

## **AVR INTERRUPT PROGRAMMING**

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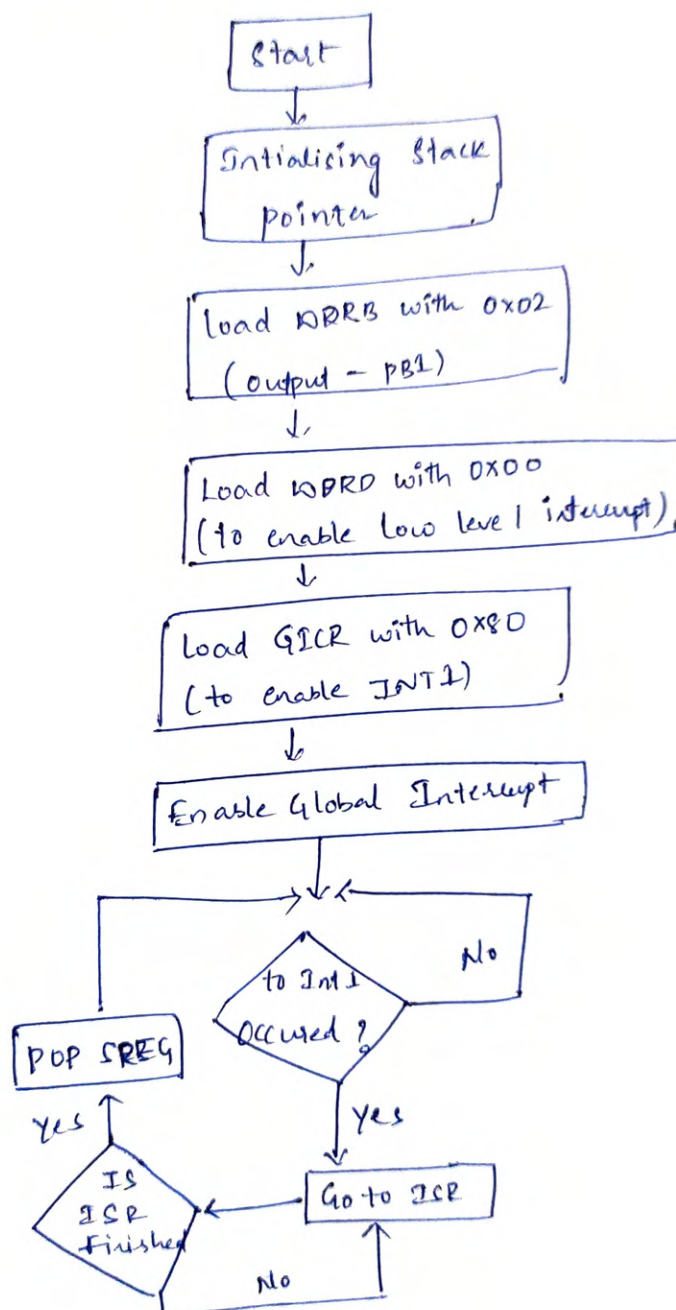
ROLL NO : EE20B1 00

## 1) SWITCHING ON LED FOR 1 SEC USING INTERRUPT 1 IN ASSEMBLY

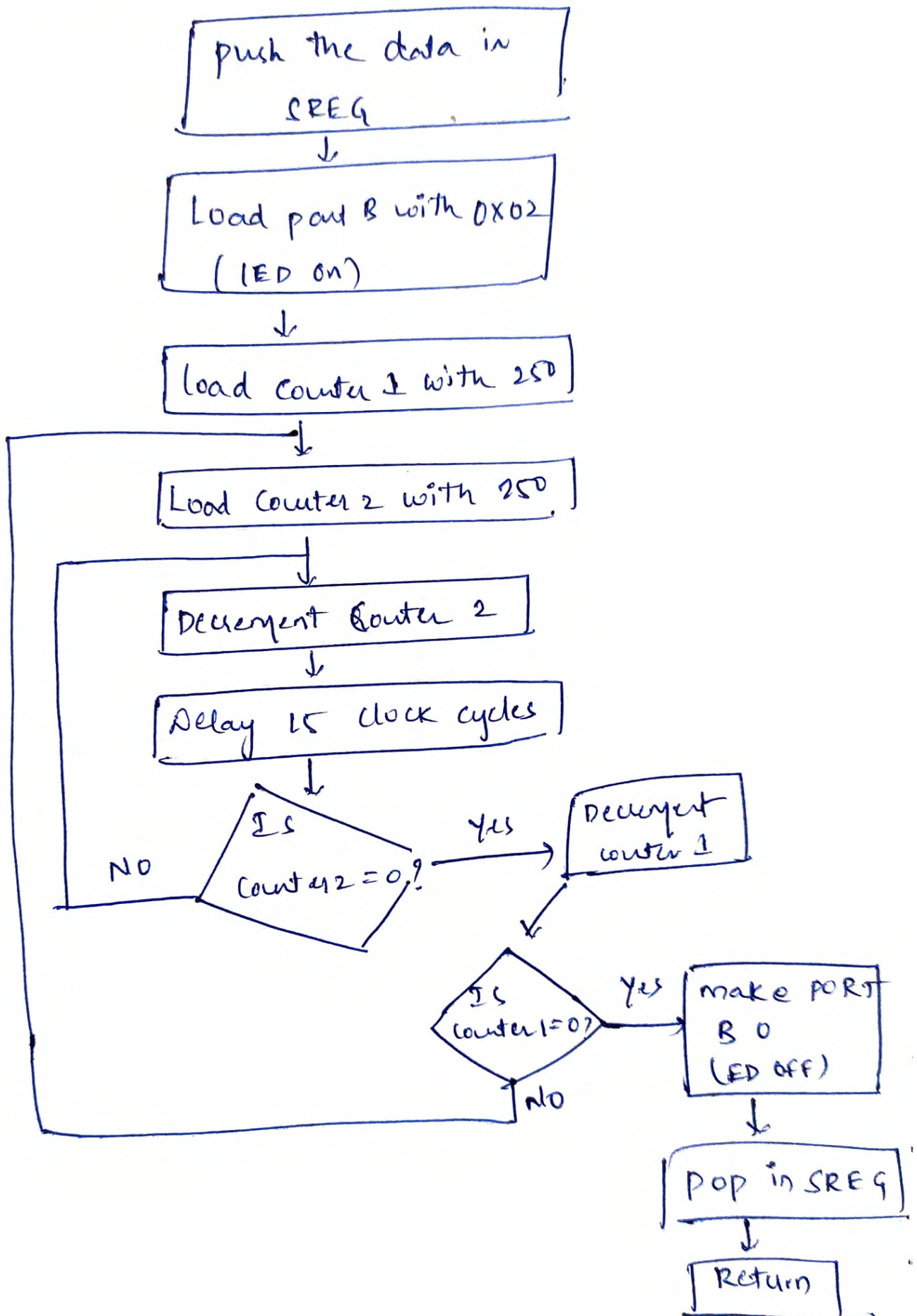
The main target of the experiment is to switch on the led for 1 sec when the switch is on using interrupt 1 from pin d.3. The led is connected to pin b.1 which is the output. Whenever the interrupt\_1 occurs (i.e. low level in pin d.3) the ISR executes and led will be on for 1 sec and off. After ISR is completed the control comes back to the main program.

### Flow chart:

Q1) . flow chart logics



ISR:



## CODE:

```
.org 0x0000
rjmp reset

.org 0x0002
rjmp int1_ISR

.org 0x0100

reset:
    ;Loading stack pointer address
    LDI R16,0x70
    OUT SPH,R16
    LDI R16,0x00
    OUT SPL,R16

    ;Interface port B pin1 to be output
    LDI R16,0x02
    OUT DDRB,R16
    ;so to view LED blinking

    ; port d as input
    LDI R16,0x00
    OUT DDRD,R16

    ;Set MCUCR register to enable low level interrupt
    LDI R16,0x00
    OUT MCUCR,R16

    ;Set GICR register to enable interrupt 1
    LDI R16,0x80
    OUT GICR,R16

    ; CLEARING THE PORT B
    LDI R16,0x00
    OUT PORTB,R16

    SEI
ind_loop:rjmp ind_loop    ; REMAINS HERE FOR A WHILE

int1_ISR:IN R16,SREG
    PUSH R16

    LDI R16,0x0A
    MOV R0,R16
    ;Modify below loops to make LED blink for 1 sec
c1:    LDI R16,0x02
    OUT PORTB,R16
```

```

        LDI R16,250
a1:      LDI R17,250
a2:      DEC R17
        NOP
        NOP
        NOP
        NOP
        NOP
        NOP
        NOP
        NOP
        NOP
        NOP
        NOP
        NOP
        BRNE a2
        DEC R16
        BRNE a1

```

```

; Calculation of delay = (250*16 -1)*250 + 4*250 -1 + 1
; without considering over head we get 1000000 which corresponds to 1

```

sec

```

        LDI R16,0x00
        OUT PORTB,R16

; recovering the value in SREG
        POP R16
        OUT SREG,R16
; returning from interrupt
        RETI

```

## 2) BLINKING LED FOR 10 TIMES WHEN SWITCH IS ON USING INTERRUPT 0 (ASSEMBLY)

The main target of this experiment is to blink the led for 1 sec ( i.e. 1 sec on and 1 sec off ) for 10 times. This has to be implemented using interrupt 0. Port B.1 will be connected to led and acts as a output. When the interrupt 0 occurs , the led blinks 10 times and switches off. Inorder to switch on the interrupt we have to make pin d.2 as 0 (low level interrupt ). After the ISR is completed , the control comes back to the previous program.

**2. Use int0 to redo the same in the demo program (duely filled in). Once the switch is pressed the LED should blink 10 times (ON (or OFF) - 1 sec, duty cycle could be 50 % ). Demonstrate both the cases.**

**CODE:**



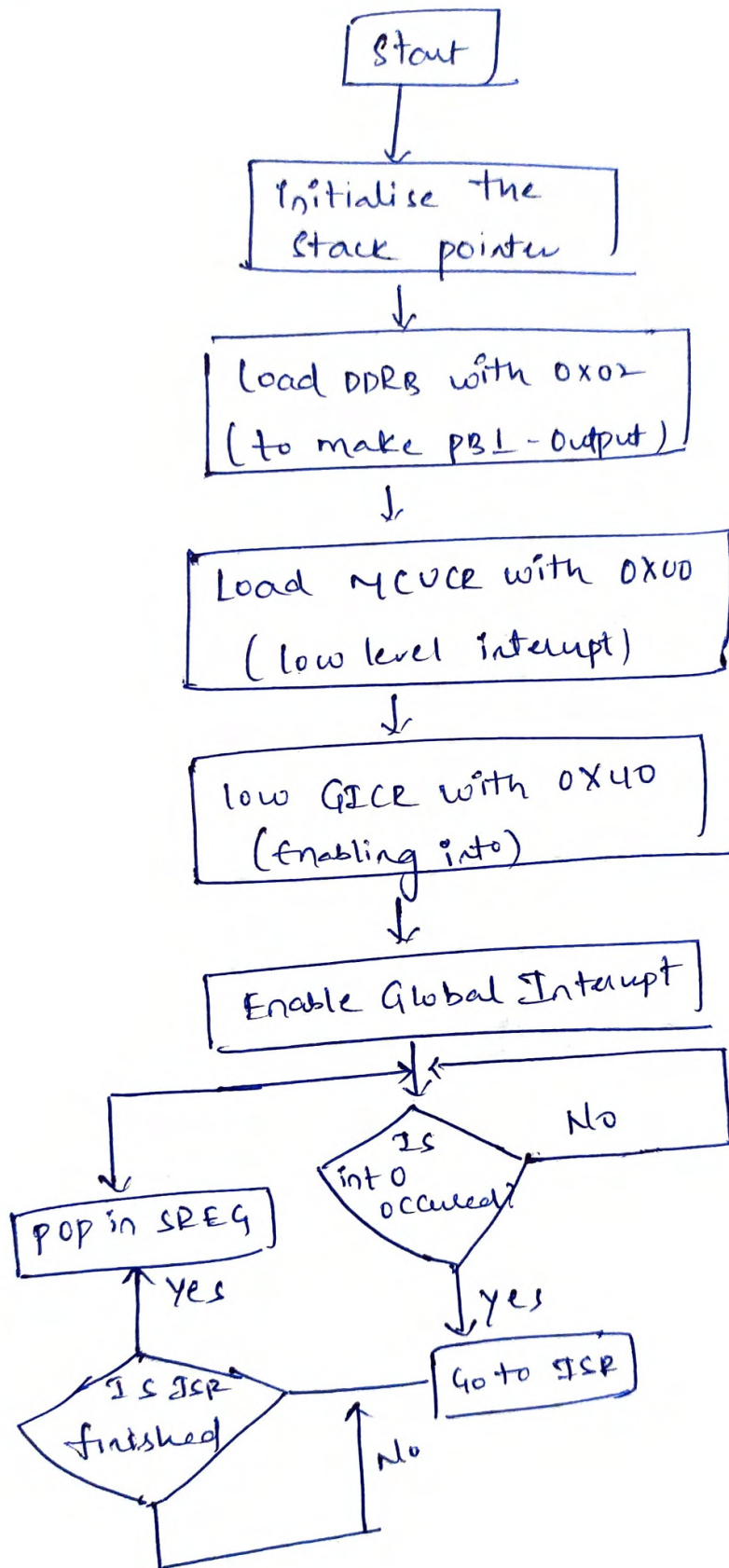
```

NOP
NOP
NOP
BRNE a2
DEC R16
BRNE a1
; Calculation of delay
;  $(250 \times 16 - 1) \times 250 + 4 \times 250 - 1$ 
; without considering over head we get 1000000 which corresponds to 1
sec
; as frequency is 1 MHZ
IN R21,PORTB
LDI R22,0x02
EOR R21,R22
OUT PORTB,R21
DEC R20
BRNE again

LDI R16,0x00
OUT PORTB,R16
; recovering the value in SREG
POP R16
OUT SREG,R16
; returning from interrupt
RETI

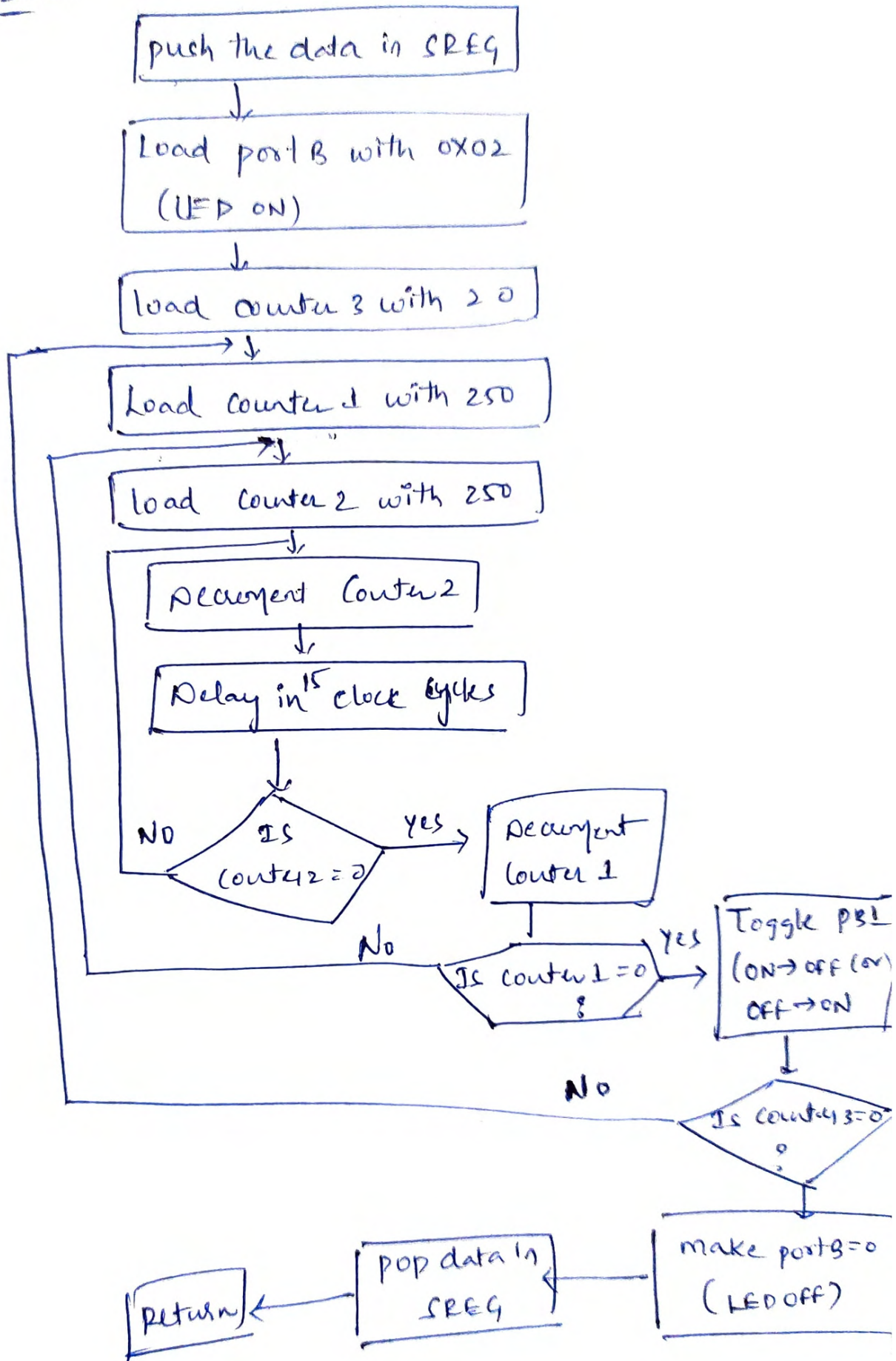
```

## FLOW CHART:





ISR:



### 3) Blinking led 10 times when switch is clicked using interrupt1 (C).

The main target of this experiment is to write the above assembly code in C

#### 3. Rewrite the program in 'C' (int1).

#### CODE:

```
#include <avr/io.h>
#include <util/delay.h>
#include <avr/interrupt.h>

ISR (INT1_vect)
{
    int i;
    for (i=1;i<=10;i++) // 10 TIMES BLINKING FOR LED
    {
        PORTB=0x02;
        _delay_ms(1000); // DELAY OF 1SEC
        PORTB=0x00;
        _delay_ms(1000);
    }
}

int main(void)
{
    DDRD=0x00; //Set appropriate data direction for D
    DDRB=0x02; //Make PB0 as output
    MCUCR=0x00; //Set MCUCR to level triggered
    GICR=0x80; //Enable interrupt 1
    PORTB=0x00;
    PORTD=0x08;
    sei(); // global interrupt flag

    while (1) //wait
    {
    }
}
```

---

## 1) Blinking led 10 times when switch is clicked using interrupt0 (C).

The main target of this experiment is to write the above C code using interrupt 0.

### CODE:

```
#include <avr/io.h>
#include <util/delay.h>
#include <avr/interrupt.h>

ISR (INT1_vect)
{
    int i;
    for (i=1;i<=10;i++) // 10 TIMES BLINKING FOR LED
    {
        PORTB=0x02;
        _delay_ms(1000); // DELAY OF 1SEC
        PORTB=0x00;
        _delay_ms(1000);
    }
}

int main(void)
{
    DDRD = 0x00 ; //Set appropriate data direction for D
    DDRB=0x02; //Make PB0 as output
    MCUCR=0x00; //Set MCUCR to level triggered
    GICR=0x40; //Enable interrupt 0
    PORTB=0x00;
    PORTD=0x04;
    sei(); // global interrupt flag

    while (1) //wait
    {
    }
}
```

---

## **Final Outcomes of Experiment :**

1. Usage of loops in assembly language for hardware
2. Use of stack pointer
3. Using different interrupts for hardware
4. Understanding I/O programming
5. Hardware and software aspects in Avr - Atmega 8.
6. Handling timers and delays
7. Clear understanding of Microchip studio IDE
8. Programming timers and interrupts with C language and assembly language