human-activity-recognition-using-neural-networks

January 5, 2021

```
[1]: # This Python 3 environment comes with many helpful analytics libraries
     \rightarrow installed
     # It is defined by the kaggle/python Docker image: https://github.com/kaggle/
     \rightarrow docker-python
     # For example, here's several helpful packages to load
     import numpy as np # linear algebra
     import pandas as pd # data processing, CSV file I/O (e.g. pd.read_csv)
     # Input data files are available in the read-only "../input/" directory
     # For example, running this (by clicking run or pressing Shift+Enter) will list_
     →all files under the input directory
     import os
     for dirname, _, filenames in os.walk('/kaggle/input'):
         for filename in filenames:
             print(os.path.join(dirname, filename))
     # You can write up to 20GB to the current directory (/kaggle/working/) that ⊔
     →gets preserved as output when you create a version using "Save & Run All"
     # You can also write temporary files to /kaggle/temp/, but they won't be saved_
     →outside of the current session
```

/kaggle/input/human-activity-recognition-with-smartphones/train.csv/kaggle/input/human-activity-recognition-with-smartphones/test.csv

Import Libraries

```
[2]: # To store data
import pandas as pd

# To do linear algebra
import numpy as np
from numpy import pi

# To create plots
from matplotlib.colors import rgb2hex
from matplotlib.cm import get_cmap
```

```
import matplotlib.pyplot as plt
# To create nicer plots
import seaborn as sns
# To create interactive plots
from plotly.offline import init_notebook_mode, iplot
import plotly.graph_objs as go
init_notebook_mode(connected=True)
# To get new datatypes and functions
from collections import Counter
from cycler import cycler
# To investigate distributions
from scipy.stats import norm, skew, probplot
from scipy.optimize import curve_fit
# To build models
from sklearn.preprocessing import StandardScaler, LabelEncoder
from sklearn.model_selection import train_test_split
from sklearn.metrics import accuracy_score
from sklearn.decomposition import PCA
from sklearn.manifold import TSNE
# To qbm light
from lightgbm import LGBMClassifier
# To measure time
from time import time
```

<IPython.core.display.HTML object>

Load Data

```
# Create label
     label = both_df.pop('Activity')
     print('Shape Train:\t{}'.format(train_df.shape))
    print('Shape Test:\t{}\n'.format(test_df.shape))
    train_df.head()
    Shape Train:
                     (7352, 564)
    Shape Test:
                     (2947, 564)
[3]:
        tBodyAcc-mean()-X
                           tBodyAcc-mean()-Y tBodyAcc-mean()-Z
                                                                   tBodyAcc-std()-X \
                 0.288585
     0
                                    -0.020294
                                                        -0.132905
                                                                           -0.995279
     1
                 0.278419
                                    -0.016411
                                                        -0.123520
                                                                           -0.998245
     2
                 0.279653
                                    -0.019467
                                                        -0.113462
                                                                           -0.995380
     3
                 0.279174
                                    -0.026201
                                                        -0.123283
                                                                           -0.996091
     4
                 0.276629
                                    -0.016570
                                                        -0.115362
                                                                           -0.998139
        tBodyAcc-std()-Y
                          tBodyAcc-std()-Z tBodyAcc-mad()-X tBodyAcc-mad()-Y \
    0
               -0.983111
                                  -0.913526
                                                     -0.995112
                                                                        -0.983185
     1
               -0.975300
                                  -0.960322
                                                     -0.998807
                                                                        -0.974914
     2
               -0.967187
                                  -0.978944
                                                     -0.996520
                                                                        -0.963668
     3
                                  -0.990675
                                                     -0.997099
                                                                        -0.982750
               -0.983403
     4
               -0.980817
                                  -0.990482
                                                     -0.998321
                                                                        -0.979672
        tBodyAcc-mad()-Z
                           tBodyAcc-max()-X
                                                 angle(tBodyAccMean,gravity)
     0
               -0.923527
                                  -0.934724
                                                                    -0.112754
     1
               -0.957686
                                  -0.943068
                                                                     0.053477
     2
               -0.977469
                                  -0.938692
                                                                    -0.118559
     3
               -0.989302
                                  -0.938692
                                                                    -0.036788
     4
               -0.990441
                                  -0.942469
                                                                     0.123320
        angle(tBodyAccJerkMean),gravityMean)
                                                angle(tBodyGyroMean,gravityMean)
     0
                                     0.030400
                                                                        -0.464761
     1
                                    -0.007435
                                                                        -0.732626
     2
                                     0.177899
                                                                         0.100699
     3
                                    -0.012892
                                                                         0.640011
     4
                                     0.122542
                                                                         0.693578
        angle(tBodyGyroJerkMean,gravityMean)
                                                angle(X,gravityMean)
     0
                                    -0.018446
                                                           -0.841247
     1
                                     0.703511
                                                           -0.844788
     2
                                     0.808529
                                                           -0.848933
     3
                                    -0.485366
                                                           -0.848649
     4
                                    -0.615971
                                                           -0.847865
```

```
angle(Y,gravityMean) angle(Z,gravityMean)
                                              subject Activity
                                                                  Data
0
              0.179941
                                   -0.058627
                                                       STANDING
                                                    1
                                                                 Train
1
               0.180289
                                   -0.054317
                                                    1 STANDING Train
2
               0.180637
                                   -0.049118
                                                    1 STANDING
                                                                 Train
3
               0.181935
                                   -0.047663
                                                    1 STANDING Train
               0.185151
                                   -0.043892
                                                    1 STANDING Train
```

[5 rows x 564 columns]

Dataset Exploration

```
[4]:
                            count
     fBodyAcc
                                79
     fBodyGyro
                                79
     fBodyAccJerk
                                79
     tGravityAcc
                                40
     tBodyAcc
                                40
     tBodyGyroJerk
                                40
     tBodyGyro
                                40
     tBodyAccJerk
                                40
     tBodyAccMag
                                13
     tGravityAccMag
                                13
     tBodyAccJerkMag
                                13
     tBodyGyroMag
                                13
     tBodyGyroJerkMag
                                13
     fBodyAccMag
                                13
     fBodyBodyAccJerkMag
                                13
     fBodyBodyGyroMag
                                13
     fBodyBodyGyroJerkMag
                                13
     angle
                                 7
                                 1
     subject
     Data
                                 1
```

Mainly there are 'acceleration' and 'gyroscope' features. A few 'gravity' features are there as well. Impressive how many features there are in regard of the limited number of sensors used.

```
[5]: # Get null values and dataframe information
print('Null Values In DataFrame: {}\n'.format(both_df.isna().sum().sum()))
both_df.info()
```

```
Null Values In DataFrame: 0
```

<class 'pandas.core.frame.DataFrame'>

RangeIndex: 10299 entries, 0 to 10298 Columns: 563 entries, tBodyAcc-mean()-X to Data dtypes: float64(561), object(2) memory usage: 44.2+ MB

Distribution of Labels

Disregarding the possibility of flawed data, the participants seem to walk roughly 10% faster downwards.

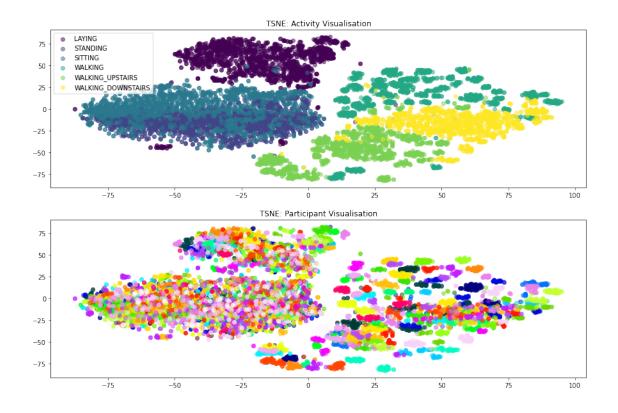
```
[7]: # Create datasets
    tsne_data = both_df.copy()
    data_data = tsne_data.pop('Data')
    subject_data = tsne_data.pop('subject')

# Scale data
    scl = StandardScaler()
    tsne_data = scl.fit_transform(tsne_data)

# Reduce dimensions (speed up)
    pca = PCA(n_components=0.9, random_state=3)
    tsne_data = pca.fit_transform(tsne_data)

# Transform data
    tsne = TSNE(random_state=3)
    tsne_transformed = tsne.fit_transform(tsne_data)
```

```
# Create subplots
fig, axarr = plt.subplots(2, 1, figsize=(15,10))
### Plot Activities
# Get colors
n = label.unique().shape[0]
colormap = get_cmap('viridis')
colors = [rgb2hex(colormap(col)) for col in np.arange(0, 1.01, 1/(n-1))]
# Plot each activity
for i, group in enumerate(label_counts.index):
   # Mask to separate sets
   mask = (label==group).values
   axarr[0].scatter(x=tsne_transformed[mask][:,0], y=tsne_transformed[mask][:
→,1], c=colors[i], alpha=0.5, label=group)
axarr[0].set_title('TSNE: Activity Visualisation')
axarr[0].legend()
### Plot Subjects
# Get colors
n = subject_data.unique().shape[0]
colormap = get_cmap('gist_ncar')
colors = [rgb2hex(colormap(col)) for col in np.arange(0, 1.01, 1/(n-1))]
# Plot each participant
for i, group in enumerate(subject_data.unique()):
   # Mask to separate sets
   mask = (subject_data==group).values
   axarr[1].scatter(x=tsne_transformed[mask][:,0], y=tsne_transformed[mask][:
→,1], c=colors[i], alpha=0.5, label=group)
axarr[1].set_title('TSNE: Participant Visualisation')
plt.show()
```



Plot-1: Activities are mostly separable.

Plot-2: Personal Information of the participants are visualised.

Accuracy on testset: 0.9553

The separability of the participants seems to dissent concerning their activity in second t-SNE plots.

```
[9]: # Store the data
     data = []
     # Iterate over each activity
     for activity in label_counts.index:
         # Create dataset
         act_data = both_df[label==activity].copy()
         act_data_data = act_data.pop('Data')
         act_subject_data = act_data.pop('subject')
         # Scale data
         scl = StandardScaler()
         act_data = scl.fit_transform(act_data)
         # Reduce dimensions
         pca = PCA(n_components=0.9, random_state=3)
         act_data = pca.fit_transform(act_data)
         # Split training testing data
         enc = LabelEncoder()
         label_encoded = enc.fit_transform(act_subject_data)
         X_train, X_test, y_train, y_test = train_test_split(act_data,__
      →label_encoded, random_state=3)
         # Fit basic model
         print('Activity: {}'.format(activity))
         lgbm = LGBMClassifier(n_estimators=500, random_state=3)
         lgbm = lgbm.fit(X_train, y_train)
         score = accuracy_score(y_true=y_test, y_pred=lgbm.predict(X_test))
         print('Accuracy on testset:\t{:.4f}\n'.format(score))
         data.append([activity, score])
    Activity: LAYING
    Accuracy on testset:
                            0.6481
    Activity: STANDING
    Accuracy on testset:
                            0.5493
    Activity: SITTING
```

Accuracy on testset:

Accuracy on testset:

Activity: WALKING_UPSTAIRS

Activity: WALKING
Accuracy on testset:

0.5303

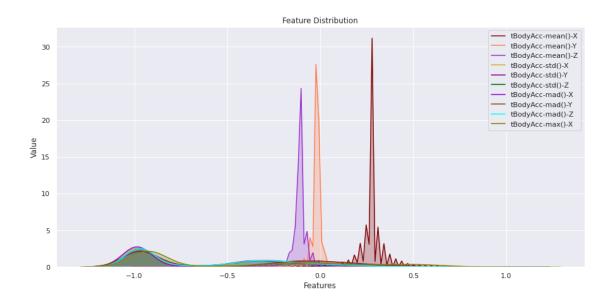
0.9513

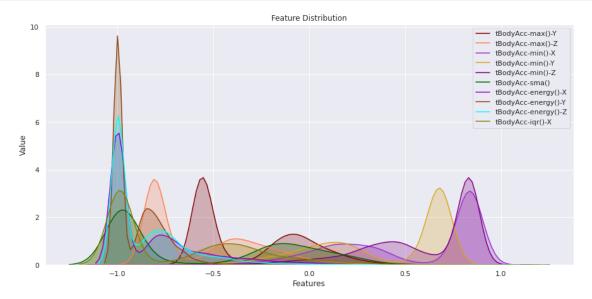
0.9249

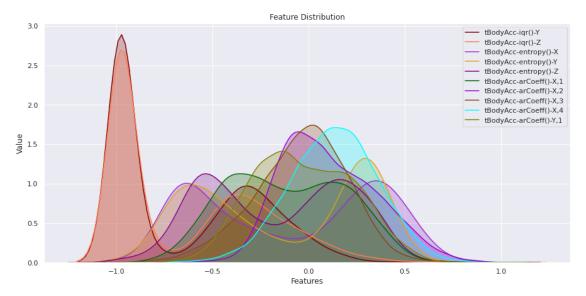
Activity: WALKING_DOWNSTAIRS
Accuracy on testset: 0.9091

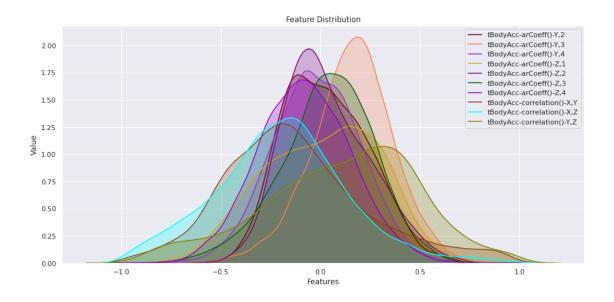
```
[10]: Accuracy Seconds
Activity
LAYING 0.648148 82.944000
STANDING 0.549266 81.322667
SITTING 0.530337 75.818667
WALKING 0.951276 73.472000
WALKING_UPSTAIRS 0.924870 65.877333
WALKING_DOWNSTAIRS 0.909091 59.989333
```

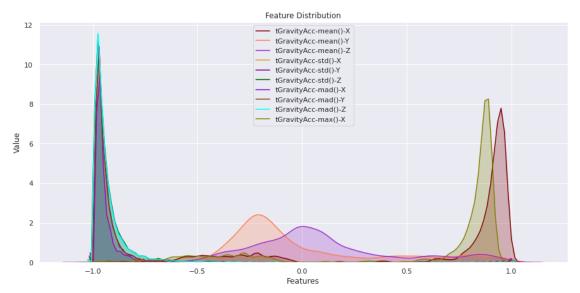
Visualizations for feature distributions











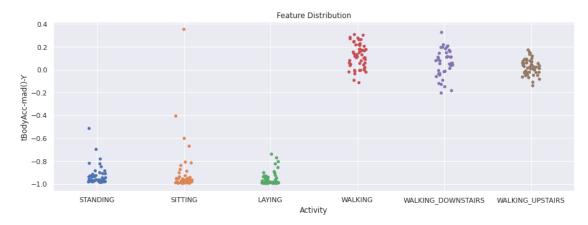
```
[16]: sns.set(rc={'figure.figsize':(15,10)})
      plt.subplot(221)
      fig1 = sns.stripplot(x='Activity', y= train_df.
      ⇒loc[train_df['Activity'] == "STANDING"].iloc[:,10], data= train_df.
       →loc[train_df['Activity']=="STANDING"], jitter=True)
      plt.title("Feature Distribution")
      plt.grid(True)
      plt.show(fig1)
      plt.subplot(224)
      fig2 = sns.stripplot(x='Activity', y= train_df.
       →loc[train_df['Activity']=="STANDING"].iloc[:,11], data= train_df.
       →loc[train_df['Activity']=="STANDING"], jitter=True)
      plt.title("Feature Distribution")
      plt.grid(True)
      plt.show(fig2)
      plt.subplot(223)
      fig2 = sns.stripplot(x='Activity', y= train_df.
      ⇒loc[train_df['Activity'] == "STANDING"].iloc[:,12], data= train_df.
      →loc[train_df['Activity']=="STANDING"], jitter=True)
      plt.title("Feature Distribution")
      plt.grid(True)
      plt.show(fig2)
      plt.subplot(222)
      fig2 = sns.stripplot(x='Activity', y= train_df.
      →loc[train_df['Activity'] == "STANDING"].iloc[:,13], data= train_df.
      →loc[train_df['Activity']=="STANDING"], jitter=True)
      plt.title("Feature Distribution")
      plt.grid(True)
      plt.show(fig2)
```



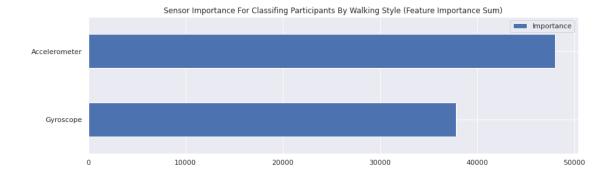


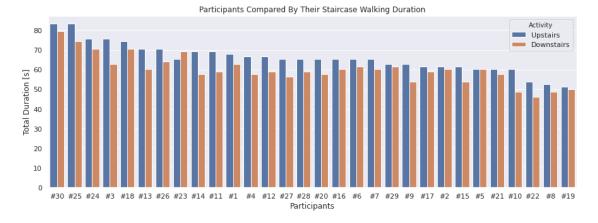






```
[18]: # Create dataset
      tsne_data = both_df[label=='WALKING'].copy()
      data_data = tsne_data.pop('Data')
      subject_data = tsne_data.pop('subject')
      # Scale data
      scl = StandardScaler()
      tsne_data = scl.fit_transform(tsne_data)
      # Split training testing data
      enc = LabelEncoder()
      label_encoded = enc.fit_transform(subject_data)
      X_train, X_test, y_train, y_test = train_test_split(tsne_data, label_encoded,__
      →random_state=3)
      # Create model
      lgbm = LGBMClassifier(n_estimators=500, random_state=3)
      lgbm = lgbm.fit(X_train, y_train)
      # Get importances
      features = both_df.drop(['Data', 'subject'], axis=1).columns
      importances = lgbm.feature_importances_
      # Sum importances
      data = {'Gyroscope':0, 'Accelerometer':0}
      for importance, feature in zip(importances, features):
          if 'Gyro' in feature:
              data['Gyroscope'] += importance
          if 'Acc' in feature:
              data['Accelerometer'] += importance
      # Create dataframe and plot
      sensor_df = pd.DataFrame.from_dict(data, orient='index').rename(columns={0:
      →'Importance'})
      sensor_df.plot(kind='barh', figsize=(14,4), title='Sensor Importance For_
      →Classifing Participants By Walking Style (Feature Importance Sum)')
      plt.show()
```





```
[20]: # Create data and plot plt.figure(figsize=(15,5))
```



```
[21]: def plotSkew(x):
    # Fit label to norm
    (mu, sigma) = norm.fit(x)
    alpha = skew(x)

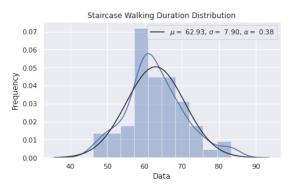
    fig, axarr = plt.subplots(1, 2, figsize=(15,4))

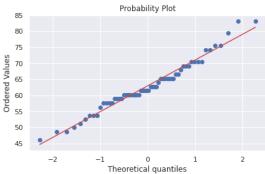
# Plot label and fit
    sns.distplot(x, fit=norm, ax=axarr[0])
    axarr[0].legend(['$\mu=$ \{:.2f\}, $\sigma=$ \{:.2f\}, $\\alpha=$ \{:.2f\}'.

$\informat(\text{mu}, \sigma, \alpha)], loc='\text{best'})
    axarr[0].set_title('Staircase Walking Duration Distribution')
    axarr[0].set_ylabel('Frequency')

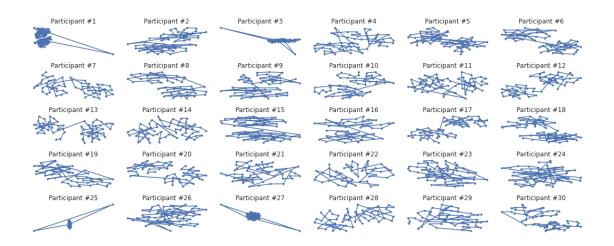
# Plot probability plot
    res = probplot(x, plot=axarr[1])
    plt.show()

plotSkew(duration_df)
```





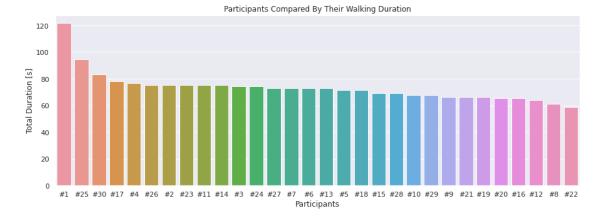
```
[22]: fig, axarr = plt.subplots(5, 6, figsize=(15,6))
      for person in range(0, 30):
          # Get data
          single_person = both_df[(label=='WALKING') & (both_df['subject']=='#{}'.
       →format(person+1))].drop(['subject', 'Data'], axis=1)
          # Scale data
          scl = StandardScaler()
          tsne_data = scl.fit_transform(single_person)
          # Reduce dimensions
          pca = PCA(n_components=0.9, random_state=3)
          tsne_data = pca.fit_transform(tsne_data)
          # Transform data
          tsne = TSNE(random_state=3)
          tsne_transformed = tsne.fit_transform(tsne_data)
          # Create plot
          axarr[person//6][person%6].plot(tsne_transformed[:,0], tsne_transformed[:
       \hookrightarrow,1], '.-')
          axarr[person//6] [person%6].set_title('Participant #{}'.format(person+1))
          axarr[person//6][person%6].axis('off')
      plt.tight_layout()
      plt.show()
```



```
[23]: # Group the data by participant and compute total duration of walking
mask = label=='WALKING'
duration_df = (both_df[mask].groupby('subject')['Data'].count() * 1.28)

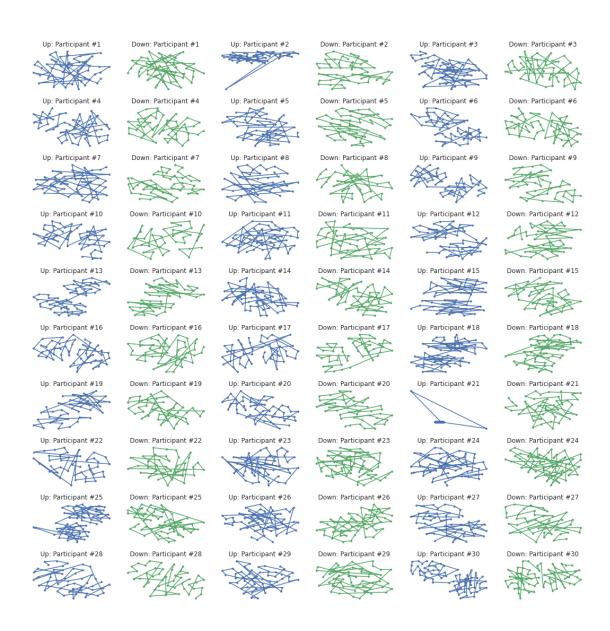
# Create plot
plot_data = duration_df.reset_index().sort_values('Data', ascending=False)

plt.figure(figsize=(15,5))
sns.barplot(data=plot_data, x='subject', y='Data')
plt.title('Participants Compared By Their Walking Duration')
plt.xlabel('Participants')
plt.ylabel('Total Duration [s]')
plt.show()
```



```
[24]: # Create subplots
fig, axarr = plt.subplots(10, 6, figsize=(15,15))
```

```
# Iterate over each participant
for person in range(0, 30):
   # Get data
   single_person_up = both_df[(label=='WALKING_UPSTAIRS') &_
\rightarrowaxis=1)
   single_person_down = both_df[(label=='WALKING_DOWNSTAIRS') &_
\rightarrowaxis=1)
   # Scale data
   scl = StandardScaler()
   tsne_data_up = scl.fit_transform(single_person_up)
   tsne_data_down = scl.fit_transform(single_person_down)
   # Reduce dimensions
   pca = PCA(n_components=0.9, random_state=3)
   tsne_data_up = pca.fit_transform(tsne_data_up)
   tsne_data_down = pca.fit_transform(tsne_data_down)
   # Transform data
   tsne = TSNE(random_state=3)
   tsne_transformed_up = tsne.fit_transform(tsne_data_up)
   tsne_transformed_down = tsne.fit_transform(tsne_data_down)
   # Create plot
   axarr[2*person/6][2*person%6].plot(tsne_transformed_up[:,0],__
→tsne_transformed_up[:,1], '.b-')
   axarr[2*person//6][2*person%6].set_title('Up: Participant #{}'.
→format(person+1))
   axarr[2*person//6][2*person%6].axis('off')
   axarr[2*person//6][(2*person%6)+1].plot(tsne_transformed_down[:,0],__
→tsne_transformed_down[:,1], '.g-')
   axarr[2*person//6][(2*person%6)+1].set_title('Down: Participant #{}'.
→format(person+1))
   axarr[2*person//6][(2*person%6)+1].axis('off')
plt.tight_layout()
plt.show()
```



```
[25]: # Use SS class fro jdarcy
class SSA(object):
    __supported_types = (pd.Series, np.ndarray, list)

def __init__(self, tseries, L, save_mem=True):
    __i''

    Decomposes the given time series with a singular-spectrum analysis.

→ Assumes the values of the time series are
    recorded at equal intervals.

Parameters
-------
```

```
tseries: The original time series, in the form of a Pandas Series, \Box
\hookrightarrowNumPy array or list.
       L : The window length. Must be an integer 2 <= L <= N/2, where N is the \Box
\hookrightarrow length of the time series.
       save_mem : Conserve memory by not retaining the elementary matrices. __
→ Recommended for long time series with
            thousands of values. Defaults to True.
       Note: Even if an NumPy array or list is used for the initial time\sqcup
⇒series, all time series returned will be
       in the form of a Pandas Series or DataFrame object.
       # Tedious type-checking for the initial time series
       if not isinstance(tseries, self.__supported_types):
           raise TypeError('Unsupported time series object. Try Pandas Series, L
→NumPy array or list.')
       # Checks to save us from ourselves
       self.N = len(tseries)
       if not 2 \le L \le self.N/2:
            raise ValueError('The window length must be in the interval [2, N/
→2].')
       self.L = L
       self.orig TS = pd.Series(tseries)
       self.K = self.N - self.L + 1
       # Embed the time series in a trajectory matrix
       self.X = np.array([self.orig_TS.values[i:L+i] for i in range(0, self.
\rightarrowK)]).T
       # Decompose the trajectory matrix
       self.U, self.Sigma, VT = np.linalg.svd(self.X)
       self.d = np.linalg.matrix_rank(self.X)
       self.TS_comps = np.zeros((self.N, self.d))
       if not save mem:
            # Construct and save all the elementary matrices
            self.X_elem = np.array([ self.Sigma[i]*np.outer(self.U[:,i], VT[i,:
→]) for i in range(self.d) ])
            \# Diagonally average the elementary matrices, store them as columns<sub>\sqcup</sub>
\rightarrow in array.
           for i in range(self.d):
```

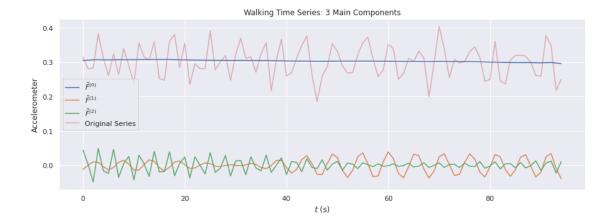
```
X_{rev} = self.X_{elem}[i, ::-1]
                self.TS_comps[:,i] = [X_rev.diagonal(j).mean() for j in_
\rightarrowrange(-X_rev.shape[0]+1, X_rev.shape[1])]
            self.V = VT.T
       else:
            # Reconstruct the elementary matrices without storing them
           for i in range(self.d):
                X_elem = self.Sigma[i]*np.outer(self.U[:,i], VT[i,:])
                X_{rev} = X_{elem}[::-1]
                self.TS_comps[:,i] = [X_rev.diagonal(j).mean() for j in_
→range(-X_rev.shape[0]+1, X_rev.shape[1])]
            self.X_elem = 'Re-run with save_mem=False to retain the elementary_<math>\sqcup
⇔matrices.'
            # The V array may also be very large under these circumstances, so_{\sqcup}
\rightarrow we won't keep it.
            self.V = 'Re-run with save_mem=False to retain the V matrix.'
       # Calculate the w-correlation matrix.
       self.calc wcorr()
   def components_to_df(self, n=0):
       Returns all the time series components in a single Pandas DataFrame\sqcup
\hookrightarrow object.
        ,,,
       if n > 0:
           n = min(n, self.d)
       else:
           n = self.d
       # Create list of columns - call them F0, F1, F2, ...
       cols = ['F{}'.format(i) for i in range(n)]
       return pd.DataFrame(self.TS_comps[:, :n], columns=cols, index=self.
→orig_TS.index)
   def reconstruct(self, indices):
       Reconstructs the time series from its elementary components, using the \Box
\rightarrow given indices. Returns a Pandas Series
       object with the reconstructed time series.
       Parameters
```

```
indices: An integer, list of integers or slice(n,m) object, __
→representing the elementary components to sum.
       if isinstance(indices, int): indices = [indices]
       ts_vals = self.TS_comps[:,indices].sum(axis=1)
       return pd.Series(ts_vals, index=self.orig_TS.index)
   def calc_wcorr(self):
       Calculates the w-correlation matrix for the time series.
       # Calculate the weights
       w = np.array(list(np.arange(self.L)+1) + [self.L]*(self.K-self.L-1) +
→list(np.arange(self.L)+1)[::-1])
       def w_inner(F_i, F_j):
           return w.dot(F_i*F_j)
       # Calculated weighted norms, ||F_i||_w, then invert.
       F_wnorms = np.array([w_inner(self.TS_comps[:,i], self.TS_comps[:,i])__
→for i in range(self.d)])
       F \text{ wnorms} = F \text{ wnorms}**-0.5
       # Calculate Wcorr.
       self.Wcorr = np.identity(self.d)
       for i in range(self.d):
           for j in range(i+1,self.d):
               self.Wcorr[i,j] = abs(w_inner(self.TS_comps[:,i], self.
→TS_comps[:,j]) * F_wnorms[i] * F_wnorms[j])
               self.Wcorr[j,i] = self.Wcorr[i,j]
   def plot_wcorr(self, min=None, max=None):
       Plots the w-correlation matrix for the decomposed time series.
       if min is None:
           min = 0
       if max is None:
           max = self.d
       if self.Wcorr is None:
           self.calc_wcorr()
       ax = plt.imshow(self.Wcorr)
```

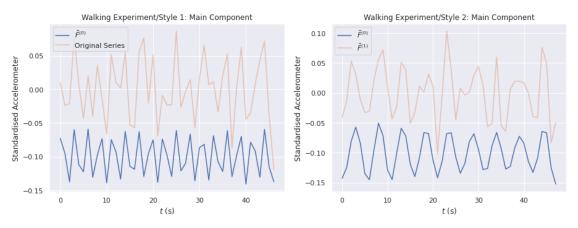
```
plt.xlabel(r'$\tilde{F}_i$')
                       plt.ylabel(r'$\tilde{F}_j$')
                       plt.colorbar(ax.colorbar, fraction=0.045)
                       ax.colorbar.set_label('$W_{i,j}$')
                       plt.clim(0,1)
                        # For plotting purposes:
                       if max == self.d:
                                   \max rnge = self.d-1
                        else:
                                   max_rnge = max
                       plt.xlim(min-0.5, max_rnge+0.5)
                       plt.ylim(max_rnge+0.5, min-0.5)
# Euclidean norm of the acceleration
walking_series = both_df[(label=='WALKING') &_

→ (both_df['subject'] == '#1')][['tBodyAcc-mean()-X', 'tBodyAcc-mean()-Y', 

□ (both_df['subject'] == '#1')][['tBodyAcc-mean()-X', 'tBodyAcc-mean()-Y', 
□ (both_df['subject'] == '#1')][['tBodyAcc-mean()-X', 'tBodyAcc-mean()-Y', 
□ (both_df['subject'] == '#1')][['tBodyAcc-mean()-X', 'tBodyAcc-mean()-Y', 
□ (both_df['subject'] == '#1')][['tBodyAcc-mean()-X', 'tBodyAcc-mean()-Y', 
□ (both_df['subject'] == '#1')][['tBodyAcc-mean()-X', 'tBodyAcc-mean()-Y', 
□ (both_df['subject'] == '#1')][['tBodyAcc-mean()-X', 'tBodyAcc-mean()-Y', 
□ (both_df['subject'] == '#1')][['tBodyAcc-mean()-X', 'tBodyAcc-mean()-Y', 
□ (both_df['subject'] == '#1')][['tBodyAcc-mean()-X', 'tBodyAcc-mean()-Y', 
□ (both_df['subject'] == '#1')][['tBodyAcc-mean()-X', 'tBodyAcc-mean()-Y', 
□ (both_df['subject'] == '#1')][['tBodyAcc-mean()-X', 'tBodyAcc-mean()-X', 'tBodyAcc-m
  →'tBodyAcc-mean()-Z']].reset_index(drop=True)
walking series = (walking series**2).sum(axis=1)**0.5
# Decomposing the series
series_ssa = SSA(walking_series, 30)
# Plotting the decomposition
plt.figure(figsize=(15,5))
series_ssa.reconstruct(0).plot()
series_ssa.reconstruct([1,2]).plot()
series_ssa.reconstruct([3,4]).plot()
series_ssa.orig_TS.plot(alpha=0.4)
plt.title('Walking Time Series: 3 Main Components')
plt.xlabel(r'$t$ (s)')
plt.ylabel('Accelerometer')
legend = [r'*]^{{(\{0\})}}^*.format(i) for i in range(3)] + ['Original_{\square}]
 ⇔Series']
plt.legend(legend);
```



```
[26]: # Both walking styles from a single participant
                style1 = both_df.loc[78:124][['tBodyAcc-mean()-X', 'tBodyAcc-mean()-Y',__
                 style1 = ((style1**2).sum(axis=1)**0.5)
                style1 -= style1.mean()
                style2 = both df.loc[248:295][['tBodyAcc-mean()-X', 'tBodyAcc-mean()-Y', 'tBodyAcc-mean()-Y', 'tBodyAcc-mean()-Y', 'tBodyAcc-mean()-Y', 'tBodyAcc-mean()-Y', 'tBodyAcc-mean()-X', 'tBodyAcc-mean()-X',
                 →'tBodyAcc-mean()-Z']].reset_index(drop=True)
                style2 = (style2**2).sum(axis=1)**0.5
                style2 -= style2.mean()
                # Decompose
                style1_ssa = SSA(style1, 20)
                style2_ssa = SSA(style2, 20)
                # Create plot
                fig, axarr = plt.subplots(1, 2, figsize=(15,5))
                # Plotting the decomposition style 1
                (style1_ssa.reconstruct([0,1])-0.1).plot(ax=axarr[0])
                style1_ssa.orig_TS.plot(alpha=0.4, ax=axarr[0])
                axarr[0].set_title('Walking Experiment/Style 1: Main Component')
                axarr[0].set_xlabel(r'$t$ (s)')
                axarr[0].set_ylabel('Standardised Accelerometer')
                legend = [r'$\dot{{F}}^{{(\{0\})}}'.format(i) for i in range(1)] + ['Original_{\square}]
                  →Series']
                axarr[0].legend(legend);
                # Plotting the decomposition style 2
                (style2 ssa.reconstruct([0,1])-0.1).plot(ax=axarr[1])
                style2_ssa.orig_TS.plot(alpha=0.4, ax=axarr[1])
                axarr[1].set title('Walking Experiment/Style 2: Main Component')
                axarr[1].set_xlabel(r'$t$ (s)')
```

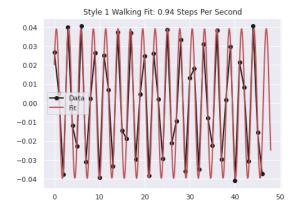


```
[27]: # Function to fit a sinus
      def fit_sin(tt, yy):
          '''Fit sin to the input time sequence, and return fitting parameters "amp",_{\sqcup}
       → "omega", "phase", "offset", "freq", "period" and "fitfunc"'''
          tt = np.array(tt)
          yy = np.array(yy)
          # Assume uniform spacing
          ff = np.fft.fftfreq(len(tt), (tt[1]-tt[0]))
          Fyy = abs(np.fft.fft(yy))
          # Exclude the zero frequency "peak"
          guess_freq = abs(ff[np.argmax(Fyy[1:])+1])
          guess_amp = np.std(yy) * 2.**0.5
          guess_offset = np.mean(yy)
          guess = np.array([guess_amp, 2.*np.pi*guess_freq, 0., guess_offset])
          # Sinus
          def sinfunc(t, A, w, p, c):
              return A * np.sin(w*t + p) + c
          # Fit sinus
          popt, pcov = curve_fit(sinfunc, tt, yy, p0=guess)
          A, w, p, c = popt
          f = w/(2.*pi)
          fitfunc = lambda t: A * np.sin(w*t + p) + c
          return {"amp": A, "omega": w, "phase": p, "offset": c, "freq": f, "period": u
       →1./f, "fitfunc": fitfunc, "maxcov": np.max(pcov), "rawres": □

→ (guess, popt, pcov)}
```

```
# Get data
main_style1 = style1_ssa.reconstruct([0, 1])
tt1 = main_style1.index
yy1 = main_style1.values
tt_res1 = np.arange(0, 48, 0.1)
# Fit data
res1 = fit_sin(tt1, yy1)
# Get data
main_style2 = style2_ssa.reconstruct([0, 1])
tt2 = main_style2.index
yy2 = main_style2.values
tt_res2 = np.arange(0, 48, 0.1)
# Fit data
res2 = fit_sin(tt2, yy2)
# Plot data
fig, axarr = plt.subplots(1, 2, figsize=(15,5))
# Plot data
axarr[0].plot(tt1, yy1, "-ok", label='Data', linewidth=2)
axarr[0].plot(tt_res1, res1['fitfunc'](tt_res1), "r-", label='Fit', linewidth=2)
axarr[0].set_title('Style 1 Walking Fit: {:.2f} Steps Per Second'.

¬format((res1['omega']*1.28)/(pi)))
axarr[0].legend(loc="best")
axarr[1].plot(tt2, yy2, "-ok", label='Data', linewidth=2)
axarr[1].plot(tt_res2, res2['fitfunc'](tt_res2), "r-", label='Fit', linewidth=2)
axarr[1].set_title('Style 2 Walking Fit: {:.2f} Steps Per Second'.
→format((res2['omega']*1.28)/(pi)))
axarr[1].legend(loc="best")
plt.show()
```





```
[28]: # Get data
      tsne_data = both_df[label=='WALKING'].copy()
      data_data = tsne_data.pop('Data')
      subject_data = tsne_data.pop('subject')
      # Scale data
      scl = StandardScaler()
      tsne_data = scl.fit_transform(tsne_data)
      # Reduce dimensions
      pca = PCA(n components=0.9, random state=3)
      tsne_data = pca.fit_transform(tsne_data)
      # Transform data
      tsne = TSNE(random_state=3)
      tsne_transformed = tsne.fit_transform(tsne_data)
      # Create subplots
      fig, axarr = plt.subplots(1, 1, figsize=(15,10))
      ### Plot Subjects
      # Get colors
      n = subject_data.unique().shape[0]
      colormap = get_cmap('gist_ncar')
      colors = [rgb2hex(colormap(col)) for col in np.arange(0, 1.01, 1/(n-1))]
      for i, group in enumerate(subject_data.unique()):
          # Mask to separate sets
          mask = (subject_data==group).values
          axarr.scatter(x=tsne_transformed[mask][:,0], y=tsne_transformed[mask][:,1],__
      →c=colors[i], alpha=0.5, label=group)
      axarr.set_title('TSNE Walking Style By Participant')
      plt.show()
```



Feature Scaling

Pre-processing and data preparation to feed data into Artificial Neural Network.

```
[29]: from sklearn.preprocessing import MinMaxScaler
      scaler = MinMaxScaler()
      scaler.fit(train df.iloc[:,0:562])
      mat_train = scaler.transform(train_df.iloc[:,0:562])
      print(mat_train)
      [[0.64429225 0.48985291 0.43354743 ... 0.79825103 0.47068654 0.
                                                                               ]
       [0.63920942 0.49179472 0.4382399 ... 0.79848665 0.47284164 0.
                                                                               ]
      [0.63982653 0.49026642 0.44326915 ... 0.79872236 0.47544109 0.
                                                                               ٦
                                                                               1
       [0.63669369 0.49149469 0.47748909 ... 0.84506893 0.52040559 1.
       [0.64482708 0.49057848 0.42085971 ... 0.84323381 0.51266974 1.
                                                                               1
       [0.67575173 0.49378844 0.39806642 ... 0.84348837 0.51834742 1.
                                                                               ]]
[30]: scaler = MinMaxScaler()
      scaler.fit(test_df.iloc[:,0:562])
      mat_test = scaler.transform(test_df.iloc[:,0:562])
      print(mat_test)
      [[0.6718788  0.55764282  0.52464834  ...  0.62209457  0.46362736  0.
                                                                               ]
        \hbox{\tt [0.69470427\ 0.57426358\ 0.42707858\ ...\ 0.62446791\ 0.45014396\ 0.} 
                                                                               ]
```

```
1
      [0.68636345 0.55310221 0.42794829 ... 0.62380956 0.45251181 0.
                                                                            ٦
      [0.74529355 0.64526771 0.43015674 ... 0.62088108 0.58803909 1.
      [0.65638384 0.62620241 0.44817885 ... 0.61581385 0.59135763 1.
                                                                            1
      [0.58994885 0.56560474 0.41032069 ... 0.61537208 0.59163879 1.
                                                                            11
[31]: temp = []
      for i in train_df.Activity:
          if i == "WALKING": temp.append(0)
          if i == "WALKING_UPSTAIRS": temp.append(1)
          if i == "WALKING DOWNSTAIRS": temp.append(2)
          if i == "SITTING": temp.append(3)
          if i == "STANDING": temp.append(4)
          if i == "LAYING": temp.append(5)
      train_df["n_Activity"] = temp
[32]: temp = []
      for i in test_df.Activity:
          if i == "WALKING": temp.append(0)
          if i == "WALKING_UPSTAIRS": temp.append(1)
          if i == "WALKING_DOWNSTAIRS": temp.append(2)
          if i == "SITTING": temp.append(3)
          if i == "STANDING": temp.append(4)
          if i == "LAYING": temp.append(5)
      test_df["n_Activity"] = temp
[33]: train_df.drop(["Activity"] , axis = 1 , inplace = True)
[34]: test_df.drop(["Activity"], axis = 1, inplace = True)
[35]: from keras.utils import to_categorical
      y_train = to_categorical(train_df.n_Activity , num_classes=6)
      y_test = to_categorical(test_df.n_Activity , num_classes=6)
[36]: X_train = mat_train
      X \text{ test} = \text{mat test}
[37]: print(X_train.shape , y_train.shape)
      print(X_test.shape , y_test.shape)
     (7352, 562) (7352, 6)
     (2947, 562) (2947, 6)
```