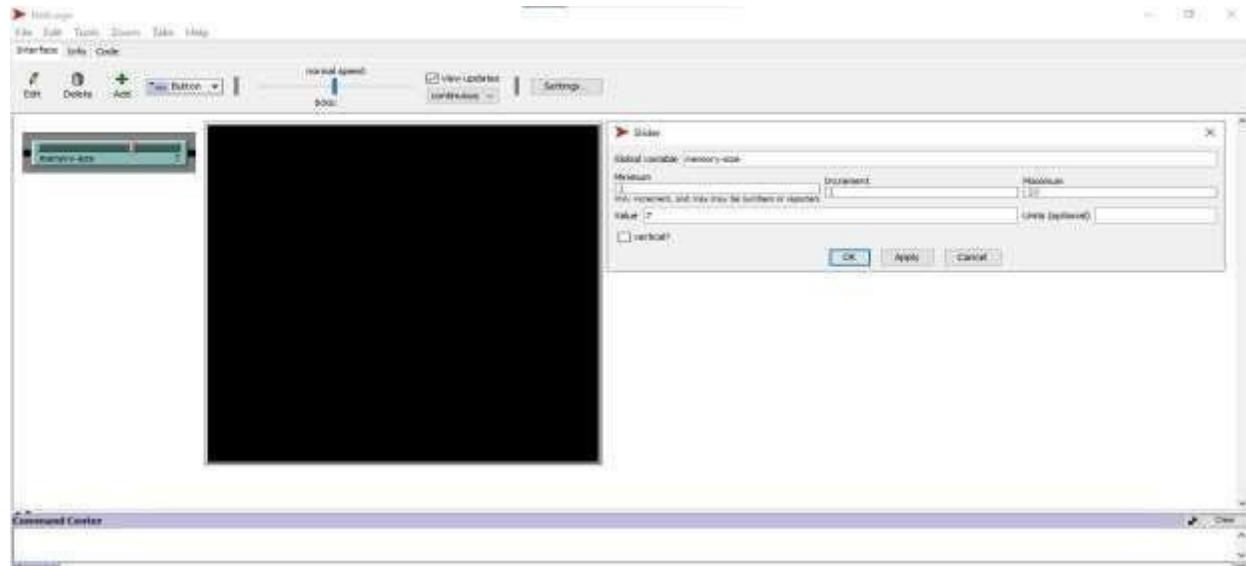
Add these sliders in Interface:

1. **memory-size** o

Min: 1 o Max:

10 o

Initial: 7



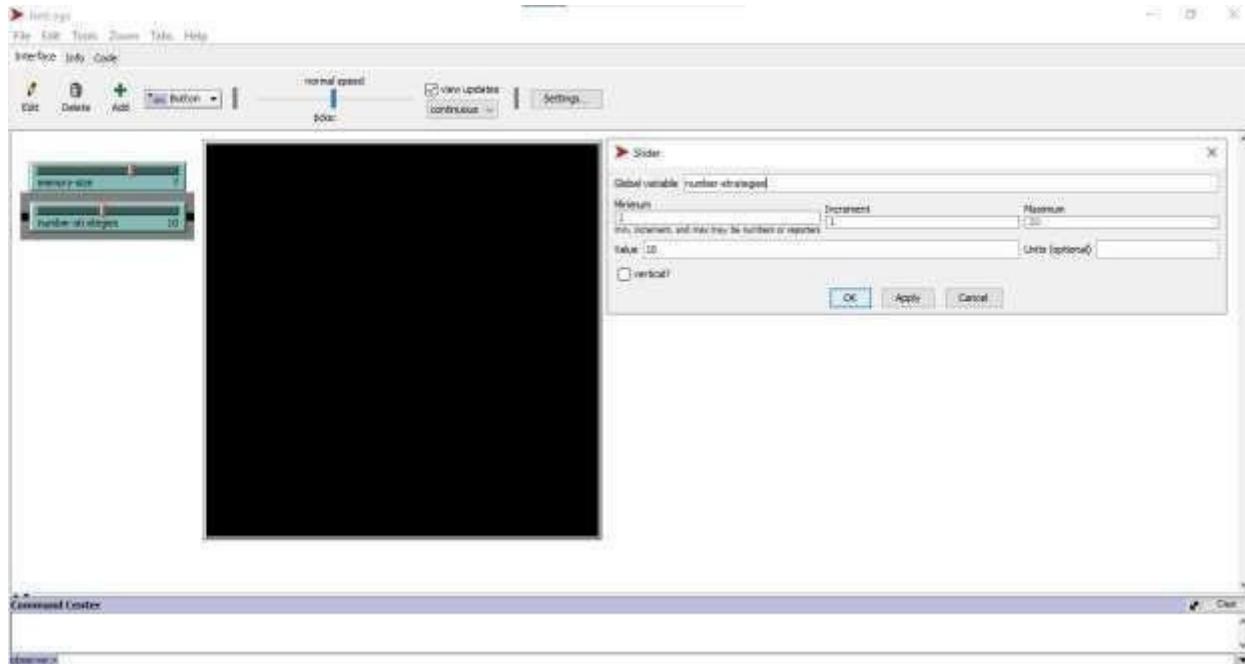
2. **number-**

**strategies** o

Min:

1 o Max: 20

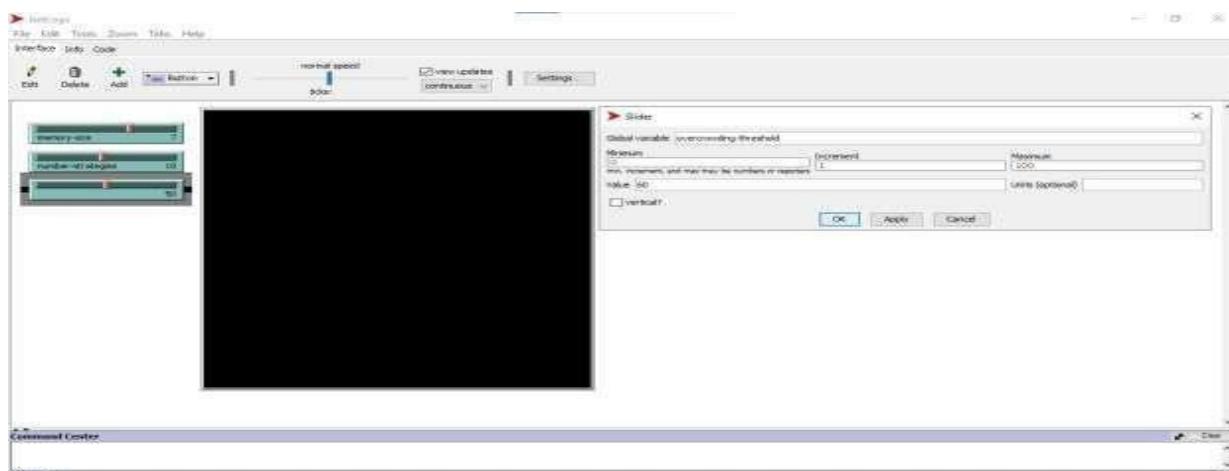
o Initial: 10



### 3. overcrowding-

**threshold** o Max:

100 o Initial: 60

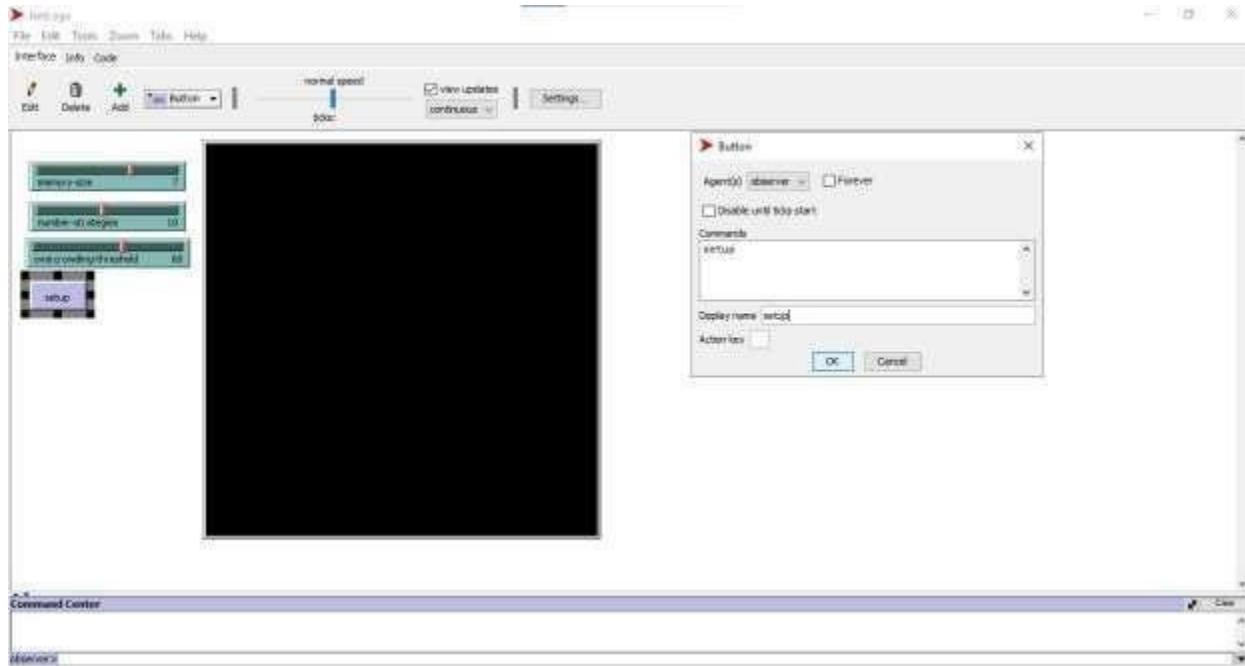


## Buttons

### 1. setup o

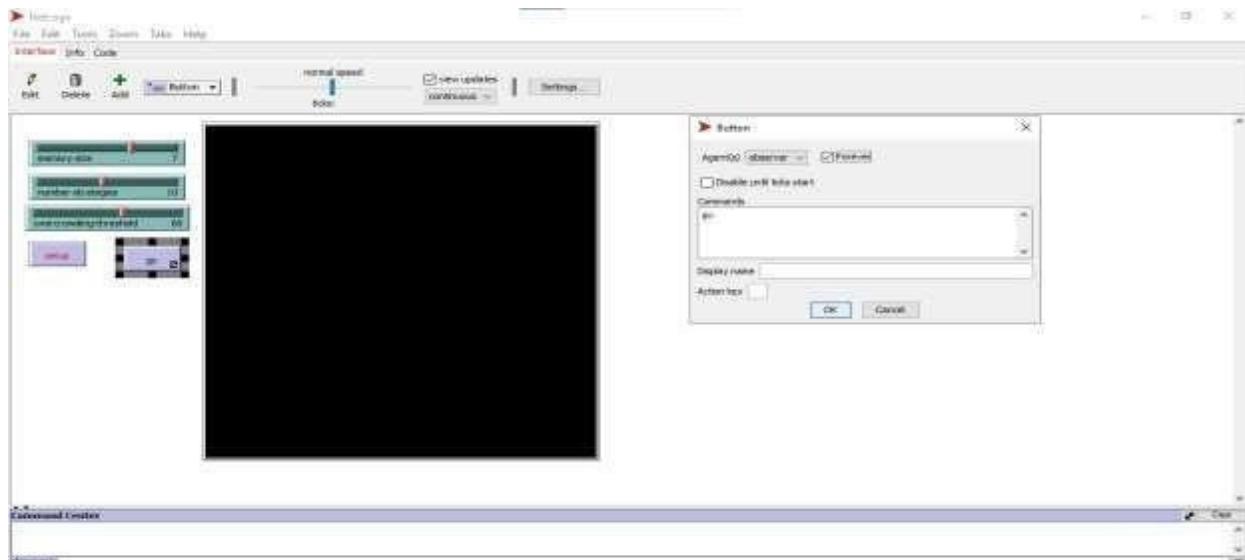
Command: setup o

Display name: setup



2. go ○ Command: go o

Check: **Forever**



### Add a Plot

- Right-click → **Plot**
- **Name:** Bar Attendance
- **X axis label:** Time
- **Y axis label:** Attendance

- **X min:** 0
- **X max:** 10
- **Y min:** 0
- **Y max:** 100

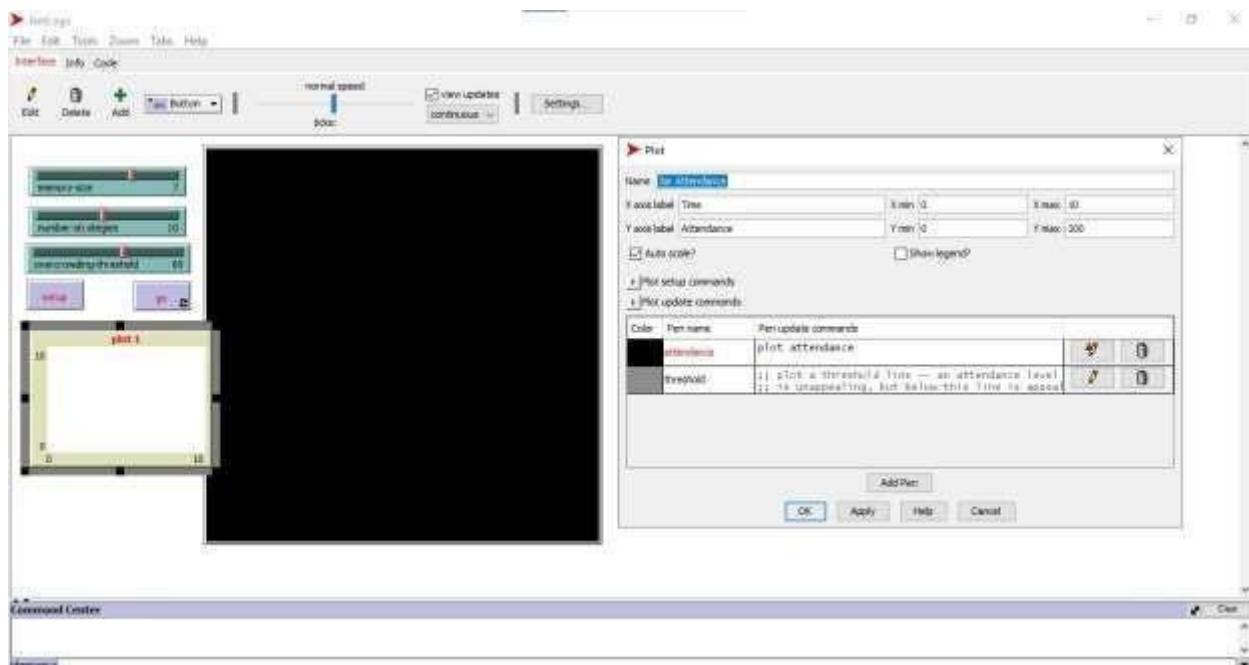
## 1. Pen 1

- **Pen name:** attendance
- **Pen update commands:** plot attendance

## 2. Pen 2

- **Pen name:** threshold
- **Pen update commands:**

```
;; plot a threshold line -- an attendance level above this line makes the bar
;; is unappealing, but below this line is appealing plot-pen-reset plotxy 0
overcrowding-threshold plotxy plot-x-max overcrowding-threshold
```



**Step 2: Add the Full Code in the Code Tab**

```

globals [
  attendance
  ;; the current attendance at the bar history
  past-values
  ;; list of past values of attendance home-patches
  green-patches
  ;; agentset of green patches bar-patches
  blue-patches
  ;; agentset of blue patches crowded-patch
  crowded-patch
  ;; patch where we show the "CROWDED" label
]

turtles-own [
  strategies
  best-strategy
  index-of-current-best-strategy
  attend?
  ;; true if the agent currently plans to
  ;; attend the bar prediction
  bar-prediction
  ;; current prediction of the bar
  attendance-reward
  ;; the amount that each agent has been
  ;; rewarded
]

to setup
  clear-all
  set-default-
  shape turtles
  "person"

  ;; create the 'homes' set home-patches patches with [pycor < 0 or (pxcor <
  ; 0 and pycor >= 0)] ask home-patches [ set pcolor green ]
  ;; create the 'bar' set bar-patches patches with [pxcor > 0 and
  ; pycor > 0] ask bar-patches [ set pcolor blue ]

  ;; initialize the previous attendance randomly so the agents have a
  ; history ;; to work with from the start set history n-values (memory-size *
  ; 2) [random 100] set attendance first history

  ;; use one of the patch labels to visually indicate whether or not
  ; the ;; bar is "crowded" ask patch (0.75 * max-pxcor) (0.5 * max-
  ; pycor) [
    ; set crowded-patch self set plabel-color yellow
  ]

  ;; create the agents and give them random strategies
  ;; these are the only strategies these agents will ever have though they ;;
  ; can change which of this "bag of strategies" they use every tick create-
  ; turtles 100 [ set color white move-to-empty-one-of home- patches set
  ; strategies n-values number-strategies [random-strategy] set best-
  ; strategy first strategies set reward 0 update-strategies
]

```

```

;; start the clock reset-ticks
end

to go
  ;; update the global variables ask crowded-patch
  [ set plabel "" ]
  ;; each agent predicts attendance at the bar and decides whether or not to go ask
  turtles [ set prediction predict-attendance best-strategy sublist history 0
  memory-size set attend? (prediction <= overcrowding-threshold) ;; true or
  false
  ;; scale the turtle's color a shade of red depending on its reward level (white for little reward, black
  for high reward) set color scale-color red reward (max [ reward ] of turtles + 1) 0
]
  ;;
  ;; depending on their decision the turtles go to the bar or stay at home
  ask turtles [ ifelse attend? [ move-to-empty-one-of bar-patches set
  attendance attendance + 1 ]
  [ move-to-empty-one-of home-patches ]
]

  ;;
  ;; if the bar is crowded indicate that on the view
  set attendance count turtles-on bar-patches
  ifelse attendance > overcrowding-threshold [
  ask crowded-patch [ set plabel "CROWDED" ]
]
[
  ask turtles with [ attend? ] [
  set reward reward + 1
]
]

  ;;
  ;; update the attendance history
  ;; remove oldest attendance and prepend latest attendance
  set history fput attendance but-last history ;; the agents
  decide what the new best strategy is ask turtles [ update-
  strategies ]
  ;;
  ;; advance the clock tick end

  ;;
  ;; determines which strategy would have predicted the best results had it been used this round.
  ;;
  ;; the best strategy is the one that has the sum of smallest differences between the
  ;; current attendance and the predicted attendance for each of the preceding

```

```

;; weeks (going back MEMORY-SIZE weeks)
;; this does not change the strategies at all, but it does (potentially) change the one
;; currently being used and updates the performance of all strategies to update-strategies let best-
    score memory-size * 100 + 1 foreach strategies [ the-strategy ->      let score 0      let week
    1 repeat memory-size [    set prediction predict-attendance the-strategy sublist history week
    (week + memory-size)    ;; increment the score by the difference between this week's
    attendance and your prediction for this week    set score score + abs (item (week - 1) history
    - prediction)    set week week + 1
]
if (score <= best-score) [    set
    best-score score    set best- strategy
    the-strategy
]
]
end
;; this reports a random strategy. a strategy is just a set of weights from -1.0 to 1.0 which
;; determines how much emphasis is put on each previous time period when making
;; an attendance prediction for the next time period to-report
random-strategy report n-values (memory-size + 1) [1.0 -
random-float 2.0] end

```

```

;; This reports an agent's prediction of the current attendance
;; using a particular strategy and portion of the attendance history. ;;
More specifically, the strategy is then described by the formula ;;
 $p(t) = x(t - 1) * a(t - 1) + x(t - 2) * a(t - 2) + ..$ 
;; ... +  $x(t - \text{MEMORY-SIZE}) * a(t - \text{MEMORY-SIZE}) + c * 100$ ,
;; where  $p(t)$  is the prediction at time  $t$ ,  $x(t)$  is the attendance of the bar at time  $t$ ,
;;  $a(t)$  is the weight for time  $t$ ,  $c$  is a constant, and  $\text{MEMORY-SIZE}$  is an external parameter to-report
predict-attendance [strategy subhistory]
;; the first element of the strategy is the constant,  $c$ , in the prediction formula.
;; one can think of it as the the agent's prediction of the bar's attendance ;;
in the absence of any other data
;; then we multiply each week in the history by its respective weight report 100 * first strategy
+ sum (map [ [weight week] -> week * weight ] butfirst strategy subhistory) end

```

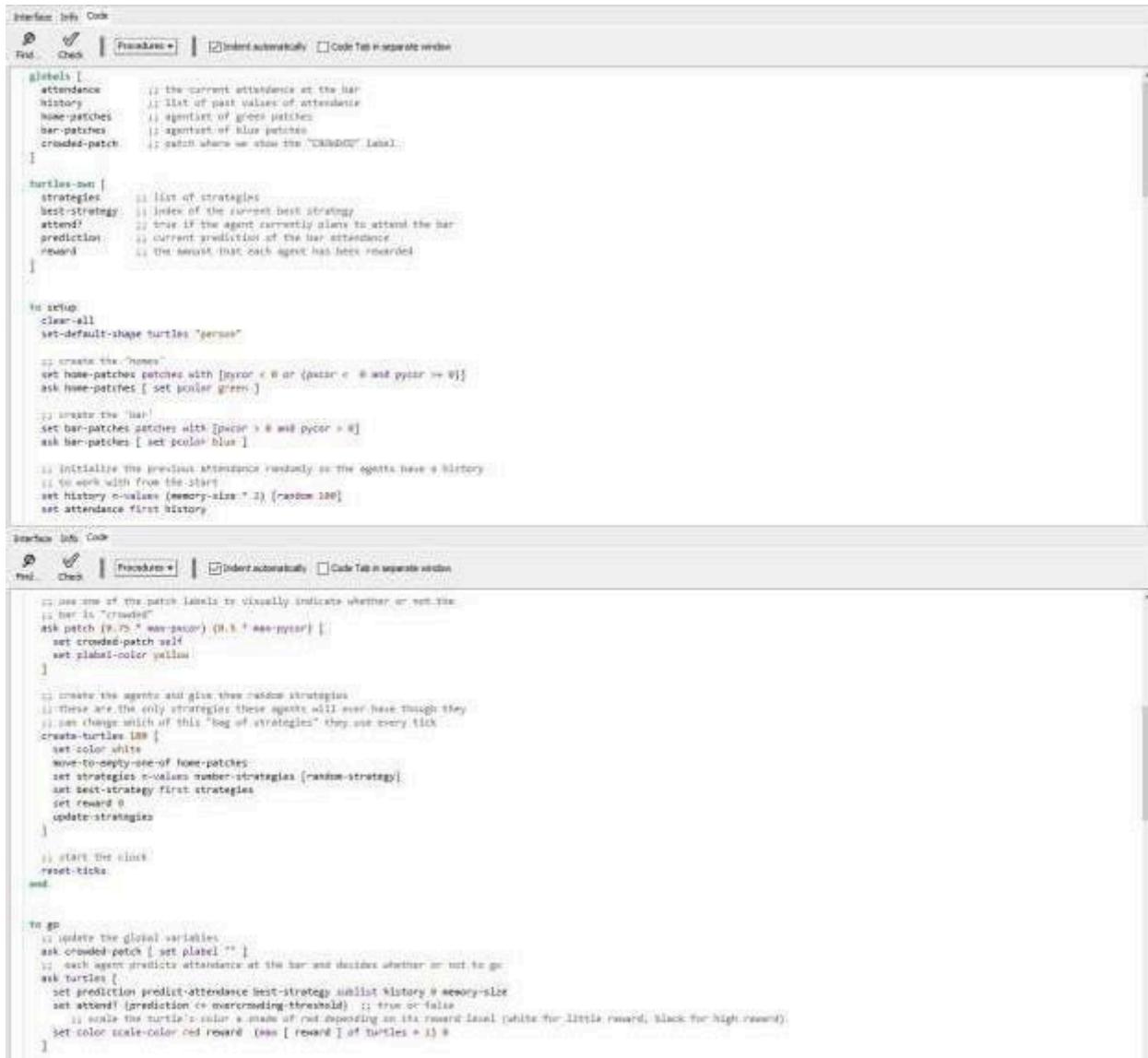
```

;; In this model it doesn't really matter exactly which patch
;; a turtle is on, only whether the turtle is in the home area
;; or the bar area. Nonetheless, to make a nice visualization ;;
this procedure is used to ensure that we only have one ;;
turtle per patch.

```

**to move-to-empty-one-of [locations] ;;** turtle procedure  
**move-to one-of locations while [any? other turtles-here] [ move-to one-of locations**

**]**  
**end**



```

Interface Info Code
File Check Procedures + Insert automatically CodeTab in separate window
globals [
  attendance          ; the current attendance at the bar
  history             ; list of past values of attendance
  home-patches        ; agentset of green patches
  bar-patches         ; agentset of blue patches
  crowded-patch       ; patch where we show the "CROWDED" label
]

turtles-on [
  strategies          ; list of strategies
  best-strategy        ; index of the current best strategy
  attend?             ; true if the agent currently plans to attend the bar
  prediction          ; current prediction of the bar attendance
  reward              ; the amount that each agent has been rewarded
]

; to setup
clear-all
set-default-shape turtles "person"

;;; create the "homes"
set home-patches patches with [pxcor < 0 or (pxcor > 0 and pycor > 0)]
ask home-patches [ set polar green ]

;;; create the "bar"
set bar-patches patches with [pxcor > 0 and pycor > 0]
ask bar-patches [ set polar blue ]

;;; initialize the previous attendance randomly so the agents have a history
;;; to work with from the start
set history n-values (memory-size * 2) [random 100]
set attendance first history

; to go
;;; update the global variables
ask crowded-patch [ set plabel "" ]
;;; each agent predicts attendance at the bar and decides whether or not to go
ask turtles [
  set prediction predict-attendance best-strategy amidst history * memory-size
  set attend? (prediction >= overcrowding-threshold) ;; true or false
  ;;; scale the turtle's value a range of red according to its reward (red for little reward, black for high reward)
  set color scale-color red reward (min [reward] of turtles + 1) 0
]

```

```

File Check | Procedures - |  Indent automatically  CodeTab in separate window

<-- modeling on their decision the turtles go to the bar or stay at home
ask turtles [
  ifelse attend? [
    [ move-to-empty-one-of bar-patches
      set attendance attendance + 1]
    [ move-to-empty-one-of home-patches ]
  ]
]

<-- If the user is crowded indicate that in the view
set attendance-count turtles-on bar-patches
ifelse attendance > over-crowding-threshold [
  ask crowded-patch [ set shape "CROWDED" ]
]

ask turtles with [ attend? ] [
  set reward reward + 1
]

update-the-attendance-History
remove-oldest-attendance-and-project-latest-attendance
set history first attendance but-last-history
the-agents-decide-what-the-user-wants-strategy:
ask turtles [ update-strategies ]
advance-the-clock
tick
end

File Check | Procedures - |  Indent automatically  CodeTab in separate window

<-- determines which strategy would have predicted the best results had it been used this round.
<-- the best strategy is the one that has the sum of squared differences between the
<-- current attendance and the predicted attendance for each of the preceding
<-- weeks (going back HISTORY-SIZE weeks)
<-- this does not change the strategies at all, but it does (potentially) change the user
<-- correctly, being used and updates the performance of all strategies
no update-strategies
int best-score memory-size = 100 + 1
foreach strategies [ the-strategy ->
  let score 0
  let week 1
  repeat memory-size [
    set prediction predict-attendance the-strategy subhistory week (week + memory-size)
    ; increment the score by the difference between this week's attendance and your prediction for this week
    set score score + abs ((last week - 1) history - prediction)
    set week week + 1
  ]
  if (score == best-score) [
    set best-score score
    set best-strategy the-strategy
  ]
]
and

<-- This reports a random strategy. A strategy is just a set of weights from -1.0 to 1.0 which
<-- determines how much emphasis is put on each previous time period when scaling
<-- an attendance prediction for the next time period
no-report random-strategy
  report n-values (memory-size + 1) (1.0 - random-float 2.0)
and

<-- This reports an agent's prediction of the current attendance
<-- using a particular strategy and portion of the attendance history
<-- More specifically, the strategy is that described by the formula
<--  $P(t) = c_0 + c_1 * t_0 + c_2 * t_1 + \dots + c_{n-1} * t_{n-2} + c_n * t_n$ 
<-- where  $P(t)$  is the prediction at time  $t$ ,  $c_i$  is the attendance at time  $t_i$ ,
<--  $c_n$  is the weight for time  $t_n$ ,  $c$  is a constant, and HISTORY-SIZE is an external parameter.
no-report predict-attendance [strategy subhistory]
<-- the first element of the strategy is the constant,  $c_0$  is the prediction formula.
<-- we can think of it as the the agent's prediction of the user's attendance
<-- in the absence of any other data
<-- Here we multiply each week in the history by its respective weight
report 100 * first strategy + sum (map [weight week] -> week * weight) butfirst strategy subhistory
end

<-- In this model it doesn't really matter exactly which patch
<-- a turtle is on, only whether the turtle is in the same area
<-- or the bar area. Nonetheless, to make a nice visualization
<-- this procedure is used to ensure that we only have one
<-- turtle per patch
move-to-empty-one-of [locations] ; turtle procedure
move-to-over-all-locations
while [any? other turtles-in-patch] [
  move-to-one-of locations
]
end

```

## Output:

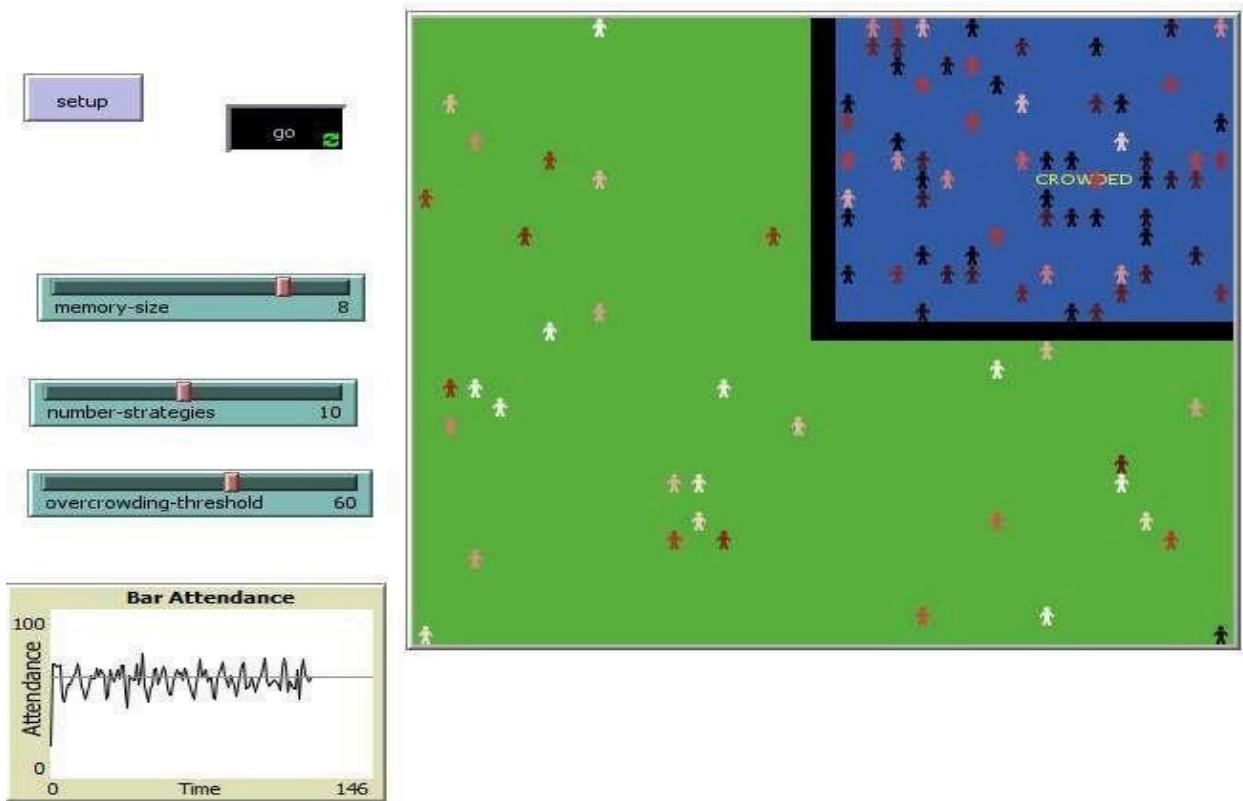


## Observations

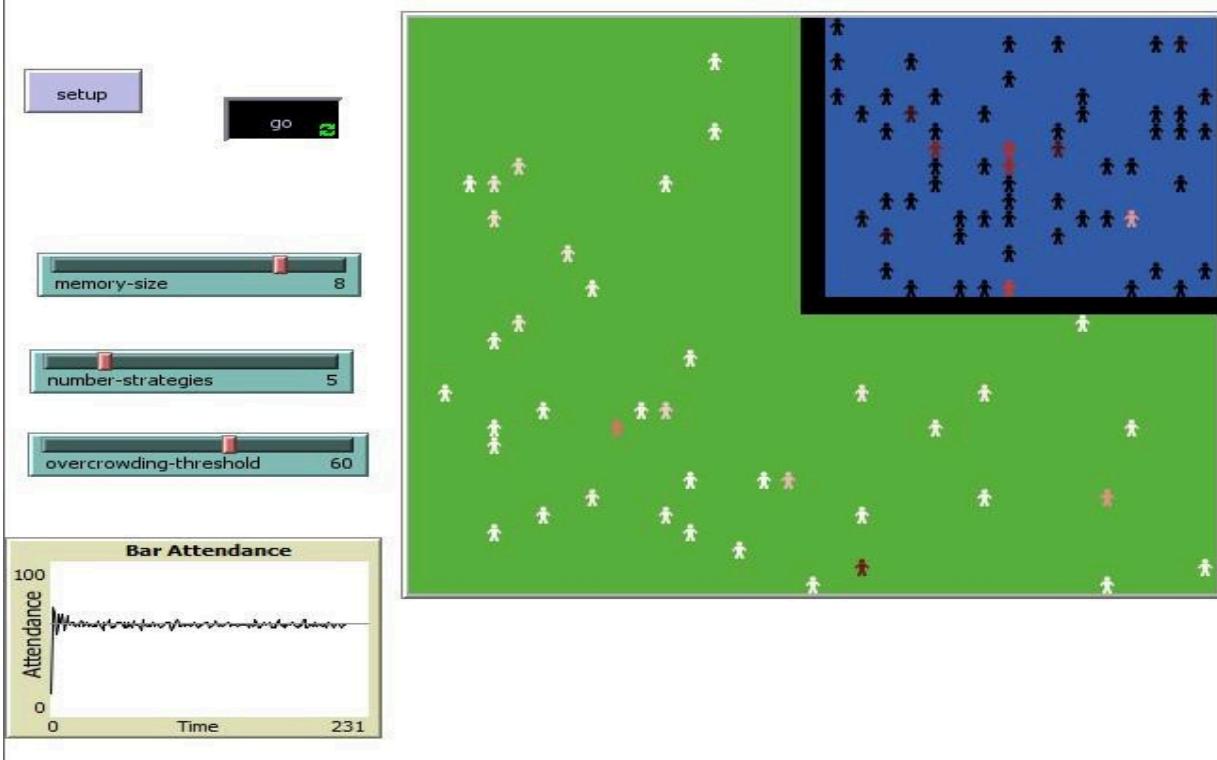
- Turtles turn darker red as their reward increases.
- Attendance oscillates based on predictions.
- “CROWDED” appears when attendance > threshold.
- Strategies improve over time as predictions become more accurate.
- The bar rarely stabilizes because agents compete to outguess each other.

## STUDENT TASK

1. Increase memory-size and note changes in prediction stability.



**OBSERVATION** With memory-size set to 8, agents use the past 8 weeks of attendance data to make predictions. This results in relatively stable and consistent predictions of bar attendance compared to smaller memory sizes. Fluctuations from tick to tick are reduced, and agents make more informed decisions about whether to attend the bar, leading to smoother attendance patterns over time. **2.** Decrease number-strategies and observe if agents perform worse.



### Observation:

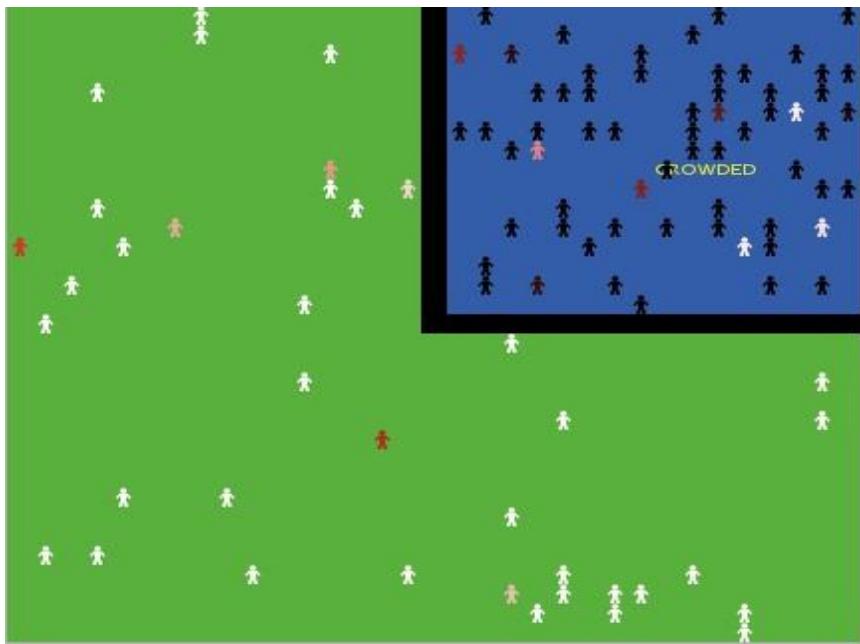
With the number of strategies reduced to 5, each agent has fewer options to choose from when predicting attendance. As a result, agents perform slightly worse compared to having more strategies, because they have a smaller pool of strategies to find the most accurate prediction. This leads to less optimal decisions and more fluctuations in attendance at the bar.

**3.** Run the model multiple times and note fluctuations in crowded days.

Running the model multiple times shows that the number of crowded days fluctuates across simulations. Even with the same parameters, random variations in agents' initial positions, strategies, and predictions lead to differences in which days the bar becomes crowded. This

demonstrates the role of randomness in the model and how small differences in initial conditions can affect outcomes.

#### 4. Compare reward levels between regularly attending vs avoiding agents.



#### Observation:

Agents who regularly attend the bar when it is not crowded tend to accumulate higher rewards, as their predictions allow them to avoid overcrowding and gain points consistently. In contrast, agents who often avoid the bar or attend when it is crowded earn lower rewards. This demonstrates that successful prediction and decision-making directly influence an agent's reward level.

#### 5. Modify overcrowding-threshold and study behavior shifts.



#### Observation:

Changing the overcrowding-threshold alters agents' behavior. Increasing the threshold allows more agents to attend the bar before it is considered crowded, resulting in higher attendance and fewer agents avoiding the bar. Decreasing the threshold makes the bar

crowded more quickly, causing more agents to stay home. This demonstrates how the overcrowding-threshold directly influences decision-making and overall attendance patterns.

### **Post-Lab Questions**

#### **1. Why do agents need multiple strategies instead of just one?**

Multiple strategies give agents options to predict attendance more accurately. With only one strategy, agents may consistently make poor predictions if that strategy is not suitable for the current conditions.

#### **2. How does reward influence future predictions?**

Higher rewards indicate successful predictions. Agents tend to favor strategies that have performed well in the past, improving the accuracy of future predictions.

#### **3. What happens when memory-size is too small or too large?**

A small memory-size leads to unstable predictions because agents rely on limited historical data. A very large memory-size can slow adaptation, as agents weigh old data too heavily, reducing responsiveness to recent changes.

#### **4. Why does the model display “CROWDED”?**

The “CROWDED” label appears when the bar’s attendance exceeds the overcrowding-threshold, signaling that too many agents are attending and some may need to avoid the bar to maximize reward.

#### **5. How does the visualization help understand reward accumulation?**

Color changes of turtles (white to black) represent reward levels, allowing quick visual comparison of agents who attend successfully versus those who avoid or fail. This helps understand patterns of reward accumulation over time.

### **Lab 11: Strategy-Based Decision Making (El Farol Bar Model – Extension)**

### **Objective**

- To study decision-making under limited information
- To understand how agents use prediction strategies
- To analyze overcrowding behavior in shared resources
- To observe reward-based learning using historical data

### **Tool / Environment**

- **Software:** NetLogo 6.4.0

- **Platform:** Windows
- **Environment:** Interface + Code Tab

## Theory

- ElFarol is a popular bar in Santa Fe that becomes unpleasant when it is too crowded. Each person must decide whether to go or stay home without knowing how many others will attend. In this model, agents do not have perfect information. They use past attendance data
- and simple prediction strategies to guess how crowded the bar will be. This is called bounded rationality because decisions are based on limited experience, not perfect calculation. Each agent has several prediction strategies and checks which one worked best
- in the past. The most accurate strategy is used to make the current decision. An agent goes to the bar only if the predicted attendance is below a fixed overcrowding limit. Over time, agents learn and adapt their behavior. As a result, attendance keeps changing instead of
- settling at one fixed value. This model shows how complex group behavior can emerge from simple individual decision rules, as explained by Brian Arthur (1994).

Key	Components
-----	------------

**Component Description**

attendance  
number of turtles currently in the bar    **history** last

several weeks of attendance    **strategies**

prediction formulas (weights)

**reward**    increases when agent attends a non-crowded bar

**best-strategy** current most accurate strategy

**crowded-patch** patch displaying “CROWDED” message

## Lab Procedure

### Step 1: Add Required Interface Elements

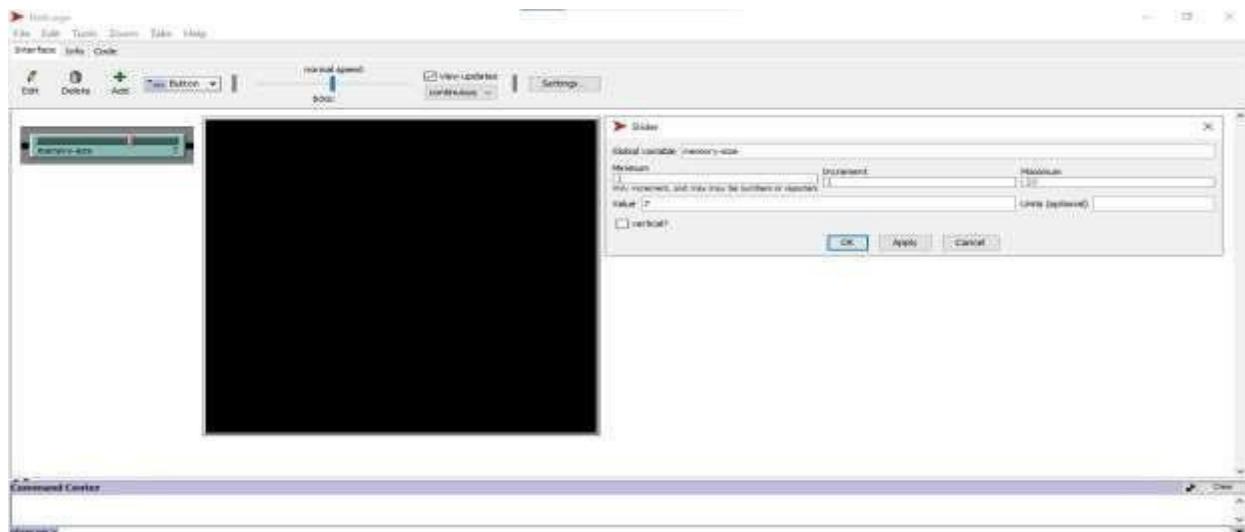
#### Sliders

Add these sliders in Interface:

1. **memory-size** o

Min: 1 o Max: 10 o

Initial: 7

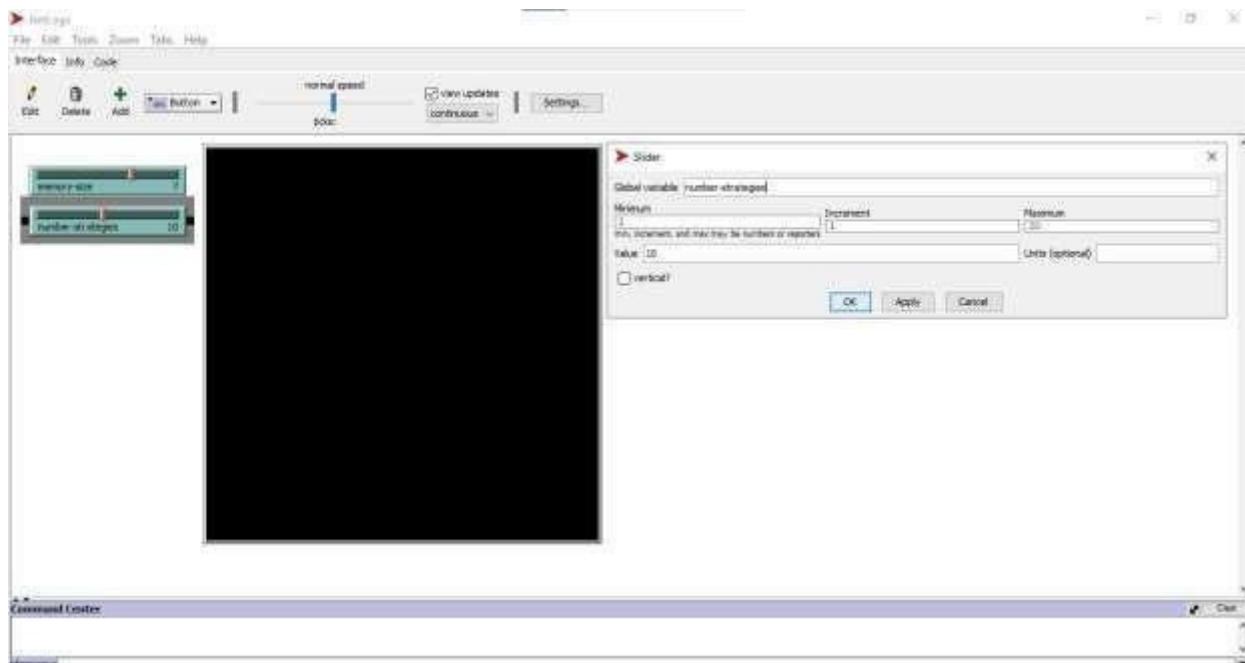


## 2. number-

strategies o Min:

1 o Max: 20

o Initial: 10

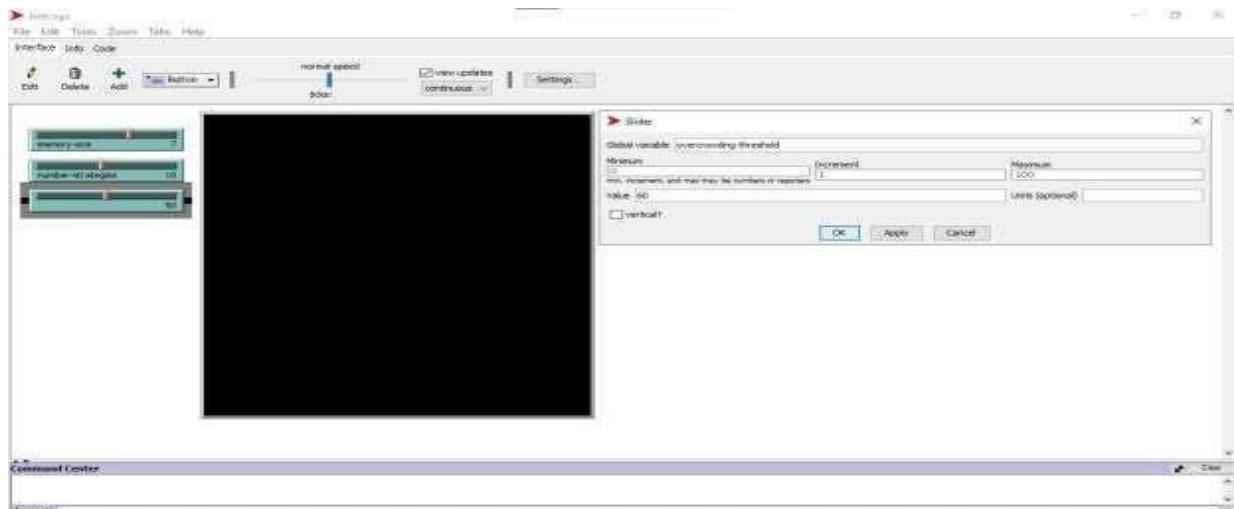


## 3. overcrowding-

threshold o Min:

0 o Max: 100 o

Initial: 60

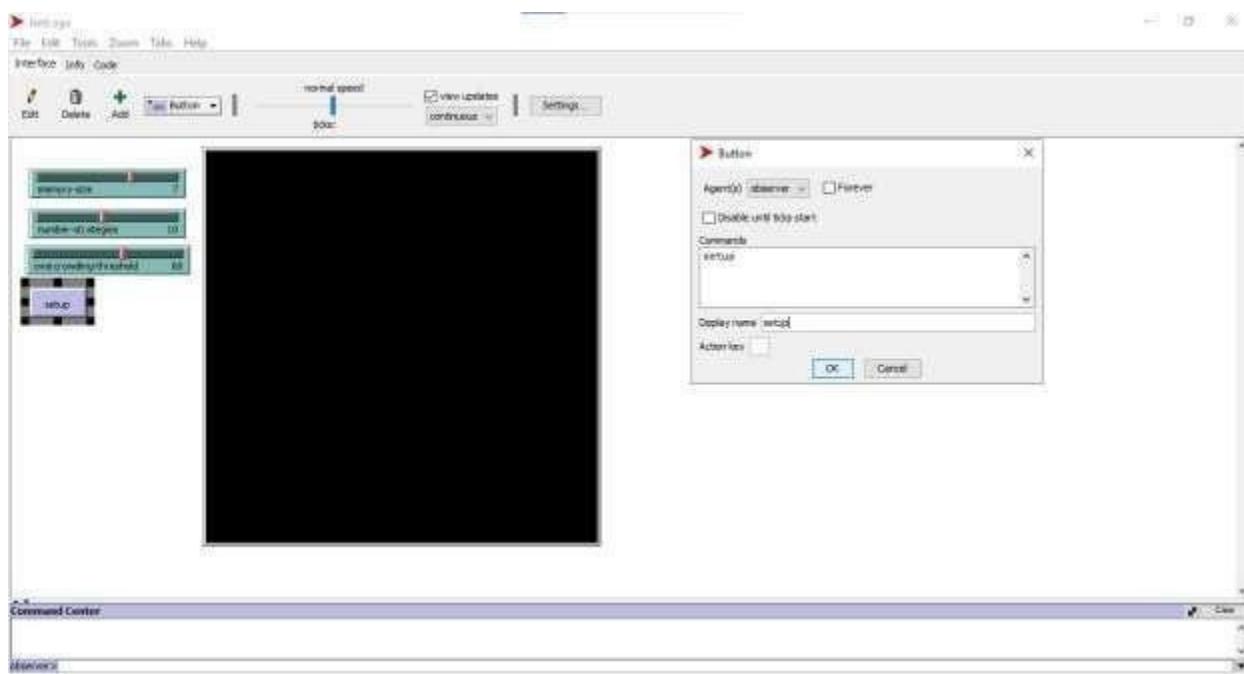


## Buttons

### 1. setup o

Command: setup o

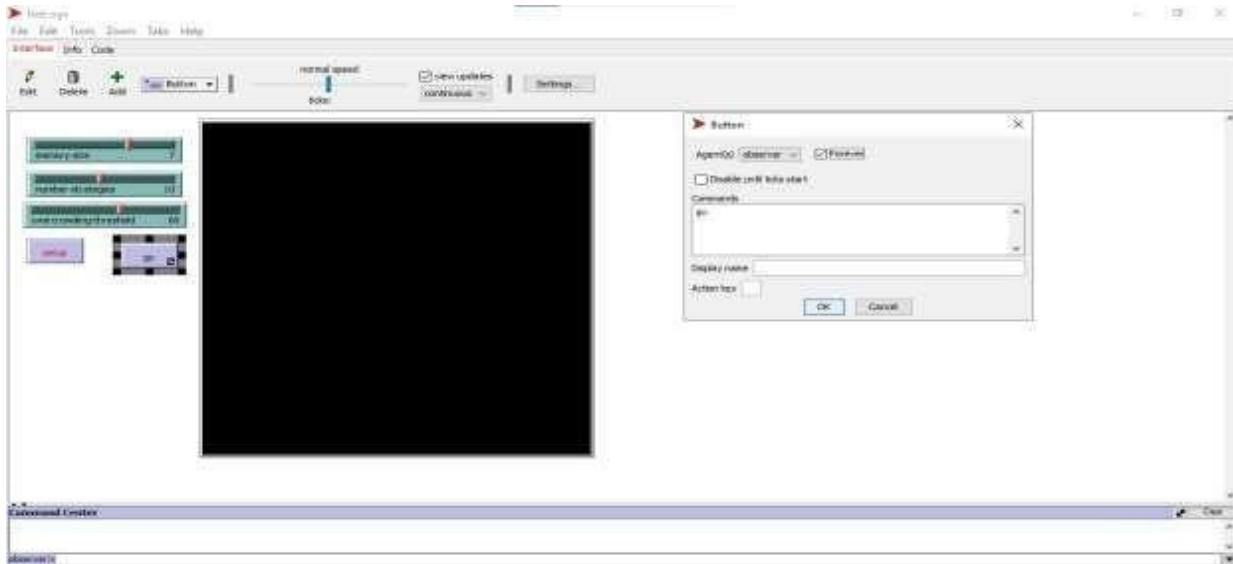
Display name: setup



### 2. go o Command:

go

o Check: **Forever**



## Add a Plot

- Right-click → **Plot**
- **Name:** Bar Attendance
- **X axis label:** Time
- **Y axis label:** Attendance
- **X min:** 0
- **X max:** 10
- **Y min:** 0
- Y max:** 100

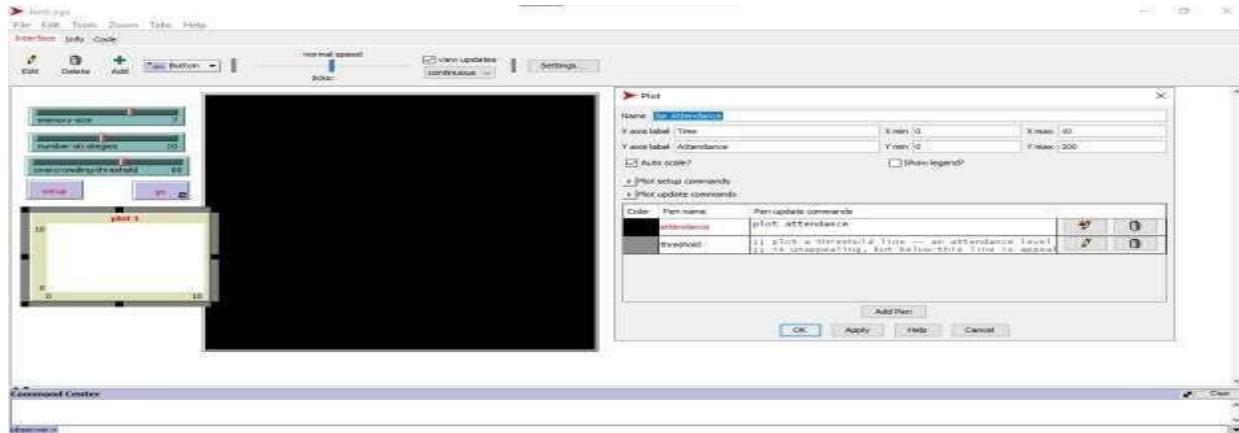
### 1. Pen 1

- **Pen name:** attendance
- **Pen update commands:** plot attendance

### 2. Pen 2

- **Pen name:** threshold
- **Pen update commands:**

```
;; plot a threshold line -- an attendance level above this line makes the bar
;; is unappealing, but below this line is appealing plot-pen-reset plotxy 0
overcrowding-threshold plotxy plot-x-max overcrowding-threshold
```



## Add a Plot

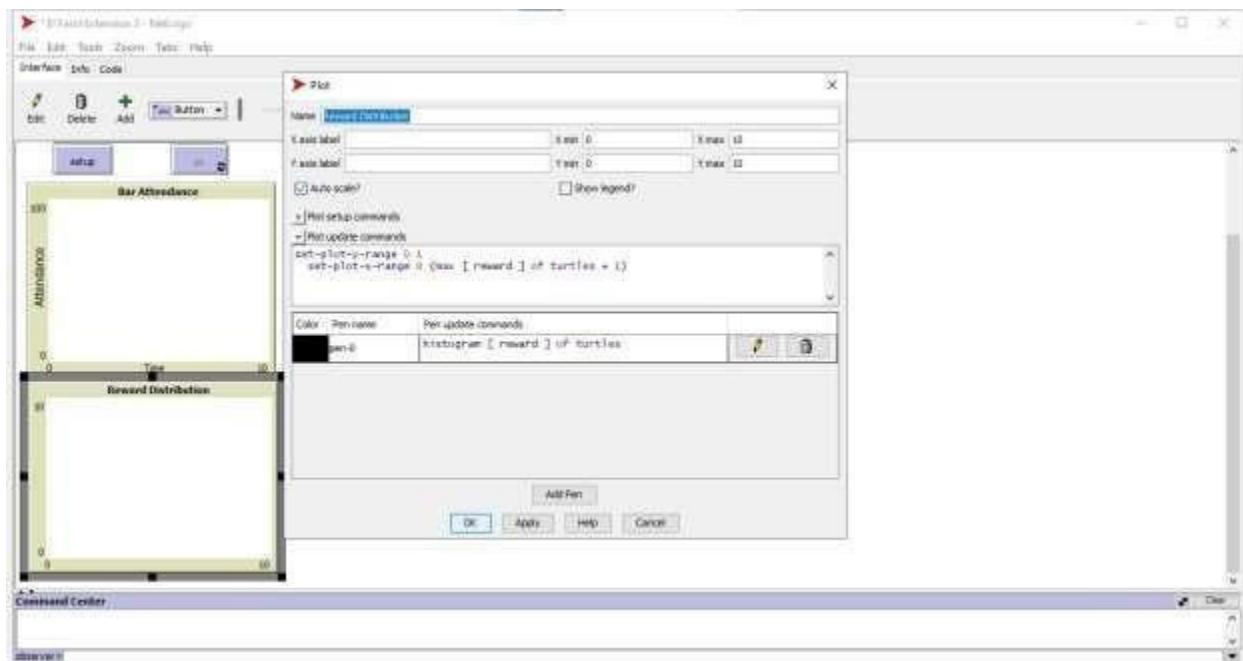
- Right-click → **Plot**
- **Name:** RewardDistribution
- **X min:** 0
- **X max:** 10 • **Y min:** 0
- **Y max:** 10

### 1. Plot update commands:

```
set-plot-y-range 0 1 set-plot-x-range 0 (max [ reward
] of turtles + 1)
```

### 2. Pen

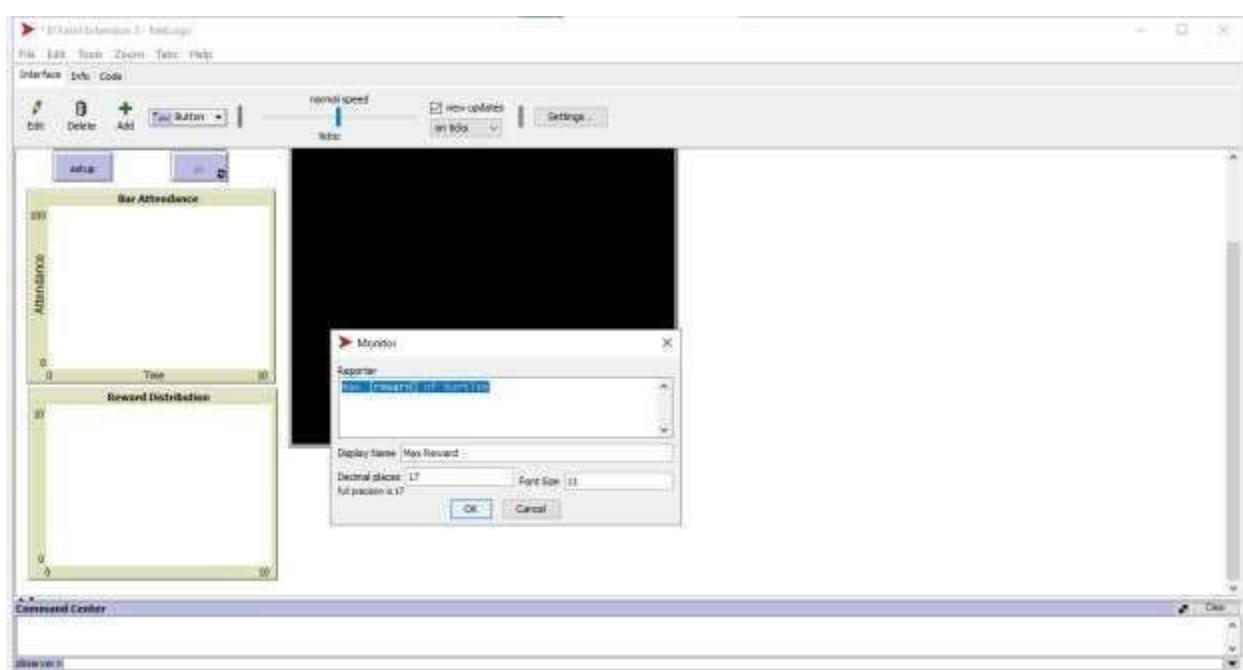
- **Pen name:** pen-0
- **Pen update commands:** histogram [ reward ] of turtles



## Monitor: Max Reward

- **Type:** Monitor
- **Display Name:** Max Reward
- **Reporter:** max[reward] of turtles
- **Decimal places:** 17

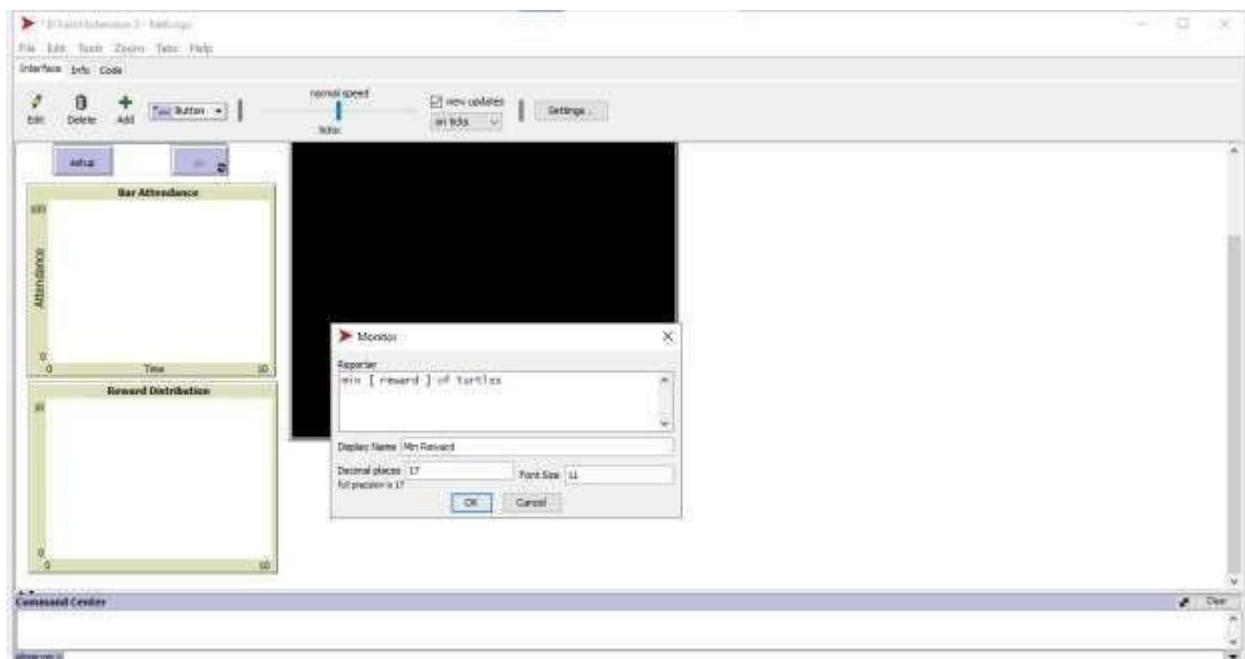
**Font size:** 11



## Monitor: Min Reward

- **Type:** Monitor
- **Display Name:** Min Reward
- **Reporter:** max[reward ] of turtles
- **Decimal places:** 17

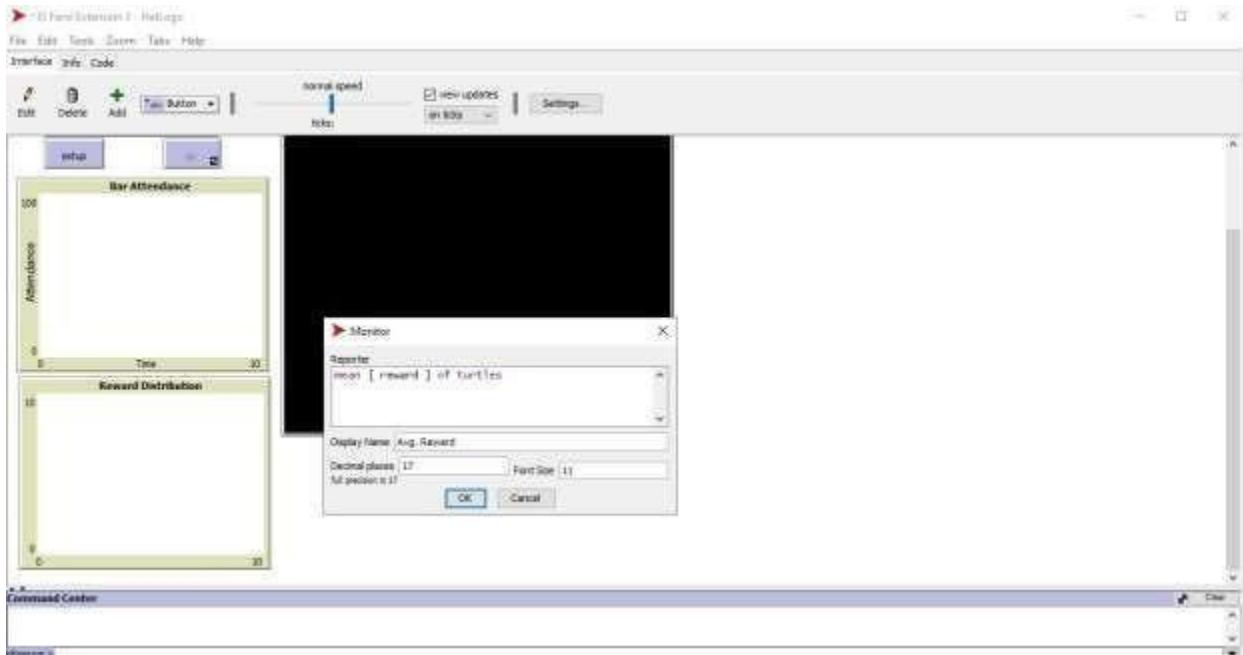
**Font size:** 11



## Monitor: Average Reward

- **Type:** Monitor
- **Display Name:** Avg. Reward
- **Reporter:** max[reward ] of turtles
- **Decimal places:** 17

**Font size:** 11



## Step 2: Add the Full Code in the Code Tab

```
global attendance ;; the current attendance at the bar history ;;
list of past values of attendance home-patches ;; agentset of green patches bar-patches ;; agentset of blue patches crowded-patch ;; patch where we show the "CROWDED" label
```

]

```
turtles-own [
    strategies ;; list of strategies best-strategy ;; index of the current best strategy attend? ;; true if the agent currently plans to attend the bar prediction ;; current prediction of the bar attendance reward ;; the amount that each agent has been rewarded
```

]

```
to setup clear-all set-default-shape turtles "person"
```

```
;; create the 'homes' set home-patches patches with [pycor < 0 or (pxcor < 0 and pycor >= 0)] ask home-patches [ set pcolor green ]
```

```
;; create the 'bar' set bar-patches patches with [pxcor > 0 and pycor > 0] ask bar-patches [ set pcolor blue ]
```

```

;; initialize the previous attendance randomly so the agents have a history
;; to work with from the start set history n-values
(memory-size * 2) [random 100] set attendance first
history

;; use one of the patch labels to visually indicate whether or not the
;; bar is "crowded" ask patch (0.75 * max-pxcor)
(0.5 * max-pycor) [ set crowded-patch self set
plabel-color yellow
]

;; create the agents and give them random strategies create-
turtles 100 [ set color white move-to-empty-one-of home-
patches      set strategies n-values number-strategies
[random-strategy] set best-strategy first strategies
      set reward 0 update-strategies
]

```

;; start the clock reset-ticks

**end**

**to go**

```

;; update the global variables ask crowded-patch
[ set plabel "" ]
;; have each agent predict attendance at the bar and decide whether or not to go
ask turtles [      set prediction predict-attendance best-strategy sublist history
0 memory-size set attend? (prediction <= overcrowding-threshold) ;; true or
false
;; scale the turtle's color a shade of red depending on its reward level (white for little reward, black
for high reward) set color scale-color red reward (max [ reward ] of turtles + 1) 0
]

```

;; depending on their decision the turtles go to the bar or stay at home

```

ask turtles [ ifelse attend? [ move-to-empty-one-of bar-patches set
attendance attendance + 1 ]
[ move-to-empty-one-of home-patches ]
]

```

;; if the bar is crowded indicate that on the view

```

set attendance count turtles-on bar-patches

```

```

ifelse attendance > overcrowding-threshold [
  ask crowded-patch [ set plabel "CROWDED"
] ]
[
  ask turtles with [ attend? ] [
    set reward reward + 1
]
]

;; update the attendance history set history fput
  attendance but-last history
;; have the agents decide what the new best strategy is ask turtles
  [ update-strategies ]
;; update the plots
;; my-update-plots

;; advance the clock tick end

;; determines which strategy would have predicted the best results had it been used this round.
;; the best strategy is the one that has the sum of smallest difference between the
;; current attendance and the predicted attendance for each of the preceding
;; weeks (going back MEMORY-SIZE weeks) to update-strategies let best-score memory-size * 100
  + 1 foreach strategies [ the-strategy -> let score 0 let week 1 repeat memory-size
    [ set prediction predict-attendance the-strategy sublist history week (week + memory-size) ;;
      increment the score by the difference between this week's attendance and your prediction for
      this week set score score + abs (item (week - 1) history - prediction)
      set week week + 1
    ]
    if (score <= best-score) [      set
      best-score score      set best- strategy
      the-strategy
    ]
  ]
end

;; thisreports a random strategy. a strategy is just a set of weights from -1.0 to 1.0 which
;; determines how much emphasis is put on each previous time period when making
;; anattendance prediction for the next time period to-report
random-strategy report n-values (memory-size + 1) [1.0 -
random-float 2.0] end

;; This reports an agent's prediction of the current attendance

```

```

;; using a particular strategy and portion of the attendance history. ;;
More specifically, the strategy is then described by the formula ;; p(t)
= x(t - 1) * a(t - 1) + x(t - 2) * a(t -2) +..
;; ... + x(t - MEMORY-SIZE) * a(t - MEMORY-SIZE) + c * 100,
;; where p(t) is the prediction at time t, x(t) is the attendance of the bar at time t,
;; a(t) is the weight for time t, c is a constant, and MEMORY-SIZE is an external parameterto-report
predict-attendance [strategy subhistory]
;; the first element of the strategy is the constant, c, in the prediction formula.
;; one can think of it as the the agent's prediction of the bar's attendance
;; in the absence of any other data
;; then we multiply each week in the history by its respective weight report 100 * first strategy
+ sum (map [ [weight week] -> week * weight ] butfirst strategy subhistory) end

```

```

;; In this model it doesn't really matter exactly which patch
;; a turtle is on, only whether the turtle is in the home area
;; or the bar area. Nonetheless, to make a nice visualization ;;
this procedure is used to ensure that we only have one ;;
turtle per patch.
to move-to-empty-one-of [locations] ;; turtle procedure
move-to one-of locations while [any? other turtles-
here] [
  move-to one-of locations
]
End

```

```

Labels:
  attendance      ;;; the current attendance of the bar
  history         ;;; list of past values of attendance
  home-patches    ;;; agents of green patches
  bar-patches     ;;; agents of blue patches
  crmada-patch   ;;; patch where we start the "CRMADA" label

variables:
  strategies      ;;; list of strategies
  last-strategy   ;;; index of the current best strategy
  attend?         ;;; true if the agent currently plans to attend the bar
  prediction      ;;; current prediction of the bar attendance
  record          ;;; list to store that each agent has been recorded

to setup
  clear-all
  set-default-shape turtles "person"
  ;;; create the "home"
  set home-patches with [pxcor < 0 and pycor < 0]
  ask home-patches [ set pencolor green ]
  ;;; create the "bar"
  set bar-patches with [pxcor > 0 and pycor > 0]
  ask bar-patches [ set pencolor blue ]
  ;;; initialize the previous attendance randomly so the agents have a history
  ;;; to work with from the start
  set history n-values (memory-size * 2) [random 100]
  set attendance first history

```

```

Scratch 3.0: Code



- Check
- Procedures
- Indent automatically
- Code Tab in separate window


- // use one of the patch labels to visually indicate whether or not the
  // bar is "crowded"
  ask patch (0.75 * max-pcxor) (0.5 * max-pcyor) [
    set crowded-patch self
    set plabel-color yellow
  ]

  // create the agents and give them random-strategies
  create-turtles 100 [
    set color white
    move-to-empty-one-of home-patches
    set strategies n-values number-strategies (random-strategy)
    set best-strategy first strategies
    set reward 0
    update-strategies
  ]

  // start the clock
  reset-ticks
  end

  to go
    // update the global variables
    ask crowded-patch [ set plabel "" ]
    // have each agent predict attendance at the bar and decide whether or not to go
    ask turtles [
      set prediction predict-attendance best-strategy n-values history #memory-size
      set attend? (prediction <= overcrowing-threshold) ; true or false
      ; scale the turtle's value 0 (not attending) to 100 (attending)
      set color scale-color red reward ; ask [ reward ] of turtle + 1
    ]
    // depending on their decision the turtles go to the bar or stay at home
    ask turtles [
      ifelse attend? [
        move-to-empty-one-of bar-patches
        set attendance attendance + 1
        [ move-to-empty-one-of home-patches ]
      ]
    ]
    ; if the bar is crowded indicate that on the side
    set attendance count turtles-on bar-patches
    ifelse attendance > overcrowing-threshold [
      ask crowded-patch [ set plabel "CROWDED" ]
    ]
    ; ask turtles with [ attend? ] [
    ;   set reward reward + 1
    ; ]
    ; update the attendance history
    set history (put attendance but-last history)
    ; have the agents decide what the new best strategy is
    ask turtles [ update-strategies ]
    ; update the plots
    ; my-updates-plots
    ; advance the clock
    tick
  end.

```

```

  to-report random-strategy
    let best-score memory-size * 100 * 1
    foreach strategies [ the-strategy ->
      let score 0
      let week 1
      repeat memory-size [
        set prediction predict-attendance the-strategy n-values history week (week + memory-size)
        ; increment the score by the difference between this week's attendance and your prediction for this week
        set score score + abs ((item (week - 1) history) - prediction)
        set week week + 1
      ]
      if (score <= best-score) [
        set best-score score
        set best-strategy the-strategy
      ]
    ]
    end

    ; this reports a random strategy. a strategy is just a list of weights from -1.0 to 1.0 which
    ; determines how much weight it put on each previous time-period when making
    ; an attendance prediction for the next time-period
    report random-strategy
    report n-values (memory-size + 1) [1.0 - random-float 2.0]
  end

```

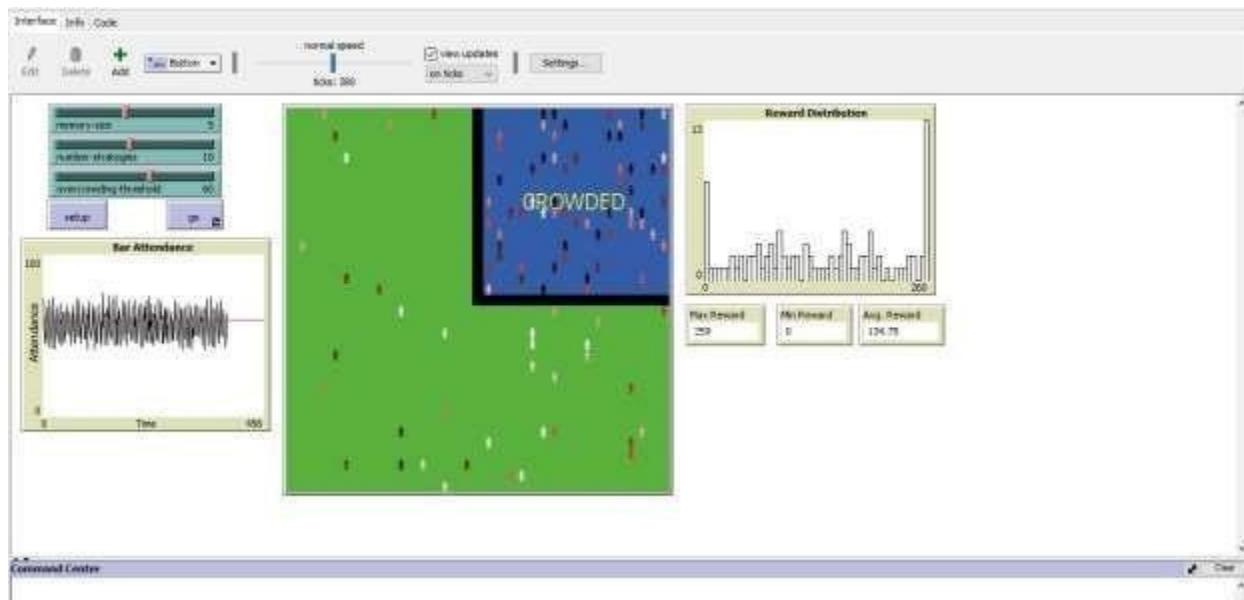
```

; This reports an agent's prediction of the current attendance
; using a particular strategy and portion of the attendance history;
; more specifically, the strategy is then described by the formula
;  $p(t) = \alpha(t-1) * \alpha(t-2) * \dots * \alpha(t-MEMORY-SIZE) * \alpha(t) + c$  / 100,
; where  $p(t)$  is the prediction at time  $t$ ,  $\alpha(t)$  is the attendance of the bar at time  $t$ ,
;  $\alpha(t)$  is the weight for time  $t$ ,  $c$  is a constant, and MEMORY-SIZE is an external parameter.
; report predict-attendance [strategy history]
; is the third column of the strategy is the constant,  $c$  is the prediction formula.
; one can think of it as the the agent's prediction of the bar's attendance.
; In the absence of any other data
; when no strategy was used in the history by its respective weight
; report 100 * first strategy + sum [ weight week ] > week * weight ) bufffirst strategy history)
; end

; In this model it doesn't really matter exactly which patch
; a turtle is on, only whether the turtle is in the home area
; or on the bar area. Nonetheless, to make a nice visualization
; this procedure is used to ensure that we only have one
; turtle per patch.
move-to-empty-one-of [locations] ; turtle procedure
move-to-one-of [locations]
while [any? other turtles here] [
move-to-one-of [locations]
]

```

## Output:

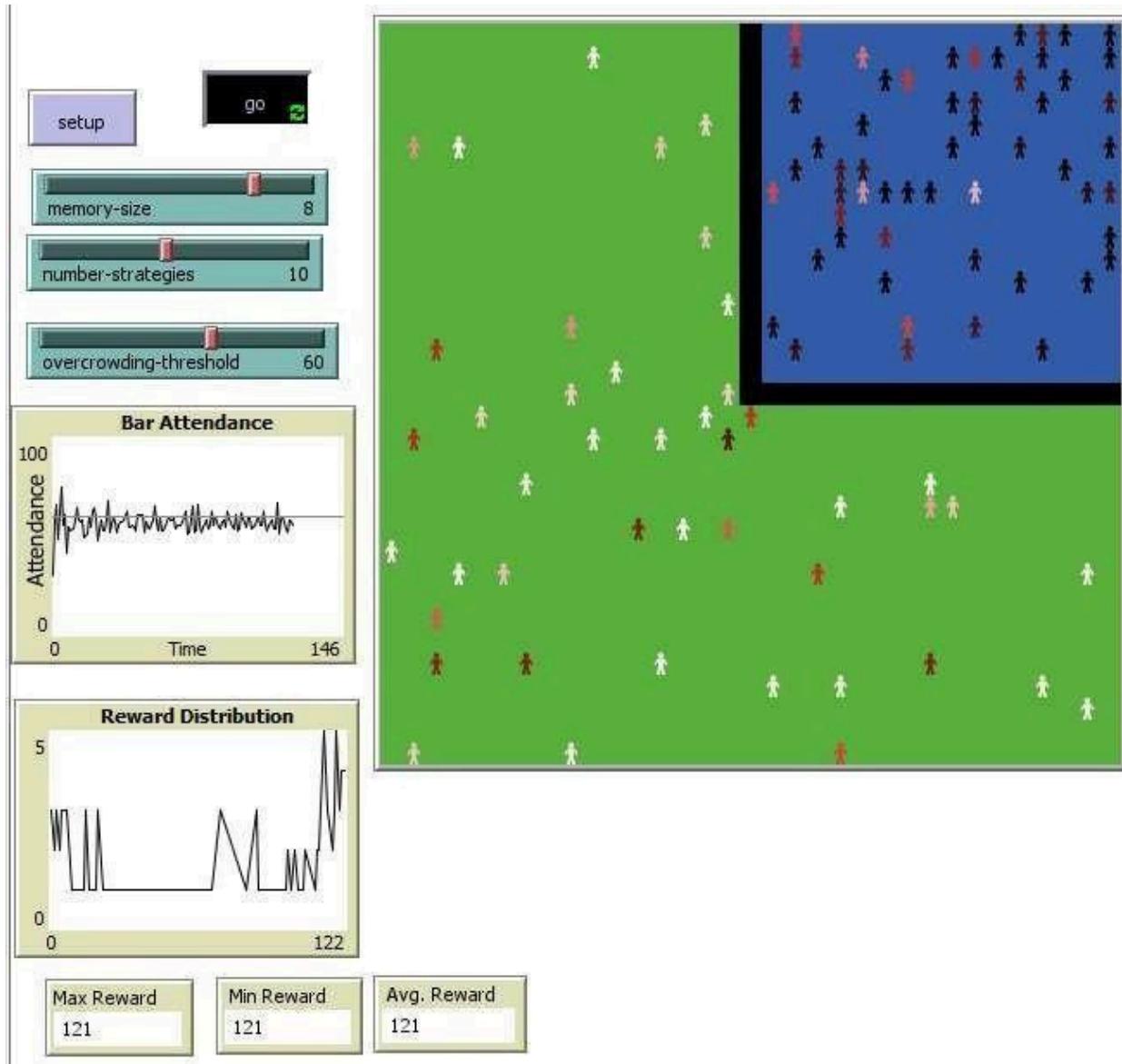


## Observations

- Attendance fluctuates rather than stabilizing
  - Agents continuously switch strategies
- Some agents earn consistently higher rewards
- Overcrowding emerges without coordination

## STUDENT TASK

1. IncreaseMEMORY-SIZE and observe prediction stability



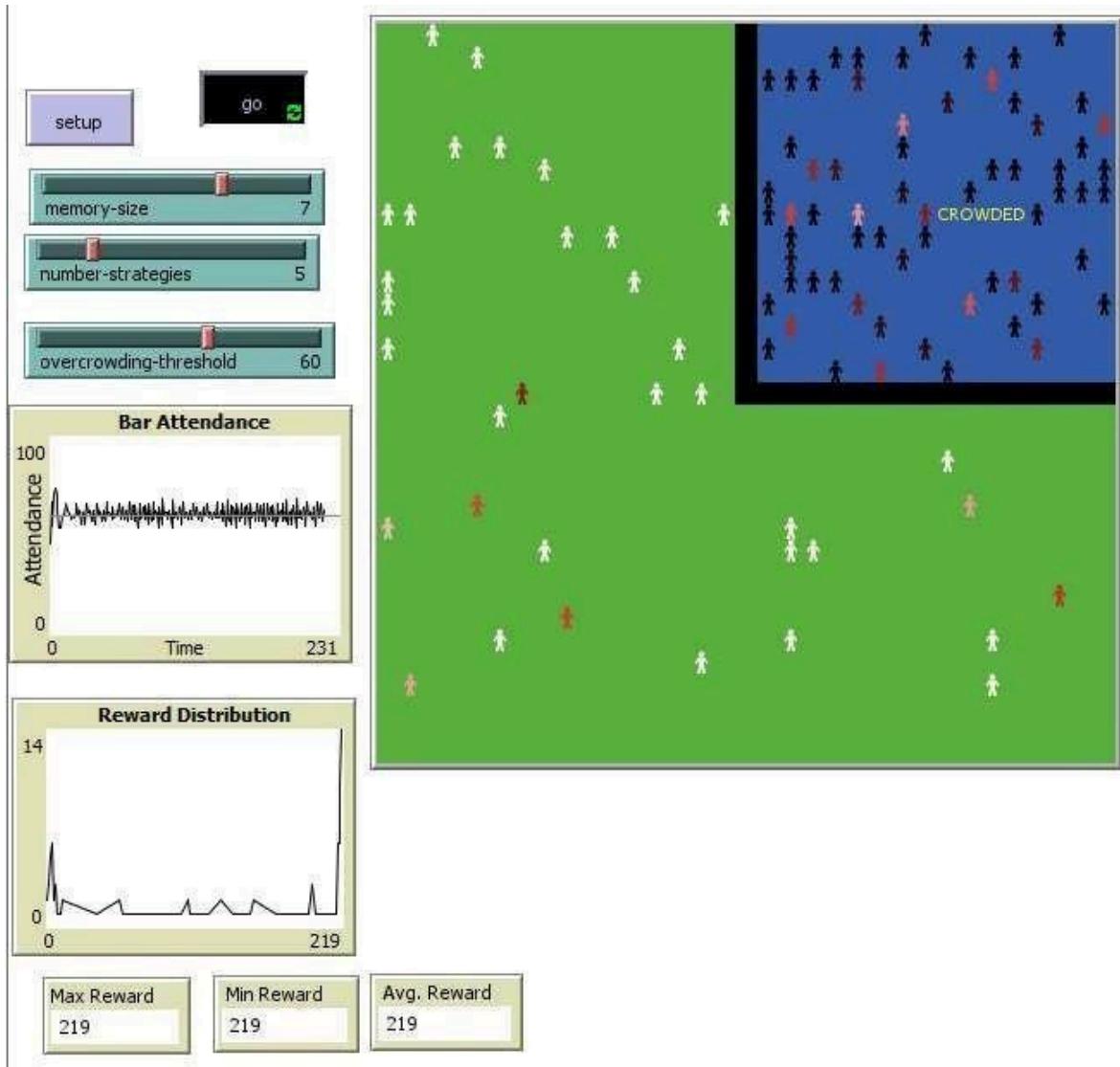
### Observation:

With MEMORY-SIZE set to 8, each agent uses the past 8 weeks of attendance data to make predictions. This results in more stable and consistent predictions compared to smaller memory sizes. Fluctuations in predicted attendance from tick to tick are reduced, allowing agents to make more informed decisions about attending the bar, which leads to smoother attendance patterns over time.



2.

Reduce NUMBER-STRATEGIES and compare learning speed



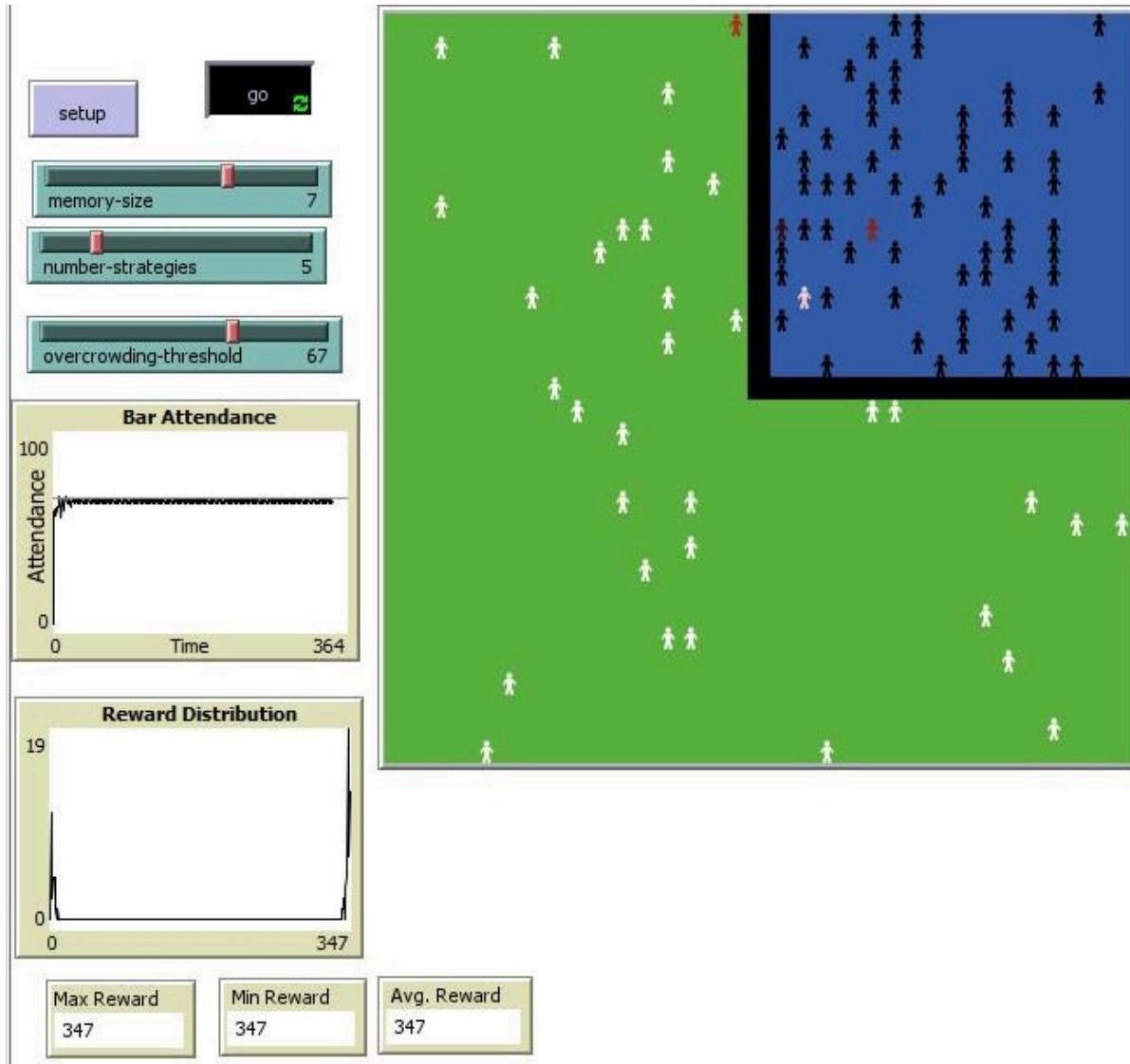
### Observation:

With the number of strategies reduced to 5, each agent has fewer options to choose from when predicting attendance. As a result, learning is slower because agents have a smaller pool of

3.

strategies to identify the most accurate predictions. This leads to less optimal decisions and slightly more fluctuations in bar attendance compared to having more strategies.

Change OVERCROWDING-THRESHOLD and analyze attendance

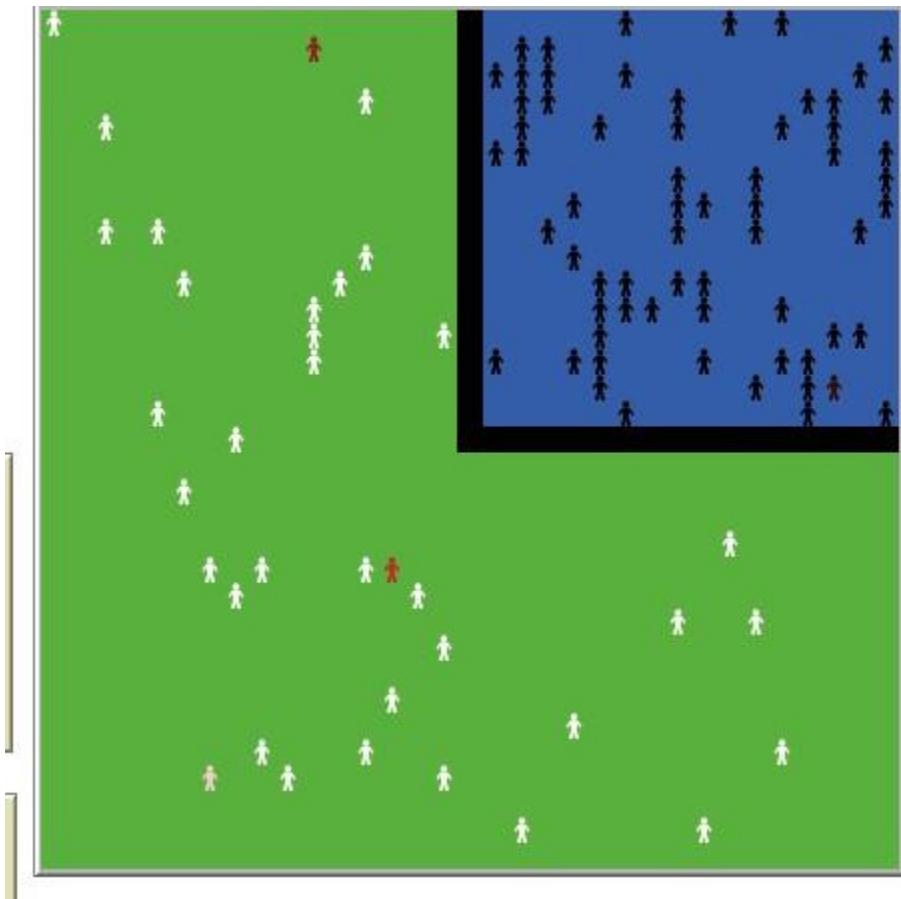


**Observation:**

#### 4.

With the overcrowding-threshold set to 67, more agents are allowed to attend the bar before it is considered crowded. This results in higher overall attendance and fewer agents avoiding the bar. The bar reaches the ‘CROWDED’ state less frequently, and agents adjust their behavior accordingly, demonstrating how the threshold directly influences attendance patterns and decision-making.

Observer reward distribution over long runs



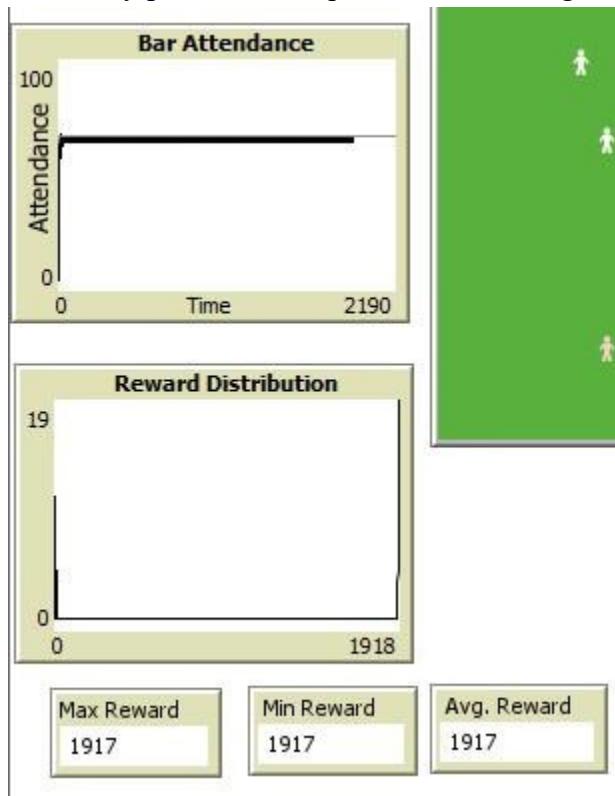
#### Observation:

Over long runs, agents who consistently attend the bar when it is not crowded accumulate higher rewards, while those who avoid the bar or attend when it is crowded accumulate fewer rewards. The reward distribution shows a clear pattern where successful prediction and

## 5.

decision-making lead to greater rewards. This is visually represented by turtles' colors, with darker turtles indicating higher accumulated rewards.

Identify periods of frequent overcrowding



### Observation:

Periods of frequent overcrowding occur when many agents predict that attendance will be low and decide to go to the bar simultaneously. These periods can be identified by repeated appearances of the 'CROWDED' label on the bar patches. This demonstrates how collective decision-making based on similar strategies can lead to temporary spikes in attendance, even though agents are trying to avoid overcrowding.

## **Post-Lab Questions**

### **1. Why do agents fail to reach a stable attendance level?**

Agents continuously adapt their decisions based on predictions and past attendance. Since many agents act simultaneously, their collective behavior changes attendance each tick, preventing a perfectly stable level.

### **2. How does limited memory affect predictions?**

Limited memory reduces the historical data agents can use, leading to less accurate and more fluctuating predictions of attendance.

### **3. Why is always attending not the chosen strategy?**

Always attending risks overcrowding the bar, which lowers rewards. Agents learn to balance attendance to maximize reward rather than blindly attending every tick.

### **4. What role does reward play in learning?**

Reward signals which strategies are successful. Agents prefer strategies that have yielded higher rewards, guiding future predictions and improving decision-making over time.

### **5. How does this model reflect real economic behavior?**

The model mimics situations where individuals make decisions based on limited information and adapt to avoid overcrowded resources, similar to real-world markets where participants respond to supply, demand, and collective behavior.

## Lab 12: Brian's Brain — A 2D Cellular Automaton

### Objective

- To explore the dynamics of a two-dimensional cellular automaton (CA) with three cell states.
- To observe moving and stable patterns called gliders.
- To interactively manipulate cell states and understand how simple rules lead to complex behaviors.

### Tool / Environment

- **Software:** NetLogo 6.4.0
- **Platform:** Windows
- **Environment:** Interface + Code Tab

### What is Brian's Brain?

Brian's Brain is a 2D cellular automaton. Unlike simpler CAs (like Conway's Game of Life) that use only two states (live and dead), Brian's Brain uses three states:

Cell State	Color	Description
Firing	White	Active cell that will soon become refractory
Refractory	Red	Just fired, cannot fire again immediately
Dead	Black	Inactive cell, can become firing if conditions are met

This CA is interesting because many patterns **move steadily across the grid**, forming **gliders** and other dynamic structures.

### Lab Procedure

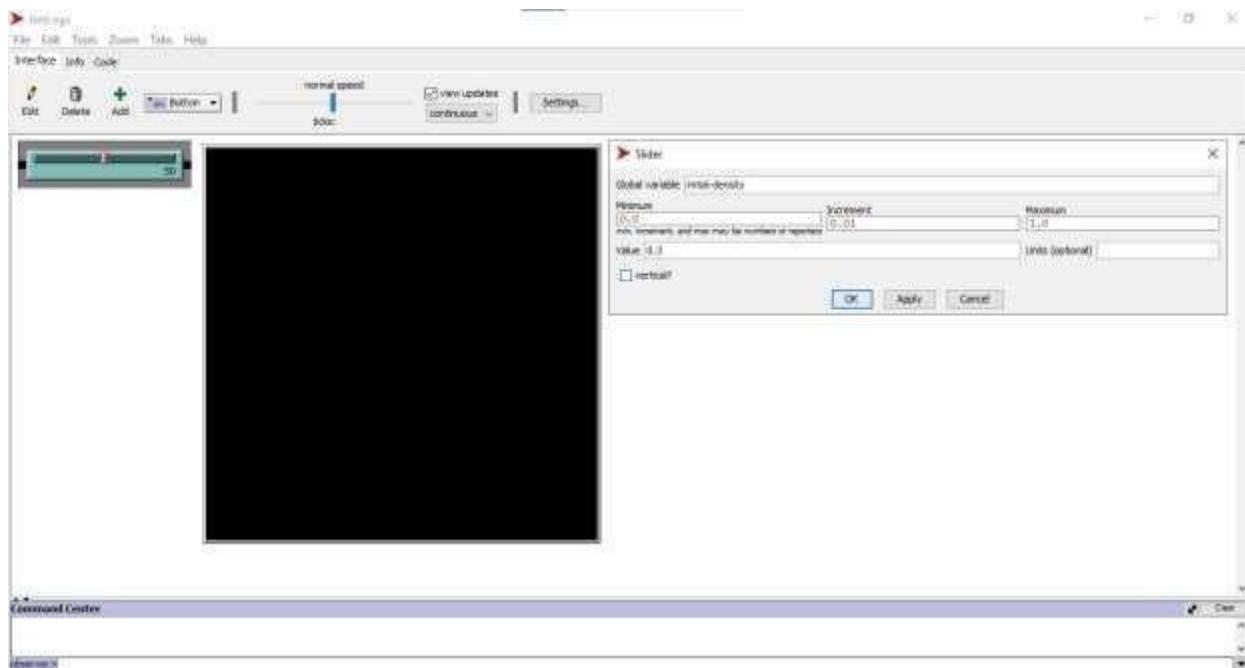
#### Step 1: Add Required Interface Elements

##### Sliders

Add these sliders in the Interface tab:

##### INITIAL-DENSITY

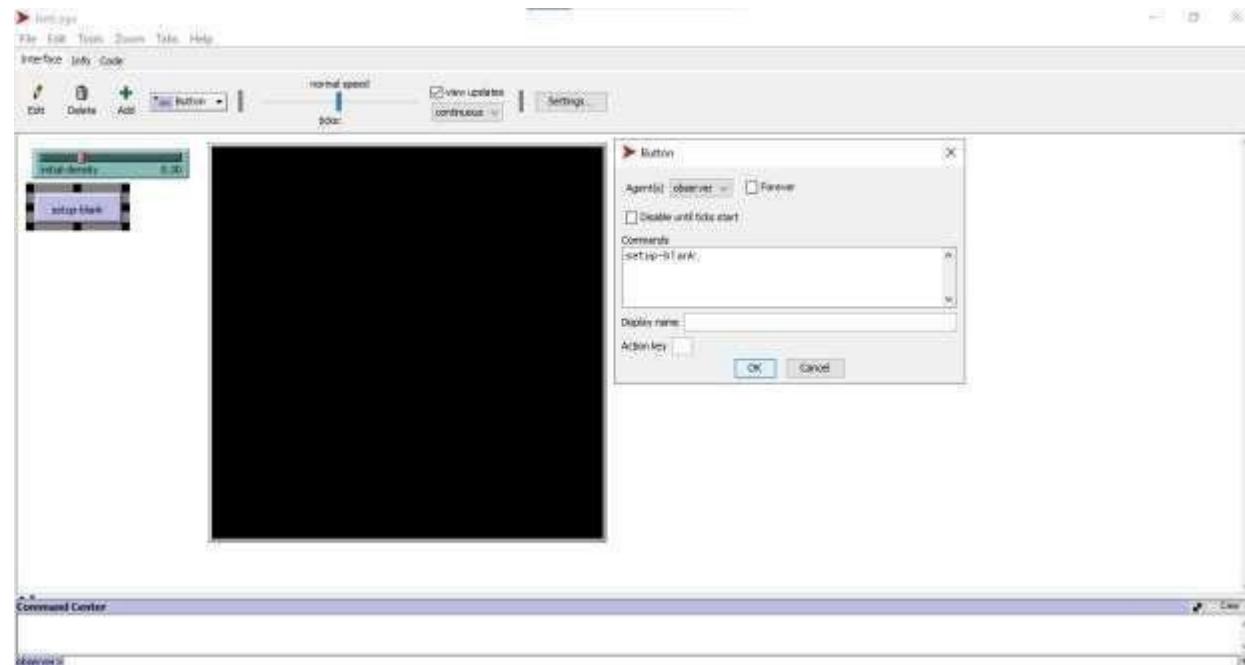
- Min: 0.0 ○ Max: 1.0 ○ Initial: 0.3
- Increment: 0.01



## Buttons

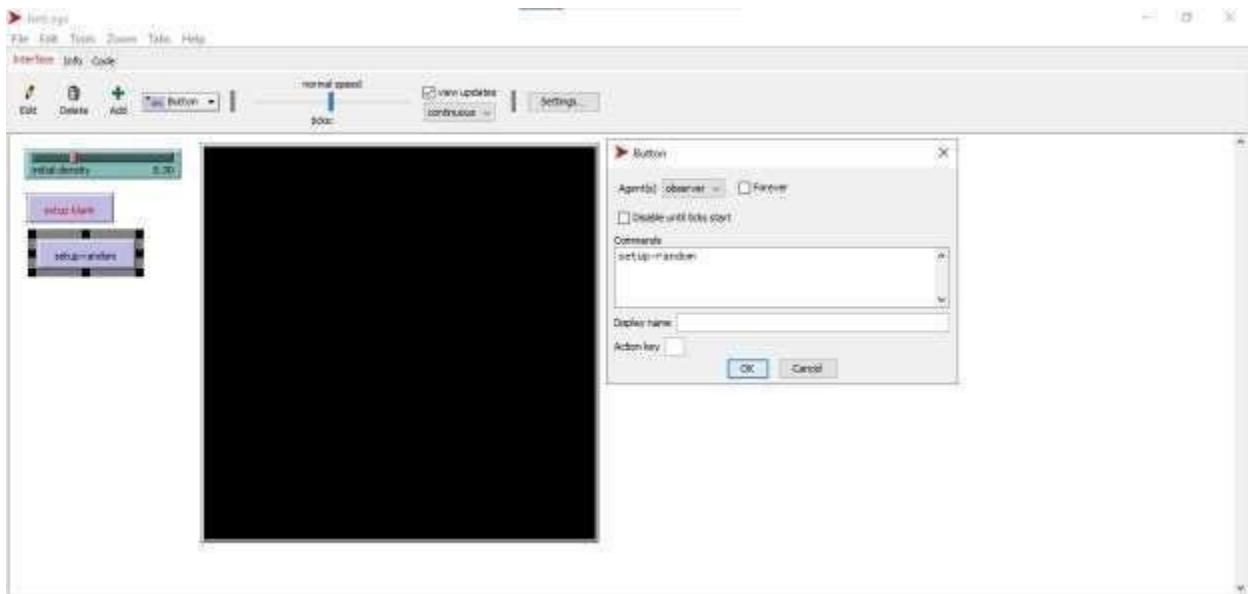
### 1. Setup Blank

- o Command: setup-blank



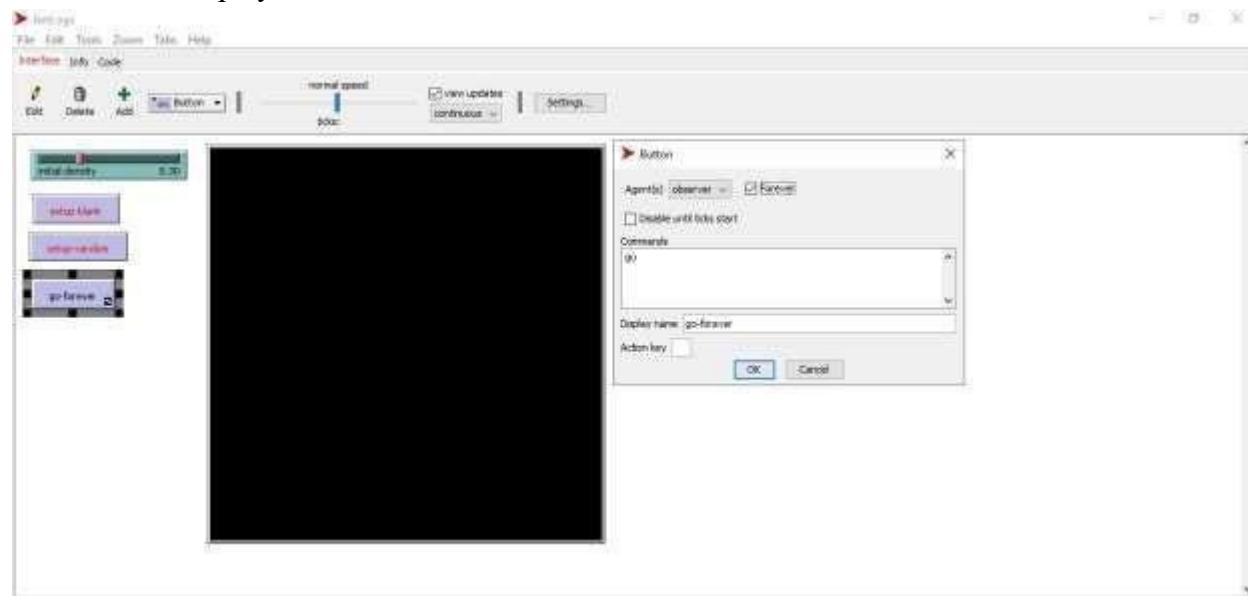
### 2. Setup Random

- o Command: setup-random



### 3. Go Forever

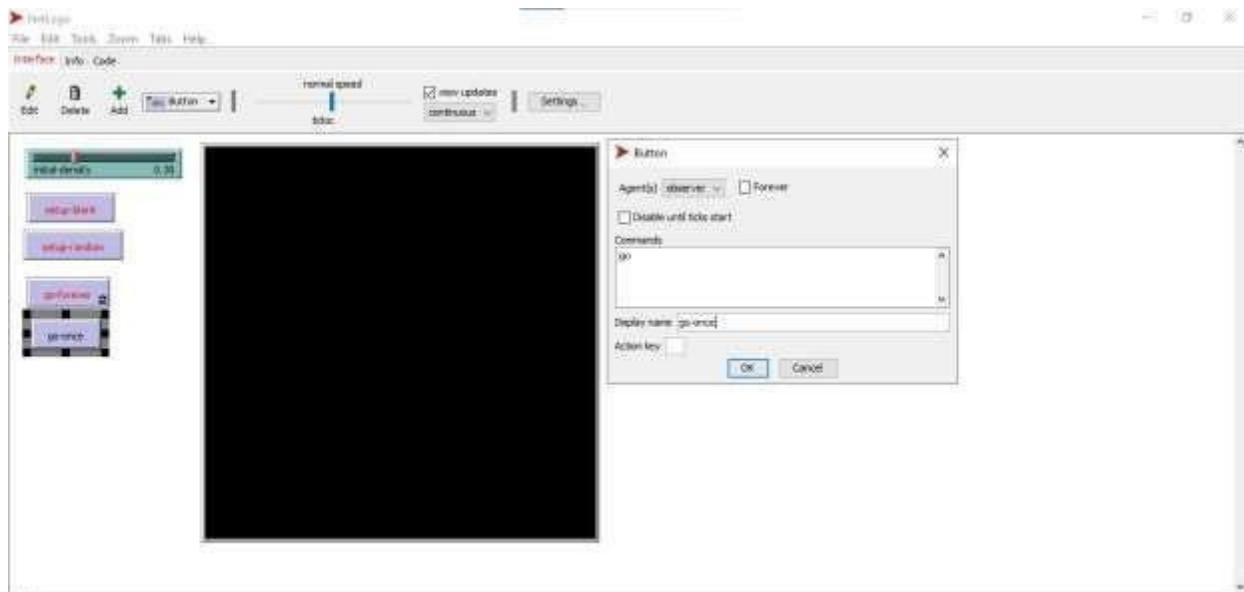
- o Command: go
- o Display name: Go Forever



### 4. Go Once

- o Command: go
- o Display name: Go

## Once



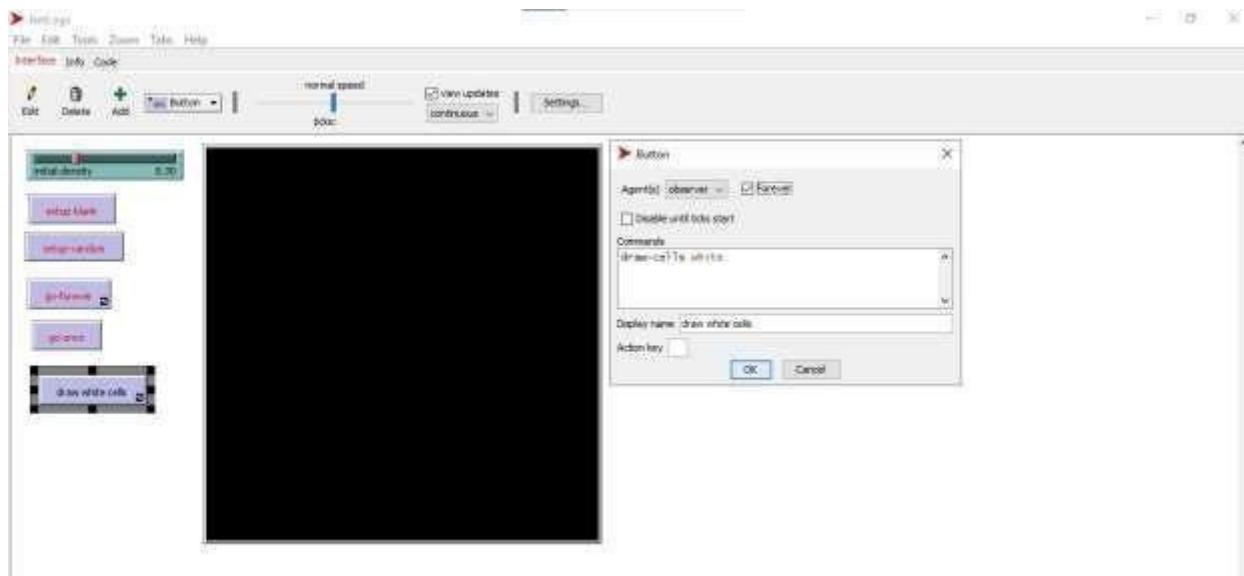
### 5. Draw White Cells

Command: draw-cells white

Display name: Draw White

Cells

Action: Forever



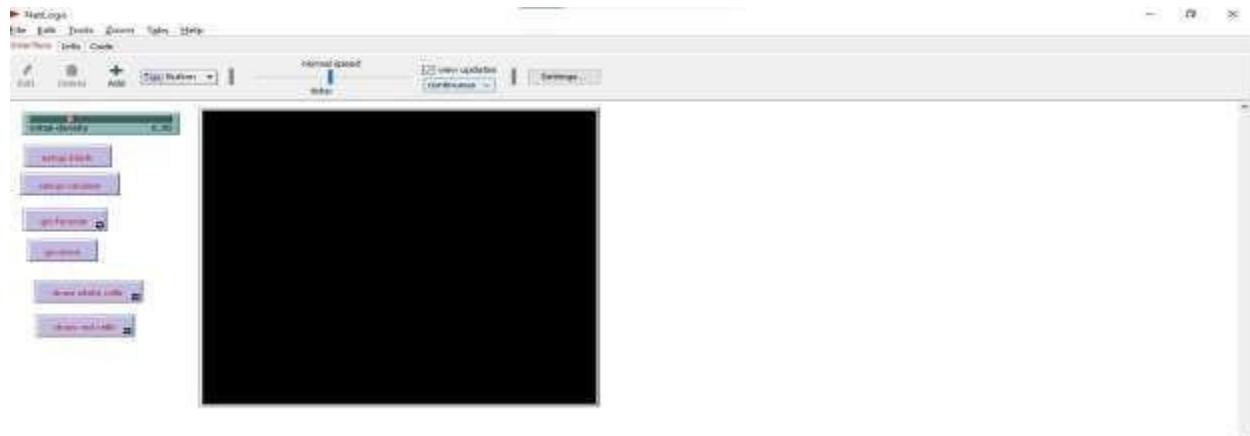
### 6. Draw Red Cells

Command: draw-cells red

Display name: Draw Red

Cells

Action: Forever



7. **Note o Text:** When one of these

buttons is down, you

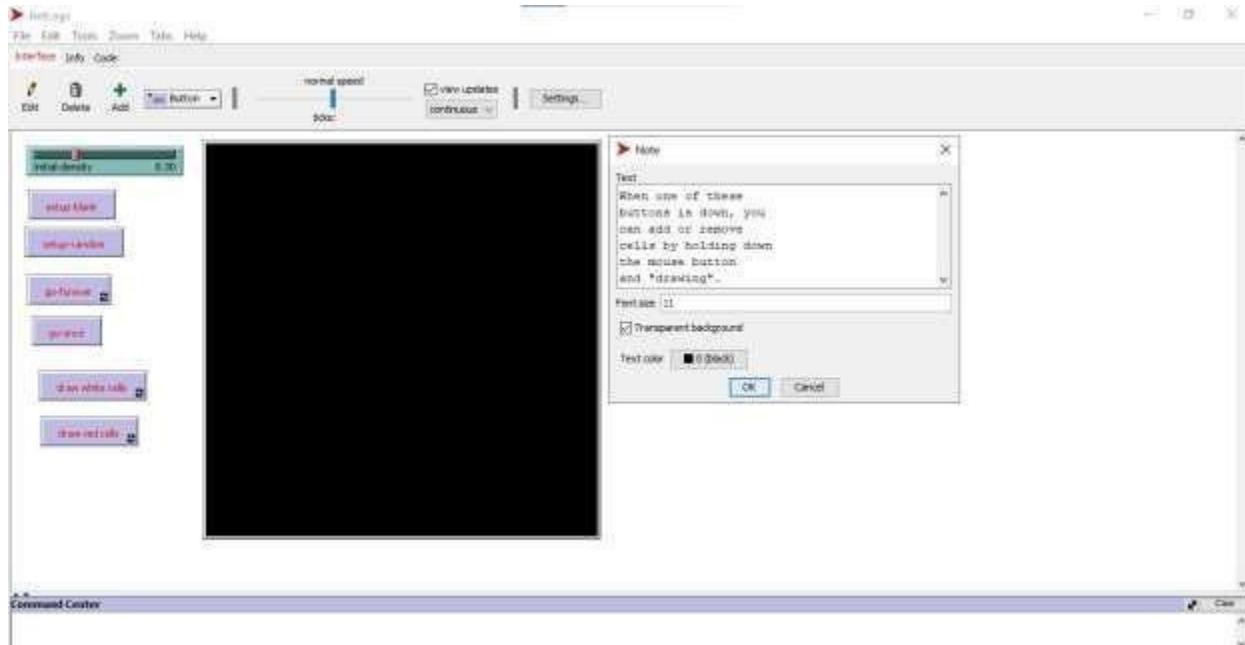
can add or remove

cells by holding

down the mouse

button and

"drawing".



## Step 2: Add the Full Code in the Code Tab

```

globals [erasing?;;isthecurrentdraw-cells mouse click erasing or
adding?
]

```

```

patches-own [
  firing?      ;; white cells refractory?      ;; red cells firing-
  neighbors ;; counts how many neighboring cells are firing
]

```

```

to setup-blank
  clear-all ask
    patches
    [ cell-death
    ] reset-ticks
  end

```

```

to setup-
  random clear-
  all ask patches
  [ ifelse random-float 1.0 < initial-density
    [ cell-birth ]
  ]

```

```

[ cell-death ]
] reset-ticks

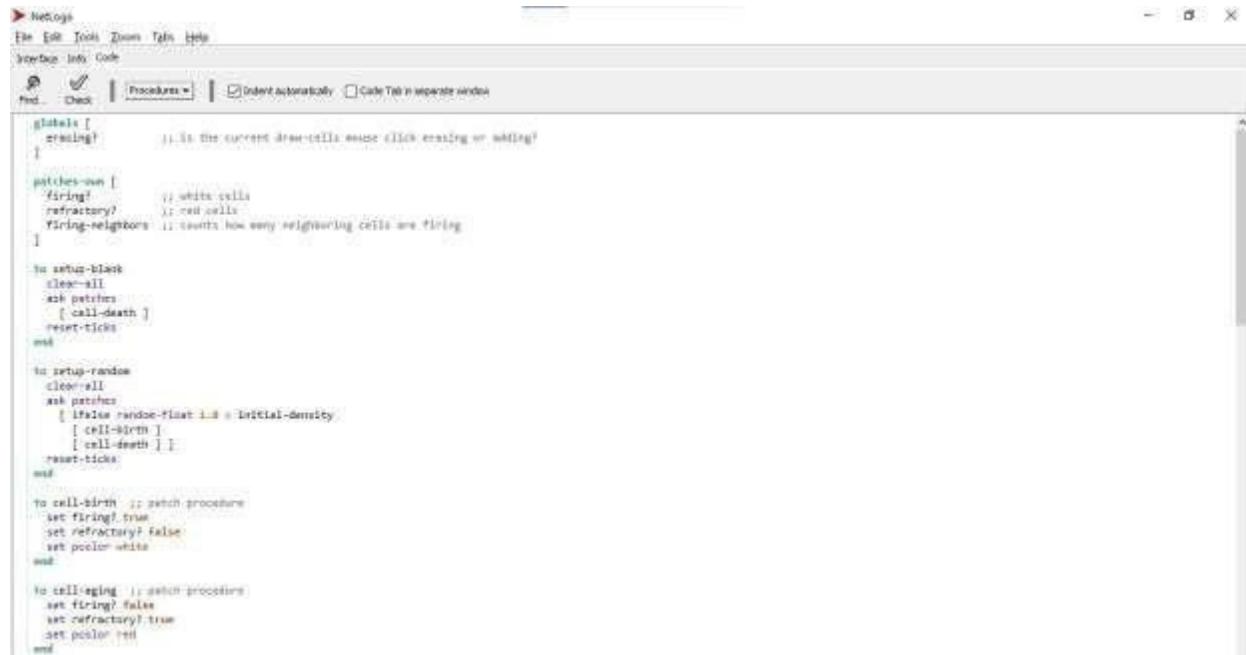
end

to cell-birth ; patch
  procedure set firing? true
  set refractory? false set
  pcolor white end

to cell-aging ; patch
  procedure set firing? false
  set refractory? true set
  pcolor red

end

```



```

to cell-death ; patch procedure
  set firing? false set
  refractory? false set pcolor
  black end

```

```

to go ask patches
  [ set firing-neighbors count neighbors with [firing?] ]
  ; Starting a new "ask patches" here ensures that all the patches
  ; finish executing the first ask before any of them start executing

```

;; the second ask. This keeps all the patches in sync with each other, ;;  
so the births and deaths at each generation all happen in lockstep. ask  
patches [ ifelse firing?

```
[ cell-aging ]
[ ifelse refractory?
  [ cell-death ] [ if
    firing-neighbors =
      2[ cell-birth ] ]
  ] tick
end
```



**to draw-cells** [target-color] ifelse mouse-down? [ if erasing? = 0 [ set  
erasing? target-color = [pcolor] of patch mouse-xcor mouse- ycor  
]  
ask patch mouse-xcor mouse-ycor  
[ ifelse erasing? [ cell-  
death  
][  
ifelse target-color = white [  
cell-birth  
][  
cell-aging  
]  
]  
]  
]  
display  
][  
set erasing? 0  
]

```
end
```

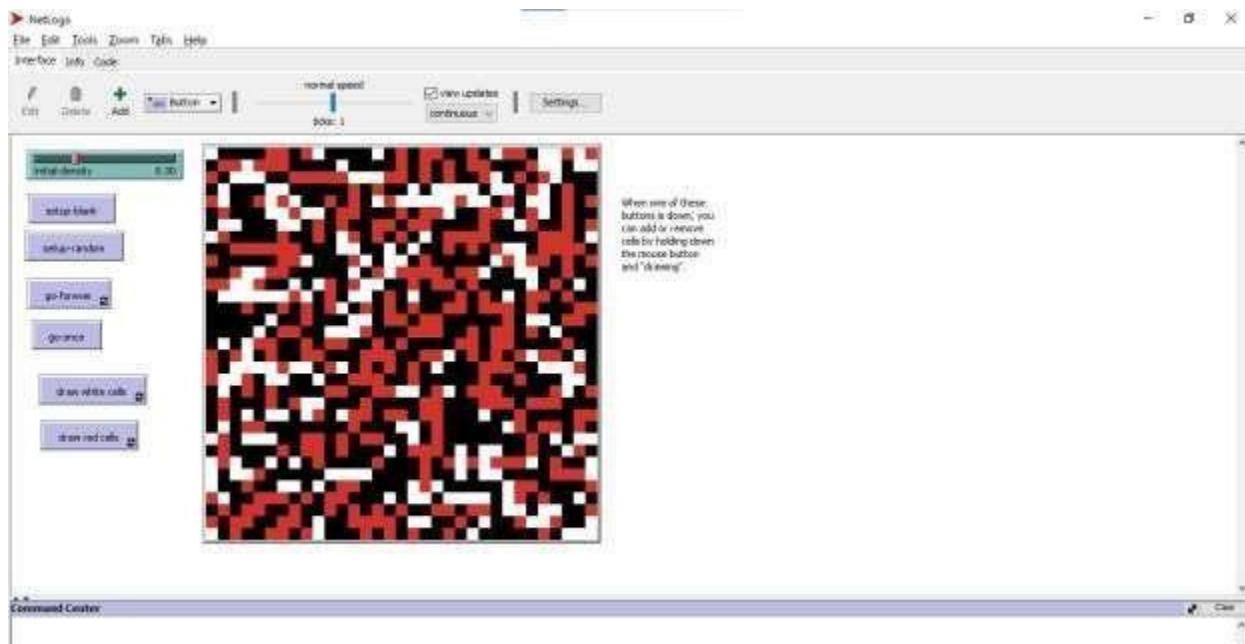
```
to mouse-cell [target-color]
  if mouse-dead? [
    set erasing? true
    ask erasing? target-color of patch mouse-xcor mouse-ycor
  ]
  ask switch mouse-xcor mouse-ycor [
    if mouse-dead? [
      self-death
    ]
    ifelse target-color = white [
      cell-kite
    ]
    [
      cell-agings
    ]
  ]
  display
  set erasing?
end
```

## Output

### 1. Select random



### 2. Select go-once

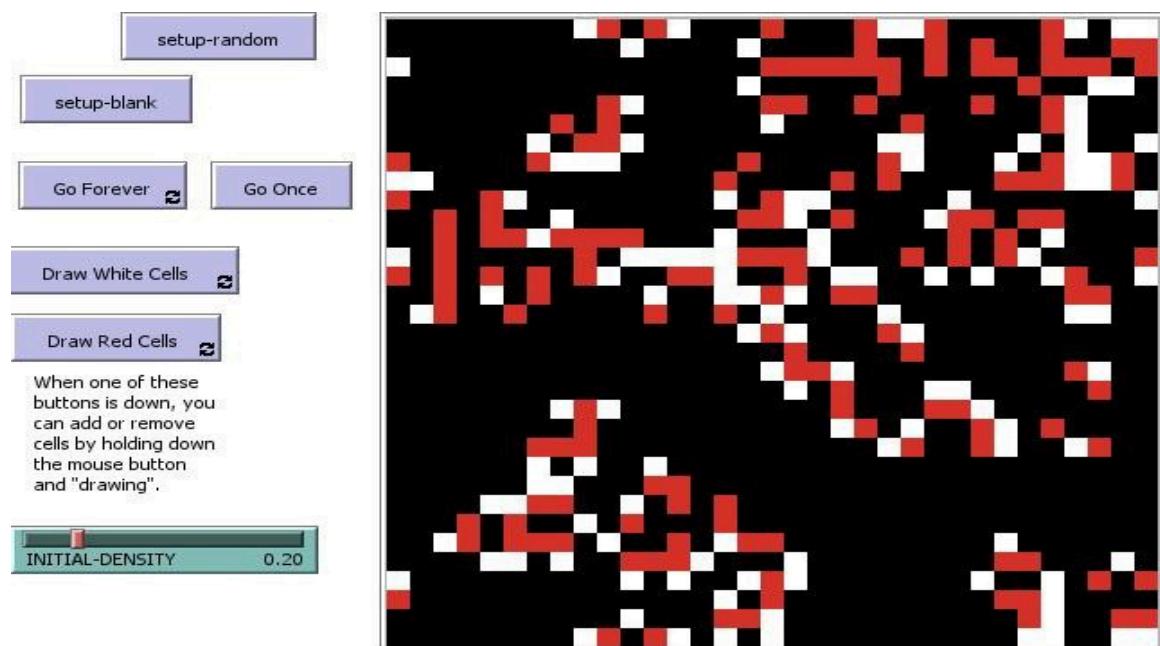
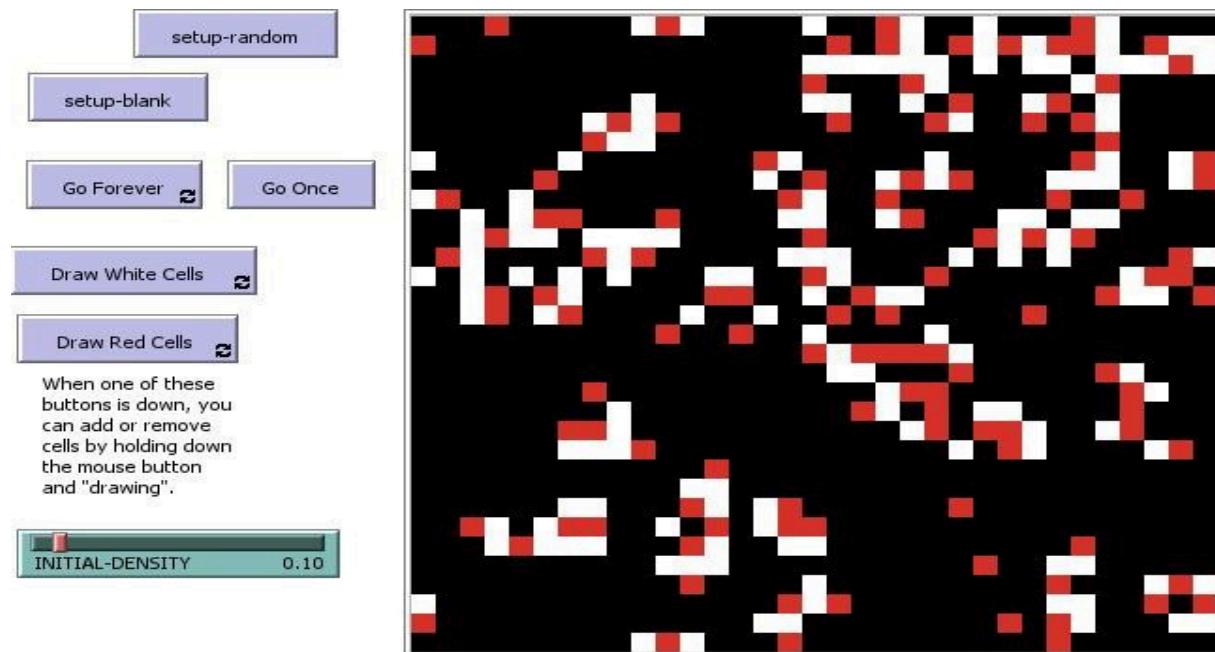


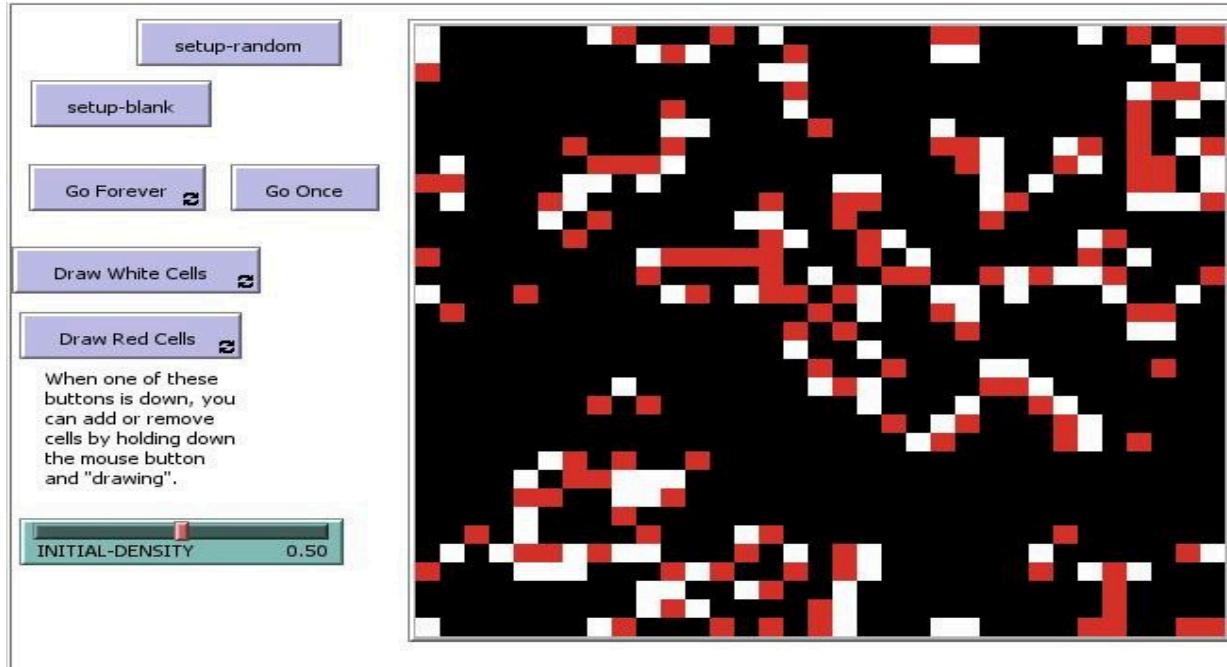
### 3. Select go-forever



## STUDENT TASK

1. **Explore Initial Patterns**
  - o Use the Setup Random button to initialize the grid with different INITIALDENSITY values (0.1, 0.2, 0.5).
  - o Observe how the density of firing cells affects the evolution of patterns over time.





## OBSERVATION

**Density 0.1:** Few firing cells; patterns grow slowly, and clusters are small.

**Density 0.2:** More firing cells; clusters form faster, and activity spreads more widely.

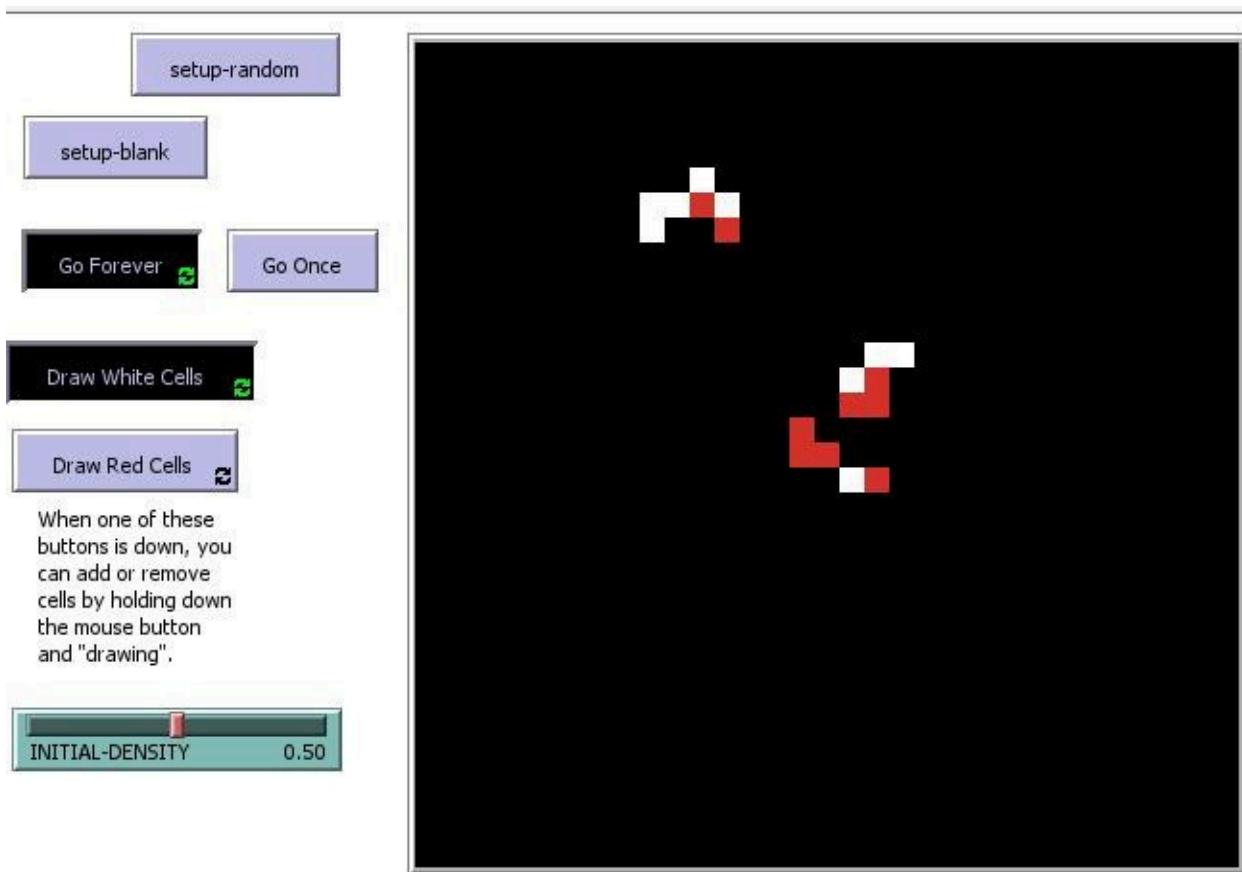
**Density 0.5:** Many firing cells; the grid is highly active, and patterns emerge rapidly but may die out or stabilize depending on neighbor interactions.



2.

**Observe Gliders** o Run Go Forever and watch for moving patterns (gliders).

- o Try drawing small groups of firing cells manually using Draw White Cells to see if you can create new gliders.

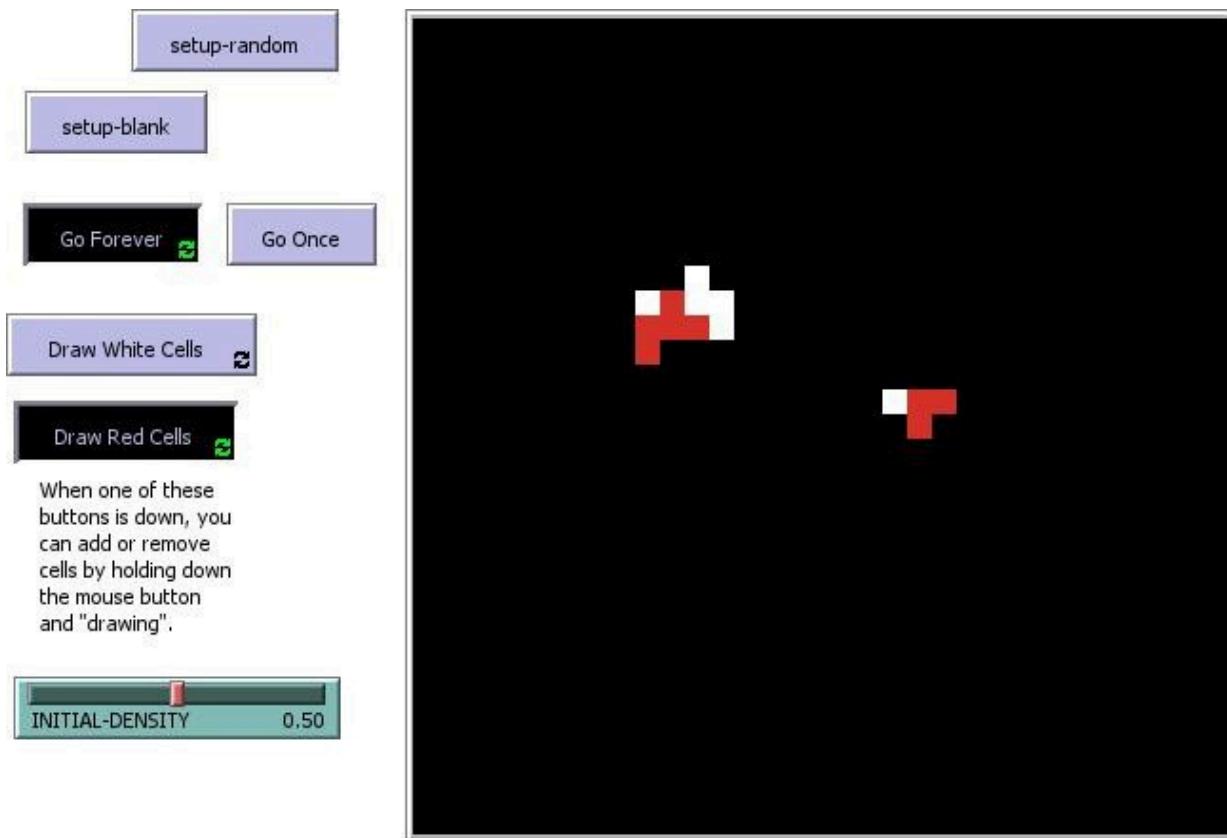


### Observation

Gliders are small patterns of firing cells that move diagonally across the grid while maintaining their structure. By manually drawing specific configurations, new gliders can be created. This demonstrates that local arrangements of cells determine the emergence and direction of moving patterns in the cellular automaton.

### 3.

**Manipulate the Grid** o Use Draw Red Cells and mouse erasing to modify patterns during the simulation. o Observe how adding or removing cells affects glider formation and stability.



### Observation

Manipulating the grid during the simulation shows that adding or removing cells significantly affects glider behavior. Red cells can block or destroy gliders, while erasing cells can create opportunities for new gliders to emerge. This demonstrates that the system is highly sensitive to local changes, and small modifications can dramatically alter pattern stability and evolution.

**Experiment with Cell Rules** o Modify the go procedure to require 3 firing neighbors for a dead cell to become firing. o Compare the simulation outcome with the original rule.

4.

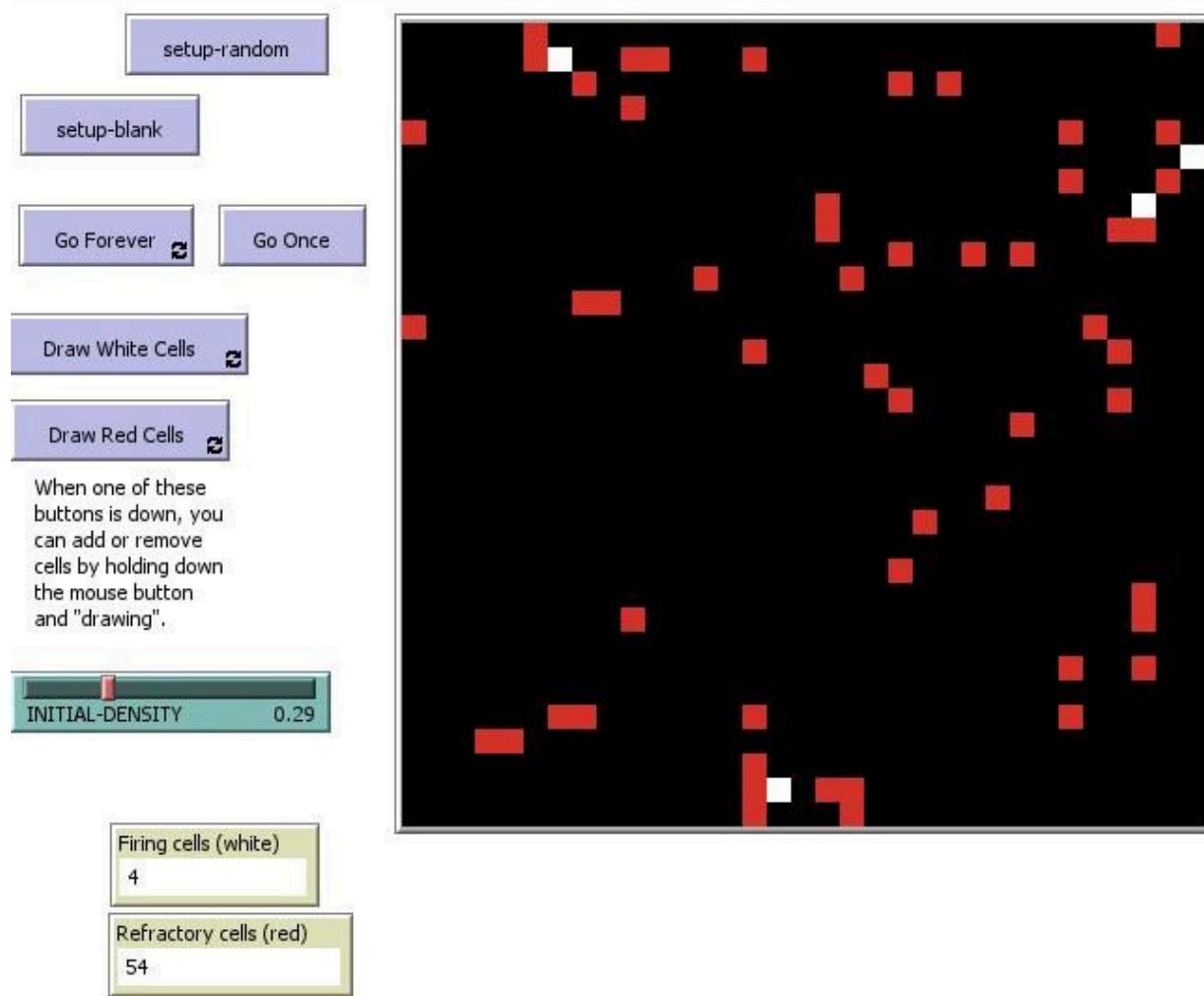
```
to go
ask patches
[ set firing-neighbors count neighbors with [firing?]
;; Starting a new "ask patches" here ensures that all
;; finish executing the first ask before any of them :
;; the second ask. This keeps all the patches in sync
;; so the births and deaths at each generation all happen
ask patches
[ ifelse firing?
[ cell-aging ]
[ ifelse refractory?
[ cell-death ]
[ if firing-neighbors = 3
[ cell-birth ] ] ] ]
tick
end
```

### Observation

Changing the birth rule to require 3 firing neighbors reduces the number of new cells and slows pattern evolution. Compared to the original rule (2 neighbors), fewer gliders and moving patterns emerge. This demonstrates how small changes in local rules can drastically alter the overall behavior and dynamics of the cellular automaton.

- Monitor Cell Counts**
  - o Observe the monitors for firing and refractory cells.
  - o Record the number of cells in each state at regular intervals (every 10 ticks).

5.

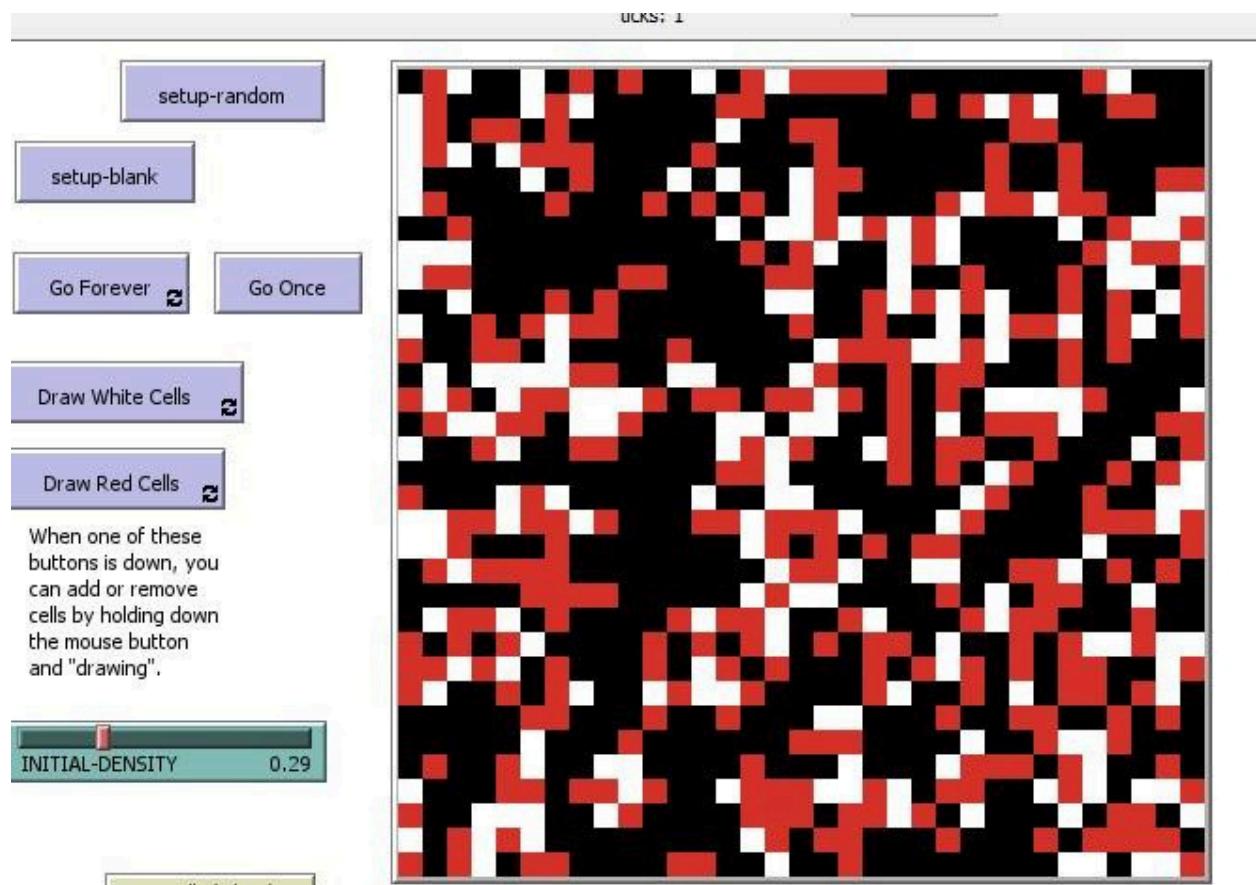


### Observation:

The monitors show how many cells are in the firing and refractory states at each tick. Firing (white) cells increase and then transition to refractory (red), while refractory cells eventually die and become black. Recording the counts every 10 ticks highlights the oscillatory nature of the system and how cells cycle through active and inactive states over time.

## 6.

**Pattern Analysis** o Identify stable patterns, oscillators, and moving gliders. o Note the direction, speed, and interaction of gliders.



## OBSERVATION

The simulation shows three types of patterns:

- **Stable patterns** like blocks remain unchanged over time.
- **Oscillators** cycle through repeating states without moving.

7.

- **Gliders** are small patterns that move diagonally across the grid. Gliders maintain their shape, move at a steady speed, and interact with other patterns, sometimes merging or disappearing upon collision. Observing these patterns demonstrates how local interactions lead to complex and dynamic behavior in cellular automata.

## POST LAB QUESTIONS

### 1. Understanding the Rules

- o Explain the three states of cells in Brian's Brain and how each state transitions to the next.

- Firing (white):** Active cells that turn refractory in the next tick.
  - Refractory (red):** Recently fired cells that cannot fire immediately; they turn dead next.
  - Dead (black):** Inactive cells that can become firing if exactly 2 neighbors are firing.

- o Why does a dead cell only become firing if it has exactly 2 firing neighbors?

This ensures controlled propagation and allows patterns like gliders to form, preventing overcrowding of firing cells.

### 2. Observation and Analysis

- o What differences do you notice when running the simulation with different initial densities?

Low density produces slow, sparse patterns; medium density forms clusters and moving gliders; high density results in rapid activity and sometimes chaotic patterns.

- o How many distinct types of gliders can you identify in your simulation?

Multiple gliders are observed, usually moving diagonally. Variations in shape may produce differences in speed or interaction.

### 3. Experimentation

- o What happens if you change the rule for dead cells from 2 firing neighbors to 3?

Fewer cells are born, pattern evolution slows, and glider formation is often reduced or prevented.

- o How does manually adding or removing cells affect the formation and movement of gliders?

Adding or removing cells can block or create gliders, redirect their movement, or destabilize existing patterns, showing sensitivity to local changes.

### 4. Critical Thinking

- o Why do gliders move steadily across the grid while other patterns remain static?

Gliders maintain a repeating firing-refractory-dead configuration that shifts position each tick while preserving shape. Other patterns lack this coordinated structure, so they remain static or oscillate in place.

- o How does the combination of firing, refractory, and dead states lead to complex behavior despite the simplicity of the rules?

The interplay of the three states with neighbor interactions produces oscillations, gliders, and stable patterns, demonstrating emergent complexity from simple local rules.

- 5. Extension Question** o Propose a modification to the Brian's Brain rules that could create new types of moving patterns or oscillators. Explain your reasoning.

Introduce a “super-firing” state: if a firing cell has 3 or more firing neighbors, it generates two new firing cells in adjacent positions. This could create faster-moving gliders or new oscillators by increasing local propagation while keeping predictable rules.

## Lab 13: One-Dimensional (1D) Elementary Cellular Automata

### Objective

- To understand the concept of one-dimensional cellular automata (1D CA).
- To study how different elementary CA rules generate different patterns.
- To observe how simple binary rules can produce complex and unpredictable behavior.

### Tool / Environment

- **Software:** NetLogo 6.4.0
- **Platform:** Windows
- **Environment:** Interface + Code Tab

### Theory

#### What is a 1D Cellular Automaton?

This lab demonstrates **one-dimensional cellular automata (1D CA)** using NetLogo. A cellular automaton is a simple computational system that evolves over time according to a fixed set of rules. It consists of a collection of cells arranged in a structure, where each cell can exist in one of two states: **ON** or **OFF**.

At the start, the system is initialized with a specific pattern of ON and OFF cells. At each time step (called a **tick**), all cells update their states simultaneously based on predefined rules. These rules determine whether a cell will turn ON or OFF in the next step.

In **one-dimensional cellular automata**, cells are arranged in a single horizontal row. Each cell observes:

- Its own current state
- The state of its immediate left neighbor
- The state of its immediate right neighbor

Using this information, the cell determines the state of the cell directly **below it** in the next row. This process continues row by row until the bottom of the screen is reached, producing a visual pattern over time.

#### Rule System in 1D Cellular Automata

Since each cell checks three cells (left, center, right) and each cell can be either ON or OFF, there are **8 possible neighborhood combinations**:

III, IIO, IOI, IOO,

OII, OIO, OOI, OOO

Each combination has a rule that decides whether the next cell will be ON or OFF. Because each of these 8 rules can independently be ON or OFF, there are:

**$2^8 = 256$  possible rules**

These rules are known as **Elementary Cellular Automaton rules**.

## Rule Representation

In this model:

- **I** represents an ON cell
- **O** represents an OFF cell

Each rule switch corresponds to one neighborhood configuration. For example:

- If the **OOO** switch is ON, then when a cell and both its neighbors are OFF, the next cell will turn ON.
- If the switch is OFF, the next cell will remain OFF.

The overall rule is represented as a **rule number (0–255)**, calculated by converting the ON rule combinations from binary to decimal and adding them.

### Example:

If the switches **011** and **001** are ON:

- 011 (binary) = 3
- 001 (binary) = 1
- Rule number = 4

## Importance of Cellular Automata

Cellular automata are simple in structure but capable of producing very complex patterns. In his book “**A New Kind of Science**”, Stephen Wolfram explains that such simple computational systems can model many natural phenomena more effectively than traditional mathematical equations.

Because of this, cellular automata are used to study:

- Pattern formation
- Complex systems
- Natural processes

- Computational theory

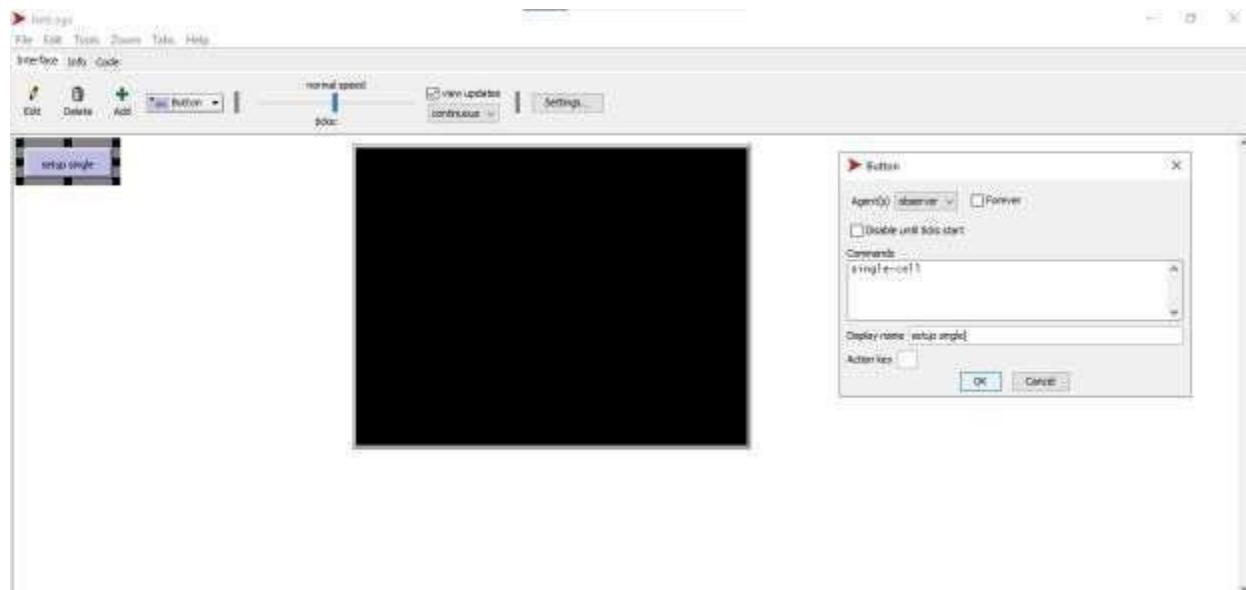
This model allows users to explore **all 256 elementary CA rules** and observe how simple rule changes can lead to dramatically different behaviors.

## Lab Procedure

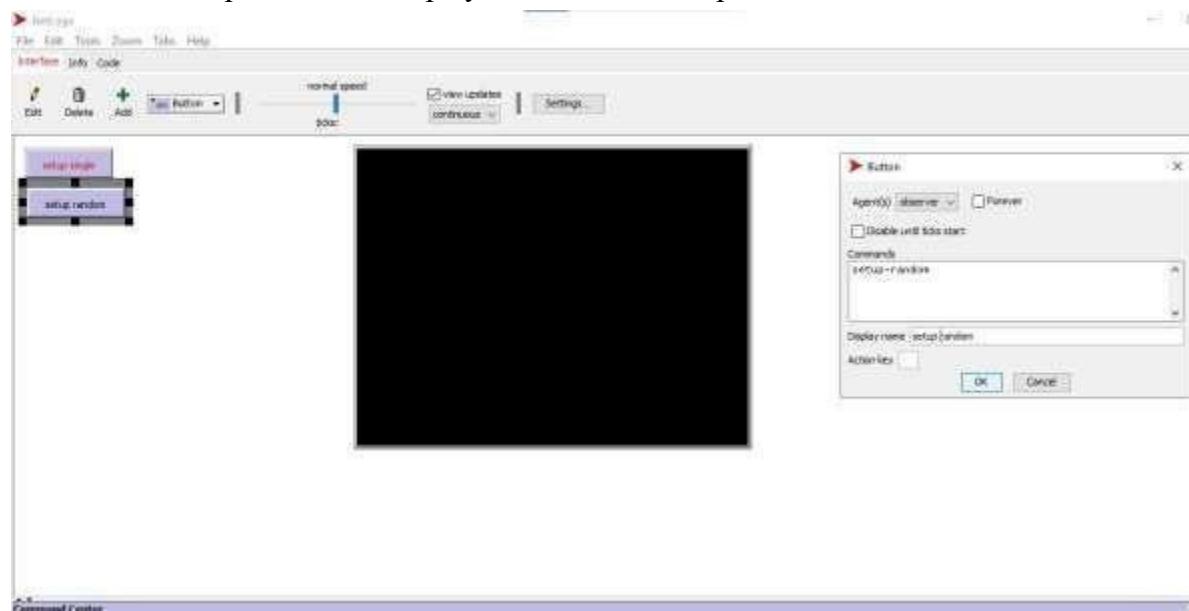
### Step 1: Add Required Interface Elements Design

the Interface exactly as shown:

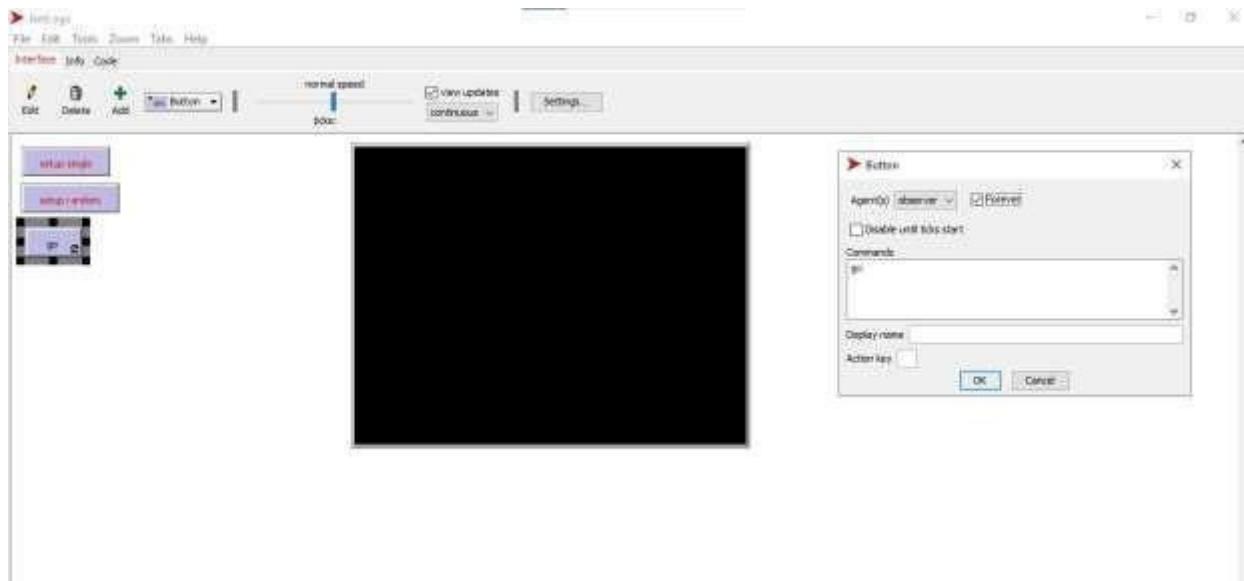
- Buttons:
- Commands: setup-cell
  - Display Name: setup single



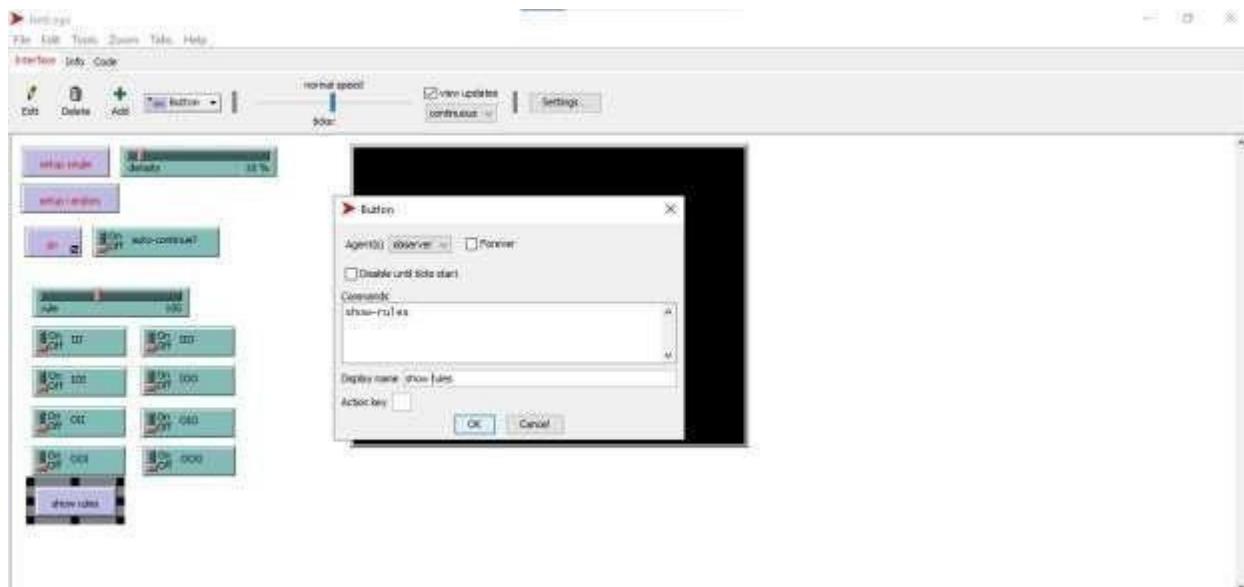
- o Commands: setup-random o Display Name: setup random



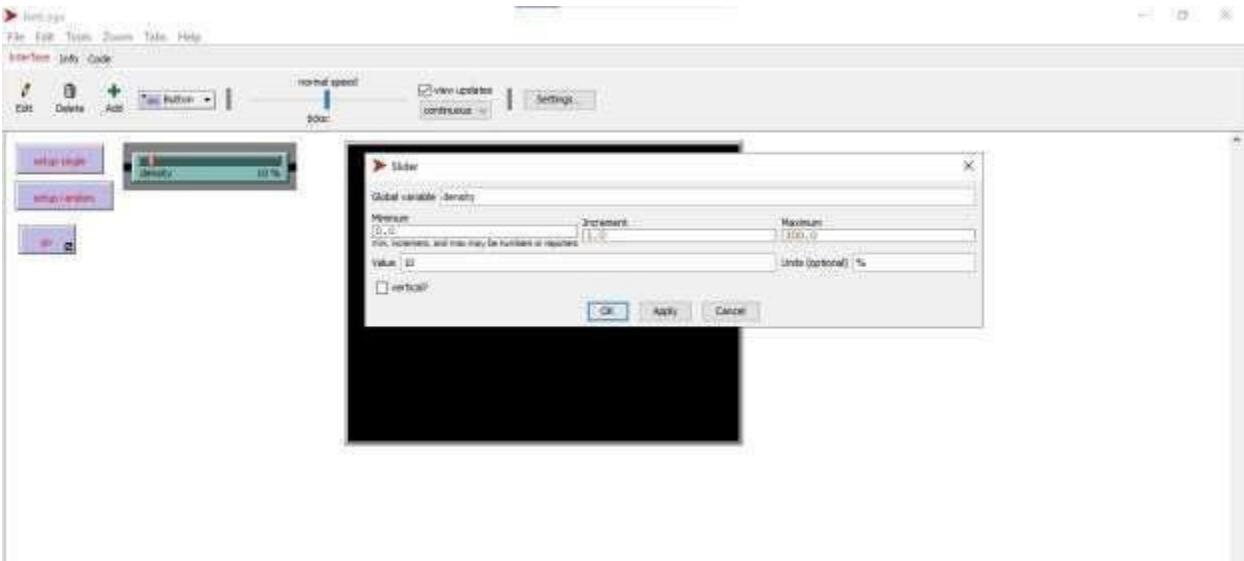
- o go (forever button)



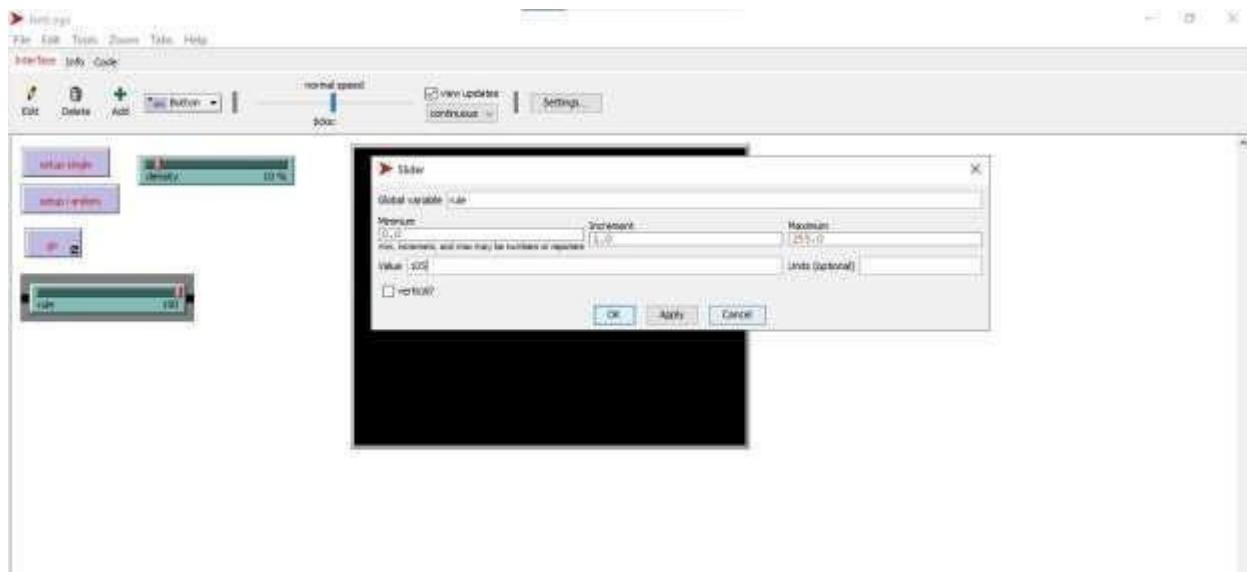
- o Commands: show-rules o Display Name: show rules



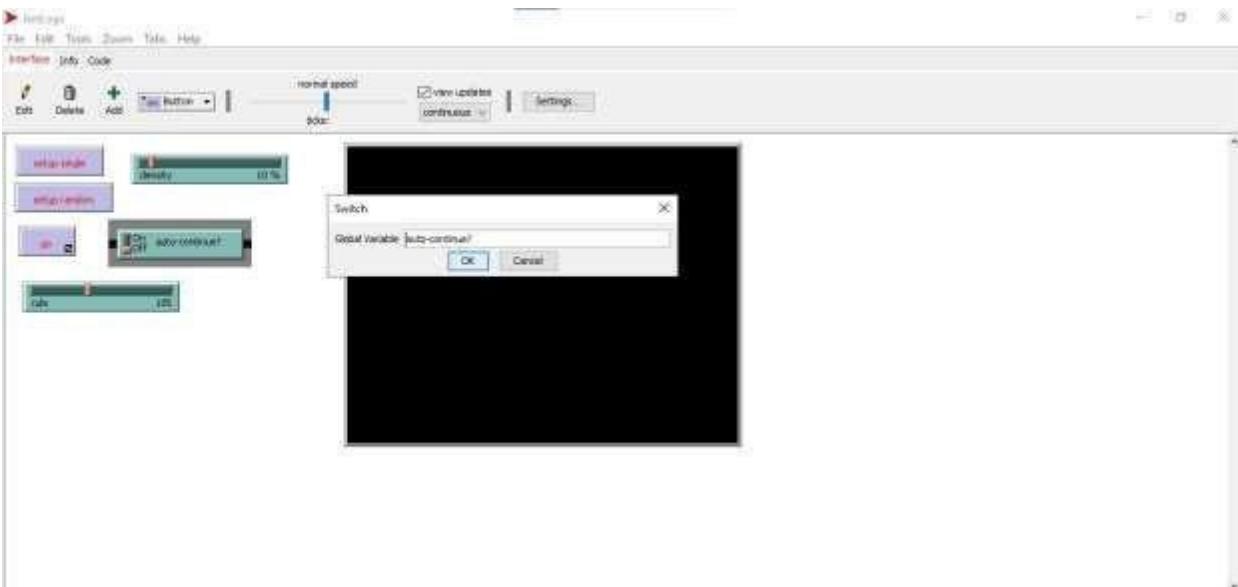
- Slider:
  - density (0.0–100.0, default 10 and increment 1.0)



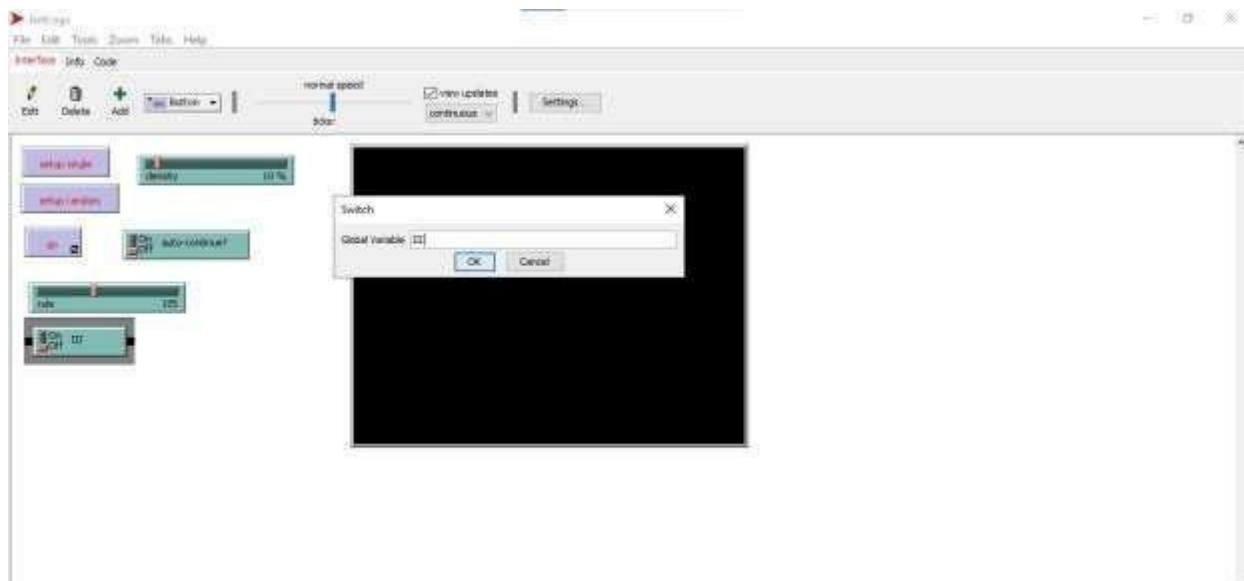
- rule (0.0–255.0, default 105 and increment 1.0)



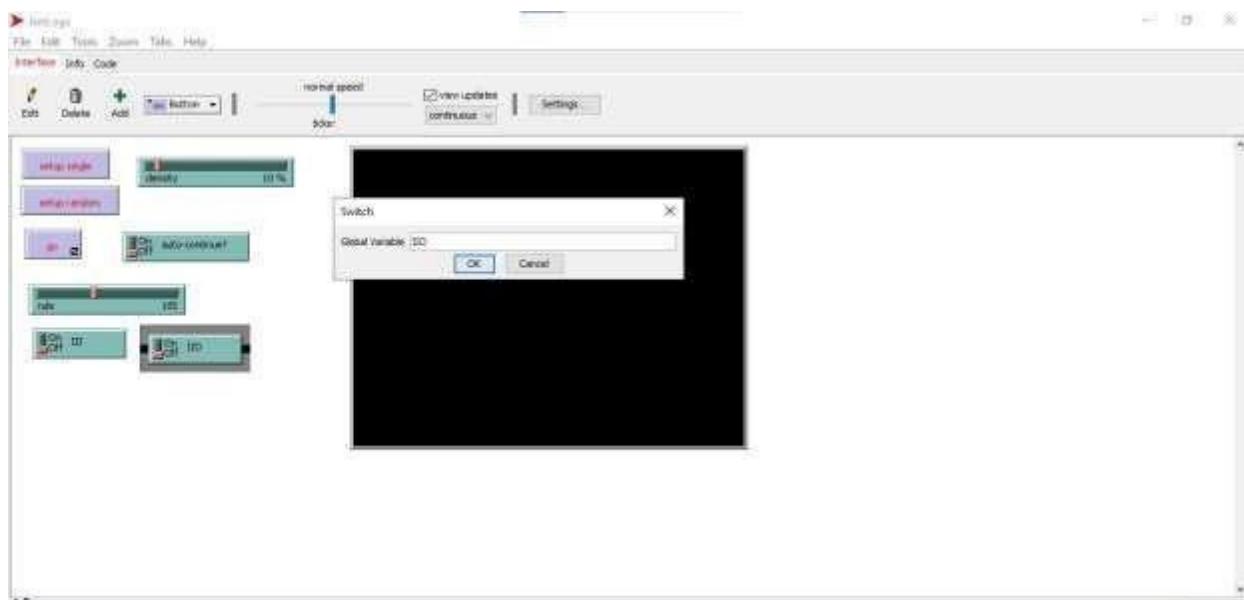
- Switch:
  - auto-continue?



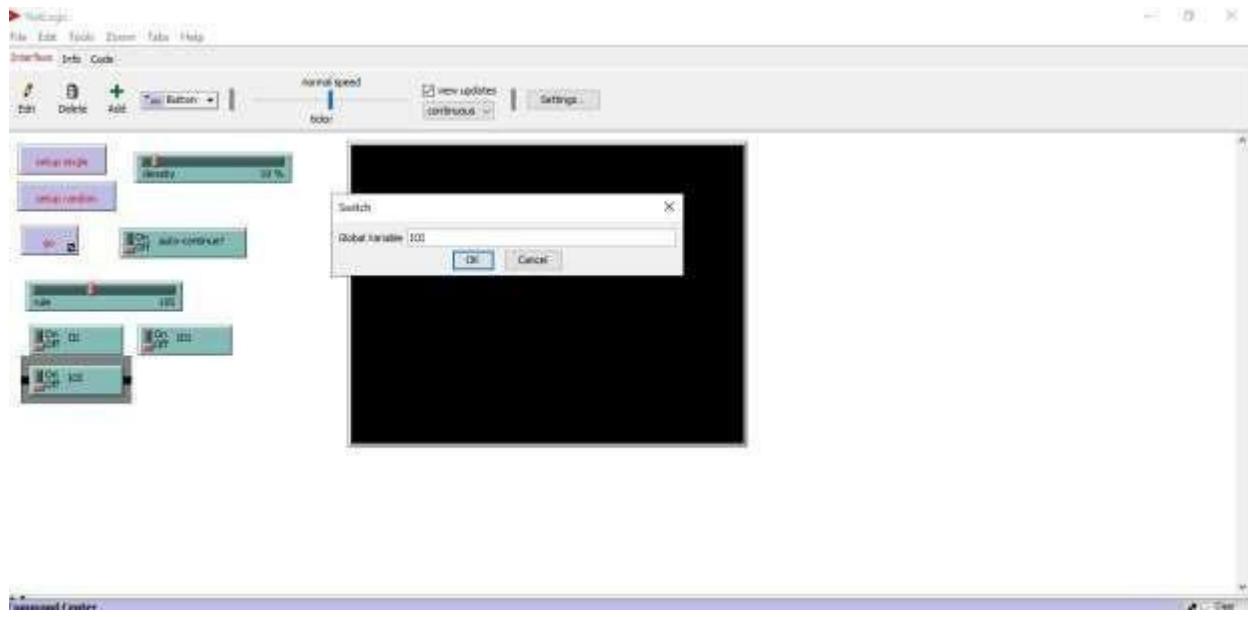
- switches:
  - 111



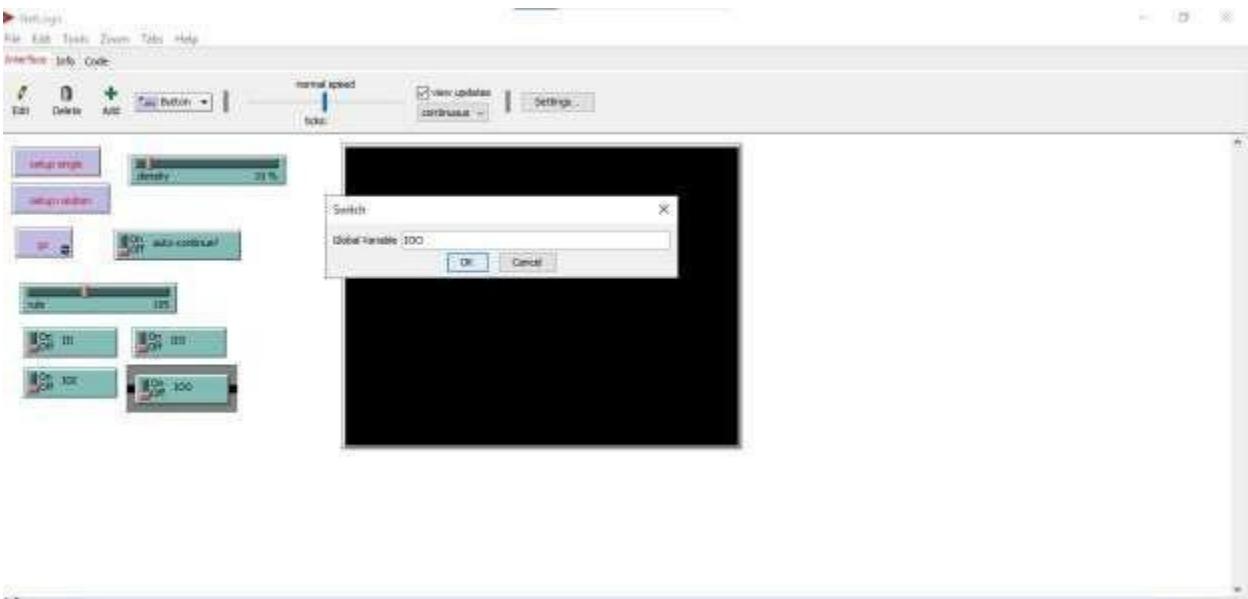
o 110



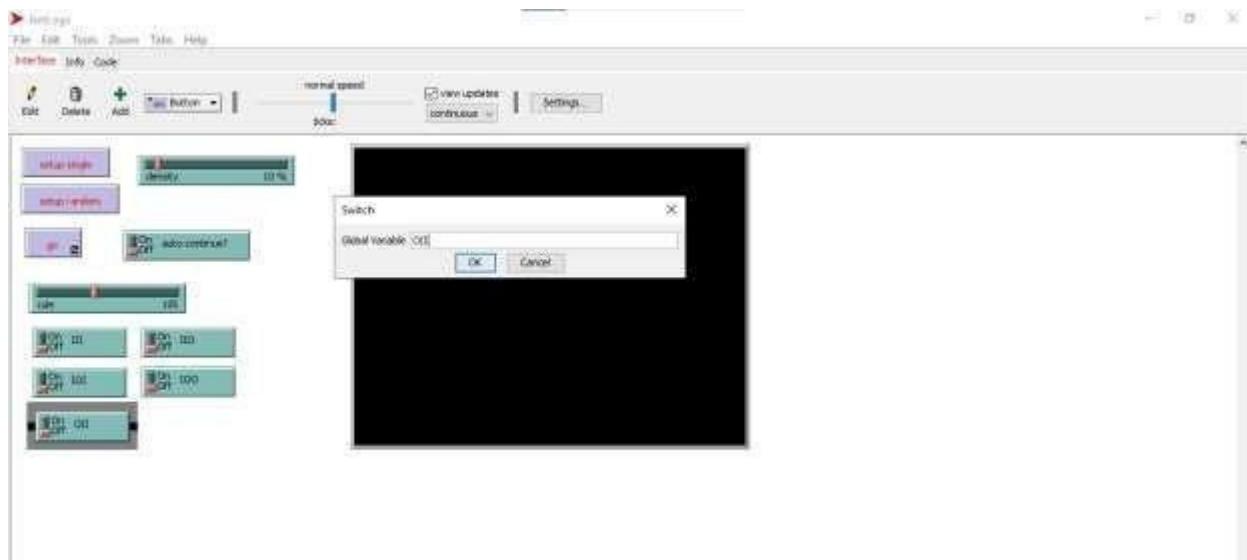
o 101



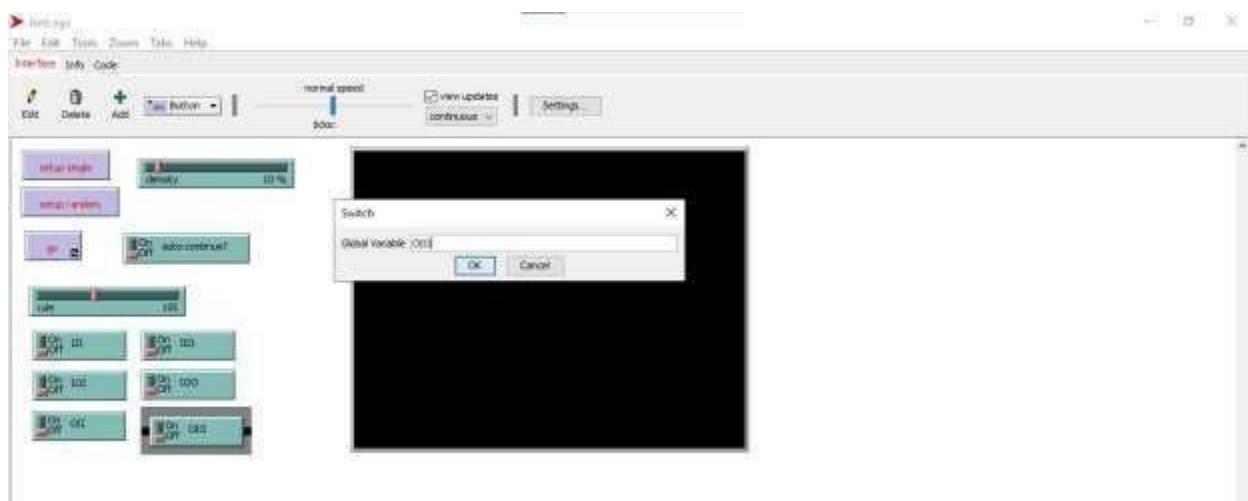
o 100



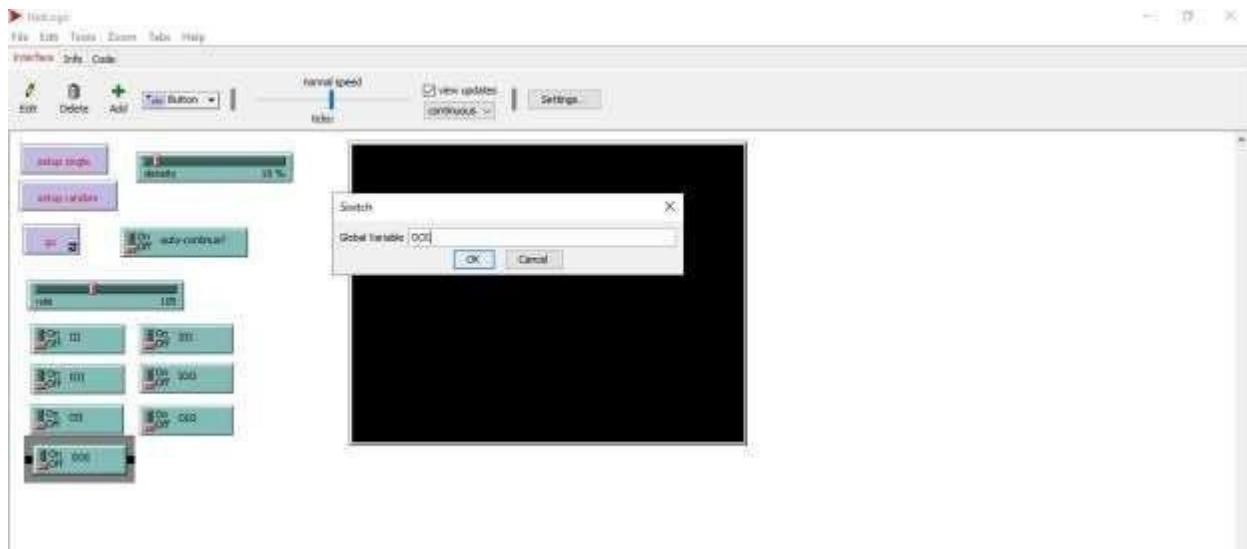
o 011



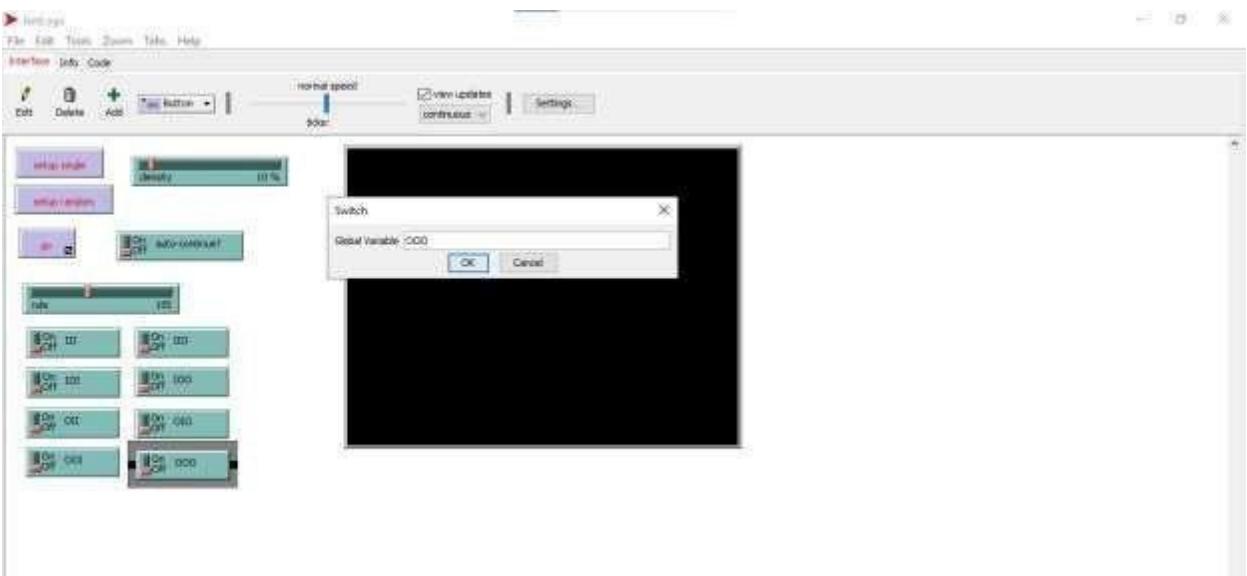
o 010



o 001

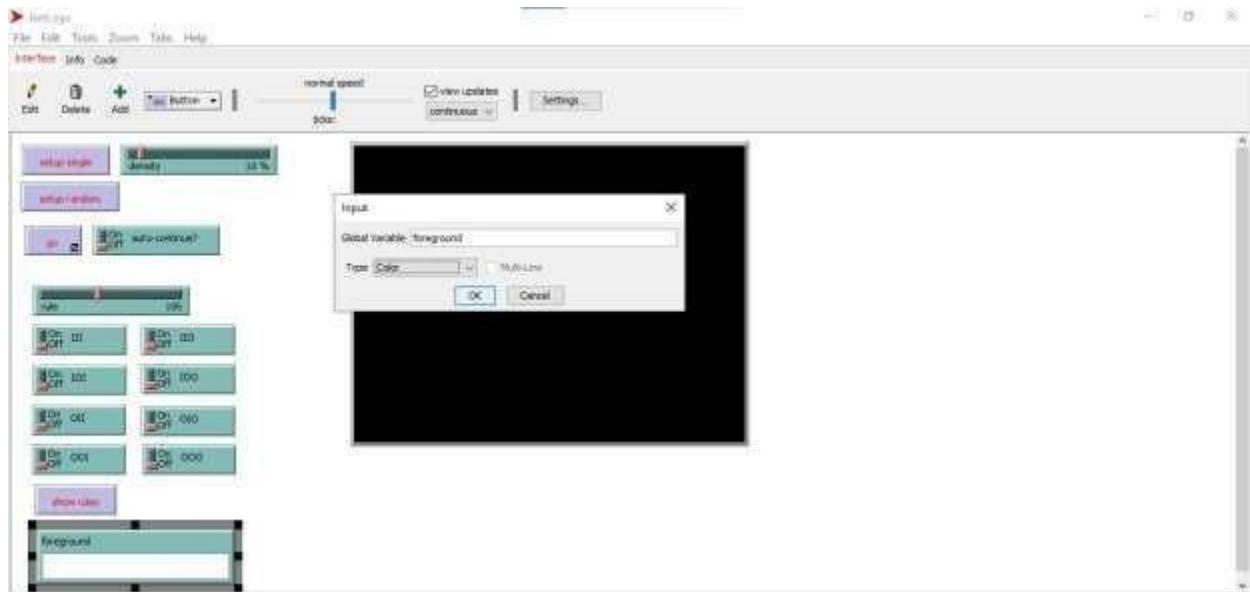


o 000

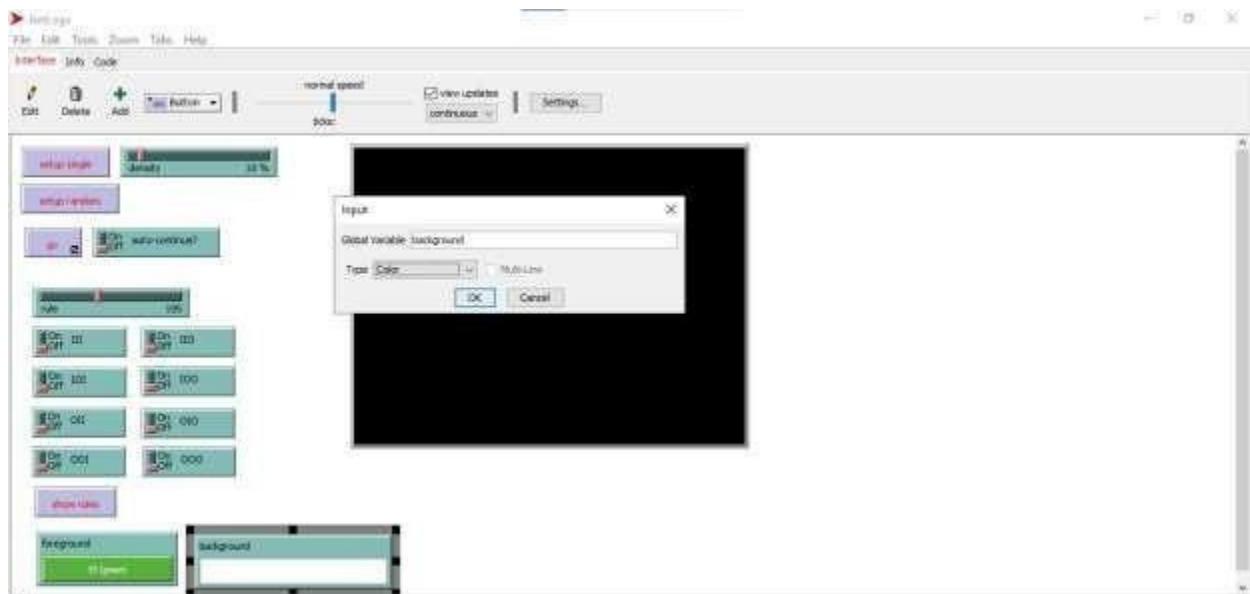


Color choosers: o

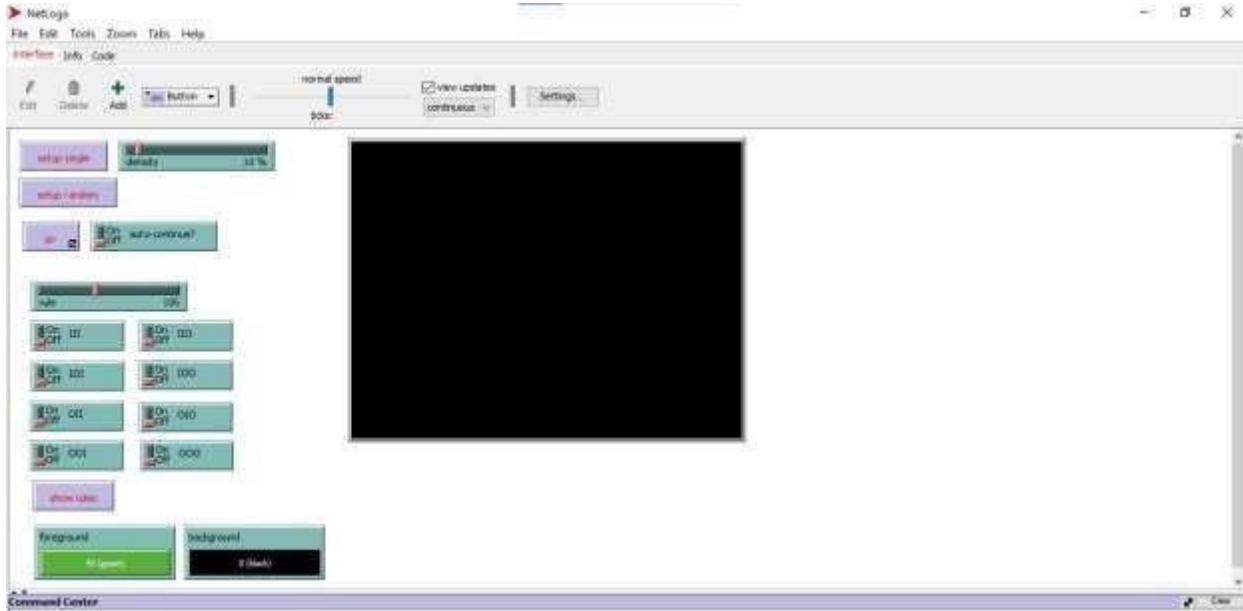
Foreground



o      Background



Set the world background to black and foreground to green.



## Step 2: Add the Full Code in the Code Tab

```
globals
[ row ;; current row old-rule ;; previous rule rules-shown? ;;
flag to check if rules have been displayed gone? ;; flag to
check if go has already been pressed
]
```

```
patches-own
[on?]
```

```
to startup ;; initially, nothing has been displayed
set rules-shown? false set gone? false set
old-rule rule end
```

```
;;;;;;
;;; Setup Procedures ;;;
;;;;;;
to setup-general ;; setup general working environment clear-patches clear-turtles set
row max-pycor ;; reset current row refresh-rules set gone? false set rules- shown?
false ;; rules are no longer shown since the view has been cleared end
```

```
to single-cell setup-general reset-ticks ask patches with [pycor = row] [set on? false set pcolor background] ;; initialize top row ask patch 0 row [ set pcolor foreground ] ;; setup single cell in top center ask patch 0 row [ set on? true ] end
```

```
to setup-random setup-general reset-ticks ask patches with [pycor = row] ;; randomly place cells across the top of the world
```

```
[  
  set on? ((random-float 100) < density) color-patch  
]
```

```
end
```

```
to setup-continue let on?-list [] if not gone? ;; make sure go has already been called
```

```
[ stop ]
```

```
;; copy cell states from the current row to a list set on?-list map [ p -> [ on? ] of p ] sort patches with [ pycor = row ] setup-general ask patches with [ pycor = row ]
```

```
[  
  set on? item (pxcor + max-pxcor) on?-list ;; copy states from list to top row color-patch  
]
```

```
end
```

```
;;;;;;;;;;;
```

```
;;; GO Procedures   ;;;
```

```
;;;;;;;;;;;
```

```
to go if (rules-shown?) ;; don't do unless we are properly set up
```

```
[ stop ] if (row = min-pycor) ;; if we reach the end, continue from the top or stop
```

```
[
```

```
  ifelse auto-continue?
```

```
[
```

```
    set gone? true display ;; ensure everything gets drawn  
    before we clear it setup-continue
```

```
]
```

```

[
ifelse gone?
  [ setup-continue ];; a run has already been completed, so continue with another [ set
  gone? true stop ];; otherwise just stop
]
]

ask patches with [ pycor = row ];; apply rule
[ do-rule ] set row (row - 1) ask patches with [ pycor = row ]
  ;; color in changed cells
[ color-patch ] tick

```

end

**to** do-rule ;; patch procedure let left-on? [on?] of patch-at -1 0 ;; set to true if the  
 patch to the left is on let right-on? [on?] of patch-at 1 0 ;; set to true if the  
 patch to the right is on

;; each of these lines checks the local area and (possibly) ;;  
 sets the lower cell according to the corresponding switch  
 let new-value  
 (iii and left-on? and on? and right-on?) or  
 (iio and left-on? and on? and (not right-on?)) or  
 (ioi and left-on? and (not on?) and right-on?) or  
 (ioo and left-on? and (not on?) and (not right-on?)) or (oii and (not  
 left-on?) and on? and right-on?) or  
 (oio and (not left-on?) and on? and (not right-on?)) or  
 (ooi and (not left-on?) and (not on?) and right-on?) or  
 (ooo and (not left-on?) and (not on?) and (not right-on?))  
 ask patch-at 0 -1 [ set on? new-value ] **end**

;;;;;;  
 ;;; Utility Procedures ;;;

;;;;;;

**to** color-patch ;;patch procedure ifelse on?

```
[ set pc当地 foreground ]  [
  set pc当地 background ]
end
```

```

to-report bindigit [number power-of-two] ifelse
  (power-of-two = 0)
  [ report floor number mod 2 ]
  [ report bindigit (floor number / 2) (power-of-two - 1) ] end

to refresh-rules ;; update either switches or slider depending on which has been changed last ifelse (rule
  = old-rule)
  [
    if (rule != calculate-rule)
      [ set rule calculate-rule ]
  ]
  [ extrapolate-switches ] set
    old-rule rule end

to extrapolate-switches
  ;;set the switches based on the slider set
  ooo ((bindigit rule 0) = 1) set ooi
  ((bindigit rule 1) = 1) set oio ((bindigit
  rule 2) = 1) set oii
  ((bindigit rule 3) = 1) set ioo
  ((bindigit rule 4) = 1) set ioi
  ((bindigit rule 5) = 1) set iio
  ((bindigit rule 6) = 1) set iii
  ((bindigit rule 7) = 1) end

to-report calculate-rule
  ;;set the slider based on the switches
  let result 0 if ooo [ set result result +
    1 ] if ooi [ set result result + 2 ] if oio
  [ set result result + 4 ] if oii [ set
  result result + 8 ] if ioo [ set result
  result + 16 ] if ioi [ set result result +
  32 ] if iio [ set result result
  + 64 ] if iii [ set result result + 128
  ] report result end

```

```

::::::::::::::::::
;; SHOW-RULES RELATED PROCEDURES ;;
::::::::::::::::::

```

```

to show-rules ;; preview cell state transitions
setup-general ask patches with [pycor > max-
pycor - 12]
[ set pcolor gray - 1 ] let i 0 foreach list-rules [ the-rule ->      let px (min-
pxcor + i * floor (world-width / 8) + floor (world-width / 16)) - 4      ask
patch px (max-pycor - 4)
[
sprout 1
[
set xcor xcor - 3      print-block item 0 the-
rule ;; left cell      set xcor xcor + 3 print-
block item 1 the-rule ;; center cell set xcor
xcor + 3      print-block item 2 the- rule ;; right
cell      setxy (xcor - 3) (ycor - 3) print-
block item 3 the-rule ;; next cell state die
]  ]  set i
(i + 1)
]
set rules-shown? true end

;; turtle procedure to print-block [print-on?] ;; draw a 3x3 block with the color
determined by the state ask patches in-radius 1.5 ;; like "neighbors", but includes the
patch we're on too
[
set on? print-on?
color-patch
]
end

to-report list-rules ;; return a list of state-transition 4-tuples corresponding to the switches report (list
lput ooo [false false false] lput ooi [false false true] lput oio
[false true false] lput oii [false true true] lput ioo [true false false] lput ioi [ true
false true] lput iio[ true true false] lput iii[ true true
true ])
end

```

NetLogo

File Edit Tools Zoom Tabs Help

Interact Info Code

Find Check Procedures  Indent automatically  CodeTab in separate window

```
globals
{
    row           ; current row
    old-rule      ; previous rule
    rules-shown? ; flag to check if rules have been displayed
    gone?         ; flag to check if go has already been pressed
}

patches-on
[on?]

to startup ; initially, nothing has been displayed
  set rules-shown? false
  set gone? false
  set old-rule rule
end

;---- Setup Procedures ----
;-----

to setup-general ; setup_general working environment
  clear-patches
  clear-turtles
  set row max-pycor ; reset current row
  refresh-rules
  set gone? false
  set rules-shown? false ; rules are no longer shown since the view has been cleared
end

to single-cell
  setup-general
  reset-ticks
  ask patches with [pycor = row] [set go? false set pixels background] ; initialize top row
  ask patch 0 row 1 [set pixels foreground] ; set a single cell in top center
  ask patch 0 row 1 [set go? true]
end
```

NetLogo

File Edit Tools Zoom Tabs Help

Interact Info Code

Find Check Procedures  Indent automatically  CodeTab in separate window

```
to setup-random
  setup-general
  reset-ticks
  ask patches with [pycor = row] ; randomly place cells across the top of the world
  [
    set go? (random-float 100) < density
    color-patch
  ]
end

to setup-continue
  let on?-list []
  if not gone? ; make sure go? has already been called
  [
    stop
    ; copy cell states from the current row to a list
    set on?-list map [ p -> [ go? ] of p ] sort-patches with [ pycor = row ]
    setup-general
    ask patches with [ pycor = row ]
    [
      set and-item (pxcor + max-pycor) on?-list ; copy states from list to top row
      color-patch
    ]
  ]
end

;---- OO Procedures ----
;-----
```

> NetLogo  
File Edit Tools Zoom Tabs Help  
Interface Info Code  
Find Check | Procedures ▾ |  Indent automatically  Code Tab in separate window

```
to move-patch [<> patch procedure
  let left-on? [on?] of patch-at -1 0 ; set to true if the patch to the left is on
  let right-on? [on?] of patch-at 1 0 ; set to true if the patch to the right is on
  ; each of these lines checks the initial case and (possibly)
  ; sets the target cell according to the corresponding switch
  let new-value
    (l0l and left-on?) and on? or
    (l0l and left-on?) and (not right-on?) or
    (l0l and left-on?) and (not on?) and right-on? or
    (l00 and left-on?) and (not on?) and (not right-on?) or
    (l0l and (not left-on?) and on?) and right-on? or
    (l0l and (not left-on?) and on?) and (not right-on?) or
    (l00 and (not left-on?) and (not on?) and right-on?) or
    (l00 and (not left-on?) and (not on?) and (not right-on?))
  ask patch-at 0 -1 [ set on? new-value ]
end

;-----;
; Utility Procedures ;;
;-----;

to color-patch [<> patch procedure
  ifelse on?
    [ set pencolor foreground ]
    [ set pencolor background ]
  end

  to-report bindigit [number power-of-two]
    ifelse (power-of-two = 0)
      [ report this number end 2 ]
      [ report bindigit (floor number / 2) (power-of-two - 1) ]
  end
end
```

> NetLogo  
File Edit Tools Zoom Tabs Help  
Interface Info Code  
Find Check | Procedures ▾ |  Indent automatically  Code Tab in separate window

```
to refresh-rules [<> update either switches or sliders depending on which has been changed last
  ifelse (rule = old-rule)
    [
      if (rule >= calculate-rule)
        [ set rule calculate-rule ]
      [ extrapolate-switches ]
      set old-rule rule
    end

    to extrapolate-switches
      ; set the switches based on the sliders
      set ooo ((bindigit rule 0) * 1)
      set ooo ((bindigit rule 1) * 1)
      set ooo ((bindigit rule 2) * 1)
      set ooo ((bindigit rule 3) * 1)
      set ooo ((bindigit rule 4) * 1)
      set ooo ((bindigit rule 5) * 1)
      set ooo ((bindigit rule 6) * 1)
      set ooo ((bindigit rule 7) * 1)
    end

    to-report calculate-rule
      ; set the slider based on the switches
      let result 0
      if ooo [ set result result + 1 ]
      if ooo [ set result result + 2 ]
      if ooo [ set result result + 4 ]
      if ooo [ set result result + 8 ]
      if ooo [ set result result + 16 ]
      if ooo [ set result result + 32 ]
      if ooo [ set result result + 64 ]
      if ooo [ set result result + 128 ]
      report result
    end
```

```

> NetLogo
File Edit Tools Zoom Help
Interface Info Code
Find Check Procedure - [ ] Define automatically [ ] Code Tab in separate window
Code
;;; SHREK-RULES RELATED PROCEDURES ;;
;;

; to show-rules [ ; preview cell state transitions;
; ask patches with [pxcor < max-patches - 1]
; [ set pixels gray - 1 ]
; set 1 =
; foreach list-rules [ the-rule -
; [ let px (max-patches + 1) * Floor (pxcor/width / 1) + Floor (pxcor/width / 1) * 1
; ask patches in-radius px [set pixels gray - 1]
; ]
; sprout 1
; [
; set max-size = 2
; print-block item 0 the-rule ;;> left-cell
; set max-size + 1
; print-block item 1 the-rule ;;> central-cell
; set max-size + 2
; print-block item 2 the-rule ;;> right-cell
; setay (max-size * 3) (pxcor - 1)
; print-block item 3 the-rule ;;> next-cell-state
; set max-size = 2
; ]
; set 1 (1 + 1)
; ]
; set rules-shown true
; end

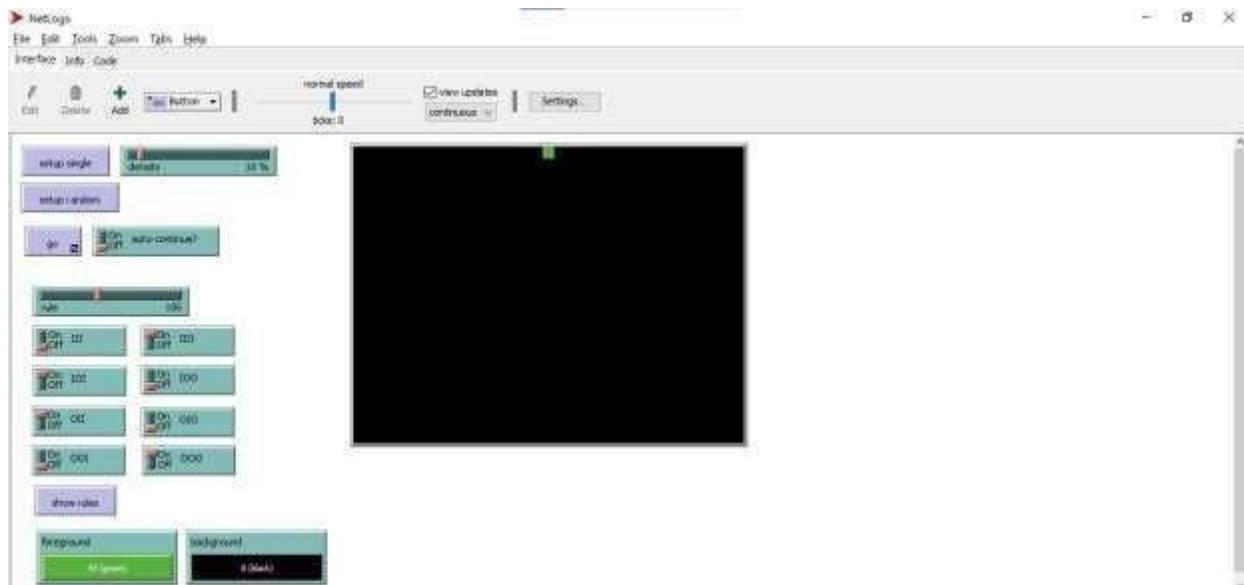
; turtle procedure
; to print-block [print-out] ; draw a 3x3 block with the color determined by the state
; ask patches in-radius 1.5 ; like "neighbors", but excludes the patch at rx or rx
; [
; set an? print-out?
; color-patch
; ]
; end

; to-report list-rules ; return a list of state-transition 4-tuples corresponding to the switches
; report (list (put acc [false false false]
; [put on [false false true]
; put off [false true false]
; put off [false true true]
; put on [true false false]
; put off [true false true]
; put on [true true false]
; put off [true true true]]))
; end

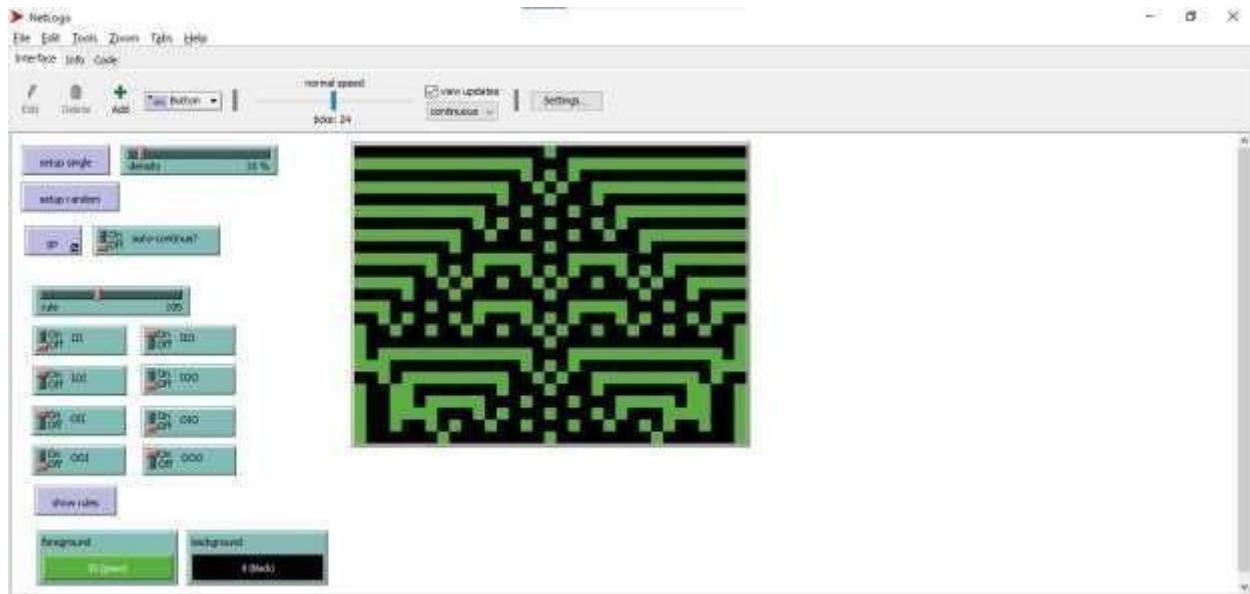
```

## Output

### Select setup single



Select go

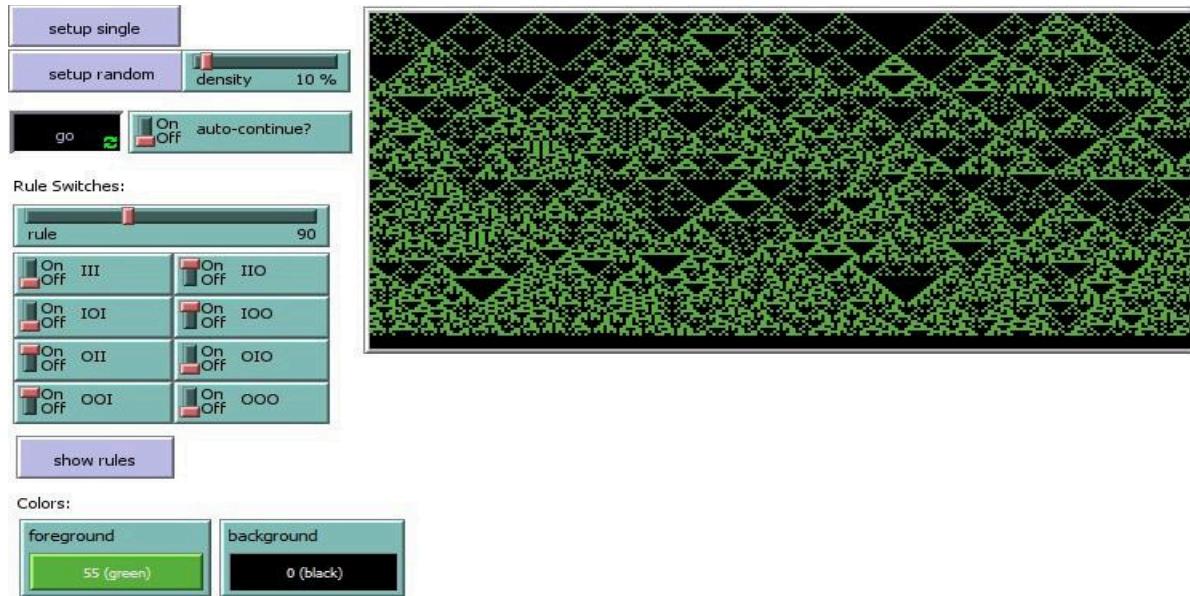
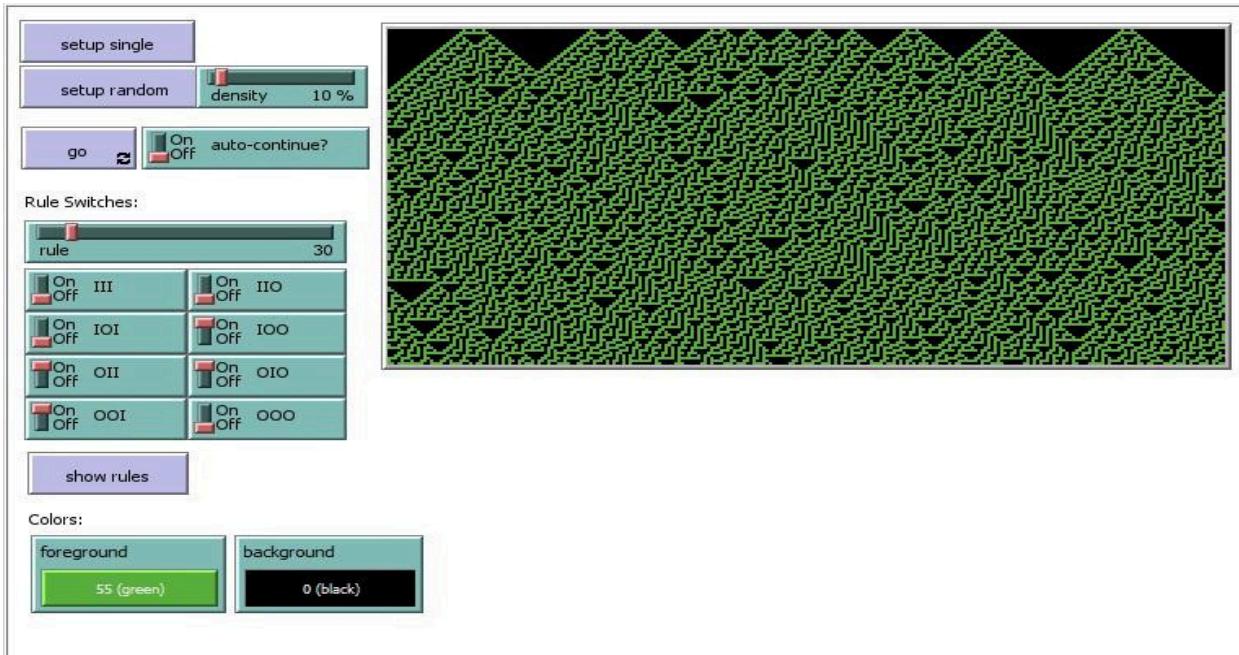


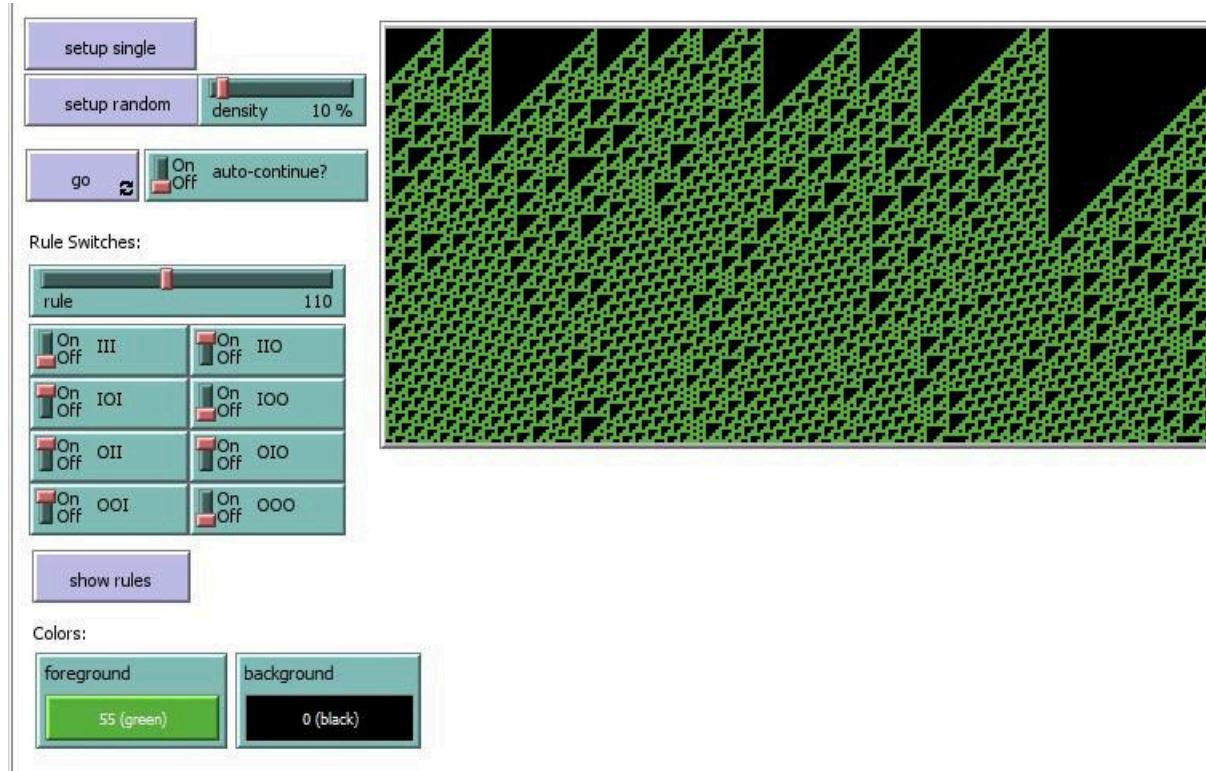
## How to Run the Model

1. Select a rule-number (e.g., 30, 90, 110).
2. Click setup to initialize the grid.
3. Click go to generate the CA pattern over time.
4. Use go-once to observe step-by-step evolution.
5. Observe how changing the rule changes the overall pattern.

## STUDENT TASK

1. Run the simulation using Rule 30, Rule 90, and Rule 110.





### Observation:

- **Rule 30:** Produces a chaotic, asymmetric pattern. Small initial changes lead to complex, seemingly random structures.
  - **Rule 90:** Generates a regular, symmetric triangular pattern. Glider-like structures appear along diagonals.
  - **Rule 110:** Produces complex patterns with both periodic and chaotic regions. Supports moving structures that can interact, showing behavior capable of universal computation.
2. Compare the visual patterns generated by each rule.

### Observation:

- **Rule 30:** Chaotic and asymmetric; no clear repetition; looks random.
- **Rule 90:** Highly regular and symmetric; forms triangular, fractal-like patterns.
- **Rule 110:** Complex mix of periodic and chaotic regions; shows both stable and moving structures.

The differences highlight how simple rule changes in 1D cellular automata can produce drastically different behaviors, from complete order to apparent randomness.

### 3. Change the initial cell value and observe the difference.

- Starting with a **single cell in the top center** produces the classic patterns for each rule (Rule 30 chaotic, Rule 90 symmetric, Rule 110 complex).
- Starting with **multiple or random cells** at the top row changes the evolution:
  - **Rule 30:** Appears more filled and irregular.
  - **Rule 90:** Maintains symmetry but shows overlapping triangles.
  - **Rule 110:** More complex interactions and additional moving structures appear.

The initial configuration significantly affects the resulting pattern, demonstrating sensitivity to starting conditions in cellular automata.

### 4. Identify whether the pattern is regular, chaotic, or complex.

#### • **Rule 30:** Chaotic no repeating pattern, unpredictable behavior.

#### • **Rule 90:** Regular highly symmetric and repetitive triangular patterns.

#### • **Rule 110:** Complex —contains both periodic structures and chaotic regions, with moving patterns interacting in non-trivial ways.

### 5. Stop the simulation after several ticks and analyze symmetry or randomness.

- **Rule 30:** Asymmetric and random-looking; no visible symmetry, patterns appear irregular.
- **Rule 90:** Symmetric; patterns maintain clear triangular repetition across the grid.
- **Rule 110:** Partially symmetric; contains both ordered regions and irregular areas, showing a mix of periodic and chaotic behavior.

Stopping after several ticks highlights the characteristic structure of each rule and shows how initial conditions and rule choice affect the evolution of patterns.

## POST LAB QUESTIONS

### 1. What is an elementary cellular automaton?

An elementary cellular automaton (ECA) is a one-dimensional grid of cells where each cell has two possible states (on/off or 1/0). The state of each cell in the next generation depends only on its current state and the state of its immediate neighbors, following a simple deterministic rule.

### 2. Why are there exactly 256 possible elementary CA rules?

Each cell has 3 neighbors (left, center, right), giving  $2^3 = 8$  possible neighborhood patterns. Each pattern can produce either 0 or 1 in the next state. Therefore, the total number of rules is  $2^8 = 256$ .

### **3. Describe the behavior of Rule 30 and Rule 90.**

- **Rule 30:** Chaotic and asymmetric; produces seemingly random patterns even from a single initial cell.
- **Rule 90:** Regular and symmetric; generates triangular, fractal-like patterns that repeat predictably.

### **4. How does changing the initial condition affect the pattern?**

The initial configuration of the top row (single cell or multiple/random cells) significantly affects the resulting evolution. Some rules (like Rule 30) amplify randomness, while others (like Rule 90) preserve symmetry but may create overlapping structures.

### **5. Why is Rule 110 considered important in computational theory?**

Rule 110 is capable of universal computation; it can simulate any Turing machine. Its patterns include both stable and moving structures, demonstrating how simple rules can produce complex, computable behavior.